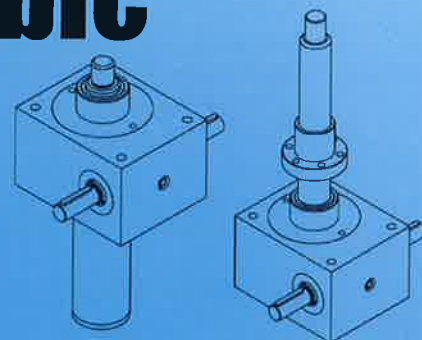




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**Screw jack cubic  
Type BG**



# History

**1969** Mr. Enzfelder established a job shop in Vienna. Equipped with some machinery, the Enzfelder Company manufactured machine parts according to drawings.

Within one year the number of employees rose to 3. The Enzfelder company started manufacturing threaded spindles and nuts according to drawings. Then the range of manufacturing was enlarged by toothed wheels, screw wheels and endless screws according to drawings.

**1974** The company including the complete manufacture was relocated to Enzesfeld.

**1975** The manufacture of spindle gears was launched. The company's experience in the manufacture of trapezoid-threaded spindles, nuts, worm gear pairs and casings was a valuable basis for the construction. After many tests, the serial production of spindle gears was launched one year later. The result was a product characterized by a first-rate price-performance ratio. The product was distributed by dealers all over Europe.

**1981** The planning and construction of small hydropower plants was launched to replace diesel generators. Environmental protection was not really a topic at that time, however, and the production was stopped in 1986.

**1989** The Enzfelder GesmbH company replaced the Franz Enzfelder Company.

**1990** Scissor-type lifting platforms and cable winches were added to the delivery program.

**1991** Resilient spacer shafts were tested and added to the production range. At the same time, the telescopic spindle gear was developed. A patent for this principle was applied for and issued.

**1993** The sale of spindle gears under their own name was launched and presented for the first time at the Hannover industrial fair. We have been approached with a variety of tasks and have provided solutions according to the customers' needs ever since.

**1994** In cooperation with our customers we produced the first bevel gears to specification.

**1995** Spindle bearing arrangements were designed and included in the standard program.

**1996** The Enzfelder company produced planet gear to specification for the first time.

**1998-1999** The standard programs were enlarged. Additionally, bevel gears are manufactured in a standard design.

**2000** The development of electric cylinders in standard design for very high loads (5-1000kN) was started. At the same time the telescopic spindle gears were refined to save the customer the guiding and locking devices. Since that time we have been able to offer telescopic cylinders, too.

**2001** The development of electric cylinders was completed, and these cylinders were added to the standard program.

At the same time the development and fabrication of cubic spindle gears for lifting loads between 2.5 and 150kN was started. These gears were added to the standard program as well.

**2002** were extended and optimized the series of the electric cylinders. Further we provide an electronic 2D-3D product catalogue of the spindle gears, it makes it possible to integrate our products into your system.

**2002-2003** We putted our new assembling and packaging hall, beside the manufacturing hall, in operation

**2003** We increased our machinery by buying a CNC machine tool with 7 axes, brand AXA. That new CNC machine allows a precise machining of the screw jack housings in only two clamping.

**2003-2004** The engineering started to use new 3-D CAD software, Solid Edge. That software enables our customers to integrate easily our drawings.

**2004** We opened a sales office in France.

**2004-2005** We started to design the high performance screw jacks HSG and we created a range of 10 different sizes.

**2005** First participation to an exhibition in France: INDUSTRIE 2005 at Lyon.

**2005-2006** We started to design a new range of telescopic screw jacks TSGLR. Today, these new telescopic screw jacks, with a more compact design, are used in the stage industry, in the aircraft industry, on train lifting equipments and in machine building.

**2008** We replaced the tread grinding machine by a new CNC thread grinding machine, brand Mikromat.

**2008-2009** transmission program is certified to ATEX

**2009-2010** beginning of the series production of Quick-lifting screw jacks SHG

**2010** Development of the transmission range Servo lifting gear (backlash & game adjustable)

Expand our global market with traders in Australia

**2011** development Servo lifting electric cylinder SHELZ (Servo lifting gear with cylindrical structure) and the beginning of the ELZP Series Electric cylinders parallel for Industry sector applications.

**2012** acquisition of the product group UniCe worm gear, helical worm geared motors, couplings, torque limiters and slip clutches. Expansion screw jacks cubic BG up to size for 1000kN

**2013-2014** revision of the telescopic spindle cylinder TSGZ the new cost-optimized design.

Development of product group Electric PNEU, electric cylinder with ball screw, stainless version in hygienically optimized design with mounting dimensions, speeds and forces such as pneumatic cylinder.

**2014** first Quick-lifting screw jacks with cylindrical structure can be delivered SHGZ = Quick-lifting electric cylinder

In recent years, customer problems are solved in the drive and lifting technology from us. Depending on the application, we developed the optimal solution and made with the best possible price / performance ratio.



# Content of Catalog

**ENZFELDER** GMBH  
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Here I should be! If you need me and I am not here, YOU can request me free of charge at company Enzfelder!

**Type BG  
CAD-Files**

**Enzfelder GmbH**

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**01 - 2004**

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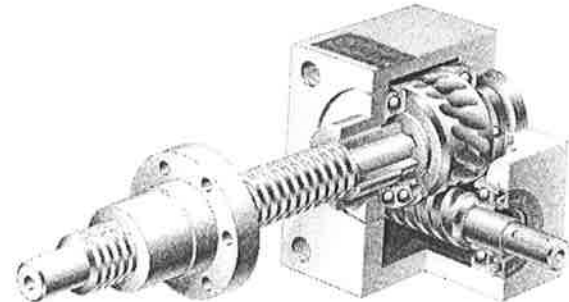
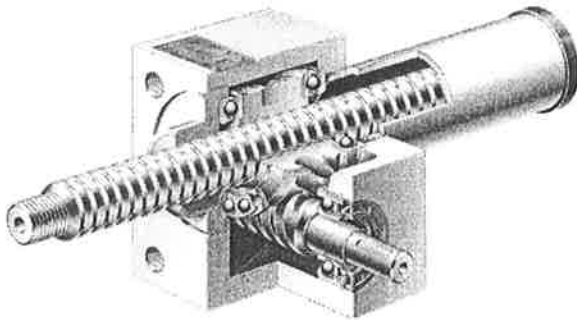
Representation not obligatory  
Subjects to measurements  
changes



# Selection of spindle gears

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For the correct selection of spindle gears the following data are of decisive importance:

- |  |                      |
|--|----------------------|
| 1.) load   | [kN]                 |
| 2.) lifting speed                                  | [m/min]              |
| 3.) operating cycle                                | [%/10min] [%/hour]   |
| 4.) spindle length (buckling)                      | [mm]                 |
| 5.) tensile- or pressure load                      | [kN]                 |
| 6.) ambient temperature                            | [°C]                 |
| 7.) fitting length (please indicate when ordering) | [mm]                 |
| 8.) critical speed of the spindle                  | [min <sup>-1</sup> ] |

If you use the questionnaire on page 17 please provide the data available.

How to proceed in the selection: on the basis of the desired load data (in kN) a suitable type of gear is selected from the preselection table below.

Sizes	rated power kN	rated power in kN by ball bearing spindle	gearbox material	size of spindle	size of ball bearing spindle	gear reduction		length of stroke per rotation in mm		length of stroke per rotation in mm by ball bearing spindle	efficiency in %		efficiency in % by ball bearing spindle	max. driving power duty cycle 20%/h in kW	max. driving power duty cycle 10%/h in kW	weight in kg excl. lifting element	weight in kg per 100mm stroke
						H	L	H	L		H	L					
BG 2,5	2,5	---	AL-Leg.	Tr 14x4	-----	4:1	16:1	1,0	0,25	----	34	24	---	0,18	0,25	0,6	0,1
BG 5	5	5		Tr 18x4	1605	4:1	16:1	1,0	0,25	1,25	30	23	57	0,3	0,42	1,2	0,35
BG 10	10	10		Tr 20x4	2005	4:1	16:1	1,0	0,25	1,25	28	21	56	0,5	0,7	2,1	0,45
BG 25	25	12,5	GG	Tr 30x6	2505	6:1	24:1	1,0	0,25	0,83	27	19	55	1,2	1,7	6,0	0,7
BG 50	50	22/42		Tr 40x7	4005/10	7:1	28:1	1,0	0,25	0,71/1,43	25	18	53/56	2,3	3,2	17	1,2
BG 100	100	65	GGG	Tr 55x9	5010	9:1	36:1	1,0	0,25	1,1	19	14	47	5,1	7,1	32	2,0
BG 150	150	---		Tr 60x9	-----	9:1	36:1	1,0	0,25	----	19	14	---	7,2	10	41	2,4

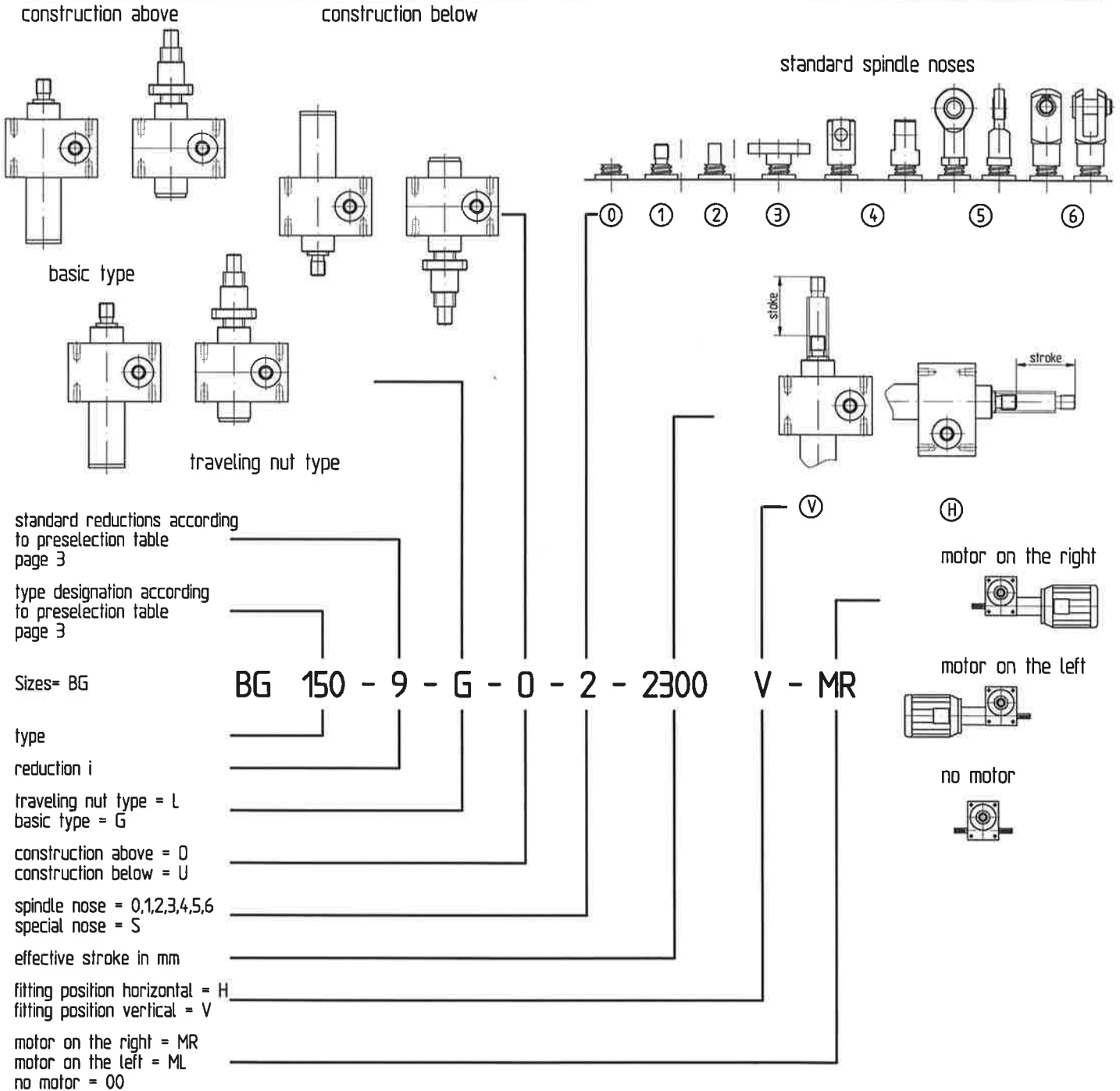
Read off the dimensioned sketch and the performance table on the corresponding page of the catalog:

- whether the dimensions of gear and spindle fit into your system.
- which gear reduction must be selected for the desired lifting speed (for higher lifting speeds the use of a double-thread spindle may be necessary).
- whether the power required for the desired lifting speed is admissible.
- whether under pressure load the critical buckling force is not exceeded.
- whether the critical revolutions/min of the spindle are not exceeded.
- If one of these requirements cannot be met the type next in size must be chosen.
- If point 6 is not sufficient, choose one of the types next in size or ask for special types (questionnaire see page 17)



# Survey of construction modes with exemple for ordering

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Above example for ordering:  
 Sizes type 150, reduction 9:1, basic type construction up, spindle nose 2,  
 stroke 2300mm, mounted vertical, with motor mounted on the right.

Additionally available options:

rigid protection  
 expansion bellows  
 spring steel spirals  
 square locking device to prevent twisting

three-phase A.C. motor with or without brake  
 d.c. motor  
 gear motor  
 limit stop

overload clutch  
 ball bearing spindle  
 cardanplate  
 oil lubrication

The required options must be added to the order ID or marked in the questionnaire.



# Spindle gear Basic type (G)

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sheet measure	Sizes/Types							
	Index	BG 2,5	BG 5	BG 10	BG 25	BG 50	BG 100	BG 150
		BG002,5_GA_?	BG005_GA_?	BG010_GA_?	BG025_GA_?	BG050_GA_?	BG100_GA_?	BG150_GA_?
	A	92	120	140	195	240	300	325
	A <sub>1</sub>	56	75	89	109	150	170	200
<p>square locking device to prevent twisting</p>	B	60	80	100	130	180	200	210
	C	50	72	85	105	145	165	195
	D	38	52	63	81	115	131	155
	E	48	60	78	106	150	166	170
	F	21	24	27,5	45	47,5	67,5	65
	G	20	25	32	45	63	71	71
	H	14	18	20	36	36	56	56
	I	6	10	11	12	15	17	20
	J <sub>6</sub>	9	10	14	16	20	25	25
	K	M6	M8	M8	M10	M12	M20	M24
	L <sup>1)</sup>	20/45	20/48/76 <sup>4)</sup>	30/55/74 <sup>4)</sup>	30/60	45/80	55/80	55/90
	N <sub>1</sub>	25	32	37	41	58,5	80	87,5
	N <sub>2</sub>	25	30	38	41	58,5	80	87,5
	O	18	24	28	31	39	46	49
	P	12	19	20	22	29	48	48
	Q	28	32	42	50	65	90	95
	Q <sub>1</sub>	30x30	35x35	40x40	50x50	65x65	90x90	100x100
	Q <sub>2</sub> <sup>3)</sup>	80	80	85	100	100	110	110
	R	M8	M12	M14	M20	M30	M36	M48x2
	S	50	62	75	82	117	160	175
	T <sup>2)</sup>	27	35/48	45/49	50	65	95	95
	U <sup>2)</sup>	12	12/25	18/22	23	32	40	40
	V <sup>2)</sup>	26	30/48	39/57	46	60	85	90
	W	Tr 14x4	Tr 18x4	Tr 20x4	Tr 30x6	Tr 40x7	Tr 55x9	Tr 60x9
	W <sub>KGT</sub>	-----	1605	2005	2505	4005/10	5010	-----
	Y	3	3	5	5	6	8	8
	Z	12	13	15	15	16	30	40

1) The second measurement are for type with run off safty  
 2) The second measurement are for type with ball bearing spindle  
 3) The second measurement are for type with ball bearing spindle in construction below  
 4) The measurement are for type with ball bearing spindle and run off safty in construction below  
 Special executions on request are possible  
 Subjects to measurements changes, representation not obligatory



# Spindle gear Traveling nut type (L)

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sheet measure	Sizes/Types							
	Index	BG 2,5	BG 5	BG 10	BG 25	BG 50	BG 100	BG 150
		BG002,5_LA_?	BG005_LA_?	BG010_LA_?	BG025_LA_?	BG050_LA_?	BG100_LA_?	BG150_LA_?
	A	92	120	140	195	240	300	325
	A <sub>1</sub>	56	75	89	109	150	170	200
	B	60	80	100	130	180	200	210
	C	50	72	85	105	145	165	195
	D	38	52	63	81	115	131	155
	E	48	60	78	106	150	166	170
	F	21	24	27,5	45	47,5	67,5	65
	G	20	25	32	45	63	71	71
	H	14	18	20	36	36	56	56
	I	6	10	11	12	15	17	20
	J <sub>6</sub>	9	10	14	16	20	25	25
	K	M6	M8	M8	M10	M12	M20	M24
	L	69	95	112	134	185/171 <sup>1)</sup>	232	244
	M <sub>1</sub> <sup>1)</sup>	24	28/28	32/32	38/38	63/53	72/72	85
	M <sub>2</sub> <sup>1)</sup>	44	48/48	55/55	62/62	95/80	110/110	125
	M <sub>3</sub> <sup>1)</sup>	34	38/38	45/45	50/50	78/68	90/90	105
	M <sub>4</sub> <sup>1)</sup>	25	44/44	44/44	46/46	73/59	97/97	99
	M <sub>5</sub> <sup>1)</sup>	10	12/12	12/12	14/14	16/16	18/18	20
	M <sub>6</sub> <sup>1)</sup>	6	6/5,5	7/7	7/7	9/7	11/11	11
	N <sub>1</sub>	25	32	37	41	58,5	80	87,5
	N <sub>2</sub>	25	30	38	41	58,5	80	87,5
	O	18	24	28	31	39	46	49
	P	12	15	20	25	30	45	55
	R <sub>6</sub>	8	12	15	20	25	40	45
	S	50	62	75	82	117	160	175
	U	12	12	18	23	32	40	40
	V	26	30	39	46	60	85	90
	W <sup>1)</sup>	Tr 14x4	Tr 18x4	Tr 20x4	Tr 30x6	Tr 40x7	Tr 55x9	Tr 60x9
	W <sub>KGT</sub>	-----	1605	2005	2505	4005/10 <sup>2)</sup>	5010	-----
	X	10	12	15	20	25	25	25
	Y	3	3	5	5	6	8	8
	Z	12	13	15	15	16	30	40

<sup>1)</sup> The second measurement are for type with ball bearing spindle

<sup>2)</sup> The same measurement as Tr-nut

<sup>2)</sup> Are for Type with KGT 4005

Special executions on request are possible

Subjects to measurements changes, representation not obligatory




# Spindle gear accessories


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## Flange plate (FP)

Sizes		measurement in mm							
		F <sub>1</sub>	F <sub>2</sub>	F <sub>3</sub>	F <sub>4</sub>	F <sub>5</sub>	F <sub>6</sub>	F <sub>7</sub>	F <sub>8</sub>
BG 2,5	BG002,5_K3	50	40	26	M8	16	6	7	M4
BG 5	BG005_K3	65	48	30	M12	20	7	9	M5
BG 10	BG010_K3	80	60	39	M14	21	8	11	M6
BG 25	BG025_K3	90	67	46	M20	23	10	11	M8
BG 50	BG050_K3	110	85	60	M30	30	15	13	M8
BG 100	BG100_K3	150	117	85	M36	50	20	17	M10
BG 150	BG150_K3	170	130	90	M48x2	50	25	21	M10

## Spindle nose 4 (SE)

Sizes		measurement in mm						
		GK <sub>1</sub>	GK <sub>2</sub>	GK <sub>3</sub>	GK <sub>4</sub>	GK <sub>5</sub>	GK <sub>6</sub>	GK <sub>7</sub> H8
BG 2,5	BG002,5_K4	40	30	12	10	25	M8	8
BG 5	BG005_K4	55	40	15	15	30	M12	10
BG 10	BG010_K4	63	45	20	18	40	M14	12
BG 25	BG025_K4	78	53	30	20	45	M20	16
BG 50	BG050_K4	100	70	35	30	60	M30	20
BG 100	BG100_K4	130	97	40	33	85	M36	22
BG 150	BG150_K4	120	75	60	45	90	M48x2	40

## Pivoting head (GK)

Baugröße		measurement in mm								
		GK <sub>1</sub>	GK <sub>2</sub>	GK <sub>3</sub>	GK <sub>4</sub>	GK <sub>5</sub>	GK <sub>6</sub>	GK <sub>7</sub>	GK <sub>8</sub>	GK <sub>9</sub>
BG 2,5	BG002,5_K5	24	36	48	8	6	13	M8x1,25	12	8
BG 5	BG005_K5	34	50	67	10	8	18	M12x1,75	17,5	12
BG 10	BG010_K5	40	61	81	12	10	21	M14x2	20	15
BG 25	BG025_K5	53	77	103,5	16	13	32	M20x1,5	27,5	20
BG 50	BG050_K5	73	110	146,5	22	19	41	M30x2	37	30
BG 100	BG100_K5	82	125	166	25	21	50	M36x3	42	35
BG 150	BG150_K5	102	145	196	32	27	60	M42x3	52	45

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

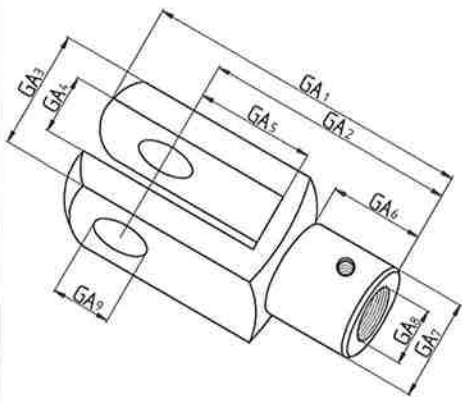




# Spindle gear accessories

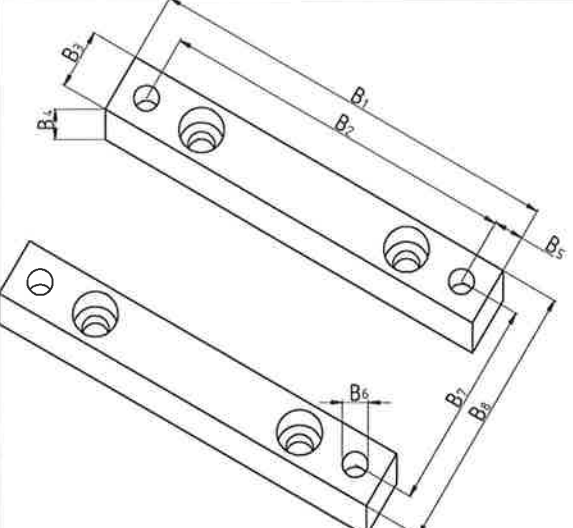
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## Fork head (GA)



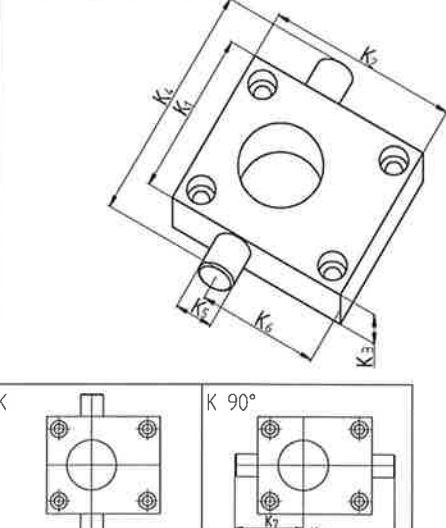
Sizes	Icon	measurement in mm								
		GA <sub>1</sub>	GA <sub>2</sub>	GA <sub>3</sub>	GA <sub>4</sub>	GA <sub>5</sub>	GA <sub>6</sub>	GA <sub>7</sub>	GA <sub>8</sub>	GA <sub>9</sub> H8
BG 2,5	BG002,5_K6	42	32	16	8	16	12	14	M8	8
BG 5	BG005_K6	62	48	24	12	24	18	20	M12	12
BG 10	BG010_K6	72	56	27	14	28	22,5	24	M14	14
BG 25	BG025_K6	105	80	40	20	40	30	34	M20	20
BG 50	BG050_K6	148	110	60	30	60	40	48	M30	30
BG 100	BG100_K6	188	144	72	36	72	54	60	M36	36
BG 150	BG150_K6	--	--	--	--	--	--	--	--	--

## Fastening strips (BL)



Sizes	Icon	measurement in mm							
		B <sub>1</sub>	B <sub>2</sub>	B <sub>3</sub>	B <sub>4</sub>	B <sub>5</sub>	B <sub>6</sub>	B <sub>7</sub>	B <sub>8</sub>
BG 2,5	BG002,5_BL	90	75	12	10	7,5	6,5	38	50
BG 5	BG005_BL	120	100	20	10	10	8,5	52	72
BG 10	BG010_BL	140	120	20	10	10	8,5	63	85
BG 25	BG025_BL	170	150	25	12	10	11	81	105
BG 50	BG050_BL	230	204	30	16	13	13,5	115	145
BG 100	BG100_BL	270	236	40	25	17	22	131	171
BG 150	BG150_BL	290	250	50	30	20	26	155	205

## Cardan plate (K)



Sizes	Icon	measurement in mm						K 90° turned	
		K <sub>1</sub>	K <sub>2</sub>	K <sub>3</sub>	K <sub>4</sub>	K <sub>5</sub>	K <sub>6</sub>	K <sub>4</sub>	K <sub>7</sub>
BG 2,5	BG002,5_KAR	50	60	15	70	10	38	80	32
BG 5	BG005_KAR	72	80	20	102	15	49	110	46
BG 10	BG010_KAR	85	100	25	125	20	60	140	60
BG 25	BG025_KAR	105	130	30	145	25	76	170	74
BG 50	BG050_KAR	145	180	40	205	35	102	240	108
BG 100	BG100_KAR	165	200	50	235	45	117	270	118
BG 150	BG150_KAR	195	210	60	275	50	120	290	130

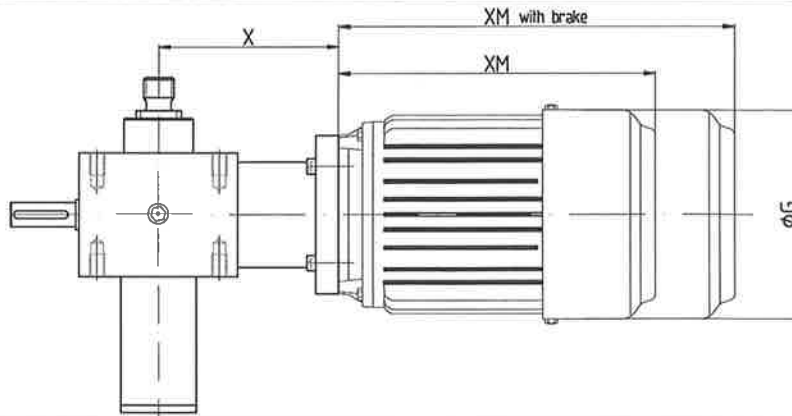
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 Subjects to measurements changes, representation not obligatory



# Spindle gear accessories

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## Spindle gear with elastic coupling and motor



Sizes		motortype	IEC-flange			motor shaft	X	XM	XM with brake	ØG
			φA	φB	φE					
BG 2,5	BG002,5_Flan80	56	80	50	65	φ9x20	79,5	167	--	110
	BG002,5_Flan90	63	90	60	75	φ11x23	82,5	180	231	118
BG 5	BG005_Flan90	63	90	60	75	φ11x23	96,5	180	231	118
	BG005_Flan105	71	105	70	85	φ14x30	103,5	210	262	139
BG 10	BG010_Flan90	63	90	60	75	φ11x23	106,5	180	231	118
	BG010_Flan105	71	105	70	85	φ14x30	113,5	210	262	139
	BG010_Flan120	80	120	80	100	φ19x40	126,5	233	288	156
BG 25	BG025_Flan105	71	105	70	85	φ14x30	144	210	262	139
	BG025_Flan120	80	120	80	100	φ19x40	154	233	288	156
BG 50	BG050_Flan120	80	120	80	100	φ19x40	176,5	233	288	156
	BG050_Flan140	90	140	95	115	φ24x50	186,5	281	356	165
	BG050_Flan160	100	160	110	130	φ28x60	198,5	312	390	196
BG 100	BG100_Flan120	80	120	80	100	φ19x40	206,5	233	288	156
	BG100_Flan140	90	140	95	115	φ24x50	216,5	281	356	165
	BG100_Flan160	112	160	110	130	φ28x60	228,5	371	458	220
BG 150	BG150_Flan160	100	160	110	130	φ28x60	241	312	390	196
	BG150_Flan160	112	160	110	130	φ28x60	241	371	458	220
	BG150_Flan200	132	200	130	165	φ38x80	263	416	522	259

### Crank handles

Ch 1			
BG	5	10	25
a F 7	10	14	16
b P 9	3	5	5
c	11,4	16,3	18,3
d	28	38	38
h1	28	38	38
h2	13	14	14
h3	48	65	65
l	100	160	160

Ch 2			
BG	50	100	150
a F 7	20	25	25
b P 9	6	8	8
c	22,8	27,3	28,3

Dimensional variations according to DIN 7168 medium. Deviating dimensions on request.

### Hand wheels

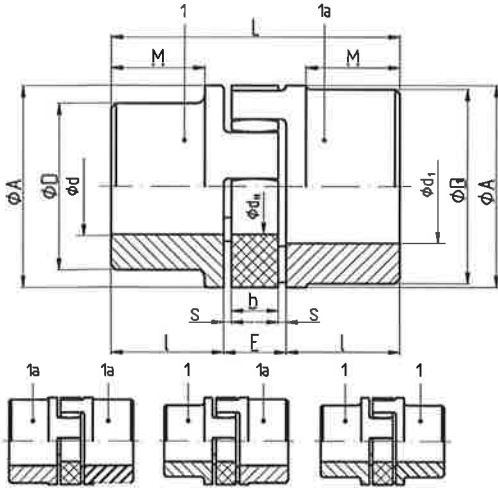
type	d	N	b	n	L	G	D	Pkt. gw B 97	Weight kg
BG 5	80	26	13,0	16	30	58,5	22	10	0,16
BG 10	125	31	15,0	18	34	67,5	23	14	1,3
BG 25	160	36	18,0	20	37	67,5	23	14	1,5
BG 50, 100	200	42	20,5	24	45	80,0	26	18	1,0
BG 100, 150	250	48	23,0	28	51	90,0	28	24	1,3



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## Elastic couplings (KU)



Finish-borings are made according to the ISO system of tolerances H7. Feather key grooves are made according to DIN 6885/1. The max. angle shift is 1°30', the twisting angle 3,2° at M1 nom. The operable temperature range lies between -40°C and +100°C.

Type R	M1 nom in Nm at 80° Shore <sup>1)</sup>	M1 nom in Nm at 92° Shore <sup>1)</sup>	M1 nom in Nm at 98° Shore <sup>1)</sup>	pilot drill	hub 1 finished phi d	holes	hub 1a finished phi d1	phi A	phi D	phi D	L	L	E	s	b	M	phi d	material	weight <sup>2)</sup> type 1 in kg	weight <sup>2)</sup> type 1a in kg	
14	4	7	12	-	4	14	-	30	30	-	35	11	13	1,5	10	-	10	GG	0,14	0,14	
19/24	5	10	17	4	6	19	-	6	24	40	32	40	66	25	16	2	12	-	18	0,32	0,36
24/28	17	35	60	6	8	24	6	8	28	55	40	48	78	30	18	2	14	24	27	0,60	0,72
28/38	46	95	160	8	10	28	8	10	38	65	48	65	90	35	20	2,5	15	28	30	0,97	1,33
38/45	93	190	325	10	12	38	36	38	45	80	66	77	114	45	24	3	18	37	38	2,08	2,46
42/55	130	265	450	12	14	42	40	42	55	95	75	94	126	50	26	3	20	40	46	3,21	3,93
48/60	150	310	525	13	15	48	46	48	60	105	85	102	140	56	28	3,5	21	45	51	4,41	5,19
55/70	180	375	625	18	20	55	52	55	70	120	98	120	160	65	30	4	22	52	60	6,64	8,10
65/75 <sup>2)</sup>	205	425	640	20	22	65	63	65	75	135	115	135	185	75	35	4,5	26	61	68	10,13	11,65
75/90 <sup>2)</sup>	475	975	1465	28	30	75	73	75	90	160	135	160	210	85	40	5	30	69	80	16,03	19,43

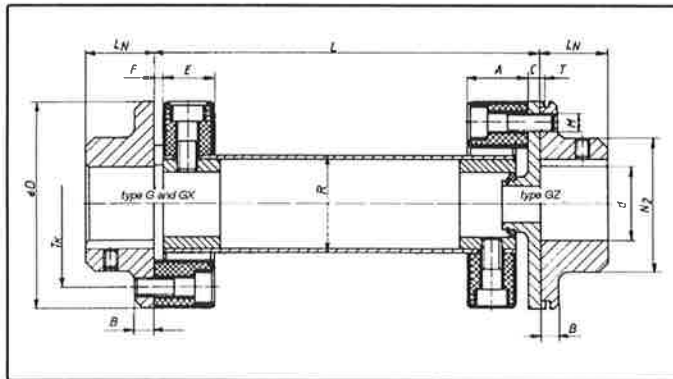
<sup>1)</sup> The rated turning moments are valid for normal operation with slight jolts; due to the higher start-up moment of three-phase squirrel cage motors an infact factor of 2 must be taken into account.

<sup>2)</sup> from size 65/75 95° Shore on

<sup>3)</sup> weight for GG, aluminium approx. 60% less.

Product as delivered: enclosed

## Elastic propeller shafts G/GX/GZ

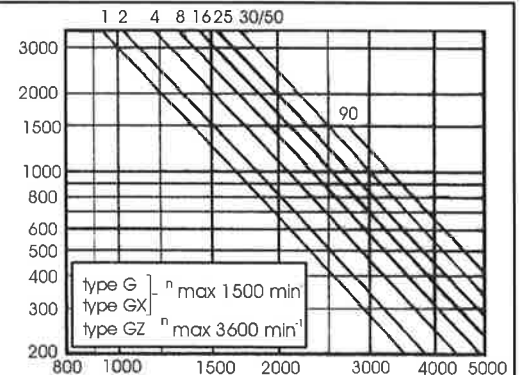


RPM - length - diagramm:

Selection chart for sizes according to RPM and length of joint

RPM n (min<sup>-1</sup>)

length L (mm)



size	rated torque [Nm] type			weight [kg]		max. shift of angle		A	B	C	ø D	d	d max	E	F	L <sub>11</sub>	ø N <sub>11</sub>	R	T	T <sub>r</sub> / M
	G	GX	GZ	for 2 hubs	for 1 m tube	G+GX	GZ													
1	10	10	10	1,0	1,1	3°	1°	24	7	5	56	8	25	22	2	24	36	30	1,5	ø 44 / 2 x M6
2	20	30	20	2,2	1,4	3°	1°	24	8	5	85	12	38	20	4	28	55	40	1,5	ø 68 / 2 x M8
4	40	60	40	3,4	1,6	3°	1°	28	8	5	100	15	45	24	4	30	65	45	1,5	ø 80 / 3 x M8
8	80	120	80	7,3	2,2	3°	1°	32	10	5	120	18	55	28	4	42	80	60	1,5	ø 100 / 3 x M10
16	160	240	160	12,4	2,5	3°	1°	42	12	5	150	20	70	36	6	50	100	70	1,5	ø 125 / 3 x M12
25	250	370	250	19,1	3,1	3°	1°	46	14	5	170	20	85	40	6	55	115	85	1,5	ø 140 / 3 x M14
30	400	550	400	31,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	ø 165 / 3 x M16
50	600	-	600	32,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	ø 165 / 3 x M16
90	900	-	900	58,7	7,6	3°	1°	70	19	5	260	30	110	62	8	80	160	125	2,0	ø 215 / 3 x M20

Special executions on request are possible  
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## Limit stop (EA)

type about

type below

	A	B	Limit switch type	S1
BG2,5	32	stroke+80	current max. at voltage	250V 0,25A 120V 0,5A 24V 7A
BG5	32	stroke+80		
BG10	38	stroke+85		
BG25	43	stroke+100	type of connection	binding posts
BG50	52	stroke+100		
BG100	60	stroke+110		
BG150	60	stroke+110	setting range E	±10
temperature min/max				-10°C +80°C
system of protection				IP 65
type of switch				mech.

Limit switches must be adjusted in situ!  
Product as delivered: enclosed

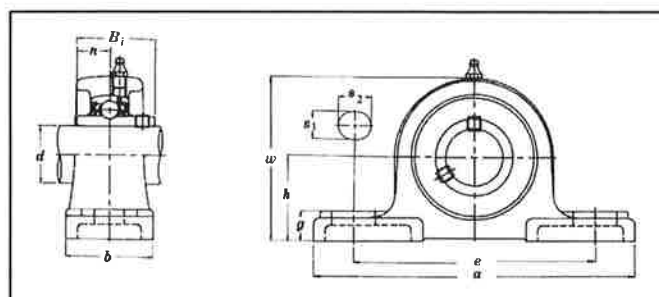
## Safety nuts

Connected with the loaded traveling nut via driving pins, the locking nut runs at idle. As the threads in the traveling nut wear it approaches the idling, unloaded and therefore unworn safety nut. The wear is ascertained by checking the slot H. When the table entry H has declined by half the traveling nut must be replaced!

The visual check of the slot H can be automated by integrating an automatic disconnecting limit switch which is actuated when the raveling nut sinks.

Standard sheet on request.  
Product as delivered: enclosed

## Pedestal bearing



Typ	ø d (mm)	Dimensions (mm)									Bolt Used (mm)	Weight (kg)
		h	a	e	b	s <sub>2</sub>	s <sub>1</sub>	g	w	n		
UCP 206	25	36,5	140	105	38	19	13	13	71	14,3	10	0,8
UCP 206	30	42,9	165	121	48	21	17	15	84	15,9	14	1,3
UCP 207	35	47,6	167	127	48	21	17	16	93	17,6	14	1,6
UCP 208	40	49,2	184	137	64	21	17	17	98	19,0	14	2,0
UCP 209	46	54,0	190	146	64	21	17	17	106	19,0	14	2,2
UCP 210	50	57,2	206	159	60	22	20	19	113	19,0	16	2,9
UCP 212	60	69,8	241	184	70	25	20	22	138	25,4	16	4,9
UCP 214	70	79,4	266	210	72	30	25	28	156	30,2	20	6,8
UCP 216	80	88,9	292	232	78	35	25	32	174	33,3	20	9,0
UCP 217	86	95,2	310	247	83	40	25	32	185	34,1	20	10,8

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# Mounting and Maintenance Instructions for Spindle gear BG2,5 - BG150

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## Mounting

Spindle gears must be mounted in true alignment on a flat surface which must be so stiff that it can assume the maximal load without oscillations or deformations. The alignment and correct positioning of the spindle gear must be done very carefully as no side forces should act on spindle and guide rings.

In lifting systems the spindle noses (in case of the basic type) or the traveling nuts (in case of the traveling nut type) must lie level with each other before the worms of the spindle gears are connected.

Before the driving gear is mounted the sense of rotation must be checked: in bevel gear driven lifting systems the sense of rotation can easily be confused; the result would be faulty mounting and possible damage of the installation.

Before putting it into service the spindle gear or the lifting system should be turned by hand once. If this requires non uniform forces the spindles are misaligned both to each other and to the installation. Adjustments are necessary; the fastening screws must be worked loose and the whole lifting gear must again be turned by hand. Spindles must be lubricated before being put into service; they are delivered non-greased!

Oil-lubricated worm gears: the upper screwed sealing plug must be replaced by the vent screw provided.

Attention! Misalignment and faulty gripping lead to increased power consumption, which is converted into friction and noise. The consequence is quick wear.

Additional add-on pieces: check under "Options".

If our specifications and performances according to the technical instructions are not observed and/or the components are not used as prescribed, any warranty claims will no longer be applicable.

## Maintenance

Greases spindle and worm gear via lubricating nipple at regular intervals (~30-50 operating hours), clean and lubricate the spindle at the same time. The intervals depend on the given operating conditions and the duty cycle of the spindle gears. In case doubt please set up the lubrication plan together with us. The use of spindle spray increases the working life of the spindle and spindle nut. After approx. 200-300 operating hours the wear of the traveling nut or the worm wheel due to the backlash of threads should be checked. The maximal normal backlash of single trapezoid threads must not exceed 1/4 of the thread pitch. In the cases of multiple threads or special threads 1/4 of P is the maximum normal acceptable backlash. When the maximum normal backlash is reached the traveling nut or the worm wheel must be replaced. After a short run-in period all screws must be checked.

After approx. 500 operating hours we recommend cleaning gear and spindle to remove the grease, checking all piece parts as to wear, and recharging them with new grease.

Recommended lubricants: Shell Darina 2, Castrol Grease MS3, BP Energrease LS-EP2.

The lubricant recommended can be used both for gears and spindles. If a high-grade spindle lubricant is to be used, we recommend Klueberplex GE 11-680.

For special conditions (e.g. higher temperatures) we recommend the lubricants specified in the enclosed technical manual.

In case of possible dirt accumulation in or damage of the spindle, expansion bellows or spring steel spirals must be used to protect the spindle. For oil-lubricated gears please ask for a special service manual.

If you order spare parts the gear specifications marked on the type plate must be provided.



# Critical compressive force

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Slender spindles subjected to compression are liable to buckle laterally. Before defining the permissible compressive force acting on the spindle the safety factors applying to the lifting equipment must be taken into account.

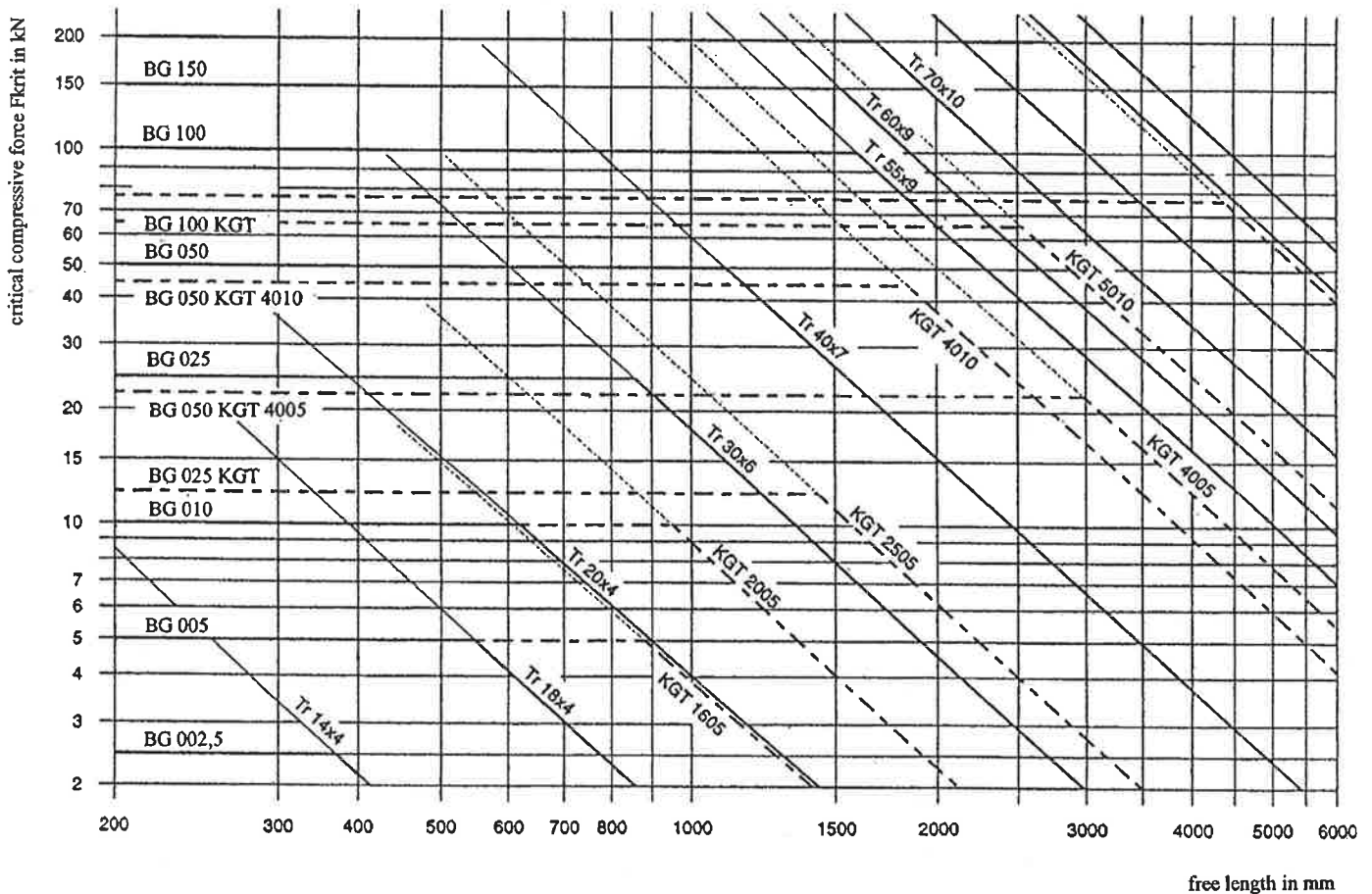
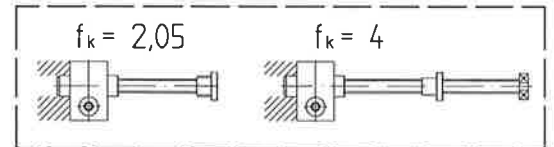
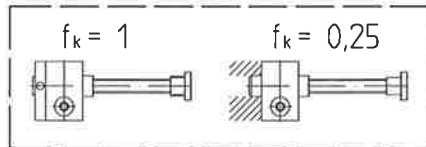
$F$  (kN) = axial force

$f_k$  = correction facto taking into account type of spindle bearing arrangement

$F_{krit}$  (kN) = critical compressive force depending on free length  $L$ .

$s$  = safety factor depends one use usual values between 3 and 6

$$F \leq f_k \times F_{krit} \times \frac{1}{s}$$



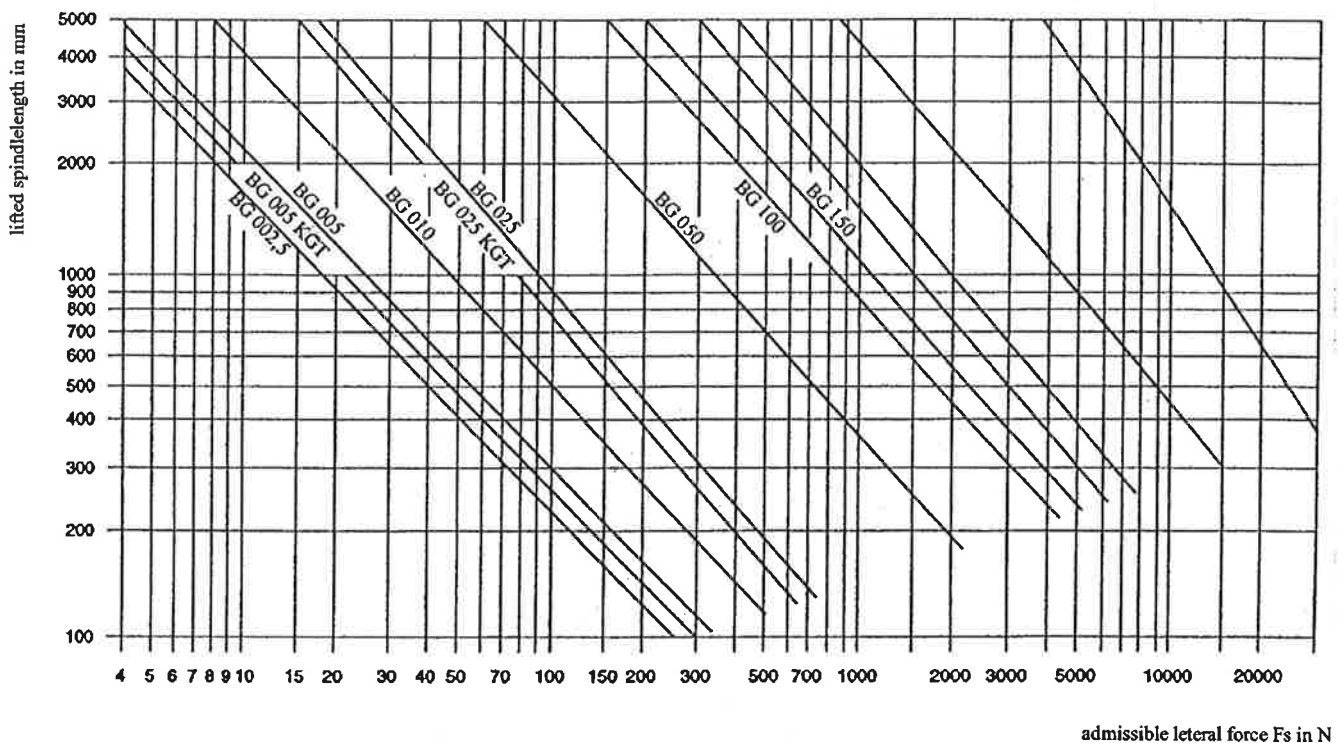


# Additional forces acting on the spindle gear

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## Lateral forces

When determining the lateral force acting on the spindle, possible forces resulting from the spindle moment  $M_{sp}$  and, if the spindle is mounted horizontally, the dead weight must be taken into account. The diagram below illustrates the maximum permissible lateral force  $F_s$  depending on the free spindle length without any additional lateral guide.



## Spindle torque

The Spindle torque  $M_{sp}$  is the torque acting on the various parts of the equipment via the spindle ends 3,4,6 or the running nut. The spindle torque can be calculated using the factor  $f_M$  in the table below.

$F$  (kN) = axial force

$f_M$  = conversion factor including screw geometry and friction.

$M$  (Nm) = torque of the elevating screw

The lower value applies under normal lubrication conditions, the higher value in case of dry friction and static friction.

$$F \times f_M = M_{sp}$$

	BG 2,5	BG 5	BG 10	BG 25	BG 50	BG 100	BG 150
$f_M$	1,1.....2,6	1,5.....3,1	1,6.....3,4	2,4.....5,1	3,0.....6,8	4,0.....9,3	4,3.....10,1



## Additional forces acting on the spindle gear

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### Maximum driving torque

If the spindle gear is locking due to an obstacle, the maximum torques illustrated in Table 1 can still be picked up by the toothing at the transmission shaft.

In elevating equipment with serial spindle elevating gears the spindle gear next to the drive can transmit this moment via the transmission shaft.

	BG 2,5	BG 5	BG 10	BG 25	BG 50	BG 100	BG 150
$M_{T \max}$ (Nm)	1,5	3,4	7,1	18	38	93	148

Tab. 1

### Forces and moments acting on the transmission shaft

If the spindle gears are driven via belts or chains, care must be taken to ensure that the arising thrust force is kept at a tolerable level. This thrust force is caused by the fact that the equipment is driven via a clutch not free from lateral force.

In this case Table 2 applies

In the worst case quick wear may occur, due to bending of the worm shaft the worm may be lifted from the worm wheel, which must be avoided.

	BG 2,5	BG 5	BG 10	BG 25	BG 50	BG 100	BG 150
$F_{r \max}$ (kN)	0,07	0,1	0,2	0,3	0,5	0,8	0,8

Tab. 2

### Required speed of the driving motor

The required speed of the driving motor is calculated from the proposed elevating speed, spindle gear ratio and the gear ratio of the transmission elements (e.g. bevel gears).

There may be several possibilities to reach a specific elevating speed.

### Choosing the driving motor

By determining the driving torque and choosing the speed the driving motor can be defined.

After choosing the driving motor the elevating equipment must be tested to avoid overload of the spindle gears or the transmission elements.

In elevating equipment with several spindle lifting gears uneven loading of the individual spindle gears may lead to overstrain.

To avoid this, elevating equipment should be protected with safety switches or torque-limited clutches.

Also, spindle gears should not be subjected to excessive vibration because the function of the automatic lock may no longer be guaranteed in such case. To avoid accidents brakes or brake motors should be integrated in the elevating equipment.





# Additional forces acting on the spindle gear

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## Required driving torque of a spindle gear

The required driving torque of a spindle gear is calculated from the axial load resting on the spindle, the transmission and the efficiency. Please bear in mind that the starting moment may be higher than the moment required during operation.

This applies particularly to spindle gears after a long standstill and to low-efficiency gears.

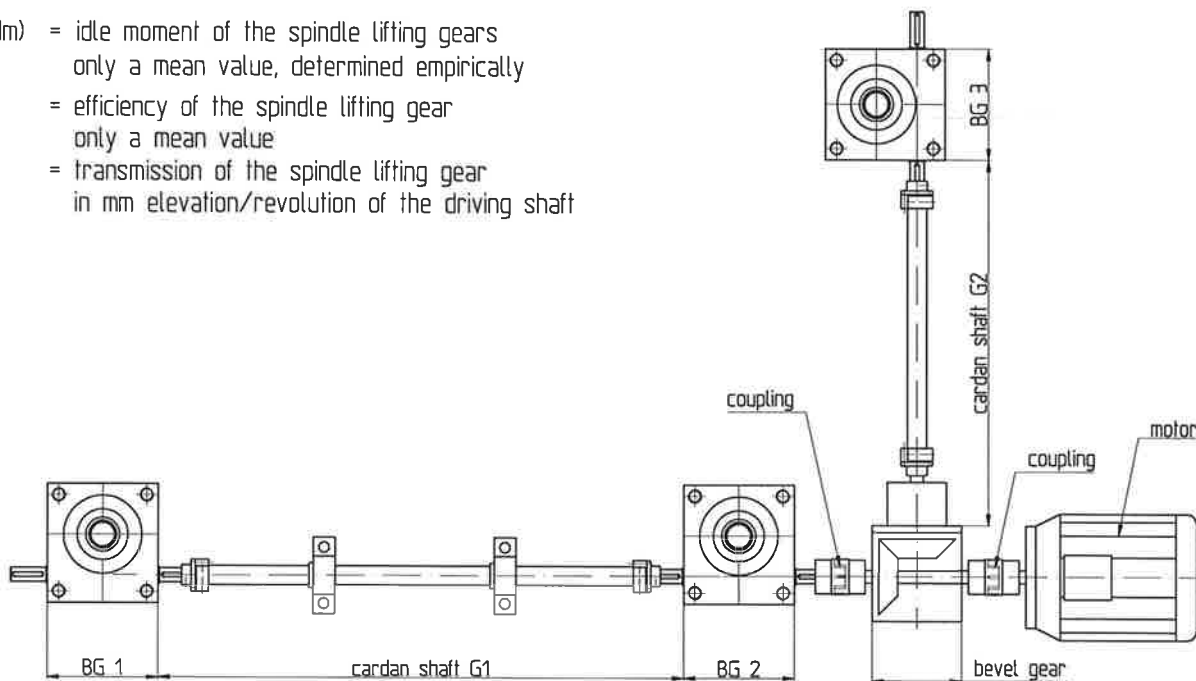
## Required driving torque of spindle elevating equipment

The required driving torque of spindle elevating equipment is calculated from the driving torques of the individual spindle gears, taking the arising friction losses in the transmission elements (clutches, propeller shaft, bevel gears,...) into account.

It is helpful illustrate the flux of forces in a sketch.

- F (kN) = axial force
- $M_T$  (Nm) = required driving torque of the spindle lifting gear at the driving shaft
- $M_0$  (Nm) = idle moment of the spindle lifting gears only a mean value, determined empirically
- $\eta$  = efficiency of the spindle lifting gear only a mean value
- $\frac{P}{I}$  = transmission of the spindle lifting gear in mm elevation/revolution of the driving shaft

$$M_T = \frac{F}{2 \times \pi \times \eta_{G1}} \times \frac{P}{I} + M_0$$



$$M_{\text{driving motor}} = M_{T \text{ BG1}} \times \frac{1}{\eta_{G1}} + M_{T \text{ BG2}} + M_{T \text{ BG3}} \times \frac{1}{\eta_{G2}} \times \frac{1}{\eta_K}$$

$M_{T \text{ BG1}}$  = required driving torque spindle gear

$\eta_{G1}$  = efficiency cardan shaft G1. Value around 0,75 to 0,95 depending on the number of pedestal bearings

$\eta_K$  = efficiency bevel gear (only in case of flux via toothing, here between cardan shaft G1 and motor) value around 0,9



Questionnaire

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COMPANY.....
ADDRESS.....
NAME..... Dept..... Phone..... Fax.....

To be able to prepare a proposal meeting your specific demands, please provide us with the following information:

In which systems are the lifting elements to be used?

Number of systems.....
Number of lifting elements per system.....

AXIAL LOAD

per system pressure dynamic..... kN tension dynamic..... kN
static..... kN static..... kN
per spindle pressure dynamic..... kN tension dynamic..... kN
static..... kN static..... kN
Type of buckling load according to Euler I□, II□, III□ oder IV□

OPERATING CONDITIONS

Effective stroke..... mm
Side forces acting..... kN
Lifting speed desired..... mm/min
Mounting of spindle..... vertically/horizontally
Ambient temperature..... °C
Duty cycle/load conditions per 10min.....
per hour.....
Distance per alternation of load..... mm

FOR WHICH PARTS DO YOU WISH TO RECEIVE OUR OFFER?

Spindle lifting element with lifting spindle:

Basic type..... 0 oder U
Spindle nose..... 0/1/2/3/4/5/6

Spindle lifting element with rotating spindle and traveling nut:

Travling nut type..... 0 oder U
Spindle nose..... 0/1/2

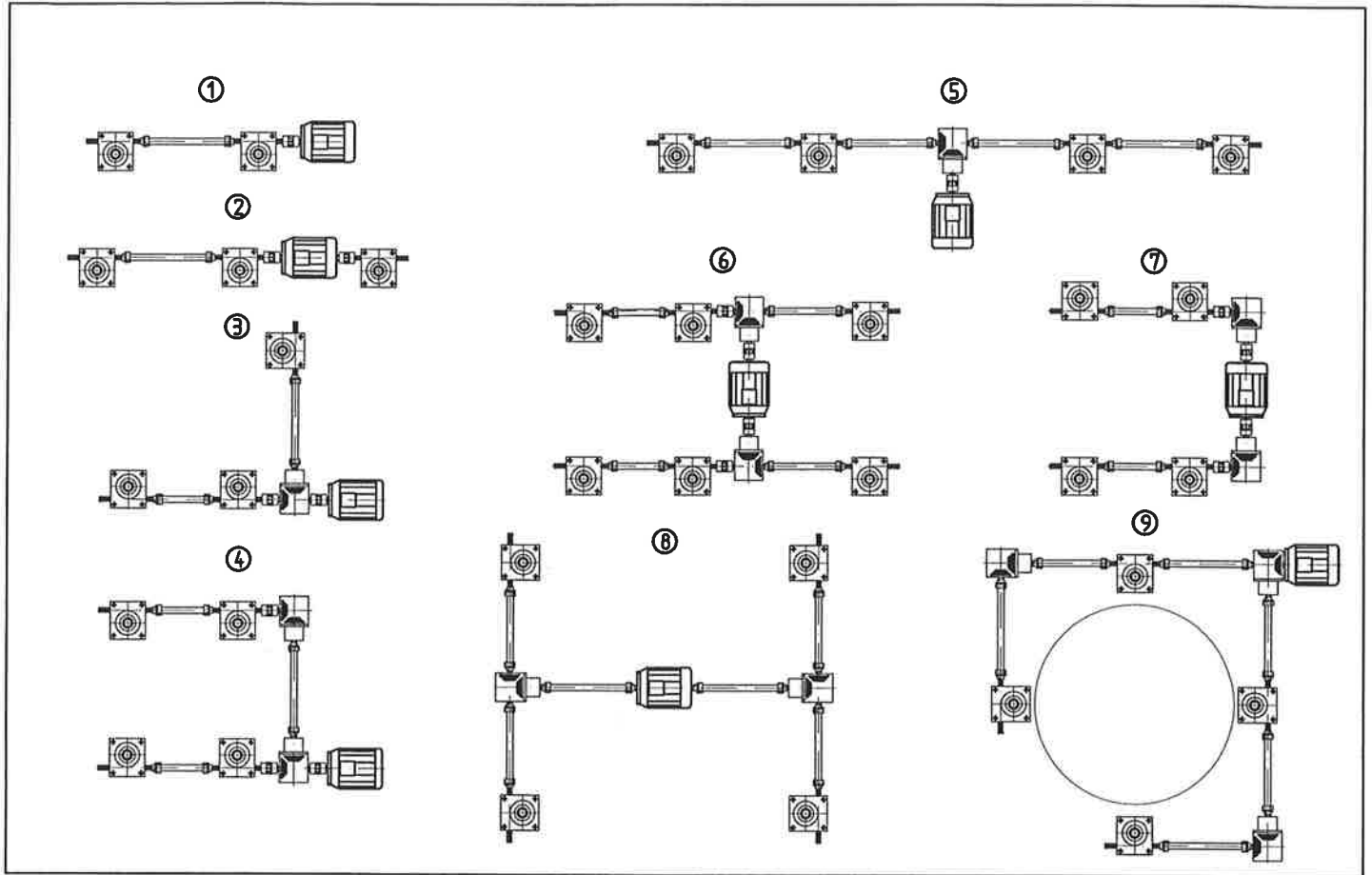
Expansion bellows..... yes/no
Bevel gear box..... yes/no
Elastic cardan shafts..... yes/no
Couplings..... yes/no
Pedestal bearings..... yes/no
Motor; voltage..... frequency..... system of protection.....
Limit stop..... yes/no
Crank handle, handwheel..... yes/no
Fastening strips..... yes/no
Cardan plate..... yes/no
Safety nut..... yes/no
Other.....



# Examples for arrangements

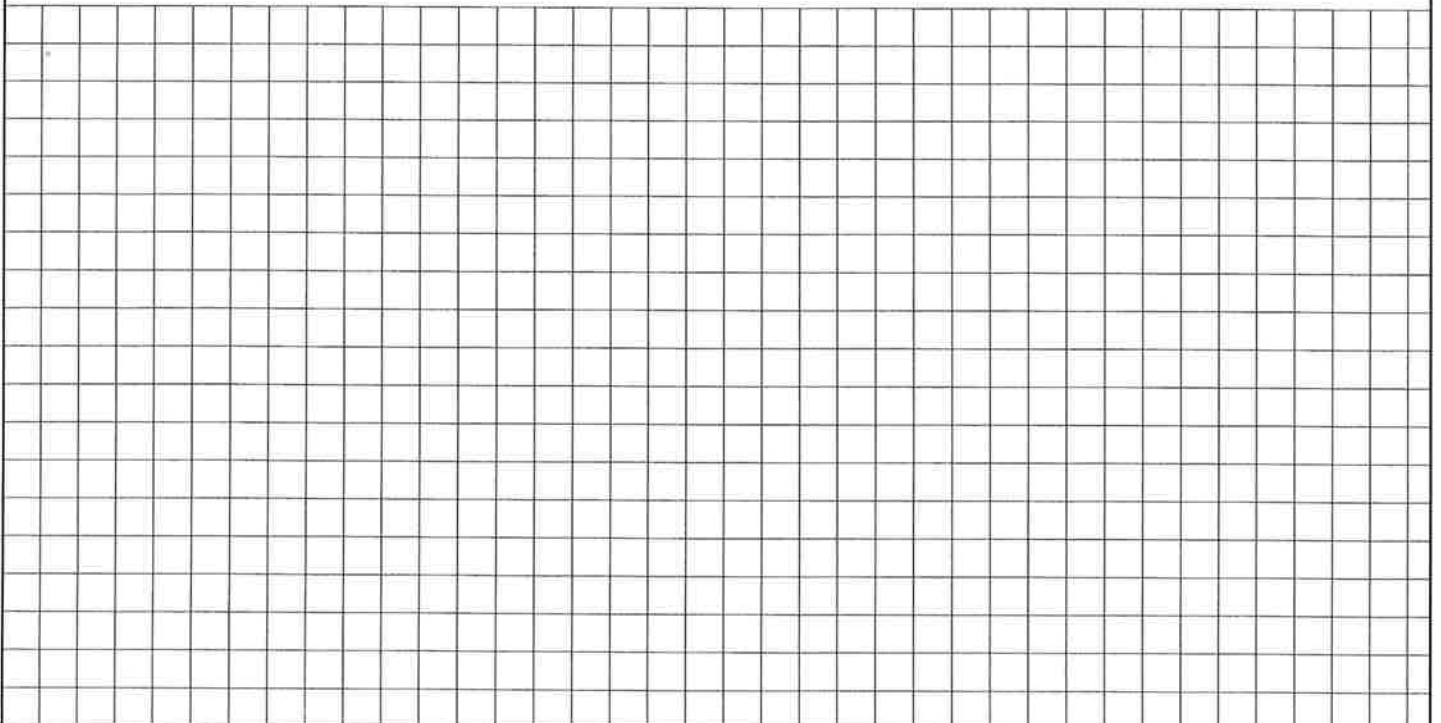
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Please provide us with a sketch on the desired arrangement as shown above or according to your own ideas.  
Please enter the distance from spindle to spindle and possibly lateral guidings into the sketch.  
If you wish to receive an offer on spindle lifting elements actuated by multi-thread spindles or ball screw spindles,  
or if stainless material is desired, please let us know, too.

## Sketch

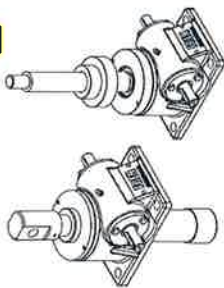


# Product overview 03/2015

Eichergasse 36, A-2551 Enzelsfeld, Tel.: +43 (0) 2256 81287 - 00, Fax: +43 (0) 2256 81287 - 95, office@entzfelder.at, www.entzfelder.at

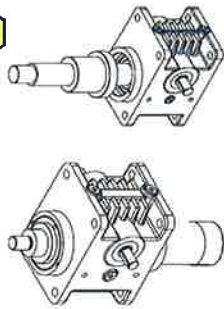
**SG**

Screw jack  
Classic



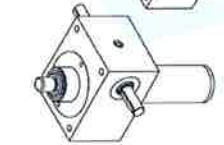
**HSG**

High performance-  
Screw jack



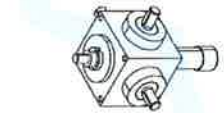
**BG**

Screw jack  
Cubic



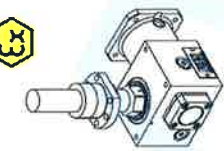
**SHG**

Quick-lifting  
screw jack



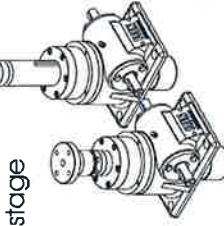
**SH**

Servo lifting  
gear



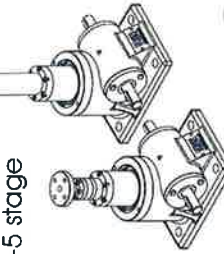
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



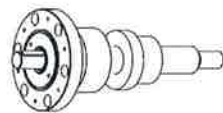
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



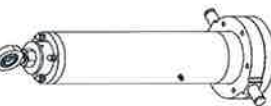
**SLA**

Spindlebearing



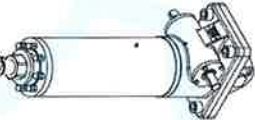
**SEZ**

Spindlebearings-  
Cylinder



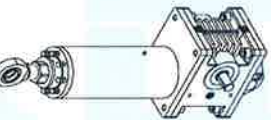
**ELZ**

Electric cylinder



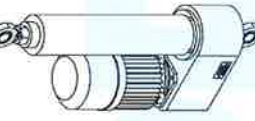
**HELZ**

High performance-  
Electric cylinder



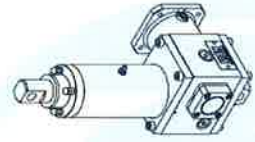
**ELZP**

Electric cylinder  
Parallel



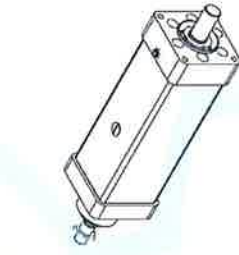
**SHELZ**

Servo electric-  
cylinder



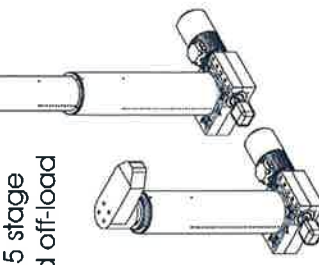
**EPNEU**

Spindle-  
Electric cylinder



**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



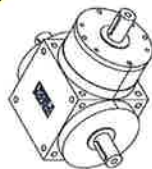
**K**

Bevel gear  
Type K



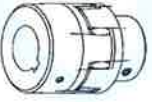
**H**

Bevel gear  
Type H



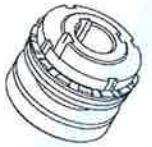
**R / GS**

Elastic / backlash-free  
Coupling



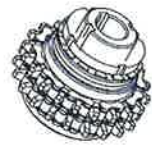
**RT**

Slip hub



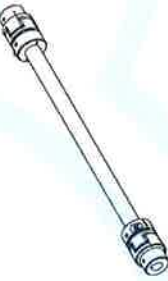
**RK**

Slip coupling



**ZR**

FREN  
Connecting shaft



**G / GX**

Elastic  
Connecting shaft

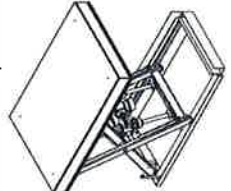


Cardan shaft



**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



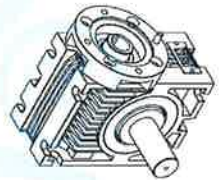
**PLG**

Planetary gear



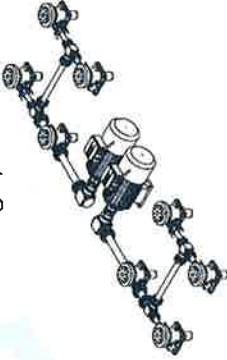
**uniCe**

Worm gear



**HA**

Lifting system



**Special gear**

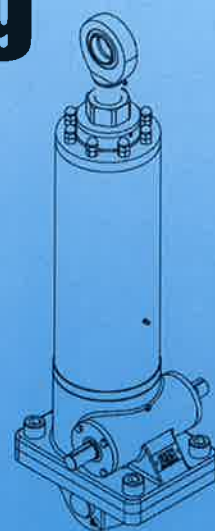




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**Electric cylinder  
Type ELZ**



# History

**1969** Mr. Enzfelder established a job shop in Vienna. Equipped with some machinery, the Enzfelder Company manufactured machine parts according to drawings.

Within one year the number of employees rose to 3. The Enzfelder company started manufacturing threaded spindles and nuts according to drawings. Then the range of manufacturing was enlarged by toothed wheels, screw wheels and endless screws according to drawings.

**1974** The company including the complete manufacture was relocated to Enzesfeld.

**1975** The manufacture of spindle gears was launched. The company's experience in the manufacture of trapezoid-threaded spindles, nuts, worm gear pairs and casings was a valuable basis for the construction. After many tests, the serial production of spindle gears was launched one year later. The result was a product characterized by a first-rate price-performance ratio. The product was distributed by dealers all over Europe.

**1981** The planning and construction of small hydropower plants was launched to replace diesel generators. Environmental protection was not really a topic at that time, however, and the production was stopped in 1986.

**1989** The Enzfelder GesmbH company replaced the Franz Enzfelder Company.

**1990** Scissor-type lifting platforms and cable winches were added to the delivery program.

**1991** Resilient spacer shafts were tested and added to the production range. At the same time, the telescopic spindle gear was developed. A patent for this principle was applied for and issued.

**1993** The sale of spindle gears under their own name was launched and presented for the first time at the Hannover industrial fair. We have been approached with a variety of tasks and have provided solutions according to the customers' needs ever since.

**1994** In cooperation with our customers we produced the first bevel gears to specification.

**1995** Spindle bearing arrangements were designed and included in the standard program.

**1996** The Enzfelder company produced planet gear to specification for the first time.

**1998-1999** The standard programs were enlarged. Additionally, bevel gears are manufactured in a standard design.

**2000** The development of electric cylinders in standard design for very high loads (5-1000kN) was started. At the same time the telescopic spindle gears were refined to save the customer the guiding and locking devices. Since that time we have been able to offer telescopic cylinders, too.

**2001** The development of electric cylinders was completed, and these cylinders were added to the standard program.

At the same time the development and fabrication of cubic spindle gears for lifting loads between 2.5 and 150kN was started. These gears were added to the standard program as well.

**2002** were extended and optimized the series of the electric cylinders. Further we provide an electronic 2D-3D product catalogue of the spindle gears, it makes it possible to integrate our products into your system.

**2002-2003** We putted our new assembling and packaging hall, beside the manufacturing hall, in operation

**2003** We increased our machinery by buying a CNC machine tool with 7 axes, brand AXA. That new CNC machine allows a precise machining of the screw jack housings in only two clamping.

**2003-2004** The engineering started to use new 3-D CAD software, Solid Edge. That software enables our customers to integrate easily our drawings.

**2004** We opened a sales office in France.

**2004-2005** We started to design the high performance screw jacks HSG and we created a range of 10 different sizes.

**2005** First participation to an exhibition in France: INDUSTRIE 2005 at Lyon.

**2005-2006** We started to design a new range of telescopic screw jacks TSGLR. Today, these new telescopic screw jacks, with a more compact design, are used in the stage industry, in the aircraft industry, on train lifting equipments and in machine building.

**2008** We replaced the tread grinding machine by a new CNC thread grinding machine, brand Mikromat.

**2008-2009** transmission program is certified to ATEX

**2009-2010** beginning of the series production of Quick-lifting screw jacks SHG

**2010** Development of the transmission range Servo lifting gear (backlash & game adjustable)

Expand our global market with traders in Australia

**2011** development Servo lifting electric cylinder SHELZ (Servo lifting gear with cylindrical structure) and the beginning of the ELZP Series Electric cylinders parallel for Industry sector applications.

**2012** acquisition of the product group UniCe worm gear, helical worm geared motors, couplings, torque limiters and slip clutches. Expansion screw jacks cubic BG up to size for 1000kN

**2013-2014** revision of the telescopic spindle cylinder TSGZ the new cost-optimized design.

Development of product group Electric PNEU, electric cylinder with ball screw, stainless version in hygienically optimized design with mounting dimensions, speeds and forces such as pneumatic cylinder.

**2014** first Quick-lifting screw jacks with cylindrical structure can be delivered SHGZ = Quick-lifting electric cylinder

In recent years, customer problems are solved in the drive and lifting technology from us. Depending on the application, we developed the optimal solution and made with the best possible price / performance ratio.



# Content of Catalog

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering  
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## Product information

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

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FREN Electric cylinders are an advancement of our standard program. By thought construction is an electrical cylinder in the situation also components out to be taken up. The lift link inside electrical cylinders is protected by the tubing system from any damage by environmental influences and is approximately to rotate secured.

In the FREN Electric cylinder there is a robust worm gear pair driving a trapezoid thread spindle. The gear box is made of nodular graphite cast iron 50 fit high loads and meeting high safety standards. The worm is hardened and ground and running on tapered roller bearings. The worm wheel is made of high-strength material which is particularly resistant to abrasion; it is mounted between deep groove ball thrust bearings. The thrust tube consists of steel and is outside polished and chromium plated. The spindle ends can be supplied after customer's request also stainless.

The ELZ5 to ELZ350 line ist the worm gear alternatively filled with grease or oil and the tubing system is lubricated with grease on delivery and fit for operating temperatures ranging between -30°C and +80°C. To be increased the trapezoid thread spindle is the life span additionally coated with lubricating varnish by better fail-safe characteristics to be achieved and thus. The operating factor at maximum load is 20% per hour 30% per 10 minutes.

The trapezoid thread spindles are stand single-threads double-thread three-thread and four-thread execution. For higher demands with regard to lifting speed and operating factor we use ball screw spindles. FREN Electric cylinders are fitted with blue prime coat (RAL 5012)

### **Advantages opposite hydraulic cylinders**

Exact synchronism of several lifting spindles also in case of eccentric stress

Automatic lock at standstill, consequently 100% prevention of sinking after customer's request

Synchronous actuation by motors or crank handle possible.

Precise adjustment and measuring possible

Operable in any position

Indifference to temperature over long periods

Many combinations possible thanks to standard piece parts

Large accessory assortment

High thrusts (up to 1000kN) and long strokes (up to 2500mm) feasible

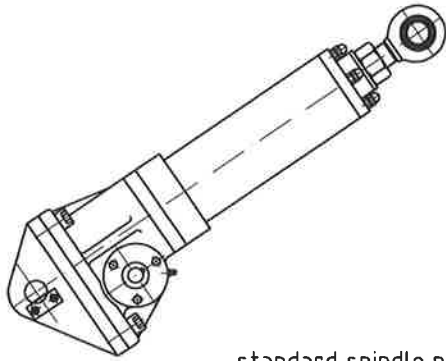
No leakages



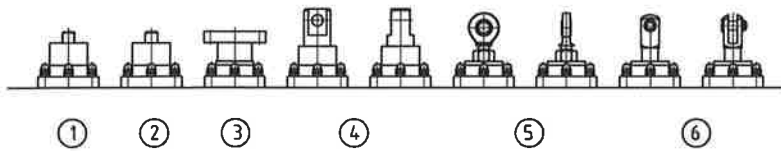
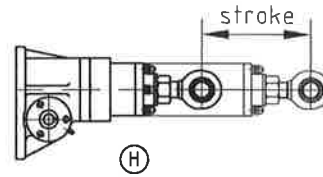
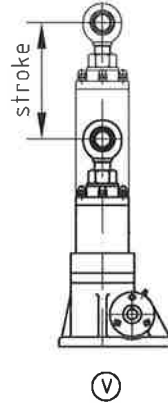


# Survey of construction modes with example for ordering

**ENZFELDER** GMBH  
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standard spindle noses



standard reductions according to preselection table page 5

type designation according to preselection page 5

Electric cylinder = ELZ

type

reduction i

spindle nose = 1,2,3,4,5,6  
 special nose = So

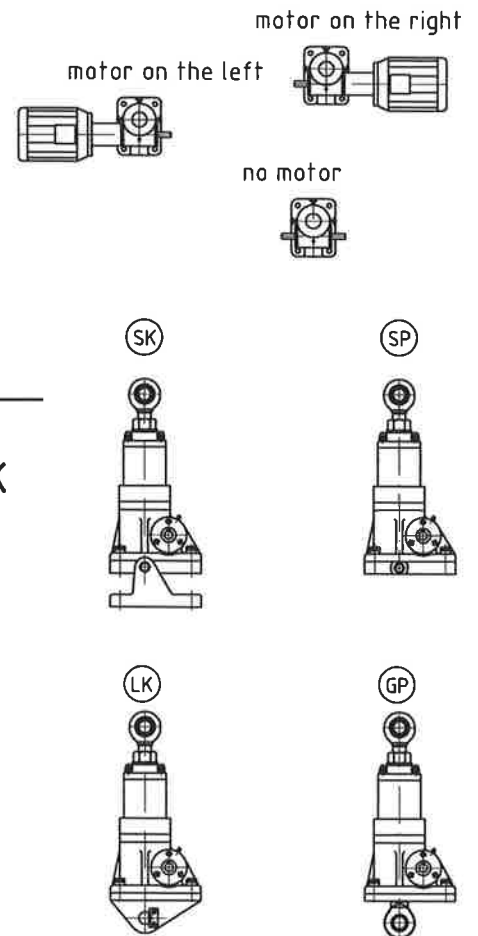
effective stroke in mm

fitting position horizontal = H  
 fitting position vertical = V

motor on the right = MR  
 motor on the left = ML  
 no motor = 00

swivelling console = SK  
 swivelling plate = SP  
 bearing console = LK  
 pivoting plate = GP

**ELZ 150 - 8 - 5 - 230 - H - MR-LK**



Above example for ordering:  
 Electric cylinder type 150, reduction 8:1, spindelnose 5, stroke 230, mounted horizontal, with motor mounted on the right and bearing console

additionally available options:

ball bearing spindle  
 limit stop  
 stainless execution  
 safty nut

three-phase A.C. motor with or without brake  
 d.c. motor  
 gear motor

impulse transmitter  
 overload clutch  
 oil lubrication

the required options must be added to the order ID or marked in the questionnaire.



# Selection of Electric cylinder with trapezoid thread spindle

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For the correct selection of spindle gears the following data are of decisive importance:

- |  |                    |  |
|--|--------------------|--|
| 1.) load   | [kN]               |  |
| 2.) lifting speed                                  | [m/min]            |  |
| 3.) operating cycle                                | [%/10min] [%/hour] |  |
| 4.) spindle length (buckling)                      | [mm]               |  |
| 5.) tensile- or pressure load                      | [kN]               |  |
| 6.) ambient temperature                            | [°C]               |  |
| 7.) fitting length (please indicate when ordering) | [mm]               |  |
| 8.) critical speed of the spindle                  | [min-1]            | If you use the questionnaire on page 33 please provide the data available. |

How to proceed in the selection: on the basis of the desired load data (in kN) a suitable type of gear is selected from the preselection table below.

Preselection Table																			
Single-thread spindle actuated Electric cylinders																			
Type	ELZ 5		ELZ 15		ELZ 30		ELZ 50		ELZ 100		ELZ 150		ELZ 200		ELZ 300		ELZ 350		
rated power kN	5		15		30		50		100		150		200		300		350		
size of spindle	Tr 20x6		Tr 24x6		Tr 30x6		Tr 40x9		Tr 55x12		Tr 60x12		Tr 65x12		Tr 90x16		Tr 100x16		
gear reduction	10:1	20:1	6:1	25:1	6:1	24:1	6:1	24:1	8:1	24:1	8:1	24:1	8:1	24:1	10 $\frac{1}{2}$ :1	32:1	10 $\frac{1}{2}$ :1	32:1	
length of stroke per rotation in mm	0,6	0,3	1	0,24	1	0,25	1,5	0,375	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	
torque at rated power Nm	1,65	1,14	7,7	3,18	17,68	7,96	39,8	17,05	88,42	44,21	143,24	77	199	22,6	311,3	170,5	397,8	214,3	
efficiency in %	29	21	31	18	27	15	30	17,5	27	18	25	15,5	24	15	23	14	21	13	
max. RPM	2800		2800		2800		1800		1800		1500		1500		1000		1000		
max. lifting speed m/min	1,68	0,84	2,8	0,67	2,8	0,7	2,7	0,67	2,25	0,75	2,25	0,75	2,25	0,75	1,5	0,5	1,5	0,5	
max. driving power in kW at 20% duty cycle	0,18		0,35		0,6		1,2		2,1		2,8		3,9		5,2		6,2		
max. driving power in kW at 10% duty cycle	0,23		0,46		0,8		1,6		2,8		3,8		5,1		6,9		8,3		
weight, ELZ excl. lifting element in kg	--		--		--		--		--		--		--		--		--		
100mm spindle in kg	0,2		0,3		0,43		0,8		1,5		1,8		2,15		4,2		5,2		
kg of grease contained in spindle gear	0,05		0,1		0,2		0,35		0,6		0,8		1,2		1,7		2,2		
catalog page	7		8		10		11		12		13		14		16		17		
Double-thread spindle actuated Electric cylinders																			
(no longer self-locking - braking motor must be used!)																			
rated power kN	4		12		24		40		80		120		150		220		280		
size of spindle	Tr 20x12P6		Tr 24x12P6		Tr 30x12P6		Tr 40x18P9		Tr 55x24P12		Tr 60x24P12		Tr 65x24P12		Tr 90x32P16		Tr 100x32P16		
length of stroke per rotation in mm	1,2	0,6	2	0,48	2	0,5	3	0,75	3	1	3	1	3	1	3	1	3	1	
max. lifting speed m/min	3,36	1,68	5,6	1,34	5,6	1,4	5,4	1,35	4,5	1,5	4,5	1,5	4,5	1,5	3	1	3	1	
torque at rated power Nm	1,96	1,32	8,9	3,53	19,6	8,3	45,5	19,1	95,5	51	159,2	83	204,6	108,52	300	159,2	417,7	222,8	
efficiency in %	39	29	43	26	39	23	42	25	40	25	36	23	35	22	35	22	32	20	

Read off the dimensioned sketch and the performance table on the corresponding page of the catalog:

- whether the dimensions of gear and spindle fit into your system.
- which gear reduction must be selected for the desired lifting speed  
(for higher lifting speeds the use of a double-thread spindle may be necessary).
- whether the power required for the desired lifting speed is admissible.
- whether under pressure load the critical buckling force is not exceeded.
- whether the critical revolutions/min of the spindle are not exceeded.
- If one of these requirements cannot be met the type next in size must be chosen.
- If point 6 is not sufficient, choose one of the types next in size or ask for special types (questionnaire see pages 33-34)!



# Selection of Electric cylinder with ball bearing spindle

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Power transmission- and lifting engineering

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For the correct selection of spindle gears the following data are of decisive importance:

- |  |                    |
|--|--------------------|
| 1.) load   | [kN]               |
| 2.) lifting speed                                  | [m/min]            |
| 3.) operating cycle                                | [%/10min] [%/hour] |
| 4.) spindle length (buckling)                      | [mm]               |
| 5.) tensile- or pressure load                      | [kN]               |
| 6.) ambient temperature                            | [°C]               |
| 7.) fitting length (please indicate when ordering) | [mm]               |
| 8.) critical speed of the spindle                  | [min-1]            |

If you use the questionnaire on page 33 please provide the data available.

How to proceed in the selection: on the basis of the desired load data (in kN) a suitable type of gear is selected from the preselection table below.

**Preselection Table**  
Electric cylinder with ball bearing spindle  
(no longer self-locking - braking motor must be used!)

Type	ELZ 5		ELZ 15		ELZ 30		ELZ 50		ELZ 100		ELZ 150		ELZ 200		ELZ 300		ELZ 350	
rated power kN	21,8		27		58		82,6		106,8		210,8		210,8		269		336	
size of spindle	KGT 2005		KGT 2505		KGT 3210		KGT 4010		KGT 5010		KGT 6310		KGT 6310		KGT 8010		KGT 10010	
gear reduction	10:1	20:1	6:1	25:1	6:1	24:1	6:1	24:1	8:1	24:1	8:1	24:1	8:1	24:1	10%:1	32:1	10%:1	32:1
length of stroke per rotation in mm	0,5	0,25	0,834	0,2	1,67	0,416	1,67	0,416	1,25	0,416	1,25	0,416	1,25	0,416	0,938	0,313	0,938	0,313
torque at rated power Nm	3,6	2,48	6,4	2,53	27,5	11,3	39,13	16,1	37,94	19,7	76,25	42,4	76,25	42,4	75,7	39,35	96,38	50,64
efficiency in %	48	35	56	34	56	34	56	34	56	36	55	33	55	35	53	34	52	33
max. RPM	3000		3000		3000		1800		1800		1500		1500		1000		1000	
max. lifting speed m/min	1,5	0,750	2,5	0,6	5	1,248	3	0,749	2,25	0,749	1,875	0,624	1,875	0,624	0,938	0,313	0,938	0,313
max. driving power in kW at 20% duty cycle	0,18		0,35		0,6		1,2		2,1		2,8		3,9		5,2		6,2	
max. driving power in kW at 10% duty cycle	0,23		0,46		0,8		1,6		2,8		3,8		5,1		6,9		8,3	
weight, ELZ excl. lifting element in kg	--		--		--		--		--		--		--		--		--	
100mm spindle in kg	0,2		0,34		0,56		0,815		1,325		2,17		2,17		3,6		4	
kg of grease contained in spindle gear	0,05		0,1		0,2		0,35		0,6		0,8		1,2		1,7		2,2	
catalog page	7		8		10		11		12		13		14		16		17	

**Electric cylinder with ball bearing spindle**  
(no longer self-locking - braking motor must be used!)

rated power kN	14,6		27		26,8		36,4		76		250		250		322		478	
size of spindle	KGT 2006		KGT 2510		KGT 3220		KGT 4020		KGT 5020		KGT 6320		KGT 6320		KGT 8020		KGT 10020	
length of stroke per rotation in mm	0,6	0,3	1,67	0,4	3,33	0,833	3,33	0,833	2,5	0,833	2,5	0,833	2,5	0,833	1,875	0,625	1,875	0,625
max. lifting speed m/min	1,8	0,9	5	1,2	10	2,5	6	1,5	4,5	1,5	3,75	1,25	3,75	1,25	1,875	0,625	1,875	0,625
torque at rated power Nm	2,9	2	12,8	5,1	25,4	10,45	34,5	14,2	54	28	180,86	100,48	180,86	100,48	181,25	94,2	274,23	144,08
efficiency in %	48	35	56	34	56	34	56	34	56	36	55	33	55	35	53	34	52	33

Read off the dimensioned sketch and the performance table on the corresponding page of the catalog:

- whether the dimensions of gear and spindle fit into your system.
- which gear reduction must be selected for the desired lifting speed  
(for higher lifting speeds the use of a double-thread spindle may be necessary).
- whether the power required for the desired lifting speed is admissible.
- whether under pressure load the critical buckling force is not exceeded.
- whether the critical revolutions/min of the spindle are not exceeded.
- If one of these requirements cannot be met the type next in size must be chosen.
- If point 6 is not sufficient, choose one of the types next in size or ask for special types (questionnaire see pages 33-34)!

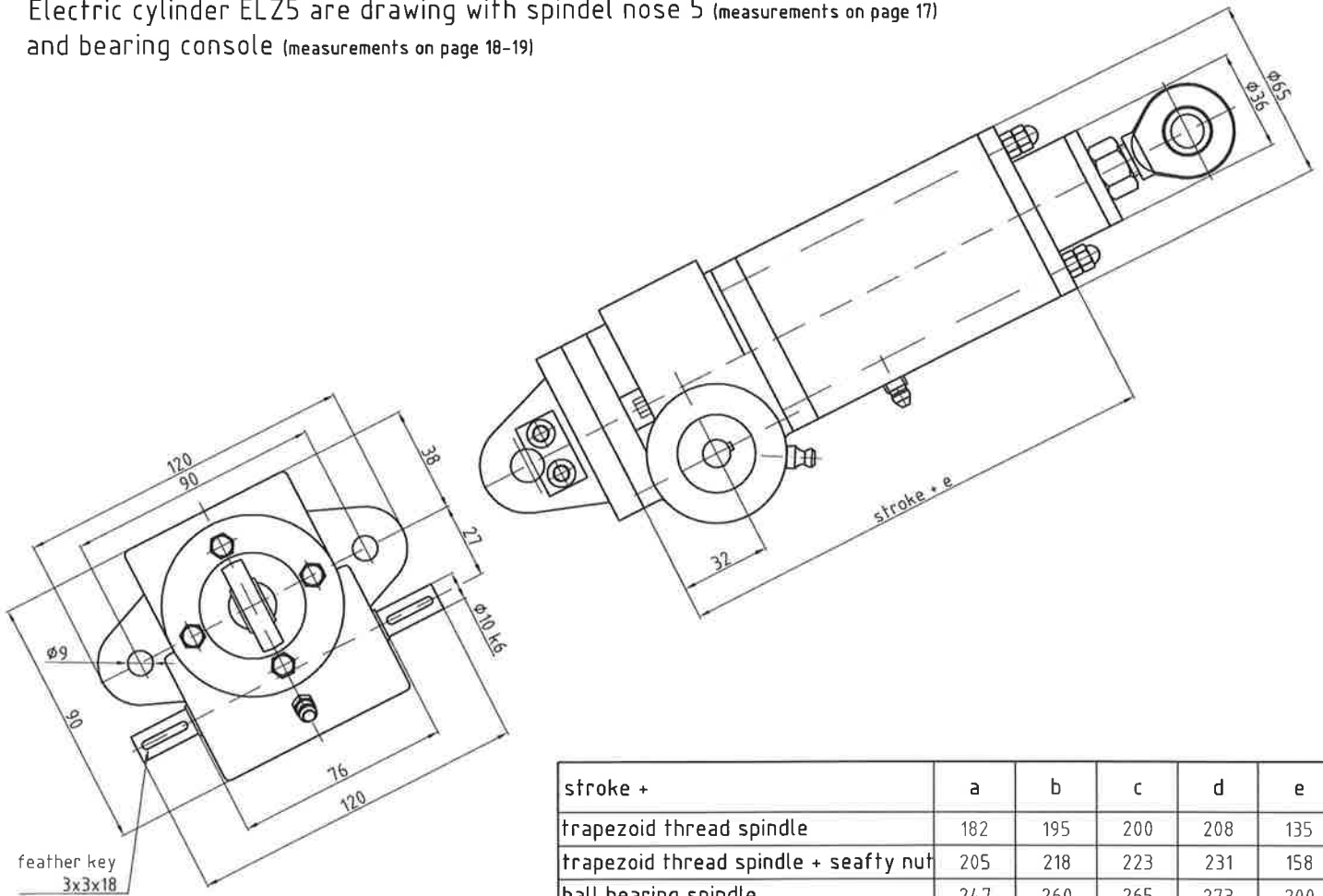


# Electric cylinder ELZ 5

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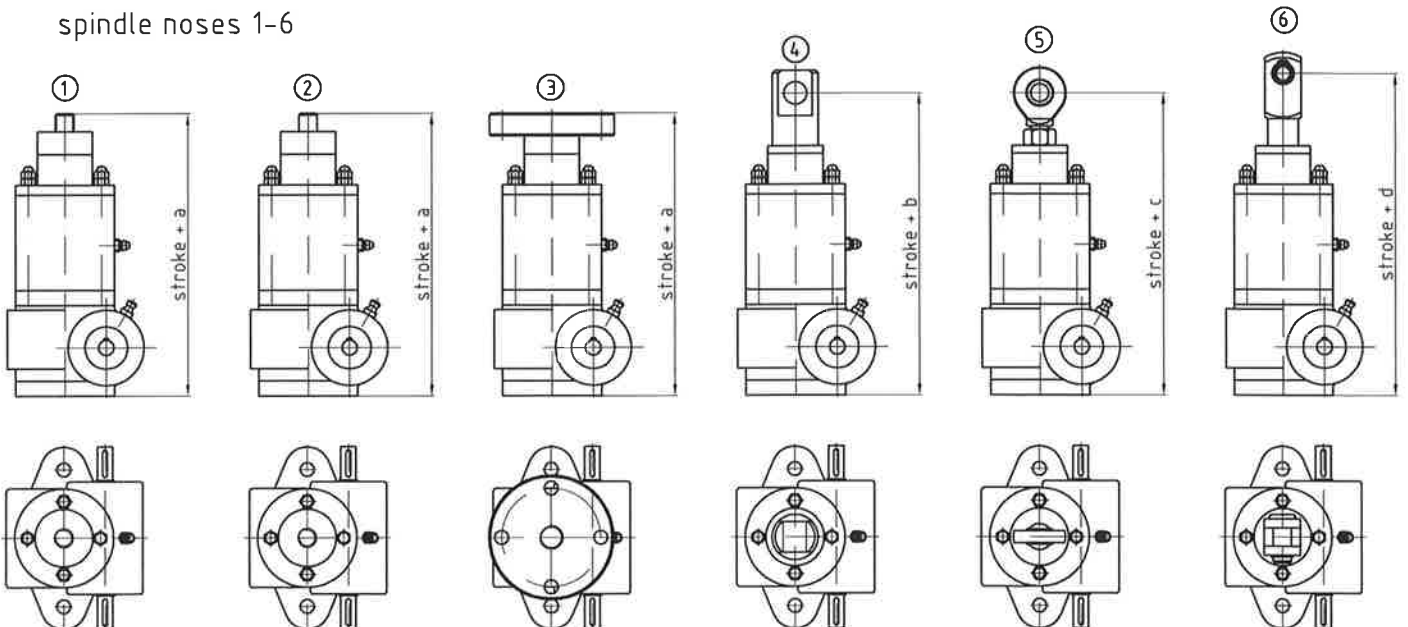
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Internet: www.enzfelder.at

Electric cylinder ELZ5 are drawing with spindel nose 5 (measurements on page 17)  
and bearing console (measurements on page 18-19)



stroke +	a	b	c	d	e
trapezoid thread spindle	182	195	200	208	135
trapezoid thread spindle + safety nut	205	218	223	231	158
ball bearing spindle	247	260	265	273	200
ball bearing spindle + safety nut	270	283	288	296	223

## spindel noses 1-6



spindel noses 90° turned are possible

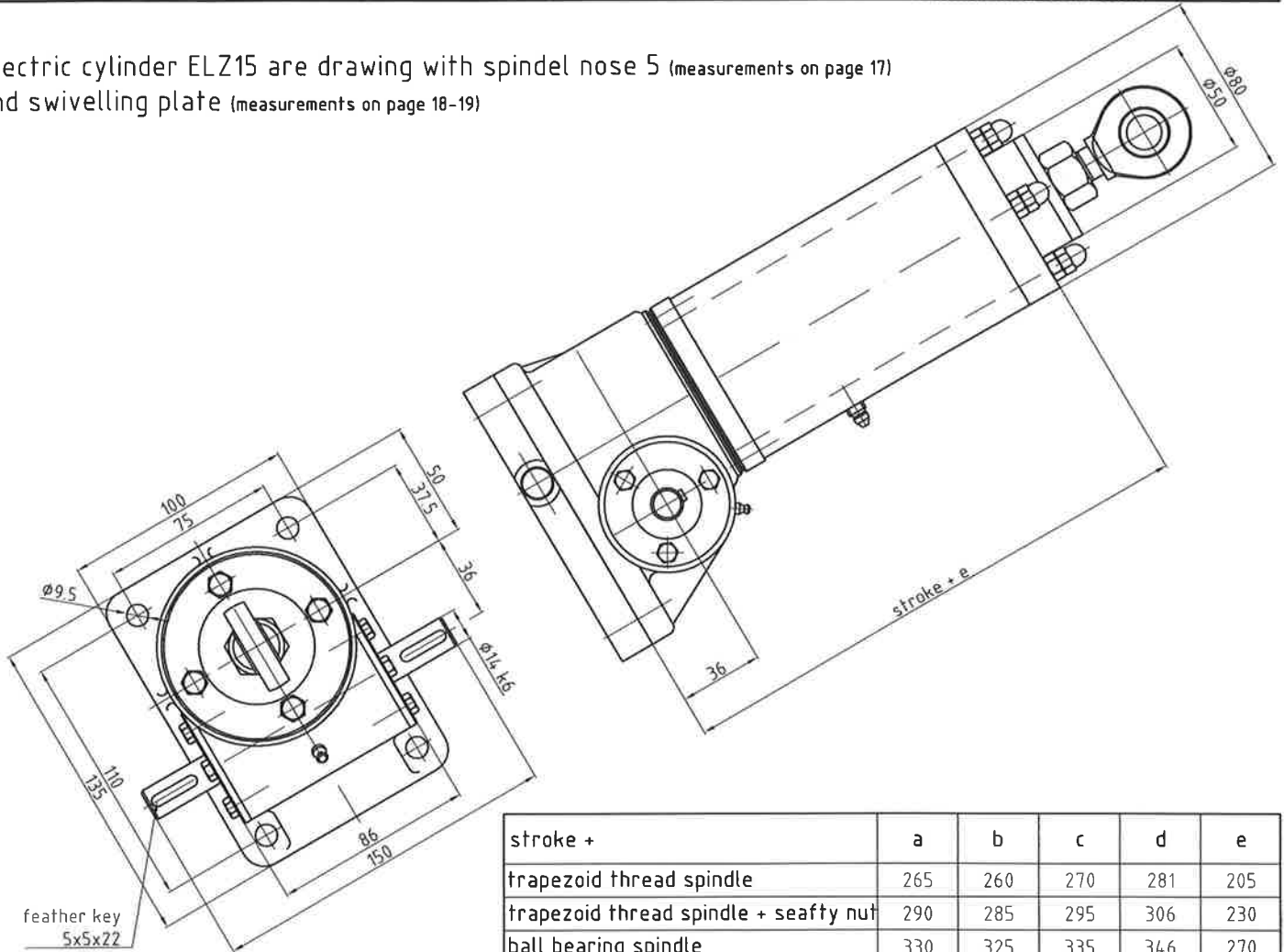
Special executions on request are possible  
Subjects to measurements changes, representation not obligatory



# Electric cylinder ELZ 15

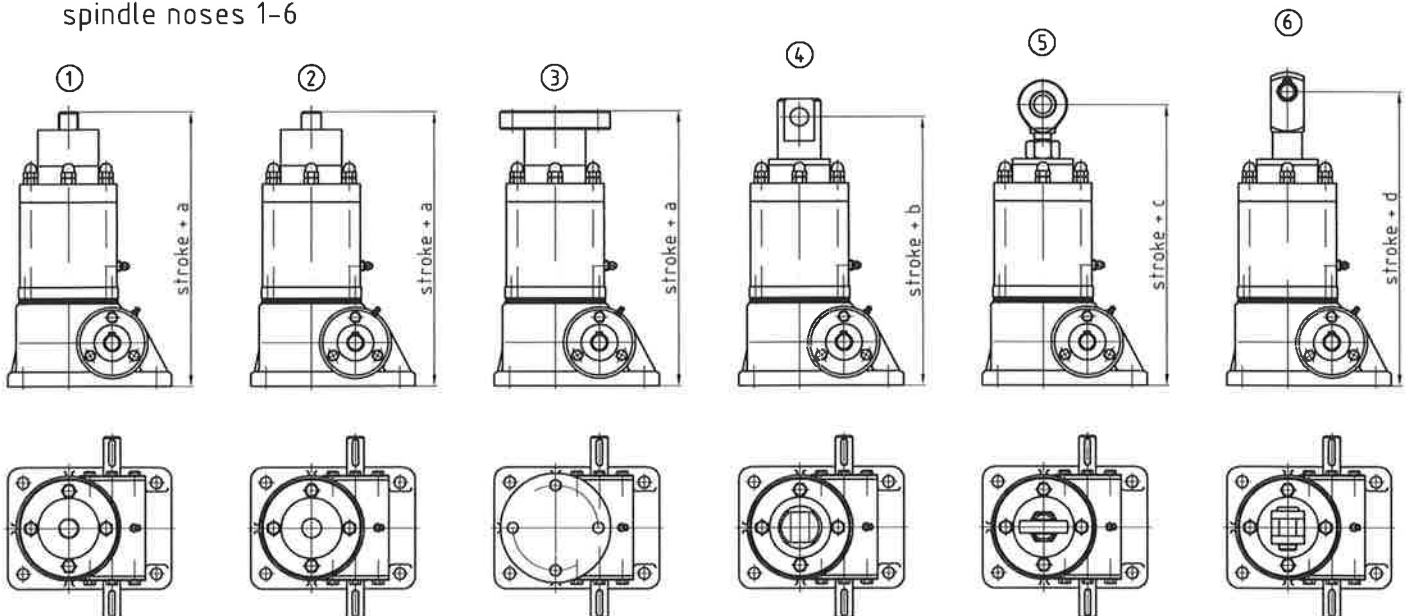
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Electric cylinder ELZ15 are drawing with spindle nose 5 (measurements on page 17)  
 and swivelling plate (measurements on page 18-19)



stroke +	a	b	c	d	e
trapezoid thread spindle	265	260	270	281	205
trapezoid thread spindle + safety nut	290	285	295	306	230
ball bearing spindle	330	325	335	346	270
ball bearing spindle + safety nut	355	350	360	371	295

spindle noses 1-6



spindel noses 90° turned are possible

Special executions on request are possible  
 Subjects to measurements changes, representation not obligatory

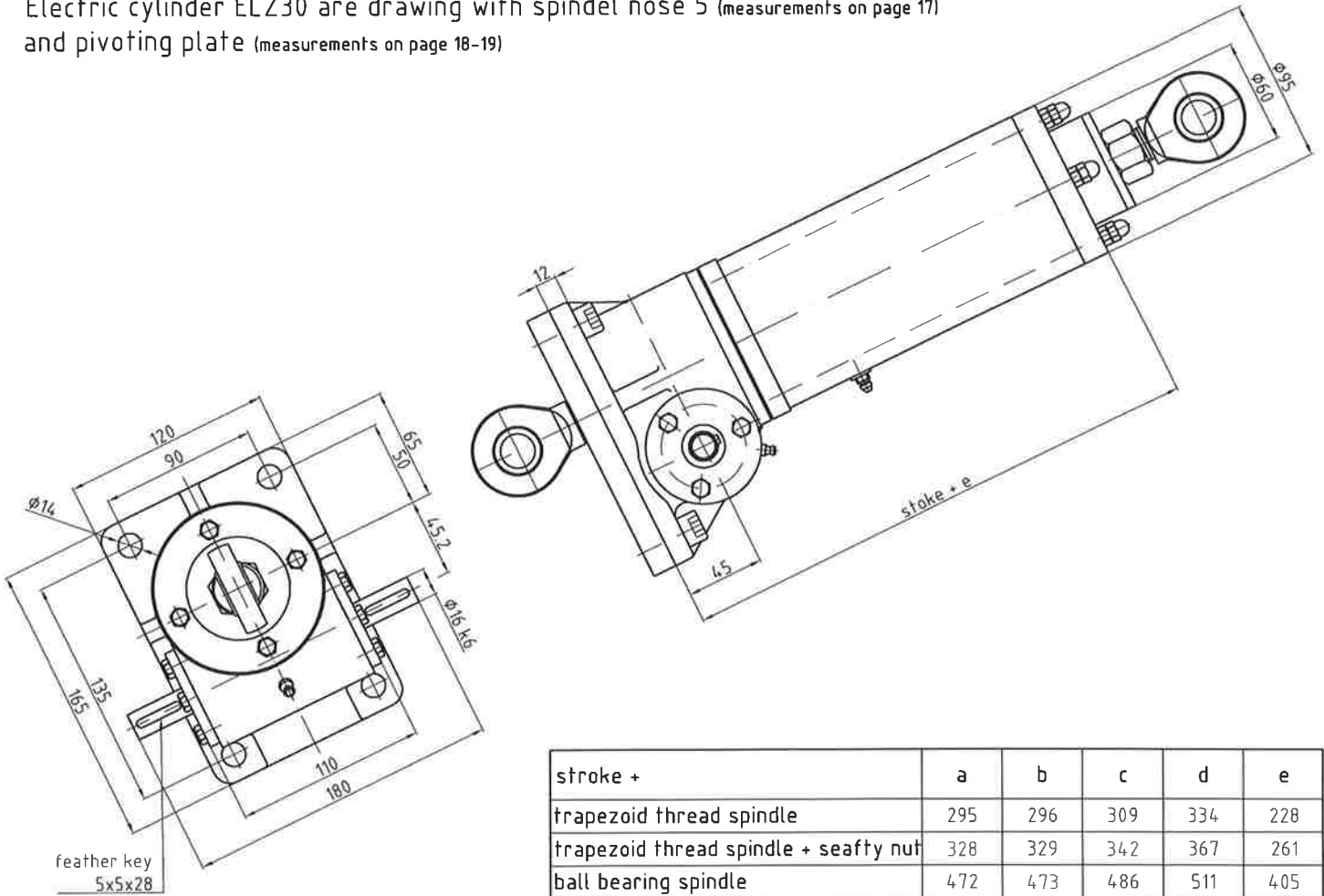


# Electric cylinder ELZ 30

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lifting engineering

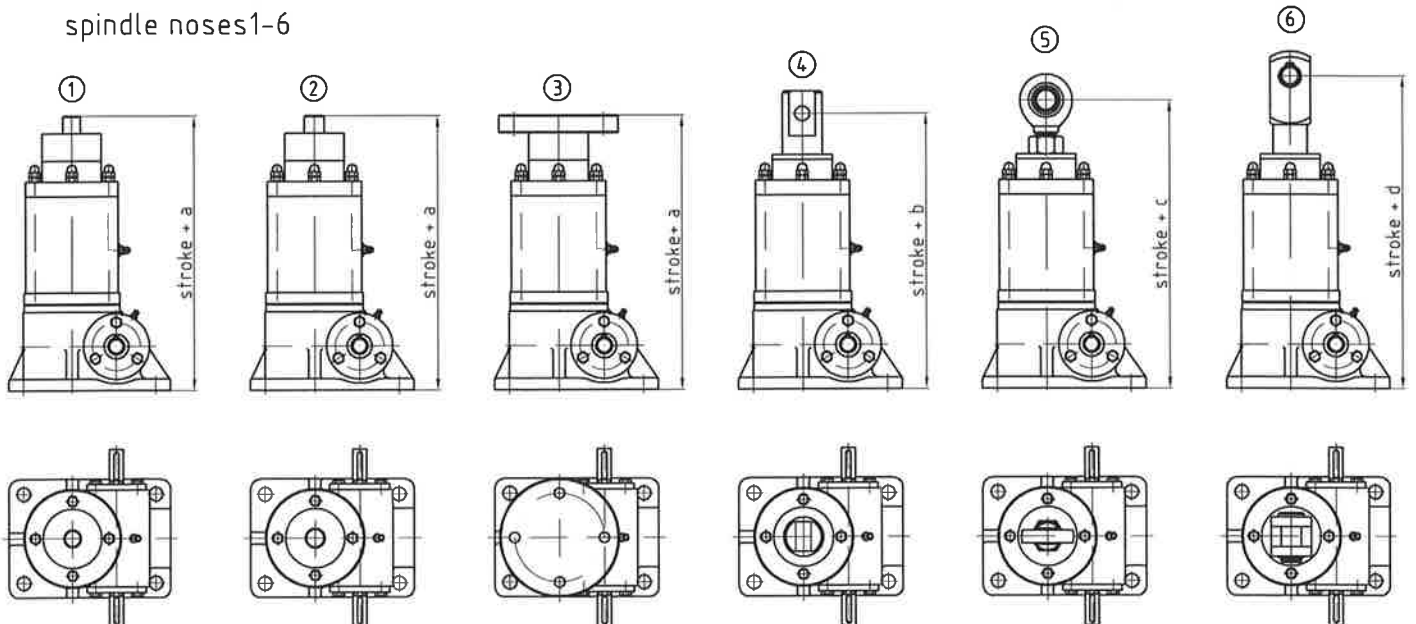
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Electric cylinder ELZ30 are drawing with spindle nose 5 (measurements on page 17)  
and pivoting plate (measurements on page 18-19)



stroke +	a	b	c	d	e
trapezoid thread spindle	295	296	309	334	228
trapezoid thread spindle + safety nut	328	329	342	367	261
ball bearing spindle	472	473	486	511	405
ball bearing spindle + safety nut	521	522	535	460	438

spindle noses 1-6



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

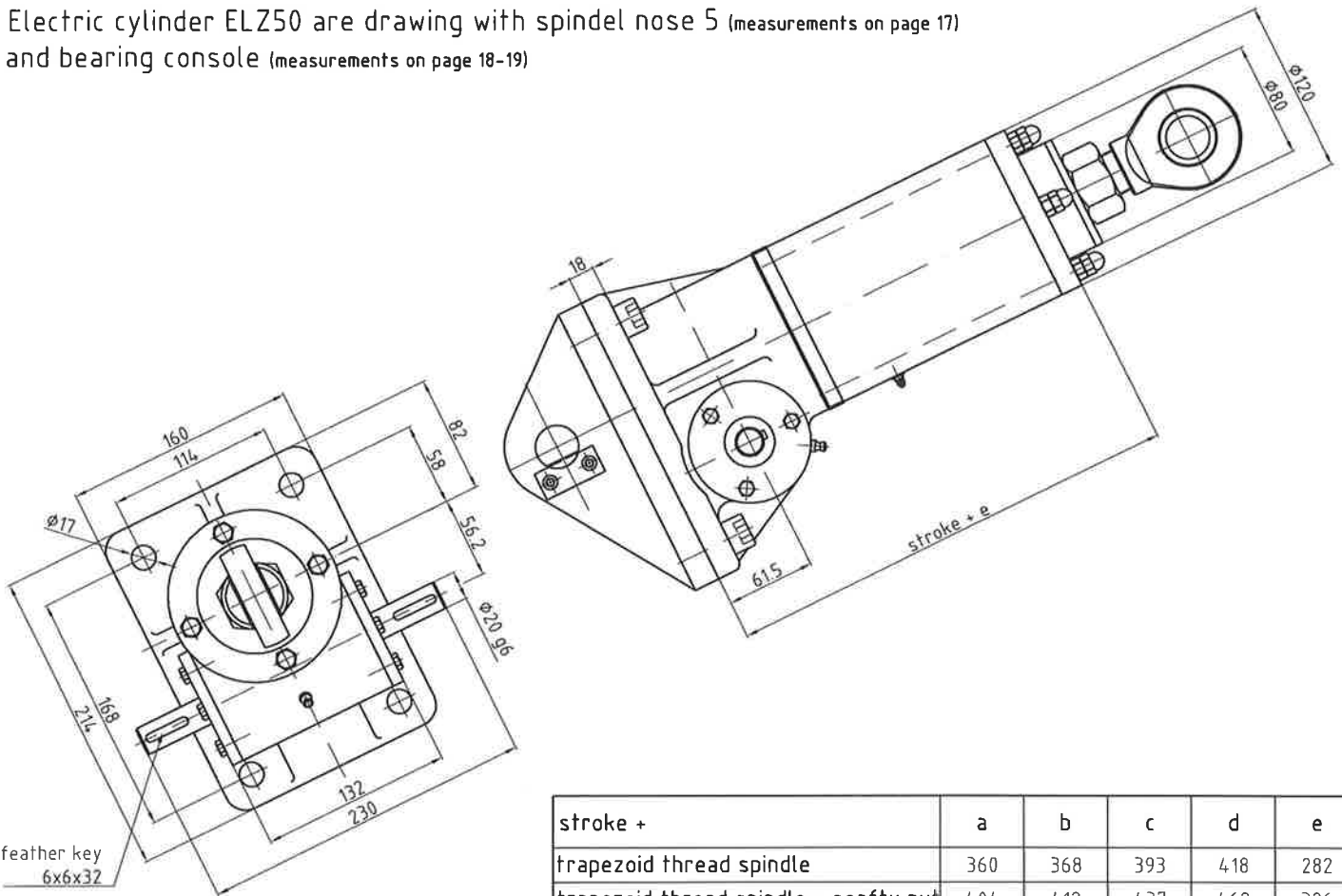


# Electric cylinder ELZ 50

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Power transmission- and  
lifting engineering

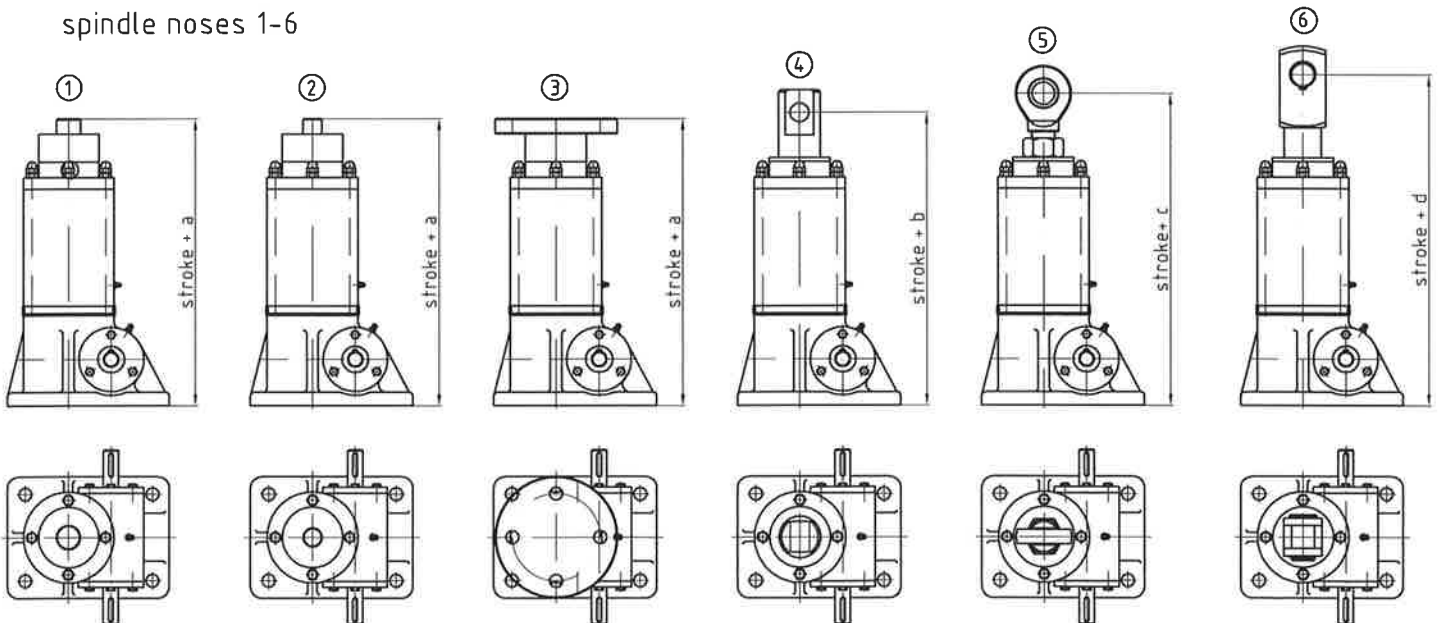
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Electric cylinder ELZ50 are drawing with spindle nose 5 (measurements on page 17)  
and bearing console (measurements on page 18-19)



stroke +	a	b	c	d	e
trapezoid thread spindle	360	368	393	418	282
trapezoid thread spindle + safety nut	404	412	437	462	326
ball bearing spindle	447	455	480	505	369
ball bearing spindle + safety nut	491	499	524	549	413

spindle noses 1-6



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

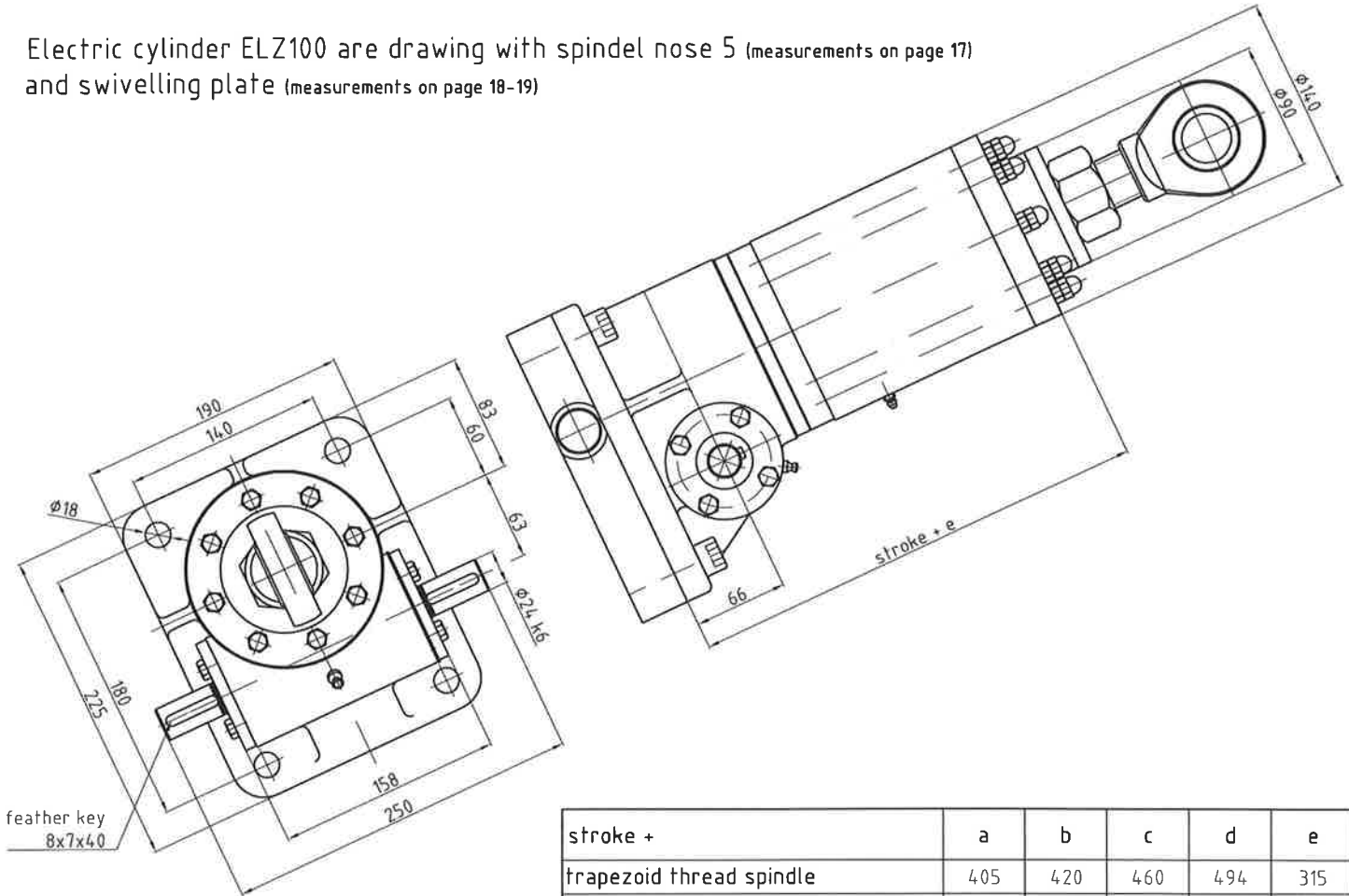


# Electric cylinder ELZ 100

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lifting engineering

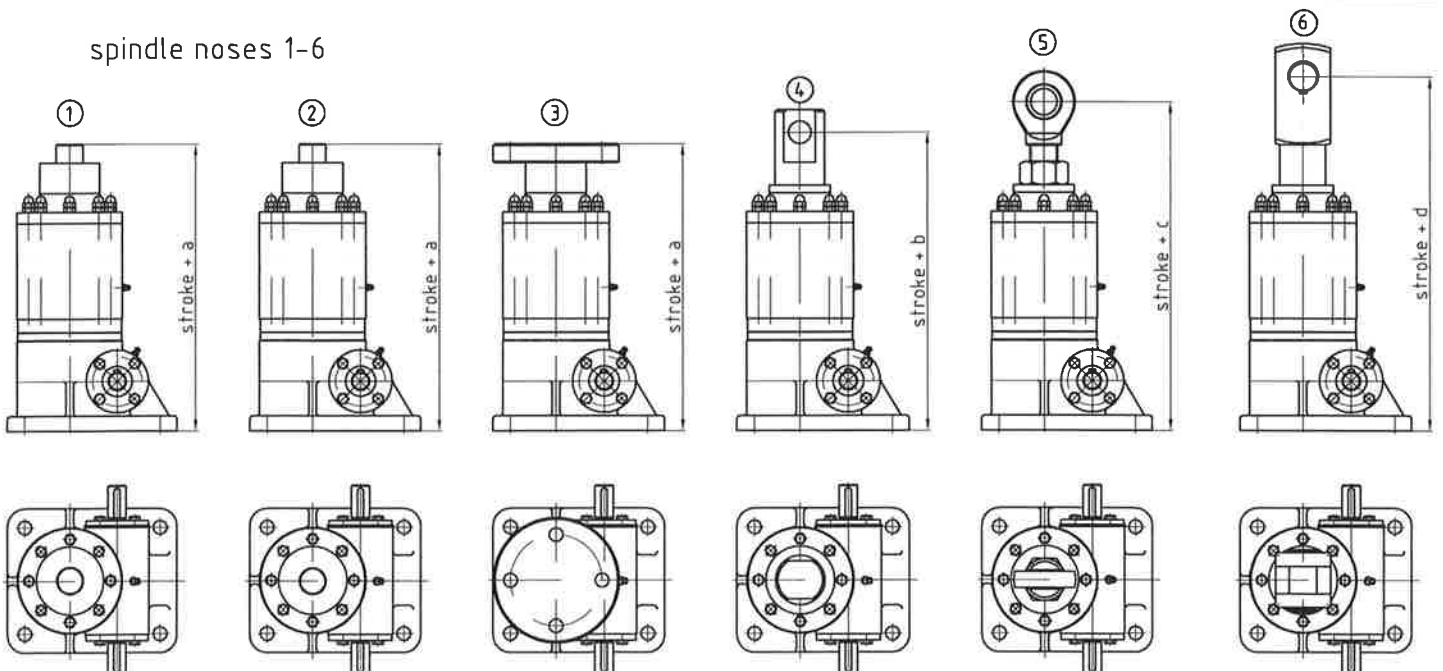
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Electric cylinder ELZ100 are drawing with spindle nose 5 (measurements on page 17)  
and swivelling plate (measurements on page 18-19)



stroke +	a	b	c	d	e
trapezoid thread spindle	405	420	460	494	315
trapezoid thread spindle + safety nut	461	476	516	550	371
ball bearing spindle	520	535	575	609	430
ball bearing spindle + safety nut	576	591	631	665	486

spindle noses 1-6



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory



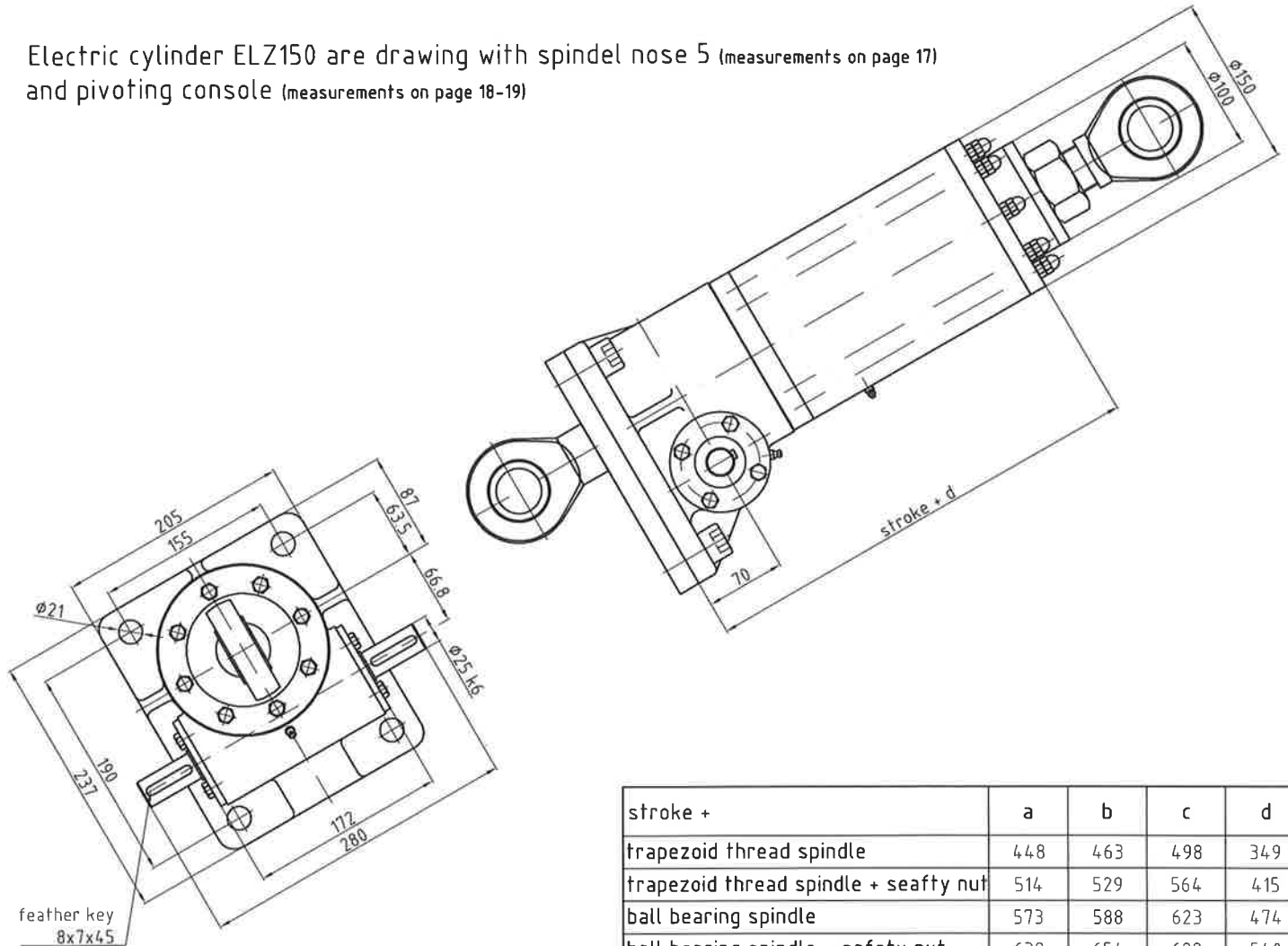


# Electric cylinder ELZ 150

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lifting engineering

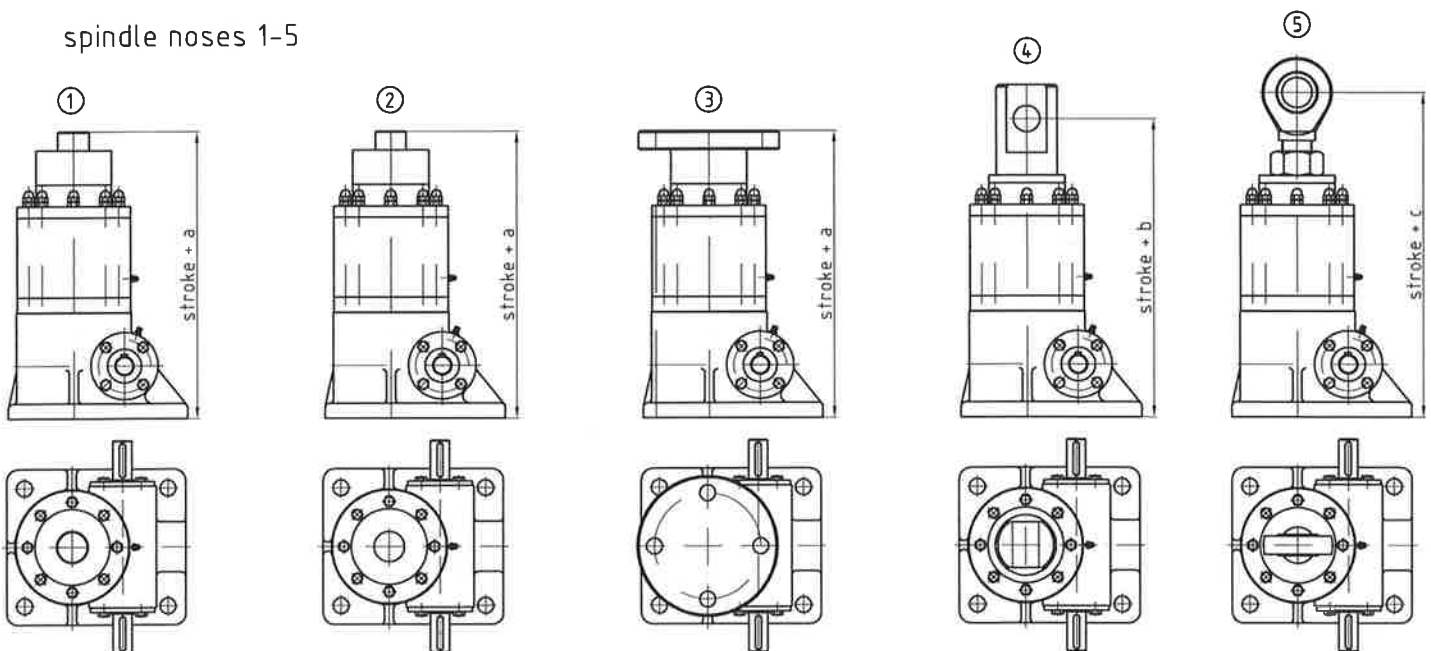
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Electric cylinder ELZ150 are drawing with spindel nose 5 (measurements on page 17)  
and pivoting console (measurements on page 18-19)



stroke +	a	b	c	d
trapezoid thread spindle	448	463	498	349
trapezoid thread spindle + seaffty nut	514	529	564	415
ball bearing spindle	573	588	623	474
ball bearing spindle + safety nut	639	654	689	540

spindel noses 1-5



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

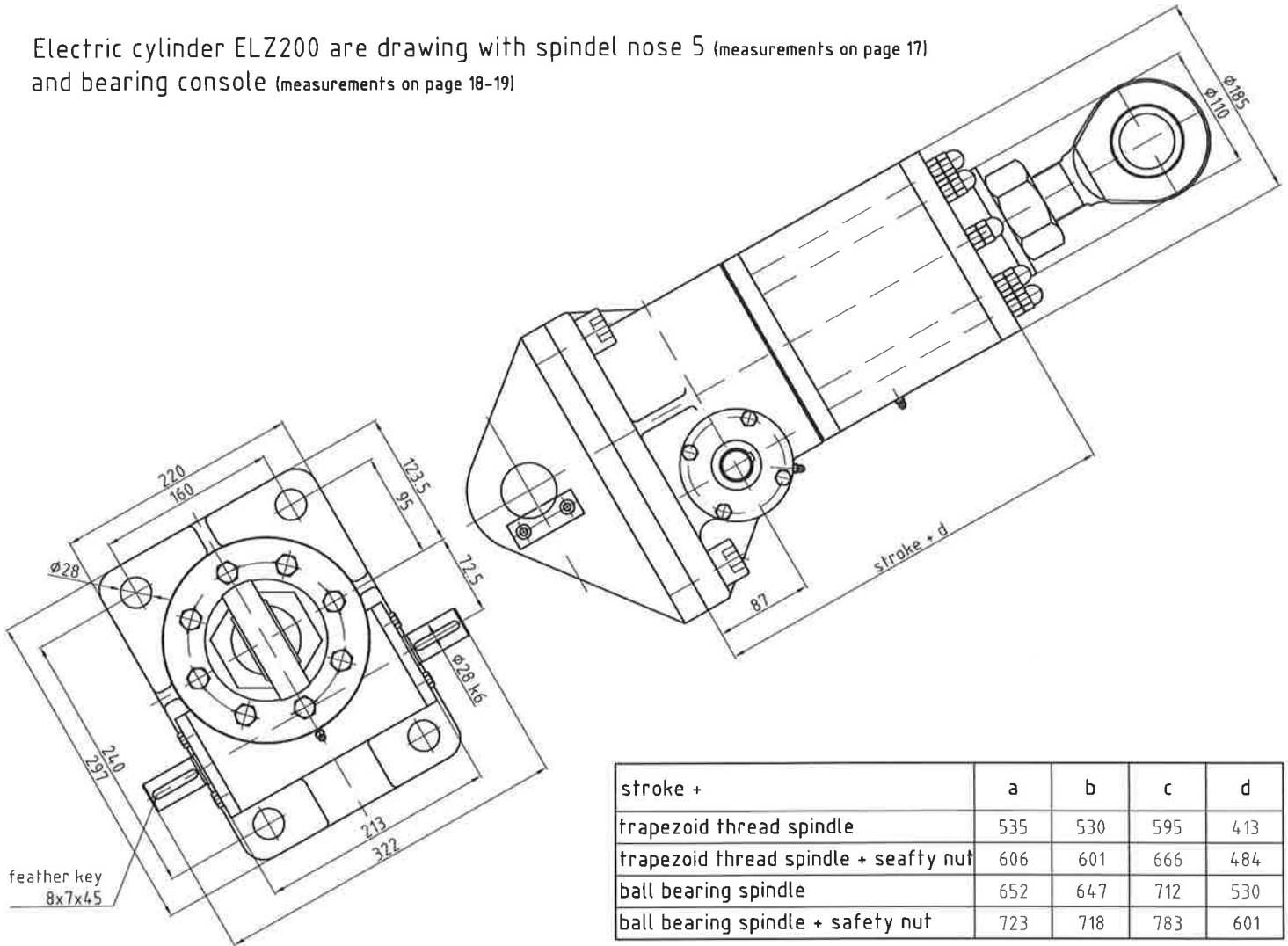


# Electric cylinder ELZ 200

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lifting engineering

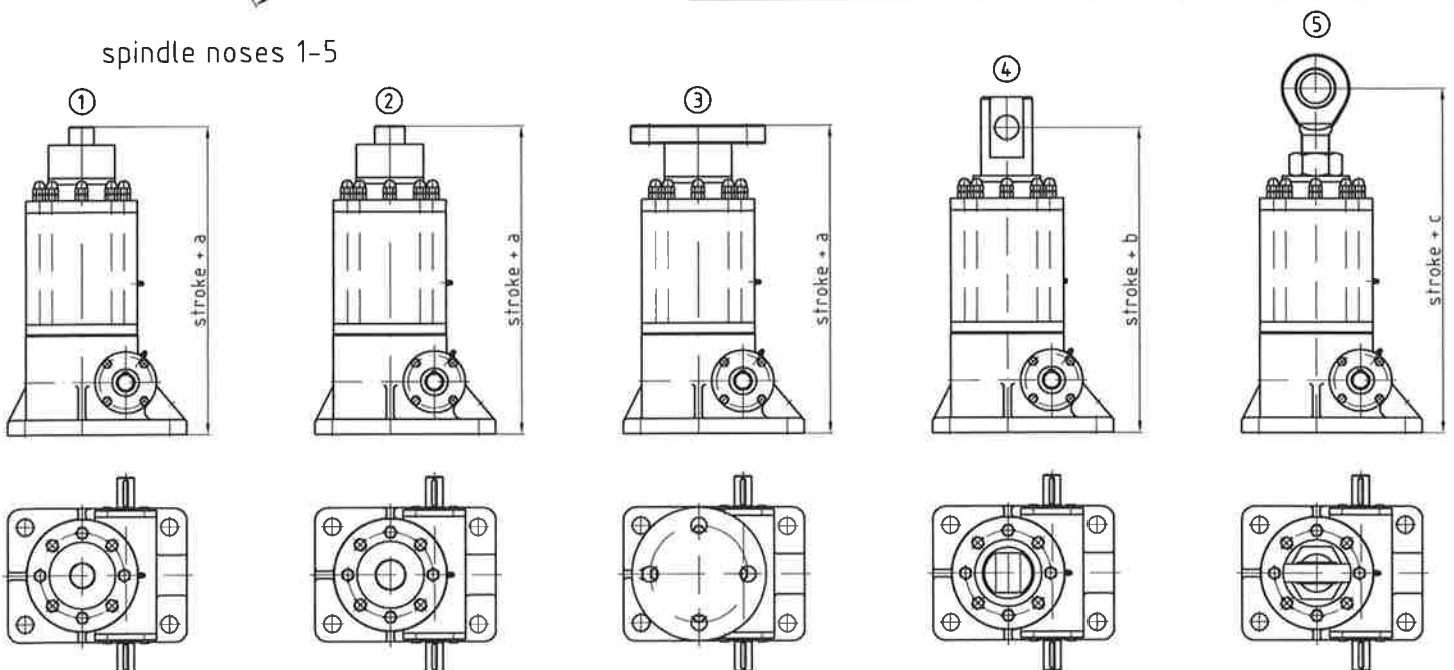
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Electric cylinder ELZ200 are drawing with spindle nose 5 (measurements on page 17)  
and bearing console (measurements on page 18-19)



stroke +	a	b	c	d
trapezoid thread spindle	535	530	595	413
trapezoid thread spindle + seafy nut	606	601	666	484
ball bearing spindle	652	647	712	530
ball bearing spindle + safety nut	723	718	783	601

spindle noses 1-5



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

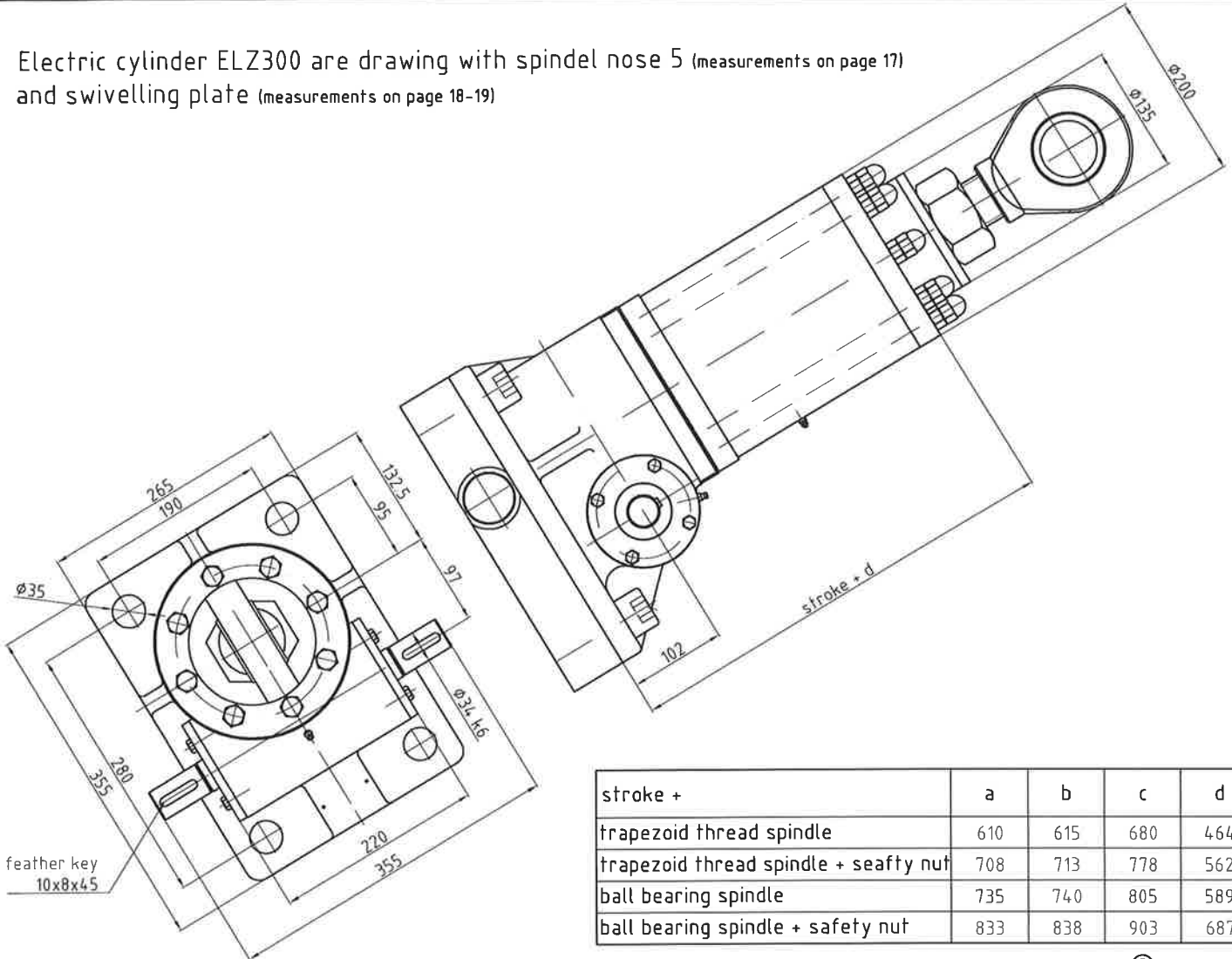


# Electric cylinder ELZ 300

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Power transmission- and  
lifting engineering

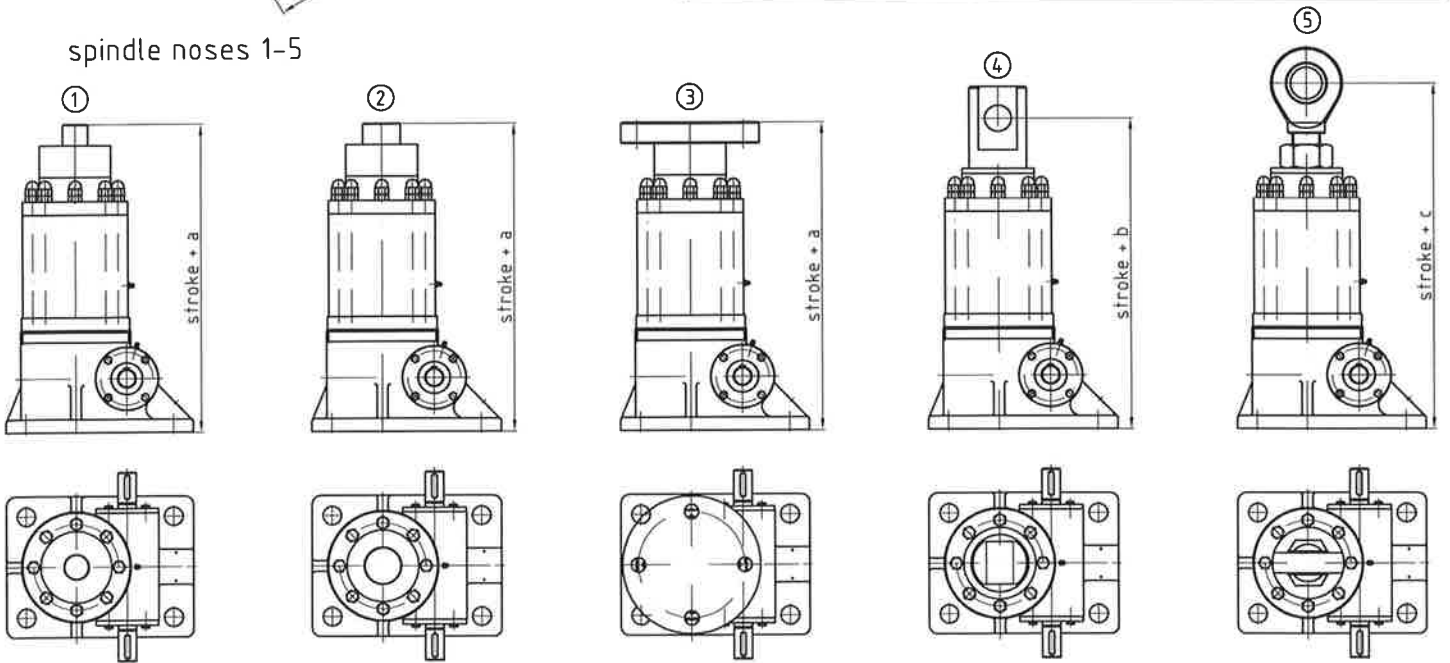
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Electric cylinder ELZ300 are drawing with spindle nose 5 (measurements on page 17)  
and swivelling plate (measurements on page 18-19)



stroke +	a	b	c	d
trapezoid thread spindle	610	615	680	464
trapezoid thread spindle + seaffty nut	708	713	778	562
ball bearing spindle	735	740	805	589
ball bearing spindlde + safety nut	833	838	903	687

spindle noses 1-5



spindel noses 90° turned are possible

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory

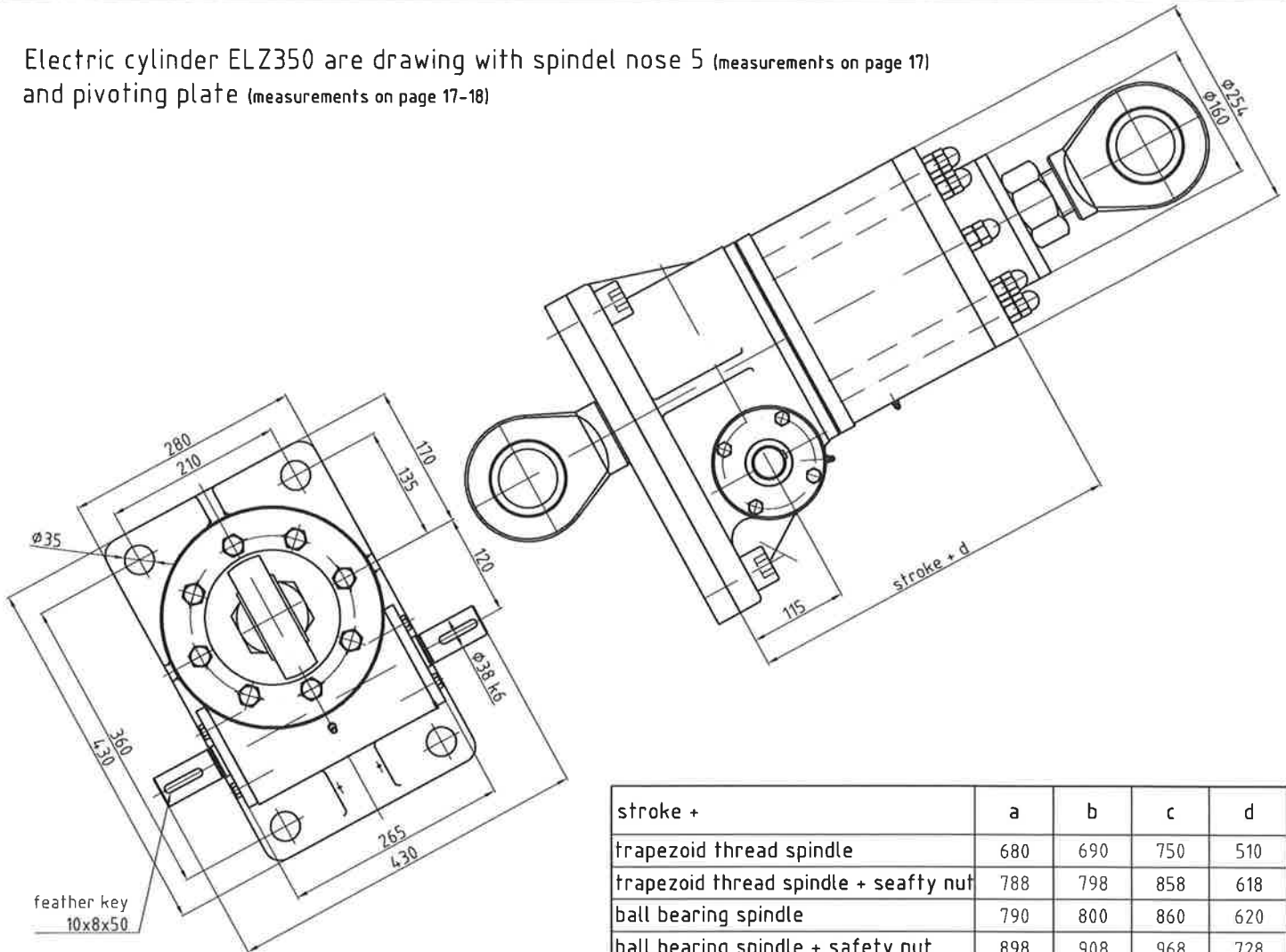


# Electric cylinder ELZ 350

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Power transmission- and  
lifting engineering

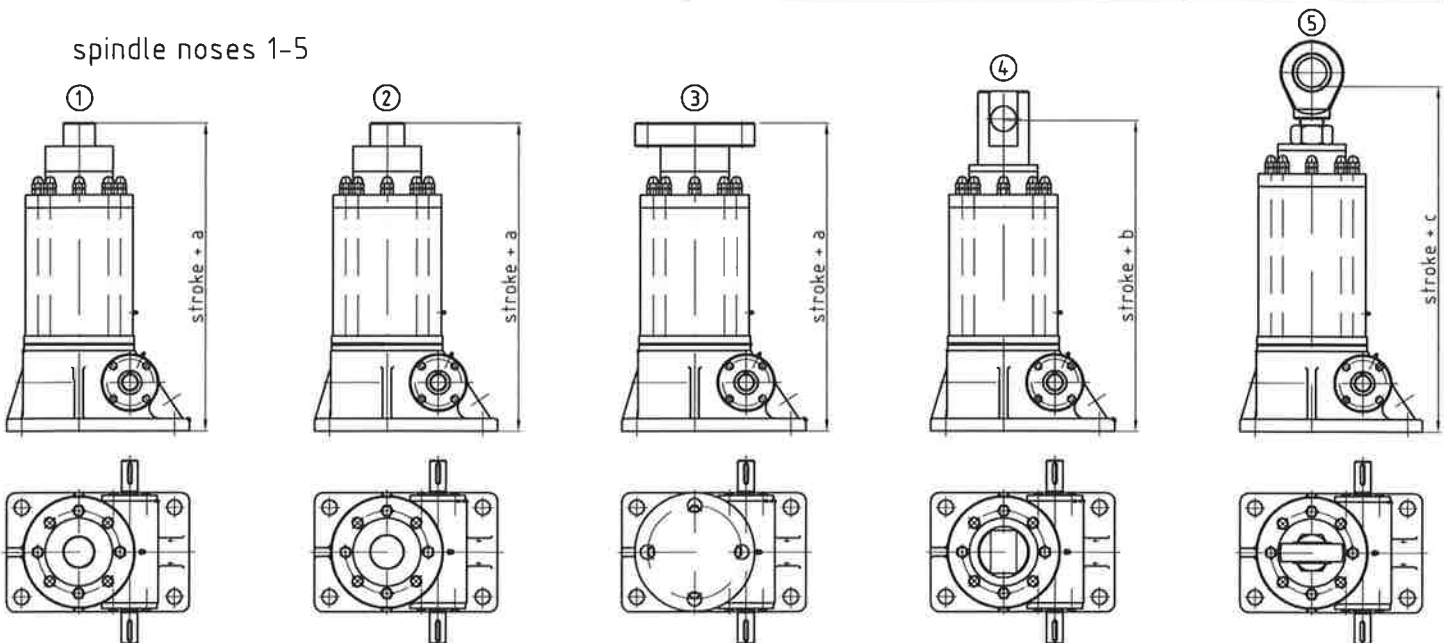
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Electric cylinder ELZ350 are drawing with spindle nose 5 (measurements on page 17)  
and pivoting plate (measurements on page 17-18)



stroke +	a	b	c	d
trapezoid thread spindle	680	690	750	510
trapezoid thread spindle + seafy nut	788	798	858	618
ball bearing spindle	790	800	860	620
ball bearing spindle + safety nut	898	908	968	728

spindle noses 1-5



spindel noses 90° turned are possible

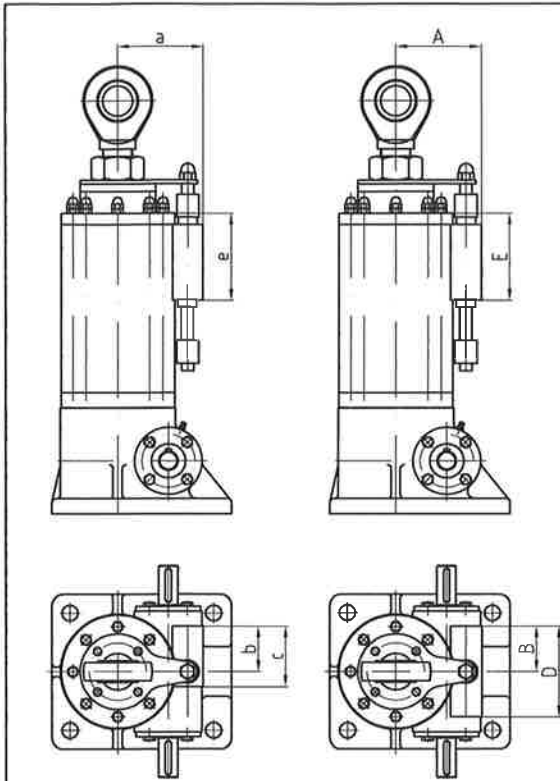
Special executions on request are possible  
Subjects to measurements changes, representation not abligatory



# Limit stop with infinitely adjustable limit switches

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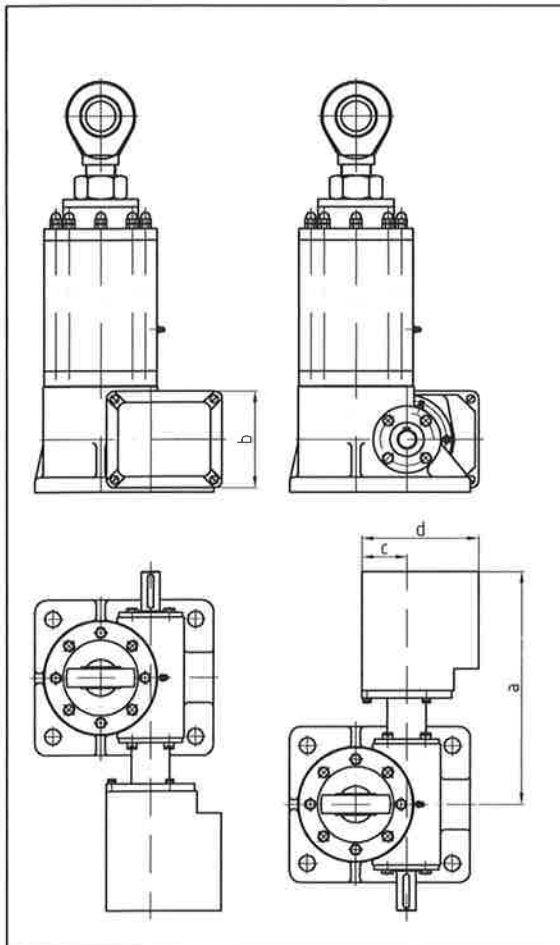


## Limit stop with ever one operating limit switch above and down

ELZ	5	15	30	50	100	150	200	300	350
a	71	79	81,5	99	106	112	132,5	136	163
b	60	60	60	60	60	60	60	60	60
c	80	80	80	80	80	80	80	80	80
d	120	120	120	120	120	120	120	120	120
e	106,5	115	115	115	115	115	120	125	130
Special executions on request									

## Limit stop with ever one operating and emergency limit switch above and down

ELZ	5	15	30	50	100	150	200	300	350
A	71	79	81,5	99	106	112	132,5	136	163
B	60	60	60	60	60	60	60	60	60
C	80	80	80	80	80	80	80	80	80
D	120	120	120	120	120	120	120	120	120
E	106,5	115	115	115	115	115	120	125	130
Special executions on request									



## Limit stop with Geared com limit switch with ever one operating limit switch above and down

ELZ	5	15	30	50	100	150	200	300	350
a <sub>x</sub>	221	241,5	251	260	273	282	298	303	322
b	128	128	128	128	128	128	128	128	128
c	59	59	59	59	59	59	59	59	59
d	153	153	153	153	153	153	153	153	153
Special executions on request									

× Measure a dependet from stroke

## Limit stop with Geared com limit switch with ever one operating and emergency limit switch above and down

ELZ	5	15	30	50	100	150	200	300	350
a <sub>x</sub>	246	266,5	276	285	298	307	323	328	347
b	128	128	128	128	128	128	128	128	128
c	59	59	59	59	59	59	59	59	59
d	153	153	153	153	153	153	153	153	153
Special executions on request									

× Measure a dependet from stroke

Limit switch housing made of glass fibre reinforced polycarbonate with the degree of protection IP66

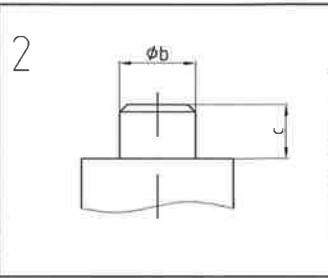
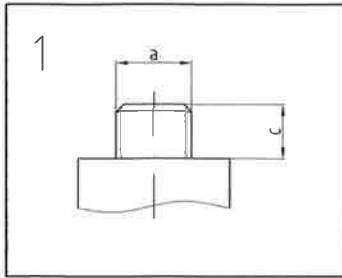
Special executions on request are possible  
Subjects to measurement's changes, representation not obligatory



# Spindle noses

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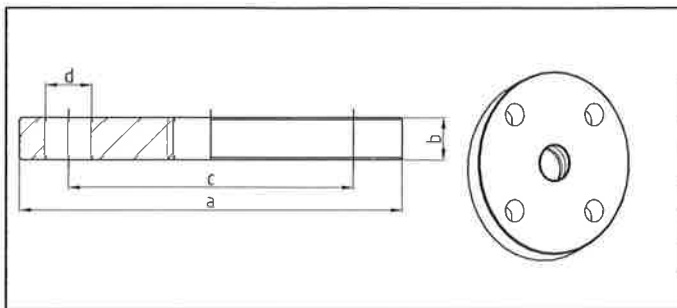
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## Spindle nose 1 and 2

ELZ	5	15	30	50	100	150	200	300	350
a	M12	M16	M20x1,5	M30x1,5	M36x3	M42x1,5	M50x3	M70x3	M80x3
phi b	12	16	20	25	35	40	50	70	80
c	22	20	32	42	45	50	62	65	75

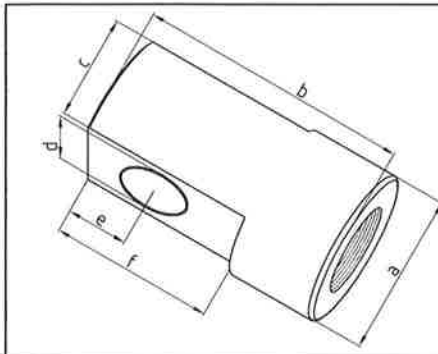
Special executions on request



## Spindle nose 3

ELZ	5	15	30	50	100	150	200	300	350
a	82	90	120	160	165	150	220	260	280
b	15	15	18	20	25	25	30	40	55
c	65	70	90	115	120	140	160	200	220
phi d	7	9	10,5	17	18	21	26	27	33

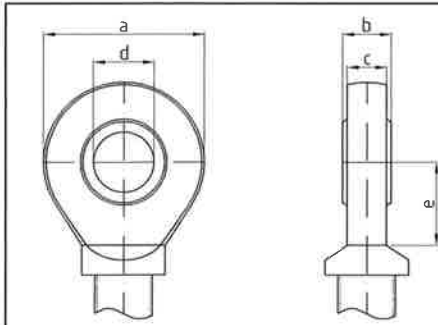
Special executions on request



## Spindle nose 4

ELZ	5	15	30	50	100	150	200	300	350
a	30	35	40	55	65	80	85	108	120
b	50	50	65	90	100	120	130	155	175
c	20	25	30	40	50	60	65	80	100
phi d	15	15	15	25	30	35	40	50	60
e	15	15	23	30	30	45	50	60	100
f	30	35	46	60	70	90	100	120	130

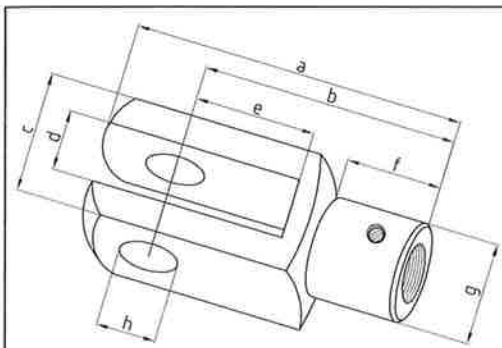
Special executions on request



## Spindle nose 5

ELZ	5	15	30	50	100	150	200	300	350
a	34	40	53	73	82	92	112	135	160
b	10	12	16	22	25	28	35	44	49
c	8,5	10,5	13,5	20	22	24	31	39	43
phi d	12	15	20	30	35	40	50	60	70
e	19	20	27,5	37	43	48	60	75	87

Special executions on request



## Spindle nose 6

ELZ	5	15	30	50	100	150	200	300	350
a	62	72	105	148	188	265	-----	-----	-----
b	48	56	80	110	144	192	-----	-----	-----
c	24	27	40	60	72	96	-----	-----	-----
d	12	14	20	30	36	50	-----	-----	-----
e	24	28	40	60	72	96	-----	-----	-----
f	18	22,5	30	40	54	73	-----	-----	-----
g	20	24	34	48	60	82	-----	-----	-----
phi h	12	14	20	30	36	50	-----	-----	-----

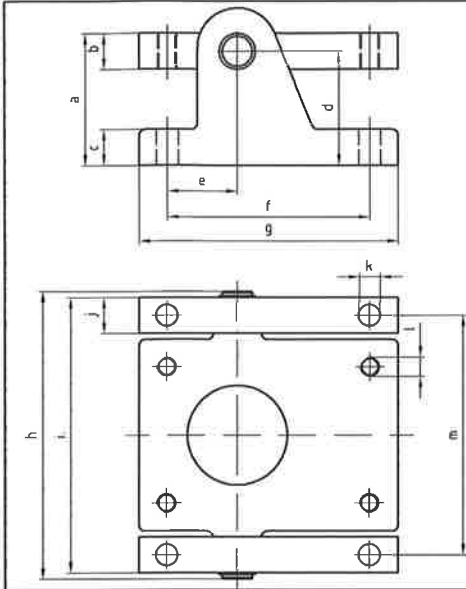
Special executions on request  
---- on request

Special executions on request are possible  
Subjects to measurements changes, representation not obligatory



# Swivelling console, Swivelling plate, Bearing console and Pivoting plate

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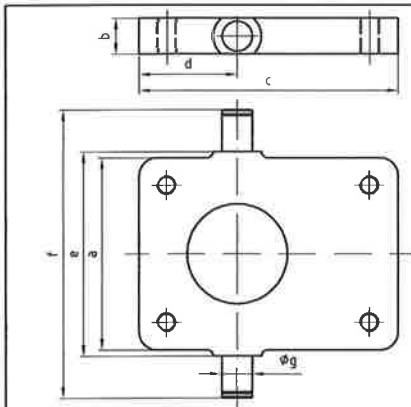


## Swivelling console (SK)

ELZ	5	15	30	50	100	150	200	300	350
a	50	67,5	90	110	110	150	160	170	210
b	10	15	25	30	35	45	50	60	65
c	8	15	20	30	30	30	40	50	60
d	45	60	77,5	95	92,5	127,5	135	140	177,5
e	30	37,5	50	58	60	63,5	95	95	135
f	60	110	135	168	180	190	240	280	360
g	70	135	165	215	225	237	297	355	430
h	150	150	190	240	270	297	322	411	424
i	144	140	180	230	260	285	310	395	410
j	10	15	25	30	30	35	40	60	60
k	6	9	13	18	18	21	26	35	35
l	M8	M8	M12	M16	M16	M20	M24	M30	M30
m	134	125	155	200	230	250	270	335	350

Special executions on request

Product as delivered: enclosed

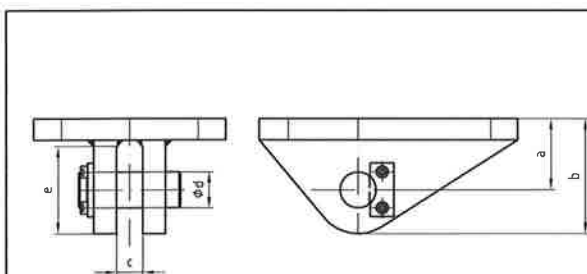


## Swivelling plate (SP)

ELZ	5	15	30	50	100	150	200	300	350
a	120	100	120	160	190	205	220	265	280
b	10	15	25	30	35	45	50	60	65
c	65	135	165	215	225	237	297	355	430
d	32,5	50	65	81,5	82,5	87	123,5	133	170
e	124	110	130	170	200	215	230	275	290
f	150	150	190	240	270	297	322	411	424
g	8 f7	14 h7	20 h7	25 h7	32 h7	40 h7	45 h7	55 h7	60 h7

Special executions on request

Product as delivered: enclosed

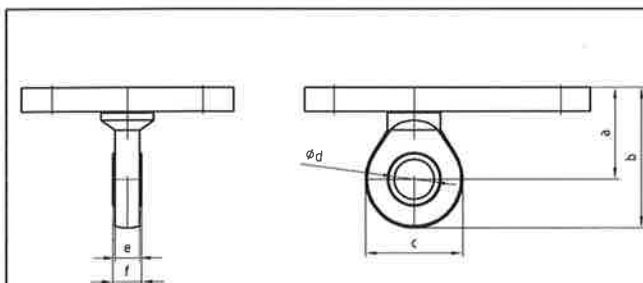


## Bearing console (LK)

ELZ	5	15	30	50	100	150	200	300	350
a	30	40	46	59,5	65	71	86	101,5	115
b	47	61	72,5	96	106	117	142	169	195
c	10	12	16	22	26	28	35	44	49
d	12	15	20	30	35	40	50	60	70
e	34	42	54	73	82	92	112	135	162

Special executions on request

Product as delivered: enclosed



## Pivoting plate (GP)

ELZ	5	15	30	50	100	150	200	300	350
a	37	45	52	69	80	96	112	129	144
b	54	65	78,5	105,5	121	147	168	196,5	224
c	34	40	53	73	82	92	112	135	160
d	12	15	20	30	35	40	50	60	70
e	8	10	13	19	21	23	30	38	42
f	10	12	16	22	25	28	35	44	49

Special executions on request

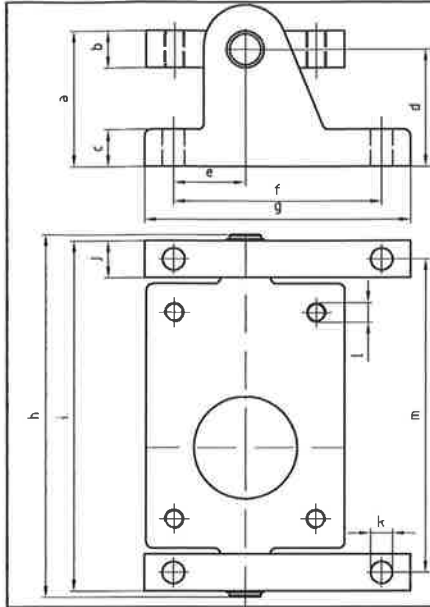
Product as delivered: enclosed

Special executions on request are possible  
Subjects to measurements changes, representation not Obligatory



# Swivelling console, Swivelling plate, Bearing console and Pivoting plate 90° turned

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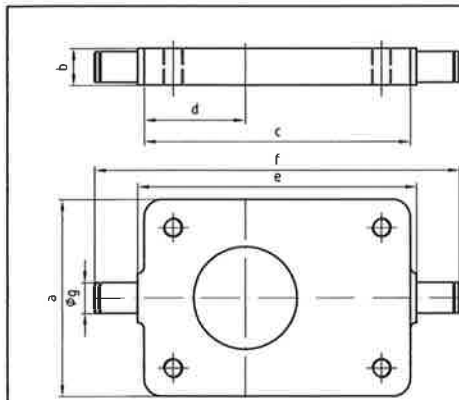


## Swivelling console 90° turned (SK)

ELZ	5	15	30	50	100	150	200	300	350
a	50	67,5	90	110	110	150	160	170	210
b	10	15	25	30	35	45	50	60	65
c	8	15	20	30	30	30	40	50	60
d	45	60	77,5	95	92,5	127,5	135	140	177,5
e	30	37,5	50	58	60	63,5	95	95	135
f	60	110	135	168	180	190	240	280	360
g	70	135	165	215	225	237	297	355	430
h	106	185	235	295	305	329	399	501	574
i	100	175	225	285	295	317	387	485	560
j	10	15	25	30	30	35	40	60	60
k	6	9	13	18	18	21	26	35	35
l	M8	M8	M12	M16	M16	M20	M24	M30	M30
m	90	160	200	255	265	282	347	425	500

Special executions on request

Product as delivered: enclosed

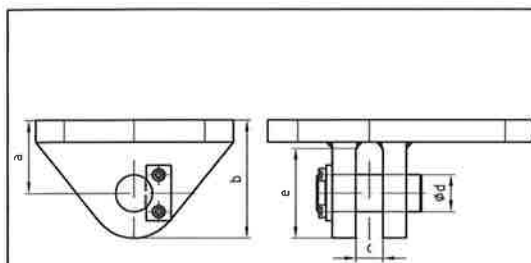


## Swiveling plate 90° turned (SP)

ELZ	5	15	30	50	100	150	200	300	350
a	120	100	120	160	190	205	220	265	280
b	10	15	25	30	35	45	50	60	65
c	65	135	165	215	225	237	297	355	430
d	32,5	50	65	81,5	82,5	87	123,5	133	170
e	80	145	175	223,5	235	247	307	365	440
f	160	185	235	293,5	305	329	399	501	574
g	8 f7	14 h7	20 h7	25 h7	32 h7	40 h7	45 h7	55 h7	60 h7

Special executions on request

Product as delivered: enclosed

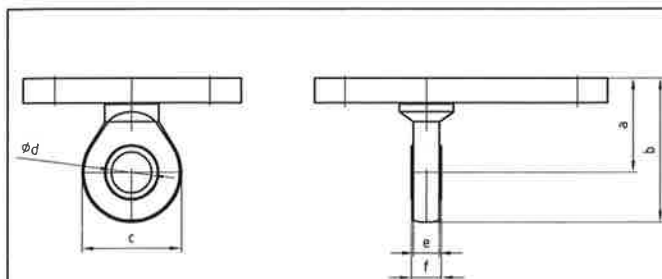


## Bearing console turned (LK)

ELZ	5	15	30	50	100	150	200	300	350
a	30	40	46	59,5	65	71	86	101,5	115
b	47	61	72,5	96	106	117	142	169	195
c	10	12	16	22	26	28	35	44	49
d	12	15	20	30	35	40	50	60	70
e	34	42	54	73	82	92	112	135	162

Special executions on request

Product as delivered: enclosed



## Pivoting plate (GP)

ELZ	5	15	30	50	100	150	200	300	350
a	37	45	52	69	80	96	112	129	144
b	54	65	78,5	105,5	121	147	168	196,5	224
c	34	40	53	73	82	102	112	135	160
d	12	15	20	30	35	45	50	60	70
e	8	10	13	19	21	27	30	38	42
f	10	12	16	22	25	32	35	44	49

Special executions on request

Product as delivered: enclosed

Special executions on request are possible  
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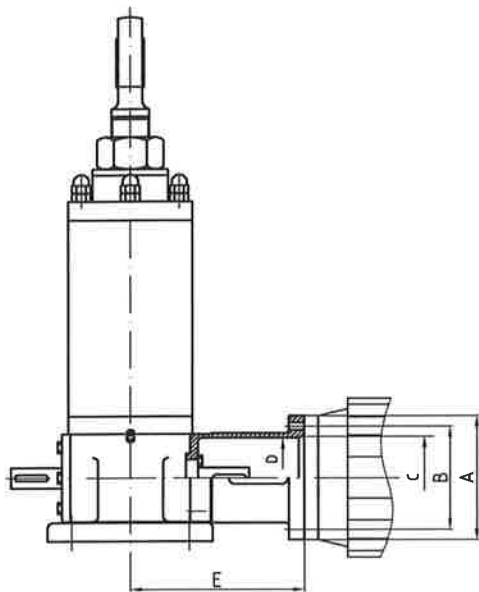




# Motor flanges Crank handles, Hand wheels

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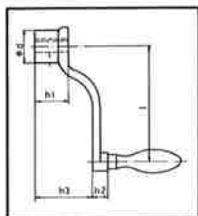
## Motor flanges



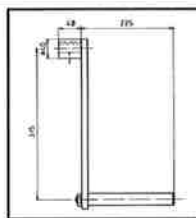
**Important:**

Unless otherwise requested by the customer, motor flanges are mounted on the right, as shown above!  
Engines and fastening bolts are delivered non mounted.

	type of motor	flange $\phi A$	$\phi B$	$\phi C$	$\phi D$	E	shaft ends $\phi$		4 pcs bolts DIN 912 f. motor
							SG	Motor	
ELZ 5	56 B14	80	65	50	44	93	10	9	M5 x 16
	63 B14	90	75	60	44	96	10	11	M5 x 20
	71 B14	105	85	70	44	103	10	14	M6 x 25
ELZ15	63 B14	90	75	60	52	114	14	11	M5 x 20
	71 B14	105	85	70	52	121	14	14	M6 x 25
	80 B14	120	100	80	52	131	14	19	M6 x 25
ELZ 30	71 B14	105	85	70	59	136	16	14	M6 x 25
	80 B14	120	100	80	59	146	16	19	M6 x 25
	90 B14	140	115	95	59	156	16	24	M8 x 25
ELZ 50	90 B14	140	115	95	76	181	20	24	M8 x 25
	100 B14	160	130	110	76	193	20	28	M8 x 25
	112 B14	160	130	110	76	193	20	28	M8 x 25
ELZ 100	100 B14	160	130	110	80	203	24	28	M8 x 25
	112 B14	160	130	110	80	203	24	28	M8 x 25
	132 B14	200	215	180	80	225	24	38	M10 x 30
ELZ 150	100 B14	160	130	110	84	218	25	28	M8 x 25
	112 B14	160	130	110	84	218	25	28	M8 x 25
	132 B14	200	215	180	84	240	25	38	M10 x 30
ELZ 200	132 B14	200	215	180	100	263	28	38	M10 x 30
	160 B5	350	300	250	100	307	28	42	M16 x 60 + 4 nuts
ELZ 300	132 B14	200	215	180	114	278	34	38	M10 x 30
	160 B5	350	300	250	114	312	34	42	M16 x 60 + 4 nuts
ELZ 350	160 B5	350	300	250	130	349	38	42	M16 x 60 + 4 nuts
	180 B5	350	300	250	130	351	38	48	M16 x 60 + 4 nuts



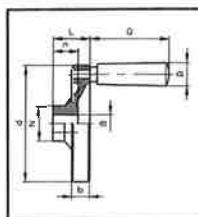
## Crank handles



	Ch 1		
BG	5	10	25
a F 7	10	14	16
b P 9	3	5	5
c	11,4	16,3	18,3
d	28	38	38
h1	28	38	38
h2	13	14	14
h3	48	65	65
l	100	160	160

	Ch 2		
BG	50	100	150
a F 7	20	25	25
b P 9	6	8	8
c	22,8	27,3	28,3

Dimensional variations according to DIN 7168 medium.  
Deviating dimensions on request.



## Hand wheels

type	d	N	b	n	L	G	D	P1st dH6 & H7	Weight [kg]
BG 5	80	26	13,0	16	30	58,5	22	10	0,16
BG 10	125	31	15,0	18	34	67,5	23	14	1,3
BG 25	160	36	18,0	20	37	67,5	23	14	1,5
BG 50, 100	200	42	20,5	24	45	80,0	26	18	1,0
BG 100, 150	250	48	23,0	28	51	90,0	28	24	1,3

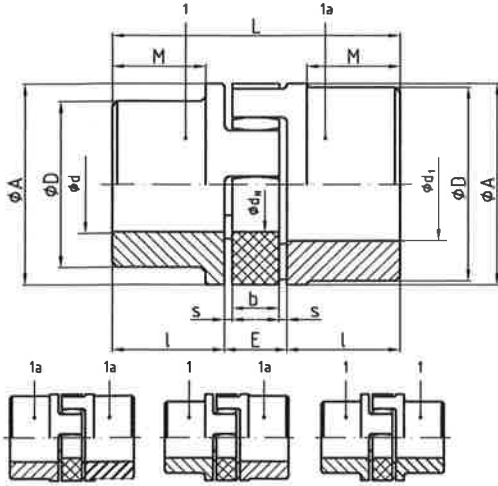
Special executions on request are possible  
Subjects to measurements changes, representation not obligatory



# Elektric cylinder accessories

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## Elastic coupling (KU)

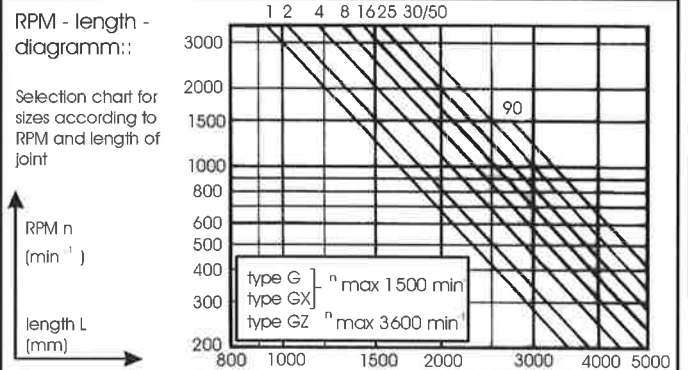
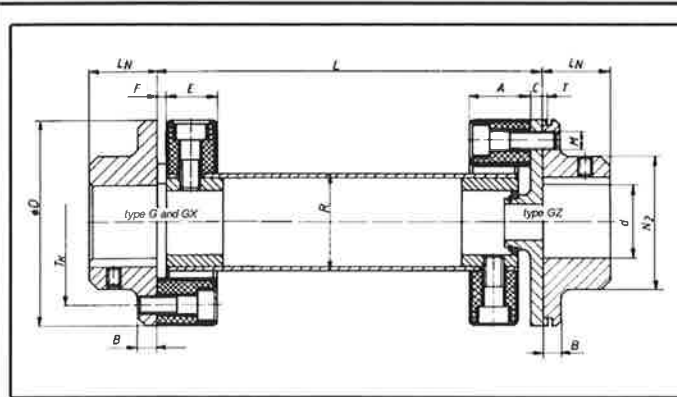


Type R	Mt nom in Nm at 80° Shore <sup>1</sup>	Mt nom in Nm at 92° Shore <sup>1</sup>	Mt nom in Nm at 98° Shore <sup>1</sup>	holes pilot drill	hub 1 finished φd	hub 1a finished φd <sub>1</sub>	φA	φD	φD <sub>1</sub>	L	l	E	s	b	M	φd <sub>1</sub>	material	weight <sup>3)</sup> type 1 in kg	weight <sup>3)</sup> type 1a in kg		
14	4	7	12	-	4	14	-	-	-	30	30	-	35	11	13	1,5	10	-	10	0,14	0,14
19/24	5	10	17	4	6	19	-	6	24	40	32	40	66	25	16	2	12	-	18	0,32	0,36
24/28	17	35	60	6	8	24	6	8	28	55	40	48	78	30	18	2	14	24	27	0,60	0,72
28/38	46	95	160	8	10	28	8	10	38	65	48	65	90	35	20	2,5	15	28	30	0,97	1,33
38/45	93	190	325	10	12	38	36	38	45	80	66	77	114	45	24	3	18	37	38	2,08	2,46
42/55	130	265	450	12	14	42	40	42	55	95	75	94	126	50	26	3	20	40	46	3,21	3,93
48/60	150	310	525	13	15	48	46	48	60	105	85	102	140	56	28	3,5	21	45	51	4,41	5,19
55/70	180	375	625	18	20	55	52	55	70	120	98	120	160	65	30	4	22	52	60	6,64	8,10
65/75 <sup>2)</sup>	205	425	640	20	22	65	63	65	75	135	115	135	185	75	35	4,5	26	61	68	10,13	11,65
75/90 <sup>2)</sup>	475	975	1465	28	30	75	73	75	90	160	135	160	210	85	40	5	30	69	80	16,03	19,43

Finish-borings are made according to the ISO system of tolerances H7. Feather key grooves are made according to DIN 6885/1. The max. angle shift is 1°30', the twisting angle 3,2° at Mt nom. The operable temperature range lies between -40°C and +100°C.

<sup>1)</sup> The rated turning moments are valid for normal operation with slight jolts; due to the higher start-up moment of three-phase squirrel cage motors an impact factor of 2 must be taken into account.  
<sup>2)</sup> from size 65/75 95° Shore on  
<sup>3)</sup> weight for GG, aluminium approx. 60% less.  
 Product as delivered: enclosed

## Elastic propeller shafts G/GX/GZ



size	rated torque [Nm]			weight [kg]		max. shift of angle		A	B	C	φD	d	d max	E	F	L <sub>II</sub>	φN <sub>1</sub>	R	T	T <sub>x</sub> / M
	G	GX	GZ	for 2 hubs	for 1 m tube	G+GZ	GX													
1	10	10	10	1,0	1,1	3°	1°	24	7	5	56	8	25	22	2	24	36	30	1,5	φ 44 / 2 x M6
2	20	30	20	2,2	1,4	3°	1°	24	8	5	85	12	38	20	4	28	55	40	1,5	φ 68 / 2 x M8
4	40	60	40	3,4	1,6	3°	1°	28	8	5	100	15	45	24	4	30	65	45	1,5	φ 80 / 3 x M8
8	80	120	80	7,3	2,2	3°	1°	32	10	5	120	18	55	28	4	42	80	60	1,5	φ 100 / 3 x M10
16	160	240	160	12,4	2,5	3°	1°	42	12	5	150	20	70	36	6	50	100	70	1,5	φ 125 / 3 x M12
25	250	370	250	19,1	3,1	3°	1°	46	14	5	170	20	85	40	6	55	115	85	1,5	φ 140 / 3 x M14
30	400	550	400	31,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	φ 165 / 3 x M16
50	600	-	600	32,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	φ 165 / 3 x M16
90	900	-	900	58,7	7,6	3°	1°	70	19	5	260	30	110	62	8	80	160	125	2,0	φ 216 / 3 x M20

Special executions on request are possible  
 Subjects to measurements changes, representation not obligatory



# Calculations

## Symbols:

F (kN)	= dynamic load	$P_{Elz}$ (kW)	= operating performance of the spindle gear
v (m/min)	= lifting speed	$P_{ges}$ (kW)	= operating performance of all spindle gears
s (mm)	= spindle pitch	$P_{Anl}$ (kW)	= operating performance of the system
n (R/min)	= revolutions/min at the worm	$\eta_{ges}$	= operating efficiency (preselection table page 5)
i	= worm gear reduction	$\eta_{Anl}$	= efficiency of the system
$f_M$	= factor for spindle load torque	$M_{sp}$ (Nm)	= spindle load torque
		M (Nm)	= load torque at the worm

## Driving power:

If the required driving power cannot be read sufficiently clear from the preselection and performance charts, it is computed as follows:

Driving power  $P_{Elz}$  per spindle gear:

$$P_{Elz} = \frac{F \times v}{61,2 \times \eta_{ges}}$$

## Driving power $P_{ges}$ all of multiple spindle systems:

After adding the individual performances  $P_{Elz}$  to reach the total performance  $P_{ges}$ , the losses of spacer shafts, bevel gears, couplings, pedestal bearings, alignment errors etc. must be allowed for.

Standard value in case of 2 spindle gears	$\eta$ 0,95
3 spindle gears	$\eta$ 0,90
4 spindle gears	$\eta$ 0,85
6-8 spindle gears	$\eta$ 0,80

$$P_{Anl} = \frac{P_{ges}}{\eta_{Anl}}$$

## Starting capacity:

To compute the starting capacity the performance value  $P_{Elz}$  or  $P_{Anl}$  is multiplied by 1.3.

## Ambient temperature:

At an ambient temperature higher than +20°C the operating factor must be reduced in correspondence with the following table.

Ambient temperature °C	50	60	70	80
max. permiss.OF in %/h	18	15	10	5
max. permiss.OF in %/10min	27	22	15	8

## Load torque at the worm:

$$M = \frac{F \times s}{2 \times \pi \times i \times \eta_{ges}}$$

$$M = \frac{9550 \times P_{Elz}}{n}$$



# Operating and Mounting Instructions for Electric cylinders

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## Mounting

Spindle gears without swivelling equipment must be mounted in true alignment on a flat surface which must be so stiff that it can assume the maximal load without oscillations or deformations.

In lifting systems the spindle noses (in case of the basic type) or the traveling nuts (in case of the traveling nut type) must lie level with each other before the worms of the spindle gears are connected.

Before the driving gear is mounted the sense of rotation must be checked: in bevel gear driven lifting systems the sense of rotation can easily be confused; the result would be faulty mounting and possible damage of the installation.

Before putting it into service the electric cylinder or the lifting system should be turned by hand once. If this requires non uniform forces the electric cylinders are misaligned both to each other and to the installation. Adjustments are necessary; the fastening screws must be worked loose and the whole lifting gear must again be turned by hand.

Oil-lubricated worm gears: the upper screwed sealing plug must be replaced by the vent screw provided.

If our specifications and performances according to the technical instructions are not observed and/or the components are not used as prescribed, any warranty claims will no longer be applicable.

## Maintenance

By electric cylinder the worm gears are filled with the greasing AGIP GRS M2 and the tube systems are filled with the greasing Klüberplex GE 11-680 in the factory.

Grease the worm gear and the tube system only in the driven out condition with the lubricating nipples at regular intervals (~ 30-50 operating hours). The intervals depend on the given operating conditions and the duty cycle of the spindle gears. In case of doubt please set up the lubrication plan together with us. After approx. 200-300 operating hours the wear of the tube system due to the backlash of threads should be checked. The maximal normal backlash of single trapezoid threads must not exceed 1/4 of the thread pitch. In the cases of multiple threads or special threads 1/4 of P is the maximum normal acceptable backlash.

When the maximum normal backlash is reached, the traveling nut in the tube system must be replaced. After a short run-in period all screws must be checked.

After approx. 500 operating hours we recommend cleaning gear and spindle to remove the grease, checking all parts as to wear, and recharging them with new grease.

Recommended lubricants: Shell Darina 2, Castrol Grease MS3, BP Energrease LS-EP2.

The lubricant recommended can be used both for gears and spindles. If a high-grade spindle lubricant has to be used, we recommend Klueberplex GE 11-680.

For special conditions (e.g. higher temperatures) we recommend the lubricants specified in the enclosed technical manual.

For oil-lubricated electric cylinders please ask for a special service manual.

If you order spare parts, the gear specifications, marked on the type plate must be provided.



# Tolerances Electric cylinders

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## External dimensions

For connecting dimensions, the tolerances given in the corresponding drawings are valid. The values where no tolerance is indicated are untoleranced dimensions.

## The axial backlash of the spindle

The axial backlash of the traveling nut in the tubing system is necessary for the building-up of an adequate lubricating film. Wear during operation will increase the axial backlash; please pay attention to our operating and maintenance instructions.

Spindle pitch P (mm)	6	7	8	10	12	16
max. axial backlash of the threaded spindle as manufactured (mm)	0,25	0,26	0,28	0,30	0,32	0,40
max. permissible axial backlash due to wear (mm)	1,5	1,7	2,0	2,5	3,0	4,0

## Pitch errors of the spindle

Due to the work tolerances of the processing machines a pitch error of 0,05 to 0,075 mm per 300 mm threaded length results in whirl thread spindles. In the practice this error has hardly any effect on the precision of the lifting. In case of doubt please contact us.

## Backlash of tooth flank

The backlash of the tooth profile between worm and wormwheel is 0,05 to 0,15 mm as manufactured. Due to the high speed-increasing ratios the effect on the lifting motion is practically imperceptible.

## Adjustment tolerance

An adjustment tolerance around 0,1 mm can easily be achieved with one-side load direction and manual operation. In the case of an alternation of load the above-mentioned points must be observed. For manual operation also fixed stop motion devices can be used.

In case of a motor drive a number of additional factors must be taken into account, e.g. speed of the driving motor, lifting load, flywheel effect, speed-reducing ratios in the piece parts, efficiency, load direction etc.. If suitable limit switches are used, which are adjusted in the process of assemblage, the stop point can be determined relatively exactly (prerequisite: constant operating conditions).

If in certain cases greater halting precision is required, braking motors or motor operators equipped with brakes must be used. Fixed stroke-arresting devices are not permissible. If in certain cases running against fixed devices is unavoidable, adequate steps must be taken to make sure that overstress is prevented (e. g. by slipping clutch, load-controlled motor cutoff, etc.).

For further information please contact us.



# Questionnaire

COMPANY \_\_\_\_\_  
ADDRESS \_\_\_\_\_  
NAME \_\_\_\_\_ Dept \_\_\_\_\_ Phone \_\_\_\_\_ Fax \_\_\_\_\_

To be able to prepare a proposal meeting your specific demands, please provide us with the following information:

In which systems are the lifting elements to be used?

Number of systems \_\_\_\_\_  
Number of lifting elements per system \_\_\_\_\_

## AXIAL LOAD

per system	pressure	dynamic	_____ kN	tension	dynamic	_____ kN
		static	_____ kN		static	_____ kN
per spindle	pressure	dynamic	_____ kN	tension	dynamic	_____ kN
		static	_____ kN		static	_____ kN

## OPERATING CONDITIONS

Effective stroke \_\_\_\_\_ mm  
Side forces acting \_\_\_\_\_ kN  
Lifting speed desired \_\_\_\_\_ mm/min  
Mounting of spindle \_\_\_\_\_ vertically/horizontally  
Ambient temperature \_\_\_\_\_ °C  
Duty cycle/load conditions per 10min \_\_\_\_\_  
per hour \_\_\_\_\_  
Distance per alternation of load \_\_\_\_\_ mm

## FOR WHICH PARTS DO YOU WISH TO RECEIVE OUR OFFER?

### Electric cylinder with trapezoid thread spindle

Spindle nose \_\_\_\_\_ 0/1/2/3/4/5/6/So  
Separate spindle nose \_\_\_\_\_

### Electric cylinder with ball bearing spindle

Spindle nose \_\_\_\_\_ 0/1/2/3/4/5/6/So  
Separate spindle nose \_\_\_\_\_

bevel gear box \_\_\_\_\_ yes/no  
Elastic cardan shaft \_\_\_\_\_ yes/no  
Couplings \_\_\_\_\_ yes/no  
Pedestal bearing \_\_\_\_\_ yes/no  
Motor flanges \_\_\_\_\_ yes/no  
Motor; voltage \_\_\_\_\_ frequency \_\_\_\_\_ system of protection \_\_\_\_\_  
Limit stop \_\_\_\_\_ yes/no  
Crank handle, handwheel \_\_\_\_\_ yes/no  
bearing console \_\_\_\_\_ yes/no  
Swivelling console \_\_\_\_\_ yes/no  
Swivelling plate \_\_\_\_\_ yes/no  
Other \_\_\_\_\_

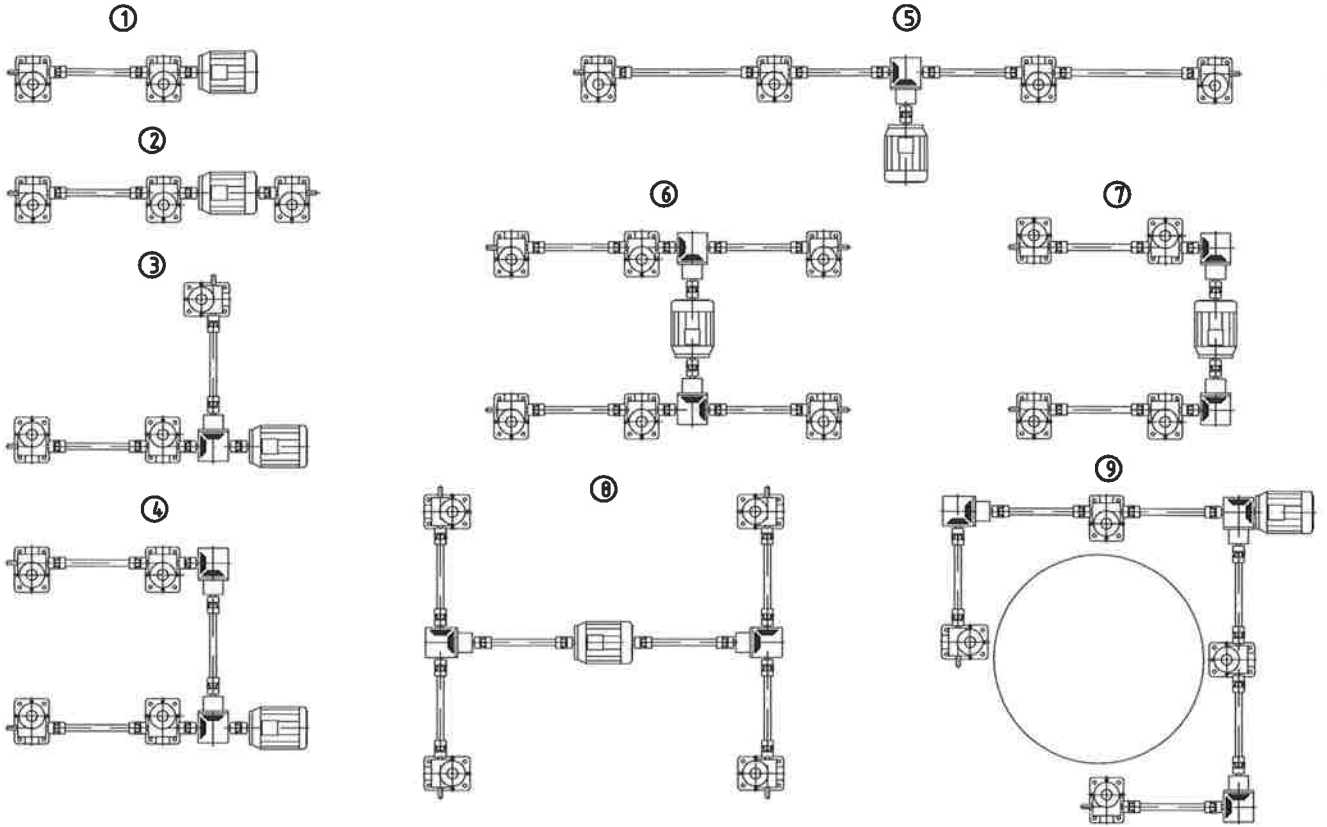


# Examples for arrangements

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

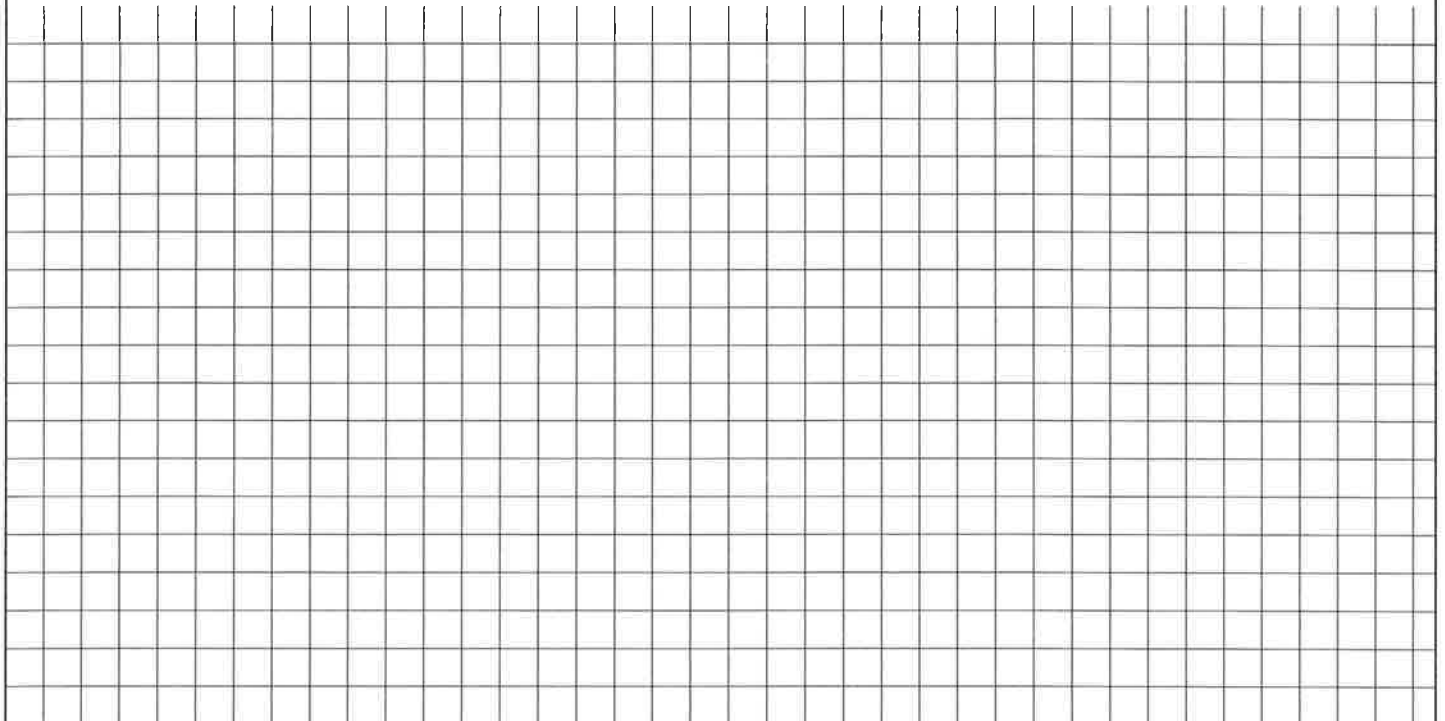
Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Anordnungsbeispiele



Please provide us with a sketch on the desired arrangement as shown above or according to your own ideas.  
Please enter the distance from spindle to spindle and possibly lateral guidings into the sketch.  
If you wish to receive an offer on spindle lifting elements actuated by multi-thread spindles or ball screw spindles,  
or if stainless material is desired, please let us know, too.

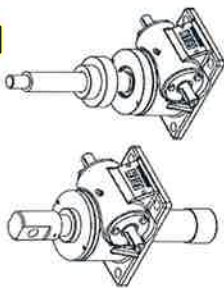
## Sketch



# Product overview 03/2015

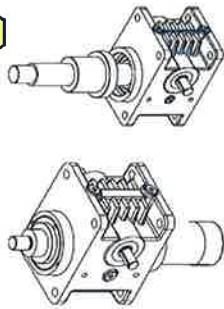
**SG**

Screw jack  
Classic



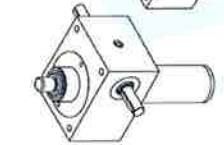
**HSG**

High performance-  
Screw jack



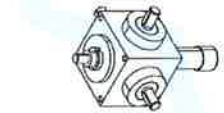
**BG**

Screw jack  
Cubic



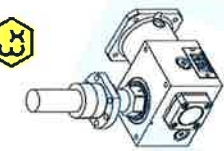
**SHG**

Quick-lifting  
screw jack



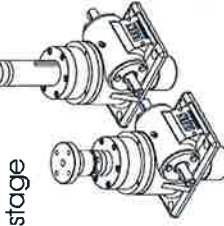
**SH**

Servo lifting  
gear



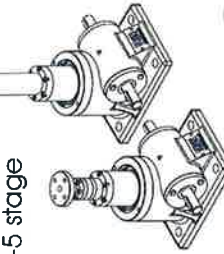
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



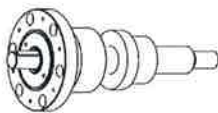
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



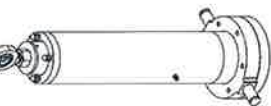
**SLA**

Spindlebearing



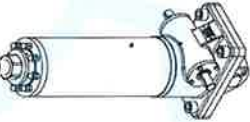
**SEZ**

Spindlebearings-  
Cylinder



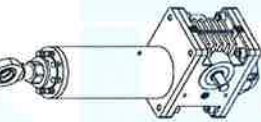
**ELZ**

Electric cylinder



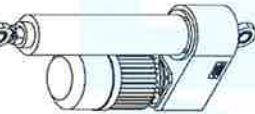
**HELZ**

High performance-  
Electric cylinder



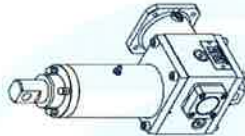
**ELZP**

Electric cylinder  
Parallel



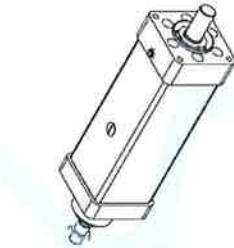
**SHELZ**

Servo electric-  
cylinder



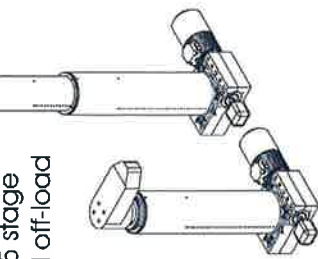
**EPNEU**

Spindle-  
Electric cylinder



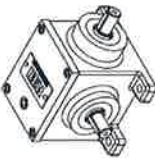
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



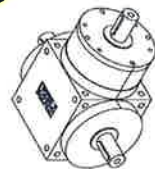
**K**

Bevel gear  
Type K



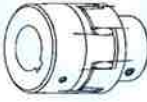
**H**

Bevel gear  
Type H



**R / GS**

Elastic / backlash-free  
Coupling



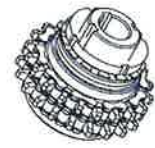
**RT**

Slip hub



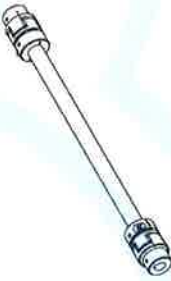
**RK**

Slip coupling



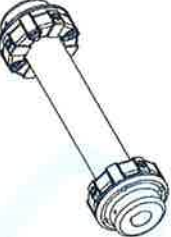
**ZR**

FREN  
Connecting shaft

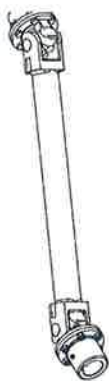


**G / GX**

Elastic  
Connecting shaft

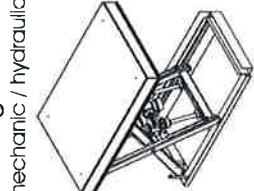


Cardan shaft



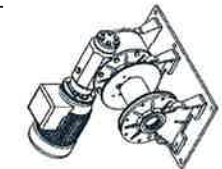
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



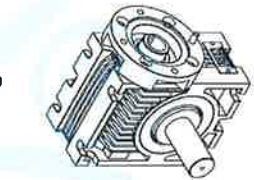
**PLG**

Planetary gear



**uniCe**

Worm gear

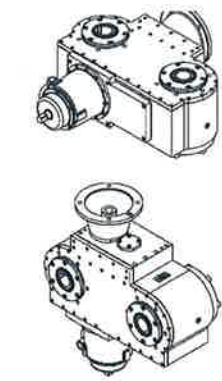


**HA**

Lifting system



**Special gear**



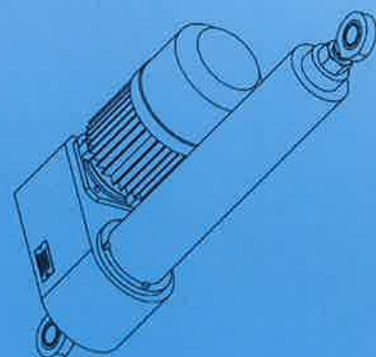




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**Electric cylinder parallel  
Type ELZP**



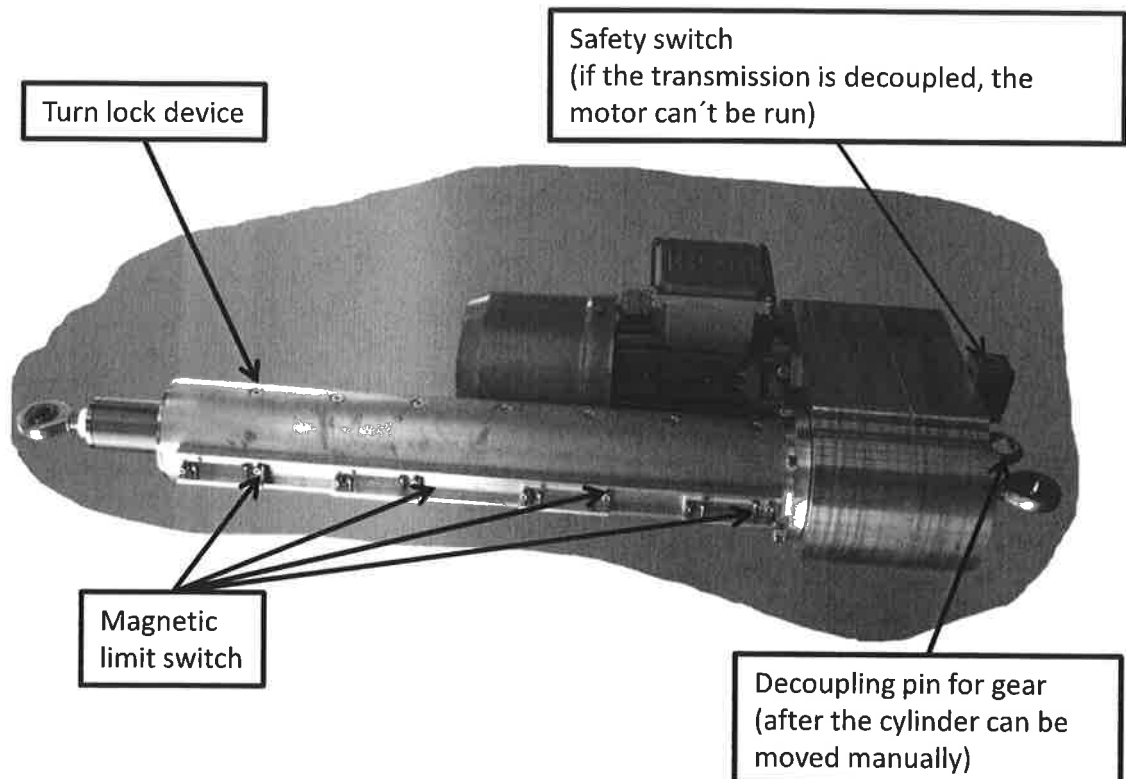
# ELZP

## Elektrozylinder parallel

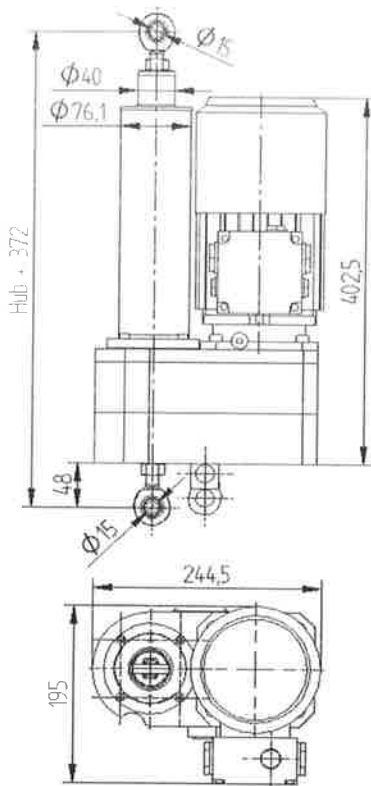
The newly developed electric cylinder ELZP is an ideal extension of the comprehensive program of gear of the company Enzfelder. With the special construction, motor receives parallel to the cylinder tube, you get a very compact cylinder which convinces with its maximum efficiency. In combination with the specially developed transmission decoupling system, for manual emergency operation, the ELZP is ideal for opening and closing of gates, doors, windows and flaps. This is just one of countless possibilities for the cylinder is ideal for, you just need to let your ideas run wild.

### Advantages of the cylinder:

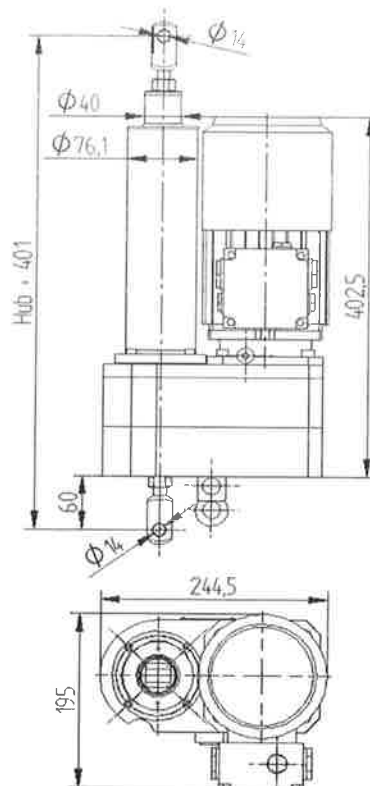
- + Compact design and maximum efficiency
- + High lifting speeds
- + Long life
- + Large selection of custom equipment
- + Transmission decoupling system for manual emergency operation
- + Wide application range



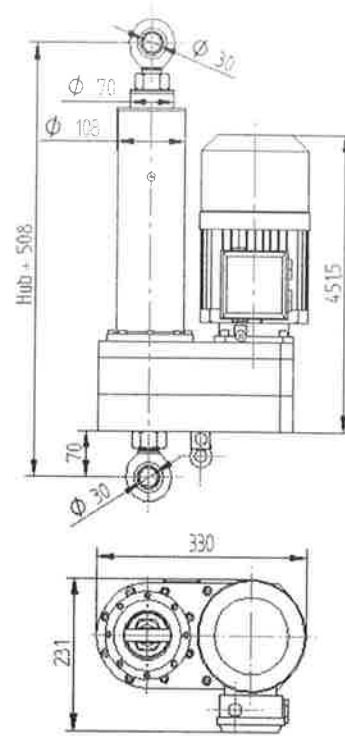
**ELZP 0006/ 0018**  
with swivel head



**ELZP 0006/ 0018**  
with clevis



**ELZP 0050**  
with swivel head



Gearbox						Motor			
Designation	Nominal power	Lifting speed	Duty cycle	Spindle	Max. rpm	Designation	Power	Voltage	Brake
ELZP 0006	6 kN	2,933 m/min	30 %/h	KGT 1610	1400	AC motor 7WAR 72N4-BRS	0,37 kW	400 V / AC	230 V
ELZP 0018	18 kN	1,653 m/min	30 %/h	KGT 2510	900	AC motor 7WAR 81N4-BRS	0,75 kW	400 V / AC	230V
ELZP 0050	50 kN	1,467 m/min	30 %/h	KGT 3210	1370	AC motor 7WAR 91S4-BR20	1,1 kW	400 V / AC	230 V

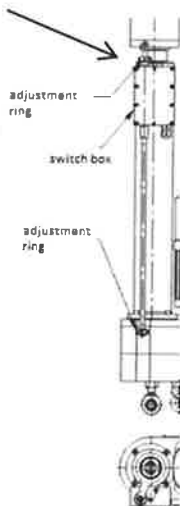
**Stepless limit switch SEA**

operating or operating and emergency limit switches turn only at the top and the lower end position switch as an opener or closers possible

**Switching capacity**

250 V	AC	13 A
250 V	AC	9 A
250 V	AC	6 A
250 V	AC	3 A
24 V	DC	8 A
24 V	DC	2 A

Possibilities:  
SEA2 or SEA4



**Magnetic limit switch MEA**

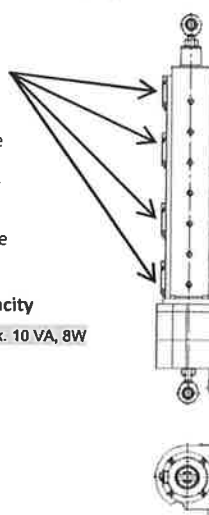
**Magnetic switch:**

adjustable limit switch, there are also intermediates possible. This type of limit switch is always with a turn lock device

**Switching capacity**

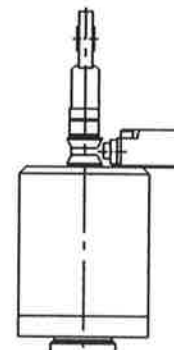
max. 250 V AC/DC 0,5 A max. 10 VA, 8W

Cablelength: 1 m  
Possibilities:  
MEA1 bis MEA10



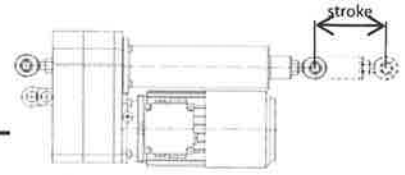
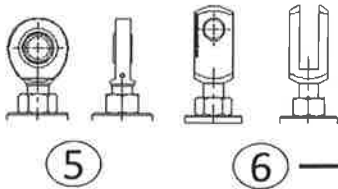
**Tension-pressure Overload protection ÜS**

With the Overload protection the process path can slightly differ but not more than 9 mm.



SI = with safety nut  
 00 = without safety nut

GEK = with transmission decoupling system  
 00 = without gear decoupling system



AC = AC brake motor  
 DC = DC brake motor  
 00 = without motor

00 = without turn lock device  
 VS = with turn lock device

00 = no limit switch  
 MEA = magnetic limit switch  
 SEA = stepless limit switch

00 = no Overload protection  
 Üsx = Overload protection  
 x is the release force in kN

Standard ratio  
 on request are  
 other reductions  
 possible

Refers to the  
 possible nominal power

ELZP  
 Electric cylinder  
 parallel

**ELZP 0006-5,44-5-GEK-SI-450-AC-VS-5-SEA4-ÜS7**

Type

Gear size

Reduction i

Spindle nose

Transmission decoupling

Safety nut

Stroke mm

Motor

Turn lock device


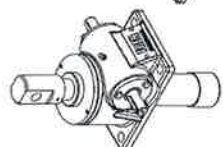

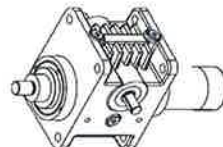
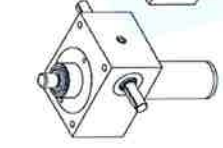

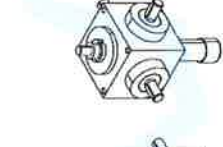

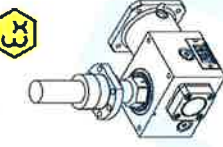
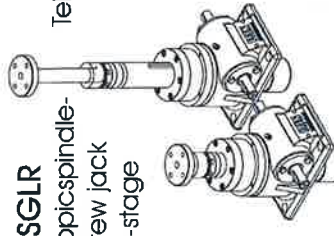
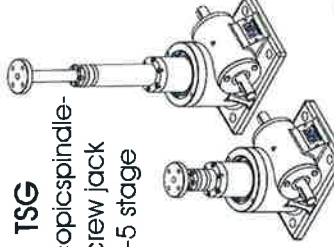

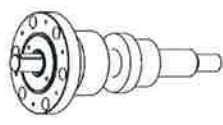



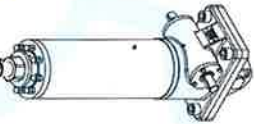

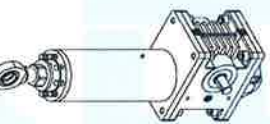

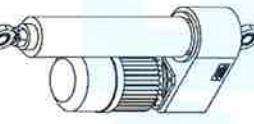

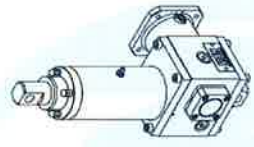


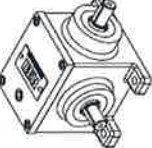



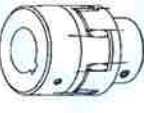



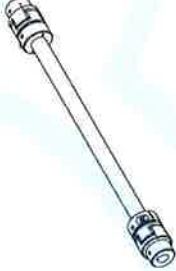
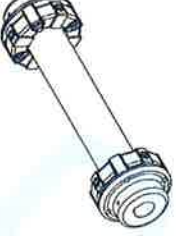
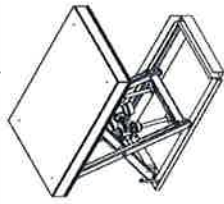



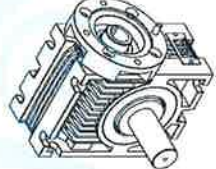

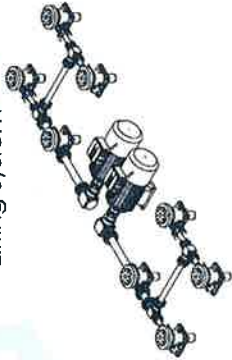
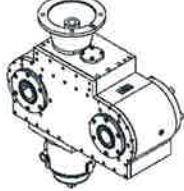
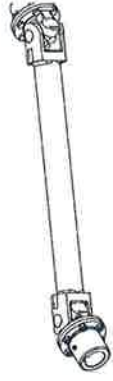
Head on the housing

Limit switch

Number of Switches

Tension-pressure -overload protection

# Product overview 03/2015

<p><b>SG</b> Screw jack Classic </p> 	<p><b>HSG</b> High performance- Screw jack </p> 	<p><b>BG</b> Screw jack Cubic</p> 	<p><b>SHG</b> Quick-lifting screw jack </p> 	<p><b>SH</b> Servo lifting gear </p> 	<p><b>TSGLR</b> Telescopic spindle- Screw jack 2-stage</p> 	<p><b>TSG</b> Telescopic spindle- Screw jack 2-5 stage</p> 
<p><b>SLA</b> Spindlebearing </p> 	<p><b>SEZ</b> Spindlebearings- Cylinder </p> 	<p><b>ELZ</b> Electric cylinder </p> 	<p><b>HELZ</b> High performance- Electric cylinder </p> 	<p><b>ELZP</b> Electric cylinder Parallel </p> 	<p><b>SHELZ</b> Servo electric- cylinder </p> 	<p><b>EPNEU</b> Spindle- Electric cylinder</p> 
<p><b>K</b> Bevel gear Type K </p> 	<p><b>H</b> Bevel gear Type H </p> 	<p><b>R / GS</b> Elastic / backlash-free Coupling </p> 	<p><b>RT</b> Slip hub</p> 	<p><b>RK</b> Slip coupling</p> 	<p><b>ZR</b> FREN </p> 	<p><b>G / GX</b> Elastic Connecting shaft</p> 
<p><b>HT</b> Lifting table mechanic / hydraulic</p> 	<p><b>SW</b> Rope winche</p> 	<p><b>PLG</b> Planetary gear </p> 	<p><b>uniCe</b> Worm gear</p> 	<p><b>HA</b> </p> 	<p><b>Special gear</b></p> 	<p><b>Cardan shaft</b></p> 



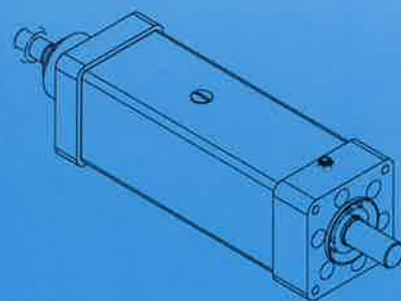
**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

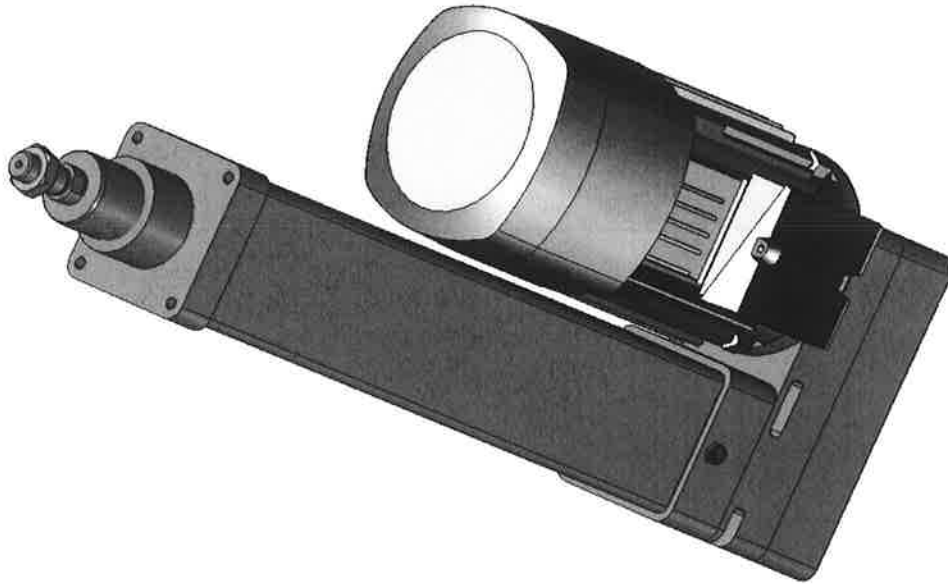
**electromechanical**

**stainless linear cylinder**

**Type EPNEU**



# CATALOG CONTENTS



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page 5	Selection
page 6,7	prefix table / Performance data
page 8,9	Stock number code, size and equipment selection
page 10	Dimensions EPNEU – linear cylinder
page 11	Dimensions EPNEU reduction gear
page 12	Dimensions EPNEU cylinder mounting
page 13	Dimensions EPNEU piston connection
page 14	Mounting and Operating Instructions - Summary

# GENERAL PRODUCT INFORMATION

for

## EPNEU Stainless linear cylinder

Mechanical linear drives are often more preferred than pneumatic or hydraulic ones. The simple control and precise positioning (up to 1/100mm), in connection with the high efficiency and the power density makes it to a real allround talent. Because it does not use oil like hydraulic cylinder, even in a case of damage there is no outflow of oil. All outsideparts of the cylinder is made out off stainless steel, it is perfect useable even in the food industrie, chemical industrie and packing industrie.

Through a jointless connection between piston rod and piston end, there is no pullout or twisting even by high loads.

This modular system is rounded off by three-phase AC-motor, direct current or stepping motors / servomotors.

You can choose between direct connection of the motor shaft and cylinder shaft, or through different front end gears (axial or parallel), thereby adjust the speed of the cylinder. So you can reach the max. efficiency of the drive system.

Through lifetimecalculations it is possible to estimate the true lifetime very exactly under real conditions.

The front end gears or other components are also availble in stainless steel.

Because of the simple structure of the electro mechanical linear cylinder „EPNEU“, the cost-to-performance ratio is very good.

The standard cylinders are equipped with ball screw drives.

Also useable is, if the situation required, a trapezoid or planetary drive.

The same connection measurements to the standardized pneumatic linear cylinder, makes it possible to use components from the automation sector.

If used as a total closed design (IP66 to IP68), the lubrication and filter points are totally sealed.

The useage of the cylinder should allthrough be questioned in the factory. (depends on speed , load, duty cycle,.....)



# QUESTIONNAIRE

traveling distance = stroke(in mm) + 2x safety (2x min.20mm)= \_\_\_\_\_ mm  
(for example 100 + 40)

holding force: \_\_\_\_\_ N ( for example 500N)

dyn. force : \_\_\_\_\_ N (for example 400N) (announce the progress at variable force)

self-locking needed: YES / NO (for example No)

pitch: \_\_\_\_\_ mm (for example. ?? uninportant)

moving speed: \_\_\_\_\_ mm/sec (for example 150mm/sec)

number of strokes (double stroke) per minute or per hour: \_\_\_\_\_ (for example 6 x pro min)

Number of strokes per day: \_\_\_\_\_ ( for example 2 shift = 2 shift x 8 hour x 60min x 6 = 5760 strokes)

needed lifetime: \_\_\_\_\_ Years ( for example 5 Years)

installation: jointed / cylinder front **and** base fixed / cylinder front **or** base fixed  
( for example jointed )

# SELECTION

## life control

Lifetime calculation for comparison with the table Pre-Selection – Performance Data

lifetime travel =

$$(\text{number of stroke/day}) \times (\text{stroke} \times 2) \times (\text{favored lifetime}) \times 0,000365 = \text{km}$$

for example.: 5760 x (100 x 2 = 200) x 5 x 0,000365 = 2102,4km  
 in the example, the lifetime of travel in 5 years 2102,4km!!!

Now select the size and pitch from Table Pre-Selection – Performances

In the example chosen: EPNEU040 with KGT1605

## Congestion control

compare permissible travel with size, holding force and load:

control force – traveling distance				
Type / size	max. stroke	jointed	front <u>or</u> base fixed	front <u>and</u> base fixed
EPNEU040	800mm	1.300N	2.000N	2.600N
EPNEU050	900mm	2.800N	4.000N	4.500N
EPNEU063	1100mm	3.500N	4.500N	6.000N
EPNEU080	1200mm	6.000N	8.500N	8.500N
EPNEU100	1500mm	10.000N	13.000N	13.000N
EPNEU125	1500mm	15.000N	18.000N	18.000N

For example.: holding force is bigger as dyn. load = 500N is lesser as 1300N therefore the cylinder is sufficient!

## Speed control

Calculate drive speed:

$$\left( \frac{\text{movement speed} \times 60}{\text{pitch of spindle}} \right) = \text{Revolutions per minute} \quad \text{for example}$$

(50mm/sec)                      5mm                      =                      1800U/min

Maximum speed (RPM) at traveling distance							
Type / traveling distance	200mm	350mm	600mm	800mm	1000mm	1250mm	1500mm
EPNEU040	3000	1500	700	450	300	200	150
EPNEU050	3000	1700	800	500	350	240	180
EPNEU063	3000	2500	1120	720	500	320	240
EPNEU080	3000	3000	1400	900	600	400	300
EPNEU100	3000	3000	1900	1150	800	520	370
EPNEU125	3000	3000	2200	1400	950	650	480

For example: actual speed is less than maximum speed (3000RPM at 200mm traveling distance), therefore the cylinder is usable!

**PRE-SELECTION – PERFORMANCE DATA**

<b>TYPE</b>	<b>EPNEU 040</b>	<b>EPNEU 050</b>	<b>EPNEU 063</b>	<b>EPNEU 080</b>	<b>EPNEU 100</b>	<b>EPNEU 125</b>
<b>Spindle</b>	<b>KGT 1605</b>	<b>KGT 2005</b>	<b>KGT 2505</b>	<b>KGT 3205</b>	<b>KGT 4005</b>	
Nominal force N	2100	2500	3000	4500	5200	
Efficiency cylinder	0,86	0,84	0,8	0,78	0,75	
Torque without load *	0,6	0,7	0,8	0,9	1	
Torque for nominal force **	2,54	3,07	3,78	5,49	6,52	
Lifetime distance at nominal force (km)	630	630	630	630	630	
Lifetime distance at 50% nominal force (km)	5000	5000	5000	5000	5000	
force stat. N						
<b>Spindle</b>	<b>KGT1610</b>	<b>KGT2010</b>	<b>KGT 2510</b>	<b>KGT3210</b>	<b>KGT 4010</b>	
Nominal force N	2600	3000	3500	8000	10000	
Efficiency cylinder	0,9	0,88	0,87	0,86	0,83	
Torque without load *	1	1,1	1,15	1,2	1,3	
Torque for nominal force **	5,6	6,53	7,55	16,01	20,48	
Lifetime distance at nominal force (km)	1250	1250	1250	1250	1250	
Lifetime distance at 50% nominal force (km)	10000	10000	10000	10000	10000	
force stat. N						
<b>Spindle</b>		<b>KGT 2020</b>	<b>KGT 2520</b>	<b>KGT 3220</b>	<b>KGT 4020</b>	
Nominal force N		3200	4800	8500	11000	
Efficiency cylinder		0,9	0,9	0,89	0,88	
Torque without load *		1,9	1,9	2	2,2	
Torque for nominal force **		13,22	18,88	32,4	41,99	
Lifetime distance at nominal force (km)		1250	1250	1250	1250	
Lifetime distance at 50% nominal force (km)		10000	10000	10000	10000	
force stat. N						

For deviating data or higher loads, please ask at the factory!

Attention: Observe for strokes EPNEU-linear cylinders ( except those marked) are not self-locking!

**PRE-SELECTION – PERFORMANCE DATA**

<b>TYPE</b>	<b>EPNEU 040</b>	<b>EPNEU 050</b>	<b>EPNEU 063</b>	<b>EPNEU 080</b>	<b>EPNEU 100</b>	<b>EPNEU 125</b>
<b>Spindle</b>		<b>KGT 2050</b>	<b>KGT 2550</b>	<b>KGT 3240</b>	<b>KGT 4040</b>	
Nominal force N		2200	4200	5500	13000	
Efficiency cylinder		0,9	0,9	0,9	0,9	
Torque without load *		4	4	3,5	3,7	
Torque for nominal force **		23,45	41,14	42,4	95,66	
Lifetime distance at nominal force (km)		1250	1250	1250	1250	
Lifetime distance at 50% nominal force (km)		10000	10000	10000	10000	
force stat. N						
<b>Spindle</b>	<b>Tr 16 x 2</b>	<b>Tr 20 x 3</b>	<b>Tr 25 x 3</b>	<b>Tr 32 x 4</b>	<b>Tr 40 x 6</b>	
Nennkraft	1500	2600	3300	5600	10500	
Efficiency cylinder	0,28	0,28	0,28	0,28	0,28	
Torque without load *	1	1,1	1,2	1,3	1,5	
Torque for nominal force **	2,71	5,53	6,83	14,03	37,31	
Lifetime distance at nominal force (km)	650	650	650	650	650	
Lifetime distance at 50% nominal force (km)	5000	5000	5000	5000	5000	
force stat. N						
<b>Spindle</b>	<b>Tr 16 x 4</b>	<b>Tr 20 x 4</b>	<b>Tr 24 x 5</b>	<b>Tr 30 x 6</b>	<b>Tr 40 x 7</b>	
Nominal force N	1500	2600	3300	5600	10500	
Efficiency cylinder	0,35	0,38	0,39	0,38	0,34	
Torque without load *	1,2	1,3	1,4	1,5	1,7	
Torque for nominal force **	3,93	5,66	8,13	15,57	36,11	
Lifetime distance at nominal force (km)	650	650	650	650	650	
Lifetime distance at 50% nominal force (km)	5000	5000	5000	5000	5000	
force stat. N						

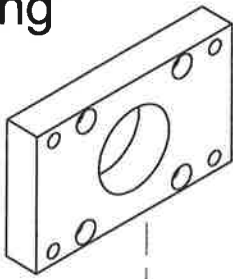
\* The idle torque is in new condition, a fluctuation band of 30%

\*\* To accelerate an approximately 1,5f-to 1.8-fold torque should be provided

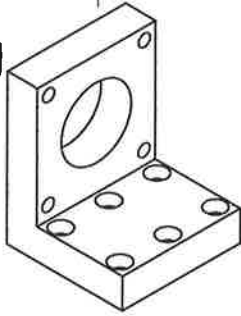
\*\*\* dynamic and static self-locking, except in case of vibrations

STOCK NUMBER CODE

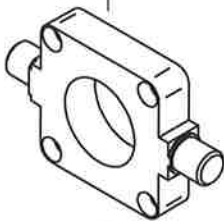
mounting plate BP



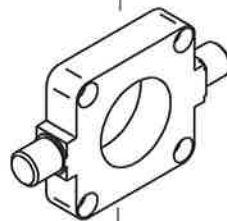
mounting brackets MW



swiveling plate SP

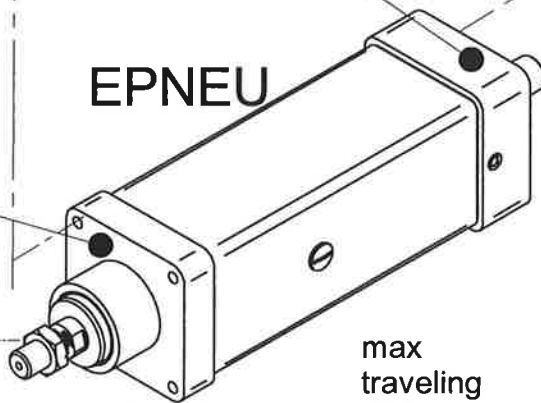


base



front

EPNEU



head1 - thread

head3 - plate

head 5 - pivote head

head 6 forke head



headtype  
head 1 = K1  
head 3 = K3  
head 5 = K5  
head 6 = K6

size  
040  
050  
063  
080  
100  
125

front attachment  
BP  
MW  
SP

max traveling distance  
Special:  
in mm  
max. 1500

Spindle type and dimension see Performance

Preload nut VS2 (2% of the nominal force) or nut backlash MSS standard (0.04 - 0.08mm)

**EPNEU100-K1-XX-150-KGT4010-IT5-VS2**

maximum traveling distance  
100  
150  
200  
300  
500  
800  
1000

spindle accuracy class  
IT7 standard  
IT5  
IT4

motorflange MF

motor is always offered in a separate article

coupling KP

servomotor

AC motor

DC motor

reduction gear axial VGA

reduction gear parallel VGP

motorflange or reduction gear  
MF - motorflange  
VGP9,8 - motor parallel  
VGA9,8 - motor axial

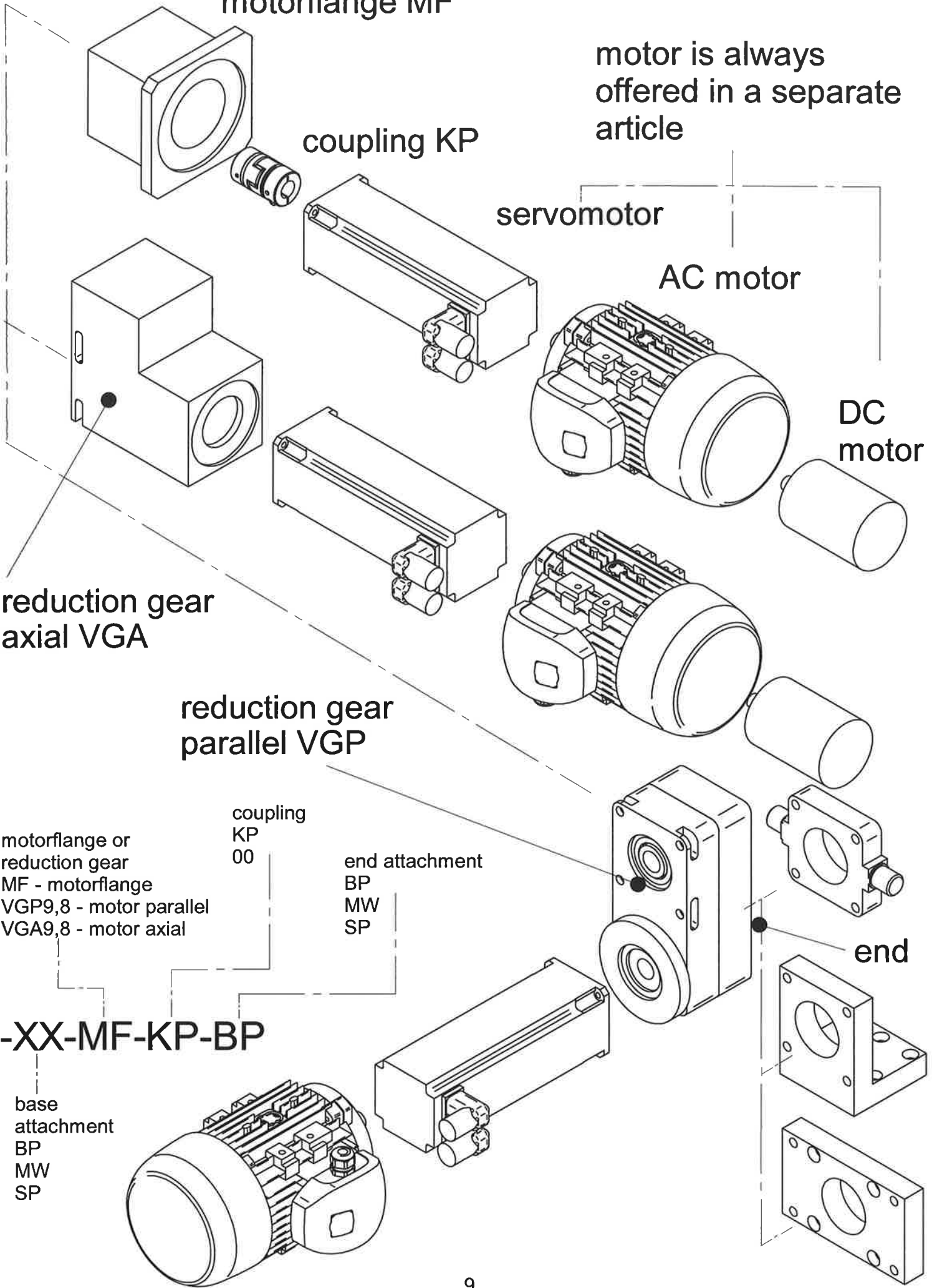
coupling  
KP  
00

end attachment  
BP  
MW  
SP

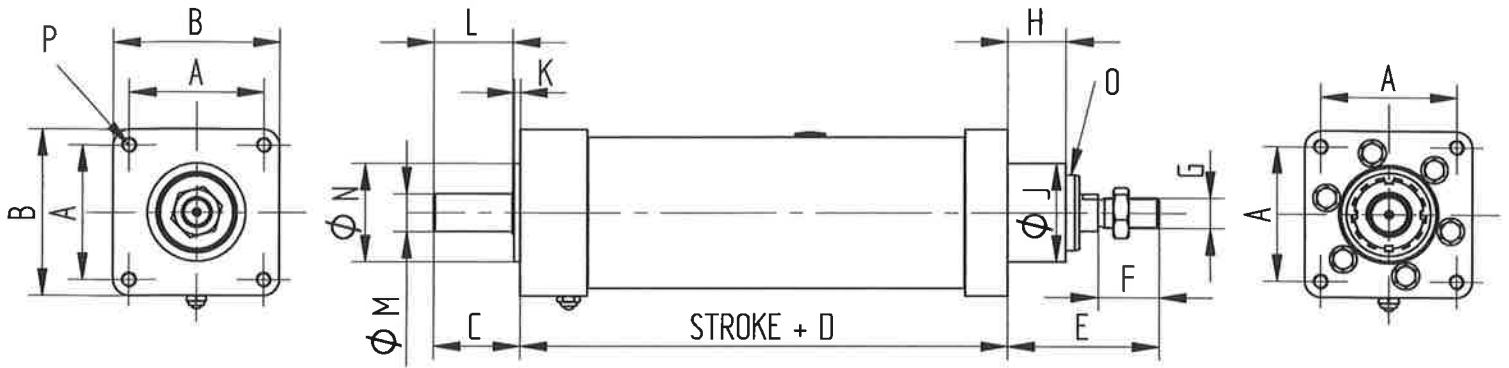
-XX-MF-KP-BP

base attachment  
BP  
MW  
SP

end



# DIMENSIONS

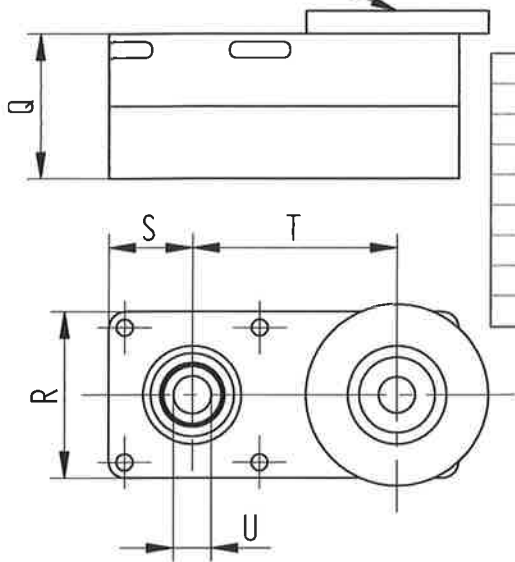


Type	EPNEU 040	EPNEU050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
A	38	46,5	56,5	72	89	110
B	52	64	74	93	110	134
C	25	30	35	45	55	65
D	134	142	152	163	171	194
E	60	75	75	90	99	118
F	25	30	30	40	40	54
G	M12x1,5	M16x1,5	M16x1,5	M20x1,5	M20x1,5	M27x2
H	20	25	25	33	38	44
J	35	40	45	55	65	75
K	4	4	4	4	4	4
L	20	25	30	40	50	60
M	8	10	15	18	25	28
N	35	40	45	55	65	92
O	20	25	30	38	50	65
P	M6	M8	M8	M10	M10	M12

# DIMENSIONS

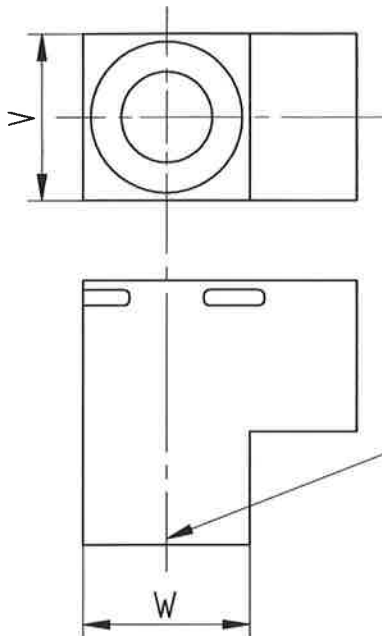
Flangesize depending on the motor

## reduction gear unit VGP



Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
reduction A	1,5	1,5	1,5	1,5	1,5	1,5
reduction B	4,6	4,6	4,6	4,6	4,6	4,6
reduction C	9,8	9,8	9,8	9,8	9,8	9,8
Q	48	66	77	90	96	108
R	52	64	74	93	110	134
S	26	32	37	46,5	55	67
T					135	
U	8	10	15	18	25	28

## reduction gear unit VGA



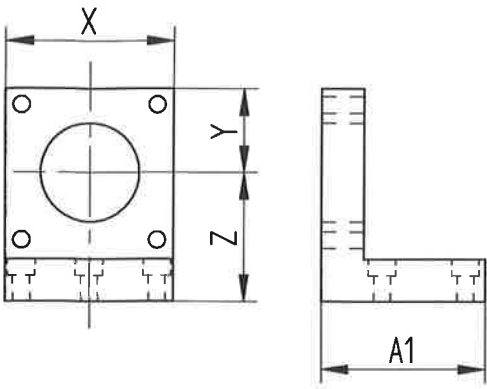
Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
reduction A	1,5	1,5	1,5	1,5	1,5	1,5
reduction B	4,6	4,6	4,6	4,6	4,6	4,6
reduction C	9,8	9,8	9,8	9,8	9,8	9,8
V	52	64	74	93	110	134
W	52	64	74	93	110	134

Flangesize depending on the motor

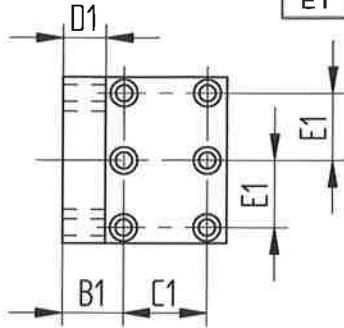


# DIMENSIONS

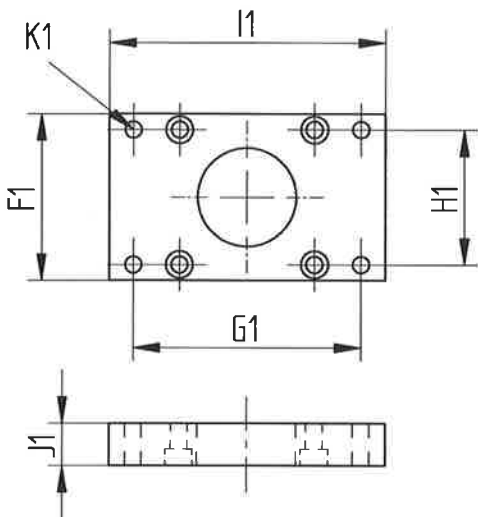
## mounting brackets MW



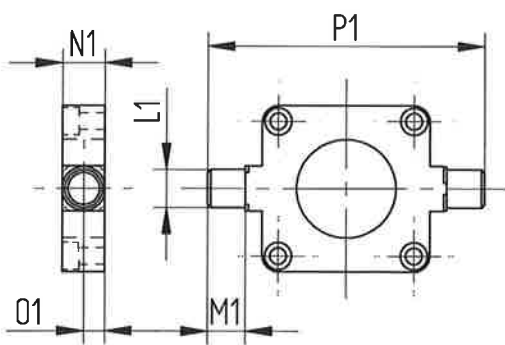
Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
X	52	64	74	93	110	134
Y	26	32	37	46,5	55	67
Z	45	55	65	75	85	100
A1	52	64	74	93	108	134
B1	24	30	32	35	40	46
C1	21	25	33	47	57	75
D1	16	20	23	24	28	33
E1	19	23,25	28,25	36	44,5	55



## mounting plate BP



Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
F1	52	64	74	93	110	134
I1	90	110	120	150	175	210
G1	72	90	100	126	150	180
H1	36	45	50	63	75	90
J1	10	12	12	16	16	20
K1	9	9	9	12	14	16

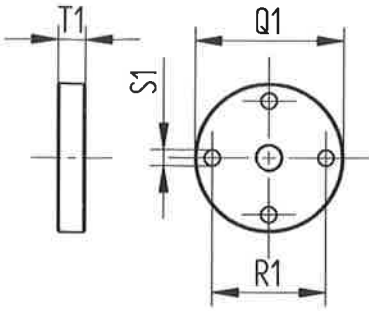


## swiveling plate SP

Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
K1	95	107	130	150	182	210
L1	16	16	20	20	25	25
M1	16	16	20	20	25	25
N1	20	24	24	28	38	50
O1	10	12	12	14	19	25
P1	95	107	130	150	182	210

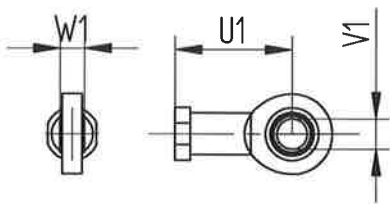
# DIMENSIONS

## head3 = plate



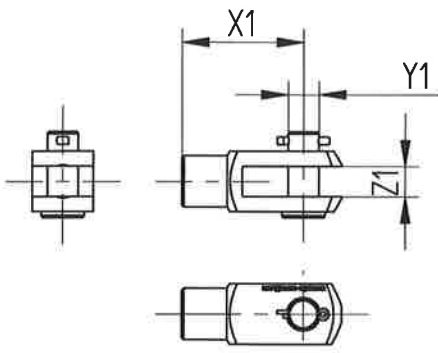
Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
Q1	65	72	72	98	98	120
R1	45	50	50	75	75	100
S1	7	9	9	10,5	10,5	13
T1	12	12	12	18	18	25

## head5 = pivoting head



Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
U1	50	64	64	77	77	110
V1	12	16	16	20	20	30
W1	16	21	21	25	25	37

## head6 = fork head



Type	EPNEU 040	EPNEU 050	EPNEU 063	EPNEU 080	EPNEU 100	EPNEU 125
X1	48	64	64	80	80	110
Y1	12	16	16	20	20	30
Z1	12	16	16	20	20	30

# MOUNTING and OPERATING INSTRUCTIONS

## short version

Control the good against grease leakage and damage when unpacking.

Attention: Because the EPNEU linear cylinder usually is not selflocking, it may be possible that the piston rod moves out! Risk against being trapped or damage of the cylinder.

Control that the cylinder corresponds to the order confirmation and make sure that the limit values are not getting overdriven.

If there are special environments (temperature over 50°C or under 0°C, glass fibre dust, thinner, very short stroke (under 50mm), rolling mills, steel mills, salt water, ... it is necessary to consultate the factory to take defense against it (expansion below, vibration damper,...).

During installation make sure, that the piston rod is parallel to the guides to avoid side forces.

If there is no motor or other drive mounted, keep attention that no side forces are on the drive shaft.

During headmounting, hold the piston rod with a key to tighten.

The mounting may take place only with retracted piston rod.

There should not be any tension in the piston rod, cylinder tube, bottom- or top plate.

Before test drive, check the direction of rotation (drive in and out) and the limit settings.

Only after slow drive test, control of the limit settings and electric (software) was positive, raise up the speed (but still keep attention to the limit values!!).

There is a risk of injury by the moving parts such as piston rod.

Lubrication: once every 500 working hours, if the travel is reach before then once a year.

(for ball screw drives use only grease without MoS2 aditives)

(for trapezoid drives use grease Klüberplex GE11-680 and only for the bearings grease whitout MoS2 aditives)

the below mentioned quantities and measurements are approx values.

The indication „stroke“ is the position of the piston rod, to reach the lubrication point.

type/travel/quantity /pitch/stroke		EPNEU 040		EPNEU 050		EPNEU 063		EPNEU 080		EPNEU 100		EPNEU 125	
KGT pitch 5	200km	30mm	0,5g	30mm	0,8g	30mm	1,1g	30mm	1,6g	30mm	2,2g	30mm	3g
KGT pitch 10	400km	30mm	0,7g	30mm	1,1g	30mm	1,4g	30mm	2,3g	30mm	3,5g	30mm	5g
KGT pitch 16	700km	30mm	0,9g	30mm		30mm		30mm		30mm		30mm	
KGT pitch 20	800km	30mm		30mm	2g	30mm	1,8g	30mm	2,6g	30mm	6g	30mm	8g
KGT pitch 40	1600km	30mm		30mm		30mm		30mm	4,2g	30mm	10g	30mm	13g
KGT pitch 50	1600km	30mm		30mm	2,8g	30mm	5g	30mm		30mm		30mm	
Tr all pitch	250km	30mm	1,1g	30mm	1,6g	30m	2,2g	30m	3,2g	30m	4,4g	30m	7

On the stainless piston rod a mixture of grease and/or abrasion of the piston rod sealing can build up by and by.

The usage in the food industrie has to be specified, to use required seals and grease.

Attention: The EPNEU linear cylinder can get up to 70°C, depending on the duty cycle!!!

# NOTES

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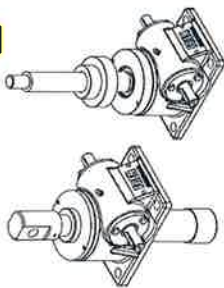
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# Product overview 03/2015

Eichergasse 36, A-2551 Enzelsfeld, Tel.: +43 (0) 2256 81 287 - 00, Fax: +43 (0) 2256 81 287 - 95, office@entzfelder.at, www.entzfelder.at

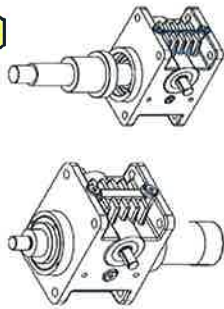
**SG**

Screw jack  
Classic



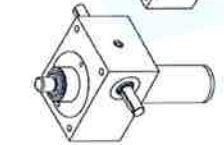
**HSG**

High performance-  
Screw jack



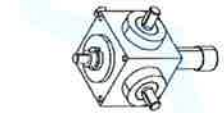
**BG**

Screw jack  
Cubic



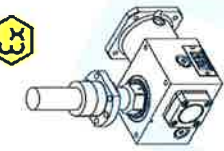
**SHG**

Quick-lifting  
screw jack



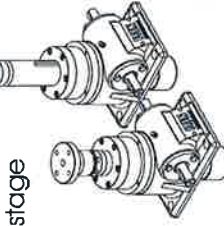
**SH**

Servo lifting  
gear



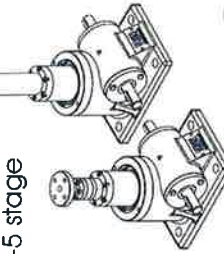
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



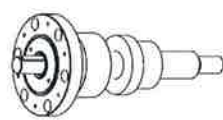
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



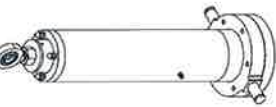
**SLA**

Spindlebearing



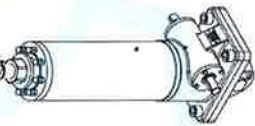
**SEZ**

Spindlebearings-  
Cylinder



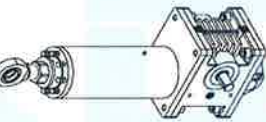
**ELZ**

Electric cylinder



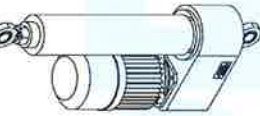
**HELZ**

High performance-  
Electric cylinder



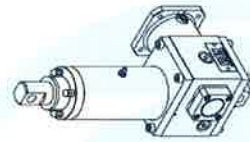
**ELZP**

Electric cylinder  
Parallel



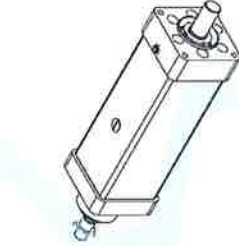
**SHELZ**

Servo electric-  
cylinder



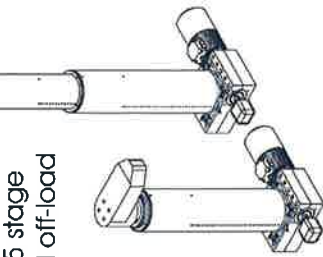
**EPNEU**

Spindle-  
Electric cylinder



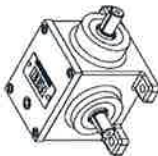
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



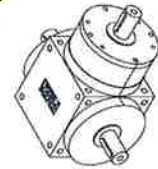
**K**

Bevel gear  
Type K



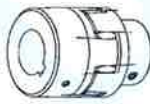
**H**

Bevel gear  
Type H



**R / GS**

Elastic / backlash-free  
Coupling



**RT**

Slip hub



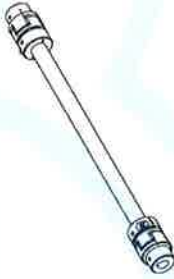
**RK**

Slip coupling



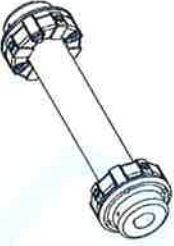
**ZR**

FREN  
Connecting shaft

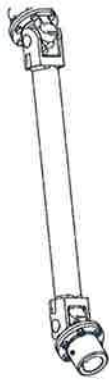


**G / GX**

Elastic  
Connecting shaft

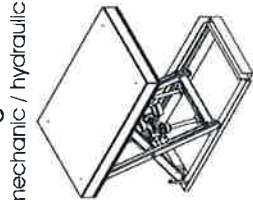


Cardan shaft



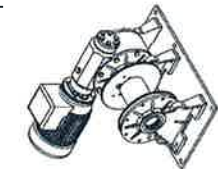
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



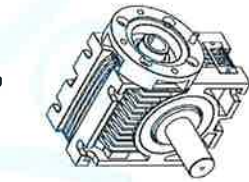
**PLG**

Planetary gear



**uniCe**

Worm gear

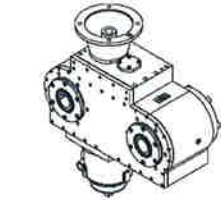


**HA**

Lifting system



**Special gear**





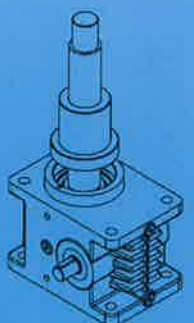
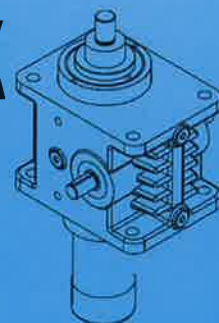
**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**High performances**

**Screw jack**

**Type HSG**



# History

**1969** Mr. Enzfelder established a job shop in Vienna. Equipped with some machinery, the Enzfelder Company manufactured machine parts according to drawings.

Within one year the number of employees rose to 3. The Enzfelder company started manufacturing threaded spindles and nuts according to drawings. Then the range of manufacturing was enlarged by toothed wheels, screw wheels and endless screws according to drawings.

**1974** The company including the complete manufacture was relocated to Enzesfeld.

**1975** The manufacture of spindle gears was launched. The company's experience in the manufacture of trapezoid-threaded spindles, nuts, worm gear pairs and casings was a valuable basis for the construction. After many tests, the serial production of spindle gears was launched one year later. The result was a product characterized by a first-rate price-performance ratio. The product was distributed by dealers all over Europe.

**1981** The planning and construction of small hydropower plants was launched to replace diesel generators. Environmental protection was not really a topic at that time, however, and the production was stopped in 1986.

**1989** The Enzfelder GesmbH company replaced the Franz Enzfelder Company.

**1990** Scissor-type lifting platforms and cable winches were added to the delivery program.

**1991** Resilient spacer shafts were tested and added to the production range. At the same time, the telescopic spindle gear was developed. A patent for this principle was applied for and issued.

**1993** The sale of spindle gears under their own name was launched and presented for the first time at the Hannover industrial fair. We have been approached with a variety of tasks and have provided solutions according to the customers' needs ever since.

**1994** In cooperation with our customers we produced the first bevel gears to specification.

**1995** Spindle bearing arrangements were designed and included in the standard program.

**1996** The Enzfelder company produced planet gear to specification for the first time.

**1998-1999** The standard programs were enlarged. Additionally, bevel gears are manufactured in a standard design.

**2000** The development of electric cylinders in standard design for very high loads (5-1000kN) was started. At the same time the telescopic spindle gears were refined to save the customer the guiding and locking devices. Since that time we have been able to offer telescopic cylinders, too.

**2001** The development of electric cylinders was completed, and these cylinders were added to the standard program.

At the same time the development and fabrication of cubic spindle gears for lifting loads between 2.5 and 150kN was started. These gears were added to the standard program as well.

**2002** were extended and optimized the series of the electric cylinders. Further we provide an electronic 2D-3D product catalogue of the spindle gears, it makes it possible to integrate our products into your system.

**2002-2003** We putted our new assembling and packaging hall, beside the manufacturing hall, in operation

**2003** We increased our machinery by buying a CNC machine tool with 7 axes, brand AXA. That new CNC machine allows a precise machining of the screw jack housings in only two clamping.

**2003-2004** The engineering started to use new 3-D CAD software, Solid Edge. That software enables our customers to integrate easily our drawings.

**2004** We opened a sales office in France.

**2004-2005** We started to design the high performance screw jacks HSG and we created a range of 10 different sizes.

**2005** First participation to an exhibition in France: INDUSTRIE 2005 at Lyon.

**2005-2006** We started to design a new range of telescopic screw jacks TSGLR. Today, these new telescopic screw jacks, with a more compact design, are used in the stage industry, in the aircraft industry, on train lifting equipments and in machine building.

**2008** We replaced the tread grinding machine by a new CNC thread grinding machine, brand Mikromat.

**2008-2009** transmission program is certified to ATEX

**2009-2010** beginning of the series production of Quick-lifting screw jacks SHG

**2010** Development of the transmission range Servo lifting gear (backlash & game adjustable)

Expand our global market with traders in Australia

**2011** development Servo lifting electric cylinder SHELZ (Servo lifting gear with cylindrical structure) and the beginning of the ELZP Series Electric cylinders parallel for Industry sector applications.

**2012** acquisition of the product group UniCe worm gear, helical worm geared motors, couplings, torque limiters and slip clutches. Expansion screw jacks cubic BG up to size for 1000kN

**2013-2014** revision of the telescopic spindle cylinder TSGZ the new cost-optimized design.

Development of product group Electric PNEU, electric cylinder with ball screw, stainless version in hygienically optimized design with mounting dimensions, speeds and forces such as pneumatic cylinder.

**2014** first Quick-lifting screw jacks with cylindrical structure can be delivered SHGZ = Quick-lifting electric cylinder

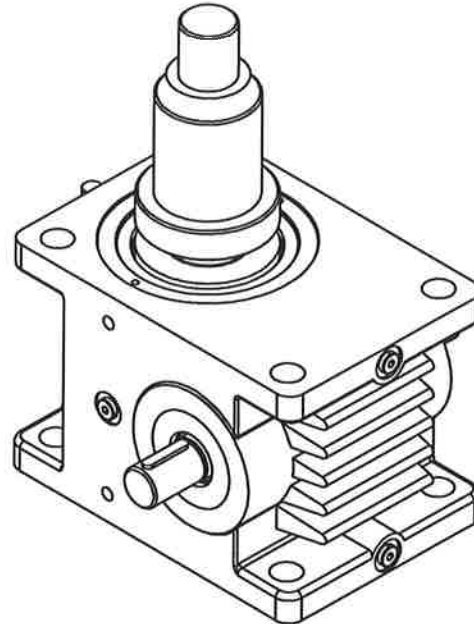
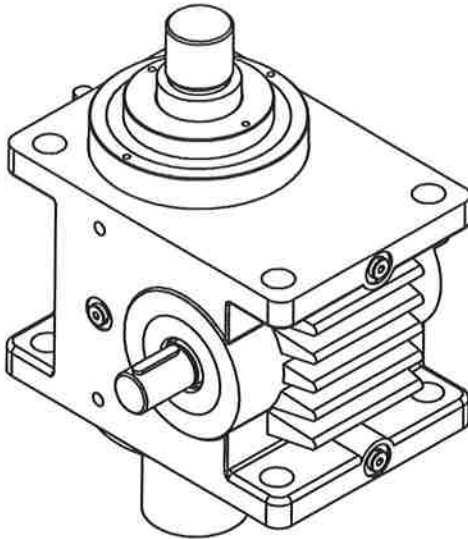
In recent years, customer problems are solved in the drive and lifting technology from us. Depending on the application, we developed the optimal solution and made with the best possible price / performance ratio.



# Technical Data

**ENZFELDER** GMBH  
**Power transmission- and  
 lifting engineering**

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FREN high performances screw jacks are strong worm gear reducers driving a trapezoidal lifting screw. The reducer cases are made of nodular cast iron GGG40 for high loads and meeting high safety standards.

The worm hardened and ground is running on angular ball bearings. The worm wheel is made of high strength material which is particularly abrasion resistant. It is running on thrust ball bearings.

The sizes HSG 31 (force 5kN) to HSG 200 (force 1000kN) are filled with oil on delivery. The trapezoidal lifting screw can be delivered on standard as a single- start spindle or as a multi- start spindle. For higher demands on regards to lifting speed or duty cycle we use ball screws (KHS) or planetary roller spindle drives (PHSG).

Type		31	36	50	63	80	100	125	140	180	200
Max. capacity	kN	5	10	25	50	100	200	350	500	750	1000
Max. tensile force	kN	5	10	25	50	100	200	350	500	750	1000
Lifting screw		Tr 18x4	Tr 22x5	Tr 40x8	Tr 50x9	Tr 60x12	Tr 70x12	Tr 100x16	Tr 120x16	Tr 140x20	Tr 160x20
Ratio N		4:1	5:1	6:1	7:1	8:1	8:1	10 2/3:1	10 2/3:1	13 1/3:1	13 1/3:1
Raise per revolution N	mm/r	1,0	1,0	1,33	1,28	1,5	1,5	1,5	1,5	1,50	1,5
Ratio L		16:1	20:1	24:1	28:1	32:1	32:1	32:1	32:1	40:1	40:1
Raise per revolution L	mm/r	0,25	0,25	0,33	0,32	0,375	0,375	0,5	0,5	0,5	0,5
Max. input power at 20% ED/ hour	kW	0,6	0,9	1,5	2,3	3,6	4,8	7,7	10,2	12,2	17,9
Max. input power at 10% ED/ hour	kW	1	1,5	2,6	4	6,3	8,4	13,5	18	21	31
Efficiency at ratio N	%										
Efficiency at ratio L	%	on request if needed									
Lifting screw efficiency	%	42,5	43	40	36,5	39,5	35,5	34	30	32	28,5
Torque on lifting screw at max load	Nm	7,5	18,5	80	190	478	1060	2600	4235	-	11115
Max. permissible torque on input shaft	Nm	13	29,5	49	168	398	705	975	1640	-	4260
case material		Al alloy	Al alloy	GGG 40	GGG 40	GGG 40	GGG 40	GGG 40	GGG 40	GGG 40	GGG 40
Weight without spindle or protection tube	kg	2	4	13	25	47	74	145	335	-	870
Weight for each 100mm stroke	kg	0,16	0,23	0,82	1,3	1,79	2,52	5,2	7,7	10,87	13,82

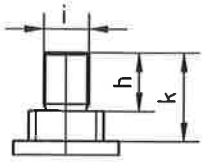




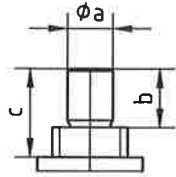
# HSG dimensions translating screw version

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Power transmission- and  
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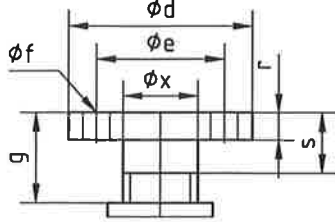
Spindle nose 1



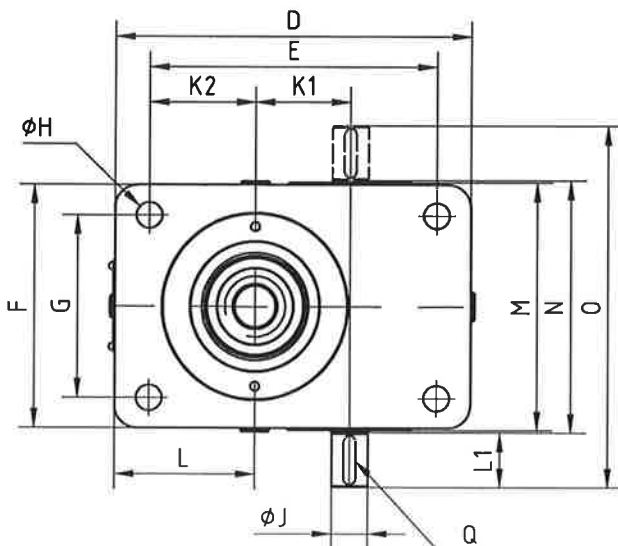
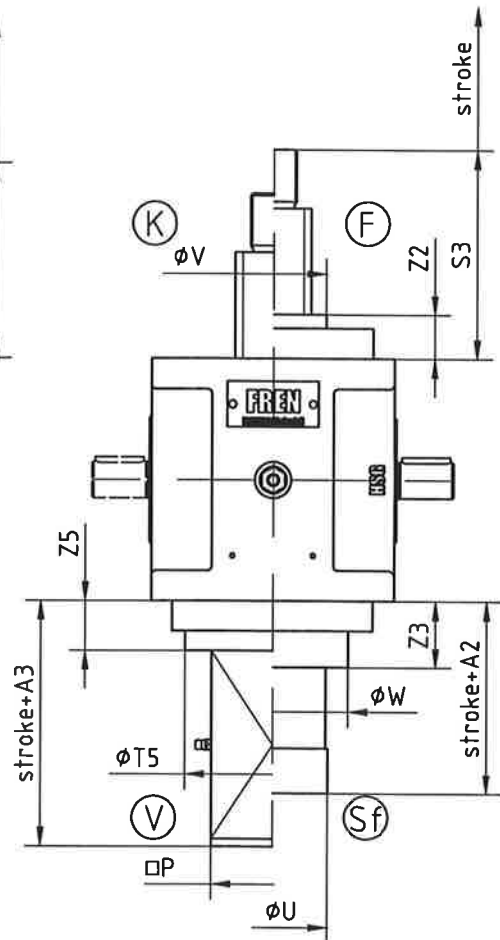
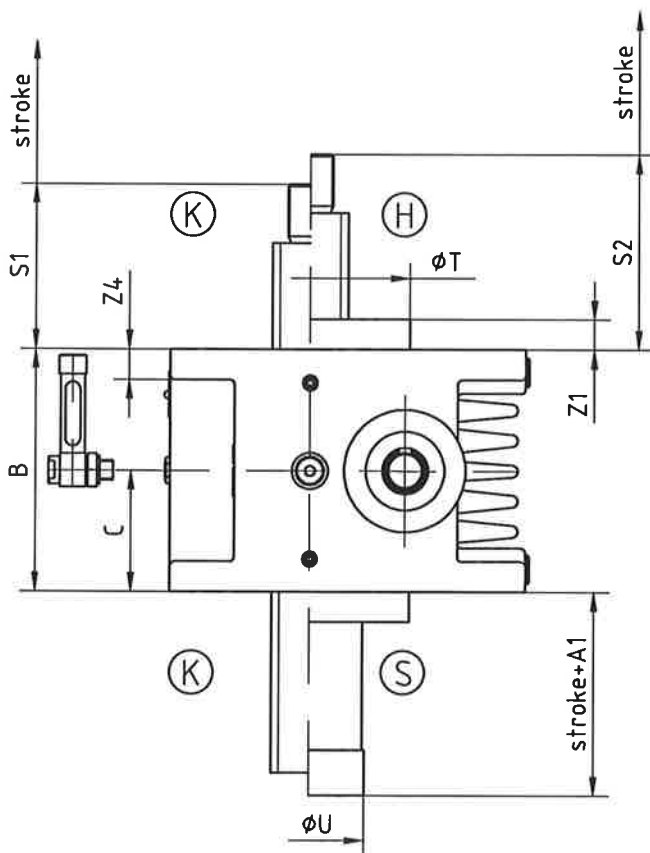
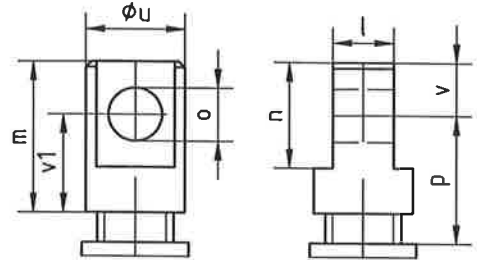
Spindle nose 2



Spindle nose 3



Spindle nose 4



**Possible executions:**

- K\_\_\_\_\_ Short cover
- H\_\_\_\_\_ high cover
- F\_\_\_\_\_ Guide
- S\_\_\_\_\_ Protection tube
- Sf\_\_\_\_\_ protection tube with guide
- V\_\_\_\_\_ locked against rotation



# HSG dimensions translating screw version

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Type	31	36	50	63	80	100	125	140	180	200
Lifting screw	Tr 18x4	Tr 22x5	Tr 40x8	Tr 50x9	Tr 60x12	Tr 70x12	Tr 100x16	Tr 120x16	Tr 140x20	Tr 160x20
A 1	22	22	22	22	22	22	22	22	22	22
A 2	39	44	46	52	61	71	76	86	96	101
A 3	98	104	117	123	136	152	154	179	189	199
B	80	105	130	160	200	230	300	350	400	450
C	40	52,5	65	80	100	15	150	175	200	225
D	117	138	175	235	275	330	410	490	595	680
E	95	110	140	190	220	270	330	390	500	550
F	80	105	130	160	200	230	300	350	420	460
G	62	80	100	120	150	175	230	260	320	330
ø H	9	9	13	17	21	28	39	46	52	66
ø J k6	10	14	16	24	32	38	42	50	60	70
K 1	31	36	50	63	80	100	125	140	180	200
K 2	31	40	50	70	75	87,5	110	130	172,5	185
L	42	54	67,5	92,5	102,5	117,5	150	180	222,5	250
L 1	15	18	28	36	58	58	82	82	95	105
M	83	108	133	163	204	235	305	355	430	470
N	86	112	136	166	206	240	310	360	432	472
O	116	148	192	238	322	356	474	524	622	682
Square P	30	40	70	80	80	100	140	180	200	220
Q	3x3x12	5x5x16	5x5x25	8x7x32	10x8x50	10x8x50	12x8x70	14x9x70	18x11x80	20x12x100
S 1	43	45	50	60	70	75	100	120	130	140
S 2	58	61	68	80	95	105	135	160	175	190
S 3	66	69	76	89	109	124	154	184	204	219
ø T f7	62	72	92	122	152	182	222	262	332	352
ø T 5	50	-	100	115	130	-	200	260	285	310
ø U	28	37	66	82	78	92	136	143	175	198
ø V	35	40	60	70	100	125	160	195	220	240
ø W	45	50	80	100	120	150	180	220	270	290
Z 1	15	16	18	20	25	30	35	40	45	50
Z 2	23	24	26	29	39	49	54	64	74	79
Z 3	29	34	39	44	54	64	74	84	94	109
Z 4	10	12	15	20	25	28	35	45	55	60
Z 5	27	-	28	33	40	-	54	63	68	73

#### Spindel end 1

h	17	24	29	39	49	54	79	99	109	119
i	M 12x1,5	M 16x1,5	M 20x1,5	M 30x2	M 42x3	M 56x3	M 80x3	M 100x4	M 120x4	M 140x4
k	37	44	49	59	69	74	99	119	129	139

#### Spindle end 2

ø a k6	12	15	20	30	40	50	80	95	110	130
b	17	24	29	39	49	54	79	99	109	119
c	37	44	49	59	69	74	99	119	129	139

#### Spindle end 3

ø d	62	72	92	122	150	182	222	262	332	352
ø e	45	50	65	85	105	135	170	205	250	270
ø f	4x ø6,6	4x ø9	4x ø14	4x ø18	4x ø22	6x ø26	8x ø30	8x ø33	8x ø39	8x ø45
g	43	45	50	60	70	75	100	120	130	140
r	8	10	12	18	20	25	30	35	45	50
s	48	25	30	40	50	55	80	100	110	120
ø x	20	30	35	50	65	85	115	140	165	185

#### Spindle end 4

l-0,2	20	25	30	40	60	75	100	120	140	160
m	50	60	70	100	130	150	230	300	330	360
n	30	40	50	70	100	120	160	200	240	280
ø o H8	15	20	25	35	50	60	80	100	120	140
p	55	60	65	85	100	110	170	220	230	240
ø u	30	40	50	65	90	110	140	170	200	220
v	15	20	25	35	50	60	80	100	120	140
v1	35	40	45	65	80	90	150	200	210	220

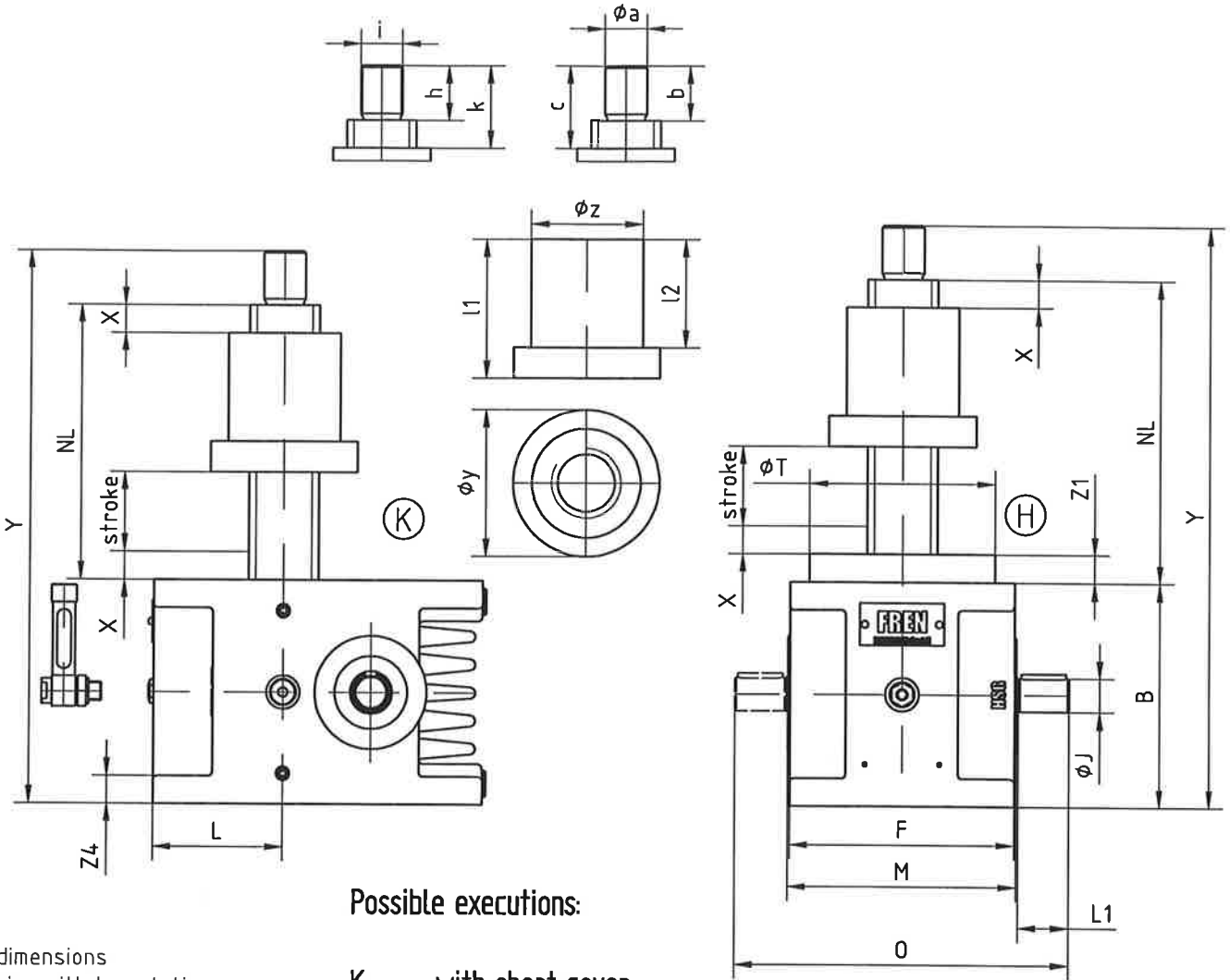


# HSG dimensions Traveling nut version

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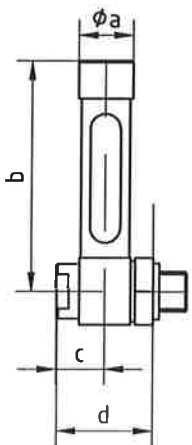
Spindle nose 1    Spindle nose 2



Possible executions:

K\_\_\_\_\_with short cover  
H\_\_\_\_\_with high cover

Missing dimensions  
See version with translating screw



## Oil gauges dimensions

Size	31	36	50	63	80	100	125	140	180	200
ø a					18	18	18	18	18	18
b	For these sizes we use an oil sight glass				80	100	125	150	200	200
c					16	16	16	16	16	16
d					33	33	33	33	33	33



# HSG dimensions Traveling nut version

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Type	31	36	50	63	80	100	125	140	180	200
Lifting screw	Tr 18x4	Tr 22x5	Tr 40x8	Tr 50x9	Tr 60x12	Tr 70x12	Tr 100x16	Tr 120x16	Tr 140x20	Tr 160x20
B	80	105	130	160	200	230	300	350	400	450
C	40	52,5	65	80	100	15	150	175	200	225
F	80	105	130	160	200	230	300	350	420	460
ø J k6	10	14	16	24	32	38	42	50	60	70
L	42	54	67,5	92,5	102,5	117,5	150	180	222,5	250
L 1	15	18	28	36	58	58	82	82	95	105
M	83	108	133	163	204	235	305	355	430	470
NL version "K"	stroke + 85	stroke + 95	stroke + 120	stroke + 140	stroke + 170	stroke + 170	stroke + 200	stroke + 220	stroke + 240	stroke + 260
NL version "H"	stroke + 100	stroke + 111	stroke + 138	stroke + 160	stroke + 195	stroke + 200	stroke + 235	stroke + 260	stroke + 285	stroke + 310
O	116	148	192	238	322	356	474	524	622	682
Q	3x3x12	5x5x16	5x5x25	8x7x32	10x8x50	10x8x50	12x8x70	14x9x70	18x11x80	20x12x100
ø T f7	62	72	92	122	152	182	222	262	332	352
Safety X	20	20	20	20	20	20	20	20	20	20
Y	NL + 97	NL + 129	NL + 169	NL + 199	NL + 249	NL + 284	NL + 379	NL + 449	NL + 509	NL + 569
Z 1	15	16	18	20	25	30	35	40	45	50
Z 4	10	12	15	20	25	28	35	45	55	60

#### Lifting nut

l 1	45	55	80	100	130	130	160	180	200	220
l 2	35	43	62	78	105	100	115	130	135	140
ø y	50	65	87	105	110	120	190	225	240	260
ø z h9	40	45	70	80	90	90	150	160	180	200

#### Spindel end 1

h	17	24	29	39	49	54	79	99	109	119
i	M 12x1,5	M 16x1,5	M 20x1,5	M 30x2	M 42x3	M 56x3	M 80x3	M 100x4	M120x4	M140x4
k	37	44	49	59	69	74	99	119	129	139

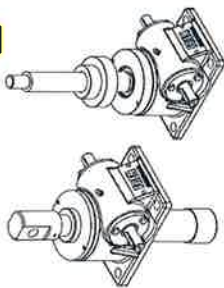
#### Spindel end 2

ø a k6	12	15	20	30	40	50	80	95	110	130
b	17	24	29	39	49	54	79	99	109	119
c	37	44	49	59	69	74	99	119	129	139

# Product overview 03/2015

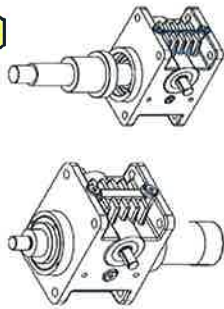
**SG**

Screw jack  
Classic



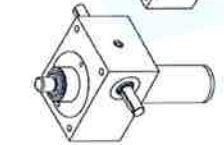
**HSG**

High performance-  
Screw jack



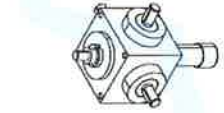
**BG**

Screw jack  
Cubic



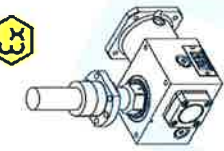
**SHG**

Quick-lifting  
screw jack



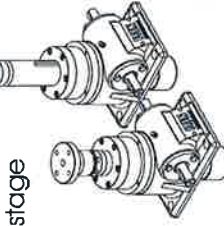
**SH**

Servo lifting  
gear



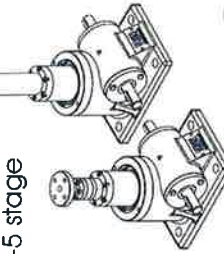
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



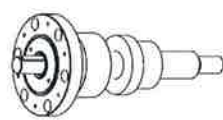
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



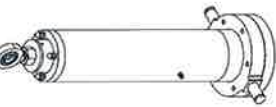
**SLA**

Spindlebearing



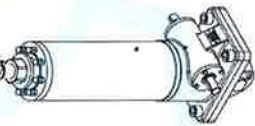
**SEZ**

Spindlebearings-  
Cylinder



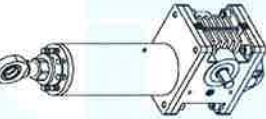
**ELZ**

Electric cylinder



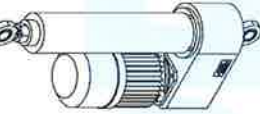
**HELZ**

High performance-  
Electric cylinder



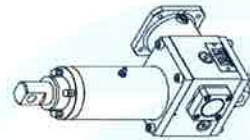
**ELZP**

Electric cylinder  
Parallel



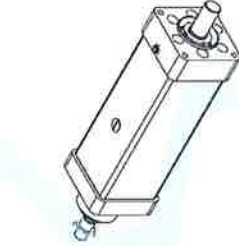
**SHELZ**

Servo electric-  
cylinder



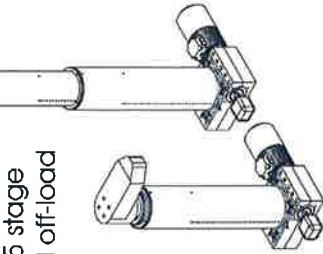
**EPNEU**

Spindle-  
Electric cylinder



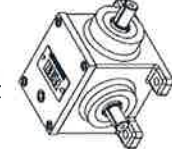
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



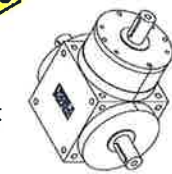
**K**

Bevel gear  
Type K



**H**

Bevel gear  
Type H



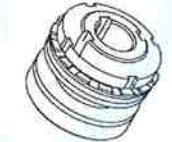
**R / GS**

Elastic / backlash-free  
Coupling



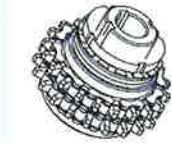
**RT**

Slip hub



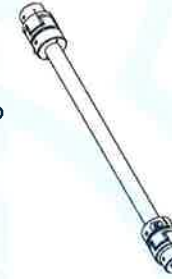
**RK**

Slip coupling



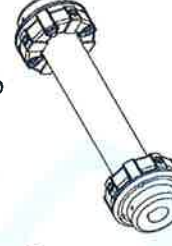
**ZR**

FREN  
Connecting shaft



**G / GX**

Elastic  
Connecting shaft

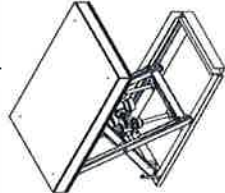


Cardan shaft



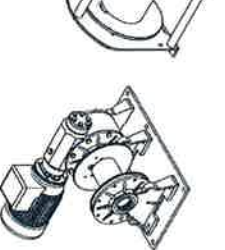
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



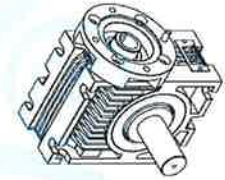
**PLG**

Planetary gear



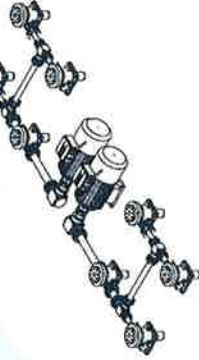
**uniCe**

Worm gear

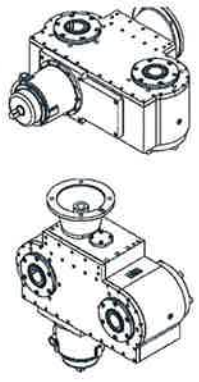


**HA**

Lifting system



**Special gear**

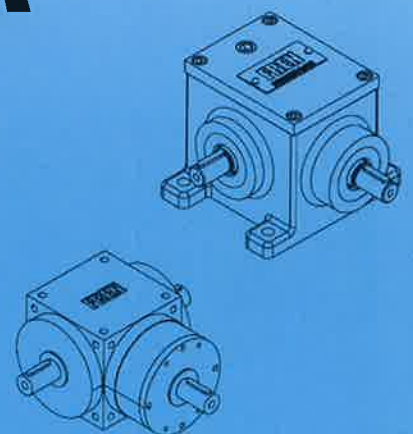




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**Bevel Gear Box  
Type K and H**



# History

**1969** Mr. Enzfelder established a job shop in Vienna. Equipped with some machinery, the Enzfelder Company manufactured machine parts according to drawings.

Within one year the number of employees rose to 3. The Enzfelder company started manufacturing threaded spindles and nuts according to drawings. Then the range of manufacturing was enlarged by toothed wheels, screw wheels and endless screws according to drawings.

**1974** The company including the complete manufacture was relocated to Enzesfeld.

**1975** The manufacture of spindle gears was launched. The company's experience in the manufacture of trapezoid-threaded spindles, nuts, worm gear pairs and casings was a valuable basis for the construction. After many tests, the serial production of spindle gears was launched one year later. The result was a product characterized by a first-rate price-performance ratio. The product was distributed by dealers all over Europe.

**1981** The planning and construction of small hydropower plants was launched to replace diesel generators. Environmental protection was not really a topic at that time, however, and the production was stopped in 1986.

**1989** The Enzfelder GesmbH company replaced the Franz Enzfelder Company.

**1990** Scissor-type lifting platforms and cable winches were added to the delivery program.

**1991** Resilient spacer shafts were tested and added to the production range. At the same time, the telescopic spindle gear was developed. A patent for this principle was applied for and issued.

**1993** The sale of spindle gears under their own name was launched and presented for the first time at the Hannover industrial fair. We have been approached with a variety of tasks and have provided solutions according to the customers' needs ever since.

**1994** In cooperation with our customers we produced the first bevel gears to specification.

**1995** Spindle bearing arrangements were designed and included in the standard program.

**1996** The Enzfelder company produced planet gear to specification for the first time.

**1998-1999** The standard programs were enlarged. Additionally, bevel gears are manufactured in a standard design.

**2000** The development of electric cylinders in standard design for very high loads (5-1000kN) was started. At the same time the telescopic spindle gears were refined to save the customer the guiding and locking devices. Since that time we have been able to offer telescopic cylinders, too.

**2001** The development of electric cylinders was completed, and these cylinders were added to the standard program.

At the same time the development and fabrication of cubic spindle gears for lifting loads between 2.5 and 150kN was started. These gears were added to the standard program as well.

**2002** were extended and optimized the series of the electric cylinders. Further we provide an electronic 2D-3D product catalogue of the spindle gears, it makes it possible to integrate our products into your system.

**2002-2003** We putted our new assembling and packaging hall, beside the manufacturing hall, in operation

**2003** We increased our machinery by buying a CNC machine tool with 7 axes, brand AXA. That new CNC machine allows a precise machining of the screw jack housings in only two clamping.

**2003-2004** The engineering started to use new 3-D CAD software, Solid Edge. That software enables our customers to integrate easily our drawings.

**2004** We opened a sales office in France.

**2004-2005** We started to design the high performance screw jacks HSG and we created a range of 10 different sizes.

**2005** First participation to an exhibition in France: INDUSTRIE 2005 at Lyon.

**2005-2006** We started to design a new range of telescopic screw jacks TSGLR. Today, these new telescopic screw jacks, with a more compact design, are used in the stage industry, in the aircraft industry, on train lifting equipments and in machine building.

**2008** We replaced the tread grinding machine by a new CNC thread grinding machine, brand Mikromat.

**2008-2009** transmission program is certified to ATEX

**2009-2010** beginning of the series production of Quick-lifting screw jacks SHG

**2010** Development of the transmission range Servo lifting gear (backlash & game adjustable)

Expand our global market with traders in Australia

**2011** development Servo lifting electric cylinder SHELZ (Servo lifting gear with cylindrical structure) and the beginning of the ELZP Series Electric cylinders parallel for Industry sector applications.

**2012** acquisition of the product group UniCe worm gear, helical worm geared motors, couplings, torque limiters and slip clutches. Expansion screw jacks cubic BG up to size for 1000kN

**2013-2014** revision of the telescopic spindle cylinder TSGZ the new cost-optimized design.

Development of product group Electric PNEU, electric cylinder with ball screw, stainless version in hygienically optimized design with mounting dimensions, speeds and forces such as pneumatic cylinder.

**2014** first Quick-lifting screw jacks with cylindrical structure can be delivered SHGZ = Quick-lifting electric cylinder

In recent years, customer problems are solved in the drive and lifting technology from us. Depending on the application, we developed the optimal solution and made with the best possible price / performance ratio.

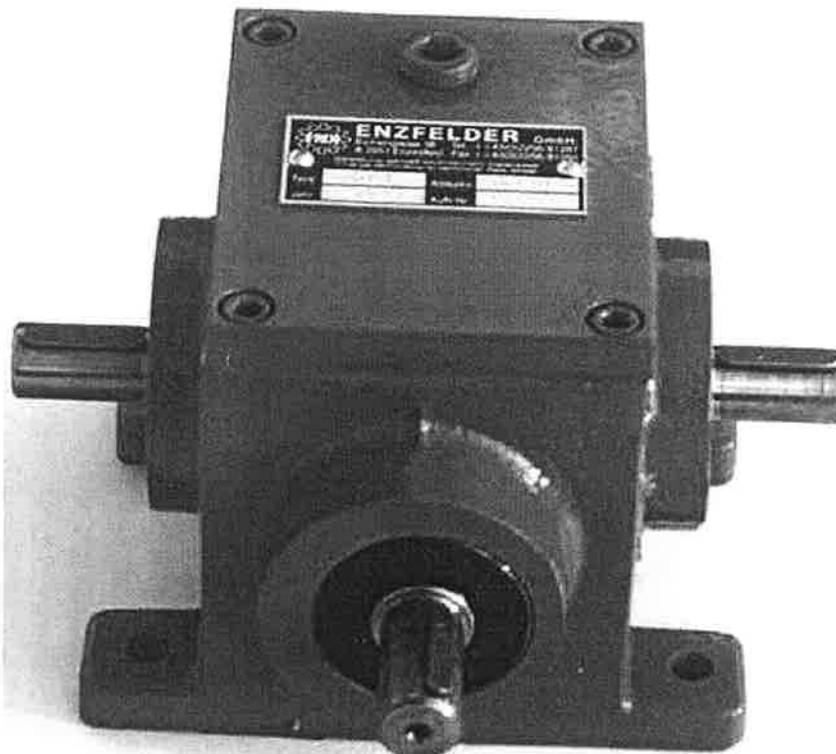


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**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

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## Product Information

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In our lifting systems 2 types of bevel gears can be used. The types H and the types K. Both of them have been used during many years. On the great diversity of the intonation has been considered, while planing and constructioning them.

The gears are built very compact and they have a very small weight. Both series can be delivered also with flange or hollow shaft. It is possible, too to deliver our gears in stainless type. If you need any other type or size, which you can not find in our catalogue, do not hesitate to contact us.

### Type H

The compact and stable construction guarantees highest power and smallest dimension and little weight. Because of the lubrication for duration of life, dependend on the gear-size, the gears are maintenance free, under normal application.

The gear housing is made of casting GGG50. The storage of the shafts is made by taper roller bearings which guarantees a long duration of life.

The toothing is a Gleason helix toothing for highest torques. Because of the contact reflection-optimized assembly mounting, an equal tooth load can be reached. Through this measures a very high efficiency of 98% can be reached.

The serie H embraces 8 sizes from type H075 to type H280.

The gear reductions are 1:1, 1,5:1, 2:1, 3:1, 4:1 and 5:1. The entrance number of revolution can go up to 6000Rpm, dependend on the size.

### Type K

The bevel gears are helix toothed and hardened. The gear housing can be made of Alu, steel or casting GGG50. The storage is a well dimensioned bearing. The advantage of the type K are the gearfeet which are casted in one piece with the housing, to allow a simply fitting, because it is possible to fit with screws from the above side.

The gears are filled with oil or grease.

The serie contains 4 sizes from type K80 to type K70.

The efficiency from this serie goes up from 80% to 85%.

It is possible to deliver gears from two shafts to four shafts.

The gear reductions are 1:1, 2:1 and 3:1.

### Mounting and Operating Instruction

The operating and mounting instructions you can find enclosed each delivery.

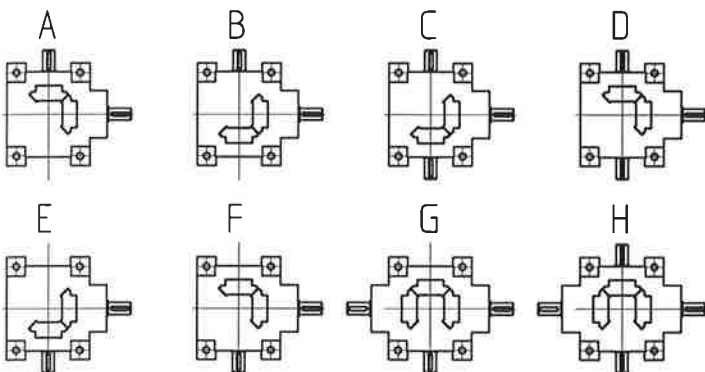


# Performance Table Type H

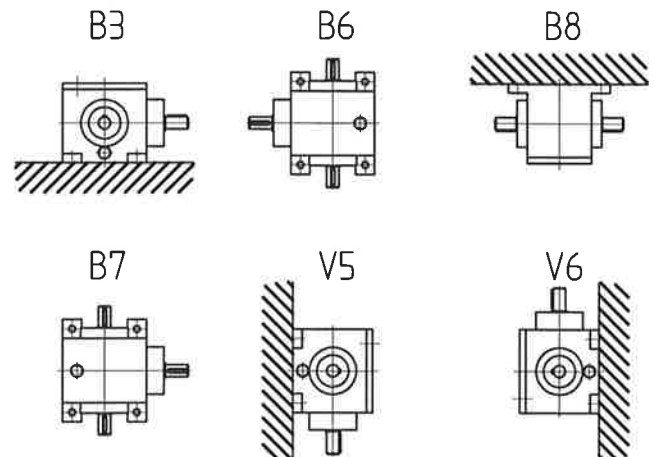
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i	Title	Unit	H75	H90	H110	H140	H170	H210	H240	H280
1:1	Nominal torque M2	Nm	45	78	150	360	585	1300	2150	3200
	max. permissible torque M2*		68	117	225	540	878	1950	3225	4800
1,5:1	Nominal torque M2	Nm	45	78	150	360	585	1300	2150	3200
	max. permissible torque M2*		68	117	225	540	878	1950	3225	4800
2:1	Nominal torque M2	Nm	42	68	150	330	544	1220	2010	3050
	max. permissible torque M2*		63	102	225	495	816	1830	3015	4575
3:1	Nominal torque M2	Nm	33	54	120	270	450	1020	1650	2850
	max. permissible torque M2*		50	81	180	405	675	1530	2475	4275
4:1	Nominal torque M2	Nm	28	52	100	224	376	860	1410	2300
	max. permissible torque M2*		42	78	150	336	564	1290	2115	3450
5:1	Nominal torque M2	Nm	25	40	85	196	320	740	1210	2000
	max. permissible torque M2*		38	60	128	294	480	1110	1815	3000
	max. rpm at input	rpm	6500	5500	4500	3500	3000	2200	2000	1700
	at 2% max Load standard output backlash	arcmin	6 bis 15	6 bis 14	6 bis 13	6 bis 13	6 bis 12	6 bis 12	6 bis 12	6 bis 11
	at 2% max Load minmal output backlash	arcmin	5 bis 6	4 bis 6	4 bis 6	3 bis 6	3 bis 6	3 bis 6	3 bis 6	3 bis 6
Force contact point is midith of shaft	Permissible Radial Load	N	900	1.300	2.000	3.500	5.000	8.500	11.000	15.000
	Input Shaft d1									
	Permissible Radial Load	N	1.100	1.600	2.500	4.500	6.000	10.500	15.000	18.000
	Output Shaft d1									
	Permissible Axial Load	N	450	650	1.000	1.750	2.500	4.250	5.500	7.500
	Input Shaft d1									
Permissible Axial Load	N	550	800	1.250	2.250	3.000	5.250	7.500	9.000	
Output Shaft d1										
	Efficiency at max. Load	%	> 98							
	Running Noise at 1500rpm, Partial Load	db(A)	70	74	76	77	78	80	82	83
	Weight	kg	4,5	8	13	22	38,5	71	103,5	155
	Service Live	h	> 15.000							
	Lubrication		up to and including H140: Synthetic Lubrication Oil, ISO VG 150							
	Operating Temperature		-30°C up to 100°C							

## Arrangement of Shafts (Type H and K):



## Fitting Position (Type H and K):





# Performance Table Type K

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i	Title	Einheit	K32	K52,5	K61,5	K70
1:1	Nominal torque M2	Nm	7,5	35	63	232
	max. permissible torque M2*		11,25	52,5	94	348
2:1	Nominal torque M2	Nm	5,8	34	68	216
	max. permissible torque M2*		8,7	51	102	324
2,5:1	Nominal torque M2	Nm	-	-	-	162
	max. permissible torque M2*		-	-	-	243
3:1	Nominal torque M2	Nm	6,6	30	62	-
	max. permissible torque M2*		10	45	93	-
max. rpm at input		rpm	3000	1500	2000	1500
at 2% max Load standard output backlash		arcmin	30	30	30	30
Force contact point is midwidth of shaft	Permissible Radial Load	N	100	200	500	1.200
	Input Shaft d1					
	Permissible Radial Load	N	100	250	800	1.650
	Output Shaft d1					
	Permissible Axial Load	N	40	50	100	405
	Input Shaft d1					
	Permissible Axial Load	N	80	160	290	635
	Output Shaft d1					
Material			AL	ST or GG		
Efficiency		%	> 80			
Running noise		db(A)	75	78	78	78
Weight		kg	1,1	5,5	9	27
Service Life		h	> 10000			
Lubrication			Grease or Oil			
Temperature			-30°C up to 100°C			

\* temporary

## Thermal performance limit (Type H and K):

Type	K32	K52,5	K61,5	K70	H75	H90	H110	H140	H170	H210	H240	H280
Thermal Performance Limit (Kw)	2,3	4	7,9	12	5,5	7,4	10,8	16,1	23,4	28,6	45,3	60,3

The gearbox performance is limited by the maximum allowable oil bath temperature. The required effective performance must not exceed the limit values allowed for continuous duty.

Duty Cycle per Hour %	100	80	60	40	20
Factor	1	1,2	1,4	1,6	1,8

If on intermitted duty or in the event of increased ambient temperature, the following factors can be applied as guide values for the determination of the related allowable thermal performance limit.  
 Duty cycle per hour in %

Duty Cycle per Hour %	100	80	60	40	20
Factor	1	1,2	1,4	1,6	1,8



# Gearbox Selection

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Performance  $P$  [kW] at  $n_{input}$  [rpm] ( $P_{input} \sim P_{output}$  at  $\eta > 98\%$ )  
Gear Ratio  $i$   
Speed  $n_{input}$ ;  $n_{output} = n_{input} : i$

Output Torque  $M_{output}$  [Nm] =  $(9550 \times P_{output}) : n_{output}$

Output Torque  $M_{output} < \text{Nominal Torque } M2_{Nominal}$

Maximum Output-torque  $M_{output\ max} < \text{Maximum permissible Outputtorque } M2_{max}$   
at up to 10 start-ups per Minute

Maximum Output Torque  $M_{output\ max} < \text{Nominal Torque } M2_{nominal}$   
at up to 60 start-ups per Minute

Maximum values for start numbers ranging between 10 to 60 start-ups will be interpolated

Speed  $n_{input} < \text{Speed } n_{1max}$

Performance  $P < \text{Thermal Performance Limit } P_{therm}$  (20°C, 100% ED)

Thermal performance limit changes with deviating temperature values and duty times according to factor indicated in the table on page 5

radial and axial

Shaft Loads  $< \text{permissible values } FQ1, FQ2, FA1, FA2$

From table on page 4 and 5 (Force contact point is mid of shaft, to realize higher values, a re-calculation must be made)

Example: given:  $n1 = 3000$  rpm  
Distributiongearbox  $n2 = 750$  rpm  
 $P = 15,5$  kW  
ED = 100%  
Ambient temperature = 20°C

Selection:  $i = n1 / n2$   $i = 3000 \text{ rpm} : 750 \text{ rpm}$   
 $i = 4:1$

$M2 = 9550 \times P / n2$   $M2 = 9550 \times 15,5 : 750$   
 $M2 = 197,37$   
Gear box H140 4:1

$M2_{exist} < M2_{nominal}$   $M2_{exist} 197,37 \text{ Nm} < M2_{nominal} 224 \text{ Nm}$   
 $n1_{exist} < n1_{max}$   $3000 \text{ rpm} < 3500 \text{ rpm max}$   
 $P_{exist} < P_{therm}$   $P = 15,5 \text{ kW} < P_{therm} 16,1 \text{ kW}$

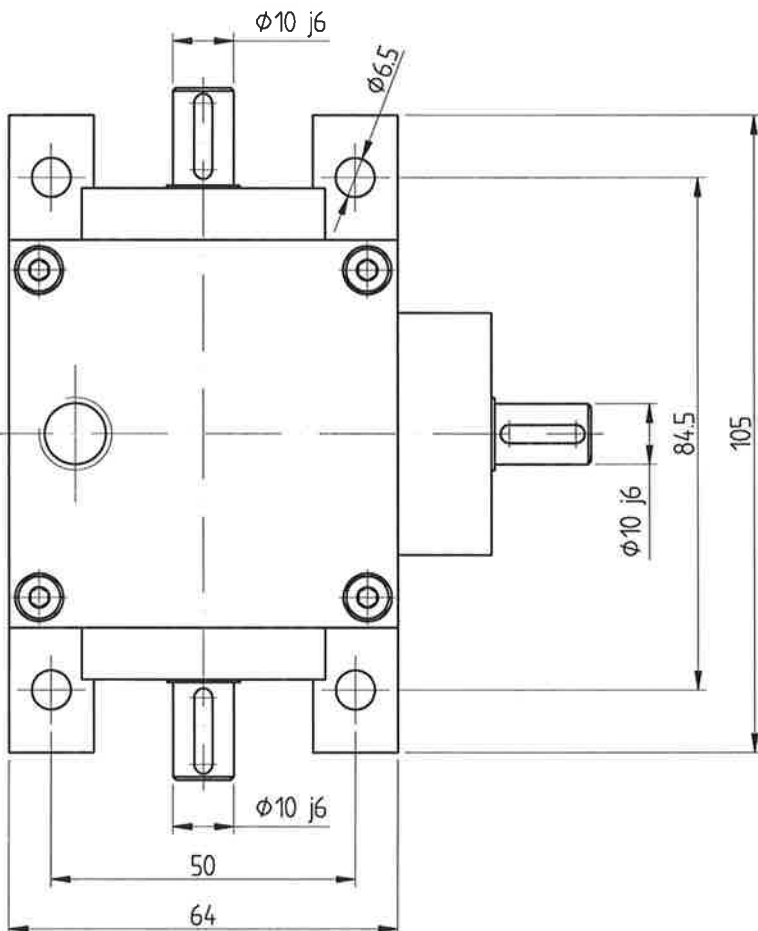
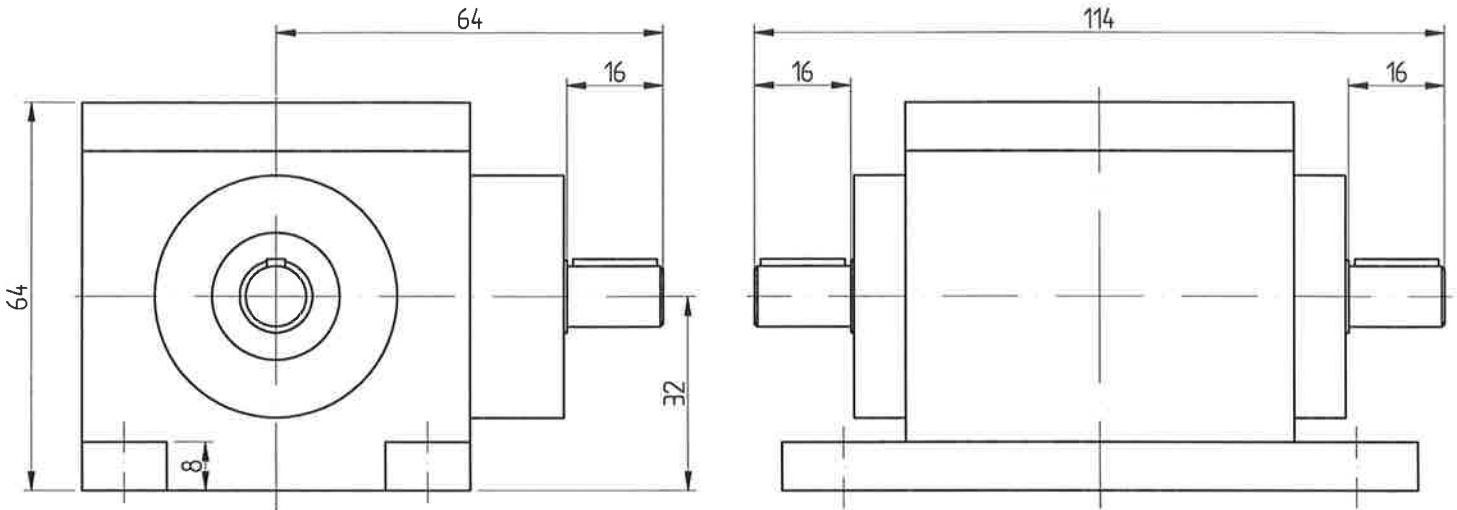
Selected: H140 4:1



# Bevel Gear Box K32

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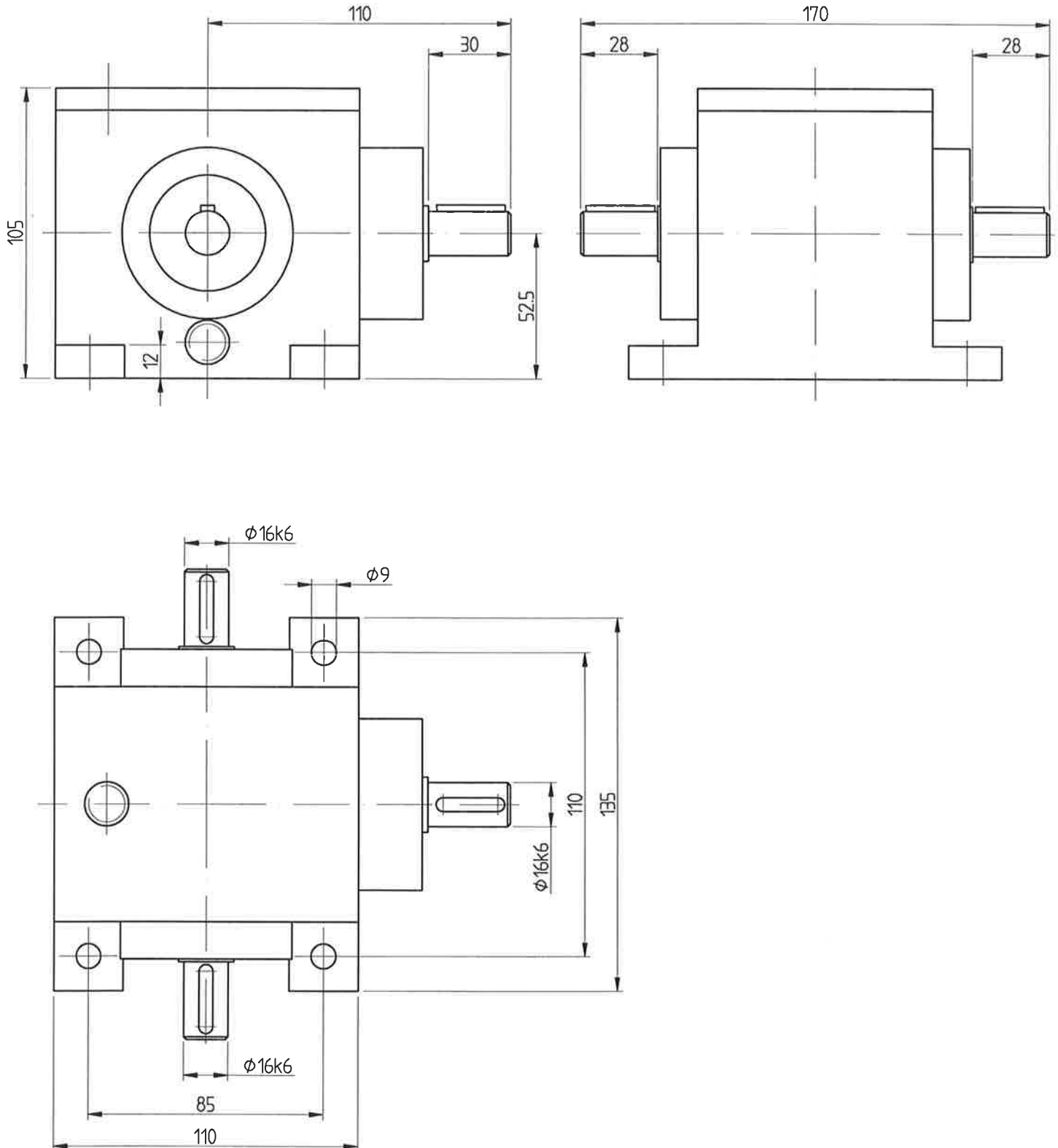




# Bevel Gear Box K 52,5

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Power transmission- and  
lifting engineering

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A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: [office@enzfelder.at](mailto:office@enzfelder.at)  
Internet: [www.enzfelder.at](http://www.enzfelder.at)

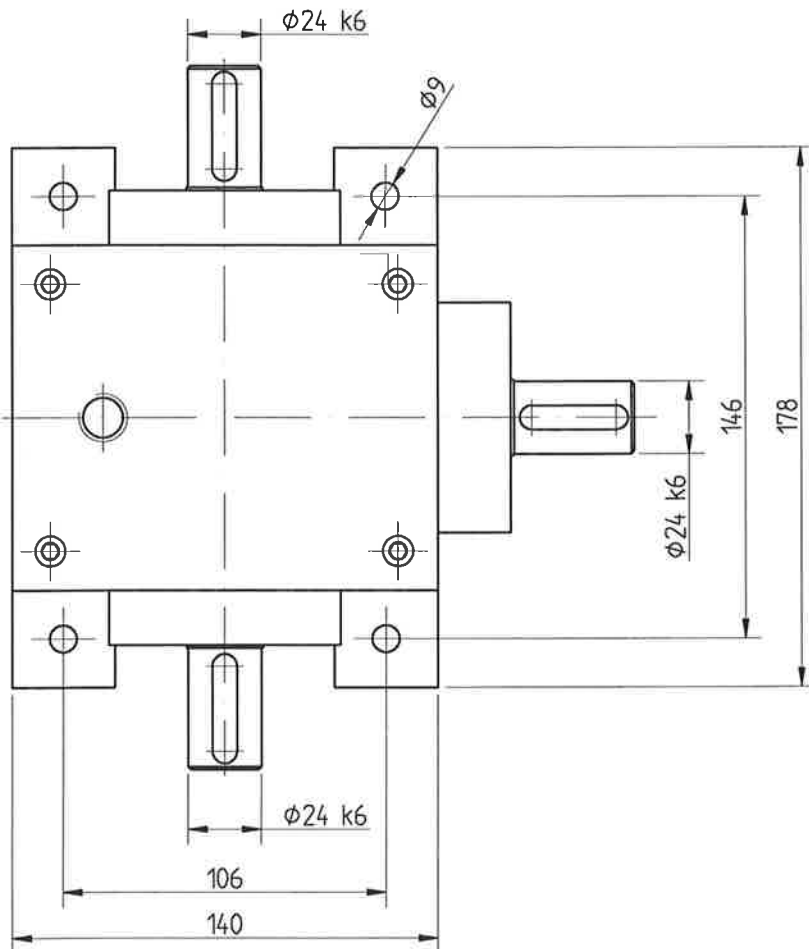
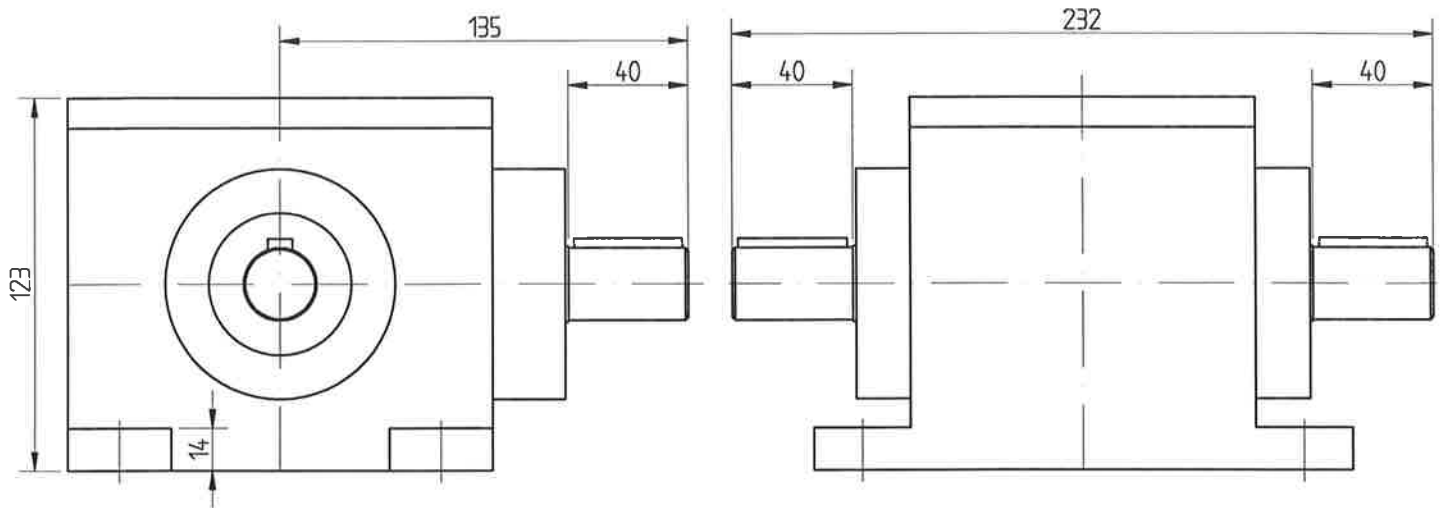




# Bevel Gear Box K 61.5

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

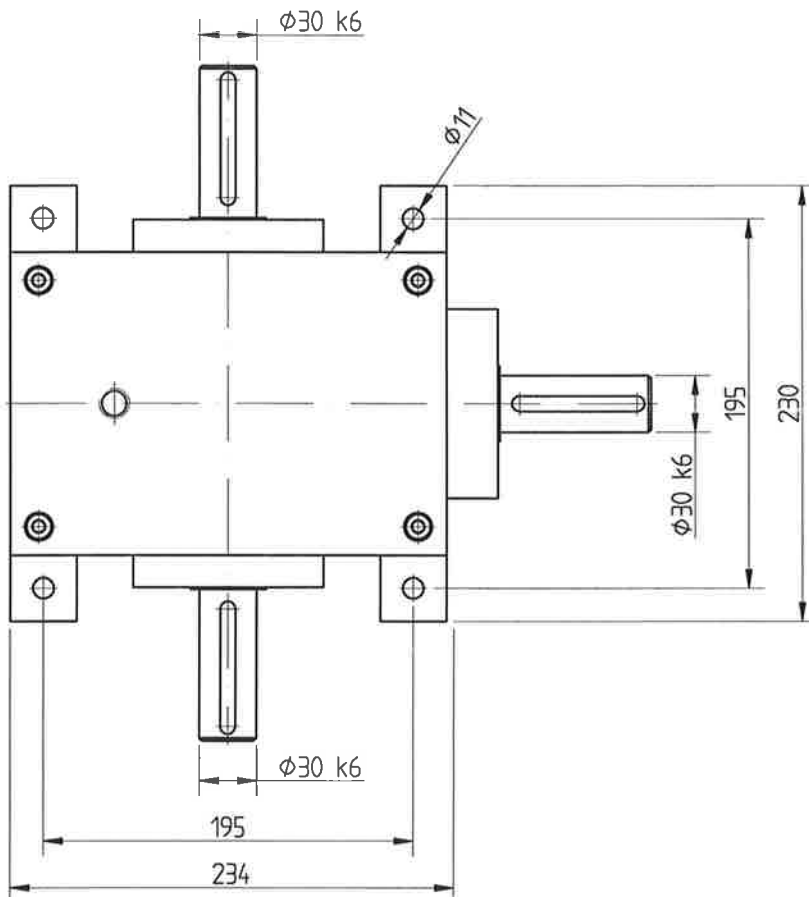
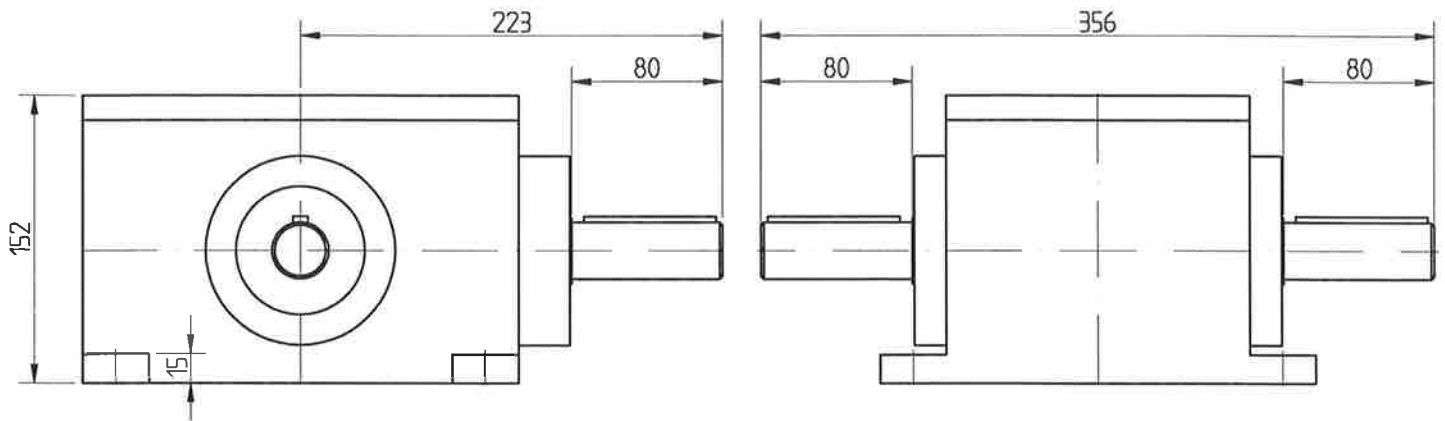




# Bevel Gear Box K 70

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
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Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at



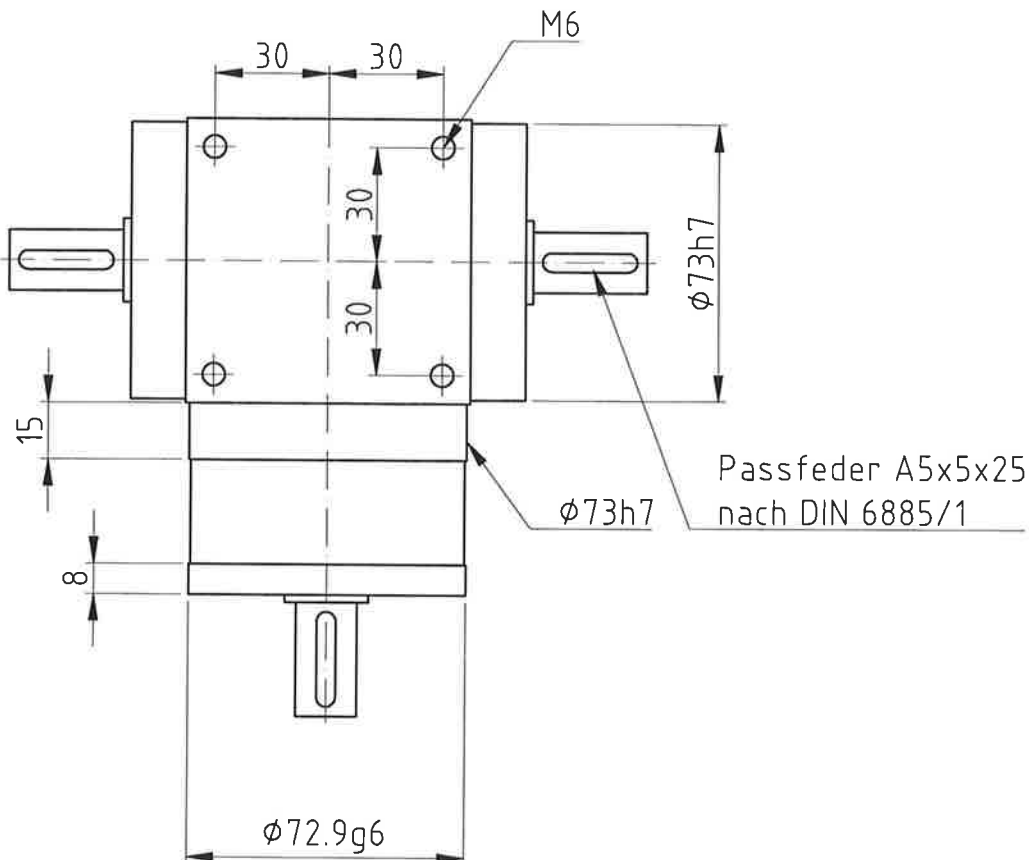
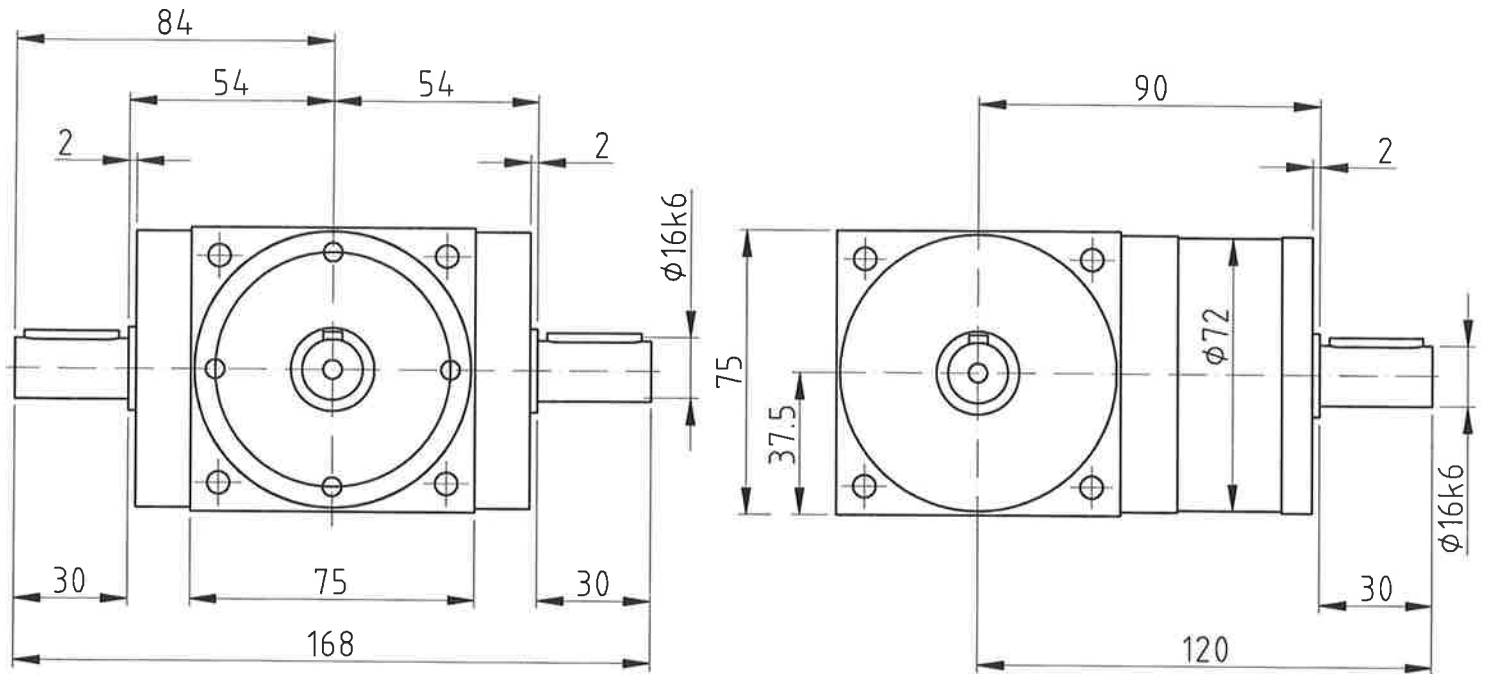




# Bevel Gear Box H075

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
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E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

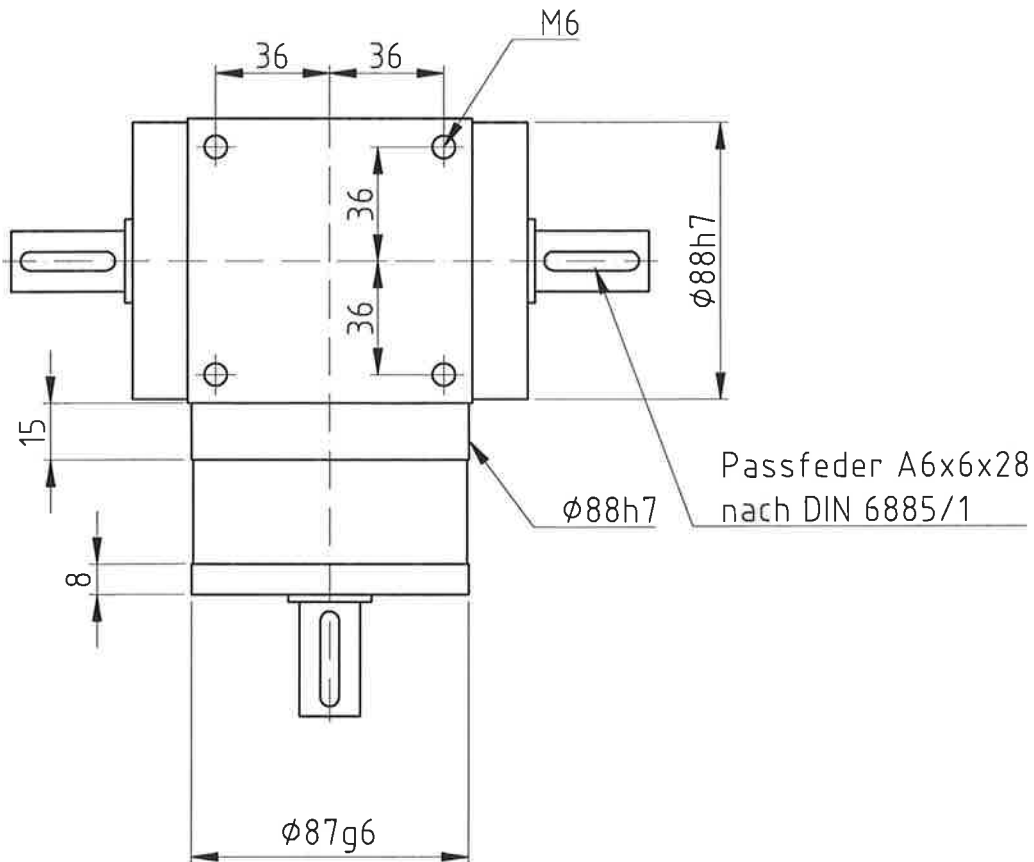
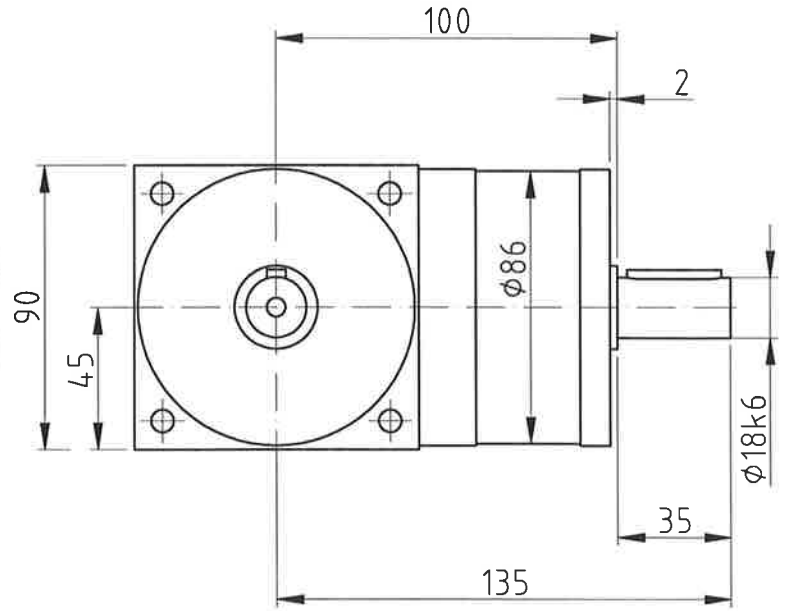
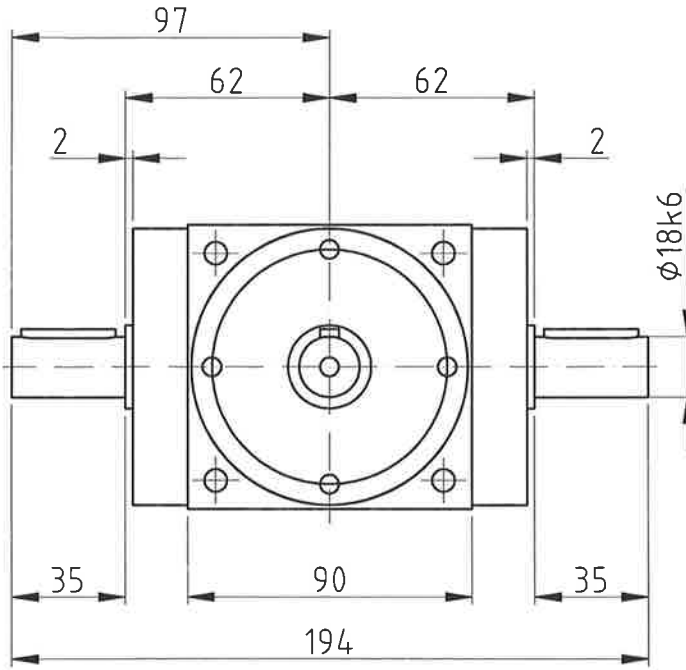




# Bevel Gear Box H090

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

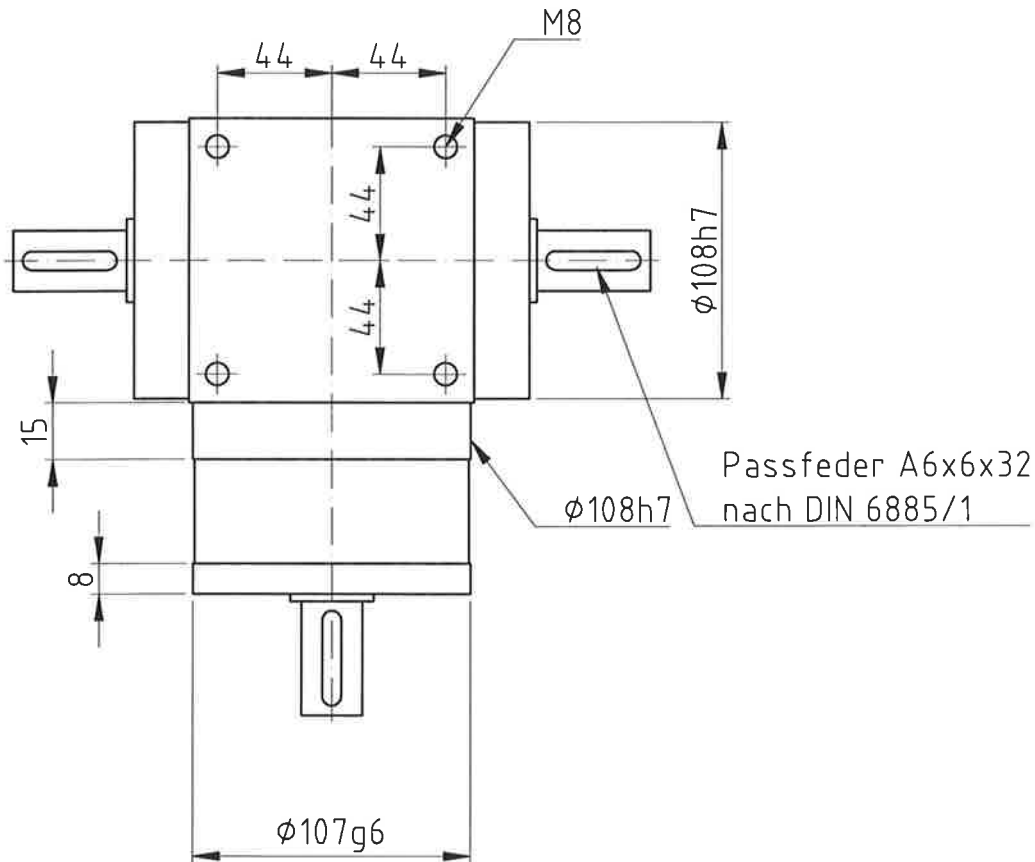
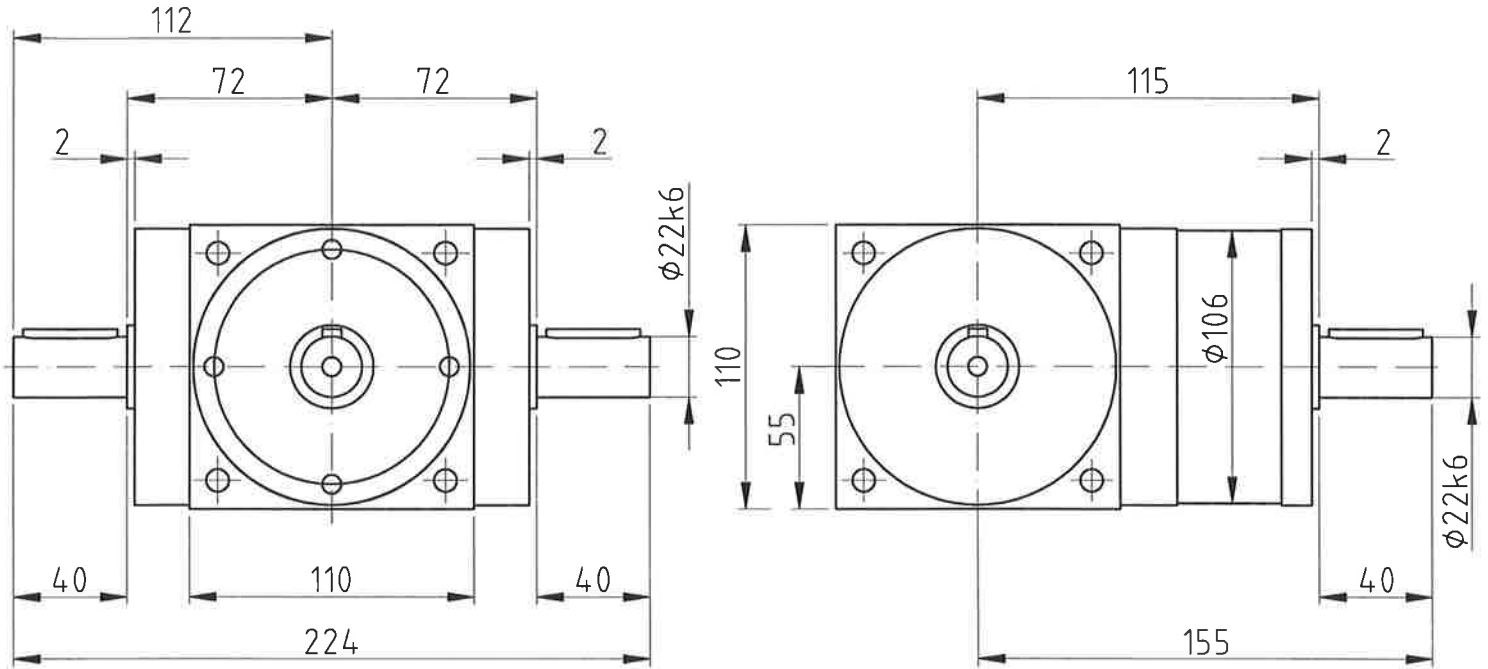




# Bevel Gear Box H110

**ENZFELDER** GMBH  
 Power transmission- and  
 lifting engineering

Eichengasse 36  
 A-2551 Enzesfeld-Lindabrunn  
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 Fax: ++43 (0) 2256 81287-95  
 E-Mail: office@enzfelder.at  
 Internet: www.enzfelder.at

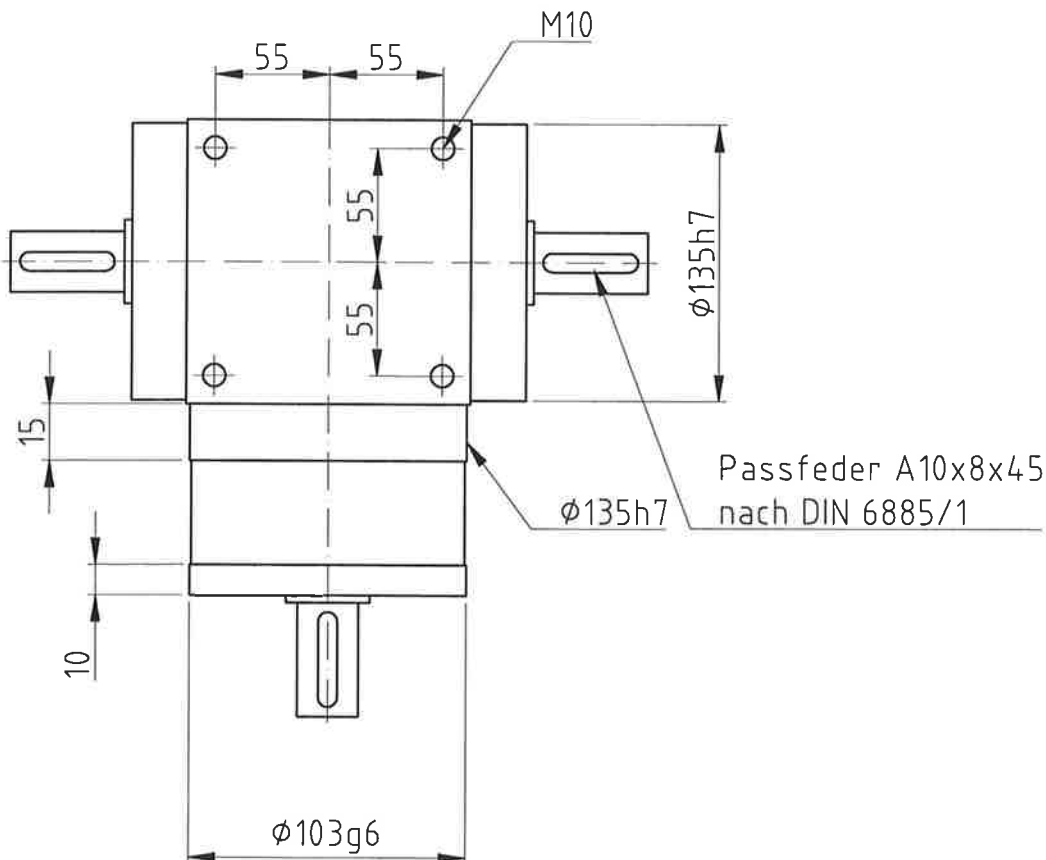
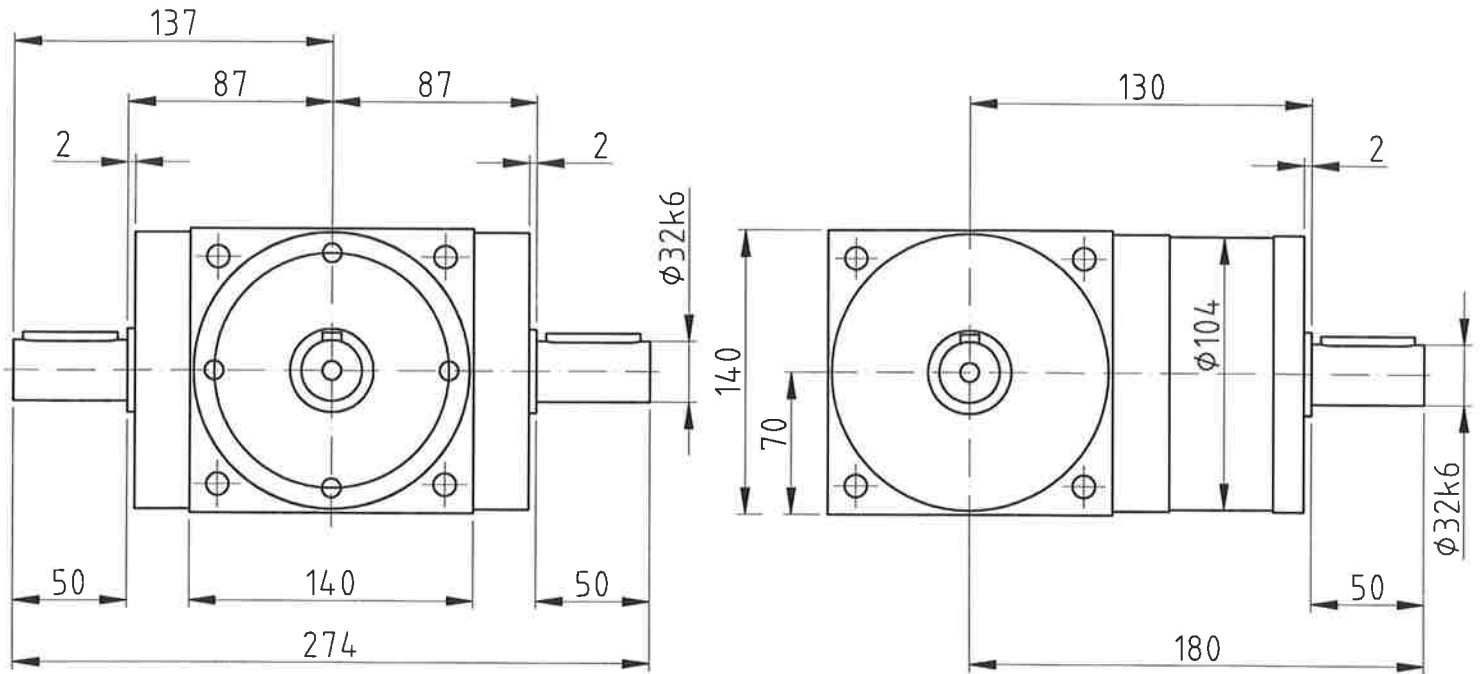




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**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
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Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

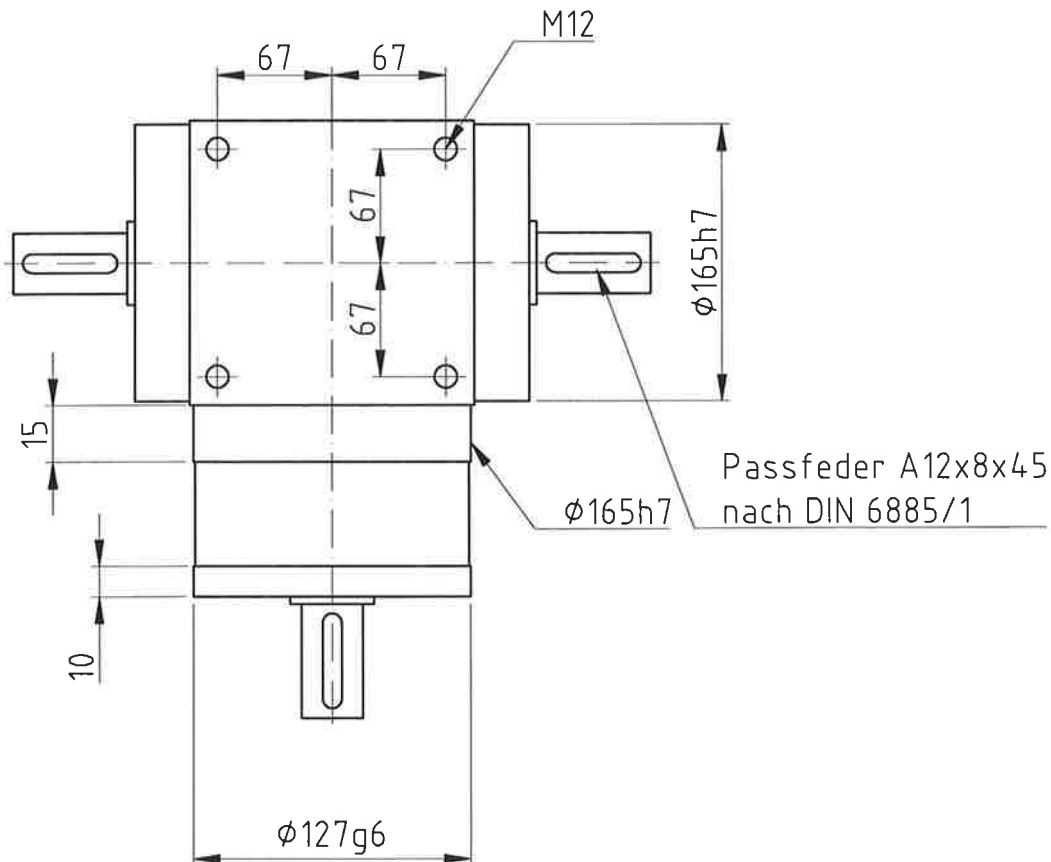
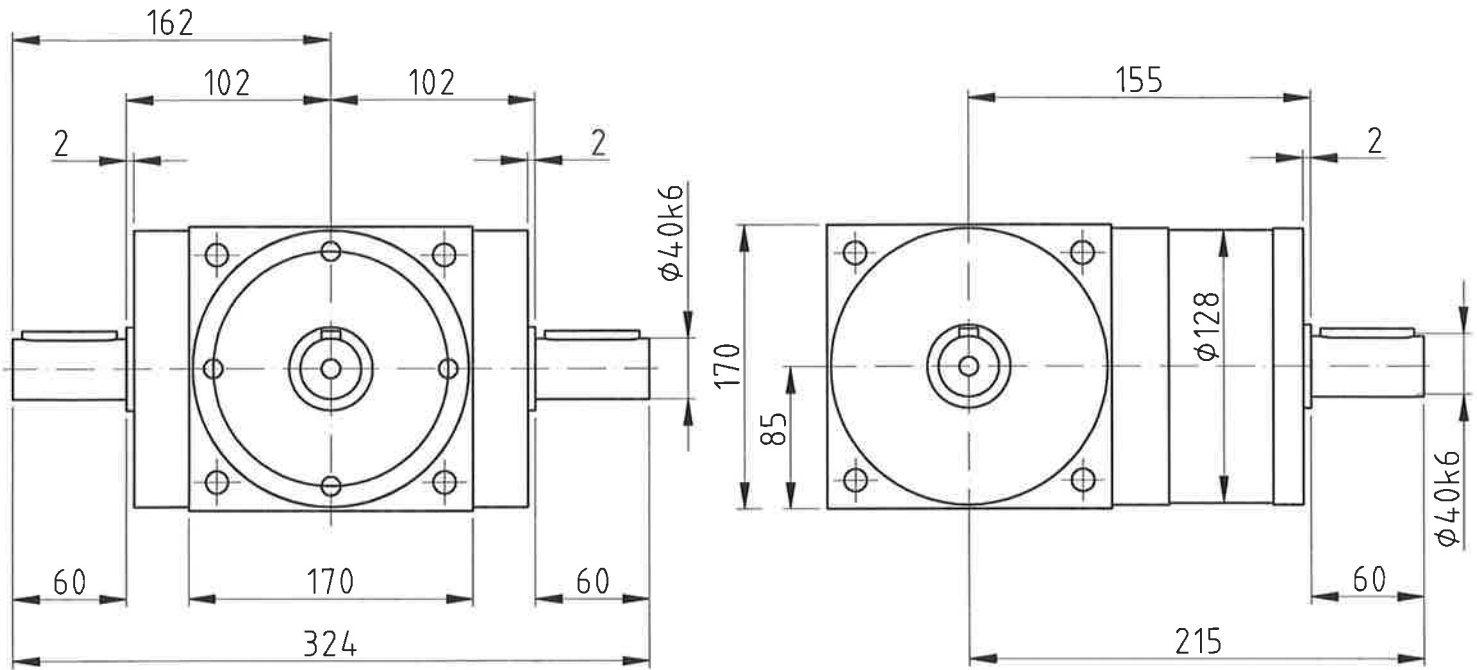




# Bevel Gear Box H170

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
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E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

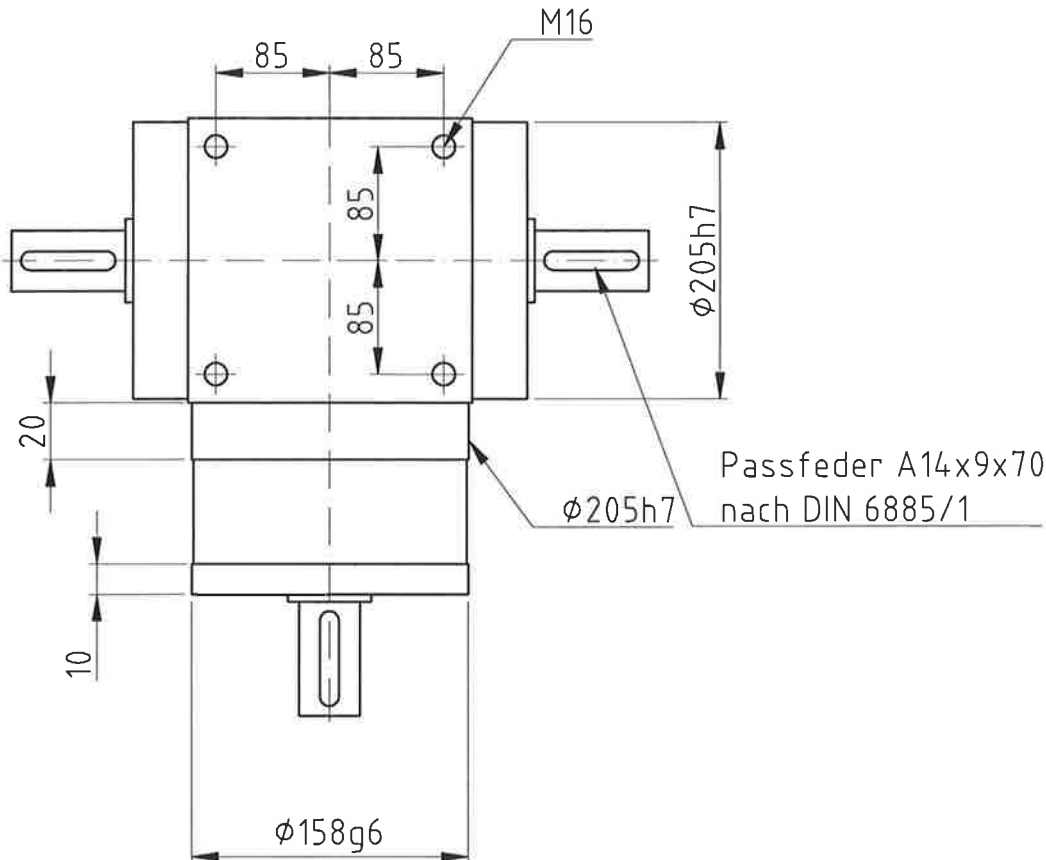
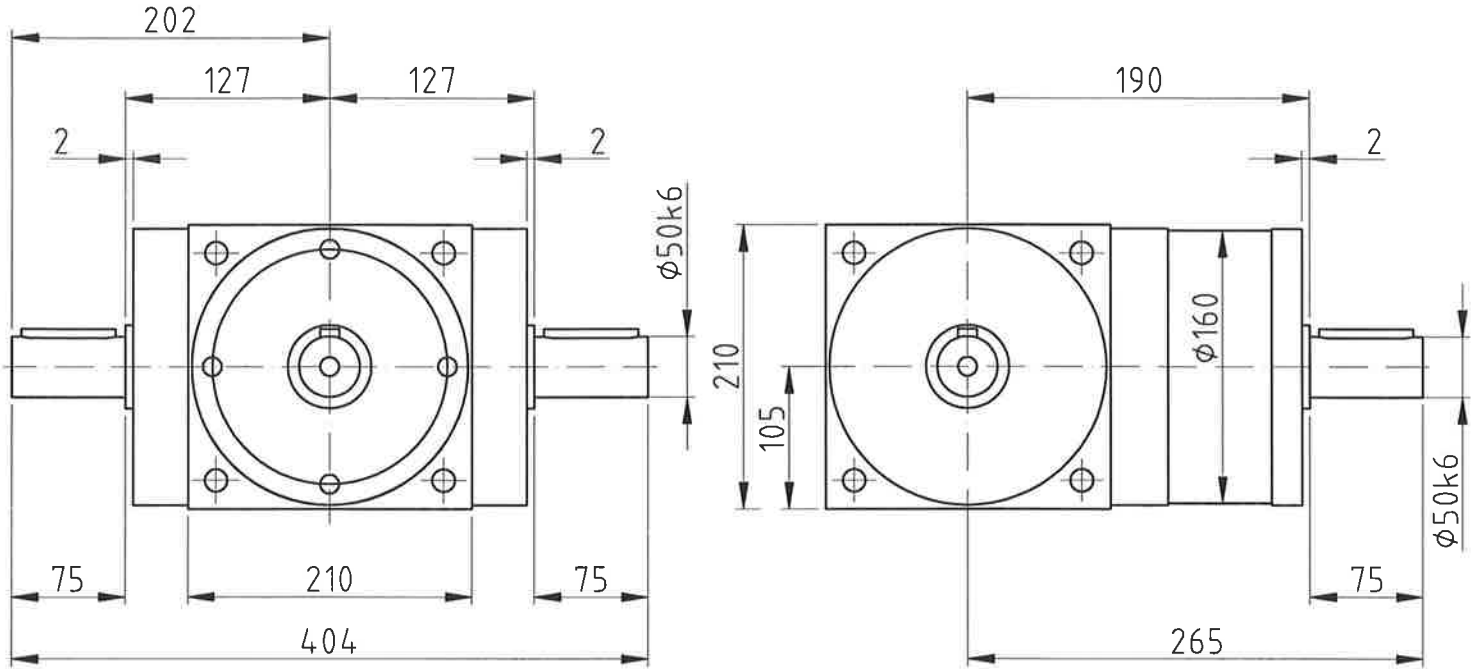




# Bevel Gear Box H210

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

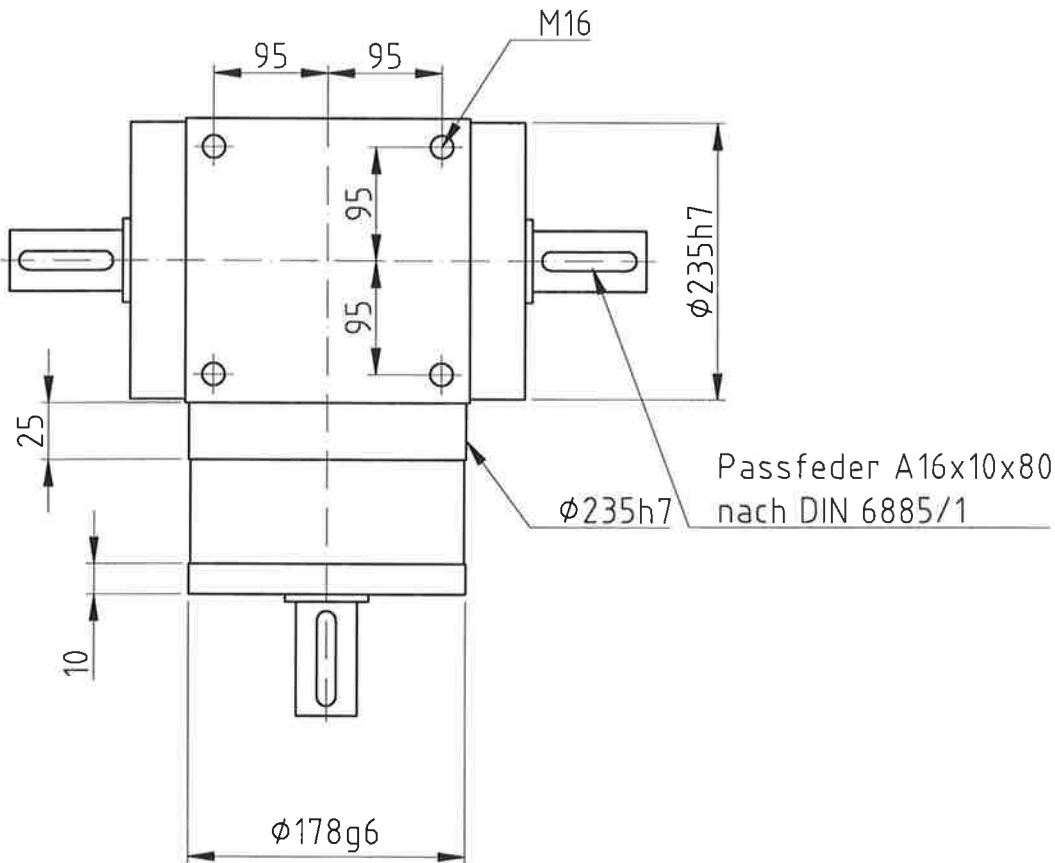
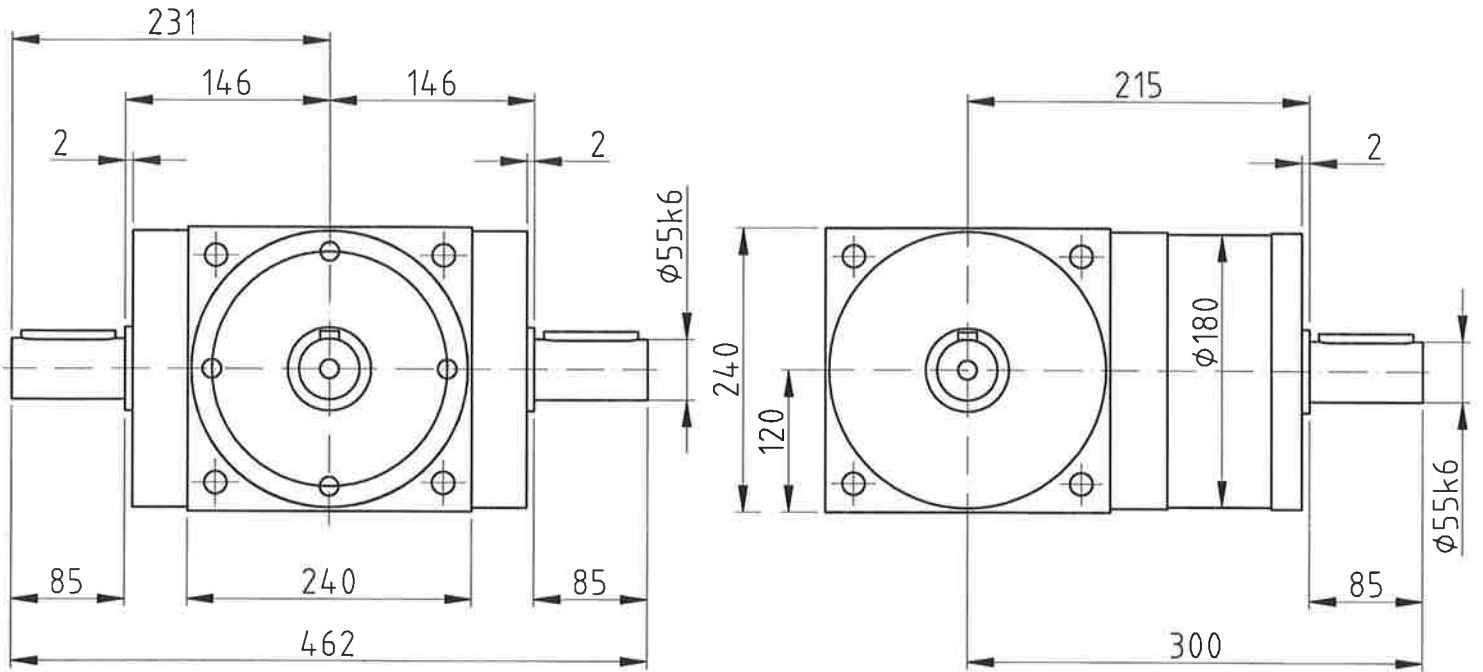




# Bevel Gear Box H240

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering

Elchengasse 36  
A-2551 Enzesfeld-Lindabrunn  
Tel.: ++43 (0) 2256 81287-0  
Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

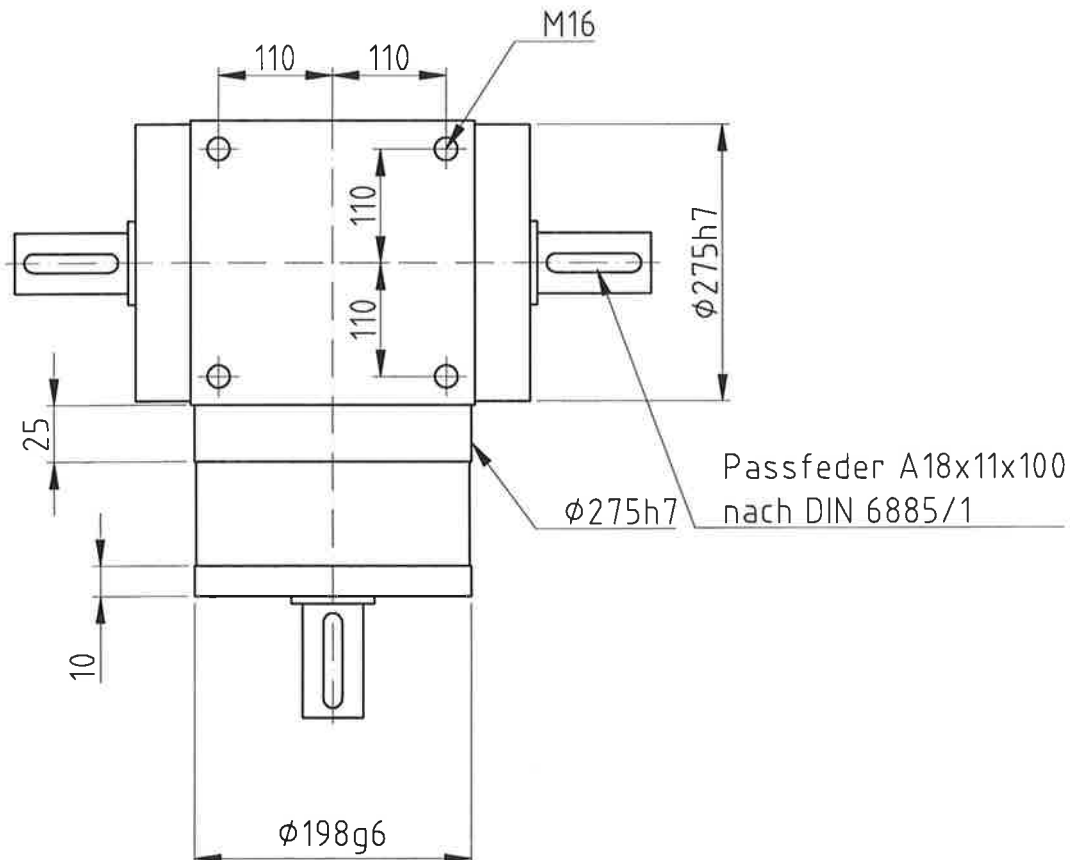
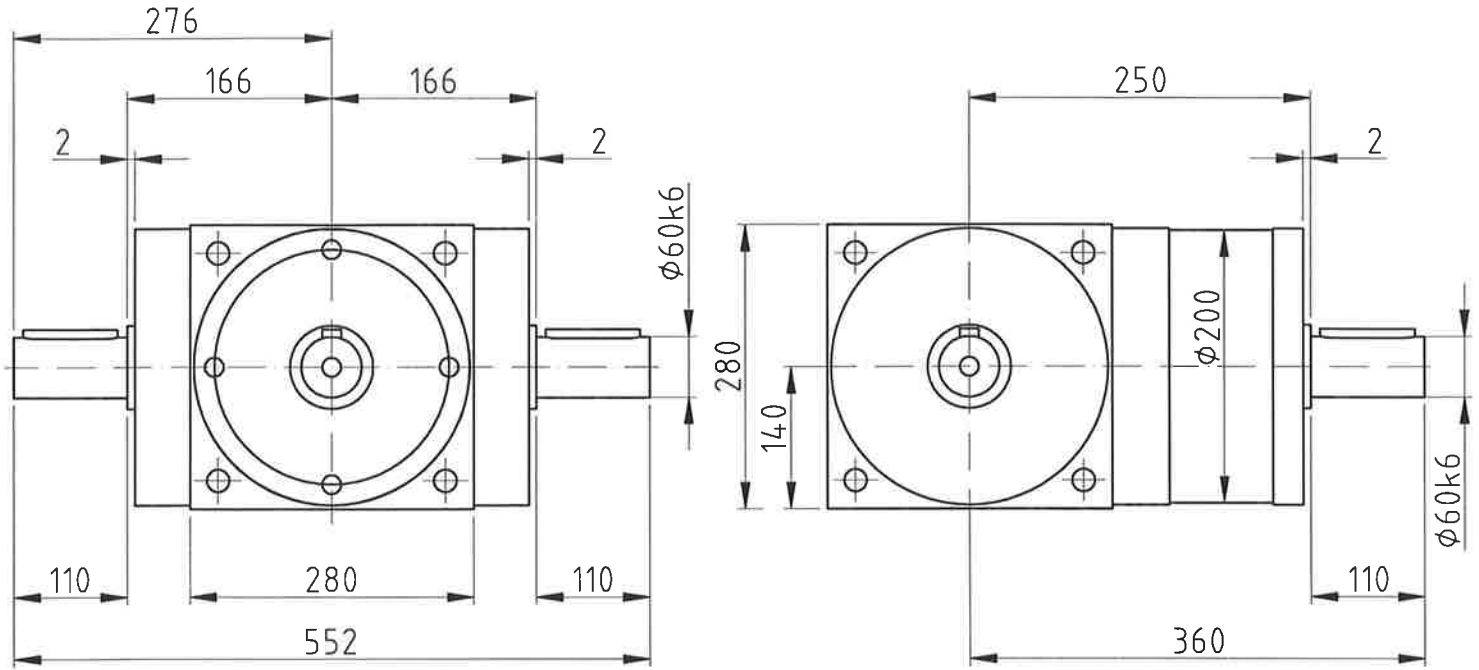




# Bevel Gear Box H280

**ENZFELDER** GMBH  
 Power transmission- and  
 lifting engineering

Eichengasse 36  
 A-2551 Enzesfeld-Lindabrunn  
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 Fax: ++43 (0) 2256 81287-95  
 E-Mail: office@enzfelder.at  
 Internet: www.enzfelder.at

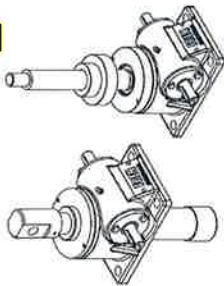




# Product overview 03/2015

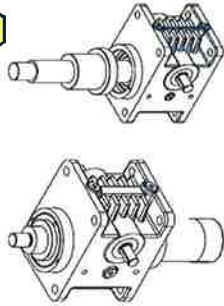
**SG**

Screw jack  
Classic



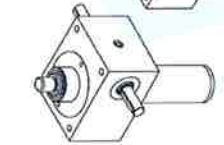
**HSG**

High performance-  
Screw jack



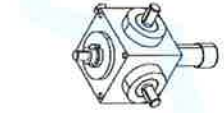
**BG**

Screw jack  
Cubic



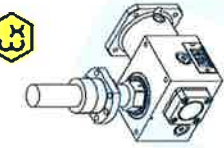
**SHG**

Quick-lifting  
screw jack



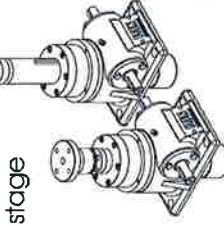
**SH**

Servo lifting  
gear



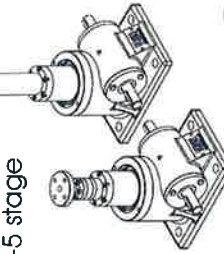
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



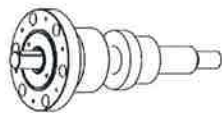
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



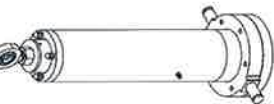
**SLA**

Spindlebearing



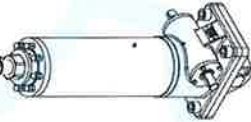
**SEZ**

Spindlebearings-  
Cylinder



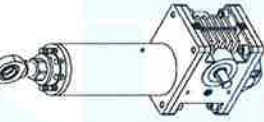
**ELZ**

Electric cylinder



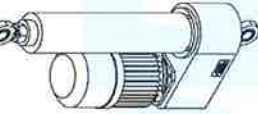
**HELZ**

High performance-  
Electric cylinder



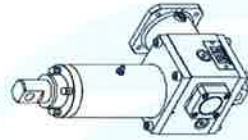
**ELZP**

Electric cylinder  
Parallel



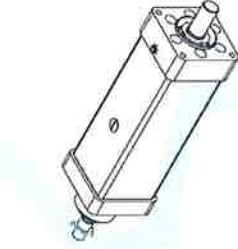
**SHELZ**

Servo electric-  
cylinder



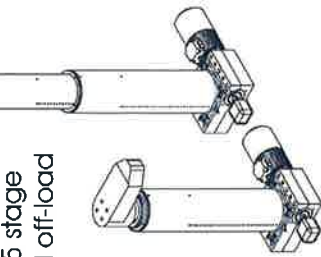
**EPNEU**

Spindle-  
Electric cylinder



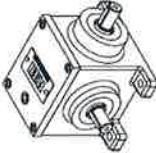
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



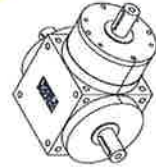
**K**

Bevel gear  
Type K



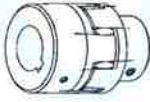
**H**

Bevel gear  
Type H



**R / GS**

Elastic / backlash-free  
Coupling



**RT**

Slip hub



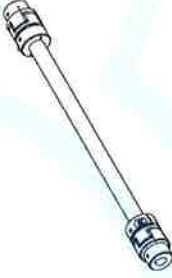
**RK**

Slip coupling



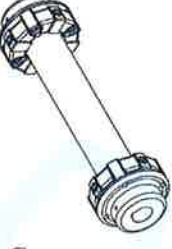
**ZR**

FREN  
Connecting shaft

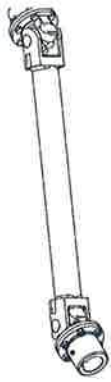


**G / GX**

Elastic  
Connecting shaft

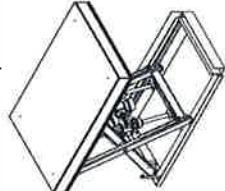


Cardan shaft



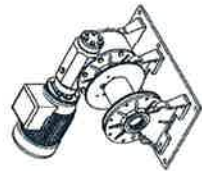
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



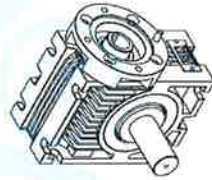
**PLG**

Planetary gear



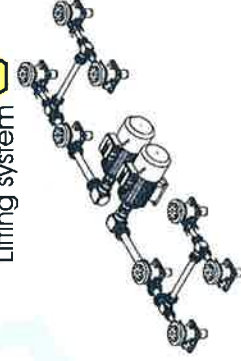
**uniCe**

Worm gear

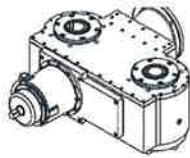
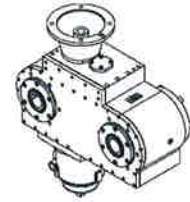


**HA**

Lifting system



**Special gear**





# ENZFELDER GmbH

Power transmission- and lifting engineering

**Claw Coupling R/GS**



**Slip Hub RT**



**Slip Coupling RK**



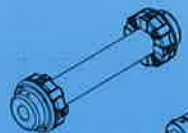
**Slip Claw Coupling RKK**



**Elastic Coupling EK**



**elastic Connectingshaft G/GX**



**FREN Connectingshaft ZR**



# History

**1969** Mr. Enzfelder established a job shop in Vienna. Equipped with some machinery, the Enzfelder Company manufactured machine parts according to drawings.

Within one year the number of employees rose to 3. The Enzfelder company started manufacturing threaded spindles and nuts according to drawings. Then the range of manufacturing was enlarged by toothed wheels, screw wheels and endless screws according to drawings.

**1974** The company including the complete manufacture was relocated to Enzesfeld.

**1975** The manufacture of spindle gears was launched. The company's experience in the manufacture of trapezoid-threaded spindles, nuts, worm gear pairs and casings was a valuable basis for the construction. After many tests, the serial production of spindle gears was launched one year later. The result was a product characterized by a first-rate price-performance ratio. The product was distributed by dealers all over Europe.

**1981** The planning and construction of small hydropower plants was launched to replace diesel generators. Environmental protection was not really a topic at that time, however, and the production was stopped in 1986.

**1989** The Enzfelder GesmbH company replaced the Franz Enzfelder Company.

**1990** Scissor-type lifting platforms and cable winches were added to the delivery program.

**1991** Resilient spacer shafts were tested and added to the production range. At the same time, the telescopic spindle gear was developed. A patent for this principle was applied for and issued.

**1993** The sale of spindle gears under their own name was launched and presented for the first time at the Hannover industrial fair. We have been approached with a variety of tasks and have provided solutions according to the customers' needs ever since.

**1994** In cooperation with our customers we produced the first bevel gears to specification.

**1995** Spindle bearing arrangements were designed and included in the standard program.

**1996** The Enzfelder company produced planet gear to specification for the first time.

**1998-1999** The standard programs were enlarged. Additionally, bevel gears are manufactured in a standard design.

**2000** The development of electric cylinders in standard design for very high loads (5-1000kN) was started. At the same time the telescopic spindle gears were refined to save the customer the guiding and locking devices. Since that time we have been able to offer telescopic cylinders, too.

**2001** The development of electric cylinders was completed, and these cylinders were added to the standard program.

At the same time the development and fabrication of cubic spindle gears for lifting loads between 2.5 and 150kN was started. These gears were added to the standard program as well.

**2002** were extended and optimized the series of the electric cylinders. Further we provide an electronic 2D-3D product catalogue of the spindle gears, it makes it possible to integrate our products into your system.

**2002-2003** We putted our new assembling and packaging hall, beside the manufacturing hall, in operation

**2003** We increased our machinery by buying a CNC machine tool with 7 axes, brand AXA. That new CNC machine allows a precise machining of the screw jack housings in only two clamping.

**2003-2004** The engineering started to use new 3-D CAD software, Solid Edge. That software enables our customers to integrate easily our drawings.

**2004** We opened a sales office in France.

**2004-2005** We started to design the high performance screw jacks HSG and we created a range of 10 different sizes.

**2005** First participation to an exhibition in France: INDUSTRIE 2005 at Lyon.

**2005-2006** We started to design a new range of telescopic screw jacks TSGLR. Today, these new telescopic screw jacks, with a more compact design, are used in the stage industry, in the aircraft industry, on train lifting equipments and in machine building.

**2008** We replaced the tread grinding machine by a new CNC thread grinding machine, brand Mikromat.

**2008-2009** transmission program is certified to ATEX

**2009-2010** beginning of the series production of Quick-lifting screw jacks SHG

**2010** Development of the transmission range Servo lifting gear (backlash & game adjustable)

Expand our global market with traders in Australia

**2011** development Servo lifting electric cylinder SHELZ (Servo lifting gear with cylindrical structure) and the beginning of the ELZP Series Electric cylinders parallel for Industry sector applications.

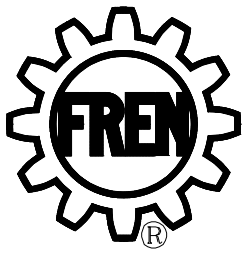
**2012** acquisition of the product group UniCe worm gear, helical worm geared motors, couplings, torque limiters and slip clutches. Expansion screw jacks cubic BG up to size for 1000kN

**2013-2014** revision of the telescopic spindle cylinder TSGZ the new cost-optimized design.

Development of product group Electric PNEU, electric cylinder with ball screw, stainless version in hygienically optimized design with mounting dimensions, speeds and forces such as pneumatic cylinder.

**2014** first Quick-lifting screw jacks with cylindrical structure can be delivered SHGZ = Quick-lifting electric cylinder

In recent years, customer problems are solved in the drive and lifting technology from us. Depending on the application, we developed the optimal solution and made with the best possible price / performance ratio.



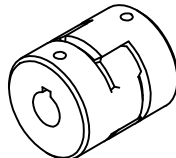
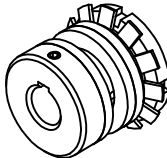
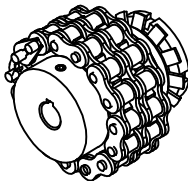
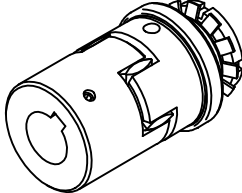
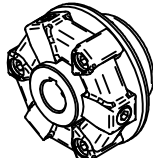
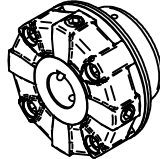
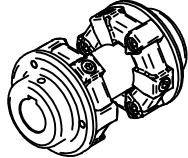
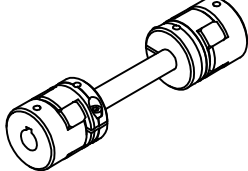
# Couplings, Connectingshafts

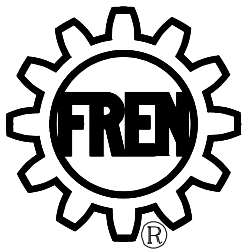
## Content

DEAR CUSTOMER

Our new catalog "Couplings, Connectingshafts" is in front of you. It shows all quality products from our house in a clear form. If you have any questions about the interpretation / dimensioning, our technical staff are gladly at your disposal. We hope that we have presented to you with our new catalog a purchase and sales assistance and wish you great success!

Your team from Enzfelder Power transmission- and lifting engineering

- 3- Claw Coupling R/GS 
- 4- Slip Hub RT 
- 5- Slip Coupling RK 
- 6- Slip Claw Coupling RKK 
- 7- elastic Coupling EK 
- 8- elastic Coupling EK 
- 9- elastic Connectingshaft G/GX 
- 10- FREN-Connectingshaft ZR 



# Claw Coupling R/GS

**ENZFELDER GmbH**

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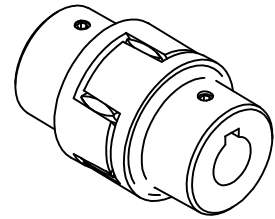
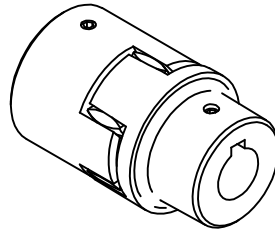
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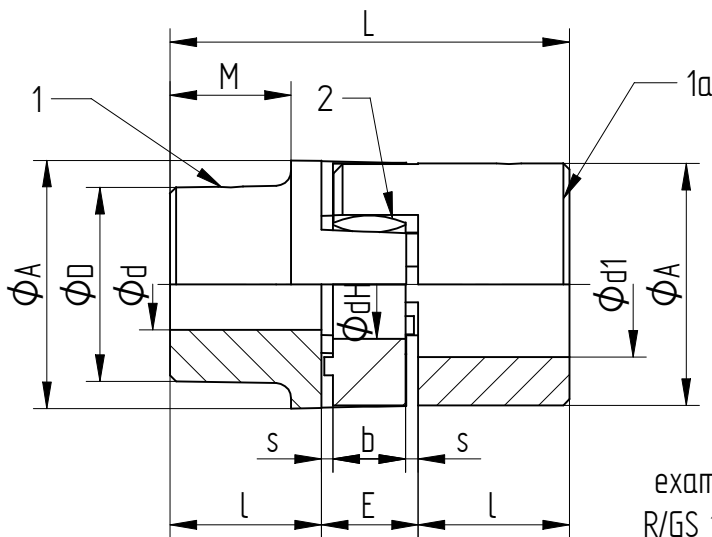
E-Mail: office@enzfelder.at

Internet: www.enzfelder.at

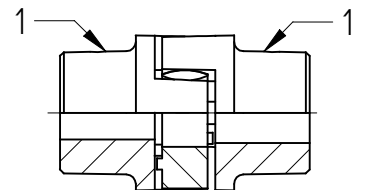
- torsionally flexible, low maintenance
- vibration damping
- axially pluggable
- compact design / low centrifugal moment
- drilling hole by ISO-clearance H7
- feather key groove by DIN 6885/1 - JS9
- explosion protection on request
- max. angular displacement = 1°30'
- Rotation angle with nominal torque = 3,2°
- Operating temperature range = -40°C bis +100°C



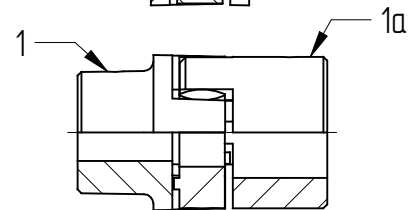
The nominal torques are valid for normal operation with soft shocks; because of the higher starting torque of three-phase squirrel-cage motors, a shock factor of 2 shall be used.



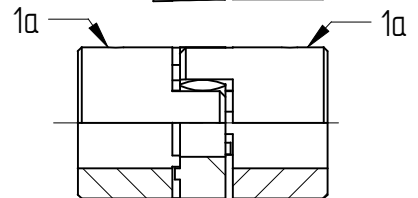
design 1-1



design 1-1a



design 1a-1a

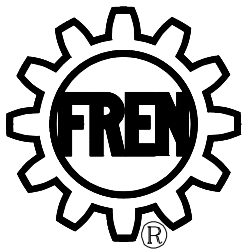


example of order:  
R/GS 19 - 16 - 19  
size - d/d1 - d/d1

size	element (design)	gear ring (part 2) nominal torque [Nm] 98 Sh A (red)	drilling hole		drilling hole		dimensions [mm]										material				
			pilot hole	Ød		pilot hole	Ød <sub>1</sub>		ØA	ØD	ØD <sub>1</sub>	L	I	E	s	b	M	Ød <sub>H</sub>	Alu	cast material	steel
				min	max		min	max													
R14	1a	12,5	-	-	-	-	4	14	30	-	30	35	11	13	1,5	10	10	10	•	-	•
R19/24	1	17	4	6	19	-	-	-	40	32	-	66	25	16	2	12	20	18	•	-	•
	1a		-	-	-	-	-	6	24	-	-	40	-	-	-	-	-	-	-	-	-
R24/28	1	60	6	8	24	-	-	-	55	40	-	78	30	18	2	14	24	27	•	•	•
	1a		-	-	-	-	-	6	8	28	-	-	48	-	-	-	-	-	-	-	-
R28/38	1	160	8	10	28	-	-	-	65	48	-	90	35	20	2,5	15	28	30	•	•	•
	1a		-	-	-	-	-	8	10	38	-	-	65	-	-	-	-	-	-	-	-
R38/45	1	325	10	12	38	-	-	-	80	66	-	114	45	24	3	18	37	38	•	•	•
	1a		-	-	-	-	-	36	38	45	-	-	77	-	-	-	-	-	-	-	-
R42/55	1	450	12	14	42	-	-	-	95	75	-	126	50	26	3	20	40	46	-	•	•
	1a		-	-	-	-	-	40	42	55	-	-	94	-	-	-	-	-	-	-	-
R48/60	1	525	13	15	48	-	-	-	105	85	-	140	56	28	3,5	21	45	51	-	•	•
	1a		-	-	-	-	-	46	48	60	-	-	102	-	-	-	-	-	-	-	-
R55/70	1	685	18	20	55	-	-	-	120	98	-	160	65	30	4	22	52	60	-	•	•
	1a		-	-	-	-	-	52	55	70	-	-	120	-	-	-	-	-	-	-	-
R65/75	1	940	20	22	65	-	-	-	135	115	-	185	75	35	4,5	26	61	68	-	•	•
	1a		-	-	-	-	-	63	65	75	-	-	135	-	-	-	-	-	-	-	-
R75/90	1	1920	28	30	75	-	-	-	160	135	-	210	85	40	5	30	69	80	-	•	•
	1a		-	-	-	-	-	73	75	90	-	-	160	-	-	-	-	-	-	-	-
R90/97	1	3600	38	40	97	-	-	-	200	160	-	245	100	45	5,5	34	81	100	-	•	•
R100/115	1	4950	48	50	115	-	-	-	225	180	-	270	110	50	6	38	89	113	-	•	•
R110/125	1	7200	58	60	125	-	-	-	255	200	-	295	120	55	6,5	42	96	127	-	•	•
R125/145	1	10000	58	60	145	-	-	-	290	230	-	340	140	60	7	46	112	147	-	•	•
R140/160	1	12800	58	60	160	-	-	-	320	255	-	375	155	65	7,5	50	124	165	-	•	•
R160/185	1	19200	78	80	185	-	-	-	370	290	-	425	175	75	9	57	140	190	-	•	•
R180/200	1	28000	83	85	200	-	-	-	420	325	-	475	195	85	10,5	64	156	220	-	•	•

resistant against rust (1.4301 & 1.4305) on enquiry

Subjects to measurement changes



# Slip Hub RT

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## RT-Slip Hubs

protect against damage by:

- overload
- shocks
- machine jams

RT-Slip Hubs are used for:

- sprockets and gears
- levers
- pulleys and wheels

advantages of RT-Slip Hubs:

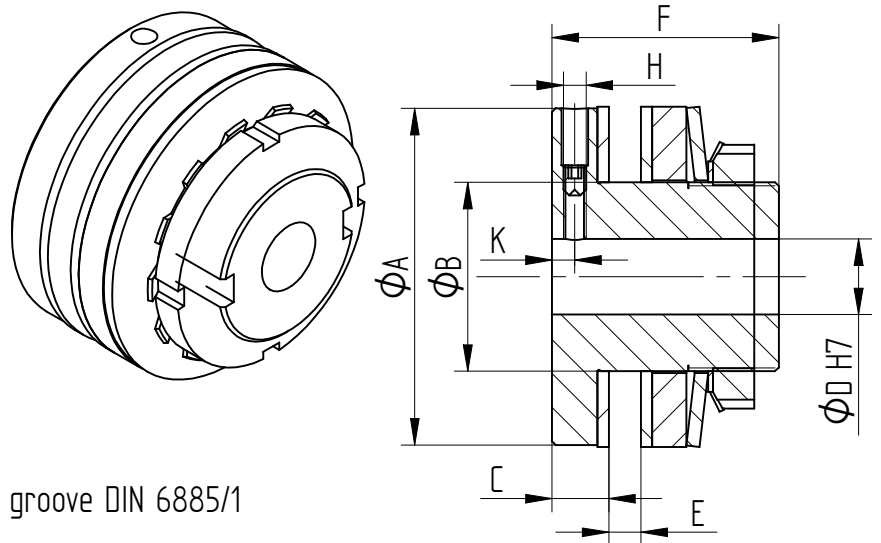
- easily assembled
- low maintenance
- compact and reliable
- torque setting by adjusting nut

example for order: RT120-20

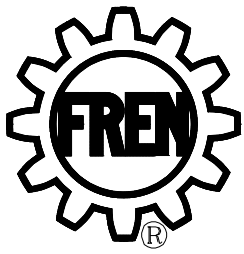
RT120 = slip hub with 120Nm max. torque

20 = drilled hole  $\varnothing 20\text{mm}$  with feather key groove DIN 6885/1

RT-Slip Hubs cost far less than a shutdown of a customer's plant. The determined torque should be 25 to 100% of the maximum shown in the tables. Too high torque will cause too much wear, too little will cause polished friction members, causing unwanted variance in the required torque. RT-Slip Hubs must be protected against oil and grease. It is necessary to check the functions from time to time. Build-in parts are to be grounded with a roughness of max.  $6\mu\text{m}$ .



size		RT12	RT20	RT40	RT70	RT120	RT190	RT350	RT630	RT1200	RT1700	RT2400	RT3500	RT5000
$T_{\max.}$	Nm	12	20	40	70	120	190	350	630	1200	1700	2400	3500	5000
$n_{\max.}$	$\text{min.}^{-1}$	800	800	800	600	500	450	410	380	340	320	300	250	220
$\varnothing A$	mm	30	38	45	55	65	75	90	110	140	160	180	210	240
$\varnothing B$ H8	mm	20	25	30	35	40	45	50	60	70	80	80	110	120
C	mm	11	11	11	13	13	15	15	18	18	23	25	25	28
$\varnothing D_{\min}$	mm	0	0	0	0	0	15	20	20	25	30	35	40	0
$\varnothing D_{\max}$	mm	12	15	19	22	25	30	32	40	50	55	65	80	100
$E_{\min}$	mm	3	3	3	4	5	7	8	9	10	11	13	14	16
$E_{\max}$	mm	7	7	9	13	13	15	16	19	22	24	28	30	32
F	mm	33	34	38	48	48	55	60	72	82	95	110	118	130
H		M4	M4	M4	M4	M4	M4	M4	M6	M6	M8	M8	M10	M10
K	mm	4	4	4	5	5	5	5	5	7	10	10	11	12
m	kg	0,4	0,6	0,9	1,4	1,7	2	2,2	3,3	6,4	9,1	13,4	20,1	24,5
smallest chain wheel		number of teeth												
chain pitch	6mm	19	23	27	32	37	42	-	-	-	-	-	-	-
	8mm	15	18	21	25	29	32	38	-	-	-	-	-	-
	3/8"	13	16	18	22	25	28	33	39	-	-	-	-	-
	1/2"	11	13	15	17	19	22	25	30	38	-	-	-	-
	5/8"	9	11	12	14	16	18	21	25	31	35	39	-	-
	3/4"	-	9	10	12	14	15	18	21	26	29	33	38	-
	1"	-	-	9	10	11	12	14	17	21	23	26	29	33
	1 1/4"	-	-	-	-	9	10	12	14	17	19	21	24	27
	1 1/2"	-	-	-	-	-	9	11	12	15	17	18	21	23
	1 3/4"	-	-	-	-	-	-	9	11	13	15	16	18	20
2"	-	-	-	-	-	-	9	10	12	13	14	16	18	



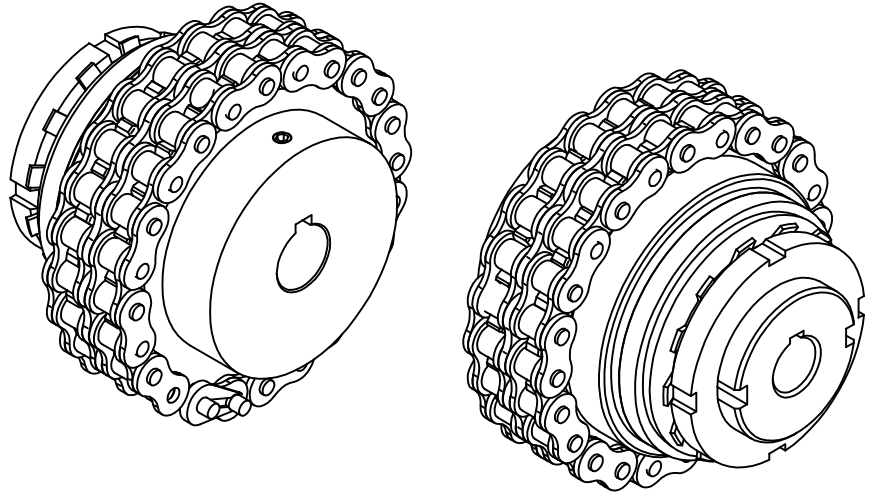
# Slip Coupling RK

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RK-Slip Couplings work as torquelimiter when connecting two shafts.  
 They consist of a RT-Slip Hub and a Chain-Coupling.

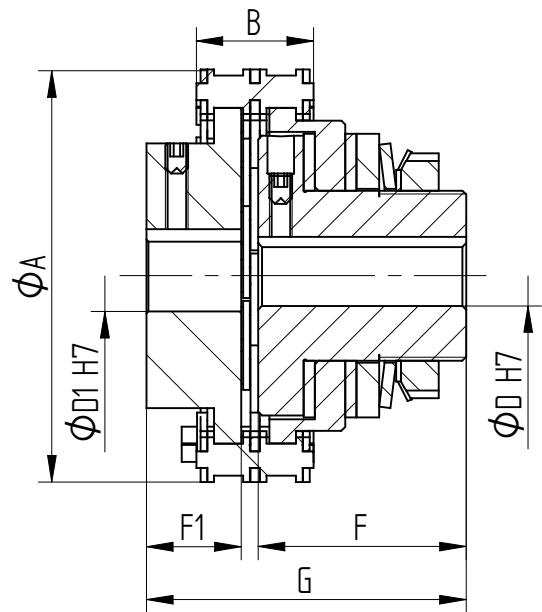
- advantages of RK-Slip Couplings:
- low maintenance
  - easily assembled
  - easy to unfasten



Only RK-Slip Couplings allow pure radial disassembling without axial dislocation of any part.

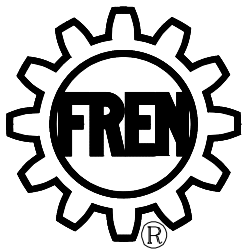
- they allow parallel misalignment of:
- 0,2mm ..... RK12 bis RK120
  - 0,25mm ... RK190 bis RK1200
  - 0,5mm ..... RK1700 bis RK5000
- a misalignment of 0,5° is tolerable

- example for order: RK190-170-20-25  
 RK190 = RK-slip coupling with 190Nm max. torque  
 170 = adjusted torque  
 20 = drilled hole  $\phi D$  20mm with feather key groove DIN 6885/1  
 25 = drilled hole  $\phi D1$  25mm with feather key groove DIN 6885/1



size		RK12	RK20	RK40	RK70	RK120	RK190	RK350	RK630	RK1200	RK1700	RK2400	RK3500	RK5000
$T_{max.}$	Nm	12	20	40	70	120	190	350	630	1200	1700	2400	3500	5000
$n_{max.}$	min. <sup>-1</sup>	800	800	800	600	500	450	410	380	340	320	300	250	220
$\phi A$	mm	54	63	72	82	91	110	134	146	194	216	240	288	337
$\phi B$	mm	24	24	24	24	24	31	31	31	31	68	68	68	68
$\phi D_{min}$	mm	0	0	0	0	0	15	20	20	25	30	35	40	0
$\phi D_{max}$	mm	12	15	19	22	25	30	32	40	50	55	65	80	100
$\phi D1_{min}$	mm	8	10	12	12	16	16	16	16	20	25	25	25	25
$\phi D1_{max}$	mm	22	28	32	38	40	43	46	46	58	74	76	90	105
F	mm	33	34	38	48	48	55	60	72	82	95	110	118	130
$F_1$	mm	16	16	20	20	20	25	30	30	40	50	50	55	65
G	mm	52	53	61	67	70	84	94	105	125	151	168	181	201
m	kg	0,7	1	1,4	2,1	2,5	3,6	4,6	6	12,1	20,9	29	41,9	55,8

Subjects to measurement changes



# Slip Claw Coupling RKK

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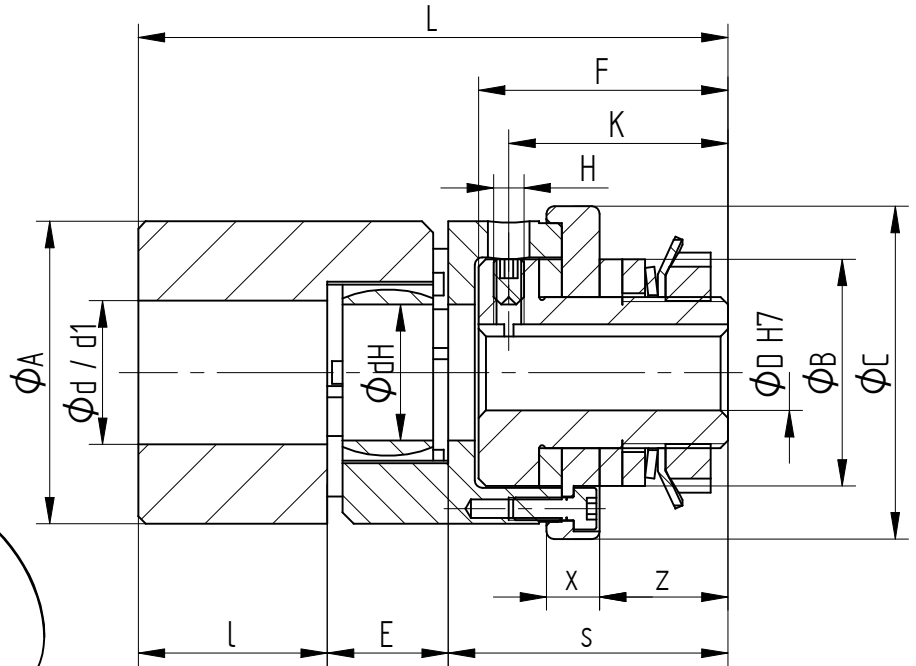
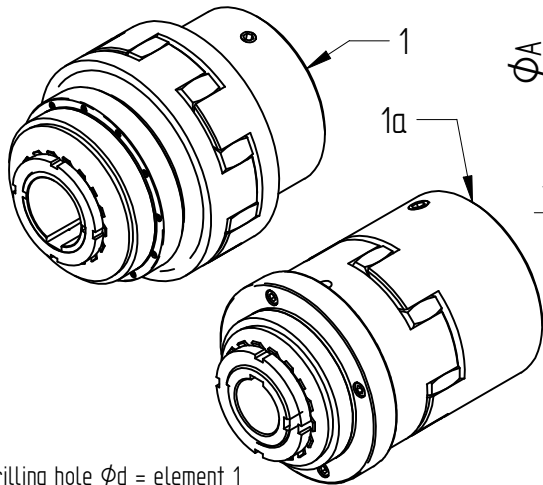
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Internet: www.enzfelder.at

RKK Slip Claw Couplings work as torque limiter when connecting two shafts.  
They consist of a RT-Slip Hub and a elastic Coupling.

Advantages of RKK Slip Claw Couplings:

- axial pluggable
- easily assembled
- torque setting in mounted situation
- drilling hole by ISO-clearance H7
- coupling half 1 & 1a possible



example of order:  
RKK 24 - 10 - 12 - 16  
size - Nm - D H7 - d/d1

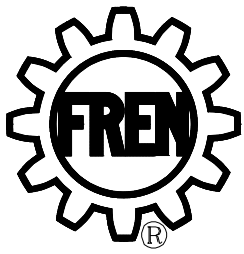
material on request

drilling hole  $\Phi d$  = element 1  
drilling hole  $\Phi d1$  = element 1a

size slip claw coupling	torque $T_{max}$	size elastic coupling	element (design)	pilot hole	drilling hole [mm]		drilling hole [mm]		dimensions [mm]														
					$\Phi d$	$\Phi d$	$\Phi d_1$	$\Phi d_1$	$\Phi A$	$\Phi D_{min}$	$\Phi D_{max}$	L	I	E	s	x	z	$\Phi B$	$\Phi C$	F	K	H	$\Phi d_H$
	Nm				min	max	min	max	min	max													
RKK19	12	R19	1	4	6	19	-	-	40	0	12	78	25	16	2	7	17	30	44	33	29	M4	18
		1a	-	-	-	-	6	24	55	0	15	90	30	18	2	9	17	38	58	34	30	M4	27
RKK24	20	R24	1	6	8	24	-	-	65	0	22	112	35	20	2,5	15	22	55	70	45	40	M5	30
		1a	-	-	-	-	8	28	80	0	25	129	45	24	3	16	24	65	86	48	43	M5	38
RKK28	70	R28	1	8	10	28	-	-	95	15	30	144	50	26	3	18	27	75	100	55	49	M6	46
		1a	-	-	-	-	10	38	105	20	32	161	56	28	3,5	18	32	90	110	60	54	M6	51
RKK38	120	R38	1	10	12	38	-	-	120	20	40	187	65	30	4	21	38	110	130	72	64,5	M6	60
		1a	-	-	-	-	12	45	135	20	40	202	75	35	4,5	21	38	110	145	72	64,5	M6	68
RKK42	190	R42	1	12	14	42	-	-	160	25	50	230	85	40	5	25	44	140	170	82	74,5	M6	80
		1a	-	-	-	-	14	55	200	30	55	265	100	45	5,5	30	52	160	210	95	85	M8	100
RKK48	350	R48	1	13	15	48	-	-	225	30	55	279	110	50	6	28	52	160	190	95	85	M8	113
		1a	-	-	-	-	15	60	255	35	65	316	120	55	6,5	34	59	180	210	110	99	M8	127
RKK55	630	R55	1	18	20	55	-	-	290	40	80	350	140	60	7	36	65	210	240	118	107	M10	147
		1a	-	-	-	-	20	70	320	0	100	385	155	65	7,5	38	72	240	265	130	117,5	M10	165
RKK65	630	R65	1	20	22	65	-	-	370	0	100	417	175	75	9	38	72	240	300	130	117,5	M10	190
		1a	-	-	-	-	22	75	420	0	100	452	195	85	10,5	38	72	240	335	130	117,5	M10	220
RKK75	1200	R75	1	28	30	75	-	-															
RKK90	1700	R90	1	38	40	97	-	-															
RKK100	1700	R100	1	48	50	115	-	-															
RKK110	2400	R110	1	58	60	125	-	-															
RKK125	3500	R125	1	58	60	145	-	-															
RKK140	5000	R140	1	58	60	160	-	-															
RKK160	5000	R160	1	78	80	185	-	-															
RKK180	5000	R180	1	83	85	200	-	-															

Subjects to measurement changes





# elastic Coupling EK

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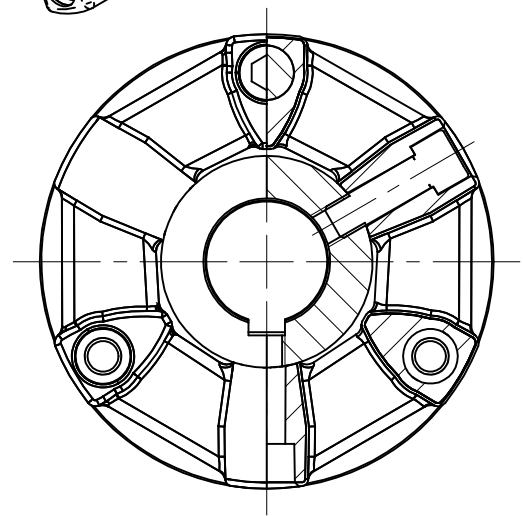
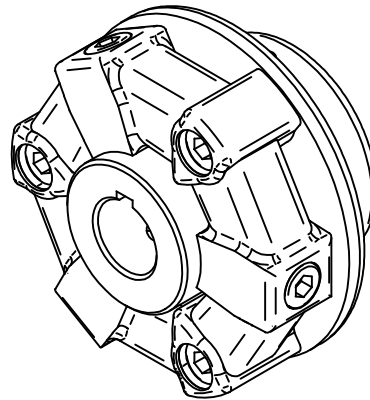
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characteristics and advantages of elastic Couplings:

- low weight, low torque of inertia
- high permissible rotation speed
- puncture proof
- high elasticity and misalignment capability by all directions (radial, axial, angular) with low counter forces on the shaft and bearings
- no precise alignment of shaft required
- shock and vibration damping
- uniformly backlash-free torque transmission
- maintenance-free, long lifetime
- no abrasion of rubber elements
- assembly requires no special tools
- attached units can be uninstalled transversely without axial screw
- by solving the radial screw the drive can be easily separated and rotated without dismantling
- no axial reaction forces on shaft and bearings

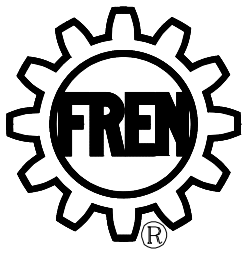


performance diagram elastic Coupling EK

size	nominal torque $T_{KN}$	max-torque $T_{Kmax}$	torsion angle by $T_{KN}$	torsion angle by $T_{Kmax}$	max. rotational speed	angular compliancy (rotation speed dependent)	axial compliancy	radial compliancy (rotation speed dependent)	permanently changing torque	acceptable power dissipation	dynamictorsional rigidity by 50 Shore	dynamictorsional rigidity by 60 Shore	axial spring value	radial spring value	angular spring value
	Nm	Nm	deg	deg	min <sup>-1</sup>	deg	mm	mm	Nm	W	Nm/rad	Nm/rad	N/mm	N/mm	Nm/deg
EK01	10	25	6°	17°	10000	3°	2	1,5	5	6	90	140	38	150	0,3
EK02	20	60	6°	17°	8000	3°	3	1,5	10	10	180	290	22	150	0,3
EK04	50	125	5°	12°	7000	3°	3	1,5	20	15	550	850	75	500	2,4
EK08	100	280	5°	14°	6500	3°	4	2	40	25	900	1500	75	500	3,6
EK12	140	360	3°	7,5°	6500	2°	4	2	50	30	2700	4400	250	1000	9,0
EK16	200	560	5°	14°	6000	3°	5	2	80	40	2000	3400	100	500	5,0
EK22	275	750	3°	7,5°	6000	2°	5	2	100	50	6100	9000	500	1300	12,0
EK25	315	875	5°	14°	5000	3°	5	2	125	68	2800	4500	140	600	7,0
EK28	420	1200	3°	7,5°	5000	2°	5	2	150	75	7500	12000	550	1400	17,0
EK30	500	1400	5°	14°	4000	3°	5	2	200	80	4800	7800	190	750	9,0
EK50	700	2100	3°	7,5°	4000	2°	5	2	300	90	12000	19000	650	2200	26,0
EK80	900	2100	3°	7,5°	4000	2°	3	1,5	320	100	16000	25000	850	2900	34,0
EK90	1100	3150	5°	14°	3600	3°	5	2	450	120	10500	16000	220	1000	17,0
EK140	1700	4900	3°	7,5°	3600	2°	5	2	700	150	26500	40000	650	2300	38,0
EK200	2400	6000	3°	7,5°	3000	2°	5	2	960	170	38700	60000	900	3100	48,0
EK250	3000	8750	3°	7,5°	3000	2°	5	2	1250	200	43000	77000	1150	4100	68,0
EK400	5000	12500	3°	7,5°	2500	2°	5	2	2000	250	75000	120000	1300	6000	88,0

angular compliancy, axial spring value, radial spring value and angular spring value by 60 Shore (static measured  $C_{dyn} = C_{stat} * 1,3$ )

Subjects to measurement changes



# elastic Coupling EK

**ENZFELDER GmbH**

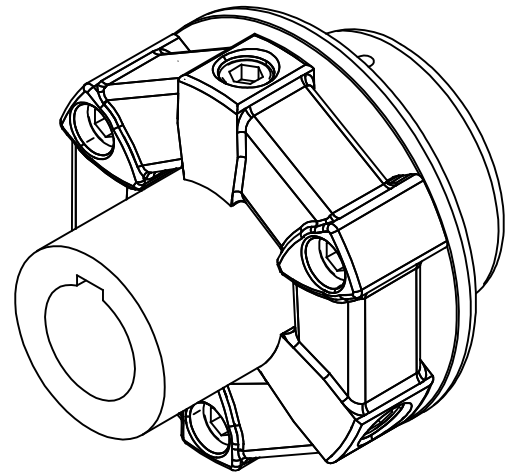
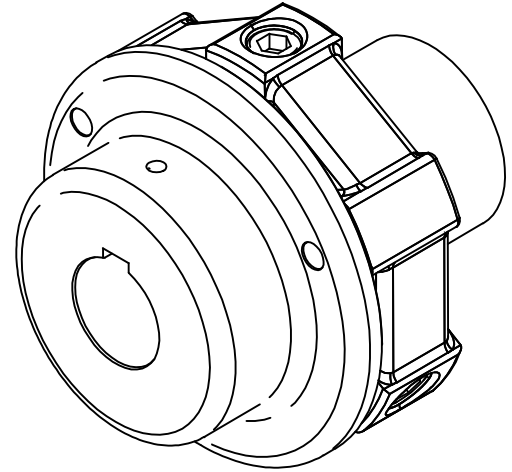
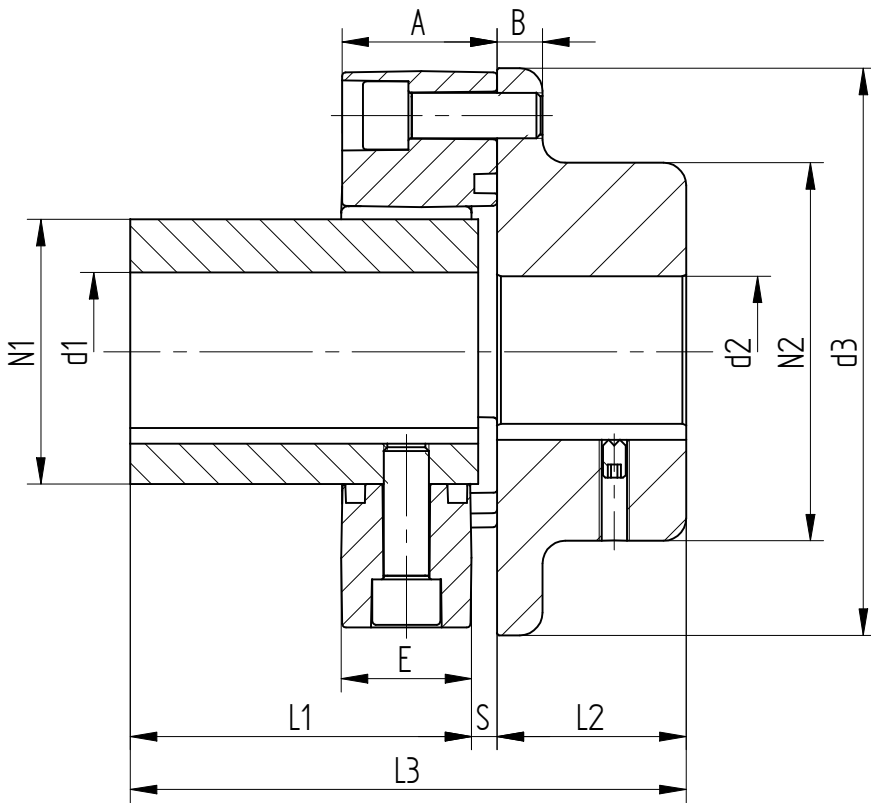
A-2551 Enzesfeld, Eichengasse 36

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Internet: www.enzfelder.at



example for order:

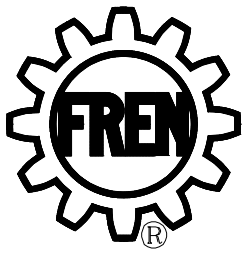
EK 01 - 10 - 20

size - d1 - d2

L1, L3 = special length on request

size	dimensions [mm]														weight [kg]	mass moment of inertia J [kg*cm <sup>2</sup> ]
	d <sub>1</sub>		d <sub>2</sub>		d <sub>3</sub>	A	B	E	L <sub>1</sub>	L <sub>2</sub>	L <sub>3</sub>	N <sub>1</sub>	N <sub>2</sub>	S		
	pilot hole	max.	pilot hole	max.												
EK01	8	19	8	25	56	24	7	22	24	24	50	30	36	2	0,47	1,6
EK02	10	26	12	38	85	24	8	20	28	28	60	40	55	4	1,06	7,3
EK04	12	30	15	45	100	28	8	24	30	30	64	45	65	4	2,31	11,3
EK08	12	38	18	55	120	32	10	28	42	42	88	60	80	4	3,45	41,0
EK12	12	38	18	55	122	32	10	28	42	42	88	60	80	4	3,55	44,2
EK16	15	48	20	70	150	42	12	36	50	50	106	70	100	6	6,16	118,8
EK22	15	48	20	70	150	42	12	36	50	50	106	70	100	6	6,42	126,5
EK25	15	55	20	85	170	46	14	40	55	55	116	85	115	6	9,31	215,0
EK28	15	55	20	85	170	46	14	40	55	55	116	85	115	6	9,51	247,8
EK30	20	65	25	100	200	58	16	50	66	66	140	100	140	8	15,21	545,5
EK50	20	65	25	100	200	58	16	50	66	66	140	100	140	8	15,6	550,5
EK80	20	65	25	100	205	65	16	61	66	66	141,5	100	140	9,5	16,6	585,5
EK90	30	85	30	110	260	70	19	62	80	80	168	125	160	8	28,67	1630,1
EK140	30	85	30	110	260	70	19	62	80	80	168	125	160	8	29,45	1742,6
EK200	35	105	35	110	300	80	19	72	94	90	192	145	160	8	33,16	3050,0
EK250	40	115	40	130	340	85	19	77	100	100	208	160	195	8	44,42	5264,0
EK400	40	120	40	140	370	105	25	95	125	125	260	170	200	10	57,23	9130,0

Subjects to measurement changes



# elastic Connectingshaft G/GX

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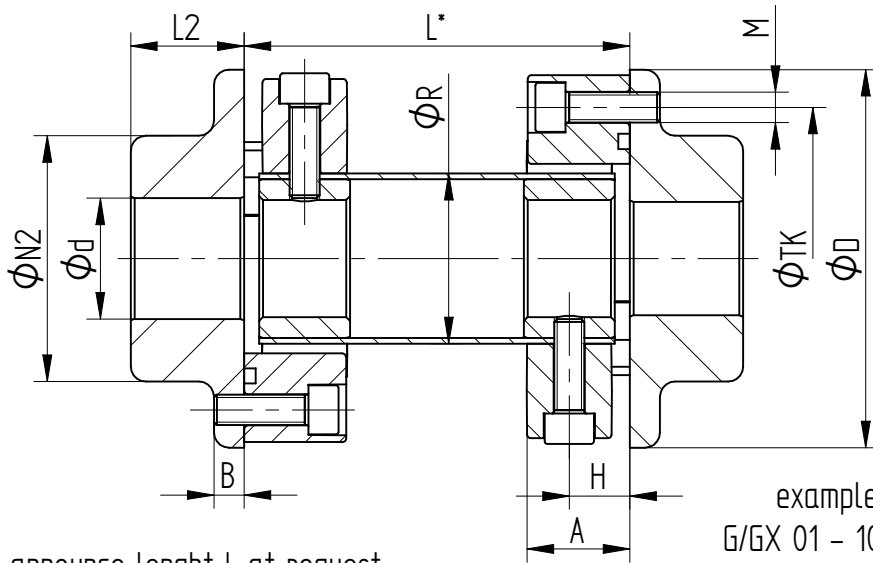
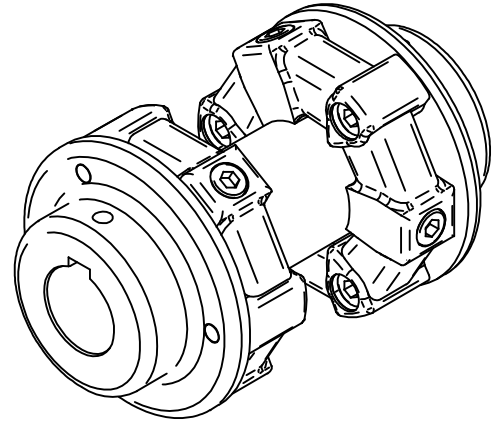
Fax: ++43/0/2256/81287-95

E-Mail: office@enzfelder.at

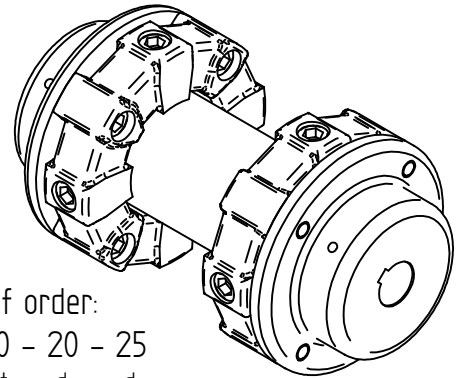
Internet: www.enzfelder.at

characteristics and advantages of elastic Connectingshaft G/GX

- simple design, highly torsionally flexible
- noise and vibration damping
- no standardized lengths, individually according to customer
- Compensation of axial, radial and angular displacement
- maintenance-free
- removal of the middle part without axial displacement



Please indicate the speed to review the critical speed

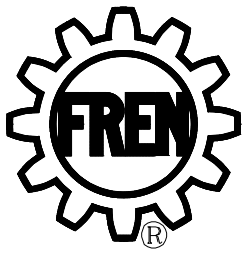


example of order:  
G/GX 01 - 1000 - 20 - 25  
size - length - d - d

\* announce length L at request

size G	T <sub>KN</sub> [Nm]	size GX	T <sub>KN</sub> [Nm]	dimensions [mm]										
				A	B	D	d		H	L <sub>2</sub>	N <sub>2</sub>	R	T <sub>K</sub>	M
							pilot hole	max.						
G01	10	GX01	10	24	7	56	8	25	13	24	36	30	44	2xM6
G02	20	GX02	30	24	8	85	12	38	14	28	55	40	68	2xM8
G04	50	GX04	60	28	8	100	15	45	16	30	65	45	80	3xM8
G08	100	GX08	120	32	10	120	18	55	18	42	80	60	100	3xM10
G12	140	-	-	32	10	122	18	55	18	42	80	60	100	4xM10
G16	200	GX16	240	42	12	150	20	70	24	50	100	70	125	3xM12
G22	275	-	-	42	12	150	20	70	24	50	100	70	125	4xM12
G25	315	GX25	370	46	14	170	20	85	26	55	115	85	140	3xM14
G28	420	-	-	46	14	170	20	85	26	55	115	85	140	4xM14
G30	500	GX30	550	58	16	200	25	100	33	66	140	100	165	3xM16
G50	700	-	-	58	16	200	25	100	33	66	140	100	165	4xM16
G80	900	-	-	65	16	205	25	100	34,5	66	140	100	165	4xM16
G90	1100	GX90	1500	70	19	260	30	110	39	80	160	125	215	3xM20
G140	1700	-	-	70	19	260	30	110	39	80	160	125	215	4xM20
G200	2400	-	-	80	19	300	35	110	44	90	160	145	250	4xM20
G250	3000	-	-	85	19	340	40	130	46	100	195	160	280	4xM20
G400	5000	-	-	105	25	370	40	140	57	125	200	170	300	4xM24

Subjects to measurement changes



# FREN-Connectingshaft ZR

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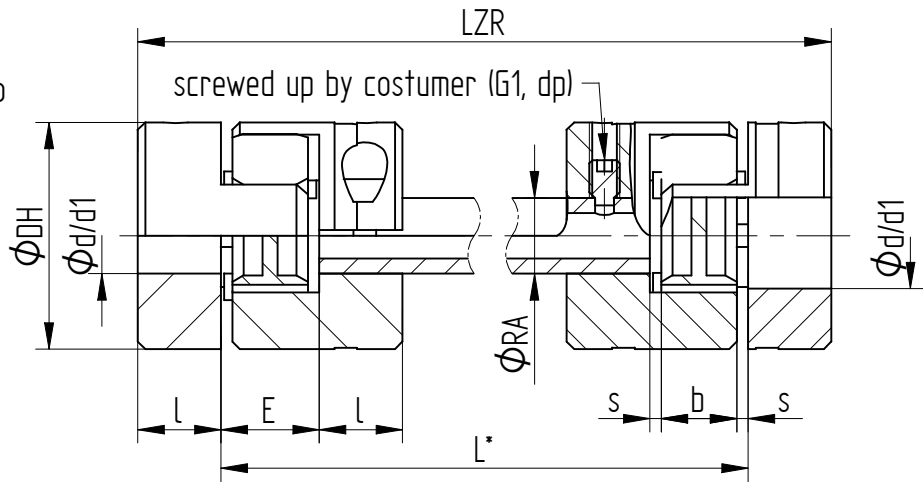
Tel: ++43/0/2256/81287-0

Fax: ++43/0/2256/81287-95

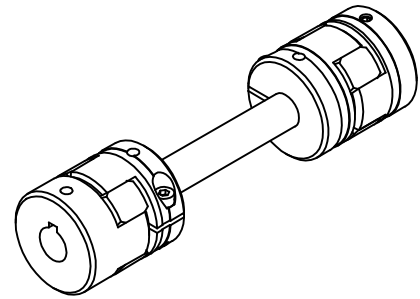
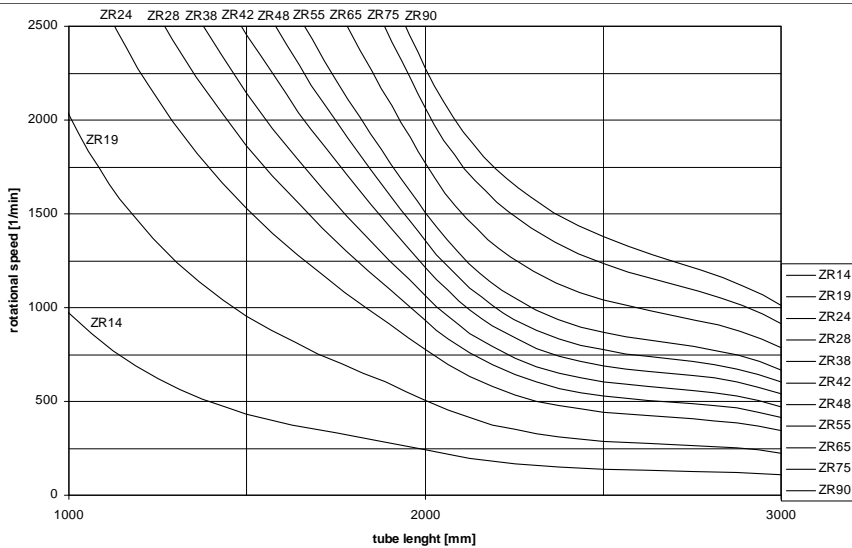
E-Mail: office@enzfelder.at

Internet: www.enzfelder.at

FREN-connectingshaft are used to overcome large shaft distances.



Please indicate the speed to review the critical speed



example of order:  
ZR 24 - 1000 - 19 - 24  
size - length - d/d1 - d/d1

\* announce length L at request

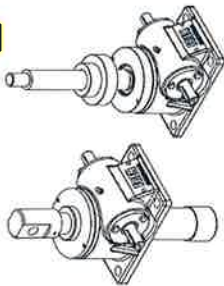
size	element (design)	drilling hole element 1		drilling hole element 1a		dimensions [mm]					intermediate pipe	attachment screw part 2 property class 10.9	L <sub>ZR</sub>				material			
		Ød	Ød	Ød <sub>1</sub>	Ød <sub>1</sub>	ØD <sub>H</sub>	l	E	s	b	R <sub>A</sub>	M <sub>1</sub>	T <sub>A</sub> [Nm]	safety screw G 1	pin hole d <sub>p</sub> [mm]	axial displacement [mm]	angular displacement [mm]	Alu	cast material	steel
ZR14	1a	-	-	4	14	30	11	13	1,5	10	Ø10x2	M3	1,8	M4	2,5	1	0,9	•	-	•
ZR19/24	1	6	19	-	-	40	25	16	2	12	Ø20x3	M6	14	M6	4	1,2	0,9	•	-	•
	1a	-	-	6	24									M8	5,5	1,4	0,9	•	•	•
ZR24/28	1	8	24	-	-	55	30	18	2	14	Ø30x4	M6	14	M8	7	1,5	0,9	•	•	•
	1a	-	-	8	28									M10	12	2,1	1,1	-	•	•
ZR28/38	1	10	28	-	-	65	35	20	2,5	15	Ø35x4	M8	35	M12	12	2,2	1,1	-	•	•
	1a	-	-	10	38									M16	12	2,6	1,2	-	•	•
ZR38/45	1	12	38	-	-	80	45	24	3	18	Ø40x4	M8	25	M16	12	3	1,2	-	•	•
	1a	-	-	12	45									M20	15	3,4	1,2	-	•	•
ZR42/55	1	14	42	-	-	95	50	26	3	20	Ø45x4	M10	49	M20	15	3,4	1,2	-	•	•
	1a	-	-	14	55															
ZR48/60	1	15	48	-	-	105	56	28	3,5	21	Ø50x4	M12	86							
	1a	-	-	15	60															
ZR55/70	1	20	55	-	-	120	65	30	4	22	Ø55x4	M12	120							
	1a	-	-	20	70															
ZR65/75	1	22	65	-	-	135	75	35	4,5	26	Ø65x5	M12	120							
	1a	-	-	22	75															
ZR75/90	1	30	75	-	-	160	85	40	5	30	Ø75x5	M16	295							
	1a	-	-	30	90															
ZR90/97	1	40	97	-	-	200	100	45	5,5	34	Ø80x5	M20	590							

Subjects to measurement changes

# Product overview 03/2015

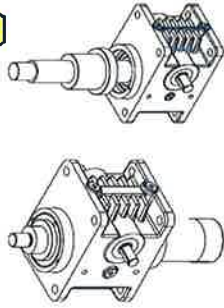
**SG**

Screw jack  
Classic



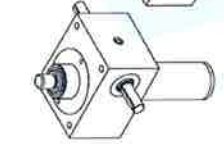
**HSG**

High performance-  
Screw jack



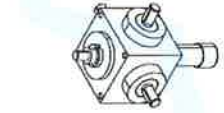
**BG**

Screw jack  
Cubic



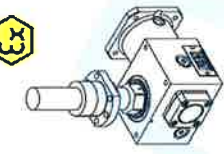
**SHG**

Quick-lifting  
screw jack



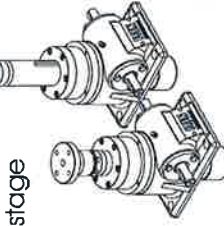
**SH**

Servo lifting  
gear



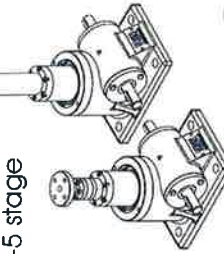
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



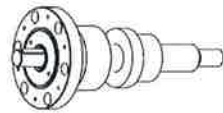
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



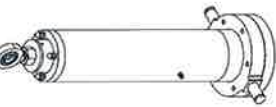
**SLA**

Spindlebearing



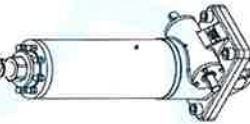
**SEZ**

Spindlebearings-  
Cylinder



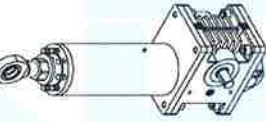
**ELZ**

Electric cylinder



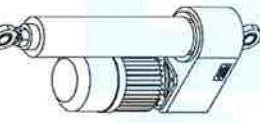
**HELZ**

High performance-  
Electric cylinder



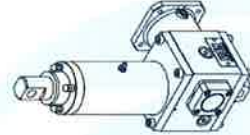
**ELZP**

Electric cylinder  
Parallel



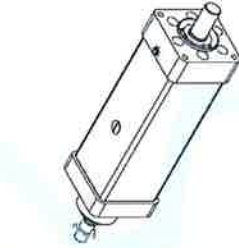
**SHELZ**

Servo electric-  
cylinder



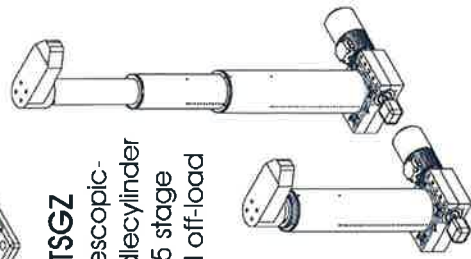
**EPNEU**

Spindle-  
Electric cylinder



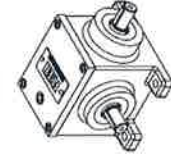
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



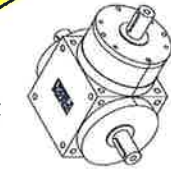
**K**

Bevel gear  
Type K



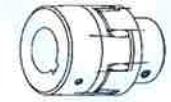
**H**

Bevel gear  
Type H



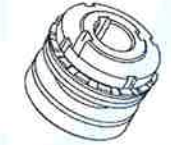
**R / GS**

Elastic / backlash-free  
Coupling



**RT**

Slip hub



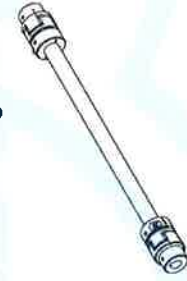
**RK**

Slip coupling



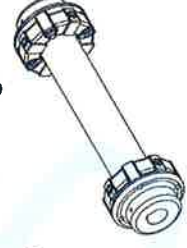
**ZR**

FREN  
Connecting shaft

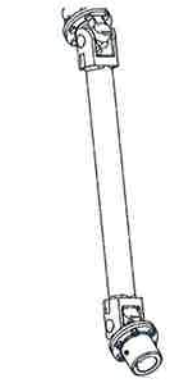


**G / GX**

Elastic  
Connecting shaft

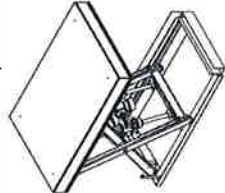


Cardan shaft



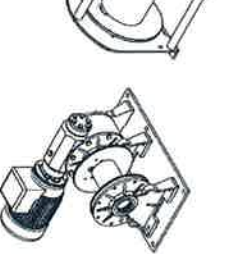
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



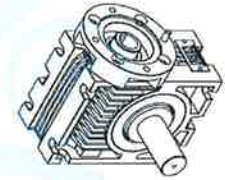
**PLG**

Planetary gear



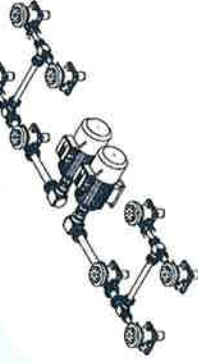
**uniCe**

Worm gear

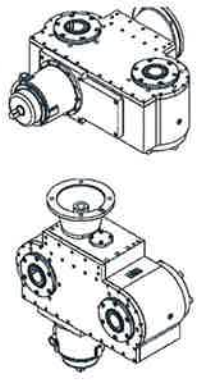


**HA**

Lifting system



**Special gear**



# Rope winches



# Explanation rope winches

## Table of contents

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Rope winch types MC and MC-B	4-5
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Rope winch type MC 3 . .	8-9
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Rope winch type AM	12-13
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Questionnaire	15

## Explanation rope winches

### Customized rope winch

There are many constructions possible for rope winches. However, a large number of standards and rules must be observed. Therefore, a few issues are addressed below.

### Rope strength

The rope strength indicated in this catalog is always for the first layer. If any other layer applies, it is specified. The rope strength is indicated in kg. The indicated rope strength is always the maximum rope strength. It is also important to indicate the working length of the rope because a minimum of 3 safety windings must always remain on the drum.

### Rope types

For lifting operations a minimum of 5-fold rope safety must be ensured in any case. Ropes for draw winches usually have a 3-fold safety against traction. However, there are uses or standards that require higher rope safety. The safety is related to the breaking load of a rope.

For normal ropes (6x36) the maximum entry is 2° for plain drums and 3° for grooved drums. The following help or pulled block should not be more than 20 x the drum length in case of grooved drums.

### Velocity

The velocity varies according to rope layer. If this does not meet your requirements, the rope must be rolled up, which obviously increases the drum length. To be able to vary the speed during operation, frequency converters or, in hydraulic winches, proportional valves are required.

### Brakes

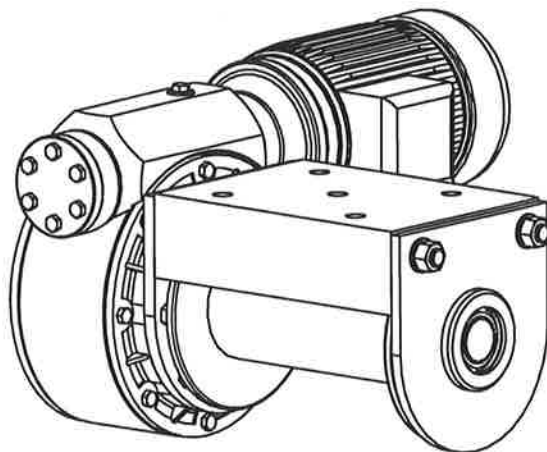
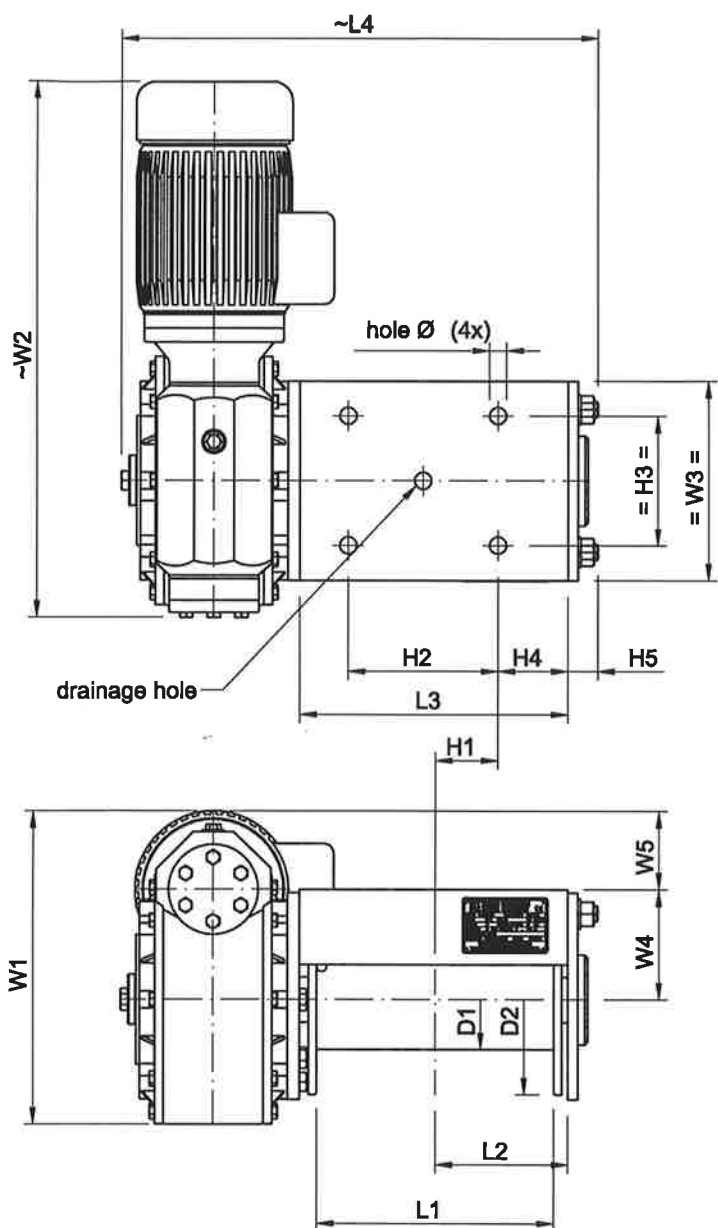
Each hoist must be equipped with a safety brake system. The only self-locking winches are worm gear winches. For lifting operations two independent brakes must be installed. In worm gear winches one brake is replaced by self-lock. During idle intervals the brakes must be closed.



# Worm gear winch Type AK

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## Rope winch AK

The self-locking worm gear winches, AK; which come in two sizes, were developed specifically for hoisting loads. The winches can be used for lifting e.g. cars. Please find the available accessories on page 14 ff.

Winch type	Rope strenght	Rope strenght	Recommended rope diameter	Speed	Drum capacity		Engine capacity	Weight
	first layer	third layer		first layer	first layer	fifth layer		
	KG.	KG.		M/MIN.	M.	M.		
MC 1200 AK	960	740	8	5	6	40	2,2	92
MC 1700 AK	1250	1000	10	5,5	8	54	3	140

AK TYPE	D1	D2	L1	L2	L3	L4	H1	H2	H3	H4	H5	W1	W2	W3	W4	W5	HOLEØ
1200	100	190	237	132.5	268	477	62.5	150	130	70	30	313.5	537	200	110	78.5	17
1700	121	240	240	134	291	540	59	170	160	75	30	400	638	240	150	105	17





# Worm gear winch

## Types MC and MC-B

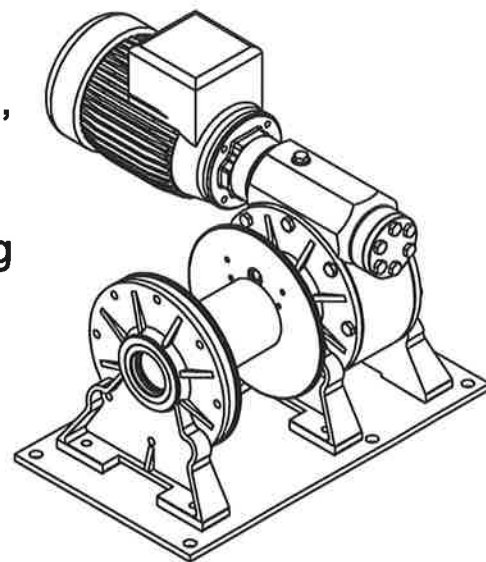
**ENZFELDER** GMBH  
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 Internet: www.enzfelder.at

### Rope winch MC

The compact and robust MC rope winch is used for traction of horizontal loads. The worm gear is self-locking, acting as simple brake.

### Rope winch MC-B

If the load is lifted up and down or moved on slopes, the motor must be designed as brake motor to be able to stop lowering immediately.



### Construction

In the construction all current safety regulations and standards were observed. The materials and manufacturing processes were selected carefully. Both winches can be operated in all mounting positions. The winches are equipped with three-phase motors (400V-50Hz). The standard model is not supplied with a grooved drum.

### Special models and accessories

As our winches are used for such a variety of applications a large number of accessories are available, so that your winch meets your individual requirements. The range goes from pressure roller to reversing switch. The winches are not ready for operating before you have chosen a control, a reversing switch, a spindle end switch, a rope pressure roller or a grooved drum. Please take note of the available accessories on page 14 ff.

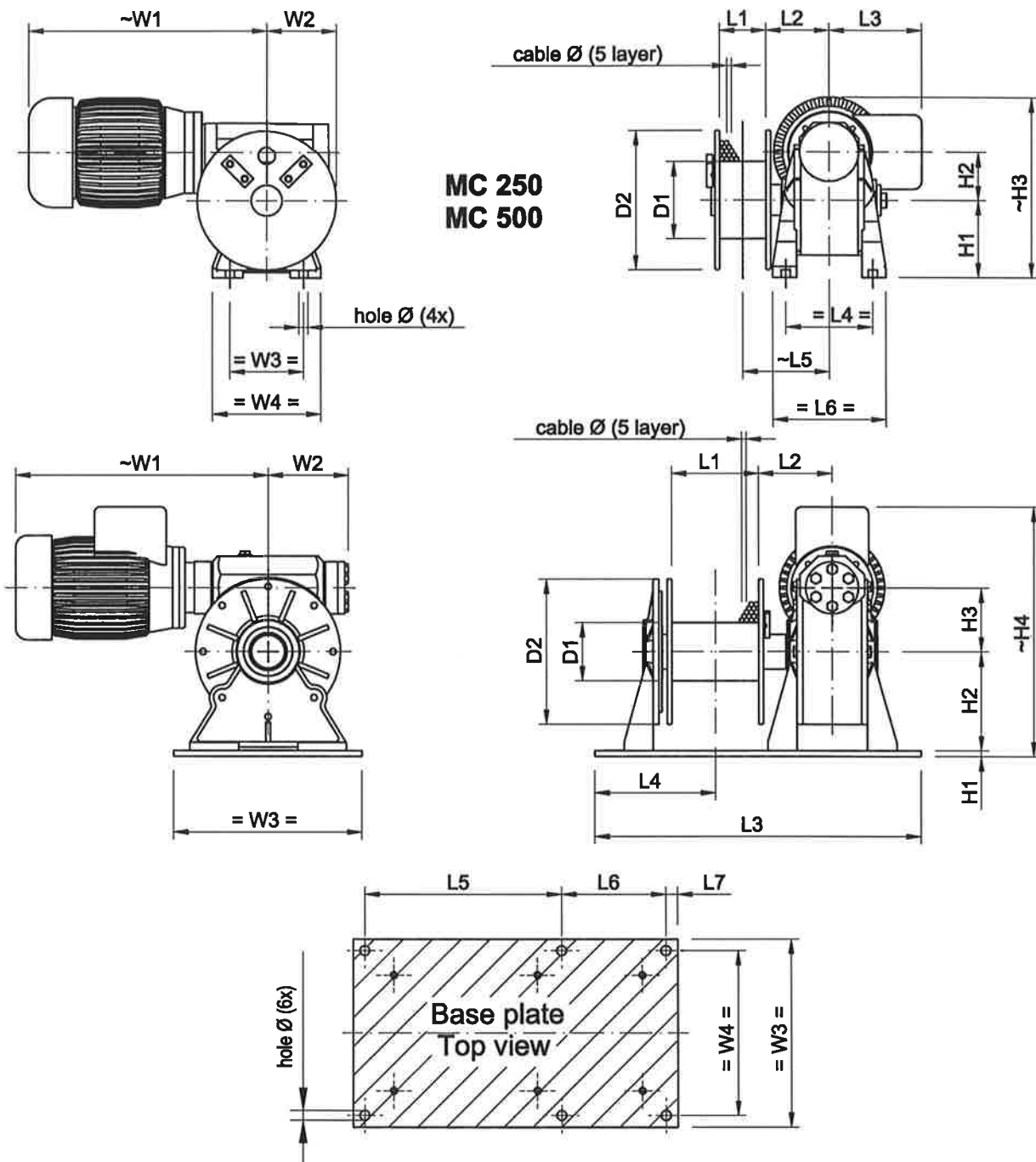
Winch type	Rope traction		Required lifting power		Proposed rope diameter (MM)	Speed (M/MIN)	Drum capacity		Motor rating (400 V KW)	Weight (without rope) (KG)
	first layer (KG)	third layer (KG)	first layer (KG)	third layer (KG)			first layer (M)	fifth layer (M)		
MC 250	250	200	200	160	6	6	3	20	0,55	22
MC 500	500	400	400	330	6	6	3	20	1,1	35
MC 950	950	730	760	490	8	5	6	40	1,5	55
MC 1200	1200	930	960	740	8	5	6	40	2,2	92
MC 1700	1700	1310	1300	1000	10	5,5	8	54	3	140
MC 2200	2200	1690	1700	1300	12	6,5	10	65	4	180
MC 2800	2800	2150	2000	1800	13	7	12	81	5,5	254



# Worm gear winch

## Types MC and MC-B

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TYPE	D1	D2	L1	L2	L3	L4	L5	L6	L7	H1	H2	H3	H4	W1	W2	W3	W4	HOLE Ø
MC 250	100	180	60	81	118.5	111	111	143	-	100	62.17	233	-	326	90	95	140	11.5
MC 500	100	200	60	91	91.9	146	121	186	-	142	86.9	319	-	374	110	140	218	11.5
MC 950	100	200	150	104	500	180	320	150	15	10	142	86.9	378.4	383	110	270	240	13
MC 1200	100	250	150	125.5	560	208	340	180	20	10	170	110	429.5	436	132	325	285	17
MC 1700	121	280	200	146.5	640	232.5	415	185	20	15	195	130	487	498	154.3	370	320	17
MC 2200	146	320	250	157	710	265	470	200	20	15	220	150	580	524	154	410	360	17
MC 2800	159	370	300	183	850	317.5	565	235	25	15	254	117.5	641.5	551	205	440	380	20

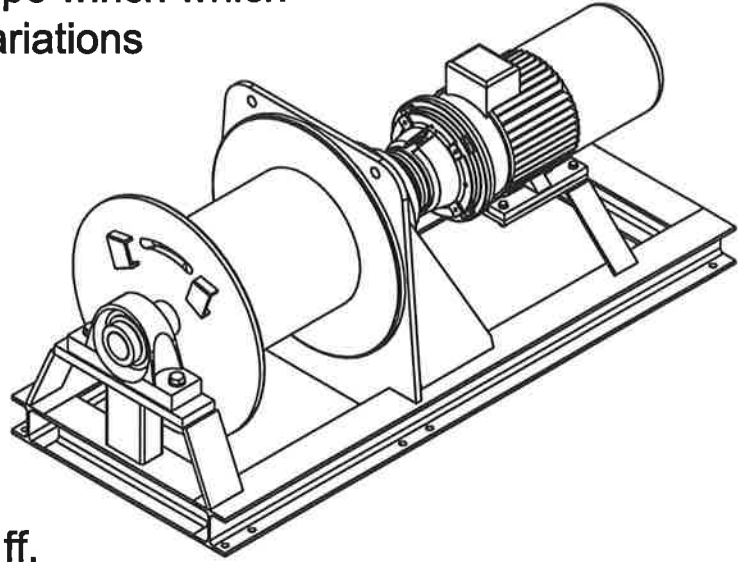


# Planetary gear winch Type SB

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## Rope winch SB

The rope winch SB is a very robust rope winch which offers the basis for large number of variations for lifting and traction of loads. The rope winch SB is cost-favorable compared to MC-3.. because it is larger, and the planetary gear is outside the drum. The winch SB is used where overall length and weight play no role, or the drum length deviates considerably from the standard length. Please find the available accessories on page 14 ff.



Winch type	Rope strength	Rope strength	Proposed rope diameter	Speed	Speed	Drum capacity	Drum capacity	Motor rating	Weight
	first layer	fifth layer		first layer	fifth layer				
	KG.	KG.	MM.	M/MIN.	M/MIN.	M.	M.	kW	KG.
SB 300 E	1200	860	10	7	9	32	190	1,5	245
SB 301 E	2100	1400	12	7	10	27	167	3	260
SB 303 E	2500	1700	15	8	12	27	167	4	340
SB 305 E	4000	2850	16	8	11	31	186	5,5	400
SB 306 E	5500	3970	18	12	17	32	194	11	620
SB 307 E	7000	4950	22	12	17	31	184	15	790
SB 309 E	9000	6300	26	14	19	29	176	22	1065
SB 310 E	13000	8950	28	9	13	28	171	22	1360
SB 311 E	16000	10660	34	10	15	25	157	30	1575
SB 313 E	20000	13600	38	6	8	27	160	22	2220
SB 315 E	32000	21700	48	7	11	26	156	45	2450

Winch type	Rope strength	Rope strength	Proposed rope diameter	Speed	Speed	Drum capacity	Drum capacity	Motor rating	Oil pressure	Volume flow
	first layer	fifth layer		first layer	fifth layer					
	KG.	KG.	MM.	M/MIN.	M/MIN.	M.	M.	kW		
SB 303 H	2500	1700	15	20	29	27	167	9	130	50
SB 305 H	4000	2850	16	26	37	31	186	19	215	55
SB 306 H	5500	3970	18	27	37	32	194	27	215	80
SB 307 H	7000	4950	22	30	42	29	184	39	185	130
SB 309 H	9500	6630	26	26	37	29	176	45	225	125
SB 310 H	13000	8950	28	12	18	28	171	30	200	55
SB 311 H	14000	9700	32	10	15	25	157	30	210	115
SB 313 H	20000	13600	38	10	15	27	160	38	170	120
SB 315 H	32000	21700	48	8	12	26	156	50	190	160

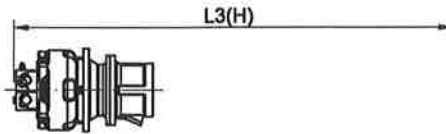


# Planetary gear winch Type SB

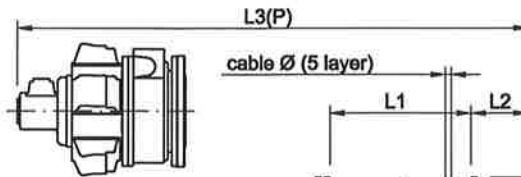
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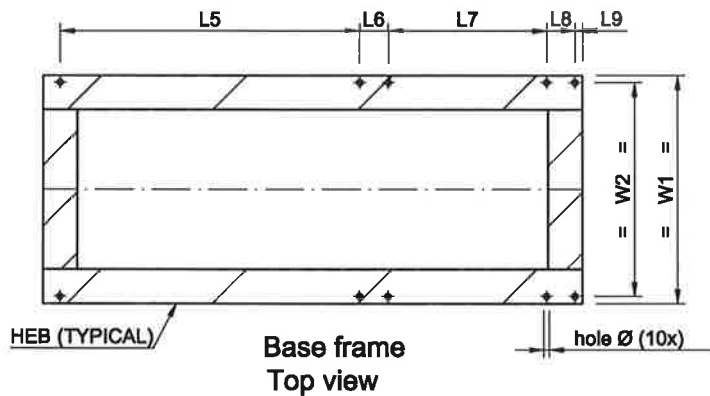
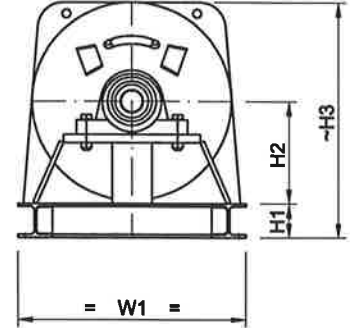
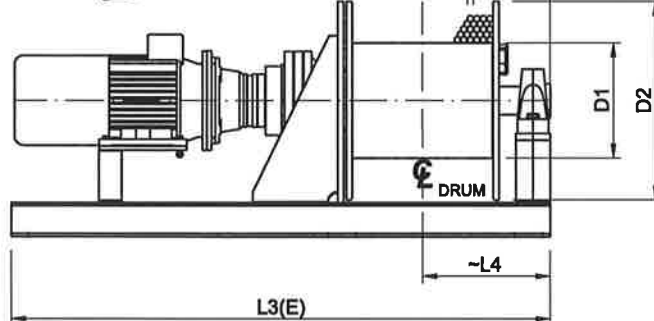
Hydraulic motor



Air motor



Electric motor



The L3 measurement depends on the motor

TYPE	D1	D2	L1	L2	L3(E)	L3(H)	L3(P)	L4	L5	L6	L7	L8	L9	H1	H2	H3	W1	W2	HEB	HOLE Ø
300	195	410	500	155	1400	-	1450	405	630	80	540	80	20	100	215	520	500	460	100	14
301	195	410	500	155	1500	-	-	405	730	80	540	80	20	100	215	520	500	460	100	14
303	244	500	500	155	1500	1300	1600	405	720	80	550	80	20	100	260	610	600	560	100	14
305	298	500	500	155	1600	1300	1600	405	820	80	550	80	20	100	260	610	600	560	100	14
306	355	600	500	165	1900	1500	1800	415	1110	80	560	80	20	100	310	710	700	660	100	17
307	406	700	500	200	1900	1550	1900	450	1055	100	560	100	25	120	360	830	800	750	120	19
309	455	750	500	215	1950	1550	1950	465	1070	110	560	110	30	140	385	900	900	840	140	22
310	470	850	500	259	2000	1600	-	509	1050	120	590	120	40	160	435	1020	1000	940	160	26
311	508	950	500	259	2050	1650	1950	509	1100	120	590	120	40	160	495	1130	1100	1040	160	26
313	610	1100	500	260	2100	1800	2150	510	1140	120	590	120	40	180	570	1300	1300	1230	180	32
315	660	1200	500	299	2500	2100	-	549	1490	140	590	140	40	200	620	1420	1500	1420	200	36



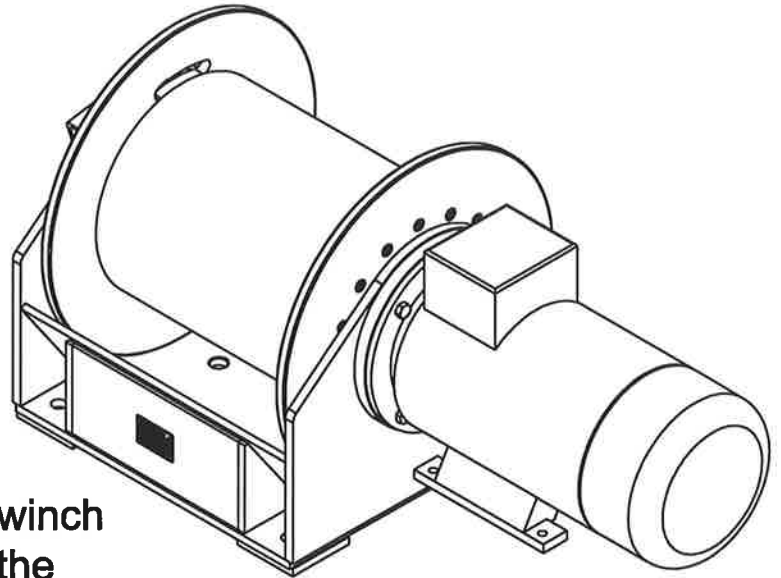
# Compact winch

## Type MC 3 ..

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### Rope winch MC303 to 313

The compact winch series MC303 to MC313 has been popular as lifting and traction winch for many years. As the planetary gear is inside the drum this is a very compact version. Also, the gear is protected inside the drum. The winch can be equipped with electromotor, hydraulic motor or air motor, whichever you prefer. Moreover, the winch is very variable in rope speed due to the planetary gear. Please find the available accessories on page 14 ff.



Winch type	Rope strenght	Rope strength	Proposed rope diameter	Speed	Speed	Drum capacity first layer	Drum capacity fift layer	Motor rating 400V	Weight
	first layer	fifth layer		first layer	fifth layer				
	KG.	KG.	MM.	M/MIN.	M/MIN.	M.	M.	kW	KG.
MC 303 E	2000	1560	12	11	14	40	227	4	325
MC 305 E	4000	2900	16	9	12	29	173	5,5	400
MC 306 E	5500	3970	18	12	17	30	179	11	560
MC 307 E	7000	4960	22	12	17	30	184	15	710
MC 309 E	9000	6425	24	13	19	35	211	22	850
MC 311 E	14000	9700	30	13	19	45	276	30	1100
MC 313 E	20000	14000	34	8	12	46	214	30	1500

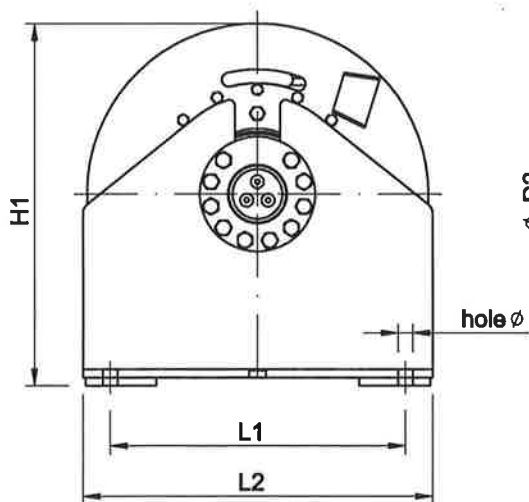
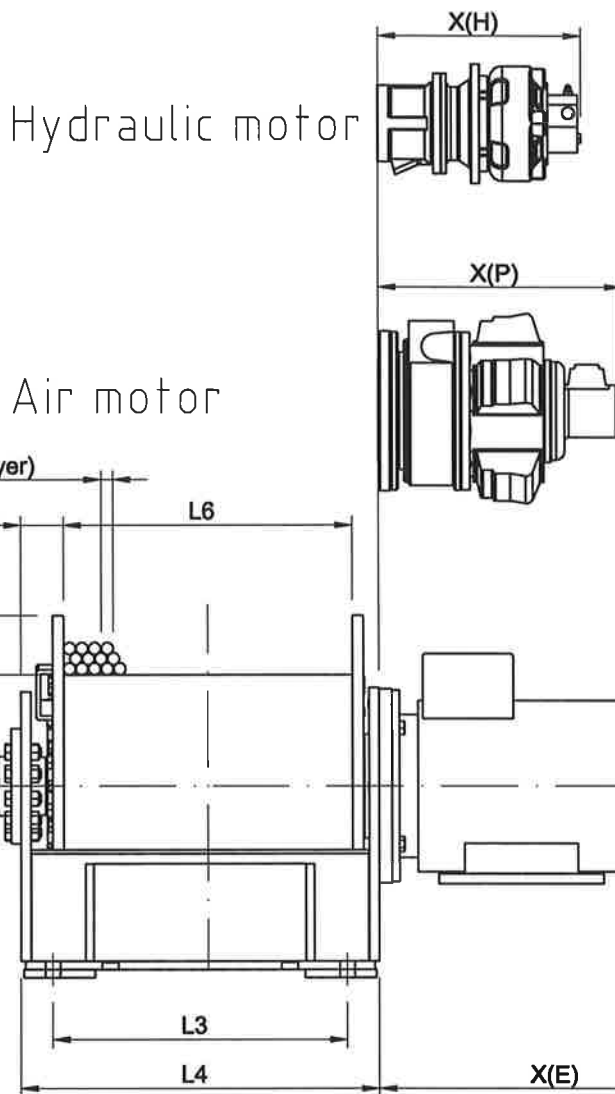
Winch type	Rope strenght	Rope strength	Proposed rope diameter	Speed	Speed	Drum capacity first layer	Drum capacity fifth layer	Oil pressure	Volume flow
	first layer	fifth layer		first layer	fifth layer				
	KG.	KG.	MM.	M/MIN.	M/MIN.	M.	M.	BAR	L/MIN.
MC 303 H	2000	1560	12	15	19	40	227	85	45
MC 305 H	4000	2900	16	9	12	29	173	130	38
MC 306 H	5500	3970	18	12	17	30	179	170	50
MC 307 H	7000	4960	22	12	17	30	184	155	80
MC 309 H	9000	6425	24	13	19	35	211	225	70
MC 311 H	14000	9700	30	13	19	45	276	210	115
MC 313 H	20000	14000	34	8	12	46	214	190	115



# Compact winch Type MC 3 . .

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The measurement X depends on the motor.

TYPE	D1	D2	L1	L2	L3	L4	L5	L6	H1	HOLEØ
MC 303	326	480	440	500	440	546	58	450	510	20
MC 305	326	480	440	500	440	546	58	450	510	20
MC 306	355	540	490	560	505	615	74	500	575	22
MC 307	405	625	560	640	520	656	78	530	660	25
MC 309	457	700	640	720	585	721	80	590	738	27
MC 311	508	800	720	820	825	985	100	830	840	33
MC 313	610	950	878	980	880	1055	110	890	995	34



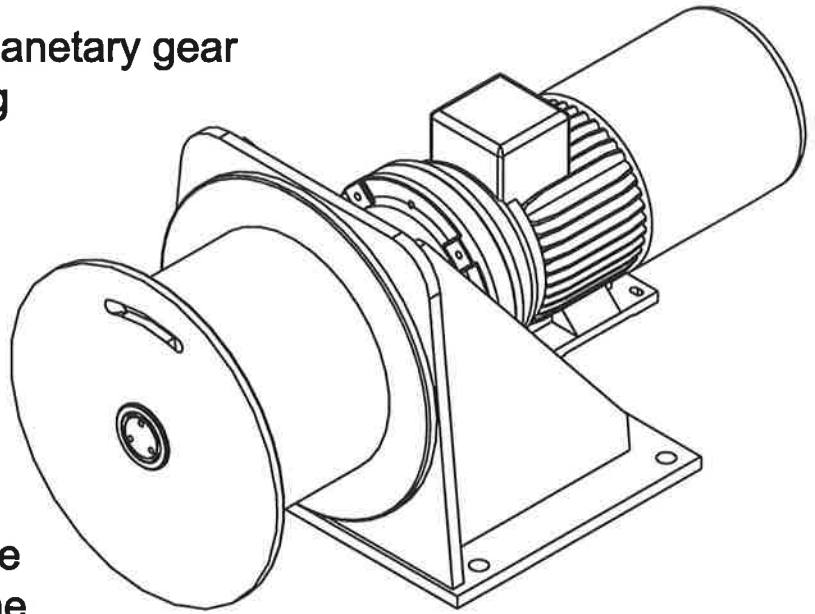
# Planetary gear winch Type FD

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## Rope winch FD

The FD winch is equipped with a planetary gear and a drum without a thrust bearing (flying drum). It is used where only a short rope length is required. Thus a short drum is sufficient, and no thrust bearing is required. The drum diameter is 22 times as large as the rope diameter, this is why this winch can be classified as 3M train of gears. Also, due to this large drum diameter the working life of the rope. Please find the available accessories on page 14 ff.



Winch type	Rope strength first layer KG.	Rope strength KG. / IN LAYER	Proposed rope diameter MM.	Speed first layer M/MIN.	Speed top layer M/MIN.	Drum capacity first layer M.	Drum capacity M./ IN LAYER	Motor rating kW	Weight KG.
FD 300 E	950	800/4	8	15	18	17	70/4	2,2	120
FD 301 E	1850	1500/4	11	15	19	12	53/4	4	140
FD 303 E	2300	2000/3	12	12	14	14	43/3	4	200
FD 305 E	3350	2800/3	14	14	17	13	42/3	7,5	240
FD 306 E	4100	3500/3	16	11	13	18	59/3	7,5	370
FD 307 E	5250	4500/3	18	15	18	19	60/3	11	590

Winch type	Rope strength first layer KG.	Rope strength KG. / IN LAYER	Proposed rope diameter MM.	Speed first layer M/MIN.	Speed top layer M/MIN.	Drum capacity first layer M.	Drum capacity M./ IN LAYER	Oil pressure BAR	Volume flow L/MIN.
FD 300 H	950	800/4	8	20	24	17	70/4	130	65
FD 301 H	1850	1500/4	11	15	19	12	53/4	120	70
FD 303 H	2300	2000/3	12	12	14	14	43/3	135	52
FD 305 H	3350	2800/3	14	14	17	13	42/3	140	50
FD 306 H	4100	3500/3	16	11	13	18	59/3	130	70
FD 307 H	5250	4500/3	18	15	18	19	60/3	140	70

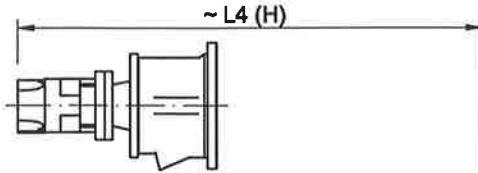


# Planetary gear winch Type FD

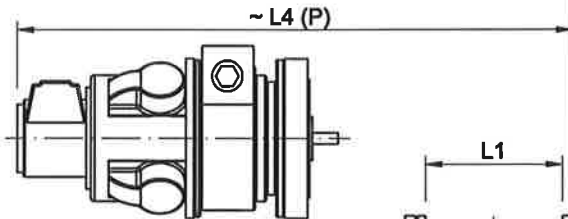
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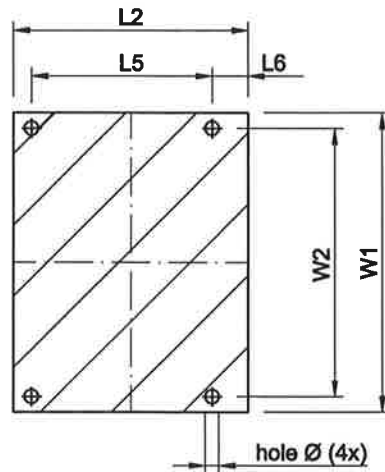
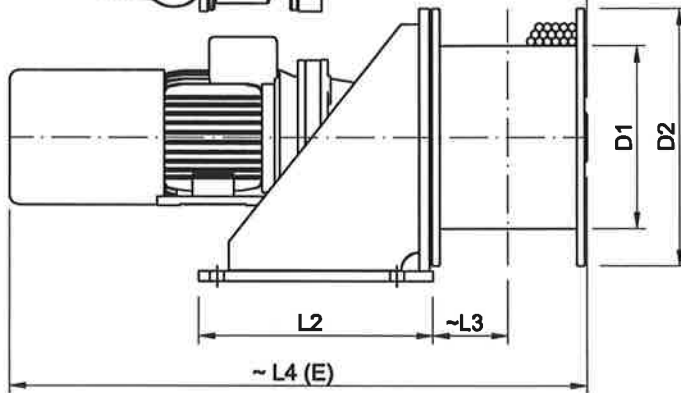
Hydraulic motor



Air motor



Electric motor



Base plate  
Top view

TYPE	D1	D2	L1	L2	L3	L4(E)	L4(H)	L4(P)	L5	L6	H1	H2	W1	W2	HOLEØ
300	244	380	176	310	93	774	548.5	742	240	44	215	405	440	400	18
301	244	380	176	310	93	832	557.5	765	240	44	215	405	440	400	18
303	272	410	191	350	107.5	894	623	928	275	50	235	440	500	450	22
305	272	410	210	350	116	1064	669	1054	275	50	235	440	500	450	22
306	355	500	266	455	146	1120	831	1110	350	70	280	530	580	520	27
307	406	625	270	510	150	1332	922	1258	400	75	355	668	750	680	27





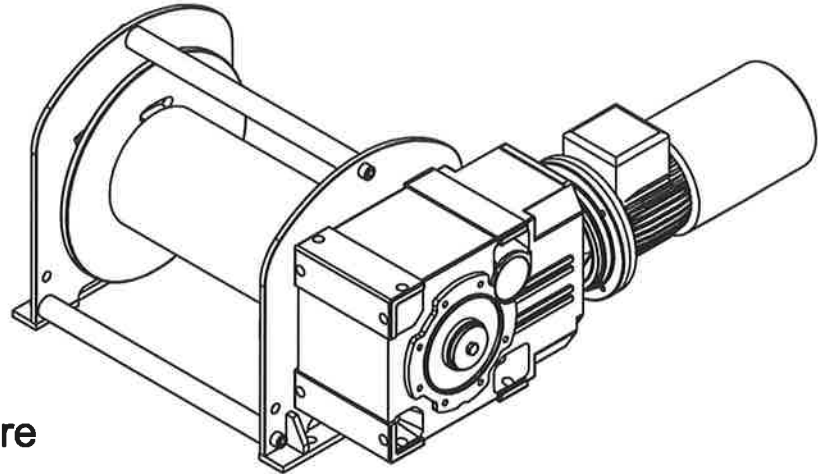
# Electric winch Type AM

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## Rope winch AM

The AM rope winch is a completely new construction. Thanks to its structure this winch is able to meet any customer requirement. The gears are highly efficient. The drum and the gear are borne on 2 large cheeks and the same time fastened to your construction. The winch can be used for all lifting and traction operations. We configure the winch according to your use. They are available with 3 different speeds. Please find the available accessories on page 14 ff.



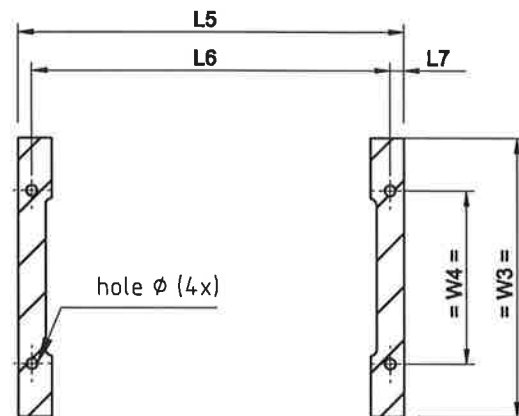
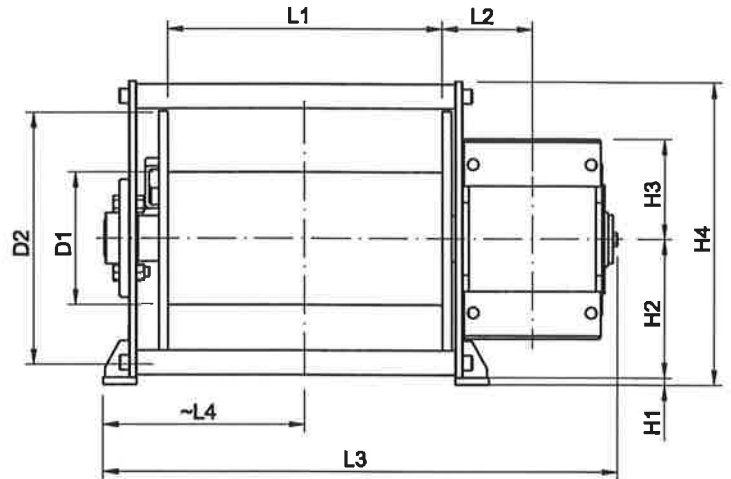
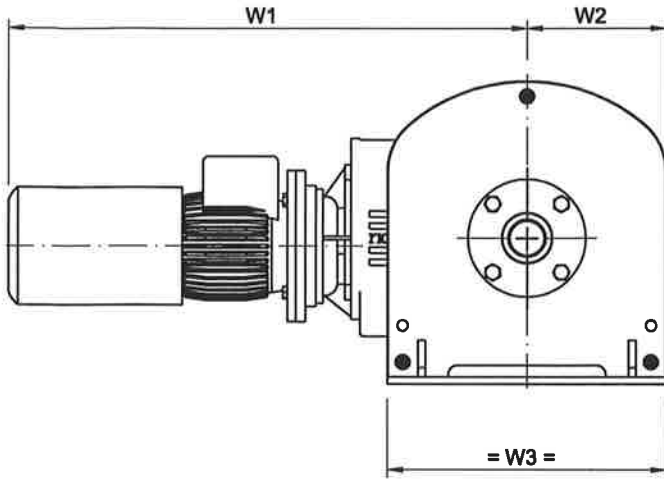
Winch type	Rope traction		Rope lifting power		Proposed rope diameter MM.	Speed M/MIN.	Drum capacity		Motor rating 400 V kW
	first layer KG.	third layer KG.	first layer KG.	third layer KG.			first layer M.	fifth layer M.	
AL 300	300	245	250	200	6	6	3	20	0,26
AH 300	300	245	250	200	6	13	3	20	0,55
AL 500	500	450	450	370	6	3	3	20	0,24
AM 500	500	450	470	370	6	6	3	20	0,50
AH 500	500	450	480	370	6	13	3	20	1,10
AL 750	750	600	700	570	8	3	8	48	0,37
AM 750	750	600	700	570	8	6	8	48	0,75
AH 750	750	600	700	570	8	12	8	48	1,50
AL 1200	1200	1000	1000	825	9	4	12	70	0,75
AM 1200	1200	1000	1000	825	9	6	12	70	1,10
AH 1200	1200	1000	1000	825	9	12	12	70	2,20
AL 1800	1800	1460	1600	1300	11	5	14	83	1,50
AM 1800	1800	1460	1700	1380	11	7	14	83	2,20
AH 1800	1800	1460	1650	1340	11	14	14	83	4,00
AL 2800	2800	2500	2480	2210	14	5	24	146	2,20
AM 2800	2800	2500	2420	2160	14	8	24	146	3,00



# Electric winch Type AM

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Base plate  
Top view

TYPE	D1	D2	L1	L2	L3	L4	L5	L6	L7	H1	H2	H3	H4	W1	W2	W3	W4	HOLE $\phi$
AM 300	100	200	60	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
AM 500	100	200	60	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
AM 750	127	280	150	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
AM1200	159	320	200	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
AM 1800	178	370	250	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
AM 2800	220	420	450	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-



# Accessories

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## Grooved drum

For easy windings. Required by standards depending on use.

## Extended drum

Allows winding more rope or winding rope only in first layer.

## 2nd rope connection

With an extra rope connection you can lift or pull one equipment with two ropes at the same time to prevent tilting, for example.

For certain applications the use of two ropes- one as carrier rope, the other one as emergency rope- is mandatory. In such case each of the ropes must carry the whole weight.

## Spacer

If you wind two ropes in several layers the drum must be equipped with spacer.

## Slack rope switch

To ensure that the ropes are always under tension.

## Spindle end switch

A spindle end switch is added to switch off the rope winch at the end positions.

## Rope pressure roller

For easy windings of the rope.

Other versions upon request!

## Band break

For decelerating the rope winch.

## Motor brake

For decelerating the rope winch.

## Overriding clutch

For unwinding a rope without starting up the winch.

## Reversing switch

Mounted directly on the winch motor for switching on and off in dead man's handle version. (Only without spindle end switch)

## Remote rope handling device

Directly connected up with the winch motor. Spindle end switches can not be used.

## Switchbox 1

Supplied loose. On and Off buttons are mounted at the switchbox. The switchbox is equipped with a main switch and an emergency stop button.

## Switchbox 2

Supplied loose. On and Off buttons are mounted at a remote rope control device. The switchbox is equipped with a main switch and an emergency stop button.

## Switchbox 3

Options see switchbox 1 and 2, plus velocity.

## Electric load limiting

Switches winch off in case of overload.



# Questionnaire

**ENZFELDER** GMBH  
Power transmission- and  
lifting engineering  
Eichengasse 36  
A-2551 Enzesfeld-Lindabrunn  
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Fax: ++43 (0) 2256 81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

Name of company : .....

Attn. : .....

Telephone number : .....

Fax number : .....

Date of offer : .....

Proposed date of delivery : .....

Place of use : .....

Application : .....

Type of winch : lifting or traction .....

Rope strength FIRST LAYER : .....

TOP LAYER : .....

Speed fixed (rope wound in 1 layer) : .....m/min

Speed varying (rope in several layer) : .....m/min

Proposed rope diameter : .....

Drum design : smooth / spiral grooves / grooved acc. to DIN

Number of rope connections : .....

Spacer (2 rope connections or more) : .....

Temperature during use : ..... °C

Environmental conditions : .....

Type of drive : by hand / electric / hydraulic / pneumatic

Brake motor : yes / no

Motor standard version : 400V-50Hz-IP54 .....

Maximum dimensions of winch  
in case of cramped conditions : .....

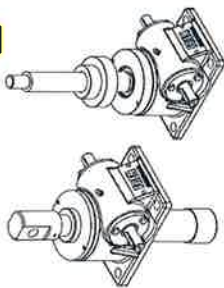
Color (standard 1 component color blue) : .....

Accessories (see page 14) : .....

# Product overview 03/2015

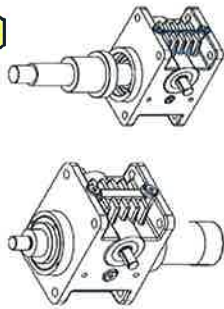
**SG**

Screw jack  
Classic



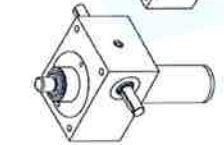
**HSG**

High performance-  
Screw jack



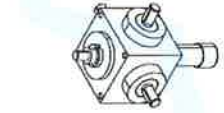
**BG**

Screw jack  
Cubic



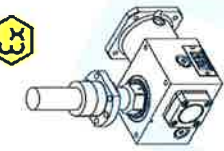
**SHG**

Quick-lifting  
screw jack



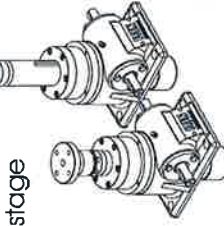
**SH**

Servo lifting  
gear



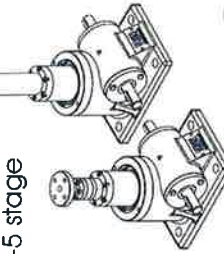
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



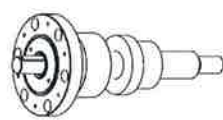
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



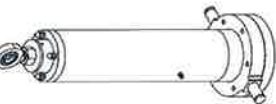
**SLA**

Spindlebearing



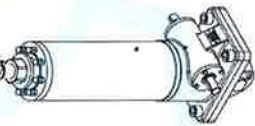
**SEZ**

Spindlebearings-  
Cylinder



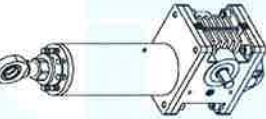
**ELZ**

Electric cylinder



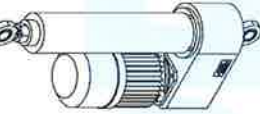
**HELZ**

High performance-  
Electric cylinder



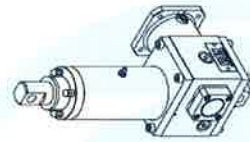
**ELZP**

Electric cylinder  
Parallel



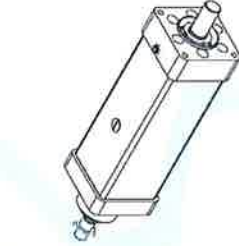
**SHELZ**

Servo electric-  
cylinder



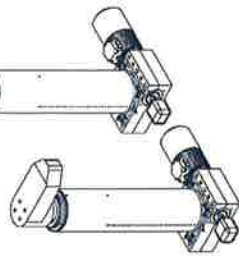
**EPNEU**

Spindle-  
Electric cylinder



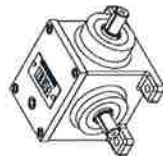
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



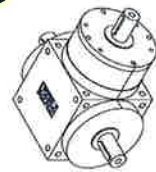
**K**

Bevel gear  
Type K



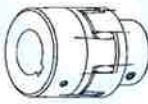
**H**

Bevel gear  
Type H



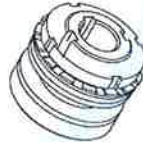
**R / GS**

Elastic / backlash-free  
Coupling



**RT**

Slip hub



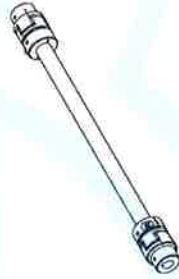
**RK**

Slip coupling



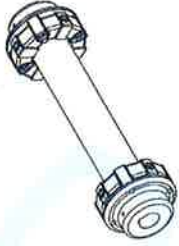
**ZR**

FREN  
Connecting shaft



**G / GX**

Elastic  
Connecting shaft

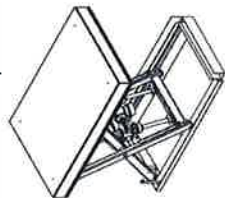


Cardan shaft



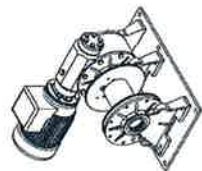
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



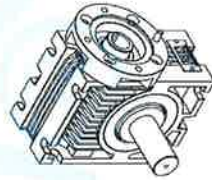
**PLG**

Planetary gear



**uniCe**

Worm gear

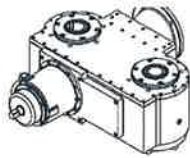
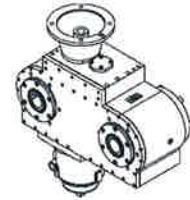


**HA**

Lifting system



**Special gear**

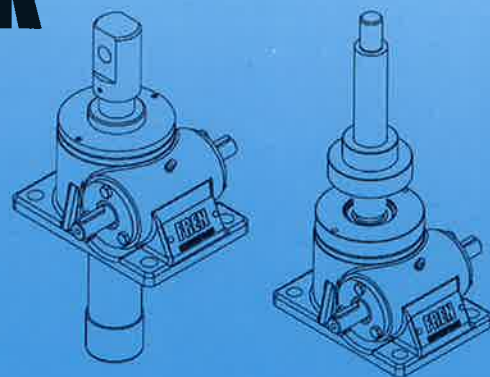




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**Screw jack  
Type SG**





# Product information

**ENZFELDER** GmbH.

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## Product information

### General:

FREN screw jacks are robust worm gear pairs driving a trapezoid thread spindle. The gearbox cases are made of ductile cast iron for high loads and meeting high safety standards. The worm is hardened and ground and running on tapered roller bearings. The worm wheel is made of high-strength material which is particularly resistant to abrasion; it is mounted between deep groove ball thrust bearings.

The SG0005 to SG0500 line is filled with grease on delivery and fit for operating temperatures ranging between  $-30^{\circ}\text{C}$  and  $+80^{\circ}\text{C}$ . The operating factor at maximum load is 20% per hour or 30% per 10 minutes. The trapezoid thread spindles are standard single-threads and double-threads execution. For higher demands with regard to lifting speed and operating factor we use ball screw spindles. FREN spindle gears are fitted with a water-soluble blue prime coat (RAL 5012). The spindle is non-lubricated on delivery: it is not to be lubricated before mounting.

### Types/Sizes:

In basically two types are to be differentiated: the basic type and the traveling nut type. The basic type is equipped with a non-rotating spindle which moves up and down. The traveling nut type is equipped with a rotating spindle on which a traveling nut moves up and down. Both types can be mounted to exit the gear either upwardly or downwardly (see page 6). FREN screw jacks are manufactured in 15 standard sizes ranging from 5kN to 3000kN and equipped with single- or double- trapezoid thread spindles or ball screw spindles.

Lifting spindles in the basic type must be secured against torsion. If this is not possible on the part of the constructor we deliver a mounted securing device.

### Applications:

Screw jacks are prefabricated parts used in engine construction and plant engineering and are widely in use there. Expediently designed, precisely manufactured according to the latest standards. Highly efficient and long-lasting, screw jacks are holding an irreplaceable position in the market and have become a fundamentally building block for the constructing engineer of today.

**Plant Engineering:** aluminium electric analysis, agitator, gate valve operating mechanism.

**Production:** machine tools, presses, lifting tables, take-up devices, tilting devices, material loadings, inlay presses, waste presses, filter screen, adjustment of the press table.

**Installation and repair:** lifting systems for rail vehicles, climbing scaffolds, working platform, mounting table, lifting ramp, loading platform, mounting table for chassis.

**Structural engineering:** concrete formwork, casting mold for a precast concrete part, adjustable mold, linear actuators for theater, impulse for window- and roof constructions, adjustment drive for tunnel formwork.

**Hydraulic engineering and shipbuilding:** impulse for sluice and slide, height adjustment of bridges, adjustment device in dockyards, adjustment for deck of ships.

**Environment engineering:** filter plant, level control system, control of flood-gates.

**Aerotechnics:** adjustment unit for Airbus.

**Machine tools:** sheet metal profiling machine, lining machine, bending machine, adjustments for compactor, gluing machine, bath for impregnation.

**Rolling mill and Foundry technology:** roller- and calender adjustment, stacking table for steel plates, height adjustment for pouring cars.

**Research and new Technologies:** closing safety device and portable hoisting platforms in nuclear power plants, laboratory and research institution, lifting gears for solar plants, wind power station.

### Advantages:

Exact synchronism of several lifting spindles also in case of eccentric stress.

Automatic lock at standstill, consequently 100% prevention of sinking.

Synchronous actuation by motors or crank handle possible.

Precise adjustment and measuring possible.

Operable in any position.

Indifference to temperature over long periods.

Many combinations possible because of the standard parts.

High thrusts (up to 3000kN) and long spindles (up to 10 000mm) feasible.



# Attachments, Example for application

**ENZFELDER** GmbH.

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Fax.: ++43(0)2256/81287-95  
E - Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Examples for attachments



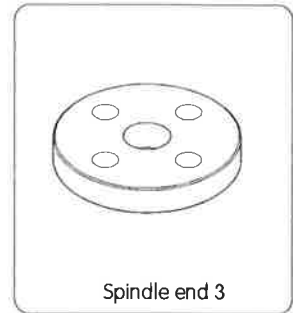
Traveling nut



traveling nut - flattened



swivelling console



Spindle end 3



Spindle end 4



Spindle end 5

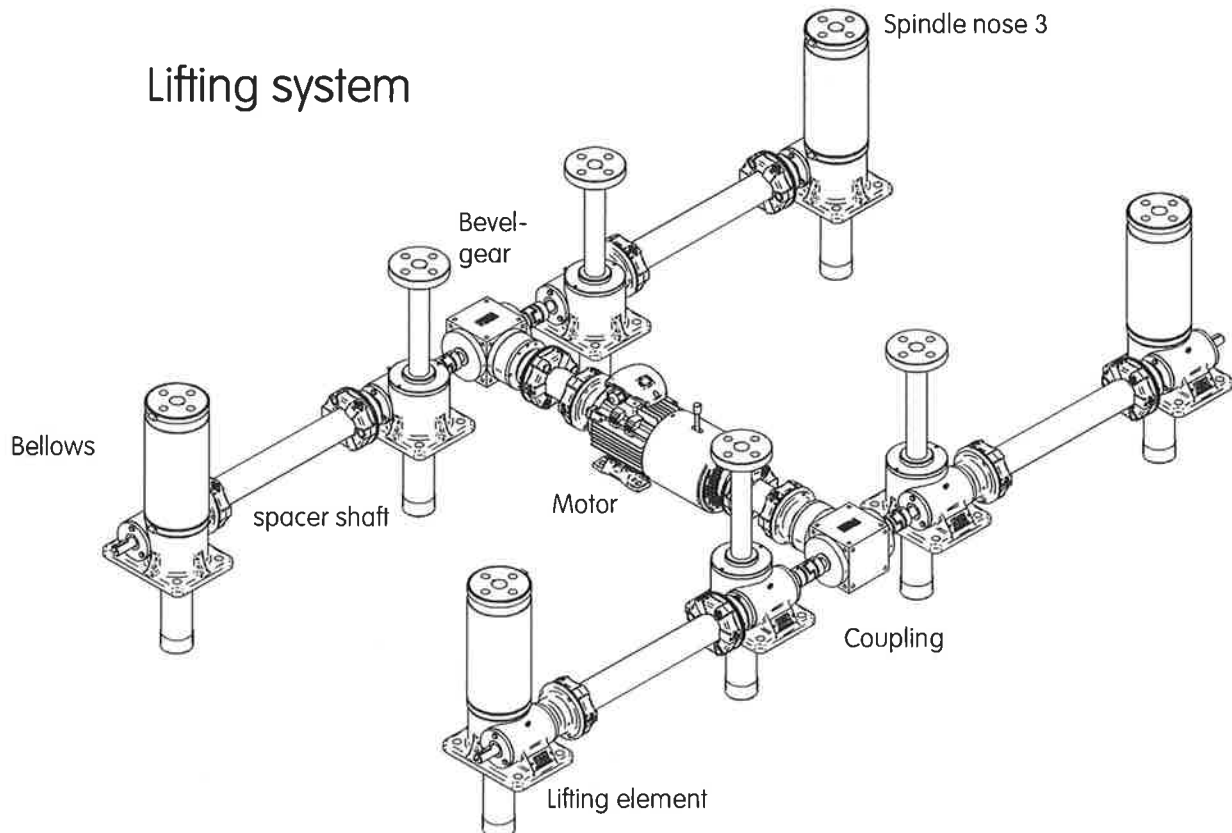


pedestal bearing



flange bearing

## Lifting system







# Selection of spindle gears

**ENZFELDER GmbH.**

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Fax.: ++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

For the correct selection of spindle gears the following data are of decisive importance:

- |  |                      |
|--|----------------------|
| 1.) load   | [kN]                 |
| 2.) lifting speed                                  | [m/min]              |
| 3.) operating cycle                                | [%/10min] [%/hour]   |
| 4.) spindle length (buckling)                      | [mm]                 |
| 5.) tensile- or pressure load                      | [kN]                 |
| 6.) ambient temperature                            | [°C]                 |
| 7.) fitting length (please indicate when ordering) | [mm]                 |
| 8.) critical speed of the spindle                  | [min <sup>-1</sup> ] |

If you use the questionnaire on page 33 please provide the data available.

How to proceed in the selection: on the base of the desired load data (in kN) a suitable type of gear is selected from the preselection table below.

## Preselection Table

Single-thread- spindle actuated gears

Type	SG 0005		SG 0010		SG 0015		SG 0020		SG 0030		SG * 0050		SG 0100		SG 0150		SG 0200		SG 0240		SG 0300		SG 0350		SG 0500			
rated power kN	5		10		15		20		30		50		100		150		200		240		300		350		500			
size of spindle	Tr 20x6		Tr 22x5		Tr 24x6		Tr 26x6		Tr 30x6		Tr 40x9 (Tr 40x7)		Tr 55x12		Tr 60x12		Tr 65x12		Tr 75x14		Tr 90x16		Tr 100x16		Tr 120x16			
gear reduction	10:1	20:1	5:1	20:1	6:1	25:1	6:1	24:1	6:1	24:1	6:1	24:1	8:1	24:1	8:1	24:1	8:1	24:1	9½:1	28:1	10½:1	32:1	10½:1	32:1	10½:1	32:1	10½:1	32:1
length of stroke per rotation in mm	0,6	0,3	1	0,25	1	0,24	1	0,25	1	0,25	1,5 (1,17)	0,375 (0,29)	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5	1,5	0,5
torque at rated power Nm	1,54	1,04	4,97	1,8	7,23	2,86	9,8	4,1	16,5	7	37,3 (35,2)	15,3 (14,2)	81	39	133	68,2	184	93,6	221	112	286	149	363	186	586	300		
efficiency in %	31	23	32	44,5	33	20	32	19	29	17	32 (26)	19,5 (16)	29	20	27	17,5	26	17	25	17	25	16	23	15	20	13		
max. RPM	2800		2800		2800		2800		2800		1800		1800		1500		1500		1500		1000		1000		1000			
max. lifting speed m/min	1,68	0,84	2,8	0,7	2,8	0,67	2,8	0,7	2,8	0,7	2,7	0,67	2,25	0,75	2,25	0,75	2,25	0,75	2,25	0,75	2,25	0,75	1,5	0,5	1,5	0,5	1,5	0,5
max. driving power in kW at 20% duty cycle	0,18		0,4		0,35		0,5		0,6		1,2		2,1		2,8		3,9		4,5		5,2		6,2		7,8			
max. driving power in kW at 10% duty cycle	0,23		0,6		0,46		0,7		0,8		1,6		2,8		3,8		5,1		5,9		6,9		8,3		10,8			
weight, basic type excl. lifting element in kg	1,5		3,2		3,2		7,8		8,2		18		23		28		40		58		75		90		180			
100mm spindle in kg	0,2		0,23		0,3		0,34		0,43		0,8		1,5		1,8		2,15		2,8		4,2		5,2		7,7			
g of grease contained in spindle gear	4,0		4,0		5,5		11,5		11,5		22,5		32,0		40,0		50,0		65,0		80,0		120,0		250,0			
catalog page	9		10		11		12		13		14		15		16		17		18		19		20		21			

## Double-thread spindle actuated gears

(no longer self-locking - braking motor must be used!)

rated power kN	4		8		12		16		24		40		80		120		150		180		220		280		400	
size of spindle	Tr20x12P6		Tr22x10P5		Tr24x12P6		Tr26x12P6		Tr30x12P6		Tr40x18P9		Tr55x24P12		Tr60x24P12		Tr65x24P12		Tr75x28P14		Tr90x32P16		Tr100x32P16		Tr120x32P16	
length of stroke per rotation in mm	1,2	0,6	2	0,5	2	0,48	2	0,5	2	0,5	3	0,75	3	1	3	1	3	1	3	1	3	1	1	3	3	1
max. lifting speed m/min	3,36	1,68	5,6	1,4	5,6	1,34	5,6	1,4	5,6	1,4	5,4	1,35	4,5	1,5	4,5	1,5	4,5	1,5	4,5	1,5	3	1	1	3	3	1
torque at rated power Nm	1,86	1,23	5,72	2,08	8,48	3,27	12,1	4,89	18,2	7,64	43,4	17,7	91,2	47,2	151	77	194	100	232	120	284	146	393	203	637	318
efficiency in %	41	31	44,5	30,5	45	28	42	26	41	25	44	27	42	27	38	25	37	24	37	24	37	24	34	22	30	20

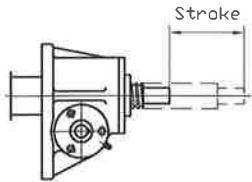
\*SG0050 is also available actuated by a lead screw Tr 40x7. Corresponding data in ( ).  
For the standard gears SG0750 and SG1000 please request the standard sheet!

Read of the dimensioned sketch and the performance table on the corresponding page of the catalog:

- whether the dimensions of gear and spindle fit into your system.
- which gear reduction must be selected for the desired lifting speed (for higher lifting speeds the use of a double-thread spindle may be necessary).
- whether the power required for the desired lifting speed is admissible.
- whether under pressure load the critical buckling force is not exceeded (see diagram on page 29).
- whether the critical revolutions/min of the spindle are not exceeded (see diagram on page 28).
- if one of these requirements cannot be met the type next in size must be chosen.
- if point 6 is not sufficient, choose one of the types next in size or ask for special types (questionnaire see pages 33-34)!



# Survey of construction modes with



Stroke:  
0-10000 mm

Reduction i  
see chart page 4

- SG \_\_ screw jack
- KSG \_\_ screw jack with ball screw drive
- PSG \_\_ screw jack with planetary roller drive
- SE \_\_ swiveling element
- KSE \_\_ swiveling element with ball screw drive
- PSE \_\_ swiveling element with planetary roller drive
- SK \_\_ design with swivel housing
- SSG \_\_ special screw jack

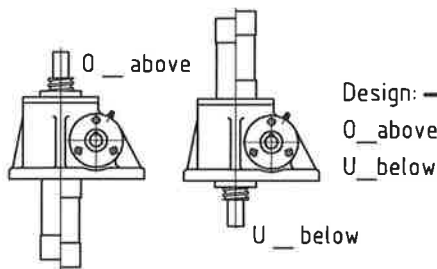
- Attachment-Driving shaft:
- 00 \_\_ without attachments
  - (M)R \_\_ motor flange right
  - (M)L \_\_ motor flange left
  - (M)R/L \_\_ motor flange right and left
  - MR \_\_ motor right
  - ML \_\_ motor left
  - MRL \_\_ motor right and left
  - GMR \_\_ gearmotor right
  - GML \_\_ gearmotor left
  - GMRL \_\_ gearmotor right and left
- HK \_\_ hand crank
  - HR \_\_ hand wheel
  - KR \_\_ coupling right
  - KL \_\_ coupling left
  - FR \_\_ flange right
  - FL \_\_ flange left
  - GER \_\_ gear limit switch at the right
  - GEL \_\_ gear limit switch at the left
  - IGR \_\_ incremental encoder at the right
  - IGL \_\_ incremental encoder at the left
  - AGR \_\_ absolute encoder at the right
  - AGL \_\_ absolute encoder at the left

SG 0000 - 0 - G - 0 - 1 - Stroke - M10 - 00 -

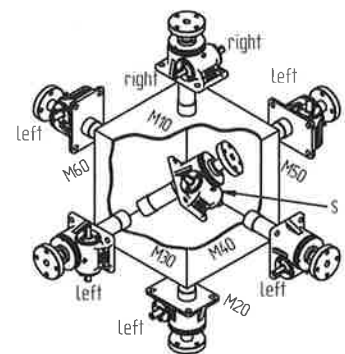
Type:  
0005 / 0015 / 0020 / 0030 / 0050 /  
0100 / 0150 / 0200 / 0240 / 0300 /  
0350 / 0500 / 0750 / 1000 / 1500 /  
2000 / 2500 / 3000

Mounting position:  
M10 / M1U / M20 / M2U / M30 /  
M3U / M40 / M4U / M50 / M5U /  
M60 / M6U / S (=obliquely)

G \_\_ Standard type

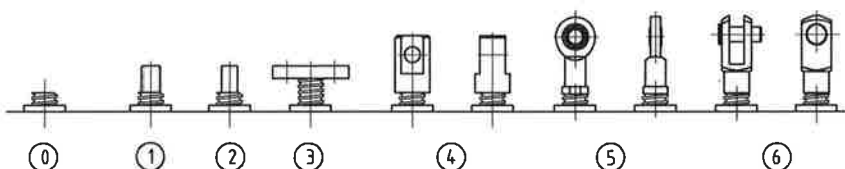
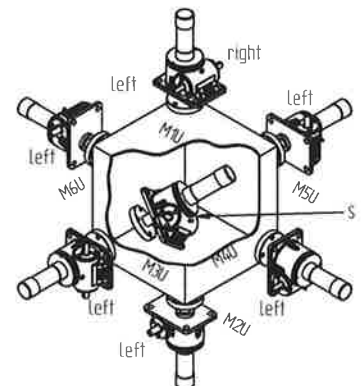


Design:  
O \_\_ above  
U \_\_ below



Spindle end SG:  
0, 1, 2, 3, 4, 5, 6, So  
Spindle end SE:  
1/4, 4/4, 5/5

standard spindle ends



## example for ordering - Basic Type

WERK ENZESFELD:  
A-2551 ENZESFELD, EICHENGASSE 36  
Tel.: ++43(0)2256/81287  
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Internet: www.enzfelder.at

### Driving shaft:

- B \_\_\_ both sides
- R \_\_\_ right
- L \_\_\_ left
- R/LS \_\_\_ standard on right / special on left
- L/RS \_\_\_ standard on left / special on right
- R/LoP \_\_\_ standard on right / standard on left  
without parallel key
- L/RoP \_\_\_ standard on left / standard on right  
without parallel key
- BoP \_\_\_ standard without parallel key
- BHW \_\_\_ both sides with quill shaft
- R/LHW \_\_\_ standard on right /left side with quill shaft
- L/RHW \_\_\_ standard on left /right side with quill shaft

### Attachment-Spindle side:

- 0 \_\_\_ without guiding
- F \_\_\_ guiding standard
- FFB \_\_\_ guiding for bellow
- FSA \_\_\_ guiding for lubrication
- FSE \_\_\_ guiding adjustable
- FSE/A \_\_\_ guiding adjustable with lubrication connection
- SIO \_\_\_ safety nut optical (short without guiding/travelling nut type)
- SIF \_\_\_ safety nut optical with guiding
- SIFSA \_\_\_ safety nut optical with guiding + lubrication connection
- SIE \_\_\_ safety nut electrically monitored with guiding
- SIESA \_\_\_ safety nut electrically monitored with guiding + lubrication connection
- SIM \_\_\_ safety nut electronically monitored with guiding
- VS \_\_\_ turn lock device with feather key on spindle

- B - F - Sf - Tr55x12 - - - - -

### Attachment-protection tube side:

- 0 \_\_\_ without guiding
- F \_\_\_ with guiding without protecting tube
- FFB \_\_\_ guiding with bellow
- S \_\_\_ protecting tube
- Sf \_\_\_ protecting tube with guide ring
- SfSA \_\_\_ guiding with lubrication connection
- SfSE \_\_\_ guiding adjustable
- SfSE/A \_\_\_ guiding adjustable with lubrication connection
- VV \_\_\_ square tube turn lock device
- VP \_\_\_ turn lock device by  
2x parallel key in the protection tube
- SIO \_\_\_ safety nut optical (short without guiding/travelling nut type)
- SIF \_\_\_ safety nut optical with guiding
- SIFSA \_\_\_ safety nut optical with guiding + lubrication connection
- SIE \_\_\_ safety nut electrically monitored with guiding
- SIESA \_\_\_ safety nut electrically monitored with guiding + lubrication connection
- SIM \_\_\_ safety nut electronically monitored with guiding

### Additional gear descriptive designations:

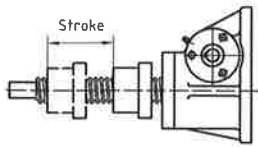
- Spindle protection:
  - FB \_\_\_ bellow
  - FS \_\_\_ flat spiral spring cover
- AS \_\_\_ turn out device
- ES \_\_\_ turn in device
- DÜ \_\_\_ drive monitoring
- GD \_\_\_ noise attenuation  
(rubber plate, distance sleeve for boring)
- Stub covering
  - SR \_\_\_ stub covering at the right  
for retrospectively building in
  - SL \_\_\_ stub covering at the left  
for retrospectively building in
- Limit stop:
  - EAS1 \_\_\_ limit switch mechanical
  - EAS2 \_\_\_ limit switch magnetical
  - EAS3 \_\_\_ limit switch inductive
  - DFE \_\_\_ compression spring turn off
- Swivelling consoles:
  - SP \_\_\_ swivelling plate
  - SP90 \_\_\_ swivelling plate 90° turned
  - SK \_\_\_ swivelling console
  - SK90 \_\_\_ swivelling console 90° turned
  - SL \_\_\_ swivelling bearing
  - SLA \_\_\_ swivel feet
  - GL \_\_\_ bearing for  
swivelling housing
- VL \_\_\_ spindle extension
- VL10 \_\_\_ spindle extension 10mm
- FI \_\_\_ filter for bellow ventilation
- SSG \_\_\_ lubricator
- SO \_\_\_ special parts

### Spindle code:

for example: Tr30x12P6  
Tr40x7 LH (left-handed)  
KGT2005



# Survey of construction modes with example



Stroke:  
0-10000 mm

Reduction i  
see chart page 4

SG \_\_ screw jack  
KSG \_\_ screw jack with ball screw drive  
SSG \_\_ special screw jack

HK \_\_ hand crank  
HR \_\_ hand wheel  
KR \_\_ coupling right  
KL \_\_ coupling left  
FR \_\_ flange right  
FL \_\_ flange left

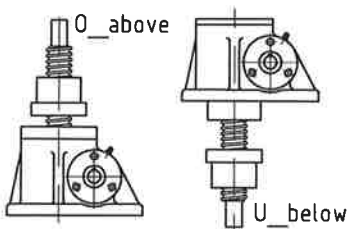
GER \_\_ gear limit switch at the right  
GEL \_\_ gear limit switch at the left  
IGR \_\_ incremental encoder at the right  
IGL \_\_ incremental encoder at the left  
AGR \_\_ absolute encoder at the right  
AGL \_\_ absolute encoder at the left

Attachment-Driving shaft:  
00 \_\_ without motor  
(M)R \_\_ motor flange right  
(M)L \_\_ motor flange left  
(M)R/L \_\_ motor flange right and left  
MR \_\_ motor right  
ML \_\_ motor left  
MRL \_\_ motor right and left  
GMR \_\_ gearmotor right  
GML \_\_ gearmotor left  
GMRL \_\_ gearmotor right and left

SG 0000 - 0 - L - 0 - 0 - Stroke - M10 - 00 -

Type:  
0005 / 0015 / 0020 / 0030 / 0050 /  
0100 / 0150 / 0200 / 0240 / 0300 /  
0350 / 0500 / 0750 / 1000 / 1500 /  
2000 / 2500 / 3000

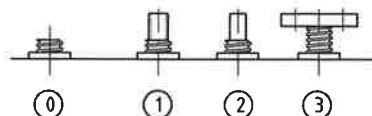
L \_\_ Travelling nut type



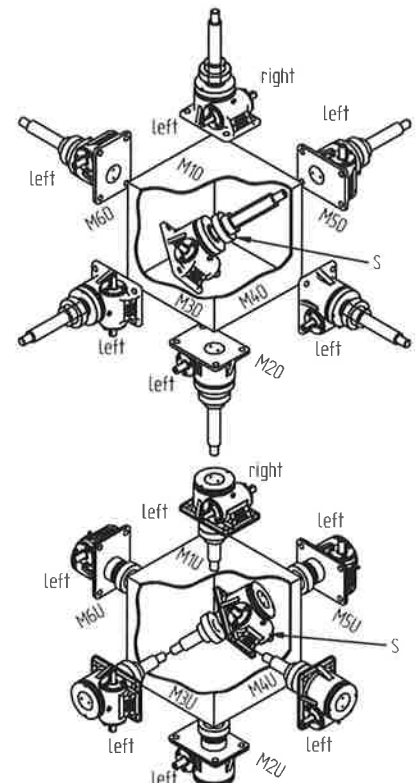
Design:  
O \_above  
U \_below

Spindle end: 0, 1, 2, 3, So  
3 \_\_ spindle end 3 with bearing  
FL \_\_ bearing of the flange UCFL  
SL \_\_ pedestal bearing UCP  
LL \_\_ floating bearing  
AS \_\_ securing against hollowing  
AH \_\_ spindle end with spacer like the ELZ

standard spindle ends



Mounting position:  
M10 / M1U / M20 / M2U / M30 /  
M3U / M40 / M4U / M50 / M5U /  
M60 / M6U / S (=obliquely)



# for ordering - Travelling nut Type

**ENZFELDER** GmbH.

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Fax:++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Driving shaft:

- B \_\_ both sides
- R \_\_ right
- L \_\_ left
- R/LS \_\_ standard on right / special on left
- L/RS \_\_ standard on left / special on right
- R/LoP \_\_ standard on right / standard on left  
\_\_ without parallel key
- L/RoP \_\_ standard on left / standard on right  
\_\_ without parallel key
- BoP \_\_ standard without parallel key
- BHW \_\_ both sides with quill shaft
- R/LHW \_\_ standard on right /left side with quill shaft
- L/RHW \_\_ standard on left /right side with quill shaft

## Travelling nut:

- LS \_\_travelling nut standard
  - LF \_\_travelling nut with guiding rings
  - LJP \_\_travelling nut with yoke plate
  - LSF \_\_travelling nut with key area
  - LSA \_\_travelling nut with lubrication connection
  - LFI \_\_travelling nut with filter for bellow ventilation
  - LSR \_\_travelling nut with protection tube
  - LSP \_\_travelling nut with spherical plate
- by ball screw:
- EFM \_\_single flange nut
  - EFDM \_\_single flange double nut
  - MFM \_\_middle flange nut

- B - LS - Tr60x12 -

## Spindle code:

for example: Tr30x12P6  
Tr40x7 LH (left-handed)  
KGT2005

## Additional gear descriptive designations:

- Spindle protection:
  - FB \_\_bellow
  - FS \_\_flat spiral spring cover
- GD \_\_noise attenuation (rubber plate, distance sleeve for boring)
- Safety nut:
  - SIO \_\_safety nut optically  
(short without guiding/travelling nut)
  - SIE \_\_safety nut electrically monitored
- Swivelling consoles:
  - SP \_\_swivelling plate
  - SP90 \_\_swivelling plate 90° turned
  - SK \_\_swivelling console
  - SK90 \_\_swivelling console 90° turned
  - SL \_\_swivelling bearing
  - SLA \_\_swivel feet
  - GL \_\_bearing for swivelling housing
- Stub covering:
  - SR \_\_stub covering at the right for retrospectively building in
  - SL \_\_stub covering at the left for retrospectively building in
- VL \_\_spindle extension  
VL10 \_\_spindle extension 10mm
- FI \_\_filter for bellow ventilation
- SSG \_\_lubricator
- AS \_\_turn out device
- SO \_\_special parts



# Screw jack SG 0005

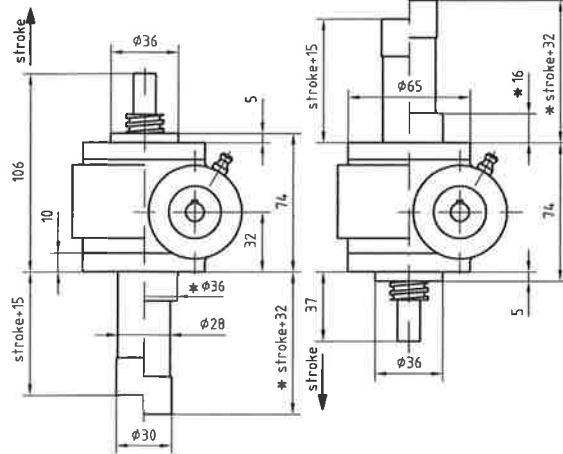
**ENZFELDER GmbH.**

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Fax.:++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Basic type (G)

above (0)

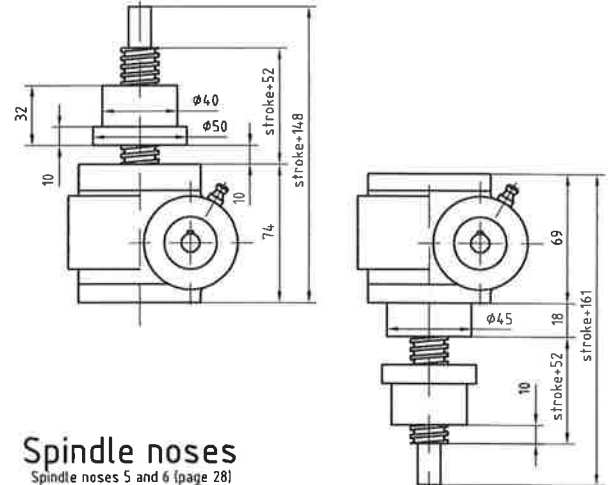
below (U)



## Traveling nut type (L)

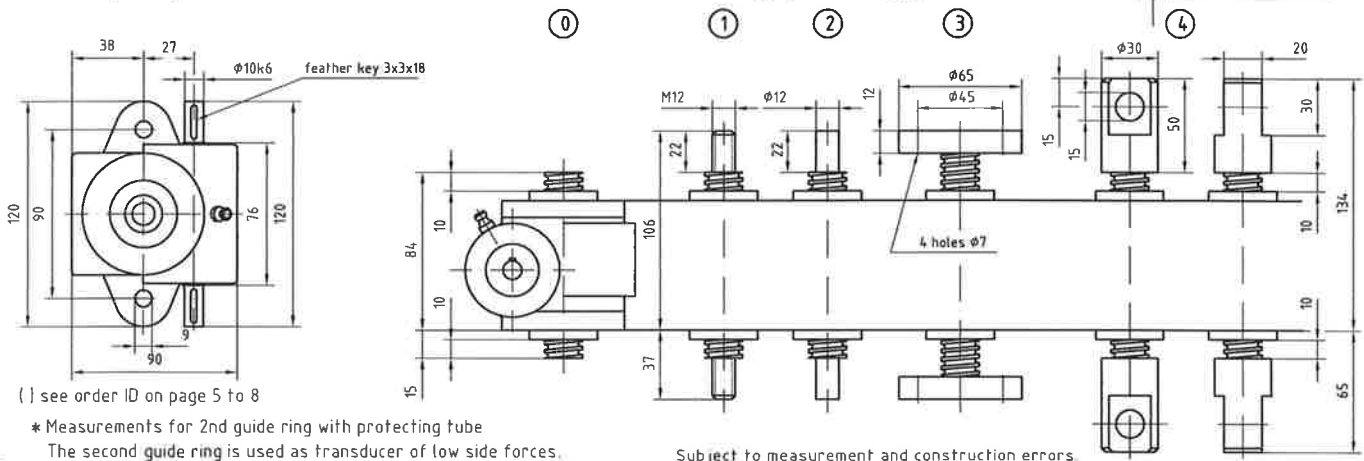
above (0)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube  
The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors

### Tr 20x6 single-thread lifting power in kN

10:1 = 0,6mm/R  
20:1 = 0,3mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		5		4		3		20:1		2		1,5		1		0,5	
	10:1	20:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	
2800	1,68	0,84	1,54   0,44	1,04   0,3	1,23   0,36	0,83   0,24	0,92   0,27	0,62   0,18	0,61   0,18	0,41   0,12	0,46   0,14	0,31   0,09	0,3	0,1	0,21   0,06			
1500	0,90	0,45	1,54   0,24	1,04   0,16	1,23   0,19	0,83   0,13	0,92   0,14	0,62   0,1	0,61   0,1	0,10   0,41	0,07   0,46	0,08   0,31	0,06	0,3	0,06   0,21	0,04		
1000	0,60	0,30	1,54   0,16	1,04   0,11	1,23   0,13	0,83   0,09	0,92   0,10	0,62   0,07	0,61   0,07	0,41   0,05	0,46   0,06	0,31   0,04	0,3	0,05	0,21   0,04			
750	0,45	0,22	1,54   0,12	1,04   0,08	1,23   0,1	0,83   0,07	0,92   0,08	0,62   0,06	0,61   0,06	0,41   0,04	0,46   0,05	0,31   0,04	0,3	0,04	0,21   0,04			
500	0,30	0,15	1,54   0,08	1,04   0,06	1,23   0,07	0,83   0,05	0,92   0,06	0,62   0,04	0,61   0,04	0,41   0,04	0,46   0,04	0,31   0,04	0,3	0,04	0,21   0,04			
200	0,12	0,06	1,54   0,04	1,04   0,05	1,23   0,04	0,83   0,04	0,92   0,04	0,62   0,04	0,61   0,04	0,41   0,04	0,46   0,04	0,31   0,04	0,3	0,04	0,21   0,04			

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 20x12P6 double-thread lifting power in kN

10:1 = 1,2mm/R  
20:1 = 0,6mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		4		3		2		1,5		1		0,5		
	10:1	20:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW		
2800	3,36	1,68	1,86   0,54	1,23   0,36	1,39   0,4	0,92   0,27	0,93   0,27	0,62   0,18	0,7	0,2	0,46   0,14	0,47   0,14	0,31   0,09	0,23   0,08	0,16   0,05
1500	1,80	0,90	1,86   0,29	1,23   0,19	1,39   0,22	0,92   0,15	0,93   0,15	0,62   0,1	0,7	0,11	0,46   0,08	0,47   0,07	0,31   0,06	0,23   0,04	0,16   0,04
100	1,20	0,60	1,86   0,19	1,23   0,13	1,39   0,14	0,92   0,10	0,93   0,10	0,62   0,07	0,7	0,07	0,46   0,06	0,47   0,05	0,31   0,04	0,23   0,04	0,16   0,04
750	0,90	0,45	1,86   0,15	1,23   0,11	1,39   0,11	0,92   0,08	0,93   0,08	0,62   0,05	0,7	0,06	0,46   0,04	0,47   0,04	0,31   0,04	0,23   0,04	0,16   0,04
500	0,60	0,30	1,86   0,1	1,23   0,07	1,39   0,08	0,92   0,05	0,93   0,06	0,62   0,04	0,7	0,05	0,46   0,04	0,47   0,04	0,31   0,04	0,23   0,04	0,16   0,04
200	0,24	0,12	1,86   0,05	1,23   0,04	1,39   0,04	0,92   0,04	0,93   0,04	0,62   0,04	0,7	0,04	0,46   0,04	0,47   0,04	0,31   0,04	0,23   0,04	0,16   0,04

### Technical specifications

max. lifting power	5 kN
gear reduction	10:1 / 20:1
dimension of spindle	Tr20x6 / Tr20x12P6
start-up moment	table entry x 1,3
casing material	aluminium
weight without lifting (kg)	1,5
weight of spindle per 100mm lifting (kg)	0,2
lubricant	grease
quantity of lubricant (kg)	0,05
max. driving power (duty cycle 20%/h)	0,18 kW
max. driving power (duty cycle 10%/h)	0,23 kW



# Screw jack SG 0010

**ENZFELDER GmbH.**

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E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Basic type (G)

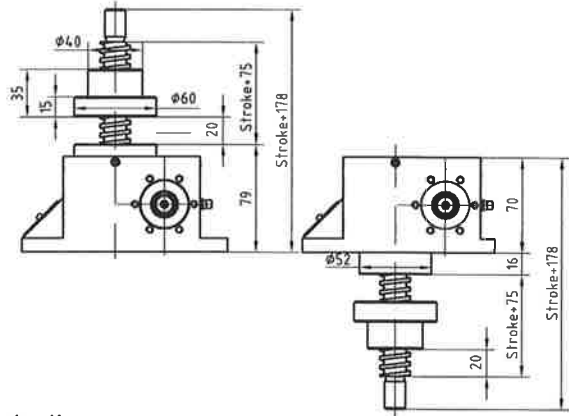
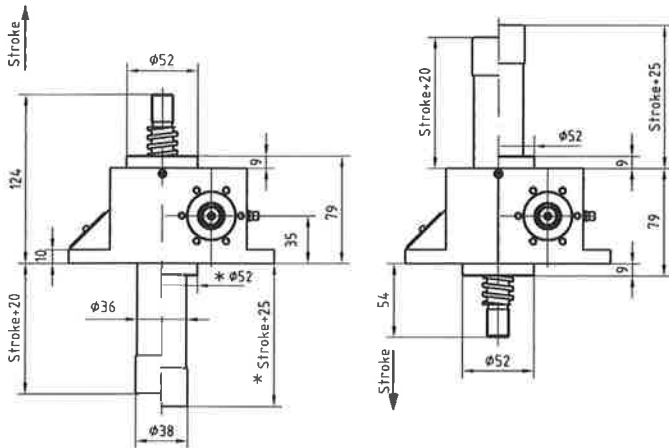
above (O)

below (U)

## Traveling nut type (L)

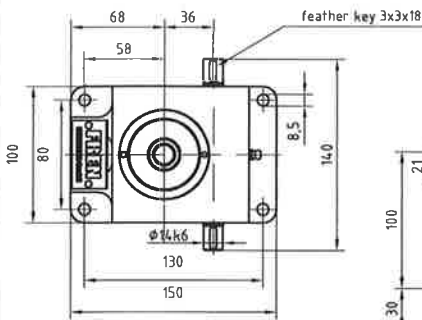
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



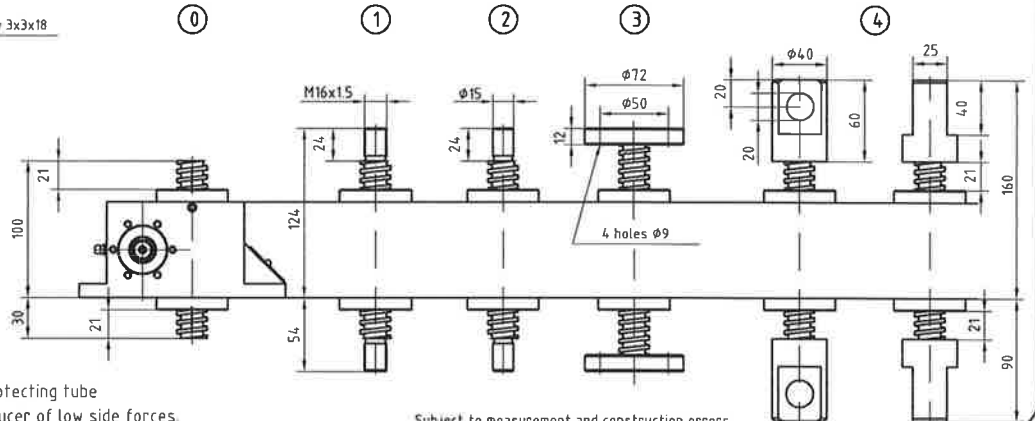
0

1

2

3

4



( ) see order ID on page 5 to 8

\*Measurements for 2nd ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

## Tr 22x5 single-thread lifting power in kN

5:1 = 1,0mm/U  
20:1 = 0,25mm/U

n <sub>1</sub> min <sup>-1</sup>	Hubgeschw m/min		5:1		20:1		5:1		20:1		5:1		20:1		5:1		20:1		5:1		20:1					
	5:1	20:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW				
2800	2,80	0,70	4,97	1,43	1,8	0,52	3,98	1,14	1,44	0,42	2,98	0,86	1,08	0,32	1,98	0,57	0,72	0,21	1,49	0,43	0,54	0,16	0,5	0,15	0,18	0,06
1500	1,50	0,375	4,97	0,77	1,8	0,28	3,98	0,61	1,44	0,15	2,98	0,46	1,08	0,17	1,98	0,31	0,72	0,12	1,49	0,23	0,54	0,09	0,5	0,08	0,18	0,03
1000	1,00	0,25	4,97	0,51	1,8	0,19	3,98	0,41	1,44	0,15	2,98	0,31	1,08	0,12	1,98	0,21	0,72	0,08	1,49	0,16	0,54	0,06	0,5	0,06	0,18	0,02
750	0,75	0,19	4,97	0,39	1,8	0,14	3,98	0,31	1,44	0,12	2,98	0,23	1,08	0,09	1,98	0,16	0,72	0,06	1,49	0,12	0,54	0,05	0,5	0,04	0,18	0,02
500	0,50	0,125	4,97	0,26	1,8	0,10	3,98	0,21	1,44	0,08	2,98	0,16	1,08	0,06	1,98	0,11	0,72	0,04	1,49	0,08	0,54	0,03	0,5	0,03	0,18	0,01
200	0,20	0,05	4,97	0,11	1,8	0,04	3,98	0,09	1,44	0,03	2,98	0,07	1,08	0,03	1,98	0,05	0,72	0,02	1,49	0,04	0,54	0,02	0,5	0,01	0,18	0,01

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

## Tr 22x10P5 double-thread lifting power in kN

5:1 = 2,0mm/U  
20:1 = 0,5mm/U

n <sub>1</sub> min <sup>-1</sup>	liff. speed m/min		5:1		20:1		5:1		20:1		5:1		20:1		5:1		20:1		5:1		20:1	
	5:1	20:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
2800	5,6	1,4	5,72	1,64	2,08	0,6	4,3	1,23	1,56	0,45	2,86	0,82	1,04	0,3	2,15	0,62	0,78	0,23	0,72	0,21	0,2	0,08
1500	3,0	0,75	5,72	0,88	2,08	0,32	4,3	0,66	1,56	0,24	2,86	0,44	1,04	0,16	2,15	0,33	0,78	0,12	0,72	0,11	0,2	0,04
1000	2,5	0,5	5,72	0,59	2,08	0,22	4,3	0,44	1,56	0,16	2,86	0,3	1,04	0,11	2,15	0,22	0,78	0,08	0,72	0,08	0,2	0,03
750	1,5	0,38	5,72	0,44	2,08	0,16	4,3	0,33	1,56	0,12	2,86	0,22	1,04	0,08	2,15	0,17	0,78	0,06	0,72	0,06	0,2	0,02
500	1,0	0,25	5,72	0,3	2,08	0,11	4,3	0,22	1,56	0,08	2,86	0,15	1,04	0,06	2,15	0,11	0,78	0,04	0,72	0,04	0,2	0,02
200	0,4	0,1	5,72	0,12	2,08	0,05	4,3	0,09	1,56	0,04	2,86	0,06	1,04	0,03	2,15	0,05	0,78	0,02	0,72	0,02	0,2	0,01

## Technical specifications

max. lifting power	10 kN
gear reduction	5:1 / 20:1
dimension of spindle	Tr22x5 / Tr22x10P5
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	3,2
weight of spindle per 100mm lifting (kg)	0,23
lubrication	grease
quantity of lubricat (kg)	0,04
max. driving power (duty cycle 20%/h)	0,4 kW
max. driving power (duty cycle 10%/h)	0,6 kW



# Screw jack SG 0015

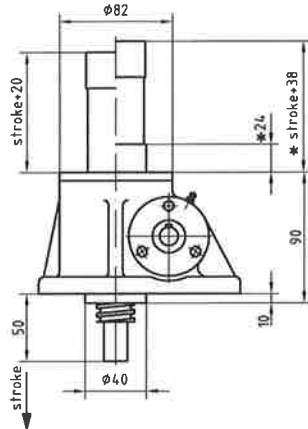
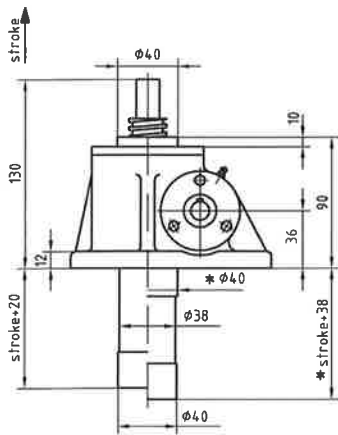
**ENZFELDER GmbH.**

WERK ENZSFELD:  
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Internet: www.enzfelder.at

## Basic type (G)

above (O)

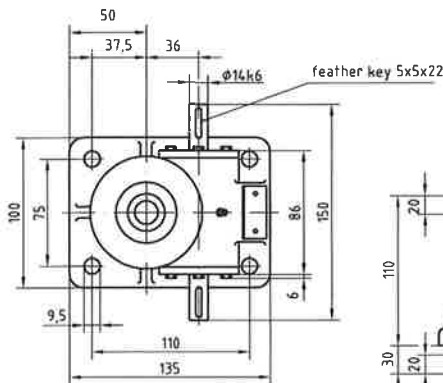
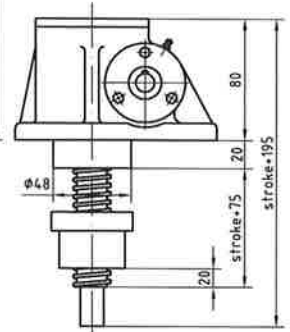
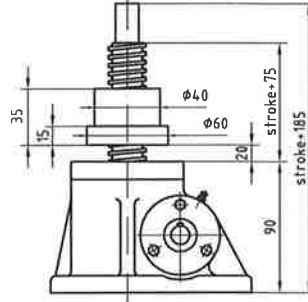
below (U)



## Traveling nut type (L)

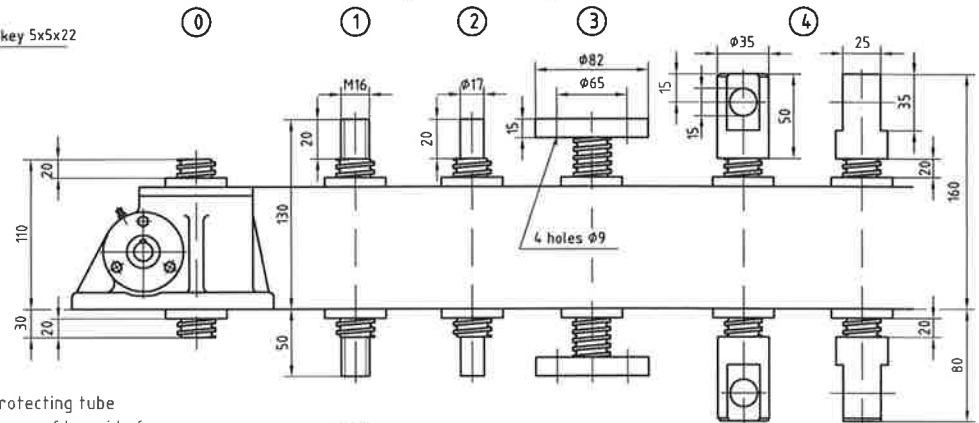
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube  
The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

### Tr 24x6 single-thread lifting power in kN

6:1 = 1,0mm/R  
25:1 = 0,24mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min	15		12		8		5		3		1														
		6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW													
2800	2,80	0,67	<i>7,23</i>	<i>2,08</i>	<i>2,86</i>	<i>0,82</i>	<i>5,78</i>	<i>1,66</i>	<i>2,29</i>	<i>0,66</i>	<i>3,86</i>	<i>1,11</i>	<i>1,52</i>	<i>0,44</i>	<i>2,41</i>	<i>0,70</i>	<i>0,95</i>	<i>0,28</i>	<i>1,45</i>	<i>0,42</i>	<i>0,57</i>	<i>0,17</i>	<i>0,48</i>	<i>0,14</i>	<i>0,19</i>	<i>0,07</i>
1500	1,50	0,36	<i>7,23</i>	<i>1,11</i>	<i>2,86</i>	<i>0,45</i>	<i>5,78</i>	<i>0,9</i>	<i>2,29</i>	<i>0,36</i>	<i>3,86</i>	<i>0,6</i>	<i>1,52</i>	<i>0,23</i>	<i>2,41</i>	<i>0,37</i>	<i>0,95</i>	<i>0,16</i>	<i>1,45</i>	<i>0,23</i>	<i>0,57</i>	<i>0,11</i>	<i>0,48</i>	<i>0,09</i>	<i>0,19</i>	<i>0,06</i>
1000	1,00	0,24	<i>7,23</i>	<i>0,74</i>	<i>2,86</i>	<i>0,3</i>	<i>5,78</i>	<i>0,6</i>	<i>2,29</i>	<i>0,24</i>	<i>3,86</i>	<i>0,4</i>	<i>1,52</i>	<i>0,16</i>	<i>2,41</i>	<i>0,25</i>	<i>0,95</i>	<i>0,11</i>	<i>1,45</i>	<i>0,15</i>	<i>0,57</i>	<i>0,08</i>	<i>0,48</i>	<i>0,07</i>	<i>0,19</i>	<i>0,06</i>
750	0,75	0,18	<i>7,23</i>	<i>0,56</i>	<i>2,86</i>	<i>0,22</i>	<i>5,78</i>	<i>0,45</i>	<i>2,29</i>	<i>0,18</i>	<i>3,86</i>	<i>0,3</i>	<i>1,52</i>	<i>0,12</i>	<i>2,41</i>	<i>0,2</i>	<i>0,95</i>	<i>0,08</i>	<i>1,45</i>	<i>0,12</i>	<i>0,57</i>	<i>0,06</i>	<i>0,48</i>	<i>0,06</i>	<i>0,19</i>	<i>0,06</i>
500	0,50	0,12	<i>7,23</i>	<i>0,37</i>	<i>2,86</i>	<i>0,15</i>	<i>5,78</i>	<i>0,3</i>	<i>2,29</i>	<i>0,12</i>	<i>3,86</i>	<i>0,2</i>	<i>1,52</i>	<i>0,09</i>	<i>2,41</i>	<i>0,13</i>	<i>0,95</i>	<i>0,06</i>	<i>1,45</i>	<i>0,09</i>	<i>0,57</i>	<i>0,06</i>	<i>0,48</i>	<i>0,06</i>	<i>0,19</i>	<i>0,06</i>
200	0,20	0,05	<i>7,23</i>	<i>0,15</i>	<i>2,86</i>	<i>0,08</i>	<i>5,78</i>	<i>0,12</i>	<i>2,29</i>	<i>0,06</i>	<i>3,86</i>	<i>0,1</i>	<i>1,52</i>	<i>0,06</i>	<i>2,41</i>	<i>0,07</i>	<i>0,95</i>	<i>0,06</i>	<i>1,45</i>	<i>0,06</i>	<i>0,57</i>	<i>0,06</i>	<i>0,48</i>	<i>0,06</i>	<i>0,19</i>	<i>0,06</i>

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 24x12P6 double-thread lifting power in kN

6:1 = 2,0mm/R  
25:1 = 0,48mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min	12		10		8		5		3		1														
		6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW	6:1 Nm   kW	25:1 Nm   kW													
2800	5,60	1,34	<i>8,48</i>	<i>2,44</i>	<i>3,27</i>	<i>0,94</i>	<i>7,07</i>	<i>2,03</i>	<i>2,72</i>	<i>0,78</i>	<i>5,65</i>	<i>1,65</i>	<i>2,18</i>	<i>0,62</i>	<i>3,53</i>	<i>1,1</i>	<i>1,36</i>	<i>0,39</i>	<i>2,12</i>	<i>0,62</i>	<i>0,82</i>	<i>0,24</i>	<i>0,71</i>	<i>0,21</i>	<i>0,27</i>	<i>0,09</i>
1500	3,00	0,72	<i>8,48</i>	<i>1,31</i>	<i>3,27</i>	<i>0,51</i>	<i>7,07</i>	<i>1,09</i>	<i>2,72</i>	<i>0,42</i>	<i>5,65</i>	<i>0,87</i>	<i>2,18</i>	<i>0,34</i>	<i>3,53</i>	<i>0,55</i>	<i>1,36</i>	<i>0,21</i>	<i>2,12</i>	<i>0,33</i>	<i>0,82</i>	<i>0,13</i>	<i>0,71</i>	<i>0,11</i>	<i>0,27</i>	<i>0,06</i>
1000	2,00	0,48	<i>8,48</i>	<i>0,87</i>	<i>3,27</i>	<i>0,34</i>	<i>7,07</i>	<i>0,73</i>	<i>2,72</i>	<i>0,28</i>	<i>5,65</i>	<i>0,58</i>	<i>2,18</i>	<i>0,23</i>	<i>3,53</i>	<i>0,36</i>	<i>1,36</i>	<i>0,15</i>	<i>2,12</i>	<i>0,22</i>	<i>0,82</i>	<i>0,1</i>	<i>0,71</i>	<i>0,08</i>	<i>0,27</i>	<i>0,06</i>
750	1,50	0,36	<i>8,48</i>	<i>0,66</i>	<i>3,27</i>	<i>0,26</i>	<i>7,07</i>	<i>0,55</i>	<i>2,72</i>	<i>0,22</i>	<i>5,65</i>	<i>0,44</i>	<i>2,18</i>	<i>0,17</i>	<i>3,53</i>	<i>0,28</i>	<i>1,36</i>	<i>0,11</i>	<i>2,12</i>	<i>0,17</i>	<i>0,82</i>	<i>0,07</i>	<i>0,71</i>	<i>0,06</i>	<i>0,27</i>	<i>0,06</i>
500	1,00	0,24	<i>8,48</i>	<i>0,44</i>	<i>3,27</i>	<i>0,17</i>	<i>7,07</i>	<i>0,37</i>	<i>2,72</i>	<i>0,15</i>	<i>5,65</i>	<i>0,29</i>	<i>2,18</i>	<i>0,13</i>	<i>3,53</i>	<i>0,19</i>	<i>1,36</i>	<i>0,08</i>	<i>2,12</i>	<i>0,12</i>	<i>0,82</i>	<i>0,06</i>	<i>0,71</i>	<i>0,06</i>	<i>0,27</i>	<i>0,06</i>
200	0,40	0,10	<i>8,48</i>	<i>0,18</i>	<i>3,27</i>	<i>0,08</i>	<i>7,07</i>	<i>0,15</i>	<i>2,72</i>	<i>0,07</i>	<i>5,65</i>	<i>0,12</i>	<i>2,18</i>	<i>0,06</i>	<i>3,53</i>	<i>0,09</i>	<i>1,36</i>	<i>0,06</i>	<i>2,12</i>	<i>0,06</i>	<i>0,82</i>	<i>0,06</i>	<i>0,71</i>	<i>0,06</i>	<i>0,27</i>	<i>0,06</i>

### Technical specifications

max. lifting power	15 kN
gear reduction	6:1 / 25:1
dimension of spindle	Tr24x6 / Tr24x12P6
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	3,2
weight of spindle per 100mm lifting (kg)	0,3
lubricant	grease
quantity of lubricant (kg)	0,1
max. driving power (duty cycle 20%/h)	0,35 kW
max. driving power (duty cycle 10%/h)	0,46 kW





# Screw jack SG 0020

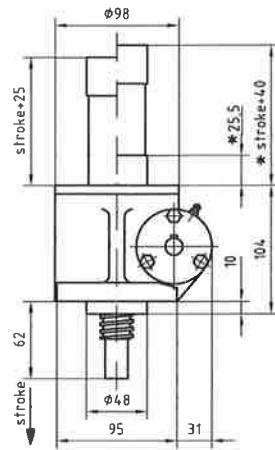
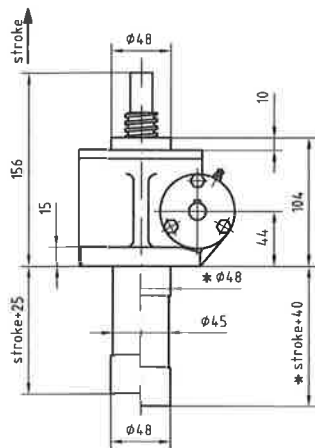
**ENZFELDER GmbH.**

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 Fax.: ++43(0)2256/81287-95  
 E-Mail: office@enzfelder.at  
 Internet: www.enzfelder.at

## Basic type (G)

above (O)

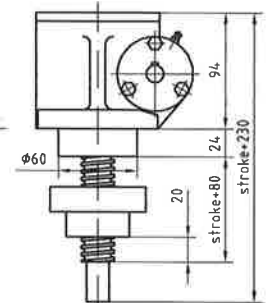
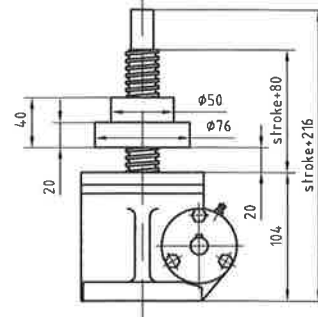
below (U)



## Traveling nut type (L)

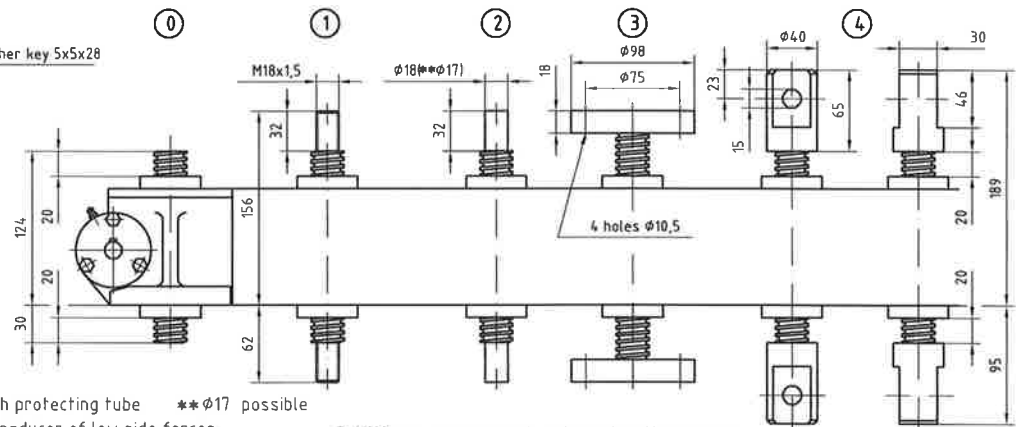
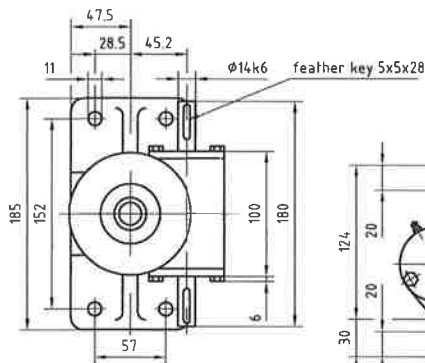
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube \*\*  $\phi 17$  possible  
 The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

## Tr 26x6 single-thread lifting power in kN

6:1 = 1,0mm/R  
 24:1 = 0,25mm/R

$n_1$ min <sup>-1</sup>	lift. speed m/min		20		15		10		8		5		2	
	6:1	24:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
2800	2,80	0,70	9,8   2,86	4,1   1,2	7,35   2,15	2,14   0,9	4,9   1,44	1,43   0,6	3,92   1,15	1,14   0,48	2,45   0,72	0,71   0,3	0,98   0,29	0,28   0,12
1500	1,50	0,375	9,8   1,53	4,1   0,65	7,35   1,15	2,14   0,48	4,9   0,77	1,43   0,32	3,92   0,61	1,14   0,26	2,45   0,38	0,71   0,16	0,98   0,16	0,28   0,08
1000	1,00	0,25	9,8   1,02	4,1   0,43	7,35   0,77	2,14   0,32	4,9   0,51	1,43   0,22	3,92   0,41	1,14   0,18	2,45   0,26	0,71   0,12	0,98   0,11	0,28   0,06
750	0,75	0,19	9,8   0,77	4,1   0,33	7,35   0,58	2,14   0,25	4,9   0,38	1,43   0,16	3,92   0,31	1,14   0,13	2,45   0,19	0,71   0,09	0,98   0,09	0,28   0,06
500	0,50	0,125	9,8   0,51	4,1   0,22	7,35   0,39	2,14   0,16	4,9   0,26	1,43   0,12	3,92   0,22	1,14   0,12	2,45   0,13	0,71   0,07	0,98   0,07	0,28   0,06
200	0,20	0,05	9,8   0,21	4,1   0,17	7,35   0,16	2,14   0,08	4,9   0,11	1,43   0,06	3,92   0,09	1,14   0,06	2,45   0,06	0,71   0,06	0,98   0,06	0,28   0,06

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available

## Tr 26x12P6 double-thread lifting power in kN

6:1 = 2,0mm/R  
 24:1 = 0,5mm/R

$n_1$ min <sup>-1</sup>	lift. speed m/min		16		12		8		6		4		2	
	6:1	24:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
2800	5,60	1,40	12,1   3,48	4,9   1,4	9,09   2,61	3,68   1,06	6,06   1,8	2,45   0,7	4,55   1,3	1,83   0,53	3,03   0,9	1,23   0,35	1,51   0,45	0,62   0,18
1500	3,00	0,75	12,1   1,86	4,9   0,75	9,09   1,4	3,68   0,57	6,06   0,93	2,45   0,37	4,55   0,7	1,83   0,28	3,03   0,46	1,23   0,19	1,51   0,23	0,62   0,1
1000	2,00	0,50	12,1   1,25	4,9   0,5	9,09   0,93	3,68   0,38	6,06   0,62	2,45   0,25	4,55   0,47	1,83   0,19	3,03   0,31	1,23   0,13	1,51   0,16	0,62   0,08
750	1,50	0,375	12,1   0,93	4,9   0,38	9,09   0,7	3,68   0,28	6,06   0,47	2,45   0,19	4,55   0,35	1,83   0,15	3,03   0,23	1,23   0,1	1,51   0,13	0,62   0,06
500	1,00	0,25	12,1   0,62	4,9   0,25	9,09   0,46	3,68   0,19	6,06   0,31	2,45   0,13	4,55   0,23	1,83   0,1	3,03   0,16	1,23   0,08	1,51   0,09	0,62   0,06
200	0,40	0,10	12,1   0,25	4,9   0,11	9,09   0,19	3,68   0,09	6,06   0,13	2,45   0,07	4,55   0,1	1,83   0,06	3,03   0,07	1,23   0,06	1,51   0,06	0,62   0,06

## Technical specifications

max. lifting power	20 kN
gear reduction	6:1 / 24:1
dimension of spindle	Tr26x6 / Tr26x12P6
start-up moment	table entry x 1,3
casing material	GJS4.00-15
weight without lifting (kg)	7,8
weight of spindle per 100mm lifting (kg)	0,34
lubricant	grease
quantity of lubricant (kg)	0,15
max. driving power (duty cycle 20%/h)	0,5 kW
max. driving power (duty cycle 10%/h)	0,7 kW



# Screw jack SG 0030

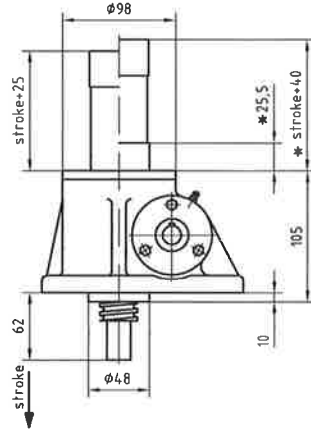
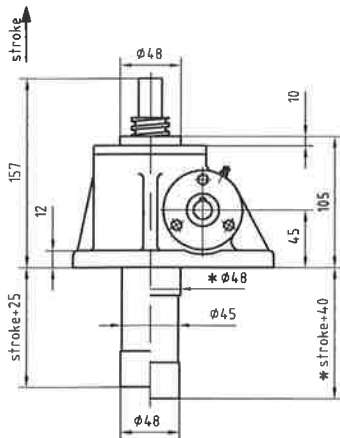
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Internet: www.enzfelder.at

## Basic type (G)

above (O)

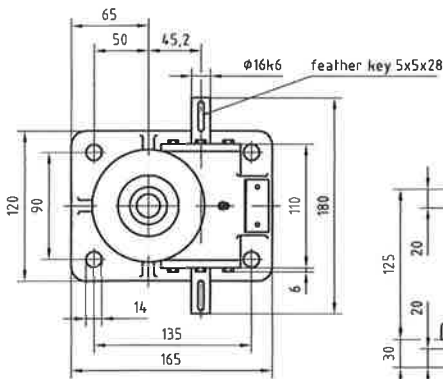
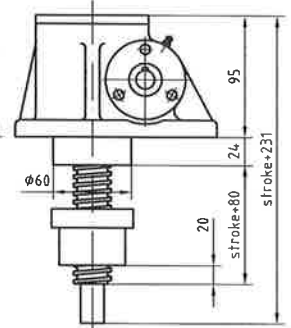
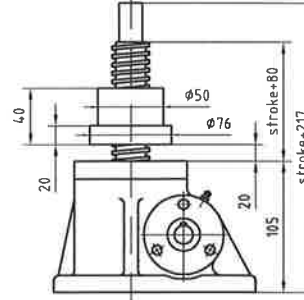
below (U)



## Traveling nut type (L)

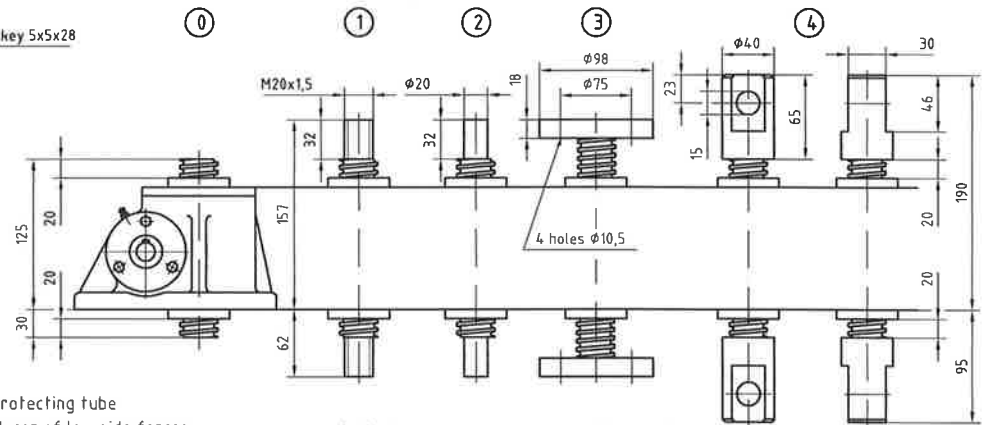
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors

### Tr 30x6 single-thread lifting power in kN

6:1 = 1,0mm/R  
24:1 = 0,25mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		30		20		15		10		5		2	
	6:1	24:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
2800	2,80	0,70	16,5   4,73	6,9   2,02	11   3,15	4,6   1,35	8,25   2,37	3,45   1	5,5   1,57	2,3   0,67	2,75   0,79	1,15   0,34	1,1   0,32	0,46   0,15
1500	1,50	0,375	16,5   2,53	6,9   1,08	11   1,69	4,6   0,72	8,25   1,27	3,45   0,54	5,5   0,85	2,3   0,36	2,75   0,42	1,15   0,18	1,1   0,17	0,46   0,09
1000	1,00	0,25	16,5   1,69	6,9   0,72	11   1,13	4,6   0,48	8,25   0,84	3,45   0,36	5,5   0,56	2,3   0,24	2,75   0,28	1,15   0,13	1,1   0,12	0,46   0,07
750	0,75	0,19	16,5   1,26	6,9   0,55	11   0,84	4,6   0,37	8,25   0,63	3,45   0,28	5,5   0,42	2,3   0,18	2,75   0,21	1,15   0,10	1,1   0,10	0,46   0,06
500	0,50	0,125	16,5   0,84	6,9   0,36	11   0,56	4,6   0,24	8,25   0,42	3,45   0,18	5,5   0,28	2,3   0,12	2,75   0,14	1,15   0,08	1,1   0,07	0,46   0,06
200	0,20	0,05	16,5   0,34	6,9   0,15	11   0,23	4,6   0,11	8,25   0,17	3,45   0,09	5,5   0,12	2,3   0,07	2,75   0,07	1,15   0,06	1,1   0,06	0,46   0,06

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 30x12P6 double-thread lifting power in kN

6:1 = 2,0mm/R  
24:1 = 0,5mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		24		18		12		8		5		2	
	6:1	24:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
2800	5,60	1,40	18,2   5,35	7,64   2,19	13,7   4	5,7   1,64	9,1   2,9	3,8   1,09	6,1   1,8	2,6   0,73	3,8   1,12	1,6   0,46	1,5   0,45	0,7   0,19
1500	3,00	0,75	18,2   2,87	7,64   1,18	13,7   2,15	5,7   0,88	9,1   1,43	3,8   0,59	6,1   0,96	2,6   0,40	3,8   0,60	1,6   0,25	1,5   0,24	0,7   0,11
1000	2,00	0,50	18,2   1,91	7,64   0,78	13,7   1,43	5,7   0,59	9,1   0,96	3,8   0,40	6,1   0,64	2,6   0,26	3,8   0,40	1,6   0,17	1,5   0,16	0,7   0,08
750	1,50	0,375	18,2   1,43	7,64   0,59	13,7   1,08	5,7   0,44	9,1   0,72	3,8   0,30	6,1   0,48	2,6   0,20	3,8   0,30	1,6   0,13	1,5   0,12	0,7   0,07
500	1,00	0,25	18,2   0,96	7,64   0,40	13,7   0,71	5,7   0,30	9,1   0,48	3,8   0,20	6,1   0,32	2,6   0,13	3,8   0,20	1,6   0,10	1,5   0,09	0,7   0,06
200	0,40	0,10	18,2   0,38	7,64   0,20	13,7   0,29	5,7   0,13	9,1   0,20	3,8   0,10	6,1   0,14	2,6   0,07	3,8   0,10	1,6   0,06	1,5   0,07	0,7   0,06

### Technical specifications

max. lifting power	30 kN
gear reduction	6:1 / 24:1
dimension of spindle	Tr30x6 / Tr30x12P6
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	8,2
weight of spindle per 100mm lifting (kg)	0,43
lubricant	grease
quantity of lubricant (kg)	0,2
max. driving power (duty cycle 20%/h)	0,6 kW
max. driving power (duty cycle 10%/h)	0,8 kW



# Screw jack SG 0050

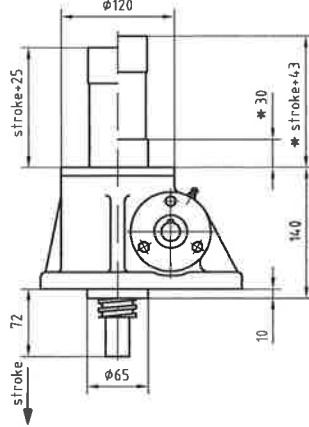
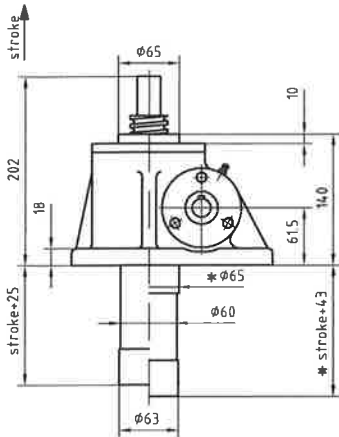
**ENZFELDER GmbH.**

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## Basic type (G)

above (O)

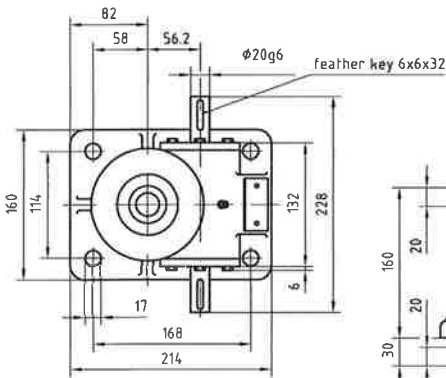
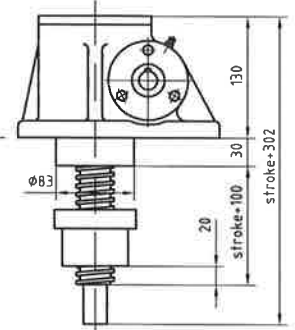
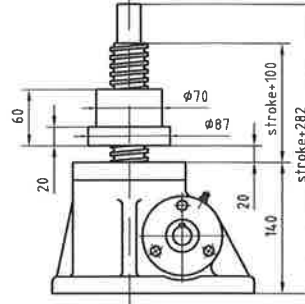
below (U)



## Traveling nut type (L)

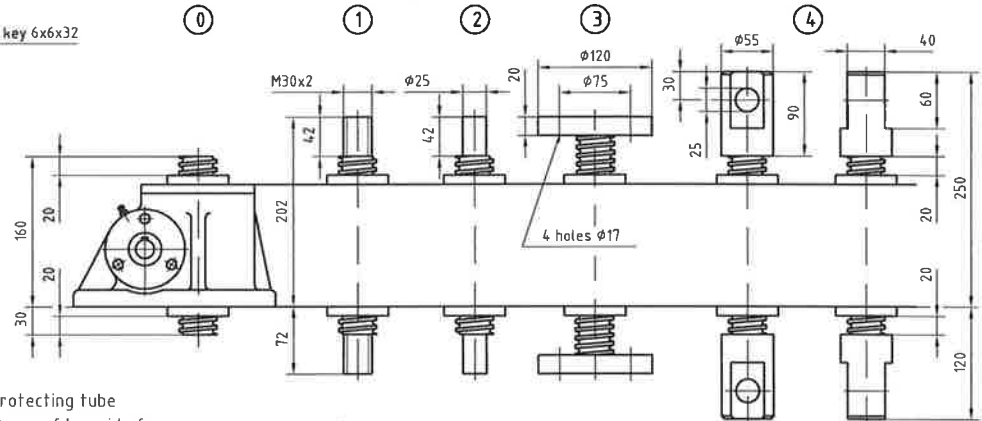
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

### Tr 40x9 single-thread lifting power in kN

6:1 = 1,5mm/R  
24:1 = 0,375mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		50		40		30		20		15		10													
	6:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1800	2,70	0,67	37,3	6,9	15,3	2,82	29,8	5,52	12,2	2,26	22,4	4,13	9,18	1,7	14,9	2,75	6,12	1,13	11,2	2,07	4,59	0,85	7,46	1,37	3,06	0,57
1500	2,25	0,56	37,3	5,75	15,3	2,35	29,8	4,59	12,2	1,88	22,4	3,44	9,18	1,4	14,9	2,29	6,12	0,94	11,2	1,72	4,59	0,71	7,46	1,15	3,06	0,47
1000	1,50	0,37	37,3	3,83	15,3	1,57	29,8	3,06	12,2	1,25	22,4	2,29	9,18	0,94	14,9	1,53	6,12	0,63	11,2	1,15	4,59	0,47	7,46	0,77	3,06	0,31
750	1,12	0,28	37,3	2,87	15,3	1,17	29,8	2,29	12,2	0,94	22,4	1,72	9,18	0,71	14,9	1,15	6,12	0,47	11,2	0,86	4,59	0,35	7,46	0,58	3,06	0,23
500	0,75	0,19	37,3	1,91	15,3	0,78	29,8	1,53	12,2	0,63	22,4	1,15	9,18	0,47	14,9	0,77	6,12	0,31	11,2	0,58	4,59	0,23	7,46	0,38	3,06	0,16
200	0,30	0,075	37,3	0,77	15,3	0,31	29,8	0,61	12,2	0,26	22,4	0,45	9,18	0,19	14,9	0,3	6,12	0,13	11,2	0,23	4,59	0,09	7,46	0,15	3,06	0,07

### Tr 40x18P9 double-thread lifting power in kN

6:1 = 3,0mm/R  
24:1 = 0,75mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		40		30		20		15		10		5													
	6:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1800	5,40	1,35	43,4	8	17,7	3,26	32	6	13,3	2,45	21,7	4	8,84	1,63	16,3	3	6,63	1,23	10,9	2	4,42	0,82	5,42	1,0	2,21	0,41
1500	4,50	1,12	43,4	6,68	17,7	2,72	32	5	13,3	2,04	21,7	3,34	8,84	1,36	16,3	2,5	6,63	1,02	10,9	1,67	4,42	0,68	5,42	0,84	2,21	0,35
1000	3,00	0,75	43,4	4,46	17,7	1,82	32	3,34	13,3	1,36	21,7	2,23	8,84	0,9	16,3	1,67	6,63	0,68	10,9	1,11	4,42	0,45	5,42	0,56	2,21	0,23
750	2,25	0,56	43,4	3,34	17,7	1,36	32	2,5	13,3	1,02	21,7	1,67	8,84	0,68	16,3	1,25	6,63	0,51	10,9	0,84	4,42	0,39	5,42	0,42	2,21	0,2
500	1,50	0,37	43,4	2,23	17,7	0,9	32	1,67	13,3	0,68	21,7	1,11	8,84	0,45	16,3	0,84	6,63	0,34	10,9	0,56	4,42	0,23	5,42	0,28	2,21	0,11
200	0,60	0,15	43,4	0,89	17,7	0,38	32	0,67	13,3	0,28	21,7	0,44	8,84	0,2	16,3	0,34	6,63	0,14	10,9	0,22	4,42	0,15	5,42	0,11	2,21	0,06

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Technical specifications

max. lifting power	50 kN
gear reduction	6:1 / 24:1
dimension of spindle*	Tr40x9 / Tr40x18P9
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	18
weight of spindle per 100mm lifting (kg)	0,8
lubricant	grease
quantity of lubricant (kg)	0,35
max. driving power (duty cycle 20%/h)	1,2 kW
max. driving power (duty cycle 10%/h)	1,6 kW
*also available with spindle Tr40x7 or Tr40x14/7	



# Screw jack SG 0100

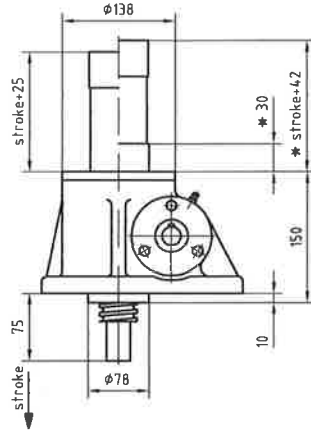
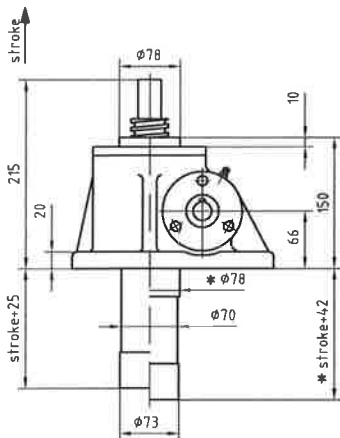
**ENZFELDER GmbH.**

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## Basic type (G)

above (O)

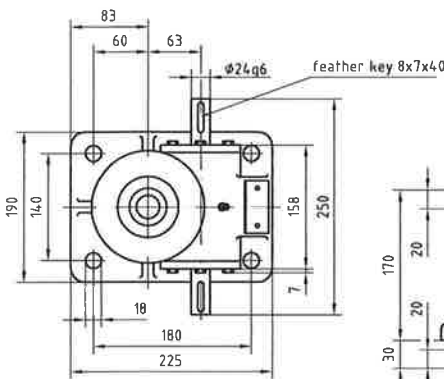
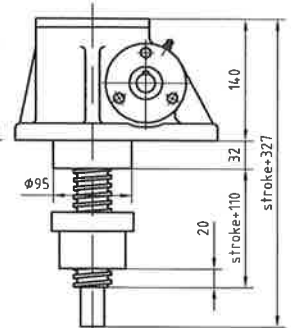
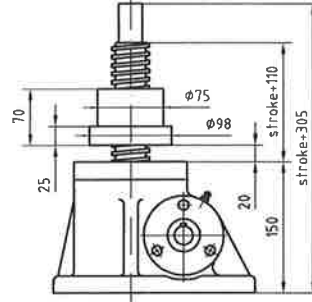
below (U)



## Traveling nut type (L)

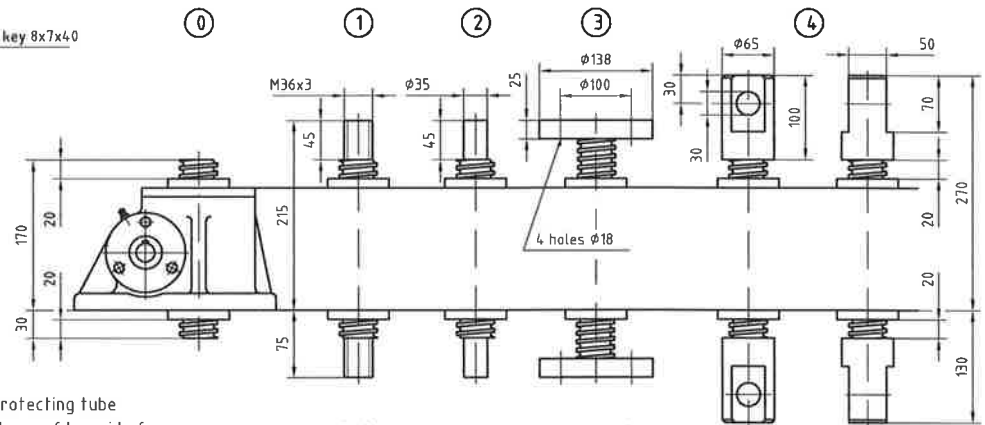
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors

### Tr 55x12 single-thread lifting power in kN

8:1 = 1,5mm/R  
24:1 = 0,5mm/R

n <sub>l</sub> min <sup>-1</sup>	lift speed m/min		100		80		60		40		20		10													
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1800	2,70	0,90	81	15,2	39	7,4	64,8	12,2	31,2	5,9	48,6	9,1	23,4	4,4	32,4	6,1	15,6	3	16,2	3,1	7,8	1,5	8,1	1,5	3,9	0,75
1500	2,25	0,75	81	12,7	39	6,1	64,8	10,2	31,2	4,9	48,6	7,6	23,4	3,7	32,4	5,1	15,6	2,5	16,2	2,5	7,8	1,3	8,1	1,3	3,9	0,62
1000	1,50	0,50	81	8,5	39	4,1	64,8	6,8	31,2	3,3	48,6	5,1	23,4	2,5	32,4	3,4	15,6	1,6	16,2	1,7	7,8	0,8	8,1	0,85	3,9	0,42
750	1,125	0,375	81	6,4	39	3,1	64,8	5,1	31,2	2,5	48,6	3,8	23,4	1,9	32,4	2,5	15,6	1,3	16,2	1,3	7,8	0,62	8,1	0,63	3,9	0,31
500	0,75	0,25	81	4,2	39	2	64,8	3,4	31,2	1,65	48,6	2,5	23,4	1,3	32,4	1,7	15,6	0,82	16,2	0,85	7,8	0,41	8,1	0,42	3,9	0,21
200	0,30	0,10	81	1,7	39	0,82	64,8	1,4	31,2	0,65	48,6	1	23,4	0,5	32,4	0,68	15,6	0,33	16,2	0,35	7,8	0,17	8,1	0,18	3,9	0,10

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 55x24P12 double-thread lifting power in kN

8:1 = 3,0mm/R  
24:1 = 1,0mm/R

n <sub>l</sub> min <sup>-1</sup>	lift speed m/min		80		60		40		20		10		5													
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1800	5,40	1,80	91,2	16,8	47,2	8,7	68,4	12,6	31,7	6,5	45,6	8,4	21,1	4,4	22,8	4,2	10,6	2,2	11,4	2,1	5,3	1,1	5,7	1,1	2,7	0,6
1500	4,50	1,50	91,2	14	47,2	7,3	68,4	10,5	31,7	5,5	45,6	7	21,1	3,6	22,8	3,5	10,6	1,8	11,4	1,8	5,3	0,9	5,7	0,9	2,7	0,5
1000	3,00	1,00	91,2	9,3	47,2	4,9	68,4	7	31,7	3,6	45,6	4,7	21,1	2,4	22,8	2,3	10,6	1,2	11,4	1,2	5,3	0,6	5,7	0,6	2,7	0,4
750	2,25	0,75	91,2	7	47,2	3,6	68,4	5,3	31,7	2,8	45,6	3,5	21,1	1,8	22,8	1,75	10,6	0,9	11,4	0,9	5,3	0,5	5,7	0,5	2,7	0,3
500	1,50	0,50	91,2	4,7	47,2	2,4	68,4	3,5	31,7	1,8	45,6	2,3	21,1	1,2	22,8	1,2	10,6	0,6	11,4	0,6	5,3	0,3	5,7	0,3	2,7	0,2
200	0,60	0,20	91,2	1,9	47,2	1,0	68,4	1,4	31,7	0,8	45,6	1,0	21,1	0,6	22,8	0,5	10,6	0,3	11,4	0,3	5,3	0,2	5,7	0,2	2,7	0,2

### Technical specifications

max. lifting power	100 kN
gear reduction	8:1 / 24:1
dimension of spindle	Tr55x12 / Tr55x24P12
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	23
weight of spindle per 100mm lifting (kg)	1,5
lubricant	grease
quantity of lubricant (kg)	0,6
max. driving power (duty cycle 20%/h)	2,1 kW
max. driving power (duty cycle 10%/h)	2,8 kW



# Screw jack SG 0150

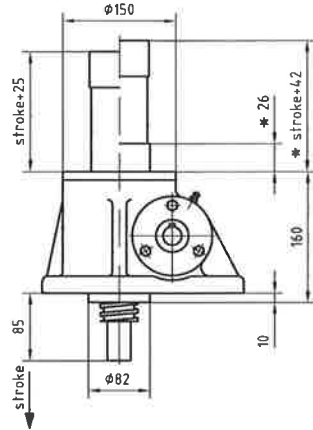
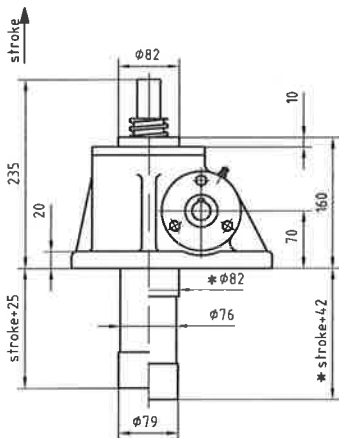
**ENZFELDER GmbH.**

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Fax.: ++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Basic type (G)

above (O)

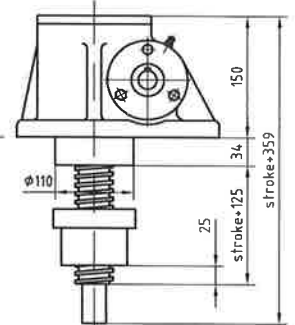
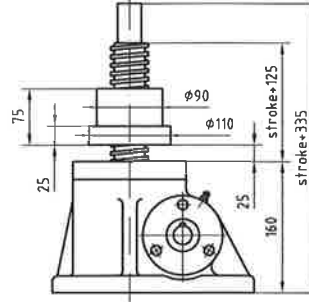
below (U)



## Traveling nut type (L)

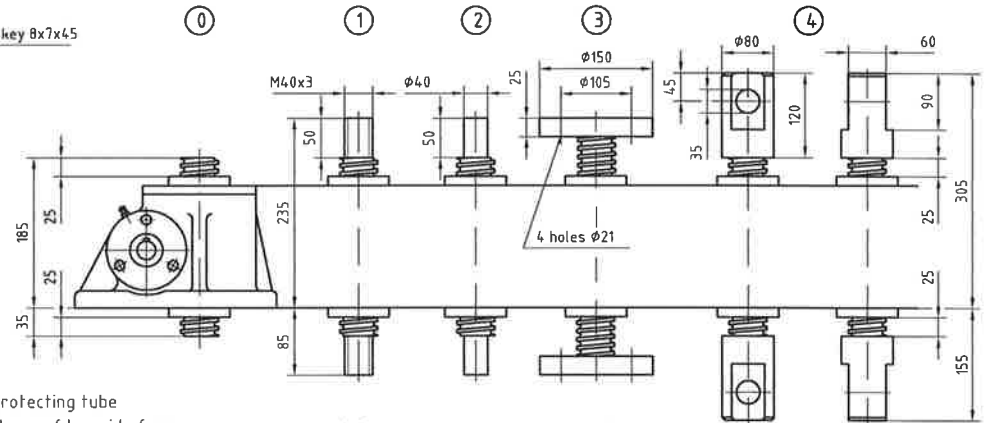
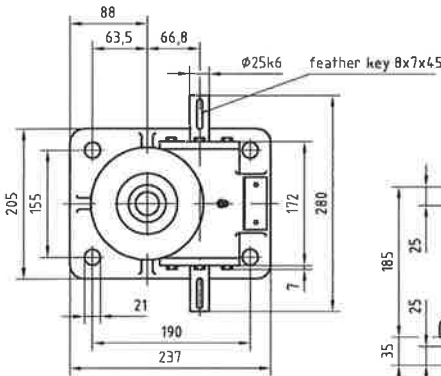
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors

## Tr 60x12 single-thread lifting power in kN

8:1 = 1,5mm/R  
24:1 = 0,5mm/R

$n_1$ min <sup>-1</sup>	liff. speed m/min		150		120		100		80		50		20	
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1500	2,25	0,75	133	20,4	68,2	10,5	106	16,3	54,6	8,4	89	13,6	45,5	7
1000	1,50	0,50	133	13,6	68,2	7,0	106	10,9	54,6	5,6	89	9,1	45,5	4,7
750	1,125	0,375	133	10,2	68,2	5,3	106	8,2	54,6	4,2	89	6,8	45,5	3,5
500	0,75	0,25	133	6,8	68,2	3,5	106	5,5	54,6	2,8	89	4,6	45,5	2,4
320	0,48	0,16	133	4,4	68,2	2,3	106	3,5	54,6	1,8	89	2,9	45,5	1,5
160	0,24	0,08	133	2,2	68,2	1,2	106	1,8	54,6	0,9	89	1,5	45,5	0,8

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

## Tr 60x24P12 double-thread lifting power in kN

8:1 = 3,0mm/R  
24:1 = 1,0mm/R

$n_1$ min <sup>-1</sup>	liff. speed m/min		120		100		80		50		20		10	
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1500	4,50	1,50	151	23,2	77	11,8	126	19,4	64,2	9,8	101	15,5	51,3	7,8
1000	3,00	1,00	151	15,5	77	7,9	126	12,9	64,2	6,6	101	10,3	51,3	5,3
750	2,25	0,75	151	11,6	77	5,9	126	9,7	64,2	4,9	101	7,7	51,3	4,6
500	1,50	0,50	151	7,7	77	3,9	126	6,5	64,2	3,3	101	5,2	51,3	2,6
320	0,96	0,32	151	5	77	2,5	126	4,2	64,2	2,1	101	3,3	51,3	1,7
160	0,48	0,16	151	2,5	77	1,3	126	2,1	64,2	1,1	101	1,7	51,3	0,9

## Technical specifications

max. lifting power	150 kN
gear reduction	8:1 / 24:1
dimension of spindle	Tr60x12 / Tr60x24P12
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	28
weight of spindle per 100mm lifting (kg)	1,8
lubricant	grease
quantity of lubricant (kg)	0,8
max. driving power (duty cycle 20%/h)	2,8 kW
max. driving power (duty cycle 10%/h)	3,8 kW



# Screw jack SG 0200

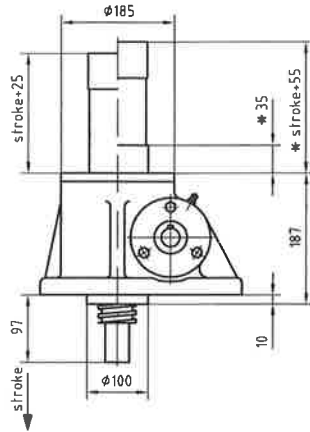
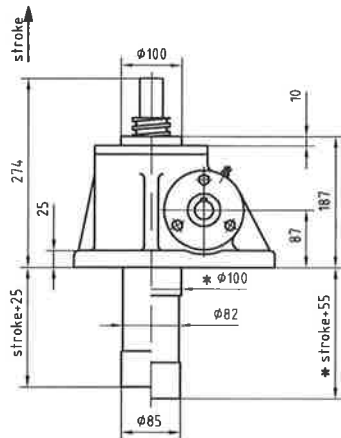
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Internet: www.enzfelder.at

## Basic type (G)

above (O)

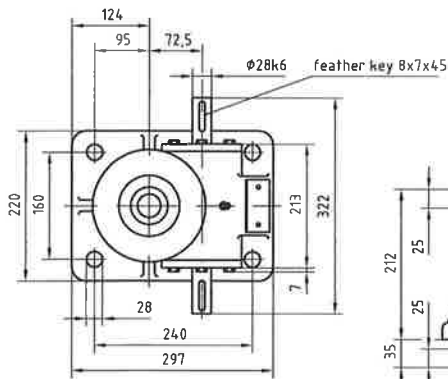
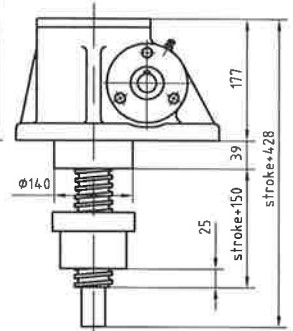
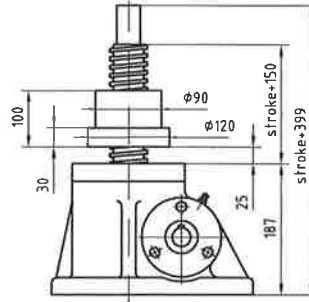
below (U)



## Traveling nut type (L)

above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)

①

②

③

④

⑤

( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

### Tr 65x12 single-thread lifting power in kN

8:1 = 1,5mm/R  
24:1 = 0,5mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		200		150		100		75		50		25													
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1500	2,25	0,75	184	28,3	93,6	14,4	138	21,2	70,2	10,8	92	14,2	46,8	7,2	69	10,6	35,1	5,4	46	7,1	23,4	3,6	23	3,6	11,7	1,8
1000	1,50	0,50	184	18,9	93,6	9,6	138	14,2	70,2	7,2	92	9,5	46,8	4,8	69	7,7	35,1	3,6	46	4,7	23,4	2,4	23	2,3	11,7	1,2
750	1,125	0,375	184	14,2	93,6	7,2	138	10,6	70,2	5,4	92	7,1	46,8	3,6	69	5,3	35,1	2,7	46	3,6	23,4	1,8	23	1,6	11,7	0,9
500	0,75	0,25	184	9,4	93,6	4,8	138	7,1	70,2	3,6	92	4,7	46,8	2,4	69	3,6	35,1	1,8	46	2,3	23,4	1,2	23	1,2	11,7	0,7
320	0,48	0,16	184	6	93,6	3,1	138	4,5	70,2	2,3	92	3,0	46,8	1,6	69	2,3	35,1	1,2	46	1,6	23,4	0,8	23	0,8	11,7	0,5
160	0,24	0,08	184	3,0	93,6	1,6	138	2,3	70,2	1,2	92	1,6	46,8	0,8	69	1,2	35,1	0,6	46	0,8	23,4	0,5	23	0,5	11,7	0,4

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 65x24P12 double-thread lifting power in kN

8:1 = 3,0mm/R  
24:1 = 1,0mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed m/min		150		100		75		50		25		16													
	8:1	24:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW												
1500	4,50	1,50	194	29,8	100	15,4	130	20	66,7	10,2	97	15,5	50	7,7	64,7	10	33,3	5,1	32,4	5	16,7	2,6	20,7	3,2	10,7	1,7
1000	3,00	1,00	194	20	100	10,2	130	13,3	66,7	6,8	97	10,3	50	5,7	64,7	6,7	33,3	3,4	32,4	3,4	16,7	1,7	20,7	2,2	10,7	1,2
750	2,25	0,75	194	15	100	7,7	130	10	66,7	5,1	97	7,8	50	3,9	64,7	5	33,3	2,6	32,4	2,5	16,7	1,3	20,7	1,6	10,7	0,9
500	1,50	0,50	194	10	100	5,1	130	6,7	66,7	3,4	97	5,2	50	2,6	64,7	3,4	33,3	1,7	32,4	1,7	16,7	0,9	20,7	1,1	10,7	0,6
320	0,96	0,32	194	6,4	100	3,3	130	4,3	66,7	2,2	97	3,3	50	1,7	64,7	2,2	33,3	1,1	32,4	1,1	16,7	0,6	20,7	0,7	10,7	0,5
160	0,48	0,16	194	3,2	100	1,7	130	2,2	66,7	1,1	97	1,7	50	0,9	64,7	1,1	33,3	0,6	32,4	0,6	16,7	0,5	20,7	0,5	10,7	0,5

### Technical specifications

max. lifting power	200 kN
gear reduction	8:1 / 24:1
dimension of spindle	Tr65x12 / Tr65x24P12
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	40
weight of spindle per 100mm lifting (kg)	2,15
lubricant	grease
quantity of lubricant (kg)	1,2
max. driving power (duty cycle 20%/h)	3,9 kW
max. driving power (duty cycle 10%/h)	5,1 kW



# Screw jack SG 0240

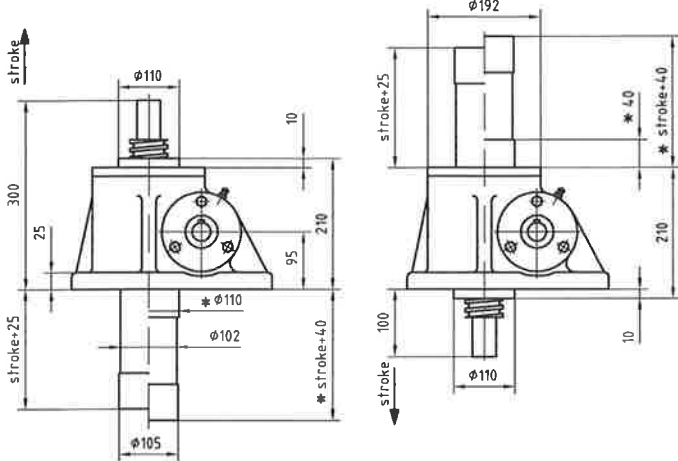
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## Basic type (G)

above (O)

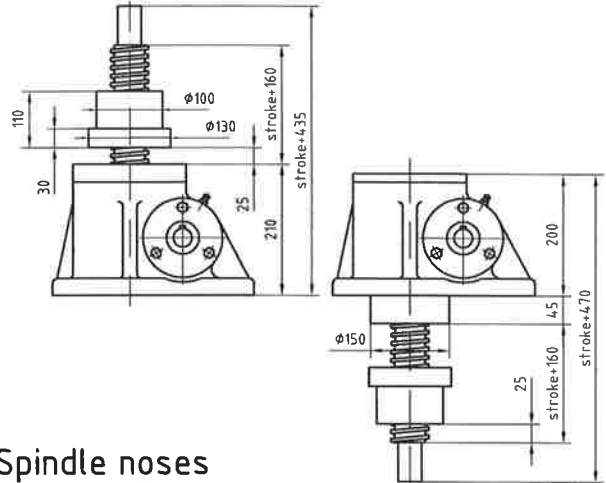
below (U)



## Traveling nut type (L)

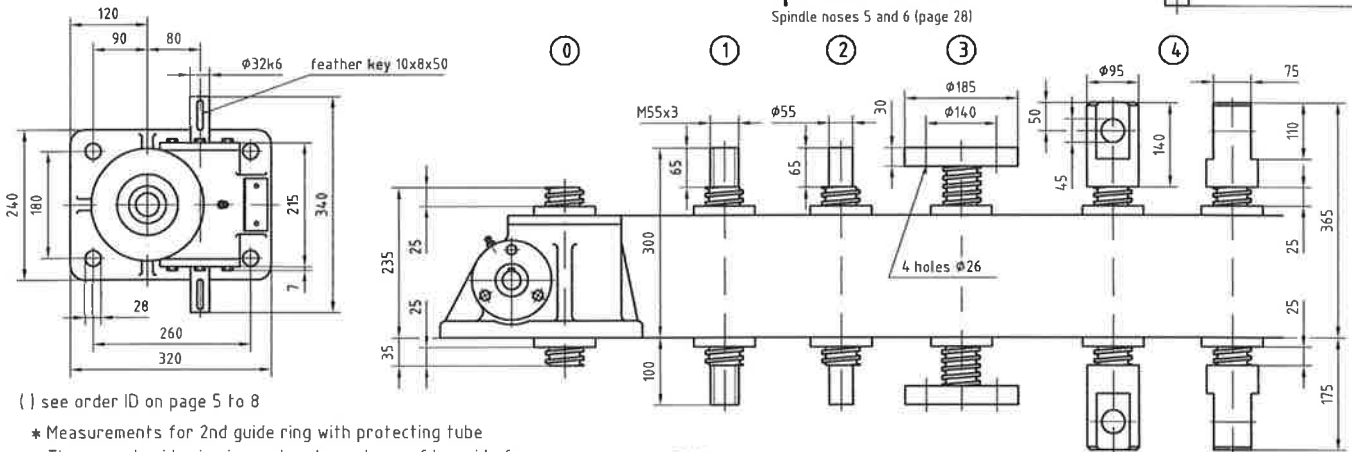
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors

### Tr 75x14 single-thread lifting power in kN

9/1 = 1,5mm/R  
28:1 = 0,5mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		240		160		120		80		60		40	
	9/1	28:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
1500	2,25	0,75	229   35,3	112   17,3	14,7   23,5	74,7   11,6	110   17,7	56   8,7	73,7   11,8	37,3   5,8	55,3   8,0	28,0   4,4	36,8   5,9	18,7   2,9
1000	1,50	0,50	229   23,6	112   11,6	14,7   15,7	74,7   7,7	110   11,8	56   5,8	73,7   7,9	37,3   3,8	55,3   5,9	28,0   2,9	36,8   4,0	18,7   1,9
750	1,125	0,375	229   17,7	112   8,7	14,7   11,8	74,7   5,8	110   8,9	56   4,4	73,7   5,9	37,3   2,9	55,3   4,4	28,0   2,2	36,8   3,0	18,7   1,5
500	0,75	0,25	229   11,8	112   5,8	14,7   7,9	74,7   3,8	110   5,9	56   2,9	73,7   4,0	37,3   1,9	55,3   3,0	28,0   1,5	36,8   2,0	18,7   0,9
320	0,48	0,16	229   7,6	112   3,7	14,7   5,1	74,7   2,5	110   3,8	56   1,9	73,7   2,5	37,3   1,3	55,3   1,9	28,0   1,0	36,8   1,3	18,7   0,7
160	0,24	0,08	229   3,8	112   1,9	14,7   2,6	74,7   1,3	110   1,9	56   1,0	73,7   1,3	37,3   0,7	55,3   1,0	28,0   0,6	36,8   0,7	18,7   0,5

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 75x28P14 double-thread lifting power in kN

9/1 = 3,0mm/R  
28:1 = 1,0mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		180		120		90		60		45		30	
	9/1	28:1	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW	Nm   kW
1500	4,50	1,50	232   35,8	120   18,4	155   23,8	80   12,2	116   17,9	60   9,2	77,3   11,9	40   6,1	58   9	30   4,6	38,7   6	40   3,2
1000	3,00	1,00	232   23,8	120   12,2	155   16	80   8,1	116   11,9	60   6,1	77,3   8	40   4	58   6	30   3,2	38,7   4	40   2
750	2,25	0,75	232   17,9	120   9,2	155   11,9	80   6,1	116   9	60   4,6	77,3   6	40   3,2	58   4,5	30   2,3	38,7   3	40   1,6
500	1,50	0,50	232   11,9	120   6,1	155   8	80   4	116   6	60   3,2	77,3   4	40   2	58   3	30   1,6	38,7   2	40   1
320	0,96	0,32	232   7,6	120   4	155   5,1	80   2	116   4	60   2	77,3   2,6	40   1	58   2	30   1	38,7   1,3	40   0,6
160	0,48	0,16	232   3,8	120   2	155   2,6	80   1	116   2	60   1	77,3   1,3	40   0,6	58   1	30   0,6	38,7   0,8	40   0,5

### Technical specifications

max. lifting power	240 kN
gear reduction	9/1 / 28:1
dimension of spindle	Tr75x14 / Tr75x28P14
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	58
weight of spindle per 100mm lifting (kg)	2,8
lubricant	grease
quantity of lubricant (kg)	1,5
max. driving power (duty cycle 20%/h)	4,5 kW
max. driving power (duty cycle 10%/h)	5,9 kW



# Screw jack SG 0300

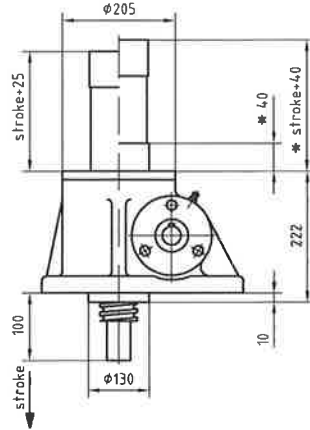
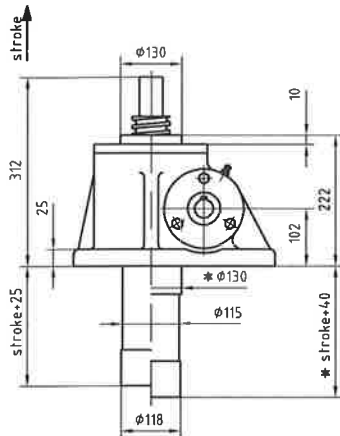
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## Basic type (G)

above (O)

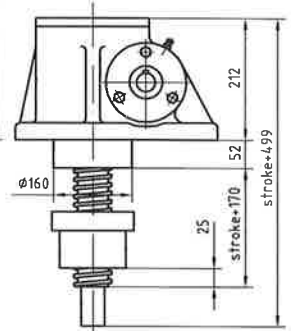
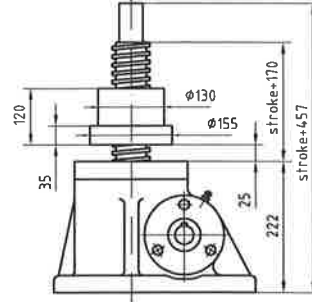
below (U)



## Traveling nut type (L)

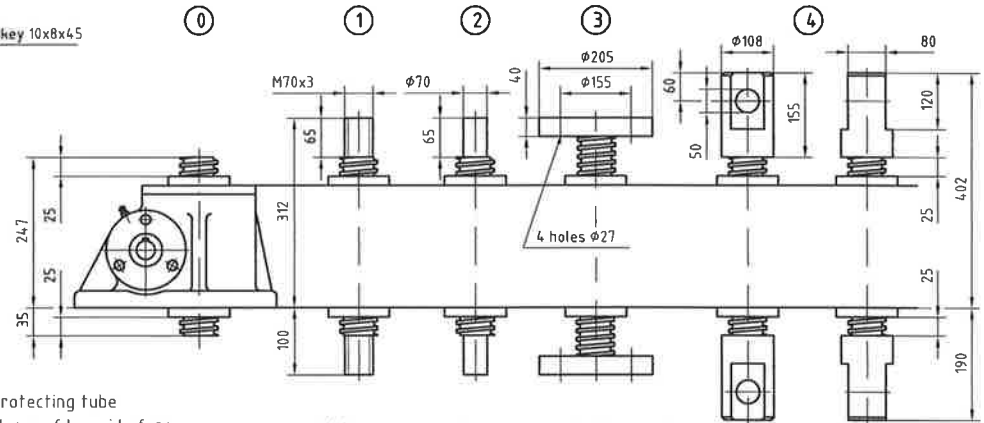
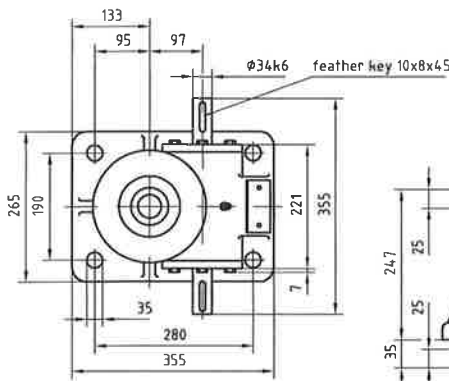
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

### Tr 90x16 single-thread lifting power in kN

10%1 = 1,5mm/R  
32:1 = 0,5mm/R

$n_1$ min <sup>-1</sup>	lift. speed m/min		300		200		150		100		75		50	
	10%1	32:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1000	1,50	0,50	286	29,4	149	15,3	191	19,6	99,3	10,2	143	14,7	74,5	7,7
750	1,125	0,375	286	22,1	149	11,5	191	14,7	99,3	7,7	143	11,1	74,5	5,8
500	0,75	0,25	286	14,7	149	7,7	191	9,8	99,3	5,1	143	7,4	74,5	3,9
360	0,54	0,18	286	10,6	149	5,5	191	7,1	99,3	3,7	143	5,2	74,5	2,8
240	0,36	0,12	286	7,1	149	3,7	191	4,8	99,3	2,5	143	3,6	74,5	1,9
120	0,18	0,06	286	3,6	149	1,9	191	2,4	99,3	1,3	143	1,8	74,5	1

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 90x32P16 double-thread lifting power in kN

10%1 = 3,0mm/R  
32:1 = 1,0mm/R

$n_1$ min <sup>-1</sup>	lift. speed m/min		220		160		120		80		60		40	
	10%1	32:1	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1000	3,00	1,00	284	29,2	146	15	207	21,2	106	10,9	155	16	79,6	7,3
750	2,25	0,75	284	21,9	146	11,3	207	15,9	106	8,2	155	12	79,6	5,5
500	1,50	0,50	284	14,6	146	7,5	207	10,6	106	5,5	155	8	79,6	3,7
360	1,08	0,36	284	10,5	146	5,4	207	7,7	106	4	155	5,2	79,6	2,7
240	0,72	0,24	284	7	146	3,6	207	5,2	106	2,8	155	3,5	79,6	1,9
120	0,36	0,12	284	3,5	146	1,8	207	2,6	106	1,4	155	1,8	79,6	1

### Technical specifications

max. lifting power	300 kN
gear reduction	10%1 / 32:1
dimension of spindle	Tr90x16 / Tr90x32P16
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	75
weight of spindle per 100mm lifting (kg)	4,2
lubricant	grease
quantity of lubricant (kg)	1,7
max. driving power (duty cycle 20%/h)	5,2 kW
max. driving power (duty cycle 10%/h)	6,9 kW





# Screw jack SG 0350

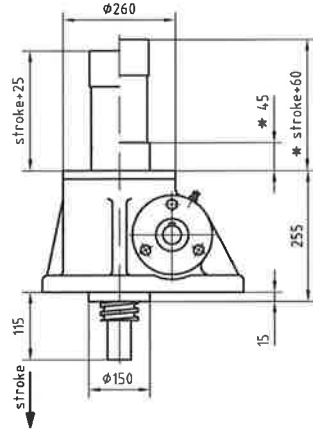
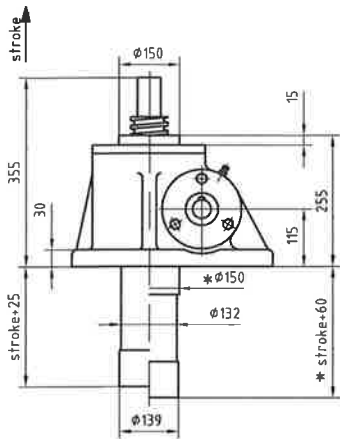
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E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Basic type (G)

above (O)

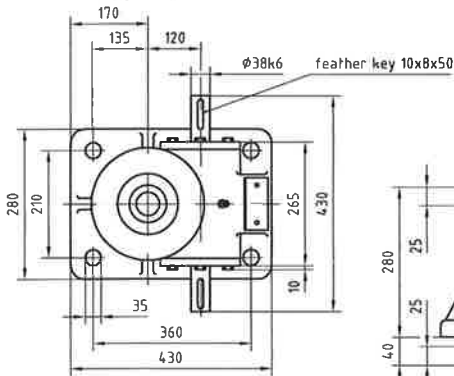
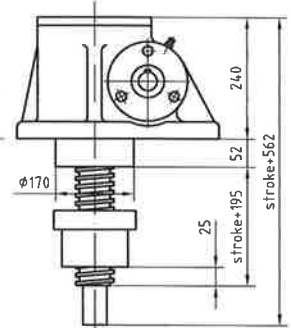
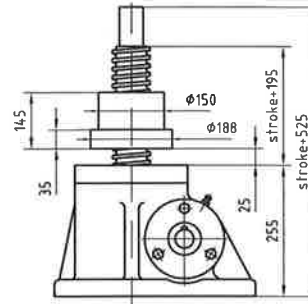
below (U)



## Traveling nut type (L)

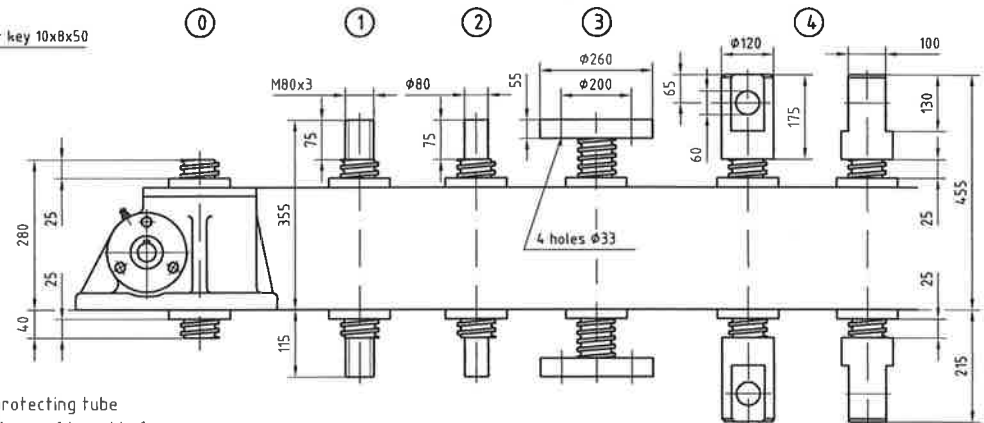
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

\* Measurements for 2nd guide ring with protecting tube

The second guide ring is used as transducer of low side forces.

Subject to measurement and construction errors.

### Tr 100x16 single-thread lifting power in kN

10% : 1 = 1,5mm/R  
32:1 = 0,5mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		350		250		200		150		100		50	
	10%:1	32:1	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW
1000	1,50	0,50	363   37,3	186   19,1	260   26,6	133   13,7	208   21,3	106   10,9	156   16	79,7   8,2	104   10,7	53,1   5,5	51,9   5,4	26,6   2,8
750	1,125	0,375	363   28	186   14,3	260   20	133   10,2	208   16	106   8,2	156   12	79,7   6,2	104   8	53,1   4,1	51,9   4,2	26,6   2,1
500	0,75	0,25	363   18,7	186   9,6	260   13,3	133   6,8	208   10,7	106   5,5	156   8	79,7   4,1	104   5,4	53,1   2,8	51,9   2,7	26,6   1,5
360	0,54	0,18	363   13,4	186   6,9	260   9,6	133   5	208   7,7	106   4	156   5,8	79,7   3	104   3,9	53,1   2,1	51,9   2,2	26,6   1,1
240	0,36	0,12	363   9	186   4,6	260   6,4	133   3,3	208   5,2	106   2,6	156   4	79,7   2,1	104   2,8	53,1   1,5	51,9   1,5	26,6   0,9
120	0,18	0,06	363   4,5	186   2,4	260   3,2	133   1,8	208   2,6	106   1,4	156   2	79,7   1,1	104   1,4	53,1   0,9	51,9   0,8	26,6   0,6

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C.

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available.

### Tr 100x32P16 double-thread lifting power in kN

10% : 1 = 3,0mm/R  
32:1 = 1,0mm/R

n <sub>1</sub> min <sup>-1</sup>	lift speed m/min		280		200		150		100		60		40	
	10%:1	32:1	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW	10%:1 Nm   kW	32:1 Nm   kW
1000	3,00	1,00	393   40,4	203   21,2	281   28,8	145   15,1	211   21,6	109   11,3	141   14,4	72,5   7,6	84,2   8,7	43,5   4,6	56,1   4,4	29   3,1
750	2,25	0,75	393   30,3	203   15,9	281   21,6	145   11,4	211   16,2	109   8,6	141   10,8	72,5   5,7	84,2   6,6	43,5   3,5	56,1   3,3	29   2,5
500	1,50	0,50	393   20,2	203   10,6	281   14,4	145   7,6	211   10,8	109   10,7	141   7,2	72,5   3,8	84,2   4,4	43,5   2,4	56,1   2,3	29   1,8
360	1,08	0,36	393   14,6	203   7,6	281   10,4	145   5,6	211   7,8	109   4,2	141   5,2	72,5   2,9	84,2   3,3	43,5   1,9	56,1   1,8	29   1,3
240	0,72	0,24	393   9,7	203   5,2	281   7	145   3,8	211   5,2	109   2,9	141   3,5	72,5   2	84,2   2,2	43,5   1,3	56,1   1,2	29   1,0
120	0,36	0,12	393   4,9	203   2,6	281   3,5	145   2	211   2,6	109   1,5	141   1,9	72,5   1,2	84,2   1,2	43,5   0,8	56,1   0,7	29   0,6

### Technical specifications

max lifting power	350 kN
gear reduction	10%:1 / 32:1
dimension of spindle	Tr100x16 / Tr100x32P16
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	90
weight of spindle per 100mm lifting (kg)	5,2
lubricant	grease
quantity of lubricant (kg)	2,2
max driving power (duty cycle 20%/h)	6,2 kW
max driving power (duty cycle 10%/h)	8,3 kW



# Screw jack SG 0500

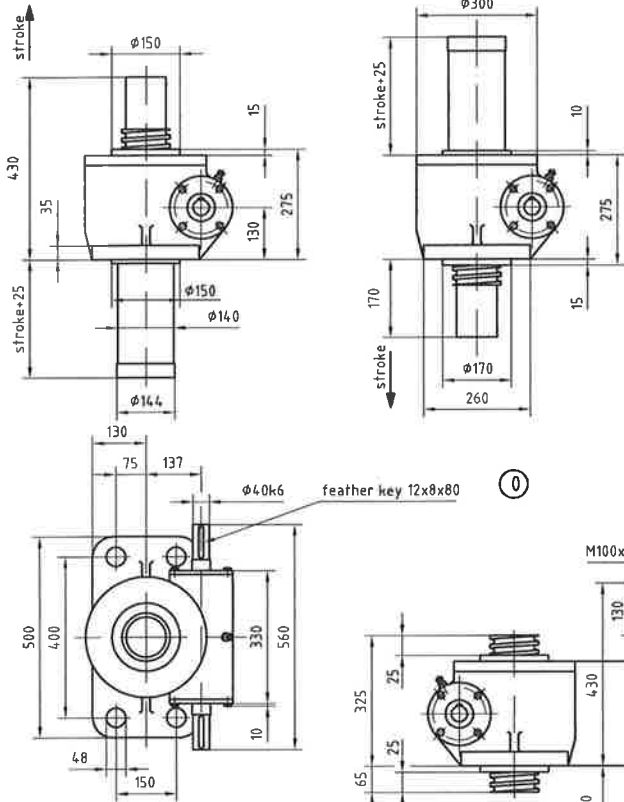
**ENZFELDER GmbH.**

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 Fax.: ++43(0)2256/81287-95  
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 Internet: www.enzfelder.at

## Basic type (G)

above (O)

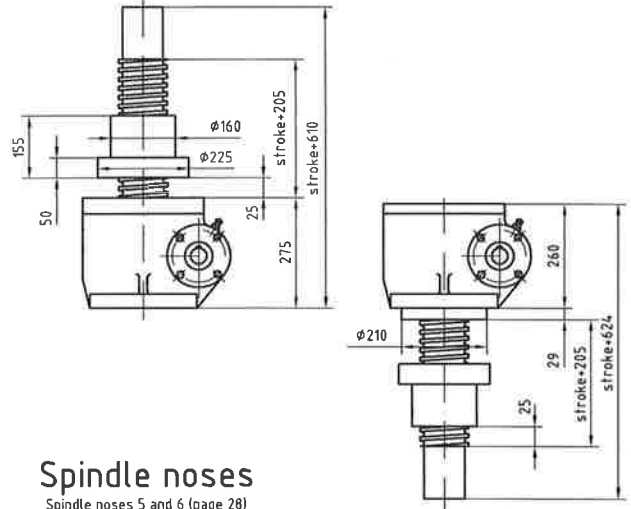
below (U)



## Traveling nut type (L)

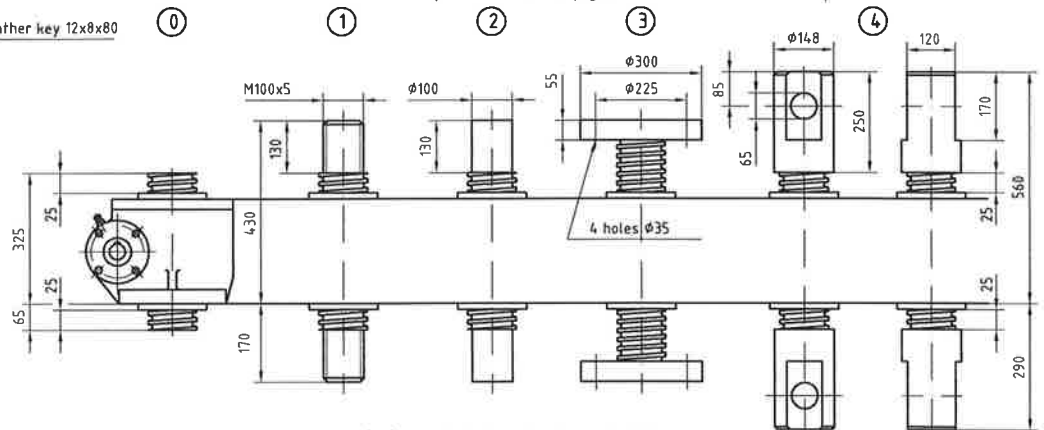
above (O)

below (U)



## Spindle noses

Spindle noses 5 and 6 (page 28)



( ) see order ID on page 5 to 8

Subject to measurement and construction errors.

## Tr 120x16 single-thread lifting power in kN

10% : 1 = 1,5mm/R  
 32:1 = 0,5mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed		500		400		250		200		100		50	
	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1
min <sup>-1</sup>	m/min	m/min	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1000	1,50	0,50	586	61,3	300	31,4	487	4,9	240	25,2	293	30,7	150	15,7
750	1,125	0,375	586	4,6	300	23,6	487	36,8	240	18,9	293	23	150	11,8
500	0,75	0,25	586	30,6	300	15,7	487	24,5	240	12,6	293	15,3	150	7,9
360	0,54	0,18	586	22,1	300	11,3	487	17,7	240	9,1	293	11,1	150	5,7
240	0,36	0,12	586	14,7	300	7,6	487	11,8	240	6,1	293	7,4	150	3,8
120	0,18	0,06	586	7,4	300	3,8	487	6	240	3,1	293	3,8	150	2

RPM, power demand and admissible lifting speed at a reduction of 10:1 and 20:1 single-thread and double-thread spindle actuated, apply to the dynamic lifting power and a 20%/h or 30%/10min duty cycle at 20°C

In the range of the spaces containing italics (above the lines) the spindle gears are overheated, the surface pressure in the thread is too high. We do not furnish a guarantee in this area.

However, it is feasible to transmit higher powers at a reduced duty cycle, or lower powers at a higher temperature (see preselection table, page 4). Please ask for further information.

For lifting speeds higher than those given in the tables, also oil-lubricated ball bearing spindles or special reductions are available

## Tr 120x32P16 double-thread lifting power in kN

10% : 1 = 3,0mm/R  
 32:1 = 1,0mm/R

n <sub>1</sub> min <sup>-1</sup>	lift. speed		400		300		200		150		75		50	
	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1	10%:1	32:1
min <sup>-1</sup>	m/min	m/min	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW	Nm	kW
1000	3,00	1,00	637	65,4	318	32,7	478	4,9	239	24,5	319	32,7	159	16,4
750	2,25	0,75	637	4,9	318	24,5	478	36,8	239	18,4	319	24,5	159	12,3
500	1,50	0,50	637	32,7	318	16,4	478	24,5	239	12,3	319	16,4	159	8,2
360	1,08	0,36	637	23,6	318	11,8	478	17,7	239	8,8	319	11,8	159	5,9
240	0,72	0,24	637	15,7	318	7,8	478	11,8	239	6	319	7,9	159	4
120	0,36	0,12	637	7,8	318	4	478	6	239	3	319	4	159	2,1

## Technical specifications

max. lifting power	500 kN
gear reduction	10%:1 / 32:1
dimension of spindle	Tr120x16 / Tr120x32P16
start-up moment	table entry x 1,3
casing material	GJS400-15
weight without lifting (kg)	180
weight of spindle per 100mm lifting (kg)	7,7
lubricant	grease
quantity of lubricant (kg)	3,3
max. driving power (duty cycle 20%/h)	7,8 kW
max. driving power (duty cycle 10%/h)	10,8 kW



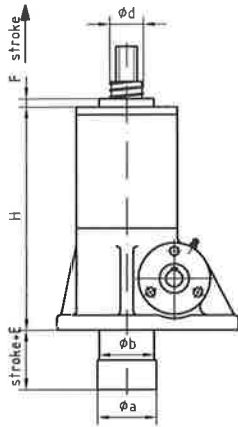
# Ball screw jack Swinging elements

**ENZFELDER GmbH.**

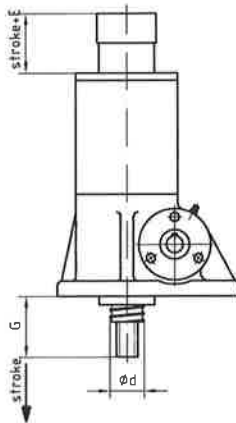
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Fax.:++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

## Basic type, ball-screw actuated (KSG)

above (O)



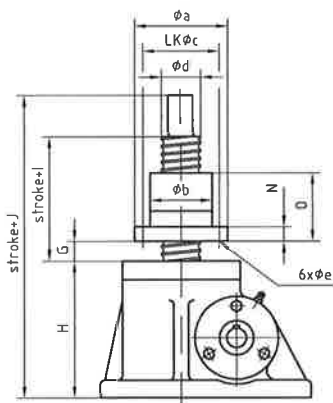
below (U)



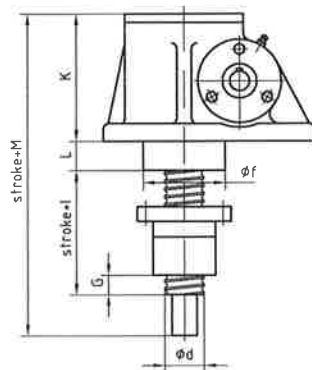
Exakt dimensions after consulting by the factory!

## Traveling nut type, ball-screw actuated (KSG)

above (O)

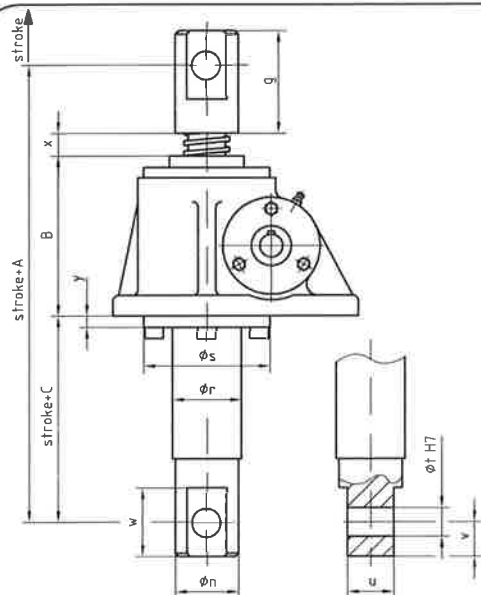


below (U)



Exakt dimensions after consulting by the factory!

## Swinging element (SE)



SE	0005	0015	0020	0030	0050	0100	0150	0200	0240	0300	0500
A	stroke+180	stroke+215	stroke+247	stroke+250	stroke+320	stroke+350	stroke+390	stroke+432	stroke+475	stroke+502	stroke+762
B	74	90	103	106	140	150	160	187	210	222	282
C	stroke+61	stroke+75	stroke+82	stroke+82	stroke+100	stroke+110	stroke+130	stroke+140	stroke+150	stroke+160	stroke+265
g	50	50	65	65	90	100	120	130	140	155	250
phi_n	30	35	40	40	55	65	80	85	95	108	148
phi_r	28	36	45	45	60	70	80	90	110	127	150
phi_s	59	65	80	80	110	120	140	160	180	190	240
phi_t H7	15	15	15	15	25	30	35	40	45	50	65
u	20	25	30	30	40	50	60	65	75	80	120
v	15	15	23	23	30	30	45	50	50	60	85
w	30	35	46	46	60	70	90	100	110	120	170
x	10	20	20	20	20	20	25	25	25	25	50
y	8	10	10	10	10	12	15	20	20	20	25

Special types available on request

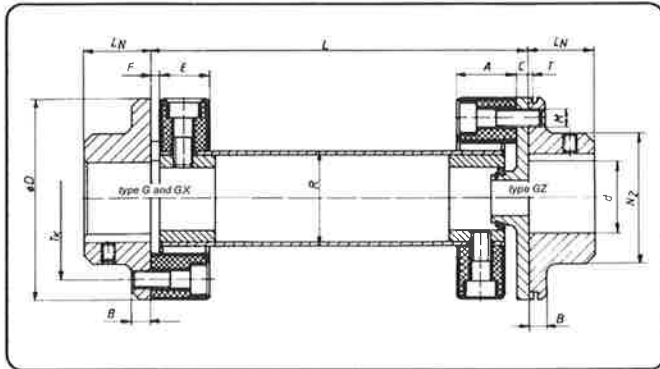


# Elastic Cardan Shafts, Pedestal Bearings, Flange Bearings

**ENZFELDER** GmbH.

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## Elastic propeller shafts G/GX/GZ

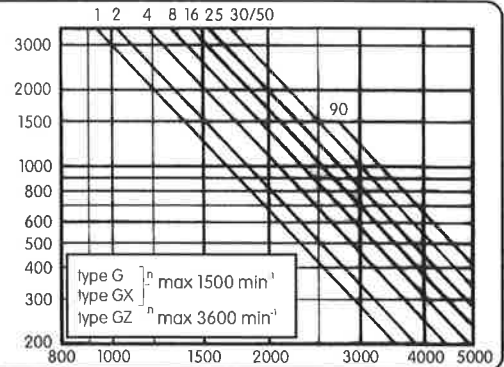


RPM - length -  
diagram:

Selection chart for  
sizes according to  
RPM and length of  
joint

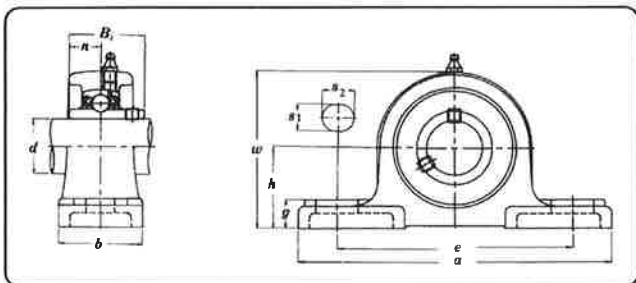
RPM n  
(min<sup>-1</sup>)

length L  
(mm)



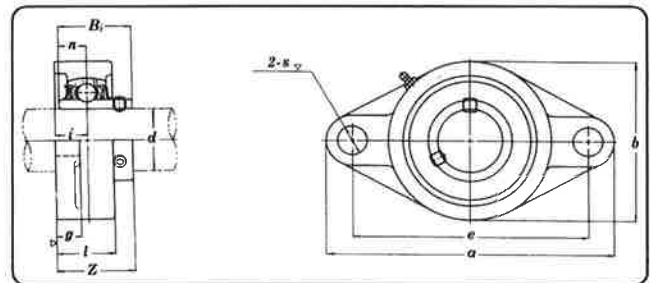
size	rated torque (Nm) type			weight (kg)		max. shift of angle		A	B	C	∅ D	d	d max	E	F	L <sub>h</sub>	∅ N <sub>2</sub>	R	T	T <sub>x</sub> /M
	G	GX	GZ	for 2 hubs	for 1 m tube	G+GZ	GX													
1	10	10	10	1,0	1,1	3°	1°	24	7	5	56	8	25	22	2	24	36	30	1,5	∅ 44 / 2 x M6
2	20	30	20	2,2	1,4	3°	1°	24	8	5	85	12	38	20	4	28	55	40	1,5	∅ 68 / 2 x M8
4	40	60	40	3,4	1,6	3°	1°	28	8	5	100	15	45	24	4	30	65	45	1,5	∅ 80 / 3 x M8
8	80	120	80	7,3	2,2	3°	1°	32	10	5	120	18	55	28	4	42	80	60	1,5	∅ 100 / 3 x M10
16	160	240	160	12,4	2,5	3°	1°	42	12	5	150	20	70	36	6	50	100	70	1,5	∅ 125 / 3 x M12
25	250	370	250	19,1	3,1	3°	1°	46	14	5	170	20	85	40	6	55	115	85	1,5	∅ 140 / 3 x M14
30	400	550	400	31,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	∅ 165 / 3 x M16
50	600	-	600	32,1	4,8	3°	1°	58	16	5	200	25	100	50	8	66	140	100	1,5	∅ 165 / 3 x M16
90	900	-	900	58,7	7,6	3°	1°	70	19	5	260	30	110	62	8	80	160	125	2,0	∅ 215 / 3 x M20

## Pedestal bearing



Type	∅ d (mm)	Dimensions (mm)								Bolt Used (mm)	Weight (kg)	
		h	a	e	b	s <sub>1</sub>	s <sub>2</sub>	g	w			n
UCP 205	25	36,5	140	105	38	19	13	13	71	14,3	10	0,8
UCP 206	30	42,9	165	121	48	21	17	15	84	15,9	14	1,3
UCP 207	35	47,6	167	127	48	21	17	16	93	17,5	14	1,6
UCP 208	40	49,2	184	137	54	21	17	17	98	19,0	14	2,0
UCP 209	45	54,0	190	146	54	21	17	17	106	19,0	14	2,2
UCP 210	50	57,2	206	159	60	22	20	19	113	19,0	16	2,9
UCP 212	60	69,8	241	184	70	25	20	22	138	25,4	16	4,9
UCP 214	70	79,4	266	210	72	30	25	28	156	30,2	20	6,8
UCP 216	80	88,9	292	232	78	35	25	32	174	33,3	20	9,0
UCP 217	85	95,2	310	247	83	40	25	32	185	34,1	20	10,8

## Flange bearing



Type	∅ d (mm)	Dimensions (mm)								Weight (kg)		
		a	e	i	g	f	s	b	Z		Bi	n
UCFL 201	12	113	90	15	11	25,5	12	60	33,3	31,0	12,7	0,48
UCFL 203	17	113	90	15	11	25,5	12	60	33,3	31,0	12,7	0,48
UCFL 204	20	113	90	15	11	25,5	12	60	33,3	31,0	12,7	0,48
UCFL 205	25	130	99	16	13	27	16	68	35,7	34,0	14,3	0,64
UCFL 207	35	161	130	19	14	34	16	90	44,4	42,9	17,5	1,2
UCFL 208	40	175	144	21	14	36	16	100	51,2	49,2	19,0	1,6
UCFL 210	50	197	157	22	15	40	19	115	54,6	51,6	19,0	2,2
UCFL 212	60	250	202	29	18	48	23	140	68,7	65,1	25,4	4,2
UCFL 214	70	265	216	31	20	54	23	160	75,4	74,6	30,2	5,7
UCFL 216	80	290	233	34	20	58	25	180	83,3	82,6	33,3	7,8

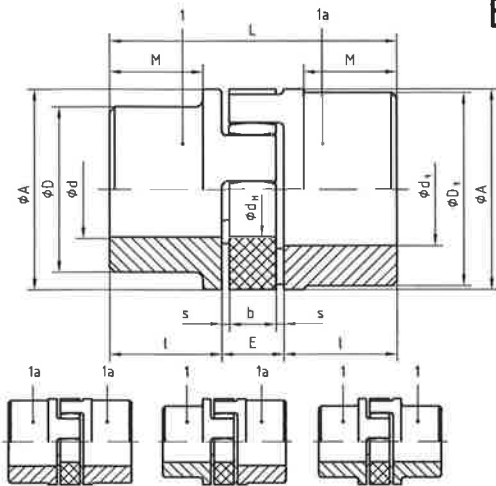


# Couplings, expansion bellows

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## Elastic couplings (KU)



Type R	Mt nom in Nm at 80° Shore <sup>1)</sup>	Mt nom in Nm at 92° Shore <sup>1)</sup>	Mt nom in Nm at 98° Shore <sup>1)</sup>	holes pilot drill	hub 1 finished φd min max	holes pilot drill	hub 1a finished φd1 min max	φA	φD	φD1	L	l	E	s	b	M	φd <sub>h</sub>	material	weight <sup>3)</sup> type 1 in kg	weight <sup>3)</sup> type 1a in kg
14	4	7	12	- 4 14	- - -	30 30	- 35 11 13 1,5 10	- 10										aluminium or GG	0,14	0,14
19/24	5	10	17	4 6 19	- 6 24	40 32 40	66 25 16 2 12 - 18												0,32	0,36
24/28	17	35	60	6 8 24	6 8 28	55 40 48	78 30 18 2 14 24 27												0,60	0,72
28/38	46	95	160	8 10 28	8 10 38	65 48 65	90 35 20 2,5 15 28 30												0,97	1,33
38/45	93	190	325	10 12 38	36 38 45	80 66 77	114 4,5 24 3 18 37 38												2,08	2,46
42/55	130	265	450	12 14 42	40 42 55	95 75 94	126 50 26 3 20 40 46												3,21	3,93
48/60	150	310	525	13 15 48	46 48 60	105 85 102	140 56 28 3,5 21 45 51												4,41	5,19
55/70	180	375	625	18 20 55	52 55 70	120 98 120	160 65 30 4 22 52 60												6,64	8,10
65/75 <sup>2)</sup>	205	425	640	20 22 65	63 65 75	135 115 135	185 75 35 4,5 26 61 68											GG	10,13	11,65
75/90 <sup>2)</sup>	475	975	1465	28 30 75	73 75 90	160 135 160	210 85 40 5 30 69 80												16,03	19,43

Finish-borings are made according to the ISO system of tolerances H7. Feather key grooves are made according to DIN 6885/1. The max. angle shift is 1°30', the twisting angle 3,2° at Mt nom. The operable temperature range lies between -40°C and +100°C.

<sup>1)</sup> The rated turning moments are valid for normal operation with slight jolts; due to the higher start-up moment of three-phase squirrel cage motors an impact factor of 2 must be taken into account.  
<sup>2)</sup> from size 65/75 95° Shore on  
<sup>3)</sup> weight for GG, aluminium approx. 60% less.

Product as delivered: enclosed

## Expansion bellows (FB)

basic type

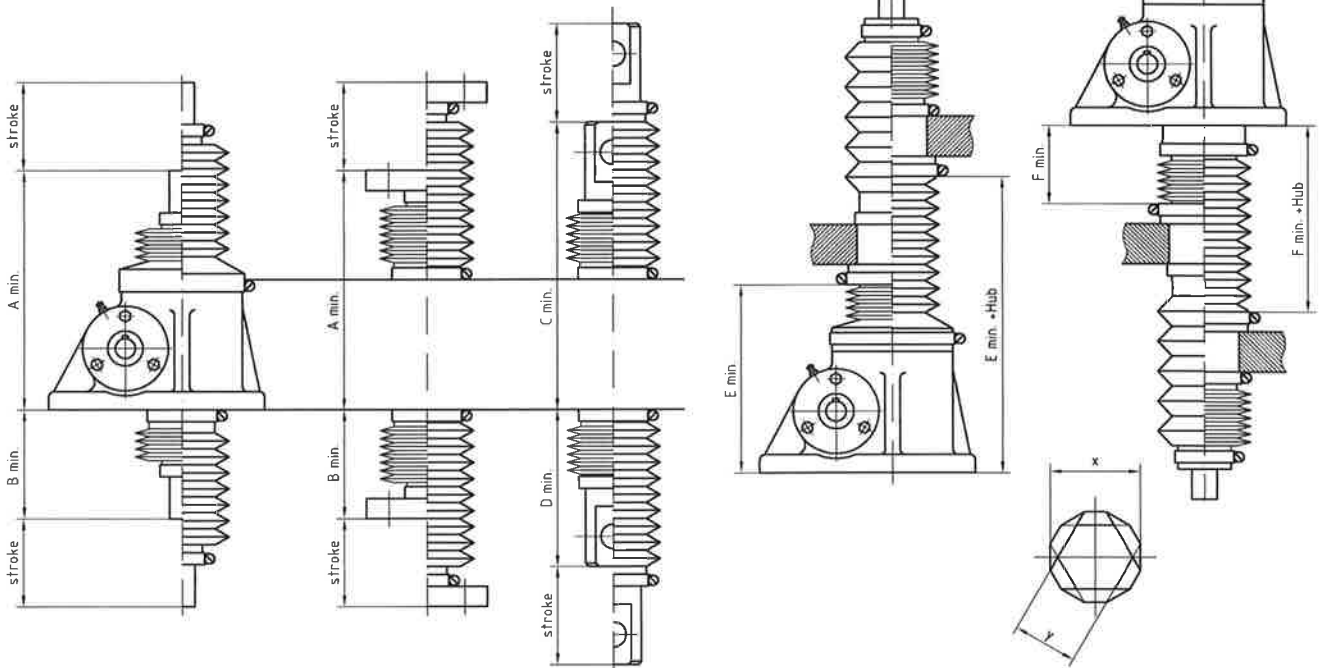
traveling nut type

spindle noses

①/②

③

④



SG	0005	0015	0020	0030	0050	0100	0150	0200	0240	0300	0350	0500
A min.	106+0,15xstroke	130+0,15xstroke	156+0,15xstroke	157+0,15xstroke	202+0,15xstroke	215+0,15xstroke	235+0,15xstroke	274+0,15xstroke	300+0,15xstroke	312+0,15xstroke	355+0,15xstroke	455+0,15xstroke
B min.	37+0,15xstroke	50+0,15xstroke	62+0,15xstroke	62+0,15xstroke	72+0,15xstroke	75+0,15xstroke	85+0,15xstroke	97+0,15xstroke	100+0,15xstroke	100+0,15xstroke	115+0,15xstroke	195+0,15xstroke
C min.	134+0,15xstroke	160+0,15xstroke	189+0,15xstroke	190+0,15xstroke	250+0,15xstroke	270+0,15xstroke	305+0,15xstroke	342+0,15xstroke	365+0,15xstroke	402+0,15xstroke	455+0,15xstroke	575+0,15xstroke
D min.	65+0,15xstroke	80+0,15xstroke	95+0,15xstroke	95+0,15xstroke	120+0,15xstroke	130+0,15xstroke	155+0,15xstroke	165+0,15xstroke	175+0,15xstroke	190+0,15xstroke	215+0,15xstroke	315+0,15xstroke
E min.	84+0,15xstroke	110+0,15xstroke	124+0,15xstroke	125+0,15xstroke	160+0,15xstroke	170+0,15xstroke	185+0,15xstroke	212+0,15xstroke	235+0,15xstroke	247+0,15xstroke	280+0,15xstroke	325+0,15xstroke
F min.	28+0,15xstroke	40+0,15xstroke	44+0,15xstroke	44+0,15xstroke	50+0,15xstroke	52+0,15xstroke	59+0,15xstroke	64+0,15xstroke	70+0,15xstroke	77+0,15xstroke	77+0,15xstroke	79+0,15xstroke
x	75	75	75	105	105	125	125	140	140	150	180	210
y	38	38	38	63	63	75	75	100	100	110	120	150

This chart is valid for closed rooms at a normal ambient temperature. In case of deviations please inquire.

Product as delivered: enclosed

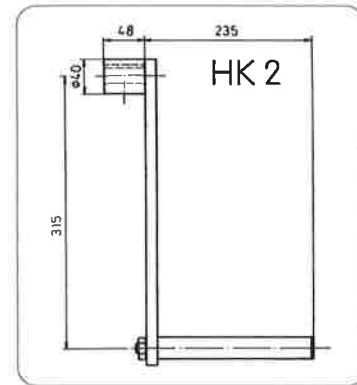
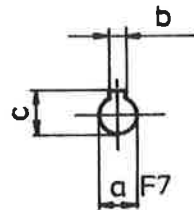
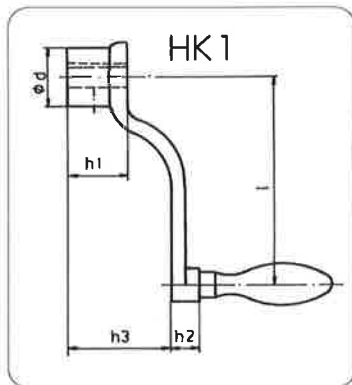


# Crank Handles, Handwheels

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## Crank handles (HK)



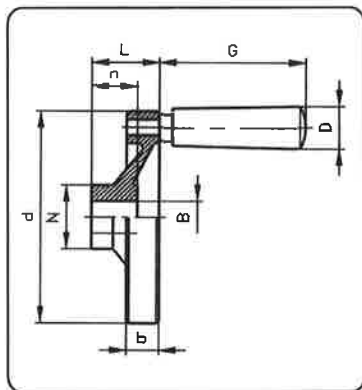
HK 1

SG	0005	0010	0015	0020	0030	0050	0100
a F 7	10	14	14	14	16	20	24
b P 9	3	5	5	5	5	6	8
c	11,4	16,3	16,3	16,3	18,3	22,8	27,3
d	28	38	38	38	38	44	48
h1	28	38	38	38	38	44	48
h2	13	14	14	14	14	21	21
h3	48	65	65	65	65	78	90
l	100	160	160	160	160	200	250

HK 2

SG	0150	0200
a F 7	25	28
b P 9	8	8
c	28,3	31,3

Dimensional variations according  
to DIN 7168 medium.  
Deviating dimensions on  
request.



## Hand wheels (HR)

type	d	N	b	n	l	G	D	Pilot drill H7	Weight kg
SG 0005	80	26	13,0	16	30	58,5	22	10	0,16
SG 0010, 0015 0020, 0030	125	31	15,0	18	34	67,5	23	14	1,3
SG 0030, 0050	160	36	18,0	20	37	67,5	23	14	1,5
SG 0050, 0100	200	42	20,5	24	45	80,0	26	18	1,0
SG 0100, 0150	250	48	23,0	28	51	90,0	28	24	1,3

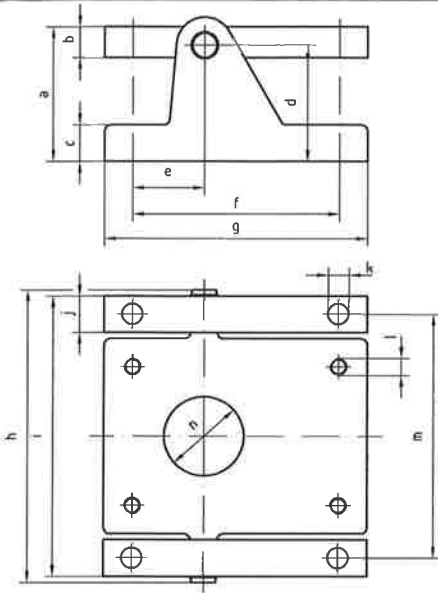


# Swivelling console, Limit stop, Turn-lock device

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## Swivelling console (SK)



SG	0005	0015	0030	0050	0100	0150	0200	0240	0300	0350	0500
a	50	67,5	90	110	110	150	160	155	170	210	200
b	10	15	25	30	35	45	50	55	60	65	80
c	8	15	20	30	30	30	40	40	50	60	80
d	45	60	77,5	95	92,5	127,5	135	127,5	140	177,5	160
e	30	37,5	50	58	60	63,5	95	90	95	135	175
f	60	110	135	168	180	190	240	260	280	360	350
g	70	135	165	215	225	237	297	320	355	430	440
h	150	150	190	240	270	297	322	344	411	424	685
i	144	140	180	230	260	285	310	330	395	410	670
j	10	15	25	30	30	35	40	40	60	60	80
k	6	9	13	18	18	21	26	26	35	35	48
l	M8	M8	M12	M16	M16	M20	M24	M24	M30	M30	M42
m	134	125	155	200	230	250	270	290	335	350	590
n	45,2	48,2	60,2	83,2	95,2	110,2	140,2	150,2	160,2	170,5	210,5

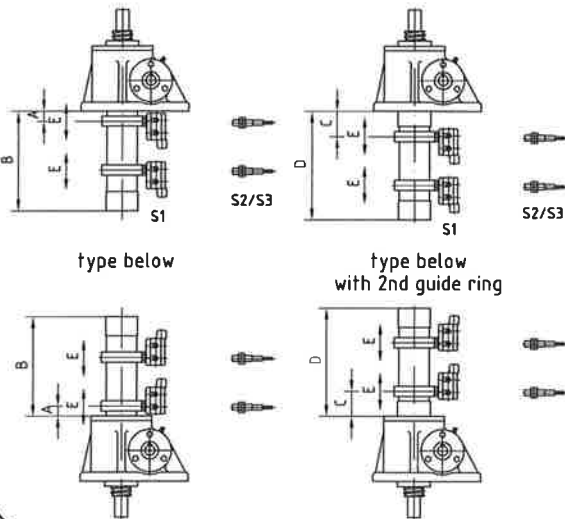
Special executions on request

Product as delivered: enclosed

type above

type above  
with 2nd guide ring

## Limit stop (EAS)

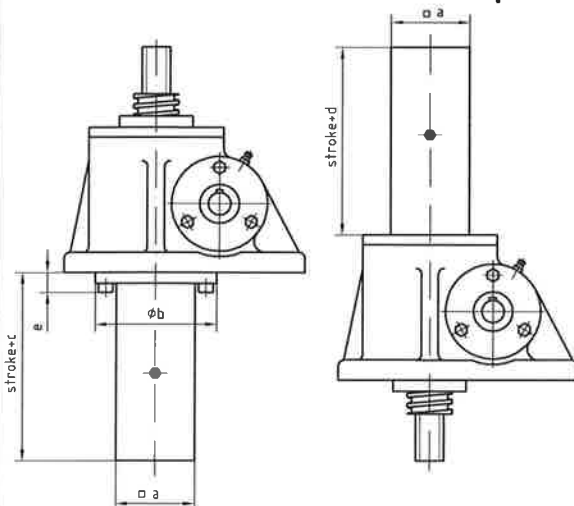


	A	B	C	D
SG 0005	32	stroke+95	47	stroke+119
SG 0015	32	stroke+105	57	stroke+130
SG 0020	32	stroke+105	57	stroke+130
SG 0030	32	stroke+105	62	stroke+135
SG 0050	32	stroke+105	62	stroke+135
SG 0100	32	stroke+105	62	stroke+135
SG 0150	32	stroke+105	58	stroke+131
SG 0200	32	stroke+105	67	stroke+140
SG 0240	32	stroke+105	72	stroke+145
SG 0300	32	stroke+105	72	stroke+145
SG 0350	32	stroke+105	77	stroke+150
SG 0500	-	-	45	stroke+120

Limit switches must be adjusted in situ!  
Product as delivered: enclosed

limit switch type	S1	S2	S3
current max. at 250V	0,25A	220mA	-
voltage 120V	0,5A	500mA	-
24V	7A	1A	1A
type of connection	binding posts	cable 3x0,5mm <sup>2</sup> 1m length	cable
setting range E	±15	the entire range	the entire range
temperature min/max	-10°C +80°C	-5°C +70°C	-25°C +70°C
system of protection	IP 65	IP 67	IP 65
type of switch	mech.	magnet	inductive

## Square turn-lock device (VV)



SG	0005	0015	0020 0030	0050	0100	0150	0200	0240 0300	0350	0500
□ a	30	40	40	70	80	90	110	120	140	180
φ b	59	70	70	108	116	129	148	177	197	240
c	stroke+67	stroke+92	stroke+92	stroke+106	stroke+112	stroke+115	stroke+121	stroke+132	stroke+137	stroke+158
d	stroke+60	stroke+77	stroke+77	stroke+90	stroke+90	stroke+100	stroke+110	stroke+110	stroke+115	stroke+158
e	11	14	14	18	20	22	22	26	26	26

A turn-lock device comprised of a grooved spindle and feather key is also available on request.

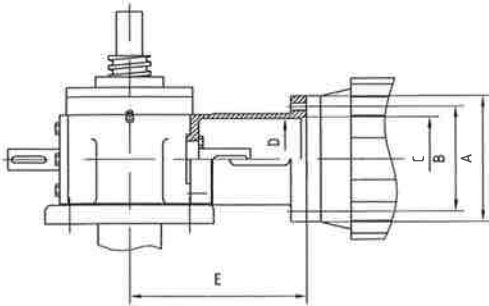


# Motor flanges, Safety nuts

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## Motor flanges (M)

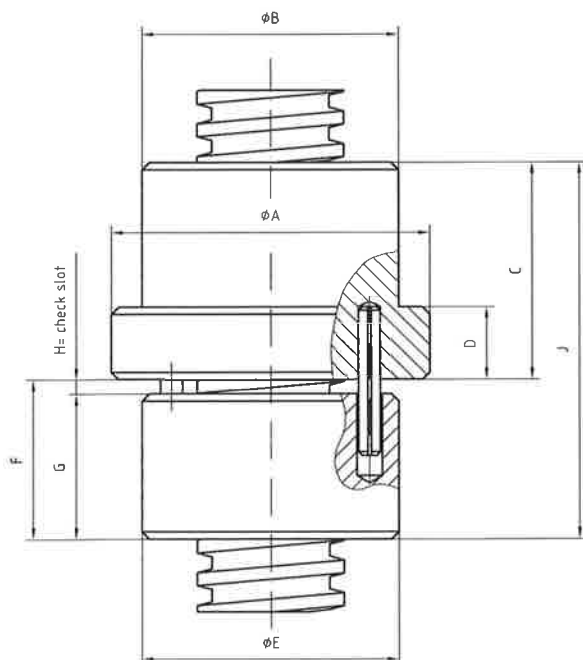


	type of motor	flange φA	φB	φC	φD	E	shaft ends φ SG	motor	4 pieces bolts DIN 912 for motor
SG 0005	56 B14	80	65	50	44	93	10	9	M5 x 16
	63 B14	90	75	60	44	96	10	11	M5 x 20
	71 B14	105	85	70	44	103	10	14	M6 x 25
SG 0015	63 B14	90	75	60	52	114	14	11	M5 x 20
	71 B14	105	85	70	52	119	14	14	M6 x 25
	80 B14	120	100	80	52	131	14	19	M6 x 25
SG 0030	71 B14	105	85	70	61	136	16	14	M6 x 25
	80 B14	120	100	80	61	146	16	19	M6 x 25
	90 B14	140	115	95	61	156	16	24	M8 x 25
SG 0050	80 B14	120	100	80	77	171	20	19	M6 x 25
	90 B14	140	115	95	76	181	20	24	M8 x 25
	100 B14	160	130	110	76	193	20	28	M8 x 25
SG 0100	112 B14	160	130	110	76	193	20	28	M8 x 25
	90 B14	140	115	95	83	192	24	24	M8 x 25
	100 B14	160	130	110	80	203	24	28	M8 x 25
SG 0150	112 B14	160	130	110	80	203	24	28	M8 x 25
	132 B14	200	165	130	80	225	24	38	M10 x 30
	100 B14	160	130	110	84	218	25	28	M8 x 25
SG 0200	112 B14	160	130	110	84	218	25	28	M8 x 25
	132 B14	200	165	130	84	240	25	38	M10 x 30
	132 B14	200	165	130	100	263	28	38	M10 x 30
SG 0240	160 B5	350	300	250	100	307	28	42	M16 x 60 + 4 nuts
	132 B14	200	165	130	108	270	32	38	M10 x 30
SG 0300	160 B5	350	300	250	108	304	32	42	M16 x 60 + 4 nuts
	132 B14	200	165	130	114	278	34	38	M10 x 30
SG 0350	160 B5	350	300	250	114	312	34	42	M16 x 60 + 4 nuts
	160 B5	350	300	250	130	349	38	42	M16 x 60 + 4 nuts
SG 0500	180 B5	350	300	250	130	351	38	48	M16 x 60 + 4 nuts
	160 B5	350	300	250	150	414	40	42	M16 x 60 + 4 nuts
	180 B5	350	300	250	150	416	40	48	M16 x 60 + 4 nuts

**Important:**

Unless otherwise requested by the customer, motor flanges are mounted on the right, as shown above!  
Engines and fastening bolts are delivered non mounted.

## Safety nuts (SI0)



SG	0005	0010 0015	0020 0030	0050	0100	0150	0200	0240	0300	0350	0500
φA	50	60	76	87	98	110	120	130	155	188	225
φB	40	40	50	70	75	90	90	100	130	150	160
C	32	35	40	60	70	75	100	110	120	145	155
D	10	15	20	20	25	25	30	30	35	35	50
φE	40	38	50	70	73	85	90	98	120	145	160
F	23	25	33	44	56	66	71	80	98	108	128
G	20	22	30	40	50	60	65	73	90	100	120
H	<b>3</b>	<b>3</b>	<b>3</b>	<b>4</b>	<b>6</b>	<b>6</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>8</b>	<b>8</b>
J	55	60	73	104	126	141	171	190	218	253	283

Connected with the loaded traveling nut via driving pins, the locking nut runs at idle. As the threads in the traveling nut wear, it approaches the idling, unloaded and therefore unworn safety nut. The wear is ascertained by checking the slot H. When the table entry H has declined by half of the traveling nut must be replaced!

The visual check of the slot H can be automated by integrating an automatic disconnecting limit switch which is actuated when the traveling nut sinks.

Also available for the basic type  
Standard sheet on request

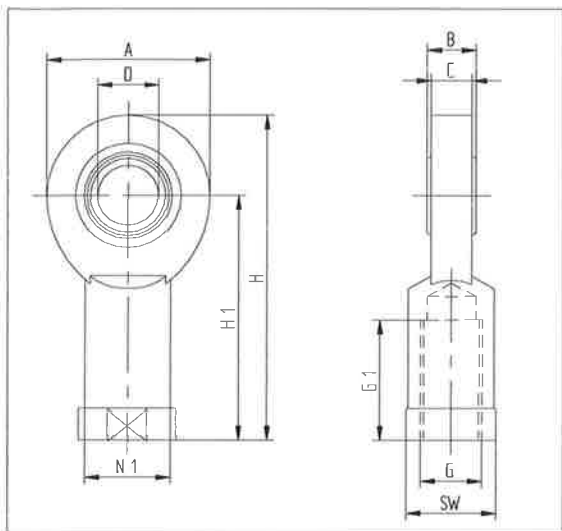
Product as delivered: enclosed





# Pivoting Heads, Fork Heads, Critical Speed

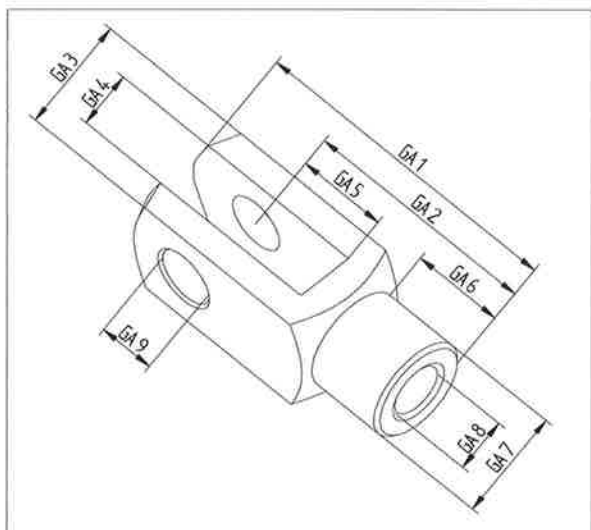
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## Pivoting heads

Type	A	B	C	D	G	G1	H	H1	SW	N1
SG 0005	34	10	8,5	12	M12	18	67	50	18	19
SG 0010	40	12	10,5	15	M14	21	81	61	21	21
SG 0015	40	12	10,5	15	M14	21	81	61	21	21
SG 0020	46	14	11,5	17	M16	24	90	67	27	25
SG 0030	53	16	13,5	20	M20 x 1,5	30	103,5	77	30	28
SG 0050	73	22	20	30	M30 x 3	45	146,5	110	46	42
SG 0100	82	25	22	35	M36 x 3	60	166	125	55	48
SG 0150	92	28	24	40	M39 x 3	65	188	142	60	52
SG 0200	112	35	31	50	M45 x 3	68	216	130	70	62
SG 0240	112	35	31	50	M45 x 3	68	216	130	70	62
SG 0300	135	44	39	60	M52 x 3	70	242,5	175	80	70
SG 0350	160	49	43	70	M56 x 4	80	280	200	85	80
SG 0500	180	55	48	80	M64 x 4	85	320	230	95	95

Special versions on request



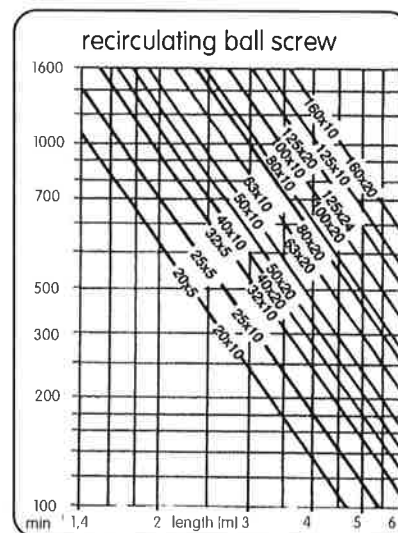
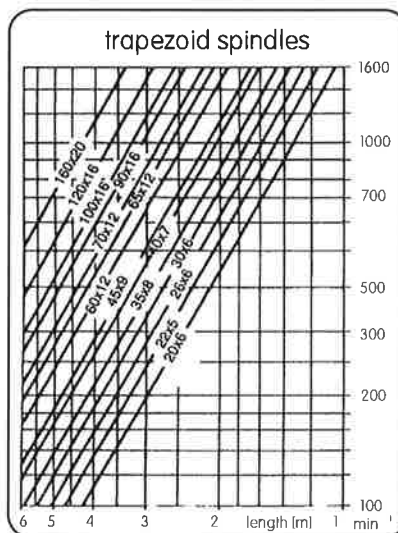
## Fork heads

Type	GA 1	GA 2	GA 3	GA 4	GA 5	GA 6	GA 7	GA 8	GA 9
SG 0005	62	48	24	12	24	18	20	M12	12
SG 0010	72	56	27	14	28	22,5	24	M14	14
SG 0015	72	56	27	14	28	22,5	24	M14	14
SG 0020	83	64	32	16	32	24	26	M16	16
SG 0030	105	80	40	20	40	30	34	M20	20
SG 0050	148	110	60	30	60	40	48	M30	30
SG 0100	188	144	72	36	72	54	60	M36	36
SG 0150	265	192	96	50	96	73	82	M45 x 2	50
SG 0200	-	-	-	-	-	-	-	-	-
SG 0240	-	-	-	-	-	-	-	-	-
SG 0300	-	-	-	-	-	-	-	-	-
SG 0350	-	-	-	-	-	-	-	-	-
SG 0500	-	-	-	-	-	-	-	-	-

Special versions on request

## Critical speed

In the L execution the critical speed depends on diameter and length of the spindle and on the spindle bearing arrangement.  
 The basis is a fixed bearing arrangement in the transmission case of the screw jacks and a single-row movalbe bearing arrangement at the spindle nose. If no movable bearing arrangement is available, the admissible RPMs of the spindle are reduced to: TPM = table entry x 0,2.



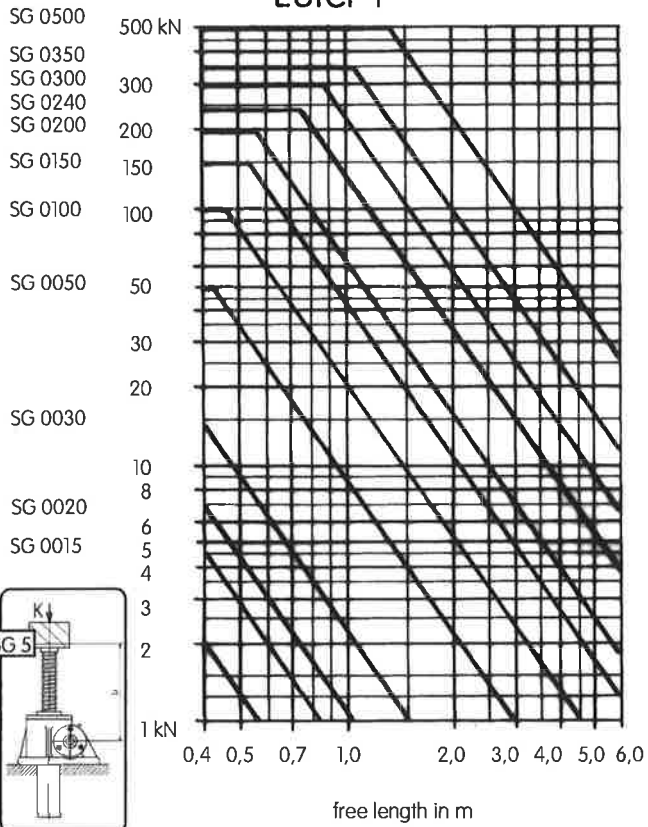


# Critical Buckling Force

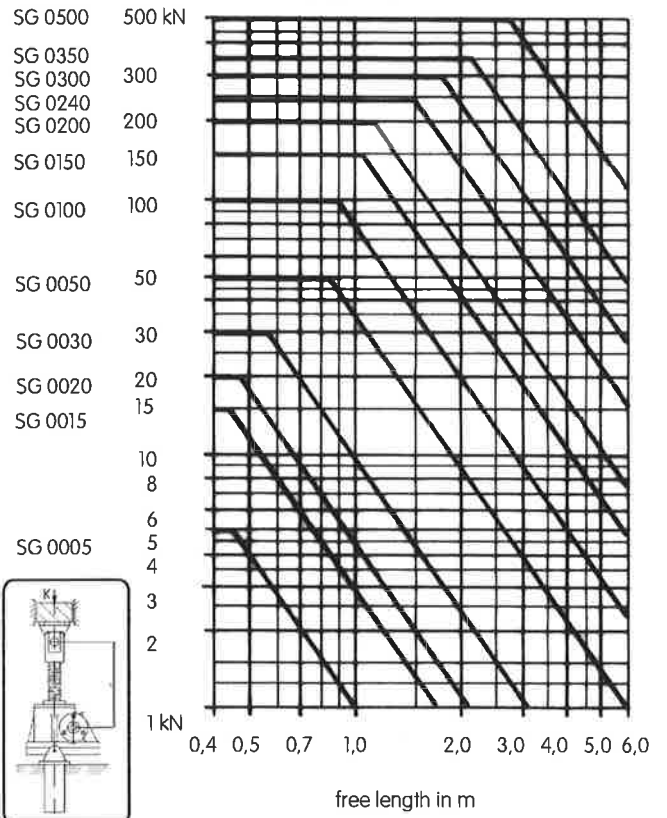
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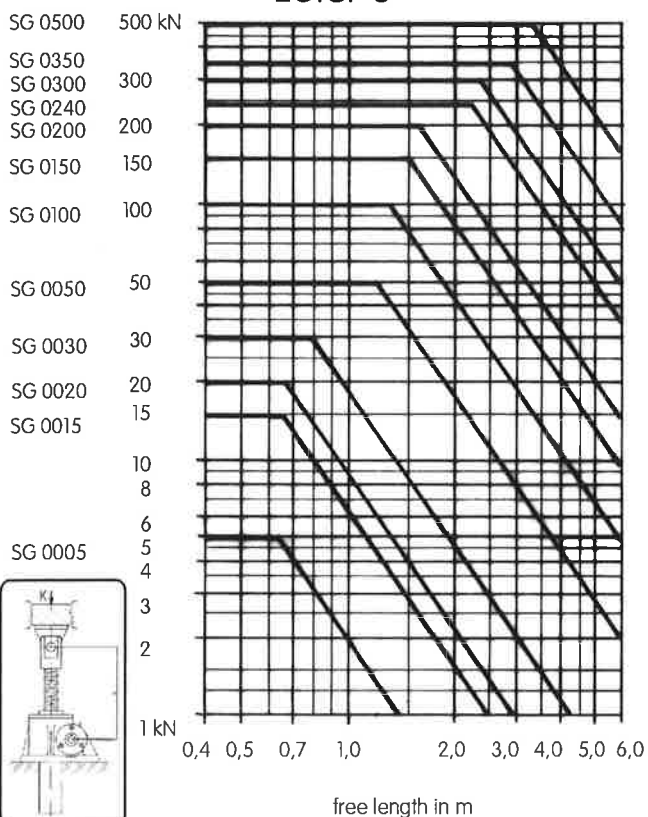
## Euler 1



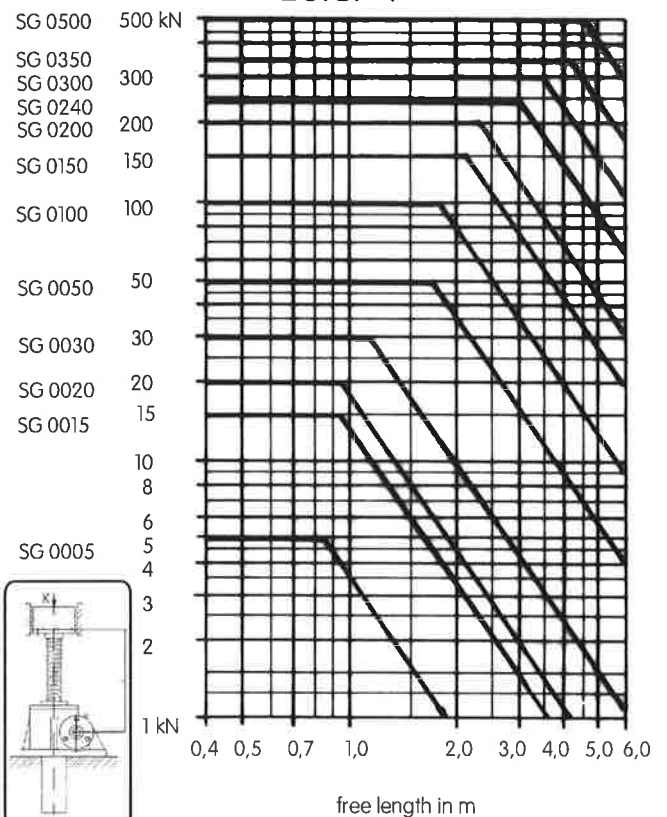
## Euler 2



## Euler 3



## Euler 4





# Calculations

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## Symbols:

F (kN)	= dynamic load	$P_{SG}$ (kW)	= operating performance of the screw jack
v (m/min)	= lifting speed	$P_{ges}$ (kW)	= operating performance of all screw jacks
s (mm)	= spindle pitch	$P_{Ant}$ (kW)	= operating performance of the system
n (R/min)	= revolutions/min at the worm	$\eta_{ges}$	= operating efficiency (preselection table page 4)
i	= worm gear reduction	$\eta_{Ant}$	= efficiency of the system
$f_M$	= factor for spindle load torque	$M_{sp}$ (Nm)	= spindle load torque
		M (Nm)	= load torque at the worm

## Driving power:

If the required driving power cannot be read sufficiently clear from the preselection and performance charts, it is computed as follows:

Driving power  $P_{SG}$  per spindle gear: 
$$P_{SG} = \frac{F \times v}{61,2 \times \eta_{ges}}$$

## Driving power $P_{ges}$ all of multiple spindle systems:

After adding the individual performances  $P_{SG}$  to reach the total performance  $P_{ges}$ , the losses of spacer shafts, bevel gears, couplings, pedestal bearings, alignment errors etc. must be allowed for.

Standard value in case of 2 screw jacks	$\eta$ 0,95	$P_{Ant} = \frac{P_{ges}}{\eta_{Ant}}$
3 screw jacks	$\eta$ 0,90	
4 screw jacks	$\eta$ 0,85	
6-8 screw jacks	$\eta$ 0,80	

## Starting capacity:

To compute the starting capacity the performance value  $P_{SG}$  or  $P_{Ant}$  is multiplied by 1.3.

## Ambient temperature:

At an ambient temperature higher than +20°C the operating factor must be reduced in correspondence with the following table.

Ambient temperature °C	50	60	70	80
max. possible duty cycle in %/h	18	15	10	5
max. possible duty cycle in %/10min	27	22	15	8

## Load torque at the worm:

$$M = \frac{F \times s}{2 \times \pi \times i \times \eta_{ges}} \qquad M = \frac{9550 \times P_{SG}}{n}$$

## Spindle load torque:

The spindle load torque  $M_{sp}$  is the load torque acting on the various parts of the system via the spindle noses 3,4 or the traveling nut. The spindle load torque can be computed with the help of the  $f_M$  factor in the table below.

$$F \times f_M = M_{sp}$$

	SG	0005	0010	0015	0020	0030	0050	0100	0150	0200	0240	0300	0350	0500
$f_M$ SG single-thread		1,87	1,81	2,07	2,17	2,42	3,29	4,5	4,84	5,0	5,8	6,98	7,5	8,5
$f_M$ SG double-thread		2,85	2,57	3,06	3,16	3,35	4,77	6,47	6,7	6,95	8,1	9,43	10,0	11,1
$f_M$ KSG						1,67	1,67		3,35					



# Mounting and maintenance instructions for Screw jacks SG 0005 - SG 0500 Grease Lubricated

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## Mounting

Spindle gears must be mounted in true alignment on a flat surface which must be so stiff that it can assume the maximal load without oscillations or deformations.

Align the screw jack and spindle with a machine spirit level and bolt them into place (do not tighten yet).

In lifting systems the spindle noses (in case of the basic type) or the traveling nuts (in case of the traveling nut type) must lie even with each other before the worms of the spindle gears are connected.

Before the driving gear is mounted the sense of rotation must be checked: in bevel gear driven lifting systems the sense of rotation can easily be confused; the result would be faulty mounting and possible damage of the installation.

Ensure that the spindle is parallel to any guidance. Use the position with the least amount of play between the screw jack element and the guidance as the point of reference.

Only when the spindle runs lightly and evenly over the entire stroke, can the mounting screws can be tightened and if necessary the screw jacks additionally pinned. An increased power requirement and increased temperatures are indicative of abnormal lateral forces.

Clean the spindle and re-lubricate it along the entire stroke length.

Attention! Misalignment and faulty gripping lead to increased power consumption, which is converted into friction and noise. The consequence is quick wear.

Additional add-on pieces: check under "Options".

If our specifications and performances according to the technical instructions are not observed and/or the components are not used as prescribed, any warranty claims will no longer be applicable.

## Maintenance

Screw jacks are filled with the greasing AGIP GRS M2 in the factory.

Grease the spindle and all lubricating nipples at regular intervals (~ 30-50 operating hours). The intervals depend on the given operating conditions and the duty cycle of the screw jacks. In case doubt please set up the lubrication plan together with us. After approx. 200-300 operating hours the wear of the traveling nut or the worm wheel due to the backlash of threads should be checked. The maximal normal backlash of single trapezoid threads must not exceed 1/4 of the thread pitch. In the cases of multiple threads or special threads 1/4 of P is the maximum normal acceptable backlash. When the maximum normal backlash is reached the traveling nut or the worm wheel must be replaced. After a short run-in period all screws must be checked.

After approx. 500 operating hours we recommend cleaning gear and spindle to remove the grease, checking all piece parts as to wear, and recharging them with new grease.

Recommended lubricants: Shell Darina 2, Castrol Grease MS3, BP Energlease LS-EP2.

The lubricant recommended can be used both for gears and spindles. If a high-grade spindle lubricant is to be used, we recommend Klüberplex GE 11-680.

For special conditions (e.g. higher temperatures) we recommend the lubricants specified in the enclosed technical manual.

In case of possible dirt accumulation in or damage of the spindle, expansion bellows or spring steel spirals must be used to protect the spindle. For oil-lubricated gears please ask for a special service manual.

If you order spare parts, the gear specifications marked on the type plate must be provided.

For more information apply for the detailed installation instructions in the company.



# Tolerances

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## 1.) External dimensions

For connecting dimensions the tolerances given in the corresponding drawings are valid. The values where no tolerance is indicated are not tolerated dimensions.

## 2.) The lateral backlash of the spindle

In the basic type (the spindle travels in and out) the lateral backlash of the spindle is the result of the difference between outside diameter of the spindle and inside diameter of the guide rings. Depending on the type of lifting element it is 0,1 to 0,3 mm. The result of these values is a lateral backlash at the end of the spindle, depending on the stroke (or how far the spindle is actually extended) if 2 guide rings are used. The approximate values of this lateral backlash "S" are listed in the table below. This lateral backlash can be reduced if required.

Backlash "S" (mm) with second guide ring									
stroke in mm	SG 0005	SG 0010/0015/0020	SG 0030	SG 0050	SG 0100/0150	SG 0200	SG 0300	SG 0350	SG 0500
0	0,6	0,7	0,7	0,9	1,0	1,0	1,0	1,1	1,1
75	0,9	1,0	1,0	1,2	1,3	1,2	1,3	1,3	1,3
150	1,3	1,3	1,3	1,5	1,6	1,5	1,4	1,5	1,5
300	2,0	1,9	1,9	2,1	2,2	2,0	2,0	1,9	1,9
500	3,0	2,7	2,7	2,9	3,0	2,6	2,6	2,5	2,4
750		3,7	3,7	4,0	4,0	3,5	3,4	3,2	3,0
1000		4,7	4,7	5,0	5,0	4,3	4,2	3,9	3,6
1500			6,7	7,1	7,0	6,0	5,8	5,3	4,8
2000			8,6	9,1	9,0	7,7	7,4	6,7	6,1
2500				11,2	11,0	9,3	9,0	8,2	7,3

## 3.) The axial backlash of the spindle

The axial backlash of the spindle (basic type) and of the traveling nut (traveling nut type) is necessary for the building-up of an adequate lubricating film. Wear during operation will increase the axial backlash; please pay attention to our operating and maintenance instructions. If desired the axial backlash can be limited accordingly through low-backlash or adjustable backlash executions.

spindle pitch (mm)	6	7	8	10	12	16
max. axial backlash of the threaded spindle as manufactured (mm)	0,25	0,26	0,28	0,30	0,32	0,40
max. permissible axial backlash due to wear (mm)	1,5	1,7	2,0	2,5	3,0	4,0

## 4.) Pitch errors of the spindle

Due to the work tolerances of the processing machines a pitch error of 0,05 to 0,075 mm per 300 mm threaded length results in whirl thread spindles. In the practice this error has hardly any effect on the precision of the lifting. In case of doubt please contact us.

## 5.) Straightness of the spindle

The threaded spindles are made of drawn material and deviate from straightness max. by 0,5 mm per 1 m spindle length.

## 6.) Backlash of tooth flank

The backlash of the tooth profile between worm and wormwheel is 0,0 to 0,15 mm as manufactured. Due to the high speed-increasing ratios the effect on the lifting motion is practically imperceptible.

## 7.) Adjustment tolerance

An adjustment tolerance around 0,1 mm can easily be achieved with one-side load direction and manual operation. In the case of an alternation of load the above-mentioned points must be observed. For manual operation also fixed stop motion devices can be used.

In case of a motor drive a number of additional factors must be taken into account, e.g. speed of the driving motor, lifting load, flywheel effect, speed-reducing ratios in the piece parts, efficiency, load direction etc..

If suitable limit switches are used, which are adjusted in the process of assemblage, the point can be determined relatively exactly (prerequisite: constant operating conditions).

If in certain cases greater consider accuracy is required, braking motors or motor operators equipped with brakes must be used. Fixed stroke-arresting devices are not permissible. If in certain cases running against fixed devices is unavoidable, adequate steps must be taken to make sure that overstress is prevented (e.g. by slipping clutch, load-controlled motor cutoff, etc.).



# Questionnaire

**ENZFELDER** GmbH.

WERK ENZESFELD:  
A-2551 ENZESFELD, EICHENGASSE 36  
Tel.: ++43(0)2256/81287  
Fax.: ++43(0)2256/81287-95  
E-Mail: office@enzfelder.at  
Internet: www.enzfelder.at

COMPANY ADDRESS NAME Dept Phone Fax

To be able to prepare a proposal meeting your specific demands, please provide us with the following information:

In which systems are the lifting elements to be used?

Number of systems  
Number of lifting elements per system

### AXIAL LOAD

per system pressure dynamic kN tension dynamic kN  
static kN static kN  
per spindle pressure dynamic kN tension dynamic kN  
static kN static kN  
Type of buckling load according to Euler (see page 29) I  , II  , III  oder IV

### OPERATING CONDITIONS

Effective stroke mm  
Side forces acting kN  
Lifting speed desired mm/min  
Mounting of spindle vertically/horizontally  
Ambient temperature °C  
Duty cycle/load conditions per 10min per hour  
Distance per alternation of load mm

### FOR WHICH PARTS DO YOU WISH TO RECEIVE OUR OFFER?

#### Spindle lifting element with lifting spindle:

Basic type 0 or U  
Spindle nose 0/1/2/3/4/5/6/So

#### Spindle lifting element with rotating spindle and traveling nut:

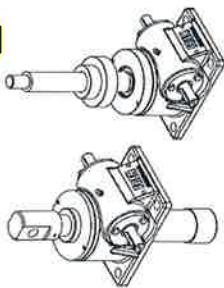
Travling nut type 0 or U  
Spindle nose 0/1/2/3/So

Expansion bellows yes/no  
Bevel gear box yes/no  
Elastic cardan shafts yes/no  
Couplings yes/no  
Pedestal bearings yes/no  
Motor; voltage frequency system of protection  
Limit stop yes/no  
Crank handle, handwheel yes/no  
Swinging element yes/no  
Swivelling console yes/no  
Safety nut yes/no  
Other

# Product overview 03/2015

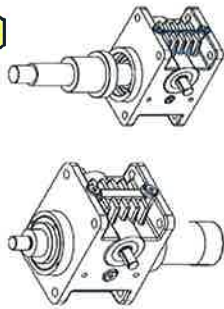
**SG**

Screw jack  
Classic



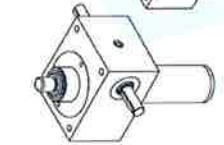
**HSG**

High performance-  
Screw jack



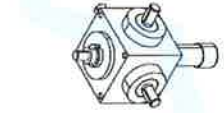
**BG**

Screw jack  
Cubic



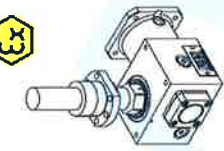
**SHG**

Quick-lifting  
screw jack



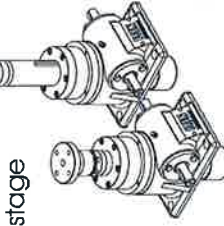
**SH**

Servo lifting  
gear



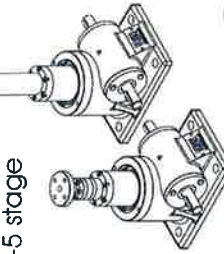
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



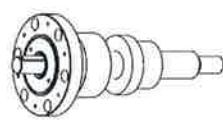
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



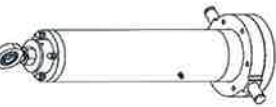
**SLA**

Spindlebearing



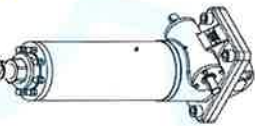
**SEZ**

Spindlebearings-  
Cylinder



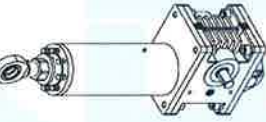
**ELZ**

Electric cylinder



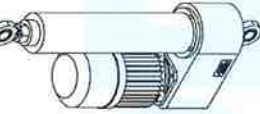
**HELZ**

High performance-  
Electric cylinder



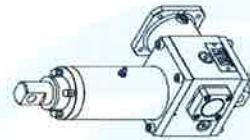
**ELZP**

Electric cylinder  
Parallel



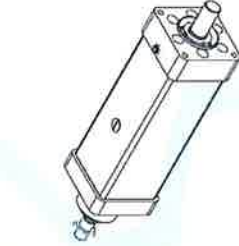
**SHELZ**

Servo electric-  
cylinder



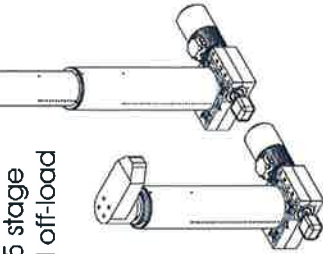
**EPNEU**

Spindle-  
Electric cylinder



**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



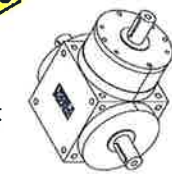
**K**

Bevel gear  
Type K



**H**

Bevel gear  
Type H



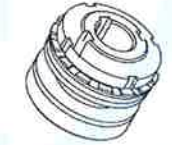
**R / GS**

Elastic / backlash-free  
Coupling



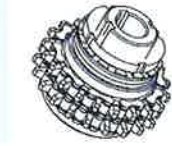
**RT**

Slip hub



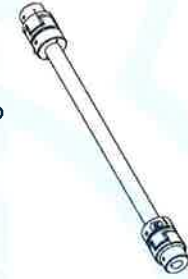
**RK**

Slip coupling



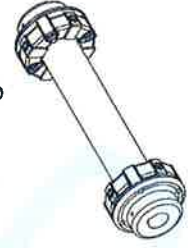
**ZR**

FREN  
Connecting shaft

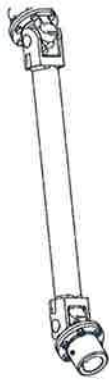


**G / GX**

Elastic  
Connecting shaft

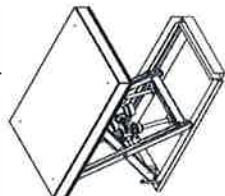


Cardan shaft



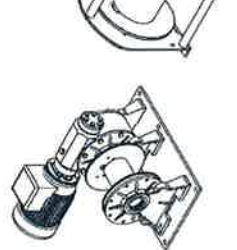
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



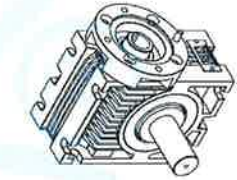
**PLG**

Planetary gear



**uniCe**

Worm gear

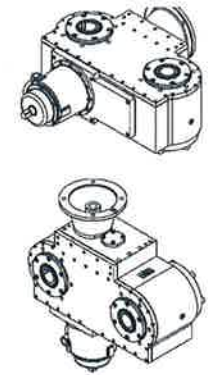


**HA**

Lifting system



**Special gear**

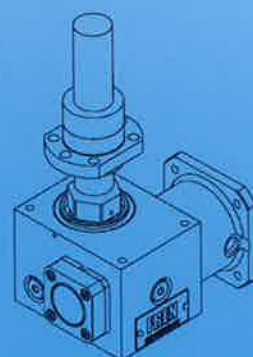




**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

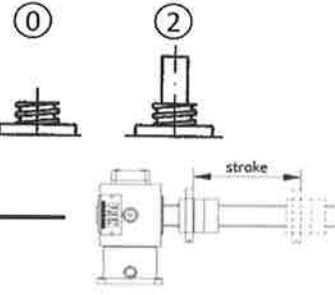
**Servo lifting gear  
Type SH**





FEM = Flanged single nut  
 ZEM = Cylindrical single nut  
 FEMV = Flanged single nut prestressed  
 ZEMV = Cylindrical single nut prestressed  
 FDM = Double flange nut  
 ZDM = Cylindrical double nut

O = Version above  
 U = Version below



H = horizontal  
 V = vertical

00 = without motor  
 M = with motor

00 = without nut housing  
 MG = with nut housing

00 = without floating bearing  
 LL = with floating bearing

Standard:  
 10arcmin = 10 arcmin  
 Special:  
 5arcmin = 5 arcmin

Reductions:  
 45 = 45:1  
 30 = 30:1  
 15 = 15:1

Refers to the axis distance

SH  
 Servo lifting gear

**SH 35 - 45(10arcmin) - FEM - O - 0 - 500 - H - M - MG - LL**

Type

Gear size

Reduction i

Backlash

Traveling nut version

Version

Spindle nose

Stroke mm

Fitting position

Motor

Nut housing

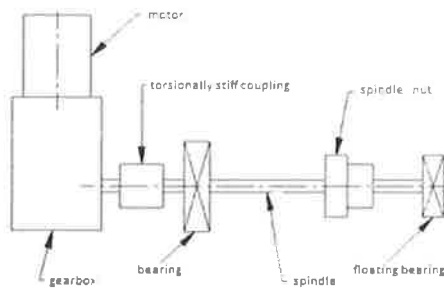
Floating bearing

# SH

## Servo lifting gear

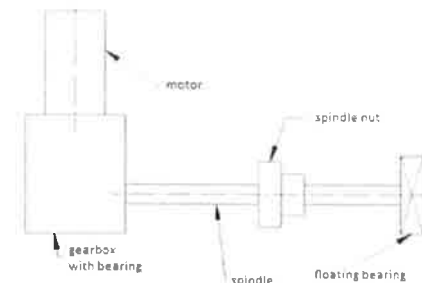
The revolutionary servo lifting gear series is one of the high-end products of the company Enzfelder. These transmissions are specially designed for the high demands of precise adjustment and driving elements. Only through years of experience and know-how of the company Enzfelder, it is possible to realize such a precise and simple gear. Thanks to a special gear a backlash torque transmission can be guaranteed. To really achieve the highest accuracy, it was also important to simplify and improve the previously existing types of drive.

### Prior art to 2008



- Unnecessary expensive components
- Complicated mounting
- Very susceptible to stresses in the spindle
- Many different suppliers
- Requires lots of space

### Enzfelder solution



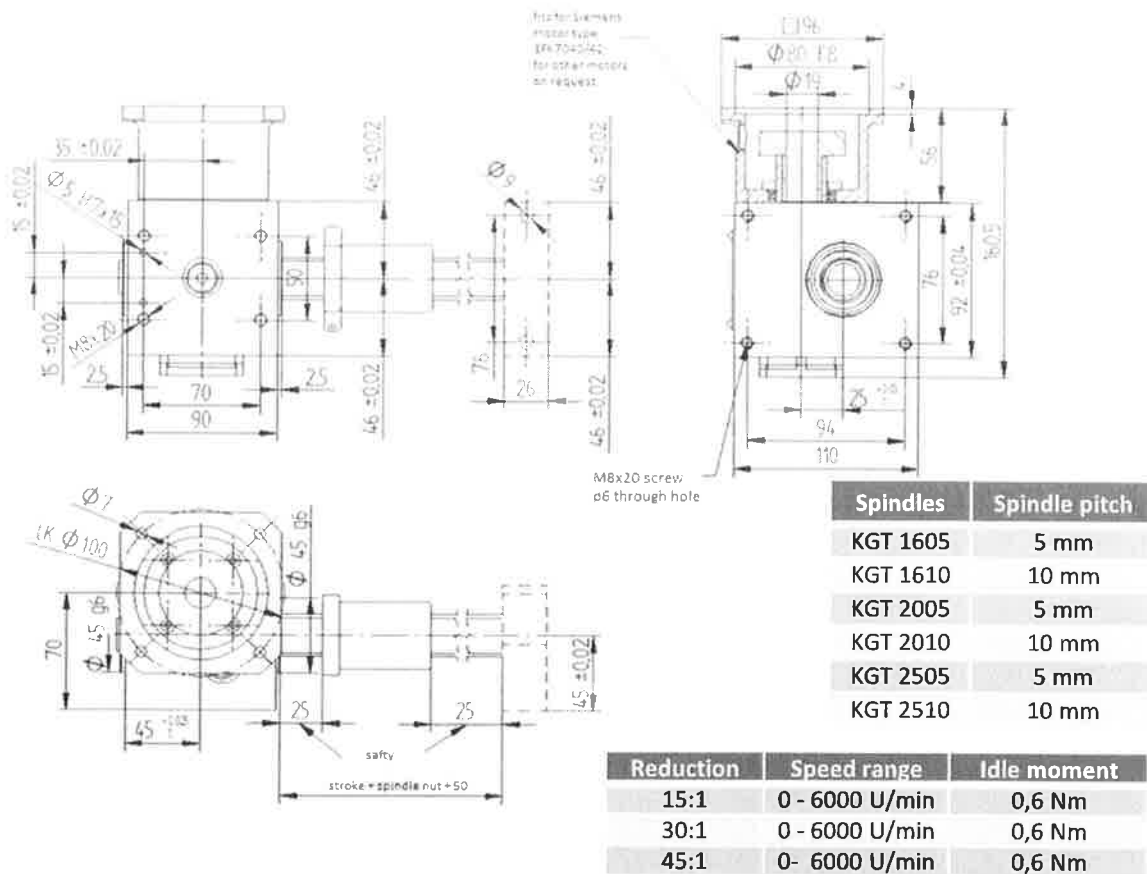
- + Effective overall concept
- + Easy installation
- + Space saving
- + Everything from one source
- + The highest possible efficiency
- + Positioning accuracy to 0.02 mm possible
- + Backlash of 10 arc minutes (on request 5 arcmin)
- + Adjustable backlash

The company Enzfelder solves the problem with a hollow shaft, in combination with a special clamping system. This makes it possible to connect the motor directly to the gearbox and so there is no play between the motor and gearbox.

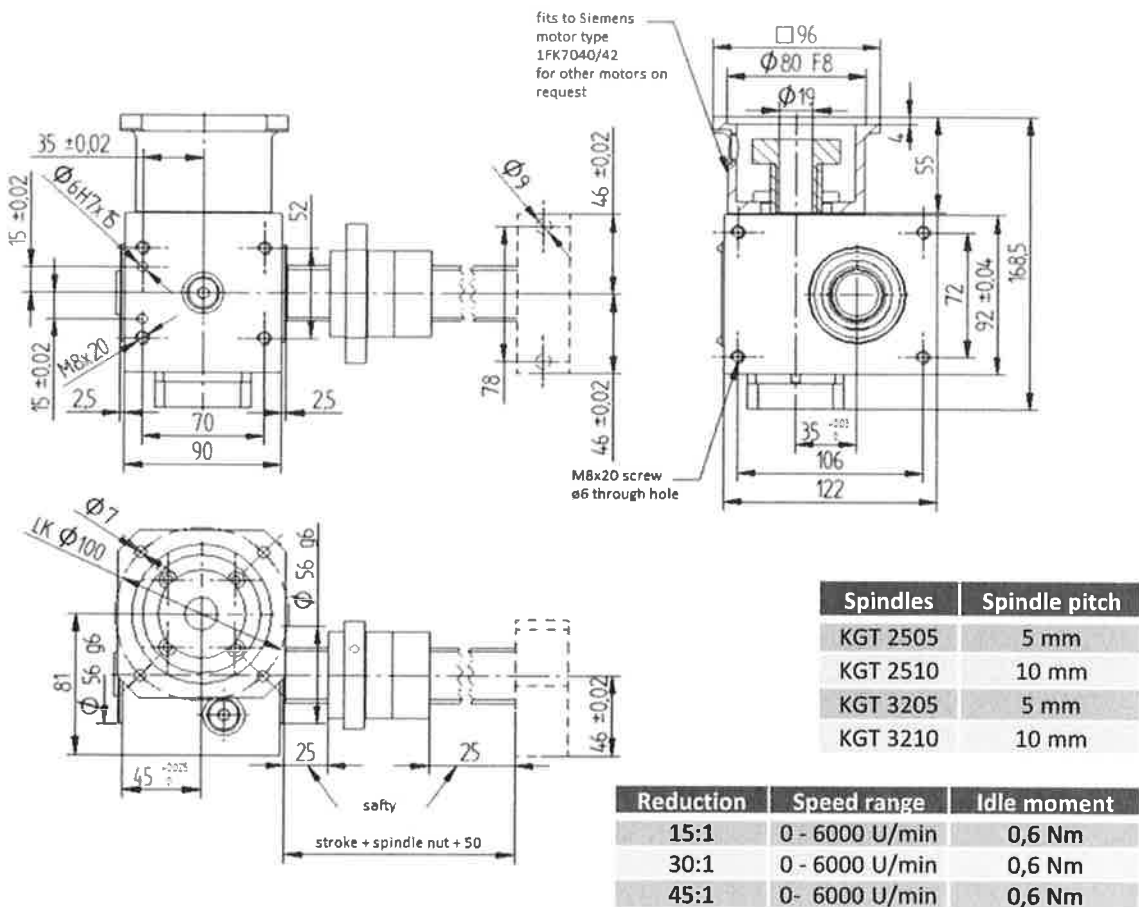
### Advantages of servo lifting gear:

- + Compact design and maximum efficiency
- + High lifting speeds
- + Long life
- + Very precise torque transmission
- + Simple gear mounting
- + Large selection of custom equipment
- + Wide application range

## Servo lifting gear SH 025



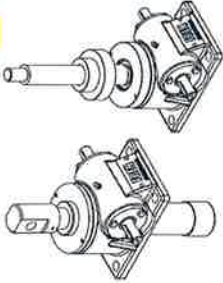
## Servo lifting gear SH 035



# Product overview 03/2015

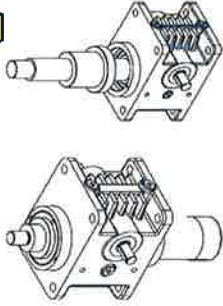
**SG**

Screw jack  
Classic



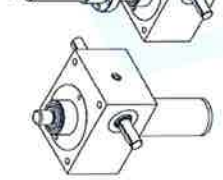
**HSG**

High performance-  
Screw jack



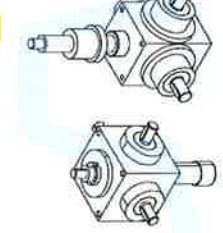
**BG**

Screw jack  
Cubic



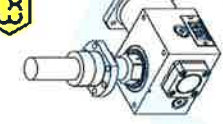
**SHG**

Quick-lifting  
screw jack



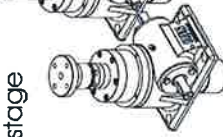
**SH**

Servo lifting  
gear



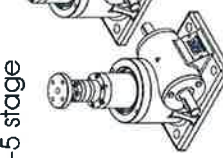
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



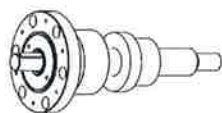
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



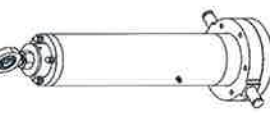
**SLA**

Spindlerebearing



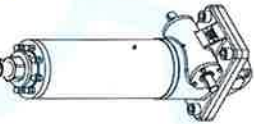
**SEZ**

Spindlerebearings-  
Cylinder



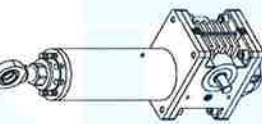
**ELZ**

Electric cylinder



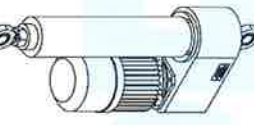
**HELZ**

High performance-  
Electric cylinder



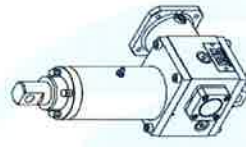
**ELZP**

Electric cylinder  
Parallel



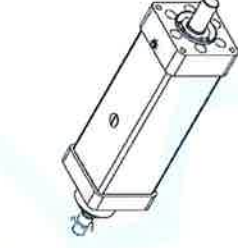
**SHELZ**

Servo electric-  
cylinder



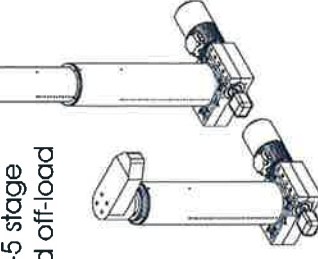
**EPNEU**

Spindle-  
Electric cylinder



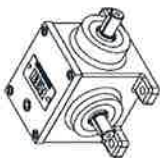
**TSGZ**

Telescopic-  
spindlerebearing  
2-5 stage  
And off-load



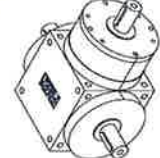
**K**

Bevel gear  
Type K



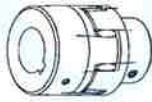
**H**

Bevel gear  
Type H



**R / GS**

Elastic / backlash-free  
Coupling



**RT**

Slip hub



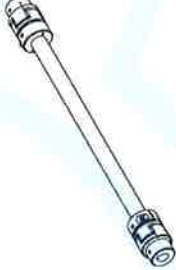
**RK**

Slip coupling



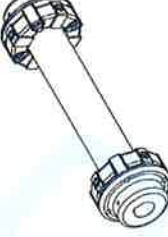
**ZR**

FREN  
Connecting shaft

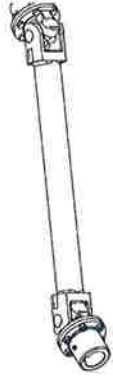


**G / GX**

Elastic  
Connecting shaft

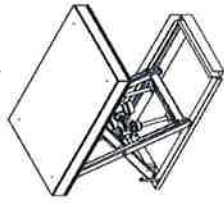


Cardan shaft



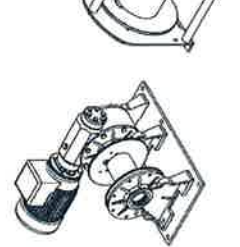
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



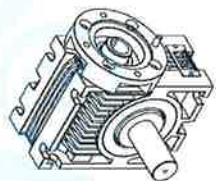
**PLG**

Planetary gear



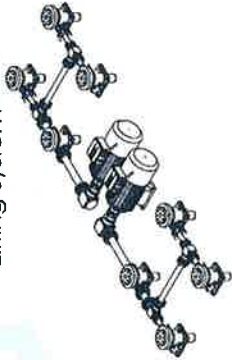
**uniCe**

Worm gear

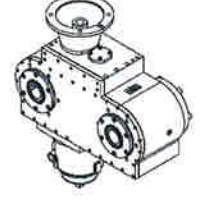


**HA**

Lifting system



**Special gear**



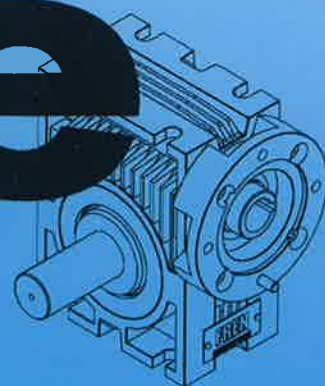


**ENZFELDER** GmbH

**Power transmission- and  
lifting engineering**

**unice**®

**worm gear units**



## **Introduction**

Variety, quality, price and delivery capacity are important points at the choice of innovative gears.

The perfect combination of this points and also to find the best solution for every industrial sector and any application, that is what we are looking after.

Gears of Enzfelder GmbH are used all over the world.

It does not matter if food-, automotive-, material- or metalworking- industry, we always have a solution for your drive.

If you do not find in our catalog what are you looking for, than ask please for a consultation.

We work continuing on a further development of our products.


All specifications in this catalog are not strictly obligatory.  
Change of measurements are reserved


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<b>advantage</b> .....	<b>2</b>
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## advantage


### Why should you choice uniCe gear?


Approved application since 1967 with quality from austria!


 uniCe Worm gear units can be fixed on each side as the housing is strictly prismatic and shows accordingly holes or slots

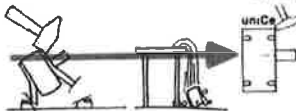
 uniCe Worm gear units can be fixed in any required position. After this the upper oil screw is changed against a breather – in so far as a breather is necessary

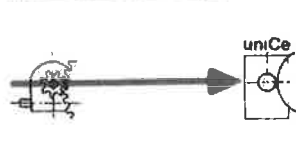
 uniCe high overload is allowed by special gear teeth. At least 100% more load is obtainable before breaking of teeth is possible.

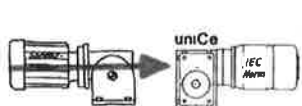
 uniCe The housing is consequently made of one piece (size 35, 40, 50, 63) or in such a way, that sealing surfaces are cylindrical and do not transmit torque.

 uniCe Hollow output shaft allows direct assembly on driven machines without coupling; saves room where compactness is desired.

 uniCe Extremely high hung overload because the bearings are bigger then the worm gear.

 uniCe The one-piece-housing consequently is very stiff.

 uniCe Built in slip coupling: (torque limiter) allows a determined safety factor for all the parts before and after the gear unit. The desired torque cannot be exceeded. Further advantages: Protection against shock loads, operating faults and overloads. Also available with double end shafts and hollow shafts.

 uniCe Assembly of IEC-flanged motors with B5-flange (with through holes), in most cases also B14 type (with tapped holes), NEMA-flanges, air- or hydraulic-motors is possible. An oilseal in the Motorflange is not necessary. Changing the motor for another frequency or voltage is as easy as replacing a motor because of electric damage.

Housing made from warm hardened aluminium of higher rigidity than cast-iron.

Aluminium gives three times better heat dissipation and shows the same heat expansion as the bronze-rim (whilst a cast-iron housing only has half of this) therefore the mating situation of worm and wheel does not change from cold to warm gear.

Integrated fan from size 63 or bigger (when necessary) allowing highly increased heat-dissipation.

Cool air is driven along the fins, designed so that the whole area is effected. Special information can be obtained on request.

## Application

you can find worm gears in the most different applications.

For Example:

conveyor plant (belt conveyor)

food industry, special purpose machinery manufacture, aerotechnics,

automation, automotive industry, and much more

## type designation

example for the designation of a worm gear

e.g.: uniCe-35-N-6-W-QH-FI-QC

1      -2 -3-4-5 - 6 - 7 -8

1. uniCe = normal worm gear  
uniTeCe = pre-stage worm gear
  
2. distance between axles [mm] (size)  
35 , 40 , 50 , 63 , 80 , 100
  
3. N = normal version  
R = version with built in slip coupling
  
4. reduction  
6 , 8 , 10 , 12 , 16 , 20 , 25 , 30 , 36 , 40 , 50 , 63 , 80

attention at pre-stage gear (uniTeCe)

pre-stage reduction size dependency = 6,25 / 10 / 12,5

gear reduction x pre-stage reduction = total reduction

z.B.: 20 x 6,25 = 125

### 5. driving side:

#### 5.1 axle drive shaft

**W** = drive shaft

#### 5.2 motor flange and hollow shaft

z.B.: **JM / 140 / 24**

**JM** = driving side motor flange for motor according to IEC-norm

**140** = flange diameter [mm] dependent to size

uniCe 35 : ø90, ø105, ø120, ø140, ø160

uniCe 40 : ø90, ø105, ø120, ø140, ø160, ø200

uniCe 50 : ø120, ø140, ø160, ø200

uniCe 63 : ø140, ø160, ø200, ø250

uniCe 80 : ø160, ø200, ø250, ø300

uniCe 100 : ø200, ø250, ø300, ø350



24 = hole diameter of worm [mm] dependent to size  
(drilled and grooved)  
uniCe 35 :  $\varnothing 9$ ,  $\varnothing 11$   $\varnothing 14$   
uniCe 40 :  $\varnothing 9$ ,  $\varnothing 11$ ,  $\varnothing 14$ ,  $\varnothing 19$   
uniCe 50 :  $\varnothing 11$ ,  $\varnothing 14$ ,  $\varnothing 19$ ,  $\varnothing 24$   
uniCe 63 :  $\varnothing 14$ ,  $\varnothing 19$ ,  $\varnothing 24$ ,  $\varnothing 28$   
uniCe 80 :  $\varnothing 19$ ,  $\varnothing 24$ ,  $\varnothing 28$ ,  $\varnothing 38$   
uniCe 100 :  $\varnothing 24$ ,  $\varnothing 28$ ,  $\varnothing 38$ ,  $\varnothing 42$ ,  $\varnothing 48$

### 5.3 engine mounting

e.g.: ATDC 63 A 2 B 14 KK1 PTO 2W

ATDC = motor with brake (optional)

63 = size

A = power class

2 = number of poles  
standard 2 poles or 4 poles

B 14 = flange according IEC look on page 7

please choice size, power class and number of poles out of table on page 40.

KK1 = terminal box position  
KK1, KK2, KK3, KK4 (page 5)

PTO = bimetallic device PTO (optional)  
or PTC

2W = second driving shaft (optional)

#### 6. output side:

QH = driven hollow shaft

QAB = driven shaft on both sides

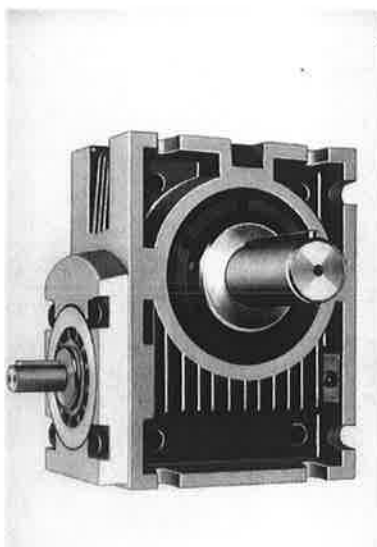
QA = driven shaft on side QA (=right)

QB = driven shaft on side QB (=left)

7. Fl = flange on output side  
only on side QB

8. QC = second driving shaft

## mounting position



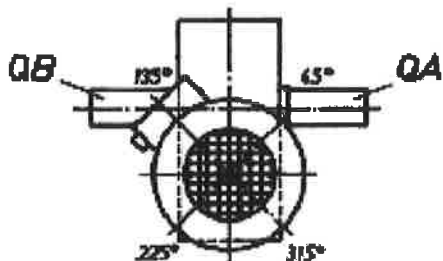
### universal mounting:

The gears can be fixed on each housing side.  
The housing have holes and sluts which are not only used for mounting, also they are used to assemble covers, arm, end switch, torque reaction bar and much more.

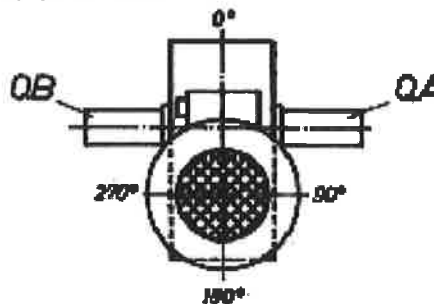
Attention at size 80 and 100 , after mounting the upper oilscrew is changed against a breather.

## Terminal box position

Please give us the position of the terminal box by your order



uniCe 35, 40, 50 and 63



uniCe 80 and 100

the position depends on size

$0^\circ / 45^\circ = \text{KK1}$

$90^\circ / 135^\circ = \text{KK2}$

$180^\circ / 225^\circ = \text{KK3}$

$270^\circ / 315^\circ = \text{KK4}$

## selection of size

power ratings are based upon 20.000 hours of continuous, uniform running (i.e. 10 years of 2000 hours).

Thermal limits of power ratings are based upon an ambient temperature of 76°F (20°C), synthetic lubricants and a maximum temperature of 195°F (90°C). During the first 10 hours 212°F (100°C) is permitted.

Other conditions are to be corrected by service factors shown below.

$$T_{2Tab} \geq T_2 \cdot b_1 \cdot b_2 \cdot b_3 \cdot b_4$$

$$P_{1Tab} \geq \frac{P_2}{\eta} \cdot b_1 \cdot b_2 \cdot b_3 \cdot b_4 \left( P_2 = \frac{T_2 \cdot n_2}{9550} \right)$$

**Attention!** Please check after selection:

if  $T_{2max} \geq T_2$  and

if  $\frac{P_{Mot} \cdot \eta \cdot 9550}{n_2} \leq T_{2max}$

$T_{2Tab}$  = allowed torque acc. table [Nm]

$T_2$  = required torque for driven machine [Nm]

$T_{2max}$  = allowed max. torque of chosen gear [Nm]

$P_{1Tab}$  = allowed input power acc. table [kW]

$P_2$  = power required to drive the machine [kW]  
= output power of the gear

$P_{Mot}$  = motor power [kW]

$\eta$  = efficiency of the gear

$n_2$  = positive output speed of the gear

b<sub>1</sub>

Betriebsart Class of Load conditions de service	Lebensdauer Life time of Gear durée de vie du réducteur			
	4000 h	12000 h	20000 h	30000 h
last stoßfrei uniform presque sans à-coup $T_2 + 10\%$	0,7	0,9	1,0	1,2
mittlere Stöße moderate shocks à-coups moyens $T_2 + 25\%$	0,8	1,0	1,2	1,4
starke Stöße heavy shocks à-coups forts $T_2 + 100\%$	1,0	1,3	1,5	1,8

b<sub>2</sub>

Art des Antriebes Type of Motor genre d'entraînement	Zahl der Anläufe pro Stunde number of starts per hour nombre de démarrages par heure			
	1, ... 5	6, ... 30	30, ... 120	120, ... 600
Elektro-, Öl-, Druckluftmotor Electric-, Oil-, Air-Motor Moteur électrique, hydr., pneum.	1,0	1,1	1,2	1,3
Verbrennungsmotor Combustion engine moteur thermique à 4-8 Zyl. 4-8 cyl.	1,2	1,3	1,4	1,6
Verbrennungsmotor Combustion engine moteur thermique à 1-3 Zyl. 1-3 cyl.	1,3	1,4	1,6	1,7

b<sub>3</sub>

Gehäusetemperatur Temperature of the gearbox température du carter	Umgebungstemperatur °C Ambient Temperature °C température environnante °C				
	15-25	25-32	32-40	40-45	45-50
65 — 75 °C	1,2	1,4	1,8	2,7	3,4
75 — 85 °C	1,0	1,2	1,5	1,4	2,0
85 — 95 °C	0,9	1,1	1,4	1,5	1,8
95 — 100 °C	0,8	1,0	1,2	1,4	1,6

b<sub>4</sub>

max. Einschaltdauer bezogen auf 10 Minuten max. Running-Time under Load during 10 minutes durée maximale de marche durant 10 min.	
0—2 min	0,6
2—4 min	0,7
4—6 min	0,8
6—8 min	0,9
8—10 min	1,0

**standard IEC flange:**

size	standard IEC flange															
	56B5	63B5	63B14	71B5	71B14	80B5	80B14	90B5	90B14	100B14	100B5	112B14	112B5	132B5	160B5	180B5
uniCe 035	X		X		X											
uniTeCe 035	X		X		X											
uniCe 040	X		X		X		X									
uniTeCe 040	X		X		X											
uniCe 050		X		X			X		X							
uniTeCe 050		X		X			X									
uniCe 063				X		X			X	X		X				
uniTeCe 063				X		X			X							
uniCe 080						X		X			X		X	X		
uniCe 100						X		X			X		X	X	X	X

the table shows possible motor flange depended to the size

**max. torque:**

below-mentioned the max. torque, depended on size and rpm.

By the same the efficiency and max. allowed driving power.

$n_1 = 3000 \text{ min}^{-1}$	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	$i_{ges}$	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$
6,00	62	1,27	0,88	124	1,85	0,89	176	3,30	0,91	338	8,69	0,94	640	9,91	0,93	1000	22,80	0,95
8,00	67	0,99	0,85	104	1,41	0,85	204	2,63	0,89	468	6,04	0,93	750	8,14	0,91	1160	19,00	0,94
10,00	88	0,86	0,82	142	1,28	0,83	288	2,32	0,87	746	5,38	0,90	634	7,65	0,90	1300	13,20	0,92
12,00	74	0,75	0,78	115	1,06	0,79	228	1,97	0,84	636	4,83	0,90	874	7,35	0,89	1300	15,20	0,92
16,00	56	0,59	0,73	91	0,84	0,74	191	1,62	0,81	498	3,84	0,87	693	6,25	0,87	1450	10,00	0,88
20,00	100	0,56	0,70	158	0,82	0,72	328	1,43	0,77	858	3,84	0,83	549	4,68	0,82	1160	7,78	0,85
25,00	84	0,47	0,65	130	0,68	0,66	259	1,21	0,72	730	2,87	0,82	1030	4,50	0,80	2070	7,04	0,83
30,00	67	0,42	0,60	103	0,62	0,60	235	1,05	0,70	608	2,30	0,85	856	4,09	0,78	1760	6,14	0,80
36,00	53	0,38	0,54	89	0,56	0,55	197	0,93	0,66	433	2,01	0,78	691	3,75	0,76	1420	5,26	0,76
40,00	51	0,36	0,52	84	0,56	0,56	172	0,87	0,63	438	1,76	0,76	615	3,46	0,74	1320	4,67	0,74
50,00	71	0,32	0,45	71	0,48	0,50	140	0,77	0,57	355	1,53	0,71	487	3,10	0,71	1030	4,06	0,68
63,00	33	0,27	0,38	56	0,42	0,43	113	0,62	0,50	280	1,32	0,66	386	2,65	0,66	836	3,27	0,63
80,00	28	0,27	0,35	41	0,36	0,34	76	0,51	0,44	233	1,21	0,53	370	2,09	0,57	740	3,15	0,58

$n_1 = 1500 \text{ min}^{-1}$	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	$i_{ges}$	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$	$\eta$ [%]	$T_{2max}$	$P_{1Tab}$
6,00	70	0,87	0,89	140	1,29	0,89	198	2,34	0,91	406	6,18	0,94	820	10,10	0,94	1200	22,10	0,94
8,00	75	0,68	0,86	117	0,97	0,86	229	1,78	0,89	524	4,14	0,93	940	7,77	0,92	1310	16,80	0,93
10,00	98	0,56	0,83	158	0,84	0,84	321	1,53	0,87	832	3,58	0,90	708	6,35	0,89	1460	13,80	0,91
12,00	82	0,49	0,80	122	0,71	0,80	253	1,31	0,84	707	3,16	0,90	987	5,97	0,88	2030	11,80	0,89
16,00	64	0,37	0,74	103	0,56	0,74	217	1,08	0,81	565	2,48	0,87	783	5,17	0,86	1640	8,98	0,87
20,00	112	0,36	0,72	178	0,54	0,73	370	0,97	0,77	967	2,27	0,83	620	3,64	0,80	1310	7,46	0,83
25,00	93	0,30	0,66	144	0,43	0,66	288	0,77	0,72	811	1,81	0,82	1140	3,36	0,78	2300	6,74	0,81
30,00	74	0,28	0,61	113	0,40	0,61	257	0,69	0,70	666	1,50	0,83	951	3,15	0,76	1970	5,80	0,78
36,00	58	0,24	0,56	98	0,35	0,56	215	0,64	0,65	473	1,28	0,78	768	2,68	0,75	1570	5,00	0,74
40,00	57	0,23	0,53	93	0,35	0,57	190	0,58	0,62	484	1,15	0,76	683	2,45	0,72	1480	4,73	0,72
50,00	46	0,20	0,46	79	0,31	0,51	156	0,52	0,56	395	1,00	0,71	542	1,90	0,68	1150	3,95	0,66
63,00	36	0,17	0,40	62	0,25	0,44	125	0,42	0,50	311	0,84	0,65	429	1,56	0,64	907	3,40	0,60
80,00	31	0,17	0,36	45	0,23	0,34	82	0,32	0,44	252	0,77	0,52	411	1,49	0,54	801	2,81	0,56

n <sub>1</sub> = 1000 min <sup>-1</sup>																		
i <sub>ges</sub>	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]
6,00	74	0,70	0,87	148	1,02	0,88	208	1,83	0,90	428	4,73	0,93	870	7,21	0,93	1270	16,70	0,94
8,00	80	0,53	0,84	126	0,76	0,84	248	1,44	0,87	566	3,26	0,92	1016	5,62	0,91	1410	12,90	0,92
10,00	105	0,45	0,82	170	0,67	0,82	346	1,23	0,85	895	2,87	0,89	739	5,80	0,88	1610	10,50	0,90
12,00	88	0,40	0,78	138	0,56	0,77	272	1,03	0,82	760	2,55	0,88	1030	4,67	0,86	2150	8,79	0,88
16,00	68	0,31	0,72	110	0,44	0,72	232	0,81	0,79	606	1,94	0,85	814	3,65	0,84	1760	6,74	0,85
20,00	117	0,29	0,69	186	0,43	0,69	387	0,76	0,75	1012	1,80	0,81	644	2,98	0,79	1430	5,60	0,82
25,00	98	0,24	0,64	152	0,34	0,63	304	0,62	0,69	857	1,45	0,80	1200	2,50	0,77	2420	5,10	0,79
30,00	79	0,22	0,58	120	0,31	0,57	257	0,55	0,67	709	1,16	0,82	1000	2,15	0,75	2050	4,44	0,76
36,00	62	0,19	0,53	104	0,29	0,52	229	0,51	0,62	504	1,01	0,76	807	1,79	0,74	1650	3,79	0,72
40,00	60	0,19	0,50	98	0,29	0,53	200	0,47	0,59	509	0,89	0,74	718	1,68	0,70	1570	3,63	0,69
50,00	48	0,15	0,43	84	0,25	0,47	162	0,42	0,53	410	0,75	0,68	569	1,40	0,66	1190	3,04	0,63
63,00	38	0,13	0,37	65	0,21	0,40	131	0,34	0,46	323	0,66	0,62	450	1,21	0,61	943	2,59	0,57
80,00	33	0,13	0,33	47	0,19	0,31	87	0,25	0,41	266	0,60	0,49	435	1,11	0,49	847	2,09	0,53

n <sub>1</sub> = 750 min <sup>-1</sup>																		
i <sub>ges</sub>	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]
6,00	78	0,58	0,87	155	0,83	0,87	220	1,53	0,89	457	3,98	0,93	924	5,81	0,93	1350	14,00	0,93
8,00	84	0,44	0,84	133	0,64	0,84	260	1,19	0,87	600	2,67	0,92	1060	4,77	0,91	1480	10,30	0,92
10,00	109	0,37	0,82	176	0,56	0,82	358	1,05	0,85	928	2,45	0,88	799	4,47	0,87	1650	8,31	0,90
12,00	82	0,32	0,78	144	0,46	0,77	285	0,87	0,81	794	2,16	0,87	1100	3,81	0,85	2250	7,17	0,88
16,00	70	0,25	0,72	113	0,36	0,71	238	0,70	0,78	619	1,61	0,84	874	3,12	0,83	1840	5,55	0,85
20,00	122	0,23	0,69	194	0,36	0,69	404	0,63	0,74	1056	1,49	0,80	691	2,45	0,77	1460	4,50	0,81
25,00	104	0,20	0,63	160	0,29	0,63	320	0,52	0,68	901	1,20	0,78	1280	2,02	0,75	2550	4,09	0,79
30,00	81	0,18	0,58	124	0,26	0,57	282	0,46	0,66	732	0,95	0,81	1060	1,80	0,73	2140	3,50	0,76
36,00	65	0,15	0,52	108	0,23	0,52	238	0,43	0,61	523	0,87	0,74	859	1,53	0,72	1720	3,04	0,71
40,00	62	0,15	0,50	102	0,23	0,53	208	0,40	0,58	529	0,75	0,72	764	1,37	0,67	1600	2,86	0,69
50,00	49	0,13	0,43	83	0,20	0,46	165	0,34	0,51	419	0,64	0,67	606	1,23	0,62	1240	2,41	0,63
63,00	39	0,11	0,37	67	0,17	0,40	135	0,29	0,45	335	0,56	0,60	480	1,07	0,57	996	2,06	0,56
80,00	34	0,10	0,33	49	0,15	0,30	90	0,22	0,40	227	0,53	0,46	450	0,90	0,49	878	1,62	0,53

n <sub>1</sub> = 500 min <sup>-1</sup>																		
i <sub>ges</sub>	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]
6,00	84	0,44	0,87	167	0,65	0,87	236	1,21	0,88	480	3,17	0,92	973	4,32	0,92	1420	10,60	0,93
8,00	90	0,33	0,84	142	0,48	0,83	279	0,92	0,86	637	2,04	0,91	1140	3,65	0,90	1590	7,94	0,92
10,00	115	0,29	0,81	186	0,43	0,81	379	0,78	0,84	980	1,78	0,88	828	3,23	0,86	1800	6,31	0,90
12,00	97	0,24	0,77	152	0,35	0,76	301	0,66	0,80	839	1,59	0,86	1140	2,79	0,84	2380	5,48	0,88
16,00	76	0,19	0,71	123	0,28	0,70	258	0,54	0,77	673	1,25	0,83	904	2,20	0,81	1920	4,23	0,85
20,00	129	0,19	0,68	204	0,26	0,68	425	0,51	0,72	1045	1,15	0,79	716	1,80	0,76	1550	3,41	0,81
25,00	108	0,15	0,63	167	0,22	0,62	333	0,41	0,66	937	0,91	0,77	1330	1,50	0,74	2650	3,09	0,79
30,00	85	0,13	0,57	130	0,20	0,56	296	0,36	0,64	768	0,73	0,80	1110	1,30	0,72	2220	2,63	0,76
36,00	68	0,12	0,51	113	0,18	0,51	249	0,33	0,59	548	0,64	0,73	897	1,18	0,70	1790	2,28	0,71
40,00	65	0,11	0,48	107	0,18	0,52	218	0,31	0,55	553	0,57	0,70	798	1,07	0,64	1690	2,09	0,69
50,00	52	0,10	0,42	88	0,15	0,45	174	0,26	0,49	442	0,48	0,66	633	0,92	0,58	1300	1,79	0,63
63,00	41	0,09	0,36	70	0,12	0,39	142	0,22	0,42	350	0,42	0,58	500	0,83	0,51	1010	1,50	0,56
80,00	34	0,08	0,32	50	0,12	0,30	91	0,17	0,38	282	0,41	0,45	459	0,63	0,48	894	1,10	0,53

n <sub>1</sub> = 150 min <sup>-1</sup>																		
i <sub>ges</sub>	uniCe 035			uniCe 040			uniCe 050			uniCe 063			uniCe 080			uniCe 100		
	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]	T <sub>2max</sub>	P <sub>1Tab</sub>	η [%]
6,00	99	0,20	0,85	198	0,28	0,85	280	0,53	0,88	575	1,32	0,92	1170	1,51	0,91	1700	4,71	0,92
8,00	106	0,14	0,82	164	0,21	0,81	322	0,35	0,85	737	0,86	0,91	1320	1,37	0,89	1830	3,50	0,90
10,00	131	0,12	0,79	212	0,19	0,79	433	0,33	0,83	1045	0,77	0,87	904	1,24	0,79	2070	2,79	0,88
12,00	109	0,10	0,75	170	0,15	0,74	336	0,28	0,78	936	0,68	0,86	1250	1,05	0,76	2800	2,38	0,85
16,00	85	0,08	0,68	137	0,12	0,67	289	0,22	0,75	754	0,52	0,82	995	0,89	0,72	2210	1,80	0,82
20,00	145	0,08	0,65	231	0,11	0,65	479	0,20	0,70	1045	0,48	0,76	787	0,72	0,66	1740	1,49	0,77
25,00	120	0,07	0,59	186	0,09	0,58	371	0,17	0,65	1045	0,37	0,76	1440	0,59	0,64	2910	1,34	0,74
30,00	95	0,06	0,54	145	0,09	0,52	330	0,14	0,62	854	0,29	0,79	1210	0,53	0,62	2430	1,14	0,71
36,00	74	0,06	0,48	124	0,08	0,47	274	0,13	0,57	605	0,26	0,72	973	0,46	0,60	1980	0,99	0,65
40,00	71	0,04	0,45	117	0,08	0,48	240	0,12	0,54	610	0,23	0,70	865	0,42	0,55	1850	0,94	0,63
50,00	56	0,04	0,39	96	0,07	0,42	190	0,11	0,47	481	0,20	0,64	687	0,39	0,49	1420	0,79	0,56
63,00	44	0,03	0,33	76	0,06	0,36	153	0,09	0,41	377	0,16	0,58	543	0,32	0,42	1110	0,56	0,50
80,00	37	0,03	0,29	54	0,04	0,26	99	0,06	0,37	306	0,14	0,43	498	0,22	0,44	971	0,41	0,46

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor
0,06	16,65	12,39	80,00	0,36	2,48	uniCe 035	-	56A-4B5
	21,14	10,84	63,00	0,40	3,36	uniCe 035	-	56A-4B5
	26,64	9,89	50,00	0,46	4,67	uniCe 035	-	56A-4B5
	33,30	9,12	40,00	0,53	6,21	uniCe 035	-	56A-4B5
	37,00	8,67	36,00	0,56	6,72	uniCe 035	-	56A-4B5
	44,40	7,87	30,00	0,61	9,37	uniCe 035	-	56A-4B5
	53,28	7,10	25,00	0,66	13,13	uniCe 035	-	56A-4B5
	66,60	6,19	20,00	0,72	18,08	uniCe 035	-	56A-4B5
	83,25	5,09	16,00	0,74	12,51	uniCe 035	-	56A-4B5
	111,00	4,13	12,00	0,80	19,86	uniCe 035	-	56A-4B5
	133,20	3,57	10,00	0,83	27,31	uniCe 035	-	56A-4B5
	166,50	2,96	8,00	0,86	25,48	uniCe 035	-	56A-4B5
	222,00	2,30	6,00	0,89	30,52	uniCe 035	-	56A-4B5
	16,65	11,70	80,00	0,34	3,83	uniCe 040	-	56A-4B5
	21,14	11,92	63,00	0,44	5,22	uniCe 040	-	56A-4B5
	26,64	10,97	50,00	0,51	7,17	uniCe 040	-	56A-4B5
	33,30	9,81	40,00	0,57	9,49	uniCe 040	-	56A-4B5
	37,00	8,67	36,00	0,56	11,24	uniCe 040	-	56A-4B5
	44,40	7,87	30,00	0,61	14,35	uniCe 040	-	56A-4B5
	53,28	7,10	25,00	0,66	20,29	uniCe 040	-	56A-4B5
	66,60	6,28	20,00	0,73	28,34	uniCe 040	-	56A-4B5
	83,25	5,09	16,00	0,74	20,22	uniCe 040	-	56A-4B5
	111,00	4,13	12,00	0,80	29,54	uniCe 040	-	56A-4B5
	133,20	3,61	10,00	0,84	43,72	uniCe 040	-	56A-4B5
	166,50	2,96	8,00	0,86	39,53	uniCe 040	-	56A-4B5
	222,00	2,30	6,00	0,89	60,94	uniCe 040	-	56A-4B5
	4,26	86,06	312,50	0,64	1,08	uniTeCe 035	12,5	56A-4B5
	5,33	55,29	250,00	0,51	1,02	uniTeCe 035	6,25	56A-4B5
	5,33	75,11	250,00	0,70	1,49	uniTeCe 035	12,5	56A-4B5
	5,92	52,58	225,00	0,54	1,11	uniTeCe 035	6,25	56A-4B5
	6,66	61,76	200,00	0,72	1,03	uniTeCe 035	12,5	56A-4B5
	7,10	47,73	187,50	0,59	1,55	uniTeCe 035	6,25	56A-4B5
	8,52	43,03	156,25	0,64	2,17	uniTeCe 035	6,25	56A-4B5
	8,88	50,07	150,00	0,78	1,64	uniTeCe 035	12,5	56A-4B5
	10,66	37,55	125,00	0,70	2,98	uniTeCe 035	6,25	56A-4B5
	13,32	30,88	100,00	0,72	2,06	uniTeCe 035	6,25	56A-4B5
	17,76	27,85	75,00	0,86	2,52	uniTeCe 035	12,5	56A-4B5
	2,96	105,15	450,00	0,54	0,93	uniTeCe 040	12,5	56A-4B5
	3,38	72,29	393,75	0,43	0,86	uniTeCe 040	6,25	56A-4B5
	3,55	95,45	375,00	0,59	1,18	uniTeCe 040	12,5	56A-4B5
	4,26	66,50	312,50	0,49	1,18	uniTeCe 040	6,25	56A-4B5
	4,26	86,06	312,50	0,64	1,67	uniTeCe 040	12,5	56A-4B5
5,33	59,46	250,00	0,55	1,57	uniTeCe 040	6,25	56A-4B5	
5,33	76,15	250,00	0,71	2,34	uniTeCe 040	12,5	56A-4B5	
5,92	52,58	225,00	0,54	1,85	uniTeCe 040	6,25	56A-4B5	
6,66	61,76	200,00	0,72	1,67	uniTeCe 040	12,5	56A-4B5	
7,10	47,73	187,50	0,59	2,37	uniTeCe 040	6,25	56A-4B5	
8,88	50,07	150,00	0,78	2,44	uniTeCe 040	12,5	56A-4B5	

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor	
0,09	16,83	18,39	80,00	0,36	1,67	uniCe 035	-	56B-4B5	
	21,37	16,09	63,00	0,40	2,26	uniCe 035	-	56B-4B5	
	26,92	14,69	50,00	0,46	3,15	uniCe 035	-	56B-4B5	
	33,75	8,91	80,00	0,35	3,18	uniCe 035	-	56A-2B5	
	35,89	20,67	37,50	0,86	3,39	uniTeCe 035	6,25	56B-4B5	
	3,59	141,69	375,00	0,59	0,80	uniTeCe 040	12,5	56B-4B5	
	4,31	127,75	312,50	0,64	1,13	uniTeCe 040	12,5	56B-4B5	
	5,38	113,04	250,00	0,71	1,57	uniTeCe 040	12,5	56B-4B5	
	5,98	78,04	225,00	0,54	1,25	uniTeCe 040	6,25	56B-4B5	
	6,73	91,67	200,00	0,72	1,12	uniTeCe 040	12,5	56B-4B5	
	7,18	70,84	187,50	0,59	1,60	uniTeCe 040	6,25	56B-4B5	
	8,61	63,88	156,25	0,64	2,25	uniTeCe 040	6,25	56B-4B5	
	10,77	56,52	125,00	0,71	3,15	uniTeCe 040	6,25	56B-4B5	
	12,00	38,21	225,00	0,53	2,33	uniTeCe 040	6,25	56A-2B5	
	13,46	45,84	100,00	0,72	2,25	uniTeCe 040	6,25	56B-4B5	
	14,40	34,74	187,50	0,58	2,97	uniTeCe 040	6,25	56A-2B5	
	17,95	37,16	75,00	0,78	3,28	uniTeCe 040	6,25	56B-4B5	
	27,00	22,85	100,00	0,72	3,97	uniTeCe 040	6,25	56A-2B5	

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor	
0,13	16,94	26,39	80,00	0,36	1,16	uniCe 035	-	63A-4B14	
	21,51	23,09	63,00	0,40	1,58	uniCe 035	-	63A-4B14	
	27,10	21,07	50,00	0,46	2,19	uniCe 035	-	63A-4B14	
	33,88	19,42	40,00	0,53	2,91	uniCe 035	-	63A-4B14	
	34,50	12,59	80,00	0,35	2,25	uniCe 035	-	56B-2B5	
	37,64	18,47	36,00	0,56	3,16	uniCe 035	-	63A-4B14	
	43,81	10,77	63,00	0,38	3,06	uniCe 035	-	56B-2B5	
	8,67	91,65	156,25	0,64	1,02	uniTeCe 035	6,25	63A-4B14	
	10,84	79,99	125,00	0,70	1,40	uniTeCe 035	6,25	63A-4B14	
	11,04	56,72	250,00	0,50	0,90	uniTeCe 035	6,25	56B-2B5	
	12,27	53,01	225,00	0,52	1,01	uniTeCe 035	6,25	56B-2B5	
	13,55	65,77	100,00	0,72	0,97	uniTeCe 035	6,25	63A-4B14	
	14,72	49,09	187,50	0,58	1,37	uniTeCe 035	6,25	56B-2B5	
	17,66	44,31	156,25	0,63	1,89	uniTeCe 035	6,25	56B-2B5	
	18,07	53,32	75,00	0,78	1,54	uniTeCe 035	6,25	63A-4B14	
	22,08	38,18	125,00	0,68	2,61	uniTeCe 035	6,25	56B-2B5	
	36,13	29,66	37,50	0,86	2,36	uniTeCe 035	6,25	63A-4B14	
	44,16	22,36	62,50	0,80	3,91	uniTeCe 035	6,25	56B-2B5	
	55,20	18,54	50,00	0,82	3,63	uniTeCe 035	6,25	56B-2B5	
	5,42	162,20	250,00	0,71	1,10	uniTeCe 040	12,5	63A-4B14	
	6,02	111,98	225,00	0,54	0,87	uniTeCe 040	6,25	63A-4B14	
	7,23	101,65	187,50	0,59	1,11	uniTeCe 040	6,25	63A-4B14	
	9,03	106,65	150,00	0,78	1,14	uniTeCe 040	12,5	63A-4B14	
	3,61	233,30	375,00	0,68	1,10	uniTeCe 050	12,5	63A-4B5	
	4,34	155,53	312,50	0,54	1,00	uniTeCe 050	6,25	63A-4B5	

**selection table based on power:**

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{2 Tab}$ [Nm]	$i_{ges}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
0,18	17,41	35,54	80,00	0,36	0,86	uniCe 035	-	63B-4B14	
	22,11	31,10	63,00	0,40	1,17	uniCe 035	-	63B-4B14	
	27,86	28,38	50,00	0,46	1,63	uniCe 035	-	63B-4B14	
	34,83	26,16	40,00	0,53	2,16	uniCe 035	-	63B-4B14	
	38,69	24,88	36,00	0,56	2,34	uniCe 035	-	63B-4B14	
	43,67	14,96	63,00	0,38	2,20	uniCe 035	-	63A-2B14	
	46,43	22,58	30,00	0,61	3,27	uniCe 035	-	63B-4B14	
	68,78	13,00	40,00	0,52	3,95	uniCe 035	-	63A-2B14	
	11,14	107,73	125,00	0,70	1,04	uniTeCe 035	6,25	63B-4B14	
	18,57	71,82	75,00	0,78	1,14	uniTeCe 035	6,25	63B-4B14	
	36,68	35,46	75,00	0,76	2,08	uniTeCe 035	6,25	63A-2B14	
	37,15	39,95	37,50	0,86	1,75	uniTeCe 035	6,25	63B-4B14	
	44,02	31,06	62,50	0,80	2,82	uniTeCe 035	6,25	63A-2B14	
	55,02	25,76	50,00	0,82	2,61	uniTeCe 035	6,25	63A-2B14	
	73,36	20,00	37,50	0,85	3,11	uniTeCe 035	6,25	63A-2B14	
	7,43	136,91	187,50	0,59	0,83	uniTeCe 040	6,25	63B-4B14	
	8,92	123,44	156,25	0,64	1,17	uniTeCe 040	6,25	63B-4B14	
	9,29	143,64	150,00	0,78	0,85	uniTeCe 040	12,5	63B-4B14	
	12,23	75,01	225,00	0,53	1,19	uniTeCe 040	6,25	63A-2B14	
	13,93	88,58	100,00	0,72	1,16	uniTeCe 040	6,25	63B-4B14	
	3,71	314,21	375,00	0,68	0,82	uniTeCe 050	12,5	63B-4B5	
	4,46	269,33	312,50	0,70	1,07	uniTeCe 050	12,5	63B-4B5	
	5,57	185,54	250,00	0,60	1,02	uniTeCe 050	6,25	63B-4B5	
	6,19	175,06	225,00	0,63	1,23	uniTeCe 050	6,25	63B-4B5	



**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor	
0,25	21,75	43,92	63,00	0,40	0,83	uniCe 035	-	71A-4B14	
	27,40	40,08	50,00	0,46	1,15	uniCe 035	-	71A-4B14	
	34,25	36,95	40,00	0,53	1,53	uniCe 035	-	71A-4B14	
	38,06	35,13	36,00	0,56	1,66	uniCe 035	-	71A-4B14	
	43,95	20,64	63,00	0,38	1,59	uniCe 035	-	63B-2B14	
	45,67	31,89	30,00	0,61	2,31	uniCe 035	-	71A-4B14	
	46,00	31,66	30,00	0,61	2,33	uniCe 035	-	63C-4B14	
	54,80	28,75	25,00	0,66	3,24	uniCe 035	-	71A-4B14	
	55,20	28,55	25,00	0,66	3,26	uniCe 035	-	63C-4B14	
	69,23	17,93	40,00	0,52	2,86	uniCe 035	-	63B-2B14	
	76,92	16,76	36,00	0,54	3,18	uniCe 035	-	63B-2B14	
	85,63	20,63	16,00	0,74	3,09	uniCe 035	-	71A-4B14	
	86,25	20,48	16,00	0,74	3,11	uniCe 035	-	63C-4B14	
	17,13	47,40	80,00	0,34	0,95	uniCe 040	-	71A-4B14	
	17,72	84,94	156,25	0,63	0,99	uniTeCe 035	6,25	63B-2B14	
	18,27	101,43	75,00	0,78	0,81	uniTeCe 035	6,25	71A-4B14	
	21,92	87,69	62,50	0,81	1,11	uniTeCe 035	6,25	71A-4B14	
	36,53	56,42	37,50	0,86	1,24	uniTeCe 035	6,25	71A-4B14	
	44,30	42,86	62,50	0,80	2,04	uniTeCe 035	6,25	63B-2B14	
	73,84	27,60	37,50	0,85	2,26	uniTeCe 035	6,25	63B-2B14	
	8,77	174,32	156,25	0,64	0,83	uniTeCe 040	6,25	71A-4B14	
	10,96	177,49	125,00	0,81	0,89	uniTeCe 040	12,5	71A-4B14	
	11,04	176,21	125,00	0,81	0,90	uniTeCe 040	12,5	63C-4B14	
	12,31	103,50	225,00	0,53	0,86	uniTeCe 040	6,25	63B-2B14	
	13,70	145,38	100,00	0,83	0,80	uniTeCe 040	12,5	71A-4B14	
	14,77	94,09	187,50	0,58	1,09	uniTeCe 040	6,25	63B-2B14	
	5,48	325,41	250,00	0,75	1,14	uniTeCe 050	12,5	71A-4B5	
	6,09	247,22	225,00	0,63	0,87	uniTeCe 050	6,25	71A-4B5	
	7,31	221,87	187,50	0,68	1,16	uniTeCe 050	6,25	71A-4B5	
	9,13	212,99	150,00	0,81	1,19	uniTeCe 050	12,5	71A-4B5	
	3,04	593,34	450,00	0,76	0,80	uniTeCe 063	12,5	71A-4B5	
4,38	375,06	312,50	0,69	1,05	uniTeCe 063	6,25	71A-4B5		

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor
0,37	34,15	54,84	40,00	0,53	1,03	uniCe 035	-	71B-4B14
	35,13	35,21	80,00	0,35	0,80	uniCe 035	-	71A-2B14
	37,94	52,15	36,00	0,56	1,12	uniCe 035	-	71B-4B14
	44,38	30,25	63,00	0,38	1,09	uniCe 035	-	63C-2B14
	45,53	47,34	30,00	0,61	1,56	uniCe 035	-	71B-4B14
	54,64	42,68	25,00	0,66	2,18	uniCe 035	-	71B-4B14
	55,92	28,43	50,00	0,45	2,50	uniCe 035	-	63C-2B14
	56,20	28,29	50,00	0,45	2,51	uniCe 035	-	71A-2B14
	68,30	37,25	20,00	0,72	3,01	uniCe 035	-	71B-4B14
	69,90	26,29	40,00	0,52	1,95	uniCe 035	-	63C-2B14
	70,25	26,16	40,00	0,52	1,96	uniCe 035	-	71A-2B14
	77,67	24,57	36,00	0,54	2,17	uniCe 035	-	63C-2B14
	78,06	24,45	36,00	0,54	2,18	uniCe 035	-	71A-2B14
	85,38	30,63	16,00	0,74	2,08	uniCe 035	-	71B-4B14
	93,20	22,75	30,00	0,60	2,96	uniCe 035	-	63C-2B14
	113,83	24,83	12,00	0,80	3,30	uniCe 035	-	71B-4B14
	174,75	14,76	16,00	0,73	3,80	uniCe 035	-	63C-2B14
	175,63	14,69	16,00	0,73	3,82	uniCe 035	-	71A-2B14
	21,68	71,70	63,00	0,44	0,87	uniCe 040	-	71B-4B14
	27,32	65,96	50,00	0,51	1,19	uniCe 040	-	71B-4B14
	17,08	91,05	80,00	0,44	0,90	uniCe 050	-	71B-4B5
	22,37	107,26	125,00	0,68	0,93	uniTeCe 035	6,25	63C-2B14
	36,43	83,74	37,50	0,86	0,84	uniTeCe 035	6,25	71B-4B14
	74,56	40,45	37,50	0,85	1,54	uniTeCe 035	6,25	63C-2B14
	18,21	150,55	75,00	0,78	0,81	uniTeCe 040	6,25	71B-4B14
	28,10	90,26	100,00	0,72	1,00	uniTeCe 040	6,25	71A-2B14
	8,74	282,28	156,25	0,70	1,02	uniTeCe 050	6,25	71B-4B5
	9,11	316,15	150,00	0,81	0,80	uniTeCe 050	12,5	71B-4B5
	10,93	241,51	125,00	0,75	1,53	uniTeCe 050	6,25	71B-4B5
	11,18	193,07	250,00	0,61	0,89	uniTeCe 050	6,25	63C-2B5
	12,43	182,04	225,00	0,64	1,08	uniTeCe 050	6,25	63C-2B5
	13,66	203,24	100,00	0,79	1,07	uniTeCe 050	6,25	71B-4B5
	14,91	160,89	187,50	0,68	1,46	uniTeCe 050	6,25	63C-2B5
	3,64	780,97	375,00	0,81	0,85	uniTeCe 063	12,5	71B-4B5
	4,37	642,97	312,50	0,80	1,26	uniTeCe 063	12,5	71B-4B5
	5,46	476,74	250,00	0,74	1,02	uniTeCe 063	6,25	71B-4B5
	6,07	440,36	225,00	0,76	1,07	uniTeCe 063	6,25	71B-4B5
	7,29	390,49	187,50	0,81	1,71	uniTeCe 063	6,25	71B-4B5

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor	
0,55	45,47	70,47	30,00	0,61	1,05	uniCe 035	-	71C-4B14	
	54,56	63,54	25,00	0,66	1,47	uniCe 035	-	71C-4B14	
	56,20	42,06	50,00	0,45	1,69	uniCe 035	-	71B-2B14	
	68,20	55,45	20,00	0,72	2,02	uniCe 035	-	71C-4B14	
	70,25	38,88	40,00	0,52	1,32	uniCe 035	-	71B-2B14	
	78,06	36,34	36,00	0,54	1,47	uniCe 035	-	71B-2B14	
	85,25	45,59	16,00	0,74	1,40	uniCe 035	-	71C-4B14	
	93,67	33,65	30,00	0,60	2,00	uniCe 035	-	71B-2B14	
	112,40	30,37	25,00	0,65	2,76	uniCe 035	-	71B-2B14	
	113,67	36,97	12,00	0,80	2,22	uniCe 035	-	71C-4B14	
	136,40	31,96	10,00	0,83	3,05	uniCe 035	-	71C-4B14	
	140,50	26,17	20,00	0,70	3,80	uniCe 035	-	71B-2B14	
	170,50	26,49	8,00	0,86	2,85	uniCe 035	-	71C-4B14	
	175,63	21,83	16,00	0,73	2,57	uniCe 035	-	71B-2B14	
	227,33	20,56	6,00	0,89	3,41	uniCe 035	-	71C-4B14	
	27,28	98,20	50,00	0,51	0,80	uniCe 040	-	71C-4B14	
	34,10	87,80	40,00	0,57	1,06	uniCe 040	-	71C-4B14	
	35,13	50,84	80,00	0,34	0,81	uniCe 040	-	71B-2B14	
	37,89	77,63	36,00	0,56	1,26	uniCe 040	-	71C-4B14	
	38,64	76,13	36,00	0,56	1,28	uniCe 040	-	80A-4B14	
	44,60	50,64	63,00	0,43	1,11	uniCe 040	-	71B-2B14	
	46,37	69,10	30,00	0,61	1,64	uniCe 040	-	80A-4B14	
	55,64	62,30	25,00	0,66	2,31	uniCe 040	-	80A-4B14	
	69,55	55,13	20,00	0,73	3,23	uniCe 040	-	80A-4B14	
	86,94	44,71	16,00	0,74	2,30	uniCe 040	-	80A-4B14	
	115,92	36,25	12,00	0,80	3,37	uniCe 040	-	80A-4B14	
	21,65	121,30	63,00	0,50	1,03	uniCe 050	-	71C-4B5	
	22,08	118,95	63,00	0,50	1,05	uniCe 050	-	80A-4B14	
	17,05	160,19	80,00	0,52	1,57	uniCe 063	-	71C-4B5	
	74,93	59,83	37,50	0,85	1,04	uniTeCe 035	6,25	71B-2B14	
	36,37	124,67	37,50	0,86	1,12	uniTeCe 040	6,25	71C-4B14	
	10,91	359,52	125,00	0,75	1,03	uniTeCe 050	6,25	71C-4B5	
	11,13	352,54	125,00	0,75	1,05	uniTeCe 050	6,25	80A-4B14	
	14,99	237,97	187,50	0,68	0,99	uniTeCe 050	6,25	71B-2B5	
	18,19	235,32	75,00	0,81	1,08	uniTeCe 050	6,25	71C-4B5	
	28,10	146,86	100,00	0,79	1,30	uniTeCe 050	6,25	71B-2B5	
	4,36	957,17	312,50	0,80	0,85	uniTeCe 063	12,5	71C-4B5	
	5,46	775,07	250,00	0,81	1,25	uniTeCe 063	12,5	71C-4B5	
6,82	649,94	200,00	0,84	0,87	uniTeCe 063	12,5	71C-4B5		
7,27	581,30	187,50	0,81	1,15	uniTeCe 063	6,25	71C-4B5		
8,73	478,58	156,25	0,80	1,69	uniTeCe 063	6,25	71C-4B5		
9,09	504,26	150,00	0,87	1,40	uniTeCe 063	12,5	71C-4B5		
12,49	318,21	225,00	0,76	1,36	uniTeCe 063	6,25	71B-2B5		
13,64	324,97	100,00	0,84	1,74	uniTeCe 063	6,25	71C-4B5		

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor	
0,75	55,60	57,97	50,00	0,45	1,22	uniCe 035	-	71C-2B14	
	69,50	53,59	40,00	0,52	0,96	uniCe 035	-	71C-2B14	
	77,22	50,09	36,00	0,54	1,06	uniCe 035	-	71C-2B14	
	92,67	46,38	30,00	0,60	1,45	uniCe 035	-	71C-2B14	
	111,20	41,87	25,00	0,65	2,00	uniCe 035	-	71C-2B14	
	139,00	36,07	20,00	0,70	2,76	uniCe 035	-	71C-2B14	
	173,75	30,09	16,00	0,73	1,86	uniCe 035	-	71C-2B14	
	231,67	24,12	12,00	0,78	3,06	uniCe 035	-	71C-2B14	
	347,50	17,52	8,00	0,85	3,84	uniCe 035	-	71C-2B14	
	35,33	115,57	40,00	0,57	0,81	uniCe 040	-	80B-4B14	
	39,25	102,19	36,00	0,56	0,95	uniCe 040	-	80B-4B14	
	44,13	69,80	63,00	0,43	0,80	uniCe 040	-	71C-2B14	
	45,30	67,99	63,00	0,43	0,83	uniCe 040	-	80A-2B14	
	47,10	92,76	30,00	0,61	1,22	uniCe 040	-	80B-4B14	
	56,52	83,64	25,00	0,66	1,72	uniCe 040	-	80B-4B14	
	57,08	62,74	50,00	0,50	1,13	uniCe 040	-	80A-2B14	
	70,65	74,01	20,00	0,73	2,41	uniCe 040	-	80B-4B14	
	71,35	56,22	40,00	0,56	1,50	uniCe 040	-	80A-2B14	
	79,28	49,69	36,00	0,55	1,79	uniCe 040	-	80A-2B14	
	88,31	60,02	16,00	0,74	1,72	uniCe 040	-	80B-4B14	
	95,13	45,17	30,00	0,60	2,28	uniCe 040	-	80A-2B14	
	114,16	41,41	25,00	0,66	3,14	uniCe 040	-	80A-2B14	
	117,75	48,66	12,00	0,80	2,51	uniCe 040	-	80B-4B14	
	141,30	42,58	10,00	0,84	3,71	uniCe 040	-	80B-4B14	
	176,63	34,87	8,00	0,86	3,35	uniCe 040	-	80B-4B14	
	178,38	29,71	16,00	0,74	3,05	uniCe 040	-	80A-2B14	
	28,26	141,93	50,00	0,56	1,10	uniCe 050	-	80B-4B14	
	34,75	90,69	80,00	0,44	0,83	uniCe 050	-	71C-2B5	
	17,66	210,87	80,00	0,52	1,20	uniCe 063	-	80B-4B5	
	22,43	207,58	63,00	0,65	1,50	uniCe 063	-	80B-4B5	
	74,13	83,41	37,50	0,86	1,49	uniTeCe 040	6,25	71C-2B14	
	18,84	309,77	75,00	0,81	0,82	uniTeCe 050	6,25	80B-4B14	
	27,80	202,43	100,00	0,79	0,94	uniTeCe 050	6,25	71C-2B5	
	37,68	167,79	37,50	0,88	1,18	uniTeCe 050	6,25	80B-4B14	
	38,05	153,36	75,00	0,81	1,49	uniTeCe 050	6,25	80A-2B14	
	76,11	83,07	37,50	0,88	2,12	uniTeCe 050	6,25	80A-2B14	
	5,65	1020,26	250,00	0,81	0,95	uniTeCe 063	12,5	80B-4B5	
	7,54	765,20	187,50	0,81	0,87	uniTeCe 063	6,25	80B-4B5	
	8,90	640,41	312,50	0,80	1,14	uniTeCe 063	12,5	71C-2B5	
9,04	629,98	156,25	0,80	1,29	uniTeCe 063	6,25	80B-4B5		
11,30	510,13	125,00	0,81	1,90	uniTeCe 063	6,25	80B-4B5		
12,68	427,23	225,00	0,76	1,01	uniTeCe 063	6,25	80A-2B5		
13,90	434,85	200,00	0,84	1,15	uniTeCe 063	12,5	71C-2B5		
14,27	423,58	200,00	0,84	1,18	uniTeCe 063	12,5	80A-2B5		
15,22	387,97	187,50	0,82	1,57	uniTeCe 063	6,25	80A-2B5		
19,03	328,64	150,00	0,87	1,94	uniTeCe 063	12,5	80A-2B5		

**selection table based on power:**

P <sub>Mot</sub> [kW]	n <sub>2</sub> [1/min]	T <sub>2 Tab</sub> [Nm]	i <sub>ges</sub>	η [%]	f <sub>B</sub>	Getriebe	i Vorstufe	Motor
1,1	45,87	139,71	30,00	0,61	0,81	uniCe 040	-	80C-4B14
	55,04	125,97	25,00	0,66	1,14	uniCe 040	-	80C-4B14
	68,80	111,46	20,00	0,73	1,60	uniCe 040	-	80C-4B14
	71,53	82,25	40,00	0,56	1,03	uniCe 040	-	80B-2B14
	79,47	72,70	36,00	0,55	1,22	uniCe 040	-	80B-2B14
	86,00	90,39	16,00	0,74	1,14	uniCe 040	-	80C-4B14
	95,37	66,09	30,00	0,60	1,56	uniCe 040	-	80B-2B14
	114,67	73,29	12,00	0,80	1,66	uniCe 040	-	80C-4B14
	137,60	64,13	10,00	0,84	2,46	uniCe 040	-	80C-4B14
	143,05	52,87	20,00	0,72	2,99	uniCe 040	-	80B-2B14
	172,00	52,53	8,00	0,86	2,23	uniCe 040	-	80C-4B14
	178,81	43,47	16,00	0,74	2,09	uniCe 040	-	80B-2B14
	229,33	40,77	6,00	0,89	3,43	uniCe 040	-	80C-4B14
	238,42	34,81	12,00	0,79	3,30	uniCe 040	-	80B-2B14
	34,40	189,33	40,00	0,62	1,00	uniCe 050	-	80C-4B14
	37,83	180,48	36,00	0,65	1,19	uniCe 050	-	90S-4B14
	38,22	178,65	36,00	0,65	1,20	uniCe 050	-	80C-4B14
	54,48	138,83	25,00	0,72	2,07	uniCe 050	-	90S-4B14
	57,22	104,65	50,00	0,57	1,34	uniCe 050	-	80B-2B14
	85,13	99,96	16,00	0,81	2,17	uniCe 050	-	90S-4B14
	113,50	77,75	12,00	0,84	3,25	uniCe 050	-	90S-4B14
	21,62	315,84	63,00	0,65	0,98	uniCe 063	-	90S-4B14
	21,84	312,63	63,00	0,65	0,99	uniCe 063	-	80C-4B5
	27,24	273,81	50,00	0,71	1,44	uniCe 063	-	90S-4B14
	35,76	155,68	80,00	0,53	1,50	uniCe 063	-	80B-2B5
	45,40	192,05	30,00	0,83	3,47	uniCe 063	-	90S-4B14
	17,20	329,81	80,00	0,54	1,25	uniCe 080	-	80C-4B5
	22,89	342,81	125,00	0,75	0,96	uniTeCe 050	6,25	80B-2B14
	57,22	158,49	50,00	0,86	1,29	uniTeCe 050	6,25	80B-2B14
	76,29	121,54	37,50	0,88	1,45	uniTeCe 050	6,25	80B-2B14
	8,72	958,57	156,25	0,80	0,85	uniTeCe 063	6,25	90S-4B14
	9,16	912,67	312,50	0,80	0,80	uniTeCe 063	12,5	80B-2B5
	10,90	776,21	125,00	0,81	1,25	uniTeCe 063	6,25	90S-4B14
	11,01	768,31	125,00	0,81	1,26	uniTeCe 063	6,25	80C-4B5
	13,62	650,89	100,00	0,84	0,87	uniTeCe 063	6,25	90S-4B14
	14,31	619,73	200,00	0,84	0,80	uniTeCe 063	12,5	80B-2B5
	15,26	567,64	187,50	0,82	1,07	uniTeCe 063	6,25	80B-2B5
	18,16	505,00	75,00	0,87	1,40	uniTeCe 063	6,25	90S-4B14
	19,07	480,82	150,00	0,87	1,32	uniTeCe 063	12,5	80B-2B5
	27,24	347,89	50,00	0,90	1,51	uniTeCe 063	6,25	90S-4B14
	28,61	309,86	100,00	0,84	1,61	uniTeCe 063	6,25	80B-2B5
	36,32	263,72	37,50	0,91	1,54	uniTeCe 063	6,25	90S-4B14

**selection table based on power:**

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{2 Tab}$ [Nm]	$i_{ges}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
1,5	78,89	99,87	36,00	0,55	0,89	uniCe040	-	80C-2B14	
	94,67	90,79	30,00	0,60	1,13	uniCe040	-	80C-2B14	
	113,60	83,23	25,00	0,66	1,56	uniCe040	-	80C-2B14	
	142,00	72,63	20,00	0,72	2,18	uniCe040	-	80C-2B14	
	177,50	59,72	16,00	0,74	1,52	uniCe040	-	80C-2B14	
	236,67	47,82	12,00	0,79	2,40	uniCe040	-	80C-2B14	
	284,00	41,87	10,00	0,83	3,39	uniCe040	-	80C-2B14	
	355,00	34,30	8,00	0,85	3,03	uniCe040	-	80C-2B14	
	39,25	237,23	36,00	0,65	0,91	uniCe050	-	90L-4B14	
	47,10	212,90	30,00	0,70	1,21	uniCe050	-	90L-4B14	
	56,52	182,48	25,00	0,72	1,58	uniCe050	-	90L-4B14	
	70,65	156,13	20,00	0,77	2,37	uniCe050	-	90L-4B14	
	71,00	127,11	40,00	0,63	1,35	uniCe050	-	80C-2B14	
	88,31	131,39	16,00	0,81	1,65	uniCe050	-	90L-4B14	
	117,75	102,19	12,00	0,84	2,48	uniCe050	-	90L-4B14	
	141,30	88,20	10,00	0,87	3,64	uniCe050	-	90L-4B14	
	176,63	72,18	8,00	0,89	3,17	uniCe050	-	90L-4B14	
	235,50	55,35	6,00	0,91	3,58	uniCe050	-	90L-4B14	
	28,26	359,90	50,00	0,71	1,10	uniCe063	-	90L-4B14	
	35,33	308,20	40,00	0,76	1,57	uniCe063	-	90L-4B14	
	44,98	210,17	63,00	0,66	1,33	uniCe063	-	90S-2B14	
	45,08	209,73	63,00	0,66	1,34	uniCe063	-	80C-2B5	
	17,66	437,96	80,00	0,54	0,94	uniCe080	-	90L-4B5	
	22,43	408,76	63,00	0,64	1,05	uniCe080	-	90L-4B5	
	75,73	166,96	37,50	0,88	1,05	uniTeCe50	6,25	80C-2B14	
	11,30	1020,26	125,00	0,81	0,95	uniTeCe63	6,25	90L-4B14	
	18,84	663,79	75,00	0,87	1,07	uniTeCe63	6,25	90L-4B14	
	22,61	553,15	62,50	0,87	1,50	uniTeCe63	6,25	90L-4B14	
	28,26	457,27	50,00	0,90	1,15	uniTeCe63	6,25	90L-4B14	
	37,68	346,64	37,50	0,91	1,17	uniTeCe63	6,25	90L-4B14	

**selection table based on power:**

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{2Tab}$ [Nm]	$i_{ges}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
2,2	47,07	312,47	30,00	0,70	0,82	uniCe 050	-	90LB-4B14	
	56,48	267,83	25,00	0,72	1,08	uniCe 050	-	90LB-4B14	
	70,60	229,15	20,00	0,77	1,61	uniCe 050	-	90LB-4B14	
	77,92	177,97	36,00	0,66	1,11	uniCe 050	-	90L-2B14	
	88,25	192,84	16,00	0,81	1,13	uniCe 050	-	90LB-4B14	
	93,50	157,29	30,00	0,70	1,49	uniCe 050	-	90L-2B14	
	112,20	134,82	25,00	0,72	1,92	uniCe 050	-	90L-2B14	
	117,67	149,99	12,00	0,84	1,69	uniCe 050	-	90LB-4B14	
	140,25	115,35	20,00	0,77	2,84	uniCe 050	-	90L-2B14	
	141,20	129,45	10,00	0,87	2,48	uniCe 050	-	90LB-4B14	
	175,31	97,07	16,00	0,81	1,97	uniCe 050	-	90L-2B14	
	176,50	105,94	8,00	0,89	2,16	uniCe 050	-	90LB-4B14	
	233,75	75,50	12,00	0,84	3,02	uniCe 050	-	90L-2B14	
	235,33	81,24	6,00	0,91	2,44	uniCe 050	-	90LB-4B14	
	350,63	53,33	8,00	0,89	3,83	uniCe 050	-	90L-2B14	
		35,30	452,34	40,00	0,76	1,07	uniCe 063	-	90LB-4B14
		39,22	417,82	36,00	0,78	1,13	uniCe 063	-	90LB-4B14
		44,52	311,44	63,00	0,66	0,90	uniCe 063	-	90L-2B14
		57,24	300,98	25,00	0,82	2,69	uniCe 063	-	100LA-4B14
		71,55	243,72	20,00	0,83	3,97	uniCe 063	-	100LA-4B14
		89,44	204,37	16,00	0,87	2,76	uniCe 063	-	100LA-4B14
		28,24	505,91	50,00	0,68	1,07	uniCe 080	-	90LB-4B5
		17,65	666,61	80,00	0,56	1,20	uniCe 100	-	90LB-4B5
		22,59	811,87	62,50	0,87	1,02	uniTeCe 063	6,25	90LB-4B14
		37,65	508,77	37,50	0,91	0,80	uniTeCe 063	6,25	90LB-4B14
		74,80	256,11	37,50	0,91	1,32	uniTeCe 063	6,25	90L-2B14

**selection table based on power:**

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{zTab}$ [Nm]	$i_{gas}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
3	79,08	239,10	36,00	0,66	0,82	uniCe 050	-	90LB-2B14	
	94,90	211,33	30,00	0,70	1,11	uniCe 050	-	90LB-2B14	
	113,88	181,14	25,00	0,72	1,43	uniCe 050	-	90LB-2B14	
	142,35	154,97	20,00	0,77	2,12	uniCe 050	-	90LB-2B14	
	237,25	101,44	12,00	0,84	2,25	uniCe 050	-	90LB-2B14	
	284,70	87,55	10,00	0,87	3,29	uniCe 050	-	90LB-2B14	
	355,88	71,65	8,00	0,89	2,85	uniCe 050	-	90LB-2B14	
	474,50	54,95	6,00	0,91	3,20	uniCe 050	-	90LB-2B14	
	39,39	567,34	36,00	0,78	0,83	uniCe 063	-	100LB-4B14	
	47,27	503,09	30,00	0,83	1,32	uniCe 063	-	100LB-4B14	
	56,72	414,19	25,00	0,82	1,96	uniCe 063	-	100LB-4B14	
	57,70	352,54	50,00	0,71	1,01	uniCe 063	-	100L-2B14	
	70,90	335,39	20,00	0,83	2,88	uniCe 063	-	100LB-4B14	
	71,18	305,92	40,00	0,76	1,43	uniCe 063	-	90LB-2B14	
	72,13	301,89	40,00	0,76	1,45	uniCe 063	-	100L-2B14	
	80,14	278,85	36,00	0,78	1,55	uniCe 063	-	100L-2B14	
	88,63	281,25	16,00	0,87	2,01	uniCe 063	-	100LB-4B14	
	96,17	253,23	30,00	0,85	2,40	uniCe 063	-	100L-2B14	
	115,40	203,58	25,00	0,82	3,59	uniCe 063	-	100L-2B14	
	118,17	218,21	12,00	0,90	3,24	uniCe 063	-	100LB-4B14	
	177,25	150,32	8,00	0,93	3,49	uniCe 063	-	100LB-4B14	
	180,31	138,24	16,00	0,87	3,60	uniCe 063	-	100L-2B14	
	236,33	113,95	6,00	0,94	3,56	uniCe 063	-	100LB-4B14	
	35,45	581,89	40,00	0,72	1,17	uniCe 080	-	100LB-4B5	
	36,06	452,84	80,00	0,57	0,82	uniCe 080	-	100L-2B5	
	45,19	418,43	63,00	0,66	0,92	uniCe 080	-	90LB-2B5	
	141,80	179,82	10,00	0,89	3,94	uniCe 080	-	100LB-4B5	
	144,25	162,86	20,00	0,82	3,37	uniCe 080	-	100L-2B5	
	17,73	905,16	80,00	0,56	0,88	uniCe 100	-	100LB-4B5	
	22,51	763,73	63,00	0,60	1,19	uniCe 100	-	100LB-4B5	
	28,36	666,75	50,00	0,66	1,72	uniCe 100	-	100LB-4B5	
	37,96	658,89	75,00	0,87	0,97	uniTeCe 063	6,25	90LB-2B14	
	75,92	344,09	37,50	0,91	0,98	uniTeCe 063	6,25	90LB-2B14	



**selection table based on power:**

$P_{\text{Mick}}$ [kW]	$n_2$ [1/min]	$T_{2 \text{ Tab}}$ [Nm]	$i_{\text{gear}}$	$\eta$ [%]	$f_B$	Getriebe	$i_{\text{Vorstufe}}$	Motor
4	47,17	672,21	30,00	0,83	0,99	uniCe 063	-	100LC-4B14
	56,60	553,43	25,00	0,82	1,47	uniCe 063	-	100LC-4B14
	57,70	470,05	50,00	0,71	0,76	uniCe 063	-	100LB-2B14
	70,75	448,14	20,00	0,83	2,16	uniCe 063	-	100LC-4B14
	72,13	402,52	40,00	0,76	1,09	uniCe 063	-	100LB-2B14
	80,14	371,80	36,00	0,78	1,16	uniCe 063	-	100LB-2B14
	88,44	375,79	16,00	0,87	1,50	uniCe 063	-	100LC-4B14
	96,17	337,64	30,00	0,85	1,80	uniCe 063	-	100LB-2B14
	115,40	271,44	25,00	0,82	2,69	uniCe 063	-	100LB-2B14
	117,92	291,56	12,00	0,90	2,42	uniCe 063	-	100LC-4B14
	141,50	242,97	10,00	0,90	3,42	uniCe 063	-	100LC-4B14
	144,25	219,80	20,00	0,83	3,90	uniCe 063	-	100LB-2B14
	176,88	200,85	8,00	0,93	2,61	uniCe 063	-	100LC-4B14
	180,31	184,31	16,00	0,87	2,70	uniCe 063	-	100LB-2B14
	235,83	152,26	6,00	0,94	2,67	uniCe 063	-	100LC-4B14
	22,46	1020,47	63,00	0,60	0,89	uniCe 100	-	100LC-4B5
	28,30	890,88	50,00	0,66	1,29	uniCe 100	-	100LC-4B5
	35,38	777,50	40,00	0,72	1,90	uniCe 100	-	100LC-4B5
	36,06	614,38	80,00	0,58	1,20	uniCe 100	-	100LB-2B5
	39,31	719,19	36,00	0,74	2,18	uniCe 100	-	100LC-4B5
45,79	525,53	63,00	0,63	1,59	uniCe 100	-	100LB-2B5	

**selection table based on power:**

$P_{\text{Motor}}$ (kW)	$n_2$ (1/min)	$T_{2 \text{ Tab}}$ (Nm)	$i_{\text{gas}}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor
5,5	57,92	743,62	25,00	0,82	1,09	uniCe 063	-	112MB-4B14
	72,40	602,15	20,00	0,83	1,61	uniCe 063	-	112MB-4B14
	80,42	509,47	36,00	0,78	0,85	uniCe 063	-	112MB-2B14
	90,50	504,94	16,00	0,87	1,12	uniCe 063	-	112MB-4B14
	96,50	462,66	30,00	0,85	1,31	uniCe 063	-	112MB-2B14
	115,80	371,94	25,00	0,82	1,96	uniCe 063	-	112MB-2B14
	120,67	391,76	12,00	0,90	1,80	uniCe 063	-	112MB-4B14
	144,80	326,47	10,00	0,90	2,55	uniCe 063	-	112MB-4B14
	180,94	252,56	16,00	0,87	1,97	uniCe 063	-	112MB-2B14
	181,00	269,88	8,00	0,93	1,94	uniCe 063	-	112MB-4B14
	241,33	204,59	6,00	0,94	1,98	uniCe 063	-	112MB-4B14
	361,88	134,99	8,00	0,93	3,47	uniCe 063	-	112MB-2B14
	482,50	102,33	6,00	0,94	3,30	uniCe 063	-	112MB-2B14
	58,20	703,94	25,00	0,78	1,62	uniCe 080	-	132S-4B5
	81,08	492,32	36,00	0,76	1,40	uniCe 080	-	132SA-2B5
	97,30	421,06	30,00	0,78	2,03	uniCe 080	-	132SA-2B5
	116,76	359,88	25,00	0,80	2,86	uniCe 080	-	132SA-2B5
	121,25	381,21	12,00	0,88	2,59	uniCe 080	-	132S-4B5
	145,50	321,29	10,00	0,89	2,20	uniCe 080	-	132S-4B5
	182,44	250,48	16,00	0,87	2,77	uniCe 080	-	132SA-2B5
	291,90	161,95	10,00	0,90	3,91	uniCe 080	-	132SA-2B5
	28,96	1197,05	50,00	0,66	0,96	uniCe 100	-	112MB-4B5
	29,10	1191,29	50,00	0,66	0,97	uniCe 100	-	132S-4B5
	36,20	1044,70	40,00	0,72	1,42	uniCe 100	-	112MB-4B5
	40,22	966,34	36,00	0,74	1,62	uniCe 100	-	112MB-4B5
	45,95	720,11	63,00	0,63	1,16	uniCe 100	-	112MB-2B5
	46,33	714,19	63,00	0,63	1,17	uniCe 100	-	132SA-2B5

**selection table based on power:**

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{2 Tab}$ [Nm]	$i_{gas}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
7,5	58,12	1010,54	25,00	0,82	0,80	uniCe 063	-	112MC-4B14	
	72,65	818,29	20,00	0,83	1,18	uniCe 063	-	112MC-4B14	
	90,81	686,18	16,00	0,87	0,82	uniCe 063	-	112MC-4B14	
	96,00	634,18	30,00	0,85	0,96	uniCe 063	-	112MC-2B14	
	115,20	509,83	25,00	0,82	1,43	uniCe 063	-	112MC-2B14	
	121,08	532,38	12,00	0,90	1,33	uniCe 063	-	112MC-4B14	
	144,00	412,84	20,00	0,83	2,08	uniCe 063	-	112MC-2B14	
	145,30	443,65	10,00	0,90	1,88	uniCe 063	-	112MC-4B14	
	180,00	346,19	16,00	0,87	1,44	uniCe 063	-	112MC-2B14	
	181,63	366,75	8,00	0,93	1,43	uniCe 063	-	112MC-4B14	
	240,00	268,59	12,00	0,90	2,37	uniCe 063	-	112MC-2B14	
	242,17	278,02	6,00	0,94	1,46	uniCe 063	-	112MC-4B14	
	288,00	223,83	10,00	0,90	3,33	uniCe 063	-	112MC-2B14	
	360,00	185,03	8,00	0,93	2,53	uniCe 063	-	112MC-2B14	
	480,00	140,27	6,00	0,94	2,41	uniCe 063	-	112MC-2B14	
	48,73	1117,00	30,00	0,76	0,85	uniCe 080	-	132MA-4B5	
	80,92	673	36,00	0,76	1,0	uniCe 080	-	132SB-2B5	
	91,38	674,12	16,00	0,86	1,16	uniCe 080	-	132MA-4B5	
	97,10	575,36	30,00	0,78	1,49	uniCe 080	-	132SB-2B5	
	116,52	491,76	25,00	0,80	2,09	uniCe 080	-	132SB-2B5	
	146,20	436,02	10,00	0,89	1,62	uniCe 080	-	132MA-4B5	
	182,75	360,57	8,00	0,92	2,61	uniCe 080	-	132MA-4B5	
	243,67	276,31	6,00	0,94	2,97	uniCe 080	-	132MA-4B5	
	291,30	221,29	10,00	0,90	2,86	uniCe 080	-	132SB-2B5	
	36,33	1419,68	40,00	0,72	1,04	uniCe 100	-	112MC-4B5	
	40,36	1313,21	36,00	0,74	1,20	uniCe 100	-	112MC-4B5	
45,71	987,08	63,00	0,63	0,85	uniCe 100	-	112MC-2B5		
46,24	975,90	63,00	0,63	0,86	uniCe 100	-	132SB-2B5		
57,60	845,57	50,00	0,68	1,22	uniCe 100	-	112MC-2B5		
73,10	813,25	20,00	0,83	1,61	uniCe 100	-	132MA-4B5		

$P_{Mot}$ [kW]	$n_2$ [1/min]	$T_{2 Tab}$ [Nm]	$i_{gas}$	$\eta$ [%]	$f_B$	Getriebe	$i$ Vorstufe	Motor	
9,2	58,80	1165,49	25,00	0,78	0,98	uniCe 080	-	132MB-4B5	
	81,75	816,80	36,00	0,76	0,85	uniCe 080	-	132MA-2B5	
	91,88	822,42	16,00	0,86	0,95	uniCe 080	-	132MB-4B5	
	98,10	698,58	30,00	0,78	1,23	uniCe 080	-	132MA-2B5	
	117,72	597,08	25,00	0,80	1,73	uniCe 080	-	132MA-2B5	
	122,50	631,16	12,00	0,88	1,56	uniCe 080	-	132MB-4B5	
	147,00	531,94	10,00	0,89	1,33	uniCe 080	-	132MB-4B5	
	183,75	439,90	8,00	0,92	2,14	uniCe 080	-	132MB-4B5	
	245,00	337,10	6,00	0,94	2,43	uniCe 080	-	132MB-4B5	
	294,30	268,69	10,00	0,90	2,36	uniCe 080	-	132MA-2B5	
	367,88	217,34	8,00	0,91	3,45	uniCe 080	-	132MA-2B5	
	490,50	166,58	6,00	0,93	3,84	uniCe 080	-	132MA-2B5	
	36,75	1721,34	40,00	0,72	0,86	uniCe 100	-	132MB-4B5	
	40,83	1592,24	36,00	0,74	0,99	uniCe 100	-	132MB-4B5	
	49,00	1398,59	30,00	0,78	1,41	uniCe 100	-	132MB-4B5	
	73,50	992,16	20,00	0,83	1,32	uniCe 100	-	132MB-4B5	

**selection table based on power:**

$P_{\text{Motor}}$ [kW]	$n_2$ [1/min]	$T_{2 \text{ Tab}}$ [Nm]	$i_{\text{ges}}$	$\eta$ [%]	$f_B$	Getriebe	$i_{\text{Vorstufe}}$	Motor
11	97,30	842,13	30,00	0,78	1,02	uniCe 080	-	132MB-2B5
	116,76	719,77	25,00	0,80	1,43	uniCe 080	-	132MB-2B5
	121,67	759,81	12,00	0,88	1,30	uniCe 080	-	132MC-4B5
	146,00	640,37	10,00	0,89	1,11	uniCe 080	-	132MC-4B5
	182,50	529,57	8,00	0,92	1,78	uniCe 080	-	132MC-4B5
	243,33	405,81	6,00	0,94	2,02	uniCe 080	-	132MC-4B5
	291,90	323,90	10,00	0,90	1,96	uniCe 080	-	132MB-2B5
	364,88	262,00	8,00	0,91	2,86	uniCe 080	-	132MB-2B5
	486,50	200,82	6,00	0,93	3,19	uniCe 080	-	132MB-2B5
	40,56	1916,80	36,00	0,74	0,82	uniCe 100	-	132MC-4B5
	48,67	1683,68	30,00	0,78	1,17	uniCe 100	-	132MC-4B5
	58,40	1457,03	25,00	0,81	1,58	uniCe 100	-	132MC-4B5
	73,00	1194,40	20,00	0,83	1,10	uniCe 100	-	132MC-4B5
	81,08	984,64	36,00	0,76	1,44	uniCe 100	-	132MB-2B5
	91,25	1001,57	16,00	0,87	1,64	uniCe 100	-	132MC-4B5

$P_{\text{Motor}}$ [kW]	$n_2$ [1/min]	$T_{2 \text{ Tab}}$ [Nm]	$i_{\text{ges}}$	$\eta$ [%]	$f_B$	Getriebe	$i_{\text{Vorstufe}}$	Motor
15	117,44	975,82	25,00	0,80	1,06	uniCe 080	-	132MC-2B5
	121,42	1038,24	12,00	0,88	0,95	uniCe 080	-	132MD-4B5
	145,70	875,03	10,00	0,89	0,81	uniCe 080	-	132MD-4B5
	182,13	723,62	8,00	0,92	1,30	uniCe 080	-	132MD-4B5
	242,83	554,52	6,00	0,94	1,48	uniCe 080	-	132MD-4B5
	293,60	439,12	10,00	0,90	1,44	uniCe 080	-	132MC-2B5
	367,00	355,20	8,00	0,91	2,11	uniCe 080	-	132MC-2B5
	489,33	272,25	6,00	0,93	2,35	uniCe 080	-	132MC-2B5
	48,57	2300,65	30,00	0,78	0,86	uniCe 100	-	132MD-4B5
	58,28	1990,95	25,00	0,81	1,16	uniCe 100	-	132MD-4B5
	72,85	1632,09	20,00	0,83	0,80	uniCe 100	-	132MD-4B5
	73,30	1622,07	20,00	0,83	0,81	uniCe 100	-	160L-4B5
	81,56	1334,92	36,00	0,76	1,06	uniCe 100	-	132MC-2B5
	91,06	1368,59	16,00	0,87	1,20	uniCe 100	-	132MD-4B5
	97,87	1170,98	30,00	0,80	1,50	uniCe 100	-	132MC-2B5
	98,03	1168,99	30,00	0,80	1,51	uniCe 100	-	160MB-2B5
	122,17	1043,59	12,00	0,89	1,95	uniCe 100	-	160L-4B5
	146,60	889,21	10,00	0,91	1,64	uniCe 100	-	160L-4B5
	147,05	828,03	20,00	0,85	1,40	uniCe 100	-	160MB-2B5
	183,25	727,00	8,00	0,93	1,80	uniCe 100	-	160L-4B5
	244,33	551,11	6,00	0,94	2,18	uniCe 100	-	160L-4B5
	245,08	526,05	12,00	0,90	2,47	uniCe 100	-	160MB-2B5
	294,10	448,11	10,00	0,92	2,90	uniCe 100	-	160MB-2B5
	490,17	277,64	6,00	0,95	3,60	uniCe 100	-	160MB-2B5

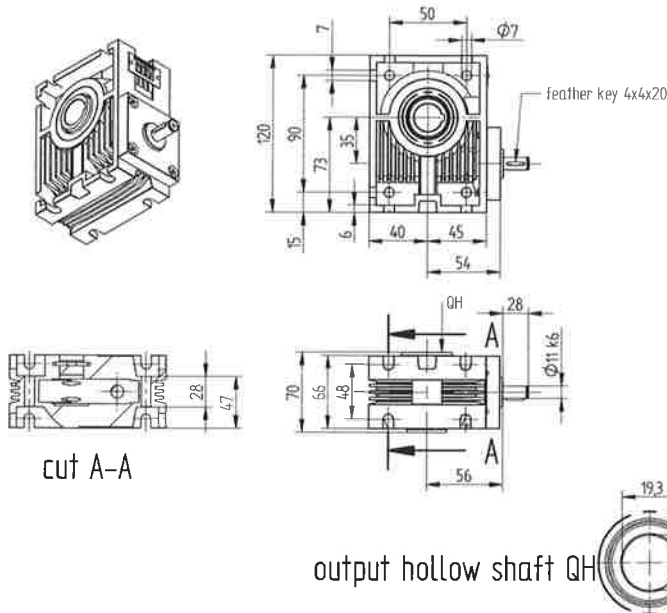
**selection table based on power:**

$P_{\text{Motor}}$ [kW]	$n_2$ [1/min]	$T_{2\text{Tab}}$ [Nm]	$i_{\text{ges}}$	$\eta$ [%]	$f_B$	Getriebe	$i_{\text{Vorstufe}}$	Motor
18,5	59,04	2423,89	25,00	0,81	0,95	uniCe 100	-	180M-4B5
	81,94	1638,59	36,00	0,76	0,87	uniCe 100	-	160L-2B5
	92,25	1666,20	16,00	0,87	0,98	uniCe 100	-	180M-4B5
	123,00	1278,38	12,00	0,89	1,59	uniCe 100	-	180M-4B5
	147,60	1089,26	10,00	0,91	1,34	uniCe 100	-	180M-4B5
	184,50	890,56	8,00	0,93	1,47	uniCe 100	-	180M-4B5
	246,00	675,10	6,00	0,94	1,78	uniCe 100	-	180M-4B5
	295,00	550,99	10,00	0,92	2,36	uniCe 100	-	160L-2B5
	368,75	450,37	8,00	0,94	2,58	uniCe 100	-	160L-2B5
	491,67	341,37	6,00	0,95	2,93	uniCe 100	-	160L-2B5

# measurements uniCe 035 & uniTeCe 035

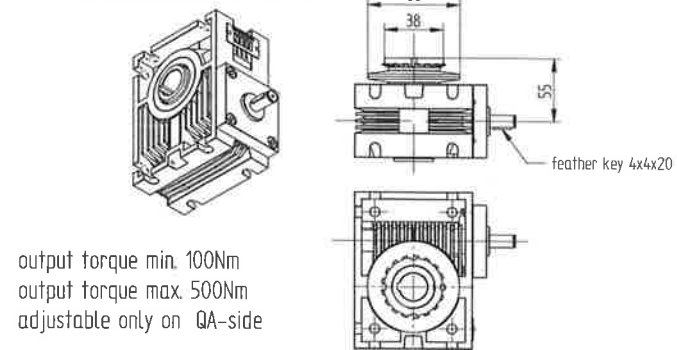
## uniCe-035-N-00-W-QH

gear with axle drive shaft and output hollow shaft



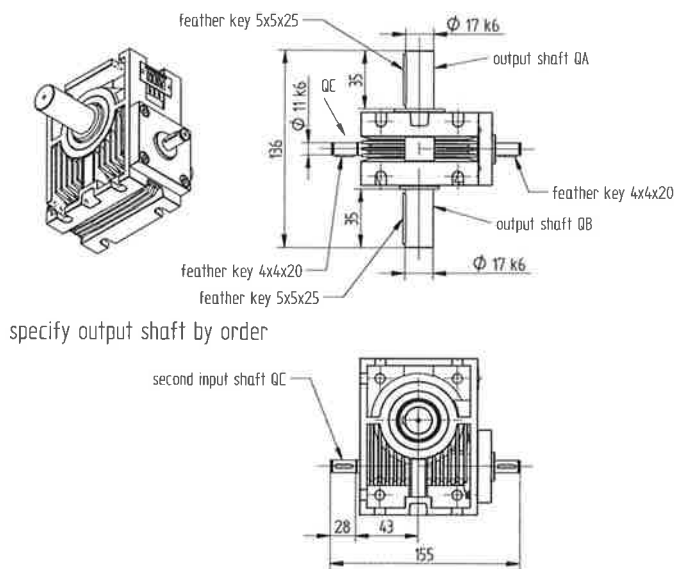
## uniCe-035-R-00-W-QH

gear with axle drive shaft, output hollow shaft and adjustable slip coupling



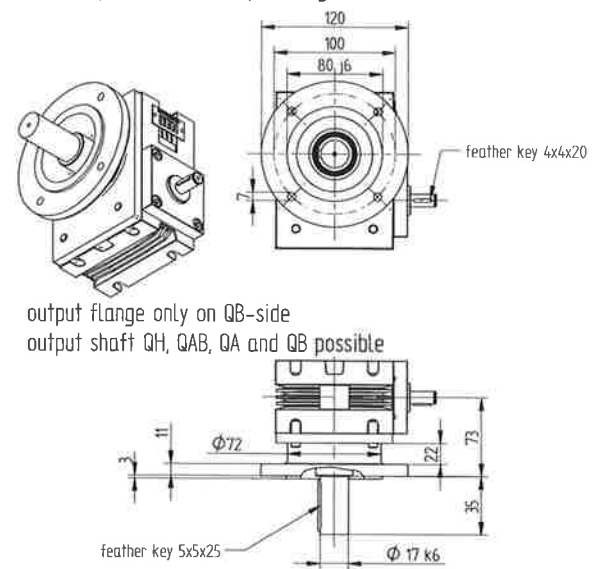
## uniCe-035-N-00-W-QAB-00-QC

gear with two input and output shafts



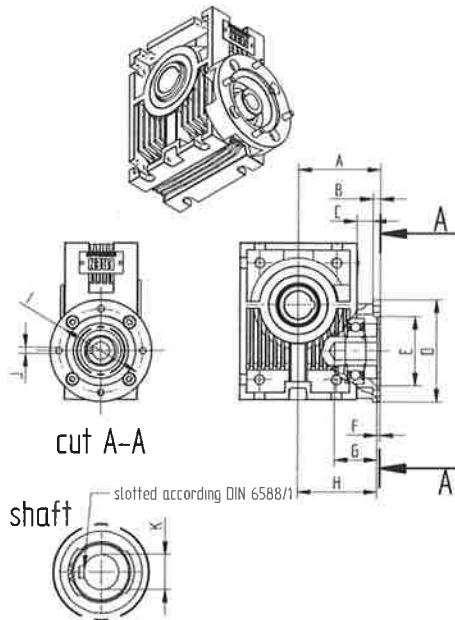
## uniCe-035-N-00-W-QB-Fl

gear with output shaft QB, output flange and axle drive shaft

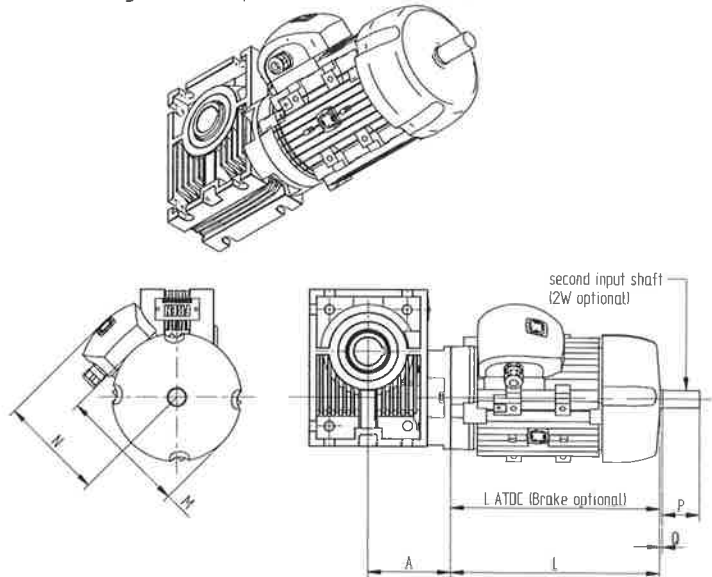


choice the gear according to the typ designation on page 3

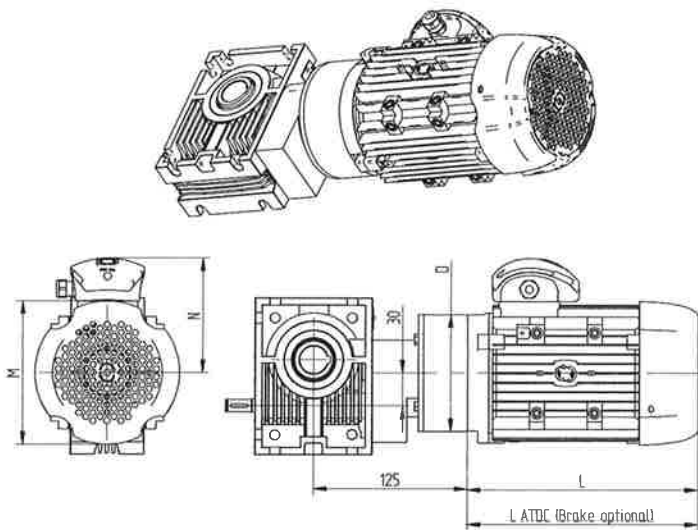
uniCe-035-N-00-JM/000/00-QH  
gear with input hollow shaft, output hollow shaft and flange



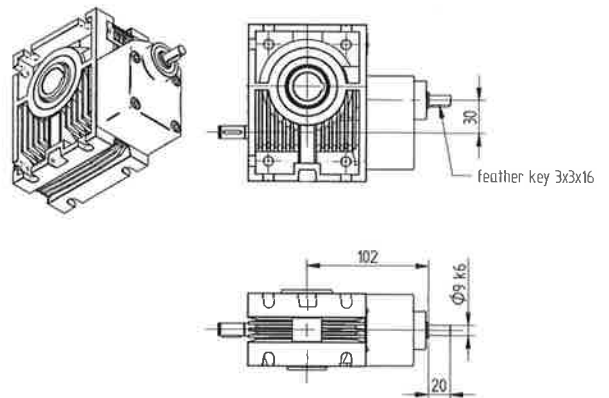
uniCe-035-N-00-Motor-QH  
gear with output hollow shaft and motor



uniTeCe-035-N-00-Motor-QH-00-QC  
gear with pre-stage, output hollow shaft, second input shaft and motor



uniTeCe-035-N-00-W-QH  
gear with pre-stage, output hollow shaft, axle drive shaft and second input shaft

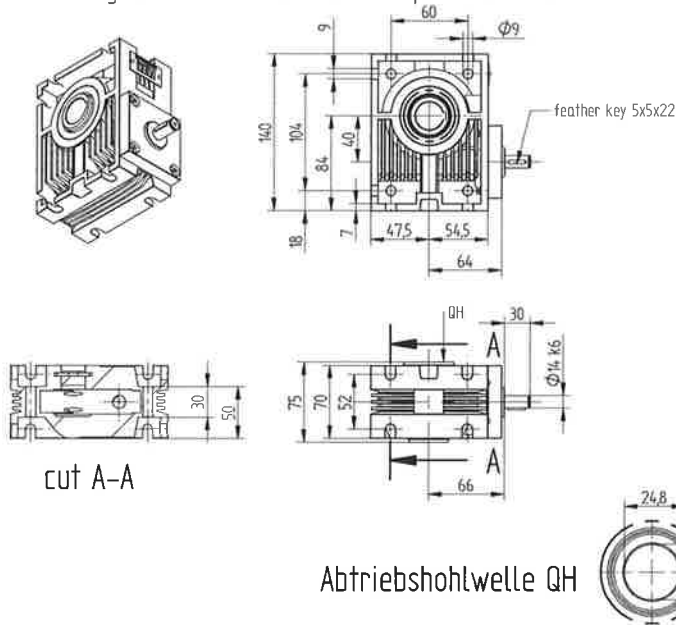


uniCe 035	A	B	C	D	E H7	F	G	H	I	J	K	L	L ATDC	M	N	O	P	Q
63B14	65	7	13	90	60	3,5	30	62	75	6	9,11,14	186,5	214,5	130	114	11	23	3
71B14		8	12	105	70				85	7		207,5	237,5	145	119	14	30	3
56B5		10	10	140	95	4			100	7		141		120	102	9	20	3
									115	9								

# measurements uniCe 040 & uniTeCe 040

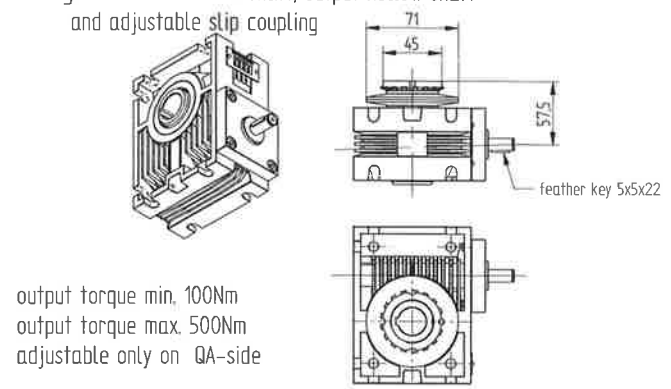
## uniCe-040-N-00-W-QH

gear with axle drive shaft and output hollow shaft



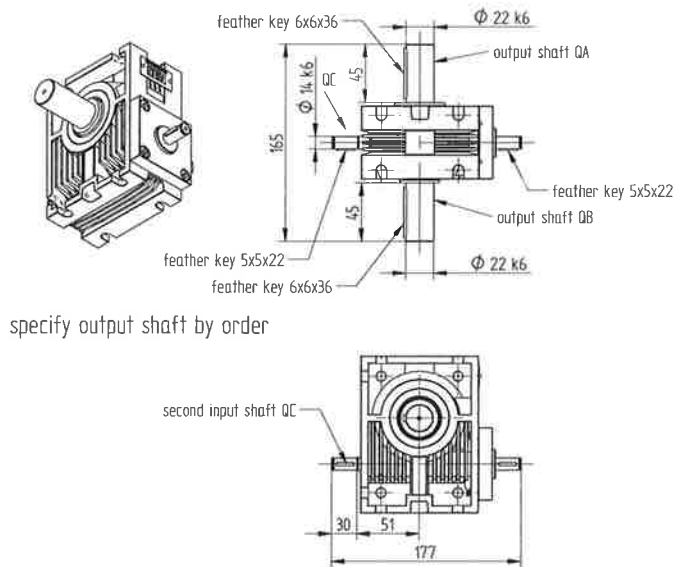
## uniCe-040-R-00-W-QH

gear with axle drive shaft, output hollow shaft and adjustable slip coupling



## uniCe-040-N-00-W-QAB-00-QC

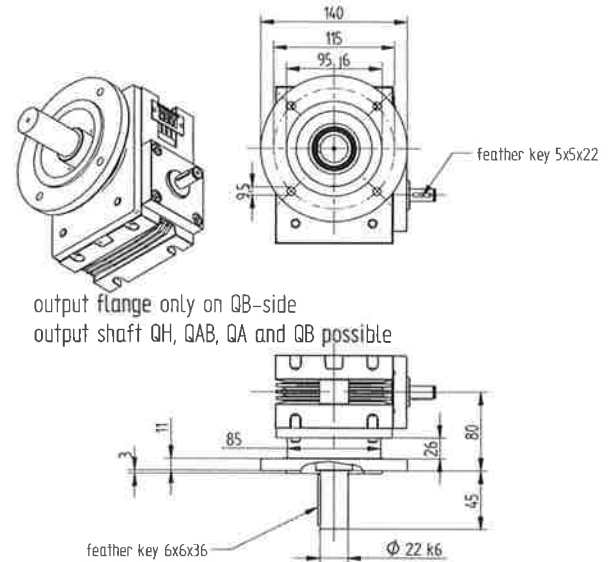
gear with two input and output shafts



specify output shaft by order

## uniCe-040-N-00-W-QB-FL

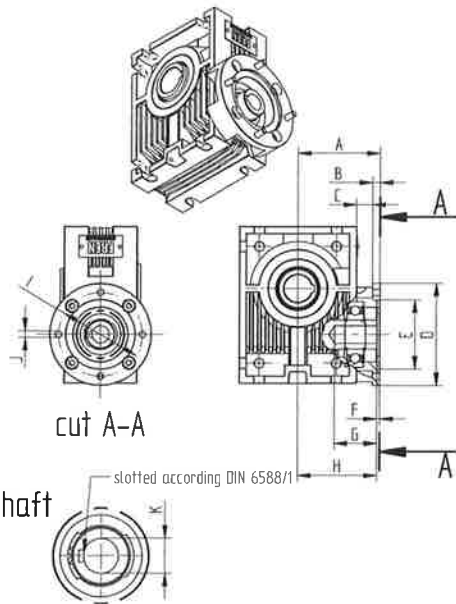
gear with output shaft QB, output flange and axle drive shaft



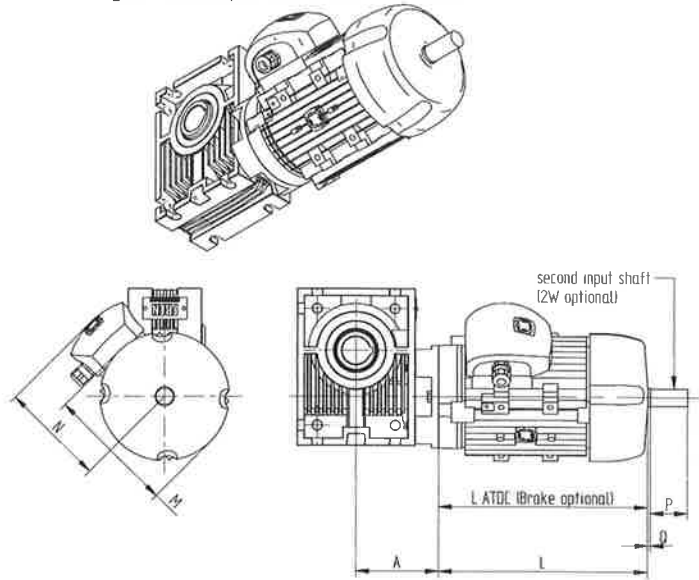
choice the gear according to the typ designation on page 3



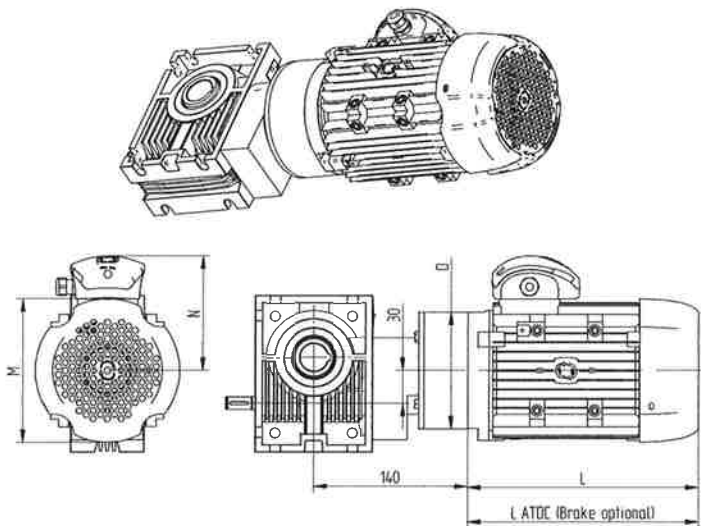
**uniCe-040-N-00-JM/000/00-QH**  
 gear with input hollow shaft, output hollow shaft and flange



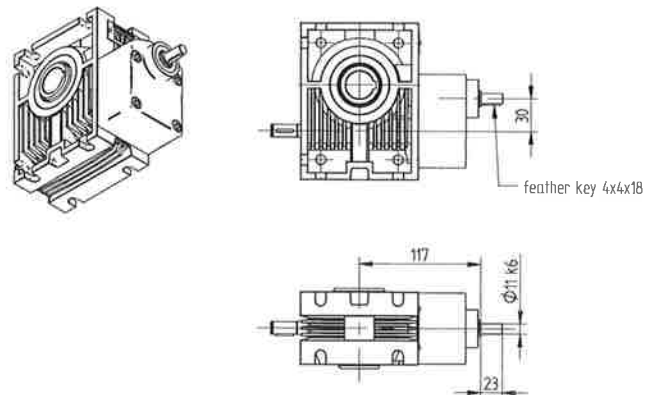
**uniCe-040-N-00-Motor-QH**  
 gear with output hollow shaft and motor



**uniTeCe-040-N-00-Motor-QH-00-QC**  
 gear with pre-stage, output hollow shaft, second input shaft and motor



**uniTeCe-040-N-00-W-QH**  
 gear with pre-stage, output hollow shaft, axle drive shaft and second input shaft

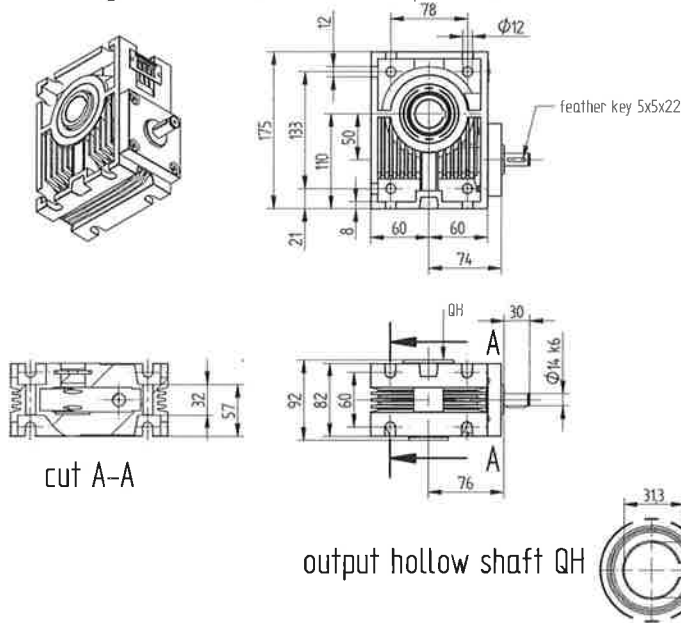


uniCe 040	A	B	C	D	E	H7	F	G	H	I	J	K	L	L ATDC	M	N	O	P	Q
63B14	74,5	8	12	90	60	3,5		40	71	75	6	9, 11, 14, 19	186,5	214,5	130	114	11	23	3
71B14				105	70	3,5				85	207,5		237,5	145	119	14	30	3	
56B5		10	10	120	80	4	100	7	141	120	102		9	20	3				
80B14				140	95	4	115	9	233	332	175		130	19	40	3			
				160	110	4,5				130	9								

# measurements uniCe 050 & uniTeCe 050

## uniCe-050-N-00-W-QH

gear with axle drive shaft and output hollow shaft

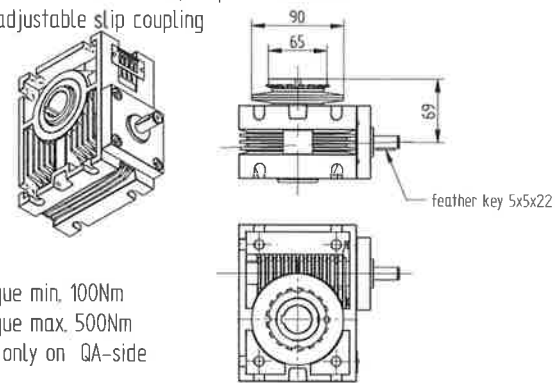


cut A-A

output hollow shaft QH

## uniCe-050-R-00-W-QH

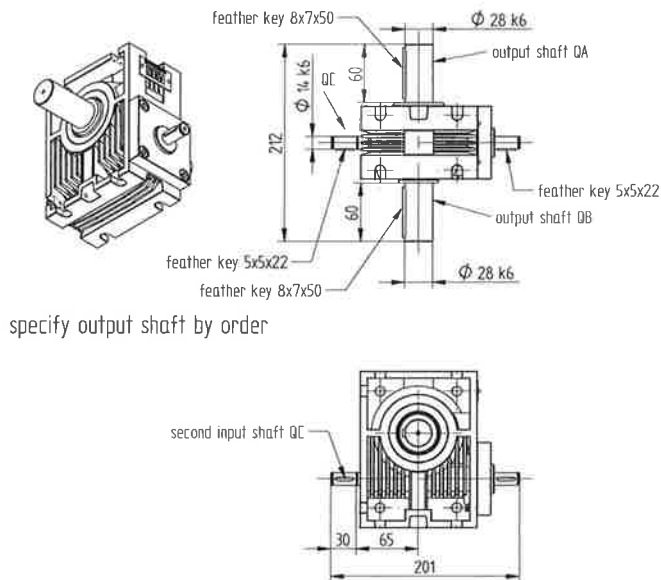
gear with axle drive shaft, output hollow shaft and adjustable slip coupling



output torque min. 100Nm  
output torque max. 500Nm  
adjustable only on QA-side

## uniCe-050-N-00-W-QAB-00-QC

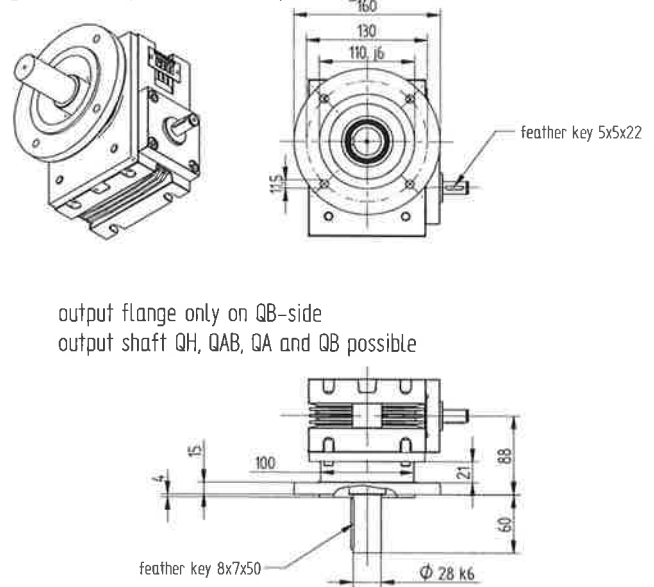
gear with two input and output shafts



specify output shaft by order

## uniCe-050-N-00-W-QB-FL

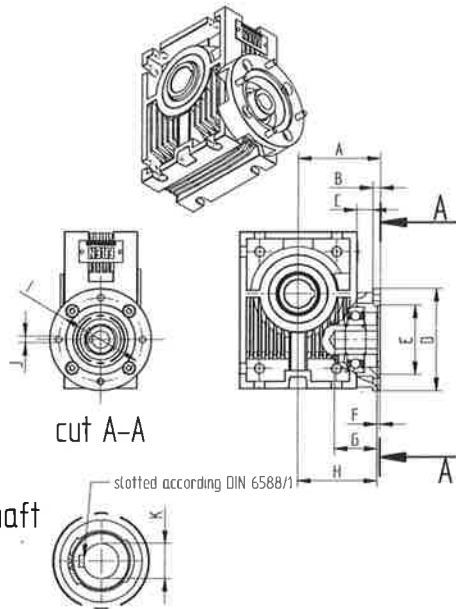
gear with output shaft QB, output flange and axle drive shaft



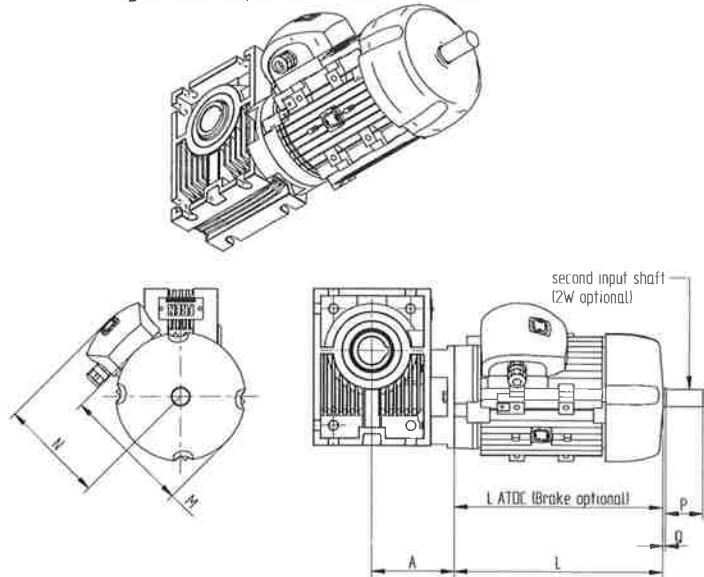
output flange only on QB-side  
output shaft QH, QAB, QA and QB possible

choice the gear according to the typ designation on page 3

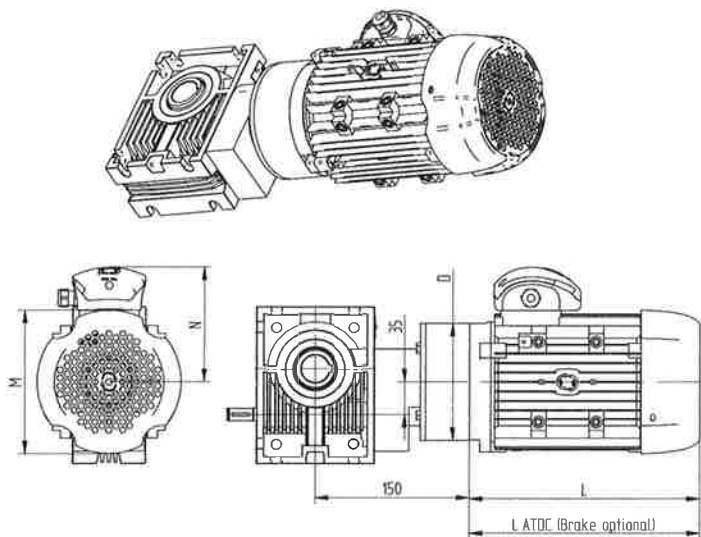
uniCe-050-N-00-JM/000/00-QH  
gear with input hollow shaft, output hollow shaft and flange



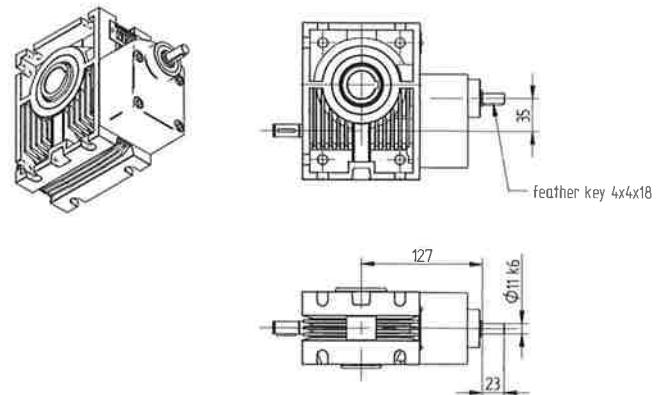
uniCe-050-N-00-Motor-QH  
gear with output hollow shaft and motor



uniTeCe-050-N-00-Motor-QH-00-QC  
gear with pre-stage, output hollow shaft, second input shaft and motor



uniTeCe-050-N-00-W-QH  
gear with pre-stage, output hollow shaft, axle drive shaft and second input shaft

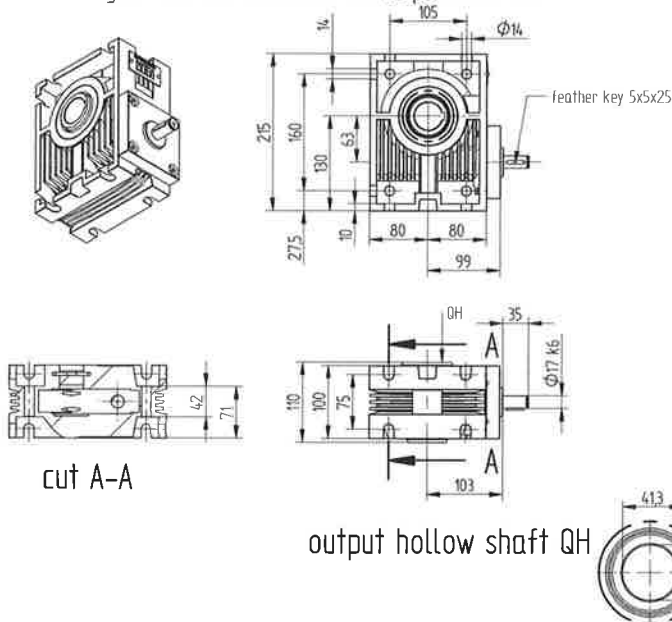


uniCe 050	A	B	C	D	E H7	F	G	H	I	J	K	L	L ATDC	M	N	O	P	Q	
80B14	88	8	20	120	80	4	50	86	100	7	11,14,19,24	233	332	175	130	19	40	3	
63B5		10	18	140	95				4,5	115		9	186,5	214,5	130	114	11	23	3
90SB14													252	347	195	145	24	50	5
90LB14		277	373	195	145	24			50	5									
71B5		207,5	237,5	145	119	14			30	3									
		13	15	200	130				165	11									

# measurements uniCe 063 & uniTeCe 063

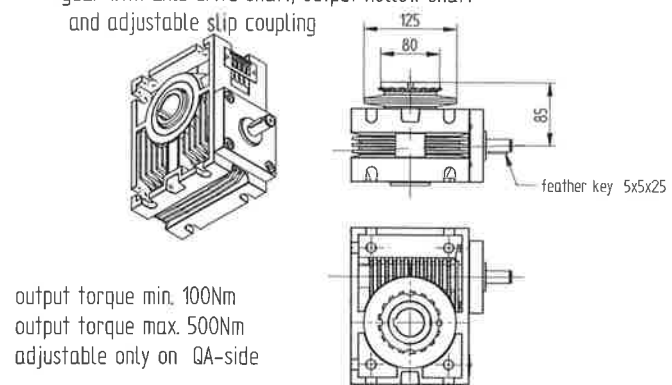
## uniCe-063-N-00-W-QH

gear with axle drive shaft and output hollow shaft



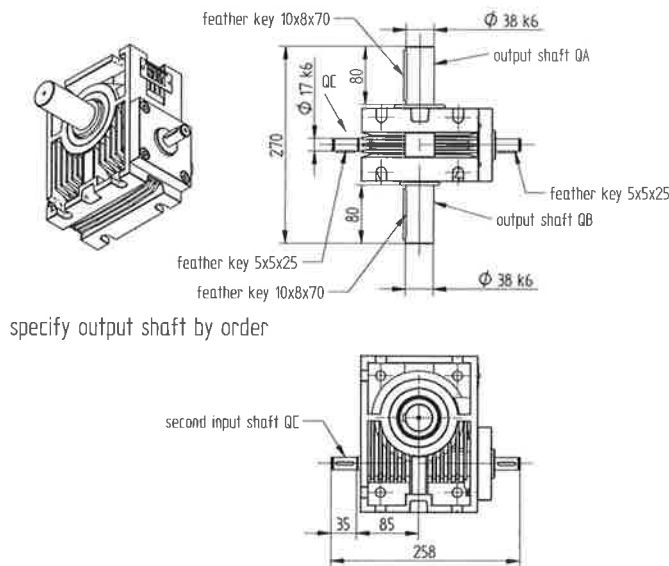
## uniCe-063-R-00-W-QH

gear with axle drive shaft, output hollow shaft and adjustable slip coupling



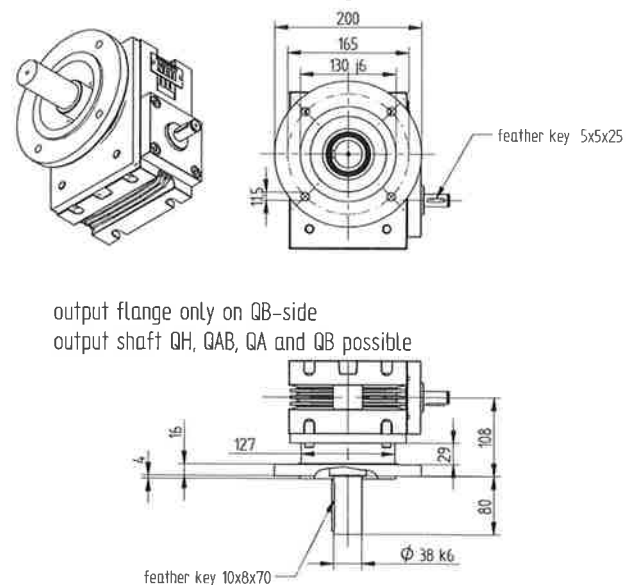
## uniCe-063-N-00-W-QAB-00-QC

gear with two input and output shafts



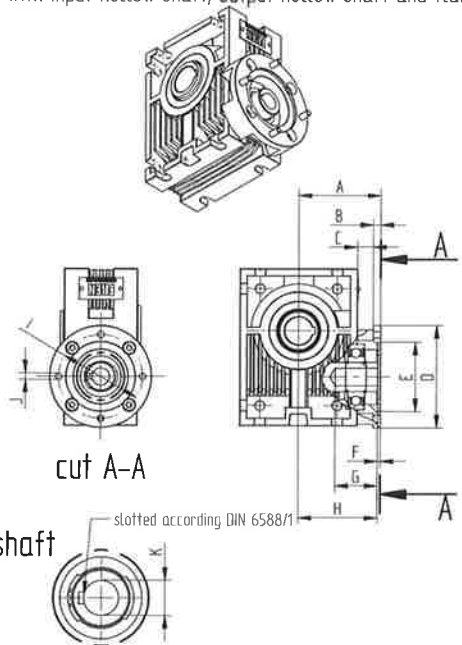
## uniCe-063-N-00-W-QB-Fl

gear with output shaft QB, output flange and axle drive shaft

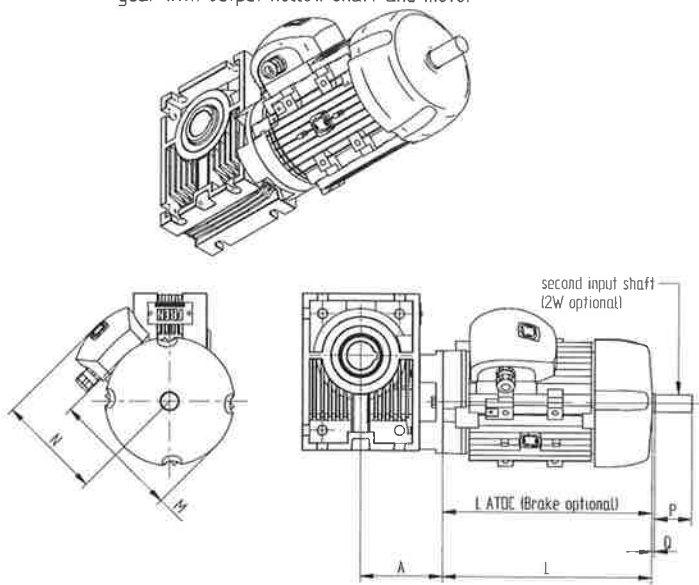


choice the gear according to the typ designation on page 3

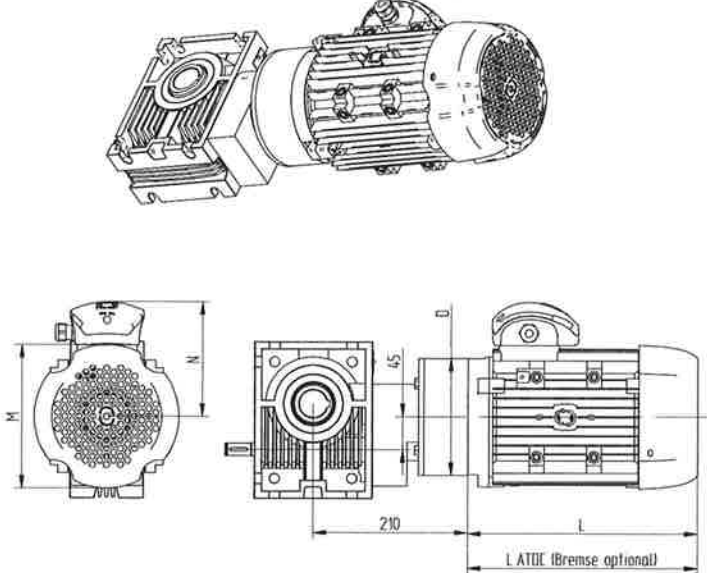
**uniCe-063-N-00-JM/000/00-QH**  
 gear with input hollow shaft, output hollow shaft and flange



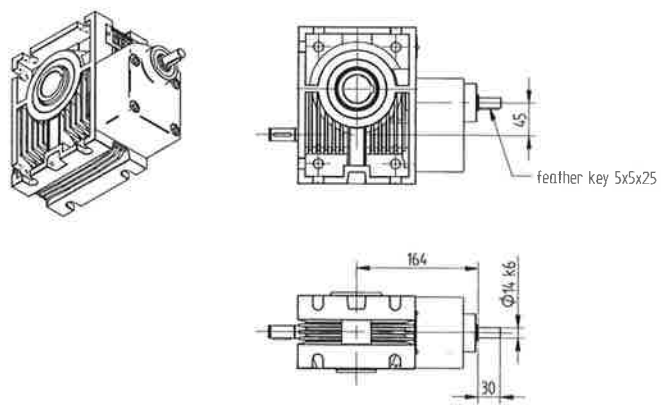
**uniCe-063-N-00-Motor-QH**  
 gear with output hollow shaft and motor



**uniTeCe-063-N-00-Motor-QH-00-QC**  
 gear with pre-stage, output hollow shaft, second input shaft and motor



**uniTeCe-063-N-00-W-QH**  
 gear with pre-stage, output hollow shaft, axle drive shaft and second input shaft

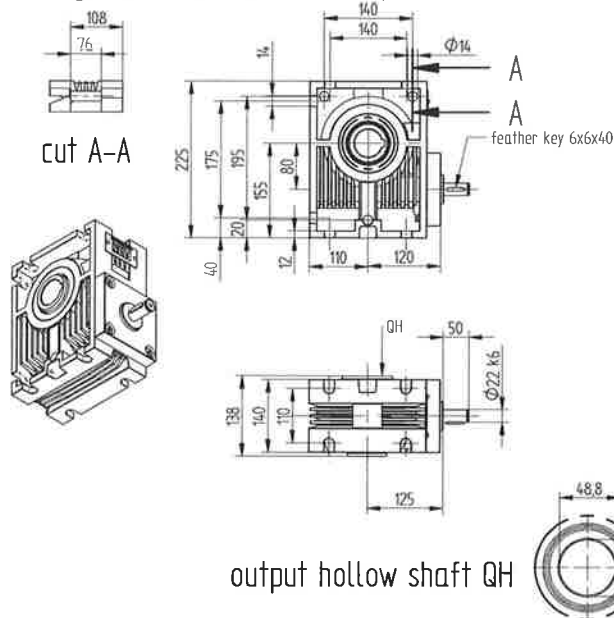


uniCe 063	A	B	C	D	E	H7	F	G	H	I	J	K	L	L ATDC	M	N	O	P	Q				
90SB14	112	10	22	140	95	4	60	108	130	115	9	14, 19, 24, 28	252	347	195	145	24	50	5				
90LB14				277	373	195							145	24	50	5							
71B5				207,5	237,5	145							119	14	30	3							
100B14				307,5	401,5	215							170	28	60	5							
112B14				316,5	431,5	240							177	28	60	5							
80B5				16	16	200							130	5	65	11	233	332	175	130	19	40	3
				21	11	250							180		215	14							

# measurements uniCe 080

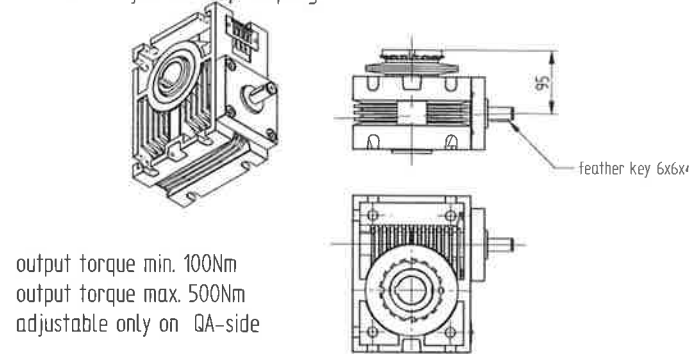
## uniCe-080-N-00-W-QH

gear with axle drive shaft and output hollow shaft



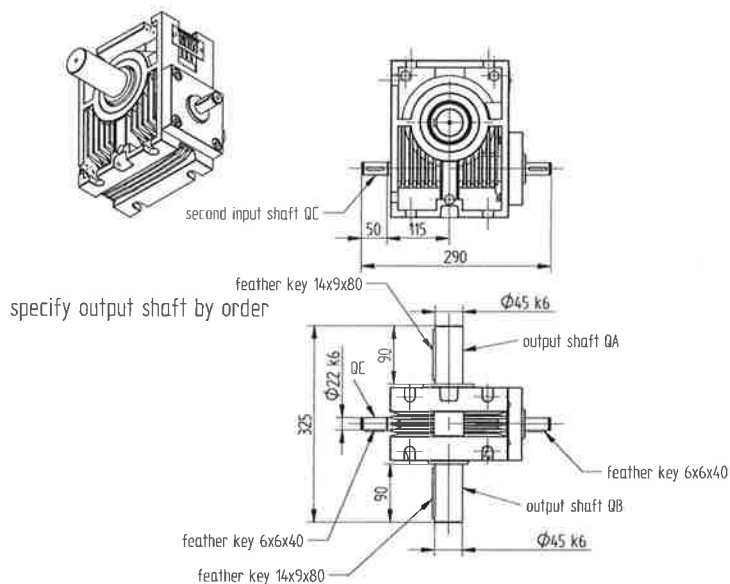
## uniCe-080-R-00-W-QH

gear with axle drive shaft, output hollow shaft and adjustable slip coupling



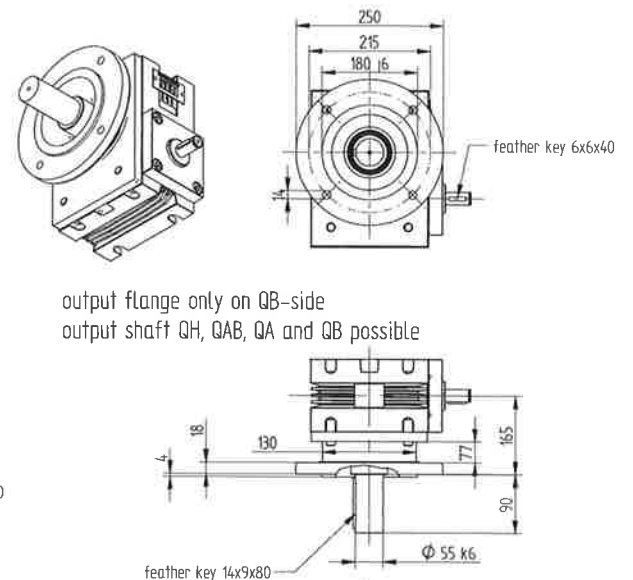
## uniCe-080-N-00-W-QAB-00-QC

gear with two input and output shafts



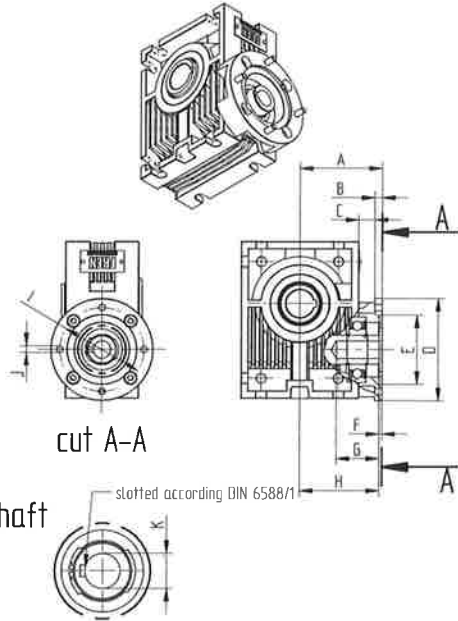
## uniCe-080-N-00-W-QB-FL

gear with output shaft QB, output flange and axle drive shaft

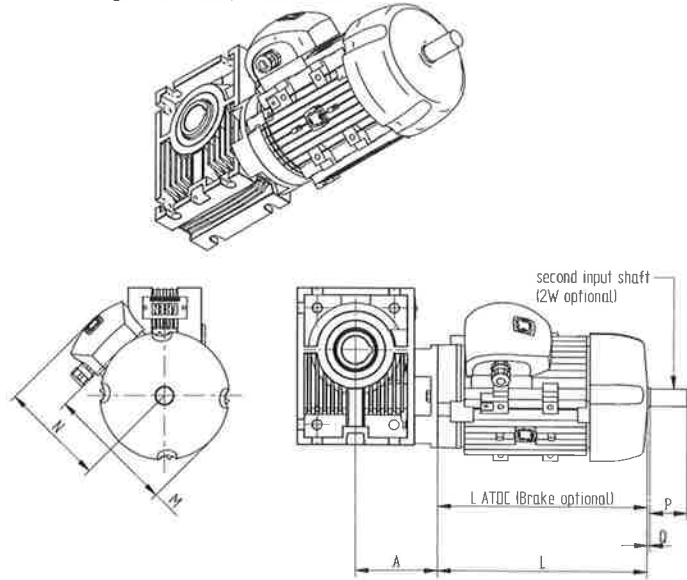


choice the gear according to the typ designation on page 3

uniCe-080-N-00-JM/000/00-QH  
gear with input hollow shaft, output hollow shaft and flange



uniCe-080-N-00-Motor-QH  
gear with output hollow shaft and motor

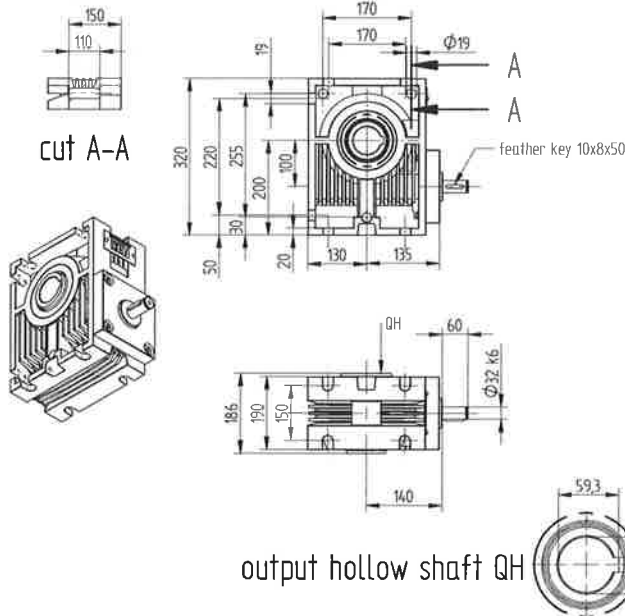


uniCe 080	A	B	C	D	E	H7	F	G	H	I	J	K	L	LATDC	M	N	O	P	Q
	131			160	110					130									
80B5	120	13		200	130	4,5		80	115	165	M10	19,24,28,38	233	332	175	130	19	40	3
90SB5													252	347	195	145	24	50	5
90LB5													277	373	195	145	24	50	5
100B5	140	17		250	180	5			215	M12	307,5		401,5	215	170	28	60	5	
112B5											316,5		431,5	240	177	28	60	5	
132SB5											371		486	275	197	38	80	5	
132MB5											411	526	275	197	38	80	5		

# measurements uniCe 100

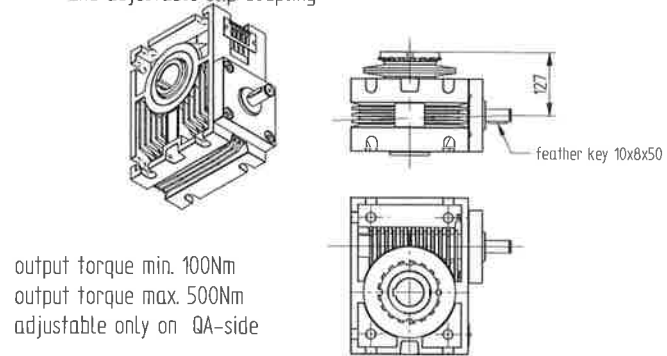
## uniCe-100-N-00-W-QH

gear with axle drive shaft and output hollow shaft



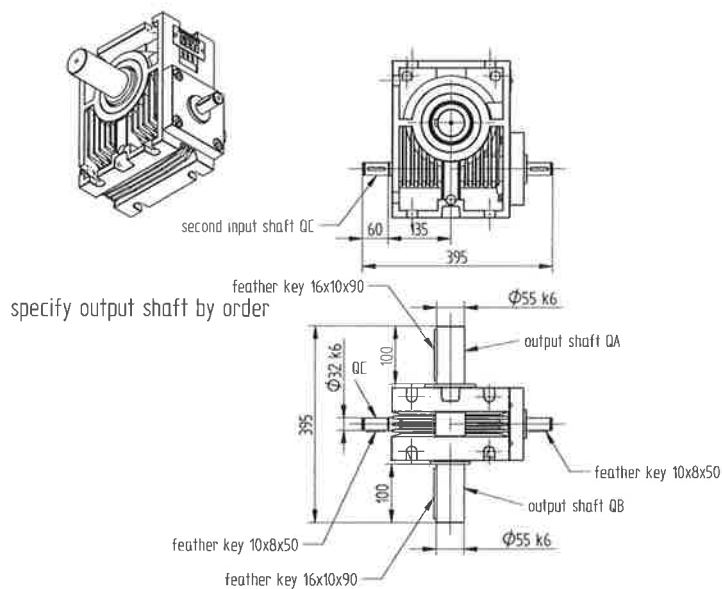
## uniCe-100-R-00-W-QH

gear with axle drive shaft, output hollow shaft and adjustable slip coupling



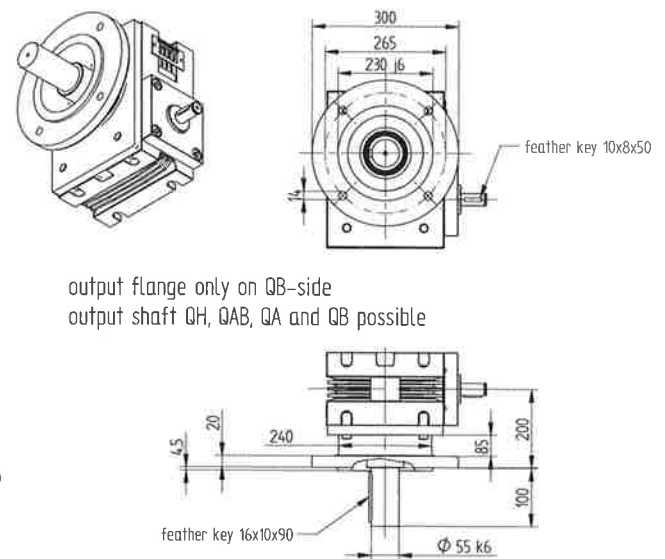
## uniCe-100-N-00-W-QAB-00-QC

gear with two input and output shafts



## uniCe-100-N-00-W-QB-FL

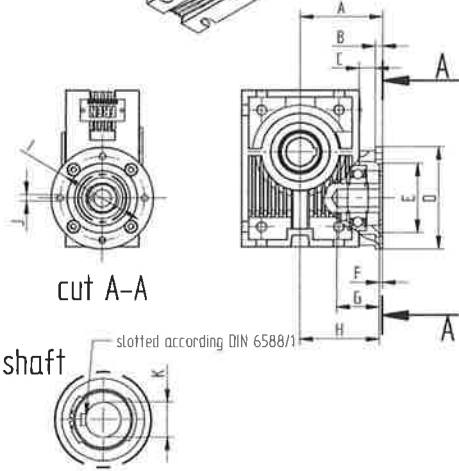
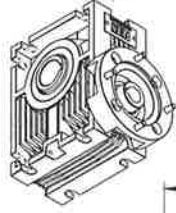
gear with output shaft QB, output flange and axle drive shaft



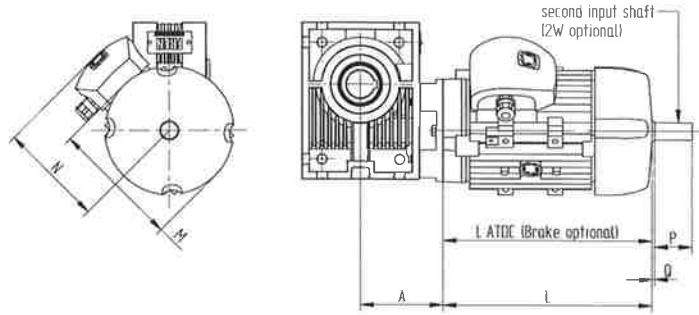
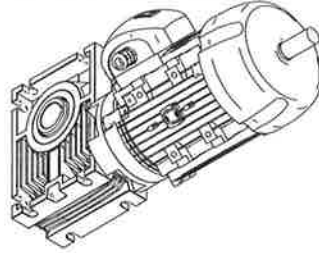
choice the gear according to the typ designation on page 3



uniCe-100-N-00-JM/000/00-QH  
gear with input hollow shaft, output hollow shaft and flange



uniCe-100-N-00-Motor-QH  
gear with output hollow shaft and motor



uniCe 100	A	B	C	D	E H7	F	G	H	I	J	K	L	LATDC	M	N	O	P	Q	
90SB5	146	13	200	130	4,5	110	129	165	M10	24,28,38,42	252	347	195	145	24	50	5		
90LB5											277	373	195	145	24	50	5		
100B5	135	16		250	180				5		215	M12	307,5	401,5	215	170	28	60	5
112B5													316,5	431,5	240	177	28	60	5
132SB5	160	20	300	230	6	265	300	18	371,5		486,5	275	197	38	80	5			
132MB5									411,5		526,5	275	197	38	80	5			
160MB5	175	25	350	250	6	300	18	500	600		330	255	42	110	5				
160LB5								555	645		330	255	42	110	5				

**overhung load:**

on output-shaft in kN  
(in the middle of normal output shaft extension)

$\eta_2$	T <sub>2</sub> uniCe 035		T <sub>2</sub> uniCe 040		T <sub>2</sub> uniCe 050		T <sub>2</sub> uniCe 063		T <sub>2</sub> uniCe 080		T <sub>2</sub> uniCe 100	
	20	40	30	80	60	120	120	250	250	500	400	800
25	3,1	3,0	3,1	3,1	5,0	4,5	7,2	7,2	7,5	7,5	15,0	14,6
40	2,8	2,5	3,1	2,7	4,2	3,7	7,2	6,8	7,5	7,5	13,8	12,0
100	2,0	1,7	2,3	1,8	3,0	2,5	5,3	4,7	6,3	4,9	9,7	7,9
250	1,4	1,1	1,6	1,1	2,0	1,5	3,7	3,1	4,2	2,8	6,4	4,6

**efficiency:**

The efficiency given in the tables is applicable for the worm gear with torque take off which is reached with the mentioned motor power.

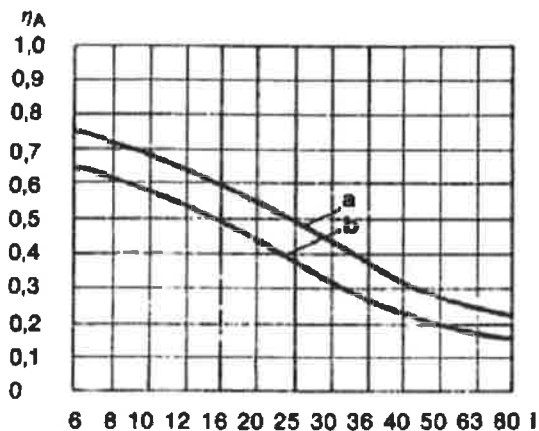
If you need a higher efficiency or self-locking, please contact us!

**self-locking:**

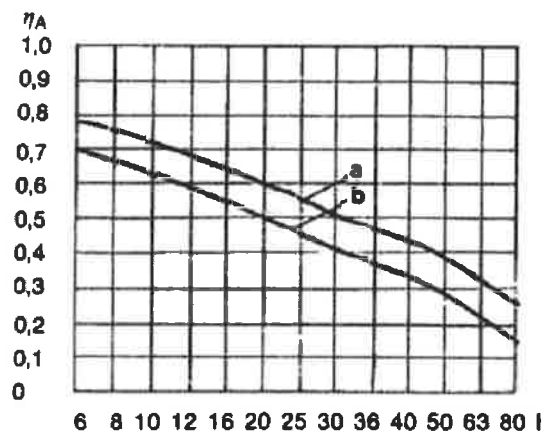
static self-locking (from the standstill):

exists when starting efficiency  $\eta_A \leq 0,5$

Size 35, 40, 50



Size 63, 80, 100

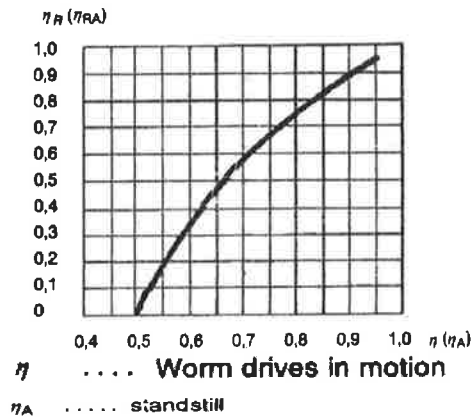


a;b..... borderlines

i ..... ratio

dynamic self-locking (when running):

require an efficiency of running  $\eta_R \leq 0,5$



### calculation of input Brakes

$\eta$  = Efficiency

$\eta_R = \eta_{Rück}$  = reactive Efficiency

$$\eta = \frac{\text{tg } \gamma}{\text{tg } (\gamma + \rho)} \quad \eta_R = \frac{\text{tg } (\gamma - \rho)}{\text{tg } \gamma} \quad \eta_R \sim 2 - \frac{1}{\eta}$$

$\gamma$  = Lead Angle

$\rho$  = Friction Angle

$i$  = Ratio

$\eta_R$  = see diagramme

$\eta_{RA}$  = acc.  $\eta_A$  for holding brakes

$T_{Mas}$  = torque which is need

$T_{Br}$  = brake torque on the outputshaft

$T_{BrMotef}$  = brake torque on the input shaft which is need

$T_{BrWirk}$  = real brake torque on the output shaft

formula:  $T_{BrMotef} = \frac{T_{Br}}{i} \cdot \eta_{Rück}$      $\eta_R = \eta_{Rück} = 2 - \frac{1}{\eta}$      $\eta_{RA} = \eta_{RückAuslauf} = 2 - \frac{1}{\eta_{Anlauf}}$  1)

After selection of brake it is necessary to control it with the starting efficiency  $\eta_{Anlauf}$   
 The brake torque is not allowed to be higher then the max. torque of the gear

$$T_{BrWirk} = \frac{T_{Mas} \cdot i}{\eta_{RückAuslauf}} = \frac{T_{Mas} \cdot i}{2 - \frac{1}{\eta_{Anlauf}}} \quad (\text{difference } \pm 30 \%)$$

example:

$T_{Mas} = 130 \text{ Nm}$     120 rpm ; Motor 2,2 kW/1440 rpm ( $T_{mot} = 15 \text{ Nm}$ ) with

gear uniCe-63-N-12 ;  $n_2 = 120 \text{ rpm}$

choice for this:  $T_2 = T_{mot} \cdot i \cdot \eta = 15 \cdot 12 \cdot 0,83^2 = 149 \text{ Nm}$

$$T_{BrMas} = T_V - T_{Mas}$$

$T_V$  = deceleration torque on the output shaft

$$T_V = 300 \text{ Nm}$$

$$\eta_{Rück} = 2 - \frac{1}{\eta} = 2 - \frac{1}{0,83} = 2 - 1,21 = 0,79$$

$$\eta_{RückAuslauf} = 2 - \frac{1}{\eta_{Anlauf}} = 2 - \frac{1}{0,6^1)} = 2 - 1,67 = 0,33$$

$$T_{BrMas} = T_V - T_{Mas} = 300 - 130 = 170 \text{ Nm}$$

$$T_{BrMotef} = \frac{T_{BrMas}}{i} \cdot \eta_{Rück} = \frac{170}{12} \cdot 0,79 = 11,2 \text{ Nm}$$

brake torque choiced     $15 \text{ Nm} = T_{BrMot}$

control calculation:

$$T_{V-Auslauf} = \frac{T_{BrMot}}{\eta_{RückAuslauf}} \cdot i = \frac{15}{0,33} \cdot 12 = 540 \text{ Nm}$$

540 Nm smaller  $T_{2max}$     589<sup>2)</sup> Nm of the gear    the choice of the brake with 15 Nm is correct

1)  $\eta_{Anlauf}$  - see page 37

2)  $\eta$  und  $T_{2max}$  see table value for 1500 rpm

### **slip coupling:**

the built in slip coupling which is running immersed in oil and is practically maintenance free.

It is designed as a friction coupling. The torque can be adjusted.

Created temperature is dissipated by the oil, when slipping continuously for more than 15 minutes temperature increases to a max. 36°F (20°C).

#### **advantages**

- exact calculation of the unit as well as the machine without excessive safety considerations
- protection against operator's mistakes and accidents
- no overloads for gear resp. plant
- smoothes peaks of load during starting-up, deceleration and normal service

A type of slip-coupling with limited adjustable torque, simply and economically constructed, is available to suit most requirements. Deliverable in most sizes.

### **Special versions:**

- worm left handed
- special ratio
- oil seals for high temperature
- special dimensions for input and output shafts
- stainless shafts
- special no-tox lubrication

Please send an inquiry for special wishes.

### **lubrication:**

lubrication for life (synthetic lubricant) is included.

Size 035 – 063 lubricate with low-viscosity grease **Marson SY 00** from **Total**

Size 080 – 100 lubricate with oil **Carter SY 220** from **Total**

	uniCe 035	uniCe 040	uniCe 050	uniCe 063	uniCe 080	uniCe 100
amount [cm <sup>3</sup> ]	40	50	125	250	880	1100

amount of lubrication

### **maintenance:**

uniCe-worm-gears are practically maintenance free.

After 100 hours of running (later each 1000 hours) it is recommended to check for lack of lubrication.

## motor:

the motors are built according to:

multiple voltage 230/400V or 400/690V

multi-frequency 50/60Hz

F class insulation

S1 continuous duty service

IP55 protection

IE2 efficiency class

tropicalized winding

painting RAL 9006

Flange according IEC

optional is:

a second shaft = 2W

a brake with hand lever = ATDC

kW	Typ	braking torque [Nm]	braking time no load [sek]	brake power [W]	Kg
0,18	ATDC 63A-2	4,5	0,15	22	7,8
0,25	ATDC 63B-2	4,5	0,15	22	8,1
0,37	ATDC 71A-2	8,0	0,15	28	9,0
0,55	ATDC 71B-2	8,0	0,15	28	9,5
0,75	ATDC 80A-2	12,5	0,20	30	12,7
1,1	ATDC 80B-2	12,5	0,20	30	13,5
1,5	ATDC 90S-2	25,0	0,25	45	16,3
2,2	ATDC 90L-2	25,0	0,25	45	18,0
3	ATDC 100L-2	38,0	0,30	60	27,0
4	ATDC 112M-2	70,0	0,35	65	37,0
5,5	ATDC 132SA-2	140,0	0,40	88	49,1
7,5	ATDC 132SB-2	140,0	0,40	88	54,5
11	ATDC 160MA-2	210,0	0,50	110	130,0
15	ATDC 160MB-2	210,0	0,50	110	140,0
18,5	ATDC 160L-2	210,0	0,50	110	155,0

kW	Typ	braking torque [Nm]	braking time no load [sek]	brake power [W]	Kg
0,12	ATDC 63A-4	4,5	0,15	22	7,8
0,18	ATDC 63B-4	4,5	0,15	22	8,1
0,25	ATDC 71A-4	8,0	0,15	28	9,0
0,37	ATDC 71B-4	8,0	0,15	28	9,5
0,55	ATDC 80A-4	12,5	0,20	30	13,4
0,75	ATDC 80B-4	12,5	0,20	30	14,8
1,1	ATDC 90S-4	25,0	0,25	45	16,5
1,5	ATDC 90L-4	25,0	0,25	45	18,3
2,2	ATDC 100LA-4	38,0	0,30	60	26,8
3	ATDC 100LB-4	38,0	0,30	60	29,5
4	ATDC 112M-4	70,0	0,35	65	37,5
5,5	ATDC 132S-4	140,0	0,40	88	51,5
7,5	ATDC 132M-4	140,0	0,40	88	57,5
11	ATDC 160M-4	210,0	0,50	110	138,0
15	ATDC 160L-4	210,0	0,50	110	152,0

inner thermal overload cut-out switches

bimetallic device = PTO

thermistor device = PTC

**motor-power-table:**

motor with 2 poles

kW	Typ	rpm	In[A]	Is/In	Cn[Nm]	Cs/Cn	$\eta$ %	cos $\phi$	J Kgm <sup>2</sup>	Kg
0,09	56A-2	2700	0,25	3,8	0,32	2,8	63,4	0,83	0,000080	3,5
0,13	56B2	2760	0,34	4,3	0,45	2,7	64,0	0,86	0,000100	3,6
0,18	63A-2	2751	0,50	4,0	0,62	2,9	66,7	0,77	0,000210	4,5
0,25	63B-2	2769	0,70	4,1	0,86	2,9	67,3	0,77	0,000300	4,7
0,37	63C-2	2796	0,93	4,8	1,26	3,3	74,7	0,77	0,000430	5,7
0,37	71A-2	2810	1,06	4,2	1,26	3,0	70,9	0,71	0,000550	6,0
0,55	71B-2	2810	1,29	5,4	1,87	3,3	77,9	0,79	0,000600	6,3
0,75	71C-2	2780	1,74	6,0	2,58	2,8	75,0	0,83	0,000680	7,3
0,75	80A-2	2854	1,76	5,9	2,51	2,8	79,0	0,78	0,000750	10,0
1,1	80B-2	2861	2,45	6,0	3,67	2,8	81,0	0,80	0,000900	11,0
1,5	80C-2	2840	3,26	6,0	5,04	2,5	79,0	0,84	0,001050	12,5
1,5	90S-2	2834	3,28	5,6	5,05	2,5	79,3	0,83	0,001200	13,0
2,2	90L-2	2805	4,75	5,2	7,49	2,9	80,6	0,83	0,001400	14,0
3	90LB-2	2847	6,20	6,5	10,06	3,4	83,2	0,84	0,002150	16,0
3	100L-2	2885	6,06	6,8	9,93	3,0	83,1	0,86	0,002900	25,0
4	100LB-2	2885	7,88	6,6	13,24	2,9	84,4	0,87	0,004200	27,0
4	112M-2	2886	7,56	7,0	13,24	2,3	84,6	0,90	0,005500	28,0
5,5	112MB-2	2895	10,35	7,1	18,14	2,5	85,8	0,89	0,008200	34,0
5,5	132SA-2	2919	10,45	7,7	17,99	2,4	85,9	0,88	0,010900	40,0
7,5	112MC-2	2880	14,55	7,6	24,87	2,4	85,5	0,87	0,010000	37,0
7,5	132SB-2	2913	13,90	7,3	24,59	2,5	87,2	0,89	0,012600	45,0
9,2	132MA-2	2943	17,63	6,3	29,85	3,0	87,6	0,86	0,020000	53,0
11	132MB-2	2919	19,71	5,6	35,99	2,3	88,6	0,91	0,025000	55,0
11	160MA-2	2941	20,02	7,2	35,72	2,7	88,5	0,90	0,037700	110,0
15	132MC-2	2936	26,76	7,6	48,79	2,4	90,7	0,89	0,032000	58,0
15	160MB-2	2941	27,06	7,0	48,71	2,7	89,8	0,89	0,049900	120,0
18,5	160L-2	2950	32,68	7,0	59,89	2,5	90,8	0,90	0,055000	135,0

motor with 4 poles

kW	Typ	rpm	In[A]	Is/In	Cn[Nm]	Cs/Cn	$\eta$ %	cos $\phi$	J Kgm <sup>2</sup>	Kg
0,06	56A-4	1332	0,23	2,8	0,43	2,8	56,0	0,67	0,00015	3,5
0,09	56B-4	1346	0,33	2,9	0,64	2,8	60,7	0,65	0,00015	3,6
0,13	63A-4	1355	0,40	3,2	0,92	2,3	64,7	0,72	0,00030	4,5
0,18	63B-4	1393	0,56	3,6	1,23	2,4	68,2	0,68	0,00040	4,7
0,25	63C-4	1380	0,74	3,4	1,73	2,3	69,5	0,70	0,00045	5,7
0,25	71A-4	1370	0,78	3,4	1,74	2,6	70,2	0,66	0,00050	6,0
0,37	71B-4	1366	1,04	3,6	2,59	2,3	71,5	0,72	0,00080	6,3
0,55	71C-4	1364	1,51	3,8	3,85	2,5	73,3	0,72	0,00150	7,3
0,55	80A-4	1391	1,49	4,3	3,78	2,4	75,0	0,71	0,00180	10,0
0,75	80B-4	1413	2,02	4,5	5,07	2,6	77,7	0,69	0,00210	11,0
1,1	80C-4	1376	2,89	4,2	7,63	2,7	76,4	0,72	0,00220	12,5
1,1	90S-4	1362	2,73	4,0	7,71	2,7	76,5	0,76	0,00240	13,0
1,5	90L-4	1413	3,62	4,9	10,14	2,6	78,7	0,76	0,00300	14,0
2,2	90LB-4	1412	5,32	5,3	14,88	3,2	80,7	0,74	0,00410	16,0
2,2	100LA-4	1431	5,00	5,1	14,68	2,3	81,4	0,78	0,00540	23,0
3	100LB-4	1418	6,55	5,4	20,20	2,7	82,6	0,80	0,00670	25,0
4	100LC-4	1415	8,36	6,0	27,00	3,0	84,2	0,82	0,00810	27,0
4	112M-4	1453	8,52	6,4	26,29	2,5	85,8	0,79	0,00950	28,0
5,5	112MB-4	1448	11,64	6,5	36,27	3,5	86,3	0,79	0,01500	35,0
5,5	132S-4	1455	11,42	6,5	36,10	2,4	87,8	0,79	0,02140	45,0
7,5	112MC-4	1453	15,68	6,9	49,29	3,0	87,4	0,79	0,02230	37,0
7,5	132MA-4	1462	15,02	7,1	48,99	2,5	87,9	0,82	0,02960	55,0
9,2	132MB-4	1470	19,32	6,2	59,77	2,6	88,1	0,78	0,03100	56,0
11	132MC-4	160	22,78	7,2	71,95	2,3	88,9	0,78	0,04000	55,0
11	160M-4	1468	21,61	6,3	71,66	2,7	89,4	0,82	0,06100	118,0
15	132MD-4	1457	30,62	6,8	98,32	2,4	89,5	0,79	0,05000	58,0
15	160L-4	1470	28,77	6,2	97,45	2,1	89,6	0,84	0,09180	132,0



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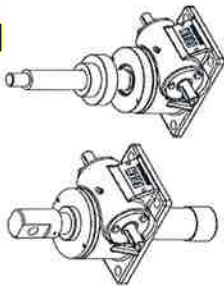
**office@enzfelder.at**

**www.enzfelder.at**

# Product overview 03/2015

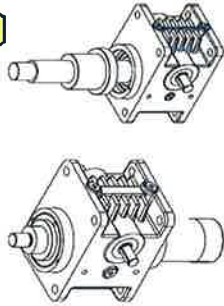
**SG**

Screw jack  
Classic



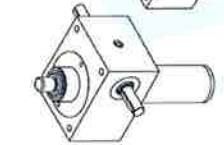
**HSG**

High performance-  
Screw jack



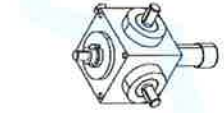
**BG**

Screw jack  
Cubic



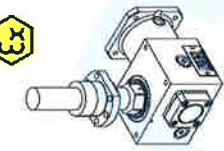
**SHG**

Quick-lifting  
screw jack



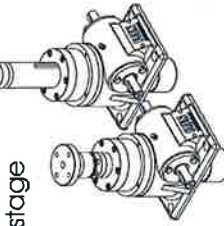
**SH**

Servo lifting  
gear



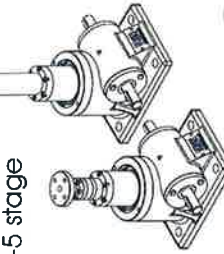
**TSGLR**

Telescopic spindle-  
Screw jack  
2-stage



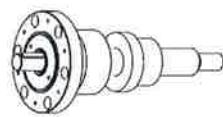
**TSG**

Telescopic spindle-  
Screw jack  
2-5 stage



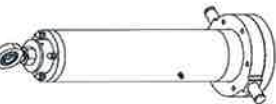
**SLA**

Spindlebearing



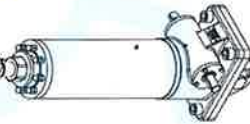
**SEZ**

Spindlebearings-  
Cylinder



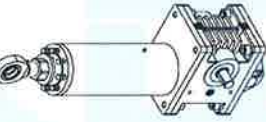
**ELZ**

Electric cylinder



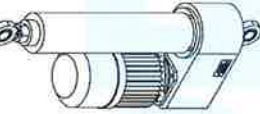
**HELZ**

High performance-  
Electric cylinder



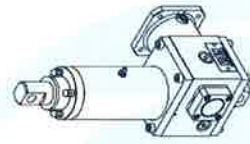
**ELZP**

Electric cylinder  
Parallel



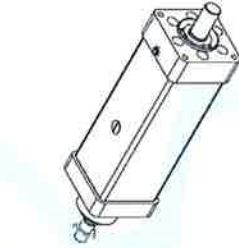
**SHELZ**

Servo electric-  
cylinder



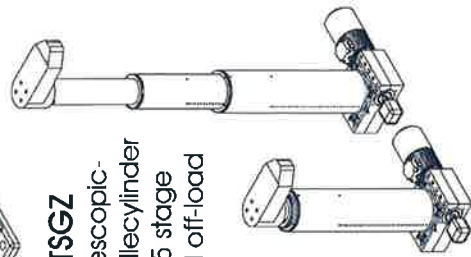
**EPNEU**

Spindle-  
Electric cylinder



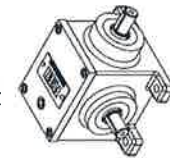
**TSGZ**

Telescopic-  
spindlecylinder  
2-5 stage  
And off-load



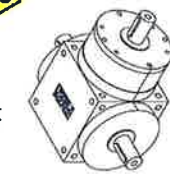
**K**

Bevel gear  
Type K



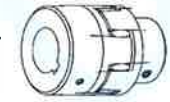
**H**

Bevel gear  
Type H



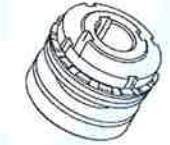
**R / GS**

Elastic / backlash-free  
Coupling



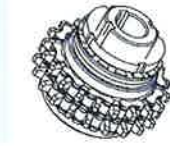
**RT**

Slip hub



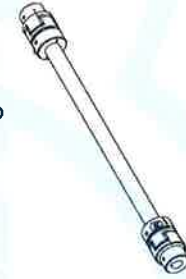
**RK**

Slip coupling



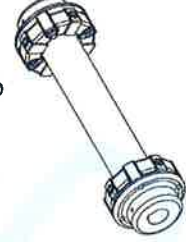
**ZR**

FREN  
Connecting shaft



**G / GX**

Elastic  
Connecting shaft

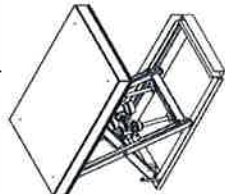


Cardan shaft



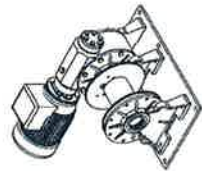
**HT**

Lifting table  
mechanic / hydraulic



**SW**

Rope winche



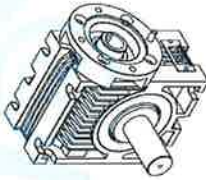
**PLG**

Planetary gear



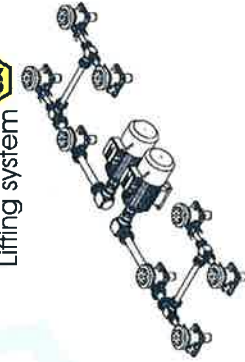
**uniCe**

Worm gear



**HA**

Lifting system



**Special gear**

