



Full Line Catalog



Lead Screw and Nut Assemblies
Linear Actuators
Linear Rail Systems

HKP Mobile App



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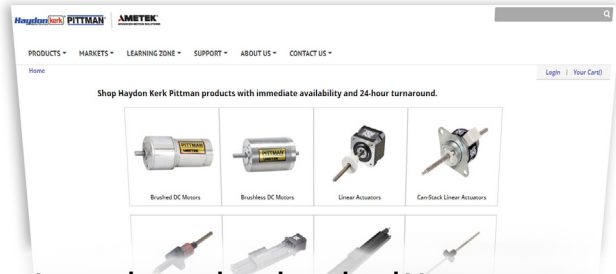


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Lead Screw and Nut Assemblies

Kerk Lead Screw Assemblies are modified Acme thread forms optimized for performance and available in a broad range of lead screw diameters, leads and nut styles, custom designed for your application. Kerk lead screws are self-adjusting, maintenance-free and require no lubrication. Providing maximum accuracy, high reliability, smooth, quiet operation and low cost, Kerk lead screw assemblies are your best choice for high performance linear motion control.

Kerk Lead Screws

- Available in standard diameters from 5/64-in (2 mm) to 15/16-in (23 mm)
- Standard leads from .012-in to almost 4-in (0.30 mm to 92 mm) including native metric and left hand threads
- Custom sizes and leads can be special ordered
- Positional bi-directional repeatability (with Kerk anti-backlash nut) is within 50 micro-inches (1.25 micron) and standard lead accuracy is better than 0.0006-in./in. (mm/ mm)
- Standard lead accuracy of .0006 in/in, with up to .0001 in/in available on selected screws; Contact factory for availability
- Complete in-house manufacturing and quality control assure uniform and consistent products

Kerk Nuts

- Available in 7 standard anti-backlash designs (ZBX, WDG, NTB, KHD, VHD, NTG, ZBA); general purpose BFW Series plus the Mini Series
- Custom nut configurations and mountings are also readily available
- Custom free-wheeling fabricated and molded solutions are available, onsite molding design & production
- The Kerk brand anti-backlash designs provide assemblies which are wear compensating with low frictional drag and exceptional positional repeatability
- Operation to more than 300 million inches of travel can be achieved



Nut and Screw Materials

In addition to the Kerk self-lubricating acetal nut material, we offer a variety of custom compounded **Kerkite® composite polymers**, formulated to provide optimum performance in their target conditions and applications.

- High performance materials
- Exceptional wear properties
- Cost and design advantages afforded through injection molding
- Mechanical, thermal and electrical properties; compatible with many chemicals and environmental conditions: temperature, chemical resistance, radiation resistance, etc.
- Compounded with lubricants, reinforcements and thermoplastic polymers

Kerk brand lead screws and linear rails start with premium grade 303 stainless steel. Kerk stainless steel lead screws are corrosion resistant, non-magnetic, and compatible with many demanding processes. The ideal starting point for a maintenance-free product, this premium quality stainless steel is being used in numerous applications including medical applications, clean rooms, food and human contact, salt spray, cryogenics and vacuum. We can also roll screws in many materials and produce nuts in alternative plastics. If the material can be molded, machined, ground, or rolled, we can likely process it.

Properties of Standard vs. Kerkite Materials			
	Standard Acetal	Kerkite KN30	Kerkite KP20
Material	Acetal w/Lubrication	Carbon Reinforced Nylon w/Lubrication	Carbon Reinforced PPS w/Lubrication
Color	Black	Blue	Black
Tensile Strength (PSI)	7,000-9,000	24,000-27,000	23,800
Flexural Modulus (PSI)	300,000-450,000	1,750,000	2,500,000
Deflection Temp (°F)	255	485	500
Thermal Exp. Coeff (IN/IN/F)	5.8×10^{-5}	1.1×10^{-5}	0.8×10^{-5}
Constant Use Temp (°F)	150	300	400
Water Absorption (%)	.2	.9	.02
*Coefficient of Friction	.08-.12	.10-.15	.15-.20
PV Limit (@ 20 IN/SEC) PSI FPM	15,000	43,000	70,000*

Please note the above values are based on polymer industry standards and should be used as reference only. Materials need to be tested in individual applications to ensure that properties will be sufficient.

*The actual value of coefficient of friction will depend on surface finish, environment and any additional lubrication.

**Please note manufacturers vary the PV listed values as well as the way PV is calculated. Please use these numbers for PV as a reference guide between materials. Higher PV materials are available.

***Please consult factory for proper use and alternative PPS materials with higher PV values.

Kerk Lead Screw TFE Coatings

We offer multiple options for lubrication. All Kerk lead screw nuts feature self-lubricating polymers. However, when maximum performance is required, Kerkote® and Black Ice® Teflon TFE coatings provide unmatched results in the most demanding applications. The purpose of TFE coating is to supply a more even distribution of lubricant than is normally found when using standard self-lubricating plastics on steel.

Kerkote TFE Coating

Lubrication to the nut/screw interface occurs by the nut picking up Kerkote® TFE particles from the soft coating as well as from the migration of the internal lubricant within the plastic nut. The lubricant, although solid, has some "spreading" ability as in fluid lubric

- Ideal for most environments (Black Ice recommended for harsh environments)
- Soft coating
- Dry lubricant
- Long term
- Maintenance-free
- Can be re-machined
- Optimized for softer plastics (acetals/nylons), with or without mechanical reinforcement
- Provides maximum level of self-lubrication
- Not intended to be used with additional lubricants
- Should not be used in environments where oils or other lubricant contamination is possible

Black Ice TFE Coating

Hard coating that remains on the screw. Rather than acting as a dry lubricant, it is an anti-friction coating whose surface properties displace the metal to which it is applied.







- Ideal for harsh environments or if reduced friction and a permanent coating is desired
- Hard coating
- Long term
- Maintenance free
- Low friction surface upon which the nut travels
- Exceptionally durable with virtually any type of polymer nut
- Not intended for use with metal or glass fiber reinforced nuts, although can withstand abrasion from contamination, rigid polymer systems, fluid impingement and wash down applications
- Not intended to be used with additional lubricants

Greases

Teflon TFE coatings are intended to be used without additional lubricants. However, there are certain applications where external lubrication may be desired. These include the use of nut materials such as glass reinforced plastic or metal. We offer a selection of greases developed specifically for these applications.

Lead Screw Nut Selection

Kerk Lead Screw Assemblies are modified acme thread forms optimized for performance and available in a broad range of lead screw diameters, leads and nut styles, custom designed for your application. Kerk lead screws are self-adjusting, maintenance-free and require no lubrication. Providing maximum accuracy, high reliability, smooth, quiet operation and low cost, Kerk lead screw assemblies are your best choice for high performance linear motion control.

		Nut Styles								
		• = Good •• = Better ••• = Best								
		Units								
										
		ZBX	ZBA	ZBM	KHD	WDG	NTB	VHD	BFW	
Max Dynamic Load	lb	35	55	1	20	75	200	350	500	
	N	155	245	4.4	89	333	890	1557	2224	
Compactness		••	••	•••	••	•••	••	•	•••	
Typical Drag Torque		••	••	••	•••	••	••	•••	N/A	
Vibration Damping	[horizontal]	•••	•••	•••	••	•	•	••	N/A	
	[vertical]	•••	•••	•••	•	•	•	•	N/A	
Smoothness		••	•••	••	••	••	••	••	•	
Backlash Compensation		••	•	••	•••	•••	•••	•••	N/A	
Drag Adujusted		N/A	•••	N/A	••	N/A	•	••	N/A	
Stiffness		••	••	••	•••	•••	•••	•••	N/A	
Easy to Modify		••	•	•	•	•	•••	•	•••	
Custom Materials Available		••	••	•	•	•	•••	•	•••	
Best for Fine Leads	<.2",5mm	•••	•••	•••	•••	•••	•	•••	•••	
Best for Long Leads	>1",25mm	•••	•••	N/A	•••	•••	•••	•••	•••	



Lead Screw by Size

Kerk Lead Screws utilize the latest in precision rolling technology. Lead screws are available in standard diameters from 5/64" to 15/16" and includes metric and left hand threads. Most standard lead screws are manufactured from 303 stainless steel and are produced using our exclusive precision rolling process. Other lead screw materials are available for application specific requirements.

Dynamic Load by Nut Type											
Diameter	Lead Range	Units	ZBX	ZBA	ZBM	KHD	WDG	NTB	VHD	BFW	
5/64 inch (2mm)	0.012-0.079 in (0.3-2.00 mm)	lbs N			1 (4.4)					10 (44)	
1/8 inch (3.2mm)	0.024-0.125 in (0.61-3.18 mm)							5 (22)		25 (111)	
0.132 inch (3.3mm)	0.020-0.315 in (0.50-8.00 mm)							5 (22)		25 (111)	
9/64 inch (3.6mm)	0.012-0.394 in (0.30-10.00 mm)							5 (22)		25 (111)	
5/32 inch (4mm)	0.033-0.500 in (0.84-12.70 mm)							5 (22)		25 (111)	
3/16 inch (5mm)	0.020-0.050 in (0.50-12.70 mm)							10 (44)	5 (22)		25 (111)
7/32 inch (5.6mm)	0.024-0.384 in (0.61-9.75 mm)							10 (44)	5 (22)		25 (111)
1/4 inch (6mm)	0.024-1.000 in (0.61-25.4 mm)			5 (22)	5 (22)			10 (44)	10 (44)		50 (222)
5/16 inch (8mm)	0.039-0.800 in (1.00-20.32 mm)			10 (44)	10 (44)		20 (89)	25 (111)	20 (89)		75 (334)
3/8 inch (10mm)	0.025-1.500 in (0.64-38.10 mm)			10 (44)	10 (44)		20 (89)	25 (111)	20 (89)		75 (334)
7/16 inch (11mm)	0.050-0.615 in (1.27-15.62 mm)			15 (67)	15 (67)			75 (334)	30 (133)		90 (400)
1/2 inch (13mm)	0.050-2.000 in (1.27-50.80 mm)			25 (111)	25 (111)			75 (334)	100 (445)	150 (667)	150 (667)
5/8 inch (16mm)	0.100-2.000 in (2.54-50.80 mm)			35 (156)	35 (156)				125 (556)	250 (1112)	225 (1001)
3/4 inch (19mm)	0.0625-3.622 in (1.59-92.00 mm)				55 (245)				150 (667)	350 (1557)	350 (1557)
7/8 inch (22mm)	0.200-1.000 in (5.08-25.4 mm)				55 (245)				200 (890)	350 (1557)	500 (2224)
15/16 inch (24mm)	0.050-3.000 in (1.27-76.20 mm)				55 (245)				200 (890)		500 (2224)

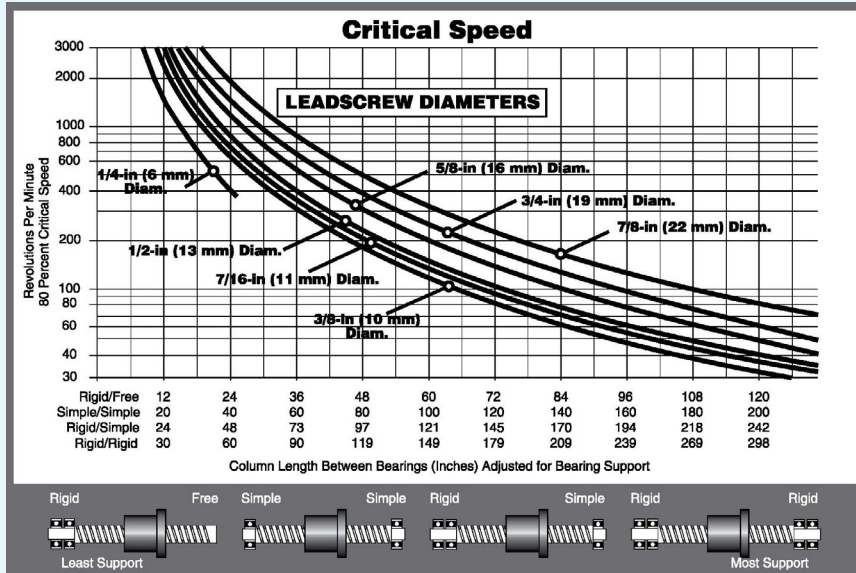
Terminology

Screw Accuracy HKP uses a unique precision rolling process for screw manufacturing. Standard lead accuracy for Kerk screws is .0006 in./in. (mm/mm). Lead accuracies are available up to .0001 in./in. (mm/mm). Please consult the factory for higher lead accuracies. Assemblies have an extremely high bi-directional repeatability of 50 micro-inches (1.25 micron).

End Machining HKP can custom machine screws to your specifications or provide cut-to-length screws for your own machining.

This is the rotational speed at which a screw may experience vibration or other dynamic problems. See CRITICAL SPEED CHART to determine if application parameters result in speed approaching critical. To minimize critical speed problems: use a longer lead, choose a larger diameter or increase bearing mount support.

Critical Speed



Lengths Lengths can be specified up to 12 ft. (4M) from stock, (depending on diameter and lead). Cut to length screws are offered in 6-in increments (6-in, 12, 18,) + 1.0-in/-0-in.

Lead Advancement per revolution. All screws are listed by lead, not pitch. **Lead = Pitch x Number of Starts**

Pitch Crest-to-crest distance or one divided by threads per inch. (On a multiple start thread, the pitch equals the lead divided by the number of starts.)

Traverse Speed The nut materials we use provide long wear-life over a wide variety of conditions. However, very high loads and/or speeds will accelerate nut wear. Special materials may be required for these situations. We offer the following guidelines for continuous duty linear traversing speeds for optimum life:

Lead	Traverse Speed	Lead	Traverse Speed
1/10 - 1/2-in	4-in/sec	1 - 12 mm	100 mm/sec
1/2 - 1-in	10-in/sec	12 - 25 mm	250 mm/sec
1 - 2 1/2-in	30-in/sec	25 - 60 mm	760 mm/sec

Maximum Load Although the Kerk Anti-Backlash Assemblies are capable of withstanding relatively high loads without catastrophic failure, these units have been designed to operate under the loading shown in the size charts.

Efficiency Efficiency is the relationship of work input to work output. It should not be confused with mechanical advantage. Listed efficiencies are theoretical values based on Kerkote TFE coated screws.

The required motor torque to drive a lead screw assembly is the sum of three components: the **inertial torque**, **drag torque**, and **torque-to-move load**. It must be noted that this is the torque necessary to drive the lead screw assembly alone. Additional torque associated with driving frictional bearings and motor shafts, moving components, and drag due to general assembly misalignment must also be considered.

Torque

$$T_j = I \alpha \quad \text{Where } I = \text{screw inertia} \\ \alpha = \text{angular acceleration}$$

Inertial Torque:

Drag Torque: The Kerk Anti-Backlash Assemblies are typically supplied with drag torque of 1 to 7 oz.-in. The magnitude of the drag torque is dependent on the standard factory settings or settings specified by the customer. Generally, the higher the preset force, the better the Anti-Backlash characteristics.

Torque-to-Move:

$$T_L = \frac{\text{LOAD} \times \text{LEAD}}{2\pi \times \text{EFFICIENCY}}$$

Back Driving Sometimes referred to as reversibility, back driving is the ability of a screw to be turned by a thrust load applied to the nut. Generally, back driving will not occur when the screw lead is less than 1/3 the diameter for uncoated screws or 1/4 the diameter for Kerkote TFE coated screws. For higher leads where back driving is likely, the torque required for holding a load is:

$$T_b = \frac{\text{LOAD} \times \text{LEAD} \times \text{BACKDRIVE EFFICIENCY}}{2\pi}$$

Screw Straightness Screw straightness is measured as Total Indicator Runout(TIR). The standard straightness for lead screws is .003-in/ft. Haydon Kerk Motion Solutions can provide tighter specifications on customer request.

Standard/Block Dimensional Tolerances

Inch		Metric (mm)	
.X	± .02	L < 4	± 0.1
.XX	± .010	4 < L ≤ 16	± 0.15
.XXX	± .005	16 < L ≤ 63	± 0.2
		63 < L ≤ 250	± 0.3

Mechanical Properties

Screw Inertia		
Screw Size	Screw Inertia	
inch (mm)	(oz-inch sec ² /inch)	(g-cm ² /cm)
5/64 (2)	3.4 x 10 ⁻⁸	9.5 x 10 ⁻⁴
1/8 (3.2)	1.8 x 10 ⁻⁷	5.0 x 10 ⁻³
9/64 (3.5)	3.4 x 10 ⁻⁷	9.5 x 10 ⁻³
5/32 (3.97)	4.9 x 10 ⁻⁷	1.4 x 10 ⁻²
3/16 (4.76)	1.1 x 10 ⁻⁶	3.1 x 10 ⁻²
7/32 (5.55)	1.8 x 10 ⁻⁶	5.0 x 10 ⁻²
1/4 (6)	3 x 10 ⁻⁵	8.3 x 10 ⁻²
5/16 (8)	5 x 10 ⁻⁵	1.4
3/8 (10)	1.5 x 10 ⁻⁵	0.4
7/16 (11)	3.5 x 10 ⁻⁵	1.0
1/2 (13)	5.2 x 10 ⁻⁵	1.4
5/8 (16)	14.2 x 10 ⁻⁵	3.9
3/4 (19)	30.5 x 10 ⁻⁵	8.5
7/8 (22)	58.0 x 10 ⁻⁵	16.1
15/16 (24)	73.0 x 10 ⁻⁵	20.3

Lead Screw	
Material	Surface Finish
303 Stainless Steel (options available)	Better than 16 micro-inches (0.4 μm)

Nuts		
Material	Tensile Strength	Coefficient of Expansion
Polyacetal with Lubricating Additive	9,700 psi	6.0 x 10 ⁻⁵ in/in/°F

*Other Kerkite materials available

Assembly			
Standard Operating Temp. Range	Coefficient of Friction		
32 - 200° F* (0 - 93° C)*	Polyacetal Nut to Screw	Static = .08	.08 **
		Dynamic = .15	.09 **
-40 - 311° F (-40 - 155° C)	Polyester/Fiberglass Nut to Screw***	Static = .07	
		Dynamic = .08	

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call Haydon Kerk Motion Solutions for optional temperature range materials.

** with Kerkote® TFE Coating

*** This material is only recommended to be used with grease. Coefficient of Friction numbers are with HSS-06 grease

Anti-Backlash Life		
Series	Without Kerkote® TFE Coating inch (cm)	With Kerkote® TFE Coating inch (cm)
ZBA	5 to 10 million (12 to 25 million)	15 to 40 million (38 to 100 million)
ZBX	40 to 60 million (100 to 150 million)	150 to 200 million (380 to 500 million)
KHD	80 to 100 million (200 to 250 million)	180 to 230 million (450 to 580 million)
WDG	100 to 125 million (250 to 315 million)	200 to 250 million (500 to 635 million)
NTB	100 to 125 million (250 to 315 million)	200 to 250 million (500 to 635 million)
VHD	200 to 225 million (500 to 570 million)	300 to 350 million (760 to 880 million)
BFW	N/A, Typical Backlash .003 to .010 (.076 to .25)	N/A, Typical Backlash .003 to .010 (.076 to .25)
NTG	5 to 10 million (12 to 25 million)	15 to 40 million (38 to 100 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. NTB style does not include mini series sizes. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

Grease Compatibility Chart

Nut Type	Grease	Lubrication Coatings	
		Kerkote®	Black Ice®
ZBX		Yes	
ZBA		Yes	
KHD	No	Yes	
VHD	No	Yes	
WDG	No	Yes	
BFW		Yes	
NTB	No	Yes	
NTG		Yes	

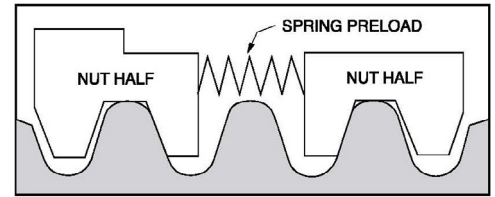
Anti-Backlash Nuts

Haydon Kerk offers a renowned portfolio of anti-backlash designs that create lead screw assemblies which are wear compensating, with low frictional drag and exceptional positional repeatability. Seven standard anti-backlash nut styles cover the range of axial, radial and torsional designs to suit a wide range of applications. Haydon Kerk provides nuts in a wide range of wear resistant, self-lubricating thermoplastic materials.

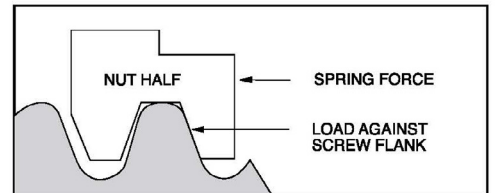
Anti-Backlash Technology

Axial Take-up Mechanism

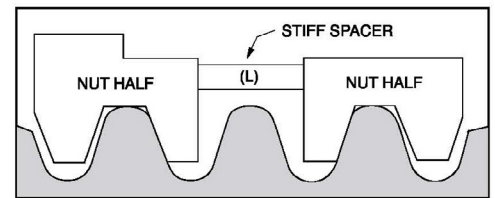
The standard method for taking up backlash is to bias two nut halves axially using some type of compliant spring. (Wavy washer, compression spring, rubber washer, etc.) The unit is very stiff in the direction in which the nut half is loaded against the flank of the screw thread. However, in the direction away from the screw thread, the nut is only as axially stiff as the amount of preload which the spring exerts.



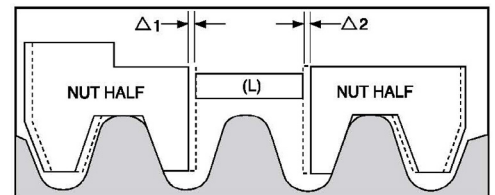
For example, if the maximum axial load to which the system is subjected is 50 lbs., the amount of spring preload must be equal to, or greater than, 50 lbs. in order to maintain intimate screw/nut contact. The problems arising from preloading in this manner are increased drag torque and nut wear. Obviously, the higher the load at the screw/nut interface, the higher the required torque to drive the nut on the screw and the more susceptible the unit is to nut wear.



An alternate method replaces the spring with a stiff spacer sized to fit exactly between the two nut halves. There is no excessive preload force at the interface and the unit is capable of carrying high axial loads in either direction with no backlash. This is fine initially. However, as use time increases, wear begins on the nut threads causing a gap to develop between the spacer (L) and the nut halves.

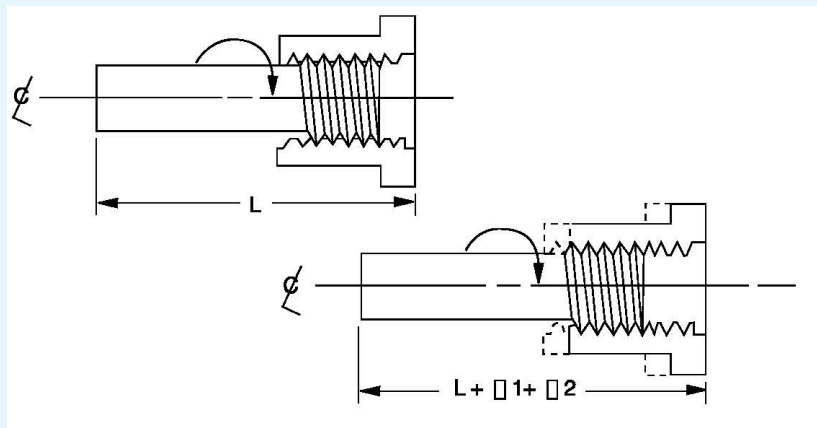


This gap ($\Delta_1 + \Delta_2$) is now the amount of backlash which has developed in the unit. This backlash can be removed by replacing the stiff spacer with a new spacer equal to $(L + \Delta_1 + \Delta_2)$. This process, although effective, would be extremely costly and difficult to implement on a continuous basis.



The Solution

What is needed, then, is a stiff spacer which will continually expand to accommodate the wear which occurs during use. This is done by creating a spacer threaded at one end with a complimentary nut torsionally biased to advance when a gap develops. The thread at the end of the spacer is a fine helix such that an axial load will not backdrive the nut once spacer growth has occurred. The preload on the unit is only the amount necessary to turn the spacer nut on the spacer rod and is independent of the external system loadings. We thus have a self-wear compensating unit which has extremely low frictional drag torque yet high axial stiffness.



KHD Nut Series

Eliminates the need for load compensating preload forces. The KHD Series anti-backlash assembly makes use of the Kerk patented AXIAL TAKE-UP MECHANISM (see Lead screw Assemblies: Anti-Backlash Technologies section) to provide backlash compensation. The unique split nut with torsional take-up provides increased load capacity and axial stiffness over comparably sized ZBX units. Although the KHD offers high axial stiffness, frictional drag torque (1-3 oz.-in.) is very low. The anti-backlash mechanism in the KHD unit eliminates the need for load compensating preload forces. The assembly consists of a 303 stainless steel screw mated with a self-lubricating polyacetal nut. End machining to customer specifications and Kerkote® TFE screw coating are optional.

KHD Series Nut Assemblies



■ Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

■ Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	NO

■ Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
80 to 100 million (200 to 250 million)	180 to 230 million (450 to 580 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

■ Identifying the KHD Series Nut Part Number Codes when Ordering

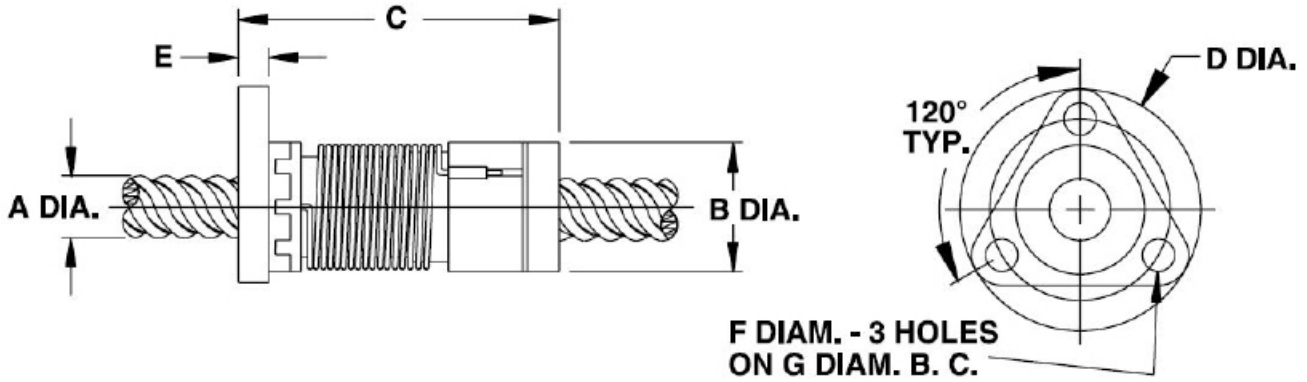
KHD	A	K	R	031	0039	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
KHD	A = Flanged (Triangular) T = Threaded X = Custom	S = Uncoated K = Kerkote® TFE Coating N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Not Available for Micro Series) (Refer to lead screw charts for availability)	031 = .313 in (8 mm) 037 = .375 in (10 mm)	(Refer to LEAD CODE Specifications chart, page 3)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

KHDA Flange Mount

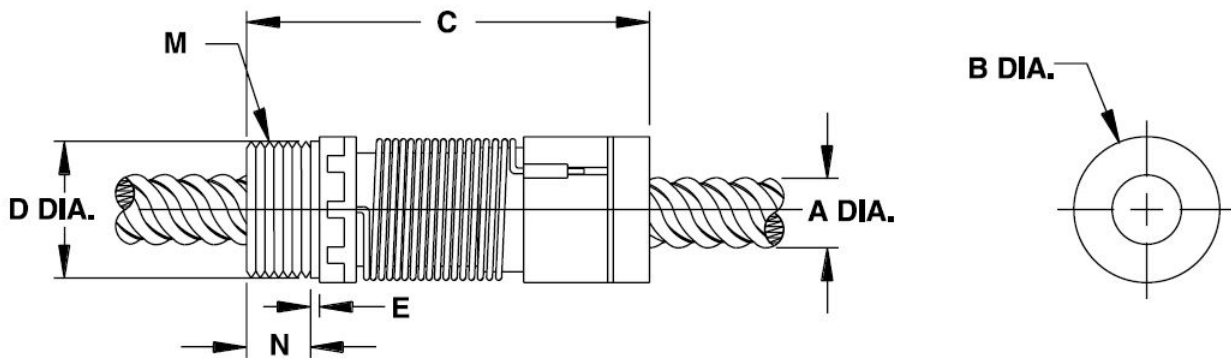
KHDA Flange Mount	Screw Diam.	Nut Diam.	Nut Length	Flange Diam.	Flange Thickness	Thread	Thread Length	Dynamic Load	Drag Torque
	A	B	C	D	E	M*	N	lbs (Kg)	oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)		
	5/16 (8)	.80 (20.3)	2.2	.75 (19.1)	.05 (1.27)	3/4-20	.35 (8.9)	20 (10)	1-3 (.007-.020)
	3/8 (10)	.80 (20.3)	(55.9)	.75 (19.1)	.05 (1.27)	3/4-20	.35 (8.9)	20 (10)	1-3 (.007-.020)



KHDT Thread Mount

KHDT Thread Mount	Screw Diam.	Nut Diam.	Nut Length	Flange Diam.	Flange Thickness	Thread	Thread Length	Dynamic Load**	Drag Torque
	A	B	C	D	E	M*	N	lbs (Kg)	oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)		
	5/16 (8)	.80 (20.3)	2.2 (55.9)	.75 (19.1)	.05 (1.27)	3/4-20	.35 (8.9)	20 (10)	1-3 (.007-.020)
	3/8 (10)	.80 (20.3)	2.2 (55.9)	.75 (19.1)	.05 (1.27)	3/4-20	.35 (8.9)	20 (10)	1-3 (.007-.020)

Metric numbers are for reference only.



Dimensional Tolerances			
Inches		Metric (mm)	
.X	± .02	< L 4	± 0.1
.XX	± .010	4 < L ≤ 16	± 0.15
.XXX	± .005	16 < L ≤ 63	± 0.2
		63 < L ≤ 250	± 0.3

■ Lead Screw Compatibility: KHD Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
0.984	25.00	0984		0.375	9.53	0.262	6.65	84			
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

NTB Nut Series

For higher load applications. The NTB Series anti-backlash assembly is designed for higher load applications than the ZBX or KHD series units. Using the specially designed take up mechanism, it maintains axial stiffness throughout its life while system torque is held to a minimum. The need to highly pre-load the nut to compensate for load has been eliminated with the Kerk NTB Series assembly.

The nut is manufactured with a self-lubricating polyacetal designed to run efficiently on the precision rolled shafting. Screws are 303 stainless and are available with the proprietary long-life Kerkote® TFE coating. The NTB's simple, compact design can be easily modified for custom applications.

The NTB assembly provides low drag torque, high system stiffness, smooth operation, and long life throughout its load and speed range.

NTB Mini Nut Series

Miniature style assemblies, with an "anti-backlash" function. The Mini Series brings Haydon Kerk quality, precision and value to products that were previously off limits to lead screw technology.



NTB Series Nut Assemblies

■ Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

■ Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
100 to 125 million (250 to 315 million)	200 to 250 million (500 to 635 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

■ Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	NO

■ Identifying the NTB Series Nut Part Number Codes when Ordering

NTB	T	K	R	025	0050	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
NTB	A = Flanged (Triangular) F = Flanged (Round) T = Threaded X = Custom Mini Series Only: B = Barrel ^m R = Rectangular ^m ^m NTB Mini Series	S = Uncoated K = Kerkote® TFE Coating N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Not Available for Micro Series) (Refer to lead screw charts for availability)	012 ^m = .125 in (3.2 mm) 013 ^m = .133 in (3.3 mm) 014 ^m = .141 in (3.6 mm) 016 ^m = .156 in (4 mm) 018 ^m = .188 in (5 mm) 021 ^m = .219 in (5.6 mm) 025 = .250 in (6 mm) 031 = .313 in (8 mm) ^m NTB Mini Series	(Refer to LEAD CODE Specifications charts, pages 4 to 8)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

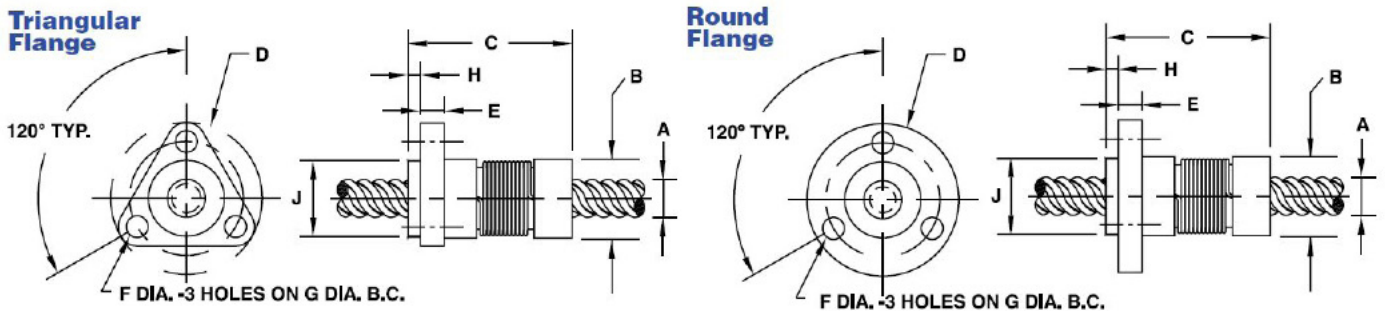
Dimensional Drawings

NTB Flange Mount

NTBA Triangular- Flange	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Hub Width H	Hub Diam. J	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/4 (6)	.52 (13.2)	1.1 (28)	1.00 (25.4)	.16 (4.0)	.143 (3.63)	.750 (19.1)	.08 (2.0)	.500 (12.7)	10 (4.5)	.5-2 (.004-.014)
	5/16 (8)	.80 (20.3)	1.8 (46)	1.50 (38.1)	.20 (5.1)	.200 (5.08)	1.125 (28.6)	.10 (2.54)	.750 (19.1)	20 (9.1)	1-3 (.007-.02)
	3/8 (10)	.80 (20.3)	1.8 (46)	1.50 (38.1)	.20 (5.1)	.200 (5.08)	1.125 (28.6)	.10 (2.54)	.750 (19.1)	20 (9.1)	1-3 (.007-.02)
	7/16 (11)	.90 (22.9)	1.8 (46)	1.62 (41.2)	.23 (5.7)	.200 (5.08)	1.125 (28.6)	.10 (2.54)	.875 (22.2)	30 (13.6)	1-3 (.007-.02)

Metric numbers are for reference only.

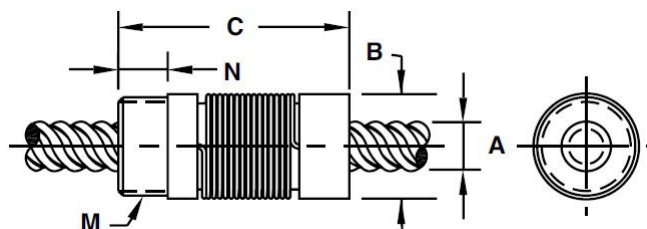
NTBF Round Flange	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Hub Width H	Hub Diam. J	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/2 (13)	1.06 (26.9)	2.1 (54)	1.75 (44.5)	.25 (6.4)	.220 (5.59)	1.406(35.71)	.12 (3.0)	1.00 (25.4)	100 (45.5)	2-6 (.014-.04)
	5/8 (16)	1.38 (34.9)	2.3 (59)	2.13 (54.1)	.28 (7.0)	.220 (5.59)	1.750(44.45)	.10 (2.54)	1.25 (31.8)	125 (56.8)	2-6 (.014-.04)
	3/4 (19)	1.56 (39.6)	2.7 (67)	2.38 (60.5)	.31 (7.9)	.220 (5.59)	2.000 (50.80)	.10 (2.54)	1.50 (38.1)	150 (68.2)	3-7 (.02-.05)
	7/8 (22)	1.75 (44.5)	2.8 (70)	2.63 (66.8)	.38 (9.5)	.220 (5.59)	2.250 (57.15)	.12 (3.0)	1.75 (44.5)	200 (90.9)	4-8 (.03-.06)
	15/16 (24)	1.75 (44.5)	2.8 (70)	2.63 (66.8)	.38 (9.5)	.220 (5.59)	2.250 (57.15)	.12 (3.0)	1.75 (44.5)	200 (90.9)	4-8 (.03-.06)



NTB Thread Mount

NTBT Thread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load**	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 (3)	.40 (10.2)	.50 (28)	3/8-24	1.25 (3.18)	5 (2.3)	.5 (.004)
	1/4 (6)	.52 (13.2)	1.1 (28)	7/16-20	.25 (6.4)	10 (4.5)	.5-2 (.004-.014)
	5/16 (8)	.80 (20.3)	1.8 (45)	3/4-20	.38 (9.5)	20 (9.1)	1-3 (.007-.02)
	3/8 (10)	.80 (20.3)	1.8 (45)	3/4-20	.38 (9.5)	20 (9.1)	1-3 (.007-.02)
	7/16 (11)	.90 (22.9)	1.8 (46)	13/16-16	.38 (9.5)	30 (13.6)	1-3 (.007-.02)
	1/2 (13)	1.06 (26.9)	2.1 (54)	15/16-16	.38 (9.5)	100 (45.5)	2-6 (.014-.04)
	5/8 (16)	1.38 (34.9)	2.3 (59)	1 1/8-16	.38 (9.5)	125 (56.8)	2-6 (.014-.04)
	3/4 (19)	1.56 (39.6)	2.7 (67)	1 3/8-16	.50 (12.7)	150 (68.2)	3-7 (.02-.05)
	7/8 (22)	1.75 (44.5)	2.8 (70)	1 9/16-16	.50 (12.7)	200 (90.9)	4-8 (.03-.06)
	15/16 (24)	1.75 (44.5)	2.8 (70)	1 9/16-16	.50 (12.7)	200 (90.9)	4-8 (.03-.06)

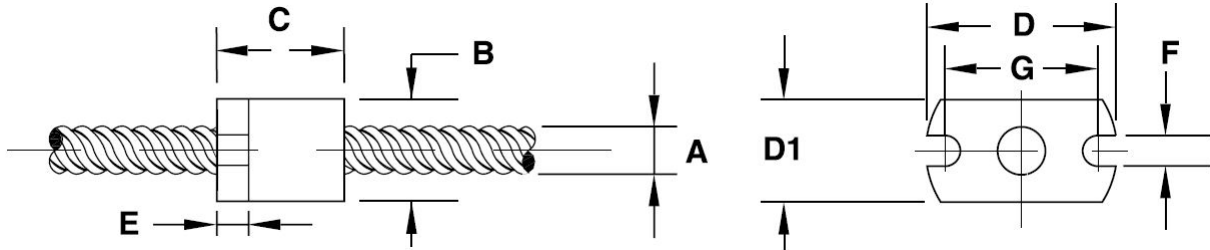
Dimensional Tolerances			
Inches	Metric (mm)		
.X	± .02	< L 4	± 0.1
.XX	± .010	4 < L ≤ 16	± 0.15
.XXX	± .005	16 < L ≤ 63	± 0.2
		63 < L ≤ 250	± 0.3



NTB Mini Flange Mount

NTBR Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Height D1	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	0.40 (10.2)	0.75 (19.1)	0.13 (3.2)	0.120 (3.05)	0.600 (15.24)	5 (2.3)	0.5 (.004)

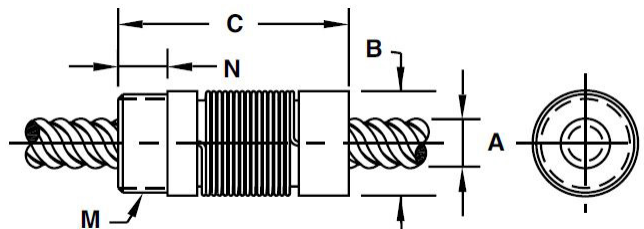
Metric numbers are for reference only.



NTB Mini Thread Mount

NTBT Thread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load**	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	3/8-24	1.25 (3.18)	5 (2.3)	0.5 (.004)

Metric numbers are for reference only.



Lead Screw Compatibility: NTB Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/8	3.2	012	0.024	0.61	0024		0.129	3.28	0.093	2.36	44
			0.039	1.00	0039		0.129	3.28	0.094	2.39	57
			0.048	1.22	0048		0.129	3.28	0.093	2.36	61
			0.075	1.91	0075		0.129	3.28	0.093	2.36	70
			0.096	2.44	0096	•	0.129	3.28	0.093	2.36	75
			0.125	3.18	0125	LH Only	0.125	3.18	0.078	1.98	80
.132	3.3	013	0.020	0.50	0020		0.132	3.35	0.104	2.64	42
			0.039	1.00	0039		0.132	3.35	0.080	2.03	61
			0.079	2.00	0079		0.132	3.35	0.080	2.03	75
			0.157	4.00	0157		0.132	3.35	0.080	2.03	84
			0.315	8.00	0315		0.132	3.35	0.080	2.03	87
9/64	3.6	014	0.012	0.30	0012		0.140	3.56	0.123	3.12	26
			0.024	0.61	0024		0.140	3.56	0.105	2.67	43
			0.048	1.22	0048		0.140	3.56	0.081	2.06	62
			0.096	2.44	0096		0.140	3.56	0.081	2.06	75
			0.394	10.00	0394		0.140	3.56	0.102	2.59	86
5/32	4	016	0.033	0.84	0033	•	0.156	3.96	0.116	2.95	45
			0.050	1.27	0050	LH Only	0.156	3.96	0.096	2.44	59
			0.094	2.39	0094		0.164	4.17	0.128	3.25	67
			0.125	3.18	0125		0.168	4.27	0.130	3.30	74
			0.250	6.35	0250		0.156	3.96	0.130	3.30	83
			0.375	9.53	0375		0.156	3.96	0.130	3.30	85
3/16	4.75	018	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
			0.500	12.70	0500	•	0.188	4.78	0.142	3.61	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: NTB Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
7/32	5.6	021	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096		0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250	•	0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

Lead Screw Compatibility: NTB Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
			1.000	25.40	1000		0.383	9.73	0.254	6.45	84
			1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			
7/16	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
			0.615	15.62	0615		0.475	12.07	0.376	9.55	82

Lead Screw Compatibility: NTB Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
			0.984	25.00	0984		0.500	12.70	0.369	9.37	84
1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84			
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
			2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: NTB Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/4	19	075	0.0625	1.59	0063		0.750	19.05	0.671	17.04	25
			0.098	2.50	0098		0.742	18.85	0.626	15.90	35
			0.100	2.54	0100	•	0.746	18.95	0.624	15.85	35
			0.1667	4.23	0167		0.727	18.47	0.645	16.38	47
			0.197	5.00	0197		0.745	18.92	0.624	15.85	51
			0.200	5.08	0200		0.741	18.82	0.632	16.05	52
			0.250	6.35	0250		0.731	18.57	0.639	16.23	57
			0.276	7.00	0276		0.750	19.05	0.624	15.85	59
			0.333	8.46	0333		0.750	19.05	0.624	15.85	64
			0.394	10.00	0394		0.745	18.92	0.619	15.72	67
			0.500	12.70	0500		0.744	18.90	0.624	15.85	73
			0.551	14.00	0551		0.750	19.05	0.624	15.85	73
			0.591	15.00	0591		0.749	19.02	0.623	15.82	74
			0.709	18.00	0709		0.780	19.81	0.650	16.51	77
			0.748	19.00	0748		0.672	17.07	0.547	13.89	80
			0.787	20.00	0787		0.780	19.81	0.648	16.46	78
			0.800	20.32	0800		0.750	19.05	0.618	15.70	79
			0.945	24.00	0945	•	0.734	18.64	0.633	16.08	80
			1.000	25.40	1000	•	0.743	18.87	0.619	15.72	81
			1.500	38.10	1500		0.712	18.08	0.590	14.99	84
1.969	50.00	1969	•	0.751	19.08	0.620	15.75	84			
2.000	50.80	2000	•	0.742	18.85	0.611	15.52	84			
2.400	60.96	2400	•	0.750	19.05	0.620	15.75	84			
3.622	92.00	3622	•	0.750	19.05	0.634	16.10	87			
7/8	22	087	0.200	5.08	0200	•	0.870	22.10	0.742	18.85	48
			0.236	6.00	0236		0.848	21.54	0.773	19.63	52
			0.250	6.35	0250		0.875	22.23	0.749	19.02	53
			0.394	10.00	0394		0.875	22.23	0.741	18.82	65
			0.500	12.70	0500		0.862	21.89	0.744	18.90	69
			0.630	16.00	0630		0.875	22.23	0.741	18.82	73
			0.667	16.94	0667		0.871	22.12	0.745	18.92	74
			0.787	20.00	0787		0.875	22.23	0.741	18.82	78
			0.945	24.00	0945		0.875	22.23	0.741	18.82	79
			1.000	25.40	1000		0.871	22.12	0.742	18.85	80
5/16	24	093	0.050	1.27	0050	LH Only	0.938	23.83	0.874	22.20	17
			2.000	50.80	2000		0.927	23.55	0.815	20.70	85
			3.000	76.20	3000	•	0.939	23.85	0.803	20.40	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

NTG Nut Series

Compact size, zero backlash, minimal drag torque. The adjustable NTG Series offers a cost effective anti-backlash assembly for applications requiring precise positional accuracy, repeatability, and smoothness. The NTG has been developed specifically for demanding applications that require zero backlash with minimal drag torque. With its compact size and no moving components, the NTG can also be easily incorporated into customer specified, custom molded parts.

An integral part of the NTG design is the ability to manually adjust the drag torque setting to match specific requirements of the application. This drag torque can also be set at the factory to meet individual customer specifications. This is especially effective with fine leads.

The standard NTG unit utilizes a self-lubricating polyacetal nut on a precision rolled 303 stainless steel screw. End machining to customer specifications and Kerkote® TFE screw coating are optional.



NTG Series Nut Assembly



NTG Mini Series Nut Assembly

NTG Mini Nut Series

The NTG Mini Series brings quality, precision and value to miniature lead screw assemblies that require a small-scale anti-backlash function and control of drag torque.

Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	YES

Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
5 to 10 million (12 to 25 million)	15 to 40 million (38 to 100 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

Identifying the NTG Series Nut Part Number Codes when Ordering

NTG	A	K	R	025	0050	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
NTG	A = Flanged (Triangular) T = Threaded X = Custom Mini Series Only: B = Barrel ^m R = Rectangular ^m	S = Uncoated K = Kerkote® TFE Coating N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Not Available for Micro Series) (Refer to lead screw charts for availability)	012 ^m = .125 in (3.2 mm) 013 ^m = .133 in (3.3 mm) 014 ^m = .141 in (3.6 mm) 016 ^m = .156 in (4 mm) 018 ^m = .188 in (5 mm) 021 ^m = .219 in (5.6 mm) 025 = .250 in (6 mm) 031 = .313 in (8 mm) 037 = .375 in (10 mm) ^m NTG Mini Series	(Refer to LEAD CODE Specifications charts, pages 4 to 6)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

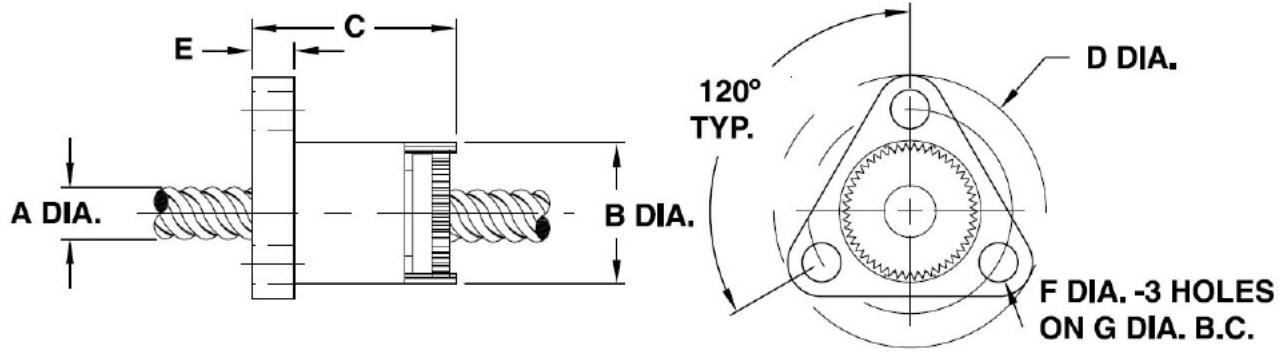
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

NTG Flange Mount

NTGA Flange Mount	Screw Diam.	Nut Diam.	Nut Length	Flange Diam.	Flange Thickness	Mounting Hole Diam.	Bolt Circle Diam.	Dynamic Load	Drag Torque
	A	B	C	D	E	F	G	lbs (Kg)	oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)		
	1/4 (6)	.52 (13.2)	.8 (20.3)	1.00 (25.4)	.16 (4.0)	.143 (3.63)	.750 (19.1)	10 (4.5)	5-2 (.004-.014)
5/16 (8)	.80 (20.3)	1.0 (25.4)	1.50 (38.1)	.20 (5.1)	.197 (5.00)	1.125 (28.6)	20 (9.1)	1-3 (.007-.02)	
3/8 (10)	.80 (20.3)	1.0 (25.4)	1.50 (38.1)	.20 (5.1)	.197 (5.00)	1.125 (28.6)	20 (9.1)	1-3 (.007-.02)	

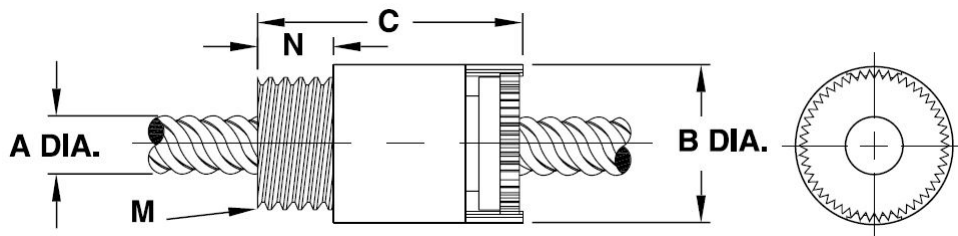
Metric numbers are for reference only.



NTGT Thread Mount

NTGT Tread Mount	Screw Diam.	Nut Diam.	Nut Length	Thread	Thread Length	Dynamic Load**	Drag Torque
	A	B	C	M*	N	lbs (Kg)	oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)		
	1/4 (6)	.520 (13.2)	.9 (22)	7/16 - 20	.250 (6.35)	10 (4.5)	5-2 (.004-.014)
5/16 (8)	.800 (20.3)	1.2 (30)	3/4 - 20	.375 (9.53)	20 (9.1)	1-3 (.007-.02)	
3/8 (10)	.800 (20.3)	1.2 (30)	3/4 - 20	.375 (9.53)	20 (9.1)	1-3 (.007-.02)	

Metric numbers are for reference only.

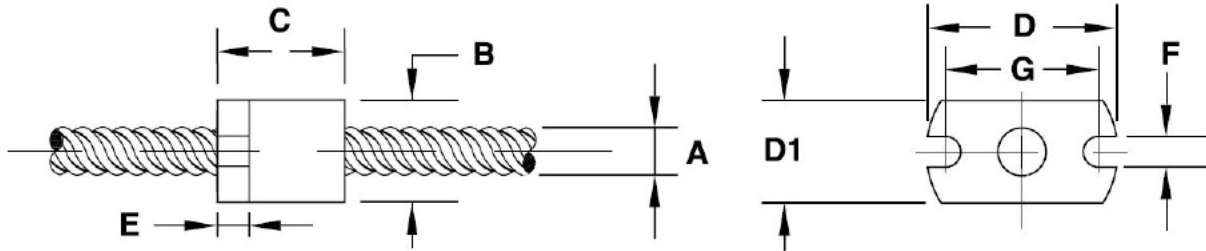


Dimensional Tolerances			
Inches		Metric (mm)	
.X	± .02	< L 4	± 0.1
.XX	± .010	4 < L ≤ 16	± 0.15
.XXX	± .005	16 < L ≤ 63	± 0.2
		63 < L ≤ 250	± 0.3

NTG Mini Flange Mount

NTGR Mini Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Height D1	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	0.40 (10.2)	0.75 (19.1)	0.13 (3.2)	0.120 (3.05)	0.600 (15.24)	5 (2.3)	0.5 (.004)

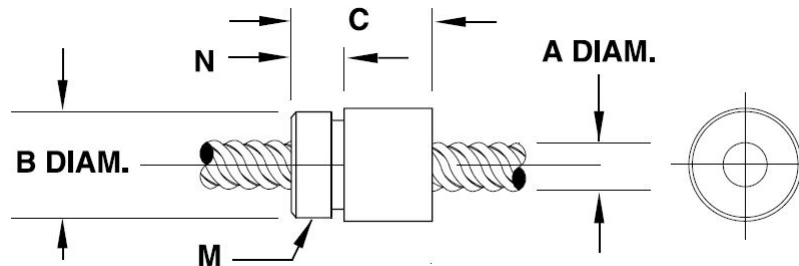
Metric numbers are for reference only.



NTGT Mini Thread Mount

NTGT Tread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load**	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	3/8-24	0.160 (4.06)	5 (2.3)	0.5 (.004)

Metric numbers are for reference only.



■ Lead Screw Compatibility: NTG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/8	3.2	012	0.024	0.61	0024		0.129	3.28	0.093	2.36	44
			0.039	1.00	0039		0.129	3.28	0.094	2.39	57
			0.048	1.22	0048		0.129	3.28	0.093	2.36	61
			0.075	1.91	0075		0.129	3.28	0.093	2.36	70
			0.096	2.44	0096	•	0.129	3.28	0.093	2.36	75
			0.125	3.18	0125	LH Only	0.125	3.18	0.078	1.98	80
.132	3.3	013	0.020	0.50	0020		0.132	3.35	0.104	2.64	42
			0.039	1.00	0039		0.132	3.35	0.080	2.03	61
			0.079	2.00	0079		0.132	3.35	0.080	2.03	75
			0.157	4.00	0157		0.132	3.35	0.080	2.03	84
			0.315	8.00	0315		0.132	3.35	0.080	2.03	87
9/64	3.6	014	0.012	0.30	0012		0.140	3.56	0.123	3.12	26
			0.024	0.61	0024		0.140	3.56	0.105	2.67	43
			0.048	1.22	0048		0.140	3.56	0.081	2.06	62
			0.096	2.44	0096		0.140	3.56	0.081	2.06	75
			0.394	10.00	0394		0.140	3.56	0.102	2.59	86
5/32	4	016	0.033	0.84	0033	•	0.156	3.96	0.116	2.95	45
			0.050	1.27	0050	LH Only	0.156	3.96	0.096	2.44	59
			0.094	2.39	0094		0.164	4.17	0.128	3.25	67
			0.125	3.18	0125		0.168	4.27	0.130	3.30	74
			0.250	6.35	0250		0.156	3.96	0.130	3.30	83
			0.375	9.53	0375		0.156	3.96	0.130	3.30	85
			0.500	12.70	0500		0.156	3.96	0.130	3.30	86
3/16	5	018	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
7/32	5.6	021	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096	•	0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250		0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

■ Lead Screw Compatibility: NTG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: NTG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

VHD Nut Series

The VHD Series anti-backlash assembly provides the maximum load carrying capability and the highest axial and radial stiffness of any Kerk® nut assembly. Designed for smooth, quiet operation and long life, the VHD assembly provides low drag torque by making use of the patented Kerk AXIAL TAKE-UP MECHANISM (see Lead screw Assemblies: Anti-Backlash Technologies section). Drag and wear associated with high pre-load forces are eliminated with the VHD Series. Screws are 303 stainless steel with Kerk's custom Kerkote® TFE extended life coating optional. Assemblies are available cut-to-length or with screws machined to your requirements.

VHD Series Nut Assemblies



VHD Series Nut

Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	NO

Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
200 to 225 million (500 to 570 million)	300 to 350 million (760 to 880 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

Identifying the VHD Series Nut Part Number Codes when Ordering

VHD	F	S	R	062	0125	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
VHD	F = Flanged (Round) T = Threaded X = Custom	S = Uncoated K = Kerkote® TFE Coating N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Not Available for Micro Series) (Refer to lead screw charts for availability)	050 = .500 in (13 mm) 062 = .625 in (16 mm) 075 = .750 in (19 mm) 087 = .875 in (22 mm)	(Refer to LEAD CODE Specifications charts, pages 3 to 4)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

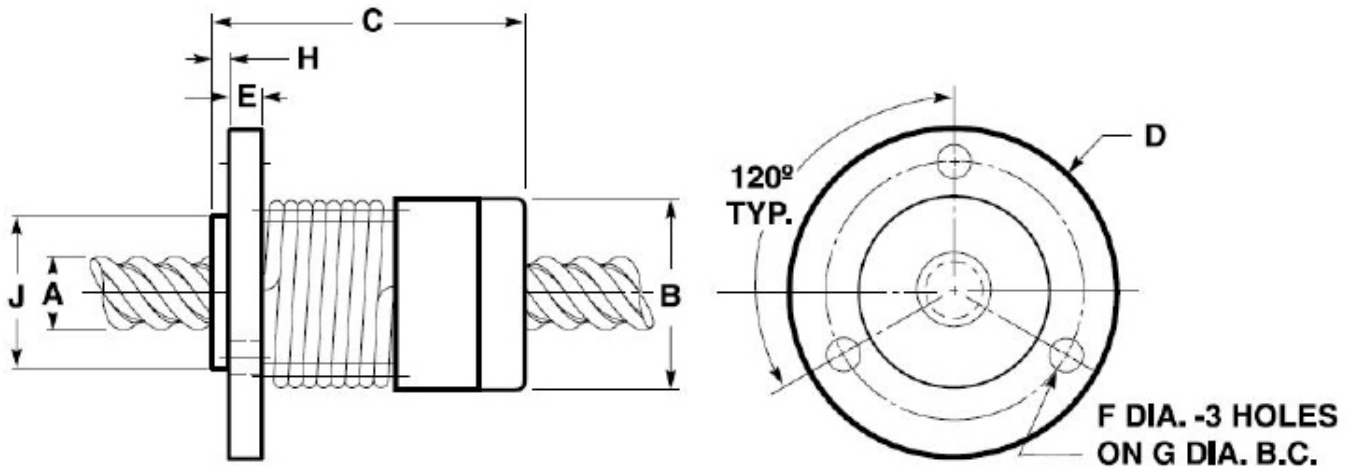
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

VHD Flange Mount

VHDF Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Hub Width H	Hub Diam. J	Dynamic Load lbs (Kg)	Drag Torque oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)		
	1/2 (13)	1.12 (28.5)	2.3 (59)	1.75 (44.5)	.23 (5.9)	.22 (5.60)	1.406 (35.71)	.12 (3.1)	.93 (23.62)	150 (68)	2-6 (.014-.02)
	5/8 (16)	1.38 (35.1)	2.6 (66)	2.08 (53)	.28 (7.1)	.22 (5.60)	1.750 (44.45)	N/A	N/A	250 (113)	2-6 (.014-.02)
	3/4 (19)	1.62 (41.2)	2.8 (71)	2.38 (60.5)	.31 (7.9)	.22 (5.60)	2.000 (50.80)	N/A	N/A	350 (159)	3-7 (.02-.05)
	7/8 (22)	1.62 (41.2)	2.8 (71)	2.38 (60.5)	.31 (7.9)	.22 (5.60)	2.000 (50.80)	N/A	N/A	350 (159)	3-7 (.02-.05)

Metric numbers are for reference only.

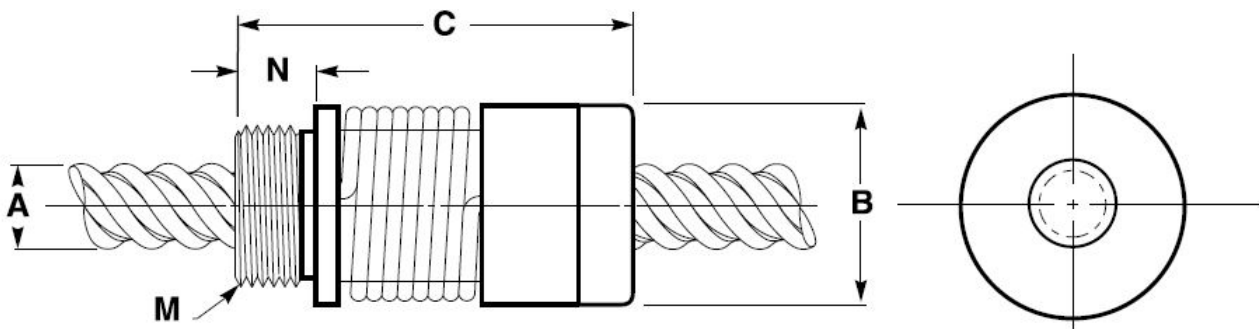


VHD Thread Mount

VHDT Tread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load** lbs (Kg)	Drag Torque oz-in (N-m)
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)		
	1/2 (13)	1.12 (28.5)	2.5 (64)	15/16-16	.50 (12.7)	150 (68)	2-6 (.014-.04)
	5/8 (16)	1.38 (35.1)	2.8 (72)	1 1/4-16	.50 (12.7)	250 (113)	2-6 (.014-.04)
	3/4 (19)	1.62 (41.2)	3.12 (79)	1 3/8-16	.50 (12.7)	350 (159)	3-7 (.02-.05)
	7/8 (22)	1.62 (41.2)	3.12 (79)	1 3/8-16	.50 (12.7)	350 (159)	3-7 (.02-.05)

Dimensional Tolerances			
Inches		Metric (mm)	
.X	± .02	< L 4	± 0.1
.XX	± .010	4 < L ≤ 16	± 0.15
.XXX	± .005	16 < L ≤ 63	± 0.2
		63 < L ≤ 250	± 0.3

Metric numbers are for reference only.



■ Lead screw Compatibility: VHD Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
0.984	25.00	0984		0.500	12.70	0.369	9.37	84			
1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84			
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
			2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

Lead Screw Compatibility: VHD Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/4	19	075	0.0625	1.59	0063		0.750	19.05	0.671	17.04	25
			0.098	2.50	0098		0.742	18.85	0.626	15.90	35
			0.100	2.54	0100	•	0.746	18.95	0.624	15.85	35
			0.1667	4.23	0167		0.727	18.47	0.645	16.38	47
			0.197	5.00	0197		0.745	18.92	0.624	15.85	51
			0.200	5.08	0200		0.741	18.82	0.632	16.05	52
			0.250	6.35	0250		0.731	18.57	0.639	16.23	57
			0.276	7.00	0276		0.750	19.05	0.624	15.85	59
			0.333	8.46	0333		0.750	19.05	0.624	15.85	64
			0.394	10.00	0394		0.745	18.92	0.619	15.72	67
			0.500	12.70	0500		0.744	18.90	0.624	15.85	73
			0.551	14.00	0551		0.750	19.05	0.624	15.85	73
			0.591	15.00	0591		0.749	19.02	0.623	15.82	74
			0.709	18.00	0709		0.780	19.81	0.650	16.51	77
			0.748	19.00	0748		0.672	17.07	0.547	13.89	80
			0.787	20.00	0787		0.780	19.81	0.648	16.46	78
			0.800	20.32	0800		0.750	19.05	0.618	15.70	79
			0.945	24.00	0945	•	0.734	18.64	0.633	16.08	80
			1.000	25.40	1000	•	0.743	18.87	0.619	15.72	81
			7/8	22	087	1.500	38.10	1500		0.712	18.08
1.969	50.00	1969				•	0.751	19.08	0.620	15.75	84
2.000	50.80	2000				•	0.742	18.85	0.611	15.52	84
2.400	60.96	2400				•	0.750	19.05	0.620	15.75	84
3.622	92.00	3622				•	0.750	19.05	0.634	16.10	87
0.200	5.08	0200				•	0.870	22.10	0.742	18.85	48
0.236	6.00	0236					0.848	21.54	0.773	19.63	52
0.250	6.35	0250					0.875	22.23	0.749	19.02	53
0.394	10.00	0394					0.875	22.23	0.741	18.82	65
0.500	12.70	0500					0.862	21.89	0.744	18.90	69
0.630	16.00	0630		0.875	22.23	0.741	18.82	73			
0.667	16.94	0667		0.871	22.12	0.745	18.92	74			
0.787	20.00	0787		0.875	22.23	0.741	18.82	78			
0.945	24.00	0945		0.875	22.23	0.741	18.82	79			
1.000	25.40	1000		0.871	22.12	0.742	18.85	80			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

WDG Nut Series

An economical anti-backlash nut assembly that provides precise positional accuracy and repeatability.

The WDG Series anti-backlash assembly utilizes an exceptionally compact design to provide stiffness and balanced accuracy for precise positioning. The unique wedge design locks the nut at the correct preload without excessive drag.

Shorter than other self-compensating nuts with similar performance, the WDG nut permits the design of smaller assemblies without sacrificing stroke length. Nut wear or momentary overload is accommodated through the WDG Series' compensation mechanism, which maintains positional accuracy in demanding applications.



WDG Series Nut Assembly

■ Highlights

- Compact Size, Moderate Load
- Cost Effective

■ Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	NO

■ Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
100 to 125 million (250 to 315 million)	200 to 250 million (500 to 635 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

■ Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

■ Identifying the WDG Series Nut Part Number Codes when Ordering

WDG	A	K	R	018	0039	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
WDG	A = Flanged (Triangular) P = Flange (Triangular with pilot) T = Threaded Micro Series X = Custom	S = Uncoated K = Kerkote® TFE Coating N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Refer to lead screw charts for availability)	018 = .188 in (5 mm) 021 = .219 in (5.6 mm) 025 = .250 in (6 mm) 031 = .313 in (8 mm) 037 = .375 in (10 mm) 043 = .438 in (11 mm) 050 = .500 in (13 mm)	(Refer to LEAD CODE Specifications charts, pages 3 to 5)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

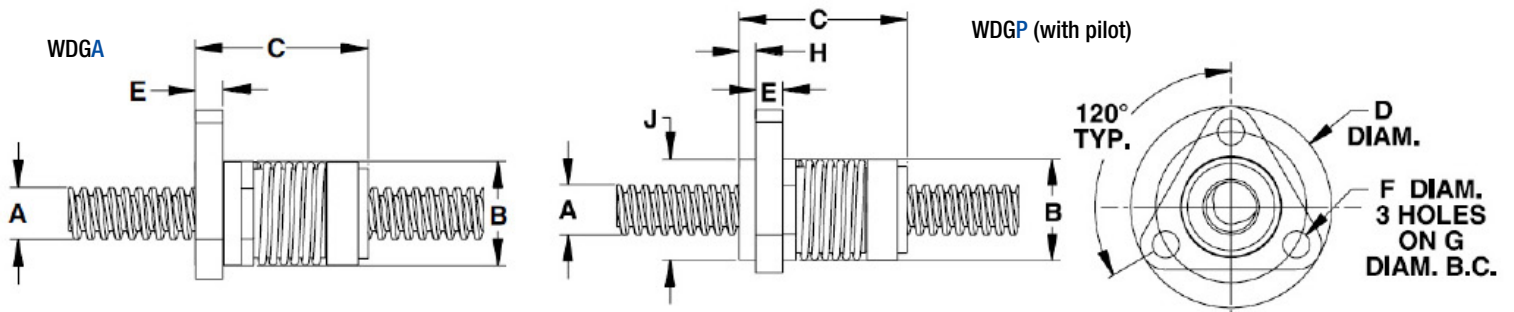
WDG Flange Mount and with pilot

	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Hub Length H	Hub Diam. J	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
WDGA Flange Mount & WDG (with pilot)	3/16 (4)	0.625 (16)	1.05 (26.6)	1.125 (28.6)	0.160 (4.1)	0.143 (3.7)	0.875 (22.2)	0.08 (2.04)	0.625 (15.9)	10 (4.5)	4 (.03)
	7/32 (5)	0.625 (16)	1.05 (26.6)	1.125 (28.6)	0.160 (4.1)	0.143 (3.7)	0.875 (22.2)	0.08 (2.04)	0.625 (15.9)	10 (4.5)	4 (.03)
	1/4 (6)	0.625 (16)	1.05 (26.6)	1.125 (28.6)	0.160 (4.1)	0.143 (3.7)	0.875 (22.2)	0.08 (2.04)	0.625 (15.9)	10 (4.5)	4 (.03)
	5/16 (8)	0.750 (19)	1.32 (33.5)	1.5 (38.1)	0.200 (5.08)	0.200 (5.08)	1.125 (28.6)	0.120 (3.05)	0.750 (19.1)	25 (11.3)	5 (.04)
	3/8 (10)	0.750 (19)	1.32 (33.5)	1.5 (38.1)	0.200 (5.08)	0.200 (5.08)	1.125 (28.6)	0.120 (3.05)	0.750 (19.1)	25 (11.3)	5 (.04)
	7/16 (11)	1.00 (25.4)	2.078 (52.8)	1.750 (44.5)	0.250 (6.35)	0.220 (5.6)	1.406 (35.7)	0.255 (6.48)	1.000 (25.4)	75 (34)	9 (.06)
	1/2 (13)	1.00 (25.4)	2.078 (52.8)	1.750 (44.5)	0.250 (6.35)	0.220 (5.6)	1.406 (35.7)	0.255 (6.48)	1.000 (25.4)	75 (34)	9 (.06)

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



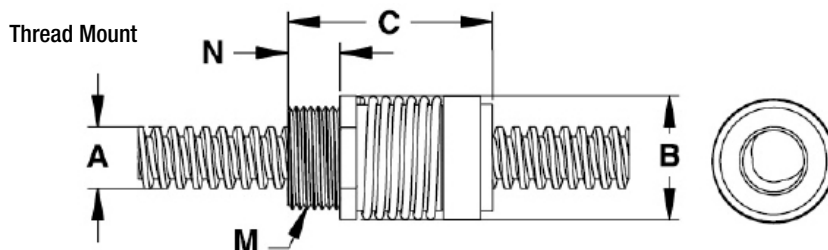
■ WDG Thread Mount

	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load**	Drag Torque**
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
WDGT Thread Mount	3/16 (4)	0.625 (16)	1.05 (26.6)	9/16 - 18	0.240 (6.1)	10 (4.5)	4 (.03)
	7/32 (5)	0.625 (16)	1.05 (26.6)	9/16 - 18	0.240 (6.1)	10 (4.5)	4 (.03)
	1/4 (6)	0.625 (16)	1.05 (26.6)	9/16 - 18	0.240 (6.1)	10 (4.5)	4 (.03)
	5/16 (8)	0.750 (19)	1.32 (33.5)	5/8 - 18	0.320 (8.1)	25 (11.3)	5 (.04)
	3/8 (10)	0.750 (19)	1.32 (33.5)	5/8 - 18	0.320 (8.1)	25 (11.3)	5 (.04)
	7/16 (11)	1.00 (25.4)	2.078 (52.8)	15/16 - 16	0.500 (12.7)	75 (34)	9 (.06)
	1/2 (13)	1.00 (25.4)	2.078 (52.8)	15/16 - 16	0.500 (12.7)	75 (34)	9 (.06)

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



Dimensional Tolerances		
Inches	Metric (mm)	
.X	± .02	< L 4 ± 0.1
.XX	± .010	4 < L ≤ 16 ± 0.15
.XXX	± .005	16 < L ≤ 63 ± 0.2
		63 < L ≤ 250 ± 0.3

■ Lead Screw Compatibility: WDG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/16	5	018	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
			0.500	12.70	0500	•	0.188	4.78	0.142	3.61	86
7/32	5.6	021	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096		0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250	•	0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

Lead Screw Compatibility: WDG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: WDG Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
7/16	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
			0.615	15.62	0615		0.475	12.07	0.376	9.55	82
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
			0.984	25.00	0984		0.500	12.70	0.369	9.37	84
			1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

ZBA Nut Series

Developed specifically for those applications that require very smooth and consistent motion, the patented ZBA Series offers a cost effective anti-backlash assembly for applications requiring precise positional accuracy and repeatability. The ZBA has been developed specifically for those applications that require very smooth and consistent motion such as printing, scanning, and coordinate measurement systems. An added benefit of the ZBA design is the ability to manually adjust the drag torque setting to match the specific requirements of the application. This drag torque can also be set at the factory to meet individual customer specifications. The inherent damping qualities of the ZBA design make it ideally suited for applications requiring noise or vibration control. The standard ZBA unit utilizes a self-lubricating polyacetal nut radially preloaded on a 303 stainless steel screw. End machining to customer specifications and Kerkote® TFE screw coating are optional.



ZBA Series Nut Assembly

■ Highlights

- Adjustable Drag Torque
- Cost Effective
- Smooth and Consistent Motion

■ Grease Compatibility

Coatings	Compatible
Kerkote TFE Coating	YES
Black Ice TFE Coating	YES
Grease	YES

■ Dimensional Tolerances

Inches	Metric (mm)
.X ± .02	< L 4 ± 0.1
.XX ± .010	4 < L ≤ 16 ± 0.15
.XXX ± .005	16 < L ≤ 63 ± 0.2
	63 < L ≤ 250 ± 0.3

■ Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
5 to 10 million (12 to 25 million)	15 to 40 million (38 to 100 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

■ Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

■ Identifying the ZBA Micro Series Nut Part Number Codes when Ordering

ZBA	A	K	R	062	0100	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
ZBA	A = Flanged (Triangular) T = Threaded Micro Series X = Custom	S = Uncoated K = Kerkote® TFE Coating G = Grease N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Refer to lead screw charts for availability)	025 = .250 in (6 mm) 031 = .313 in (8 mm) 037 = .375 in (10 mm) 043 = .438 in (11 mm) 050 = .500 in (13 mm) 062 = .625 in (16 mm) 075 = .750 in (19 mm) 087 = .875 in (22 mm) 093 = .938 in (24 mm)	(Refer to LEAD CODE Specifications charts, pages 3 to 6)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

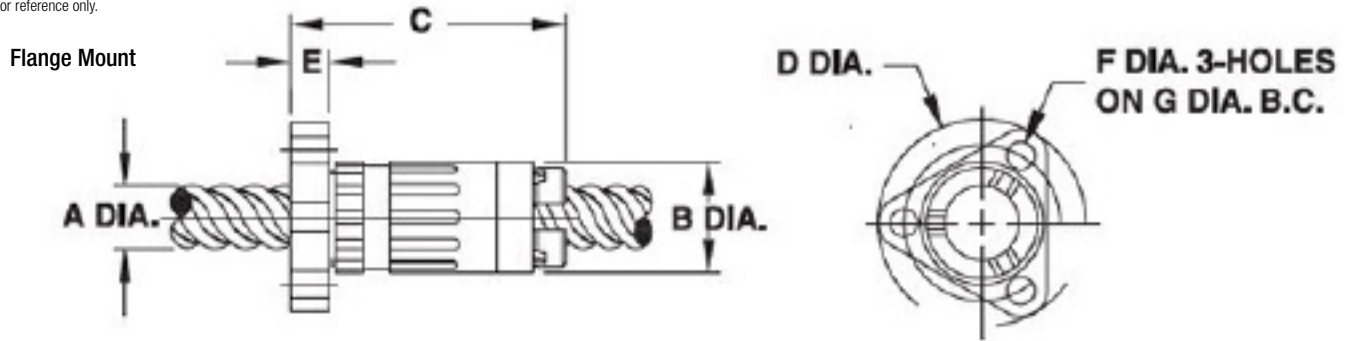
ZBA Flange Mount

ZBAA Flange Mount	Screw Diam. A inch (mm)	Nut Diam. B inch (mm)	Nut Length C inch (mm)	Flange Diam. D inch (mm)	Flange Thickness E inch (mm)	Mounting Hole Diam. F inch (mm)	Bolt Circle Diam. G inch (mm)	Dynamic Load lbs (Kg)	Drag Torque oz-in (N-m)
	1/4 (6)	.50 (12.7)	1.0 (26)	1.0 (25.4)	.18 (4.6)	.140 (3.6)	.750 (19.1)	5 (2.3)	.25 - 3 (.002 - .021)
	5/16 (8)	.70 (17.8)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	10 (5)	1 - 5 (.007 - .03)
	3/8 (10)	.70 (17.8)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	10 (5)	1 - 5 (.007 - .03)
	7/16 (11)	.80 (20.3)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	15 (7)	2 - 6 (.014 - .04)
	1/2 (13)	.89 (22.6)	2.0 (51)	1.62 (41.2)	.26 (6.6)	.200 (5.08)	1.125 (28.6)	25 (11)	3 - 7 (.02 - .05)
	5/8 (16)	1.06 (26.9)	2.0 (51)	1.75 (44.5)	.26 (6.6)	.200 (5.08)	1.375 (34.9)	35 (16)	4 - 8 (.028 - .055)
	3/4 (19)	1.70 (43.2)	2.88 (73.2)	2.63 (66.8)	0.38 (9.6)	0.218 (5.5)	2.25 (57.2)	55 (25)	5-9 (.03-.064)
	7/8 (22)	1.70 (43.2)	2.88 (73.2)	2.63 (66.8)	0.38 (9.6)	0.218 (5.5)	2.25 (57.2)	55 (25)	5-9 (.03-.064)
	15/16 (24)	1.70 (43.2)	2.88 (73.2)	2.63 (66.8)	0.38 (9.6)	0.218 (5.5)	2.25 (57.2)	55 (25)	5-9 (.03-.064)

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



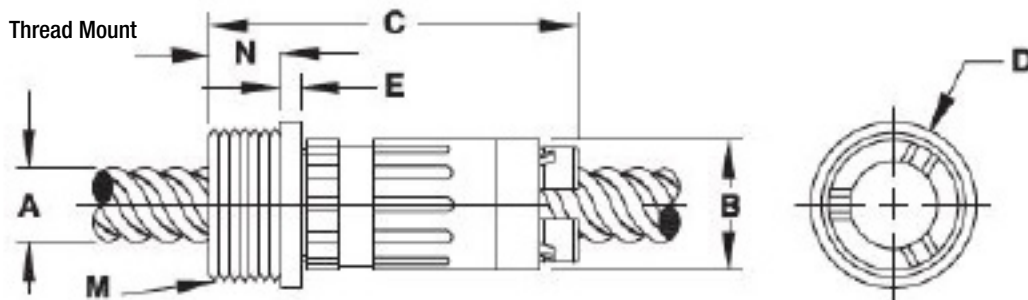
ZBX Thread Mount

ZBXT Thread Mount	Screw Diam. A inch (mm)	Nut Diam. B inch (mm)	Nut Length C inch (mm)	Flange Diam. D inch (mm)	Flange Thickness E inch (mm)	Thread M *	Thread Length N inch (mm)	Dynamic Load** lbs (Kg)	Drag Torque** oz-in (N-m)
	1/4 (6)	.50 (12.7)	1.3 (33)	.80 (20.3)	.22 (5.6)	5/8 - 18	.16 (4.1)	5 (2.3)	.25 - 3 (.002 - .021)
	5/16 (8)	.70 (17.8)	2.2 (56)	1.00 (25.4)	.17 (4.3)	5/8 - 18	.38 (9.7)	10 (5)	1 - 5 (.007 - .03)
	3/8 (10)	.70 (17.8)	2.2 (56)	1.00 (25.4)	.17 (4.3)	5/8 - 18	.38 (9.7)	10 (5)	1 - 5 (.007 - .03)
	7/16 (11)	.80 (20.3)	2.3 (59)	1.00 (25.4)	.12 (3.1)	15/16 - 16	.38 (9.7)	15 (7)	2 - 6 (.014 - .04)
	1/2 (13)	.89 (22.6)	2.3 (59)	1.02 (25.9)	.12 (3.1)	15/16 - 16	.38 (9.7)	25 (11)	3 - 7 (.02 - .05)
	5/8 (16)	1.06 (26.9)	2.4 (61)	1.06 (26.9)	.15 (3.8)	15/16 - 16	.50 (12.7)	35 (16)	4 - 8 (.028 - .055)

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



■ Lead Screw Compatibility: ZBA Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

■ Lead Screw Compatibility: ZBA Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			
7/16	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
			0.615	15.62	0615		0.475	12.07	0.376	9.55	82

■ Lead Screw Compatibility: ZBA Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
0.984	25.00	0984		0.500	12.70	0.369	9.37	84			
1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84			
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
			2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: ZBA Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/4	19	075	0.0625	1.59	0063		0.750	19.05	0.671	17.04	25
			0.098	2.50	0098		0.742	18.85	0.626	15.90	35
			0.100	2.54	0100	•	0.746	18.95	0.624	15.85	35
			0.1667	4.23	0167		0.727	18.47	0.645	16.38	47
			0.197	5.00	0197		0.745	18.92	0.624	15.85	51
			0.200	5.08	0200		0.741	18.82	0.632	16.05	52
			0.250	6.35	0250		0.731	18.57	0.639	16.23	57
			0.276	7.00	0276		0.750	19.05	0.624	15.85	59
			0.333	8.46	0333		0.750	19.05	0.624	15.85	64
			0.394	10.00	0394		0.745	18.92	0.619	15.72	67
			0.500	12.70	0500		0.744	18.90	0.624	15.85	73
			0.551	14.00	0551		0.750	19.05	0.624	15.85	73
			0.591	15.00	0591		0.749	19.02	0.623	15.82	74
			0.709	18.00	0709		0.780	19.81	0.650	16.51	77
			0.748	19.00	0748		0.672	17.07	0.547	13.89	80
			0.787	20.00	0787		0.780	19.81	0.648	16.46	78
			0.800	20.32	0800		0.750	19.05	0.618	15.70	79
			0.945	24.00	0945		0.734	18.64	0.633	16.08	80
			1.000	25.40	1000	•	0.743	18.87	0.619	15.72	81
			1.500	38.10	1500	•	0.712	18.08	0.590	14.99	84
1.969	50.00	1969		0.751	19.08	0.620	15.75	84			
2.000	50.80	2000	•	0.742	18.85	0.611	15.52	84			
2.400	60.96	2400	•	0.750	19.05	0.620	15.75	84			
3.622	92.00	3622	•	0.750	19.05	0.634	16.10	87			
7/8	22	087	0.200	5.08	0200	•	0.870	22.10	0.742	18.85	48
			0.236	6.00	0236		0.848	21.54	0.773	19.63	52
			0.250	6.35	0250		0.875	22.23	0.749	19.02	53
			0.394	10.00	0394		0.875	22.23	0.741	18.82	65
			0.500	12.70	0500		0.862	21.89	0.744	18.90	69
			0.630	16.00	0630		0.875	22.23	0.741	18.82	73
			0.667	16.94	0667		0.871	22.12	0.745	18.92	74
			0.787	20.00	0787		0.875	22.23	0.741	18.82	78
			0.945	24.00	0945		0.875	22.23	0.741	18.82	79
			1.000	25.40	1000		0.871	22.12	0.742	18.85	80
15/16	24	093	0.050	1.27	0050	LH Only	0.938	23.83	0.874	22.20	17
			2.000	50.80	2000		0.927	23.55	0.815	20.70	85
			3.000	76.20	3000	•	0.939	23.85	0.803	20.40	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

ZBX Nut Series

An economical anti-backlash nut assembly that provides precise positional accuracy and repeatability. The patented ZBX Series anti-backlash assembly offers an effective linear actuator for design operations requiring precise positional accuracy and repeatability, with minimum cost. The standard ZBX unit utilizes a patented self-lubricating polyacetal nut radially preloaded on a 303 stainless steel screw. The ZBX assembly, through its unique transfer of loads, offers exceptional torque consistency and repeatability when traversing in either direction. The inherent damping qualities of the ZBX design make it ideally suited for vertical applications requiring noise or vibration control. End machining to customer specifications and Kerkote® TFE screw coating are optional, as are designs for special operating configurations or environments.

ZBM Micro Nut Series

Made from self-lubricating acetal and Kerkite® High Performance Composite Polymers. This remarkable product line is an enabling technology, opening up a whole new range of designs. Developed in response to growing demands in many markets, Haydon Kerk Motion Solutions has offered micro screws on a custom basis for more than 10 years. Now, available as a standard product, customers can get quicker, cost effective deliveries. The Micro Series ZBM anti-backlash and Micro Series lead screws are available as standalone components or integrated into the high performance Haydon linear actuators. The Micro Series allows the miniaturization of products, reduced power consumption, and weight reduction without sacrificing performance or reliability.

■ Highlights

- Economical anti-backlash nut assembly
- Light Loads
- Ultra-Smooth Motion
- Precise positional accuracy and repeatability

■ ZBX Technical Data

Material	Polyacetal with Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.



■ ZBX Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	YES

■ ZBX Anti-Backlash Life

Without Kerkote® TFE Coating inch / (cm)	With Kerkote® TFE Coating inch / (cm)
40 to 60 million (100 to 150 million)	150 to 200 million (380 to 500 million)

Anti-backlash life is defined as the nut's ability to compensate for wear while maintaining its zero backlash properties. Above life data is based on 25% of the dynamic load rating. Life will vary with loading, operating environment, and duty cycle. The longer screw leads generally provide longer life.

■ Identifying the ZBX and ZBM Micro Series Nut Part Number Codes when Ordering

ZBX	T	S	R	025	0050	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
ZBX ZBM = Micro Series	A = Flanged (Triangular) T = Threaded Micro Series R = Rectangular X = Custom	S = Uncoated K = Kerkote® TFE Coating G = Grease N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Refer to lead screw charts for availability)	008* = .078 in (2 mm) 025 = .250 in (6 mm) 031 = .313 in (8 mm) 037 = .375 in (10 mm) 043 = .438 in (11 mm) 050 = .500 in (13 mm) 062 = .625 in (16 mm) *Micro Series only	(Refer to LEAD CODE Specifications charts, pages 4 to 6)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

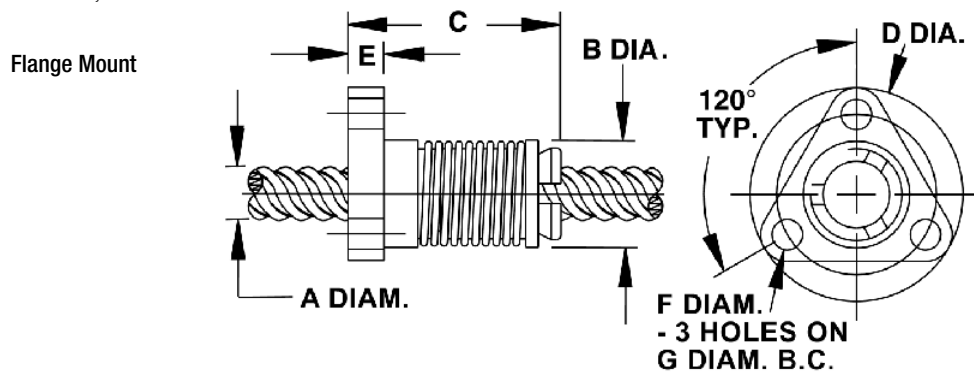
ZBX Flange Mount

ZBXA Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Dynamic Load**	Drag Torque**
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/4 (6)	.50 (12.7)	1.0 (26)	1.0 (25.4)	.18 (4.6)	.140 (3.6)	.750 (19.1)	5 (2.3)	.25 - 3 (.002 - .021)
	5/16 (8)	.70 (17.8)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	10 (5)	1 - 5 (.007 - .03)
	3/8 (10)	.70 (17.8)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	10 (5)	1 - 5 (.007 - .03)
	7/16 (11)	.80 (20.3)	1.9 (48)	1.5 (38.1)	.18 (4.6)	.200 (5.08)	1.125 (28.6)	15 (7)	2 - 6 (.014 - .04)
	1/2 (13)	.89 (22.6)	2.0 (51)	1.62 (41.2)	.26 (6.6)	.200 (5.08)	1.125 (28.6)	25 (11)	3 - 7 (.02 - .05)
5/8 (16)	1.06 (26.9)	2.0 (51)	1.75 (44.5)	.26 (6.6)	.200 (5.08)	1.375 (34.9)	35 (16)	4 - 8 (.028 - .055)	

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



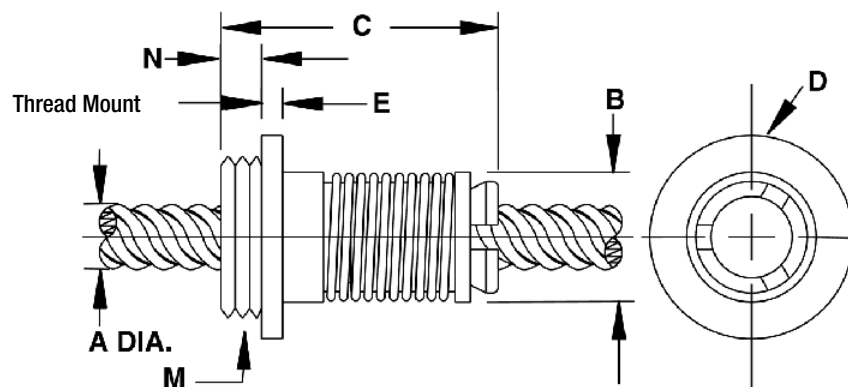
ZBX Thread Mount

ZBXT Thread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Diam. D	Flange Thickness E	Thread M*	Thread Length N	Dynamic Load**	Drag Torque**
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/4 (6)	.50 (12.7)	1.3 (33)	.80 (20.3)	.22 (5.6)	5/8 - 18	.16 (4.1)	5 (2.3)	.25 - 3 (.002 - .021)
	5/16 (8)	.70 (17.8)	2.2 (56)	1.00 (25.4)	.17 (4.3)	5/8 - 18	.38 (9.7)	10 (5)	1 - 5 (.007 - .03)
	3/8 (10)	.70 (17.8)	2.2 (56)	1.00 (25.4)	.17 (4.3)	5/8 - 18	.38 (9.7)	10 (5)	1 - 5 (.007 - .03)
	7/16 (11)	.80 (20.3)	2.3 (59)	1.00 (25.4)	.12 (3.1)	15/16 - 16	.38 (9.7)	15 (7)	2 - 6 (.014 - .04)
	1/2 (13)	.89 (22.6)	2.3 (59)	1.02 (25.9)	.12 (3.1)	15/16 - 16	.38 (9.7)	25 (11)	3 - 7 (.02 - .05)
5/8 (16)	1.06 (26.9)	2.4 (61)	1.06 (26.9)	.15 (3.8)	15/16 - 16	.50 (12.7)	35 (16)	4 - 8 (.028 - .055)	

¹metric available as required

²other spring pre-loads available

Metric numbers are for reference only.



ZBX Dimensional Tolerances			
	Inches		Metric (mm)
	.X	± .02	< L 4 ± 0.1
	.XX	± .010	4 < L ≤ 16 ± 0.15
	.XXX	± .005	16 < L ≤ 63 ± 0.2
			63 < L ≤ 250 ± 0.3

ZBM Micro Series Rectangular Anti-Backlash Nut Style for Micro Lead screws

ZBMR	ZBMW Nut Style	Screw Diam. A inch (mm)	Nut Diam. B inch (mm)	Nut Length C inch (mm)	Flange Diam. D1 inch (mm)	Flange Diam. D inch (mm)	Flange Thickness E inch (mm)	Thread M * inch (mm)	Thread Length N inch (mm)	Dynamic Load** lbs (Kg)	Drag Torque** oz-in (N-m)
	Rectangular Flange	5/64 (2)	0.22 (5.5)	0.32 (8)	0.22 (5.5)	0.47 (11.9)	0.08 (2.0)	0.07 (1.8)	0.35 (9.0)	1 (.45)	0.5 (.0035) Max.

¹metric available as required

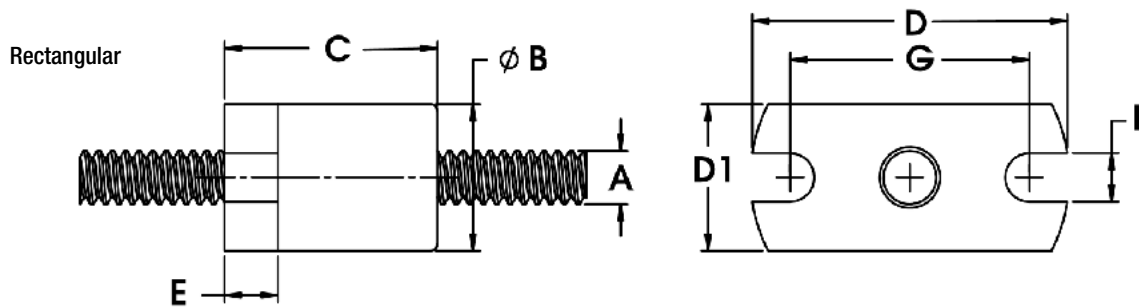
²other spring pre-loads available

Metric numbers are for reference only.

Micro Lead Screw Size List	Diameter		Diam. Code	Lead		LEAD CODE	Outside Diameter (for Reference)		Root Diameter (for Reference)		Efficiency %**
	(inches)	(mm)		(inches)	(mm)		(inches)	(mm)	(inches)	(mm)	
	5/64	2	008	0.020	0.50	0020	0.077	1.96	0.057	1.45	36**
				0.039	1.00	0039	0.079	2.01	0.059	1.50	52**
				0.079	2.00	0079	0.077	1.96	0.057	1.45	66**

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws



■ Lead Screw Compatibility: ZBX Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
5/64	2	008	0.020	0.50	0020		0.077	1.96	0.057	1.45	36**
			0.039	1.00	0039		0.079	2.01	0.059	1.50	52**
			0.079	2.00	0079		0.077	1.96	0.057	1.45	66**
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
0.400	10.16	0400		0.250	6.35	0.170	4.32	84			
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.80	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: ZBX Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
0.667	19.05	0750		0.388	9.86	0.273	6.93	84			
0.984	25.00	0984		0.375	9.53	0.262	6.65	84			
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			
7/16	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
			0.615	15.62	0615		0.475	12.07	0.376	9.55	82
Contact Details											

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: ZBX Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
			0.984	25.00	0984		0.500	12.70	0.369	9.37	84
			1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
			2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

Free Wheeling and Specialty Nuts

Haydon Kerk offers conventional style free-wheeling nuts – without anti-backlash features – in our standard self-lubricating polyacetal material, as well as a wide range of proprietary engineered thermoplastics to suit a wealth of applications. Catalog configurations provide several mounting options for quick and affordable implementation, and our extensive inhouse molding capabilities allow for highly custom and tightly integrated conformations for our OEM customers.

3DP Nut Series

Advanced technology for custom motion control prototype development. The 3DP nut offering is designed for rapid prototyping with additive manufacturing. One of the challenges with the current material offerings in 3D printing is the lack of low wear, low friction materials. For prototyping a lead screw driven assembly, it's critical to simulate the correct tribological performance of the lead nut solution to understand how the axis of motion will perform. By integrating basic anti-rotation, and axial locking features with our high efficiency thread form the 3DP nut allows for simple integration of a premium performance thread system into a 3D printed prototype. This gives engineers and developers a leg up on the competition by being able to quickly test several configurations while leveraging additive manufacturing and top performing lead nut materials. The result is shortened design cycle and rapid product launch to market allowing you to capture more market share with your latest and greatest solution.

021, 025, and 037 3DP Nuts



Examples of 3D printed nut applications

Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	YES

Technical Data

Material	Polyacetal with Lubricant Additive	Kerkite® KN30 High Performance Engineered Polymer
Tensile Strength	9,700 psi	25,000 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F	1.1 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **	
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*	

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

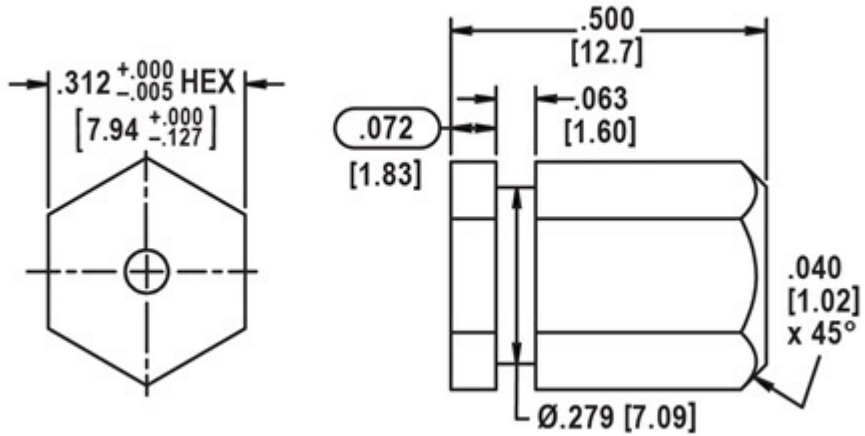
Identifying the 3DP Series Nut Part Number Codes when Ordering

3DP	H	K	R	012	0012	BZ00
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
3DP	H = Hex	S = Uncoated K = Kerkote® TFE Coating G = Grease N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Refer to lead screw charts for availability)	012 = .125 in (3.2 mm) 013 = .133 in (3.3 mm) 014 = .141 in (3.6 mm) 016 = .156 in (4 mm) 018 = .188 in (5 mm) 021 = .219 in (5.6 mm) 025 = .250 in (6 mm) 037 = .375 in (10 mm)	(Refer to LEAD CODE Specifications charts, pages 3 to 4)	BZ00 = Acetal base with lubrication matrix KZ00 = Kerkite® KN30 high performance polymer BYXX = Standard acetal base hex nut and cut to length lead screw (XX = length in inches) KYXX = Kerkite® KN30 base hex nut and cut to length lead screw (XX = length in inches)

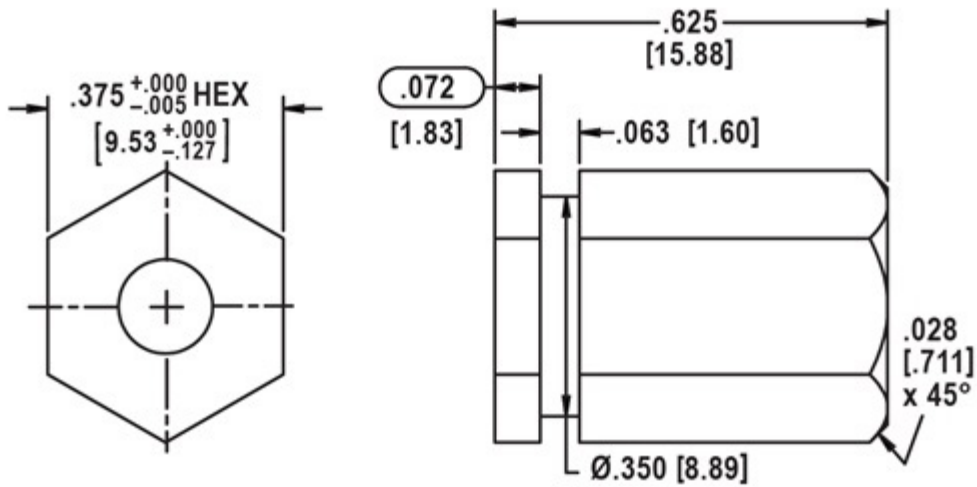
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings inch [mm]

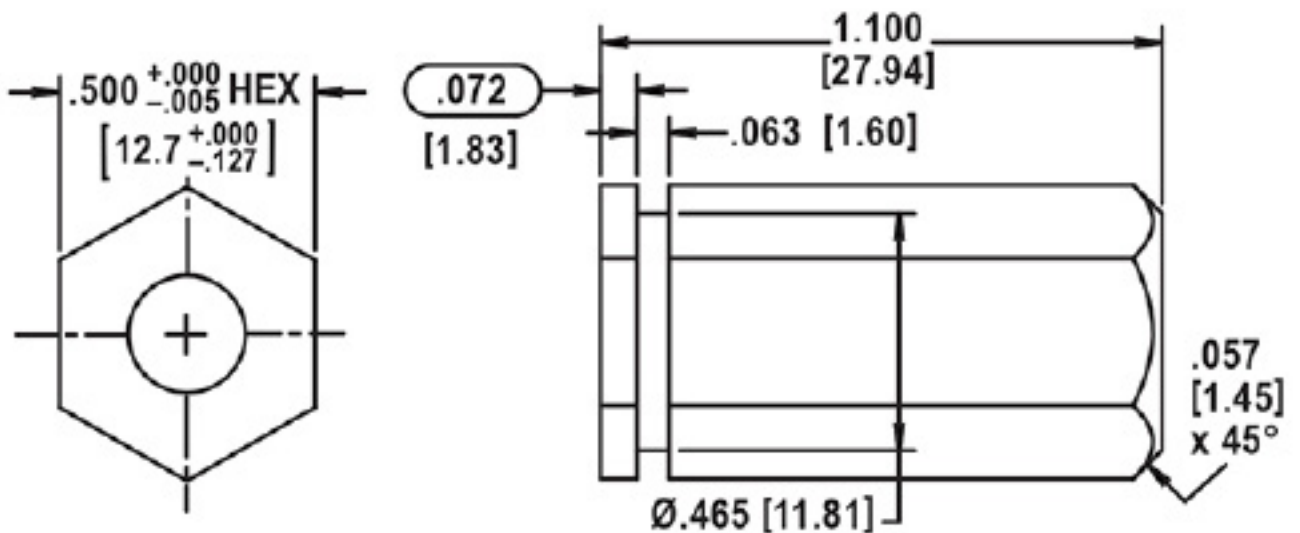
3DP Hex Nut: 012 to 021 Series



3DP Hex Nut: 025 Series



3DP Hex Nut: 037 Series



■ Lead Screw Compatibility: 3DP Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/8	3.2	012	0.024	0.61	0024		0.129	3.28	0.093	2.36	44
			0.039	1.00	0039		0.129	3.28	0.094	2.39	57
			0.048	1.22	0048		0.129	3.28	0.093	2.36	61
			0.075	1.91	0075		0.129	3.28	0.093	2.36	70
			0.096	2.44	0096	•	0.129	3.28	0.093	2.36	75
			0.125	3.18	0125	LH Only	0.125	3.18	0.078	1.98	80
.132	3.3	013	0.020	0.50	0020		0.132	3.35	0.104	2.64	42
			0.039	1.00	0039		0.132	3.35	0.080	2.03	61
			0.079	2.00	0079		0.132	3.35	0.080	2.03	75
			0.157	4.00	0157		0.132	3.35	0.080	2.03	84
			0.315	8.00	0315		0.132	3.35	0.080	2.03	87
9/64	3.6	014	0.012	0.30	0012		0.140	3.56	0.123	3.12	26
			0.024	0.61	0024		0.140	3.56	0.105	2.67	43
			0.048	1.22	0048		0.140	3.56	0.081	2.06	62
			0.096	2.44	0096		0.140	3.56	0.081	2.06	75
			0.394	10.00	0394		0.140	3.56	0.102	2.59	86
5/32	4	016	0.033	0.84	0033	•	0.156	3.96	0.116	2.95	45
			0.050	1.27	0050	LH Only	0.156	3.96	0.096	2.44	59
			0.094	2.39	0094		0.164	4.17	0.128	3.25	67
			0.125	3.18	0125		0.168	4.27	0.130	3.30	74
			0.250	6.35	0250		0.156	3.96	0.130	3.30	83
			0.375	9.53	0375		0.156	3.96	0.130	3.30	85
			0.500	12.70	0500		0.156	3.96	0.130	3.30	86
3/16	5	018	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
			0.500	12.70	0500	•	0.188	4.78	0.142	3.61	86
7/32	5.6	021	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096		0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250	•	0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

Lead Screw Compatibility: 3DP Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
			1.000	25.40	1000		0.383	9.73	0.254	6.45	84
			1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

BFW Nut Series

Conventional style, without “anti-backlash” function. The BFW Series general purpose “free-wheeling” nut is for applications not requiring anti-backlash and wear compensation. It provides effective power transmission at minimum cost, and features long life, self-lubricating polyacetal nuts.

The secure mounting and convenience of a circular flange is standard on the BFW nuts with triangular flange and thread mounting as an option. Many custom configurations are available.

Screws are 303 stainless steel with extended life, custom Kerkote® TFE coating optional. Assemblies can be supplied cut-to-length or with ends machined to customer requirements and Kerkote® TFE screw coating are optional.

BFW Series Nut Assemblies



BFW Micro Series Nut Assemblies

BFW Micro Nut Series

The BFW Micro Series enables a whole new range of micro-sized designs. It allows the miniaturization without sacrificing performance or reliability.

Backlash

N/A, Typical Backlash
.003 to .010 (.076 to .25)

Grease Compatibility

Coatings	Compatible
Kerkote® TFE Coating	YES
Black Ice® TFE Coating	YES
Grease	NO

Technical Data

Material	Polyacetal, Lubricant Additive
Tensile Strength	9,700 psi
Coefficient of Expansion	6.0 x 10 ⁻⁵ in/in/°F
Coefficient of Friction Polyacetal Nut to Screw	Static = .08 .08 ** Dynamic = .15 .09 **
Standard Operating Temperature Range	32 - 200° F* (0 - 93° C)*

* Very high or low temperatures may cause significant changes in the nut fit or drag torque. Please call the HKP Engineering Team at 603 213 6290 for optional temperature range materials.

** with Kerkote® TFE Coating.

Identifying the BFW Series Nut Part Number Codes when Ordering

BFW	A	K	R	018	0020	XXXX
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
BFW	A = Flanged (Triangular) F = Flanged (Round) T = Threaded X = Custom For Mini and Micro Series Only: B = Barrel m μ R = Rectangular m μ ^m BFW Mini Series ^μ BFW Micro Series	S = Uncoated K = Kerkote® TFE Coating G = Grease N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Not Available for Micro Series) (Refer to lead screw charts for availability)	008 = .078 in (2 mm) 012 ^m = .125 in (3.2 mm) 013 ^m = .133 in (3.3 mm) 014 ^m = .141 in (3.6 mm) 016 ^m = .156 in (4 mm) 018 ^m = .188 in (5 mm) 021 ^m = .219 in (5.6 mm) 025 = .250 in (6 mm) 031 = .313 in (8 mm) 037 = .375 in (10 mm) 043 = .438 in (11 mm) 050 = .500 in (13 mm) 062 = .625 in (16 mm) 075 = .750 in (19 mm) 087 = .875 in (22 mm) 093 = .938 in (24 mm) ^m BFW Mini Series ^μ BFW Micro Series	(Refer to LEAD CODE Specifications charts, pages 5 to 9)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

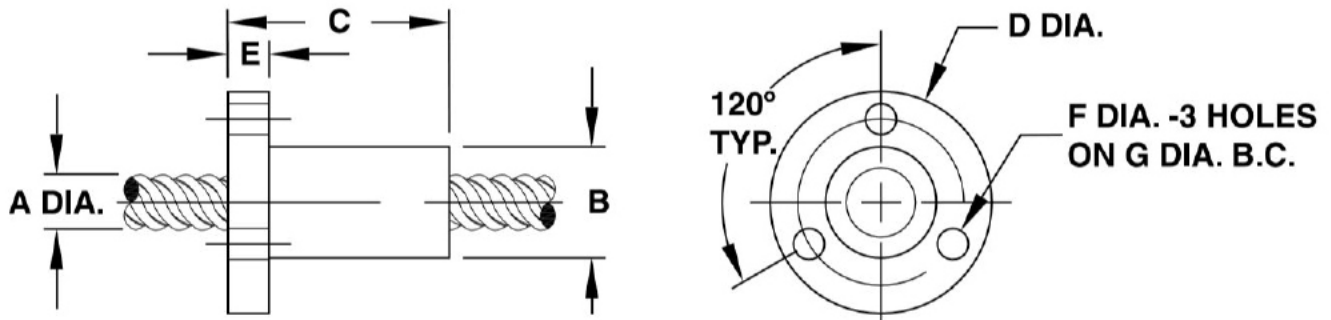
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ Dimensional Drawings

BFW Round Flange Mount

BFWF Flange Mount	Screw Diam.	Nut Diam.	Nut Length	Flange Diam.	Flange Thickness	Mounting Hole Diam.	Bolt Circle Diam.	Dynamic Load
	A	B	C	D	E	F	G	
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)
	1/4 (6)	.50 (12.7)	1.0 (25.4)	100 (25.4)	.19 (4.8)	.140 (3.56)	.750 (19.05)	50 (20)
	5/16 (8)	.63 (15.9)	1.0 (25.4)	1.13 (28.7)	.19 (4.8)	.140 (3.56)	.875 (22.23)	75 (35)
	3/8 (10)	.63 (15.9)	1.0 (25.4)	1.13 (28.7)	.19 (4.8)	.140 (3.56)	.875 (22.23)	75 (35)
	7/16 (11)	.75 (19.1)	1.5 (38)	1.50 (38.1)	.19 (4.8)	.203 (5.16)	1.125 (28.58)	90 (40)
	1/2 (13)	.75 (19.1)	1.5 (38)	1.50 (38.1)	.19 (4.8)	.203 (5.16)	1.125 (28.58)	150 (68)
	5/8 (16)	.88 (22.2)	1.5 (38)	1.50 (38.1)	.19 (4.8)	.203 (5.16)	1.188 (30.18)	225 (100)
	3/4 (19)	1.12 (28.4)	2.0 (51)	1.75 (44.4)	.25 (6.4)	.203 (5.16)	1.438 (36.53)	350 (160)
	7/8 (22)	1.50 (38.1)	2.0 (51)	2.25 (57.1)	.25 (6.4)	.203 (5.16)	1.875 (47.63)	500 (227)
	15/16 (24)	1.50 (38.1)	2.0 (51)	2.25 (57.1)	.25 (6.4)	.203 (5.16)	1.875 (47.63)	500 (227)

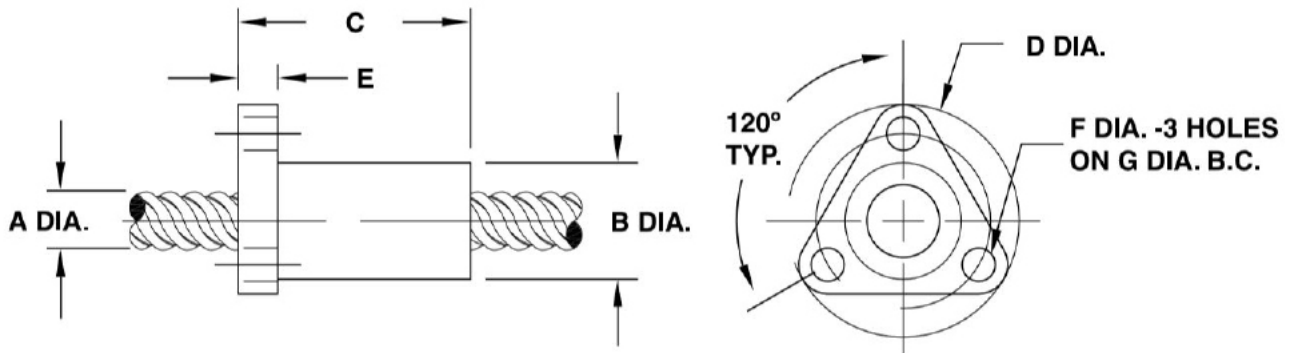
Metric numbers are for reference only.



BFW Triangular Flange Mount

BFWA Triangular Flange Mount	Screw Diam.	Nut Diam.	Nut Length	Flange Diam.	Flange Thickness	Mounting Hole Diam.	Bolt Circle Diam.	Dynamic Load**
	A	B	C	D	E	F	G	
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)
	1/4 (6)	.50 (12.7)	1.0 (25.4)	1.00 (25.4)	.17 (4.3)	.143 (3.63)	.750 (19.05)	50 (20)
	5/16 (8)	.50 (12.7)	1.9 (48.3)	1.50 (38.1)	.17 (4.3)	.197 (5.00)	1.125 (28.58)	75 (35)
	3/8 (10)	.66 (16.6)	1.9 (48.3)	1.50 (38.1)	.17 (4.3)	.197 (5.00)	1.125 (28.58)	75 (35)
	7/16 (11)	.75 (19.1)	1.9 (48.3)	1.50 (38.1)	.17 (4.3)	.197 (5.00)	1.125 (28.58)	90 (40)
	1/2 (13)	.75 (19.1)	1.9 (48.3)	1.50 (38.1)	.17 (4.3)	.197 (5.00)	1.125 (28.58)	150 (68)

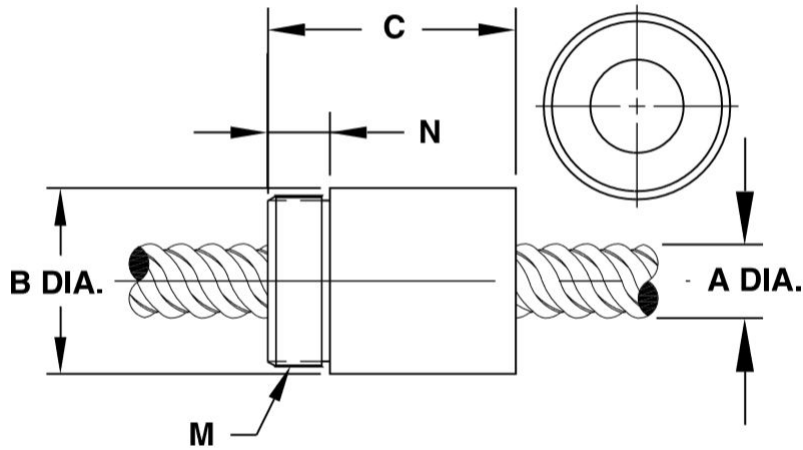
Metric numbers are for reference only.



BFW Thread Mount

BFWT Thread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load**
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)	lbs (Kg)
	1/4 (6)	.63 (15.9)	1.0 (25.4)	9/16 - 18	.187 (4.75)	50 (20)
	5/16 (8)	.75 (19.1)	1.0 (25.4)	5/8 - 18	.250 (6.35)	75 (35)
	3/8 (10)	.75 (19.1)	1.0 (25.4)	5/8 - 18	.250 (6.35)	75 (35)
	7/16 (11)	1.00 (25.4)	1.5 (38.1)	15/16 - 16	.375 (9.53)	90 (40)
	1/2 (13)	1.00 (25.4)	1.5 (38.1)	15/16 - 16	.375 (9.53)	150 (68)
	5/8 (16)	1.00 (25.4)	1.5 (38.1)	15/16 - 16	.375 (9.53)	225 (100)
	3/4 (19)	1.50 (38.1)	2.0 (51)	1 3/8 - 16	.500 (12.70)	350 (160)
	7/8 (22)	1.50 (38.1)	2.0 (51)	1 3/8 - 16	.500 (12.70)	500 (227)
	15/16 (24)	1.50 (38.1)	2.0 (51)	1 3/8 - 16	.500 (12.70)	500 (227)

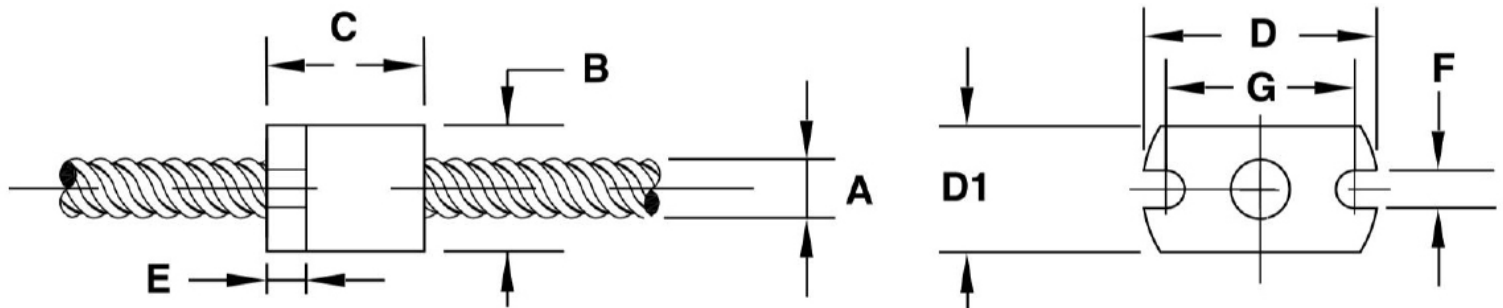
Metric numbers are for reference only.



BFW Mini Rectangular Flange Mount

BFWR Rectangular Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Height D1	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	0.40 (10.2)	0.75 (19.1)	0.13 (3.2)	0.120 (3.05)	0.600 (15.24)	25 (11)	Free Wheeling

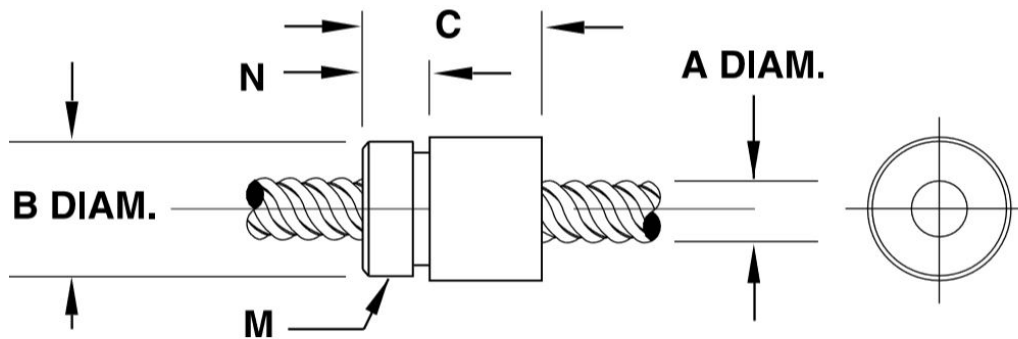
Metric numbers are for reference only.



BFW Mini Thread Mount

BFWT Thread Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Thread M*	Thread Length N	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch	inch (mm)	lbs (Kg)	oz-in (N-m)
	1/8 inch through 7/32 inch (3 mm through 5.6 mm)	0.40 (10.2)	0.50 (13)	3/8-24	0.187 (4.75)	25 (11)	Free Wheeling

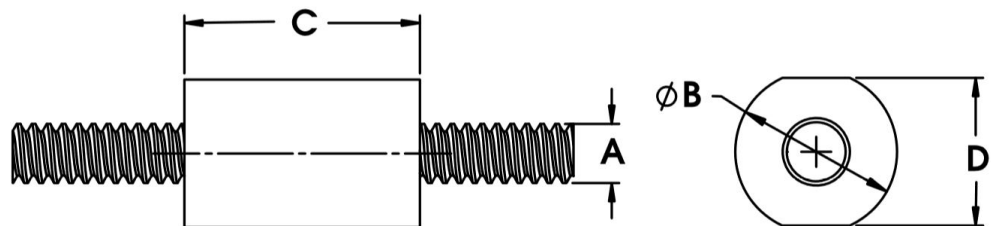
Metric numbers are for reference only.



BFW Micro Barrel Mount

BFWB Barrel Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Nut Flats D	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	5/64 (2)	0.22 (5.5)	0.32 (8)	0.20 (5.08)	10 (4.5)	Free Wheeling

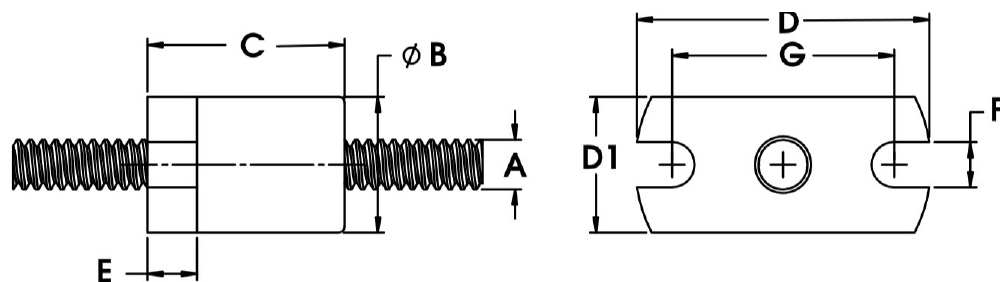
Metric numbers are for reference only.



BFW Micro Rectangular Flange Mount

BFWR Rectangular Flange Mount	Screw Diam. A	Nut Diam. B	Nut Length C	Flange Height D1	Flange Diam. D	Flange Thickness E	Mounting Hole Diam. F	Bolt Circle Diam. G	Dynamic Load	Drag Torque
	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	inch (mm)	lbs (Kg)	oz-in (N-m)
	5/64 (2)	0.22 (5.5)	0.32 (8)	0.22 (5.5)	0.47 (11.9)	0.08 (2.0)	0.07 (1.8)	0.35 (9.0)	10 (4.5)	Free Wheeling

Metric numbers are for reference only.



Lead Screw Compatibility: BFW Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
5/64	2	008	0.012	0.30	0012		0.079	2.01	0.068	1.73	24**
			0.016	0.40	0016		0.075	1.91	0.058	1.47	30**
			0.020	0.50	0020		0.077	1.96	0.057	1.45	36**
			0.039	1.00	0039		0.079	2.01	0.059	1.50	52**
			0.079	2.00	0079		0.077	1.96	0.057	1.45	66**
1/8	3.2	012	0.024	0.61	0024		0.129	3.28	0.093	2.36	44
			0.039	1.00	0039		0.129	3.28	0.094	2.39	57
			0.048	1.22	0048		0.129	3.28	0.093	2.36	61
			0.075	1.91	0075		0.129	3.28	0.093	2.36	70
			0.096	2.44	0096	•	0.129	3.28	0.093	2.36	75
			0.125	3.18	0125	LH Only	0.125	3.18	0.078	1.98	80
.132	3.3	013	0.020	0.50	0020		0.132	3.35	0.104	2.64	42
			0.039	1.00	0039		0.132	3.35	0.080	2.03	61
			0.079	2.00	0079		0.132	3.35	0.080	2.03	75
			0.157	4.00	0157		0.132	3.35	0.080	2.03	84
			0.315	8.00	0315		0.132	3.35	0.080	2.03	87
9/64	3.6	014	0.012	0.30	0012		0.140	3.56	0.123	3.12	26
			0.024	0.61	0024		0.140	3.56	0.105	2.67	43
			0.048	1.22	0048		0.140	3.56	0.081	2.06	62
			0.096	2.44	0096		0.140	3.56	0.081	2.06	75
			0.394	10.00	0394		0.140	3.56	0.102	2.59	86
5/32	4	016	0.033	0.84	0033	•	0.156	3.96	0.116	2.95	45
			0.050	1.27	0050	LH Only	0.156	3.96	0.096	2.44	59
			0.094	2.39	0094		0.164	4.17	0.128	3.25	67
			0.125	3.18	0125		0.168	4.27	0.130	3.30	74
			0.250	6.35	0250		0.156	3.96	0.130	3.30	83
			0.375	9.53	0375		0.156	3.96	0.130	3.30	85
			0.500	12.70	0500		0.156	3.96	0.130	3.30	86
3/16	5	018	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
			0.500	12.70	0500	•	0.188	4.78	0.142	3.61	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: BFW Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
7/32	5.6	021	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096		0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250	•	0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86
1/4	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Lead Screw Compatibility: BFW Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			
7/16	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
0.615	15.62	0615		0.475	12.07	0.376	9.55	82			

Lead Screw Compatibility: BFW Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
0.984	25.00	0984		0.500	12.70	0.369	9.37	84			
1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84			
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86			

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

Lead Screw Compatibility: BFW Series

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/4	19	075	0.0625	1.59	0063		0.750	19.05	0.671	17.04	25
			0.098	2.50	0098		0.742	18.85	0.626	15.90	35
			0.100	2.54	0100	•	0.746	18.95	0.624	15.85	35
			0.1667	4.23	0167		0.727	18.47	0.645	16.38	47
			0.197	5.00	0197		0.745	18.92	0.624	15.85	51
			0.200	5.08	0200		0.741	18.82	0.632	16.05	52
			0.250	6.35	0250		0.731	18.57	0.639	16.23	57
			0.276	7.00	0276		0.750	19.05	0.624	15.85	59
			0.333	8.46	0333		0.750	19.05	0.624	15.85	64
			0.394	10.00	0394		0.745	18.92	0.619	15.72	67
			0.500	12.70	0500		0.744	18.90	0.624	15.85	73
			0.551	14.00	0551		0.750	19.05	0.624	15.85	73
			0.591	15.00	0591		0.749	19.02	0.623	15.82	74
			0.709	18.00	0709		0.780	19.81	0.650	16.51	77
			0.748	19.00	0748		0.672	17.07	0.547	13.89	80
			0.787	20.00	0787		0.780	19.81	0.648	16.46	78
			0.800	20.32	0800		0.750	19.05	0.618	15.70	79
			0.945	24.00	0945	•	0.734	18.64	0.633	16.08	80
			1.000	25.40	1000	•	0.743	18.87	0.619	15.72	81
			1.500	38.10	1500		0.712	18.08	0.590	14.99	84
1.969	50.00	1969	•	0.751	19.08	0.620	15.75	84			
2.000	50.80	2000	•	0.742	18.85	0.611	15.52	84			
2.400	60.96	2400	•	0.750	19.05	0.620	15.75	84			
3.622	92.00	3622	•	0.750	19.05	0.634	16.10	87			
7/8	22	087	0.200	5.08	0200	•	0.870	22.10	0.742	18.85	48
			0.236	6.00	0236		0.848	21.54	0.773	19.63	52
			0.250	6.35	0250		0.875	22.23	0.749	19.02	53
			0.394	10.00	0394		0.875	22.23	0.741	18.82	65
			0.500	12.70	0500		0.862	21.89	0.744	18.90	69
			0.630	16.00	0630		0.875	22.23	0.741	18.82	73
			0.667	16.94	0667		0.871	22.12	0.745	18.92	74
			0.787	20.00	0787		0.875	22.23	0.741	18.82	78
			0.945	24.00	0945		0.875	22.23	0.741	18.82	79
1.000	25.40	1000		0.871	22.12	0.742	18.85	80			
15/16	24	093	0.050	1.27	0050	LH Only	0.938	23.83	0.874	22.20	17
			2.000	50.80	2000		0.927	23.55	0.815	20.70	85
			3.000	76.20	3000	•	0.939	23.85	0.803	20.40	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 *** Back-drive threshold is 50±10%

Lead Screws

Kerk Lead Screws utilize the latest in precision rolling technology. Lead screws are available in standard diameters from 5/64" to 15/16" and includes metric and left hand threads. Most standard lead screws are manufactured from 303 stainless steel and are produced using our exclusive precision rolling process. Other lead screw materials are available for application specific requirements.

Kerk® Lead Screws

Manufactured from 303 stainless steel and produced with Kerk's exclusive precision rolling process. Available in standard diameters from 1/8-in (3.2mm) to 15/16-in (23mm), with standard leads from .012-in to almost 4-in (0.30mm to 92mm) including metric and left hand threads. Custom sizes and leads can be special ordered. Positional bi-directional repeatability (with Kerk anti-backlash nut) is within 50 micro-inches (1.25 micron) and standard lead accuracy is better than 0.0006-in./in. (mm/mm). Lead accuracies are available to .0001-in./in. (mm/mm). The surface finish is better than 16 micro-inches (0.4 µm). Please consult factory for more details. Kerk stainless steel lead screws and guide rails are corrosion resistant, non-magnetic, and compatible with many demanding processes.



Identifying the Lead Screw Part Number Codes when Ordering

LSS	S	K	R	025	0024	EY10
Prefix	Nut Mounting Style	Lubrication	Thread Direction	Diameter Code	Nominal Thread Lead Code	Unique Identifier
LSS = Screw Only	S = Screw Only X = Custom	S = Uncoated K = Kerkote® TFE Coating G = Grease N = Nut only B = Black Ice® TFE Coating	R = Right hand L = Left hand (Refer to lead screw charts for availability)	008 ^m = .078-in (2) 012 ^m = .125-in (3.2) 013 ^m = .133-in (3.3) 014 ^m = .141-in (3.6) 016 ^m = .156-in (4) 018 ^m = .188-in (5) 021 ^m = .219-in (5.6) 025 = .250-in (6) 031 = .313-in (8) 037 = .375-in (10) 043 = .438-in (11) 050 = .500-in (13) 062 = .625-in (16) 075 = .750-in (19) 087 = .875-in (22) 093 = .938-in (24) ^m BFW Mini Series ^m BFW Micro Series	(Refer to LEAD CODE Specifications charts, pages 2 to 6)	FY06 = 6" CTL Kerk threadform EY10 = 10" C-T-L Haydon threadform

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Material & Teflon TFE Coating Options

Materials		Teflon TFE Coatings	
Kerkite® Composite Polymer Nuts	In addition to the Kerk® self-lubricating acetal nut material, we offer a variety of custom compounded Kerkite composite polymers. Kerkite polymers are a family of high performance materials that offer exceptional wear properties with the cost and design advantages afforded through injection molding. Kerkite polymers offer a variety of mechanical, thermal and electrical properties and are compatible with many chemicals and environmental conditions. Each member of the Kerkite family is compounded with lubricants, reinforcements and thermoplastic polymers formulated to provide optimum performance in its target conditions and applications.	Kerkote® TFE Coating	Soft coating that is a long-term, maintenance-free, dry lubricant, optimized for softer plastics like acetals and nylons, with or without mechanical reinforcement. Lubrication to the nut/screw interface occurs by the nut picking up Kerkote® TFE particles from the coating as well as from the migration of the internal lubricant within the plastic nut. The transfer of TFE to the nut continues throughout the operating life of the assembly as long as the nut periodically travels over areas with Kerkote® TFE coating. The lubricant, although solid, also has some "spreading" ability as in fluid lubricants. Kerkote® TFE coated screws provide the maximum level of self-lubrication and should not be additionally lubricated or used in environments where oils or other lubricant contamination is possible.
Special Materials	Kerk® has rolled screws in many materials, including 316 stainless, 400 series stainless, precipitate hardening materials, carbon steel, aluminum, and titanium. Kerk® nuts have been produced in many alternative plastics including PEEK, polyester, Torlon®, Vespel®, PVDF, UHMW, Ertalyte®, customer-supplied specialty materials, and metal nuts made from bronze, brass, and stainless steel. If the material can be molded, machined, ground, or rolled, we can likely process it.	Black Ice® TFE Coating	Hard coating that is long term, maintenance-free and is exceptionally durable in all types of environments, with virtually any type of polymer nut. Black Ice® TFE coating remains on the screw, offering a low friction surface upon which the nut travels. Rather than acting as a dry lubricant, Black Ice® TFE is an anti-friction coating whose surface properties displace the metal to which it is applied. Though it is not intended for use with metal or glass fiber reinforced nuts, Black Ice® TFE is bonded securely to the screw's surface and can withstand abrasion from contamination, rigid polymer systems, fluid impingement and wash down applications. Black Ice® TFE can be used in more aggressive environment conditions, or anywhere reduced friction and a permanent coating is desired. Not intended to be used with additional lubricants.

Note: There are certain applications where external lubrication may be desired. These include the use of nut materials such as glass reinforced plastic or metal. Greases, when used properly can provide unique capabilities and Haydon Kerk Motion Solutions does offer a selection of greases developed specifically for these applications. Please contact a sales engineer for assistance selecting the best lubricant for your requirements.

■ Diameter and Lead Codes

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
5/64 (.078) Micro Series	2	008 ^u	0.012	0.30	0012		0.079	2.01	0.068	1.73	24**
			0.016	0.40	0016		0.075	1.91	0.058	1.47	30**
			0.020	0.50	0020		0.077	1.96	0.057	1.45	36**
			0.039	1.00	0039		0.079	2.01	0.059	1.50	52**
			0.079	2.00	0079		0.077	1.96	0.057	1.45	66**
1/8 (.125)	3.2	012 ^m	0.024	0.61	0024		0.129	3.28	0.093	2.36	44
			0.039	1.00	0039		0.129	3.28	0.094	2.39	57
			0.048	1.22	0048		0.129	3.28	0.093	2.36	61
			0.075	1.91	0075		0.129	3.28	0.093	2.36	70
			0.096	2.44	0096	•	0.129	3.28	0.093	2.36	75
			0.125	3.18	0125	LH Only	0.125	3.18	0.078	1.98	80
17/128 (.132)	3.3	013 ^m	0.020	0.50	0020		0.132	3.35	0.104	2.64	42
			0.039	1.00	0039		0.132	3.35	0.080	2.03	61
			0.079	2.00	0079		0.132	3.35	0.080	2.03	75
			0.157	4.00	0157		0.132	3.35	0.080	2.03	84
			0.315	8.00	0315		0.132	3.35	0.080	2.03	87
9/64 (.141)	3.6	014 ^m	0.012	0.30	0012		0.140	3.56	0.123	3.12	26
			0.024	0.61	0024		0.140	3.56	0.105	2.67	43
			0.048	1.22	0048		0.140	3.56	0.081	2.06	62
			0.096	2.44	0096		0.140	3.56	0.081	2.06	75
			0.394	10.00	0394		0.140	3.56	0.102	2.59	86
5/32 (.156)	4	016 ^m	0.033	0.84	0033	•	0.156	3.96	0.116	2.95	45
			0.050	1.27	0050	LH Only	0.156	3.96	0.096	2.44	59
			0.094	2.39	0094		0.164	4.17	0.128	3.25	67
			0.125	3.18	0125		0.168	4.27	0.130	3.30	74
			0.250	6.35	0250		0.156	3.96	0.130	3.30	83
			0.375	9.53	0375		0.156	3.96	0.130	3.30	85
			0.500	12.70	0500		0.156	3.96	0.130	3.30	86
3/16 (.188)	5	018 ^m	0.020	0.50	0020		0.188	4.78	0.163	4.14	30
			0.025	0.64	0025		0.188	4.78	0.150	3.81	39
			0.039	1.00	0039		0.188	4.78	0.144	3.66	47
			0.050	1.27	0050		0.188	4.78	0.124	3.15	58
			0.100	2.54	0100		0.188	4.78	0.136	3.45	69
			0.1875	4.76	0188		0.188	4.78	0.167	4.24	78
			0.200	5.08	0200		0.188	4.78	0.124	3.15	82
			0.375	9.53	0375		0.188	4.78	0.161	4.09	84
			0.400	10.16	0400		0.188	4.78	0.124	3.15	84
			0.427	10.85	0427		0.188	4.78	0.162	4.11	85
			0.500	12.70	0500	•	0.188	4.78	0.142	3.61	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

■ Diameter and Lead Codes

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
7/32 (.219)	5.6	021 ^m	0.024	0.61	0024		0.218	5.54	0.181	4.60	31
			0.03125	0.79	0031		0.204	5.18	0.160	4.06	39
			0.048	1.22	0048		0.216	5.49	0.156	3.96	50
			0.050	1.27	0050		0.200	5.08	0.135	3.43	52
			0.0625	1.59	0063		0.218	5.54	0.142	3.61	60
			0.096	2.44	0096		0.218	5.54	0.156	3.96	66
			0.192	4.88	0192		0.218	5.54	0.156	3.96	78
			0.250	6.35	0250	•	0.204	5.18	0.140	3.56	81
			0.384	9.75	0384		0.218	5.54	0.159	4.04	86
1/4 (.250)	6	025	0.024	0.61	0024		0.250	6.35	0.218	5.54	28
			0.025	0.64	0025		0.250	6.35	0.214	5.44	30
			0.03125	0.79	0031		0.250	6.35	0.208	5.28	34
			0.039	1.00	0039		0.250	6.35	0.190	4.83	40
			0.048	1.22	0048		0.250	6.35	0.190	4.83	45
			0.050	1.27	0050	•	0.250	6.35	0.191	4.85	46
			0.059	1.50	0059		0.250	6.35	0.172	4.37	52
			0.0625	1.59	0063		0.250	6.35	0.170	4.32	52
			0.079	2.00	0079		0.250	6.35	0.170	4.32	59
			0.096	2.44	0096		0.250	6.35	0.190	4.83	61
			0.100	2.54	0100		0.250	6.35	0.190	4.83	62
			0.118	3.00	0118		0.250	6.35	0.175	4.45	68
			0.125	3.18	0125		0.250	6.35	0.190	4.83	67
			0.197	5.00	0197		0.250	6.35	0.172	4.37	72
			0.200	5.08	0200		0.250	6.35	0.170	4.32	65
			0.250	6.35	0250	•	0.250	6.35	0.168	4.27	79
			0.3125	7.94	0313		0.250	6.35	0.184	4.67	81
			0.333	8.46	0333		0.250	6.35	0.170	4.32	82
			0.394	10.00	0394		0.250	6.35	0.170	4.32	78
			0.400	10.16	0400		0.250	6.35	0.170	4.32	84
0.500	12.70	0500	•	0.250	6.35	0.169	4.29	85			
0.750	19.05	0750		0.250	6.35	0.170	4.32	86			
1.000	25.40	1000	•	0.250	6.35	0.170	4.32	84			
5/16 (.313)	8	031	0.039	1.00	0039		0.315	8.00	0.261	6.63	34
			0.057	1.44	0057		0.315	8.00	0.243	6.17	43
			0.0741	1.88	0074		0.312	7.92	0.211	5.36	51
			0.111	2.82	0111		0.312	7.92	0.232	5.89	60
			0.167	4.24	0167		0.312	7.92	0.211	5.36	69
			0.250	6.35	0250		0.312	7.92	0.234	5.94	76
			0.500	12.70	0500		0.312	7.92	0.232	5.89	83
			0.800	20.32	0800		0.306	7.77	0.243	6.17	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

Diameter and Lead Codes

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/8 (.375)	10	037	0.025	0.64	0025		0.375	9.53	0.337	8.56	21
			0.039	1.00	0039		0.394	10.01	0.350	8.89	28
			0.04167	1.06	0042		0.375	9.53	0.320	8.13	34
			0.050	1.27	0050	•	0.375	9.53	0.301	7.65	36
			0.055	1.40	0055		0.375	9.53	0.303	7.70	38
			0.059	1.50	0059	•	0.389	9.88	0.313	7.95	38
			0.0625	1.59	0063	•	0.388	9.86	0.295	7.49	41
			0.068	1.73	0068		0.388	9.86	0.295	7.49	42
			0.079	2.00	0079		0.375	9.53	0.264	6.71	47
			0.0833	2.12	0083		0.375	9.53	0.293	7.44	48
			0.100	2.54	0100	•	0.375	9.53	0.266	6.76	53
			0.125	3.18	0125	•	0.375	9.53	0.295	7.49	59
			0.157	4.00	0157		0.375	9.53	0.274	6.96	65
			0.1667	4.23	0167		0.371	9.42	0.261	6.63	61
			0.197	5.00	0197		0.375	9.53	0.266	6.76	69
			0.200	5.08	0200	•	0.375	9.53	0.266	6.76	69
			0.250	6.35	0250		0.375	9.53	0.268	6.81	70
			0.300	7.62	0300		0.375	9.53	0.255	6.48	76
			0.333	8.46	0333		0.375	9.53	0.245	6.22	78
			0.363	9.22	0363	•	0.375	9.53	0.260	6.60	79
			0.375	9.53	0375		0.375	9.53	0.265	6.73	79
			0.394	10.00	0394		0.375	9.53	0.260	6.60	79
			0.400	10.16	0400		0.375	9.53	0.293	7.44	79
			0.472	12.00	0472		0.388	9.86	0.287	7.29	82
			0.500	12.70	0500	•	0.388	9.86	0.265	6.73	81
			0.667	16.94	0667		0.375	9.53	0.273	6.93	83
			0.667	19.05	0750		0.388	9.86	0.273	6.93	84
			0.984	25.00	0984		0.375	9.53	0.262	6.65	84
1.000	25.40	1000		0.383	9.73	0.254	6.45	84			
1.200	30.48	1200	•	0.383	9.73	0.254	6.45	84			
1.250	31.75	1250		0.375	9.53	0.278	7.06	84			
1.500	38.10	1500		0.375	9.53	0.264	6.71	83			
7/16 (.438)	11	043	0.050	1.27	0050		0.437	11.10	0.362	9.19	30
			0.0625	1.59	0063	•	0.436	11.07	0.358	9.09	38
			0.079	2.00	0079		0.472	11.99	0.374	9.50	42
			0.111	2.82	0111		0.437	11.10	0.327	8.31	52
			0.118	3.00	0118		0.438	11.13	0.363	9.22	52
			0.125	3.18	0125		0.438	11.13	0.357	9.07	54
			0.197	5.00	0197		0.438	11.13	0.315	8.00	65
			0.236	6.00	0236		0.433	11.00	0.313	7.95	70
			0.250	6.35	0250		0.442	11.23	0.325	8.26	70
			0.307	7.80	0307		0.445	11.30	0.343	8.71	73
			0.325	8.26	0325		0.444	11.28	0.342	8.69	74
			0.394	10.00	0394		0.446	11.33	0.331	8.41	78
			0.472	12.00	0472		0.438	11.13	0.318	8.08	80
			0.500	12.70	0500		0.452	11.48	0.327	8.31	80
			0.615	15.62	0615		0.475	12.07	0.376	9.55	82

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

■ Diameter and Lead Codes

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
1/2 (.500)	13	050	0.050	1.27	0050		0.495	12.57	0.433	11.00	29
			0.079	2.00	0079		0.473	12.01	0.355	9.02	41
			0.098	2.50	0098		0.500	12.70	0.383	9.73	46
			0.100	2.54	0100	•	0.490	12.45	0.364	9.25	46
			0.125	3.18	0125		0.500	12.70	0.374	9.50	51
			0.157	4.00	0157		0.500	12.70	0.384	9.75	58
			0.160	4.06	0160		0.500	12.70	0.388	9.86	67
			0.1667	4.23	0167		0.500	12.70	0.384	9.75	58
			0.197	5.00	0197		0.500	12.70	0.365	9.27	62
			0.200	5.08	0200	•	0.492	12.50	0.366	9.30	63
			0.250	6.35	0250		0.500	12.70	0.382	9.70	67
			0.333	8.46	0333	•	0.497	12.62	0.362	9.19	73
			0.394	10.00	0394		0.497	12.62	0.362	9.19	76
			0.400	10.16	0400		0.497	12.62	0.364	9.25	76
			0.500	12.70	0500		0.488	12.40	0.352	8.94	79
			0.630	16.00	0630		0.500	12.70	0.374	9.50	80
			0.750	19.05	0750		0.525	13.34	0.399	10.13	83
			0.800	20.32	0800		0.500	12.70	0.370	9.40	83
			0.984	25.00	0984		0.500	12.70	0.369	9.37	84
			1.000	25.40	1000	•	0.490	12.45	0.372	9.45	84
1.500	38.10	1500		0.490	12.45	0.374	9.50	85			
2.000	50.80	2000		0.488	12.40	0.378	9.60	87			
5/8 (.625)	16	062	0.100	2.54	0100		0.615	15.62	0.498	12.65	40
			0.125	3.18	0125	•	0.625	15.88	0.470	11.94	45
			0.200	5.08	0200		0.625	15.88	0.495	12.57	53
			0.250	6.35	0250		0.625	15.88	0.469	11.91	63
			0.315	8.00	0315		0.627	15.93	0.493	12.52	68
			0.410	10.41	0410	•	0.625	15.88	0.481	12.22	72
			0.500	12.70	0500	•	0.625	15.88	0.478	12.14	76
			0.630	16.00	0630		0.625	15.88	0.491	12.47	78
			1.000	25.40	1000		0.625	15.88	0.481	12.22	83
			1.500	38.10	1500		0.625	15.88	0.499	12.67	85
			1.575	40.00	1575	•	0.625	15.88	0.499	12.67	86
			2.000	50.80	2000	•	0.625	15.88	0.499	12.67	86

Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw

** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws

***Back-drive threshold is 50±10%

■ Diameter and Lead Codes

Diameter		Diameter Code	Lead		LEAD CODE	Left Hand Available	Outside Diameter (for reference)		Root Diameter (for reference)		Efficiency %*
inches	mm		inches	mm			inches	mm	inches	mm	
3/4 (.750)	19	075	0.0625	1.59	0063		0.750	19.05	0.671	17.04	25
			0.098	2.50	0098		0.742	18.85	0.626	15.90	35
			0.100	2.54	0100	•	0.746	18.95	0.624	15.85	35
			0.1667	4.23	0167		0.727	18.47	0.645	16.38	47
			0.197	5.00	0197		0.745	18.92	0.624	15.85	51
			0.200	5.08	0200		0.741	18.82	0.632	16.05	52
			0.250	6.35	0250		0.731	18.57	0.639	16.23	57
			0.276	7.00	0276		0.750	19.05	0.624	15.85	59
			0.333	8.46	0333		0.750	19.05	0.624	15.85	64
			0.394	10.00	0394		0.745	18.92	0.619	15.72	67
			0.500	12.70	0500		0.744	18.90	0.624	15.85	73
			0.551	14.00	0551		0.750	19.05	0.624	15.85	73
			0.591	15.00	0591		0.749	19.02	0.623	15.82	74
			0.709	18.00	0709		0.780	19.81	0.650	16.51	77
			0.748	19.00	0748		0.672	17.07	0.547	13.89	80
			0.787	20.00	0787		0.780	19.81	0.648	16.46	78
			0.800	20.32	0800		0.750	19.05	0.618	15.70	79
			0.945	24.00	0945	•	0.734	18.64	0.633	16.08	80
			1.000	25.40	1000	•	0.743	18.87	0.619	15.72	81
			1.500	38.10	1500		0.712	18.08	0.590	14.99	84
1.969	50.00	1969	•	0.751	19.08	0.620	15.75	84			
2.000	50.80	2000	•	0.742	18.85	0.611	15.52	84			
2.400	60.96	2400	•	0.750	19.05	0.620	15.75	84			
3.622	92.00	3622	•	0.750	19.05	0.634	16.10	87			
7/8 (.875)	22	087	0.200	5.08	0200	•	0.870	22.10	0.742	18.85	48
			0.236	6.00	0236		0.848	21.54	0.773	19.63	52
			0.250	6.35	0250		0.875	22.23	0.749	19.02	53
			0.394	10.00	0394		0.875	22.23	0.741	18.82	65
			0.500	12.70	0500		0.862	21.89	0.744	18.90	69
			0.630	16.00	0630		0.875	22.23	0.741	18.82	73
			0.667	16.94	0667		0.871	22.12	0.745	18.92	74
			0.787	20.00	0787		0.875	22.23	0.741	18.82	78
			0.945	24.00	0945		0.875	22.23	0.741	18.82	79
			1.000	25.40	1000		0.871	22.12	0.742	18.85	80
5/16 (.938)	24	093	0.050	1.27	0050	LH Only	0.938	23.83	0.874	22.20	17
			2.000	50.80	2000		0.927	23.55	0.815	20.70	85
			3.000	76.20	3000	•	0.939	23.85	0.803	20.40	86

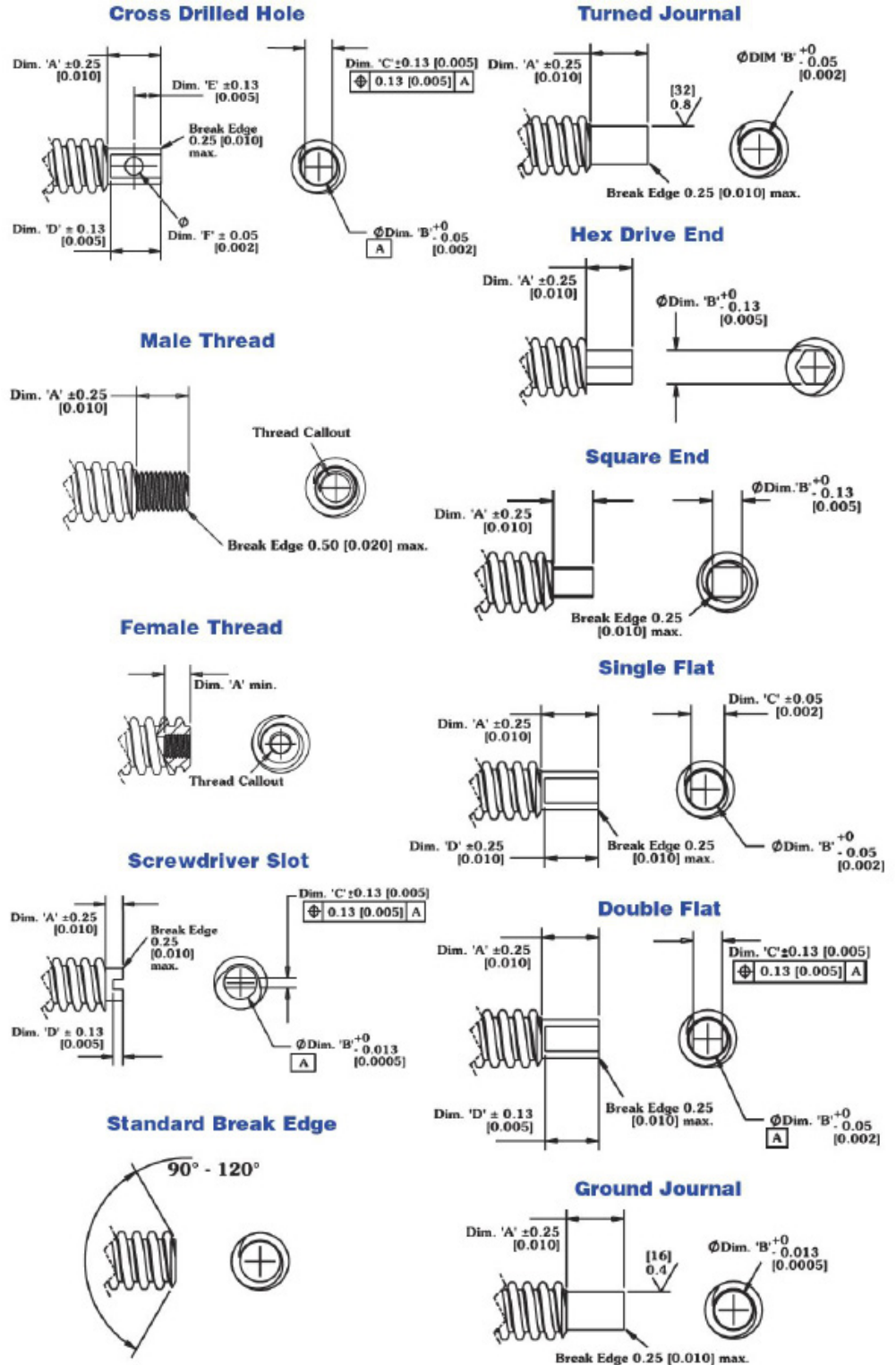
Shaded areas have been translated from their designed inch or mm dimension to an equivalent mm or inch dimension.

* Listed efficiencies are theoretical values based on Kerkote® TFE coated lead screw
 ** Listed efficiencies for Micro screws are theoretical values based on non-coated lead screws
 ***Back-drive threshold is 50±10%

■ Screw Inertia

Screw Size	Screw Inertia	
	[oz-inch-sec ² /inch]	[g-cm ² /cm]
5/64 (2)	3.4×10^{-8}	9.5×10^{-4}
1/8 (3.2)	1.8×10^{-7}	5.0×10^{-3}
9/64 (3.5)	3.4×10^{-7}	9.5×10^{-3}
5/32 (3.97)	4.9×10^{-7}	1.4×10^{-2}
3/16 (4.76)	1.1×10^{-6}	3.1×10^{-2}
7/32 (5.55)	1.8×10^{-6}	5.0×10^{-2}
1/4 (6)	3×10^{-5}	8.3×10^{-2}
5/16 (8)	5×10^{-5}	1.4
3/8 (10)	1.5×10^{-5}	0.4
7/16 (11)	3.5×10^{-5}	1.0
1/2 (13)	5.2×10^{-5}	1.4
5/8 (16)	14.2×10^{-5}	3.9
3/4 (19)	30.5×10^{-5}	8.5
7/8 (22)	58.0×10^{-5}	16.1
15/16 (24)	73.0×10^{-5}	20.3

■ Standard End Machining mm[inches]



AMETEK Haydon Kerk **Lead Screw and Nut Customization**

Haydon Kerk takes great pride in designing and developing customized solutions for your application needs.

Our Design and Development Engineers begin with our standard catalog products and build ideal solutions for your motion needs. Our factories bring your solutions into production.



Stepper Motor Linear Actuators

Our various patented designs use a proprietary manufacturing process which incorporates engineered thermoplastics in the rotor drive nut and a stainless steel lead screw. This design allows the linear actuator to be much quieter, more efficient and more durable than a v-thread and bronze nut configuration commonly used in other linear actuators.



Terminology

Detent or Residual Torque	The torque required to rotate the motor's output shaft with no current applied to the windings.
Drives	A term depicting the external electrical components to run a Stepper Motor System. This will include power supplies, logic sequencers, switching components and usually a variable frequency pulse source to determine the step rate.
Dynamic Torque	The torque generated by the motor at a given step rate. Dynamic torque can be represented by PULL IN torque or PULL OUT torque.
Holding Torque	The torque required to rotate the motor's output shaft while the windings are energized with a steady state D.C. current.
Inertia	The measure of a body's resistance to acceleration or deceleration. Typically used in reference to the inertia of the load to be moved by a motor or the inertia of a motor's rotor.
Linear Step Increment	The linear travel movement generated by the lead screw with each single step of the rotor.
Maximum Temperature Rise	Allowable increase in motor temperature by design. Motor temperature rise is caused by the internal power dissipation of the motor as a function of load. This power dissipation is the sum total from I ² R (copper loss), iron (core) loss, and friction. The final motor temperature is the sum of the temperature rise and ambient temperature.
Pulse Rate	The number of pulses per second (pps) applied to the windings of the motor. The pulse rate is equivalent to the motor step rate.
Pulses Per Second (PPS)	The number of steps that the motor takes in one second (sometimes called "steps per second"). This is determined by the frequency of pulses produced by the motor drive.
Ramping	A drive technique to accelerate a given load from a low step rate, to a given maximum step rate and then to decelerate to the initial step rate without the loss of steps.
Single Step Response	The time required for the motor to make one complete step.
Step	The angular rotation produced by the rotor each time the motor receives a pulse. For linear actuators a step translates to a specific linear distance.
Step Angle	The rotation of the rotor caused by each step, measured in degrees.
Steps Per Revolution	The total number of steps required for the rotor to rotate 360°.
Torque	<p>The sum of the frictional load torque and inertial torque.</p> <ul style="list-style-type: none"> • Pull out torque: The maximum torque the motor can deliver once the motor is running at constant speed. Since there is no change in speed there is no inertial torque. Also, the kinetic energy stored in the rotor and load inertia help to increase the pull out torque. • Pull in torque: The torque required to accelerate the rotor inertia and any rigidly attached external load up to speed plus whatever friction torque must be overcome. Pull in torque, therefore, is always less than pull out torque.
Torque to Inertia Ratio	Holding torque divided by rotor inertia.

Hybrid Linear Actuators

Haydon Kerk Motion Solutions offers a unique line of hybrid stepper motor linear actuators that open new avenues for equipment designers who require high performance and exceptional endurance in a very small package. The various patented and patent pending designs use a proprietary manufacturing process, which incorporates engineering thermoplastics in the rotor drive nut and a stainless steel acme lead screw. This allows the linear actuator to be much quieter, more efficient and more durable than the v-thread and bronze nut configuration commonly used in other linear actuators.

21000 Series Size 8 Hybrid Linear Actuators

Size 8 Hybrid Precision Stepper Motor is part of our extensive, award winning miniature motor product line and is one of the world's smallest linear actuators.

More Compact Option for Motion Applications

The 21000 Series Size 8 Linear Actuator occupies a minimal 0.8" (21 mm) space and includes numerous patented innovations that provide customers high performance and endurance in a very small package.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 21000 Series is available in a wide variety of resolutions - from 0.00006" (.0015mm) per step to 0.00157" (0.0 mm) per step.

The Size 8 Actuator delivers thrust of up to 10 lbs (44 N).



Size 8
Captive Shaft

Size 8
Non-Captive Shaft

Size 8
External Linear

Specifications

Size 8: 21 mm (0.8-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	21H4 †	
	Non-Captive	21F4 †	
	External Linear	E21H4 †	
Wiring	Bipolar		
Winding Voltage	2.5 VDC	5 VDC	7.5 VDC
Current (RMS)/phase	.49 A	.24 A	.16 A
Resistance/phase	5.1 Ω	20.4 Ω	45.9 Ω
Inductance/phase	1.5 mH	5.0 mH	11.7 mH
Power Consumption	2.45 W Total		
Rotor Inertia	1.4 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	1.5 oz (43 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 79.

Linear Travel / Step		Order Code I.D.
Screw Ø.14-in (3.56mm)		
inches	mm	
.00006	.0015*	U**
.000098*	.0025	AA**
.00012	.0030*	N
.00019*	.005	AB
.00024	.006*	K
.00039*	.01	AC
.00048	.0121*	J
.00078*	.02	AD
.00157	.04	AE

*Values truncated

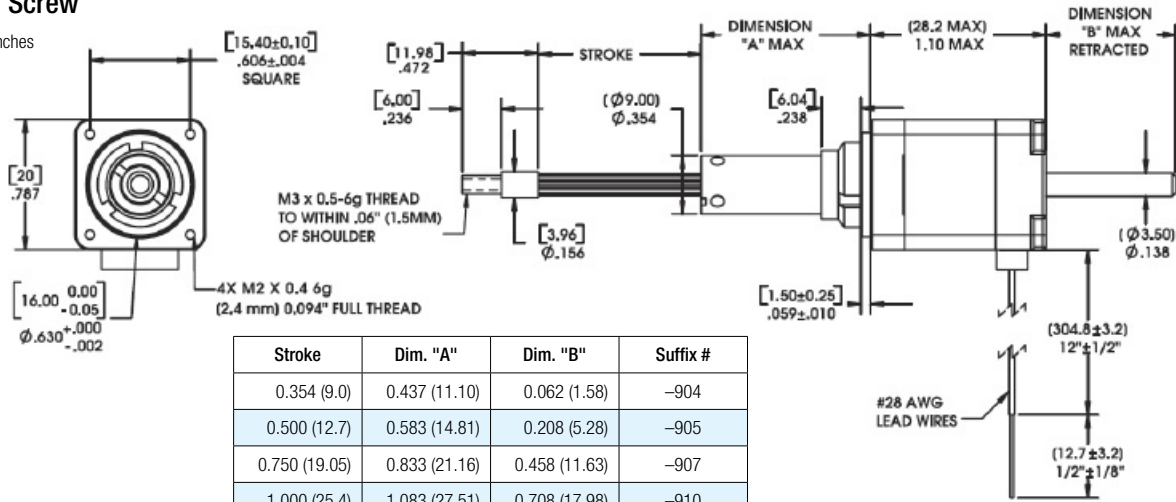
**TFE coating not available

Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

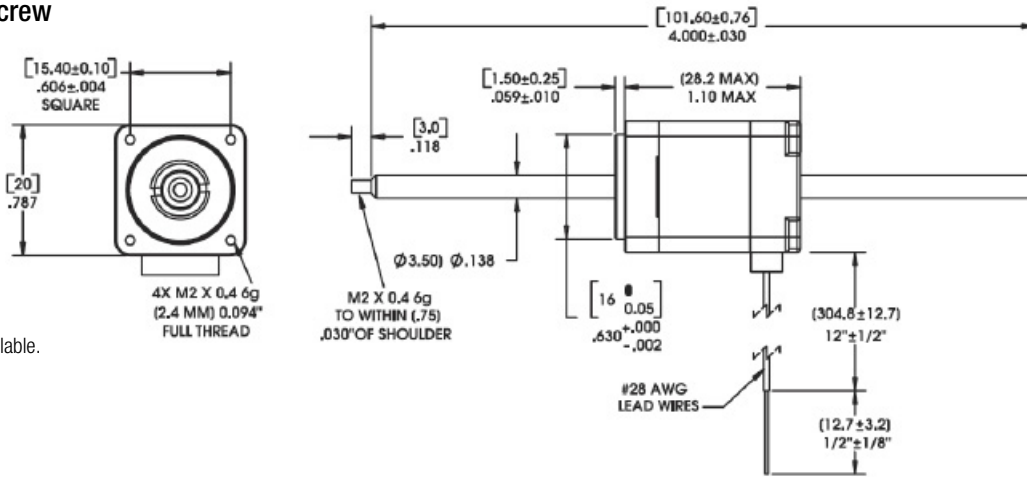
Dimensions = (mm) inches



Stroke	Dim. "A"	Dim. "B"	Suffix #
0.354 (9.0)	0.437 (11.10)	0.062 (1.58)	-904
0.500 (12.7)	0.583 (14.81)	0.208 (5.28)	-905
0.750 (19.05)	0.833 (21.16)	0.458 (11.63)	-907
1.000 (25.4)	1.083 (27.51)	0.708 (17.98)	-910
1.250 (31.8)	1.333 (33.86)	0.958 (24.33)	-912
1.500 (38.1)	1.583 (40.21)	1.208 (30.68)	-915

Non-Captive Lead Screw

Dimensions = (mm) inches

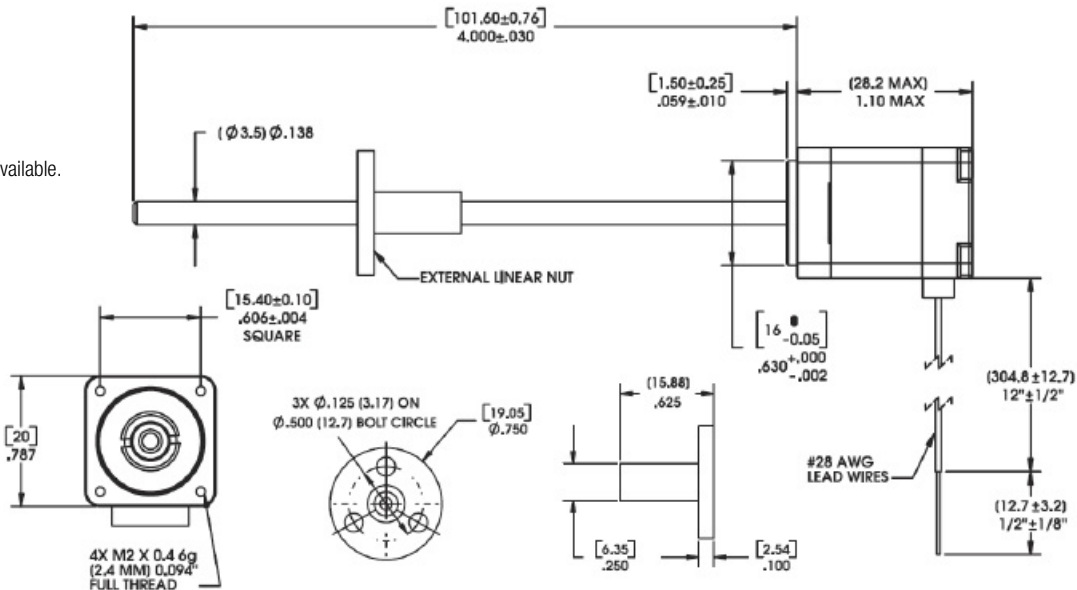


4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.

External Linear

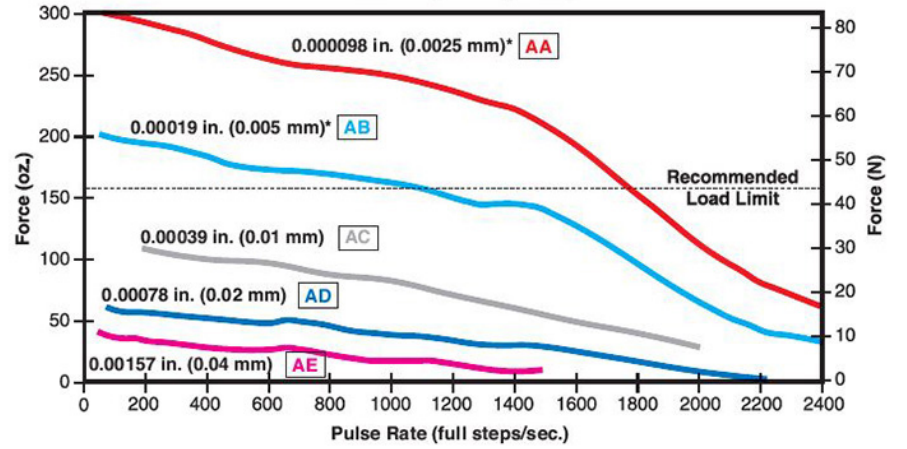
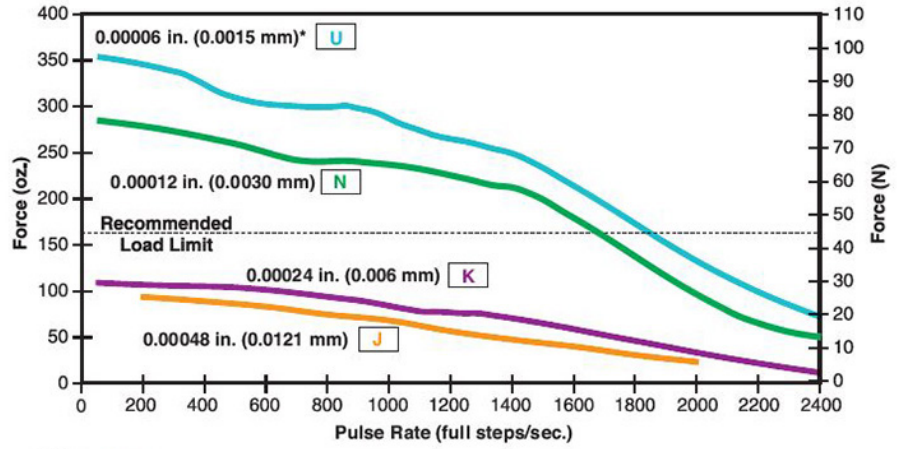
Dimensions = (mm) inches

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw



FORCE vs. LINEAR VELOCITY

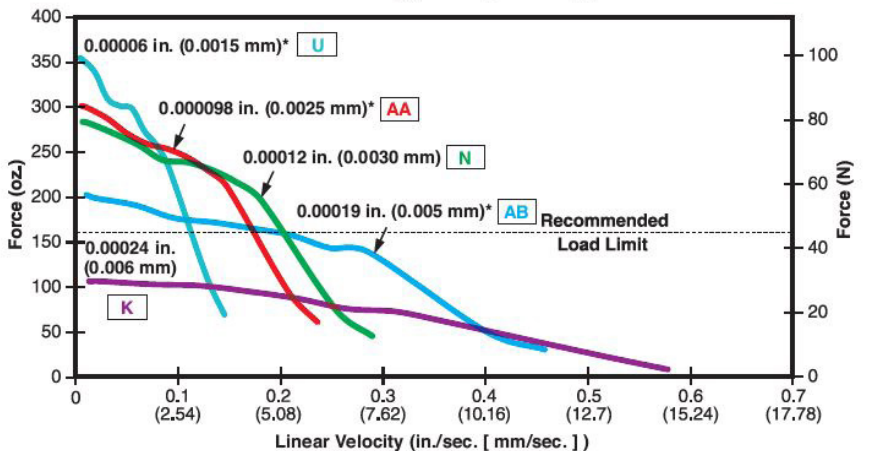
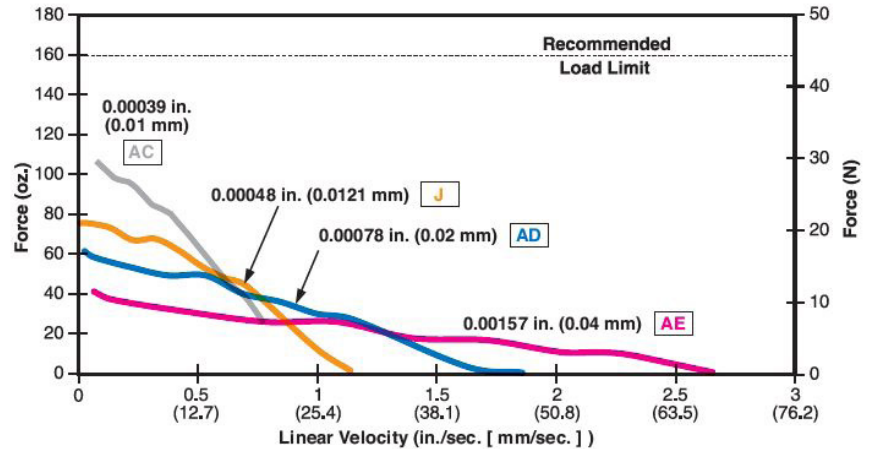
- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw

*Care should be taken when utilizing these screw pitches to ensure that the physical load limits of the motor are not exceeded. Please consult the factory for advice in selecting the proper pitch for your application.

NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

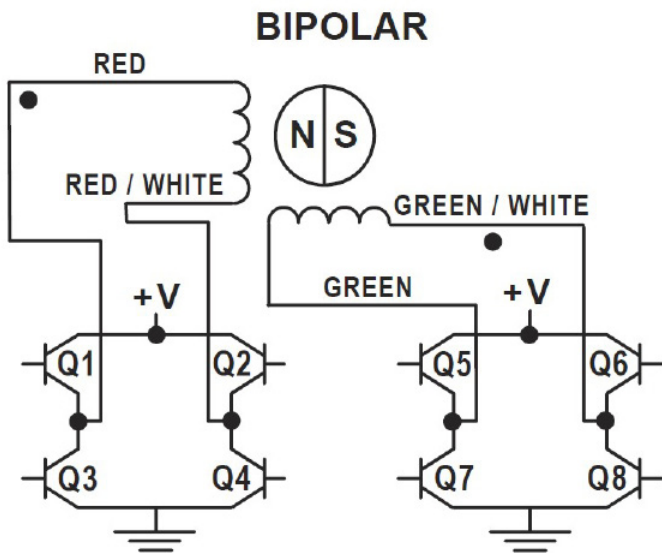


Identifying the Hybrid Part Number Codes when Ordering

E	21	H	4	AB	7.5	910
Prefix (include only when using the following) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 21 = 21000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step U* = .00006-in (.0015) AA* = .000098-in (.0025) N = .00012-in (.0030) AB = .00019-in (.005) K = .00024-in (.006) AC = .00039-in (.01) J = .00048-in (.0121) AD = .00078-in (.02) AE = .00157-in (.04) *TFE not available	Voltage 2.5 = 2.5 VDC 05 = 5 VDC 7.5 = 7.5 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Integrated Connector for Hybrid Size 8

Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 2 amps and the mating connector will handle a range of wire gauges from 24 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S04B-ZESK-2D

Mating Connector:

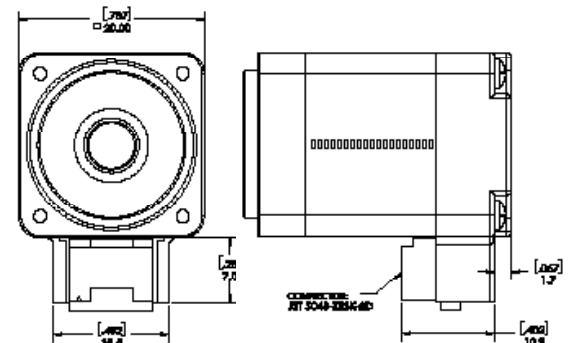
JST part # ZER-04V

Haydon Kerk Part # 56-2369-1 (12 in. Leads)

Wire to Board Connector:

JST part # SZE-002T-P0.3

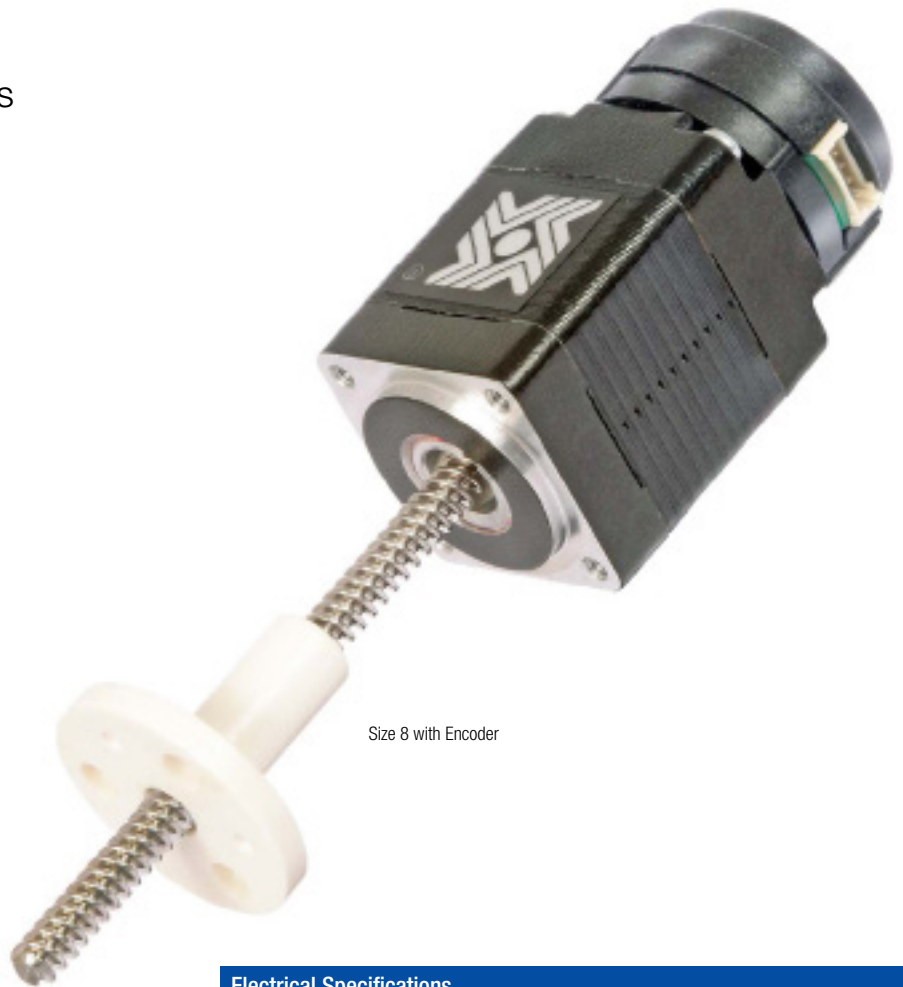
Pin #	Bipolar	Color
1	Phase 2 Start	G/W
2	Phase 2 Finish	Green
3	Phase 1 Finish	R/W
4	Phase 1 Start	Red



Encoders Designed for All Sizes of Hybrid Linear Actuators

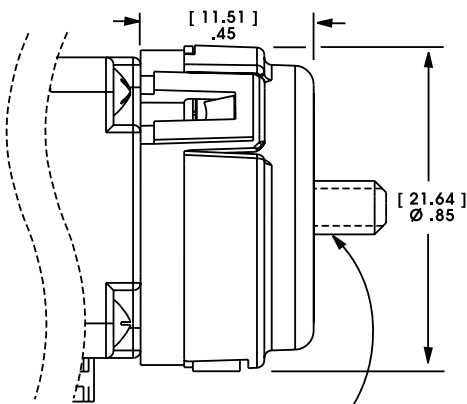
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 8 Encoder provides resolutions for applications that require 250 and 300 counts per revolution. Encoders are available for all motor configurations – captive, non-captive and external linear.

Simplicity and low cost make Encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photo-detector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Size 8 with Encoder

21mm 21000 Series Size 8



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Single Ended Encoder - Pinout - Size 8	
Connector Pin #	Description
1	+5 VDC Power
2	Channel A
3	Ground
4	Channel B

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 8	Minimum	Maximum
	- 10°C (14°F)	85°C (185°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution			
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)			
Size 8	CPR	250	300
	PPR	1000	1200

21000 Series Size 8 Double Stack Hybrid Linear Actuators

Size 8 Double Stack Hybrid Stepper Motor Linear Actuators provide enhanced performance over a single stack.

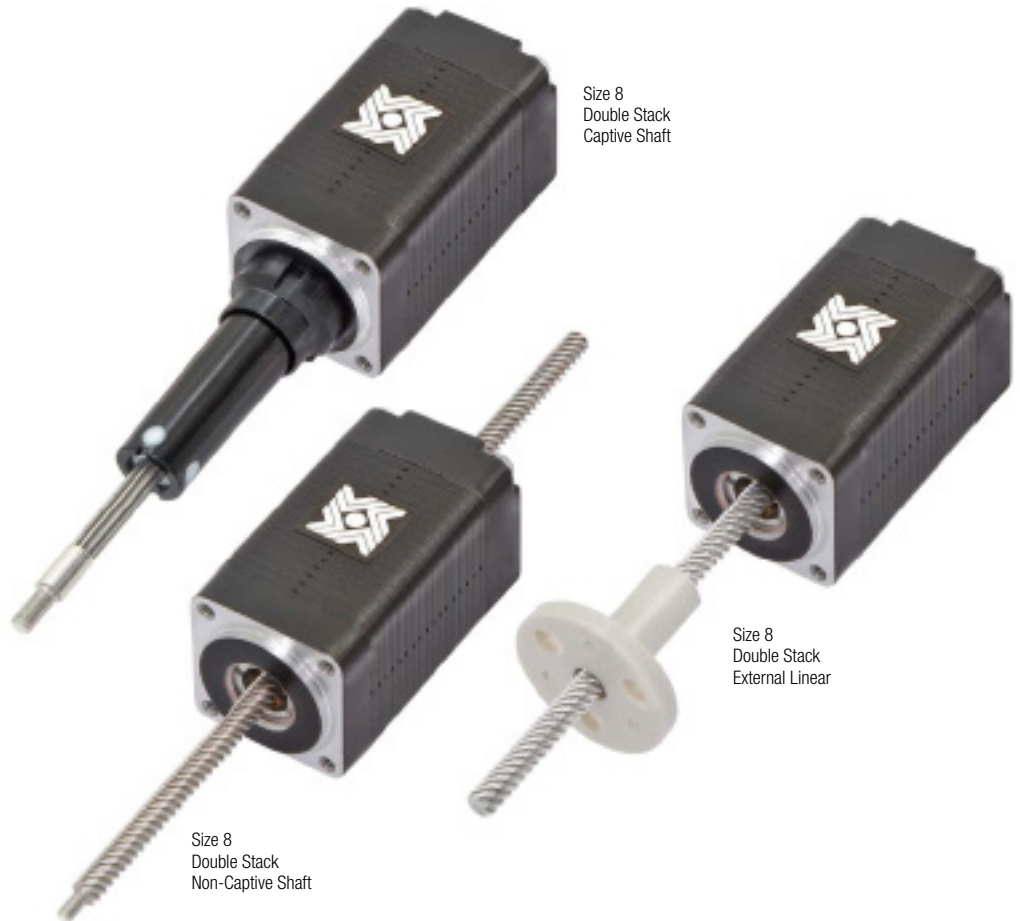
Improved Performance & New Linear Motion Design Opportunities in a 20 mm Frame Size

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 21000 Series is available in a wide variety of resolutions - from 0.000098 in (.0025 mm) per step to 0.00157 in (0.04 mm) per step. The Size 8 actuator delivers thrust of up to 17 lbs. (75 N).

Assembly options include: Incremental encoders, proximity sensors (captive types only), anti-backlash and custom nuts, and TFE coated lead screws.



Size 8
Double Stack
Captive Shaft

Size 8
Double Stack
External Linear

Size 8
Double Stack
Non-Captive Shaft

Specifications

Size 8 Double Stack: 21 mm (0.8-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	21M4 ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ †	
	Non-Captive	21L4 ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ †	
	External Linear	E21M4 ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ †	
Wiring	Bipolar		
Winding Voltage	2.5 VDC	5 VDC	7.5 VDC
Current (RMS)/phase	1.32 A	.65 A	.43 A
Resistance/phase	1.9 Ω	7.7 Ω	17.3 Ω
Inductance/phase	0.8 mH	3.2 mH	6.1 mH
Power Consumption	6.5 W Total		
Rotor Inertia	2.6 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	2.4 oz (43 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 84.

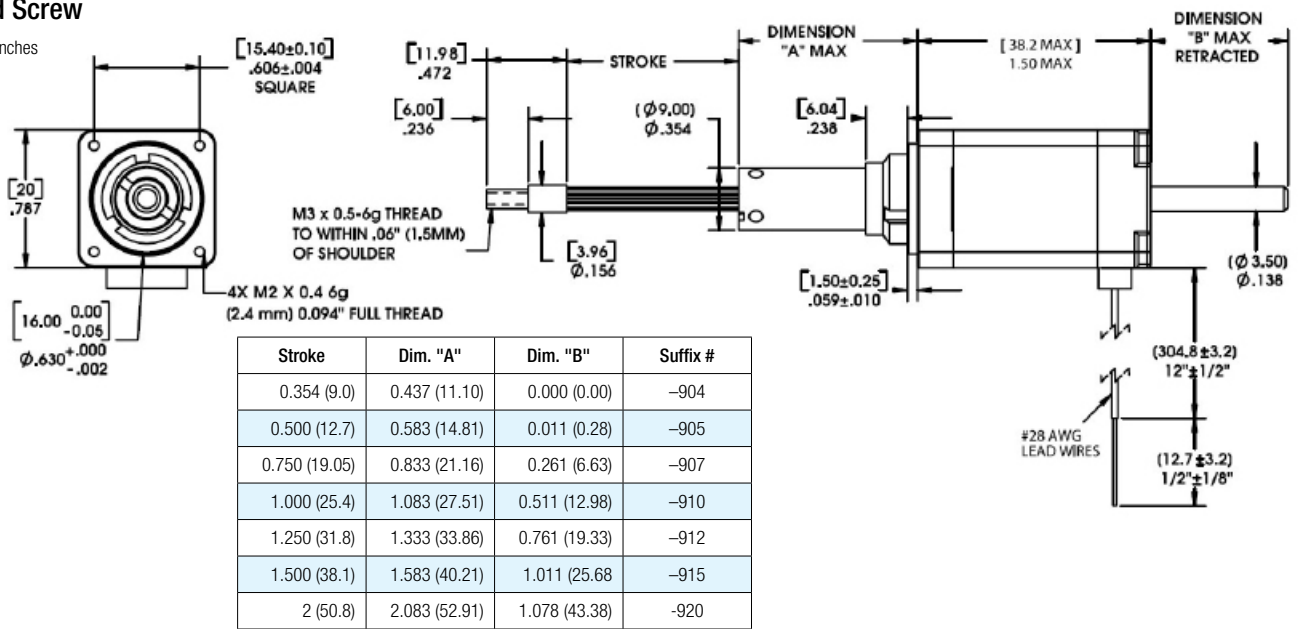
Linear Travel / Step		Order Code I.D.
Screw Ø.14-in (3.56mm)		
inches	mm	
.000098*	.0025	AA
.00012	.0030*	N
.00019*	.005	AB
.00024	.006*	K
.00039*	0.01	AC
.00048	.0121*	J
.00078*	.02	AD
.00157*	.04	AE
.00157	.04	AE

*Values truncated
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

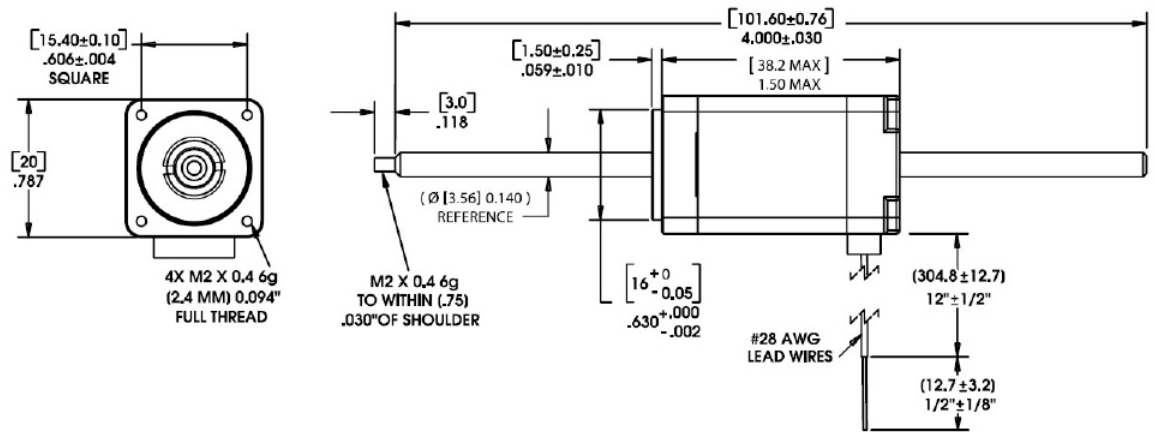
Captive Lead Screw

Dimensions = (mm) inches



Non-Captive Lead Screw

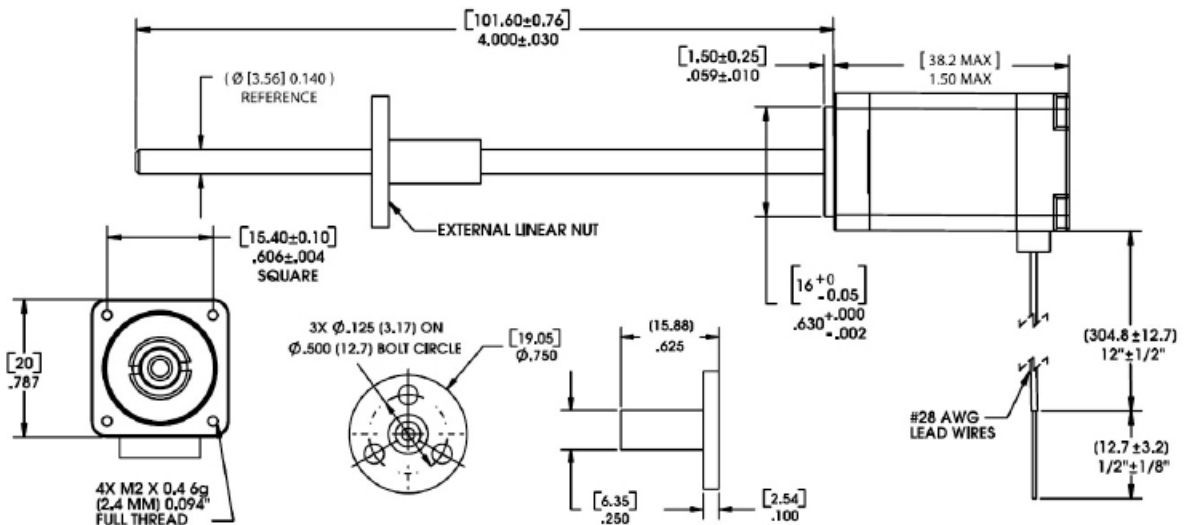
Dimensions = (mm) inches



Up to 6 in (152 mm) standard screw lengths. Longer screw lengths are available.

External Linear

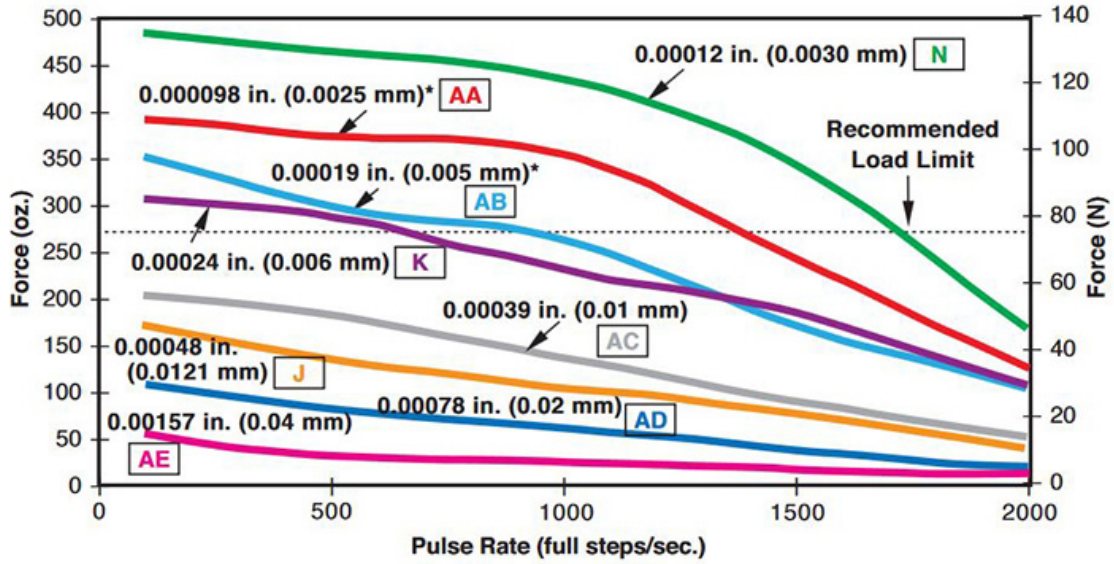
Dimensions = (mm) inches



Up to 6 in (152 mm) standard screw lengths. Longer screw lengths are available.

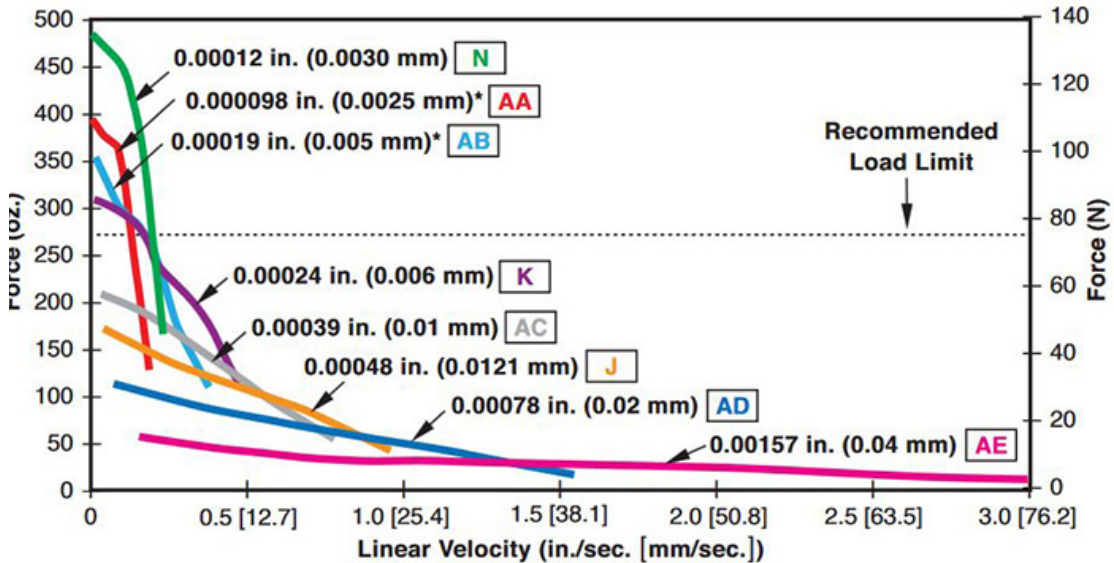
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw
- 8:1 Motor Coil to Drive Supply Voltage



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw
- 8:1 Motor Coil to Drive Supply Voltage



*Care should be taken when utilizing these screw pitches to ensure that the physical load limits of the motor are not exceeded. Please consult the factory for advice in selecting the proper pitch for your application.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

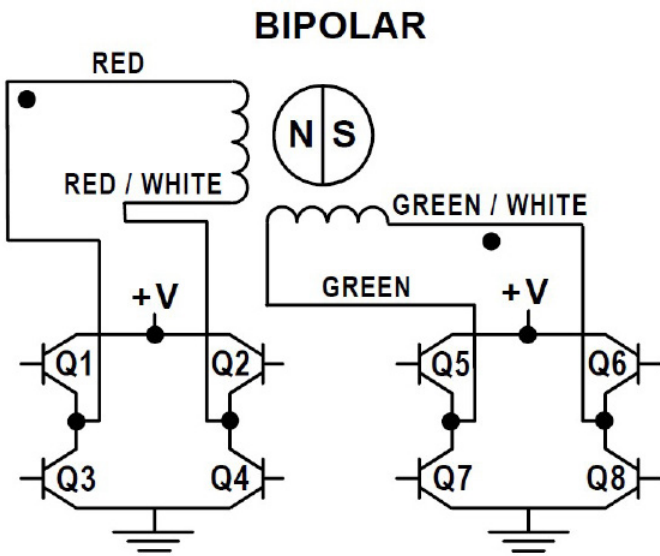
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	21	M	4	N	2.5	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor	Series Number Designation 21 = 21000 (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step AA* = .000098-in (.0025) N = .00012-in (.0030) AB = .00019-in (.005) K = .00024-in (.006) AC = .00039-in (.01) J = .00048-in (.0121) AD = .00078-in (.02) AE = .00157-in (.04) *TFE not available	Voltage 2.5 = 2.5 VDC 05 = 5 VDC 7.5 = 7.5 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

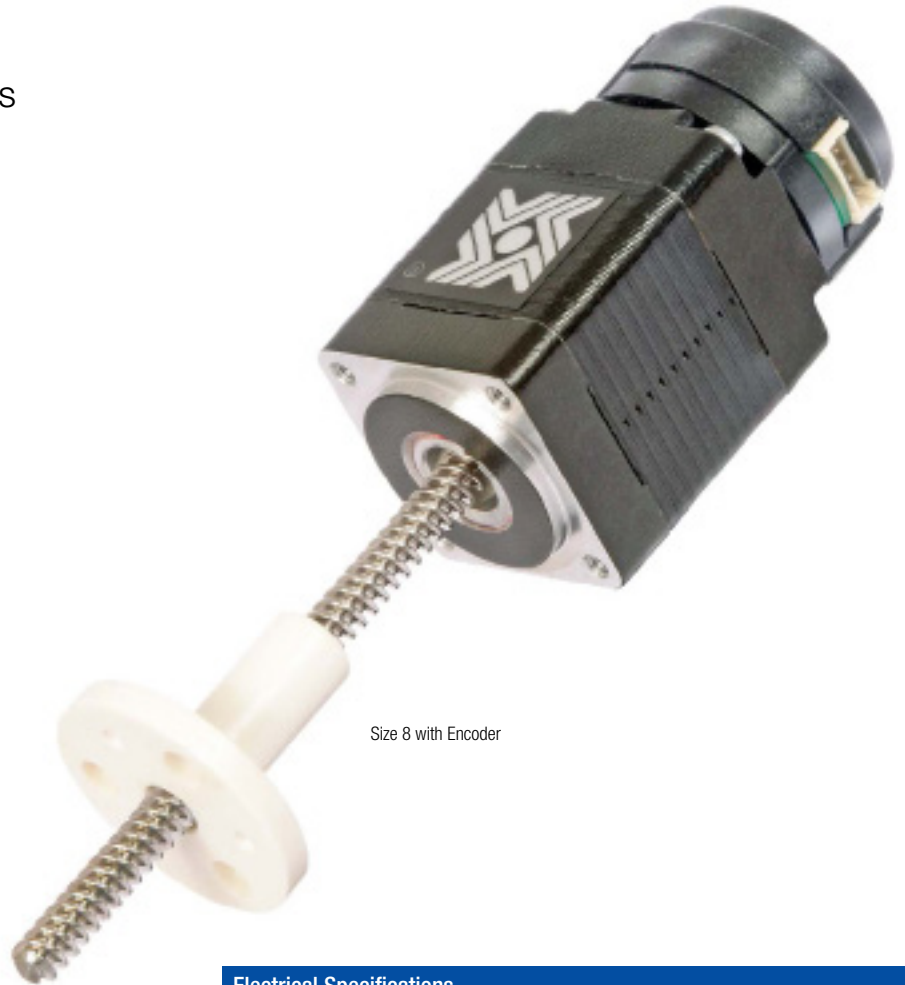
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

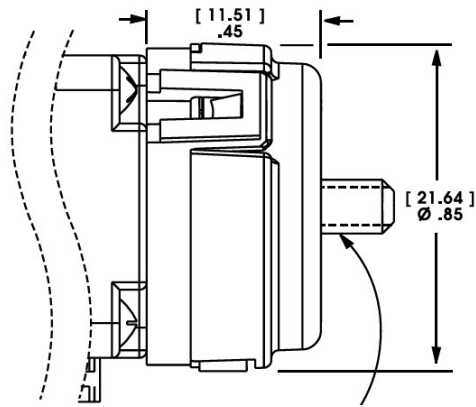
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 8 Encoder provides resolutions for applications that require 250 and 300 counts per revolution. Encoders are available for all motor configurations – captive, non-captive and external linear.

Simplicity and low cost make Encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photo-detector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Size 8 with Encoder

21mm 21000 Series Size 8



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Single Ended Encoder - Pinout - Size 8	
Connector Pin #	Description
1	+5 VDC Power
2	Channel A
3	Ground
4	Channel B

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 8	Minimum	Maximum
	- 10°C (14°F)	85°C (185°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution			
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)			
Size 8	CPR	250	300
	PPR	1000	1200

28000 Series Size 11 Hybrid Linear Actuators

Compact, production-proven precision in motion.

The various patented designs deliver high performance, opening avenues for equipment designers who require performance and endurance in a very small package.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 28000 Series is available in a wide variety of resolutions - from 0.000125-in (.003175 mm) per step to 0.002-in (.0508 mm) per step.

The Size 11 actuator delivers thrust of -up to 20 lbs. (90 N).



Size 11
Captive Shaft

Size 11
Non-Captive Shaft

Size 11
External Linear

Size 11: 28 mm (1.1-in) Hybrid Linear Actuator (1.8° Step Angle)

Part No.	Captive	28H4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †			28H6 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	Non-Captive	28F4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †			28F4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	External Linear	E28H4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †			E28H6 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
Wiring	Bipolar			Unipolar**		
Winding Voltage	2.1 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase	1.0 A	0.42 A	0.18 A	0.42 A	0.18 A	
Resistance/phase	2.1	11.9 Ω	68.6 Ω	11.9 Ω	68.6 Ω	
Inductance/phase	1.5 mH	6.7 mH	39.0 mH	3.3 mH	19.5 mH	
Power Consumption	4.2 W					
Rotor Inertia	9.0 gcm ²					
Insulation Class	Class B (Class F available)					
Weight	4.2 oz (119 g)					
Insulation Resistance	20 MΩ					

Linear Travel / Step Screw Ø.1875" (4.76mm)		Order Code I.D.
inches	mm	
.000125	.0031*	7
.00025	.0063*	9
.0005	.0127	3
.001	.0254	1
.002	.0508	2

*Values truncated.

Standard motors are Class B rated for maximum temperature of 130°C.

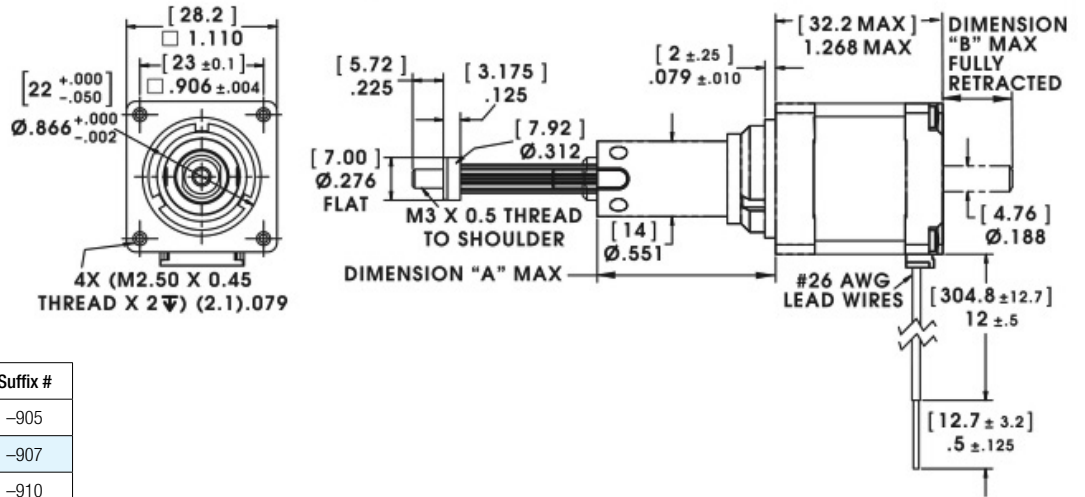
Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

†Part numbering information on page 89. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



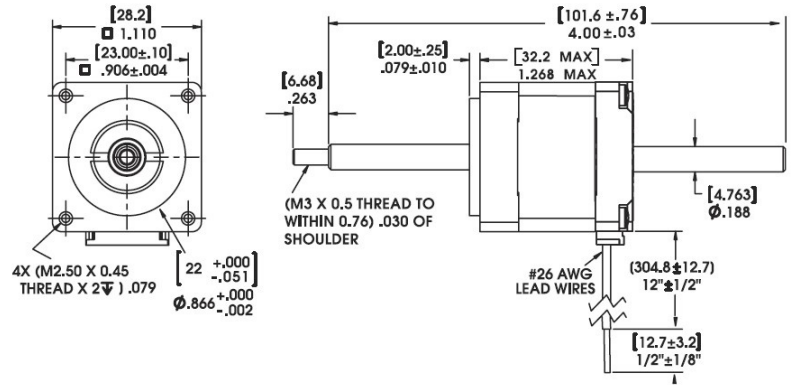
Stroke	Dim. "A"	Dim. "B"	Suffix #
0.500 (12.7)	0.806 (20.47)	0.208 (5.28)	-905
0.750 (19.05)	1.056 (26.82)	0.458 (11.63)	-907
1.000 (25.4)	1.306 (33.17)	0.708 (17.98)	-910
1.250 (31.8)	1.556 (39.52)	0.958 (24.33)	-912
1.500 (38.1)	1.806 (45.87)	1.208 (30.68)	-915
2.00 (50.8)	2.306 (58.57)	1.208 (30.68)	-920
2.500 (63.5)	2.806 (71.27)	1.208 (30.68)	-925

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

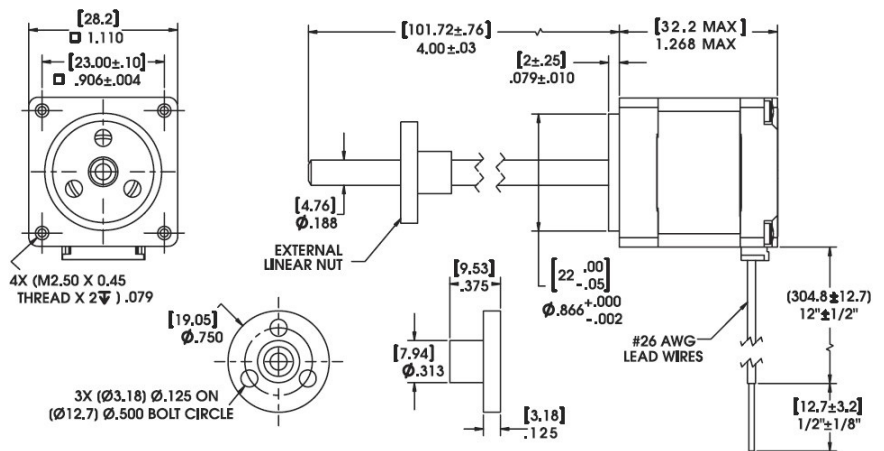


External Linear

Dimensions = (mm) inches

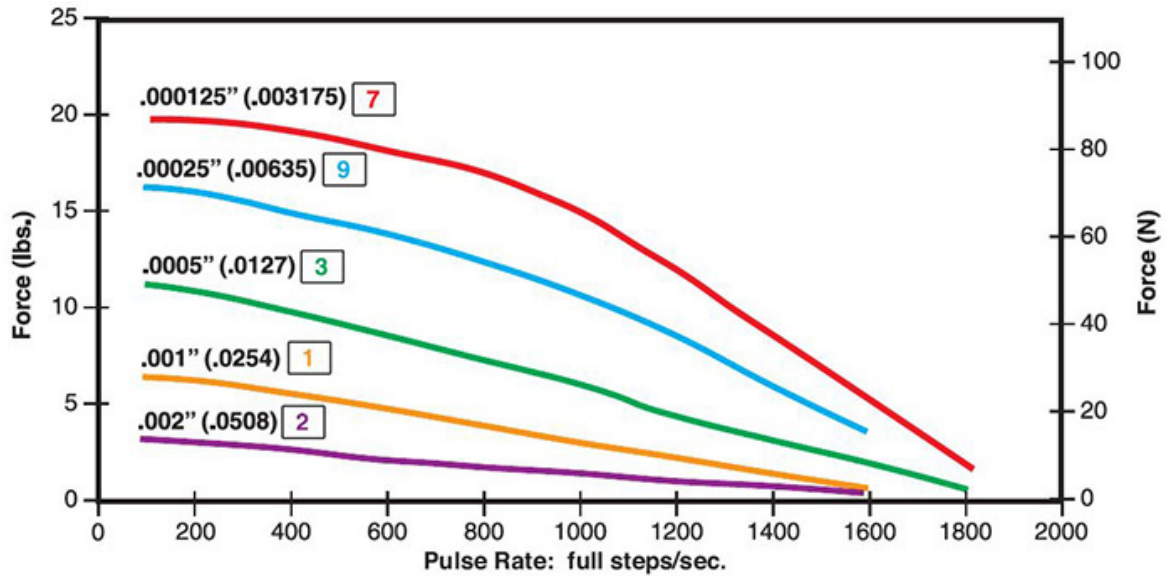
Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.



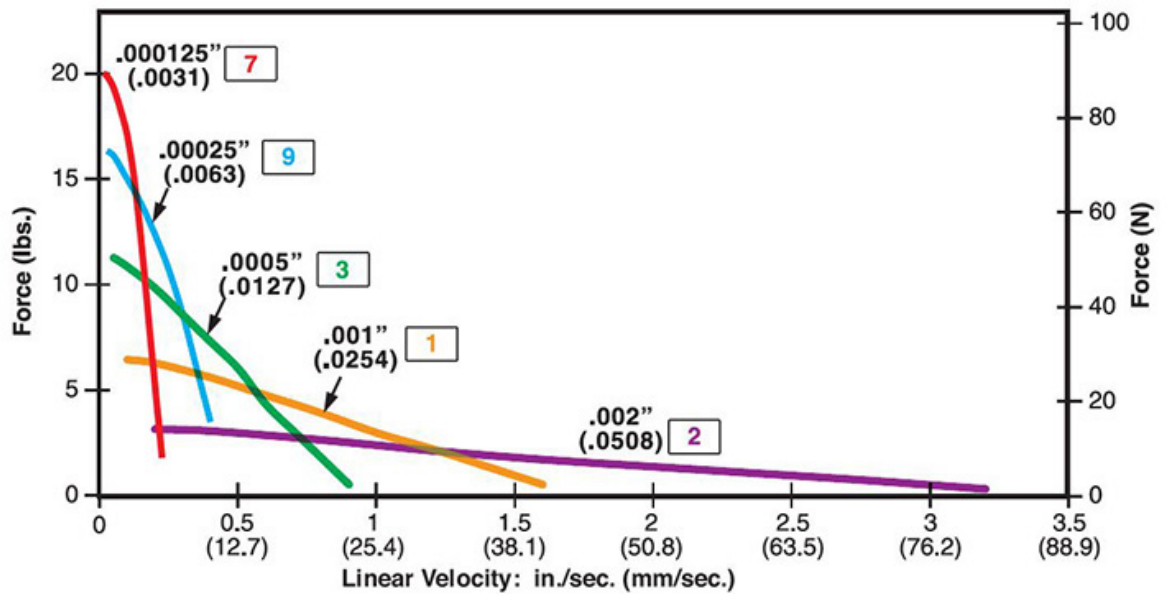
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .1875 (4.75) Lead Screw



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .1875 (4.75) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

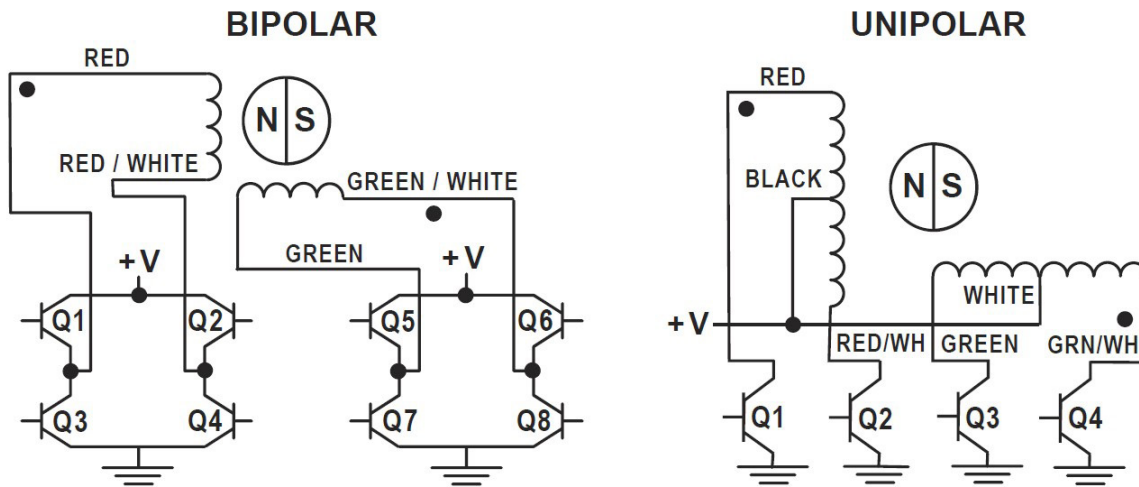
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	28	H	4	7	05	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 28 = 28000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.0508) 3 = .0005-in (.0127) 7 = .000125-in (.0031) 9 = .00025-in (.0063)	Voltage 2.1 = 2.1 VDC (Bipolar only) 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

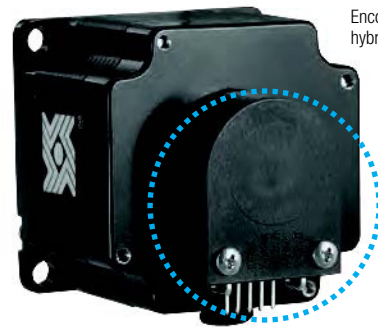
EXTEND CW
RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

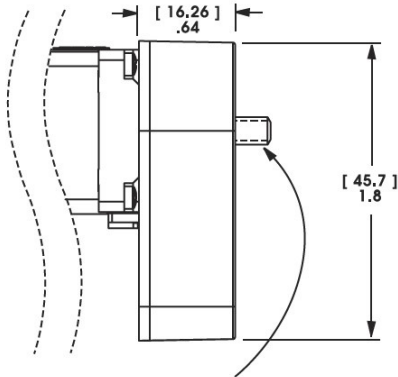
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 11 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 28000 Series Size 11



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 11

Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature

Size 11	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)

Size 11	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available. Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 11

Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 11

Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

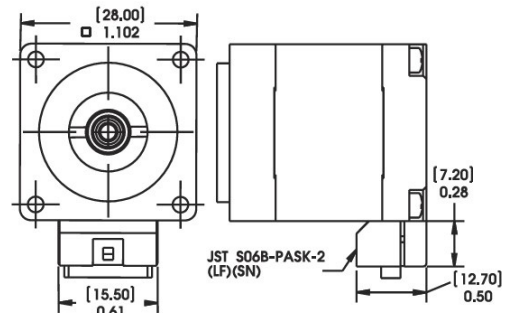
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



28000 Series Size 11 Double Stack Hybrid Linear Actuators

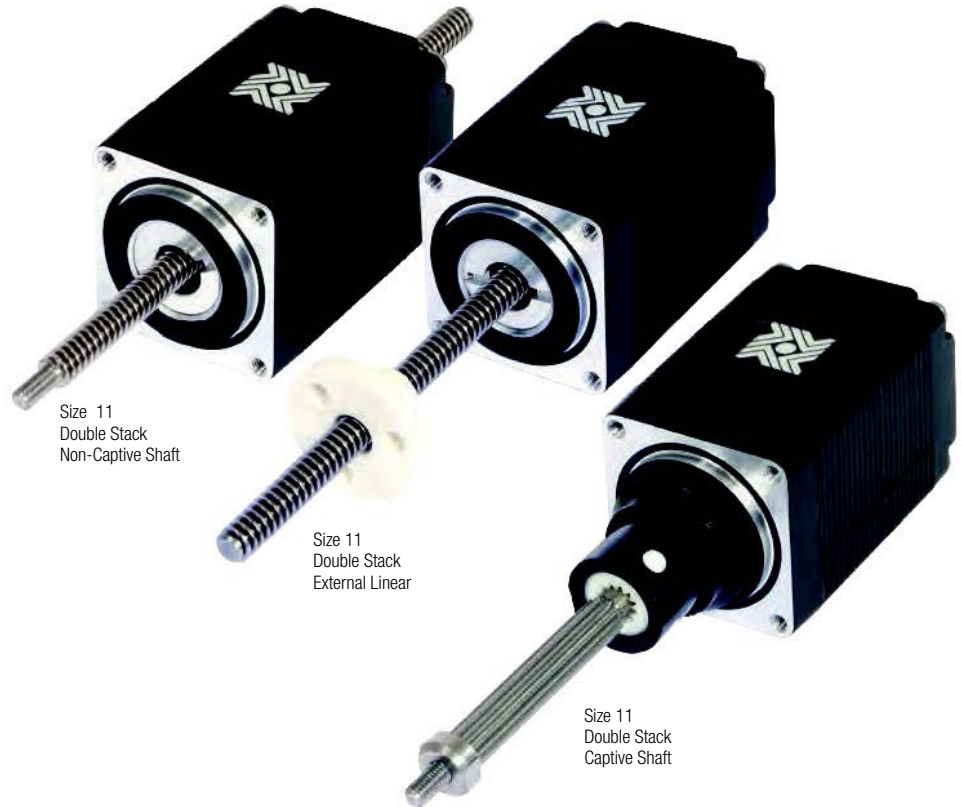
Enhanced performance in motion control

The 28000 Series is available in a wide variety of resolutions - from 0.000125" (.003175 mm) per step to 0.002" (.0508 mm) per step.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The Size 11 actuator delivers thrust of up to 30 lbs. (133 N).



Size 11 Double Stack: 28 mm (1.1-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	28M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	Non-Captive	28L4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	External Linear	E28M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
Wiring		Bipolar	
Winding Voltage	2.1 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.9 A	750 mA	313 mA
Resistance/phase	1.1 Ω	6.7 Ω	34.8 Ω
Inductance/phase	1.1 mH	5.8 mH	35.6 mH
Power Consumption	7.5 W Total		
Rotor Inertia	13.5 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	5.8 oz (180 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 94.

Linear Travel / Step		Order Code I.D.
Screw Ø.1875" (4.76mm)		
inches	mm	
.000125	.0031*	7
.00025	.0063*	9
.0005	.0127	3
.001	.0254	1
.002	.0508	2

*Values truncated.

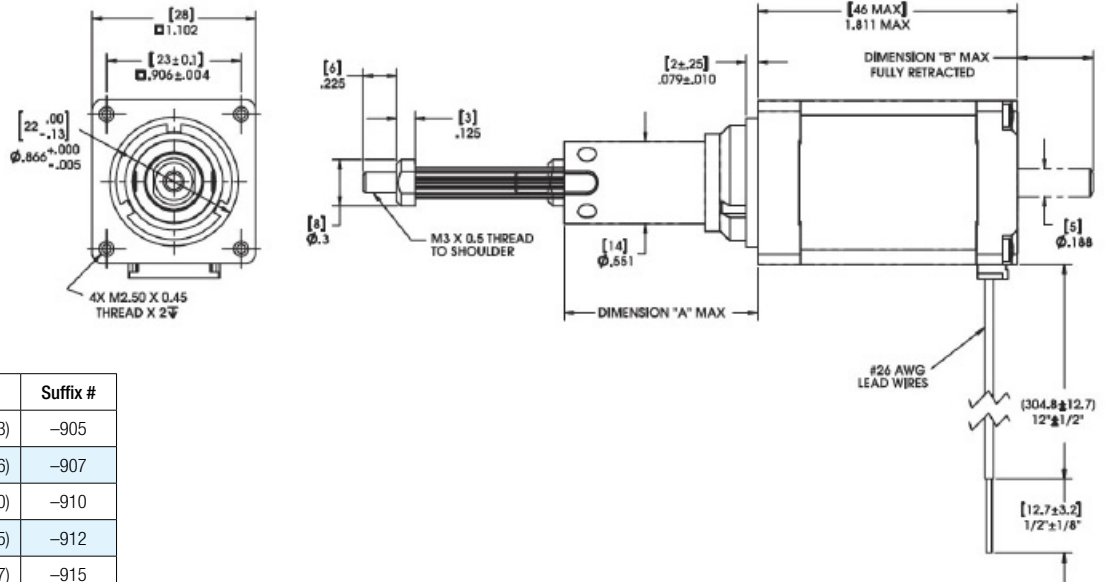
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



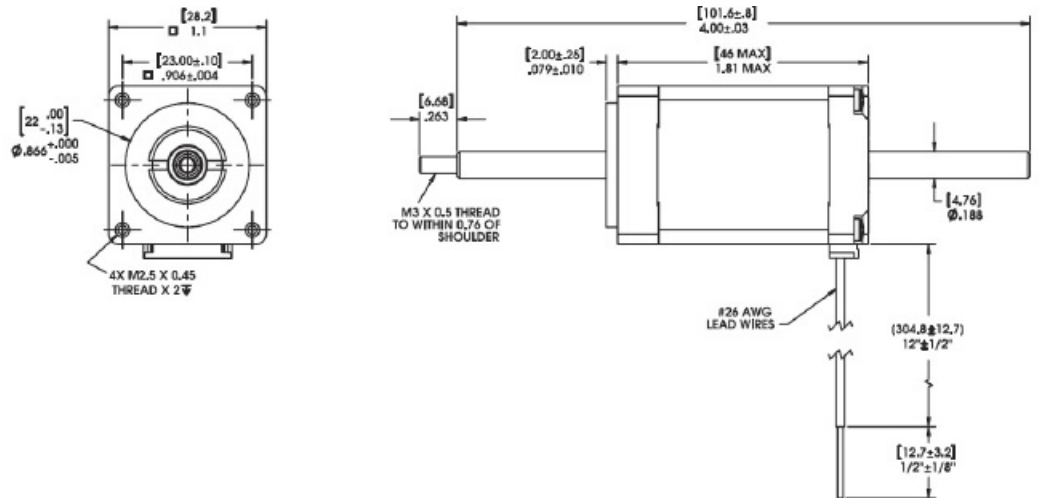
Stroke	Dim. "A"	Dim. "B"	Suffix #
0.500 (12.7)	0.80 (20.5)	0.09 (2.3)	-905
0.750 (19.05)	1.05 (26.8)	0.34 (8.6)	-907
1.000 (25.4)	1.30 (33.17)	0.59 (15.0)	-910
1.250 (31.8)	1.55 (39.5)	0.84 (21.35)	-912
1.500 (38.1)	1.806 (45.87)	1.09 (27.7)	-915
2.00 (50.8)	2.306 (58.57)	1.59 (40.4)	-920
2.500 (63.5)	2.806 (71.27)	2.09 (53.1)	-925

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

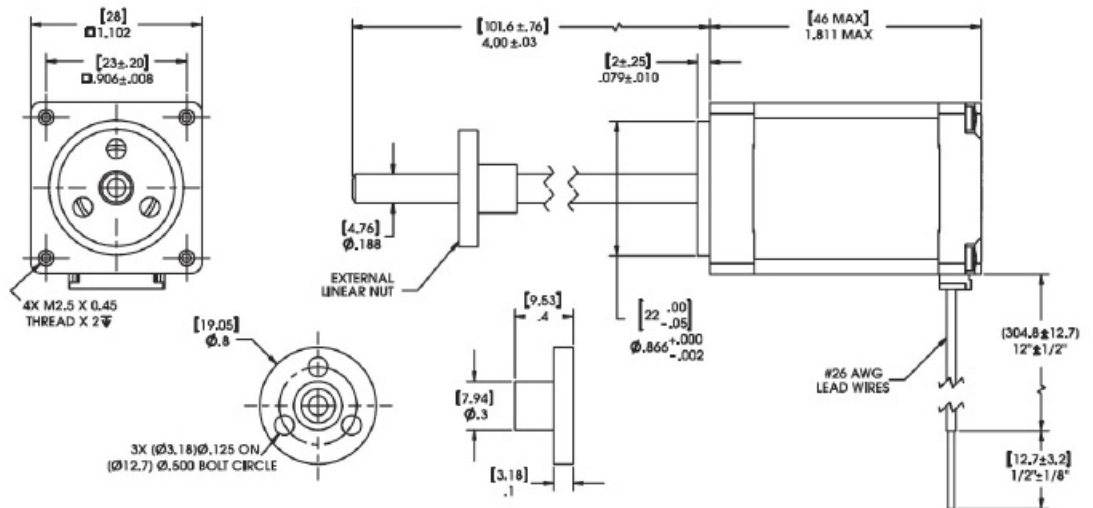


External Linear

Dimensions = (mm) inches

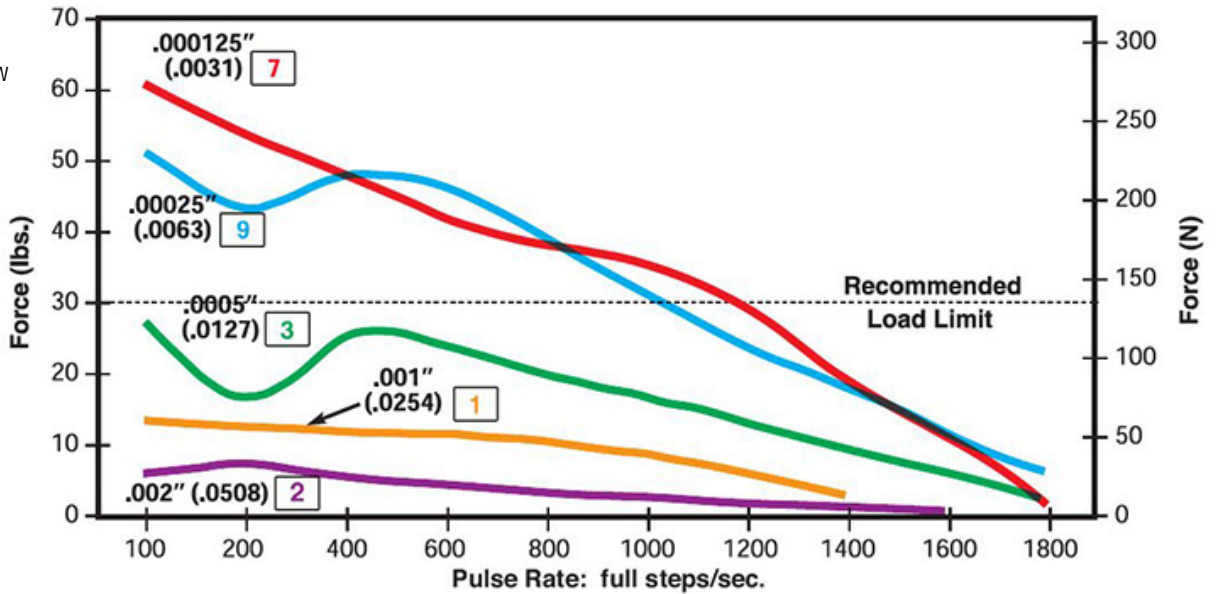
Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.



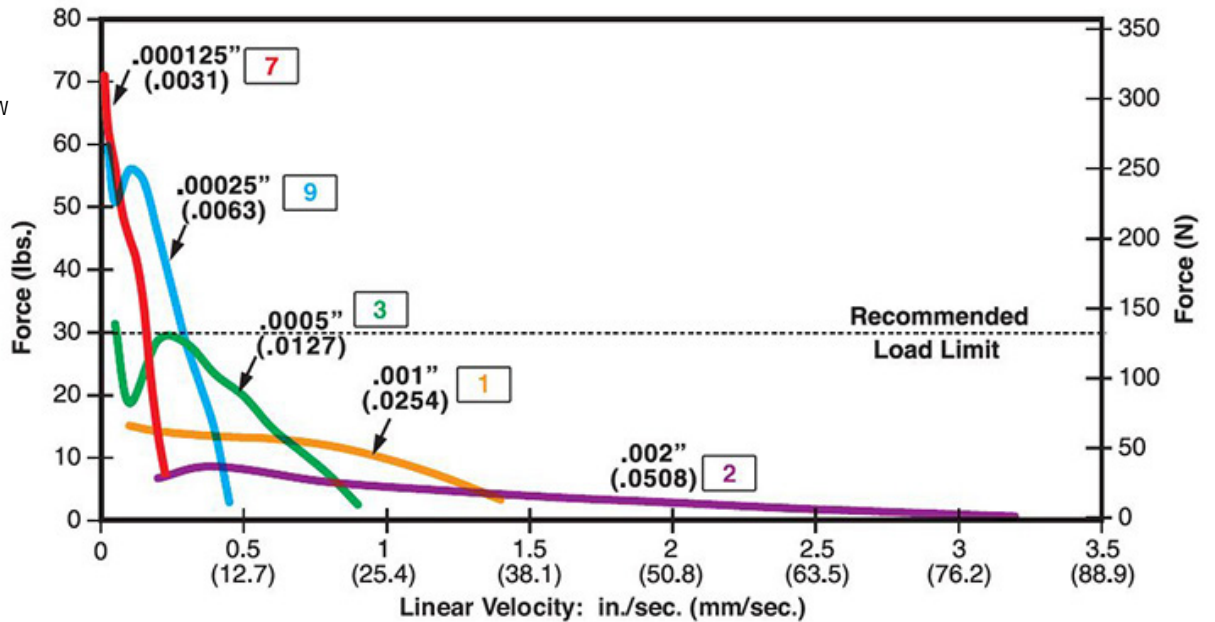
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .1875 (4.75) Lead Screw



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .1875 (4.75) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

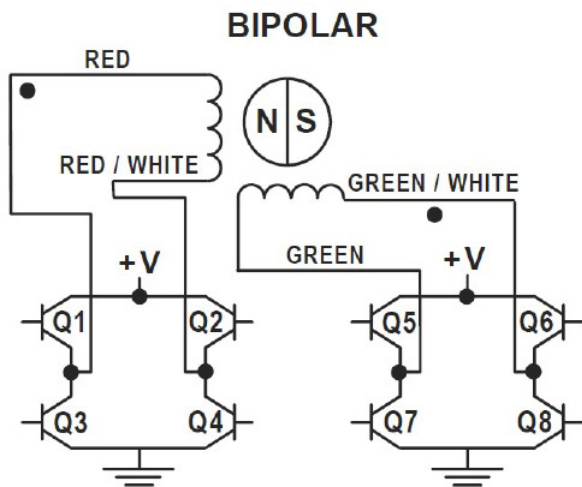
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	28	M	4	7	05	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 28 = 28000 (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.0508) 3 = .0005-in (.0127) 7 = .000125-in (.0031) 9 = .00025-in (.0063)	Voltage 2.1 = 2.1 VDC (Bipolar only) 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar Step	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

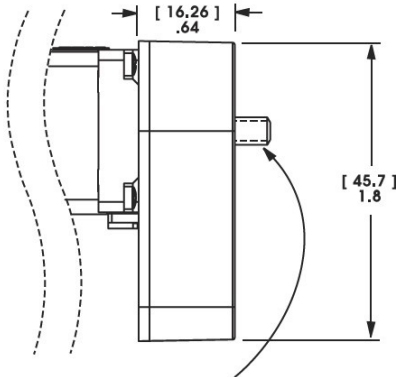
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 11 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 28000 Series Size 11



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 11

Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature

Size 11	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)

Size 11	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.

Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 11

Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 11

Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

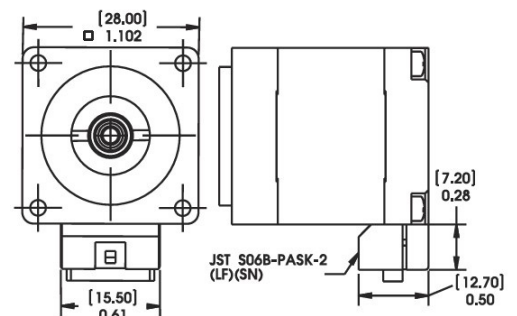
JST part # PAP-06V-S

Haydon Kerk part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part # SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



35000 Series Size 14 Hybrid Linear Actuators

Higher force, longer life and improved performance

The various patented designs deliver exceptional performance and new linear motion design opportunities.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 35000 Series is available in a wide variety of resolutions - from 0.00012-in (.003048 mm) per step to 0.00192-in (.048768 mm) per step. The motors can also be microstepped for even finer resolutions.

The Size 14 actuator delivers thrust of -up to 50 lbs. (222 N).



Size 14
Captive Shaft

Size 14
External Linear

Size 14
Non-Captive Shaft

Size 14: 35 mm (1.1-in) Hybrid Linear Actuator (1.8° Step Angle)

Part No.	Captive	35H4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			35H6 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
	Non-Captive	35F4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			35F4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
	External Linear	E35H4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			E35H6 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
Wiring	Bipolar			Unipolar**		
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase	1.25 A	0.57 A	0.24 A	0.57 A	0.24 A	
Resistance/phase	1.86 Ω	8.8 Ω	50.5 Ω	8.8 Ω	50.5 Ω	
Inductance/phase	2.8 mH	13 mH	60 mH	6.5 mH	30 mH	
Power Consumption	5.7 W					
Rotor Inertia	16.0 gcm ²					
Insulation Class	Class B (Class F available)					
Weight	5.7 oz (162 g)					
Insulation Resistance	20 MΩ					

†Part numbering information on page 100. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

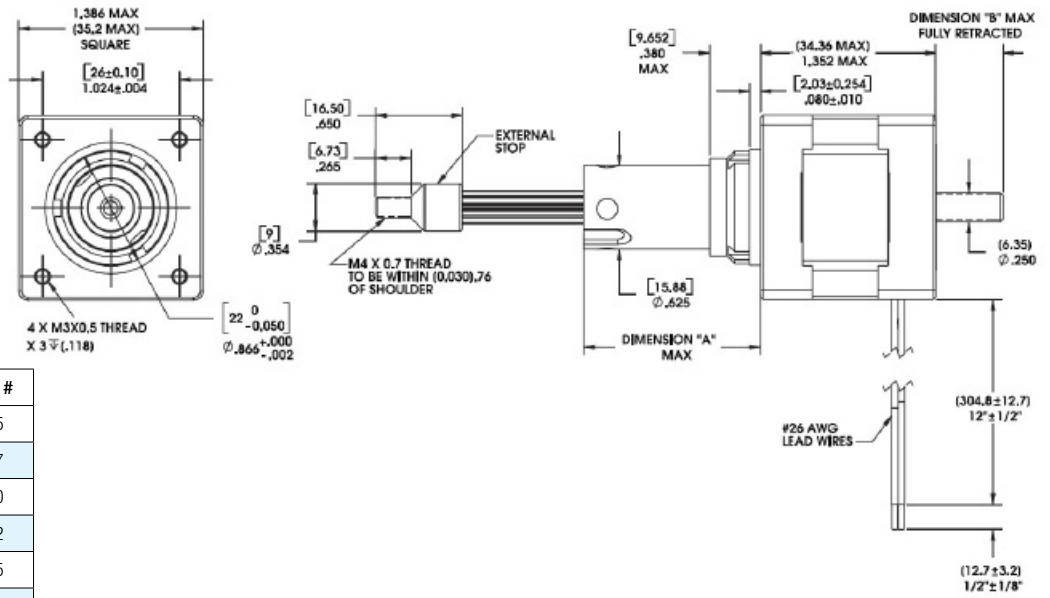
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



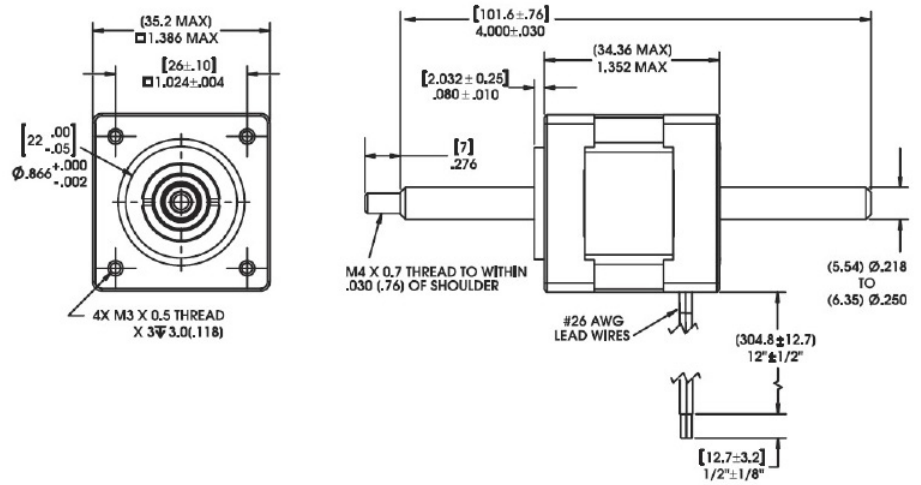
Stroke	Dim. "A"	Dim. "B"	Suffix #
0.500 (12.7)	0.82 (20.8)	0.04 (1.0)	-905
0.750 (19.05)	1.07 (27.2)	0.29 (7.4)	-907
1.000 (25.4)	1.32 (33.5)	0.54 (13.7)	-910
1.250 (31.8)	1.57 (39.9)	0.79 (20.1)	-912
1.500 (38.1)	1.82 (46.2)	1.04 (26.4)	-915
2.00 (50.8)	2.32 (58.9)	1.54 (39.1)	-920
2.500 (63.5)	2.82 (71.6)	2.04 (51.8)	-925

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

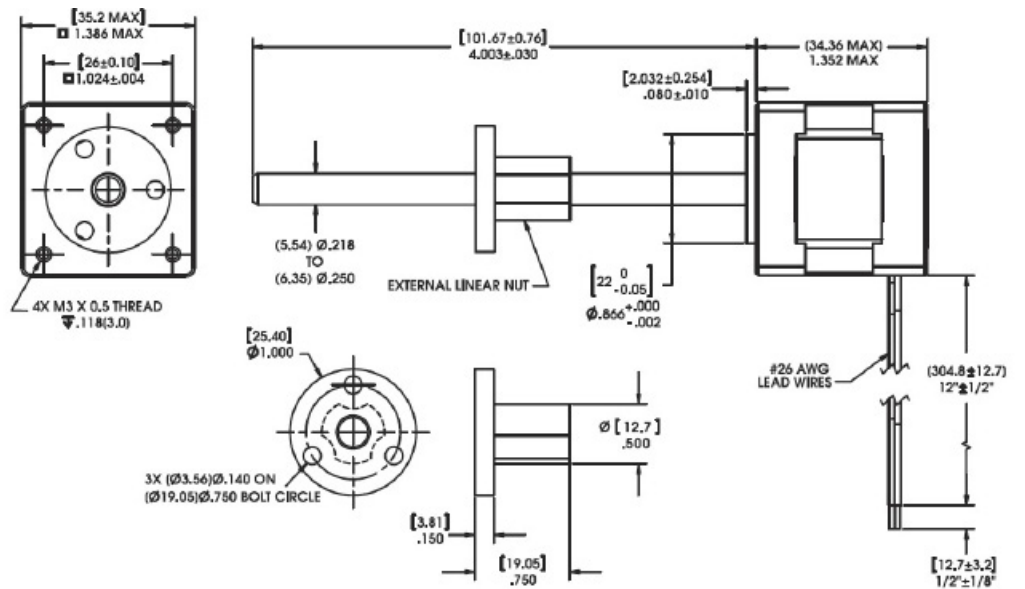


External Linear

Dimensions = (mm) inches

Integrated connector option available

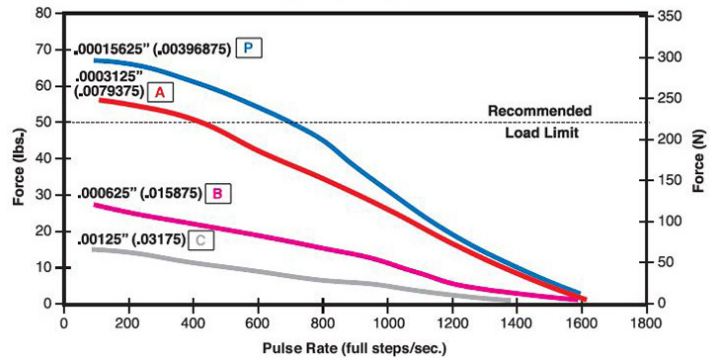
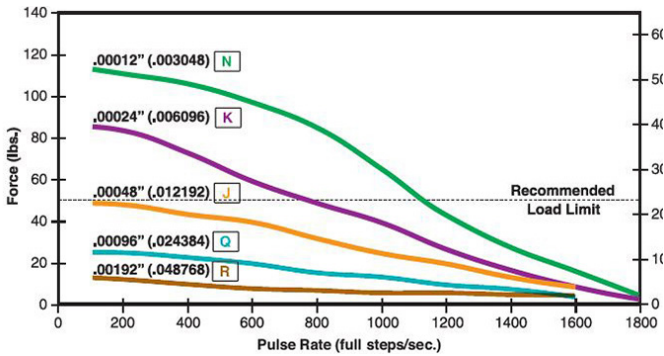
4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.



FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle

– Ø .218 (5.54) Lead Screw

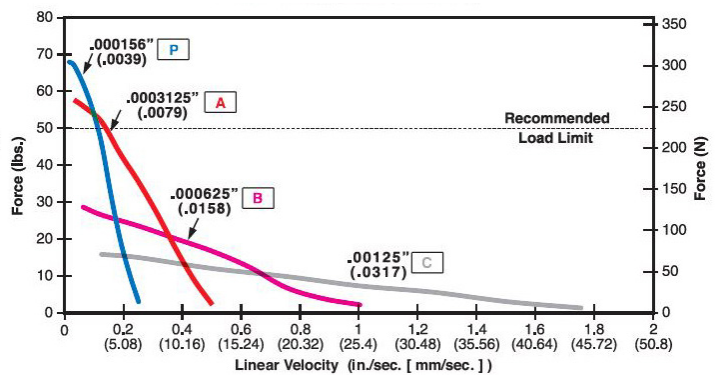
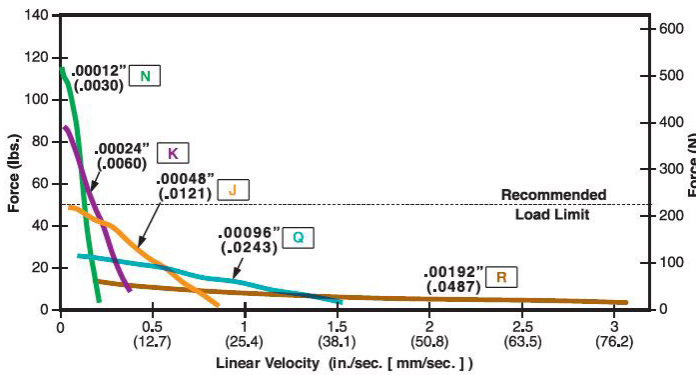
– Ø .250 (6.35) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle

– Ø .218 (5.54) Lead Screw

– Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.







Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

35000 Series

Size 14, 0.9° High Resolution Motor

Compared to the standard resolution (1.8°) this motor has been engineered to precisely deliver reliable high speed, force, up to 50 lbs (222 N), as well as a full step movement as low as 1.5 microns.

Size 14: 35 mm (1.1-in) Hybrid Linear Actuator (0.9° Step Angle)						
Part No.	Captive	35K4  †			35K6  †	
	Non-Captive	35J4  †			35J6  †	
	External Linear	E35K4  †			E35K6  †	
Wiring		Bipolar			Unipolar**	
Winding Voltage		2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		1.25 A	0.57 A	0.24 A	0.57 A	0.24 A
Resistance/phase		1.86 Ω	8.8 Ω	50.5 Ω	8.8 Ω	50.5 Ω
Inductance/phase		2.8 mH	13 mH	60 mH	6.5 mH	30 mH
Power Consumption		5.7 W				
Rotor Inertia		16.0 gcm ²				
Insulation Class		Class B (Class F available)				
Weight		5.7 oz (162 g)				
Insulation Resistance		20 MΩ				

Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	
.00006	.0015*	U
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.000078*	.00198*	V
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B

*Values truncated.

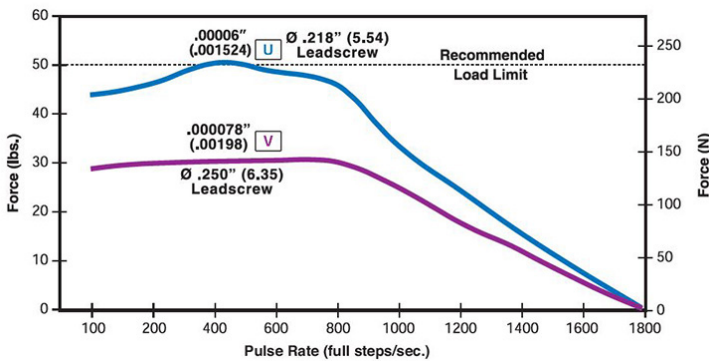
Standard motors are Class B rated for maximum temperature of 130°C.

NOTE: Refer to performance curves on previous page for codes N, K, J, Q, P, A, B

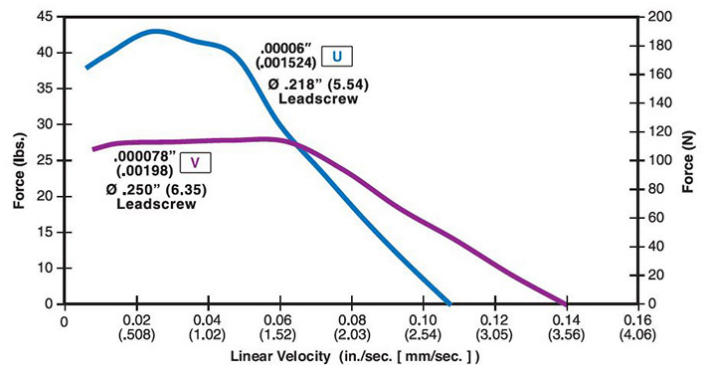
Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

†Part numbering information on page 100. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

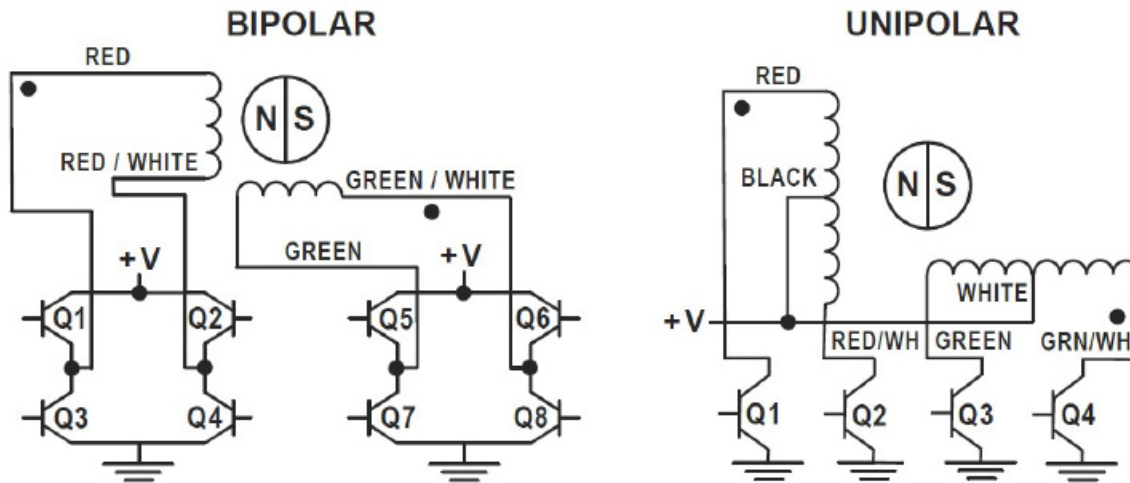
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	35	H	4	N	2.33	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 35 = 35000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version) J = 0.9° Non-captive K = 0.9° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step N = .00012-in (.0030) K = .00024-in (.0060) J = .00048-in (.0121) Q = .00096-in (.0243) P = .0015625-in (.0039) A = .003125-in (.0079) B = .00625-in (.0158) C = .0125-in (.0317) R = .00192-in (.0478) High Resolution U = .00006-in (.0015) V = .000078-in (.00198)	Voltage 2.33 = 2.33 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

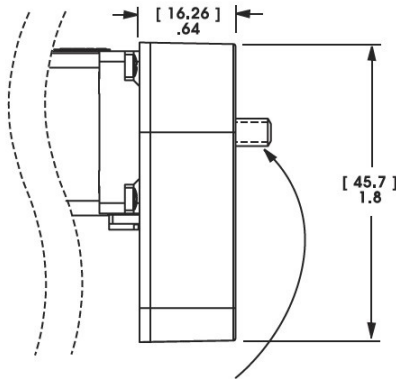
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 14 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 35000 Series Size 14



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 14

Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature

Size 14	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)

Size 14	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available. Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 14

Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 14

Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

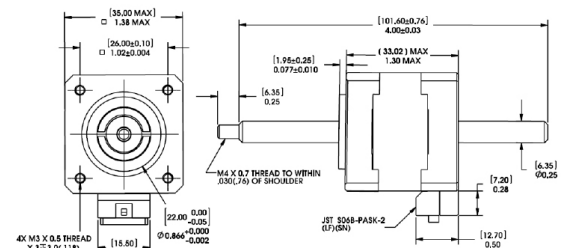
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



35000 Series Size 14 Double Stack Hybrid Linear Actuators

Improved force and performance

The 35000 Series is available in a wide variety of resolutions - from 0.000625-in (.0158 mm) per step to 0.005-in (.127 mm) per step. The motors can also be microstepped for even finer resolutions.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The Size 14 actuator delivers thrust of up to 50 lbs. (222 N).



Size 14 Double Stack: 35 mm (1.4-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	35M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	Non-Captive	35L4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	External Linear	E35M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
Wiring	Bipolar		
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current (RMS)/phase	2 A	910 mA	380 mA
Resistance/phase	1.2 Ω	5.5 Ω	31.6 Ω
Inductance/phase	1.95 mH	7.63 mH	65.1 mH
Power Consumption	9.1 W Total		
Rotor Inertia	30 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	8.5 oz (240 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 105.

Linear Travel / Step		Order Code I.D.
Screw Ø.1875" (4.76mm)		
inches	mm	
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635	Y
.00375	.0953	AG
.005	.127	Z

*Values truncated.

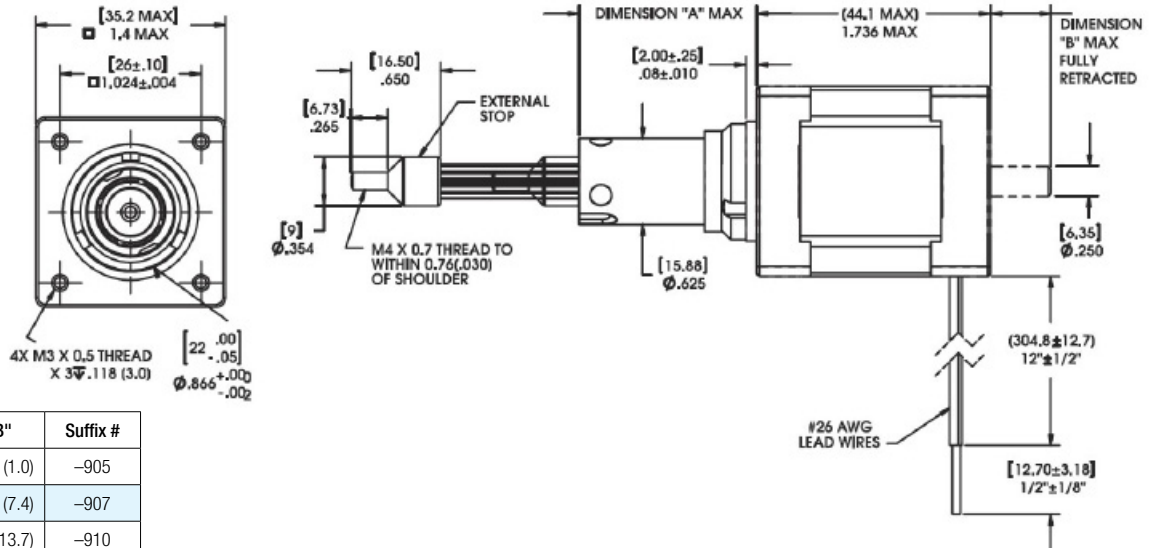
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



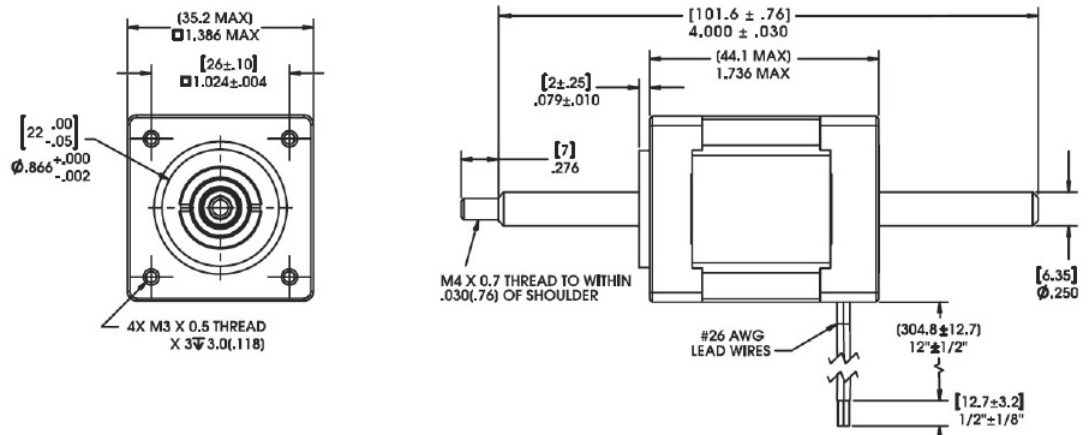
Stroke	Dim. "A"	Dim. "B"	Suffix #
0.500 (12.7)	0.82 (20.8)	0.04 (1.0)	-905
0.750 (19.05)	1.07 (27.2)	0.29 (7.4)	-907
1.000 (25.4)	1.32 (33.5)	0.54 (13.7)	-910
1.250 (31.8)	1.57 (39.9)	0.79 (20.1)	-912
1.500 (38.1)	1.82 (46.2)	1.04 (26.4)	-915
2.00 (50.8)	2.32 (58.9)	1.54 (39.1)	-920
2.500 (63.5)	2.82 (71.6)	2.04 (51.8)	-925

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

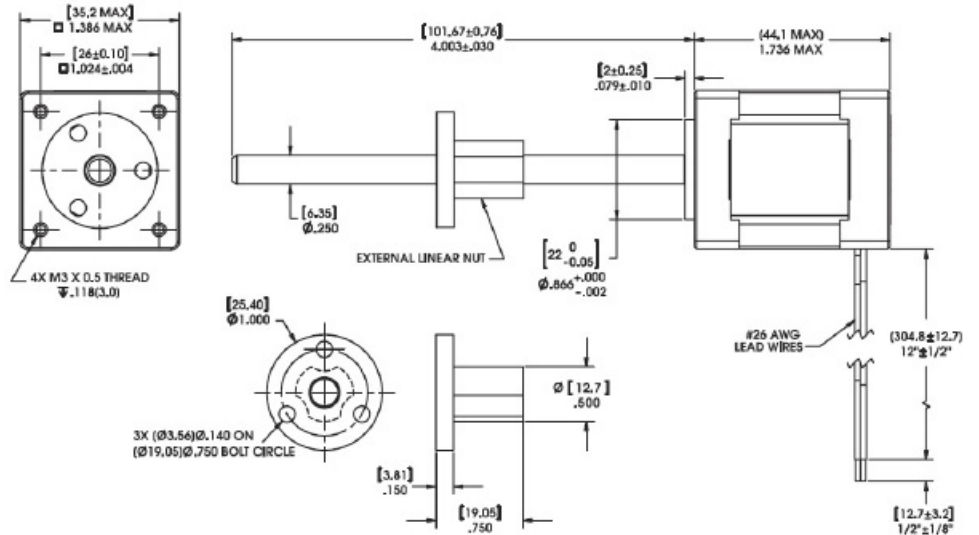


External Linear

Dimensions = (mm) inches

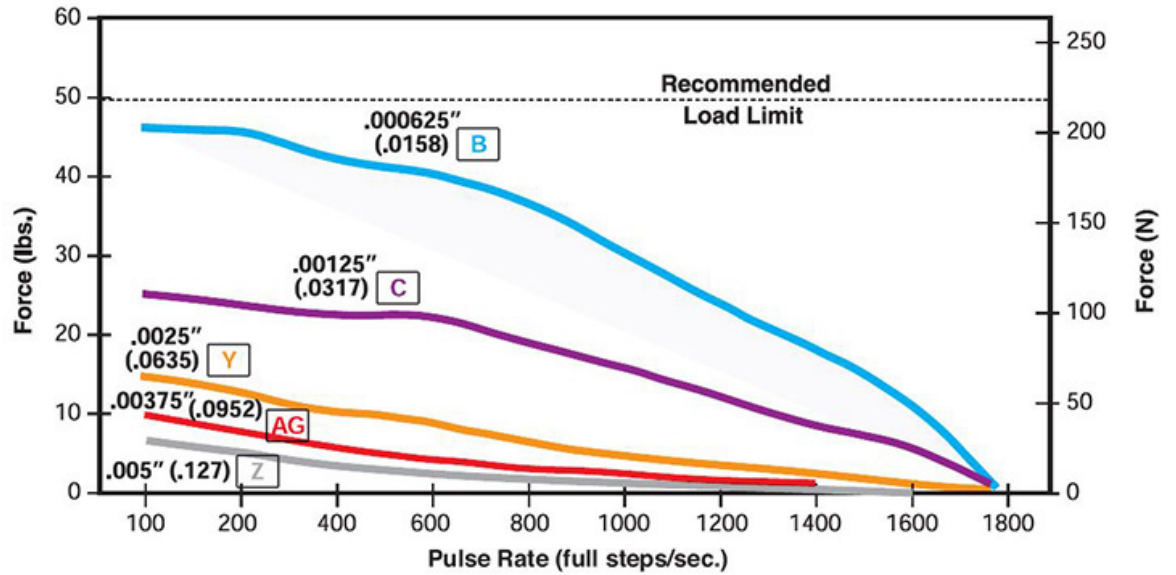
Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.



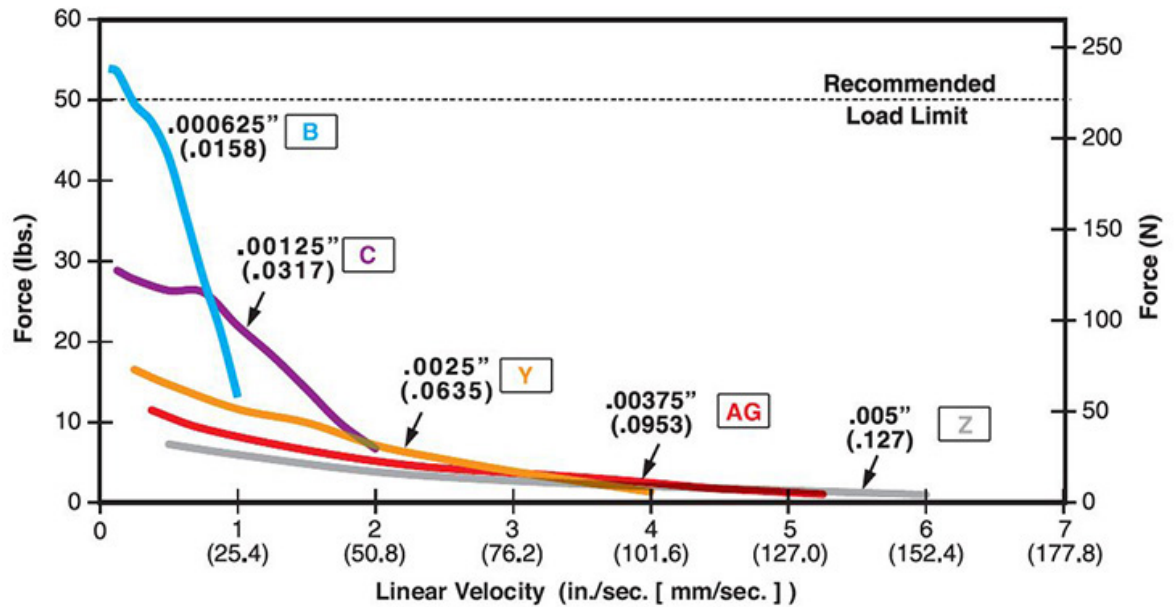
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .250 (6.35) Lead Screw



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

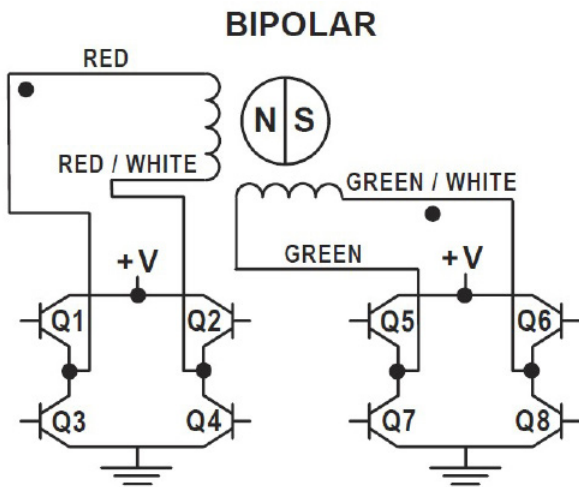
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	35	L	4	B	12	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 35 = 35000 (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step B = .000625-in (.0158) C = .00125-in (.0317) Y = .0025-in (.0635) AG = .00375-in (.0953) Z = .005-in (.127)	Voltage 2.33 = 2.33 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

EXTEND CW ↓ RETRACT CCW ↑

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

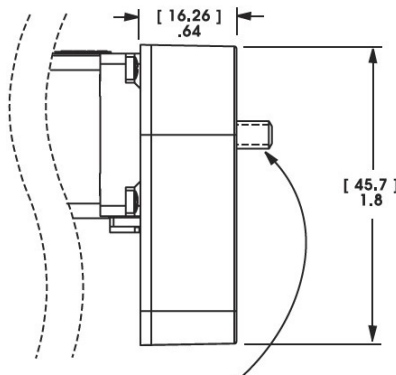
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 14 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 35000 Series Size 14



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 14	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 14	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
Size 14	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.
 Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 14			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 14

Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

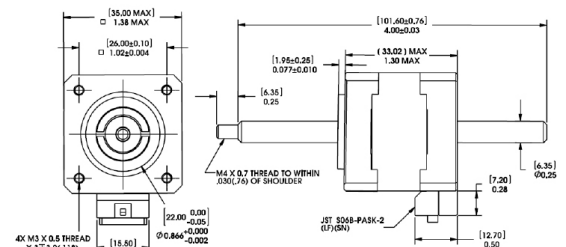
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



43000 Series Size 17 Hybrid Linear Actuators

Our best selling compact hybrid motors


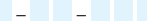



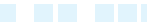
Top selling designs deliver high performance, opening avenues for equipment designers who previously settled for products with inferior performance and endurance.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 43000 Series is available in a wide variety of resolutions - from 0.00006-in. (.001524 mm) per step to 0.00192-in. (.048768 mm) per step, and delivers thrust of up to 50 lbs. (222 N), or speeds exceeding 3 inches (7.62 cm) per second.



Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)						
Part No.	Captive	43H4  †			43H6  †	
	Non-Captive	43F4  †			43F6  †	
	External Linear	E43H4  †			E43H6  †	
Wiring	Bipolar			Unipolar**		
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA	
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω	
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH	
Power Consumption	7 W					
Rotor Inertia	37 gcm ²					
Insulation Class	Class B (Class F available)					
Weight	8.5 oz (241 g)					
Insulation Resistance	20 MΩ					

†Part numbering information on page 110. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Linear Travel / Step Screw Ø .218" (5.54 mm)		Order Code I.D.
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step Screw Ø .250" (6.35 mm)		Order Code I.D.
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

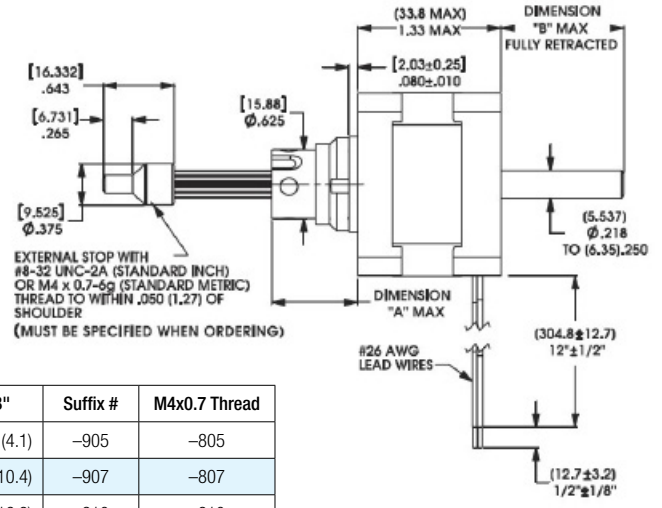
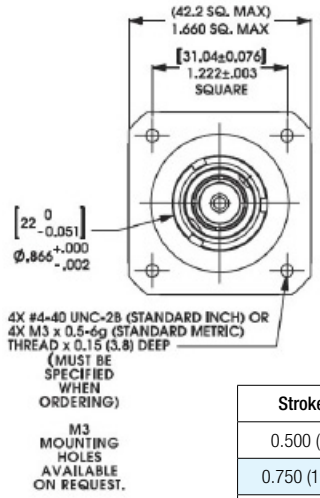
Standard motors are Class B rated for maximum temperature of 130°C. Also available, motors with high temperature capability windings up to 155°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



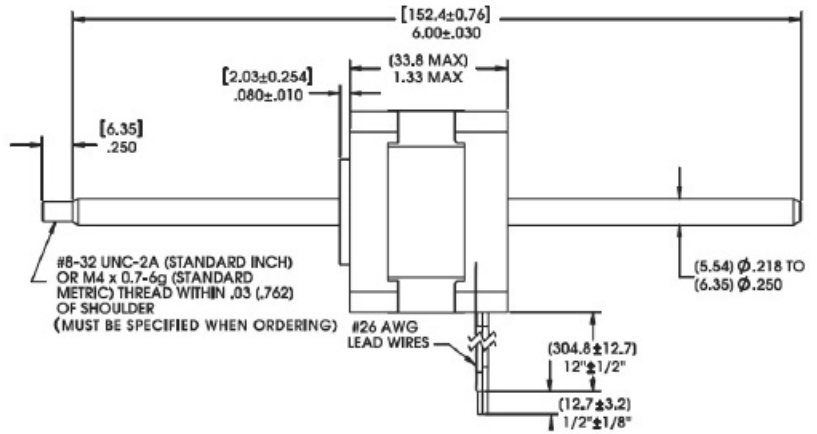
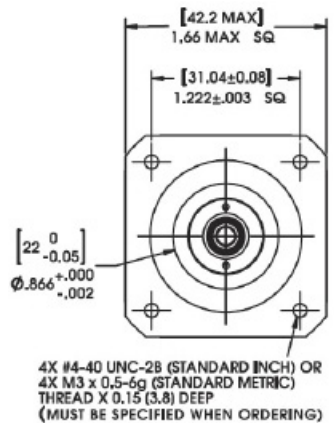
Stroke	Dim. "A"	Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0.16 (4.1)	-905	-805
0.750 (19.05)	1.03 (26.2)	0.41 (10.4)	-907	-807
1.000 (25.4)	1.28 (32.5)	0.66 (16.8)	-910	-810
1.250 (31.8)	1.53 (38.9)	0.91 (23.1)	-912	-812
1.500 (38.1)	1.78 (45.2)	1.16 (29.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	1.66 (42.2)	-920	-820
2.500 (63.5)	2.78 (70.6)	2.16 (54.9)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.

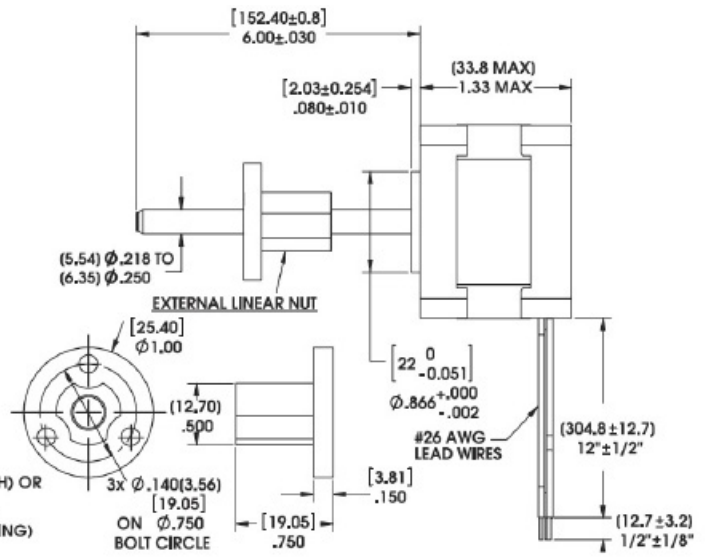
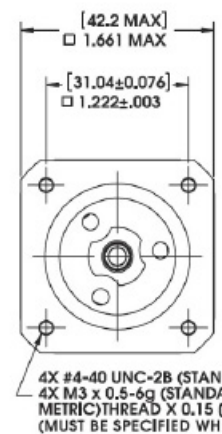


External Linear

Dimensions = (mm) inches

Integrated connector option available

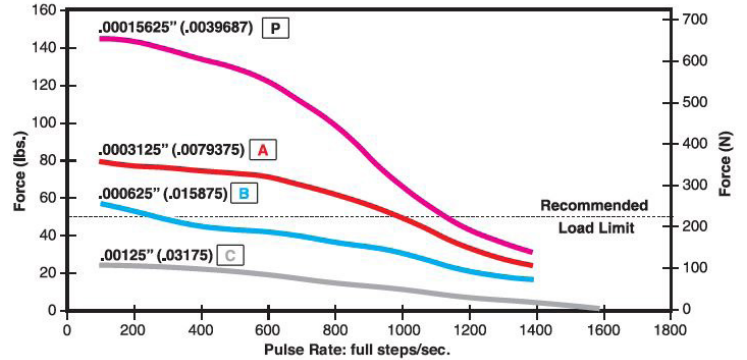
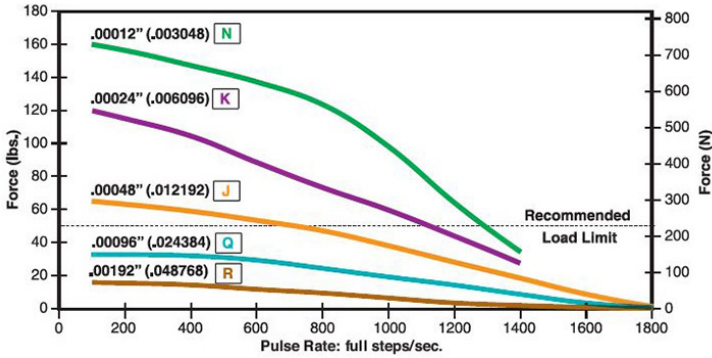
4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .218 (5.54) Lead Screw

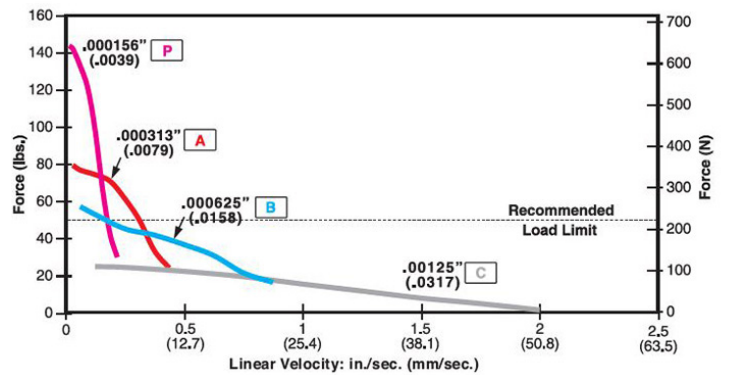
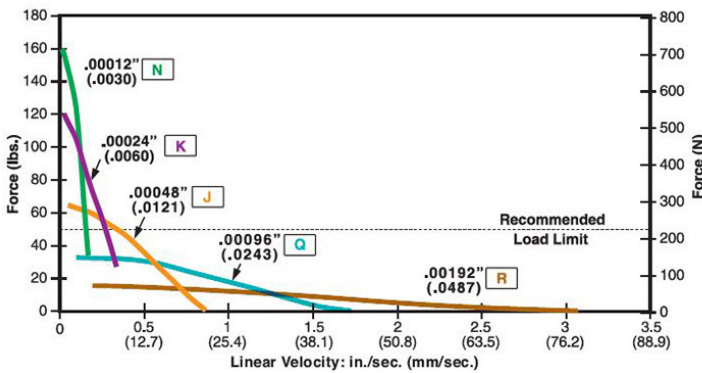
– Ø .250 (6.35) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .218 (5.54) Lead Screw

– Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.







Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

43000 Series

Size 17, 0.9° High Resolution Motor

The Size 17 High Resolution Actuator features a production-proven, patented rotor drive nut that delivers trouble-free, long-term performance.

Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (0.9° Step Angle)						
Part No.	Captive	43K4  †			43K6  †	
	Non-Captive	43J4  †			43J6  †	
	External Linear	E43K4  †			E43K6  †	
Wiring		Bipolar			Unipolar**	
Winding Voltage		2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase		1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω
Inductance/phase		2.6 mH	12 mH	70 mH	6 mH	35 mH
Power Consumption		7 W				
Rotor Inertia		37 gcm ²				
Insulation Class		Class B (Class F available)				
Weight		8.5 oz (241 g)				
Insulation Resistance		20 MΩ				

Linear Travel / Step		Order Code I.D.	
Screw Ø .218" (5.54 mm)			
inches	mm	U	
.00006	.0015*		
.00012	.0030*		N
.00024	.0060*		
.00048	.0121*		J
.00096	.0243*		

Linear Travel / Step		Order Code I.D.	
Screw Ø .250" (6.35 mm)			
inches	mm	V	
.000078*	.00198*		
.00015625	.0039*		P
.0003125	.0079*		
.000625	.0158*		A

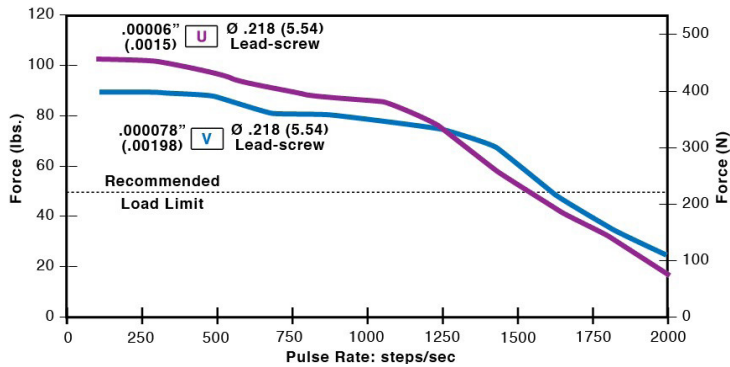
*Values truncated.

Standard motors are Class B rated for maximum temperature of 130°C.

NOTE: Refer to performance curves on previous page for codes N, K, J, Q, P, A, B

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
– 18:1 Motor Coil to Drive Supply Voltage
with two available lead screw diameters

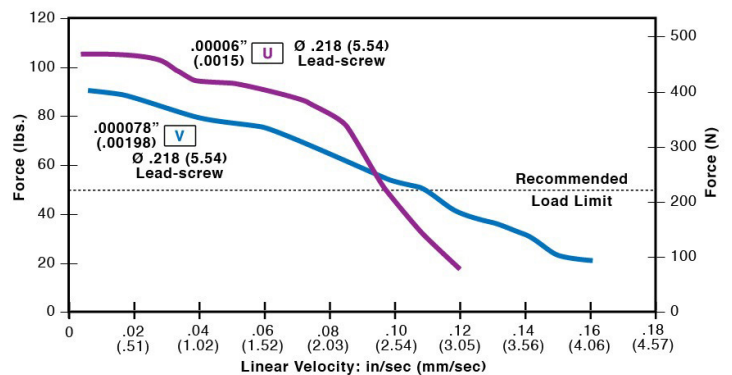


NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
– 18:1 Motor Coil to Drive Supply Voltage
with two available lead screw diameters



43000 Series Size 17 Hybrid Linear Actuators with integrated IDEA™ Drive

High performance in a compact package

The 43000 Series Single Stack actuator is available in a wide variety of resolutions – from 0.00006-in (.001524 mm) per step to 0.00192-in (.048768mm) per step. Delivers output force of up to 50 lbs (220N), or speeds exceeding 3 inches (7.62 cm) per second.

43000 Series with IDEA™ Drive features:

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability: Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

3 Available Designs

- Captive – Non-Captive – External Linear



NOTE: For more information see the Haydon Kerk IDEA™ Drive Data Sheet.

Size 17 Single Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)			
		RS-485*	USB**
Part No.	Captive	43HJ – [] – [] †	43HG – [] – [] †
	Non-Captive	43FJ – [] – [] †	43FG – [] – [] †
	External Linear	E43HJ – [] – [] †	E43HG – [] – [] †
Wiring		Bipolar	
Winding Voltage		2.33 VDC***	

†Part numbering information on page 113.

*Complementary RS-485 based drive ** USB-based IDEA drive ***Contact Haydon Kerk if a higher voltage motor is desired. Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

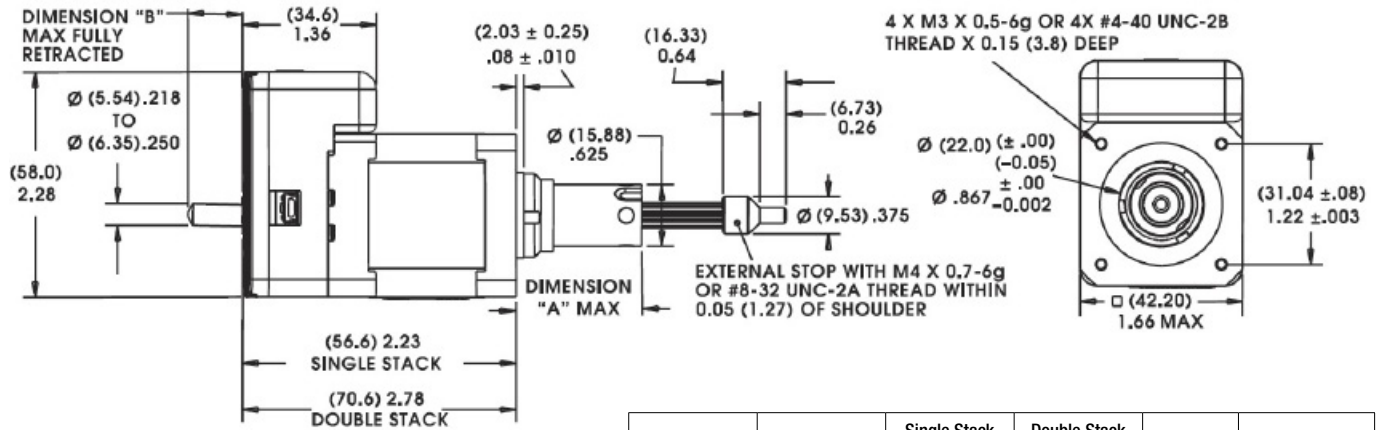
Simple to use IDEA™ Drive software with on-screen buttons and easy-to-understand programming guides

Software program generates motion profiles directly into the system and also contains a “debug” utility allowing line-by-line execution of a motion program for easy troubleshooting.



Captive Lead Screw

Dimensions = (mm) inches

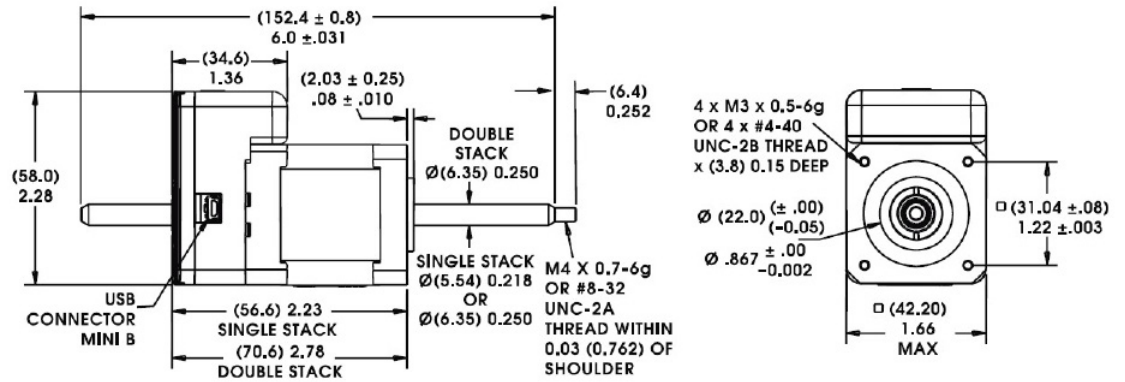


Stroke	Dim. "A"	Single Stack Dim. "B"	Double Stack Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0	0	-905	-805
0.750 (19.05)	1.03 (26.2)	0	0	-907	-807
1.000 (25.4)	1.28 (32.5)	0	0	-910	-810
1.250 (31.8)	1.53 (38.9)	0	0	-912	-812
1.500 (38.1)	1.78 (45.2)	0.232 (5.9)	0.091 (2.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	0.732 (18.6)	0.591 (15.0)	-920	-820
2.500 (63.5)	2.78 (70.6)	1.232 (31.3)	1.091 (27.7)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

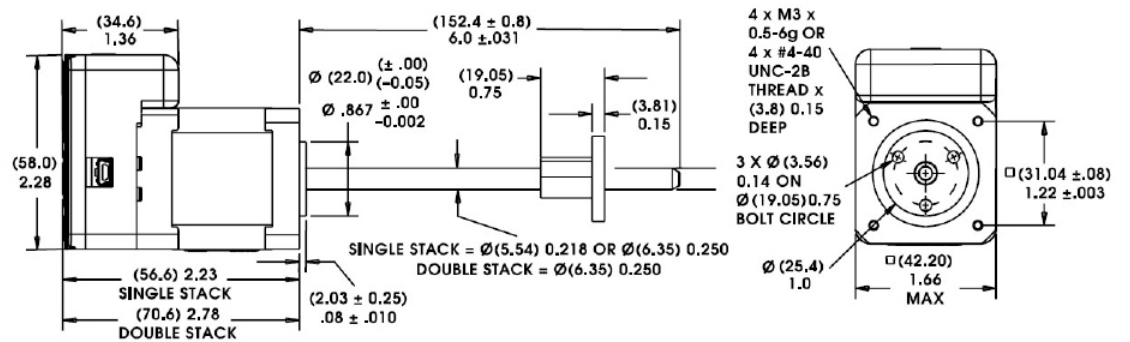
Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.



External Linear

Dimensions = (mm) inches

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

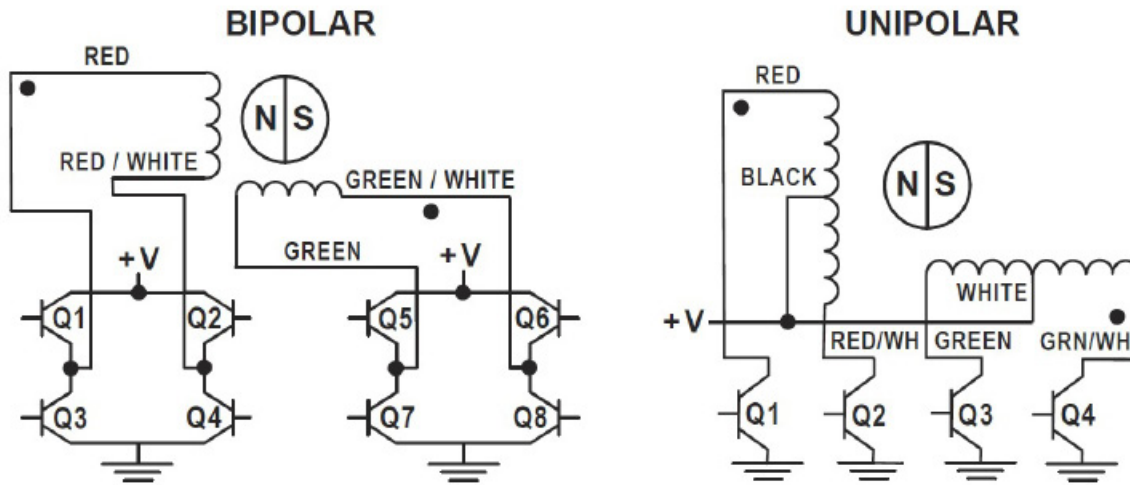


Identifying the Hybrid Part Number Codes when Ordering

E	43	H	6	N	2.33	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 43 = 43000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version) J = 0.9° Non-captive K = 0.9° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire) G = IDEA Drive (Size 17, 43000 Series, Bipolar only)	Code ID Resolution Travel/Step N = .00012-in (.0030) K = .00024-in (.0060) J = .00048-in (.0121) Q = .00096-in (.0243) P = .0015625-in (.0039) A = .003125-in (.0079) B = .00625-in (.0158) C = .0125-in (.0317) R = .0192-in (.0478) High Resolution U = .00006-in (.0015) V = .000078-in (.00198)	Voltage 2.33 = 2.33 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

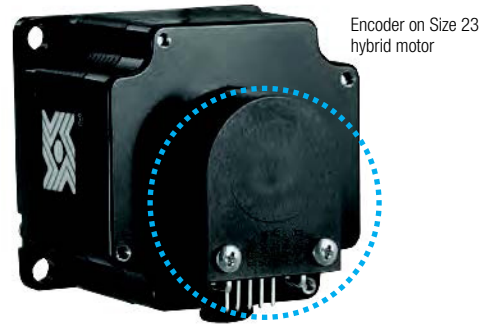
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

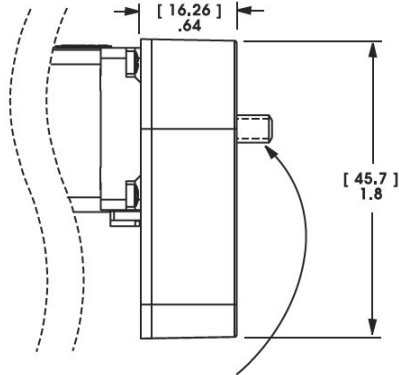
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 17 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 43000 Series Size 17



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 17

Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature

Size 17	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)

Size 17	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available. Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 17

Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 17

Hybrid Size 17 linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

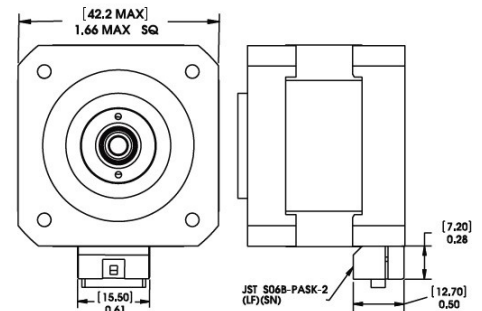
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



43000 Series Double Stack Size 17 Hybrid Linear Actuators

Exceptional performance and new linear motion design opportunities

The 43000 Series is available in a wide variety of resolutions from 0.000625-in (.0158 mm) per step to 0.005-in (.127 mm) per step. The motors can also be microstepped for even finer resolutions. The Size 17 Double Stack actuator delivers thrust of up to 75 lbs. (337 N).

3 Available Designs

- Captive
- Non-Captive
- External Linear



Size 17 Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	43M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	Non-Captive	43L4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	External Linear	E43M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
Wiring		Bipolar	
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.6 A	1.3 A	550 mA
Resistance/phase	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.33 mH	8.21 mH	45.1 mH
Power Consumption	13.2 W		
Rotor Inertia	78 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	12.5 oz (352 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 120.

Linear Travel / Step		Order Code I.D.
Screw Ø.1875" (4.76mm)		
inches	mm	
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635	Y
.00375	.0953	AG
.005	.127	Z

*Values truncated.

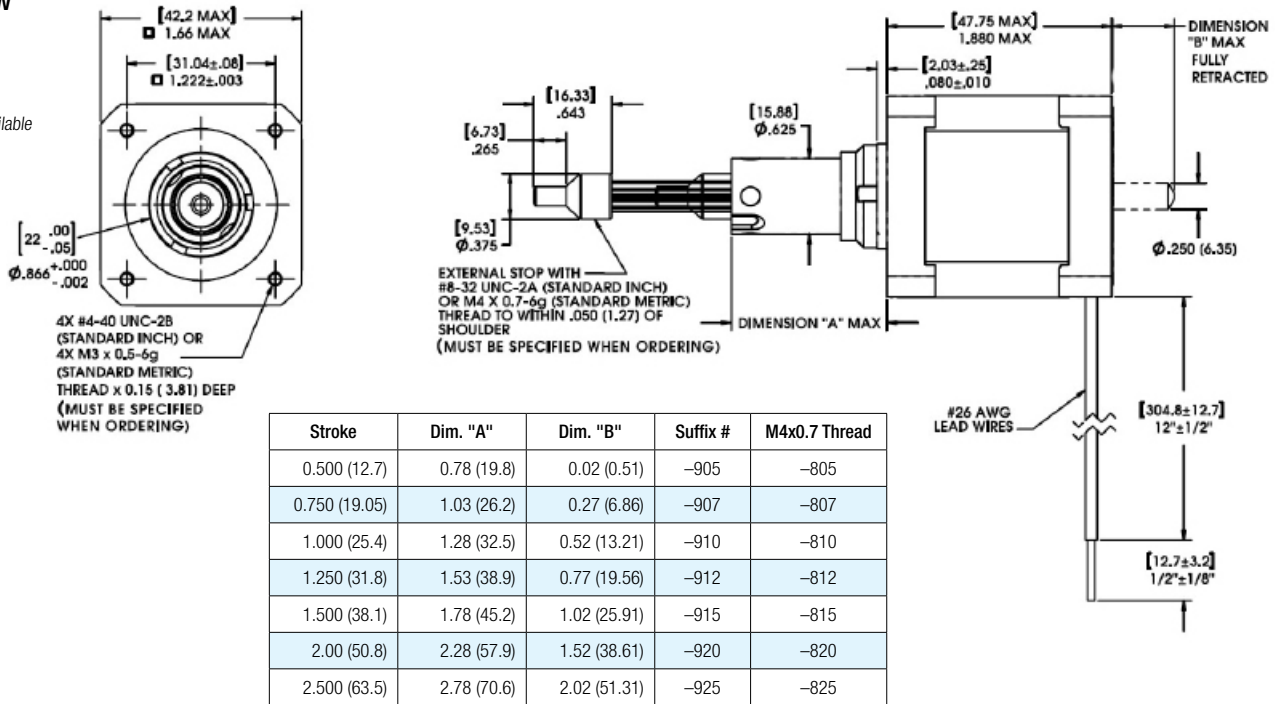
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

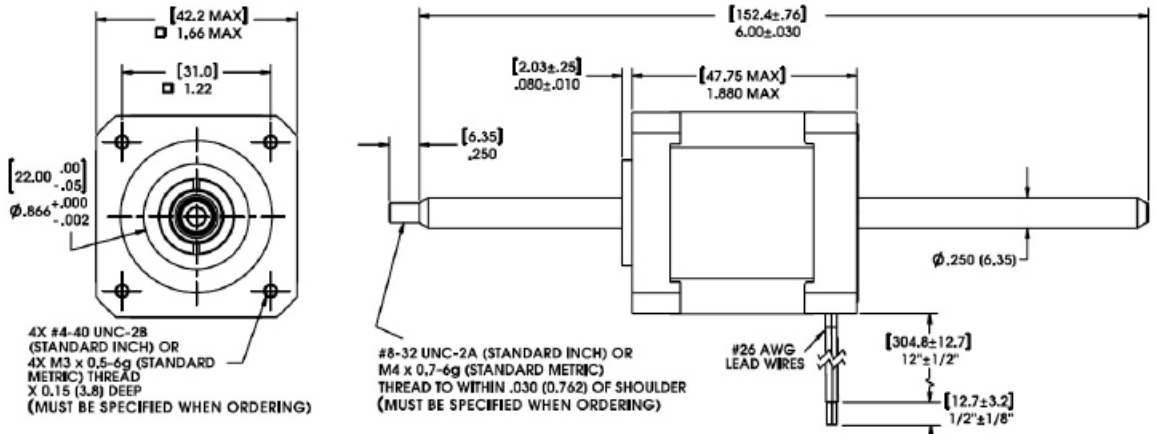


Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.

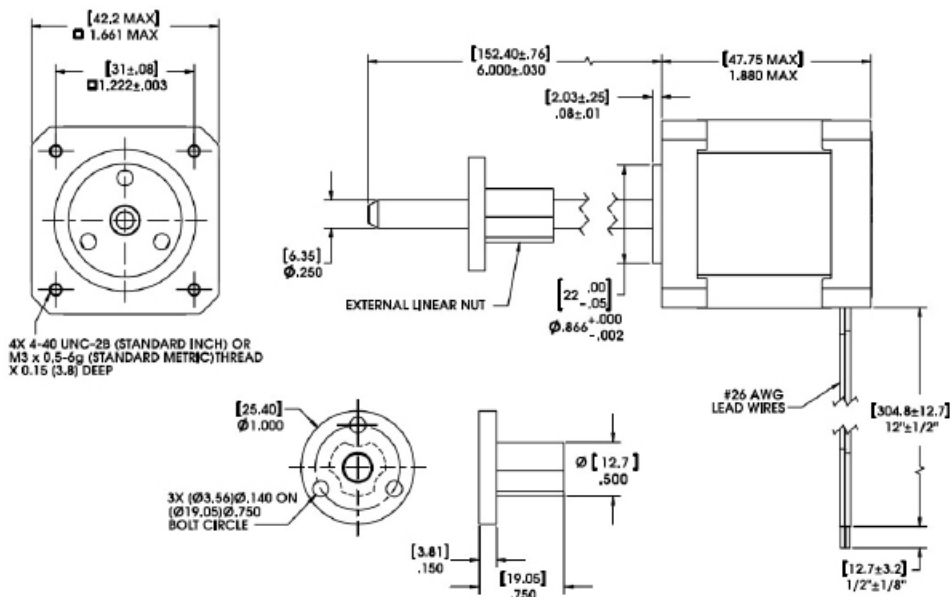


External Linear

Dimensions = (mm) inches

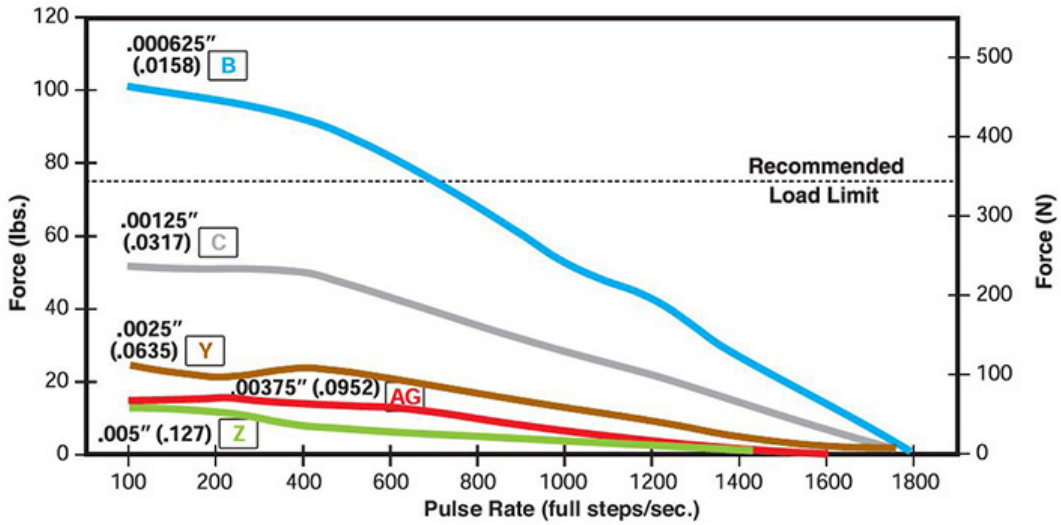
Integrated connector option available

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



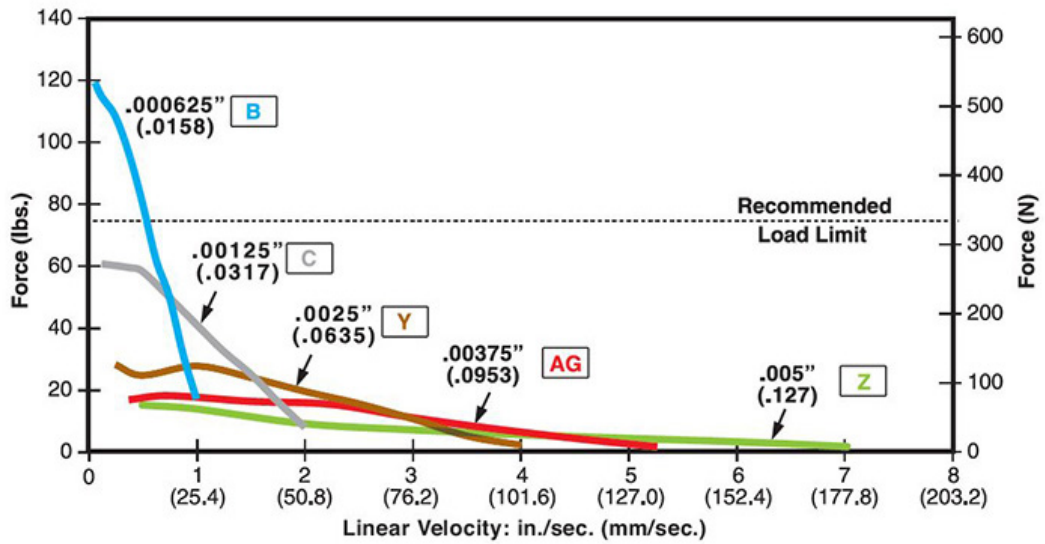
FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .250 (6.35) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

43000 Series Size 17 Double Stack Hybrid Linear Actuators with integrated IDEA™ Drive

High performance in a compact package

The 43000 Series Double Stack actuator is available in a wide variety of resolutions – from 0.000625-in (.0158 mm) per step to 0.005-in (.127 mm) per step. Delivers output force of up to 75 lbs (337N).

43000 Series with IDEA™ Drive features:

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability: Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

3 Available Designs

- Captive – Non-Captive – External Linear



Size 17
Captive Shaft

Size 17
Non-Captive Shaft

Size 17
External Linear

Size 17 Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)			
		RS-485*	USB**
Part No.	Captive	43MJ – [] – [] †	43MG – [] – [] †
	Non-Captive	43LJ – [] – [] †	43LG – [] – [] †
	External Linear	E43MJ – [] – [] †	E43MG – [] – [] †
Wiring		Bipolar	
Winding Voltage		2.33 VDC***	

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635*	Y
.00375	.0953*	AG
.005	.127*	Z

†Part numbering information on page 120.

*Complimentary complementary RS-485 based drive ** USB-based IDEA drive ***Contact Haydon Kerk if a higher voltage motor is desired. Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

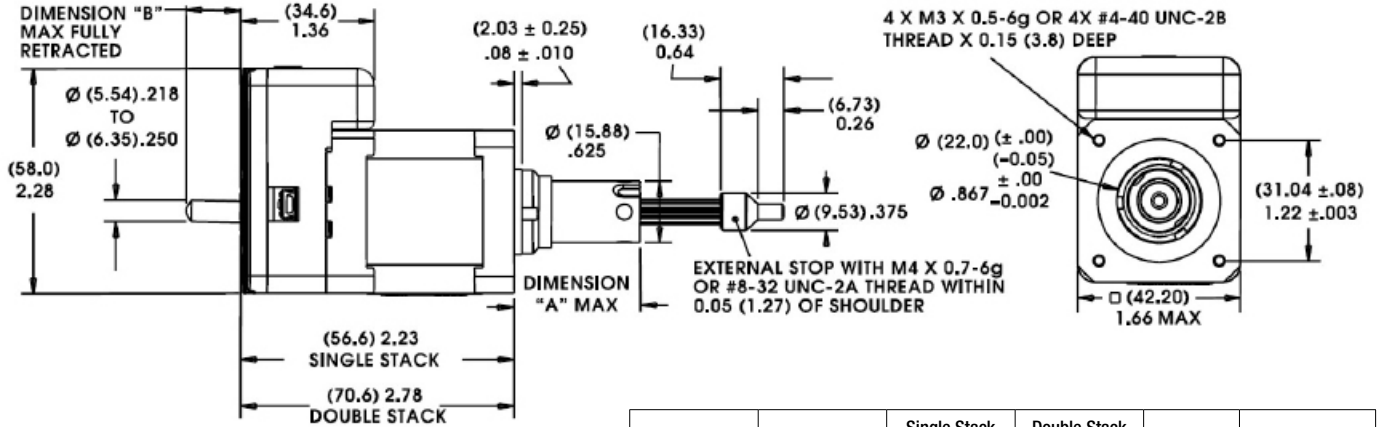
Simple to use IDEA™ Drive software with on-screen buttons and easy-to-understand programming guides

Software program generates motion profiles directly into the system and also contains a “debug” utility allowing line-by-line execution of a motion program for easy troubleshooting.



Captive Lead Screw

Dimensions = (mm) inches

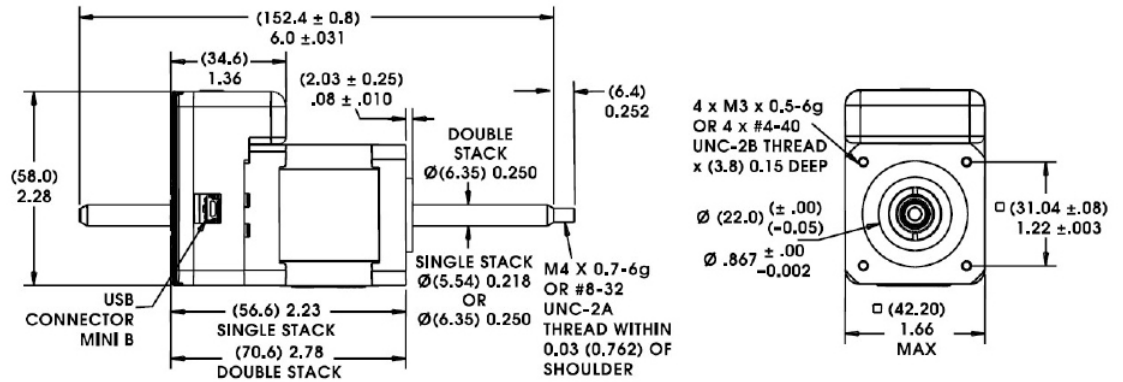


Stroke	Dim. "A"	Single Stack Dim. "B"	Double Stack Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0	0	-905	-805
0.750 (19.05)	1.03 (26.2)	0	0	-907	-807
1.000 (25.4)	1.28 (32.5)	0	0	-910	-810
1.250 (31.8)	1.53 (38.9)	0	0	-912	-812
1.500 (38.1)	1.78 (45.2)	0.232 (5.9)	0.091 (2.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	0.732 (18.6)	0.591 (15.0)	-920	-820
2.500 (63.5)	2.78 (70.6)	1.232 (31.3)	1.091 (27.7)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

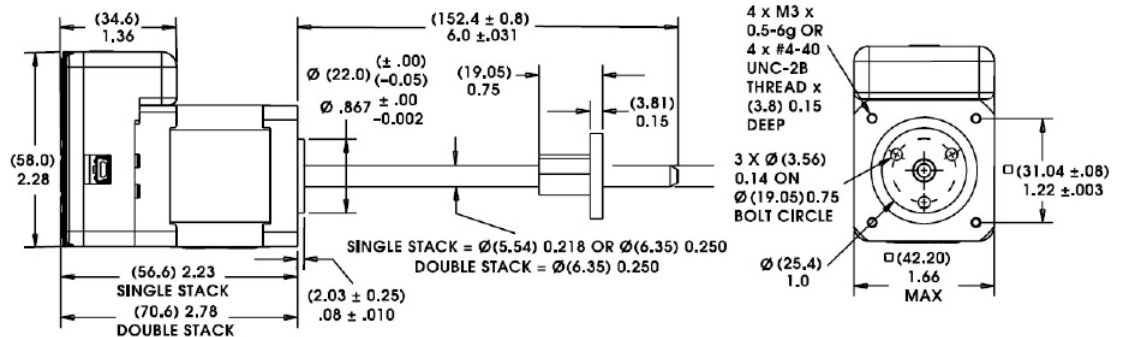
Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.



External Linear

Dimensions = (mm) inches

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

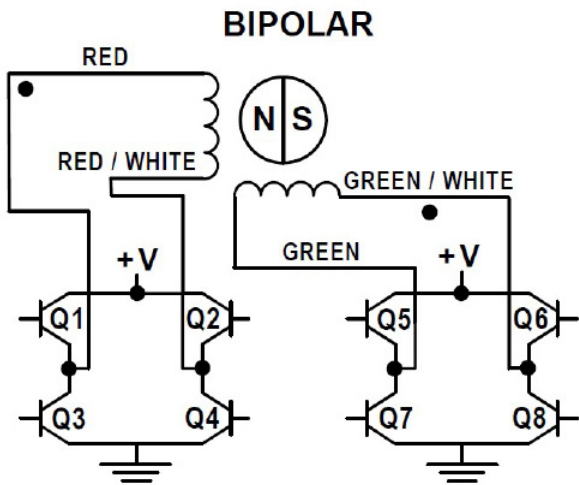


Identifying the Hybrid Part Number Codes when Ordering

E	43	M	G	C	2.33	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 43 = 43000 (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) G = IDEA Drive (Size 17, 43000 Series, Bipolar only)	Code ID Resolution Travel/Step B = .000625-in (.0158) C = .00125-in (.0317) Y = .0025-in (.0635) AG = .00375-in (.0953) Z = .005-in (.127)	Voltage 2.33 = 2.33 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

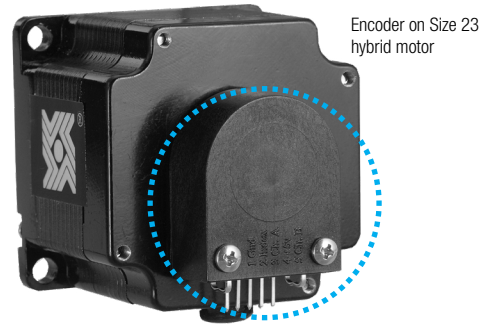
EXTEND CW ↓ ↑ RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

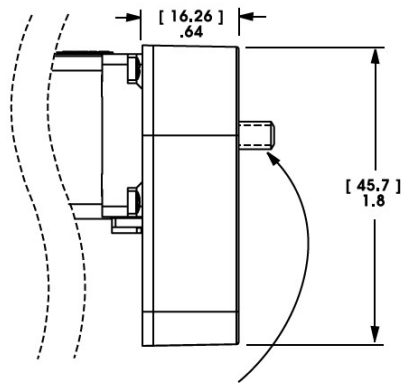
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 17 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



30 mm 43000 Series Size 17

NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.



Differential Ended Encoder - Pinout - Size 17

Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature

Size 17	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)

Size 17	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.
 Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 17

Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 17

Hybrid Size 17 linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

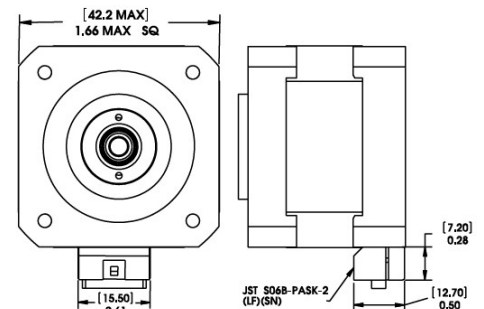
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



MAX Series

30% performance increase compared to standard Size 17

M43000 MAX Series Single Stack Size 17 Max Hybrid Linear Actuators

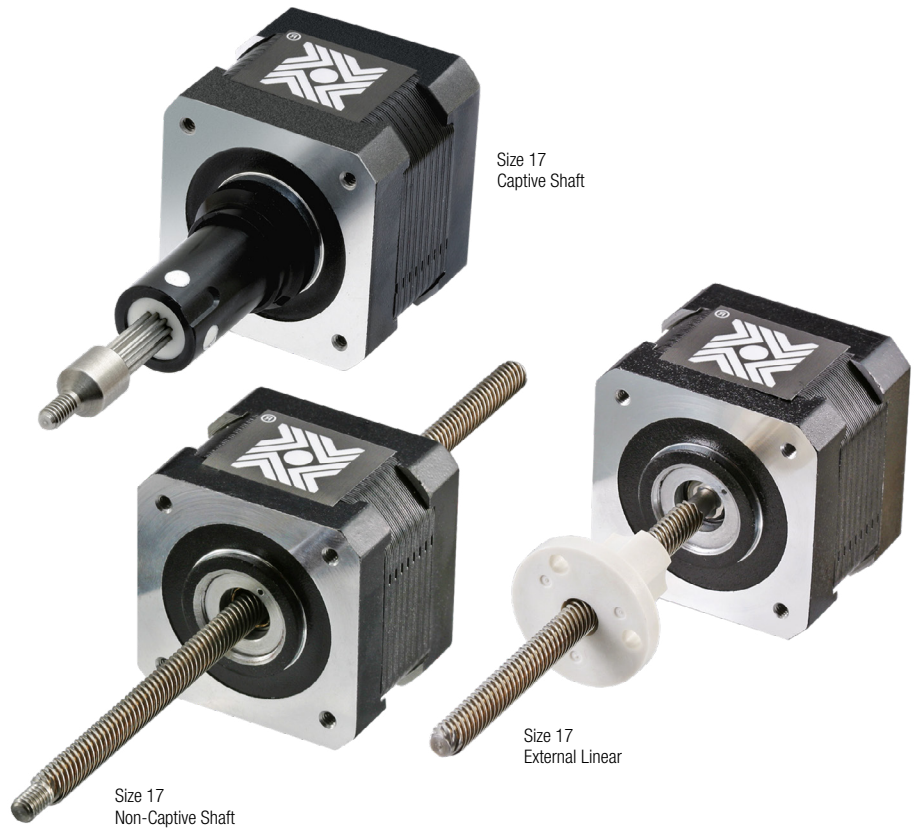
Our best selling compact hybrid motors, now with 30% performance increase

Top selling designs deliver high performance, opening avenues for equipment designers who previously settled for products with inferior performance and endurance.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The M43000 Max Series is available in a wide variety of resolutions - from 0.00006-in. (.001524 mm) per step to 0.00192-in. (.048768 mm) per step, and delivers thrust of up to 50 lbs. (222 N), or speeds exceeding 3 inches (7.62 cm) per second.



Size 17 Max: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)					
Part No.	Captive	M43H4 - - - - - †		M43H6 - - - - - †	
	Non-Captive	M43F4 - - - - - †		M43F6 - - - - - †	
	External Linear	EM43H4 - - - - - †		EM43H6 - - - - - †	
Wiring	Bipolar			Unipolar**	
Winding Voltage	2.8 VDC	5.8 VDC	13.8 VDC	5.8 VDC	13.8 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.77 Ω	8.3 Ω	47.6 Ω	8.3 Ω	47.6 Ω
Inductance/phase	2.45 mH	13.5 mH	88.0 mH	6.75 mH	44.0 mH
Power Consumption	8 W				
Rotor Inertia	37.1 gcm ²				
Temperature Rise	135° F Rise (70° C Rise)				
Insulation Class	Class B (Class F available)				
Weight	9 oz (255 g)				
Insulation Resistance	20 MΩ				

Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

Standard motors are Class B rated for maximum temperature of 130°C. Also available, motors with high temperature capability windings up to 155°C.

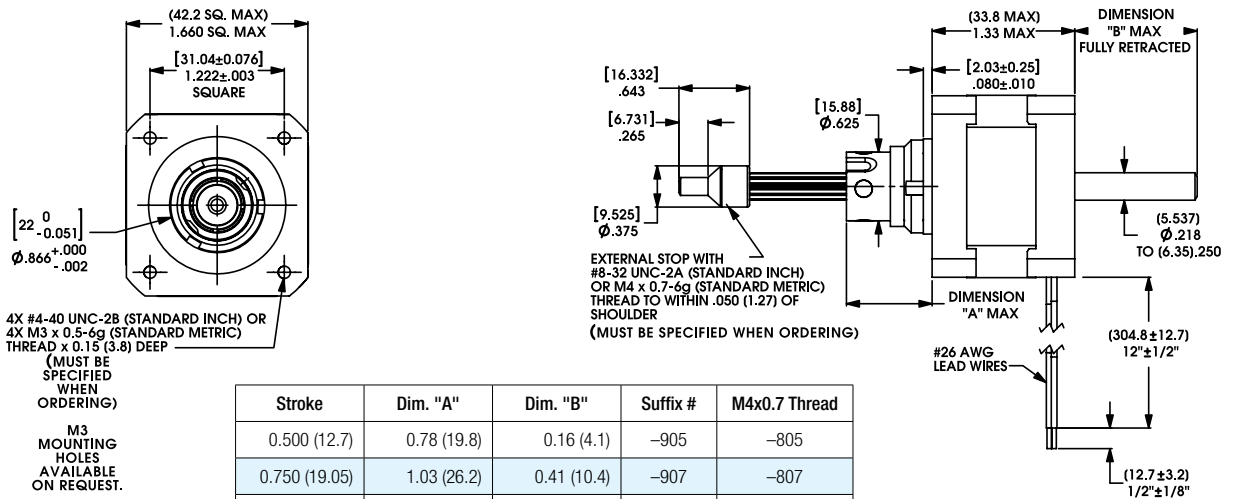
†Part numbering information on page 7. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



Stroke	Dim. "A"	Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0.16 (4.1)	-905	-805
0.750 (19.05)	1.03 (26.2)	0.41 (10.4)	-907	-807
1.000 (25.4)	1.28 (32.5)	0.66 (16.8)	-910	-810
1.250 (31.8)	1.53 (38.9)	0.91 (23.1)	-912	-812
1.500 (38.1)	1.78 (45.2)	1.16 (29.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	1.66 (42.2)	-920	-820
2.500 (63.5)	2.78 (70.6)	2.16 (54.9)	-925	-825

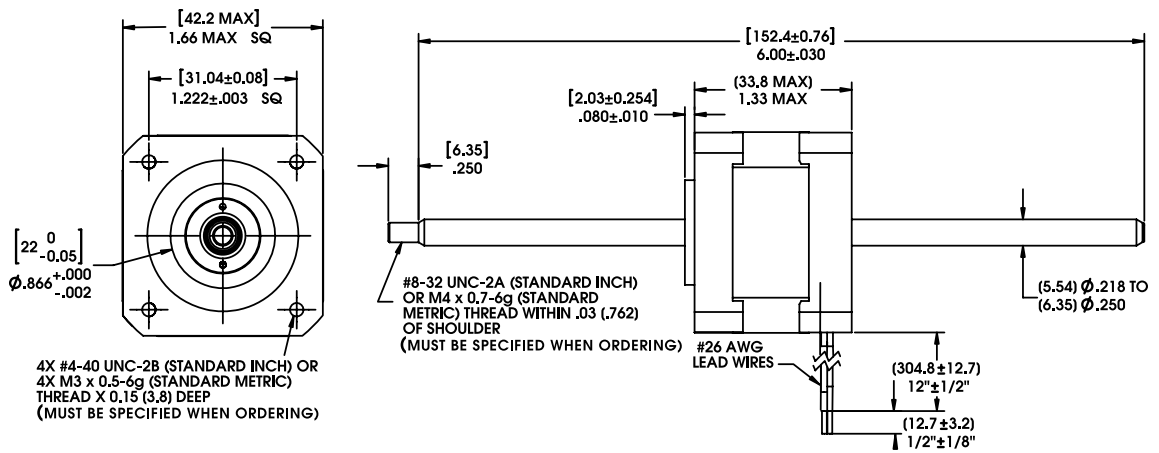
4X #4-40 UNC-2B (STANDARD INCH) OR 4X M3 x 0.5-6g (STANDARD METRIC) THREAD x 0.15 (3.8) DEEP (MUST BE SPECIFIED WHEN ORDERING)
M3 MOUNTING HOLES AVAILABLE ON REQUEST.

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



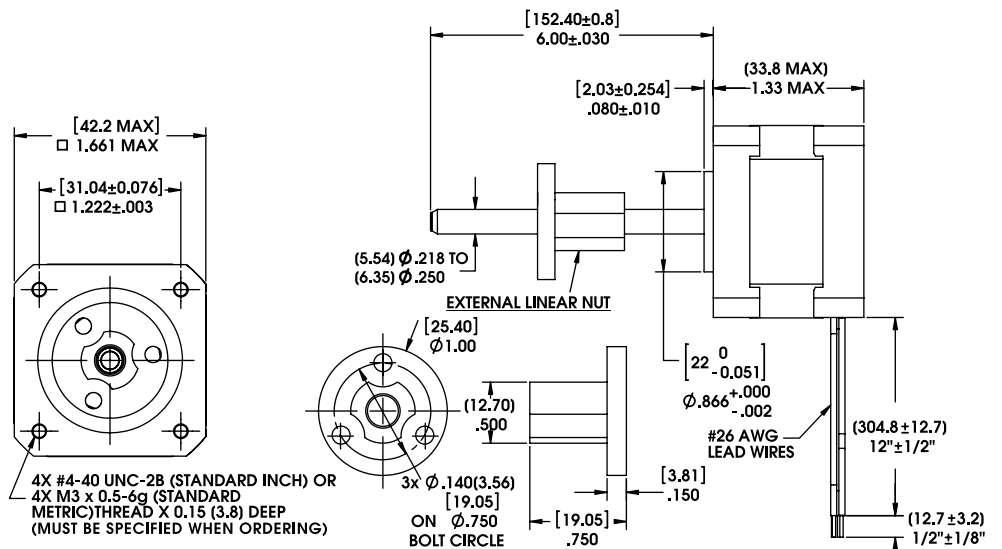
4X #4-40 UNC-2B (STANDARD INCH) OR 4X M3 x 0.5-6g (STANDARD METRIC) THREAD x 0.15 (3.8) DEEP (MUST BE SPECIFIED WHEN ORDERING)

External Linear

Dimensions = (mm) inches

Integrated connector option available

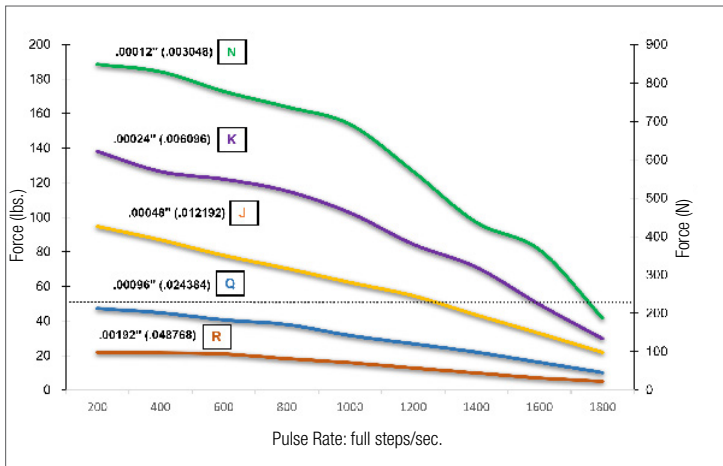
4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



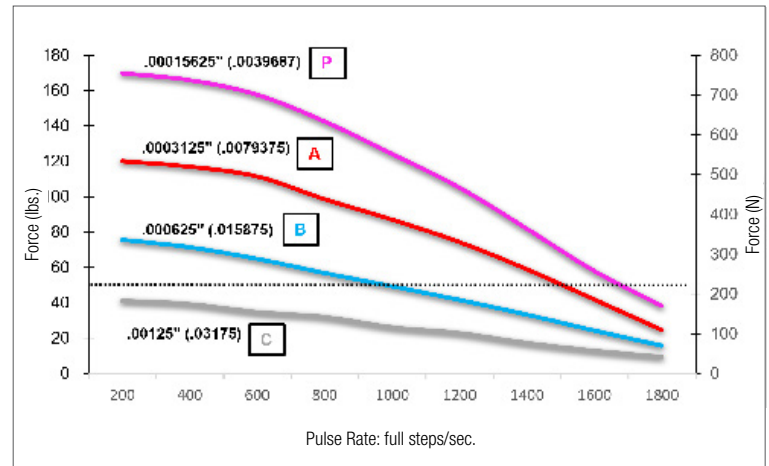
4X #4-40 UNC-2B (STANDARD INCH) OR 4X M3 x 0.5-6g (STANDARD METRIC) THREAD x 0.15 (3.8) DEEP (MUST BE SPECIFIED WHEN ORDERING)
3x Ø.140(3.56) ON Ø.750 BOLT CIRCLE

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .218 (5.54) Lead Screw

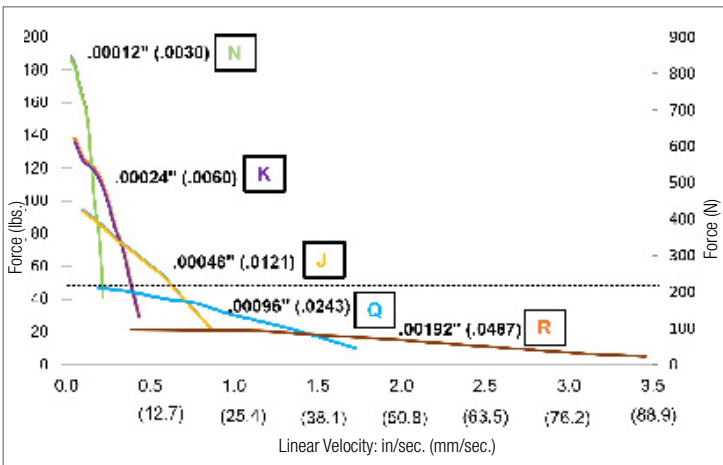


– Ø .250 (6.35) Lead Screw

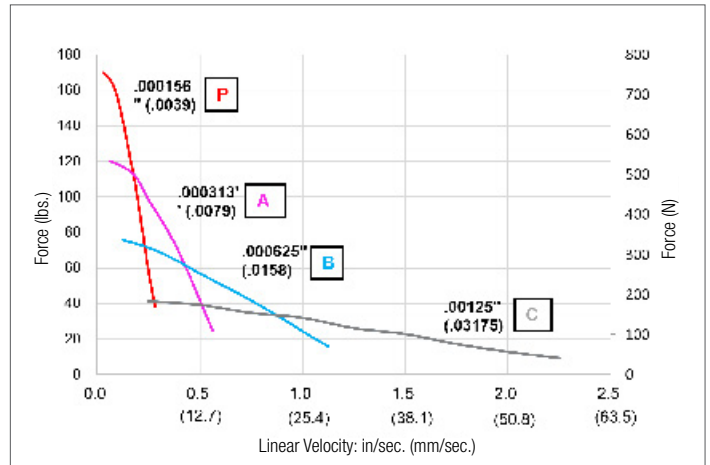


FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage

– Ø .218 (5.54) Lead Screw



– Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5.8 volt, 1/2 microstepping motor and a 40 volt power supply.







Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

M43000 Series

Size 17, 0.9° High Resolution Motor

The Size 17 Max High Resolution Actuator features a production-proven, patented rotor drive nut that delivers trouble-free, long-term performance.

Size 17 Max: 43 mm (1.7-in) Hybrid Linear Actuator (0.9° Step Angle)					
Part No.	Captive	M43K4  †		M43K6  †	
	Non-Captive	M43J4  †		M43J6  †	
	External Linear	EM43K4  †		EM43K6  †	
Wiring	Bipolar			Unipolar**	
Winding Voltage	2.8 VDC	5.8 VDC	13.8 VDC	5.8 VDC	13.8 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.77 Ω	8.3 Ω	47.6 Ω	8.3 Ω	47.6 Ω
Inductance/phase	3.2 mH	17.7 mH	116.2 mH	8.85 mH	58.1.0 mH
Power Consumption	8 W				
Rotor Inertia	37.1 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	9 oz (241 g)				
Insulation Resistance	20 MΩ				

†Part numbering information on page 7. **Unipolar drive gives approximately 30% less thrust than bipolar drive.

Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	U
.00006	.0015*	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	V
.000078*	.00198*	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B

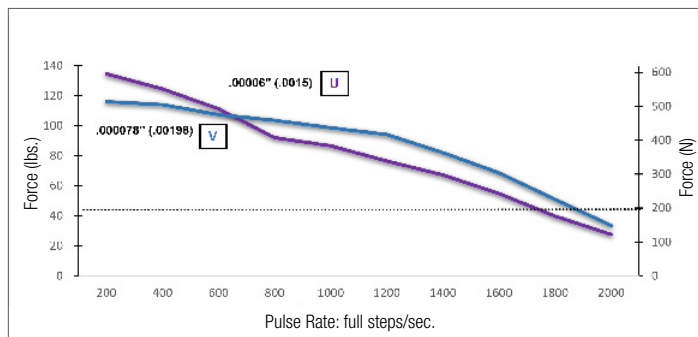
*Values truncated.

Standard motors are Class B rated for maximum temperature of 130°C.

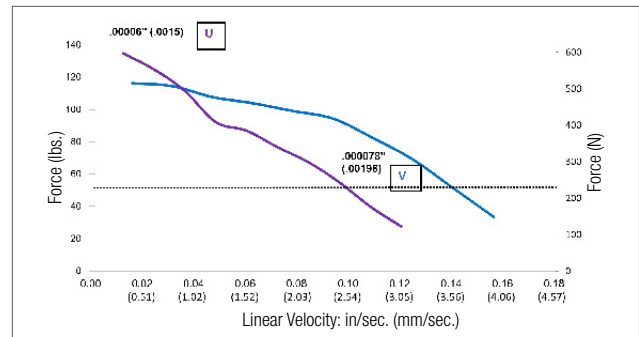
NOTE: Refer to performance curves on page 3 for codes N, K, J, Q, P, A, B

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
– 8:1 Motor Coil to Drive Supply Voltage
with two available lead screw diameters



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
– 8:1 Motor Coil to Drive Supply Voltage
with two available lead screw diameters



NOTE: All chopper drive curves were created with a 5.8 volt, 1/2 microstepping motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

M43000 MAX Series Size 17 Hybrid Linear Actuators with integrated IDEA™ Drive

High performance in a compact package

The M43000 Max Series Single Stack actuator is available in a wide variety of resolutions – from 0.00006-in (.001524 mm) per step to 0.00192-in (.048768mm) per step. Delivers output force of up to 50 lbs (220N), or speeds exceeding 3 inches (7.62 cm) per second.

M43000 Max Series with IDEA™ Drive features:

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability: Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

3 Available Designs

- Captive – Non-Captive – External Linear



NOTE: For more information see the Haydon Kerk IDEA™ Drive Data Sheet.

Size 17 Single Stack Max: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)		
Part No.	Captive	M43HG – – – – – †
	Non-Captive	M43FG – – – – – †
	External Linear	EM43HG – – – – – †
Wiring	Bipolar	
Winding Voltage	2.8 VDC**	

†Part numbering information on page 7. **Contact Haydon Kerk if a higher voltage motor is desired. Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

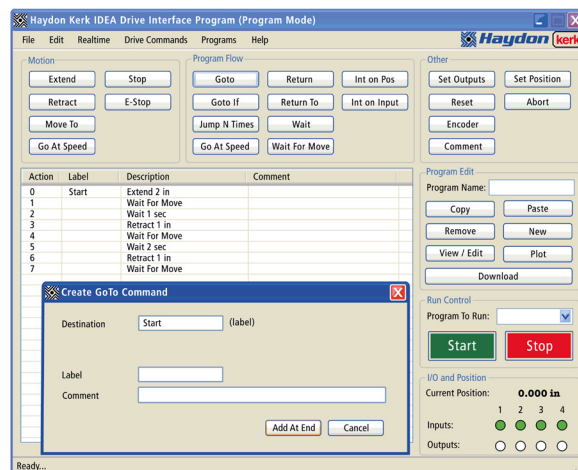
Linear Travel / Step		Order Code I.D.
Screw Ø .218" (5.54 mm)		
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

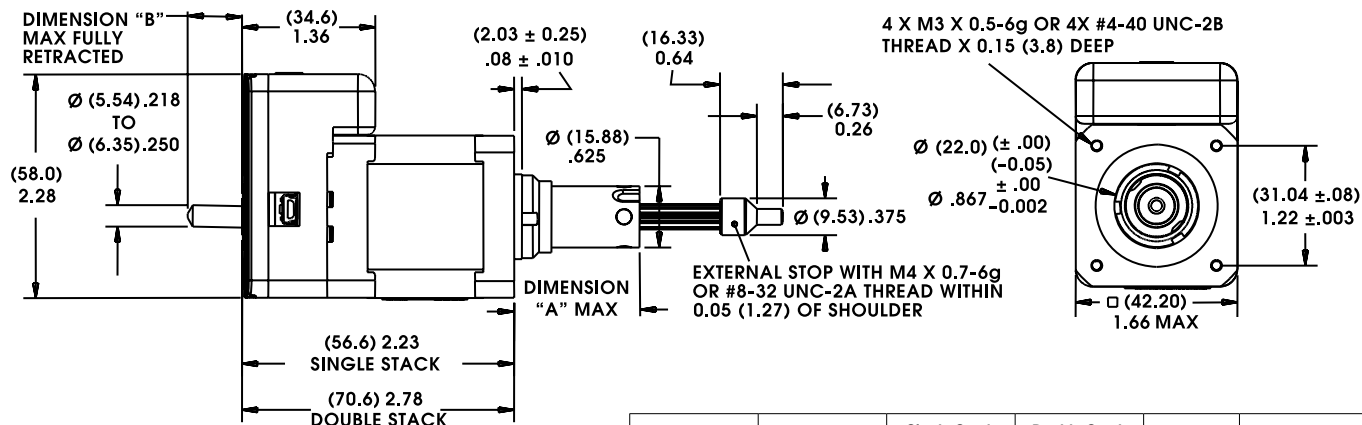
Simple to use IDEA™ Drive software with on-screen buttons and easy-to-understand programming guides

Software program generates motion profiles directly into the system and also contains a “debug” utility allowing line-by-line execution of a motion program for easy troubleshooting.



Captive Lead Screw

Dimensions = (mm) inches

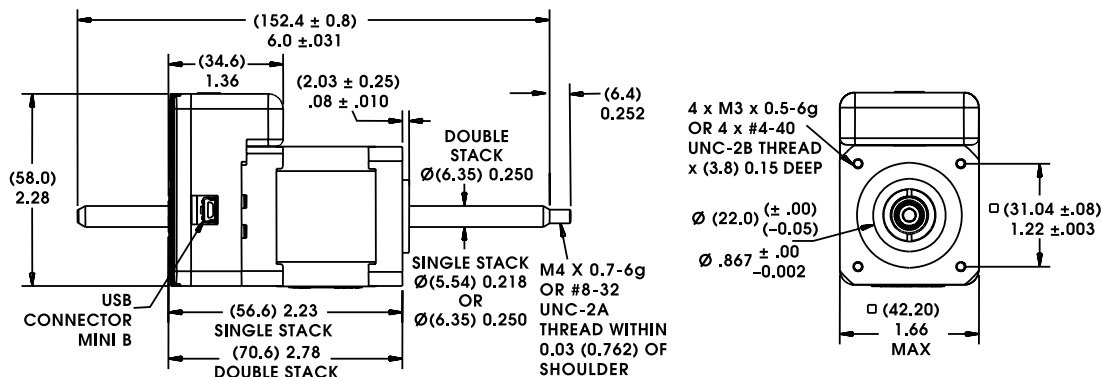


Stroke	Dim. "A"	Single Stack Dim. "B"	Double Stack Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0	0	-905	-805
0.750 (19.05)	1.03 (26.2)	0	0	-907	-807
1.000 (25.4)	1.28 (32.5)	0	0	-910	-810
1.250 (31.8)	1.53 (38.9)	0	0	-912	-812
1.500 (38.1)	1.78 (45.2)	0.232 (5.9)	0.091 (2.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	0.732 (18.6)	0.591 (15.0)	-920	-820
2.500 (63.5)	2.78 (70.6)	1.232 (31.3)	1.091 (27.7)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

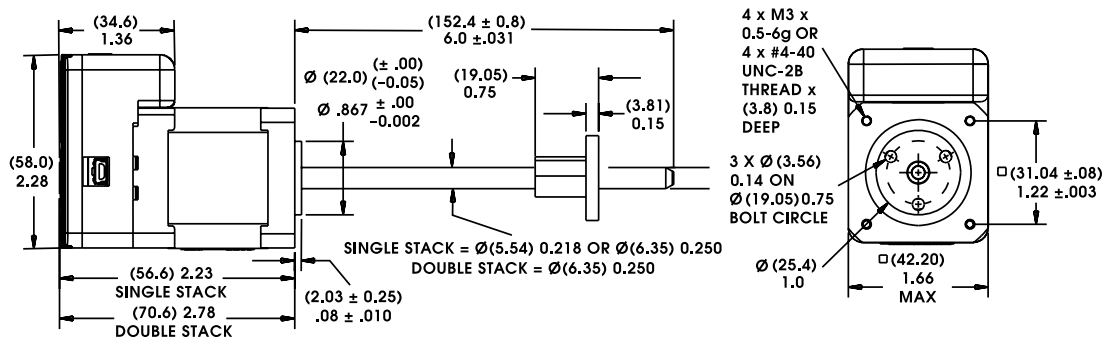
Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.



External Linear

Dimensions = (mm) inches

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

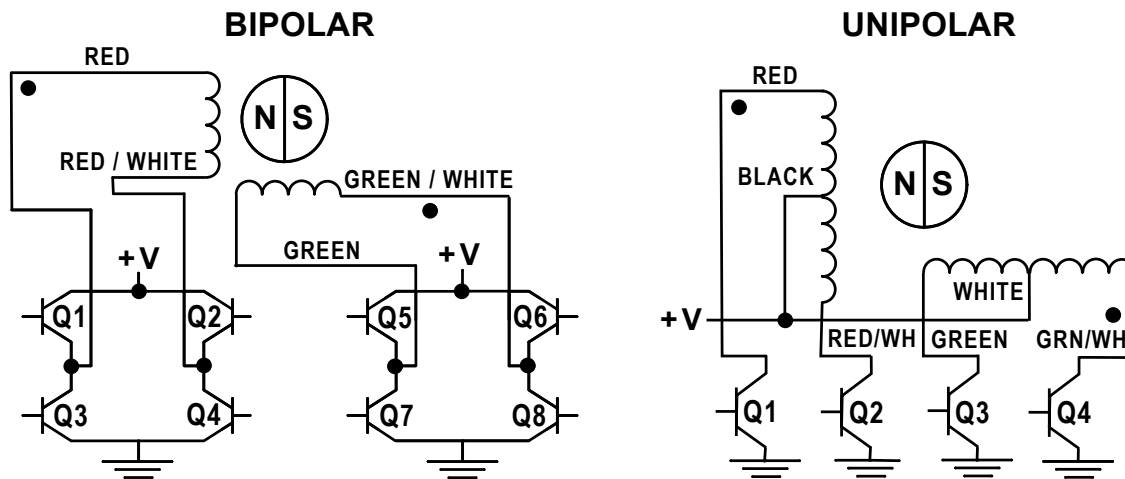


Identifying the Hybrid Part Number Codes when Ordering

E	M43	H	G	N	2.8	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation M43 = 43000 Max Series (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version) J = 0.9° Non-captive K = 0.9° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire) G = IDEA Drive (Size 17, 43000 Series, Bipolar only)	Code ID Resolution Travel/Step N = .00012-in (.0030) K = .00024-in (.0060) J = .00048-in (.0121) Q = .00096-in (.0243) P = .0015625-in (.0039) A = .003125-in (.0079) B = .00625-in (.0158) C = .0125-in (.0317) R = .0192-in (.0478) High Resolution U = .00006-in (.0015) V = .000078-in (.00198)	Voltage 2.8 = 2.8 VDC 5.8 = 5.8 VDC 13.8 = 13.8 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

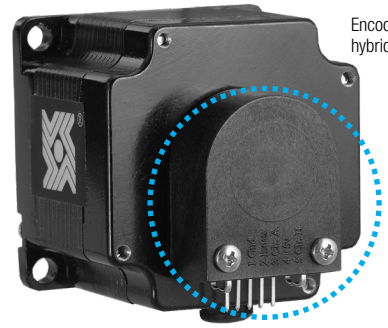
EXTEND CW
RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

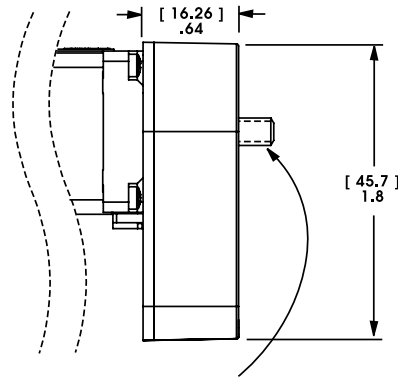
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 17 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm M43000 Series Size 17



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 17	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 17	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
Size 17	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.

Single Ended Encoder - Pinout - Size 17			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connectors

Hybrid Size 17 Max linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

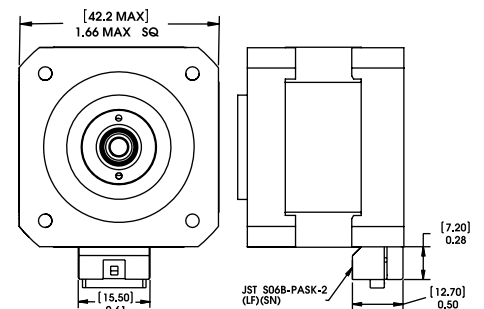
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



MAX Series

30% performance increase compared to standard size 17

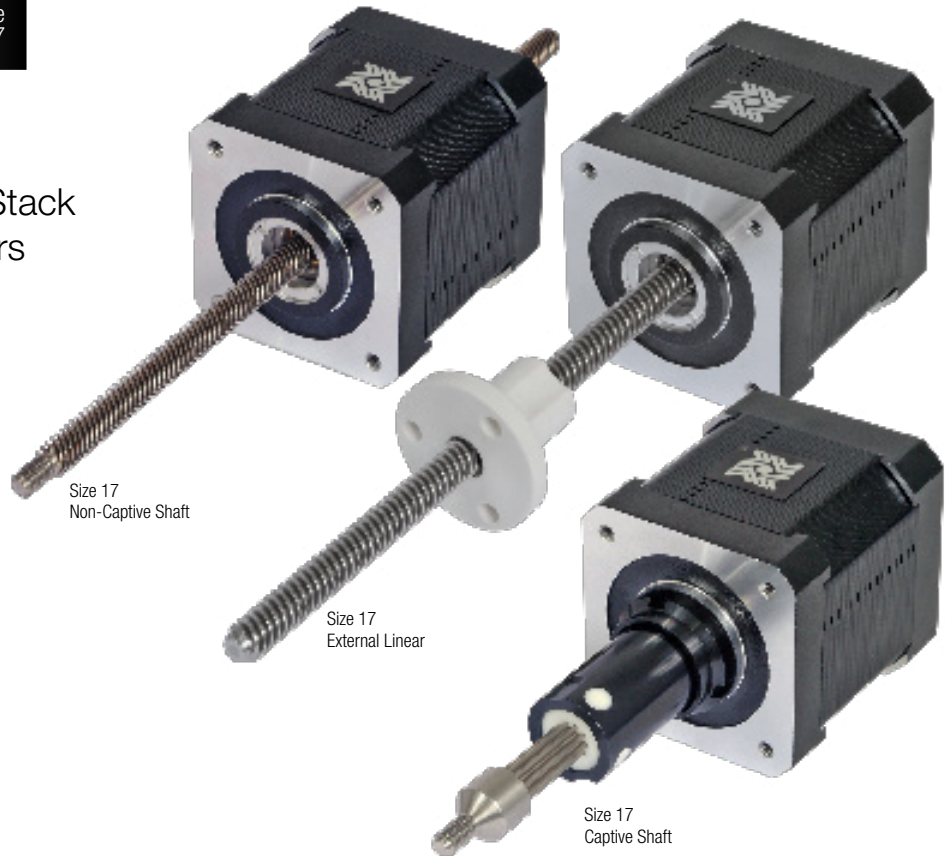
M43000 MAX Series Double Stack Size 17 Hybrid Linear Actuators




Exceptional performance and new linear motion design opportunities, now with 30% performance increase

The M43000 Max Series is available in a wide variety of resolutions from 0.000625-in (.0158 mm) per step to 0.005-in (.127 mm) per step. The motors can also be microstepped for even finer resolutions. The Size 17 Double Stack actuator delivers thrust of up to 75 lbs. (337 N).

3 Available Designs

- Captive
- Non-Captive
- External Linear



Size 17 Max Double Stack Max: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	M43M4  †	
	Non-Captive	M43L4  †	
	External Linear	EM43M4  †	
Wiring		Bipolar	
Winding Voltage	2.8 VDC	5.8 VDC	13.8 VDC
Current (RMS)/phase	2.6 A	1.3 A	550 mA
Resistance/phase	1.1 Ω	4.5 Ω	25 Ω
Inductance/phase	2.4 mH	10.5 mH	52 mH
Power Consumption	15 W		
Rotor Inertia	78.2 gcm ²		
Temperature Rise	135° F Rise (70° C Rise)		
Insulation Class	Class B (Class F available)		
Weight	14 oz (400 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 6.

Linear Travel / Step		Order Code I.D.
Screw Ø.1875" (4.76mm)		
inches	mm	
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635	Y
.00375	.0953	AG
.005	.127	Z

*Values truncated.

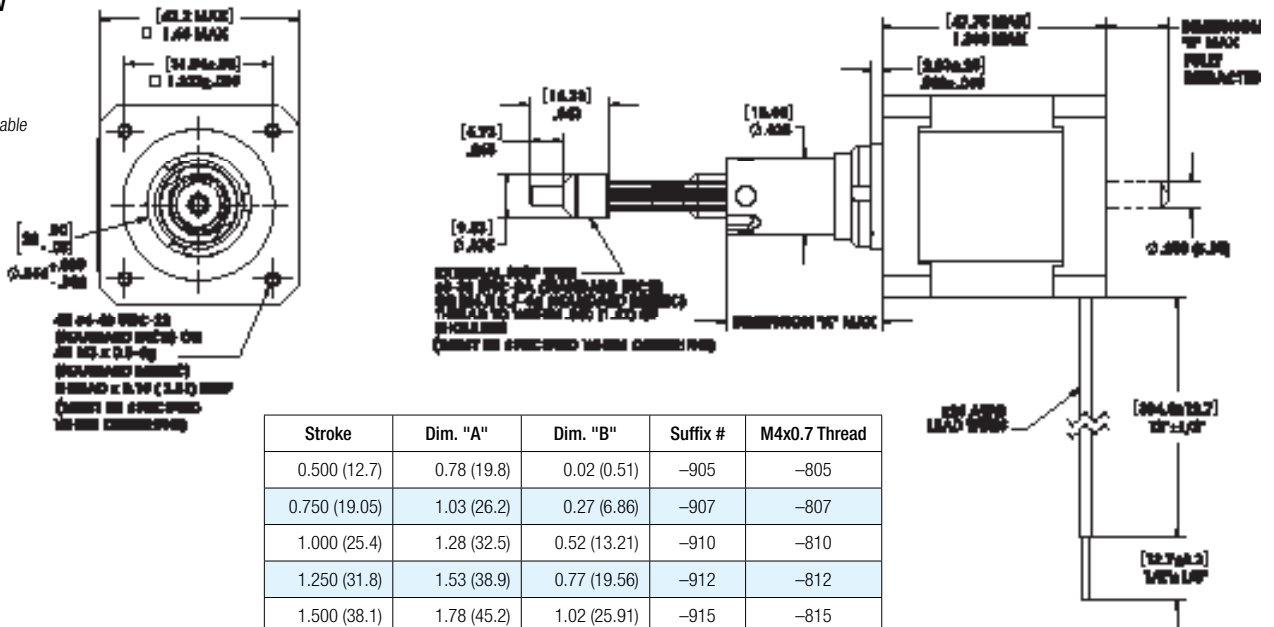
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



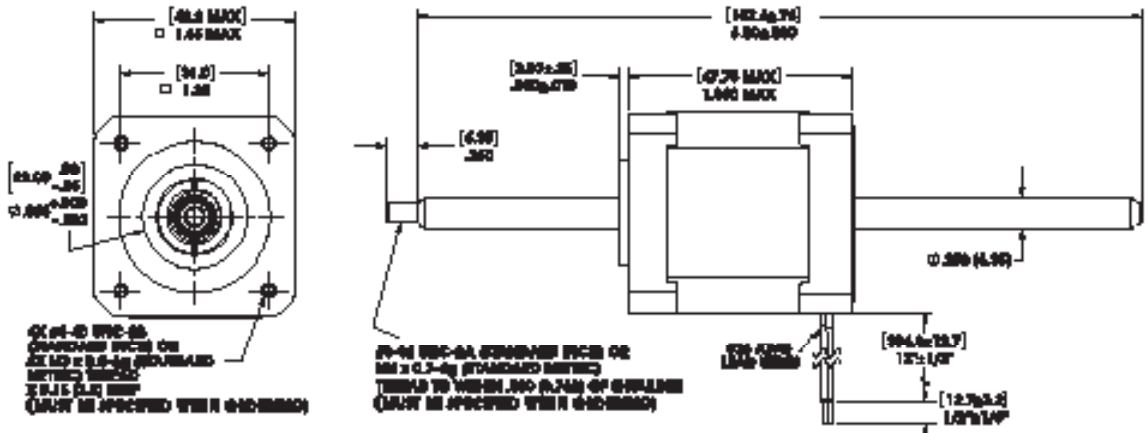
Stroke	Dim. "A"	Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0.02 (0.51)	-905	-805
0.750 (19.05)	1.03 (26.2)	0.27 (6.86)	-907	-807
1.000 (25.4)	1.28 (32.5)	0.52 (13.21)	-910	-810
1.250 (31.8)	1.53 (38.9)	0.77 (19.56)	-912	-812
1.500 (38.1)	1.78 (45.2)	1.02 (25.91)	-915	-815
2.00 (50.8)	2.28 (57.9)	1.52 (38.61)	-920	-820
2.500 (63.5)	2.78 (70.6)	2.02 (51.31)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.

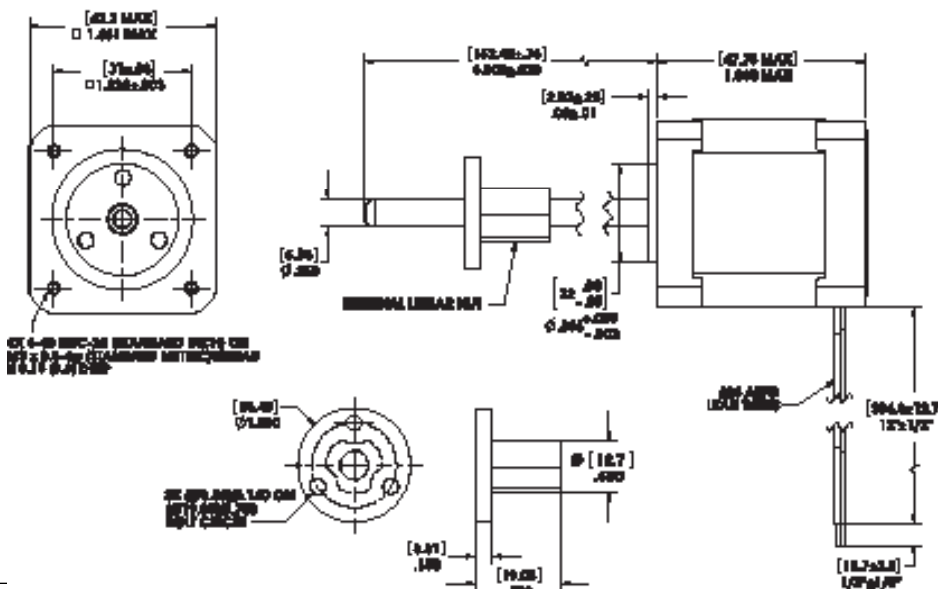


External Linear

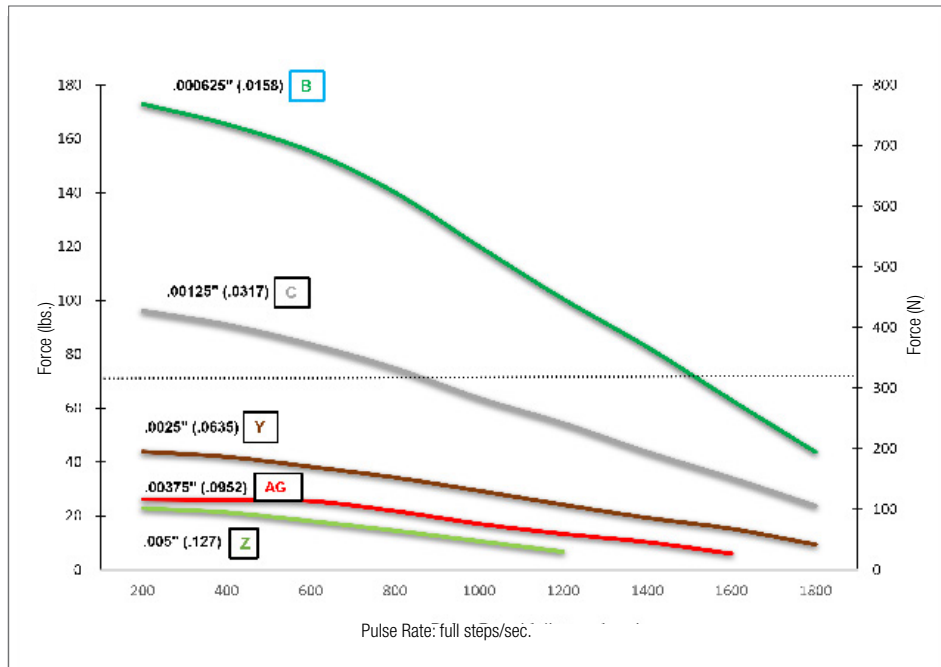
Dimensions = (mm) inches

Integrated connector option available

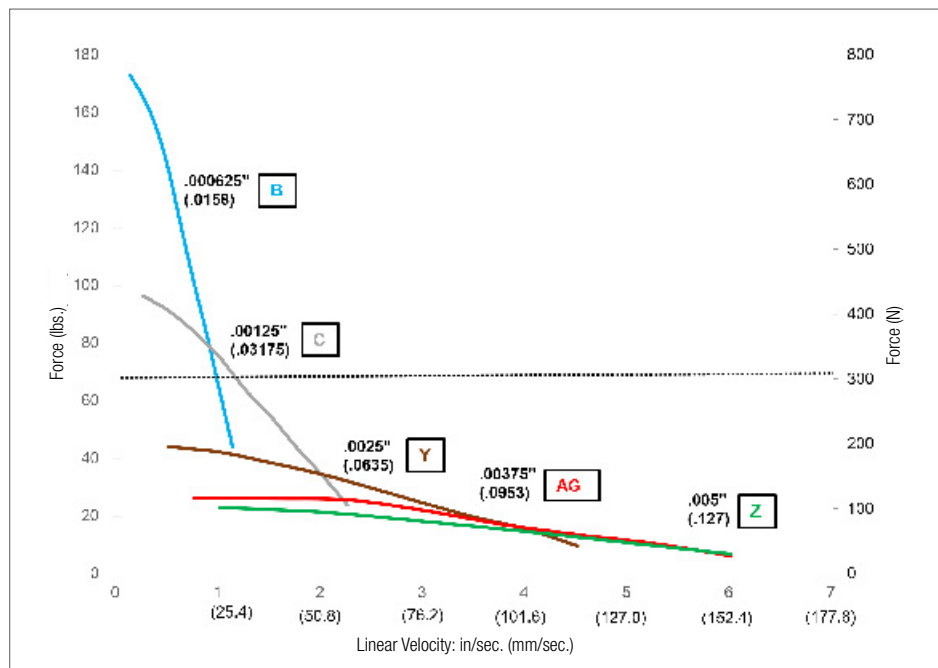
4-in [101.6 mm] standard screw lengths. Longer screw lengths are available.



FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage
 – Ø .250 (6.35) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle – 8:1 Motor Coil to Drive Supply Voltage



NOTE: All chopper drive curves were created with a 5.8 volt, microstepping motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

43000 Max Series Size 17 Double Stack Hybrid Linear Actuators with integrated IDEA™ Drive

High performance in a compact package

The M43000 Max Series Double Stack actuator is available in a wide variety of resolutions – from 0.000625-in (.0158 mm) per step to 0.005-in (.127 mm) per step. Delivers output force of up to 75 lbs (337N).

43000 Series with IDEA™ Drive features:

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability: Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

3 Available Designs

- Captive – Non-Captive – External Linear



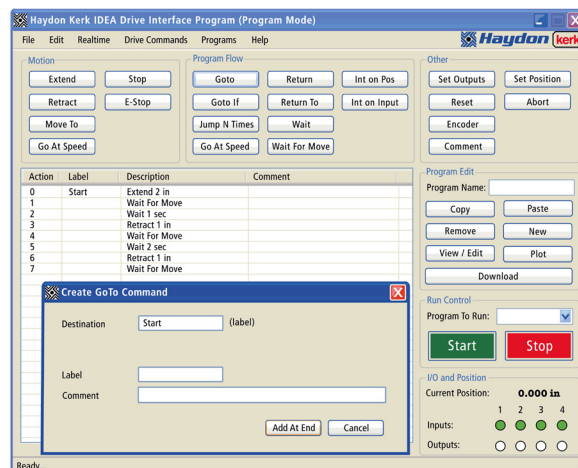
Size 17 Max Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)		
Part No.	Captive	M43MG – — — — — †
	Non-Captive	M43LG – — — — — †
	External Linear	EM43MG – — — — — †
Wiring	Bipolar	
Winding Voltage	2.8 VDC**	

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635*	Y
.00375	.0953*	AG
.005	.127*	Z

†Part numbering information on page 7. **Contact Haydon Kerk if a higher voltage motor is desired. Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

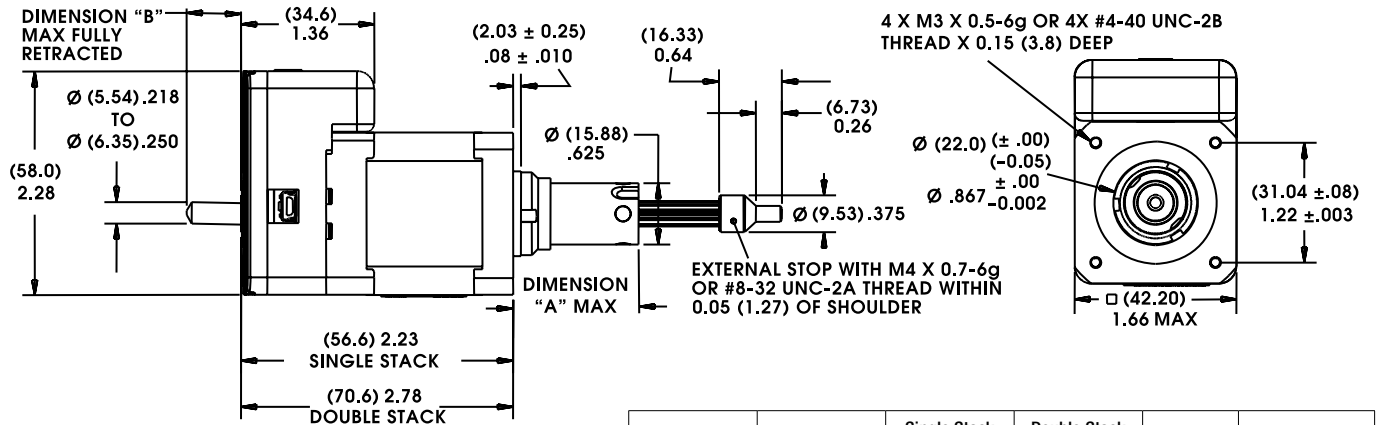
Simple to use IDEA™ Drive software with on-screen buttons and easy-to-understand programming guides

Software program generates motion profiles directly into the system and also contains a “debug” utility allowing line-by-line execution of a motion program for easy troubleshooting.



Captive Lead Screw

Dimensions = (mm) inches

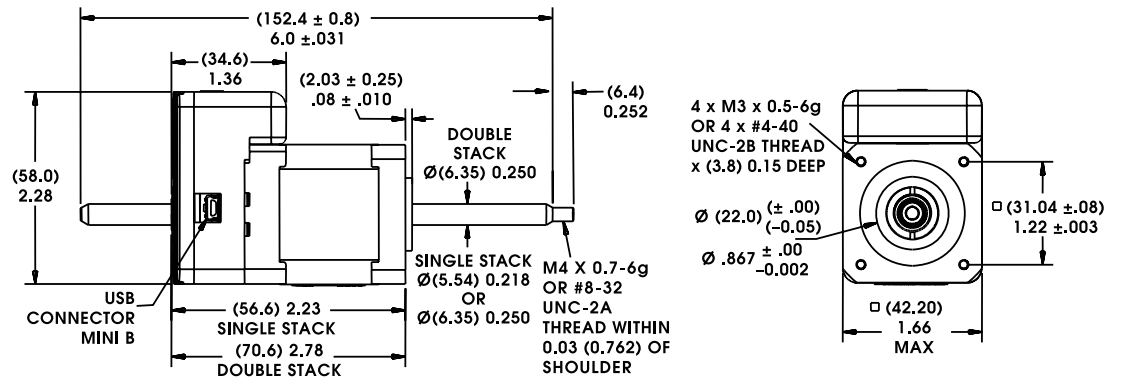


Stroke	Dim. "A"	Single Stack Dim. "B"	Double Stack Dim. "B"	Suffix #	M4x0.7 Thread
0.500 (12.7)	0.78 (19.8)	0	0	-905	-805
0.750 (19.05)	1.03 (26.2)	0	0	-907	-807
1.000 (25.4)	1.28 (32.5)	0	0	-910	-810
1.250 (31.8)	1.53 (38.9)	0	0	-912	-812
1.500 (38.1)	1.78 (45.2)	0.232 (5.9)	0.091 (2.5)	-915	-815
2.00 (50.8)	2.28 (57.9)	0.732 (18.6)	0.591 (15.0)	-920	-820
2.500 (63.5)	2.78 (70.6)	1.232 (31.3)	1.091 (27.7)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

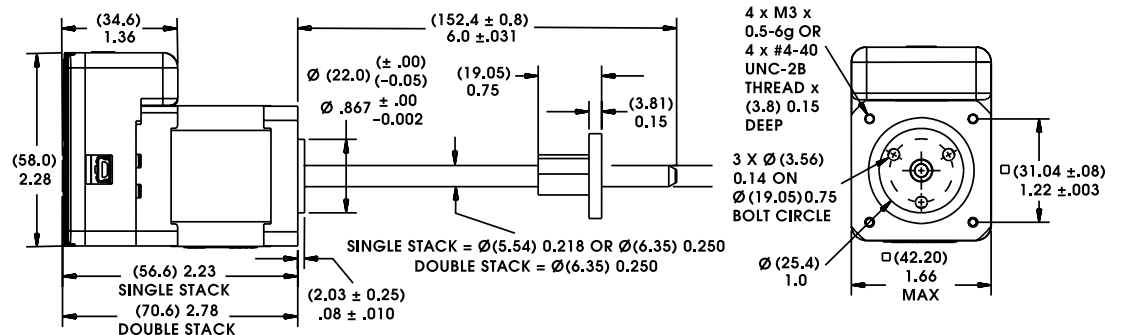
Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.



External Linear

Dimensions = (mm) inches

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

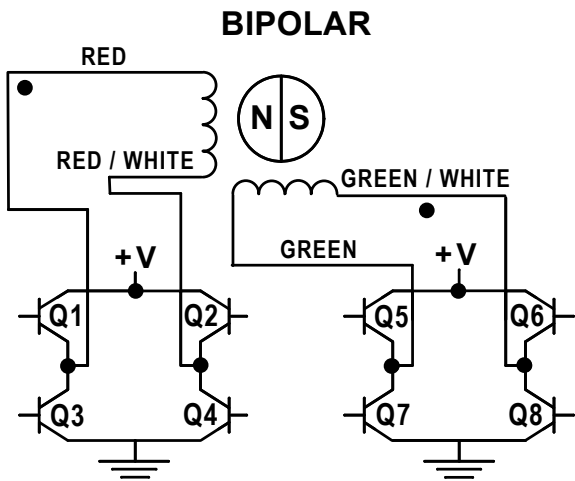


Identifying the Hybrid Part Number Codes when Ordering

E	M43	M	G	C	2.8	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation M43 = 43000 Max Series (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) G = IDEA Drive (Size 17, 43000 Series, Bipolar only)	Code ID Resolution Travel/Step B = .000625-in (.0158) C = .00125-in (.0317) Y = .0025-in (.0635) AG = .00375-in (.0953) Z = .005-in (.127)	Voltage 2.8 = 2.8 VDC 5.8 = 5.8 VDC 13.8 = 13.8 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

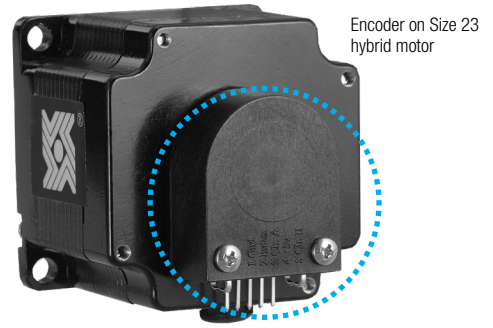
EXTEND CW ↓ RETRACT CCW ↑

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

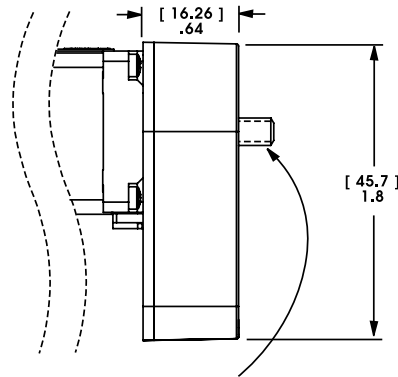
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 17 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm M43000 Series Size 17



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 17	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 17	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
Size 17	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.

Single Ended Encoder - Pinout - Size 17			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connectors

Hybrid Size 17 Max linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre-existing harnesses.

Motor Connector:

JST part # S06B-PASK-2

Mating Connector:

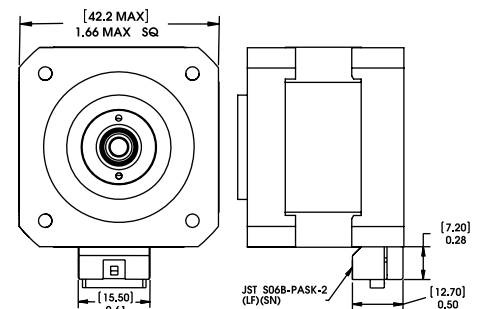
JST part # PAP-06V-S

Haydon Kerk Part #56-1210-5 (12 in. Leads)

Wire to Board Connector:

JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



57000 Series Size 23 Hybrid Linear Actuators

For applications that require forces up to 200 lbs. (890 N).

Size 23 incorporates the same high performance and durable design as the Size 17.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 57000 Series Hybrid Linear Actuator is available in a wide variety of resolutions, from 0.0003125-in. (.0079375 mm) per step to 0.002-in. (.0508 mm) per step. They deliver a thrust of up to 200 lbs. (890 N) per step. They deliver a speed of up to 200 in. (5.08 cm) per second.



Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)						
Part No.	Captive	57H4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			57H6 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
	Non-Captive	57F4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			57F4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
	External Linear	E57H4 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †			E57H6 <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> †	
Wiring		Bipolar			Unipolar**	
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A	
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω	
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH	
Power Consumption	13 W					
Rotor Inertia	166 gcm ²					
Insulation Class	Class B (Class F available)					
Weight	18 oz (511 g)					
Insulation Resistance	20 MΩ					

Linear Travel / Step		Order Code I.D.
Screw Ø .375" (9.53 mm)		
inches	mm	
.0003125	.0079*	A
.0004167	.0105*	S
.0005	.0127	3
.0008333	.0211*	T
.001	.0254	1
.002	.0508	2

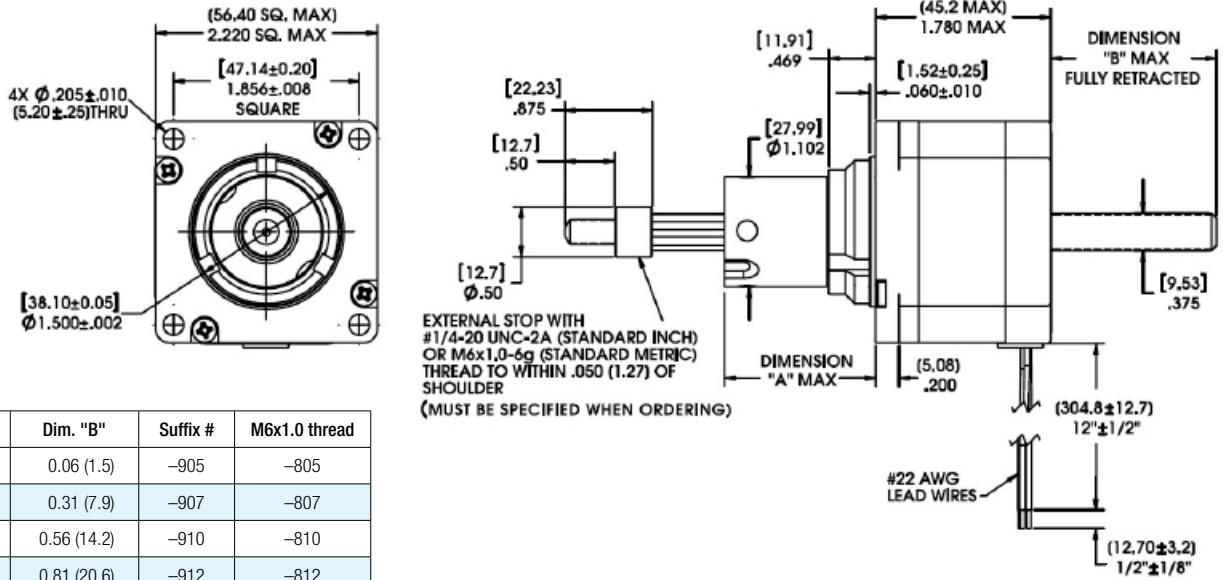
*Values truncated.
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

†Part numbering information on page 126. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Captive Lead Screw

Dimensions = (mm) inches

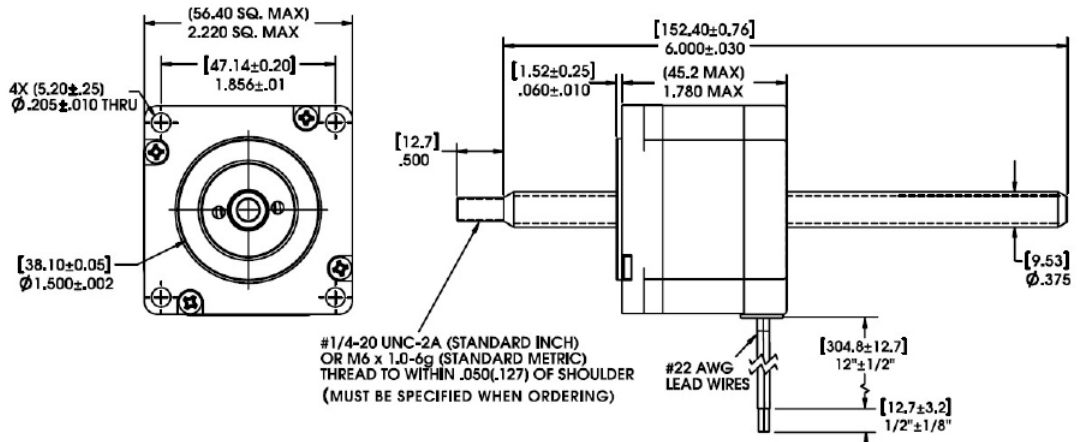


EXTERNAL STOP WITH #1/4-20 UNC-2A (STANDARD INCH) OR M6x1.0-6g (STANDARD METRIC) THREAD TO WITHIN .050 (1.27) OF SHOULDER (MUST BE SPECIFIED WHEN ORDERING)

Stroke	Dim. "A"	Dim. "B"	Suffix #	M6x1.0 thread
0.500 (12.7)	1.01 (25.7)	0.06 (1.5)	-905	-805
0.750 (19.05)	1.26 (32.0)	0.31 (7.9)	-907	-807
1.000 (25.4)	1.51 (38.4)	0.56 (14.2)	-910	-810
1.250 (31.8)	1.76 (44.7)	0.81 (20.6)	-912	-812
1.500 (38.1)	2.01 (51.1)	1.06 (26.9)	-915	-815
2.00 (50.8)	2.51 (63.8)	1.56 (39.6)	-920	-820
2.500 (63.5)	3.01 (76.5)	2.06 (52.3)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

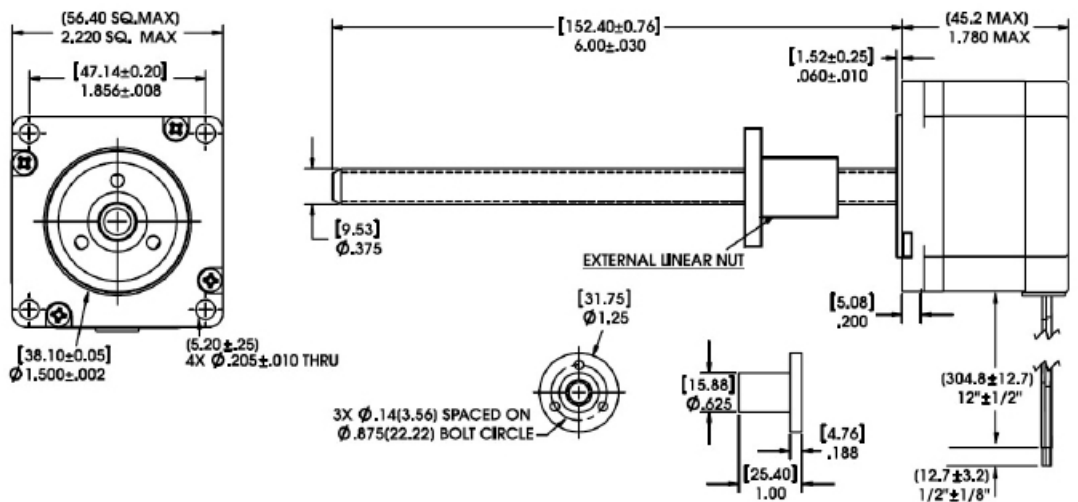


#1/4-20 UNC-2A (STANDARD INCH) OR M6 x 1.0-6g (STANDARD METRIC) THREAD TO WITHIN .050(.127) OF SHOULDER (MUST BE SPECIFIED WHEN ORDERING)

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

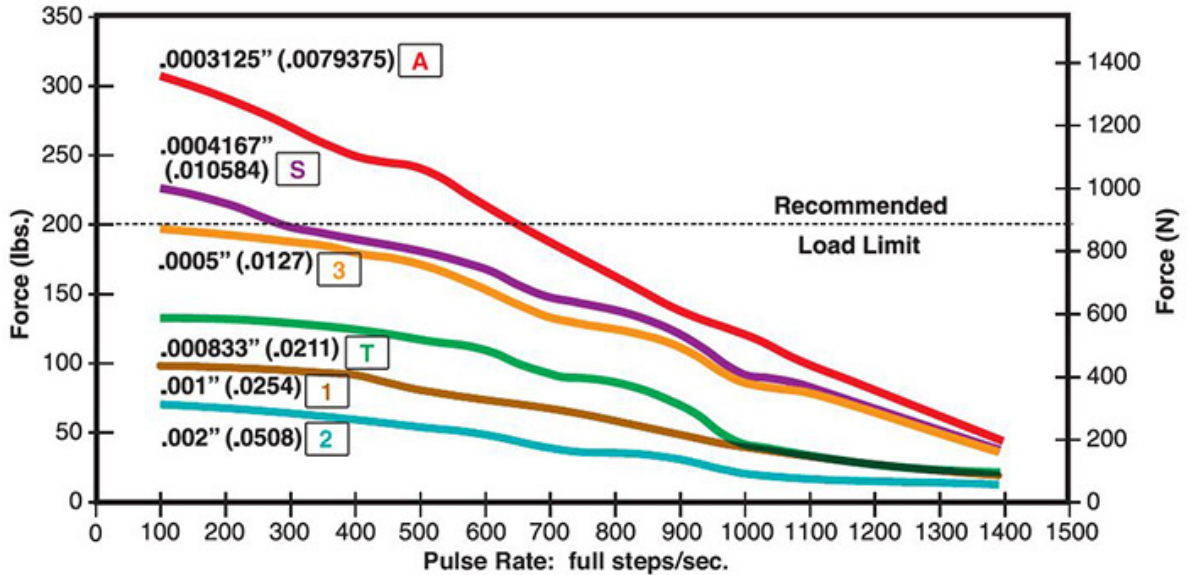
External Linear

Dimensions = (mm) inches

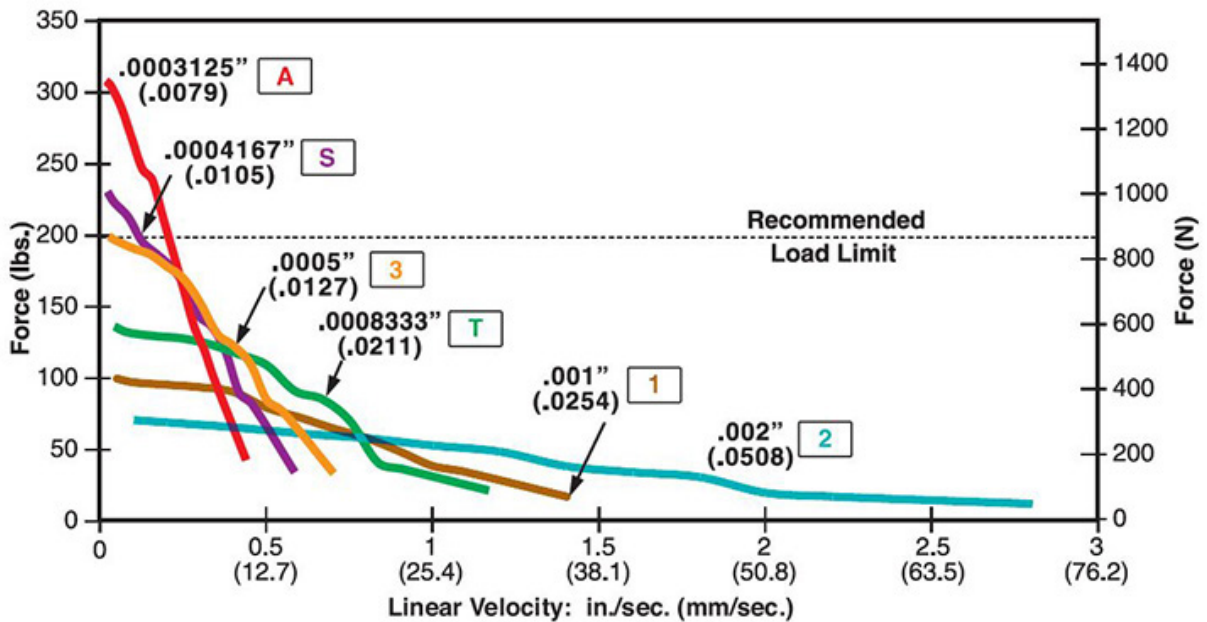


Up to 12-in (305 mm) standard screw lengths. Longer screw lengths are available.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
 – Ø .375 (9.53) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
 – Ø .375 (9.53) Lead Screw









NOTE: All chopper drive curves were created with a 5 volt motor and a 75 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

57000 Series Size 23, 0.9° High Resolution Motor

The Size 23, 0.9° high resolution hybrid offers precise, excellent motion control with a full linear step movement as low as 2 microns and a thrust capability up to 200 lbs (890 N).

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (0.9° Step Angle)						
Part No.	Captive	57K4  †			57K6  †	
	Non-Captive	57J4  †			57J6  †	
	External Linear	E57K4  †			E57K6  †	
Wiring		Bipolar			Unipolar**	
Winding Voltage		3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		2.0 A	1.3 A	0.54 A	1.3 A	0.54 A
Resistance/phase		1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase		4.2 mH	13 mH	68 mH	6 mH	27 mH
Power Consumption		13 W				
Rotor Inertia		166 gcm ²				
Insulation Class		Class B (Class F available)				
Weight		18 oz (511 g)				
Insulation Resistance		20 MΩ				

Linear Travel / Step		Order Code I.D.
Screw Ø .250" (6.35 mm)		
inches	mm	
.000125	.0031*	7
.00015625	.003969	P
.00020833	.00529166	X
.00025	.00635	9
.0004167	.01058418	S
.0005	.0127	3
.001	.0254	1

*Values truncated.

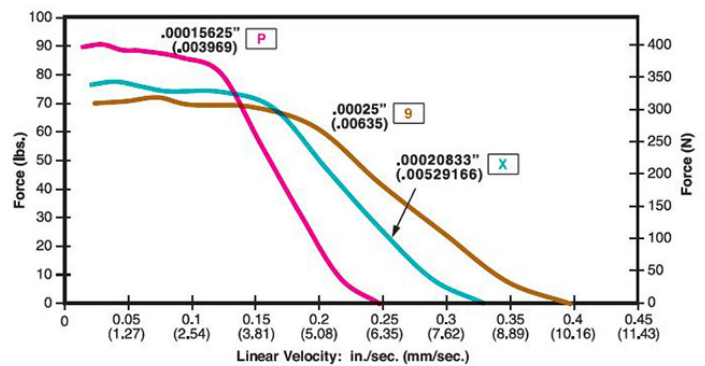
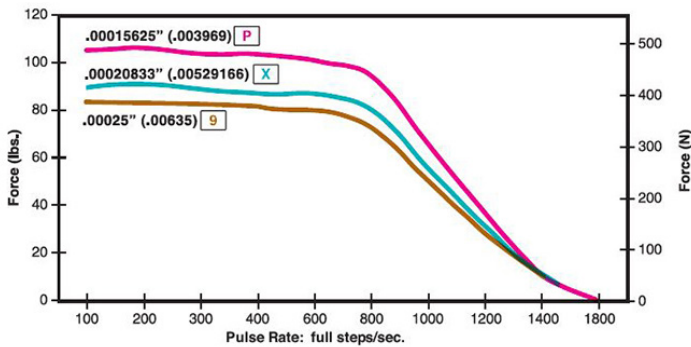
NOTE: Refer to performance curves on previous page for codes S, 3, 1.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

†Part numbering information on page 126. **Unipolar drive gives approximately 30% less thrust than bipolar drive.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters

FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters



NOTE: All chopper drive curves were created with a 5 volt motor and a 75 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

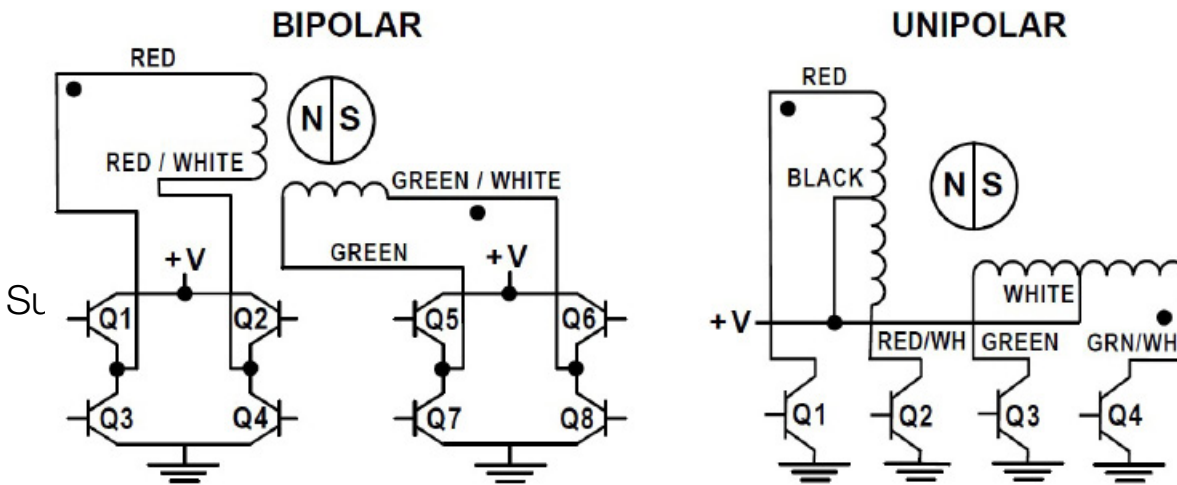
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	57	H	6	7	3.25	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 57 = 57000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version) J = 0.9° Non-captive K = 0.9° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step 7 = .000125-in (.0031) S = .0004167-in (.01058418) 3 = .0005-in (.0127) 1 = .001-in (.0254) A = .0003125-in (.0079) T = .0008333-in (.0211) 2 = .002-in (.0508) High Resolution P = .00015625-in (.003969) X = .00020833-in (.00529166) 9 = .00025-in (.0635)	Voltage 3.25 = 3.25 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step					
1		ON	OFF	ON	OFF
2		OFF	ON	ON	OFF
3		OFF	ON	OFF	ON
4		ON	OFF	OFF	ON
1		ON	OFF	ON	OFF

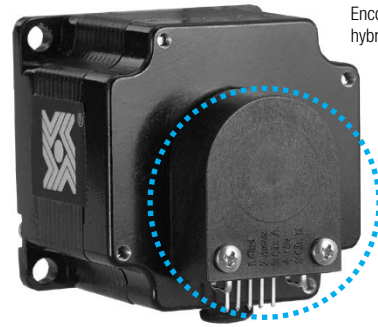
EXTEND CW
RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

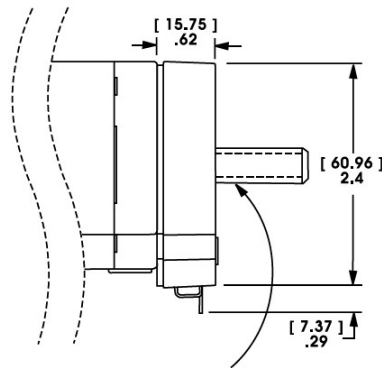
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 23 encoder is offered in resolutions of 200, 400, 1,000 and 2,000 counts per revolution. Encoders are available for all motor configurations: captive, non-captive and external linear.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

57 mm 57000 Series Size 23



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 23	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 23	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution					
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)					
Size 23	CPR	200	400*	1000	2000
	PPR	800	1600*	4000	8000

*Index Pulse Channel not available.
 Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 23			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

57000 Series Size 23 Double Stack Hybrid Linear Actuators

Greater performance in a compact size

The various patented designs deliver exceptional performance and new linear motion design opportunities. The 57000 Series is available in a wide variety of resolutions, from 0.0005-in (.0127 mm) per step to 0.005-in (.127 mm) per step. The motors can also be microstepped for even finer resolutions.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The Size 23 actuator delivers thrust of up to 200 lbs. (890 N).



Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)			
Part No.	Captive	57M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	Non-Captive	57L4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
	External Linear	E57M4 <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> - <input type="checkbox"/> †	
Wiring		Bipolar	
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.32 A	2.16 A	0.9 A
Resistance/phase	0.98 Ω	2.31 Ω	13.33 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	21.6 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 MΩ		

†Part numbering information on page 131.

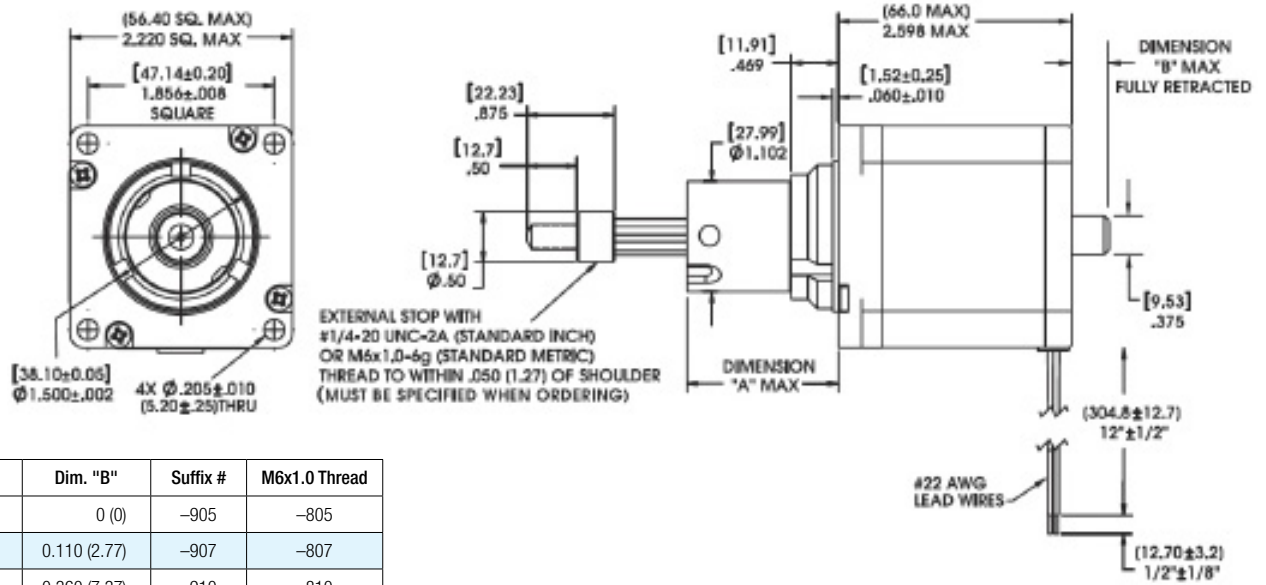
Linear Travel / Step		Order Code I.D.
Screw Ø.375" (9.53 mm)		
inches	mm	
.0005	.0127*	3
.001	.0254*	1
.002	.0508	2
.0025	.0635	Y
.005	.127	Z

*Values truncated.

Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

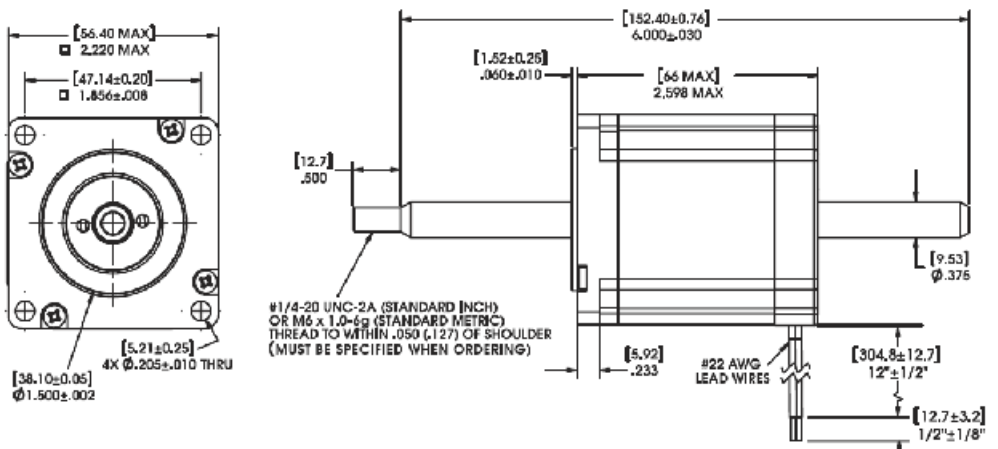


Stroke	Dim. "A"	Dim. "B"	Suffix #	M6x1.0 Thread
0.500 (12.7)	1.01 (25.7)	0 (0)	-905	-805
0.750 (19.05)	1.26 (32.0)	0.110 (2.77)	-907	-807
1.000 (25.4)	1.51 (38.4)	0.360 (7.37)	-910	-810
1.250 (31.8)	1.76 (44.7)	0.610 (15.47)	-912	-812
1.500 (38.1)	2.01 (51.1)	0.860 (21.83)	-915	-815
2.00 (50.8)	2.51 (63.8)	1.360 (34.52)	-920	-820
2.500 (63.5)	3.01 (76.5)	1.860 (47.22)	-925	-825

Non-Captive Lead Screw

Dimensions = (mm) inches

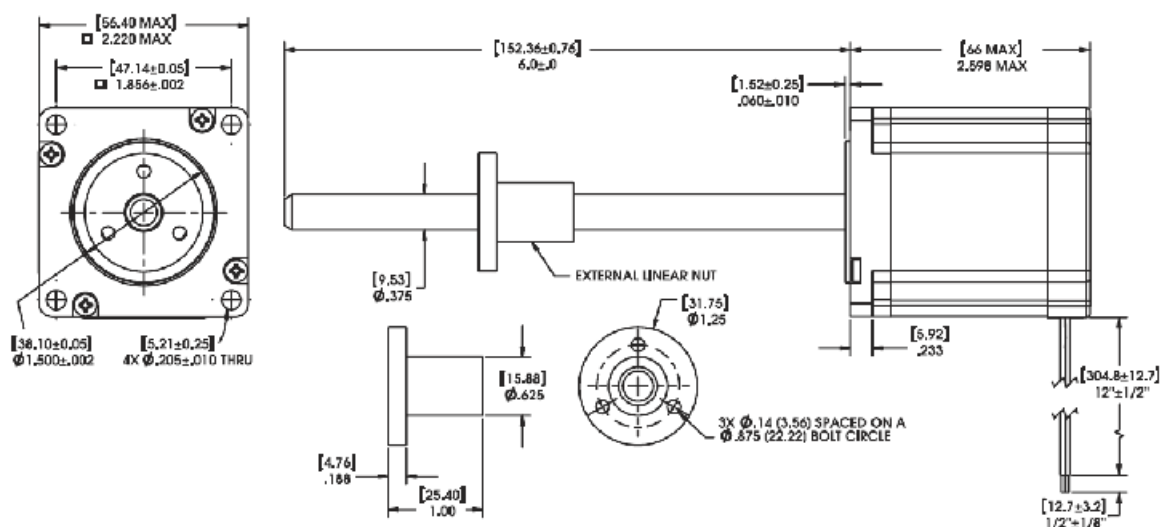
Up to 18-in (457 mm) standard screw lengths. Longer screw lengths are available.



External Linear

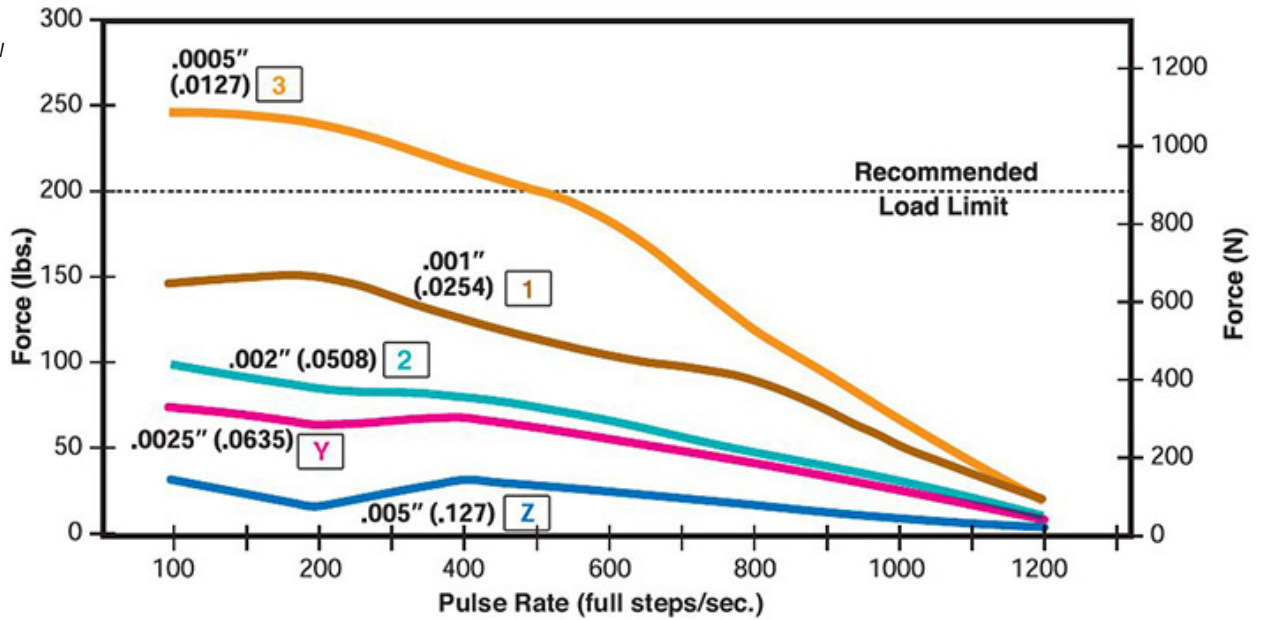
Dimensions = (mm) inches

Up to 12-in (305 mm) standard screw lengths. Longer screw lengths are available.



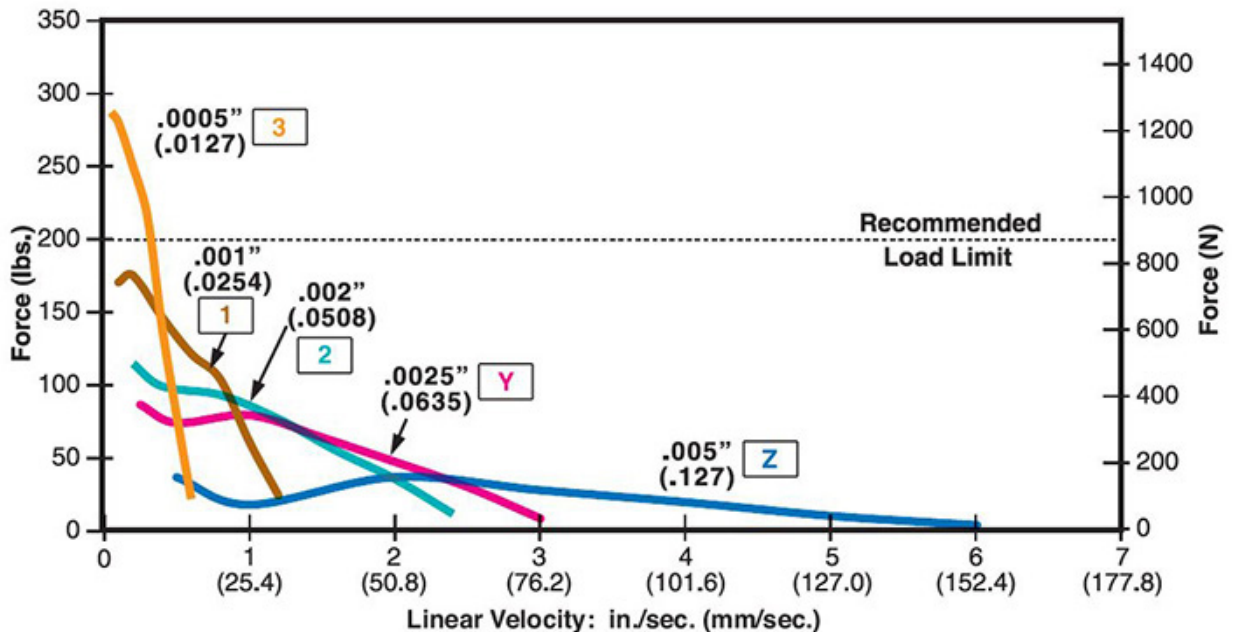
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .375 (9.53) Lead Screw



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .375 (9.53) Lead Screw

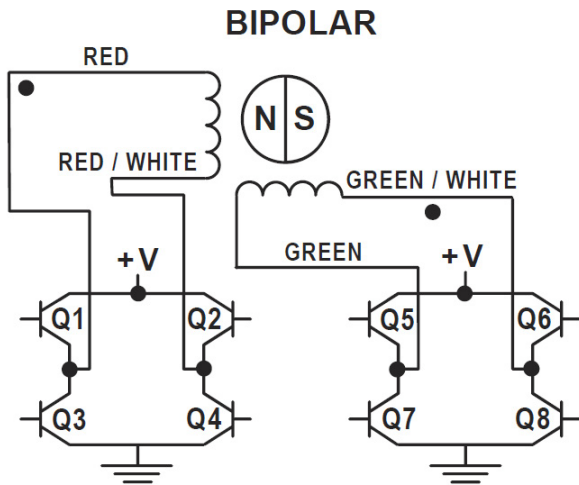


Identifying the Hybrid Part Number Codes when Ordering

E	57	M	4	3	3.25	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 57 = 57000 (Series numbers represent approximate width of motor body)	Style L = 1.8° Non-captive M = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 3 = .0005-in (.0127) 1 = .001-in (.0254) 2 = .002-in (.0508) Y = .0025-in (.0635) Z = .005-in (.127)	Voltage 3.25 = 3.25 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

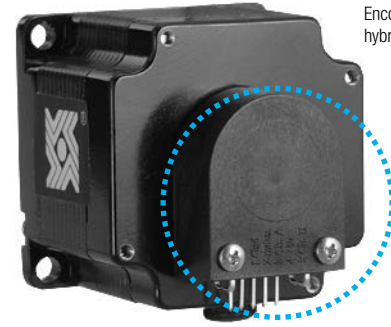
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

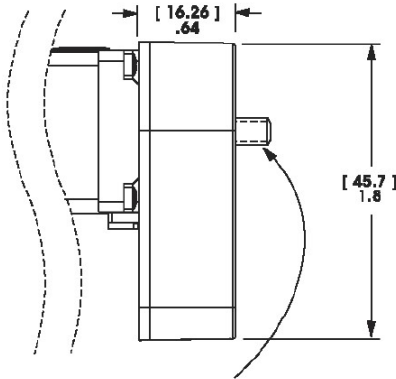
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 23 encoder is offered in resolutions of 200, 400, 1,000 and 2,000 counts per revolution. Encoders are available for all motor configurations, captive, non-captive and external linear.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

57 mm 57000 Series Size 23



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 23	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 23	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution					
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)					
Size 23	CPR	200	400*	1000	2000
	PPR	800	1600*	4000	8000

*Index Pulse Channel not available.
 Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 23			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

87000 Series Size 34 Hybrid Linear Actuators

Our largest, most powerful linear actuator

Size 34 incorporates the same precision, high performance and durable patented designs featured in our entire hybrid product line.


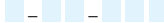

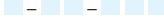

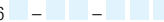
3 Available Designs

- Captive
- Non-Captive
- External Linear

The 87000 series delivers forces up to 500 lbs. (2224 N) in a compact, 3.4-in (87 mm) square package. Available in a wide variety of resolutions, from 0.0005-in (.0127 mm) per step to 0.005-in (.127 mm) per step. Speeds exceed 3.0-in (7.62 cm) per second.

In addition to our standard configurations, we can custom build this powerful motor to meet your specific motion requirements.



Size 34: 87 mm (3.4-in) Hybrid Linear Actuator (1.8° Step Angle)							
Part No.	Captive	87H4  †				87H6  †	
	Non-Captive	87F4  †				87F4  †	
	External Linear	E87H4  †				E87H6  †	
Wiring	Bipolar				Unipolar**		
Winding Voltage	2.85 VDC	5 VDC	6 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase	5.47 A	3.12 A	2.6 A	1.3 A	3.12 A	1.3 A	
Resistance/phase	0.52 Ω	1.6 Ω	2.31 Ω	9.23 Ω	1.6 Ω	9.23 Ω	
Inductance/phase	2.86 mH	8.8 mH	12.7 mH	51 mH	4.4 mH	25.5 mH	
Power Consumption	31.2 W						
Rotor Inertia	1760 gcm ²						
Insulation Class	Class B (Class F available)						
Weight	5.1 lbs. (2.3 Kg)						
Insulation Resistance	20 MΩ						

Linear Travel / Step		Order Code I.D.
Screw Ø .625" (15.88 mm)		
inches	mm	
.0005	.0127	3
.000625	.0158*	B
.00125	.0317*	C
.0025	.0635	Y
.005	.127	Z

*Values truncated.

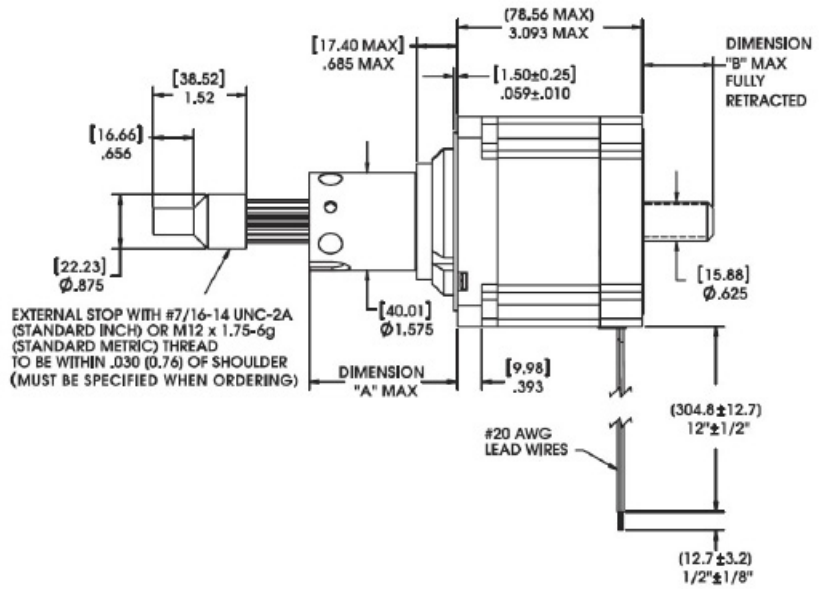
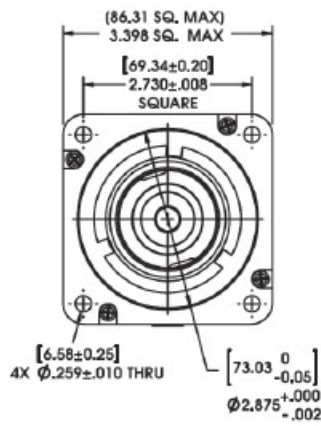
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

†Part numbering information on page 136. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Captive Lead Screw

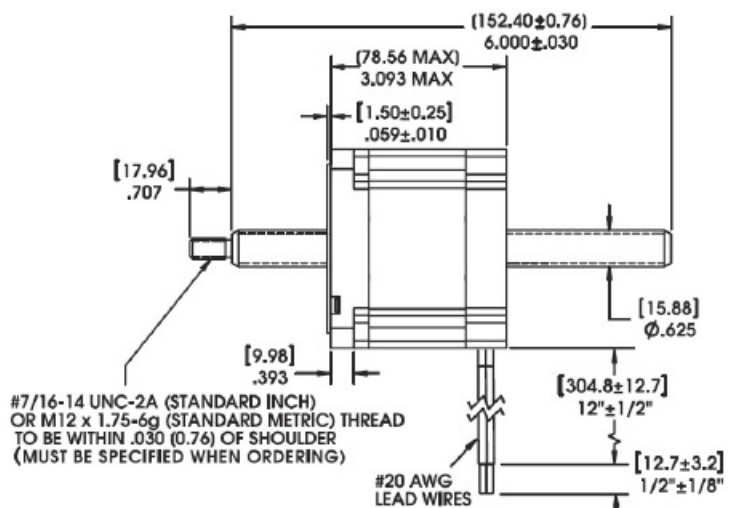
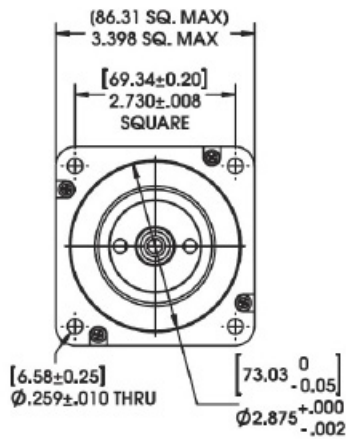
Dimensions = (mm) inches



Stroke	Dim. "A"	Dim. "B"	Suffix #	M12x1.75 Thread
0.500 (12.7)	1.225 (31.12)	0 (0)	-905	-805
1.000 (25.4)	1.725 (43.82)	0.25 (6.35)	-910	-810
1.500 (38.1)	2.225 (56.52)	0.75 (19.05)	-915	-815
2.00 (50.8)	2.725 (69.22)	1.25 (31.75)	-920	-820
2.500 (63.5)	3.225 (81.92)	1.75 (44.45)	-925	-825

Non-Captive Lead Screw

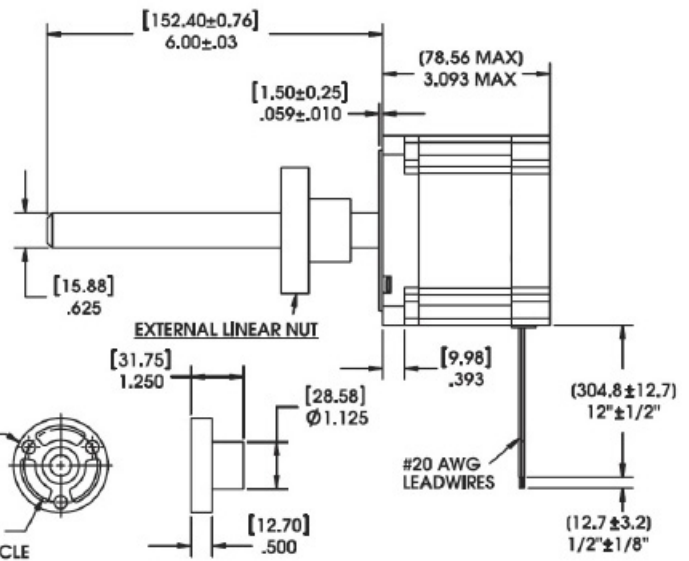
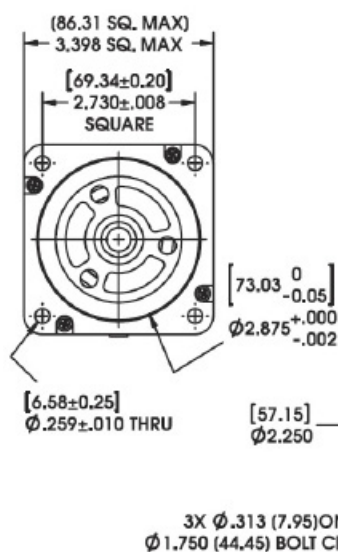
Dimensions = (mm) inches



Up to 18-in (457 mm) standard screw lengths. Longer screw lengths are available.

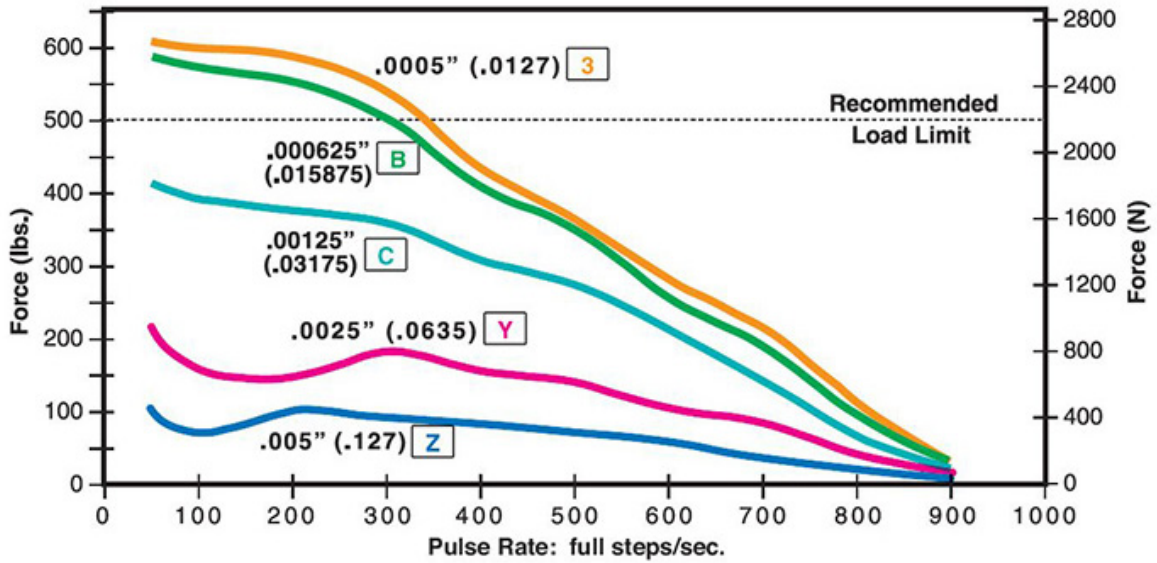
External Linear

Dimensions = (mm) inches

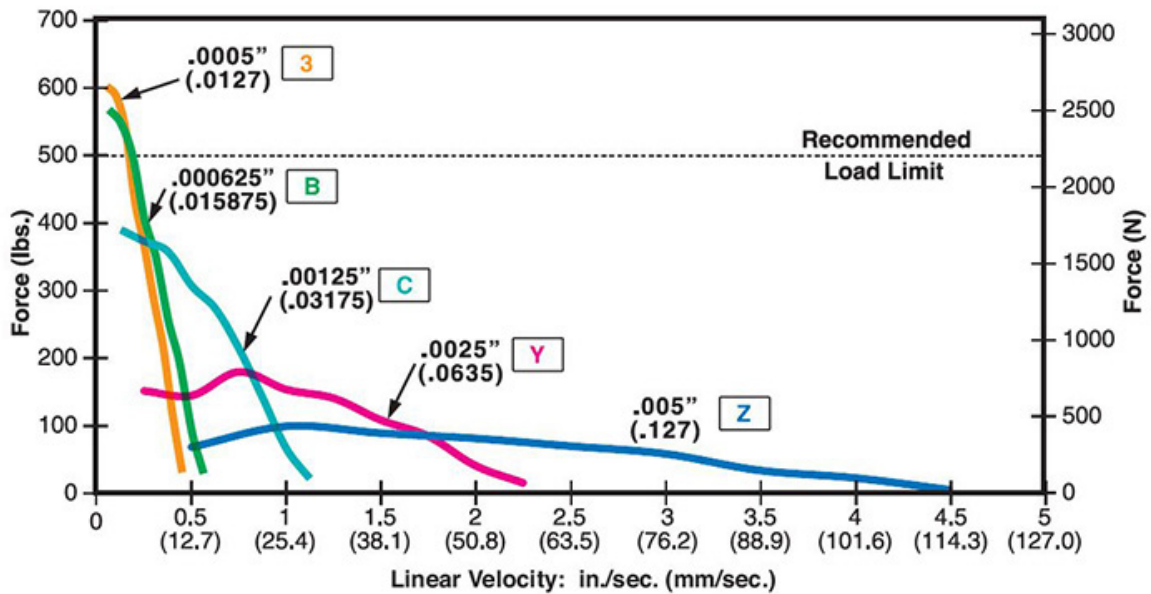


Up to 12-in (305 mm) standard screw lengths. Longer screw lengths are available.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
 – Ø .625 (15.88) Lead Screw



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
 – Ø .625 (15.88) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 75 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

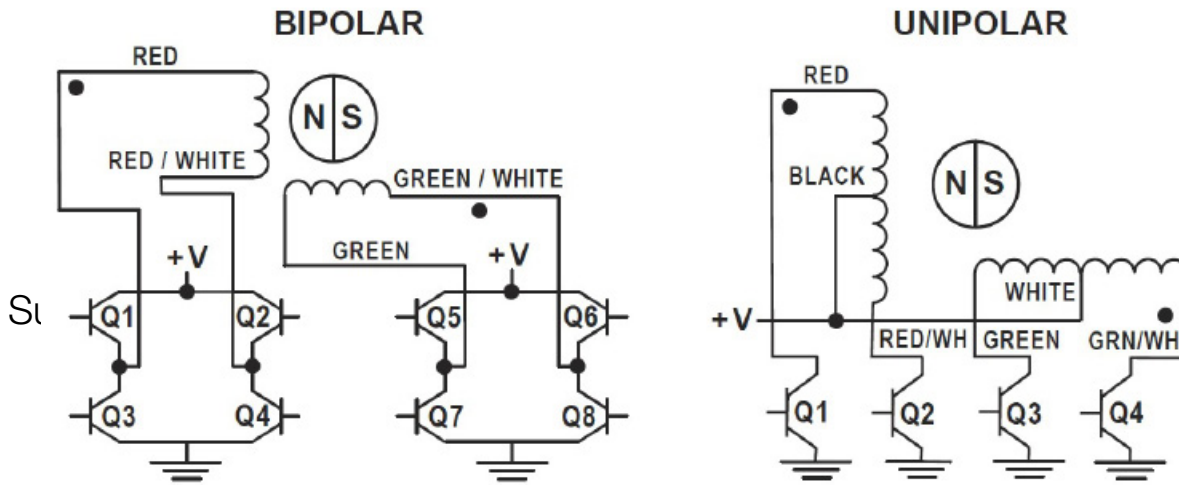
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	87	H	4	C	2.85	910
Prefix (include only when using the following) A = A Coil (See AC Synchronous Data Sheet) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 87 = 87000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step 3 = .0005-in (.0127) B = .000625-in (.0158) C = .00125-in (.0317) Y = .0025-in (.0635) Z = .005-in (.127)	Voltage 2.85 = 2.85 VDC 05 = 5 VDC 06 = 6 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

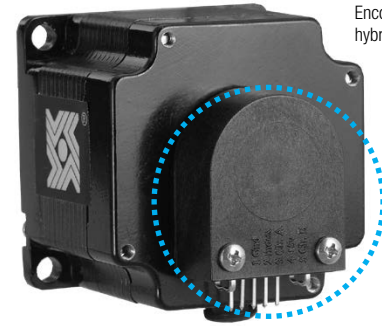
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

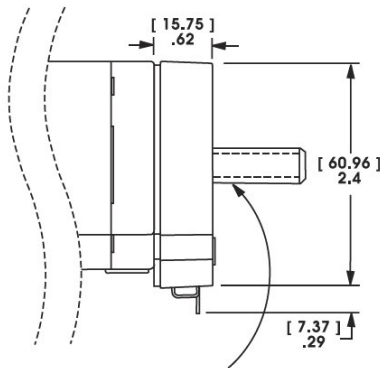
All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 34 encoder is offered in resolutions of 200, 400, 1,000 and 2,000 counts per revolution. Encoders are available for all motor configurations: captive, non-captive and external linear.

Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

87 mm 87000 Series Size 34



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Differential Ended Encoder - Pinout - Size 34	
Connector Pin #	Description
1	Ground
2	Ground
3	- Index
4	+ Index
5	Channel A -
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B -
10	Channel B +

Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
 Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
 Tracks at speeds of 0 to 100,000 cycles/sec.
 Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Size 34	Minimum	Maximum
	- 40°C (- 40°F)	100°C (212°F)

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

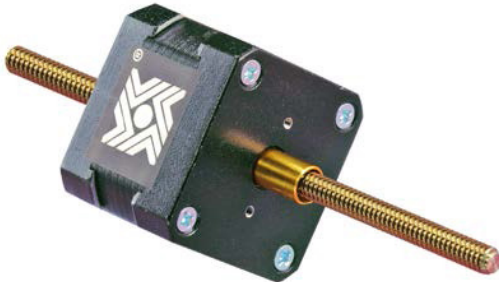
Resolution					
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)					
Size 34	CPR	200	400*	1000	2000
	PPR	800	1600*	4000	8000

*Index Pulse Channel not available.
 Contact us for additional resolution options

Single Ended Encoder - Pinout - Size 34			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		



Encoder Ready Option Shown 34000 Series Size 17



Extended Rotor Journal Shown 34000 Series Size 17



End of Stroke Proximity Sensor



TFE Coated Lead Screw



Integrated Anti-Backlash Nut

Encoder Ready Option for all Hybrid Sizes

Our Hybrid Linear Actuators can now be manufactured as an Encoder Ready Actuator. Encoder Ready Actuators can be used to install several popular hollow shaft encoders. Available with an extended rotor journal and a threaded rear housing. The motor uses a proprietary manufacturing process which incorporates engineering thermoplastics in the rotor drive nut and a stainless steel Acme Lead Screw that allows the motor to be much more efficient and durable than today's more commonly used V-thread bronze nut configurations.

Size 23 Mounting Face Plate for Size 17 Hybrids

Size 23 mounting pattern for our Hybrid Size 17 Linear Actuators.

Extended Rotor Journal for all Hybrid Sizes

Available with an extended rotor journal. The extended rotor journal can be used for encoder installation, manual adjustment, or flag installation for a positioning sensor.

Home Position Switch for Hybrids

A miniature electronic Home Position Switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions.

When ordering motors with the home position switch the part number should be preceded by an "S" prefix.

End of Stroke Proximity Sensor for all Hybrid Sized

The Sensor incorporates a hall effect device, which is activated by a rare earth magnet embedded in the end of the internal screw. The compact profile of the sensor allows for installation in limited space applications. The sensor has a virtually unlimited cycle life. Special cabling and connectors can also be provided.

When ordering motors with the proximity sensor, the part number should be preceded by a "P" prefix.

Black Ice® and Kerkote® TFE Coated Lead Screws*

TFE Coated Lead Screws for applications that require a *greaseless* screw and nut interface.

A *dry* (non-lubricated) TFE coated lead screw provides improved performance in both life and thrust as compared to a conventional stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches and is available for our brand captive, non-captive and external linear actuators. Not available for 0.00006-in (.0015 mm) and 0.000098-in (.0025 mm) resolutions.

*Certain conditions apply.

Integrated Anti-Backlash Nut for Hybrids*

Most sizes (except Size 34) of our captive and non-captive hybrid stepper motors can be equipped with an integral anti-backlash feature. There is a normal backlash between the lead screw and integral rotor nut.

Our actuators are designed for millions of cycles. However over time, additional backlash could increase and eventually double. Haydon Kerk Integrated Anti-Backlash Nut can eliminate all backlash. Designed specifically for our captive and non-captive hybrid motors, nuts use an opposing spring force to eliminate backlash between the screw and the nut interface. The nuts will self-compensate and accommodate any wear. Haydon Kerk Motion Solutions application engineers can help you select the appropriate preload for your application.

*Except Size 34.

Dual Motion Actuators

The Haydon Kerk line of dual motion hybrid actuators provide independent linear and rotary motion from a single compact actuator package. The actuators are based on unique, patented designs and incorporate Haydon Kerk proven linear and rotary motor technology. These units simplify product development by replacing what would otherwise be far more bulky and complex mechanisms.

Dual Motion Size 14 Linear/Rotary Actuators

Axially move components to their insertion positions and then rotate them.

Based on unique, patented designs and incorporate proven motor technology. Units simplify product development by replacing what would otherwise be far more bulky and complex mechanisms.

Another feature of this design is to provide an electric motor in which linear and rotary motions are controllable independently of one another.

For a rotary/linear motor, it is desirable that the linear and rotary motions be controllable independently of one another. These devices can be run using a standard two axis stepper motor driver. Performance can be enhanced using chopper and/or microstepping drives.

Encoders available. US Digital E5 for linear, E6 for rotary.



35000 Series Dual Motion with 47 mm NEMA

35000 Series: 1.8° Step Angle				
Linear Travel / Step		Load Limit		Order Code I.D.
inches	mm	lbs	N	
0.00006	0.0015*	10	44.4	U
0.000098*	0.0025	10	44.4	AA
0.00012	0.0030*	15	67	N
0.00019*	0.005	15	67	AB
0.00024	0.0061*	15	67	K
0.00039*	0.01	15	67	AC
0.00048	0.0121*	15	67	J
0.00078*	0.02	15	67	AD
0.00157*	0.04	15	67	AE

*Values truncated. Standard motors are Class B rated for maximum temperature of 130°C.

35000 Series: 0.9° Step Angle				
Linear Travel / Step		Load Limit		Order Code I.D.
inches	mm	lbs	N	
0.00003	0.00076*	10	44.4	BP
0.00005*	0.00125	10	44.4	AY
0.00006	0.0015*	15	67	U
0.000098*	0.0025	15	67	AA
0.00012	0.0030*	15	67	N
0.00019*	0.005	15	67	AB
0.00024	0.0061*	15	67	K
0.00039*	0.01	15	67	AC
0.00079*	0.02	15	67	AD

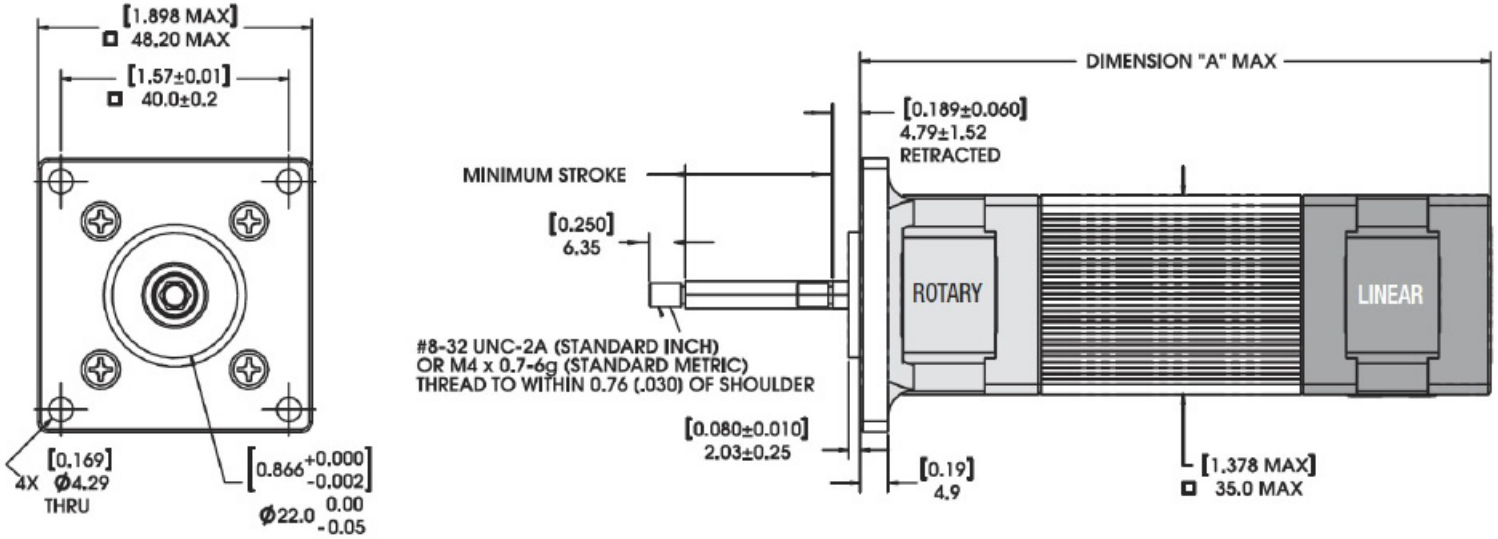
*Values truncated. Standard motors are Class B rated for maximum temperature of 130°C.

Identifying the Series 35000 Series Dual Motion Part Number Codes when Ordering

LR	35	H	H	4	J	05	910	
Prefix LR = Linear/Rotary	Series Number Designation 35 = 35000	Rotary Step Angle H = 1.8° K = 0.9° M = 1.8° Double Stack P = 0.9° Double Stack	Linear Step Angle H = 1.8° K = 0.9°	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	1.8° Step Angle Code ID Resolution Travel/Step U = .00006-in (.0015) AA = .000098-in (.0025) N = .00012-in (.0030) AB = .00019-in (.005) K = .00024-in (.0061) AC = .00039-in (.01) J = .00048-in (.0121) AD = .00078-in (.02) AE = .00157-in (.04)	0.9° Step Angle Code ID Resolution Travel/Step BP = .00003-in (.00076) AY = .00005-in (.00125) U = .00006-in (.0015) AA = .000098-in (.0025) N = .00012-in (.0030) AB = .00019-in (.005) K = .00024-in (.0061) AC = .00039-in (.01) AD = .00078-in (.02)	Voltage 05 = 5 VDC 12 = 12 VDC SP = Mixed Voltages Custom V available	Suffix Stroke Example: -910 = 1-in (26 mm) -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441. See 35000 Series Hybrid Linear Data Sheet for More Detailed Motor Information.

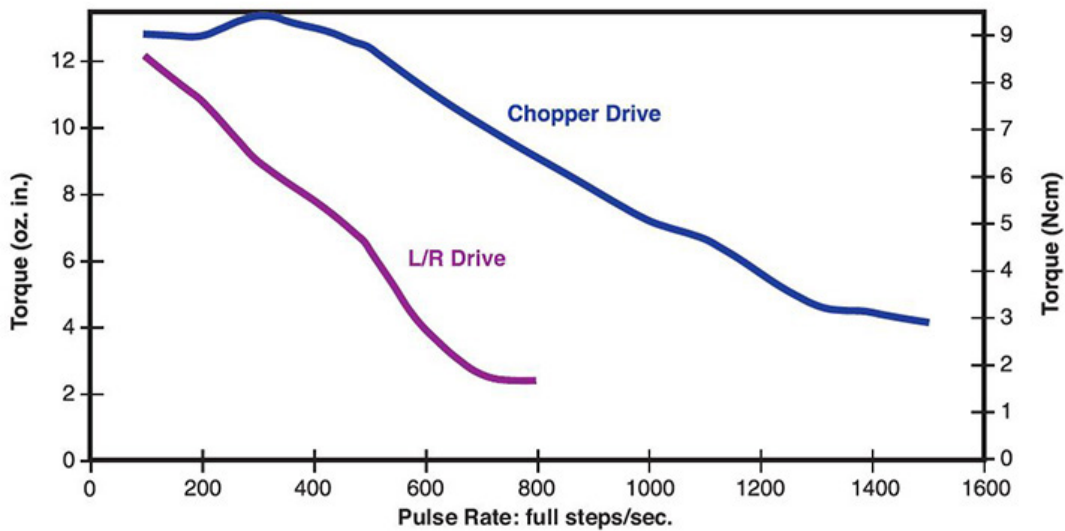
Dimensions = (mm) inches



Stroke	Dim. "A"	Suffix #	M4x0.7 Thread
0.500 (12.7)	3.9 (99.3)	-905	-805
1.00 (25.4)	4.409 (112.0)	-910	-810
2.00 (50.8)	5.409 (137.4)	-920	-820
4.00 (101.6)	7.409 (188.2)	-925	-825

Standard strokes available:
 1-in. (26 mm), 2-in. (51 mm) and 4-in. (102 mm).
 Customized strokes available to 6-in. (152 mm)

TORQUE vs. PULSE RATE: ROTARY FUNCTION – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Dual Motion Size 17 Linear/Rotary Actuators

Provide linear and rotary motions, controllable independently of one another.

For a rotary/linear motor, it is desirable that the linear and rotary motions be controllable independently of one another. These devices can be run using a standard two axis stepper motor driver. Performance can be enhanced using chopper and/or microstepping drives.

The actuators are based on unique, patented designs and incorporate proven motor technology. These units simplify product development by replacing what would otherwise be far more bulky and complex mechanisms.

Encoders available. US Digital E5 for linear, E6 for rotary.



43000 Series Dual Motion
with 57 mm NEMA

Identifying the Series 43000 Series Dual Motion Part Number Codes when Ordering

LR	43	H	H	4	J	05	910	
Prefix LR = Linear/Rotary	Series Number Designation 43 = 43000	Rotary Step Angle H = 1.8° K = 0.9° M = 1.8° Double Stack P = 0.9° Double Stack	Linear Step Angle H = 1.8° K = 0.9°	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	1.8° Step Angle Code ID Resolution Travel/Step N = .00012-in (.003) 7 = .000125-in (.0031) P = .00015625-in (.0039) AB = .00019-in (.005) K = .00024-in (.006) 9 = .00025-in (.0063) A = .0003125-in (.0079) AC = .00039-in (.01) J = .00048-in (.0121) 3 = .0005-in (.0127) B = .000625-in (.0158) AQ = .00098-in (.025) Q = .00096-in (.0243) C = 0.00125-in (.0317) BH = .00196-in (.05) R = 0.00192-in (.0487) Y = .0025-in (.0635) AG = .00375-in (.0953) Z = .005-in (.127)	0.9° Step Angle Code ID Resolution Travel/Step U = .00006-in (.0015) BB = .0000625-in (.0016) V = .00007825-in (.00198) AA = .000098-in (.0025) N = .00012-in (.003) 7 = .000125-in (.0031) P = .00015625-in (.0039) AB = .00019-in (.005) K = .00024-in (.006) 9 = .00025-in (.0063) A = .0003125-in (.0079) BG = .00049-in (.0125) J = .00048-in (.0121) B = .000625-in (.0158) AQ = .00098-in (.025) Q = .00096-in (.0243) C = .00125-in (.0317) AF = .001875-in (.0476) Y = .0025-in (.0635)	Voltage 05 = 5 VDC 12 = 12 VDC SP = Mixed Voltages Custom V available	Suffix Stroke Example: -910 = 1-in (26 mm) -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441. See 43000 Series Hybrid Linear Data Sheet for More Detailed Motor Information.

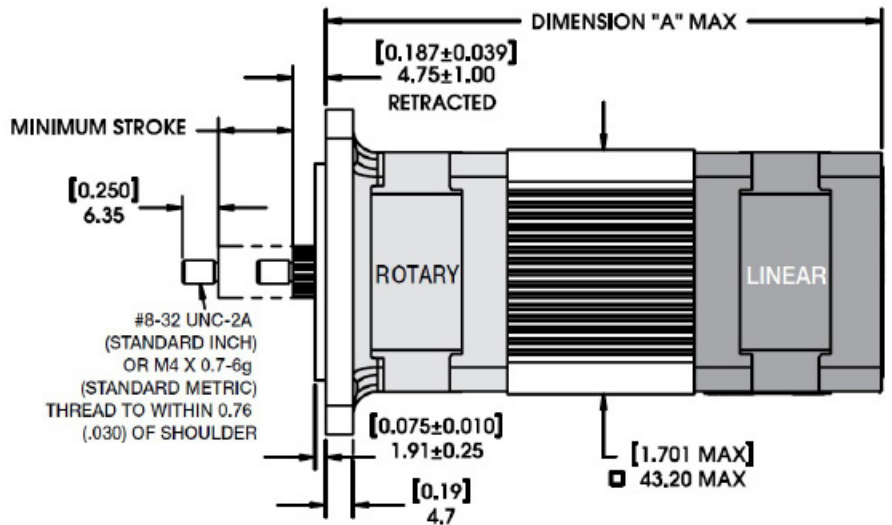
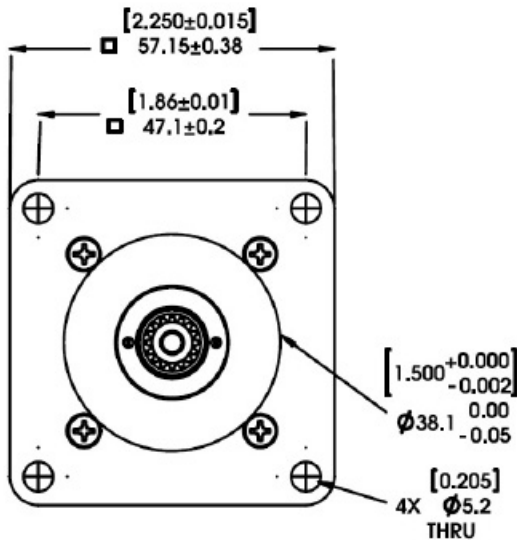
43000 Series: 1.8° Step Angle				
Linear Travel / Step		Load Limit		Order Code I.D.
inches	mm	lbs	N	
0.00012	0.003*	30	133	N
0.000125	0.0031*	30	133	7
0.00015625	0.0039*	30	133	P
0.00019*	0.005	30	133	AB
0.00024	0.0060*	30	133	K
0.00025	0.0063*	30	133	9
0.0003125	0.0079*	50	222	A
0.00039*	0.01	50	222	AC
0.00048	0.0121*	50	222	J
0.0005	0.0127*	50	222	3
0.000625	0.0158*	50	222	B
0.00098*	0.025	50	222	AQ
0.00096	0.0243*	50	222	Q
0.00125	0.0317*	50	222	C
0.00196*	0.05	50	222	BH
0.00192	0.0487*	50	222	R
0.0025	0.0635	50	222	Y
0.00375	0.0953*	50	222	AG
0.005	0.127	50	222	Z

*Values truncated. Standard motors are Class B rated for maximum temperature of 130°C.

43000 Series: 0.9° Step Angle				
Linear Travel / Step		Load Limit		Order Code I.D.
inches	mm	lbs	N	
0.00006	0.0015*	30	133	U
0.0000625	0.0016*	30	133	BB
0.00007825	0.00198*	30	133	V
0.000098*	0.0025	30	133	AA
0.00012	0.003*	30	133	N
0.000125	0.0031*	30	133	7
0.00015625	0.0039*	50	222	P
0.00019*	0.005	50	222	AB
0.00024	0.0060*	50	222	K
0.00025	0.0063*	50	222	9
0.0003125	0.0079*	50	222	A
0.00049*	0.0125	50	222	BG
0.00048	0.0121*	50	222	J
0.000625	0.0158*	50	222	B
0.00098*	0.025	50	222	AQ
0.00096	0.0243*	50	222	Q
0.00125	0.0317*	50	222	C
0.001875	0.0476*	50	222	AF
0.0025	0.0635	50	222	Y

*Values truncated. Standard motors are Class B rated for maximum temperature of 130°C.

Dimensions = (mm) inches

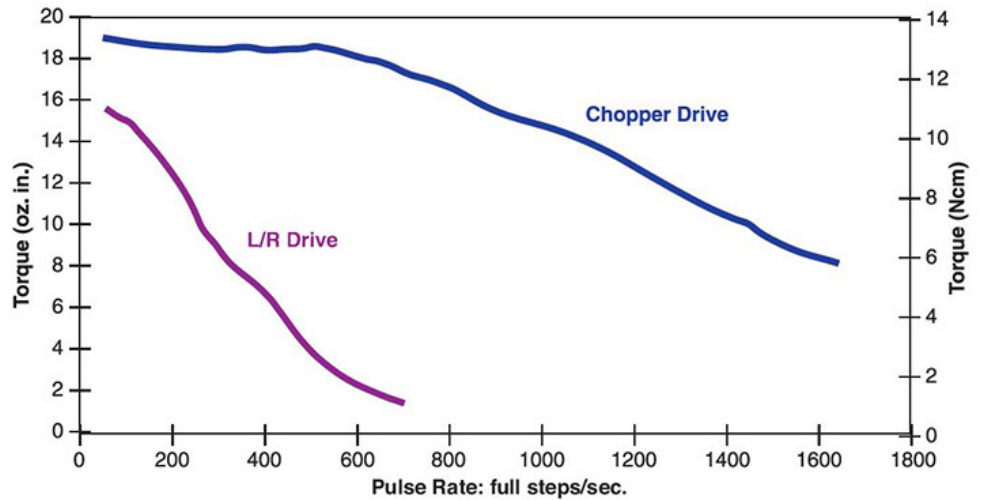


Stroke	Dim. "A"	Suffix #	M4x0.7 Thread
0.500 (12.7)	3.9 (99.3)	-905	-805
1.00 (25.4)	4.409 (112.0)	-910	-810
2.00 (50.8)	5.409 (137.4)	-920	-820
4.00 (101.6)	7.409 (188.2)	-925	-825

Standard strokes available:
1-in. (26 mm), 2-in. (51 mm) and 4-in. (102 mm).
Customized strokes available to 6-in. (152 mm)

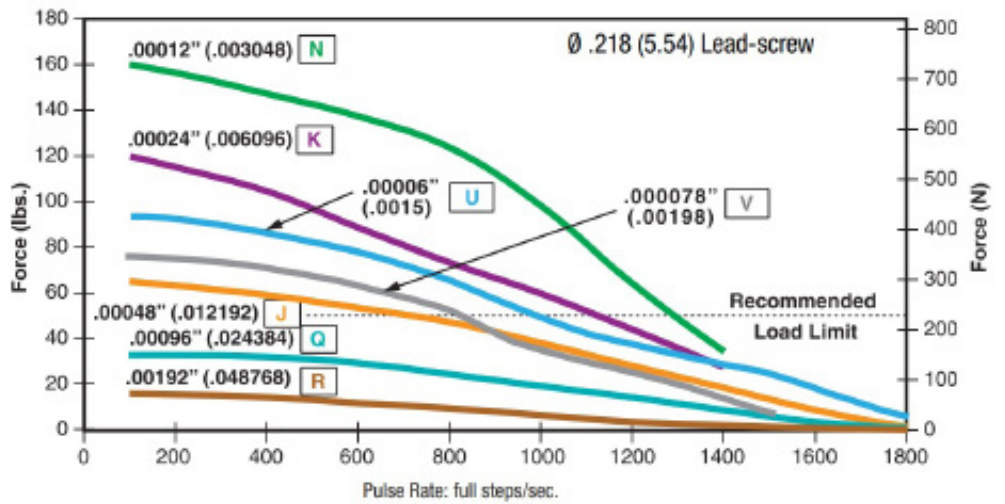
TORQUE vs. PULSE RATE: ROTARY FUNCTION

- Bipolar
- 100% Duty Cycle



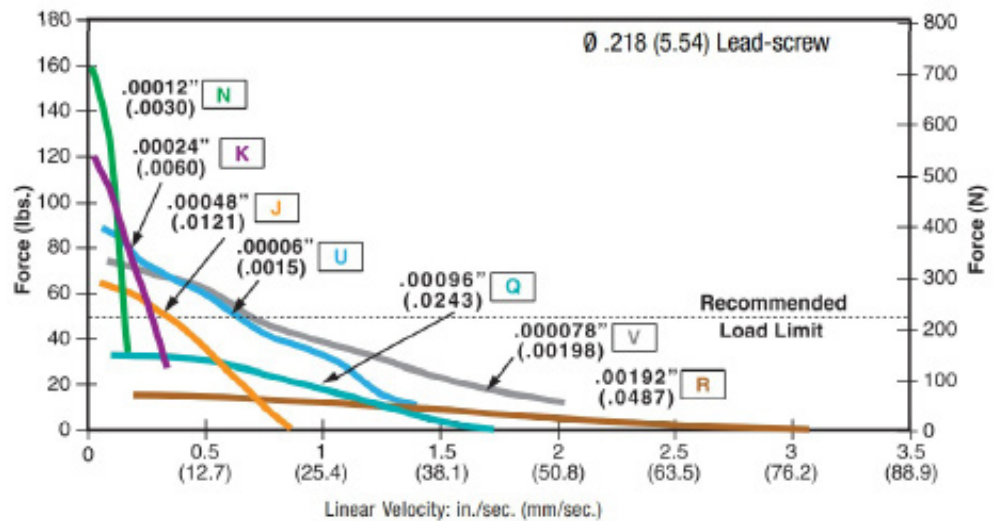
FORCE vs. PULSE RATE: LINEAR FUNCTION

- Chopper
- Bipolar
- 100% Duty Cycle
- 8:1 Motor Coil to Drive Supply Voltage



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- 8:1 Motor Coil to Drive Supply Voltage



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Can-Stack Actuators

The Haydon™ brand of can-stack stepper motor linear actuators provides both a broader range and, for a given size, significantly higher thrust than previously available from mini-steppers. Haydon Kerk Motion Solutions patented design accepts a larger rotor than conventional units, improving efficiency and eliminating the need for massive heat sinks. Unique features impart ruggedness and reliability that assure long life and consistent performance. Rare earth magnets are available for even higher thrust. All units are built with dual ball bearings for greater motion control, precise step accuracy and long life.

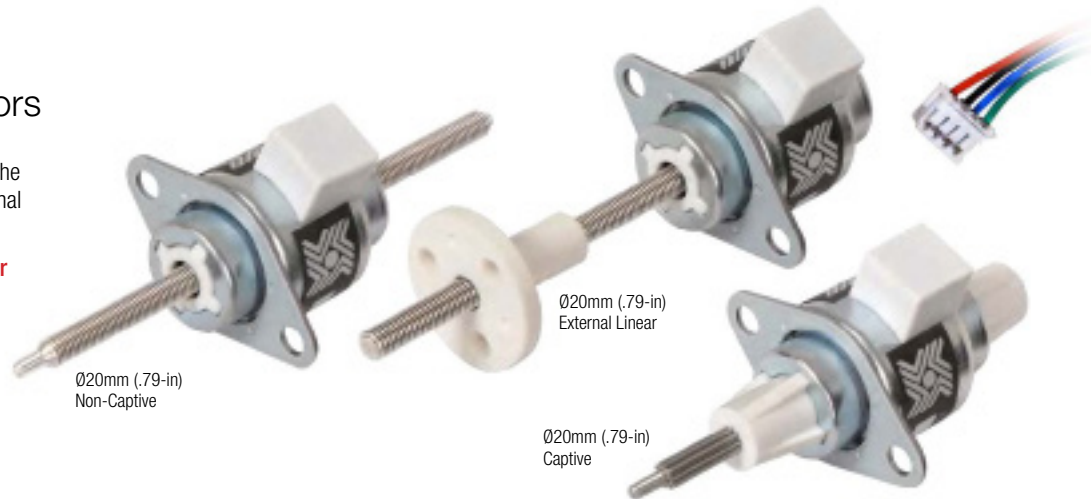
G4 19000 Series Ø 20 mm (.79-in) Can-Stack Stepper Motor Linear Actuators

Utilizing high energy rare earth (neodymium) magnets, the G4 Series linear actuators consistently deliver exceptional performance. All units are built with dual ball bearings.

The highest force of any similar size linear actuator stepper motor

Multiple versions available

- Captive
- Non-Captive
- External Linear



Specifications

Ø 20 mm (.79-in) Motor				
Part No.	Captive	1944	1954	
	Non-Captive	1934	1984	
	External Linear*	E1944	E1954	
Wiring	Bipolar			
Step angle	7.5°		15°	
Winding Voltage	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	350 mA	160 mA	338 mA	140 mA
Resistance/phase	14.0 Ω	74.5 Ω	14.8 Ω	85.5 Ω
Inductance/phase	6.24 mH	31.2 mH	6.84 mH	37.8 mH
Power Consumption	3.38 W			
Insulation Class	Class B			
Weight	1.24 oz (35 g)			
Insulation Resistance	20 MΩ			

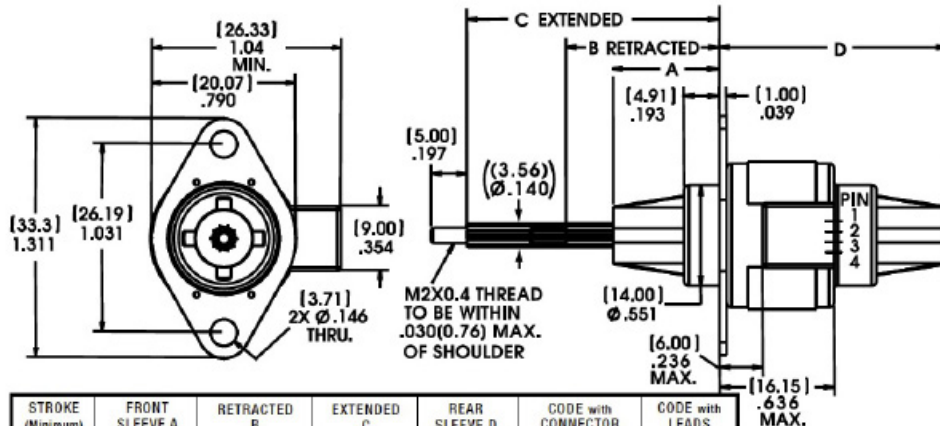
Linear Travel / Step 15° Step Angle			Order Code I.D.
step	inches	mm	
7.5° Angle	0.0005	0.013	3
	0.001	0.0254	1
	0.002	0.051	2
15° Angle	0.001	0.0254	1
	0.002	0.051	2
	0.004	0.102	4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

*Part numbering information on page 147.

Captive Lead Screw

Dimensions = (mm) inches

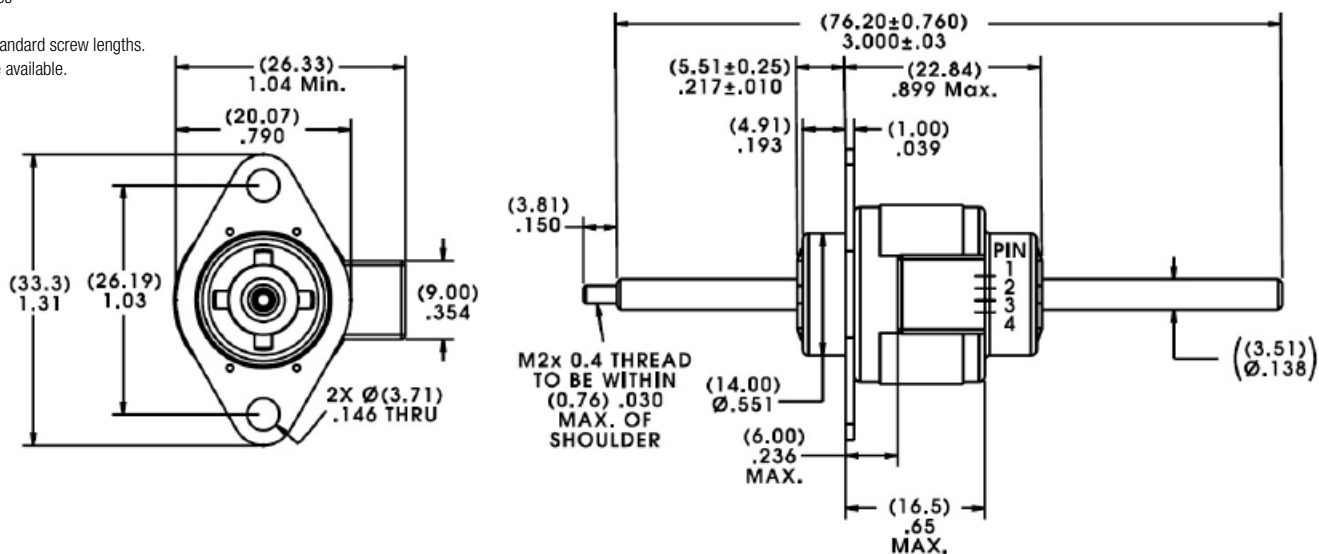


STROKE (Minimum)	FRONT SLEEVE A	RETRACTED B	EXTENDED C	REAR SLEEVE D	CODE with CONNECTOR	CODE with LEADS
(13 mm) .512	(14.75±0.25) .581±.010	(21.37±0.64) .841±.025	(35.17±0.38) 1.385±.015	(32.08 Max.) 1.263 Max.	- 905	- 1005
(18 mm) .708	(20.05±0.25) .789±.010	(26.67±0.64) 1.050±.025	(45.77±0.38) 1.802±.015	(37.38 Max.) 1.472 Max.	- 907	- 1007
(25 mm) .984	(27.05±0.25) 1.065±.010	(33.67±0.64) 1.325±.025	(59.77±0.38) 2.353±.015	(44.38 Max.) 1.747 Max.	- 910	- 1010
(31 mm) 1.22	(33.05±0.25) 1.301±.010	(39.67±0.64) 1.562±.025	(71.77±0.38) 2.826±.015	(50.78 Max.) 2.000 Max.	- 912	- 1012

Non-Captive Lead Screw

Dimensions = (mm) inches

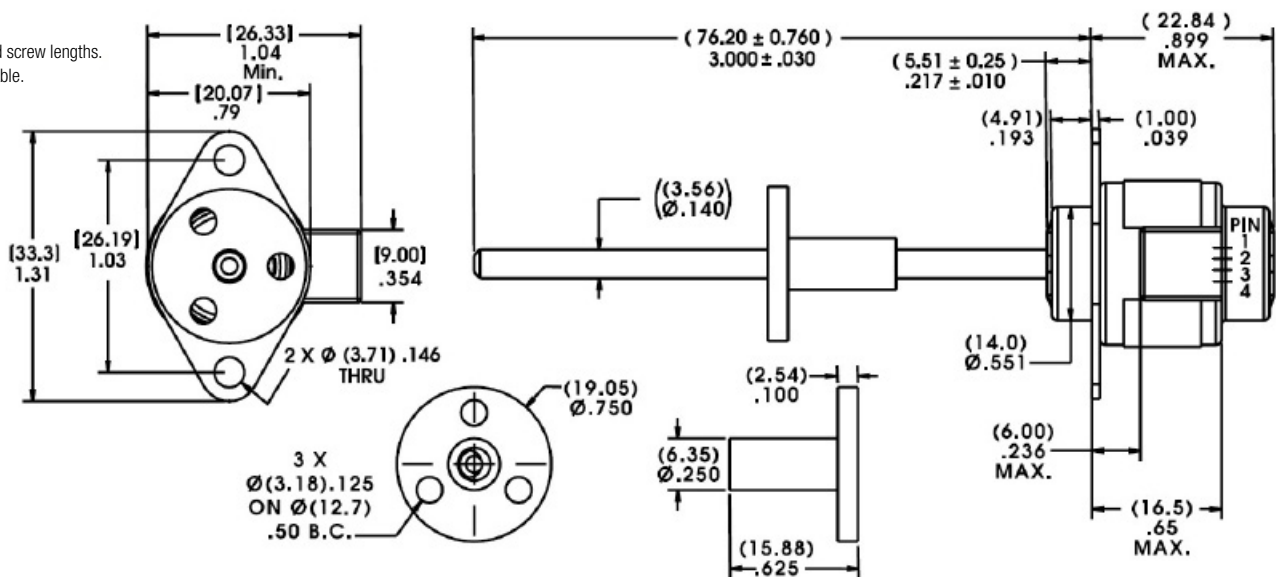
Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.



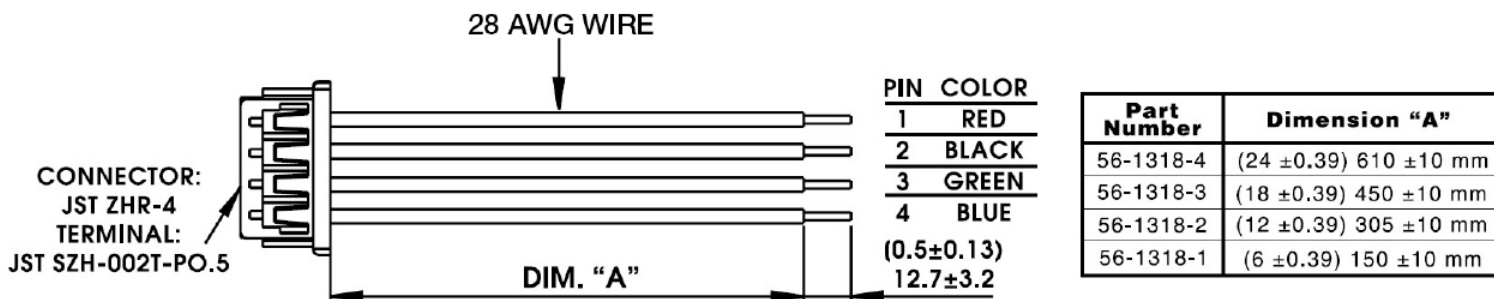
External Linear

Dimensions = (mm) inches

Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.

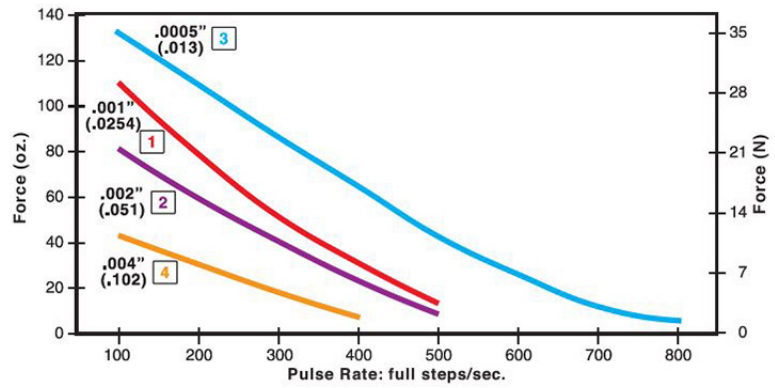


Connector



FORCE vs. PULSE RATE

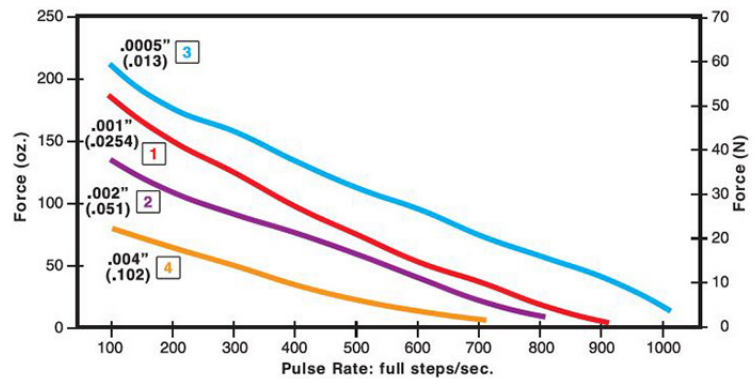
- L/R Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

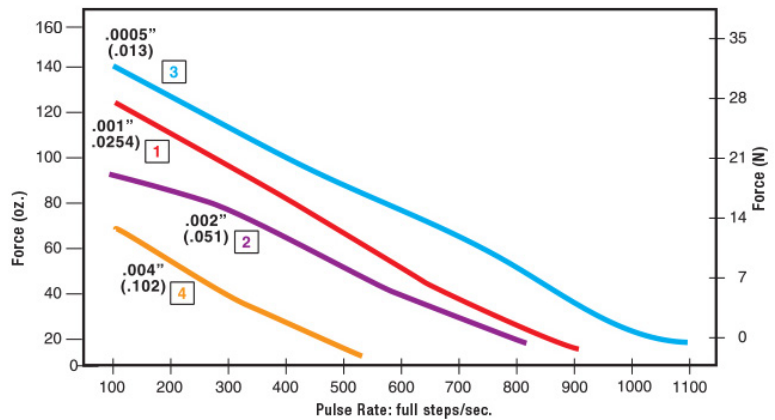
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



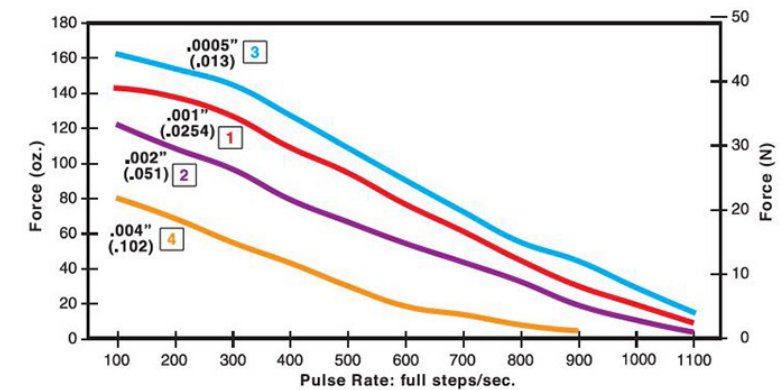
FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

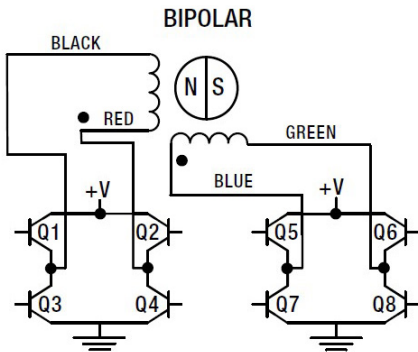
Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

Identifying the Can-Stack Number Codes when Ordering

E	19	5	4	2	05	1005
Prefix (include only when using the following) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 19 = 19000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version) 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1005 = captive 13mm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Can-Stacks: Wiring



Can-Stacks: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

EXTEND CW ↓ ↑ RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

■ Can-Stack Stepper Motor Linear Actuators Options

TFE Coated Lead Screws for applications that require a permanent, dry lubricant

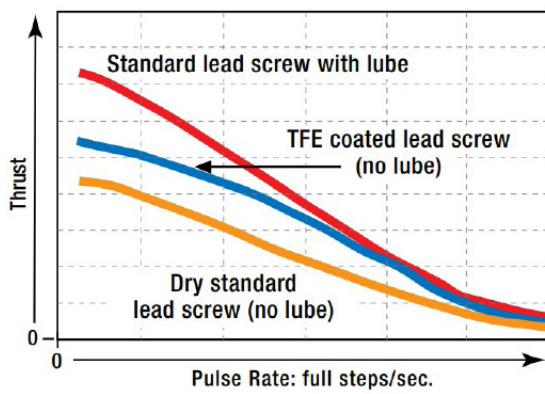
Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

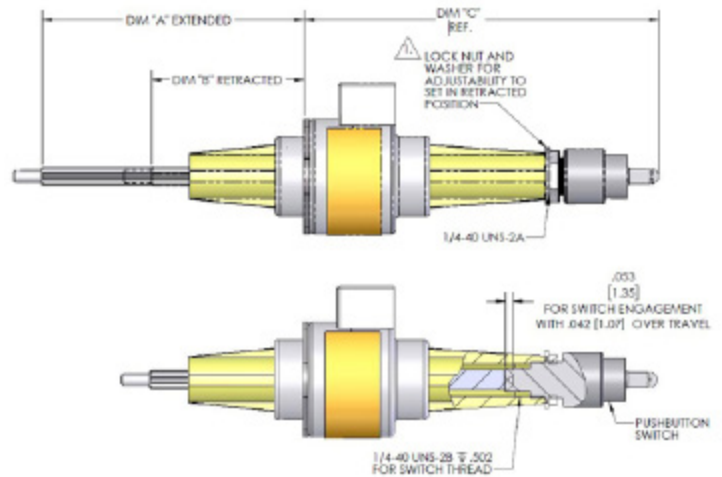
Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

Lead Screw Comparison: FORCE vs. PULSE RATE

- L/R Drive - 100% Duty Cycle



G4 19000 Series
External Linear



Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 millionths typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	 Multiple contact options available.

NOTE:
1. ADJUST LOCATION OF LOCK NUT TO ENSURE THE RETRACTED DIMENSION



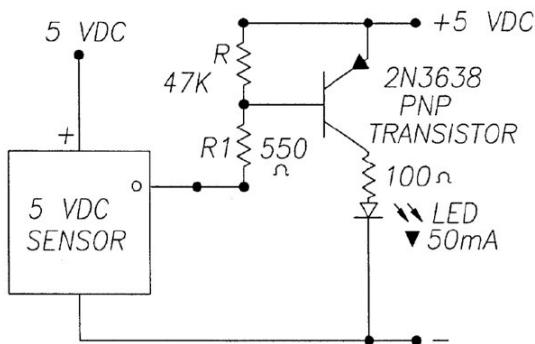
Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.512 (13)	1.385 +/- .015 (35.17 +/- 0.38)	.841 +/- .025 (21.37 +/- 0.64)	2.230 +/- .025 (56.63 +/- 0.64)
.708 (18)	1.802 +/- .015 (45.77 +/- 0.38)	1.050 +/- .025 (26.67 +/- 0.64)	2.438 +/- .025 (61.93 +/- 0.64)
.984 (25)	2.353 +/- .015 (59.77 +/- 0.38)	1.325 +/- .025 (33.67 +/- 0.64)	2.714 +/- .025 (68.93 +/- 0.64)
1.22 (31)	N/A Contact Customer Service		

■ Can-Stack Stepper Motor Linear Actuators Options

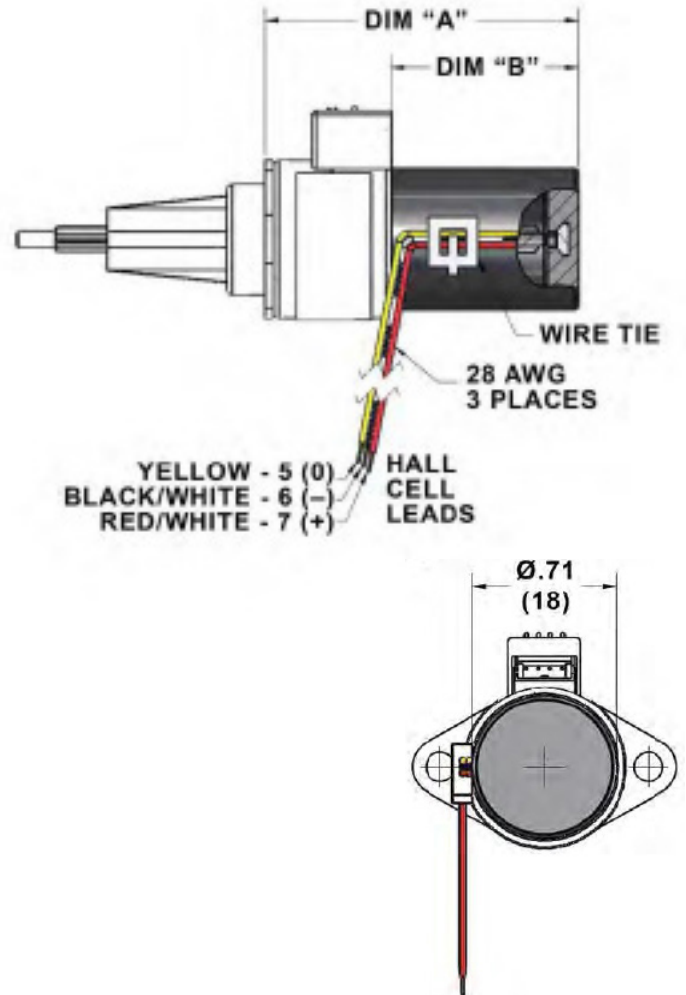
End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specifications	
Supply Voltage (VDC)	3.8 min. to 24 max.
Current Consumption	10 mA max.
Output Voltage (operated)	0.15 typ., 0.40 max. Sinking 20 mA max.
Output Current	20 mA max.
Output Leakage Current (released)	10µA max. @ Vout = 24 VDC; Vcc = 24 VDC
Output Switching Time	Rise, 10 to 90% .05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 KOhm
	Fall, 90 to 10% .15 µs typ., 1.5 µs max. @ CL = 20 pF
Temperature	- 40 to +150°C



NOTE: Sensor is category 2 ESD sensitive per DOD-STD-1686A. Assembly operations should be performed at workstations with conductive tops and operators grounded.



Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)
.512 (13)	1.360 (34.55)	.73 (18.55)
.708 (18)	1.569 (39.85)	.94 (23.85)
.984 (25)	1.844 (46.85)	1.21 (30.85)
1.22 (31)	2.081 (52.85)	1.45 (36.85)

The sensor has virtually unlimited cycle life. Special cabling and connectors can also be provided.

G4 25000 Series Ø 25 mm (1.0-in) Can-Stack Stepper Motor Linear Actuators

High durability and exceptional performance.
All units are built with dual ball bearings.

Generates higher force than other competitors

Multiple versions available

- Captive
- Non-Captive
- External Linear



Specifications

Ø 25 mm (1.0-in) Motor				
Part No.	Captive	2544	†	
	Non-Captive	2534	†	
	External Linear*	E2544	†	
Wiring		Bipolar		
Step angle		7.5°		15°
Winding Voltage		5 VDC	12 VDC	5 VDC 12 VDC
Current (RMS)/phase		385 mA	160 mA	385 mA 160 mA
Resistance/phase		13 Ω	72 Ω	13 Ω 72 Ω
Inductance/phase		10.8 mH	60 mH	8.08 mH 48 mH
Power Consumption		3.85 W		
Rotor Inertia		1.07 gcm ²		
Insulation Class		Class B		
Weight		1.74 oz (49 g)		
Insulation Resistance		20 MΩ		

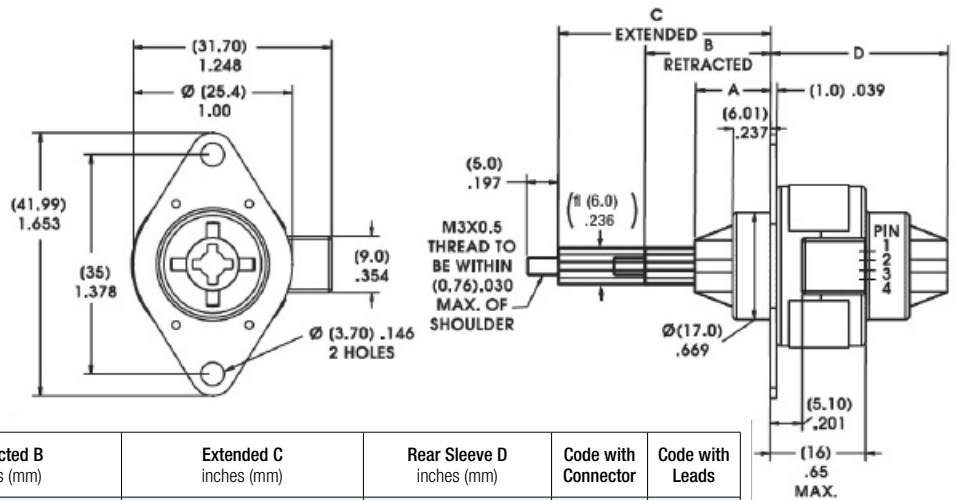
Linear Travel / Step 15° Step Angle			Order Code I.D.
step	inches	mm	
7.5° Angle	0.0005	0.013	3
	0.001	0.0254	1
	0.002	0.051	2
15° Angle	0.001	0.0254	1
	0.002	0.051	2
	0.004	0.102	4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

*Part numbering information on page 153.

Captive Lead Screw

Dimensions = (mm) inches

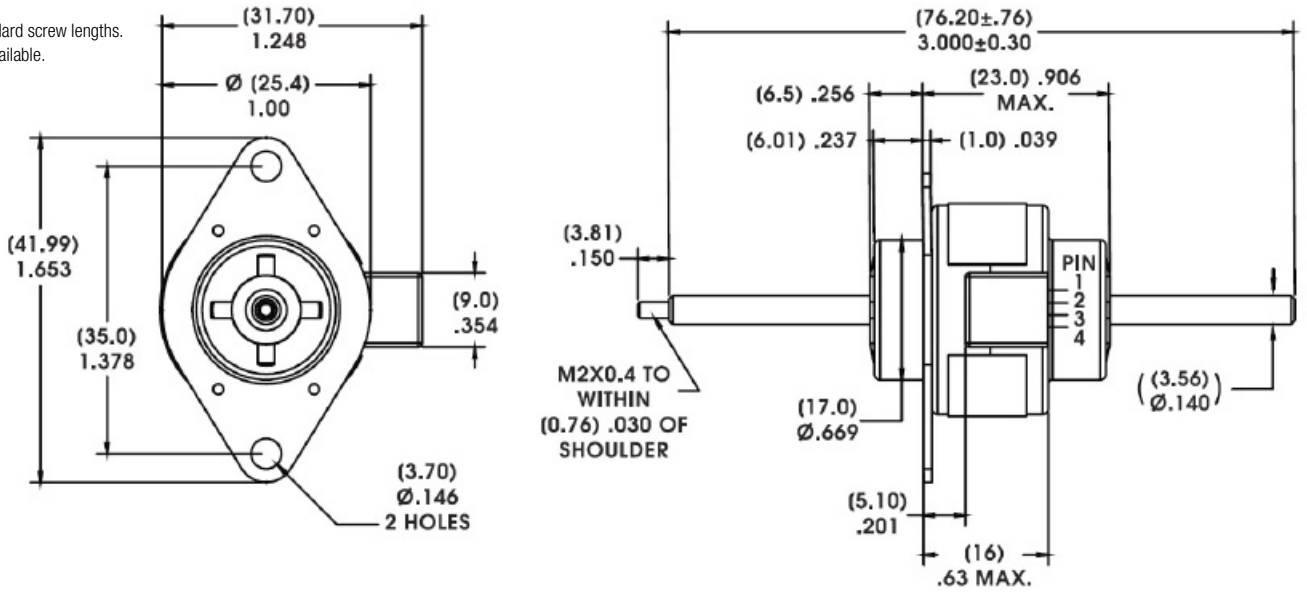


Stroke (Minimum) inches (mm)	Front Sleeve A inches (mm)	Retracted B inches (mm)	Extended C inches (mm)	Rear Sleeve D inches (mm)	Code with Connector	Code with Leads
.512 (13 mm)	.472 +/- .010 (11.99 +/- 0.25)	.787 +/- .025 (19.99 +/- 0.64)	1.329 +/- .015 (33.76 +/- 0.38)	1.128 Max. (28.65 Max.)	- 905	- 1005
.708 (18 mm)	.680 +/- .010 (17.28 +/- 0.25)	.994 +/- .025 (25.25 +/- 0.64)	1.743 +/- .015 (44.27 +/- 0.38)	1.336 Max. (33.94 Max.)	- 907	- 1007
.984 (25 mm)	.955 +/- .010 (24.26 +/- 0.25)	1.269 +/- .025 (32.23 +/- 0.64)	2.293 +/- .015 (58.24 +/- 0.38)	1.611 Max. (40.92 Max.)	- 910	- 1010
1.22 (31 mm)	1.191 +/- .010 (30.25 +/- 0.25)	1.505 +/- .025 (38.23 +/- 0.64)	2.765 +/- .015 (70.23 +/- 0.38)	1.847 Max. (46.91 Max.)	- 912	- 1012

Non-Captive Lead Screw

Dimensions = (mm) inches

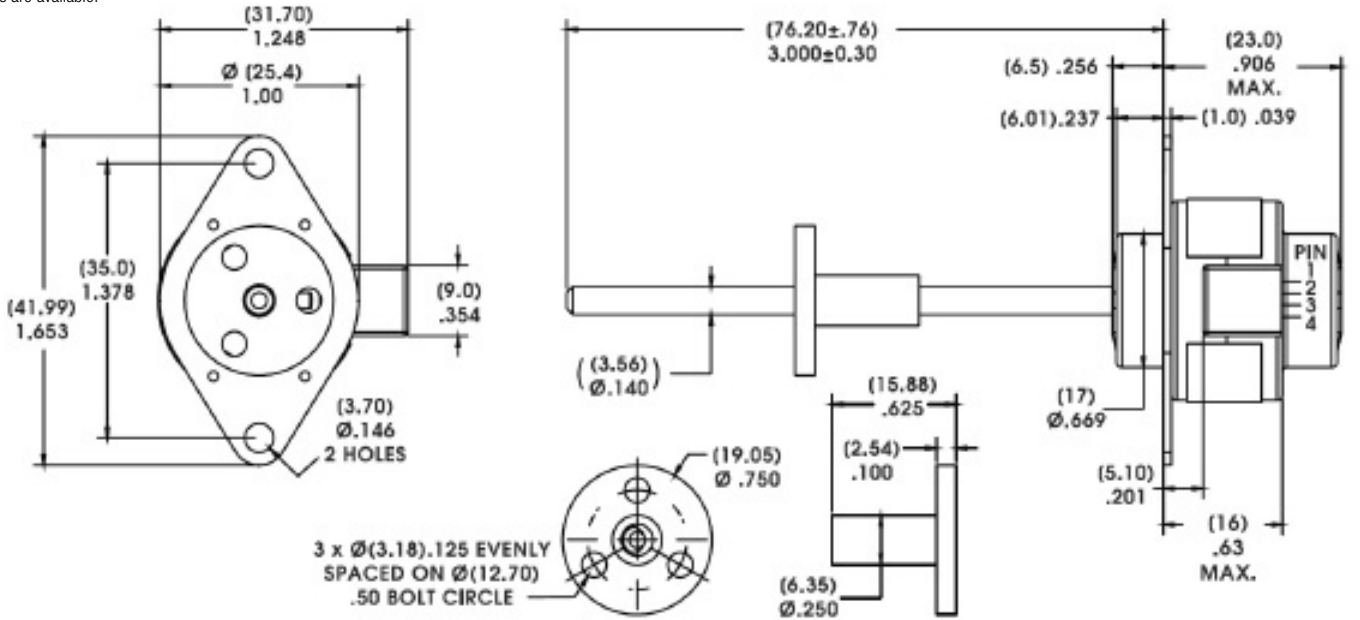
Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.



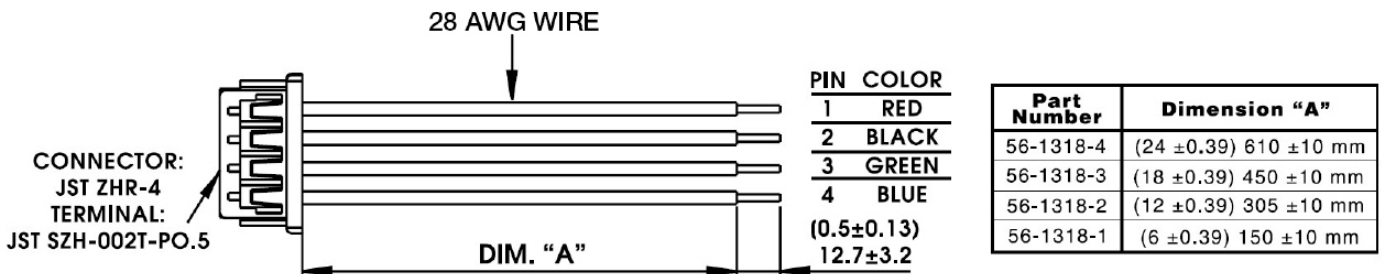
External Linear

Dimensions = (mm) inches

Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.

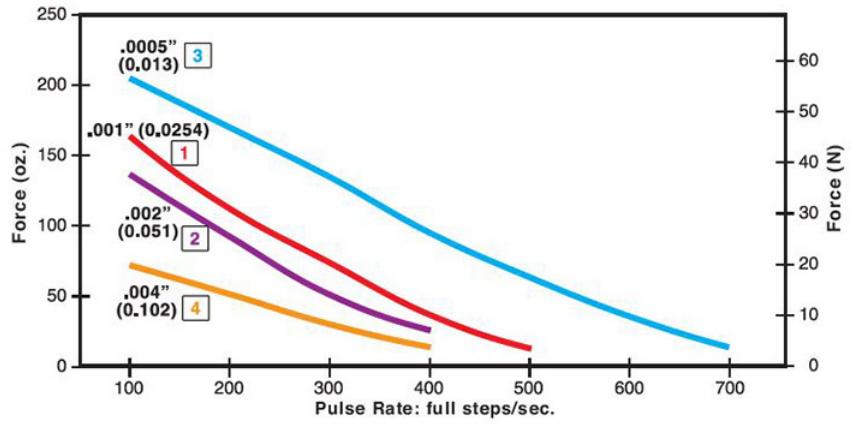


Connector



FORCE vs. PULSE RATE

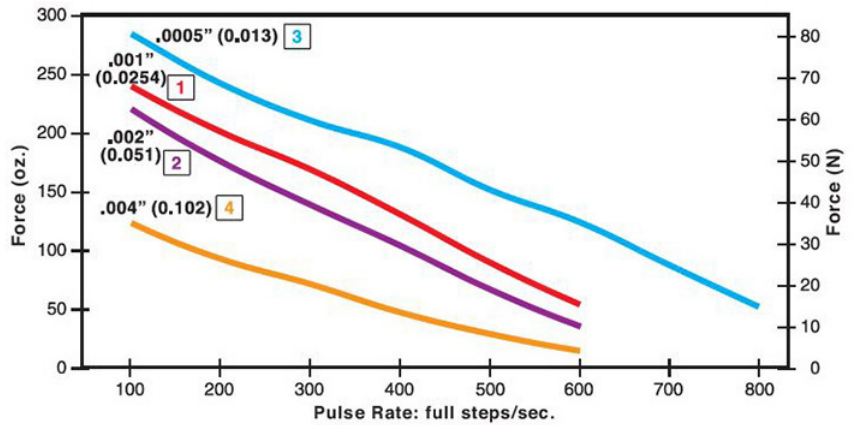
- L/R Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

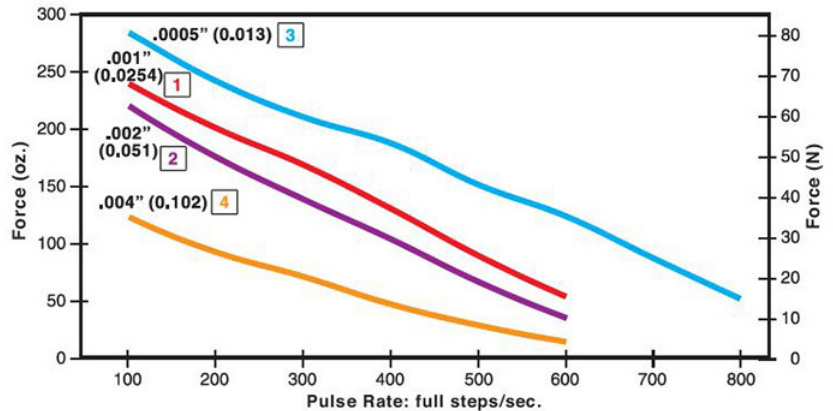
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



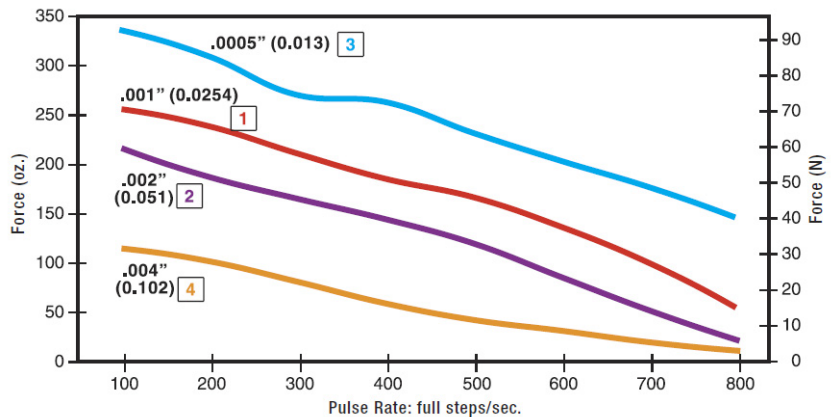
FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

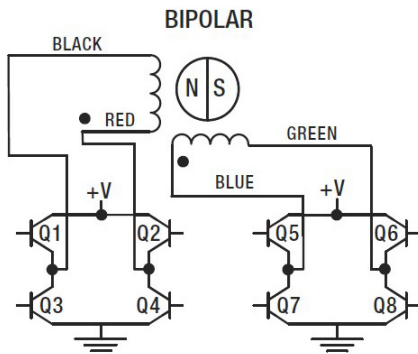
Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

Identifying the Can-Stack Number Codes when Ordering

E	25	5	4	4	12	1010
Prefix (include only when using the following) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 25 = 25000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version) 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1010 = captive 25mm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Can-Stacks: Wiring



Can-Stacks: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

EXTEND CW ↓ RETRACT CCW ↑

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

■ Can-Stack Stepper Motor Linear Actuators Options

TFE Coated Lead Screws for applications that require a permanent, dry lubricant

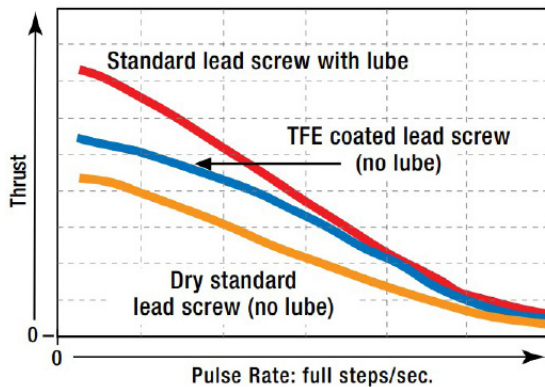
Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a “dry” stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

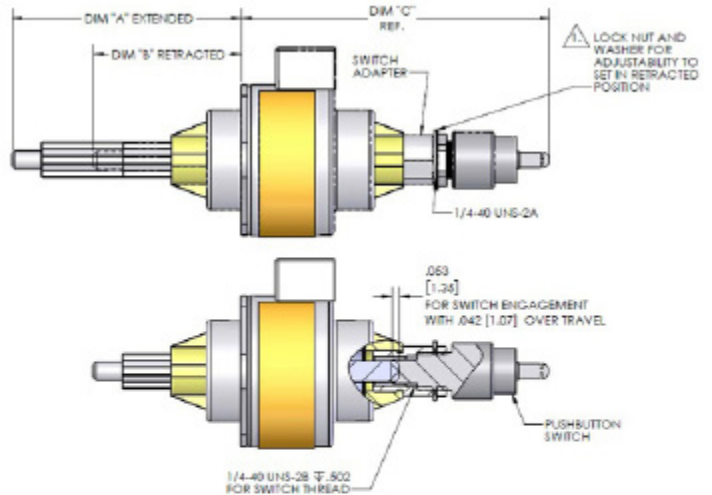
Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

Lead Screw Comparison: FORCE vs. PULSE RATE

– L/R Drive – 100% Duty Cycle



G4 25000 Series External Linear

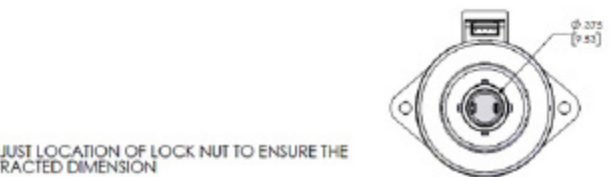


Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an “S”.



Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	 Multiple contact options available.

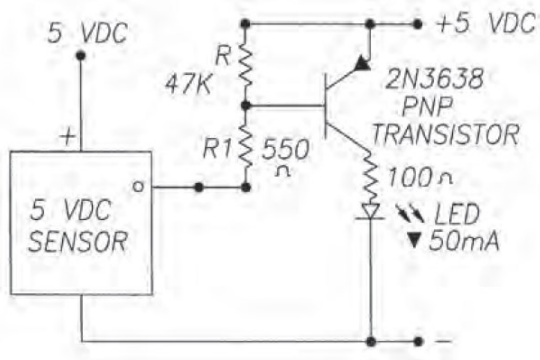
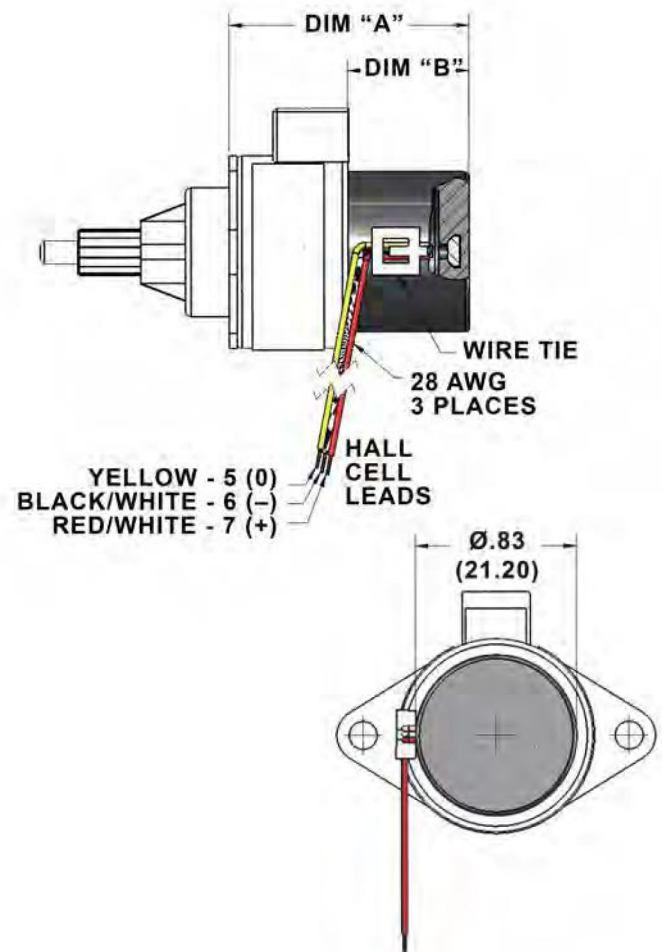
Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.512 (13)	1.329 +/- .025 (33.76 +/- 0.64)	.787 +/- .025 (19.99 +/- 0.64)	2.051 +/- .025 (52.09 +/- 0.64)
.708 (18)	1.743 +/- .025 (44.27 +/- 0.64)	.994 +/- .025 (25.25 +/- 0.64)	2.258 +/- .025 (57.35 +/- 0.64)
.984 (25)	2.293 +/- .025 (58.24 +/- 0.64)	1.269 +/- .025 (32.23 +/- 0.64)	2.534 +/- .025 (64.37 +/- 0.64)
1.22 (31)	2.765 +/- .025 (70.23 +/- 0.64)	1.505 +/- .025 (38.23 +/- 0.64)	2.770 +/- .025 (70.37 +/- 0.64)

■ Can-Stack Stepper Motor Linear Actuators Options

End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specifications	
Supply Voltage (VDC)	3.8 min. to 24 max.
Current Consumption	10 mA max.
Output Voltage (operated)	0.15 typ., 0.40 max. Sinking 20 mA max.
Output Current	20 mA max.
Output Leakage Current (released)	10µA max. @ Vout = 24 VDC; Vcc = 24 VDC
Output Switching Time	Rise, 10 to 90% .05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 KOhm
	Fall, 90 to 10% .15 µs typ., 1.5 µs max. @ CL = 20 pF
Temperature	- 40 to +150°C



Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)
.512 (13)	1.248 (31.71)	.632 (16.05)
.708 (18)	1.449 (36.81)	.833 (21.15)
.984 (25)	1.723 (43.76)	1.106 (28.10)
1.22 (31)	1.959 (49.76)	1.343 (34.10)

The sensor has virtually unlimited cycle life. Special cabling and connectors can also be provided.

G4 25000 Series E8T Encoder

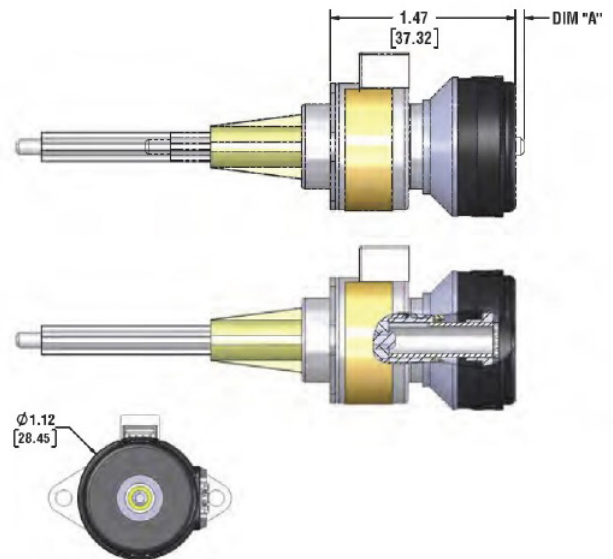
G4 25000 Series E8T Transmissive Optical Encoder is designed to provide the digital quadrature encoder feedback for high volume, compact space applications.

- Resolutions from 180 to 720
- Single-ended / Differential
- Frequency response to 100 kHz
- Low power consumption, 5 V @ 30 mA max
- High retention polarized connector

Assembly Options:

- Differential line driver with complementary outputs
- Detachable cable
- Through-hole cover

Stroke inches (mm)	Dim "A" Extended inches (mm)
.512 (13)	N/A
.708 (18)	N/A
.984 (25)	.071 (1.80)
1.22 (31)	.307 (7.80)



G4 37000 Series Ø 36 mm (1.4-in) Can-Stack Stepper Motor Linear Actuators

Outstanding durability and high performance. The G4 Series features high energy neodymium magnets and dual ball bearings.

Exceptionally high linear force-to-size ratio, ideal for precision motion

Multiple versions available

- Captive
- Non-Captive
- External Linear

Ø 37mm (1.4-in)
Non-Captive

Ø 37mm (1.4-in)
External Linear

Ø 37mm (1.4-in)
Captive



Specifications

Ø 36 mm (1.4-in) Motor									
Part No.	Captive	3744	-	-	†	3754	-	-	†
	Non-Captive	3734	-	-	†	3784	-	-	†
	External Linear	E3744	-	-	†	E3754	-	-	†
Wiring		Bipolar							
Step angle		7.5°				15°			
Winding Voltage		5 VDC		12 VDC		5 VDC		12 VDC	
Current (RMS)/phase		561 mA		230 mA		561 mA		230 mA	
Resistance/phase		8.9 Ω		52 Ω		8.9 Ω		52 Ω	
Inductance/phase		11.6 mH		65 mH		8.5 mH		46 mH	
Power Consumption		5.6 W							
Rotor Inertia		8.5 gcm ²							
Insulation Class		Class B							
Weight		4.2 oz (120 g)							
Insulation Resistance		20 MΩ							

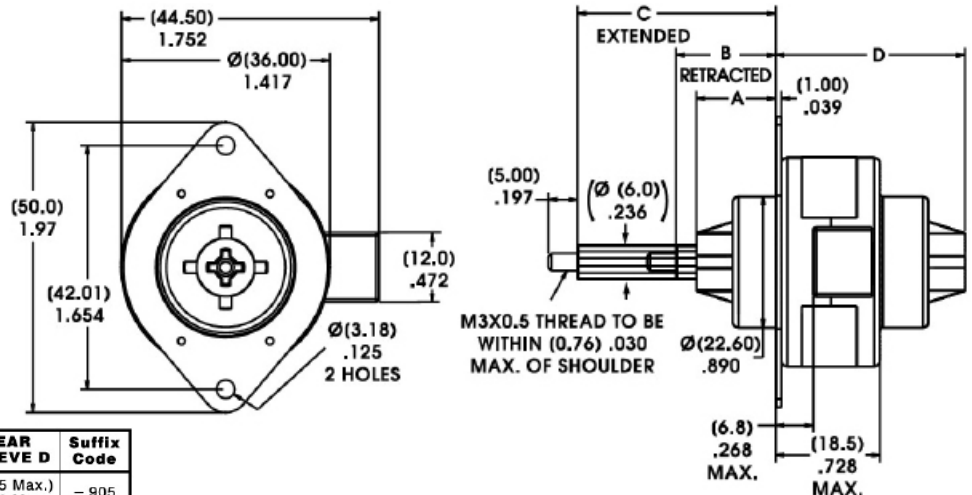
Linear Travel / Step 15° Step Angle			Order Code I.D.
step	inches	mm	
7.5° Angle	0.0005	0.013	3
	0.001	0.0254	1
	0.002	0.051	2
15° Angle	0.001	0.0254	1
	0.002	0.051	2
	0.004	0.102	4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

†Part numbering information on page 159.

Captive Lead Screw

Dimensions = (mm) inches

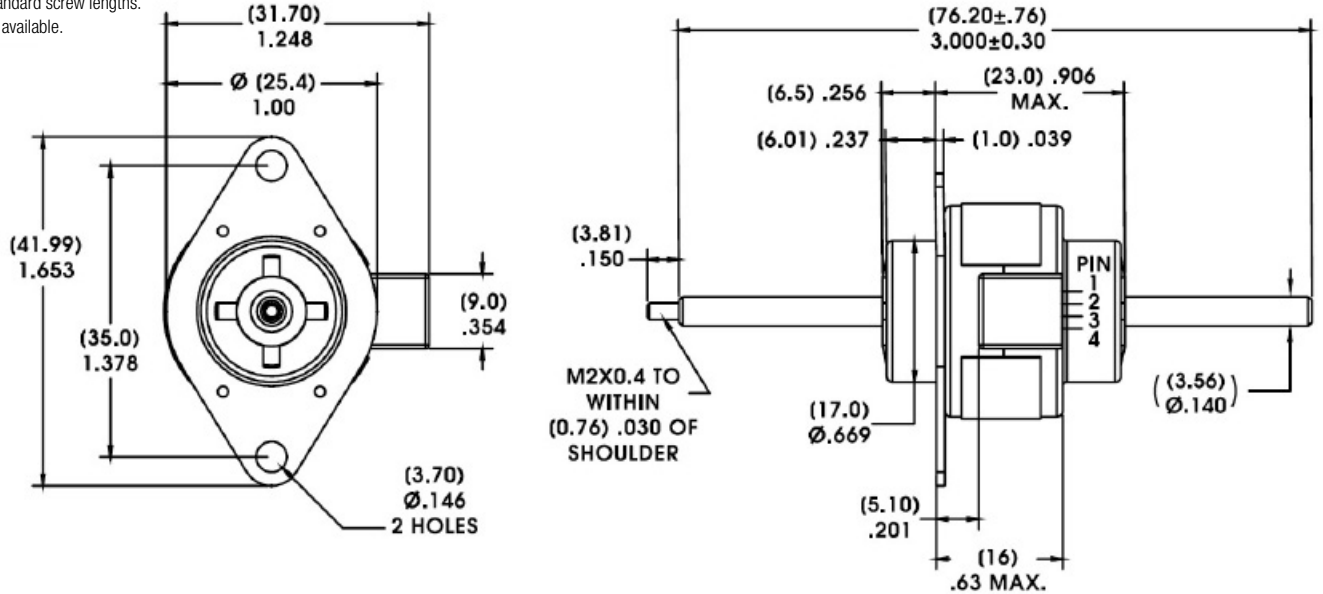


STROKE (Minimum)	FRONT SLEEVE A	RETRACTED B	EXTENDED C	REAR SLEEVE D	Suffix Code
(16.0 mm) 0.631	(13.67±0.25) .538±.010	(17.19±0.64) .677±.025	(34.24±0.38) 1.348±.015	(33.85 Max.) 1.333 Max.	- 905
(25.4 mm) 1.00	(26.37±0.25) 1.038±.010	(29.89±0.64) 1.177±.025	(56.94±0.38) 2.348±.015	(46.55 Max.) 1.833 Max.	- 910
(38.1 mm) 1.50	(39.07±0.25) 1.538±.010	(42.59±0.64) 1.677±.025	(85.04±0.38) 3.348±.015	(59.25 Max.) 2.333 Max.	- 915

Non-Captive Lead Screw

Dimensions = (mm) inches

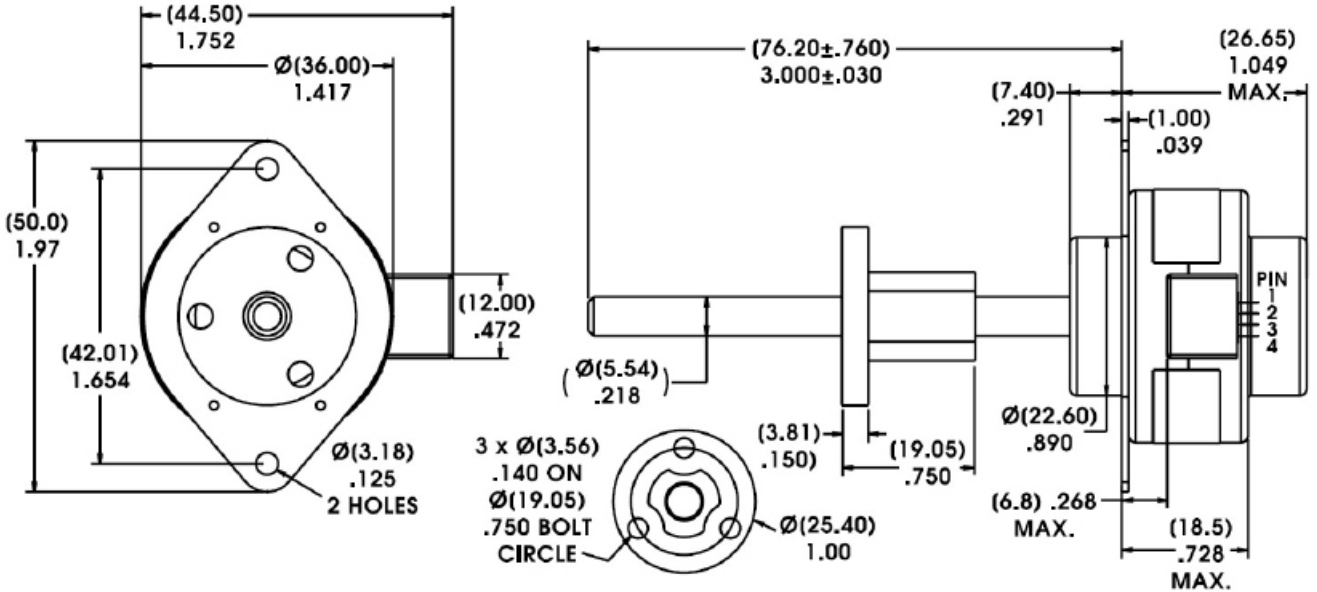
Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.



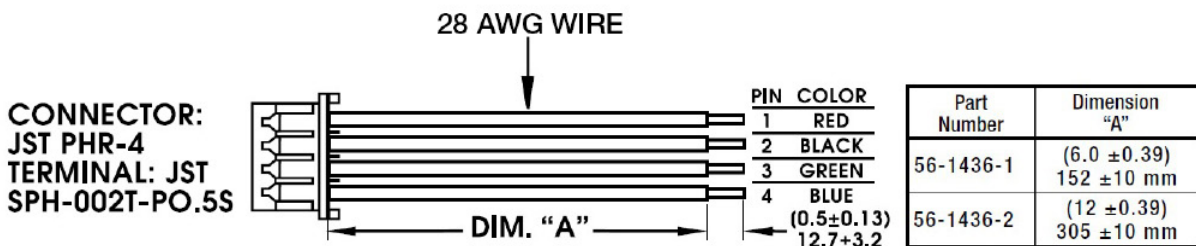
External Linear

Dimensions = (mm) inches

Up to 6.3-in (160 mm) standard screw lengths.
Longer screw lengths are available.

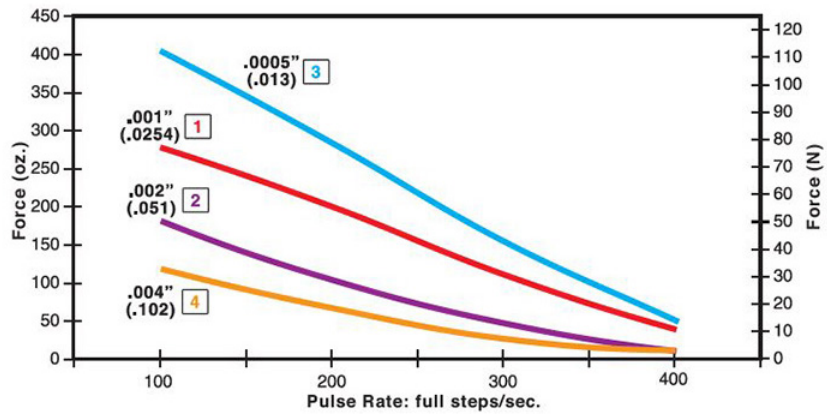


Connector



FORCE vs. PULSE RATE

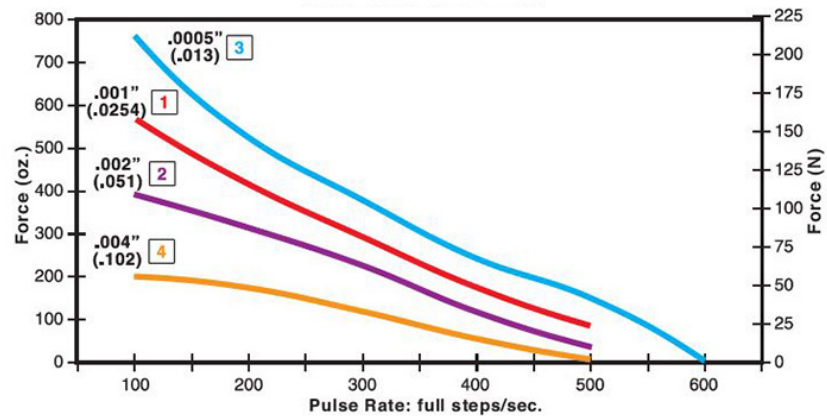
- L/R Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

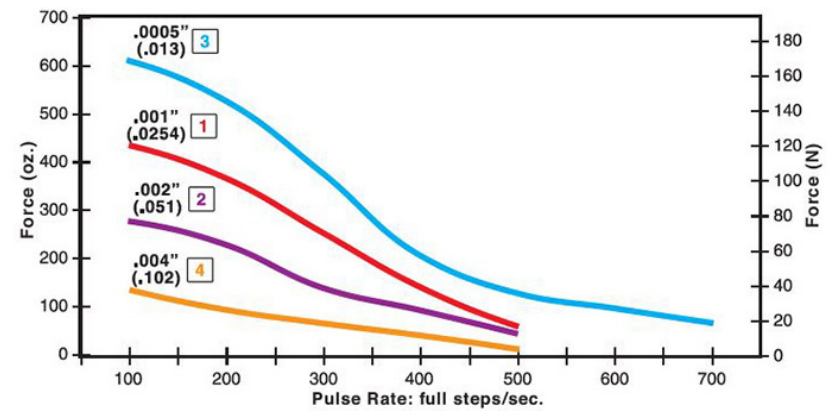
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



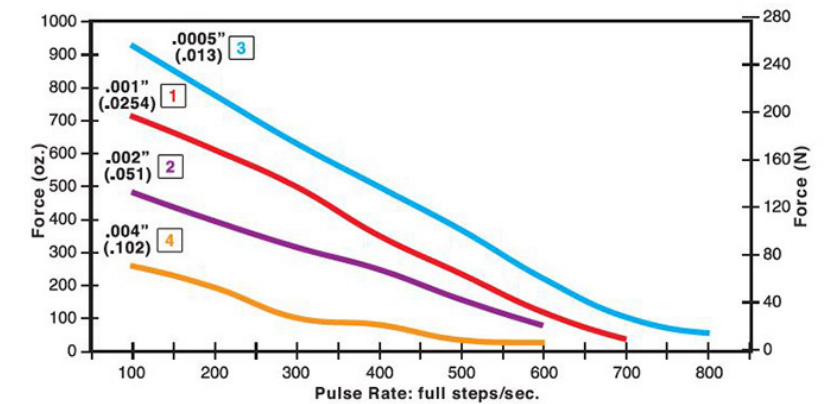
FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



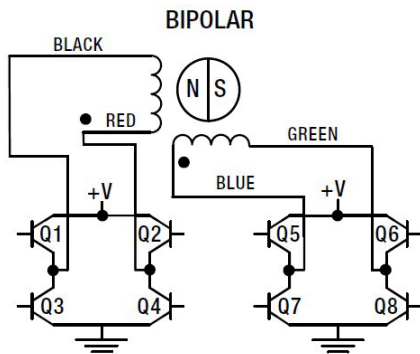
NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Actuator bearings are rated for 75 lbs. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

Identifying the Can-Stack Number Codes when Ordering

E	37	4	4	2	05	1015
Prefix (include only when using the following) E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 37 = 37000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version) 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1015 = captive 38.1mm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Can-Stacks: Wiring



Can-Stacks: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

■ Can-Stack Stepper Motor Linear Actuators Options

TFE Coated Lead Screws for applications that require a permanent, dry lubricant

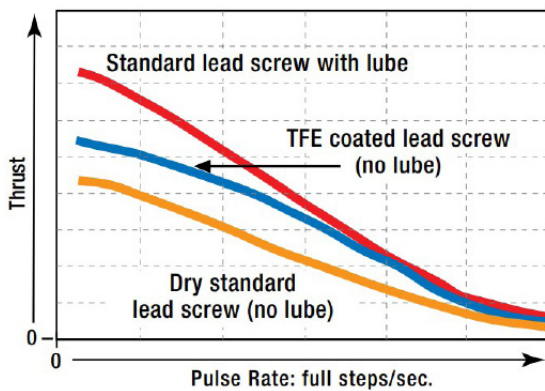
Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a “dry” stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

Lead Screw Comparison: FORCE vs. PULSE RATE

– L/R Drive – 100% Duty Cycle



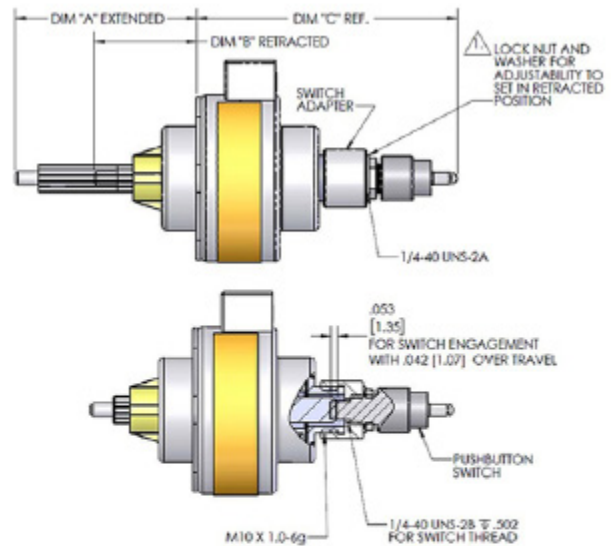
G4 37000 Series, External Linear

Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an “S”.



NOTE:
1. ADJUST LOCATION OF LOCK NUT TO ENSURE THE RETRACTED DIMENSION



Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	<p>Multiple contact options available.</p>

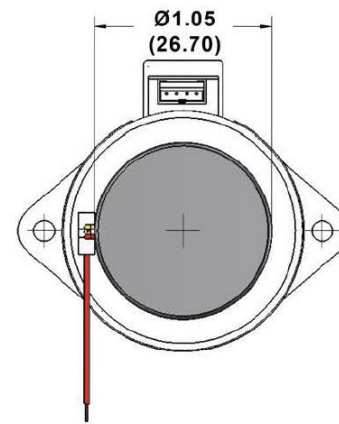
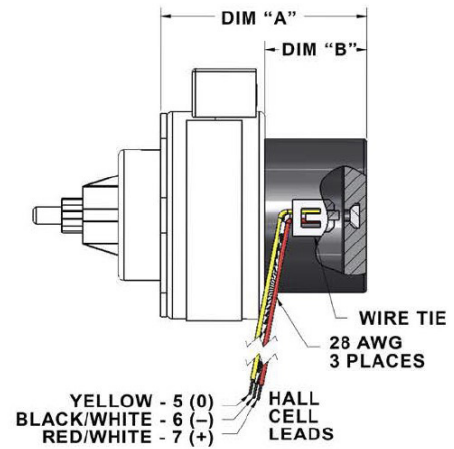
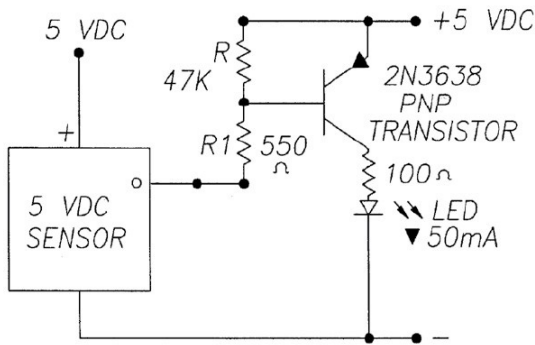
Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.631 (16)	1.348 +/- .025 (34.24 +/- 0.64)	.677 +/- .025 (17.19 +/- 0.64)	2.218 +/- .025 (56.33 +/- 0.64)
1.00 (25.4)	2.348 +/- .025 (59.94 +/- 0.64)	1.177 +/- .025 (29.89 +/- 0.64)	2.718 +/- .025 (69.03 +/- 0.64)
1.50 (38.1)	3.348 +/- .025 (85.04 +/- 0.64)	1.677 +/- .025 (42.59 +/- 0.64)	3.218 +/- .025 (81.73 +/- 0.64)

Can-Stack Stepper Motor Linear Actuators Options

End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specifications	
Supply Voltage (VDC)	3.8 min. to 24 max.
Current Consumption	10 mA max.
Output Voltage (operated)	0.15 typ., 0.40 max. Sinking 20 mA max.
Output Current	20 mA max.
Output Leakage Current (released)	10µA max. @ Vout = 24 VDC; Vcc = 24 VDC
Output Switching Time	Rise, 10 to 90% .05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 KOhm
	Fall, 90 to 10% .15 µs typ., 1.5 µs max. @ CL = 20 pF
Temperature	- 40 to +150°C



Stroke inches (mm)	Dim "A" inches (mm)	Dim "B" inches (mm)
.631 (16)	1.404 (35.65)	.695 (17.65)
1.00 (25.4)	1.906 (48.41)	1.197 (30.41)
1.50 (38.1)	2.409 (61.18)	1.700 (43.18)

The sensor has virtually unlimited cycle life. Special cabling and connectors can also be provided.

G4 37000 Series E8T Encoder

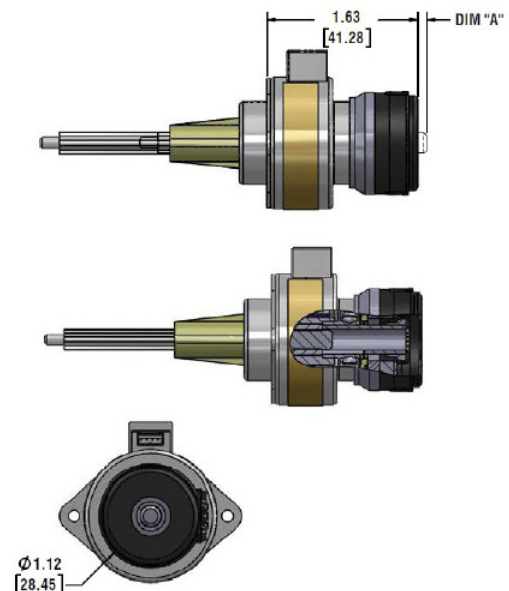
G4 37000 Series E8T Transmissive Optical Encoder is designed to provide the digital quadrature encoder feedback for high volume, compact space applications.

- Resolutions from 180 to 720
- Single-ended / Differential
- Frequency response to 100 kHz
- Low power consumption, 5 V @ 30 mA max
- High retention polarized connector

Assembly Options:

- Differential line driver with complementary outputs
- Detachable cable
- Through-hole cover

Stroke inches (mm)	Dim "A" Extended inches (mm)
.631 (16)	N/A
1.00 (25.4)	.098 (2.50)
1.50 (38.1)	.598 (15.20)



15000 Series Ø 15 mm (.59-in) Can-Stack Stepper Motor Linear Actuators

Delivering force of up to 8 lbs (35N) without compromising long life or cost. Lightweight models can also be micro- stepped for even finer resolution. Bi-directional travel motor. Available as connector stator or "space saving" flying leads type motor bodies.

The world's smallest commercial linear stepper motor

Multiple versions available

- Captive
 - External Linear with free-wheeling BFW nut
 - External Linear with ZBM anti-backlash nut*
- *May not be available in all leads

Specifications

Ø 15 mm (.59-in) Motor			
Part No.	Captive	LC1574 - - - - †	
	External Linear	LE1574 - - - - †	
Wiring	Bipolar		
Step angle	18°		
Winding Voltage	4 VDC	5 VDC	12 VDC
Current (RMS)/phase	0.2 A	0.16 A	0.07 A
Resistance/phase	20 Ω	31 Ω	180 Ω
Inductance/phase	5.6 mH	8.7 mH	48.8 mH
Power Consumption	1.6 W		
Rotor Inertia	0.09 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	LC15 0.49 oz (14 g) LE15 0.39 oz (11 g)		
Insulation Resistance	20 MΩ		
Stroke	Captive	0.5-in. (12.7 mm)	
	External Linear	up to 1.79-in. (45.4 mm)	

†Part numbering information below.

New encoder option available! See page 182.



Ø15mm (.59-in) Captive



Ø15mm (.59-in) External Linear with ZBMR Nut

Linear Travel / Step		Order Code I.D.
inches	mm	
.00059*	.015	BZ**
.00079*	.02	W**
.00098*	.025	AQ**
.00197*	.05	BH
.00394*	.10	DC

*Values truncated
**Black Ice not available

Available Standard Connectors for Series 15000

Connector	PIN			
	1	2	3	4
JST PHR-4	Red	White	Green	Black
Molex 51021-0400	Black	Green	White	Red

Available Flying Leads

Length	Order Code I.D. Suffix (add to end on I.D.)
12 inches (304.8 mm)	-999

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

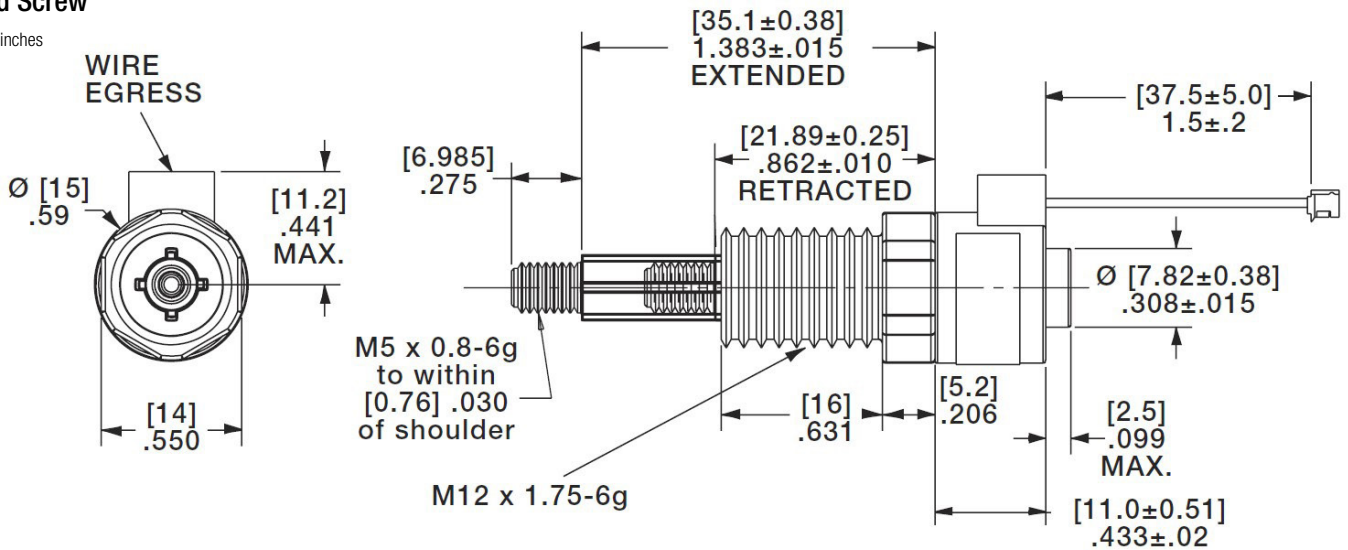
Identifying the Can-Stack Number Codes when Ordering

LC	15	7	4	W	04	999
Prefix LC = Captive LE = External Linear	Series Number Designation 15 = 15000 (Series numbers represent approximate diameters of motor body)	Step Angle 7 = 18°	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step BZ = .00059-in (.015) W = .00079-in (.02) AQ = .00098-in (.025) BH = .00197-in (.05) DC = .00394-in (.10)	Voltage 04 = 4 VDC 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -999 = 12-in leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

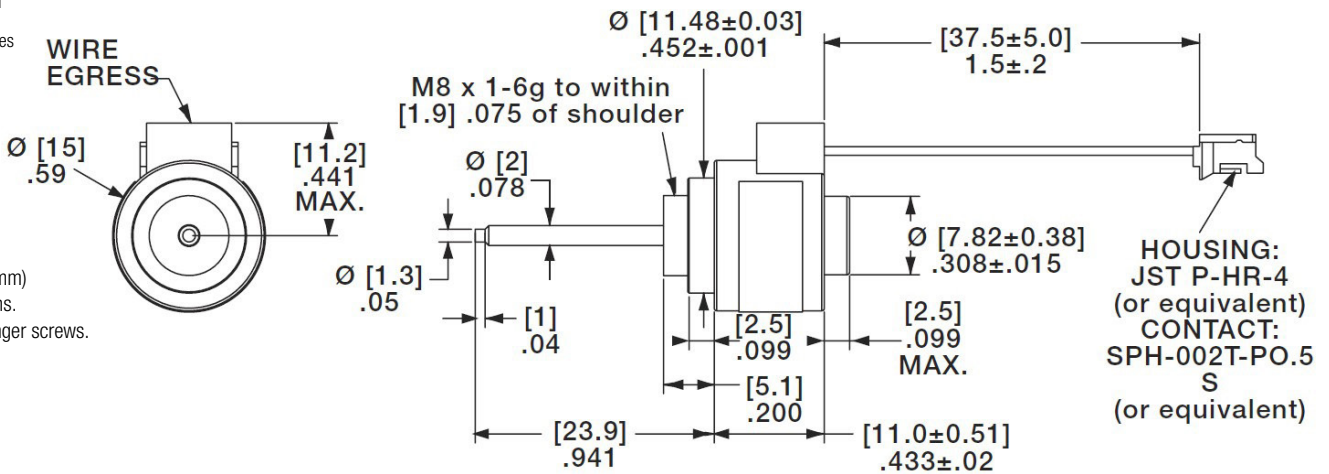
Captive Lead Screw

Dimensions = (mm) inches



External Linear

Dimensions = (mm) inches



Up to 2.36-in (59.9 mm) standard screw lengths. Consult factory for longer screws.

Stroke as shown: 0.37" (9.4mm)

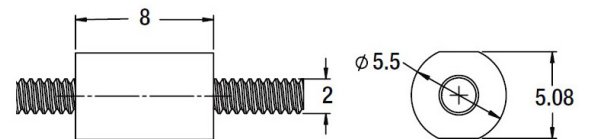
MICRO Series

Dimensions = (mm) inches

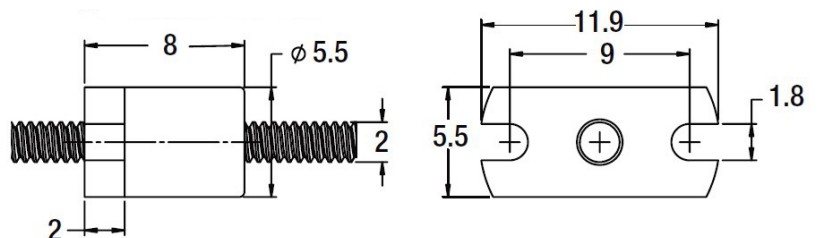
Standard nut styles. Consult the factory for custom solutions.

MICRO Series Nut Styles			
Part No.	BFW Nut Style	Dynamic Load lbs (Kg)	Drag Torque oz-in (NM)
BFWB	Barrel Mount	10 (4.5)	Free Wheeling
BFWR	Rectangular Flange		

Barrel Nut Style

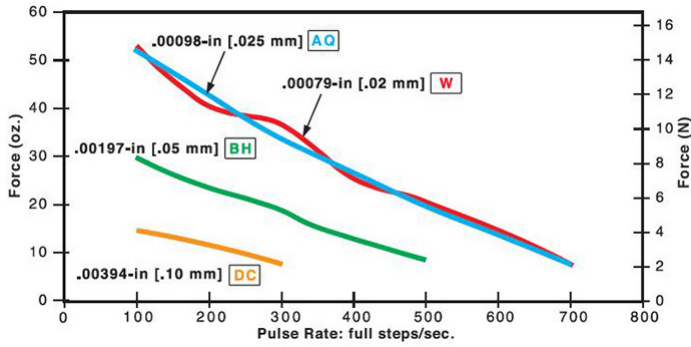


Rectangular Nut Style



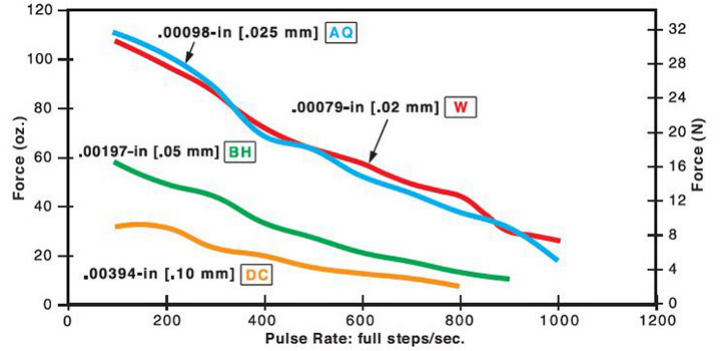
FORCE vs. PULSE RATE

– L/R Drive – Bipolar – 100% Duty Cycle



FORCE vs. PULSE RATE

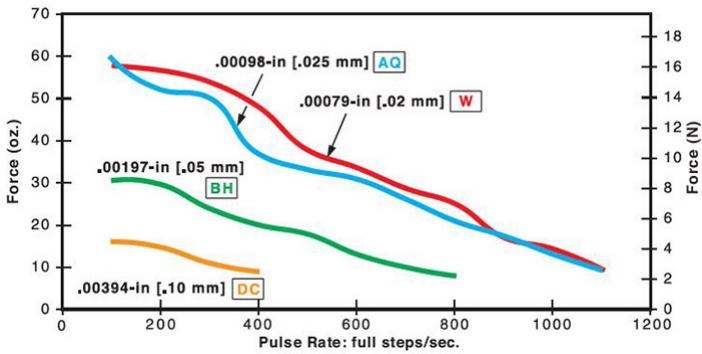
– L/R Drive – Bipolar – 25% Duty Cycle



Obtained by a special winding or by running a standard motor at double the rated current.

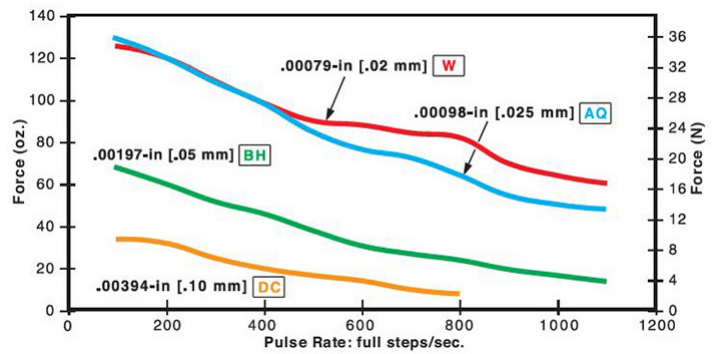
FORCE vs. PULSE RATE

– Chopper Drive – Bipolar – 100% Duty Cycle



FORCE vs. PULSE RATE

– Chopper Drive – Bipolar – 25% Duty Cycle

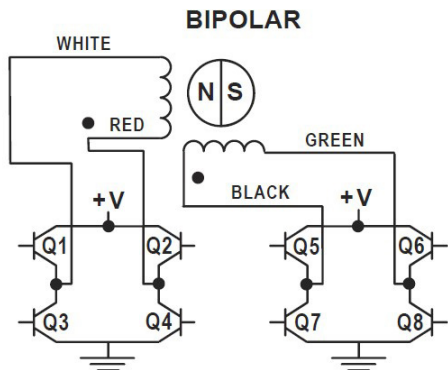


NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

15000 Series • Can-Stack Stepper Motor Linear Actuators Wiring & Stepping Sequence

Can-Stacks: **Wiring**



Can-Stacks: **Stepping Sequence**

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



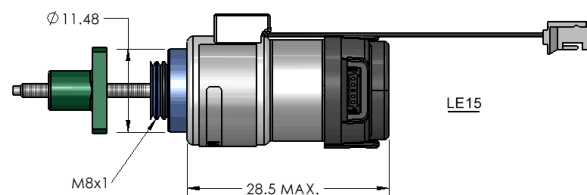
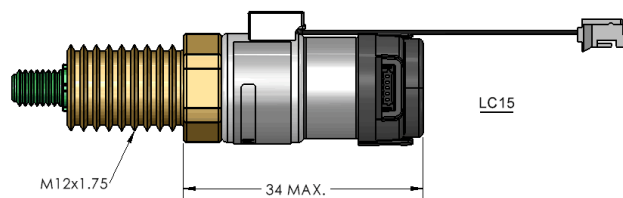
NEW! 15000 Series E16 Encoder

15000 Series E16 optical encoder is designed to provide A, B and Index digital quadrature signals for high volume, restricted space applications.

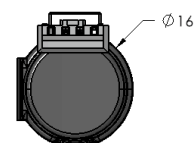
- Resolutions from 250/256 to 4000/4096
- Single-ended only
- Low power consumption, 5V @ 26mA max

Assembly Options:

- Detachable cable



Pin #	Description
1	Ground
2	Index
3	A channel
4	+5VDC power
5	B channel



Ø15mm (.59-in)
External Linear

Custom Free-Wheeling Nuts

Modified and custom free-wheeling nuts are available for the LE external linear versions. Custom geometries and materials can be combined for a wide variety of product application requirements, to help eliminate additional adjacent components as well as to deliver cost and space-saving benefits.

Z20000 Series Ø 20 mm (.79-in) Can-Stack Stepper Motor Linear Actuators

Utilizing rare earth (neodymium) magnets, the Z-Series Linear Actuators consistently deliver exceptional performance at an economical price. Also available in a special “earless” configuration without a mounting flange, which is ideal for space constrained applications.

Economical motors for high volume applications

Multiple versions available

- Captive
- Non-Captive
- External Linear



Specifications

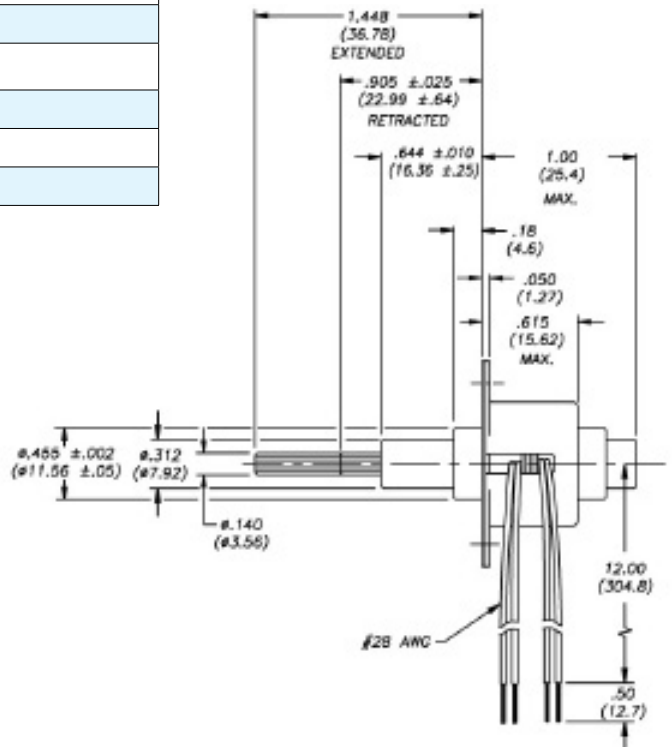
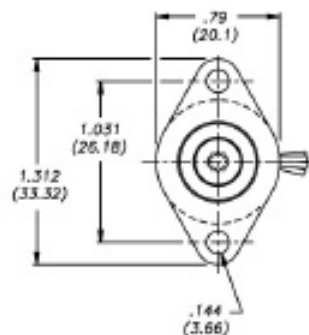
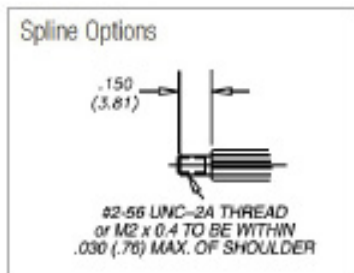
Ø 20 mm (.79-in) Z-Series Motor		
Part No.	Captive	Z2054 †
	Non-Captive	Z2084 †
	External Linear*	Z2054 - 9 †
Wiring	Bipolar	
Step angle	15°	
Winding Voltage	5 VDC	12 VDC
Current (RMS)/phase	250 mA	100 mA
Resistance/phase	20 Ω	118 Ω
Inductance/phase	5.4 mH	27 mH
Power Consumption	2.5 W	
Rotor Inertia	1.13 gcm ²	
Insulation Class	Class B	
Weight	.85 oz. (24.1 g)	
Insulation Resistance	20 MΩ	

Linear Travel / Step 15° Step Angle		Order Code I.D.
inches	mm	
0.001	0.0254	1
0.002	0.051	2
0.004	0.102	4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

*Part numbering information on page 168.

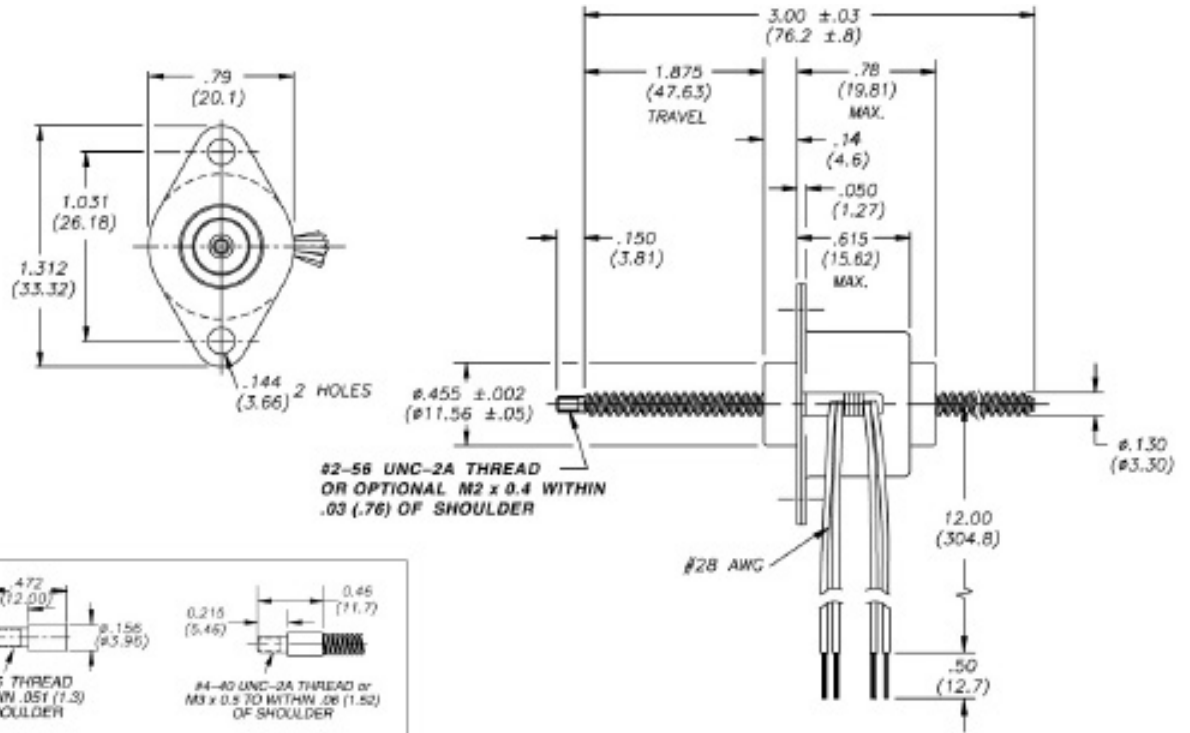
*When ordering Z-Series External Linear motors, add -900 to end of the Part Number.



Non-Captive Lead Screw

Dimensions = (mm) inches

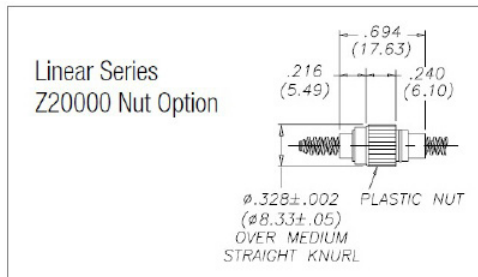
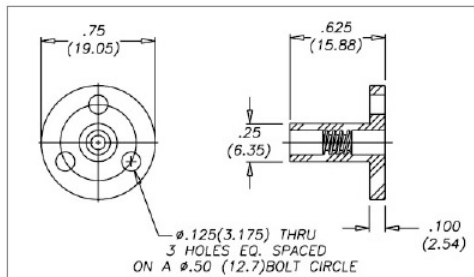
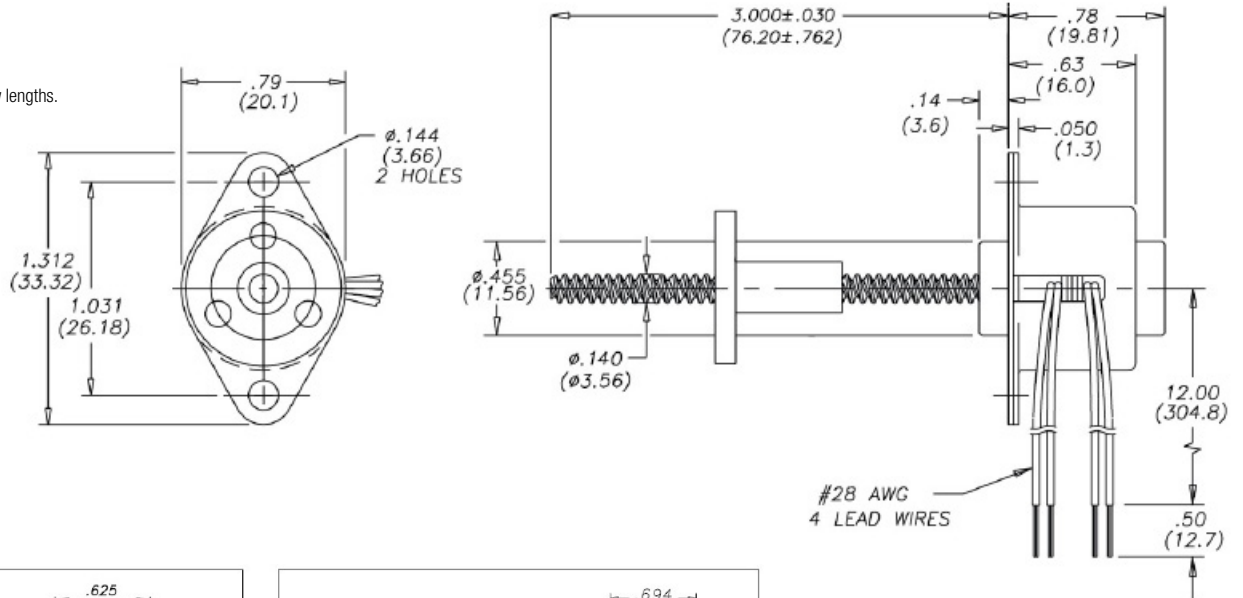
Up to 6-in (152 mm) standard screw lengths.
Longer screw lengths are available.



External Linear

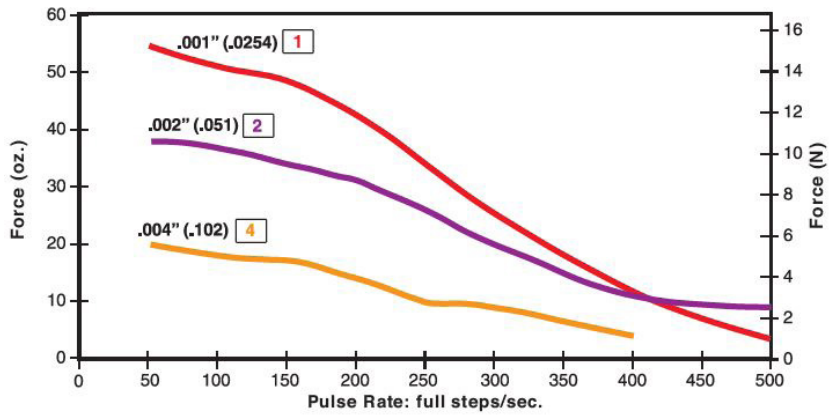
Dimensions = (mm) inches

Up to 6-in (152 mm) standard screw lengths.
Longer screw lengths are available.



FORCE vs. PULSE RATE

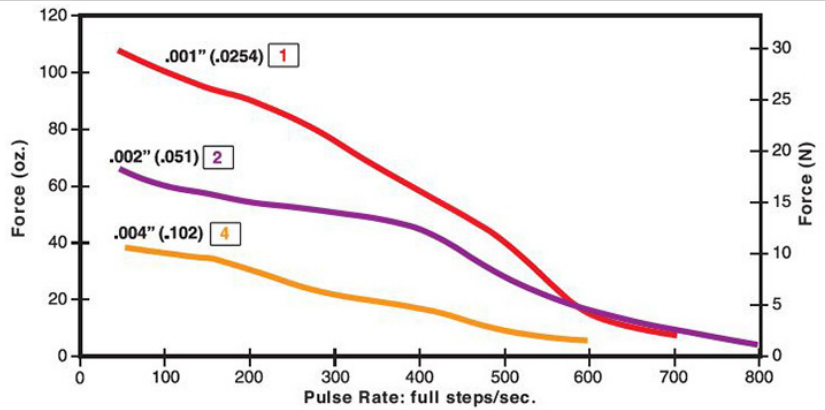
- L/R Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

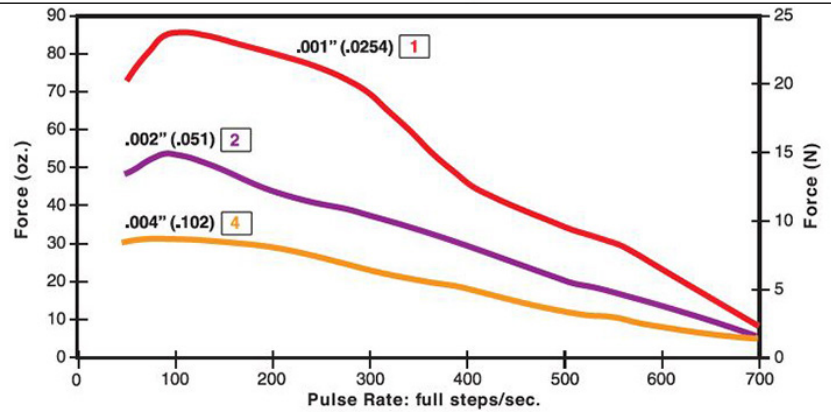
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



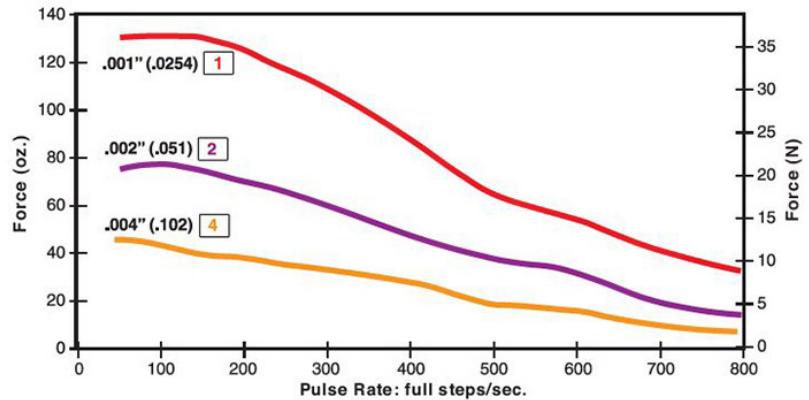
FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

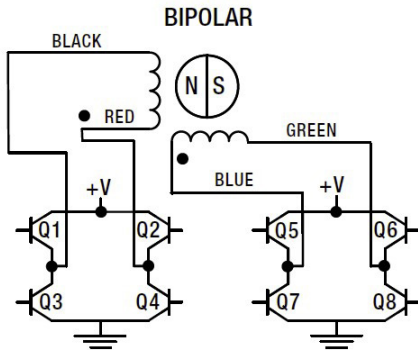
Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

Identifying the Can-Stack Number Codes when Ordering

Z	20	5	4	2	05	900
Prefix Z = Series Code	Series Number Designation 20 = 20000 (Series numbers represent approximate diameters of motor body)	Style 5 = 15° Captive or External (use -900 Suffix for External version) 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -900 used to code Z-Series external linear -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Can-Stacks: **Wiring**



Can-Stacks: **Stepping Sequence**

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

■ Can-Stack Stepper Motor Linear Actuators Options

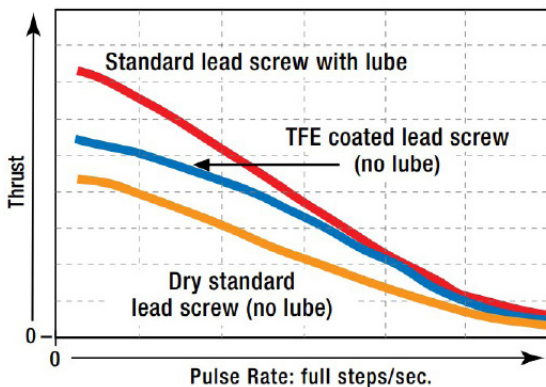
TFE Coated Lead Screws for applications that require a permanent, dry lubricant

Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

Lead Screw Comparison: FORCE vs. PULSE RATE – L/R Drive – 100% Duty Cycle



Z20000 Series Non-Captive

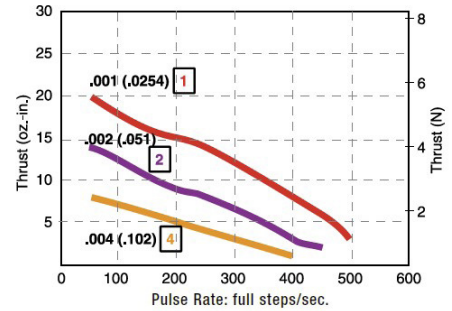
■ Can-Stack Stepper Motor Linear Actuators Options

Specially Engineered Can-Stack Linear Actuators for high temperature applications

Stepping motors specially designed for high temperature environments.

Materials meeting class F temperature ratings are used in construction.

Specialized components include high temperature bobbins, coils, lead wires, lubricant and adhesives.



Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

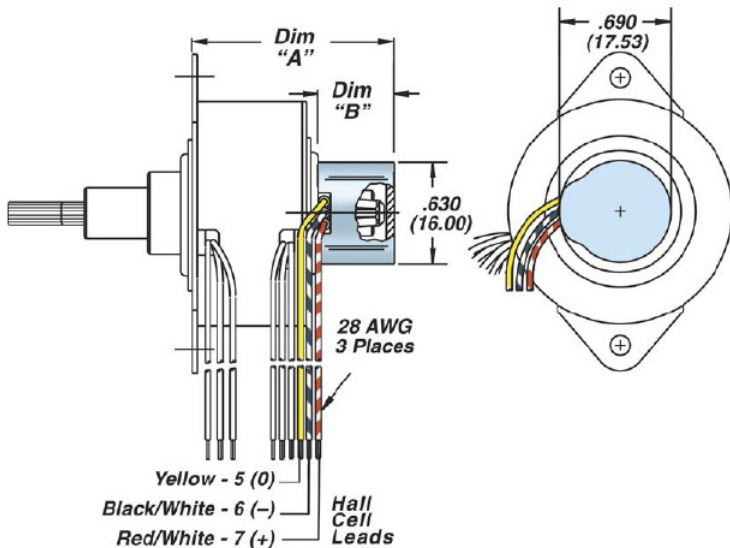
Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

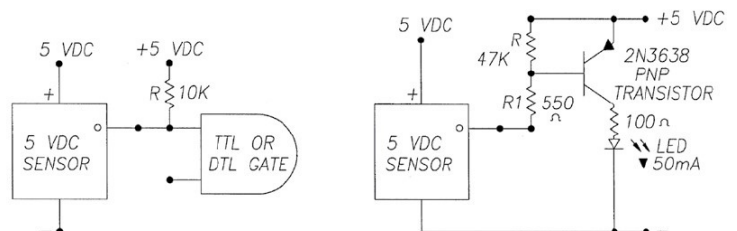
Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 millionths typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	 Multiple contact options available.

End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.



Specifications	
Supply Voltage (VDC)	3.8 min. to 24 max.
Current Consumption	10 mA max.
Output Voltage (operated)	0.15 typ., 0.40 max. Sinking 20 mA max.
Output Current	20 mA max.
Output Leakage Current (released)	10µA max. @ Vout = 24 VDC; Vcc = 24 VDC
Output Switching Time	Rise, 10 to 90%
	Fall, 90 to 10%
Temperature	-40 to +150°C



NOTE: Sensor is category 2 ESD sensitive per DOD-STD-1686A. Assembly operations should be performed at workstations with conductive tops and operators grounded.

Z26000 Series Ø 26 mm (1-in) Can-Stack Stepper Motor Linear Actuators

Designed to accommodate high volume applications

Z26000 Series motors utilize rare earth (neodymium) magnets. Also, available in a special "earless" configuration without a mounting flange. All units are built with durable dual ball bearings.

Multiple versions available

- Captive
- Non-Captive
- External Linear



NOW AVAILABLE! Shorter motor body option available (see page 174)

Specifications

Ø 26 mm (1-in) Z-Series Motor										
Part No.	Captive	Z2644	-	-	-	-	-	-	-	†
	Non-Captive	Z2634	-	-	-	-	-	-	-	†
	External Linear*	Z2644	-	-	-	-	-	-	-	9 ††
Wiring		Bipolar				Unipolar*				
Step angle		7.5°		15°		7.5°		15°		
Winding Voltage		5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase		340 mA	140 mA	340 mA	140 mA	340 mA	140 mA	340 mA	140 mA	
Resistance/phase		14.7 Ω	84 Ω	14.7 Ω	84 Ω	14.7 Ω	84 Ω	14.7 Ω	84 Ω	
Inductance/phase		8.5 mH	55 mH	6.7 mH	44 mH	4.3 mH	24 mH	3.4 mH	19 mH	
Power Consumption		3.4 W								
Rotor Inertia		1.4 gcm ²								
Insulation Class		Class B								
Weight		1.2 oz (34 g)								
Insulation Resistance		20 MΩ								

*Part numbering information on page 4. *Unipolar drive gives approximately 40% less thrust compared to bipolar drive. ** When ordering Z-Series External Linear motors, add -900 to end of the Part Number.

Linear Travel / Step 15° Step Angle			Order Code I.D.
step	inches	mm	
7.5° Angle	0.0005	0.013	3
	0.001	0.0254	1
	0.002	0.051	2
15° Angle	0.00164	0.04166	AS
	0.002	0.051	2
	0.004	0.102	4

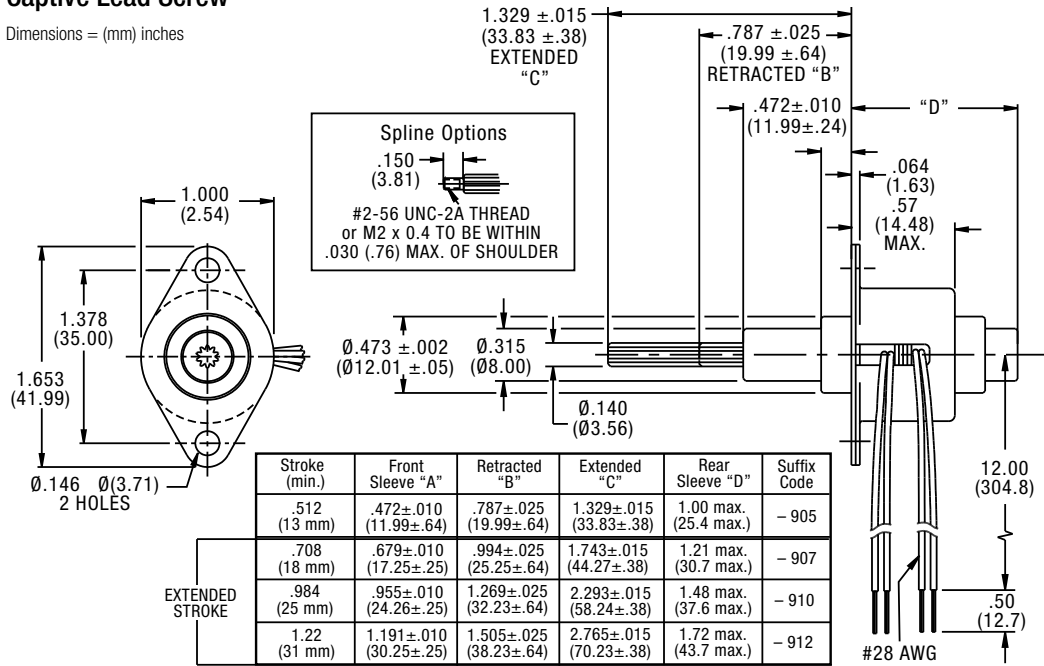
Also available, specially engineered Z26000 (Ø 26 mm, 1-in) linear actuators that extend captive lead screw travel beyond 12.7 mm (1/2-in).



Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

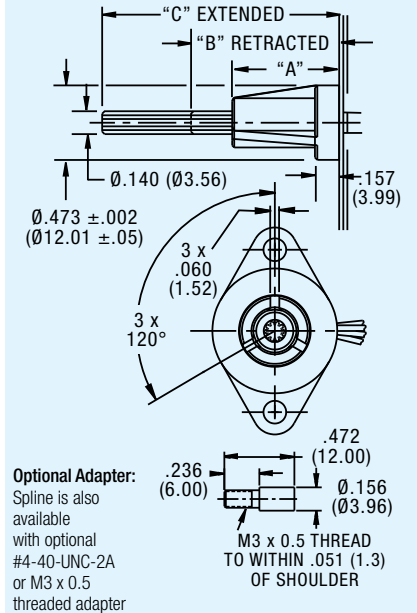
Captive Lead Screw

Dimensions = (mm) inches



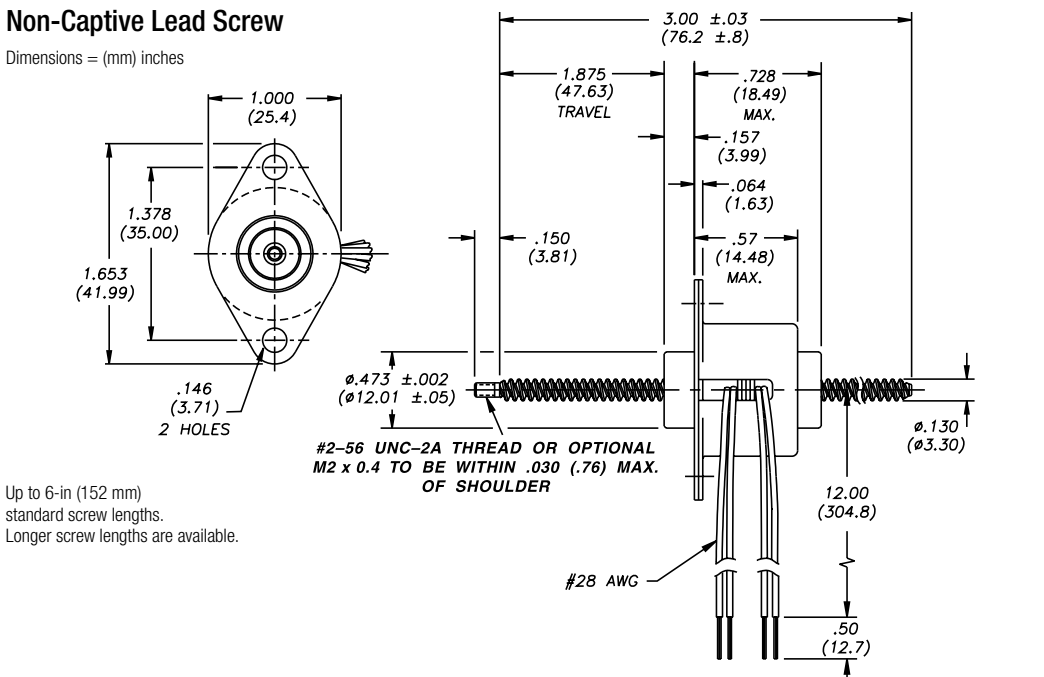
Extended Stroke Sleeve

Dimensions = (mm) inches



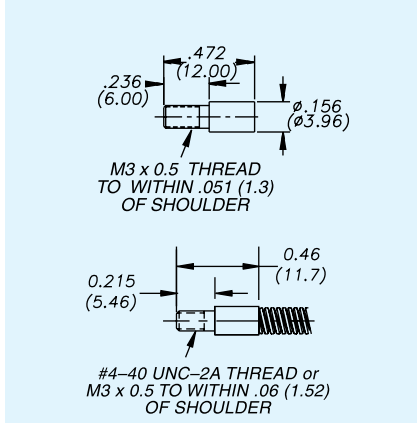
Non-Captive Lead Screw

Dimensions = (mm) inches



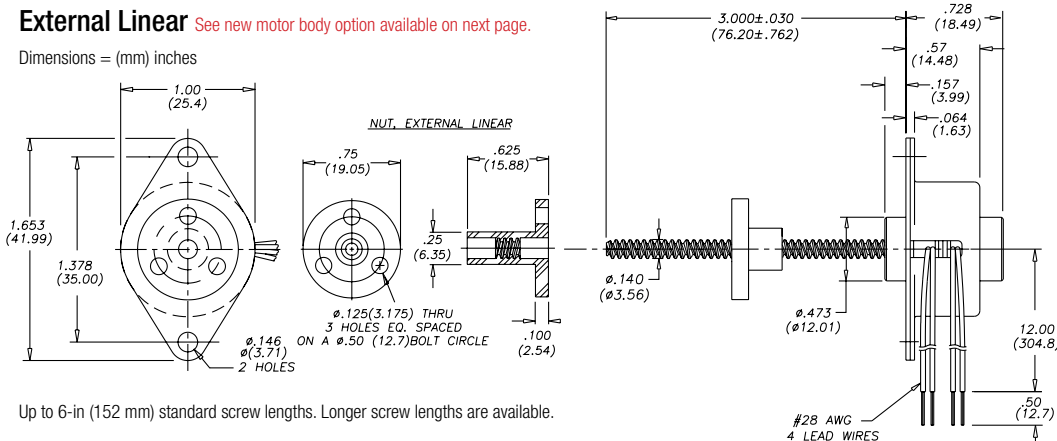
Extended Stroke Sleeve

Dimensions = (mm) inches



External Linear See new motor body option available on next page.

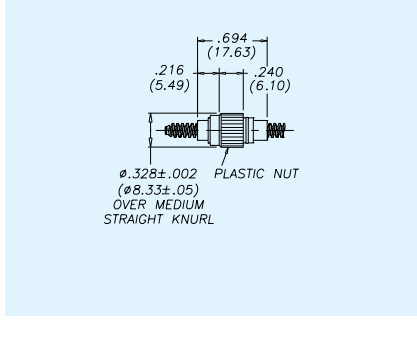
Dimensions = (mm) inches



Up to 6-in (152 mm) standard screw lengths. Longer screw lengths are available.

Linear Series Z26000 Nut Option

Dimensions = (mm) inches



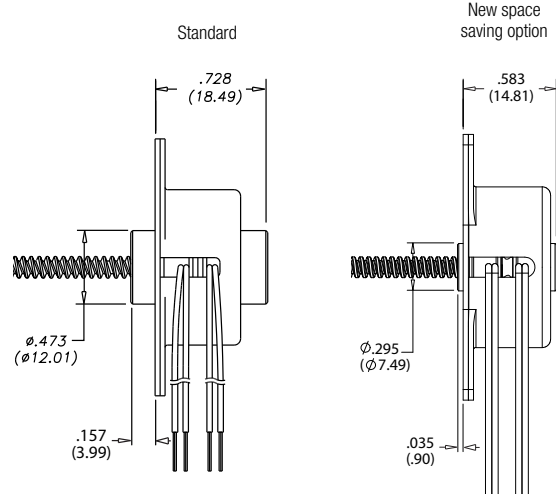


NOW AVAILABLE! Shorter External Linear Option

Designed to accommodate applications with space limitations

The Z26000 series now offers both the .728 and .583 motor body lengths with all existing Z26 motor advantages, including cost competitiveness and availability of customizations like rare earth magnets and earless options.

When ordering, the shorter motor option can be referenced using the last three suffix digits (-XXX).

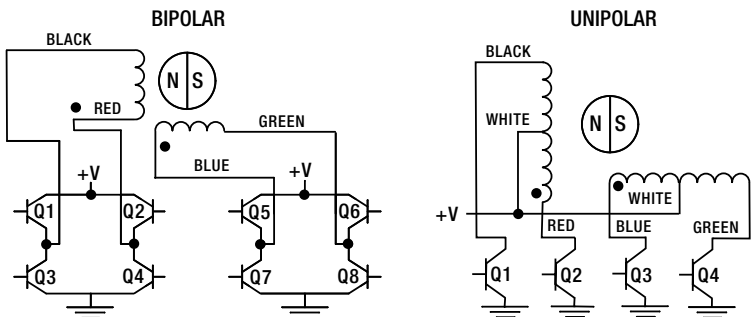


Identifying the Can-Stack Number Codes when Ordering

Z	26	4	4	2	05	900
Prefix	Series Number Designation	Style	Coils	Code ID Resolution Travel/Step	Voltage	Suffix Stroke
Z = Series Code	26 = 26000 (Series numbers represent approximate diameters of motor body)	3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version) 8 = 15° Non-Captive	4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102) AS = .04166-in (.00164)	05 = 5 VDC 12 = 12 VDC Custom V available	Example: -900 used to code Z-Series external linear -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Can-Stacks: Wiring



Can-Stacks: Stepping Sequence

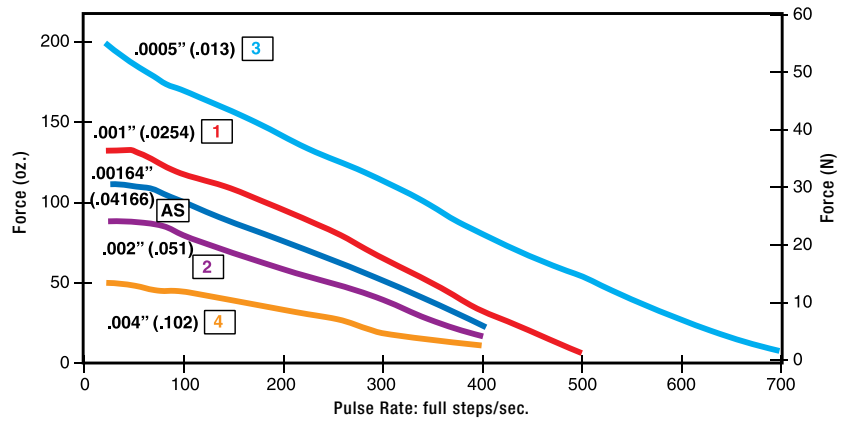
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

↑ RETRACT CCW
↓ EXTEND CW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

FORCE vs. PULSE RATE

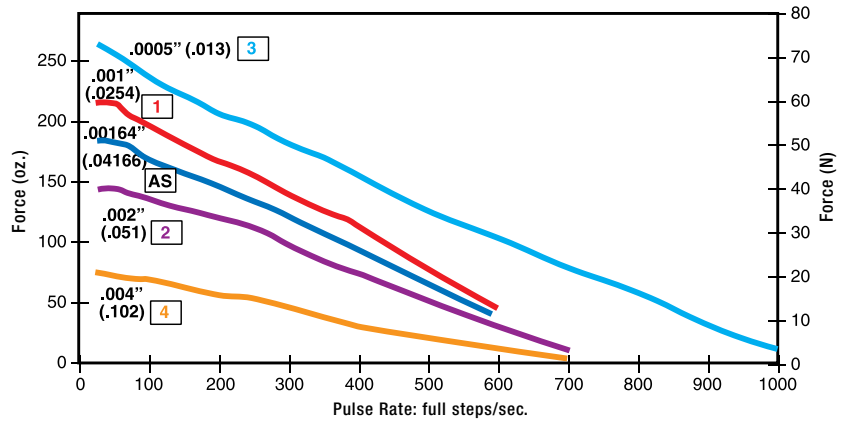
- L/R Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

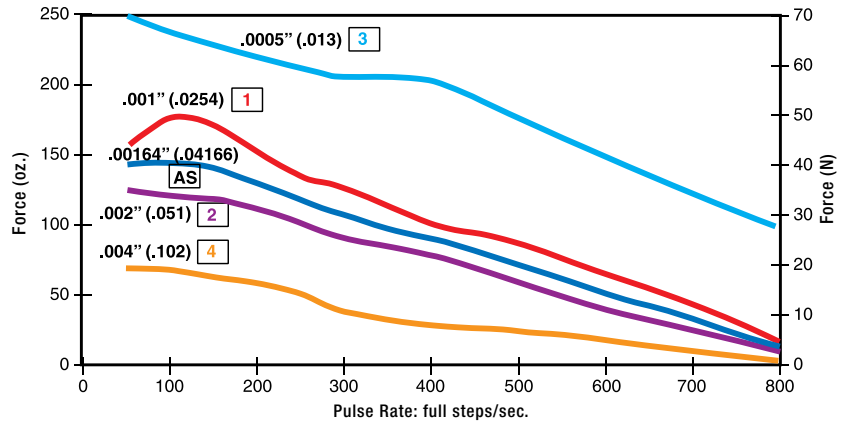
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



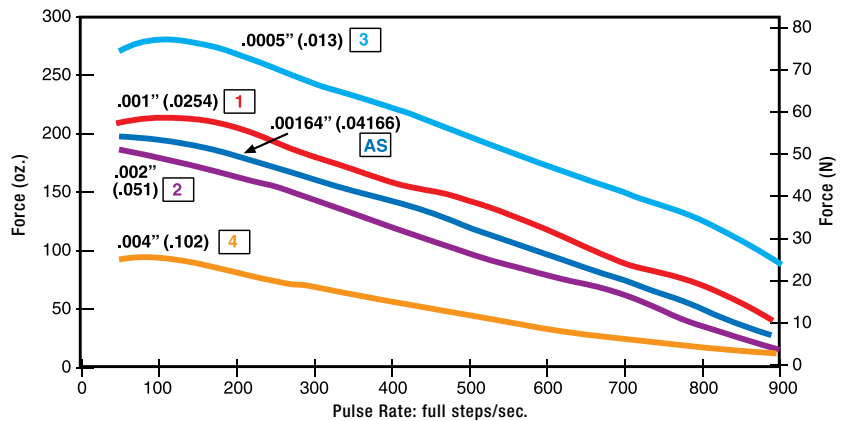
FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

AC (Alternating Current) Synchronous Actuators

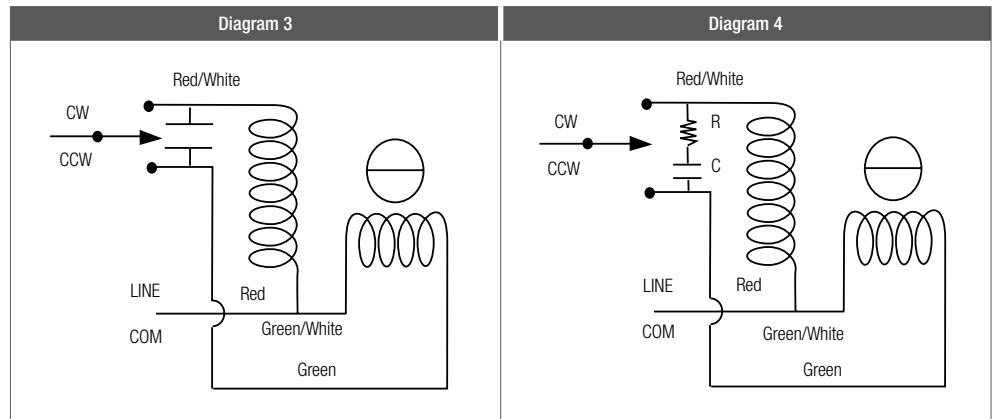
Stepping motors can also be run on AC (Alternating Current). However, one phase must be energized through a properly selected capacitor. In this case the motor is limited to only one synchronous speed. For instance, if 60 hertz is being supplied, there are 120 reversals or alterations of the power source. The phase being energized by a capacitor is also producing the same number of alterations at an offset time sequence. The motor is really being energized at the equivalent of 240 steps per second.

Alternating Current (AC) Hybrid Linear Actuators

Stepping motors can also be run on Alternating Current (AC). However, one phase must be energized through a properly selected capacitor. In this case, the motor is limited to only one synchronous speed.

For instance, if 60 hertz is being supplied, there are 120 reversals or alterations of the power source. The phase being energized by a capacitor is also producing the same number of alterations at an offset time sequence. The motor is really being energized at the equivalent of 240 steps per second.

In the case of a linear actuator the linear speed produced is dependent on the resolution per step of the motor. For example, if 60 hertz is supplied to a .001-in/step motor the resulting speed is .240-in per second (240 steps per second times .001-in/step). Many of our stepping motors are available as 300 or 600 RPM AC synchronous motors.



Electrical Data								
Series	Size	Watts	Amps	Capacitor (Mfd) @ 60 Hz	Capacitor (Mfd) @ 50 Hz	Coil Resistance (Ohms)		Connection Diagram
						Main Wind.	Cap. Wind.	
35000	14	5.7	0.21	15	15	300	300	3
43000	17	6.5	0.27	15	15	104	104	3
57000	23	13.0	0.60	30	40	35	35	3
87000*	34	30.0	2.00	200	200	2.3	2.3	4

* With 12 OHM, 100 watt resistor in series.

Identifying the AC Hybrid Part Number Codes when Ordering

A	35	H	4	N			24	800
Prefix A = A Coil)	Series Number Designation 35 = 35000 (Size 14) 43 = 43000 (Size 17) 57 = 57000 (Size 23) 87 = 87000 (Size 34)	Style F = 1.8° Non-captive H = 1.8° Captive or External (use "E" or "K" Prefix for External version) J = 0.9° Non-captive K = 0.9° Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	35000 and 43000 Series Code ID Resolution Travel/Step N = .00012-in (.0030) K = .00024-in (.0060) J = .00048-in (.0121) Q = .00096-in (.0243) P = .0015625-in (.0039) A = .0003125-in (.0079) B = .000625-in (.0158) C = .00125-in (.0317) R = .00192-in (.0478) High Resolution U = .00006-in (.0015) V = .000078-in (.00198)	57000 Series Code ID Resolution Travel/Step 7 = .000125-in (.0031) S = .0004167-in (.01058418) 3 = .0005-in (.0127) 1 = .001-in (.0254) A = .0003125-in (.0079) T = .0008333-in (.0211) 2 = .002-in (.0508) High Resolution P = .00015625-in (.003969) X = .00020833-in (.00529166) 9 = .00025-in (.0635)	87000 Series Code ID Resolution Travel/Step 3 = .0005-in (.0127) B = .000625-in (.0158) C = .00125-in (.0317) Y = .0025-in (.0635) Z = .005-in (.127)	Voltage 24 = 24 VDC	Suffix -800 = External linear (added to Captive shaft part number) -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Motor part numbers are for a captive shaft. For a non-captive shaft, change the middle letter from an "H" to an "F". Example 1: A35H4N-24 with a non-captive shaft becomes A35F4N-24.

Exception: A43K4U-24 (high resolution) and A43K4V-24 (High resolution), for a non-captive shaft substitute "J" in place of the "K". Example 2: A43K4U-24 with a non-captive shaft becomes A43J4U-24.

For an external linear shaft, add the three digit suffix - 800 to the captive shaft part number.

Example 3: A35H4N-24 with an external linear shaft becomes A35H4N-24-800.

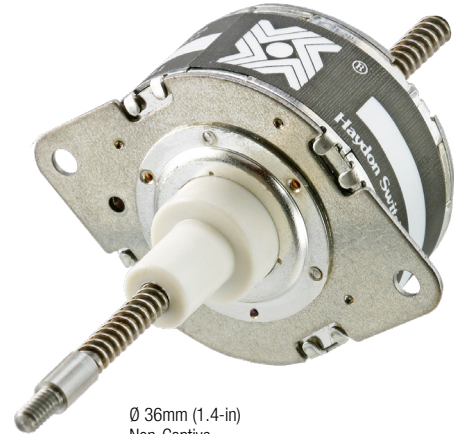
All standard motors operate at 24 Volts, represented in the part number by the number - 24 (A35H4N-24). No other suffix is required.

AC Can-Stack Linear Actuators

Stepping motors can also be run on Alternating Current (AC). However, one phase must be energized through a properly selected capacitor. In this case, the motor is limited to only one synchronous speed.

For instance, if 60 hertz is being supplied, there are 120 reversals or alterations of the power source. The phase being energized by a capacitor is also producing the same number of alterations at an offset time sequence. The motor is really being energized at the equivalent of 240 steps per second.

In the case of a linear actuator the linear speed produced is dependent on the resolution per step of the motor. For example, if 60 hertz is supplied to a .001-in/ step motor the resulting speed is .240-in per second (240 steps per second times .001-in/step). Many of our stepping motors are available as 300 or 600 RPM AC synchronous motors.



Ø 36mm (1.4-in)
Non-Captive

$$\frac{240 \text{ Steps per Revolution} \times 60 \text{ Seconds}}{24 \text{ Steps per Revolution}} = 600 \text{ RPM}$$

Identifying the AC Can-Stack Part Number Codes when Ordering

A	35	5	4	2			24	800
Prefix	Series Number Designation	Style	Coils	20000 and Z20000 Series Code ID	26000 Series Code ID	36000 Series Code ID	Voltage	Suffix
A = A Coil	20 = 20000 (Ø20mm, .79-in)	3 = 7.5° Non-Captive	4 = Bipolar (4 wire)	Resolution Travel/Step	Resolution Travel/Step	Resolution Travel/Step	24 = 24 VDC	-800 = External linear (added to Captive shaft part number)
Z = Economy Series (For 20000 and 26000 Series only)	26 = 26000 (Ø26mm, 1-in)	4 = 7.5° Captive or External (use "E" or "K" Prefix for External version)		1 = .001-in (.0254)	1 = .001-in (.0254)	1 = .001-in (.0254)		-XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.
	36 = 36000 (Ø36mm, 1.4-in)	5 = 15° Captive or External (use "E" or "K" Prefix for External version)		2 = .002-in (.051)	2 = .002-in (.051)	2 = .002-in (.051)		
	46 = 46000 (Ø46mm, 1.8-in)	8 = 15° Non-Captive		3 = .0005-in (.013)	3 = .0005-in (.013)	3 = .0005-in (.013)		
				4 = .004-in (.102)	4 = .004-in (.102)	4 = .004-in (.102)		
					9 = .00025-in (.00635)	High Resolution		
						7 = .000125-in (.0032)		
					Z26000 Series Code ID	9 = .00025-in (.00635)		
					Resolution Travel/Step			
					1 = .001-in (.0254)	46000 Series Code ID		
					2 = .002-in (.051)	Resolution Travel/Step		
					3 = .0005-in (.013)	1 = .001-in (.0254)		
					4 = .004-in (.102)	2 = .002-in (.051)		
					AS = .04166-in (.00164)	3 = .0005-in (.013)		
						4 = .004-in (.102)		
						8 = .0008-in (.203)		
						G = .016-in (.406)		

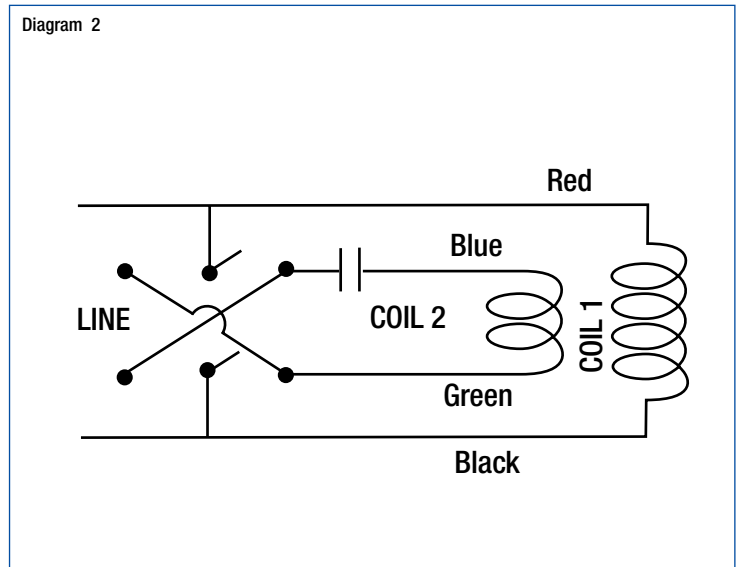
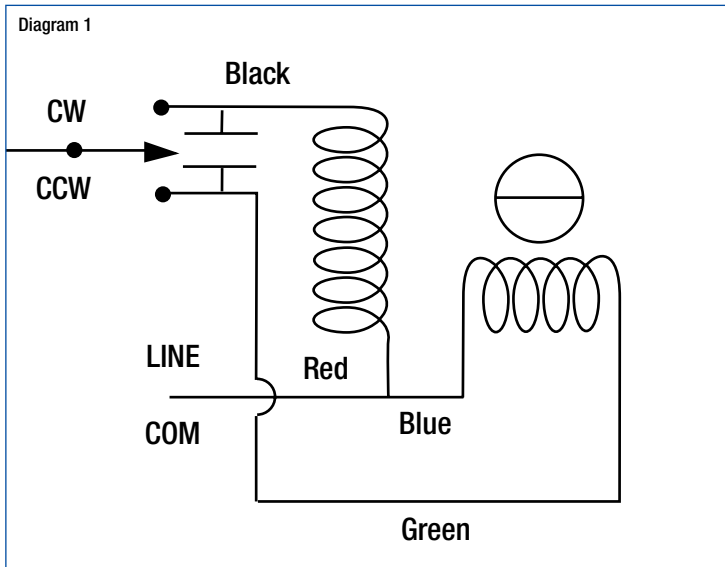
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Motor part numbers are for a captive shaft. For a non-captive shaft, change the third digit from a "4" to an "3". Example 1: A26441-24 with a non-captive shaft becomes A26341-24. Exception: When the third digit is "5" for a non-captive shaft substitute "8". Example 2: A26544-24 with a non-captive shaft becomes A26844-24.

For an external linear shaft, add the three digit suffix - 800 to the captive shaft part number. Example 3: A26441-24 with an external linear shaft becomes A26441-24 - 800. All standard motors operate at 24 Volts, represented in the part number by the suffix - 24 (A36443-24).

Specifications						
Motor Part No.	Linear Speed @ 60 Hz		Linear Speed @ 50 Hz		Maximum Force	
	(inches/sec.)	(cm/sec.)	(inches/sec.)	(cm/sec.)	(lbs.)	(Newtons)
Z20541-24-700	0.24	0.610	0.20	0.508	5.5	24
Z20542-24-700	0.48	1.219	0.40	1.016	3.0	13
Z20544-24-700	0.96	2.438	0.80	2.032	1.8	8
A26443-24	0.12	0.305	0.10	0.254	7.4	33
A26441-24	0.24	0.610	0.20	0.508	4.4	20
A26542-24	0.48	1.219	0.40	1.016	3.5	16
A26544-24	0.96	2.438	0.80	2.032	2.0	9
Z26443-24-700	0.12	0.305	0.10	0.254	13.0	58
Z26441-24-700	0.24	0.610	0.20	0.508	8.3	37
Z26542-24-700	0.48	1.219	0.40	1.016	6.6	29
Z26544-24-700	0.96	2.438	0.80	2.032	3.3	15
A36443-24**	0.12	0.305	0.10	0.254	16.0	71
A36441-24**	0.24	0.610	0.20	0.508	12.0	53
A36442-24**	0.48	1.219	0.40	1.016	6.0	27
A36544-24**	0.96	2.438	0.80	2.032	3.0	13
A46443-24**	0.12	0.305	0.10	0.254	43	191
A46441-24**	0.24	0.610	0.20	0.508	34	151
A46442-24**	0.48	1.219	0.40	1.016	20	89
A46544-24**	0.96	2.438	0.80	2.032	11	49
A46548-24**	1.92	4.877	1.60	4.064	5.4	24
A4654G-24**	3.84	9.754	3.20	8.128	2.7	12

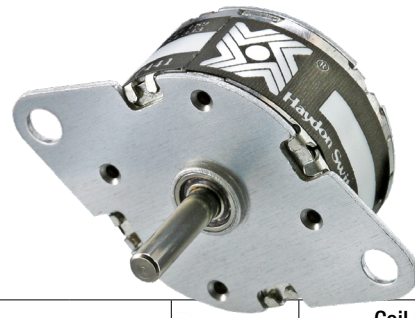
** Select motors available with 24 Volts or 120 Volts (replace 24 with 120).



NOTE: Capacitors not furnished with production units.

AC Rotary Motors

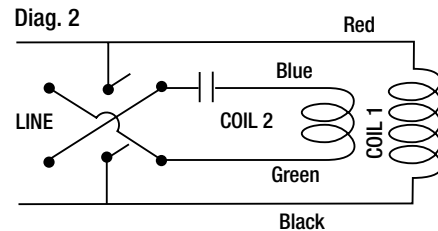
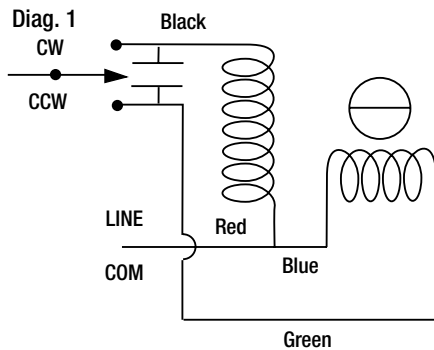
Stepping motors can also be run on AC (Alternating Current). However, one phase must be energized through a properly selected capacitor. In this case the motor is limited to only one synchronous speed. For instance, if 60 hertz is being supplied, there are 120 reversals or alterations of the power source. The phase being energized by a capacitor is also producing the same number of alterations at an offset time sequence. The motor is really being energized at the equivalent of 240 steps per second.



AC Synchronous
 Ø 26 mm (1-in)
 Ball Bearing
 26000 Series

Specifications

Motor Part No.	Rotary Speed (RPMs) @		Torque		Watts	Amps	Capacitor @		Connection Diagram	Coil Resistance (Ohms)	
	60 Hz	50 Hz	oz-in	N-cm			60 Hz	50 Hz		Main Wind	Cap. Wind
Z20540-24-700	600	500	0.5	0.4	2.5	.15	12.5	12.5	2	300	75
A26440-24	300	250	0.9	0.6	3.4	.20	15.0	15.0	2	214	54
A26540-24	600	500	0.9	0.6	3.4	.20	15.0	20.0	2	214	54
Z26440-24-700	300	250	1.2	0.8	3.4	.19	15.0	15.0	2	214	54
Z26540-24-700	600	500	1.5	1.1	3.4	.19	15.0	15.0	2	214	54
A36240-24	150	125	2.5	1.8	4.6	.23	20.0	20.0	2	160	40
A36440-24	300	250	2.6	1.8	4.6	.23	20.0	20.0	2	160	40
A36540-24	600	500	1.3	0.9	4.6	.23	20.0	20.0	2	160	40
A46440-24	300	250	8.5	6.0	10.0	.38	20.0	20.0	1	29	29
A46540-24	600	500	6.5	4.6	10.0	.38	20.0	25.0	1	58	58
A36240-120	150	125	2.5	1.8	4.6	.05	0.8	0.8	2	4000	1000
A36440-120	300	250	2.6	1.8	4.6	.05	0.8	0.8	2	4000	1000
A36540-120	600	500	1.3	0.9	4.6	.05	0.8	0.8	2	4000	1000
A46440-120	300	250	8.5	6.0	10.0	.08	0.8	0.8	1	725	725
A46540-120	600	600	6.5	4.6	10.0	.08	0.8	1.0	1	1450	1450



Capacitors not furnished (with production units).

Identifying the AC Rotary Motor Number Codes when Ordering

Z	26	5	4	0	24	700
Prefix	Series Number Designation	Style	Coils	Code ID Resolution Travel/Step	Voltage	Suffix
A = A Coil Z = Economy (For 20000 and 26000 Series, only use -700 suffix to identify AC motor)	20 = 20000 (Ø 20 mm .79-in) 26 = 26000 (Ø 26 mm 1.1-in) 36 = 36000 (Ø 36 mm 1.4-in) 46 = 46000 (Ø 46 mm 1.8-in)	4 = 7.5° 5 = 15°	4 = Bipolar (4 wire)	0 = Rotary Motor	24 = 24 VDC 120 = 120VDC Custom V for select 36000 and 46000 Series	-700 = indicates AC for Z Series motors -999 = Ball bearings -001 = Ball bearings for Z Series motors -000 = Sleeve bearings -XXX = Proprietary suffix assigned to a specific customer application. Identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

AMETEK Haydon Kerk Pittman **Stepper Motor Linear Actuator Customization**

Haydon Kerk Pittman takes great pride in designing and developing customized solutions for your application needs.

Our Design and Development Engineers begin with our standard catalog products and build ideal solutions for your motion needs. Our factories bring your solutions into production.



Multi-axis Motion Systems

Haydon Kerk offers pre-engineered and customizable solutions for multi-axis positioning requirements, leveraging our core actuator and linear rail technologies to deliver optimized system performance. Our integrated solutions solve the motion application challenges for technology driven original equipment manufacturers (OEMs) around the globe.



Z-Theta

Designed for easy integration in OEM assemblies, the Haydon Kerk Z-Theta™ offers linear + rotary point to point motion in an compact footprint. Unlike in-house component-up designs requiring engineering, multiple vendors and complex assembly integration, Z-Theta is a modular “bolt-in” package.

ZT04 Multi-Axis System

Performance in an Ultra-Compact 2-Axis Design

Designed for easy integration in OEM assemblies, the Haydon Kerk Z-Theta™ offers linear + rotary point to point motion in a compact footprint. Unlike in-house component-up designs requiring engineering, multiple vendors and complex assembly integration, Z-Theta is a modular “bolt-in” package.

At the core of Z-Theta is the patented ScrewRail™, which combines guidance and linear transmission in a slender co-axial profile. Haydon Kerk’s unique dual-motion integration with a pair of stepper motors adds rotary (theta) motion in manner that reduces motion system size by 50-80% as compared to alternative approaches, and less expensively than the equivalent components purchased separately.

The highly configurable Z-Theta provides flexibility, value, durability and performance suited for a host of lab automation, semiconductor and light factory automation applications. Performance is customized through a variety of leadscrew resolutions, available free-wheeling and anti-backlash nut selections, stepper motor configuration options, and optical encoder line counts.



Z-Theta Multi-Axis System

■ Benefits

- Compact co-axial design enables small footprint
- Easy integration into system design
- Pre-engineered modular design reduces supply chain and time to market
- Configuration options optimize performance for specific applications
- Compatible with a wide range of drive and controllers



Identifying the Z-Theta Part Number Codes when Ordering

ZT	04	A	K	B	A	J	A	A	E1	FY06
Prefix ZT = Z-Theta	Nominal Rail Size 04 = 1/2 in (13mm)	Nut Style A = Free-wheeling B = Anti-backlash	Coating S = Uncoated K = Kerkote®	Motors Frame Size B = Step- pers, Size 23 Rotary, Size 17 Linear	Rotary Motor A = 1.8°, 3.25VDC, Bipolar coils (4 wire) B = 1.8°, 5VDC, Bipolar coils (4 wire)	Rotary Motor Encoder J = 12000 CPR X = No Encoder	Linear Motor A = 1.8°, 2.33VDC, Bipolar coils (4 wire) B = 1.8°, 5VDC, Bipolar coils (4 wire)	Linear Motor Encoder A = 500 CPR C = 1000 CPR E = 2000 CPR X = No Encoder	Nominal Leadscrew Thread E1 = .050-in (1.27mm) E2 = .100-in (2.54mm) E4 = .250-in (6.35mm) E6 = .500-in (12.7mm) E7 = 1.00-in (25.4mm)	Stroke / Unique Identifier Xxx = Unique identifier

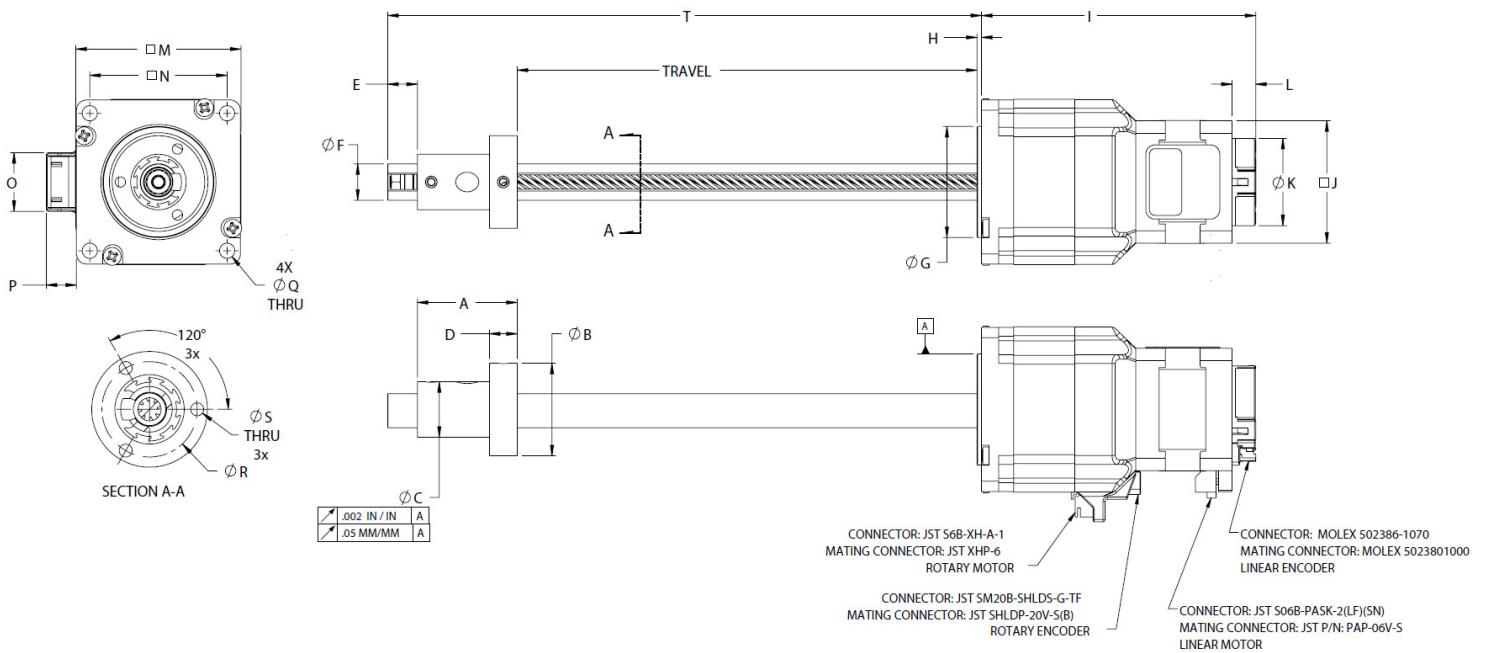
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

■ Mechanical Specifications

ZT04: Size 23 Rotary Motor, Size 17 Linear Motor		
Stroke Length Limit	in [mm]	12 [305]
Speed Limit	in/sec [mm/s]	6 [152]
Axial Force Limit	lb-f [N]	15 [67]
Load Limit (mass)	lb [kg]	5 [2.3]
Moment Load	in-lb [NM]	15 [1.7]
Torque, Theta Axis Motor	in-lb [NM]	3 [0.34]
Nut Length	in [mm]	1.4 [36]
Unit Height	in [mm]	Travel + 5.5 [140]
Width, Mounting Flange	in [mm]	2.23 [57]
Rail Material		Steel
Rail Runout	in/in [mm/25mm]	0.002 [0.05]
Rotary Repeatability (Open Loop)	in [mm]	+/-0.005 [0.13]
Rotary Resolution (@6" Radius)	in [mm]	+/-0.0031 [0.08]
Duty Cycle		100%

ZT04 Linear Specifications						
Lead Code		E1	E2	E4	E6	E7
Lead	in	0.050	0.100	0.250	0.500	1.00
	[mm]	[1.27]	[2.54]	[6.35]	[12.7]	[25.4]
Nominal Screw Diameter	in	0.25				
	[mm]	[6]				
Max Drag Torque	oz-in	2.0	TBD	3.0	4.0	5.0
	[NM]	[0.014]		[0.021]	[0.028]	[0.035]
Torque to Move Load	oz-in/lb	0.5	TBD	1.5	2.5	4.5
	[NM/Kg]	[0.004]		[0.011]	[0.018]	[0.32]
Resolution (Open Loop)	in	0.00025	0.0005	0.00125	0.0025	0.005
	[mm]	[0.00625]	[0.0127]	[0.03175]	[0.0635]	[0.127]

■ Dimensional Drawings



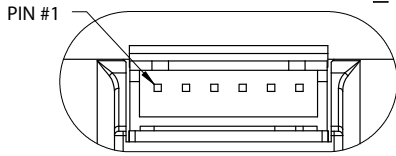
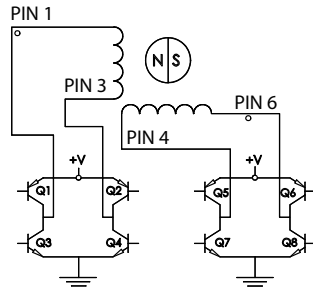
Units	A	B	C	D	E	F	G	H	I	J
in	1.35 ± .01	1.250 ± .005	.750 ± .005	.375 ± .005	.40 ± .01	.489 - .492	1.498 - 1.500	.06 ± .01	3.7 ± .1	1.65 ± .01
mm	34.29 ± 0.25	31.75 ± 0.13	19.05 ± 0.13	9.53 ± 0.13	10.16 ± 0.25	12.42 - 12.50	38.05 - 38.1	1.52 ± 0.25	93.98 ± 2.54	41.91 ± 0.25

Units	K	L	M	N	O	P	Q**	R	S**	T
in	1.18 ± .02	.32 ± .02	2.23 ± .02	1.856 ± .005	.79 - .81	.41 - .43	.205 ± .005	1.030 ± .005	.140 ± .005	= Travel + E + A+H (± .040)
mm	29.97 ± 0.51	8.13 ± 0.51	56.64 ± 0.51	47.14 ± 0.13	20.07 - 20.57	10.41 - 10.92	5.21 ± 0.13	26.16 ± 0.13	3.56 ± 0.13	= Travel + E + A+H (± 1)

** Tapped holes also available

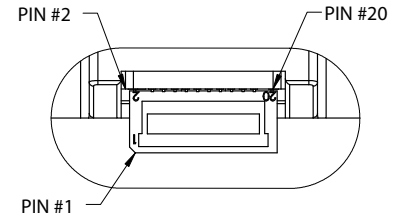
■ Connector Pinouts: Rotary

Pin #	Rotary Motor Connector Pinout
1	Phase 1 Start
2	
3	Phase 1 Finish
4	Phase 2 Finish
5	
6	Phase 2 Start



ROTARY MOTOR CONNECTOR
DETAIL VIEW

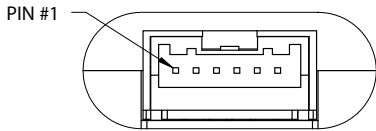
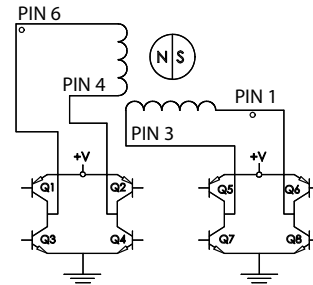
Pin #	Rotary Encoder Connector Pinout
1 - 8	Not used
9	DCOM**
10	Not used
11	VDD**
12	Chan. A+
13	Not used
14	Chan. B-
15	DGND
16	Chan. B+
17	+5V
18	Index-
19	Chan. A-
20	Index+



**Connects to EMI Filter Circuit

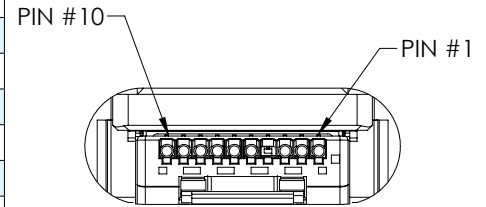
■ Connector Pinouts: Linear

Pin #	Linear Motor Connector Pinout
1	Phase 2 Start
2	
3	Phase 2 Finish
4	Phase 1 Finish
5	
6	Phase 1 Start



LINEAR MOTOR CONNECTOR
DETAIL VIEW

Pin #	Linear Encoder Connector Pinout
1	GND
2	Vcc +5VDC
3	Index-
4	Not used
5	Chan. A-
6	Chan. A+
7	Chan. B+
8	Chan. B-
9	Index+
10	Motor Ground



■ Motor Specifications: Rotary

Size 23: 57 mm (2.3 inch) Hybrid Rotary Stepper Motor (1.8° Step Angle)			
Motor Ordering Code	A	B	C
Stack Length	Single		
Wiring	Bipolar		
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current/phase	2.0 Arms	1.3 Arms	540 mArms
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH
Holding Torque	8.5 kg-cm		
Power Consumption	13 W Total		
Insulation Class	Class B		
Insulation Resistance	20 MΩ		

■ Motor Specifications: Linear

Size 17: 43 mm (1.7 inch) Hybrid Rotary Stepper Motor (1.8° Step Angle)			
Motor Ordering Code	A	B	C
Stack Length	Single		
Wiring	Bipolar		
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current/phase	1.5 A	700 mA	290 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH
Power Consumption	7 W		
Rotor Inertia	37 gcm ²		
Insulation Class	Class B (Class F available)		
Insulation Resistance	20 MΩ		

¹Part numbering information on page 192

¹Part numbering information on page 192

■ Performance Curves

SPEED vs. LINEAR FORCE (LINEAR MOTION)

- Chopper
- Bipolar
- 100% Duty Cycle

*Care should be taken when utilizing these screw pitches to ensure that the physical load limits of the motor are not exceeded. Please consult the factory for advice in selecting the proper pitch for your application.

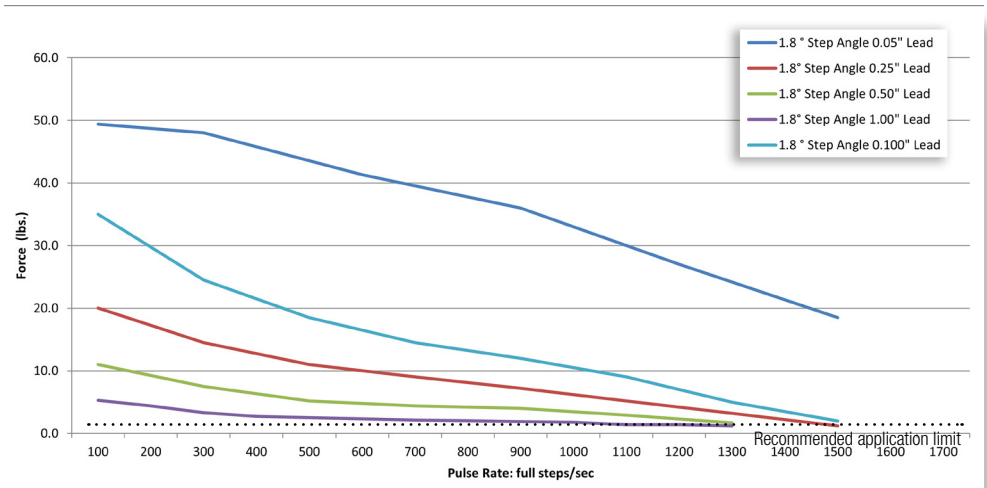
NOTE: 5 volt motor and 40 Vdc power supply (8:1 voltage ratio), X axis is Speed (Full-steps/sec), Y axis is Force (lbs)

The maximum step rate shown for each type of motor is the highest no-load start speed.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Loading is on axis with nut.

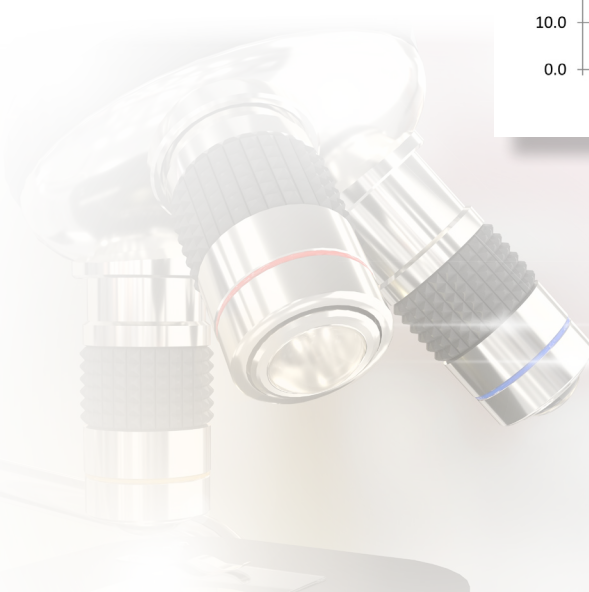
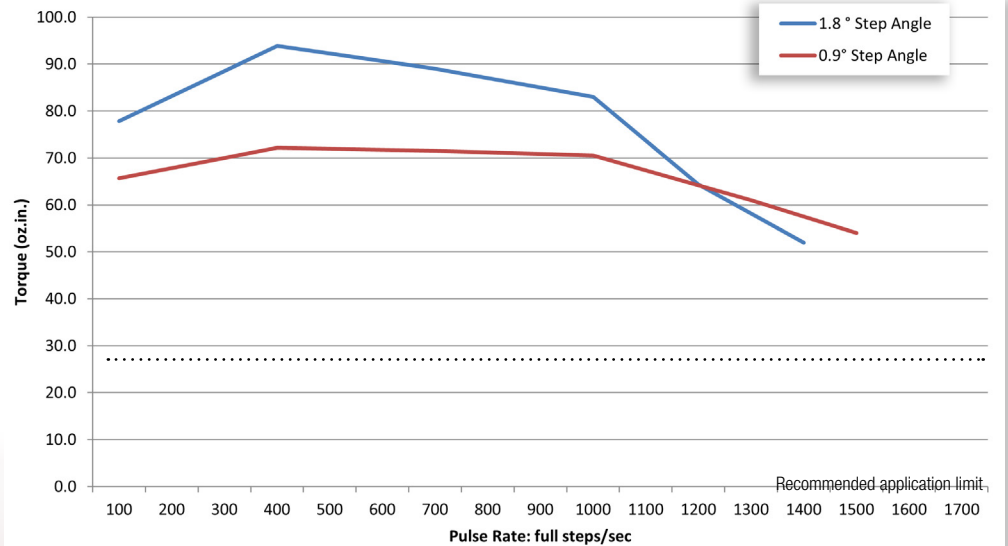


SPEED vs. PULL-OUT TORQUE (ROTARY MOTION)

- Chopper
- Bipolar
- 100% Duty Cycle

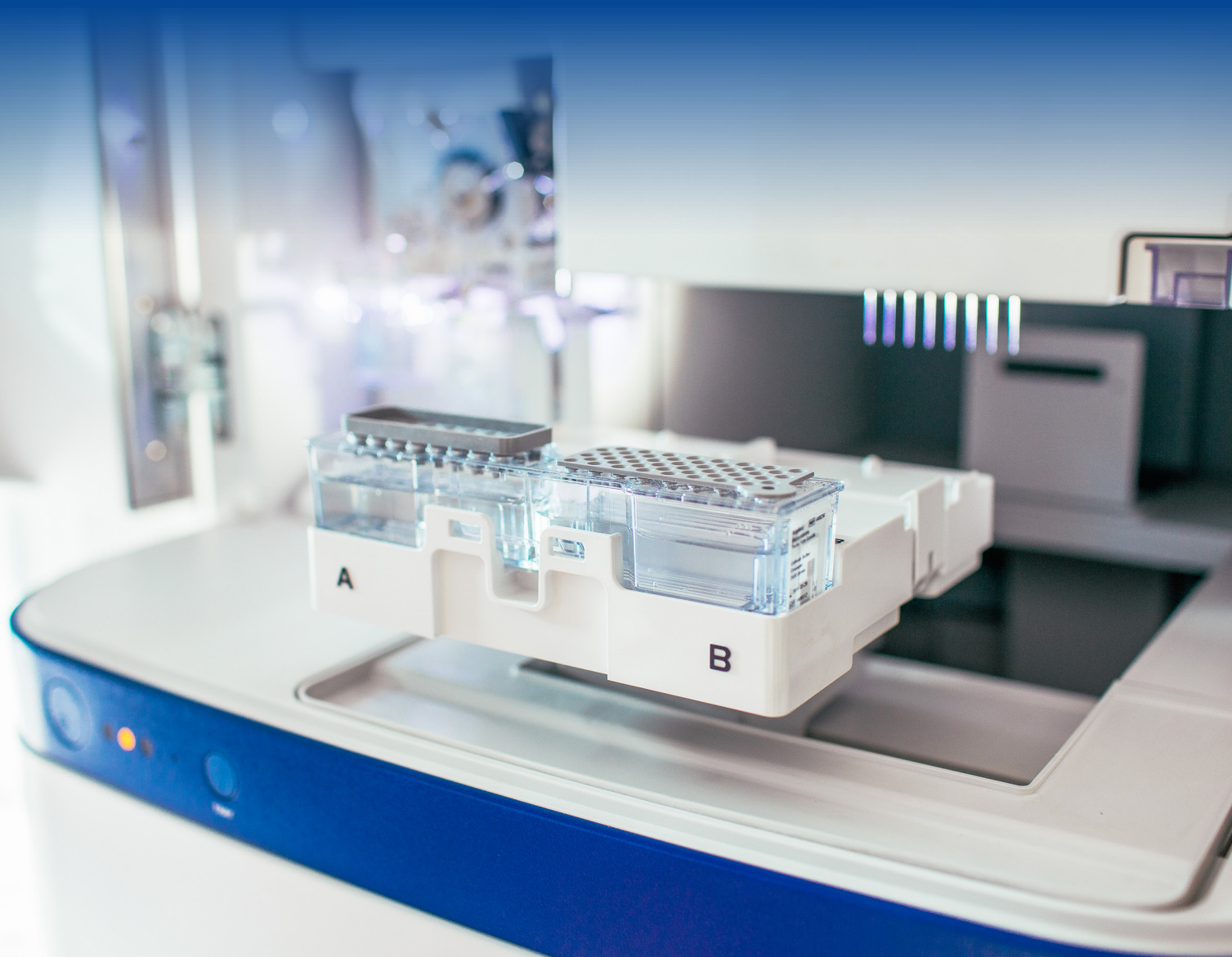
NOTE: 5 volt motor and 40 Vdc power supply (8:1 voltage ratio), X axis is Speed (Full-steps/sec), Y axis is Torque (oz.in).

Ramping can increase the performance of a motor by either increasing the top speed or getting a heavier load up to speed faster. Also, deceleration can be used to stop the motor without overshoot.



Linear Rail Systems

Haydon Kerk offers both motorized and non-motorized linear rails, guides and splines that deliver enhanced system stability, high positional accuracy, low friction and long life for a variety of linear motion applications.



Mini Motorized Slides

The compact, low profile MiniSlide™ saves engineering time. Perfect for small lab, medical equipment and optical stage applications. Highly configurable mini slide assemblies offer 2 motor options, 9 different lead screw options, 4 different lubrication options, as well as English or Metric standards.

Save
Engineering
Time!

new

MiniSlide™ motorized with Hybrid Stepper Actuator

small size, big power

Exceedingly configurable, simple to integrate MiniSlide™ assembly is ideally suited for small lab and automation equipment.

Compact, low profile

Super efficient motor

Small step resolution with 1.8° step angle

High power density and force

Encoder or encoder-ready options

Size 8 Hybrid Stepper Linear Actuator: 21 mm (0.8-in) (1.8° Step Angle)			
Wiring	Bipolar		
Winding Voltage	2.5 VDC	5 VDC	7.5 VDC
Current (RMS)/phase	.49 A	.24 A	.16 A
Resistance/phase	5.1 Ω	20.4 Ω	45.9 Ω
Inductance/phase	1.5 mH	5.0 mH	11.7 mH
Power Consumption	2.45 W		
Rotor Inertia	1.4 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	1.5 oz (43 g)		
Insulation Resistance	20 MΩ		

MiniSlide is also available with 20mm Can-Stack Motor.

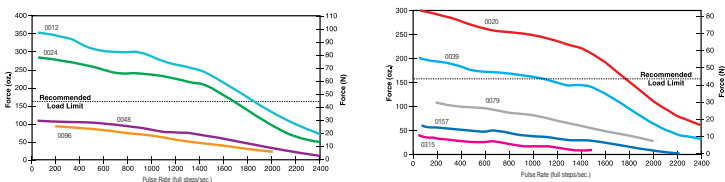
MiniSlide Load Specifications	
Design Payload (mass)	2.3kg [5 lbs]
Axial Force	45N [10 lbf]
Roll Moment*	1.13N-m [10 lbf-in]
Pitch Moment*	1.13N-m [10 lbf-in]
Yaw Moment*	0.56N-m [5 lbf-in]
Repeatability	+/-25µm [0.001 in]

* Moment data based on 0.5° deflection

Performance Curves

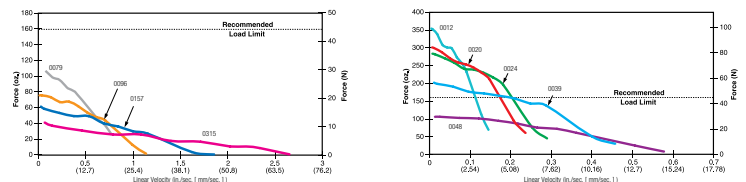
Force vs. Pulse Rate

– Chopper – 100% Duty Cycle – Bipolar – 0.14 (3.56) Lead Screw



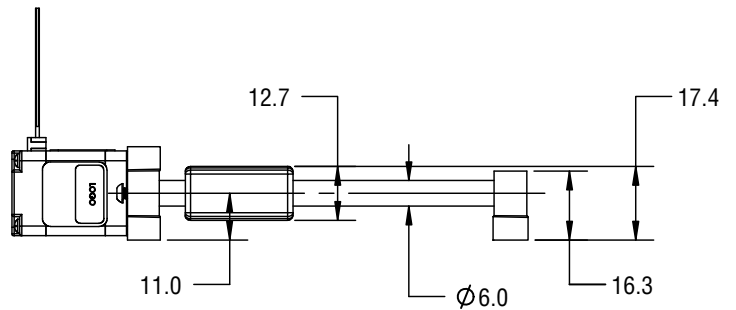
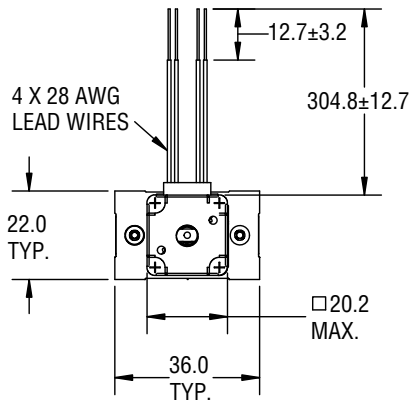
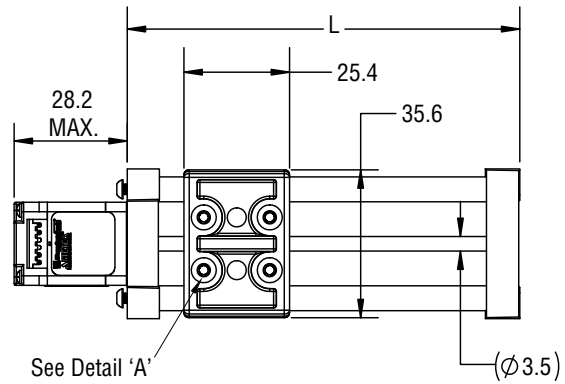
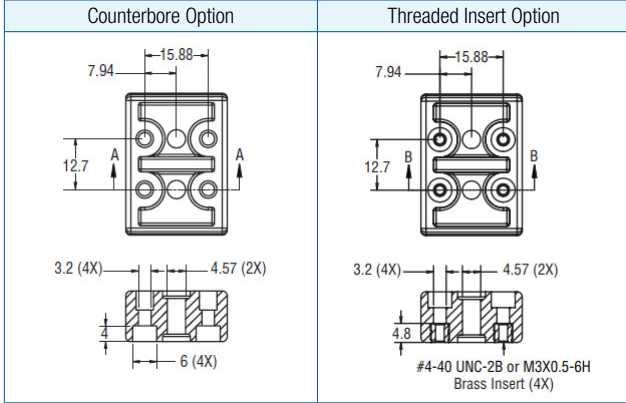
Force vs. Linear Velocity

– Chopper – 100% Duty Cycle – Bipolar – 0.14 (3.56) Lead Screw

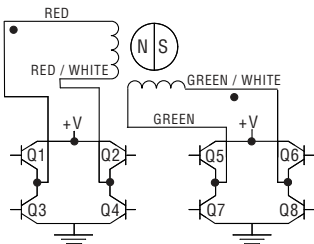


NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot. With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Detail A: Carriage Mounting Options



Wiring: Bipolar

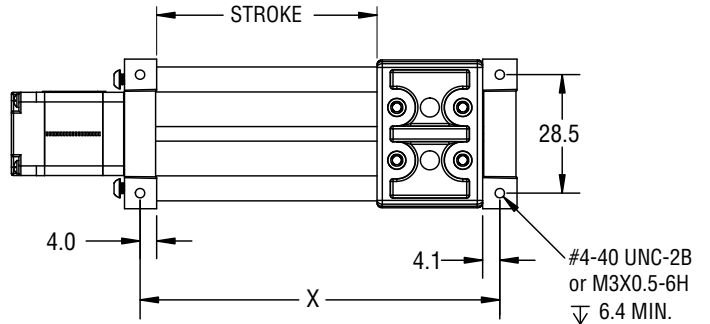


Can-Stack Motor Stepping Sequence

Bipolar Step	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

EXTEND CW ↑
RETRACT CCW ↓

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



Dimensions		
Stroke	Rail Length "L"	Mounting Holes "X"
25 mm	69.4 mm	61.5 mm
50 mm	94.4 mm	86.5 mm
75 mm	119.4 mm	111.5 mm
100 mm	144.4 mm	136.5 mm

Ordering Part Numbers for MiniSlide™ motorized with Size 8 Hybrid Stepper Actuator

MSA	02	K	H	0020	XXX
Prefix	Frame Size	Coating	Motor	Nominal Thread Lead Code	Suffix
MSA = Mini Slide Actuator	02 = 1/8" Screws	K = TFE Kerkote B = TFE Black Ice G = Grease S = No Lubricant	H = Size 8 Hybrid Stepper Linear Actuator	0020 = 1/2mm lead 0012 = 0.012" lead 0024 = 0.024" lead 0039 = 1mm lead 0048 = 0.048" lead 0079 = 2mm lead 0096 = 0.096" lead 0157 = 4mm lead 0315 = 8mm lead	805 = 50mm stroke M3 mounting 810 = 100mm stroke M3 mounting 905 = 50mm stroke #4-40 mounting 910 = 100mm stroke #4-40 mounting XXX = Unique identifier *

NOTE: Dashes must be included in the Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.
* Unique Identifier can be used to indicate additional options and/or product modifications.



Save Engineering Time!

new

MiniSlide™

motorized with Can-Stack Stepper

small size, big power

Exceedingly configurable, simple to integrate MiniSlide™ assembly is ideally suited for small lab and automation equipment.

Compact, low profile

Economically priced

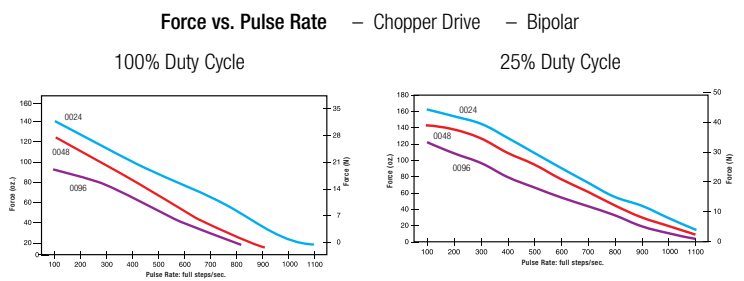
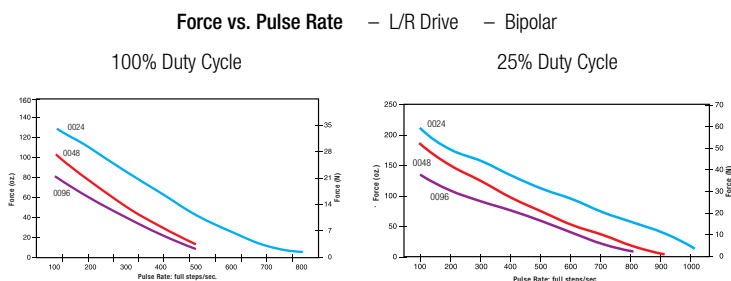
Ø 20mm (.79-in) 19000 Series Motor	
Step Angle	7.5°
Wiring	Bipolar
Winding Voltage	5 VDC 12 VDC
Current (RMS)/phase	350 mA 160 mA
Resistance/phase	14.0 Ω 74.5 Ω
Inductance/phase	6.24 mH 31.2 mH
Power Consumption	3.38 W
Insulation Class	Class B
Weight	1.24 oz (35 g)
Insulation Resistance	20 Ω

MiniSlide is also available with Size 8 Hybrid Stepper Linear Actuator.

MiniSlide Load Specifications	
Design Payload (mass)	2.3kg [5 lbs]
Axial Force	45N [10 lbf]
Roll Moment*	1.13N-m [10 lbf-in]
Pitch Moment*	1.13N-m [10 lbf-in]
Yaw Moment*	0.56N-m [5 lbf-in]
Repeatability	+/-25µm [0.001 in]

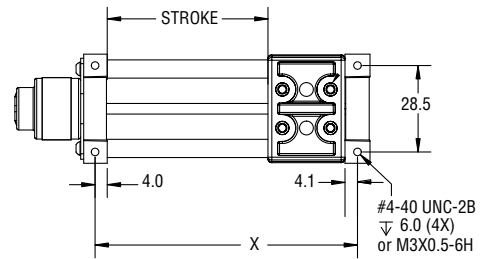
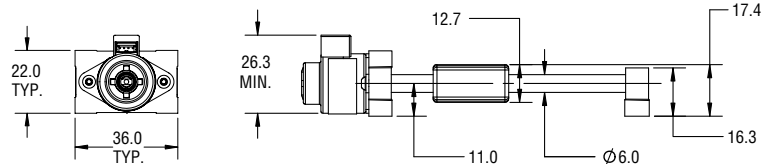
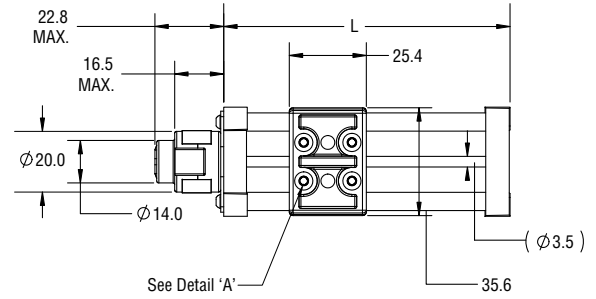
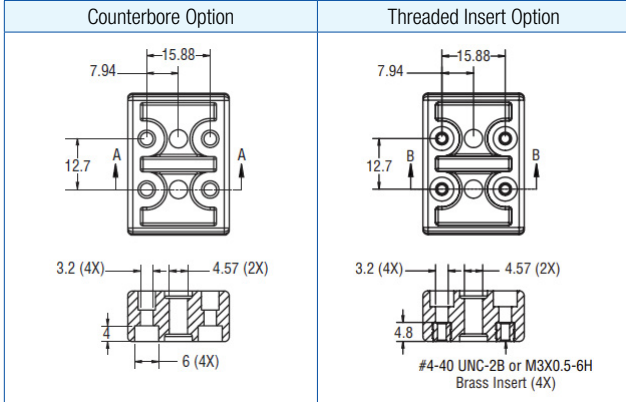
* Moment data based on 0.5° deflection

Performance Curves

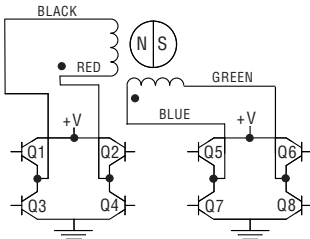


NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot. With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Detail A: Carriage Mounting Options



Wiring: Bipolar



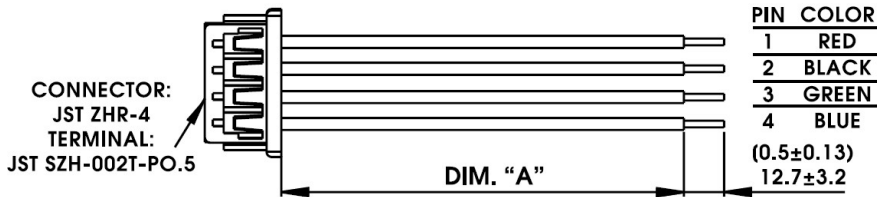
Can-Stack Motor Stepping Sequence

Bipolar Step	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Dimensions		
Stroke	Rail Length "L"	Mounting Holes "X"
25 mm	69.4 mm	61.5 mm
50 mm	94.4 mm	86.5 mm
75 mm	119.4 mm	111.5 mm
100 mm	144.4 mm	136.5 mm

Connector



Part Number	Dimension "A"
56-1318-4	(24 ±0.39) 610 ±10 mm
56-1318-3	(18 ±0.39) 450 ±10 mm
56-1318-2	(12 ±0.39) 305 ±10 mm
56-1318-1	(6 ±0.39) 150 ±10 mm

Ordering Part Numbers for MiniSlide™ motorized with 19000 Series Can-Stack Motor

MSA	02	K	C	0020	XXX
Prefix	Frame Size	Coating	Motor	Nominal Thread Lead Code	Suffix
MSA = Mini Slide Actuator	02 = 1/8" Screws	K = TFE Kerkote B = TFE Black Ice G = Grease S = No Lubricant	C = 20mm G4 19000 Can-Stack Stepper Motor	0020 = 1/2mm lead 0039 = 1mm lead 0079 = 2mm lead 0157 = 4mm lead 0315 = 8mm lead	0012 = 0.012" lead 0024 = 0.024" lead 0048 = 0.048" lead 0096 = 0.096" lead 805 = 50mm stroke M3 mounting 810 = 100mm stroke M3 mounting 905 = 50mm stroke #4-40 mounting 910 = 100mm stroke #4-40 mounting XXX = Unique identifier *

NOTE: Dashes must be included in the Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441. * Unique Identifier can be used to indicate additional options and/or product modifications.

Ball Guided Rail Systems

The BGS Linear Rail combines many technologies into a single integrated linear motion platform. The system provides excellent load capability and is engineered for both normal and overhanging loads. High roll, pitch, and yaw moment loading capability allows the system to maintain tight accuracy and repeatability, even in applications requiring significant cantilevered loading. The lead screw drives a machined aluminum carriage mounted to a precision stainless steel ball rail resulting in a rigid, smooth-operating motion system. Offers an optional wear-compensating anti-backlash driven carriage. Black Ice® TFE coated screw provides a permanent wear-resistant dry lubrication.

When integrated with an IDEA Drive, the system combines Haydon hybrid linear actuator technology with a fully programmable, integrated stepper motor drive. By combining technologies into a single preassembled unit, Haydon Kerk Motion Solutions is able to improve system integration for the equipment OEM or end user. The overall cost for the customer is also lowered by offering a complete solution as it eliminates the need for rotary-to-linear conversion, and simplified product development.

BGS Linear Rails with Recirculating Ball Slide

A BGS Motorized Linear Rail combines multiple technologies into a single integrated linear motion platform. The system provides excellent load capacity and is engineered for both normal and overhanging loads. High roll, pitch and yaw moment loading capability allows the system to maintain tight accuracy and repeatability, even in applications requiring significant cantilevered loading.

machined aluminum carriage mounted to a precision stainless steel ball slide resulting in a rigid, smooth operating motion system. The screw is coated with Black Ice® TFE coating providing a permanent wear-resistant dry lubrication.

At the heart of the BGS Linear Rail system is a Haydon hybrid linear actuator with a precision 303 stainless steel lead screw. The lead screw drives a



Hybrid Linear Actuator Motor	BGS04	BGS06	BGS08
	Size 11 Double Stack Size 17 Single Stack*	Size 17 Single Stack* Size 17 Double Stack*	Size 23 Single Stack* Size 23 Double Stack
Max. Stroke Length	18-in (460 mm)	24-in (610 mm)	30-in (760 mm)
Max. Load (Horizontal)**	22 lbs (100 N)	135 lbs (600 N)	225 lbs (1,000 N)
Roll Moment	5.72 lbs-ft (7.75 N-m)	11.62 lbs-ft (15.75 N-m)	22.50 lbs-ft (30.5 N-m)
Pitch Moment	4.88 lbs-ft (6.60 N-m)	7.93 lbs-ft (10.75 N-m)	19.36 lbs-ft (26.25 N-m)
Yaw Moment	5.68 lbs-ft (7.70 N-m)	9.15 lbs-ft (12.40 N-m)	22.27 lbs-ft (30.20 N-m)

Nominal Thread Lead		Lead Code	BGS04	BGS06	BGS08
inches	mm				
0.025	0.635	0025	•		
0.039	1.00	0039	•		
0.050	1.27	0050	•	•	
0.0625	1.59	0063	•		
0.079	2.00	0079	•	•	
0.098	2.5	0098			•
0.100	2.54	0100	•	•	•
0.118	3.00	0118	•		
0.125	3.18	0125			
0.157	4.00	0157		•	
0.197	5.00	0197		•	•
0.200	5.08	0200	•	•	•
0.250	6.35	0250	•	•	
0.315	8.00	0315			
0.375	9.53	0375		•	
0.394	10.00	0394	•		
0.400	1.016	0400		•	
0.472	12.00	0472		•	
0.500	12.70	0500	•	•	•
0.630	16.00	0630			•
0.750	19.05	0750	•	•	
0.984	25.00	0984		•	
1.000	25.40	1000	•	•	•
1.200	30.48	1200		•	

Size 11 = 28000 Series | Size 17 = 43000 Series | Size 23 = 57000 Series

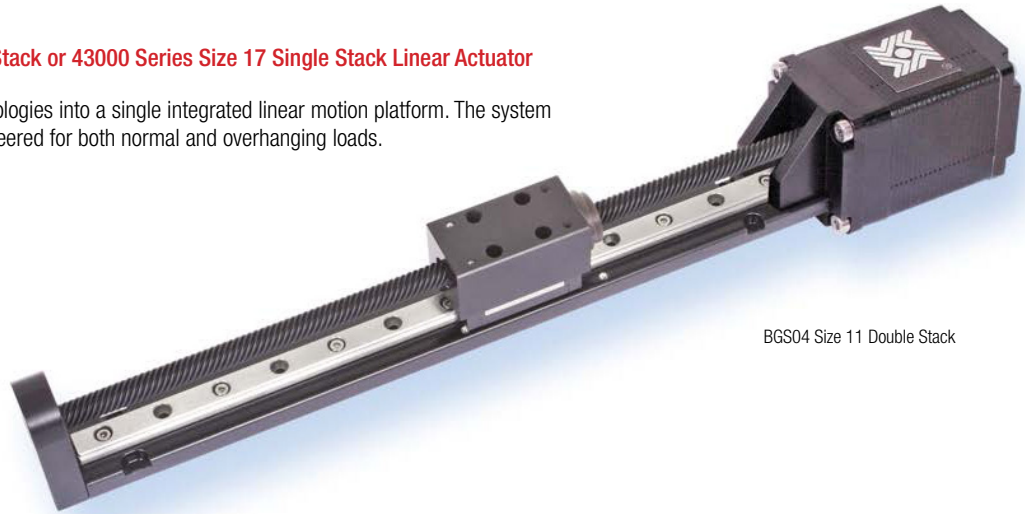
*Size 17 (43000 Series) Single and Double Stack Hybrid Linear Actuator Stepper Motors (BGS06) are available with an optional programmable IDEA™ Drive. IDEA Drives are not available in the BGS08 Linear Rail.

**For vertical load information, see specifications for the Size 11 (28000 Series), Size 17 (43000 Series), and Size 23 (57000 Series) motors.

BGS04™ Linear Rail

with Hybrid 28000 Series Size 11 Double Stack or 43000 Series Size 17 Single Stack Linear Actuator

The BGS™ Linear Rail combines many technologies into a single integrated linear motion platform. The system provides excellent load capability and is engineered for both normal and overhanging loads.



BGS04 Size 11 Double Stack

■ Specifications: BGS04

BGS with Hybrid Linear Actuator Motor	Size 11 Double Stack Size 17 Single Stack*
Max. Stroke Length	18 in (460 mm)
Max. Load (horizontal)	22 lbs (100 N)
Roll Moment	5.72 lbs-ft (7.75 Nm)
Pitch Moment	4.88 lbs-ft (6.60 Nm)
Yaw Moment	5.68 lbs-ft (7.70 Nm)

* Size 17 is available with an optional programmable IDEA™ Drive.

Nominal Thread Lead		Lead Code
inches	mm	
0.025	0.635	0025
0.039	1.00	0039
0.050	1.27	0050
0.0625	1.59	0063
0.079	2.00	0079
0.100	2.54	0100
0.118	3.00	0118
0.200	5.08	0200

Nominal Thread Lead		Lead Code
inches	mm	
0.250	6.35	0400
0.394	10.00	0472
0.500	12.70	0500
0.750	19.05	0750
1.000	25.40	1000

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

■ Identifying the BGS Part Number Codes when Ordering

BG	S	04	B	M	0025	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
BG = Ball Guide System	S = Standard	04 = Max.static load 22 lbs (100 N)	B = TFE wear resist, dry lubricant Black Ice®	M = Motorized For 43000 Series Size 17 Only G = IDEA™ integrated programmable drive – USB communications J = IDEA™ integrated programmable drive – RS485 communications	0025 = .025-in (.635) (see Lead Code charts above)	Suffix used to identify Size 11 or Size 17 motor – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M2, M2.5, M3, M4

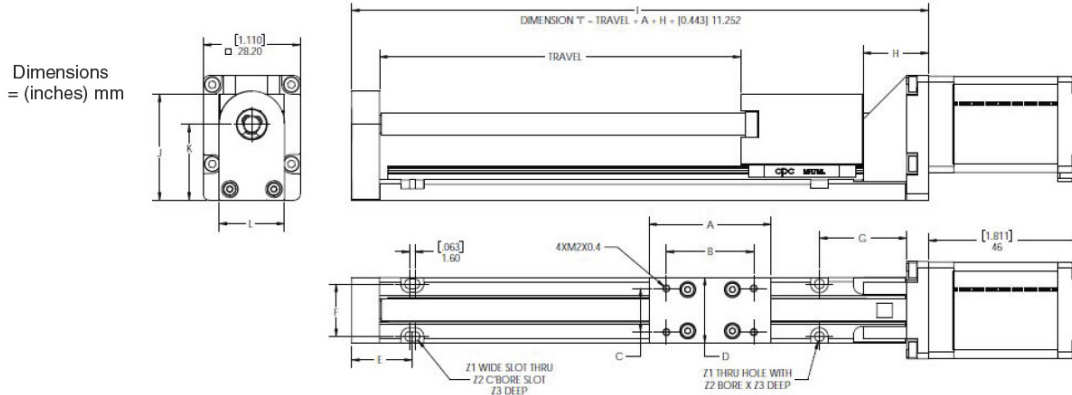
Double Stack

■ BGS04 Linear Rail with 28000 Series Size 11 Linear Actuator

Recommended for horizontal loads up to 22 lbs (100 N)

	A	B	C	D	E	F	G	H	I	J	K	L	Z1	Z2	Z3
(inch)	(1.40)	(1.00)	(0.50)	(0.75)	(0.69)	(0.60)	(1.00)	(0.75)	*	(1.22)	(0.87)	(0.75)	(0.11)	(0.20)	(0.09)
mm	35.56	25.40	12.70	19.05	17.53	15.24	25.4	19.05		30.86	22.10	19.05	2.8	5.1	2.3

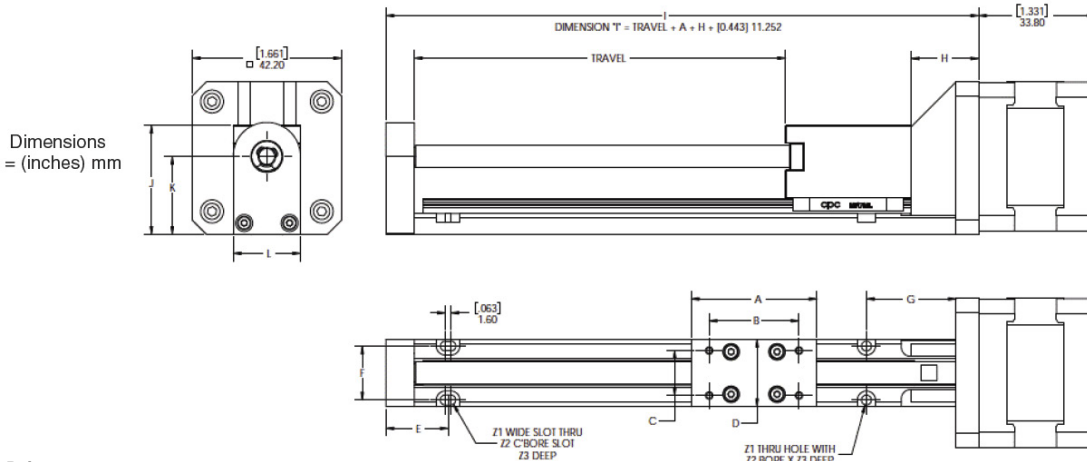
* Dimension "I" is a function of required travel distance.



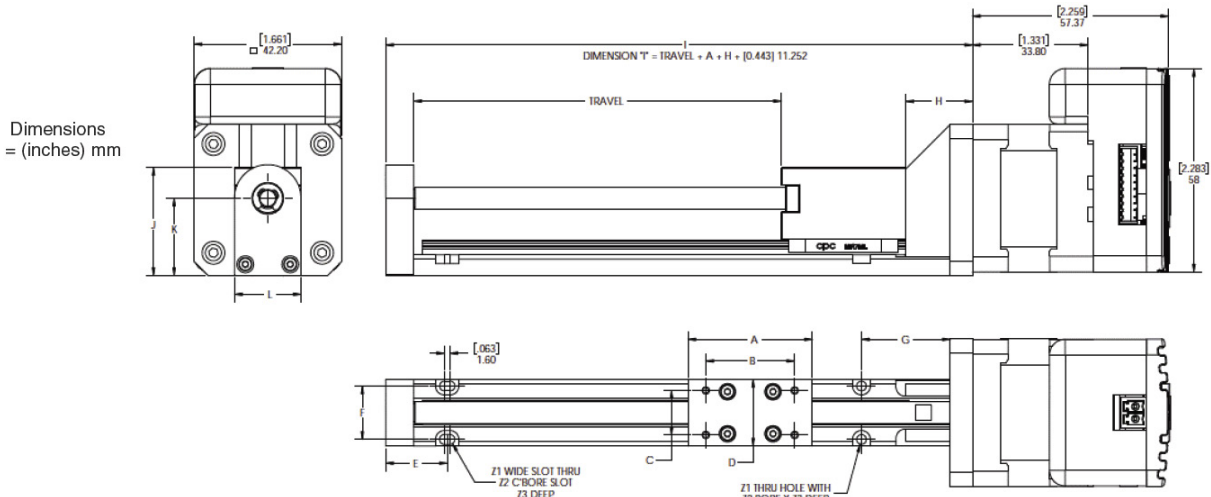
Single Stack

■ BGS04 Linear Rail with 43000 Series Size 17 Linear Actuator

Recommended for horizontal loads up to 22 lbs (100 N)



...with IDEA™ Drive



Double Stack

■ 28000 Series Size 11 Linear Actuator

Size 11 Double Stack: 28 mm (1.1-in) Hybrid Linear Actuator (1.8° Step Angle)			
Wiring	Bipolar		
Winding Voltage	2.1 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.9 A	750 mA	313 mA
Resistance/phase	1.1 Ω	6.7 Ω	34.8 Ω
Inductance/phase	1.1 mH	5.8 mH	35.6 mH
Power Consumption	7.5 W Total		
Rotor Inertia	13.5 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	5.8 oz (180 g)		
Insulation Resistance	20 MΩ		



Size 11
Double Stack External Linear

Single Stack

■ 43000 Series Size 17 Linear Actuator

Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)					
Wiring	Bipolar			Unipolar**	
Programmable Drive	IDEA™ Drive Option Available			Not Applicable	
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH
Power Consumption	7 W				
Rotor Inertia	37 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	8.5 oz (241 g)				
Insulation Resistance	20 MΩ				

Size 17 External Linear



Size 17 External Linear
with programmable IDEA Drive

IDEA™ Drive software is simple to use with on-screen buttons and easy-to-understand programming guides.

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability – Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

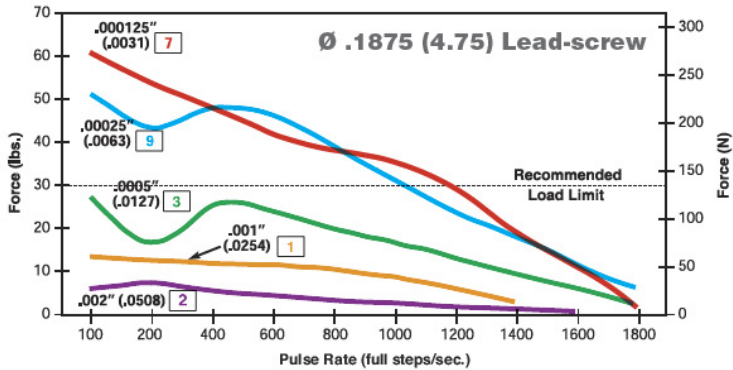
For more information see the [IDEA™ Drive Data Sheet](#)

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.
** Unipolar drive gives approximately 30% less thrust than bipolar drive.

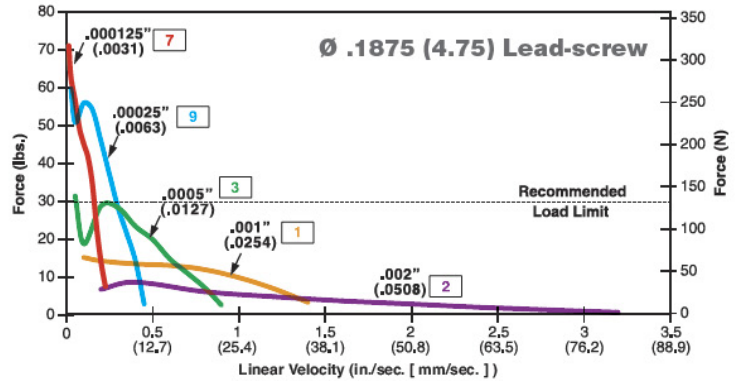
Double Stack

■ 28000 Series Size 11 Linear Actuator

FORCE vs. PULSE RATE
 - Chopper - Bipolar - 100% Duty Cycle



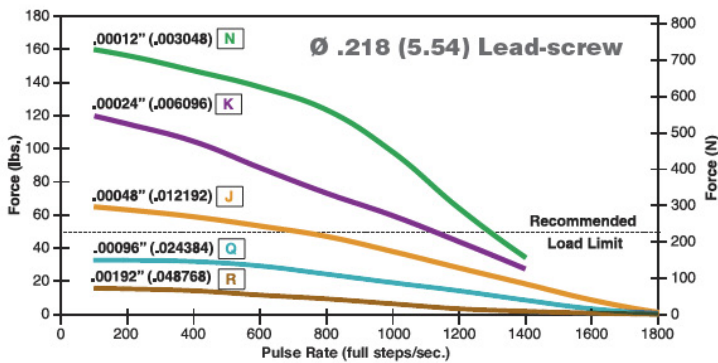
FORCE vs. LINEAR VELOCITY
 - Chopper - Bipolar - 100% Duty Cycle



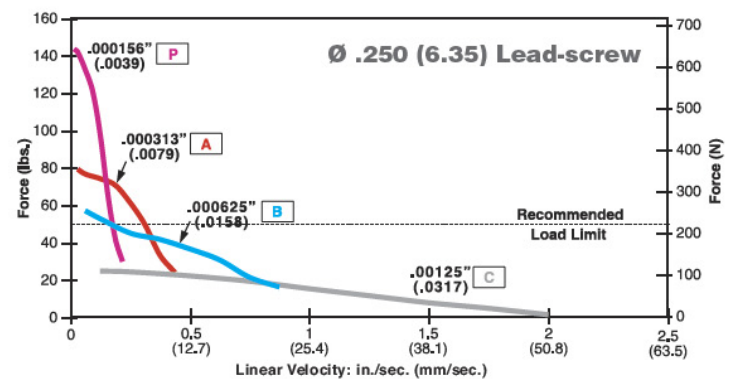
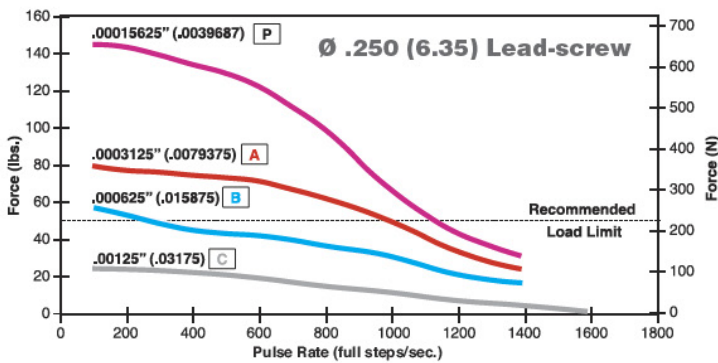
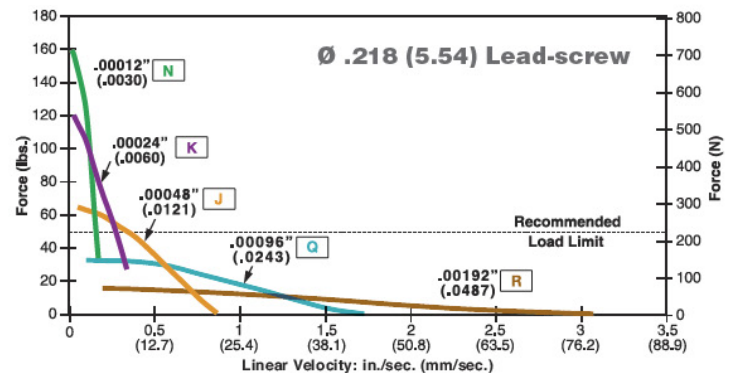
Double Stack

■ 43000 Series Size 17 Linear Actuator

FORCE vs. PULSE RATE
 - Chopper - Bipolar - 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
 - Chopper - Bipolar - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

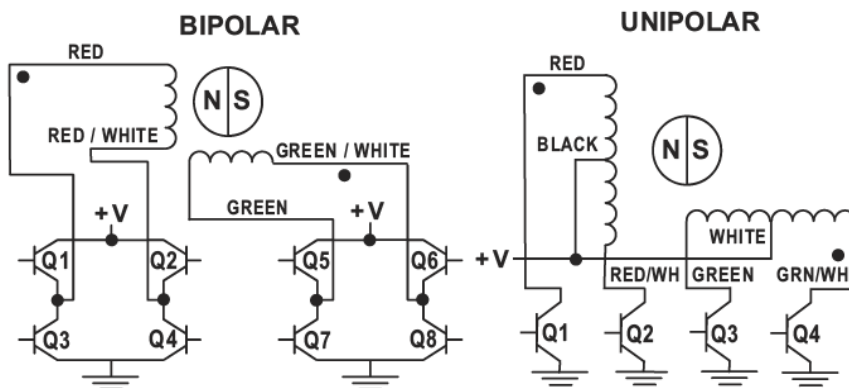
■ 28000 Series Size 11 and 43000 Series Size 17 Linear Actuators

Hybrids: Stepping Sequence

Hybrids: Wiring

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
	Unipolar	Q1	Q2	Q3	Q4
Step 1 2 3 4 1	EXTEND CW ↑ RETRACT COW ↓				
	1	ON	OFF	ON	OFF
	2	OFF	ON	ON	OFF
	3	OFF	ON	OFF	ON
	4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF	

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



Size 11 28000 Series and Size 17 43000 Series • Integrated Connectors

Hybrid Size 11 Double Stack and Size 17 Single Stack linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre existing harnesses. In addition to standard configurations, Haydon Kerk Motion Solutions can custom design this motor to meet your specific application requirements.

Motor Connector: JST part # S06B-PASK-2
Mating Connector: JST part # PAP-06V-S
 Haydon Kerk Part #56-1210-5 (12 in. Leads)
Wire to Board Connector:
 JST part number SPHD-001T-P0.5

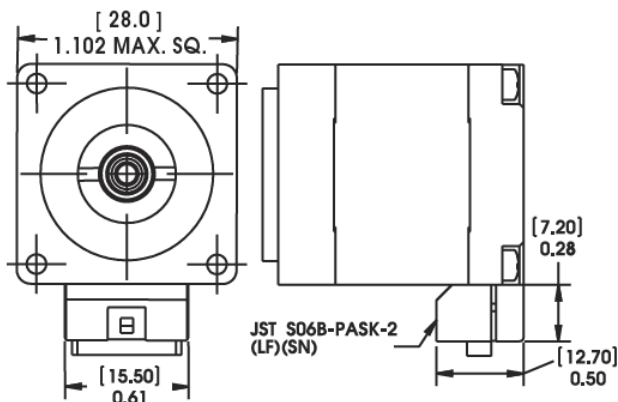


Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red

Dimensional Drawings

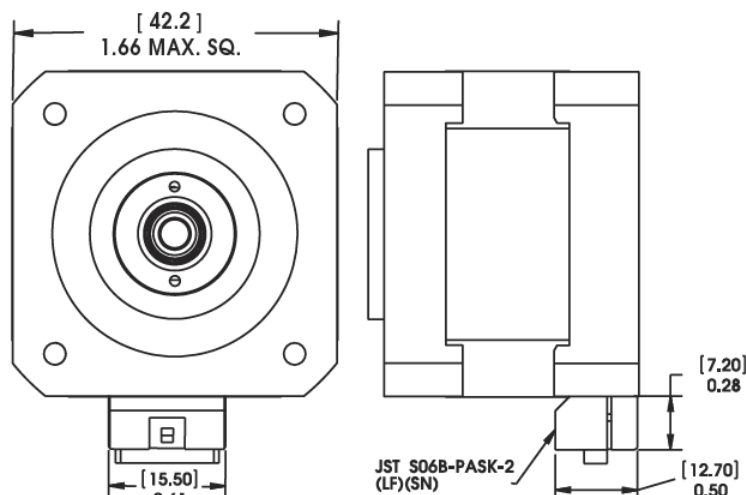
■ Integrated Connector with 28000 Series Size 11 Linear Actuator

Dimensions = (mm) inches



■ Integrated Connector with 43000 Series Size 17

Dimensions = (mm) inches

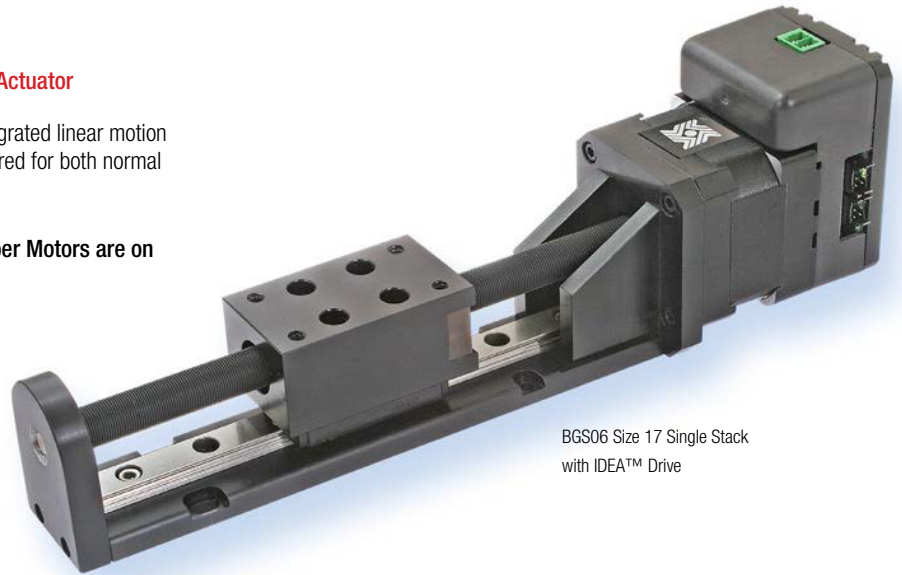


BGS06 Linear Rail

with Hybrid 43000 Series Size 17 Single or Double Stack Linear Actuator

The BGS™ Linear Rail combines many technologies into a single integrated linear motion platform. The system provides excellent load capability and is engineered for both normal and overhanging loads.

Technical specifications for Size 17 Hybrid Linear Actuator Stepper Motors are on page 3.



BGS06 Size 17 Single Stack with IDEATM Drive

Specifications: BGS06

BGS with Hybrid Linear Actuator Motor	Size 17 Single and Double Stack*
Max. Stroke Length	24 in (610 mm)
Max. Load (horizontal)	135 lbs (600 N)
Roll Moment	11.62 lbs-ft (15.75 Nm)
Pitch Moment	7.93 lbs-ft (10.75 Nm)
Yaw Moment	9.15 lbs-ft (12.4 Nm)

* Available with an optional programmable IDEATM Drive.

Nominal Thread Lead		Lead Code
inches	mm	
0.050	1.27	0050
0.079	2.00	0079
0.100	2.54	0100
0.157	4.00	0157
0.197	5.00	0197
0.200	5.08	0200
0.250	6.35	0250
0.375	9.53	0375

Nominal Thread Lead		Lead Code
inches	mm	
0.400	10.16	0400
0.472	12.00	0472
0.500	12.70	0500
0.750	19.05	0750
0.984	25.00	0984
1.000	25.40	1000
1.200	30.48	1200

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the BGS Part Number Codes when Ordering

BG	S	06	B	G	0079	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
BG = Ball Guide System	S = Standard	06 = Max.static load 135 lbs (600 N)	B = TFE wear resist, dry lubricant Black Ice®	M = Motorized G = IDEATM integrated programmable drive – USB communications J = IDEATM integrated programmable drive – RS485 communications	0079 = .079-in (2.0) (see Lead Code charts above)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M3.5, M4

Single Stack

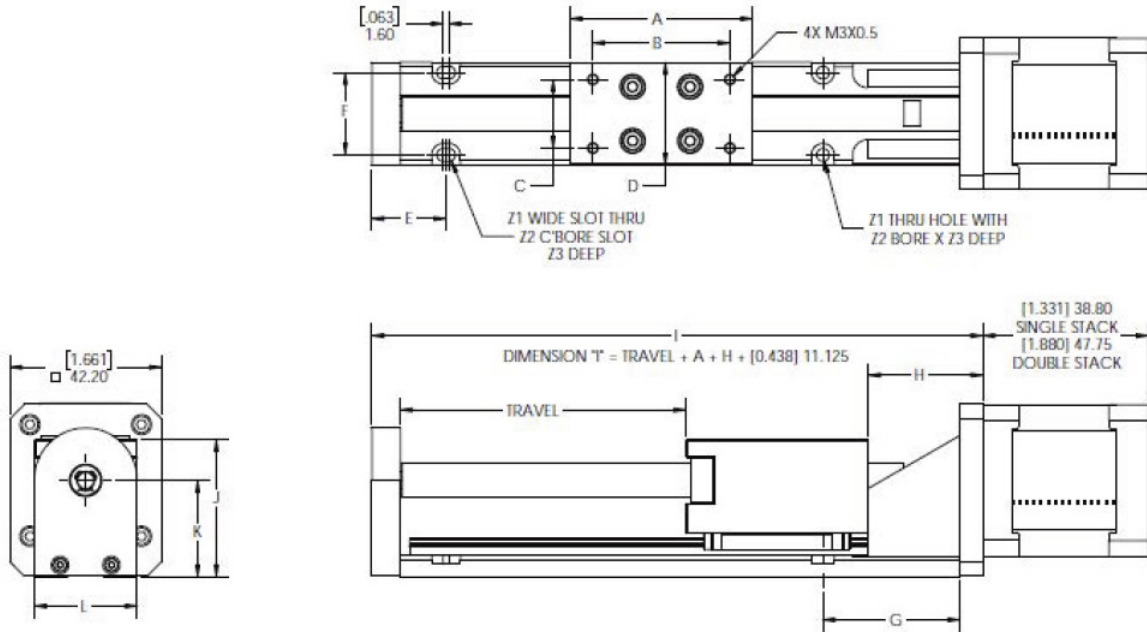
■ BGS06 Linear Rail with 43000 Series Size 17 Linear Actuator

Recommended for horizontal loads up to 135 lbs (600 N)

	A	B	C	D	E	F	G	H	I	J	K	L	Z1	Z2	Z3
(inch)	(2.00)	(1.50)	(0.75)	(1.13)	(0.81)	(0.90)	(1.50)	(1.25)	*	(1.5)	(1.05)	(1.13)	(0.14)	(0.25)	(0.13)
mm	50.80	38.10	19.05	28.58	20.57	22.86	38.10	31.75		38.15	26.77	28.58	3.6	6.3	3.3

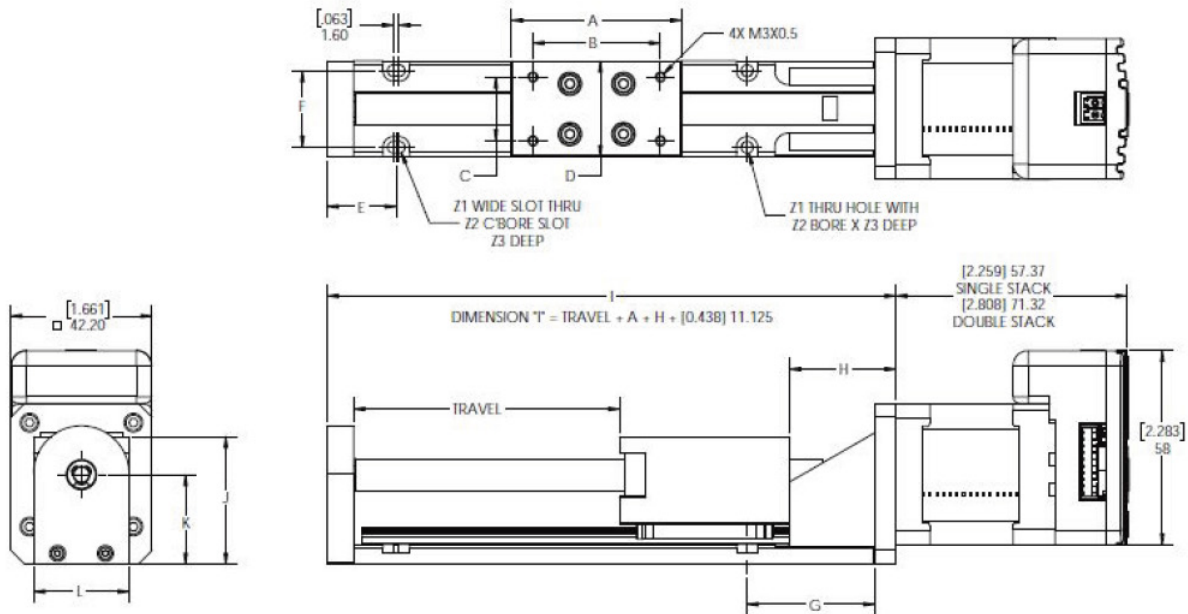
Dimensions = (inches) mm

* Dimension "I" is a function of required travel distance.



...with IDEA™ Drive

Dimensions = (inches) mm



Single Stack

Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
Programmable Drive	IDEA™ Drive Option Available			Not Applicable	
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH
Power Consumption	7 W				
Rotor Inertia	37 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	8.5 oz (241 g)				
Insulation Resistance	20 MΩ				

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Size 17 External Linear

Size 17 External Linear
with programmable IDEA Drive

IDEA™ Drive software is simple to use with on-screen buttons and easy-to-understand programming guides.

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability – Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

For more information see the [IDEA™ Drive Data Sheet](#)

Double Stack

Size 17 Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
Programmable Drive	IDEA™ Drive Option Available		
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.6 A	1.3 A	550 mA
Resistance/phase	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.33 mH	8.21 mH	45.1 mH
Power Consumption	13.2 W		
Rotor Inertia	78 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	12.5 oz (352 g)		
Insulation Resistance	20 MΩ		

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.

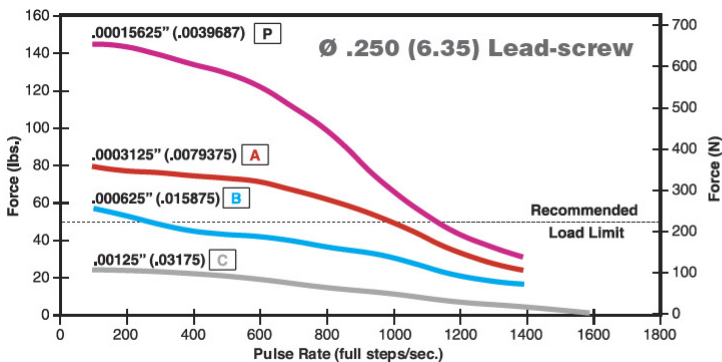
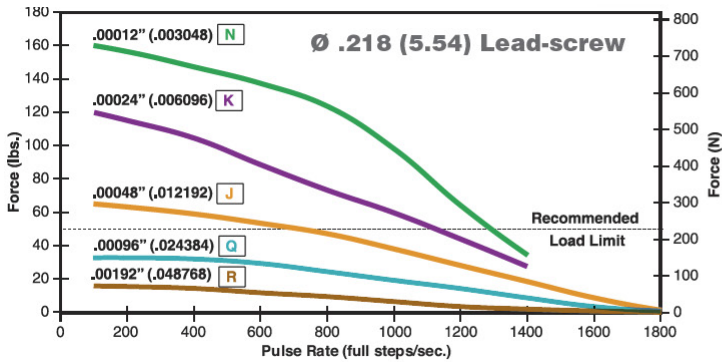
** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Size 17 Double Stack
External Linear

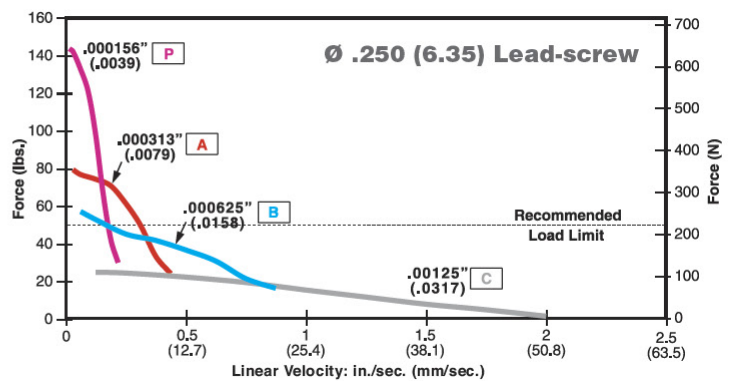
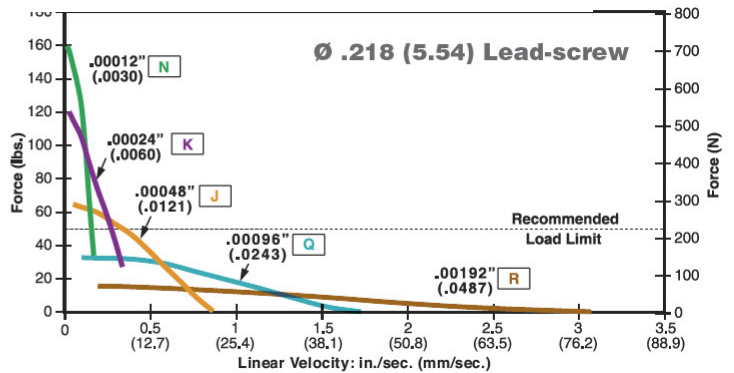
Double Stack

43000 Series Size 17 Linear Actuator

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



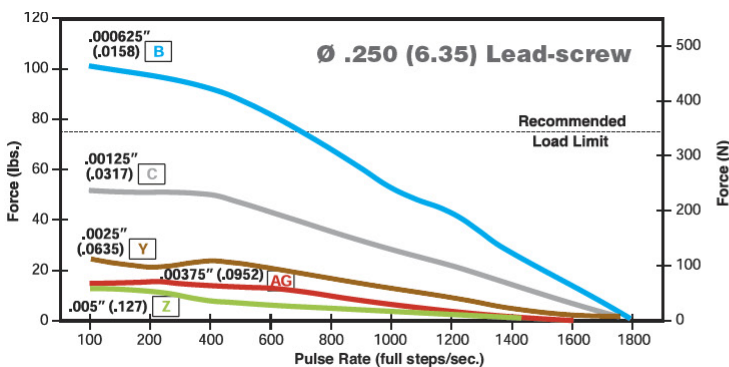
FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle



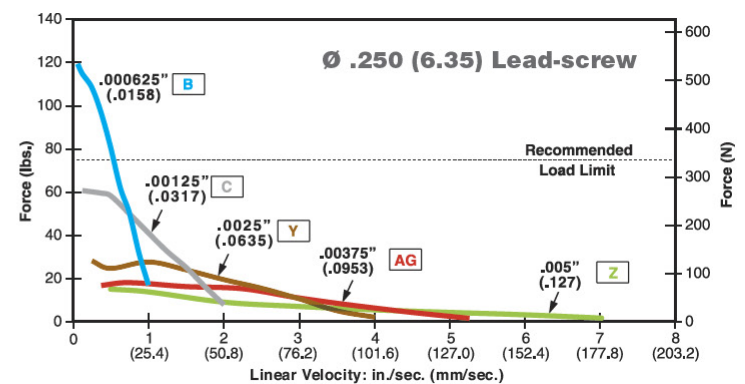
Double Stack

43000 Series Size 17 Linear Actuator

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

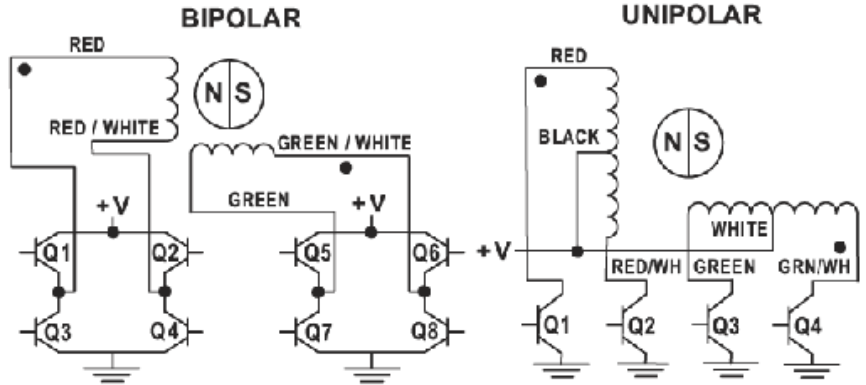
■ 28000 Series Size 11 and 43000 Series Size 17 Linear Actuators

Hybrids: Stepping Sequence

Hybrids: Wiring

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



Size 17 43000 Series • Integrated Connectors



Hybrid Size 17 linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre existing harnesses. In addition to standard configurations, Haydon Kerk Motion Solutions can custom design this motor to meet your specific application requirements.

Motor Connector:
Mating Connector:

Wire to Board Connector:

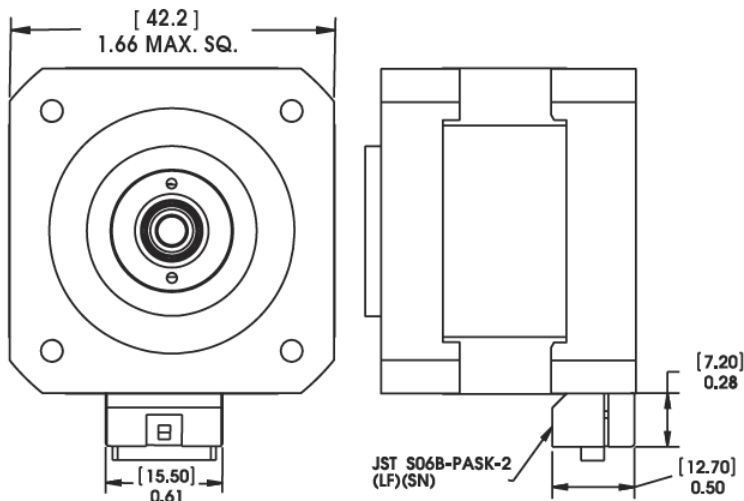
JST part # S06B-PASK-2
JST part # PAP-06V-S
Haydon Kerk Part #56-1210-5 (12 in. Leads)
JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red

Dimensional Drawing

■ 43000 Series Size 17 Linear Actuator with Integrated Connector

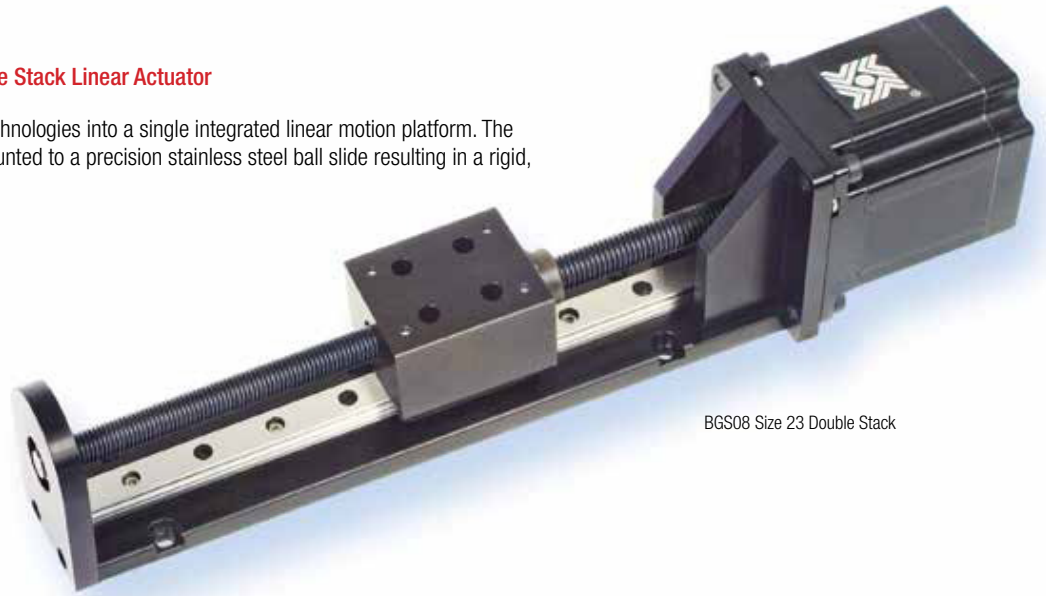
Dimensions = (mm) inches



BGS08™ Linear Rail

with Hybrid 57000 Series Size 23 Single or Double Stack Linear Actuator

This BGS™ heavy-duty linear rail combines many technologies into a single integrated linear motion platform. The lead screw drives a machined aluminum carriage mounted to a precision stainless steel ball slide resulting in a rigid, smooth-operating motion system.



BGS08 Size 23 Double Stack

Specifications: BGS08

BGS with Hybrid Linear Actuator Motor	Size 23 Single and Double Stack
Max. Stroke Length	30 in (760 mm)
Max. Load (horizontal)	225 lbs (1,000 N)
Roll Moment	22.5 lbs-ft (30.5 Nm)
Pitch Moment	19.36 lbs-ft (26.25 Nm)
Yaw Moment	22.27 lbs-ft (30.20 Nm)

Nominal Thread Lead		Lead Code
inches	mm	
0.098	2.50	0098
0.100	2.54	0100
0.197	5.00	0197
0.200	5.08	0200
0.500	12.70	0500
0.630	16.00	0630
1.000	25.40	1000

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the BGS Part Number Codes when Ordering

BG	S	08	B	M	0025	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
BG = Ball Guide System	S = Standard	08 = Max. static load 225 lbs (1,000 N)	B = TFE wear resist, dry lubricant Black Ice®	M = Motorized	0197 = .197-in (5.0) (see Lead Code charts above)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M5 and M6

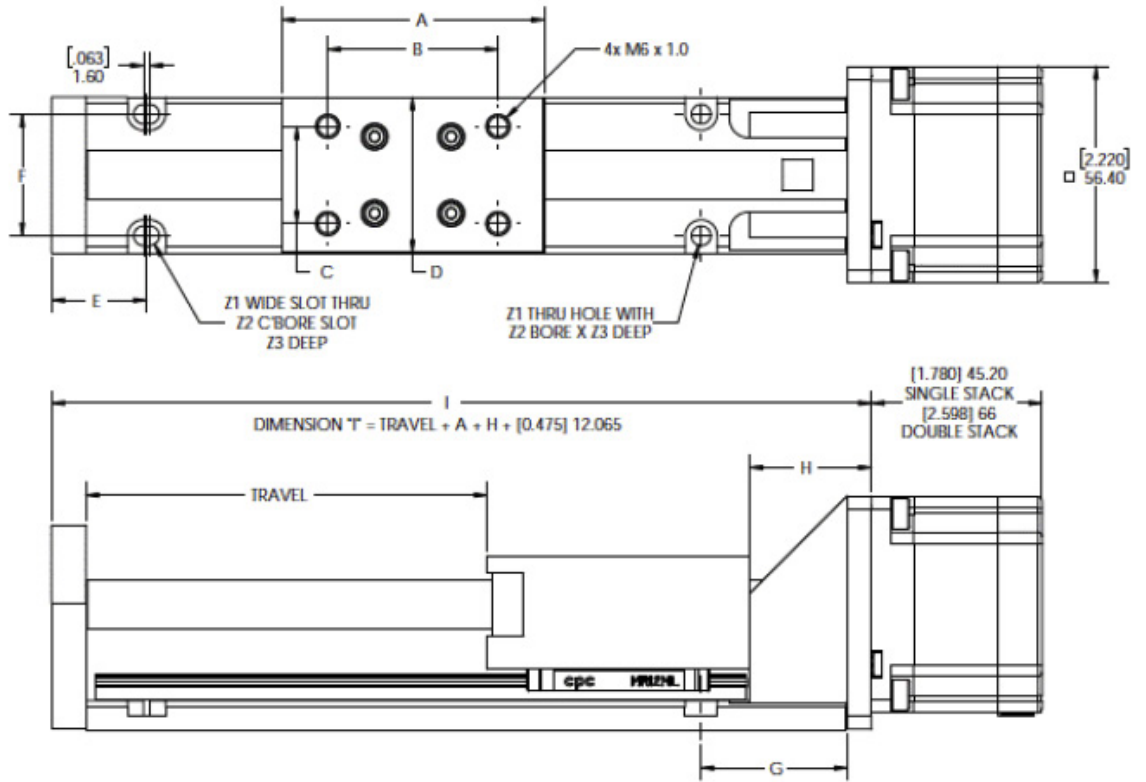
■ BGS08 Linear Rail with Hybrid 57000 Size 23 Linear Motors

Recommended for horizontal loads up to 225 lbs (1,000 N)

	A	B	C	D	E	F	G	H	I	J	K	L	Z1	Z2	Z3
(inch)	(2.70)	(1.75)	(1.00)	1.60	(0.98)	(1.25)	(1.50)	(1.25)	*	(1.79)	(1.29)	(1.60)	(0.20)	(0.33)	(0.19)
mm	68.58	44.45	25.40	40.64	24.89	31.75	38.10	31.85	*	45.39	32.69	40.64	5.1	8.4	4.8

* Dimension "I" is a function of required travel distance.

Dimensions = (inches) mm



Single Stack

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				
Rotor Inertia	166 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	18 oz (511 g)				
Insulation Resistance	20 M Ω				

** Unipolar drive gives approximately 30% less thrust than bipolar drive.



Size 23 Single Stack External Linear

Double Stack

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
	3.25 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 M Ω		

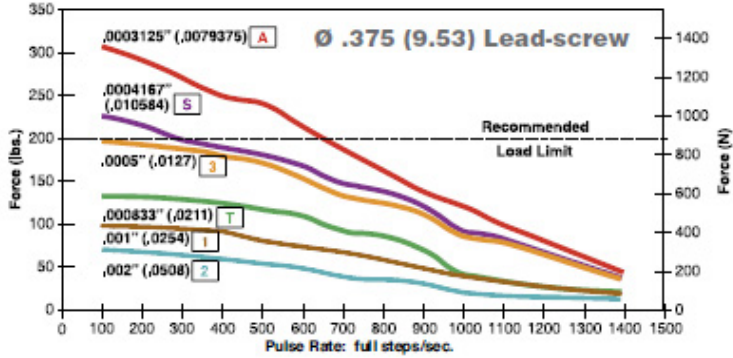


Size 23 Double Stack External Linear

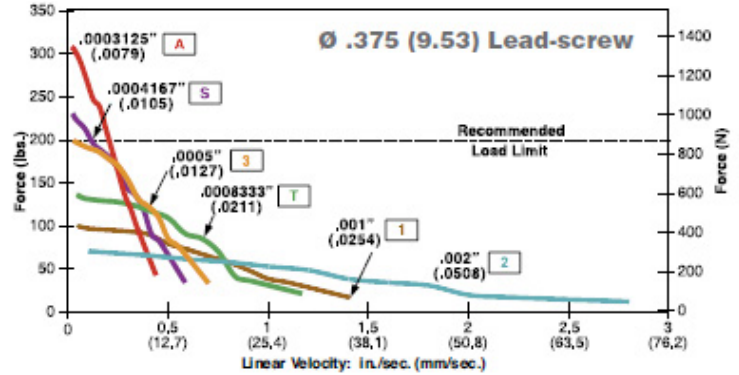
Single Stack

57000 Series Size 23 Linear Actuator

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



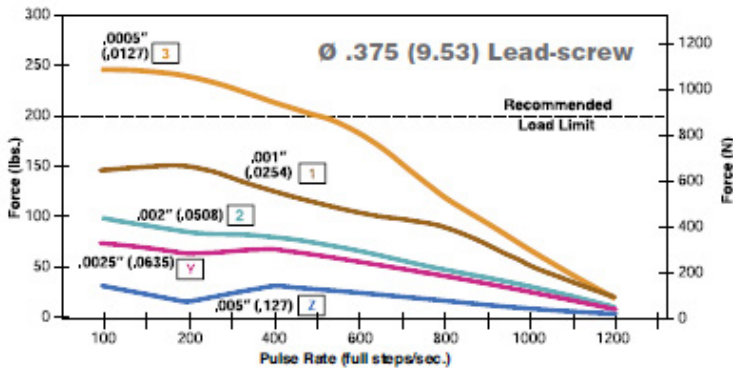
FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle



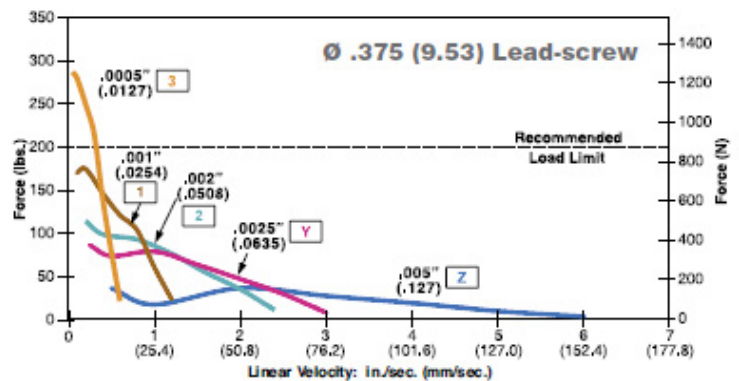
Double Stack

57000 Series Size 23 Linear Actuator

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot. With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Size 23 57000 Series • Stepping Sequence & Wiring

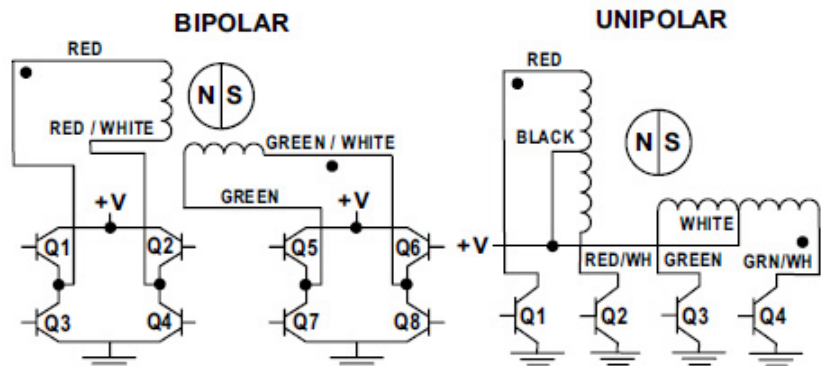
57000 Series Size 23 Linear Actuator

Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar		Q1	Q2	Q3	Q4
Step					
1		ON	OFF	ON	OFF
2		OFF	ON	ON	OFF
3		OFF	ON	OFF	ON
4		ON	OFF	OFF	ON
1		ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Hybrids: Wiring



EGS04 Motorized with 28000 Series

Linear Rail with Size 11 Double Stack Hybrid Stepper

Designed for Lab Automation and Electronic Assembly customers who need high-speed and highly-efficient point-to-point motion. This low-profile stage combines our patented screw support system, which allows for extended travel stroke without the normal reduction in screw RPM, with a ball bearing profile rail. The motorized EGS04 Linear Rail is available with either size 11 or size 17 hybrid stepper motors (see page 3). Standard carriage option is designed for horizontal loads up to 67 N (15 lbs.), and a long carriage option is available for higher loads.

- Low-profile
- High speed capability
- Efficient, stiff load support



EGS04 Motorized
Size 11 28000 Series

Specifications			
Design Payload (mass)	6.8kg [15 lbs]	Pitch Moment*	5.25 N-m [46 lbf-in]
Axial Force	133N [30 lbf]	Yaw Moment*	3 N-m [26 lbf-in]
Roll Moment*	3.1 N-m [27 lbf-in]	Repeatability	+/-25µm [0.001 in]

* Moment data based on 0.25° deflection

Identifying the Motorized EGS Part Numbers when Ordering

EGS	04	K	M	0100	E	S	M	Axx
Prefix EGS = EGS Series	Nominal Rail Size 04 = .25 in (6.35mm) diameter screw	Screw Coating / Grease K = Kerkote (standard) S = Uncoated	Drive Type M = Motorized, stepper	Lead Code 0025 = 0.025" lead 0039 = 1mm lead 0050 = 0.050" lead 0063 = 0.0625" lead 0079 = 2mm lead 0100 = 0.100" lead 0118 = 3mm lead 0200 = 0.200" lead 0250 = 0.250" lead 0394 = 10mm lead 0500 = 0.500" lead 0750 = 0.750" lead 1000 = 1.00" lead	Encoder / Feedback E = Rotary encoder X = No encoder	Carriage(s) S = Standard L = Long M = Multiple (std or long)	Carriage Mounting E = Imperial M = Metric	Stroke / Unique Identifier Axx = Unique identifier (e.g. A01)

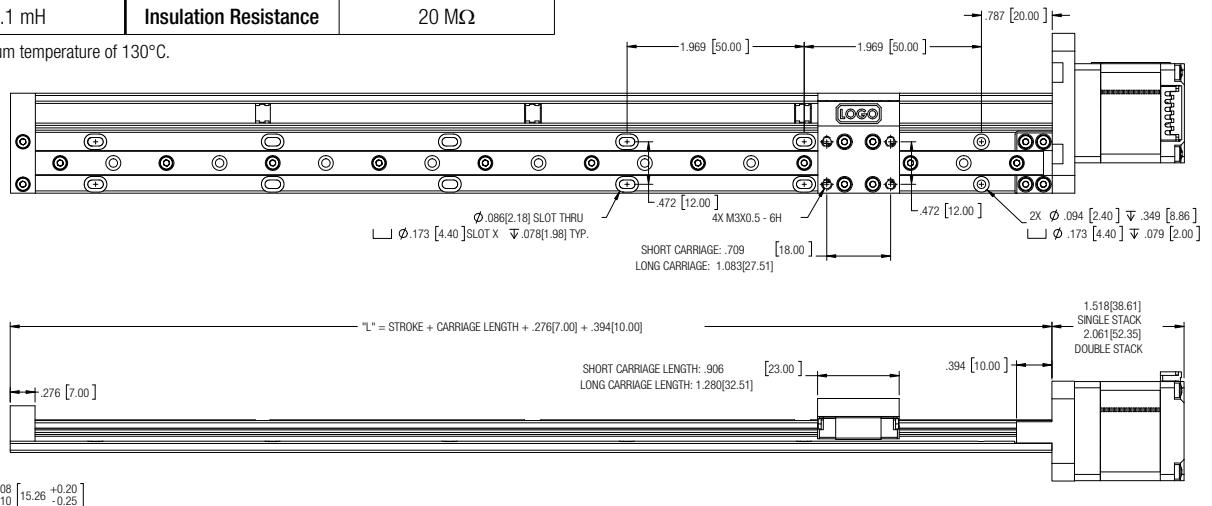
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in M3x0.5 or #4-40.

Size 11 Double Stack: 28 mm (1.1-in) Hybrid External Linear Actuator (1.8° Step Angle)

Wiring	Bipolar	Power Consumption	7.5 W Total
Winding Voltage	2.1 VDC	Rotor Inertia	13.5 gcm ²
Current (RMS)/phase	1.9 A	Insulation Class	Class B (Class F available)
Resistance/phase	1.1 Ω	Weight	5.8 oz (180 g)
Inductance/phase	1.1 mH	Insulation Resistance	20 MΩ

Standard motors are Class B rated for maximum temperature of 130°C.

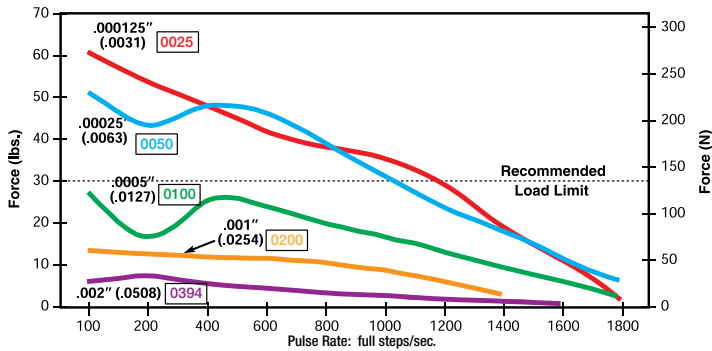
Size 11 Double Stack
28000 Series
External Linear Actuator



Double Stack

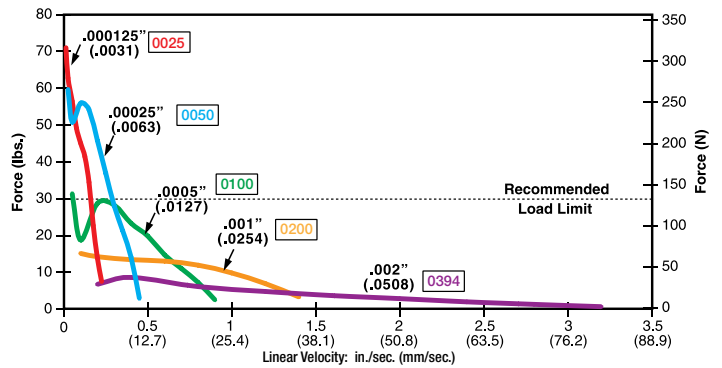
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

– Chopper – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

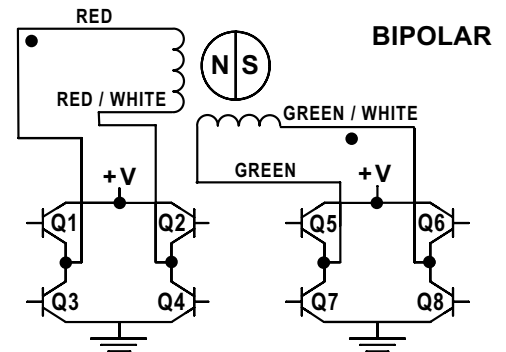
Size 11 28000 Series • Stepping Sequence & Wiring

Hybrids: Stepping Sequence

Step	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
1		ON	OFF	ON	OFF
2		OFF	ON	ON	OFF
3		OFF	ON	OFF	ON
4		ON	OFF	OFF	ON
1		ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Hybrids: Wiring

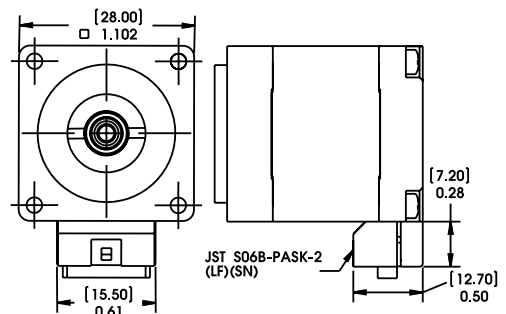


Size 11 28000 Series • Integrated Connector

Offered alone or with a harness assembly, the integrated connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk part # 56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part # SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	–
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	–
6	Phase 1 Start	Phase 1 Start	Red



EGS04 Motorized with 43000 Series

Linear Rail with Size 17 Single or Double Stack Hybrid Stepper

This low-profile stage combines our patented screw support system, which allows for extended travel stroke without the normal reduction in screw RPM, with a ball bearing profile rail. The motorized EGS04 Linear Rail is available with size 17 hybrid stepper motors. Standard carriage option is designed for horizontal loads up to 67 N (15 lbs.), and a long carriage option is available for higher loads.

- Low-profile
- High speed capability
- Efficient, stiff load support



EGS04 Motorized
Size 17 43000 Series

Identifying the Motorized EGS Part Numbers when Ordering

EGS	04	K	M	0100	E	S	M	Axx
Prefix EGS = EGS Series	Nominal Rail Size 04 = .25 in (6.35mm) diameter screw	Screw Coating / Grease K = Kerkote (standard) S = Uncoated	Drive Type M = Motorized, stepper	Lead Code 0025 = 0.025" lead 0039 = 1mm lead 0050 = 0.050" lead 0063 = 0.0625" lead 0079 = 2mm lead 0100 = 0.100" lead 0118 = 3mm lead 0200 = 0.200" lead 0250 = 0.250" lead 0394 = 10mm lead 0500 = 0.500" lead 0750 = 0.750" lead 1000 = 1.00" lead	Encoder / Feedback E = Rotary encoder X = No encoder	Carriage(s) S = Standard L = Long M = Multiple (std or long)	Carriage Mounting E = Imperial M = Metric	Stroke / Unique Identifier Axx = Unique identifier (e.g. A01)

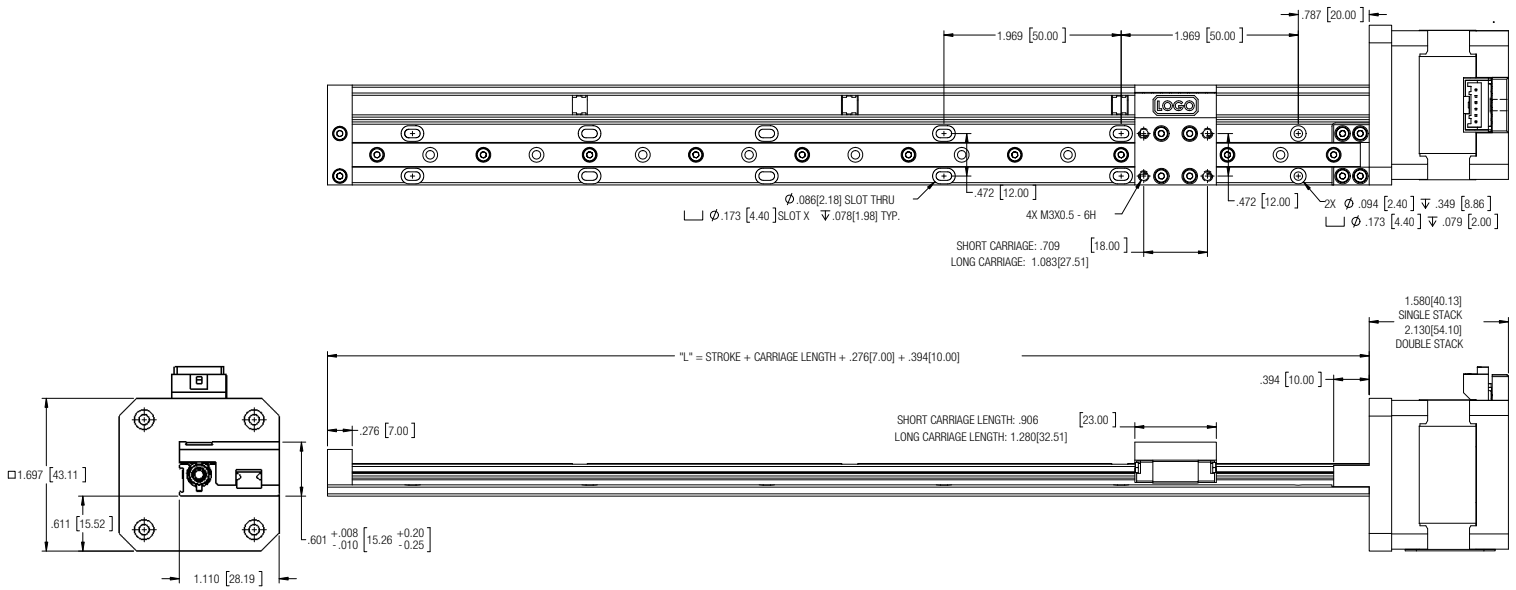
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in M3x0.5 or #4-40.

Size 17: 43 mm (1.7-in) External Linear Actuator (1.8° Step Angle)

Wiring	Single Stack					Double Stack		
	Bipolar		Unipolar**			Bipolar		
Winding Voltage	2.33 VDC [†]	5 VDC	12 VDC	5 VDC	12 VDC	2.33 VDC [†]	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA	2.6 A	1.3 A	550 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH	1.33 mH	8.21 mH	45.1 mH
Power Consumption	7 W					13.2 W		
Rotor Inertia	37 gcm ²					78 gcm ²		
Insulation Class	Class B (Class F available)					Class B (Class F available)		
Weight	8.5 oz (241 g)					12.5 oz (352 g)		
Insulation Resistance	20 MΩ					20 MΩ		

**Unipolar drive gives approximately 30% less thrust than bipolar drive.





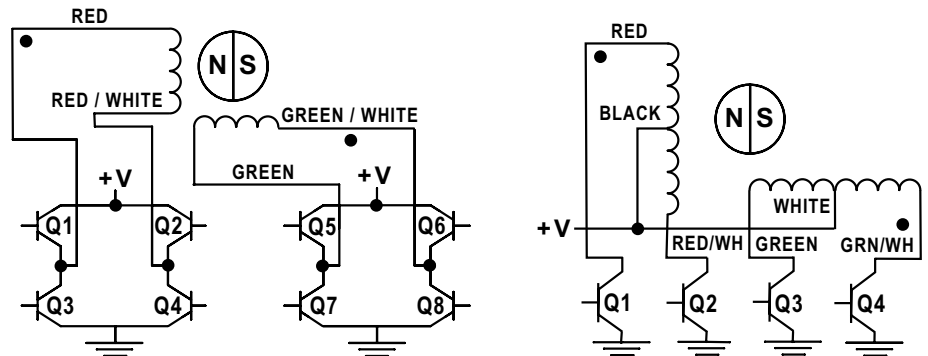
Size 17 43000 Series • Stepping Sequence & Wiring

Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

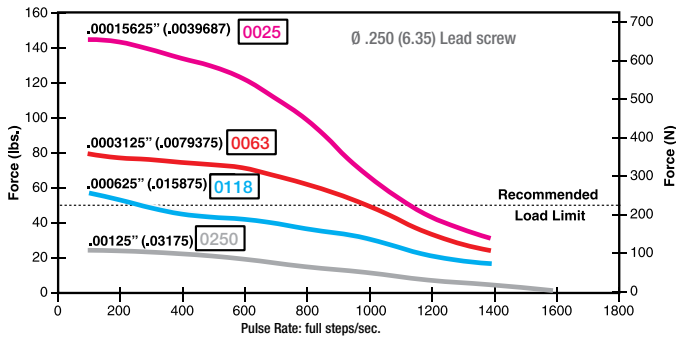
Hybrids: Wiring



Single Stack

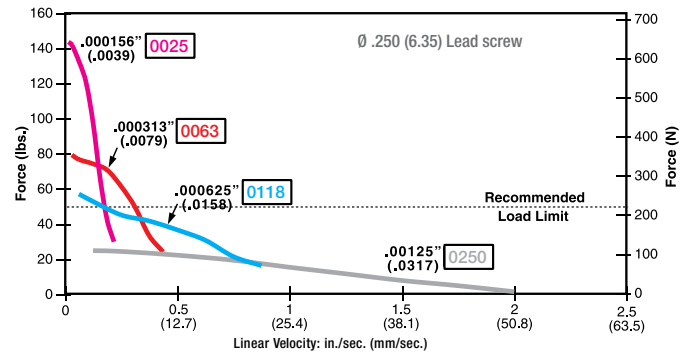
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

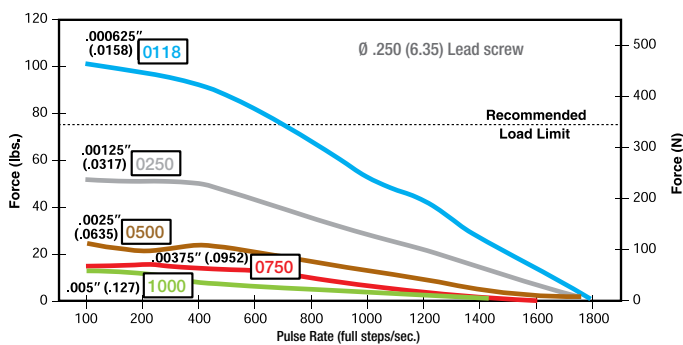
– Chopper – Bipolar – 100% Duty Cycle



Double Stack

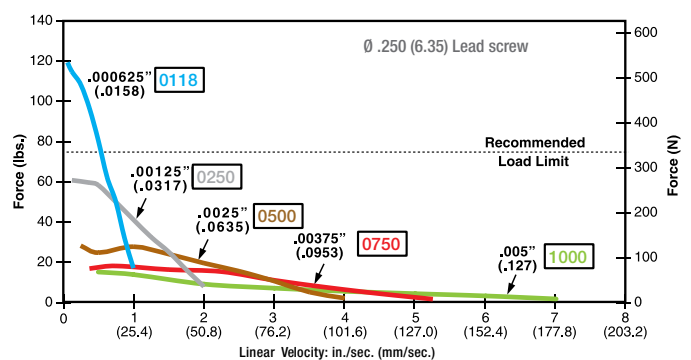
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

– Chopper – Bipolar – 100% Duty Cycle



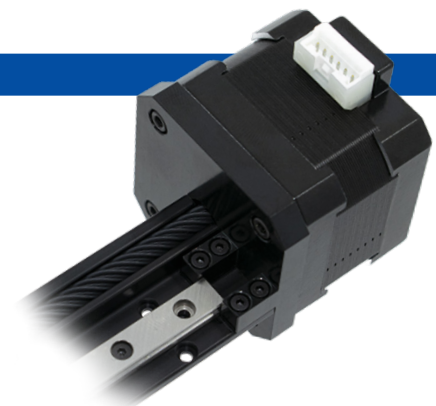
NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

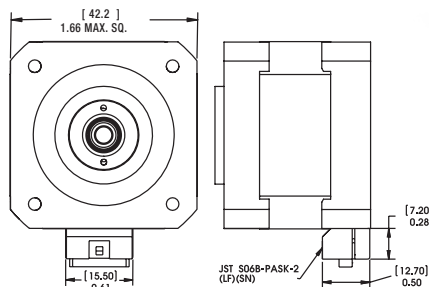
Size 17 47000 Series • Integrated Connector

Offered alone or with a harness assembly, the integrated connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk part # 56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part # SPHD-001T-P0.5



Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	–
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	–
6	Phase 1 Start	Phase 1 Start	Red

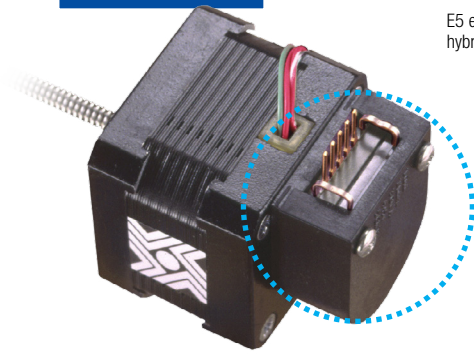


Encoders Designed for All EGS Rails

EGS Series rails are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder designs are available with two channel quadrature TTL squarewave outputs. Version with Index channel are also available. Various resolutions are available, up to 5000 CPR.

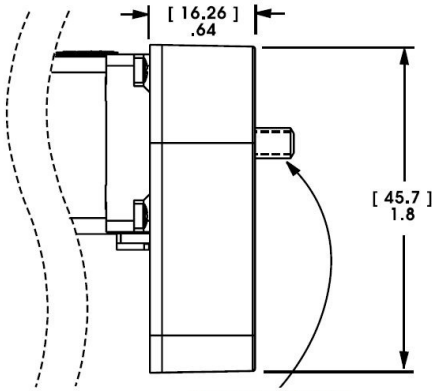
Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder modules incorporate a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.

E5 encoder on Size 17 hybrid motor

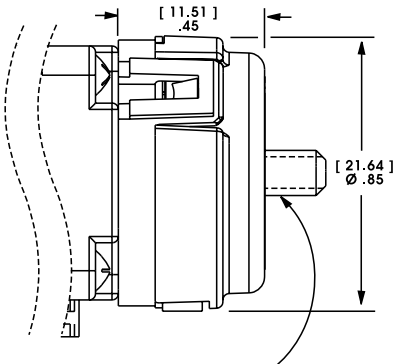


E5 Encoder Dimensions

Dimensions = [mm] inches



E4T Encoder Dimensions



Electrical Specifications

	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Index available on E4T.

Operating Temperature

	Minimum	Maximum
E4T	- 20°C (- 28°F)	100°C (212°F)
E5	- 20°C (- 40°F)	100°C (212°F)

Mechanical Specifications

	Maximum
Acceleration	250,000 rad/sec ²
Vibration (5 Hz to 2 kHz)	20 g

Resolution

	Standard Resolutions (CPR)			Maximum (CPR)
E4T	200	400	1000	1000
E5	200	400	1000	5000

*Other Resolutions Available - Contact Factory

Pinouts

E4T Single-Ended		E4T Differential		E5 Single-Ended		E5 Differential	
Connector Pin#	Description	Connector Pin#	Description	Connector Pin#	Description	Connector Pin #	Description
1	+5VDC power	1	Ground	1	Ground	1	Ground
2	A channel	2	A channel	2	Index	2	Ground
3	Ground	3	A- channel	3	A channel	3	Index-
4	B channel	4	+5VDC power	4	+5VDC power	4	Index+
		5	B channel	5	B channel	5	A- channel
		6	B- channel			6	A+ channel
						7	+5 VDC Power
						8	+5 VDC Power
						9	B- channel
						10	B+ channel

EGS04 Motorized with BLDC

Linear Rail with BLDC Motor

This low-profile stage features screw support with a ball bearing profile rail. The motorized EGS04 Linear Rail is available with a 42mm brushless DC (BLDC) servo motor for high speed applications. Standard configuration is a single stack EC042B with 1000cpr E30D encoder included. Recommended for horizontal loads up to 15 lbs (67N).

- Low-profile
- High speed capability
- Efficient, stiff load support



EGS04 Motorized
BLDC Motor

Refer to [EC042B data sheet](#) for complete motor specifications.

Identifying the Motorized EGS Part Numbers when Ordering

EGS	04	K	P	0100	E	S	M	Axx
Prefix EGS = EGS Series	Nominal Rail Size 04 = .25 in (6.35mm) diameter screw	Screw Coating / Grease K = Kerkote (standard) S = Uncoated	Drive Type P = Motorized BLDC Q = Integrated drive, BLDC	Lead Code* 0025, 0039, 0050, 0063, 0079, 0100, 0118, 0200, 0250, 0394, 0500, 0750, 1000	Encoder / Feedback E = Rotary encoder X = No encoder	Carriage(s) S = Standard L = Long M = Multiple (std or long)	Carriage Mounting E = Imperial M = Metric	Stroke / Unique Identifier Axx = Unique identifier (e.g. A01)

* Refer to page 1 or 3 for coordinating lead resolutions.

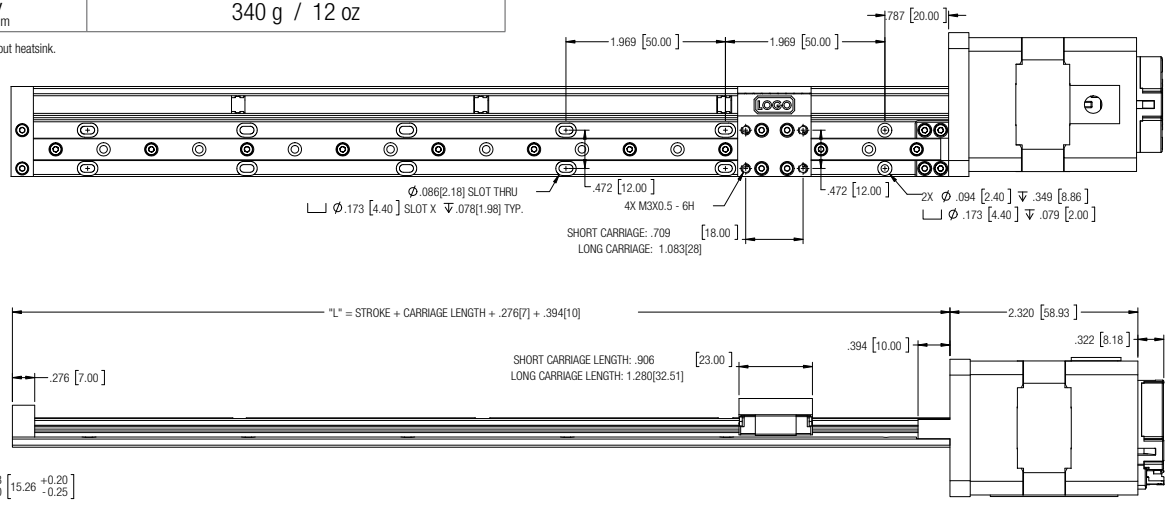
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in M3x0.5 or #4-40.

Motor Data		EC042B-1
Max DC Terminal Voltage	V_T	96 V
Max Speed (Mechanical)	ω_{MAX}	9000 rpm
Continuous Stall Torque ¹	T_{CS}	0.064 Nm / 9.0 oz-in
Peak Torque (Maximum) ¹	T_{pk}	0.38 Nm / 54 oz-in
Coulomb Friction Torque	T_f	0.0014 Nm / 0.20 oz-in
Viscous Damping Factor	D	3.4E-06 V/(rad/s) / 0.050 oz-in/krpm
Thermal Time Constant	τ_{th}	5.1 min
Thermal Resistance	R_{th}	9.1 °C/W
Max. Winding Temperature	Θ_{MAX}	105 °C
Rotor Inertia	J_r	1.4E-05 kg-m ² / 0.0021 oz-in-s ²
Motor Weight	W_m	340 g / 12 oz

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC042B motor





Slide Guided Rail Systems

Haydon Kerk Slide Guided Rails are available in many styles and sizes to meet your application needs. Many rails are offered with integrated drive, motorized, non-motorized or guide only versions without lead screw. Rails are available with wear-compensating, anti-backlash driven carriages to insure repeatability and accurate positioning. All moving surfaces include engineered polymers that provide a precise, strong and stable platform for a variety of linear motion applications.

Performance Attributes

Series	Description	Sizes	Max Stroke m	Max Load N	Motorized	Rail Only	Guide Only	Stiffness	Major Attributes
RGS	Aluminum rail w/ wear compensation	4, 6, 8, 10	2.5	67-445	•	•	•	*	High speed
RGW	Aluminum rail w/ wear compensation	6, 10	2.5	156-445	•	•	•	**	Wide base
WGS	Aluminum rail w/ wear compensation	6	2.5	156	•	•		****	Low profile
LRS	Aluminum rail w/ wear compensation	4		222	•	•		****	Higher thrust
SRA	Steel tube, no wear compensation	3, 4, 6, 8	1.6	45-440		•			Compact
SRZ	Steel tube, no wear compensation	3, 4, 6, 8	1.6	45-440		•			Compact

RGS04 Motorized with 28000 Series

Linear Rail with Size 11 Double Stack Hybrid Stepper

The RGS04 28000 Series is our smallest screw driven slide that offers exceptional linear speed, accurate positioning and long life in a compact, value-priced assembly. The length and speed of the RGS is not limited by critical screw speed, allowing high RPM and linear speeds, even over long spans. Recommended for horizontal loads up to 15 lbs (67N).



RGS04 Motorized
Size 11 28000 Series Double Stack

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the Motorized RGS Part Numbers when Ordering

RG	S	04	K	M	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard	Frame Size Load 04 = 15 lbs (67 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting M = Motorized	Nominal Thread Lead Code 0025 = .025-in (.635) 0039 = .039-in (1.00) 0050 = .050-in (1.27) 0063 = .0625-in (1.59) 0079 = .079-in (2.00) 0100 = .100-in (2.54) 0118 = .118-in (3.00) 0200 = .200-in (5.08) 0250 = .250-in (6.35) 0394 = .394-in (10.00) 0500 = .500-in (12.70) 0750 = .750-in (19.05)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in metric sizes M3, M4.

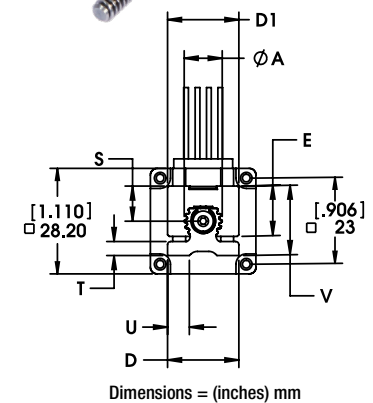
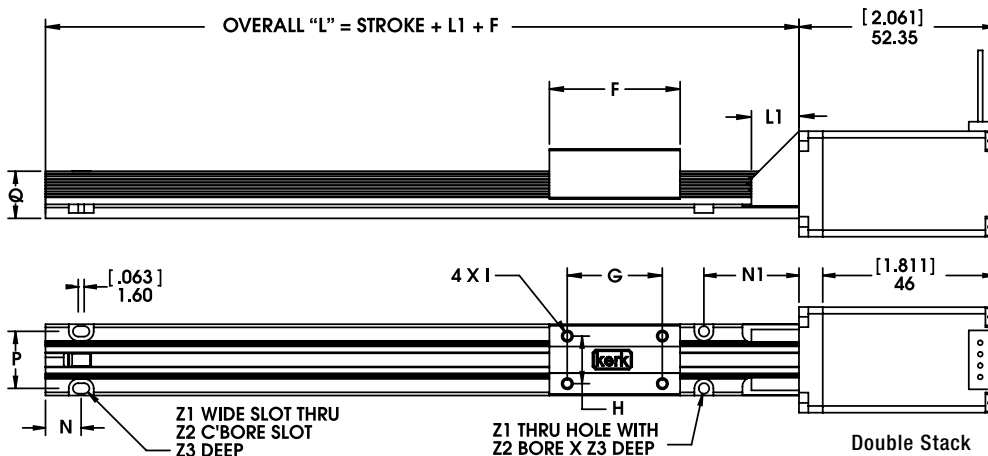
Size 11 Double Stack: 28 mm (1.1-in) Hybrid External Linear Actuator (1.8° Step Angle)

Wiring	Bipolar	Power Consumption	7.5 W Total
Winding Voltage	2.1 VDC	Rotor Inertia	13.5 gcm ²
Current (RMS)/phase	1.9 A	Insulation Class	Class B (Class F available)
Resistance/phase	1.1 Ω	Weight	5.8 oz (180 g)
Inductance/phase	1.1 mH	Insulation Resistance	20 MΩ

Standard motors are Class B rated for maximum temperature of 130°C.



Size 11 Double Stack
28000 Series
External Linear Actuator



Dimensions = (inches) mm

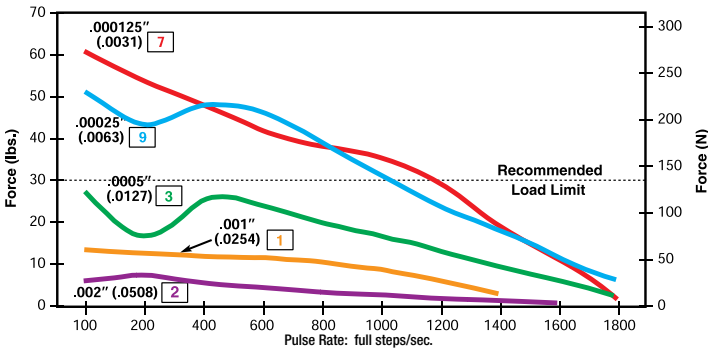
	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.40)	(0.75)	(0.75)	(0.53)	(1.40)	(1.00)	(0.50)	4-40	(0.50)	(0.38)	(1.00)	(0.60)	(0.5)	(0.37)	(0.15)	(0.23)	(0.7)	(0.11)	(0.2)	(0.09)
mm	10.2	19	19	13.5	35.6	25.4	12.7	UNC	12.7	9.52	25.4	15.2	12.7	9.4	3.8	5.8	18.0	2.8	5.1	2.3

*Metric threads also available for carriage.

Double Stack

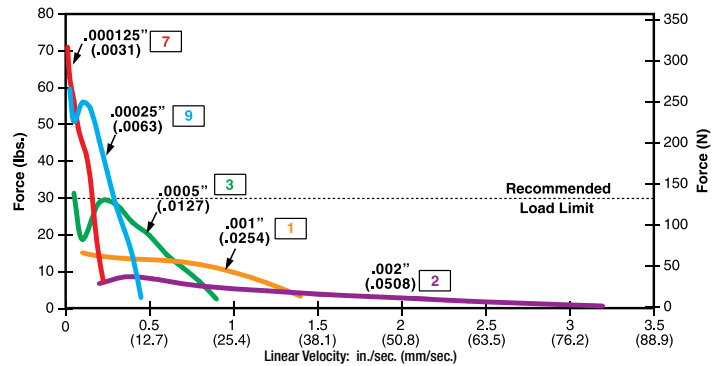
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

– Chopper – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

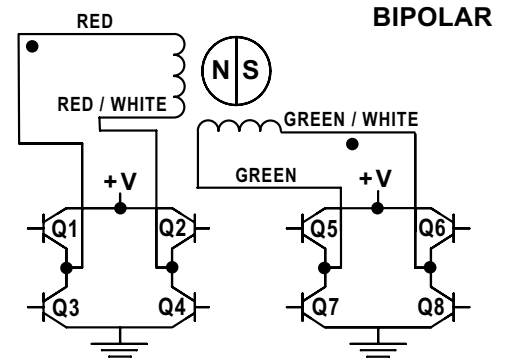
Size 11 28000 Series • Stepping Sequence & Wiring

Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step					
1		ON	OFF	ON	OFF
2		OFF	ON	ON	OFF
3		OFF	ON	OFF	ON
4		ON	OFF	OFF	ON
1		ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

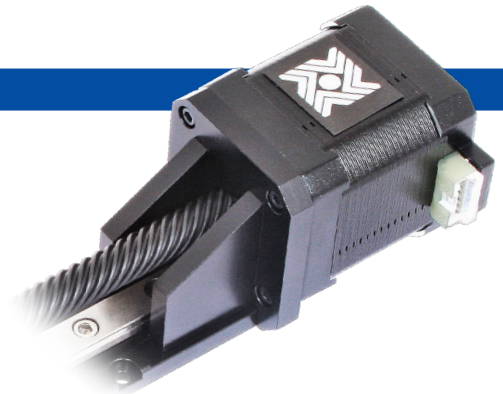
Hybrids: Wiring



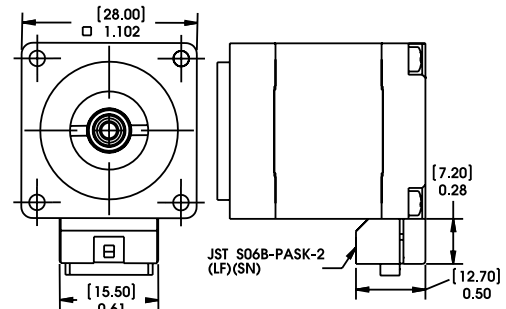
Size 11 28000 Series • Integrated Connector

Offered alone or with a harness assembly, the integrated connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk part # 56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part # SPHD-001T-P0.5



Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	–
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	–
6	Phase 1 Start	Phase 1 Start	Red



RGS04 Motorized with 43000 Series

Linear Rail with Size 17 Single or Double Stack Hybrid Stepper with or without an integrated programmable IDEA™ Drive

The RGS04 is a screw driven rail that offers exceptional linear speed, accurate positioning and long life in a compact assembly. The length and speed of the RGS is not limited by critical screw speed, allowing high RPM and linear speeds even over long spans. Recommended for horizontal loads up to 15 lbs (67N).



RGS04 Motorized
Size 17 43000 Series Double Stack

Identifying the Motorized RGS Part Numbers when Ordering

RG	S	04	K	M	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard	Frame Size Load 04 = 15 lbs (67 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting M = Motorized G = IDEA Integrated programmable drive, USB communications J = IDEA integrated programmable drive, RS485 communications	Nominal Thread Lead Code 0025 = .025-in (.635) 0039 = .039-in (1.00) 0050 = .050-in (1.27) 0063 = .0625-in (1.59) 0079 = .079-in (2.00) 0100 = .100-in (2.54) 0118 = .118-in (3.00) 0200 = .200-in (5.08) 0250 = .250-in (6.35) 0394 = .394-in (10.00) 0500 = .500-in (12.70) 0750 = .750-in (19.05)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in metric sizes M3, M4, M5, M6.

Size 17: 43 mm (1.7-in) External Linear Actuator (1.8° Step Angle)

Wiring	Single Stack					Double Stack		
	Bipolar		Unipolar**			Bipolar		
Programmable Drive	IDEA™ Drive Available					IDEA™ Drive Available		
Winding Voltage	2.33 VDC [†]	5 VDC	12 VDC	5 VDC	12 VDC	2.33 VDC [†]	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA	2.6 A	1.3 A	550 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH	1.33 mH	8.21 mH	45.1 mH
Power Consumption	7 W					13.2 W		
Rotor Inertia	37 gcm ²					78 gcm ²		
Insulation Class	Class B (Class F available)					Class B (Class F available)		
Weight	8.5 oz (241 g)					12.5 oz (352 g)		
Insulation Resistance	20 MΩ					20 MΩ		

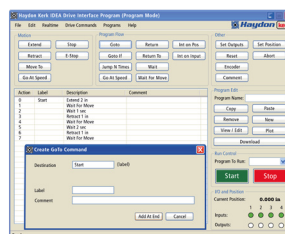
[†]43000 Series with IDEA™ Drive. Contact us if higher voltage motor is desired.

**Unipolar drive gives approximately 30% less thrust than bipolar drive.

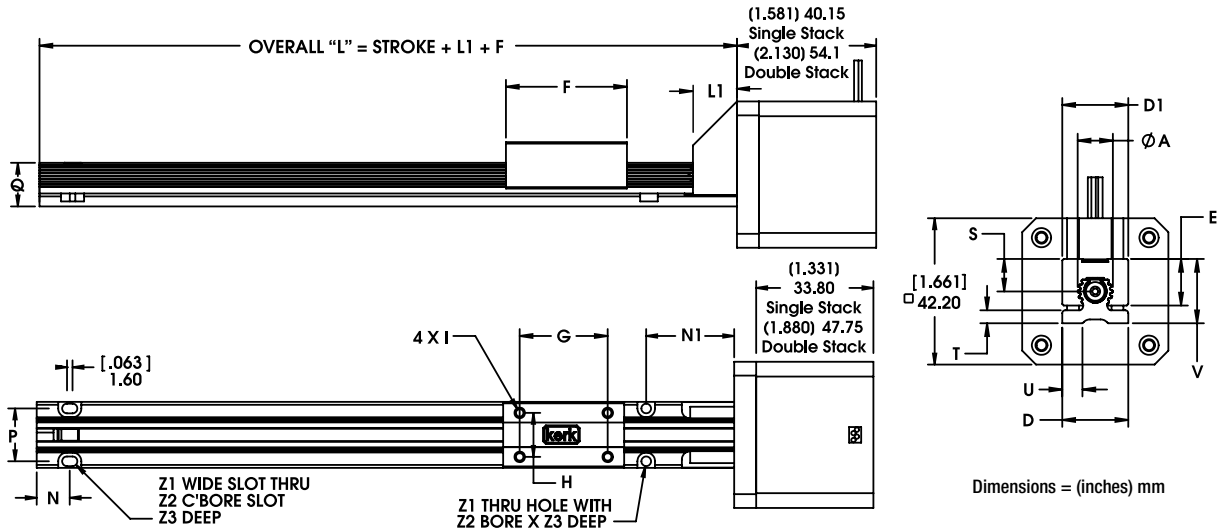


Simple to use IDEA™ Drive software with on-screen buttons and easy-to-understand programming guides

Software program generates motion profiles directly into the system and also contains a “debug” utility allowing line-by-line execution of a motion program for easy troubleshooting.



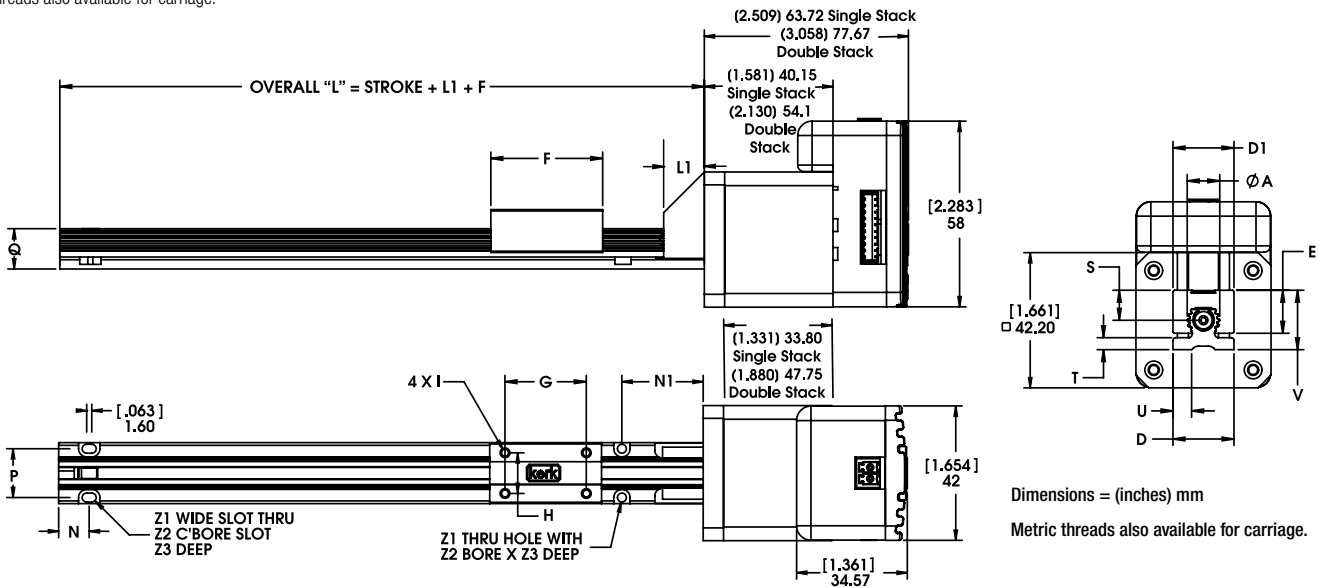
NOTE: For more information see the Haydon Kerk [IDEA Drive webpages](#).



RGS04 with 43000 Series Size 17 Single or Double Stack Linear Actuator (drawing above)
or Double Stack Linear Actuator with integrated programmable IDEA™ Drive (drawing below)

	A	D	D1	E	F	G	H	I'	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.40)	(0.75)	(0.75)	(0.53)	(1.40)	(1.00)	(0.50)	4-40	(0.50)	(0.38)	(1.00)	(0.60)	(0.5)	(0.37)	(0.15)	(0.23)	(0.73)	(0.11)	(0.2)	(0.09)
mm	10.2	19	19	13.5	35.6	25.4	12.7	UNC	12.7	9.52	25.4	15.2	12.7	9.4	3.8	5.8	18.0	2.8	5.1	2.3

*Metric threads also available for carriage.



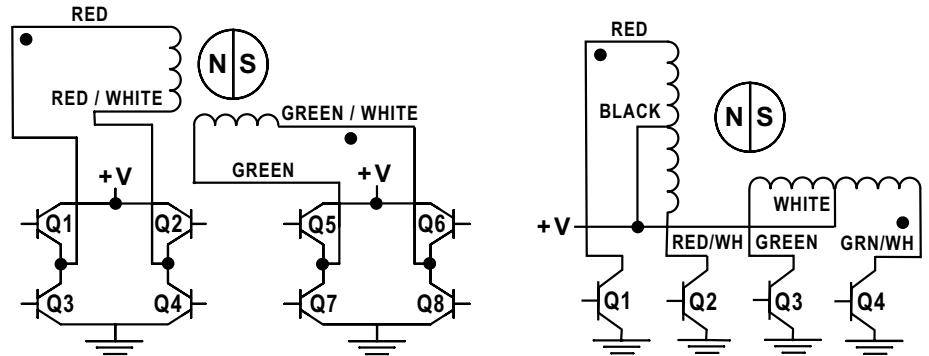
Size 17 43000 Series • Stepping Sequence & Wiring

Hybrids: Stepping Sequence

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

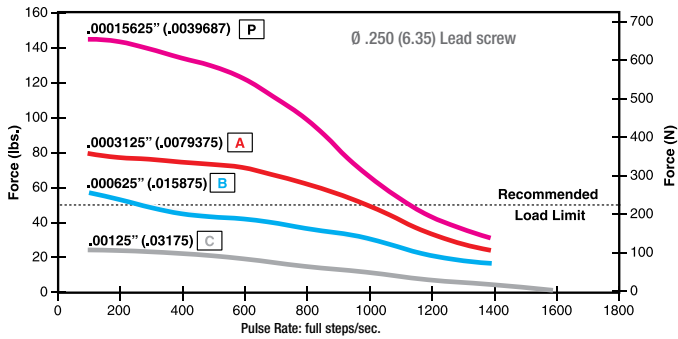
Hybrids: Wiring



Single Stack

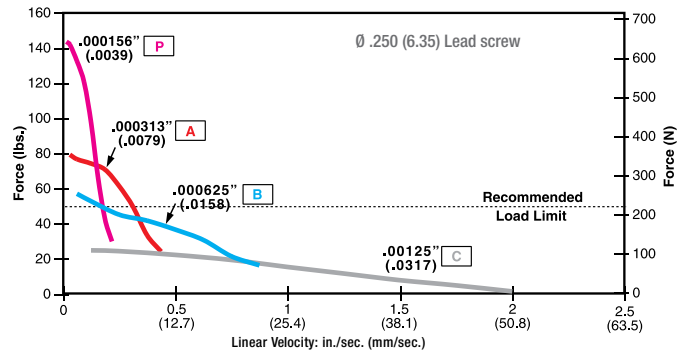
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

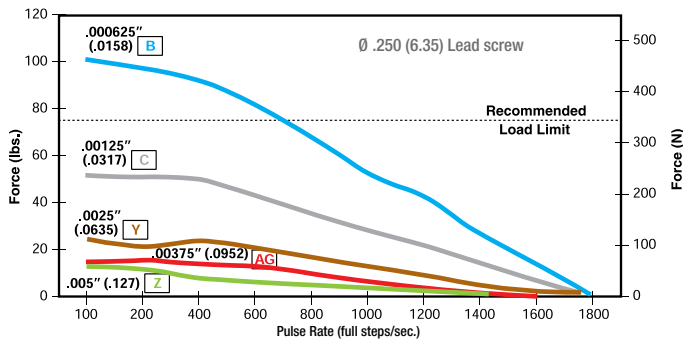
– Chopper – Bipolar – 100% Duty Cycle



Double Stack

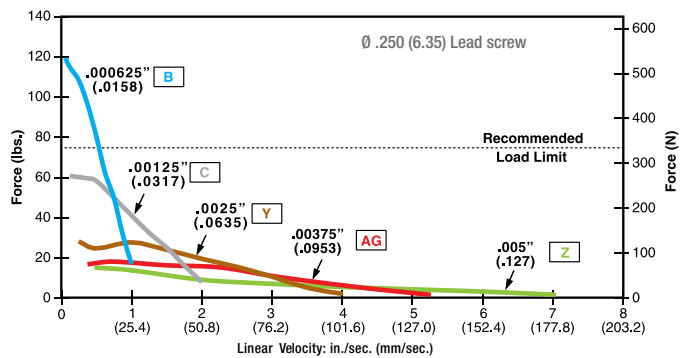
FORCE vs. PULSE RATE

– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

– Chopper – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

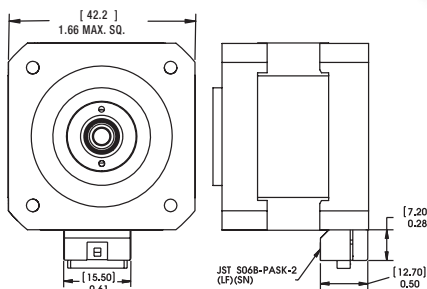
Size 17 47000 Series • Integrated Connector

Offered alone or with a harness assembly, the integrated connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk part # 56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part # SPHD-001T-P0.5



Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	–
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	–
6	Phase 1 Start	Phase 1 Start	Red



RGS04 Non-Motorized Linear Rails

Screw driven linear rail or linear rail without screw

The non-motorized RGS Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications.



RGS04 Non-Motorized
Screw Driven Linear Rail

Identifying the Non-Motorized RGS Part Numbers when Ordering

RG	S	04	K	A	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard	Frame Size Load 04 = 15 lbs (67 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None	Nominal Thread Lead Code 0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Carriage holes available in metric sizes M3, M4.

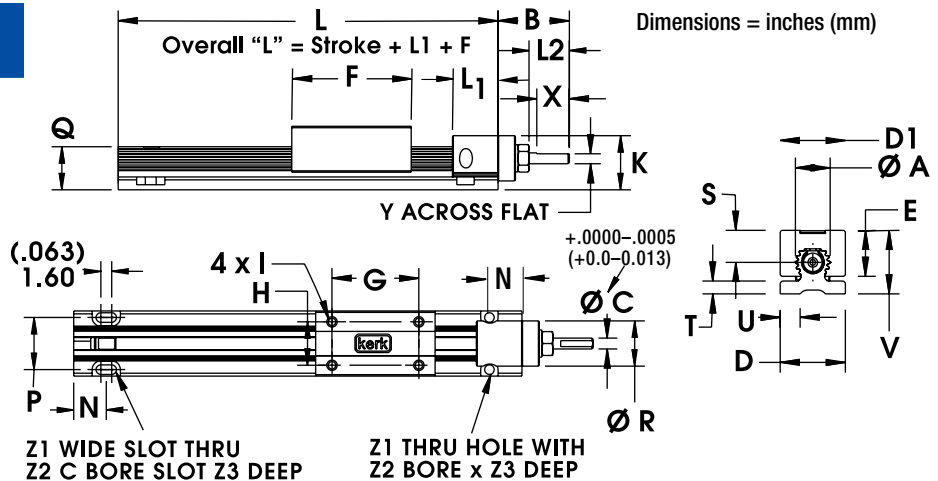
Specifications

	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load	Screw Inertia
RGS04 Non-Motorized with Guide Screw	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	0.4 (10.2)	1/4 (6.4)	3.0 (0.2)	100,000,000 (254,000,000)	1.0 (.016)	15 (67)	.3 x 10 ⁻⁵ (6.5 x 10 ⁻⁶)
	.200 (5.08)	0200			4.0 (.03)		1.5 (.023)		
	.500 (12.70)	0500			5.0 (.04)		2.5 (.039)		
	1.000 (25.40)	1000			6.0 (.04)		4.5 (.070)		

NOTE: RGS assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw
Dimensional Drawings



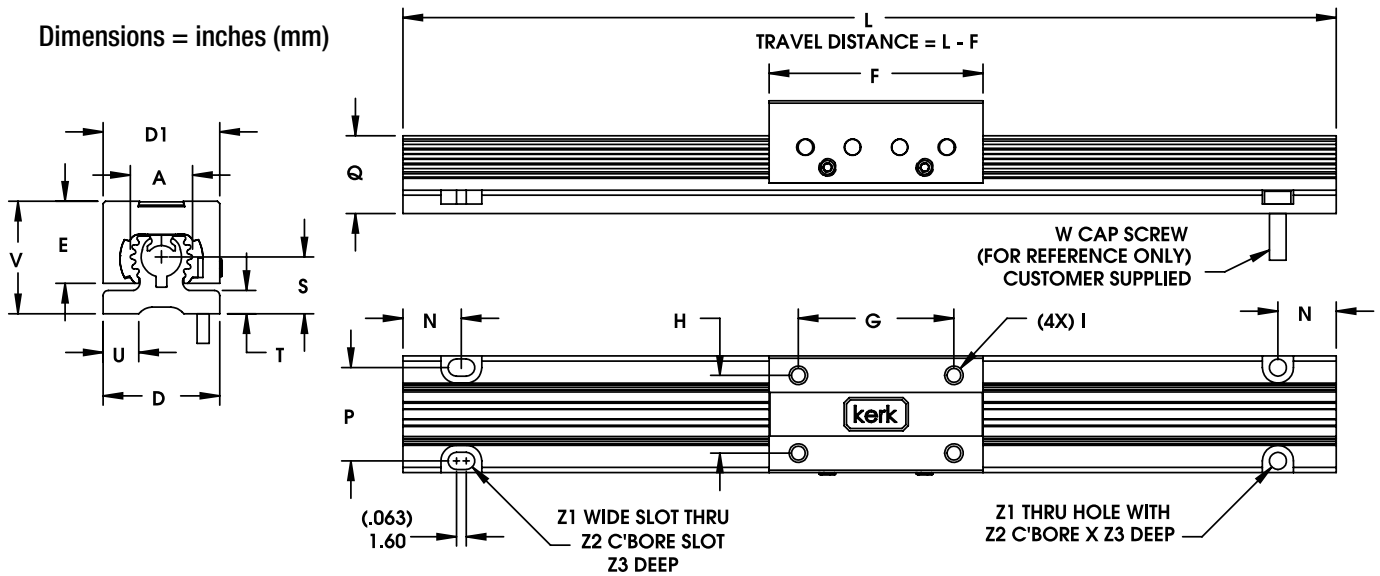
	A	B	C	D	D1	E	F	G	H	I*	K	L1	L2	N	P	Q	R	S	T	U	V	X	Z1	Z2	Z3
inch	0.40	.83	.1250	0.75	0.75	0.53	1.38	1.00	0.50	4-40	0.6	.53	.47	.375	.60	.50	.52	0.37	0.15	0.23	0.7	.38	0.115	0.20	0.09
mm	10.2	21.1	3.175	19.1	19.1	13.5	35.1	25.4	12.7	UNC	15	13.5	11.9	9.53	15.24	12.7	13.2	9.4	3.8	5.8	18.0	9.7	2.92	5.1	2.3

*Metric carriage hole sizes available M3, M4.

Non-Motorized without Lead Screw
Dimensional Drawings



RGS04 Non-Motorized
Linear Rail without Screw



	A	D	D1	E	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	0.40	0.75	0.75	0.53	1.4	1.00	0.50	4-40	.375	.60	.50	0.37	0.15	0.23	0.7	0.11	0.20	0.09
mm	10.2	19.1	19.1	13.5	36	25.4	12.7	UNC	9.53	15.24	12.7	9.4	3.8	5.8	18.0	2.8	5.1	2.3

*Metric carriage hole sizes available M3, M4.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers, Kerkite Polymers are formulated to provide optimum performance in its target conditions and applications.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris. Kerkote differs from conventional plating and coating because it is soft, more evenly distributed than other lubricants, and decreases erratic drag torques and unpredictable wear.

- Reduces friction
- Cost effective
- Long term and maintenance free

Kerkote provides the maximum level of self-lubrication, requiring no additional external lubrication or maintenance.

RGS06 and RGW06 Wide Linear Rails with 43000 Series Hybrid Motor

*Also available with 57000 Series Hybrid Motor (see pages 247-251)

Combines many Haydon Kerk Motion Solutions patented motion technologies into a single integrated, linear motion control system. The Motorized RGS linear rails feature standard wear-compensating, anti-backlash driven carriages to insure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. When integrated with an IDEA Drive, the system combines Haydon® hybrid linear actuator technology with a fully programmable, integrated stepper motor drive. RGS Series Linear Rail with Hybrid 43000 Series Size 17 Linear Actuator Stepper Motors.

Technical specifications for 43000 Series Size 17 Hybrid Linear Actuator Stepper Motors are on page 247.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).



RGW06 43000 Series Size 17
Double Stack with programmable
IDEA™ Drive

Identifying the RGS06 Part Number Codes when Ordering

RG	S	06	K	M	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	S = Standard W = Wide sensor mount capability	06 = 35 lbs (156 N) (Maximum static load)	K = TFE Kerkote®	M = Motorized G = Motorized + IDEA™ integrated programmable drive – USB communications J = Motorized + IDEA™ integrated programmable drive – RS485 communications	0050 = .050-in (1.27) 0079 = .079-in (2.00) 0100 = .100-in (2.54) 0157 = .157-in (4.00) 0197 = .197-in (5.00) 0200 = .200-in (5.08) 0250 = .250-in (6.35) 0375 = .375-in (9.53) 0400 = .400-in (10.16) 0472 = .472-in (12.00) 0500 = .500-in (12.70) 0750 = .750-in (19.05) 0984 = .984-in (25.00) 1000 = 1.000-in (25.4) 1200 = 1.200-in (30.48)	Suffix used to identify specific motors (43000 Single/ Double Stack – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

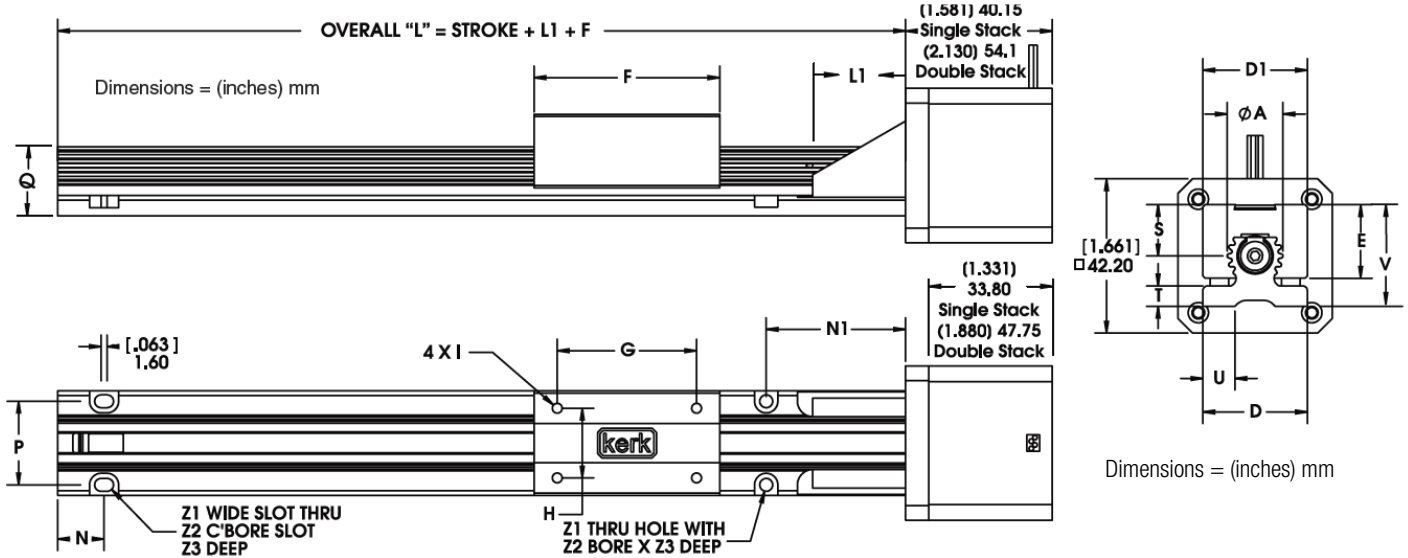
Carriage holes available in Metric sizes M2, M4, M5, M6

■ RGS06 Linear Rail with 43000 Series Size 17 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 35 lbs (156 N)

	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(1.13)	(1.13)	(0.79)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.5)	(0.9)	(0.74)	(0.55)	(0.22)	(0.35)	(1.1)	(0.14)	(0.25)	(0.13)
mm	15.2	28.7	28.7	20.1	50.8	38.1	19.0	UNC	25.4	12.7	38.1	22.9	18.8	13.9	5.6	8.9	27.9	3.6	6.3	3.3

* Metric threads also available for carriage.

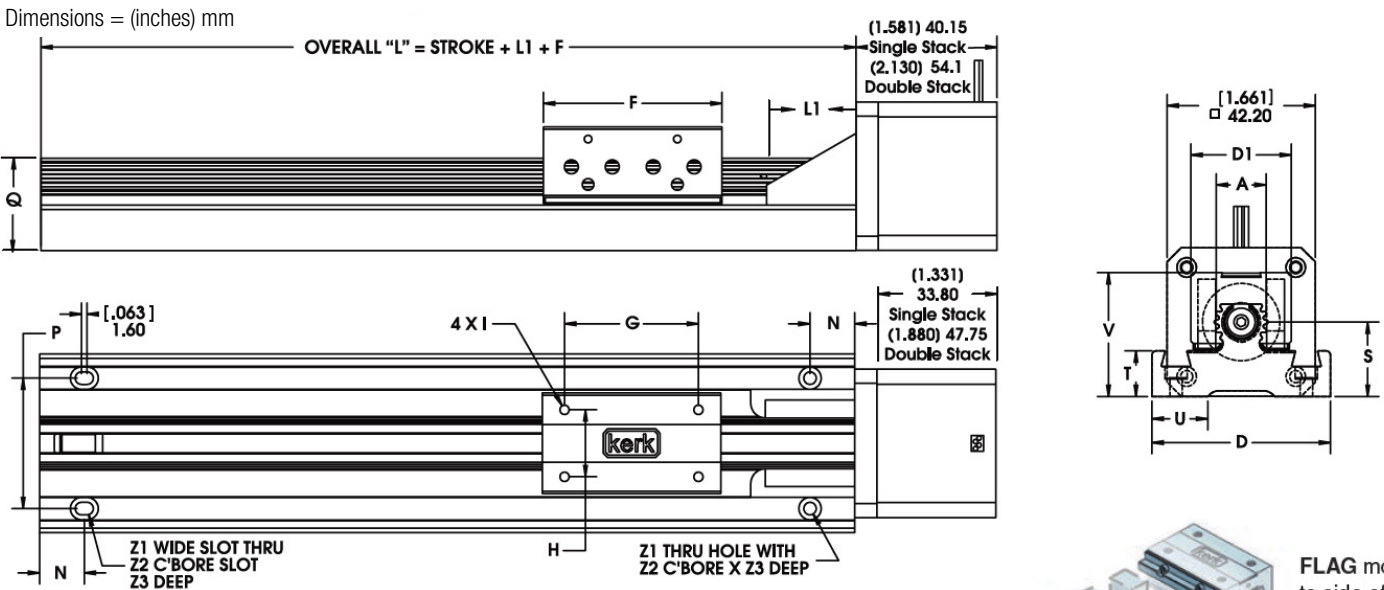


■ RGW06 Wide Linear Rail with 43000 Series Size 17 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 22 lbs (100 N)

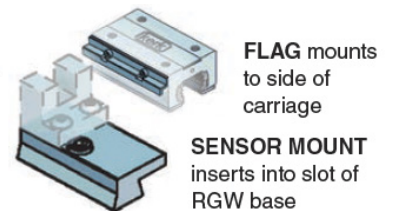
	A	D	D1	F	G	H	I*	L1	N	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(2.0)	(1.13)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.46)	(1.04)	(0.83)	(0.51)	(0.63)	(1.39)	(0.14)	(0.25)	(0.14)
mm	15.2	50.8	28.7	50.8	38.1	19.0	UNC	25.4	12.7	22.9	26.4	21.1	13.0	16.0	35.3	3.6	6.3	3.6

* Metric threads also available for carriage.



RGW06 Sensor Mount Kit Part No. RGW06SK

Sensor mount kits, based on a U-channel optical sensor, are available for the RGW Series. Each kit includes one flag, three sensor mounts, and all mounting hardware. Sensors are not included in the kit and must be ordered separately from the sensor manufacturer.



Single Stack

43000 Series Size 17

Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)					
Wiring	Bipolar			Unipolar**	
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH
Power Consumption	7 W				
Rotor Inertia	37 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	8.5 oz (241 g)				
Insulation Resistance	20 MΩ				

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

43000 Series Size 17
Double Stack External Linear



43000 Series Size 17
Single Stack External Linear

Double Stack

43000 Series Size 17

Size 17 Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)			
Wiring	Bipolar		
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.6 A	1.3 A	550 mA
Resistance/phase	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.33 mH	8.21 mH	45.1 mH
Power Consumption	13.2 W		
Rotor Inertia	78 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	12.5 oz (352 g)		
Insulation Resistance	20 MΩ		

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired. Standard motors are Class B rated for maximum temperature of 130°C.

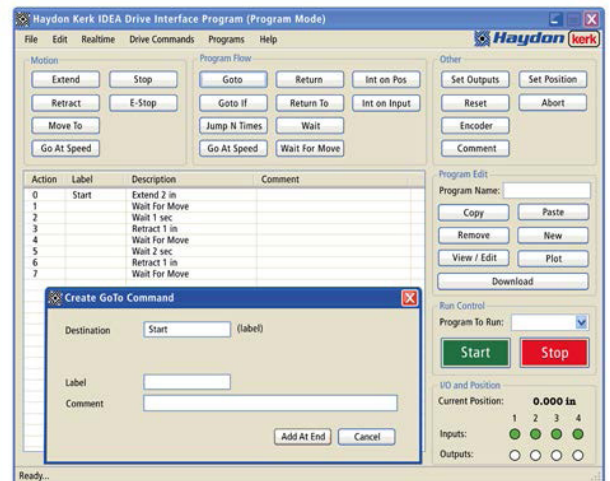
IDEA™ Drive software is simple to use with on-screen buttons and easy-to-understand programming guides.

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability – Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

For more information see the [IDEA™ Drive Data Sheet](#)



Size 17 External Linear with programmable IDEA Drive

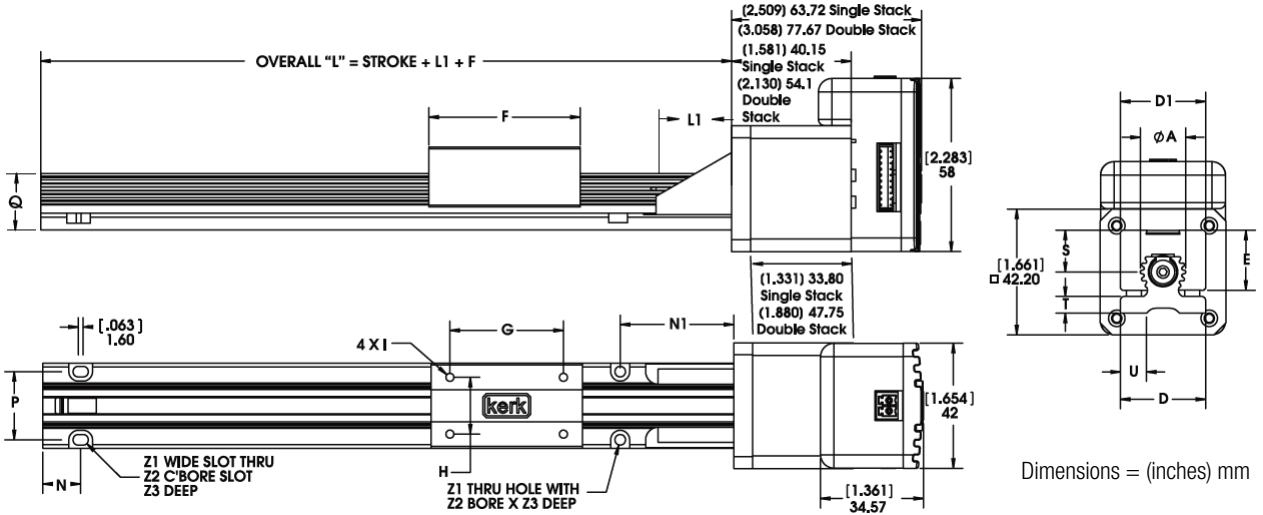


■ RGS06 with 43000 Series Size 17 Single and Double Stack linear motors with IDEA Drive

Recommended for horizontal loads up to 35 lbs (156 N)

	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(1.13)	(1.13)	(0.79)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.5)	(0.9)	(0.74)	(0.55)	(0.22)	(0.35)	(1.1)	(0.14)	(0.25)	(0.13)
mm	15.2	28.7	28.7	20.1	50.8	38.1	19.0	UNC	25.4	12.7	38.1	22.9	18.8	13.9	5.6	8.9	27.9	3.6	6.3	3.3

* Metric threads also available for carriage.

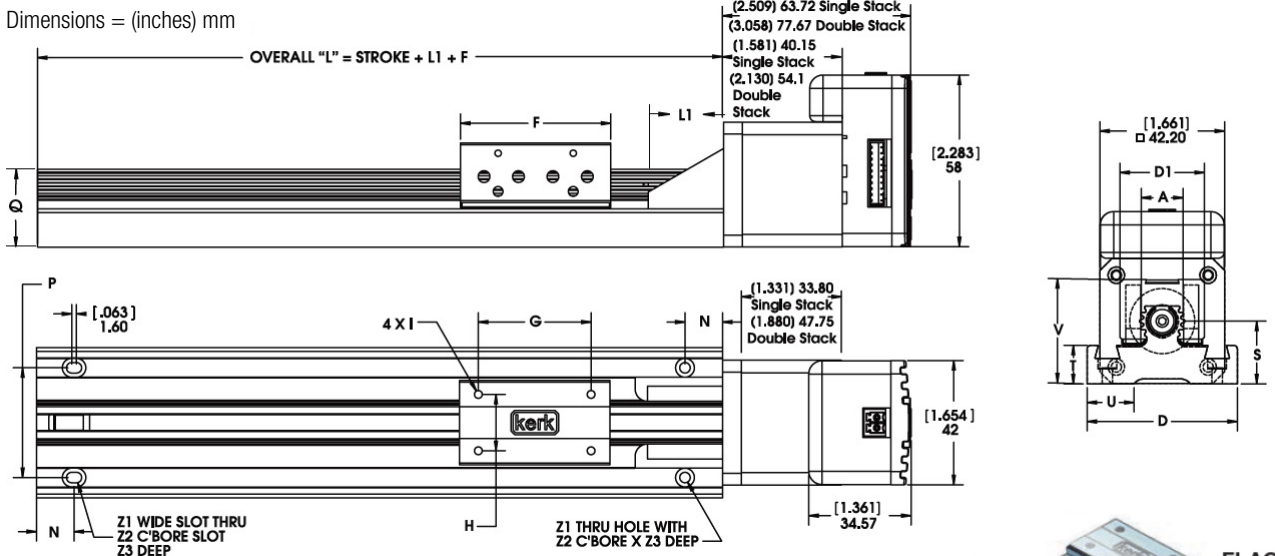


■ RGW06 Wide Rail with 43000 Series Size 17 Single Stack and Double Stack linear motors with IDEA Drive

Recommended for horizontal loads up to 35 lbs (156 N)

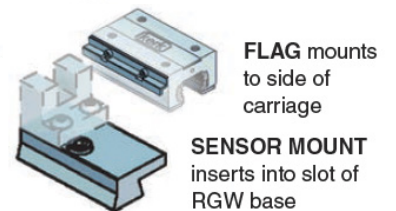
	A	D	D1	F	G	H	I*	L1	N	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(2.0)	(1.13)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.46)	(1.04)	(0.83)	(0.51)	(0.63)	(1.39)	(0.14)	(0.25)	(0.14)
mm	15.2	50.8	28.7	50.8	38.1	19.0	UNC	25.4	12.7	22.9	26.4	21.1	13.0	16.0	35.3	3.6	6.3	3.6

* Metric threads also available for carriage.



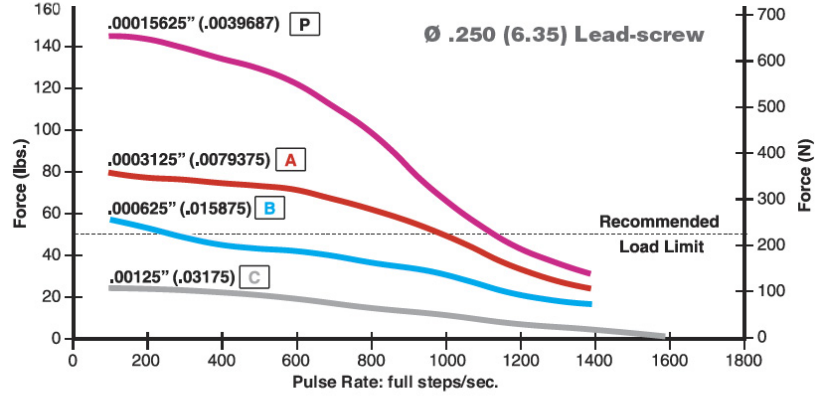
RGW06 Sensor Mount Kit Part No. RGW06SK

Sensor mount kits, based on a U-channel optical sensor, are available for the RGW Series. Each kit includes one flag, three sensor mounts, and all mounting hardware. Sensors are not included in the kit and must be ordered separately from the sensor manufacturer.

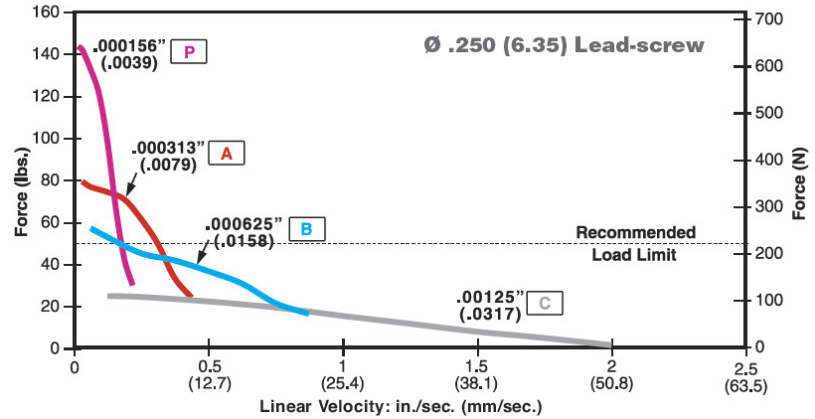


Single Stack

FORCE vs. PULSE RATE
 - Chopper
 - Bipolar
 - 100% Duty Cycle

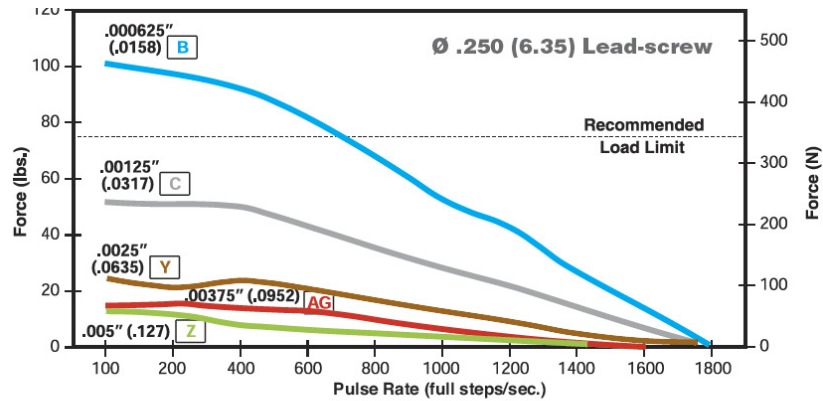


FORCE vs. LINEAR VELOCITY
 - Chopper
 - Bipolar
 - 100% Duty Cycle

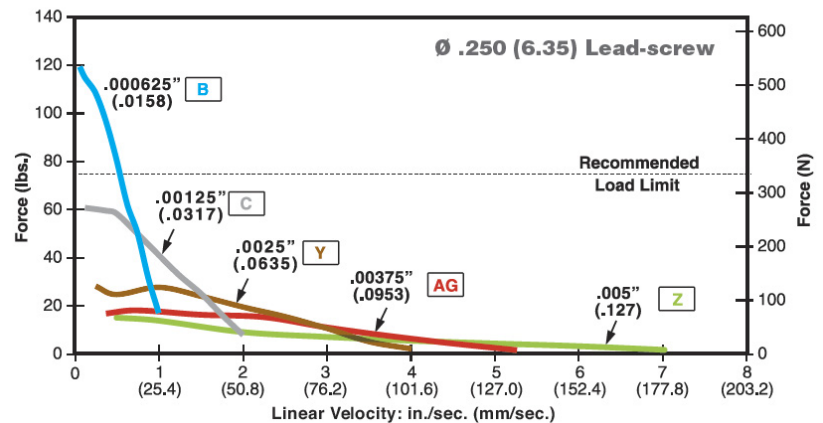


Double Stack

FORCE vs. PULSE RATE
 - Chopper
 - Bipolar
 - 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
 - Chopper
 - Bipolar
 - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

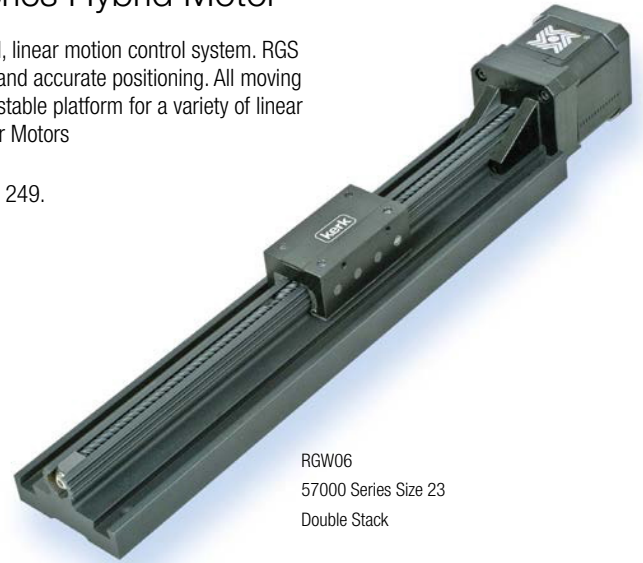
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

RGS06 and RGW06 Wide Linear Rails with 57000 Series Hybrid Motor

A combination of Haydon Kerk Motion Solutions patented motion technologies into a single integrated, linear motion control system. RGS linear rails feature standard wear-compensating, anti-backlash driven carriages to insure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. RGS Series Linear Rail with Hybrid 57000 Series Size 23 Linear Actuator Stepper Motors

Technical specifications for 57000 Series Size 23 Hybrid Linear Actuator Stepper Motors are on page 249.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).



RGW06
57000 Series Size 23
Double Stack

Identifying the BGS Part Number Codes when Ordering

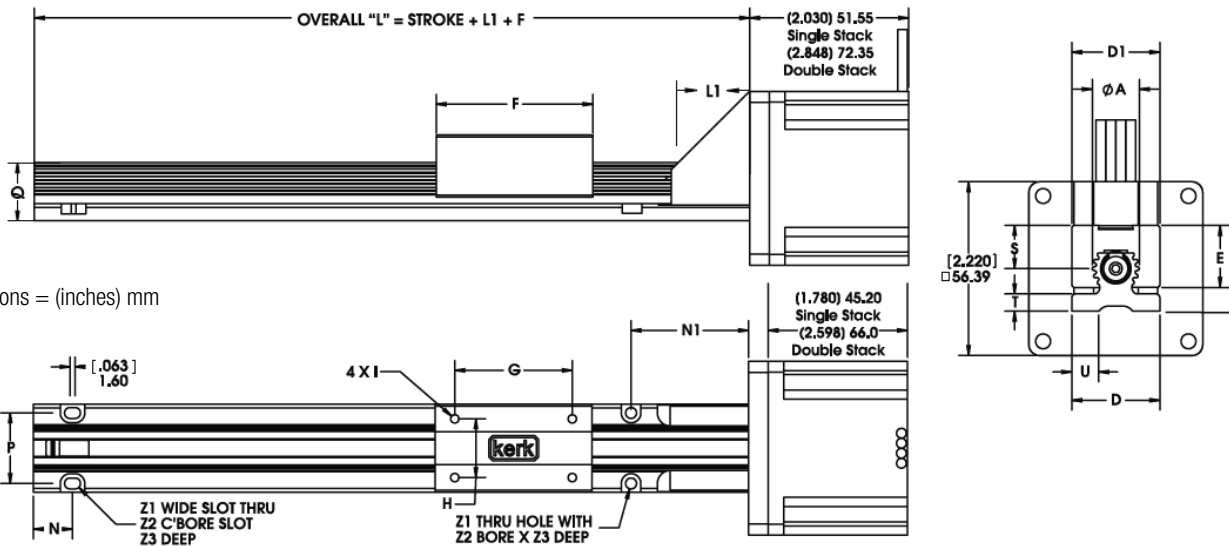
RG	S	06	K	M	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	S = Standard W = Wide sensor mount capability	06 = 35 lbs (156 N) (Maximum static load)	K = TFE Kerkote®	M = Motorized	0050 = .050-in (1.27) 0079 = .079-in (2.00) 0100 = .100-in (2.54) 0157 = .157-in (4.00) 0197 = .197-in (5.00) 0200 = .200-in (5.08) 0250 = .250-in (6.35) 0375 = .375-in (9.53) 0400 = .400-in (10.16) 0472 = .472-in (12.00) 0500 = .500-in (12.70) 0750 = .750-in (19.05) 0984 = .984-in (25.00) 1000 = 1.000-in (25.4) 1200 = 1.200-in (30.48)	Suffix used to identify specific motors (43000 Single/ Double Stack – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M4, M5, M6

■ RGS06 with 57000 Series Size 23 Single and Double Stack linear motors

Recommended for horizontal loads up to 35 lbs (156 N)



Dimensions = (inches) mm

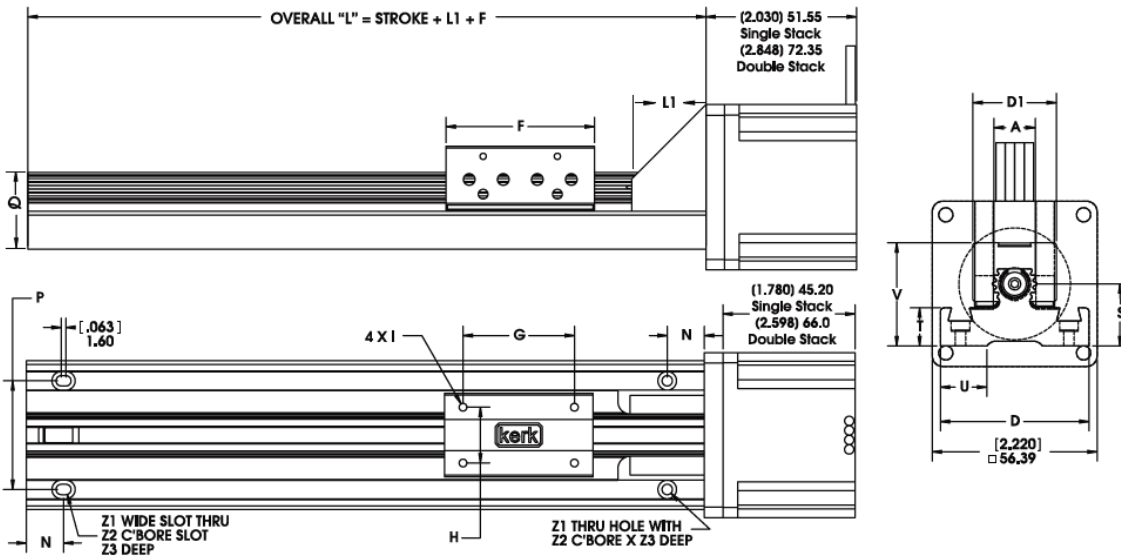
	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(1.13)	(1.13)	(0.79)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.5)	(0.9)	(0.74)	(0.55)	(0.22)	(0.35)	(1.1)	(0.14)	(0.25)	(0.13)
mm	15.2	28.7	28.7	20.1	50.8	38.1	19.0	UNC	25.4	12.7	38.1	22.9	18.8	13.9	5.6	8.9	27.9	3.6	6.3	3.3

* Metric threads also available for carriage.

■ RGW06 Wide 57000 Series Size 23 Single Stack and Double Stack linear motors

Recommended for horizontal loads up to 35 lbs (156 N)

Dimensions = (inches) mm

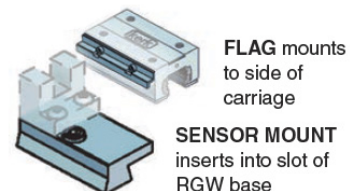


	A	D	D1	F	G	H	I*	L1	N	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.6)	(2.0)	(1.13)	(2.0)	(1.5)	(0.75)	6-32	(1.0)	(0.5)	(1.46)	(0.74)	(0.83)	(0.51)	(0.63)	(1.39)	(0.14)	(0.25)	(0.14)
mm	15.2	50.8	28.7	50.8	38.1	19.0	UNC	25.4	12.7	22.9	37.1	21.1	13.0	16.0	35.3	3.6	6.3	3.6

* Metric threads also available for carriage.

RGW06 Sensor Mount Kit Part No. RGW06SK

Sensor mount kits, based on a U-channel optical sensor, are available for the RGW Series. Each kit includes one flag, three sensor mounts, and all mounting hardware. Sensors are not included in the kit and must be ordered separately from the sensor manufacturer.



Single Stack

57000 Series Size 23

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				
Rotor Inertia	166 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	18 oz (511 g)				
Insulation Resistance	20 MΩ				

** Unipolar drive gives approximately 30% less thrust than bipolar drive. Standard motors are Class B rated for maximum temperature of 130°C.

Double Stack

57000 Series Size 23

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 MΩ		

57000 Series
Size 23
Single Stack
External Linear

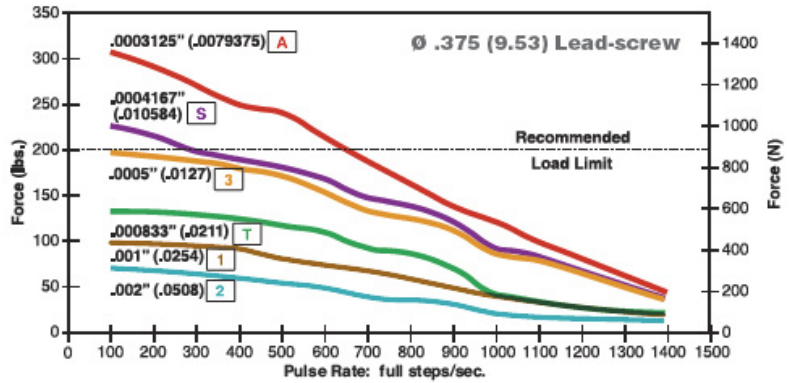


57000 Series
Size 23
Double Stack
External Linear

Single Stack

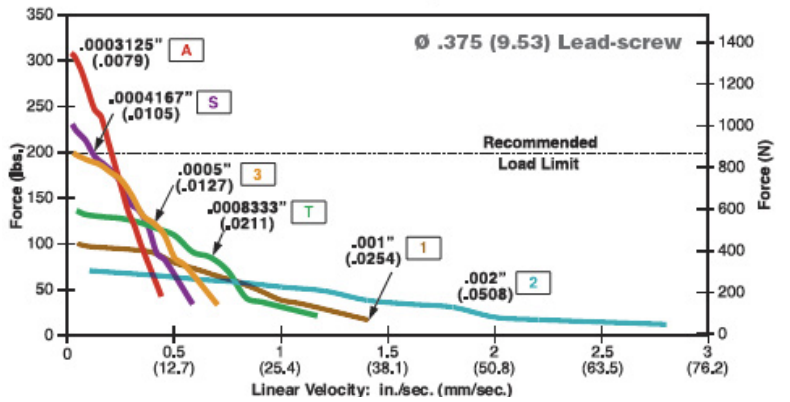
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

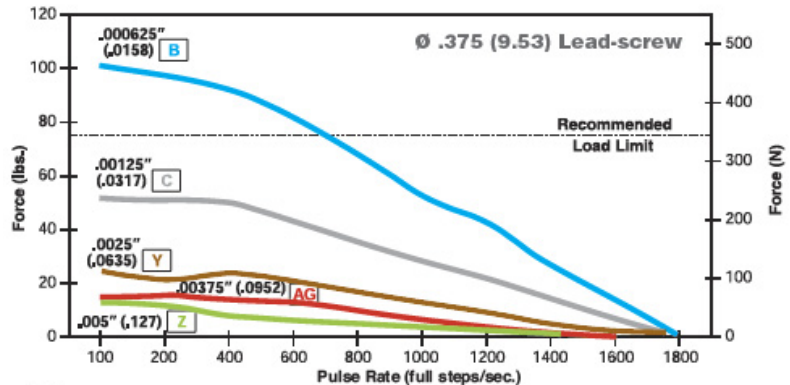
- Chopper
- Bipolar
- 100% Duty Cycle



Double Stack

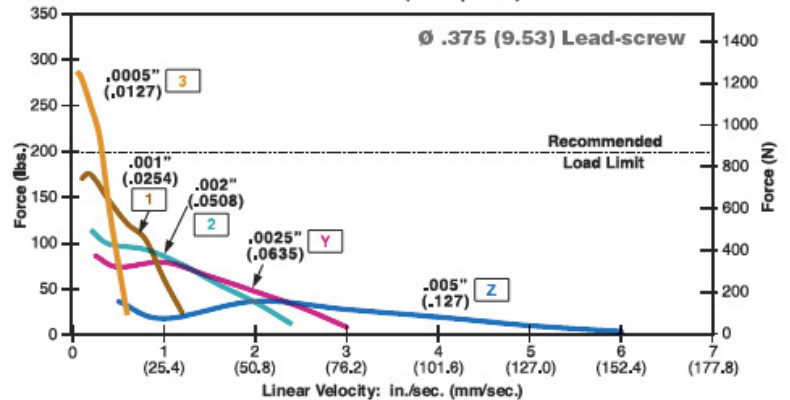
FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

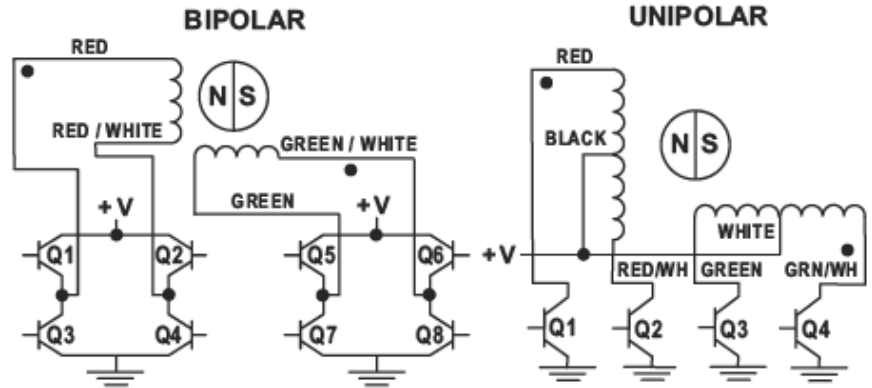
43000 Series Size 17 and 57000 Series Size 23

Hybrids: Stepping Sequence

Hybrids: Wiring

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
	Unipolar	Q1	Q2	Q3	Q4
EXTEND CW ↓ ↑ RETRACT CCW	Step				
	1	ON	OFF	ON	OFF
	2	OFF	ON	ON	OFF
	3	OFF	ON	OFF	ON
	4	ON	OFF	OFF	ON
	1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



Size 17 43000 Series • Integrated Connectors

Haydon Kerk Hybrid Size 17 Single and Double Stack linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre existing harnesses. In addition to standard configurations, Haydon Kerk Motion Solutions can custom design this motor to meet your specific application requirements.



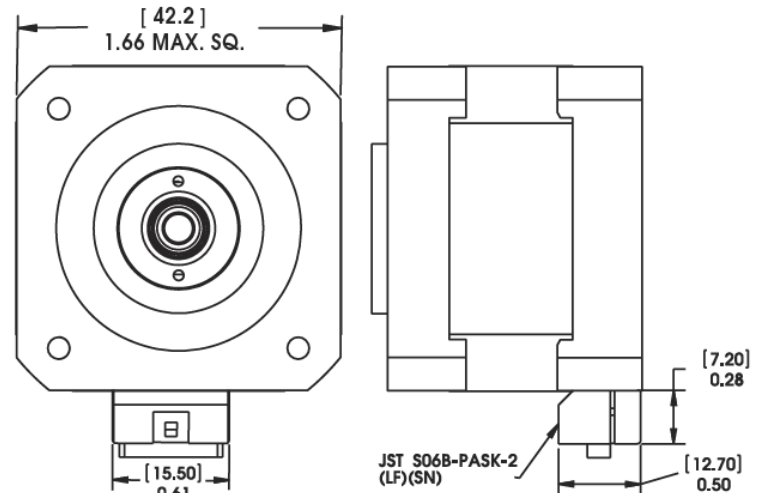
- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk Part #56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red

Dimensional Drawings

Integrated Connector with 43000 Series Size 17

Dimensions = (mm) inches



RGS06 Non-Motorized Linear Rails

- Screw driven linear rails in standard or wide format
- Linear rails without screw in standard or wide format

The non-motorized RGS Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 35 lbs (156 N).



RGW06 Wide Series, Non-Motorized Screw Driven Linear Rail

Identifying the Non-Motorized RGS Part Numbers when Ordering

RG	S	06	K	A	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard W = Wide Sensor Mount Capability	Frame Size Load 06 = 35 lbs (156 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None B = Inline Screw Motor Mount	Nominal Thread Lead Code 0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

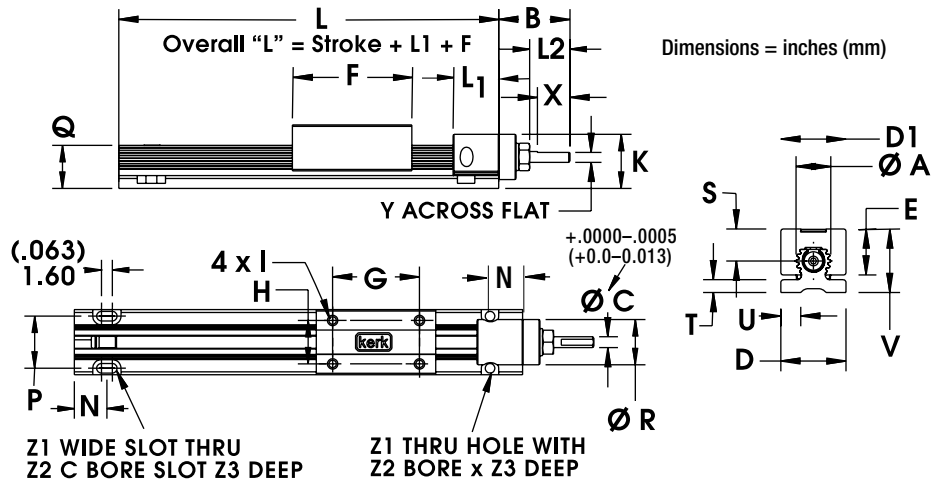
RGS06 Non-Motorized with Guide Screw	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	0.6 (15.2)	3/8 (9.5)	4.0 (0.3)	100,000,000 (254,000,000)	1.0 (.016)	35 (156)	1.5 x 10 ⁻⁵ (4.2 x 10 ⁻⁶)
	.200 (5.08)	0200			5.0 (.04)				
	.500 (12.70)	0500			6.0 (.04)				
1.000 (25.40)	1000	7.0 (.05)							

NOTE: RGS assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Standard Frame



Dimensions = inches (mm)

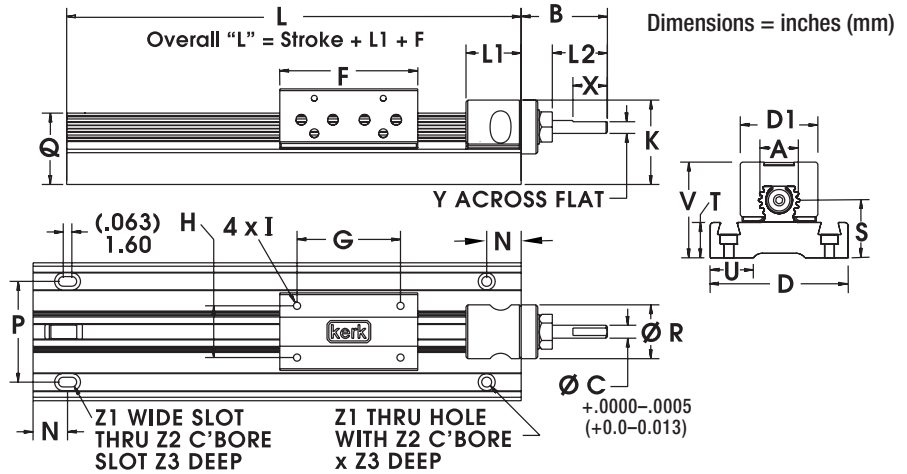
RGS06 Non-Motorized, Screw Driven

	A	B	C	D	D1	E	F	G	H	I*	K	L1	L2	N	P	Q	R	S	T	U	V	X	Z1	Z2	Z3
inch	0.60	1.25	.1875	1.13	1.13	0.79	2.0	1.50	0.750	6-32 UNC	0.9	.80	.80	.50	.90	.74	.80	.55	.22	.35	1.1	.50	.14	.25	.13
mm	15.2	31.8	4.762	28.6	28.6	20.1	51	38.1	19.1	UNC	23	20.3	20.3	12.7	22.8	18.8	20.3	14.0	5.6	8.9	28	12.7	3.6	6.4	3.3

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Wide Frame



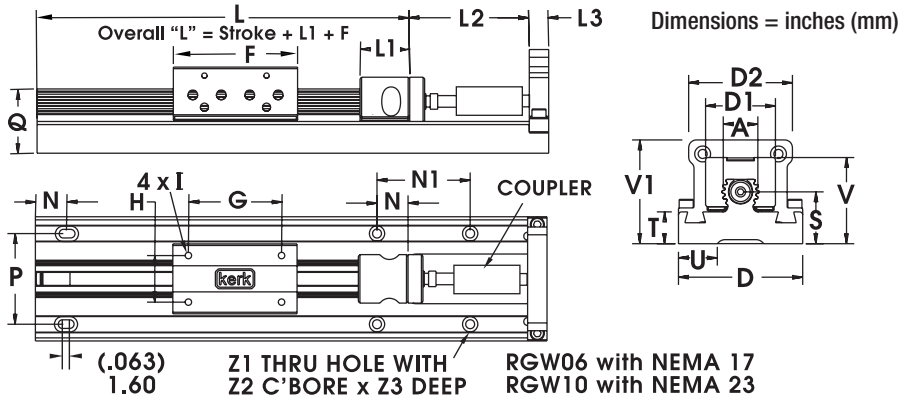
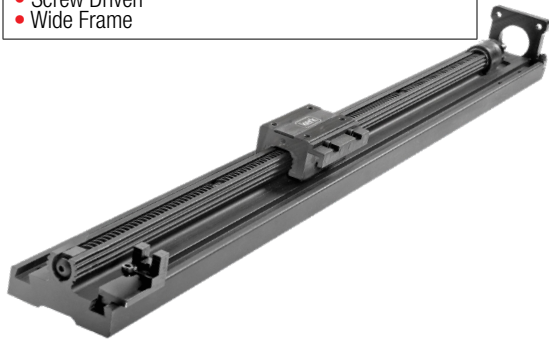
RGW06 Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Motor Mount for Non-Motorized with Lead Screw Dimensional Drawings

- Motor Mount
- Screw Driven
- Wide Frame



NOTE: The coupling shown in the dimensional drawing is not included.

RGW06 Motor Mount, Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

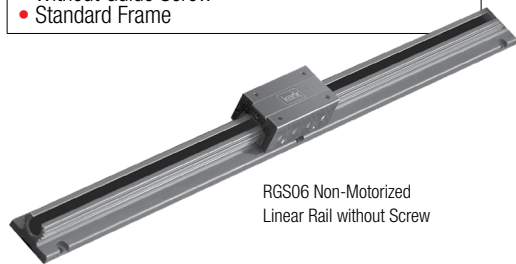
*Metric carriage hole sizes available M3, M4, M5, M6.

RGW06 Sensor Mount Kits

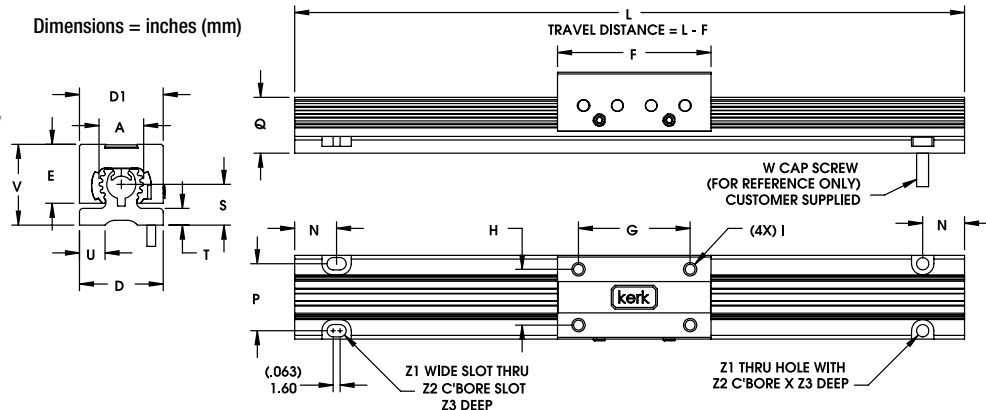
Sensor mounting kits based on U-channel optical sensor. Each kit includes one flag, three sensor mounts and all mounting hardware. Sensors are not included in the kit and must be ordered separately from sensor manufacturer. Part # RGW06SK

Non-Motorized without Lead Screw
Dimensional Drawings

- Without Guide Screw
- Standard Frame



Dimensions = inches (mm)



RGS06 Non-Motorized, Without Screw Driven

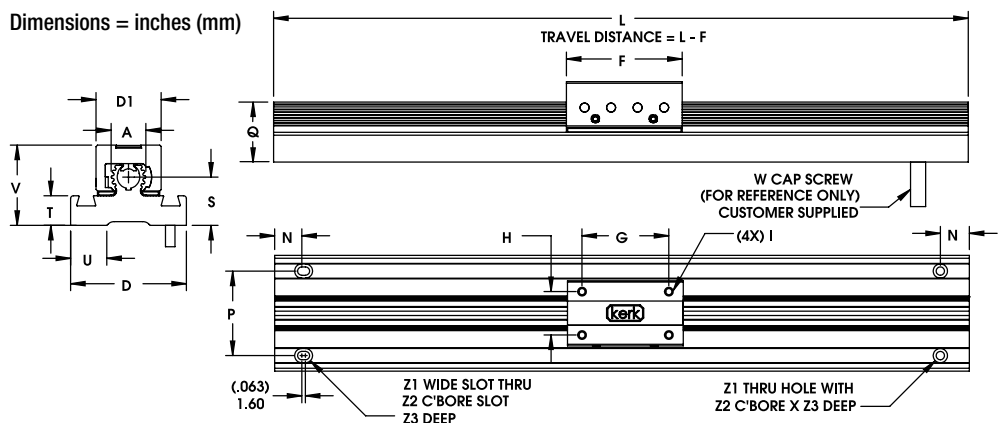
	A	D	D1	E	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	0.60	1.13	1.13	.79	2.0	1.50	.75	6-32	.50	.90	.74	.55	.22	.35	1.1	.14	.25	.13
mm	15.2	28.6	28.6	20.1	51	38.1	19	UNC	12.7	22.8	18.8	14	5.6	8.9	28	3.6	6.4	3.3

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized without Lead Screw
Dimensional Drawings

- Without Guide Screw
- Wide Frame

Dimensions = inches (mm)



RGS06 Wide Series, Non-Motorized, Without Screw Driven

	A	D	D1	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	0.60	1.13	1.13	2.0	1.50	.75	6-32	.50	1.46	1.04	.83	.51	.63	1.4	.14	.25	.14
mm	15.2	28.6	28.6	51	38.1	19	UNC	12.7	37	26.4	21.2	13	16	36	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers, Kerkite Polymers are formulated to provide optimum performance in its target conditions and applications.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris. Kerkote differs from conventional plating and coating because it is soft, more evenly distributed than other lubricants, and decreases erratic drag torques and unpredictable wear.

- Reduces friction
- Cost effective
- Long term and maintenance free

Kerkote provides the maximum level of self-lubrication, requiring no additional external lubrication or maintenance.

RGW06 Non-Motorized Linear Rails

- Screw driven linear rails in wide format
- Linear rails without screw in wide format

The non-motorized RGW Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 35 lbs (156 N).



RGW06 Wide Series, Non-Motorized Screw Driven Linear Rail

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the Non-Motorized RGW Part Numbers when Ordering

RG	W	06	K	A	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style W = Wide Sensor Mount Capability	Frame Size Load 06 = 35 lbs (156 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None B = Inline Screw Motor Mount	Nominal Thread Lead Code 0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

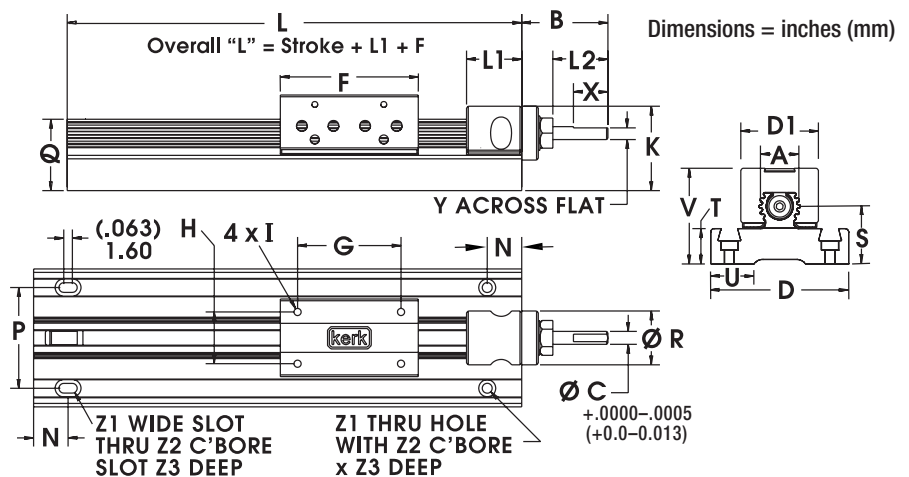
	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
RGW06 Non-Motorized with Lead Screw	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	0.6 (15.2)	3/8 (9.5)	4.0 (0.3)	100,000,000 (254,000,000)	1.0 (.016)	35 (156)	1.5 x 10 ⁻⁵ (4.2 x 10 ⁻⁶)
	.200 (5.08)	0200			5.0 (.04)		1.5 (.023)		
	.500 (12.70)	0500			6.0 (.04)		2.5 (.039)		
1.000 (25.40)	1000	7.0 (.05)			4.5 (.070)				

NOTE: RGW assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Wide Frame



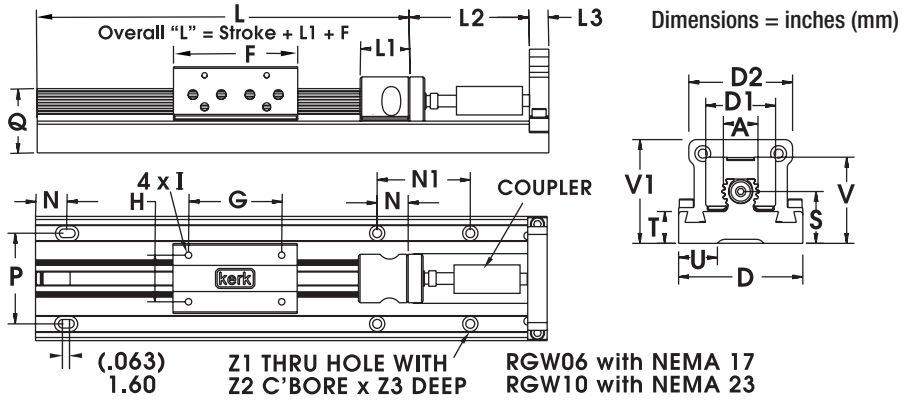
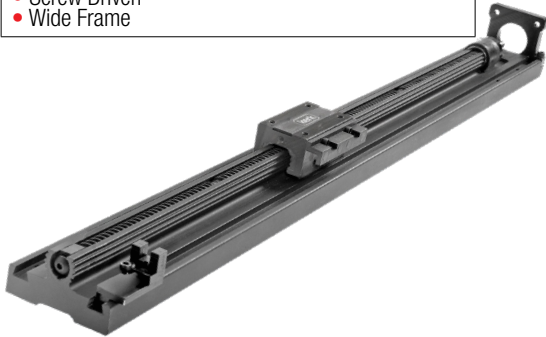
RGW06 Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Motor Mount for Non-Motorized with Lead Screw Dimensional Drawings

- Motor Mount
- Screw Driven
- Wide Frame



NOTE: The coupling shown in the dimensional drawing is not included.

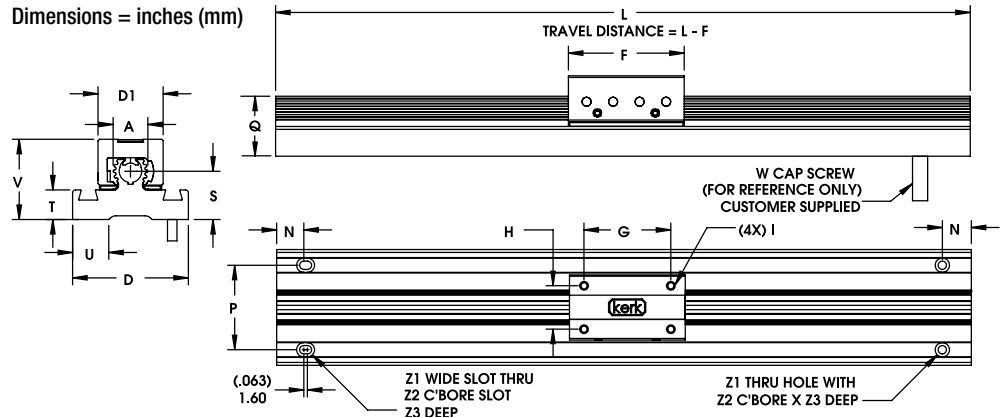
RGW06 Motor Mount, Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized without Lead Screw Dimensional Drawings

- Without Guide Screw
- Wide Frame



RGW06 Wide Series, Non-Motorized, Without Screw Driven

	A	D	D1	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	0.60	1.13	1.13	2.0	1.50	.75	6-32	.50	1.46	1.04	.83	.51	.63	1.4	.14	.25	.14
mm	15.2	28.6	28.6	51	38.1	19	UNC	12.7	37	26.4	21.2	13	16	36	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris.

- Reduces friction
- Cost effective
- Requires no additional external lubrication or maintenance

Accessory

RGW06 Sensor Mount Kits

Sensor mounting kits based on U-channel optical sensor. Each kit includes one flag, three sensor mounts and all mounting hardware. Sensors are not included in the kit and must be ordered separately from sensor manufacturer. Part # RGW06SK

RGS08 Linear Rail for Heavier Weight Applications

with 57000 Series Size 23 Single and Double Stack Hybrid Linear Actuators

A combination of Haydon Kerk Motion Solutions patented motion technologies into a single integrated, linear motion control system. RGS linear rails feature standard wear-compensating, anti-backlash driven carriages to insure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications.

Technical specifications for 57000 Series Size 23 Hybrid Linear Actuator Stepper Motors are on page 3.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).



RGS08
57000 Series Size 23
Double Stack

Identifying the RGS08 Part Number Codes when Ordering

RG	S	08	K	M	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	S = Standard	08 = 50 lbs (222 N) (Maximum static load)	K = TFE Kerkote® X = Special (example: Kerkote with grease)	M = Motorized	0098 = .098-in (2.50) 0100 = .100-in (2.54) 0197 = .197-in (5.00) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 0630 = .630-in (16.00) 1000 = 1.000-in (25.4)	Suffix used to identify specific motors (43000 Single/ Double Stack – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

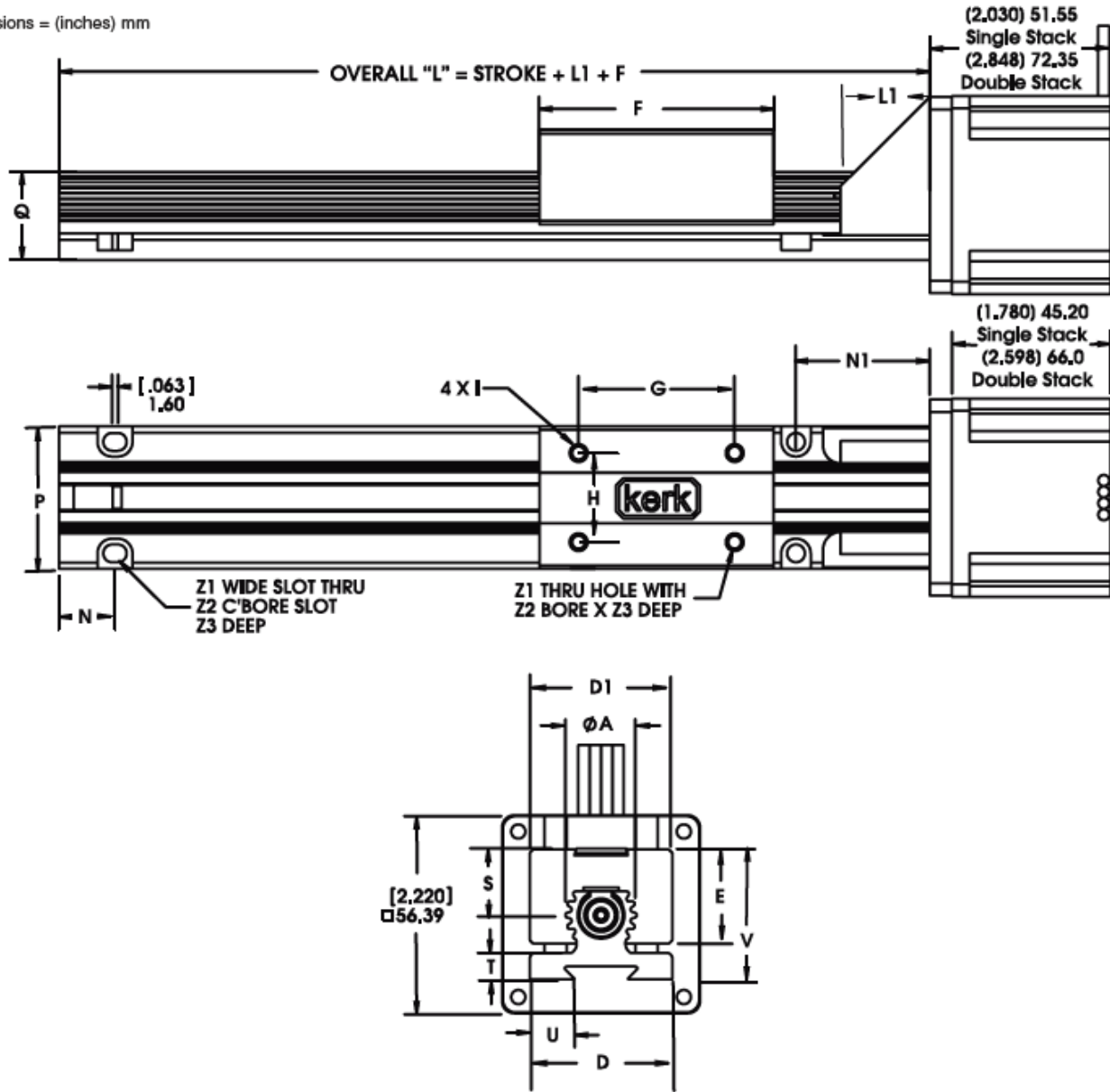
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M4, M5, M6

RGS08 with 57000 Series Size 23 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 50 lbs (222 N)

Dimensions = (inches) mm



	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(0.8)	(1.6)	(1.6)	(1.06)	(2.7)	(1.75)	(1.0)	10-20	(1.0)	(0.625)	(1.5)	(1.25)	(1.0)	(0.74)	(0.3)	(0.51)	(1.47)	(0.2)	(0.33)	(0.19)
mm	20.3	40.6	40.6	26.9	68.6	44.5	25.4	UNC	25.4	15.9	38.1	15.9	25.4	18.8	7.6	12.9	37.3	5.1	8.4	4.8

* Metric threads also available for carriage.

Single Stack

57000 Series Size 23

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				
Rotor Inertia	166 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	18 oz (511 g)				
Insulation Resistance	20 MΩ				

Standard motors are Class B rated for maximum temperature of 130°C.

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Double Stack

57000 Series Size 23

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
	3.25 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 MΩ		

57000 Series Size 23
Single Stack
External Linear



57000 Series Size 23
Double Stack
External Linear

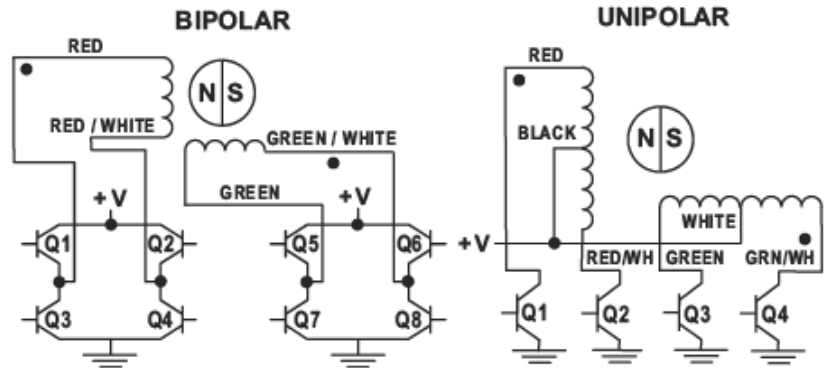
Size 23 57000 Series • Stepping Sequence & Wiring

Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4	
Step					
1	ON	OFF	ON	OFF	
2	OFF	ON	ON	OFF	
3	OFF	ON	OFF	ON	
4	ON	OFF	OFF	ON	
1	ON	OFF	ON	OFF	

↑ EXTEND CW
↓ RETRACT CCW

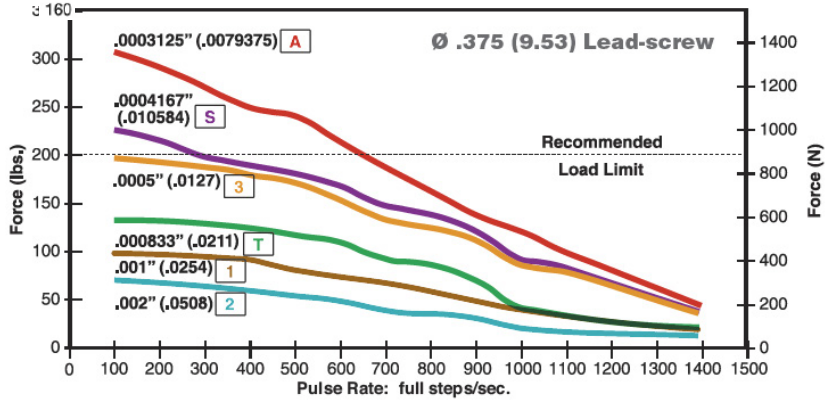
Hybrids: Wiring



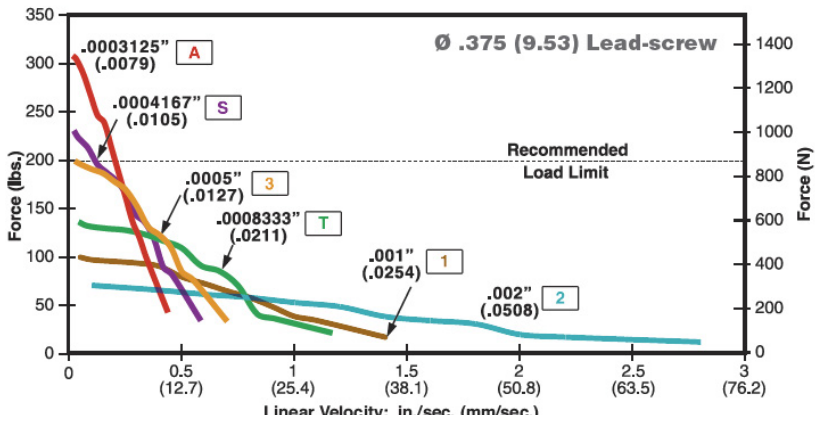
Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Single Stack

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle

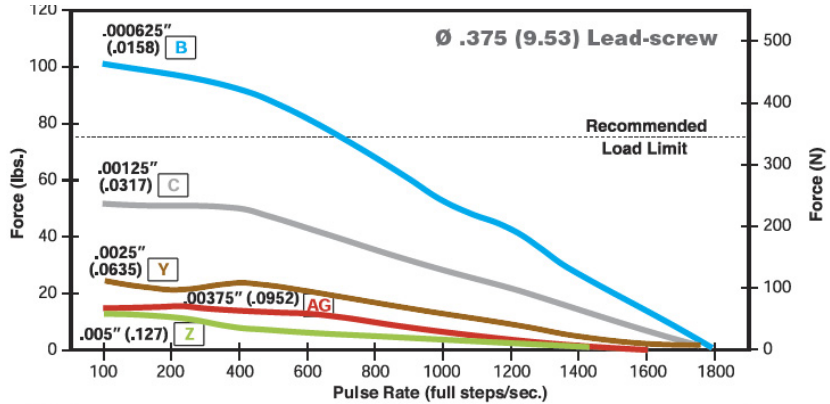


FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle

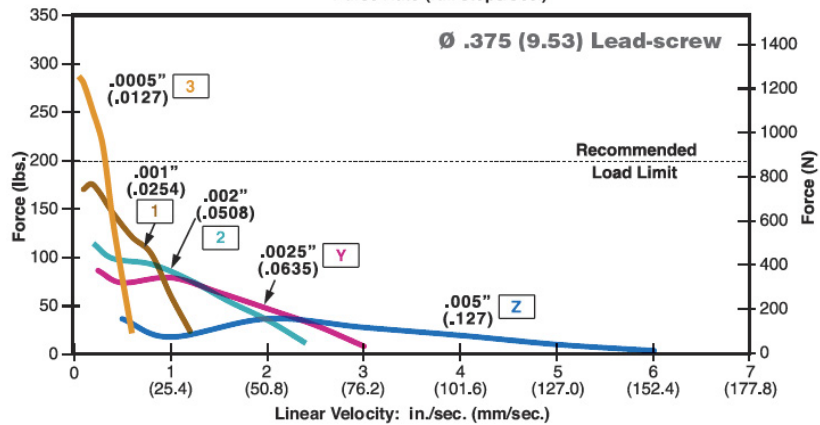


Double Stack

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
- Chopper - Bipolar - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot. With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

RGS08 Non-Motorized Linear Rails

Screw driven linear rail or linear rail without screw

The non-motorized RGS Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 50 lbs (222 N).



RGS08 Non-Motorized Screw Driven Linear Rail

Identifying the Non-Motorized RGS Part Numbers when Ordering

RG	S	08	K	A	0100	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard	Frame Size Load 08 = 50 lbs (222 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None	Nominal Thread Lead Code 0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

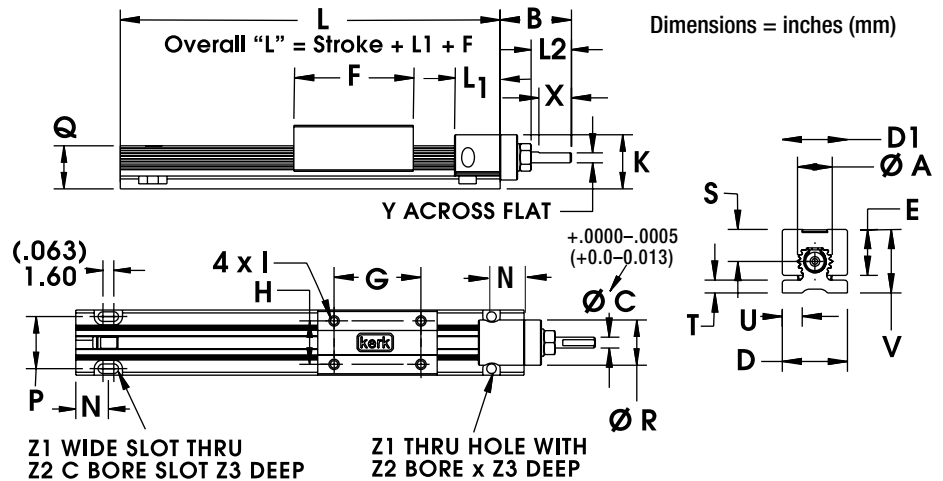
RGS08 Non-Motorized with Lead Screw	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	0.8 (20.3)	1/2 (12.7)	5.0 (0.4)	100,000,000 (254,000,000)	1.1 (.018)	50 (222)	5.2 x 10 ⁻⁵ (20.0 x 10 ⁻⁶)
	.200 (5.08)	0200			6.0 (.04)		1.7 (.027)		
	.500 (12.70)	0500			7.0 (.05)		3.0 (.047)		
1.000 (25.40)	1000	8.0 (.06)			6.0 (.096)				

NOTE: RGS assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Standard Frame



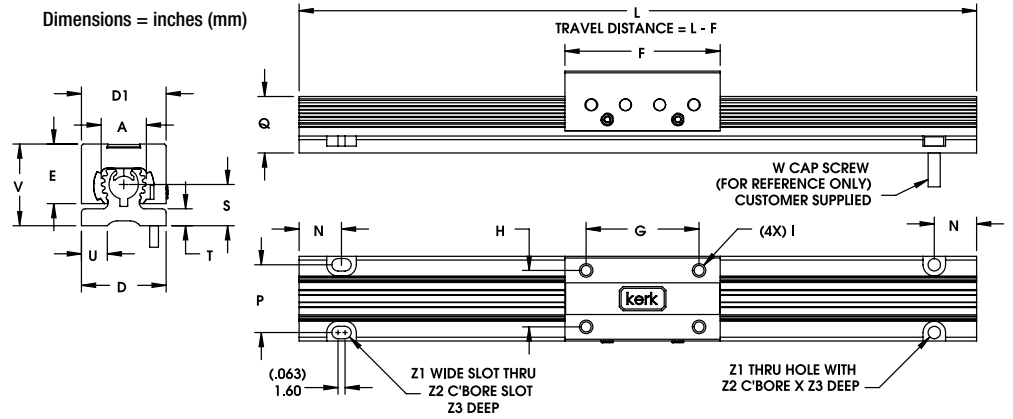
RGS08 Non-Motorized, Screw Driven

	A	B	C	D	D1	E	F	G	H	I*	K	L1	L2	N	P	Q	R	S	T	U	V	X	Z1	Z2	Z3
inch	0.80	1.50	.250	1.60	1.60	1.06	2.7	1.75	1.00	10-24 UNC	1.3	1.09	.77	.625	1.25	1.0	1.04	.74	.30	.51	1.47	.70	.22	.33	.19
mm	20.3	38.1	6.35	40.6	40.6	26.9	69	44.4	25.4		33	27.7	19.6	15.8	31.75	25.4	26.4	18.8	7.6	13	37.3	17.8	5.5	8.4	4.8

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized without Lead Screw
Dimensional Drawings

- Without Guide Screw
- Standard Frame



RGS08 Non-Motorized, Without Screw Driven

	A	D	D1	E	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	0.80	1.60	1.60	1.06	2.7	1.75	1.00	10-24	.625	1.25	1.00	.74	.30	.51	1.47	.20	.33	.19
mm	20.3	40.6	40.6	26.9	69	44.4	25.4	UNC	15.8	31.7	25.4	18.8	7.6	13	37.3	5.1	8.3	4.8

*Metric carriage hole sizes available M3, M4, M5, M6.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Material Coatings

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- Reduces friction
- Cost effective
- Long term and maintenance free

Kerkote provides the maximum level of self-lubrication, requiring no additional external lubrication or maintenance.

RGS10 and RGW10 Wide Linear Rails

with 57000 Series Size 23 Hybrid Linear Actuators

Driven by a Size 23 Hybrid motor, the 25.4 mm (1-inch) diameter splined carriage guide has been designed to carry a weight load up to 100 lbs (445 N). A high performance motion control system combines power and precision. The system combines many Haydon Kerk Motion Solutions patented motion technologies into a single integrated, linear motion control system. The Motorized RGS linear rails feature standard wear-compensating, anti-backlash driven carriages to insure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. RGS Series Linear Rail with Hybrid 57000 Series Size 23 Linear Actuator Stepper Motors

Technical specifications for 57000 Series Size 23 Hybrid Linear Actuator Stepper Motors are on page 3.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).



RGS08
57000 Series Size 23
Double Stack

■ Identifying the RGS10 and RGW10 Part Number Codes when Ordering

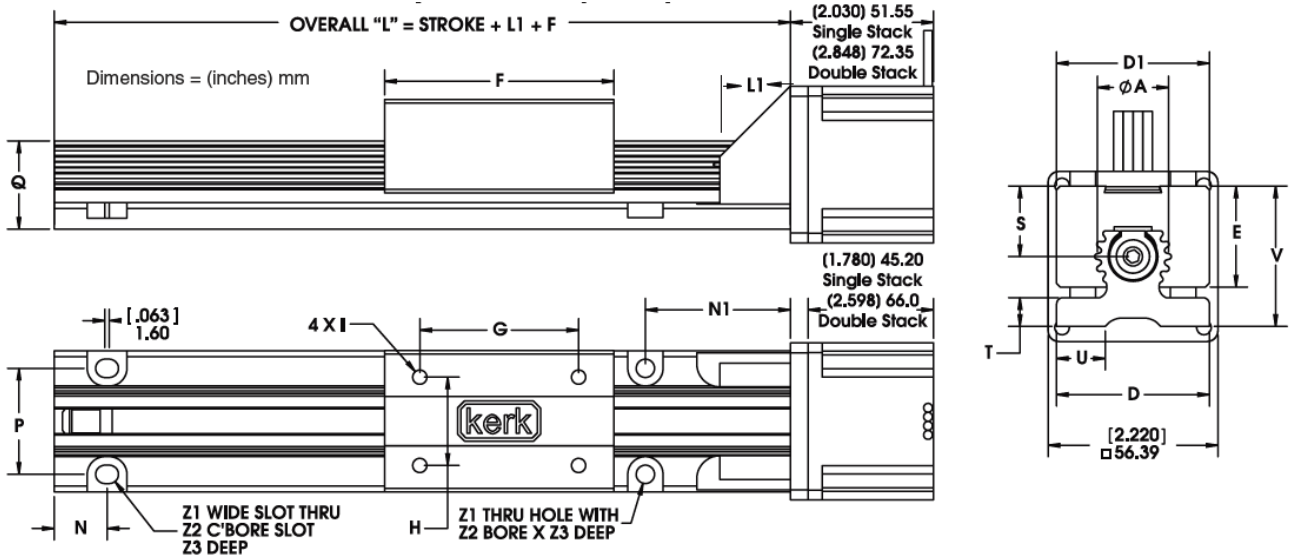
RG	S	10	K	M	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	S = Standard W = Wide sensor mount capability	10 = 100 lbs (445 N) (Maximum static load)	K = TFE Kerkote®	M = Motorized	0100 = .100-in (2.54) 0125 = .125-in (3.18) 0200 = .200-in (5.08) 0250 = .250-in (6.35) 0315 = .315-in (8.00) 0500 = .500-in (12.70) 0630 = .630-in (16.00) 1000 = 1.000-in (25.4) 1500 = 1.500-in (38.10) 2000 = 2.000-in (50.80)	Suffix used to identify specific motors (43000 Single/ Double Stack – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M4, M5, M6

■ RGS10 with 57000 Series Size 23 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 100 lbs (445 N)

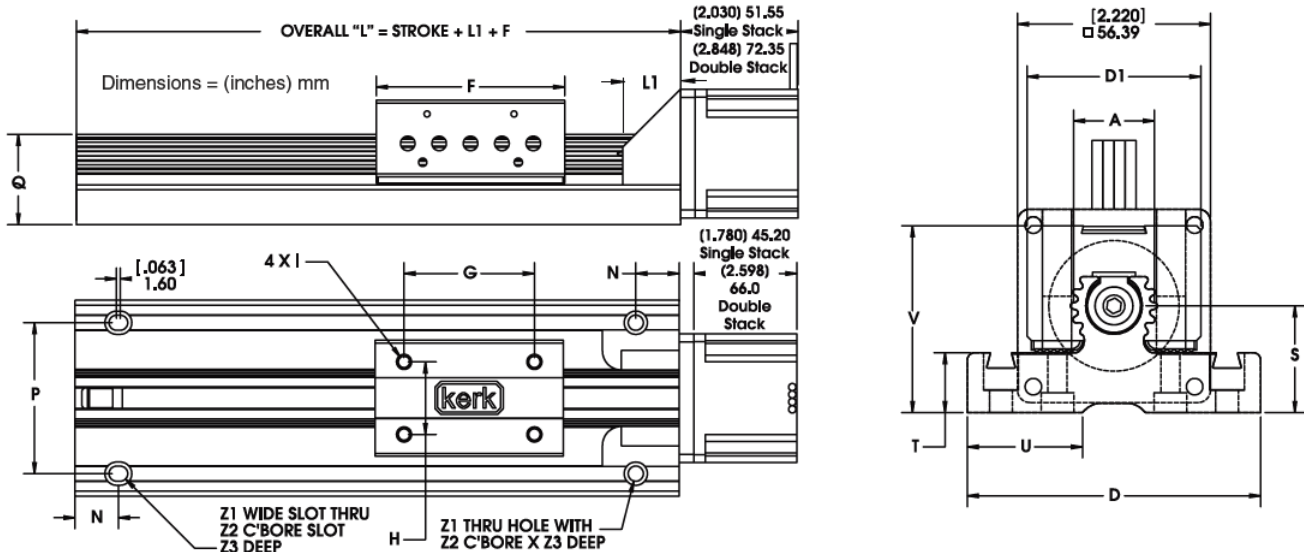


	A	D	D1	E	F	G	H	I*	L1	N	N1	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(1.0)	(2.0)	(2.0)	(1.32)	(3.3)	(2.25)	(1.25)	1/4-20	(1.0)	(0.75)	(2.045)	(1.5)	(1.25)	(0.92)	(0.375)	(0.64)	(1.83)	(0.26)	(0.5)	(0.22)
mm	25.4	50.8	50.8	33.5	83.8	57.1	31.7	UNC	25.4	19.0	52.2	38.1	37.1	23.4	9.53	16.3	46.5	6.6	12.7	5.6

* Metric threads also available for carriage.

■ RGW10 Wide with 57000 Series Size 23 Single and Double Stack Linear Actuators

Recommended for horizontal loads up to 100 lbs (445 N)

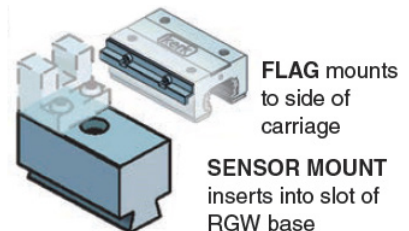


	A	D	D1	F	G	H	I*	L1	N	P	Q	S	T	U	V	Z1	Z2	Z3
(inch)	(1.0)	(3.38)	(2.0)	(3.3)	(2.25)	(1.25)	1/4-20	(1.0)	(0.75)	(2.6)	(1.56)	(1.22)	(0.69)	(1.33)	(2.15)	(0.26)	(0.4)	(0.43)
mm	25.4	85.9	50.8	83.8	57.1	31.7	UNC	25.4	19.0	66.0	39.6	31.0	17.5	33.8	54.6	6.6	10.2	10.9

* Metric threads also available for carriage.

RGW10 Sensor Mount Kit Part No. RGW10SK

Sensor mount kits, based on a U-channel optical sensor, are available for the RGW Series. Each kit includes one flag, three sensor mounts, and all mounting hardware. Sensors are not included in the kit and must be ordered separately from the sensor manufacturer.



Single Stack

57000 Series Size 23

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				
Rotor Inertia	166 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	18 oz (511 g)				
Insulation Resistance	20 MΩ				

** Unipolar drive gives approximately 30% less thrust than bipolar drive. Standard motors are Class B rated for maximum temperature of 130°C.

Double Stack

57000 Series Size 23

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
	3.25 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 MΩ		

57000 Series Size 23
Single Stack
External Linear



57000 Series Size 23
Double Stack
External Linear

Size 23 57000 Series • Stepping Sequence & Wiring

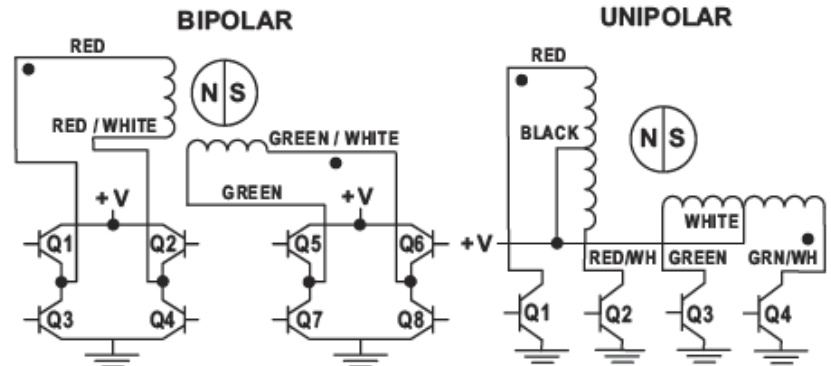
Hybrids: Stepping Sequence

Hybrids: Wiring

Step	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
	Unipolar	Q1	Q2	Q3	Q4
1	ON	OFF	ON	OFF	
2	OFF	ON	ON	OFF	
3	OFF	ON	OFF	ON	
4	ON	OFF	OFF	ON	
1	ON	OFF	ON	OFF	

EXTEND CW ↓

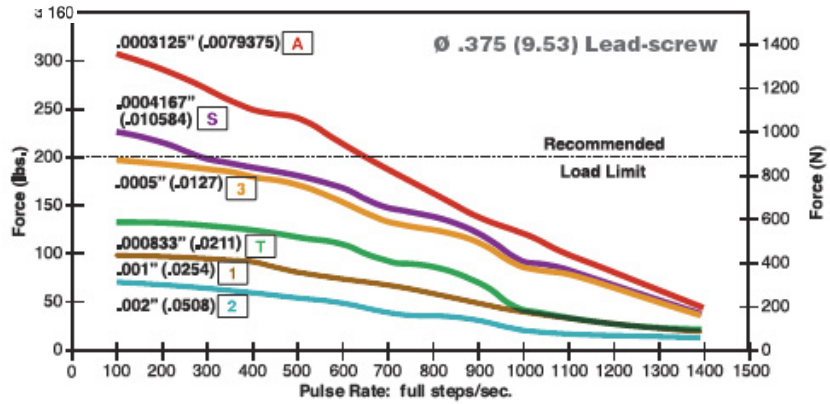
RETRACT CCW ↑



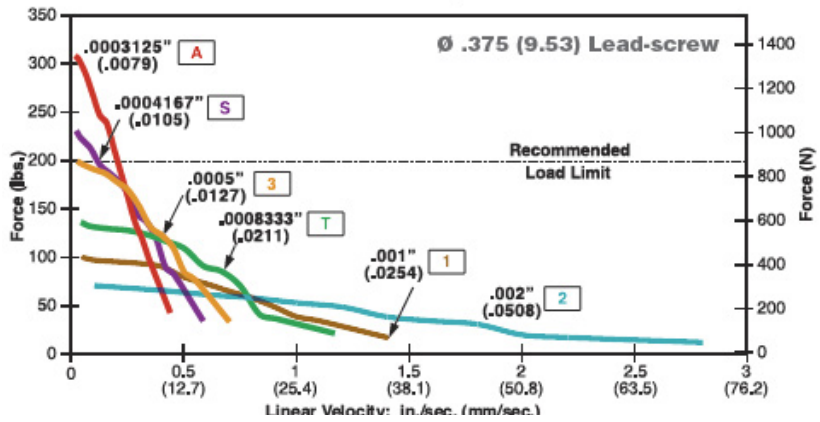
Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Single Stack

- FORCE vs. PULSE RATE
 - Chopper
 - Bipolar
 - 100% Duty Cycle

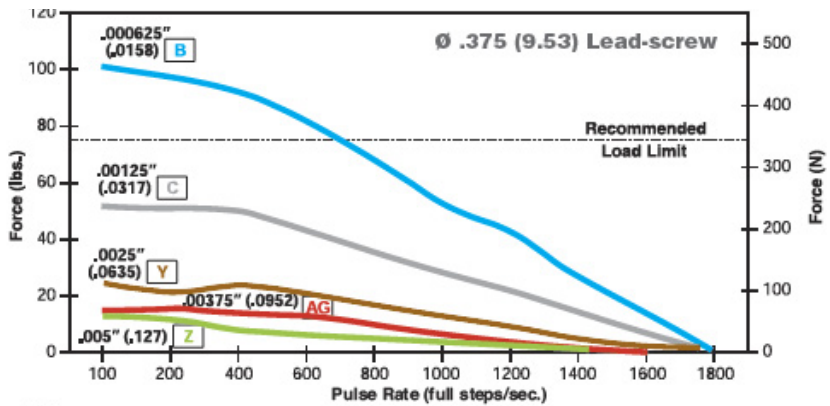


- FORCE vs. LINEAR VELOCITY
 - Chopper
 - Bipolar
 - 100% Duty Cycle

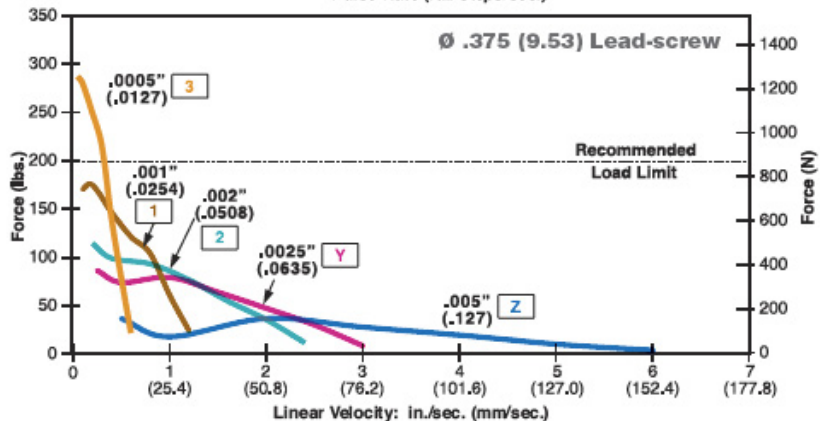


Double Stack

- FORCE vs. PULSE RATE
 - Chopper
 - Bipolar
 - 100% Duty Cycle



- FORCE vs. LINEAR VELOCITY
 - Chopper
 - Bipolar
 - 100% Duty Cycle



RGS10 Non-Motorized Linear Rails

- Screw driven linear rails in standard or wide format
- Linear rails without screw in standard or wide format

The non-motorized RGS Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 100 lbs (445 N).

RGW10 Wide Series, Non-Motorized Screw Driven Linear Rail



Identifying the Non-Motorized RGS Part Numbers when Ordering

RG	S	10	K	A	0500	XXX
Prefix RG = Rapid Guide Screw	Frame Style S = Standard W = Wide Sensor Mount Capability	Frame Size Load 10 = 100 lbs (445 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None B = Inline Screw Motor Mount	Nominal Thread Lead Code 0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

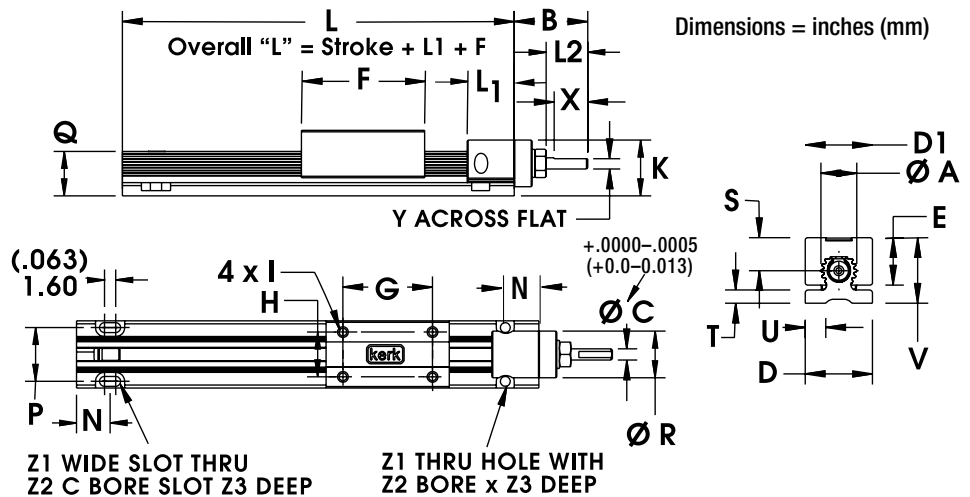
	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
RGS10 Non-Motorized with Lead Screw	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	1.0 (25.4)	5/8 (15.9)	5.0 (0.4)	100,000,000 (254,000,000)	1.3 (.020)	100 (445)	14.2 x 10 ⁻⁵ (3.9 x 10 ⁻⁶)
	.200 (5.08)	0200			6.5 (.05)		2.0 (.031)		
	.500 (12.70)	0500			7.0 (.05)		3.0 (.047)		
1.000 (25.40)	1000	8.5 (.06)			6.5 (.101)				

NOTE: RGS assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Standard Frame



Dimensions = inches (mm)

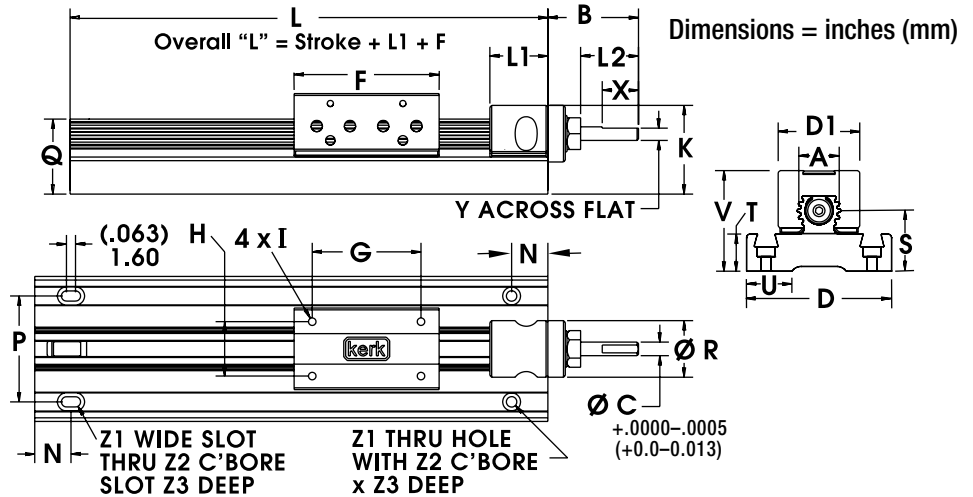
RGS10 Non-Motorized, Screw Driven

	A	B	C	D	D1	E	F	G	H	I*	K	L1	L2	N	P	Q	R	S	T	U	V	X	Y	Z1	Z2	Z3
inch	1.0	1.75	.312	2.0	2.0	1.32	3.3	2.25	1.25	1/4-20	1.6	1.3	.30	.75	1.5	1.25	1.3	.92	.375	.64	1.83	.88	.28	.26	.50	.22
mm	25.4	44.5	7.93	50.8	50.8	33.5	83	57.1	31.8	UNC	41	33	33	19	38.1	31.8	33	23.4	9.5	16.3	46.5	22.4	7.1	6.6	12.7	5.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized with Lead Screw
Dimensional Drawings

- Screw Driven
- Wide Frame



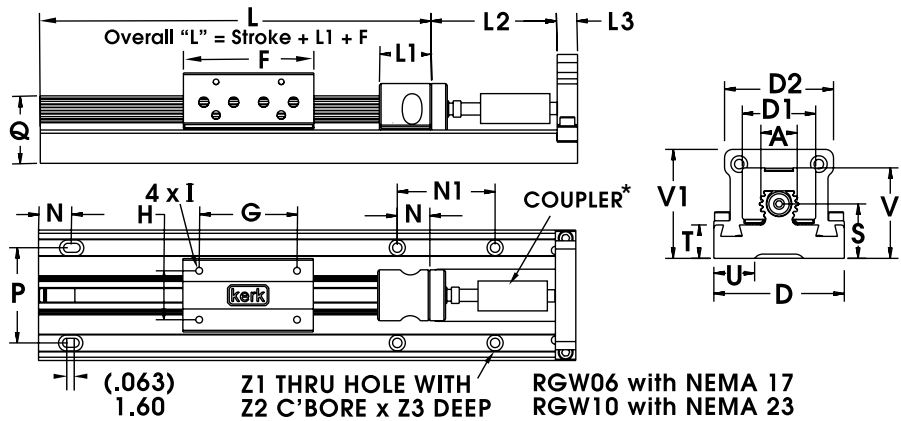
RGW10 Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	S	T	U	V	X	Y	Z1	Z2	Z3
inch	1.0	1.75	.312	3.38	2.0	3.3	2.25	1.25	1/4-20	1.9	1.3	1.3	.75	2.6	1.5	1.2	.69	1.3	2.1	.88	.28	.14	.40	.43
mm	25.4	44.5	7.93	85.7	50.8	83	57.1	31.7	UNC	48	33	33	19	66	39.6	31	17.5	33.8	54.6	22.4	7.11	6.6	10.2	10.9

*Metric carriage hole sizes available M3, M4, M5, M6.

Motor Mount for Non-Motorized with Lead Screw
Dimensional Drawings

- Motor Mount
- Screw Driven
- Wide Frame



Dimensions = inches (mm)

*NOTE: The coupling shown in the dimensional drawing is not included.

RGW10 Motor Mount, Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

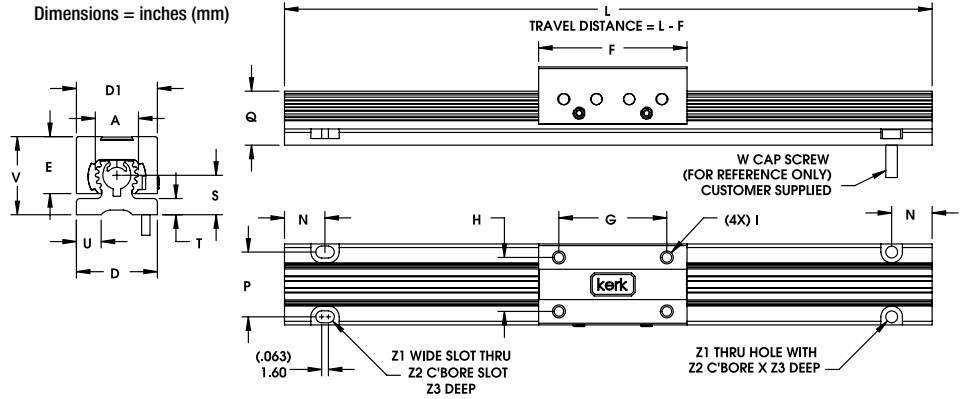
*Metric carriage hole sizes available M3, M4, M5, M6.

RGW10 Sensor Mount Kits

Sensor mounting kits based on U-channel optical sensor. Each kit includes one flag, three sensor mounts and all mounting hardware. Sensors are not included in the kit and must be ordered separately from sensor manufacturer.
Part # RGW10SK

Non-Motorized without Lead Screw
Dimensional Drawings

- Without Guide Screw
- Standard Frame



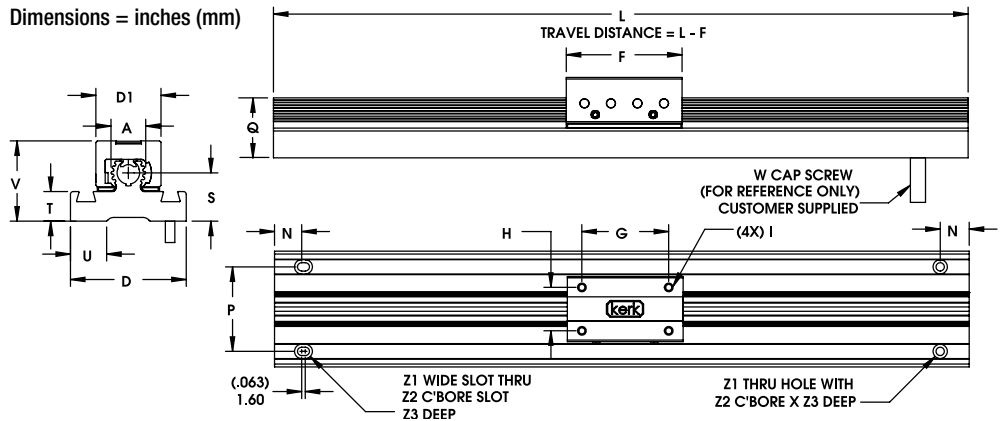
RGS10 Non-Motorized, Without Screw Driven

	A	D	D1	E	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	1.0	2.0	2.0	1.32	3.3	2.25	1.25	1/4-200	.75	1.5	1.25	.92	.375	.64	1.83	.26	.50	.22
mm	25.4	50.8	50.8	33.5	83	57.1	31.7	UNC	19	38.1	31.8	14	9.5	16.3	46.5	6.6	12.7	5.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized without Lead Screw
Dimensional Drawings

- Without Guide Screw
- Wide Frame



RGW10 Wide Series, Non-Motorized, Without Screw Driven

	A	D	D1	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	1.0	3.38	2.0	3.3	2.25	1.25	1/4-200	.75	2.6	1.5	1.2	.69	1.3	2.15	.26	.40	.43
mm	25.4	85.7	50.8	83	57.1	31.7	UNC	19	66	39.6	31	17.5	33.8	54.6	6.6	10.2	10.9

*Metric carriage hole sizes available M3, M4, M5, M6.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers, Kerkite Polymers are formulated to provide optimum performance in its target conditions and applications.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris. Kerkote differs from conventional plating and coating because it is soft, more evenly distributed than other lubricants, and decreases erratic drag torques and unpredictable wear.

- Reduces friction
- Cost effective
- Long term and maintenance free

Kerkote provides the maximum level of self-lubrication, requiring no additional external lubrication or maintenance.

RGW10 Non-Motorized Linear Rails

- Screw driven linear rails in wide format
- Linear rails without screw in wide format

The non-motorized RGW Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 100 lbs (445 N).

RGW10 Wide Series,
Non-Motorized
Screw Driven Linear Rail



To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the Non-Motorized RGW Part Numbers when Ordering

RG	W	10	K	A	0500	XXX
Prefix	Frame Style	Frame Size Load	Coating	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
RG = Rapid Guide Screw	W = Wide Sensor Mount Capability	10 = 100 lbs (445 N) (Maximum static load)	K = TFE Kerkote	A = None B = Inline Screw Motor Mount	0000 = No Screw 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

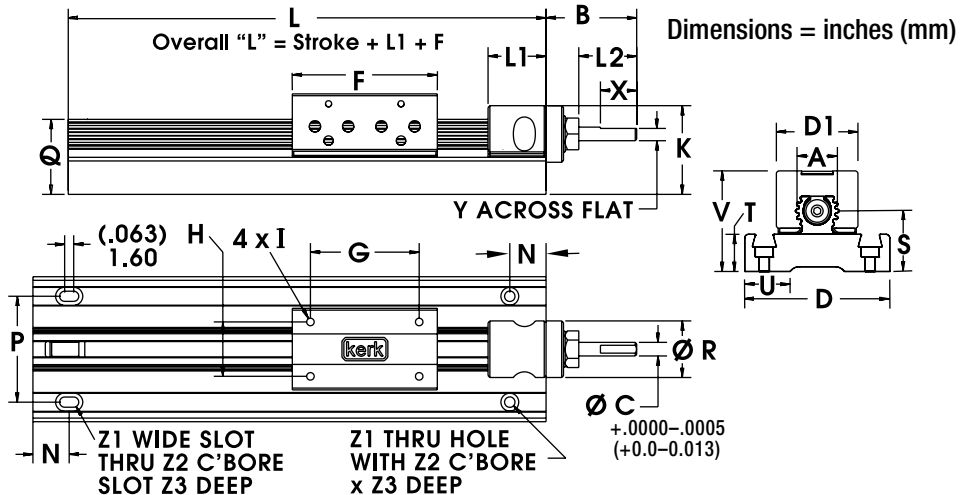
	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
RGW10 Non-Motorized with Lead Screw	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100	1.0 (25.4)	5/8 (15.9)	5.0 (0.4)	100,000,000 (254,000,000)	1.3 (.020)	100 (445)	14.2 x 10 ⁻⁵ (3.9 x 10 ⁻⁶)
	.200 (5.08)	0200			6.5 (.05)		2.0 (.031)		
	.500 (12.70)	0500			7.0 (.05)		3.0 (.047)		
1.000 (25.40)	1000	8.5 (.06)			6.5 (.101)				

NOTE: RGW assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw Dimensional Drawings

- Screw Driven
- Wide Frame



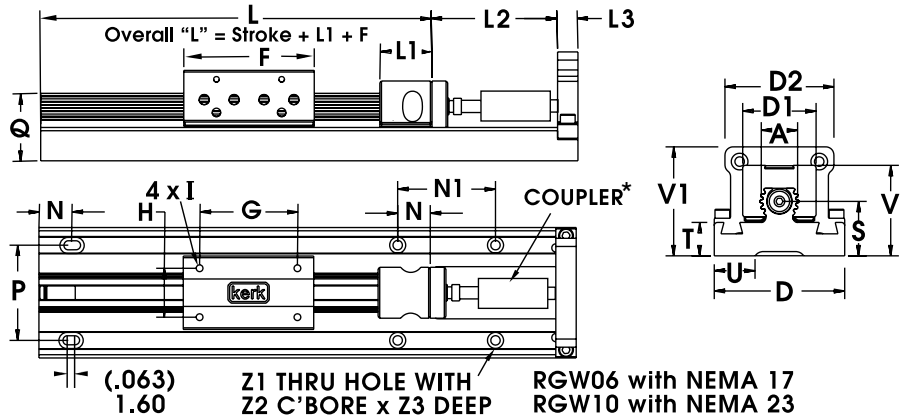
RGW10 Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	S	T	U	V	X	Y	Z1	Z2	Z3
inch	1.0	1.75	.312	3.38	2.0	3.3	2.25	1.25	1/4-20	1.9	1.3	1.3	.75	2.6	1.5	1.2	.69	1.3	2.1	.88	.28	.14	.40	.43
mm	25.4	44.5	7.93	85.7	50.8	83	57.1	31.7	UNC	48	33	33	19	66	39.6	31	17.5	33.8	54.6	22.4	7.11	6.6	10.2	10.9

*Metric carriage hole sizes available M3, M4, M5, M6.

Motor Mount for Non-Motorized with Lead Screw Dimensional Drawings

- Motor Mount
- Screw Driven
- Wide Frame



Dimensions = inches (mm) *NOTE: The coupling shown in the dimensional drawing is not included.

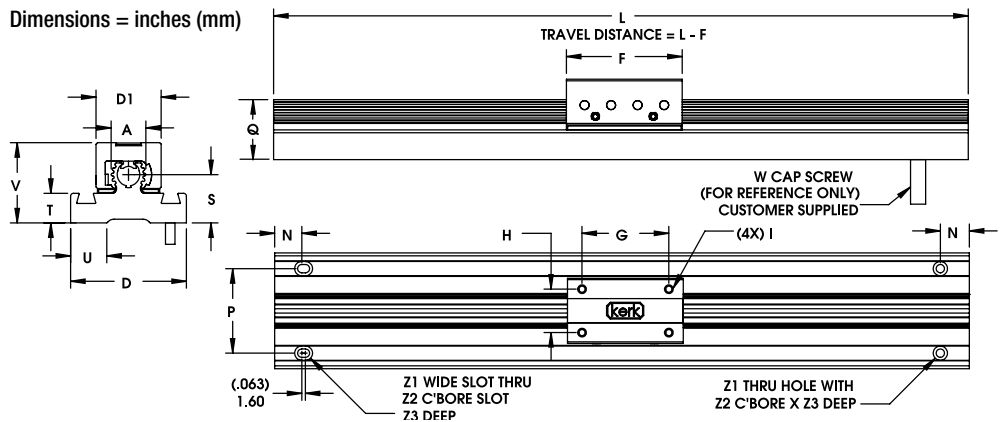
RGW10 Motor Mount, Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	D1	F	G	H	I*	K	L1	L2	N	P	Q	R	S1	T	U	V	X	Y	Z1	Z2	Z3
inch	0.60	1.25	.1875	2.0	1.13	2.0	1.50	0.750	6-32	1.2	.80	.80	.50	1.46	1.04	.80	.83	.51	.63	1.4	.50	.170	.14	.25	.14
mm	15.2	31.8	4.762	50.8	28.6	50.8	38.1	19.1	UNC	30	20.3	20.3	12.7	37.0	26.4	20.3	21.2	13.0	16.0	36	12.7	4.32	3.6	6.4	3.6

*Metric carriage hole sizes available M3, M4, M5, M6.

Non-Motorized without Lead Screw Dimensional Drawings

- Without Guide Screw
- Wide Frame



RGW10 Wide Series, Non-Motorized, Without Screw Driven

	A	D	D1	F	G	H	I*	N	P	Q	S	T	U	V	Z1	Z2	Z3
inch	1.0	3.38	2.0	3.3	2.25	1.25	1/4-200	.75	2.6	1.5	1.2	.69	1.3	2.15	.26	.40	.43
mm	25.4	85.7	50.8	83	57.1	31.7	UNC	19	66	39.6	31	17.5	33.8	54.6	6.6	10.2	10.9

*Metric carriage hole sizes available M3, M4, M5, M6.

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris.

- Reduces friction
- Cost effective
- Requires no additional external lubrication or maintenance

Accessory

RGW10 Sensor Mount Kits

Sensor mounting kits based on U-channel optical sensor. Each kit includes one flag, three sensor mounts and all mounting hardware. Sensors are not included in the kit and must be ordered separately from sensor manufacturer. Part # RGW10SK

WGS06 Linear Rails with 43000 Series Hybrid Motor

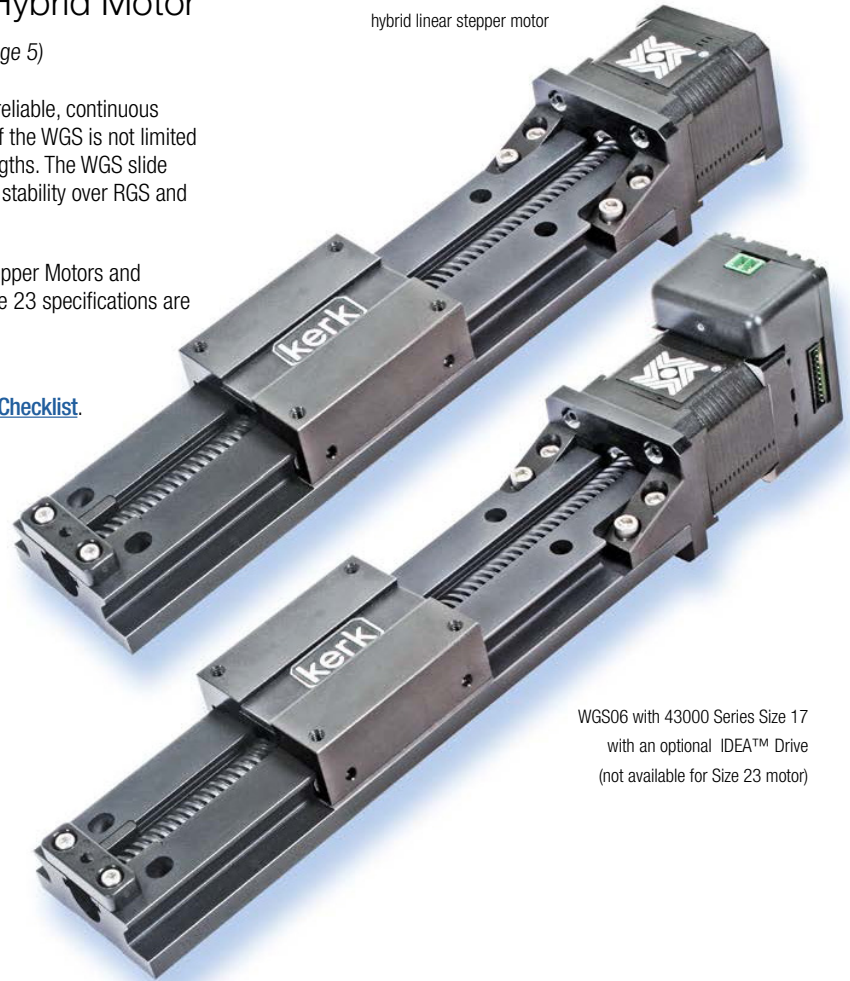
*Also available with 57000 Series Hybrid Motor (info available starting on page 5)

The Motorized WGS Linear Slide utilizes a screw-driven carriage that offers reliable, continuous linear speed while maintaining accurate positioning. The length and speed of the WGS is not limited by critical screw speed, allowing high RPM, linear speed and long stroke lengths. The WGS slide has a unique, compact profile that provides improved torsional stiffness and stability over RGS and RGW products.

Technical specifications for 43000 Series Size 17 Hybrid Linear Actuator Stepper Motors and Haydon Kerk IDEA™ programmable drives are on page 3, 57000 Series Size 23 specifications are on page 5.

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

WGS06 with 43000 Series Size 17 hybrid linear stepper motor



WGS06 with 43000 Series Size 17 with an optional IDEA™ Drive (not available for Size 23 motor)

Identifying the WGS06 Part Number Codes when Ordering

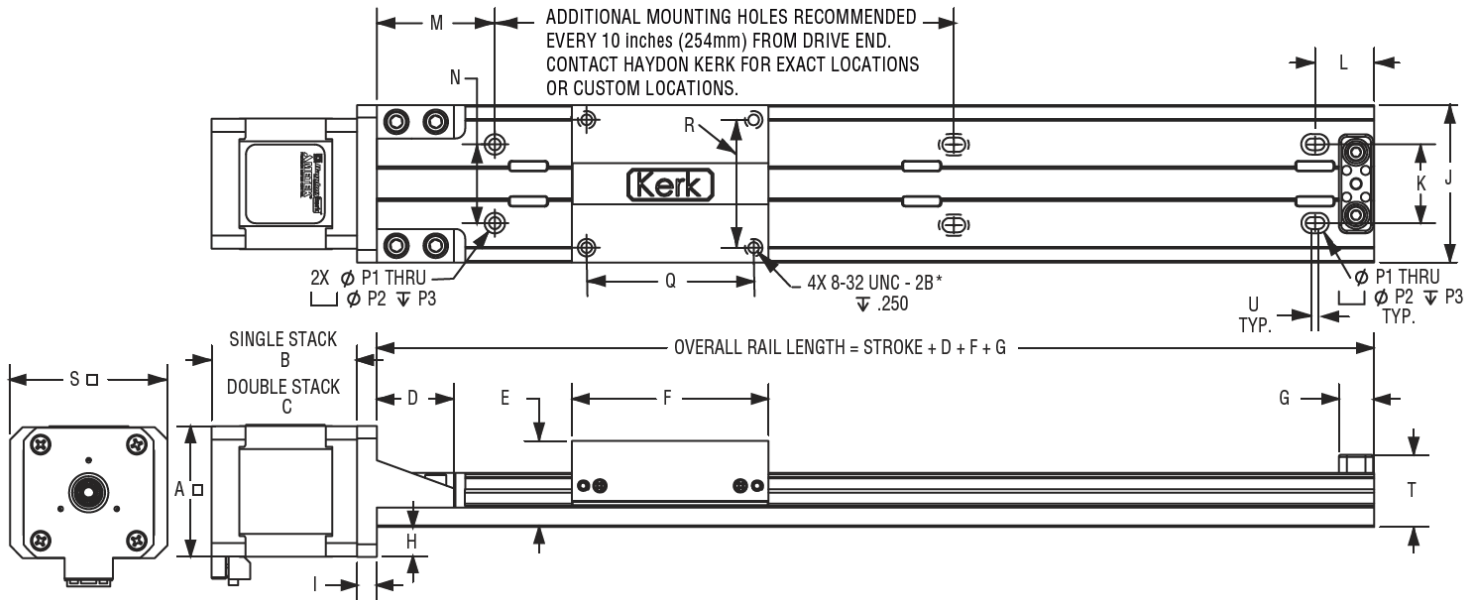
WG	S	06	K	G	0100	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
WG = Wide Guide Screw	S = Standard	06 = 35 lbs (156 N) (Maximum static load)	K = TFE Kerkote®	M = Motorized G = Motorized + IDEA™ integrated programmable drive – USB communications J = Motorized + IDEA™ integrated programmable drive – RS485 communications	0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (25.4)	– M43 = 43000 Series-Size 17 Motor – G43 = 43000 Series Size 17 Motor with IDEA Drive – M57 = 57000 Series-Size 23 Motor – or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M4, M5, M6

■ WGS06 Linear Slide with 43000 Series Size 17 Linear Actuator

Recommended for horizontal loads up to 35 lbs (156 N)



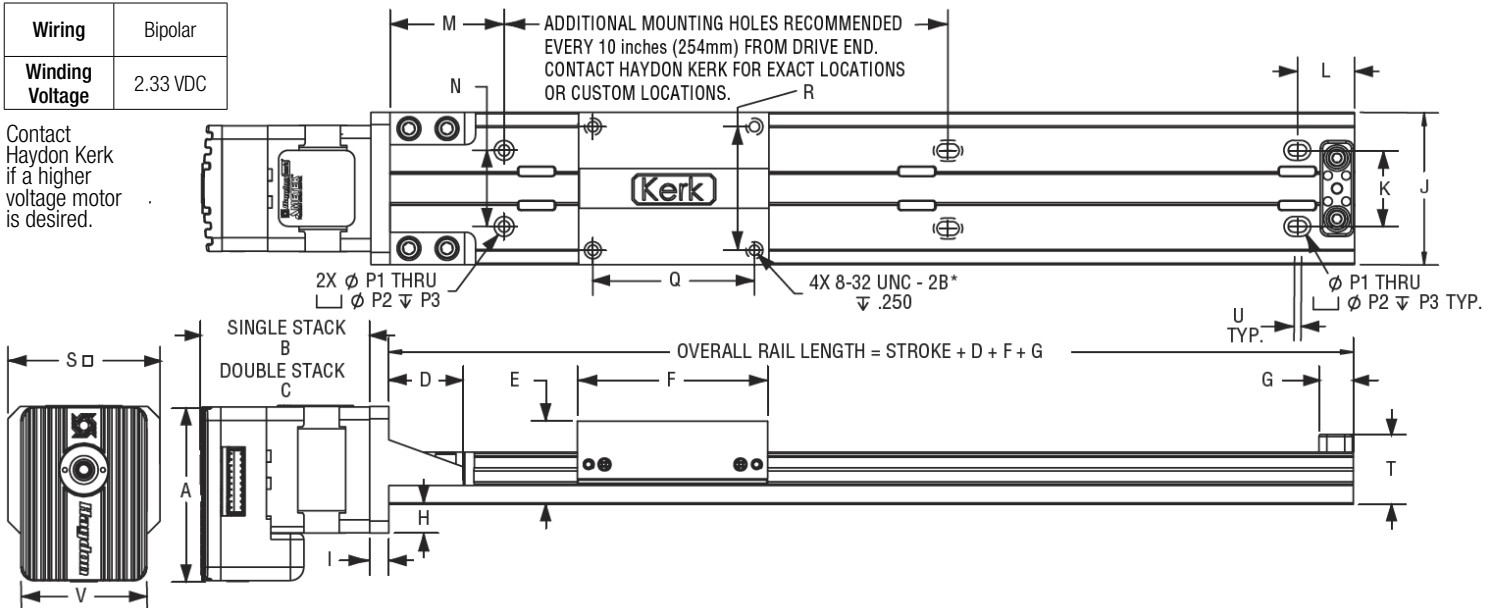
	A	B	C	D	E	F	G	H	I	J	K	L	M	N	P1	P2	P3	Q	R	S	T	U
(mm)	(42.2)	(33.8)	(47.75)	(24.9)	(27.9)	(63.5)	(11.2)	(9.7)	(6.4)	(50.8)	(25.4)	(19.1)	(38.1)	(25.4)	(3.81)	(6.60)	(6.50)	(53.95)	(41.25)	(50.8)	(23.3)	(2.3)
inch	1.660 MAX.	1.330 MAX.	1.880 MAX.	0.98	1.1	2.50	0.44	0.38	0.250	2.00	1.000	0.75	1.50	1.000	0.150	0.260	0.256	2.124	1.624	2.00	0.92	0.090

* Metric threads also available for carriage.

...with IDEA™ Drive

Wiring	Bipolar
Winding Voltage	2.33 VDC

Contact Haydon Kerk if a higher voltage motor is desired.



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	P1	P2	P3	Q	R	S	T	U	V
(mm)	(58.0)	(63.72)	(77.67)	(24.9)	(27.9)	(63.5)	(11.2)	(9.7)	(6.4)	(50.8)	(25.4)	(19.1)	(38.1)	(25.4)	(3.81)	(6.60)	(6.50)	(53.95)	(41.25)	(50.8)	(23.3)	(2.3)	(42.0)
inch	2.283 MAX.	2.509 MAX.	3.058 MAX.	0.98	1.1	2.50	0.44	0.38	0.250	2.00	1.000	0.75	1.50	1.000	0.150	0.260	0.256	2.124	1.624	2.00	0.92	0.090	1.66

* Metric threads also available for carriage.

Single Stack

43000 Series Size 17

Size 17: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
Programmable Drive	IDEA Drive option available			Not applicable	
Winding Voltage	2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	1.5 A	700 mA	290 mA	700 mA	290 mA
Resistance/phase	1.56 Ω	7.2 Ω	41.5 Ω	7.2 Ω	41.5 Ω
Inductance/phase	1.9 mH	8.7 mH	54.0 mH	4.4 mH	27.0 mH
Power Consumption	7 W				

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Nominal Thread Lead		Lead Code
inches	mm	
0.1	2.54	0100
0.2	5.08	0200
0.5	12.7	0500
1.0	25.4	1000



43000 Series Size 17
Single Stack External Linear

Double Stack

43000 Series Size 17

Size 17 Double Stack: 43 mm (1.7-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
Programmable Drive	IDEA Drive option available		
Winding Voltage	2.33 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.6 A	1.3 A	550 mA
Resistance/phase	0.9 Ω	3.8 Ω	21.9 Ω
Inductance/phase	1.33 mH	8.21 mH	45.1 mH
Power Consumption	13.2 W		

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.

Nominal Thread Lead		Lead Code
inches	mm	
0.1	2.54	0100
0.2	5.08	0200
0.5	12.7	0500
1.0	25.4	1000

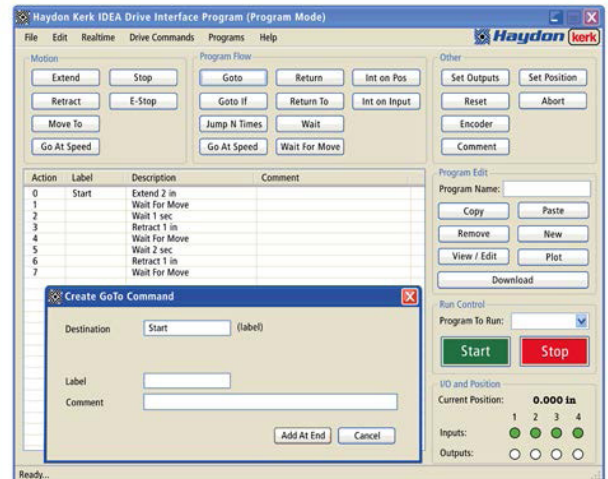


Size 17 External Linear
with programmable IDEA Drive

IDEA™ Drive software is simple to use with on-screen buttons and easy-to-understand programming guides.

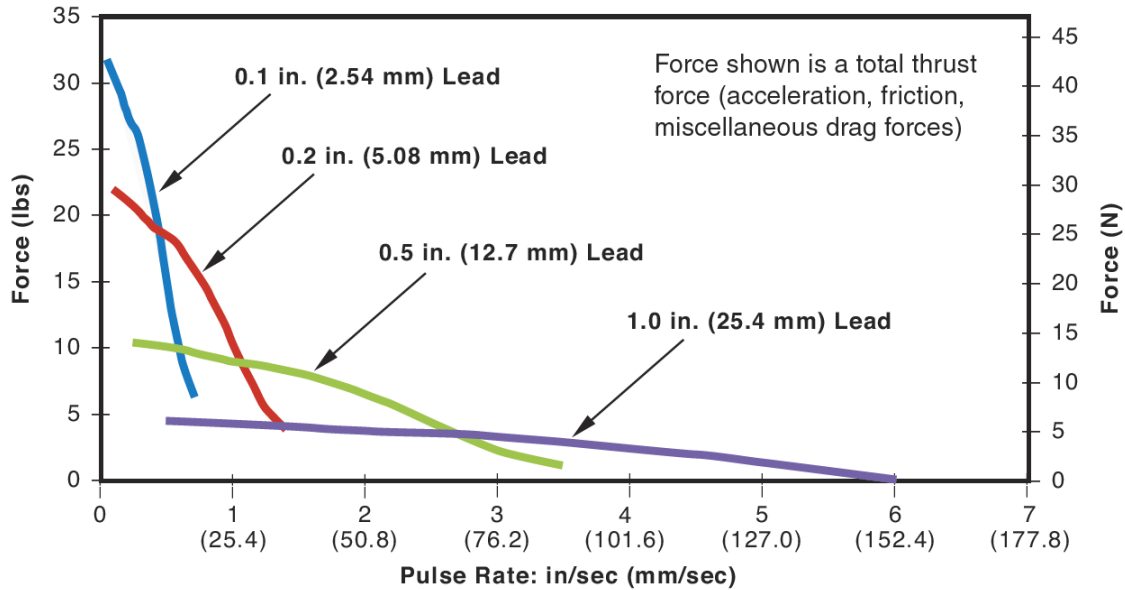
- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability – Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

For more information see the [IDEA™ Drive Data Sheet](#)



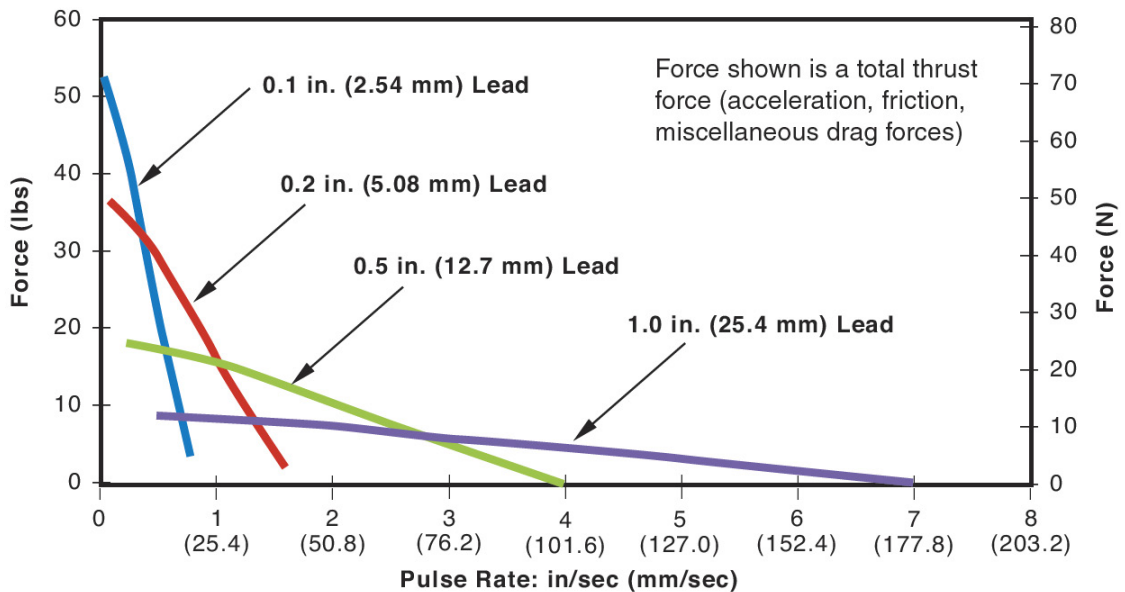
Single Stack

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



Double Stack

FORCE vs. PULSE RATE
- Chopper - Bipolar - 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

Single Stack

57000 Series Size 23

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Nominal Thread Lead		Lead Code
inches	mm	
0.1	2.54	0100
0.2	5.08	0200
0.5	12.7	0500
1.0	25.4	1000



Size 23
Single Stack
External Linear

Double Stack

57000 Series Size 23

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
	3.25 VDC	5 VDC	12 VDC
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		

Nominal Thread Lead		Lead Code
inches	mm	
0.1	2.54	0100
0.2	5.08	0200
0.5	12.7	0500
1.0	25.4	1000

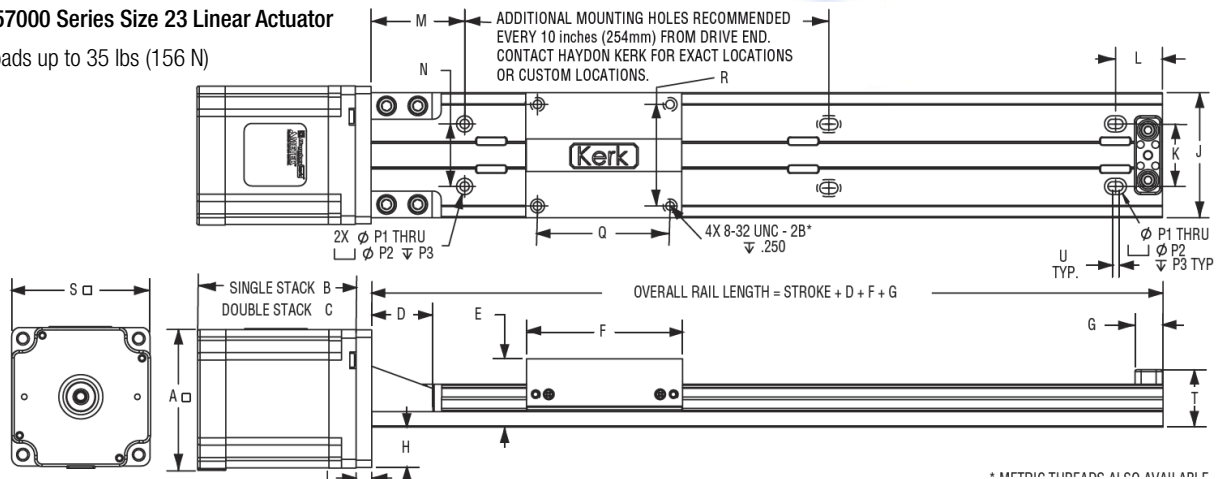


Size 23
Double Stack
External Linear

WGS Series • WGS06 Motorized • Size 23 57000 Series • Dimensional Drawings

WGS06 Linear Slide with 57000 Series Size 23 Linear Actuator

Recommended for horizontal loads up to 35 lbs (156 N)

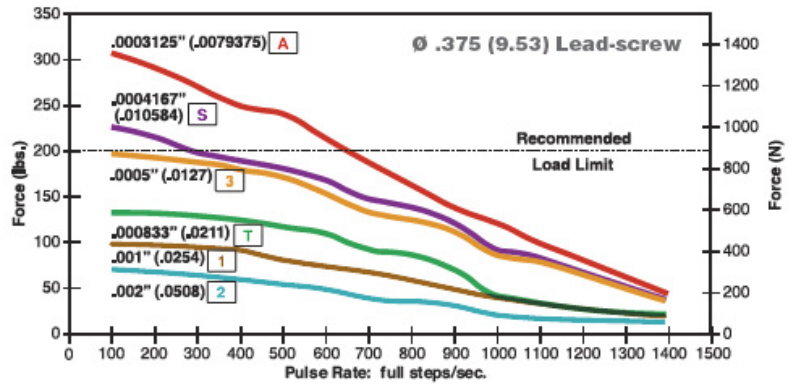


	A	B	C	D	E	F	G	H	I	J	K	L	M	N	P1	P2	P3	Q	R	S	T	U
(mm)	(56.4)	(45.2)	(66)	(24.9)	(27.9)	(63.5)	(11.2)	(16.5)	(6.4)	(50.8)	(25.4)	(19.1)	(38.1)	(25.4)	(3.81)	(6.60)	(6.50)	(53.95)	(41.25)	(56.4)	(23.3)	(2.3)
inch	2.220 MAX.	1.780 MAX.	2.598 MAX.	0.98	1.1	2.50	0.44	0.65	0.250	2.00	1.000	0.75	1.50	1.000	0.150	0.260	0.256	2.124	1.624	2.220 MAX.	0.92	0.090

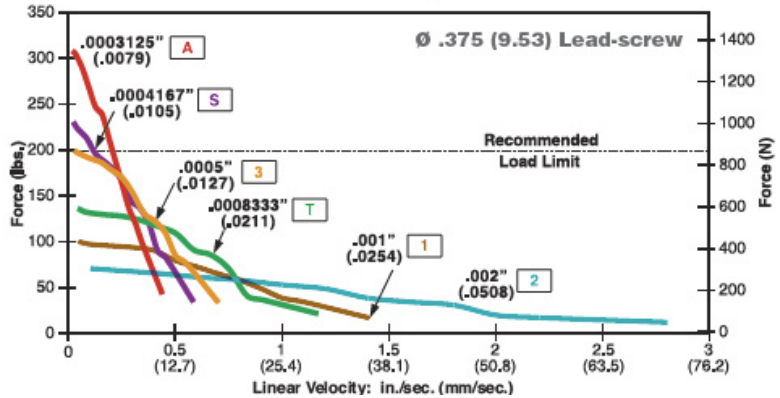
* Metric threads also available for carriage.

Single Stack

FORCE vs. PULSE RATE
– Chopper – Bipolar – 100% Duty Cycle

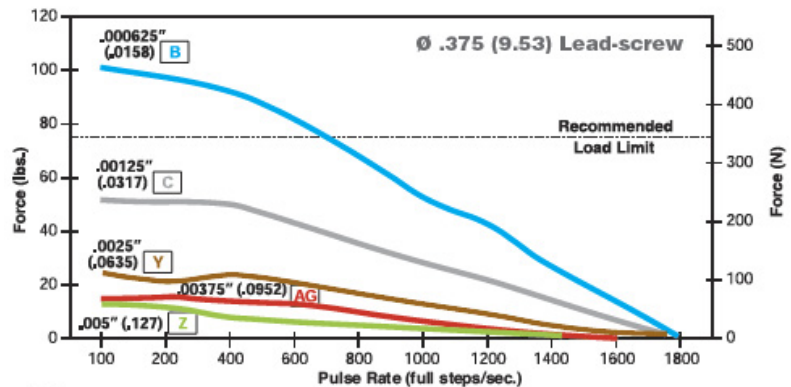


FORCE vs. LINEAR VELOCITY
– Chopper – Bipolar – 100% Duty Cycle

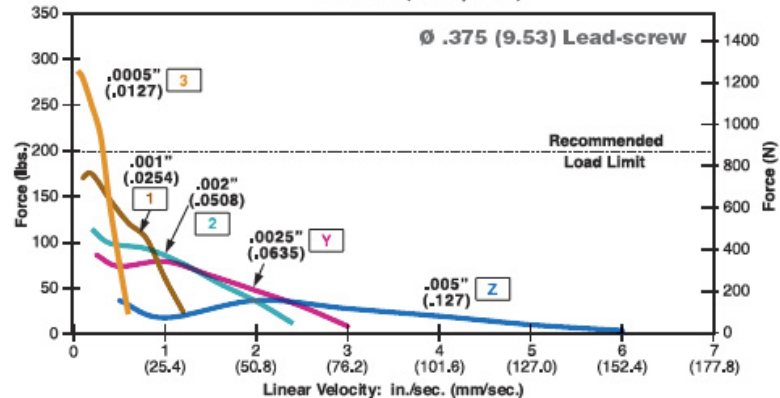


Double Stack

FORCE vs. PULSE RATE
– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
– Chopper – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

43000 Series Size 17 and 57000 Series Size 23

Hybrids: Stepping Sequence

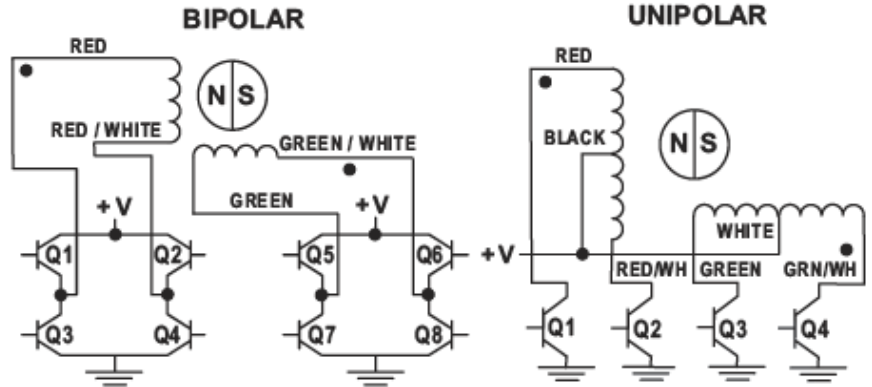
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

EXTEND CW
↓

↑
RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Hybrids: Wiring



Size 17 43000 Series • Integrated Connectors

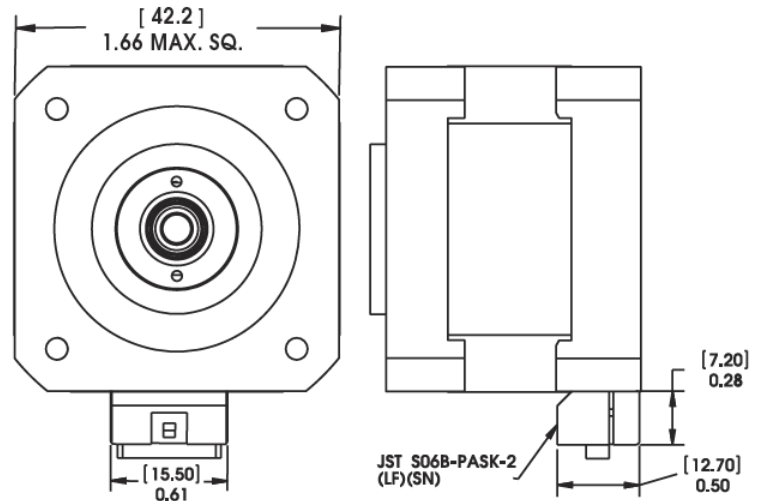
Haydon Kerk Hybrid Size 17 Single and Double Stack linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre existing harnesses. In addition to standard configurations, Haydon Kerk Motion Solutions can custom design this motor to meet your specific application requirements.



Dimensional Drawings

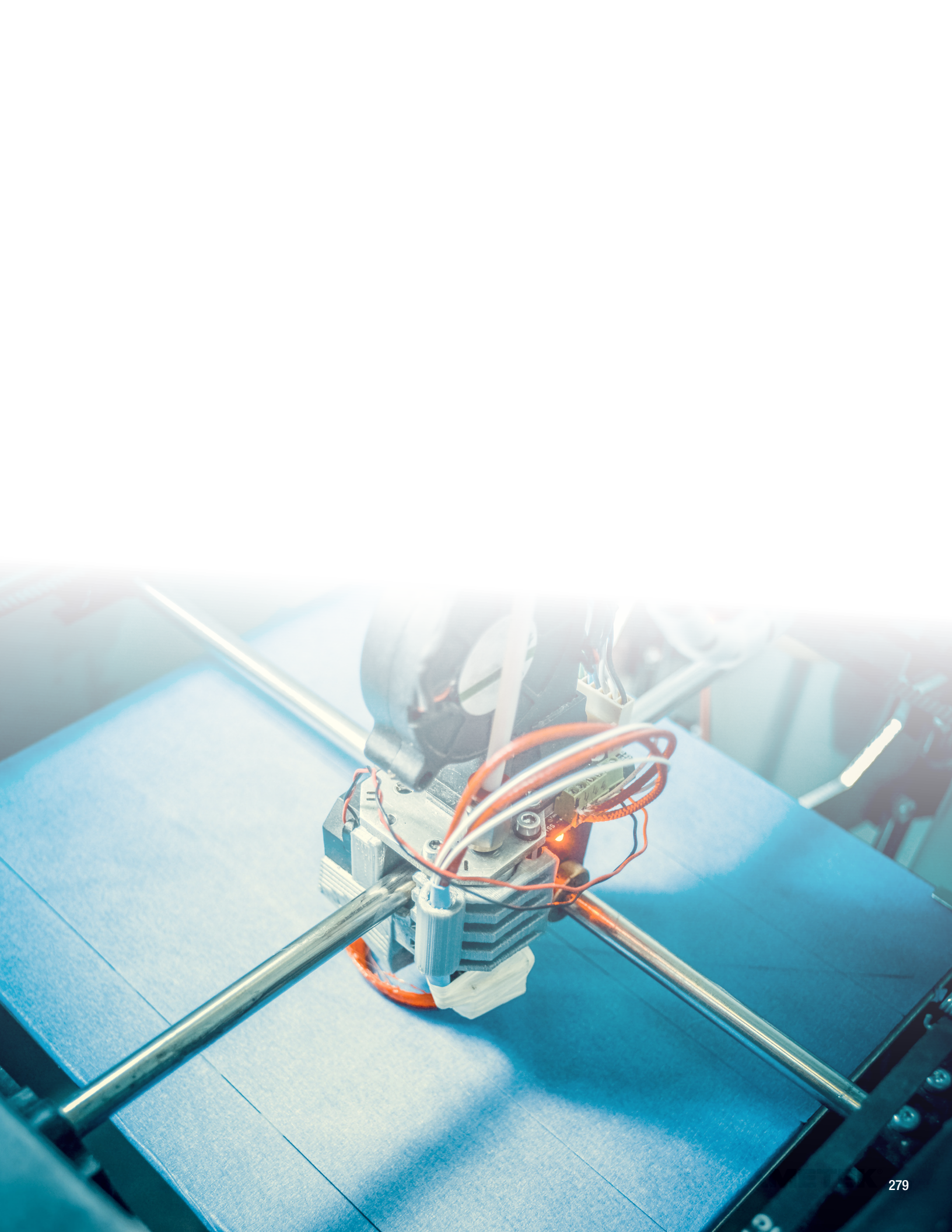
Integrated Connector with 43000 Series Size 17

Dimensions = (mm) inches



- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk Part #56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part number SPHD-001T-P0.5

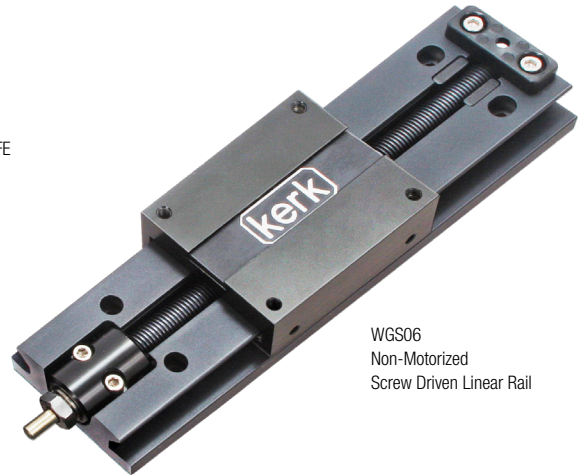
Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red



WGS06 Non-Motorized Linear Rails

• **Wide, low profile screw driven linear rails**

The non-motorized WGS Series features standard wear compensating, anti-backlash driven carriages to ensure repeatable and accurate positioning. All moving surfaces include Kerkite® engineered polymers running on Kerkote® TFE coating, providing a strong, stable platform for a variety of linear motion applications. Recommended for horizontal loads up to 35 lbs (156 N).



WGS06
Non-Motorized
Screw Driven Linear Rail

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the Non-Motorized WGS Part Numbers when Ordering

WG	S	06	K	A	0100	XXX
Prefix WG = Wide Guide Screw	Frame Style S = Standard	Frame Size Load 06 = 35 lbs (156 N) (Maximum static load)	Coating K = TFE Kerkote	Drive / Mounting A = None B = Inline Screw Motor Mount	Nominal Thread Lead Code 0100 = .100-in (2.54) 0200 = .200-in (5.08) 0500 = .500-in (12.70) 1000 = 1.000-in (2.54)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Specifications

	Inch Lead	Thread Lead Code	Nominal Rail Diam.	Nominal Screw Diam.	Typical Drag Torque	Life @ 1/4 Design Load*	Torque-to-Move Load	Design Load*	Screw Inertia
WGS06 Non-Motorized with Lead Screw	inch (mm)		inch (mm)	inch (mm)	oz - in (N-m)	inch (cm)	oz-inc/lb (Nm/Kg)	lbs (N)	oz-in-sec ² /in (kg-m-sec ² /m)
	.100 (2.54)	0100		3/8 (9.5)	4.0 (0.3)	100,000,000 (254,000,000)	1.0 (.016)	35 (156)	1.5 x 10 ⁻⁵ (4.2 x 10 ⁻⁶)
	.200 (5.08)	0200	5.0 (.04)		1.5 (.023)				
	.500 (12.70)	0500	6.0 (.04)		2.5 (.039)				
1.000 (25.40)	1000	7.0 (.05)	4.5 (.070)						

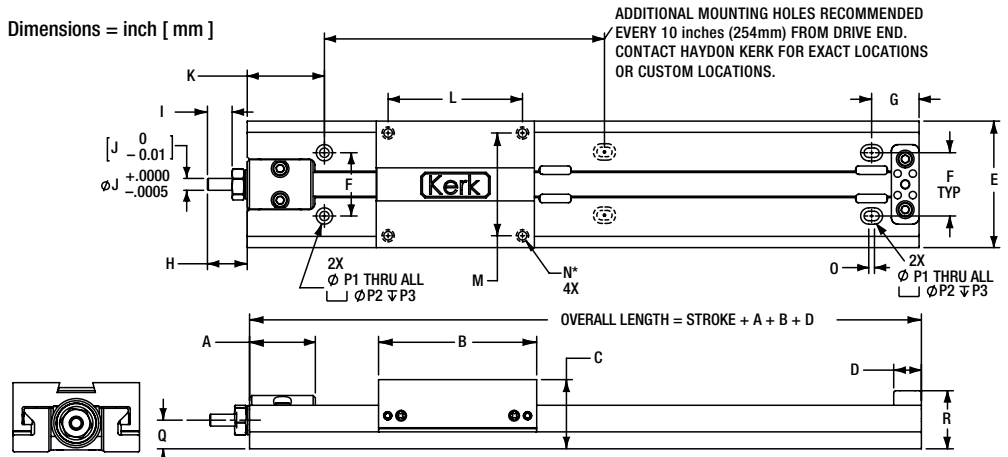
NOTE: WGS assemblies with lengths over 36 inches (914.4 mm) and/or leads higher than .5 inch (12.7 mm) will likely have higher drag torque than listed values.

*Determined with load in a horizontal position.

Non-Motorized with Lead Screw
Dimensional Drawings

- Screw Driven
- Wide Frame

Dimensions = inch [mm]



WGS06 Wide Series, Non-Motorized, Screw Driven

	A	B	C	D	E	F	G	H	I	J	K	L	M	N*	O	P1	P2	P3	Q	R
inch	1.0	2.5	1.1	.44	2.0	1.0	.75	.63	.39	.187	1.2	2.1	1.62	8-32	.09	.15	.26	.256	.45	.92
mm	25.4	63.5	28	11.2	50.8	25.4	19.1	16	9.9	4.76	39.9	53.9	41.2	UNC-2B	2.3	3.8	6.6	6.5	11.4	23.3

*Metric carriage hole sizes available M3, M4, M5, M6.

Material Coatings

Kerkite® Polymers

Compounded with lubricants, reinforcements and thermoplastic polymers, Kerkite Polymers are formulated to provide optimum performance in its target conditions and applications.

- Injection molded
- High performance
- Exceptional wear properties

Kerkote® TFE Coating

A dry lubricant, Kerkote will not become dry and paste-like, and does not attract dirt or debris. Kerkote differs from conventional plating and coating because it is soft, more evenly distributed than other lubricants, and decreases erratic drag torques and unpredictable wear.

- Reduces friction
- Cost effective
- Long term and maintenance free

Kerkote provides the maximum level of self-lubrication, requiring no additional external lubrication or maintenance.

LRS04 Motorized Linear Rails with 43000 Series

The LRS Linear Rail System in a variety of configurations, both motorized and non-motorized. These precision linear rail systems consist of a stationary base and a load bearing carriage that travels along a rigid extruded aluminum rail. The LRS Linear Rail System is available with several in-line motor options including a single stack or double stack size 17 stepper motor, a stepper motor with an integral chopper drive, or the IDEA™ programmable linear actuator, consisting of the stepper motor, drive, and controller programmed through a graphic user interface (GUI). The LRS is also available without a motor, easily allowing the designer flexibility to integrate with a variety of motor types and belt and pulley configurations.

Key Product Features

- “T” slots integrated into exterior rail bottom and sides that accommodate full length support and various mounting options.
- Loads easily attach to the compact, moving carriage with four or six M4 x 0.7 size screws.
- Load bearing carriage moves efficiently and smoothly within the internal rail geometry of this specially designed aluminum extrusion.
- Rail provides end-to-end axial stability and precise motion system accuracy.
- Automatic adjustments of slide bearing play with a patent pending “anti-backlash” linear bearing.
- Rated life equals that of the existing lead-screws of similar size.
- Lead screw end configurations adapt to various rotary motion sources.
- Kerkote® or Black Ice® TFE coatings on a 303 stainless steel lead-screw.
- Designed to Metric global engineering standards.
- For extreme control, LRS can be used with CMP or WDG high-precision anti-backlash nuts, as well as a freewheeling general purpose nut.

LRS with Size 17
Double Stack Hybrid
Linear Actuator with
IDEA programmable
Drive and Black Ice®
TFE Lead-screw.



LRS with
Size 17
Double Stack
Hybrid Linear Actuator

LRS Non-Motorized

To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the LRS04 Part Number Codes when Ordering

LR	W	04	B	M	0025	XXX
Prefix	Frame Style	Frame Size Load*	Lubrication	Drive / Mounting	Nominal Thread Lead Code	Unique Identifier
LR = Linear Rail System (LRS)	B = BFW nut C = CMP nut W = WDG nut G = Guide only	04 = 50 lbs (222 N) (Maximum static load)	S = Uncoated B = Black Ice® TFE N = No screw	A = None M = Motorized 43000 Series Size 17 Hybrid G = Motor with IDEA™ integrated programmable drive - USB communications J = Motor with IDEA™ integrated programmable drive - RS485 communications	0000 = No screw 0025 = .25-in (.635) 0031 = .03125-in (.794) 0039 = .0394-in (1.0) 0050 = .05-in (1.27) 0063 = .0625-in (1.588) 0079 = .0787-in (2.0) 0100 = .01-in (2.54) 0125 = .125-in (3.175) 0197 = .1969-in (5.0) 0250 = .25-in (6.35) 0394 = .3937-in (10.0) 0500 = .5-in (12.7) 0750 = .75-in (19.05) 1000 = 1.0-in (25.4)	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Carriage holes available in Metric sizes M3, M4, M5, M6

■ LRS04 Linear Rail with 43000 Series Size 17 Linear Actuator

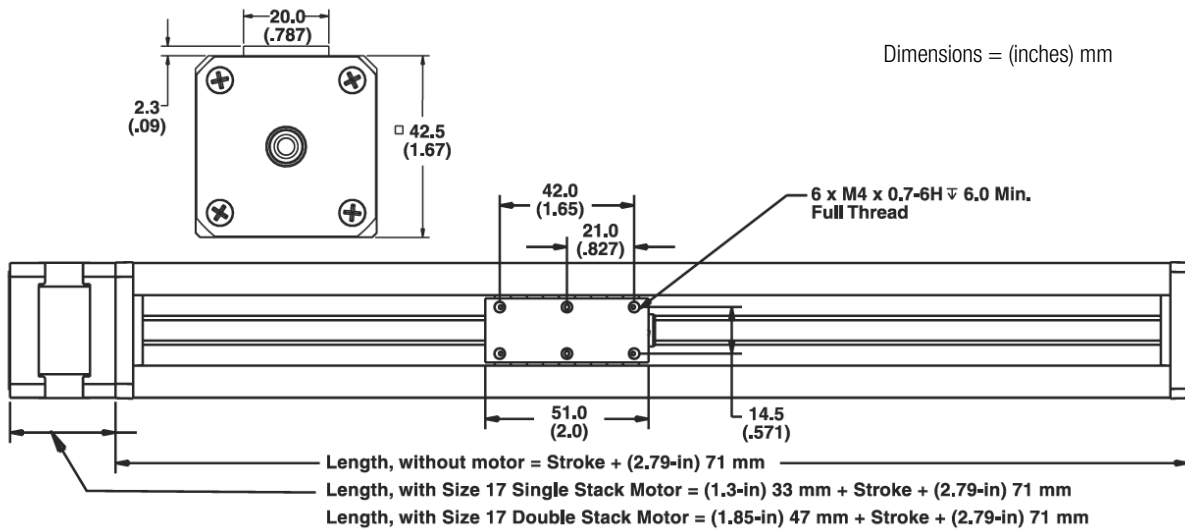
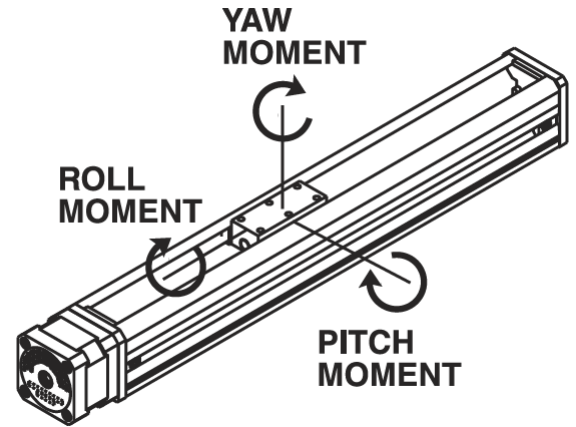
Recommended for horizontal loads up to 50 lbs (222 N)

Specifications

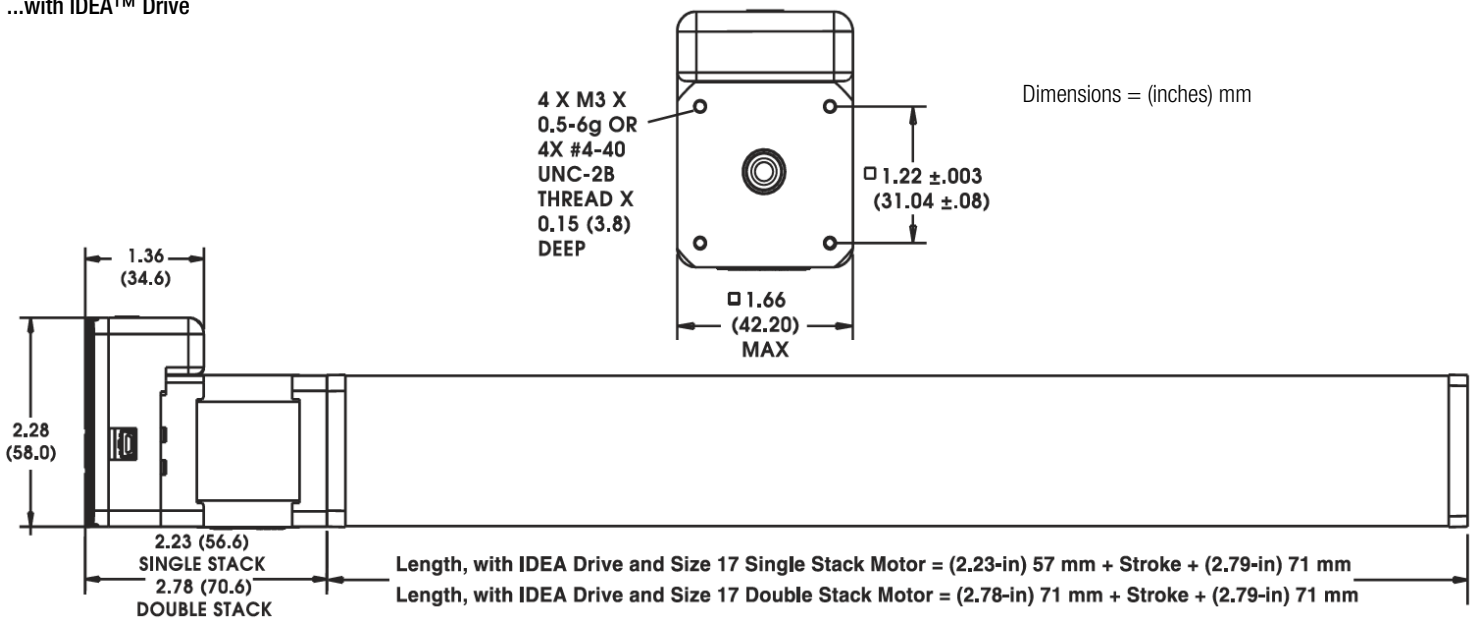
Width	Length of stroke (max)	Speed (max)	Straight line accuracy	Twist
1-5/8 in square (4.3 cm square)	40 in (1000 mm)	20 in/sec (0.5 M/sec)	+/- 0.012 in/ft (+/- 1.0 mm/M)	+/- 0.25° in/ft (+/- 0.75° /M)

Load Ratings (max)

Top load "Z" direction	Hanging / Gantry	Max. Pitch Moment	Max. Moment Roll	Max. Moment Yar
50 lbs. (225 N)	50 lbs. (225 N)	75 in - lbs (8.5 N - M)	75 in - lbs (8.5 N - M)	(8.5 N - M)



...with IDEA™ Drive



Single Stack

43000 Series Size 17

Size 23: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar			Unipolar**	
	Programmable Drive	IDEA Drive option available			Not applicable
Winding Voltage	3.25 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase	2.0 A	1.3 A	.54 A	1.3 A	.54 A
Resistance/phase	1.63 Ω	3.85 Ω	22.2 Ω	3.85 Ω	22.2 Ω
Inductance/phase	3.5 mH	10.5 mH	58 mH	5.3 mH	23.6 mH
Power Consumption	13 W				
Rotor Inertia	166 gcm ²				
Insulation Class	Class B (Class F available)				
Weight	18 oz (511 g)				
Insulation Resistance	20 MΩ				

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Double Stack

43000 Series Size 17

Size 23 Double Stack: 57 mm (2.3-in) Hybrid Linear Actuator (1.8° Step Angle)

Wiring	Bipolar		
	Programmable Drive	IDEA Drive option available	
Winding Voltage	3.25 VDC	5 VDC	12 VDC
Current (RMS)/phase	3.85 A	2.5 A	1 A
Resistance/phase	0.98 Ω	2.0 Ω	12.0 Ω
Inductance/phase	2.3 mH	7.6 mH	35.0 mH
Power Consumption	25 W Total		
Rotor Inertia	321 gcm ²		
Insulation Class	Class B (Class F available)		
Weight	32 oz (958 g)		
Insulation Resistance	20 MΩ		

* 43000 Series Single Stack with IDEA programmable drive. Contact Haydon Kerk if higher voltage motor is desired.

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Size 17
Single Stack
External Linear
with IDEA Drive



Size 17
Single Stack
External Linear

IDEA™ Drive software is simple to use with on-screen buttons and easy-to-understand programming guides.

- Fully Programmable
- RoHS Compliant
- USB or RS-485 Communication
- Microstepping Capability – Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64
- Graphic User Interface
- Auto-population of Drive Parameters
- Programmable Acceleration/Deceleration and Current Control

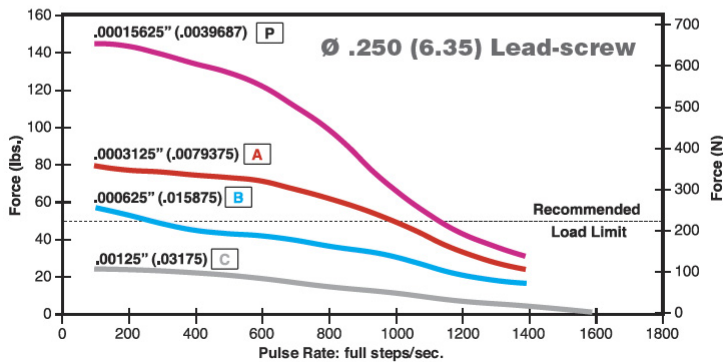
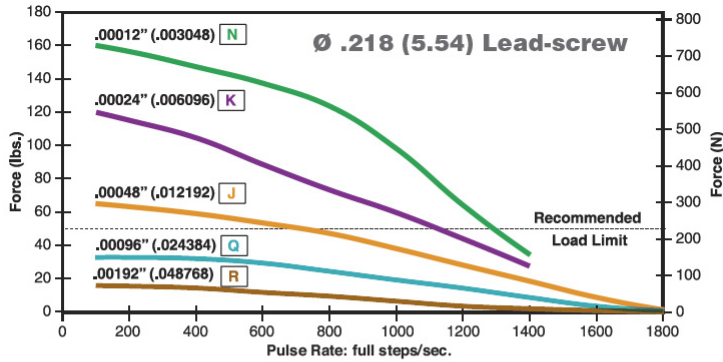
For more information see the [IDEA™ Drive Data Sheet](#)

Size 17
Double Stack
External Linear

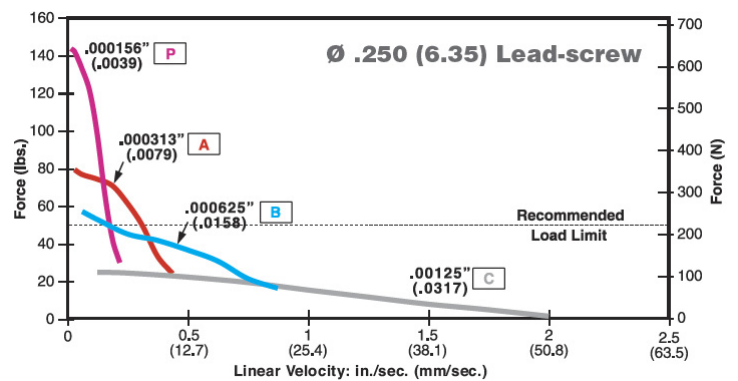
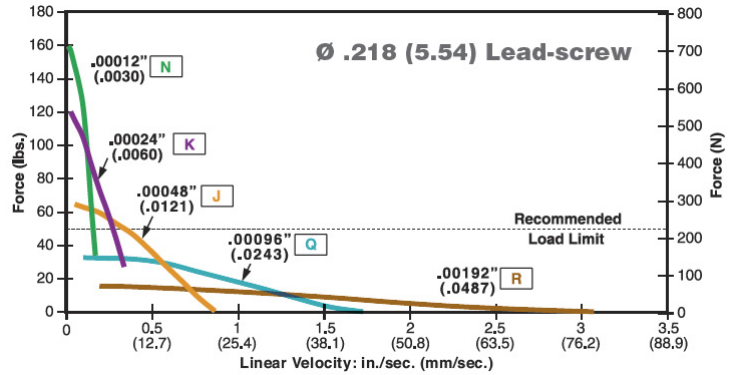


Single Stack

FORCE vs. PULSE RATE
– Chopper – Bipolar – 100% Duty Cycle

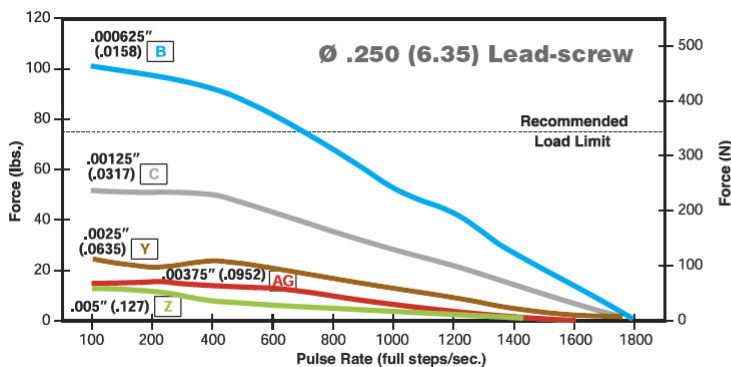


FORCE vs. LINEAR VELOCITY
– Chopper – Bipolar – 100% Duty Cycle

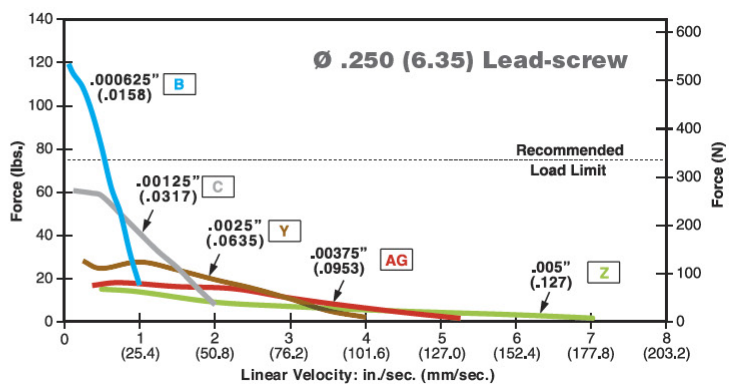


Double Stack

FORCE vs. PULSE RATE
– Chopper – Bipolar – 100% Duty Cycle



FORCE vs. LINEAR VELOCITY
– Chopper – Bipolar – 100% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction

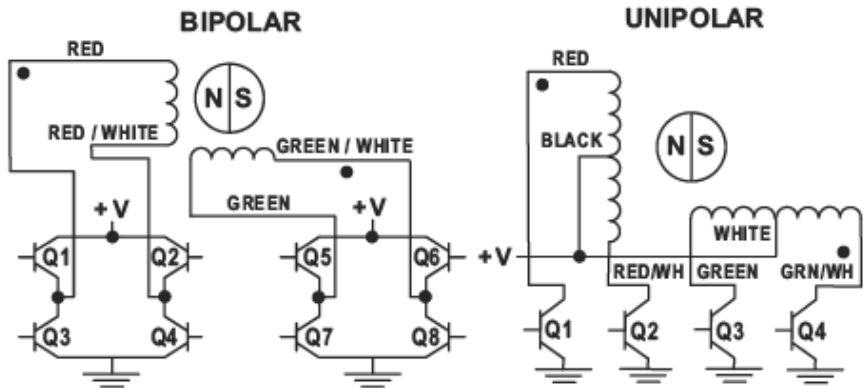
43000 Series Size 17

Hybrids: Stepping Sequence

Hybrids: Wiring

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Unipolar	Q1	Q2	Q3	Q4
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

Note: Half stepping is accomplished by inserting an off state between transitioning phases.



Size 17 43000 Series • Integrated Connectors

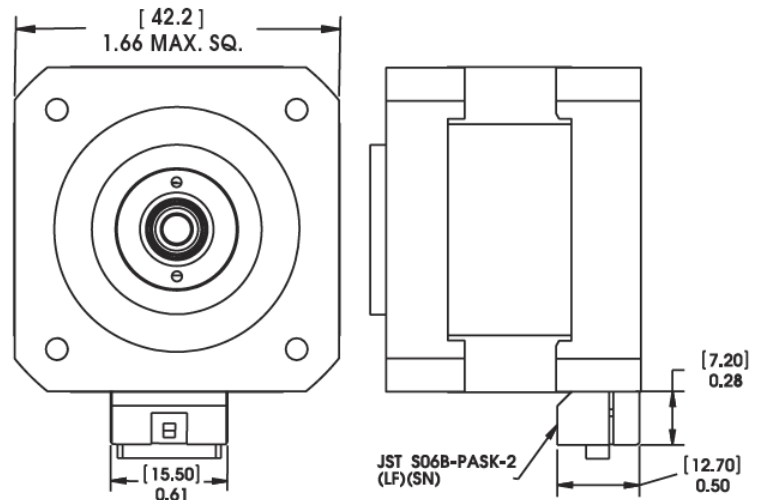
Hybrid Size 17 linear actuators are available with an integrated connector. Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. This motor is ideal for those that want to plug in directly to pre existing harnesses. In addition to standard configurations, Haydon Kerk Motion Solutions can custom design this motor to meet your specific application requirements.



Dimensional Drawings

Integrated Connector with 43000 Series Size 17

Dimensions = (mm) inches



- Motor Connector:** JST part # S06B-PASK-2
- Mating Connector:** JST part # PAP-06V-S
Haydon Kerk Part #56-1210-5 (12 in. Leads)
- Wire to Board Connector:** JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	-
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	-
6	Phase 1 Start	Phase 1 Start	Red

LRS04 Non-Motorized Linear Rails

- T-slots integrated into exterior rail bottom and sides that accommodate full length support and various mounting options

The non-motorized LRS Linear Rail System consists of a stationary base and a load-bearing carriage that travels along a rigid extruded aluminum rail. Easily allows flexibility to integrate with a variety of motor types, belt and pulley configurations.

Also available with several inline motor options, including a single stack or double stack Size 17 stepper motor, with or without a programmable IDEA™ Drive.

For extreme loads, the LRS04 can be used with CMP or WDG high precision anti-backlash nuts, as well as a freewheeling general purpose nut.



LRS04
Non-Motorized
Shown with Black Ice™ TFE Coated Lead Screw

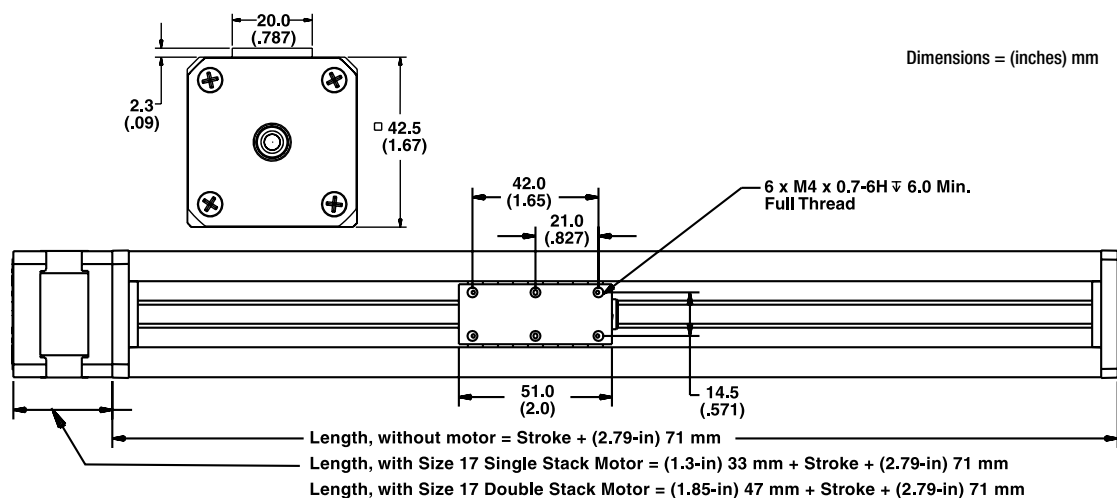
To determine what is best for your application see the [Linear Rail Applications Checklist](#).

Identifying the Non-Motorized LRS Part Numbers when Ordering

LR	W	04	B	A	0025	XXX
Prefix LR = Linear Rail System	Frame Style B = BFW Nut C = CMP Nut W = WDG Nut G = Guide only	Frame Size Load 04 = 50 lbs (222 N) (Maximum static load)	Coating S = Uncoated B = Black Ice TFE N = No screw	Drive / Mounting A = None	Nominal Thread Lead Code 0000 = No screw 0025 = 0.25-in (.635) 0031 = 0.3125-in (.794) 0039 = .0394-in (1.0) 0050 = .05-in (1.27) 0063 = .0625-in (1.588) 0079 = 0.079-in (2.0) 0100 = .100-in (2.54) 0125 = 0.125-in (3.175) 0197 = 0.197-in (5.0) 0250 = 0.250-in (6.35) 0394 = 0.3937-in (10.0) 0500 = .500-in (12.70) 0750 = 0.75-in (19.05) 1000 = 1.0-in (25.4)	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

Dimensional Drawings



SRA Screw Rail® Linear Actuators

- Coaxial Screw and Rail Guides
- Recommended anywhere low drag and minimal free play is required

Traditionally, linear motion has required separate components to handle drive, support and guidance. The compact Screw Rail combines all functions in a single, coaxial component.

By eliminating the need for external rail-to-screw alignment, the Screw Rail simplifies the design, manufacture and assembly of motion systems. The coaxial design saves as much as 80% of the space used by a two-rail system and is generally less expensive than the equivalent components purchased separately. An added benefit is the ability to get three-dimensional motion from a single Screw Rail.



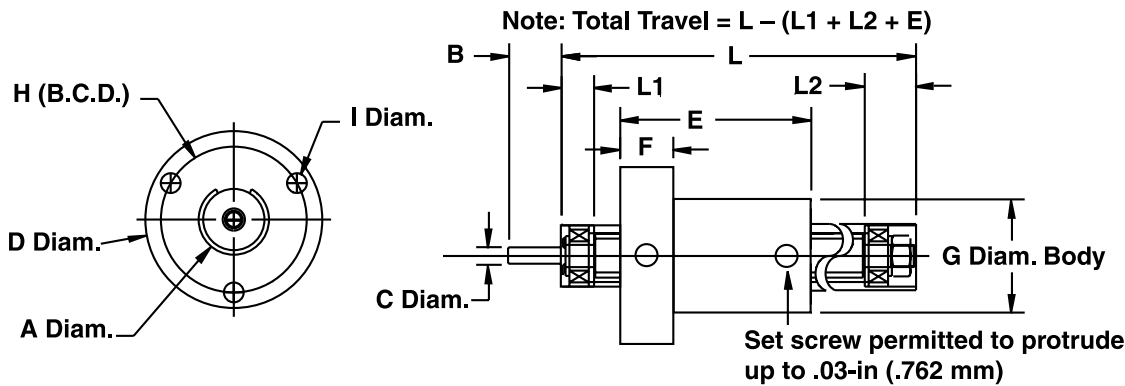
SRA Standard Screw Rail Linear Actuator

Identifying SRA Screw Rail Part Numbers when Ordering

SR	A	03	K	A	0100	XXX
Prefix SR = Screw Rail	Nut Style A = Freewheeling	Nominal Rail Diam. 03 = 3/8-in (10 mm) 04* = 1/2-in (13 mm) 06* = 3/4-in (19 mm) 08* = 1-in (25 mm)	Coating S = Uncoated K = Kerkote®	Drive / Mounting A = None	Nominal Thread Lead Code 0050 = .05-in (1.27) SRA03, SRA04 0100 = .100-in (2.54) SRA03, SRA06, SRA08 0200 = .200-in (5.08) SRA06, SRA08 0250 = .250-in (6.35) SRA03, SRA04 0375 = .375-in (9.53) SRA03 0500 = .500-in (12.70) SRA04, SRA06, SRA08 1000 = 1.00-in (25.4) SRA04, SRA06, SRA08	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Right-hand and left-hand assemblies available. *End supports available, see page 2.

Dimensional Drawings



Assembly Option



When mounted vertically, the Screw Rail can be used to simultaneously lift and rotate (Z-theta motion). With one motor driving the screw and a second rotating the rail, a compact, self-supporting pick and place mechanism can be created.

Part No.	A Diam.	B	C Diam.	D Diam.	E	F	G Diam.	H (B, C, D)	I	L1	L2	
SRA03	inch	.364/.367	.38	.1245/.1250	.98	1.0	.28	.562	.75	.094	.37	.38
	mm	9.24/9.32	9.56	3.16/3.18	24.9	25.4	7.2	14.3	19.1	2.39	9.4	9.66
SRA04	inch	.489/.492	0.62	.1870/.1875	1.25	1.4	.38	.750	1.03	0.140	0.26	0.36
	mm	12.42/12.5	15.75	4.75/4.76	31.8	36	9.5	19.1	26.2	3.56	6.6	9.1
SRA06	inch	.739/.742	0.75	.2490/.2495	1.75	2.0	.50	1.120	1.48	0.173	0.38	0.70
	mm	18.77/18.85	19.05	6.33/6.34	44.5	51	12.7	28.4	37.6	4.39	9.7	17.8
SRA08	inch	.989/.992	0.75	.2490/.2495	2.23	2.5	.63	1.495	1.92	0.200	0.48	0.77
	mm	25.12/25.2	19.05	6.33/6.34	56.6	64	15.9	38.0	48.8	5.08	12.2	19.6

Metric available as requested.

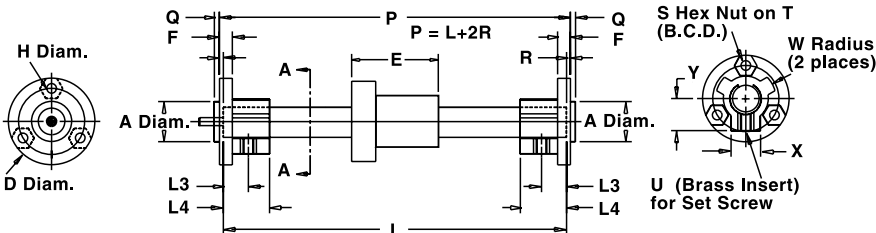
Part No.	Inch Lead**		Thread Lead Code	Nominal Rail Diam.		Nominal Screw Diam.		Max Drag Torque		Life @ 1/4 Design Load x 10 ⁶ (Non Anti-Backlash)		Torque-to-Move Lead		Design Load		Screw inertia per Unit Length		Equivalent Diam*	
	inch	mm		inch	mm	inch	mm	oz-in	NM	inch	cm	oz-in/lb	NM/Kg	lbs	NM	oz-in sec ² /in	KgM ² /M	inch	mm
SRA03	.050	1.27	0050	3/8	10	3/16	5	1.5	0.014	100 to 150	250 to 380	0.5	0.007	10	4.5	.1 x 10 ⁻⁵	.4 x 10 ⁻⁶	30	7.6
	.100	2.54	0100					2.0	0.018			1.0	0.016						
	.250	6.35	0250					2.5	0.020			1.25	0.019						
	.375	9.53	0375					3.0	0.025			2.0	0.030						
SRA04	.050	1.27	0050	1/2	13	1/4	6	2.0	0.015	150 to 200	380 to 500	0.5	0.007	25	10	.3 x 10 ⁻⁵	1.3 x 10 ⁻⁶	.39	9.9
	.250	6.35	0250					3.0	0.020			1.5	0.023						
	.500	12.7	0500					4.0	0.030			2.5	0.039						
	1.00	25.40	1000					5.0	0.040			4.5	.070						
SRA06	.100	2.54	0100	3/4	19	3/8	10	3.0	0.020	180 to 280	450 to 710	1.0	0.016	50	20	1.5 x 10 ⁻⁵	6.5 x 10 ⁻⁶	.60	15.2
	.200	5.08	0200					4.0	0.030			1.5	0.023						
	.500	12.7	0500					5.0	0.040			2.5	0.039						
	1.00	25.40	1000					6.0	0.045			4.5	0.070						
SRA08	.100	2.54	0100	1	25	1/2	13	4.0	0.030	280 to 320	710 to 810	1.0	0.016	100	45	5.2 x 10 ⁻⁵	20.0 x 10 ⁻⁶	.81	20.5
	.200	5.08	0200					5.0	0.040			1.5	0.023						
	.500	12.7	0500					6.0	0.045			2.5	0.039						
	1.00	25.40	1000					8.0	0.060			4.5	0.070						

*Screw Rail stiffness may be modeled using Classical Beam Deflection Theory with equivalent stainless steel beam of diameter given.
 **Other leads available as custom orders.

Screw Rail® End Supports

- Optional accessory providing convenience of simple and compact mounting
- End Supports slide over the outside diameter of each rail end and “key” off the slot in the Screw Rail

Kerkite® composite polymer End Supports come standard with three hex nuts that are captured in the flange for easy assembly. Also supplied with a brass threaded insert and a set screw to fasten to the outside diameter of the rail.



Dimensions E and L are referenced in the ScrewRail Dimensions VIEW AA
 Note: Total Travel = L - (E + 2 [L4])

Identifying Screw Rail End Support Part Numbers when Ordering

SR	04	ES	Z00
Prefix SR = Screw Rail	Nominal Size Diameter 04 = 1/2-in (13 mm) 06 = 3/4-in (19 mm) 08 = 1-in (25 mm)	Accessory ES = End Support	Identifier Standard

NOTE: Dashes must be included in Part Number (-) as shown above.
 For assistance call our Engineering Team at 603 213 6290.

	A Diam. inch (mm)	D inch (mm)	F inch (mm)	H Diam. inch (mm)	L3 inch (mm)	L4 inch (mm)	Q inch (mm)	R inch (mm)	S inch	T inch (mm)	U inch	W Diam. Brass Insert Inch (mm)	X inch (mm)	Y inch (mm)
SRA04	.624/.626 (15.85/15.90)	1.35 (34.3)	0.200 (5.08)	0.150 (3.81)	0.390 (9.91)	.720 (18.29)	0.080 (2.03)	0.060 (1.52)	#6-32	1.03 (26.2)	#8-32	0.47 (12.0)	0.460 (11.68)	0.500 (12.70)
SRA06	.749/.751 (19.03/19.08)	1.60 (40.6)	0.250 (6.35)	0.173 (4.39)	0.603 (15.32)	0.900 (22.86)	0.100 (2.54)	0.100 (2.54)	#8-32	1.31 (33.3)	#10-32	0.60 (15.3)	0.594 (15.09)	0.645 (16.38)
SRA08	.999/1.001 (25.38/25.43)	2.20 (55.9)	0.375 (9.53)	0.200 (5.08)	0.920 (23.37)	1.200 (30.48)	0.125 (3.18)	0.175 (4.45)	#10-32	1.82 (46.2)	#10-32	0.82 (20.9)	0.800 (20.32)	0.820 (20.83)

*Metric carriage hole sizes available M3, M4, M5, M6.

SRZ Screw Rail® Linear Actuators

- Coaxial Screw and Rail Guides
- Continuous Self-Adjusting Anti-Backlash

Traditionally, linear motion has required separate components to handle drive, support and guidance. The compact Screw Rail combines all functions in a single, coaxial component.

By eliminating the need for external rail-to-screw alignment, the Screw Rail simplifies the design, manufacture and assembly of motion systems. The coaxial design saves as much as 80% of the space used by a two-rail system and is generally less expensive than the equivalent components purchased separately. An added benefit is the ability to get three-dimensional motion from a single Screw Rail.



SRZ
Anti-Backlash
Screw Rail Linear Actuator

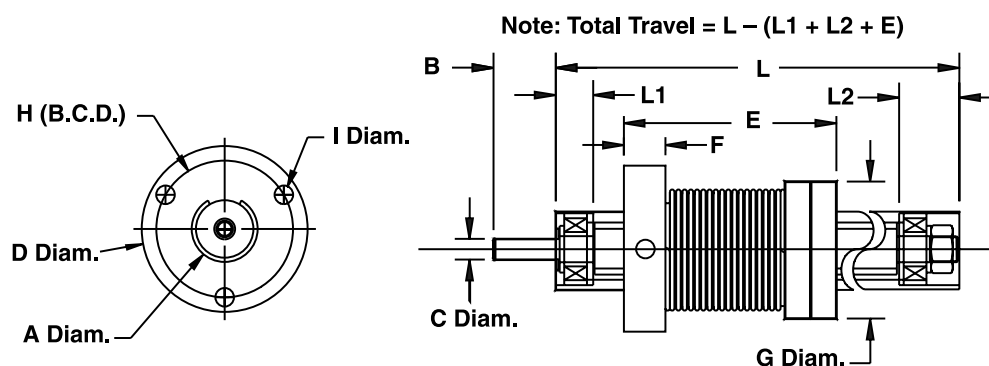
Identifying SRZ Screw Rail Part Numbers when Ordering

SR	Z	06	K	A	0100	XXX
Prefix SR = Screw Rail	Nut Style A = Anti-Backlash	Nominal Rail Diam. 03 = 3/8-in (10 mm) 04* = 1/2-in (13 mm) 06* = 3/4-in (19 mm) 08* = 1-in (25 mm)	Coating S = Uncoated K = Kerkote®	Drive / Mounting A = None	Nominal Thread Lead Code 0050 = .05 -in (1.27) SRZ03, SRZ04 0100 = .100-in (2.54) SRZ03, SRZ06, SRZ08 0200 = .200-in (5.08) SRZ06, SRZ08 0250 = .250-in (6.35) SRZ03, SRZ04 0375 = .375-in (9.53) SRZ03 0500 = .500-in (12.70) SRZ04, SRZ06, SRZ08 1000 = 1.00-in (25.4) SRZ04, SRZ06, SRZ08	Unique Identifier Suffix used to identify specific motors or a proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290. Right-hand and left-hand assemblies available.

Dimensional Drawings

Assembly Option



When mounted vertically, the Screw Rail can be used to simultaneously lift and rotate (Z-theta motion). With one motor driving the screw and a second rotating the rail, a compact, self-supporting pick and place mechanism can be created.

Part No.	A Diam.	B	C Diam.	D Diam.	E	F	G Diam.	H (B, C, D)	I	L1	L2	
SRZ03	inch	.364/.367	.38	.1245/.1250	.98	1.1	.28	.73	.75	.094	.37	.38
	mm	9.24/9.32	9.56	3.16/3.18	24.9	27.94	7.2	18.5	19.1	*	9.4	9.66
SRZ04	inch	.489/.492	0.62	.1870/.1875	1.31	1.4	.38	.97	1.03	0.140	0.26	0.36
	mm	12.42/12.5	15.75	4.75/4.76	33.3	36	9.5	24.7	26.2	*	6.6	9.1
SRZ06	inch	.739/.742	0.75	.2490/.2495	1.81	2.0	.50	1.38	1.48	0.173	0.38	0.70
	mm	18.77/18.85	19.05	6.33/6.34	46.0	51	12.7	35.1	37.6	*	9.7	17.8
SRZ08	inch	.989/.992	0.75	.2490/.2495	2.30	2.5	.63	1.72	1.92	0.200	0.48	0.77
	mm	25.12/25.2	19.05	6.33/6.34	58.4	64	15.9	43.7	48.8	*	12.2	19.6

*Metric available as requested.

Part No.	Inch Lead**		Thread Lead Code	Nominal Rail Diam.		Nominal Screw Diam.		Max Drag Torque		Life @ 1/4 Design Load x 10 ⁶ (Non Anti-Backlash)		Torque-to-Move Lead		Design Load		Screw inertia per Unit Length		Equivalent Diam*	
	inch	mm		inch	mm	inch	mm	oz-in	NM	inch	cm	oz-in/lb	NM/Kg	lbs	NM	oz-in sec ² /in	KgM ² /M	inch	mm
SRZ03	.050	1.27	0050	3/8	10	3/16	5	2.0	0.014	50 to 80	130 to 200	0.5	0.007	10	50	.1 x 10 ⁻⁵	.4 x 10 ⁻⁶	30	7.6
	.100	2.54	0100					2.5	0.018			1.0	0.016						
	.250	6.35	0250					3.0	0.020			1.25	0.019						
	.375	9.53	0375					3.5	0.025			2.0	0.030						
SRZ04	.050	1.27	0050	1/2	13	1/4	6	3.0	0.020	75 to 100	190 to 250	0.5	0.007	25	10	.3 x 10 ⁻⁵	1.3 x 10 ⁻⁶	.39	9.9
	.250	6.35	0250					4.0	0.030			1.5	0.023						
	.500	12.7	0500					5.0	0.040			2.5	0.039						
	1.00	25.40	1000					6.0	0.045			4.5	.070						
SRZ06	.100	2.54	0100	3/4	19	3/8	10	6.0	0.045	90 to 140	230 to 350	1.0	0.016	50	20	1.5 x 10 ⁻⁵	6.5 x 10 ⁻⁶	.60	15.2
	.200	5.08	0200					6.5	0.047			1.5	0.023						
	.500	12.7	0500					7.0	0.050			2.5	0.039						
	1.00	25.40	1000					7.5	0.053			4.5	0.070						
SRZ08	.100	2.54	0100	1	25	1/2	13	8.0	0.057	120 to 160	350 to 410	1.0	0.016	100	45	5.2 x 10 ⁻⁵	20.0 x 10 ⁻⁶	.81	20.5
	.200	5.08	0200					8.5	0.060			1.5	0.023						
	.500	12.7	0500					9.0	0.064			2.5	0.039						
	1.00	25.40	1000					9.5	0.067			4.5	0.070						

*Screw Rail stiffness may be modeled using Classical Beam Deflection Theory with equivalent stainless steel beam of diameter given.
 **Other leads available as custom orders.

Linear Guide Elements

Spline Shafts and Guide Rails deliver low-cost, low friction and long life for a variety of linear motion control applications.

KERK® SS and SZ Spline shafts are available in stainless steel and can be coated with our proprietary Kerkote® TFE or Black Ice® coatings. Spline Shafts provide anti-rotation for one axis motion or a drive mechanism with rotation for two axes of motion. The bushing is supplied with an integral brass collar to facilitate various mounting configurations without nut distortion.

KERK GR Guide Rail is the perfect choice for light load applications requiring minimal frictional drag, low cost and long wear. It features a burnished, centerless ground stainless steel shaft (available either uncoated or with Kerkote® TFE for additional lubricity) and a graphite and PTFE-filled thermoplastic bushing.



SS and SZ Series Spline Shafts

The Kerk® Spline Shaft (SS/SZ) series spline shaft system has been designed for light to moderate load applications, where low cost, low friction, and long life are primary design considerations. Kerk Spline Shafts provide anti-rotation for one axis motion or a drive mechanism with rotation for two axes of motion. They are excellent alternatives for applications where hex shafts, square shafts and high-cost ball splines are typically used. The assembly consists of a stainless steel spline shaft treated with Haydon Kerk Motion Solutions, Inc. proprietary low friction Kerkote® TFE coating, mated with a Kerkite® composite polymer bushing. The bushing is supplied with an integral brass collar to facilitate various mounting configurations without nut distortion. Standard shaft straightness is .003-in (.08mm/30cm) per foot. Typical radial and torsional clearance between shaft and bushing for a basic assembly (SSA) is .002-in to .003-in (.05-.08mm). An anti-backlash assembly (SZA) is available for applications requiring minimum torsional play. As with other Kerk assemblies, special bushing configurations and end machining configurations are available upon request. Aluminum or carbon steel spline shafts are also available upon request.



GR Series Linear Rails and Bushings

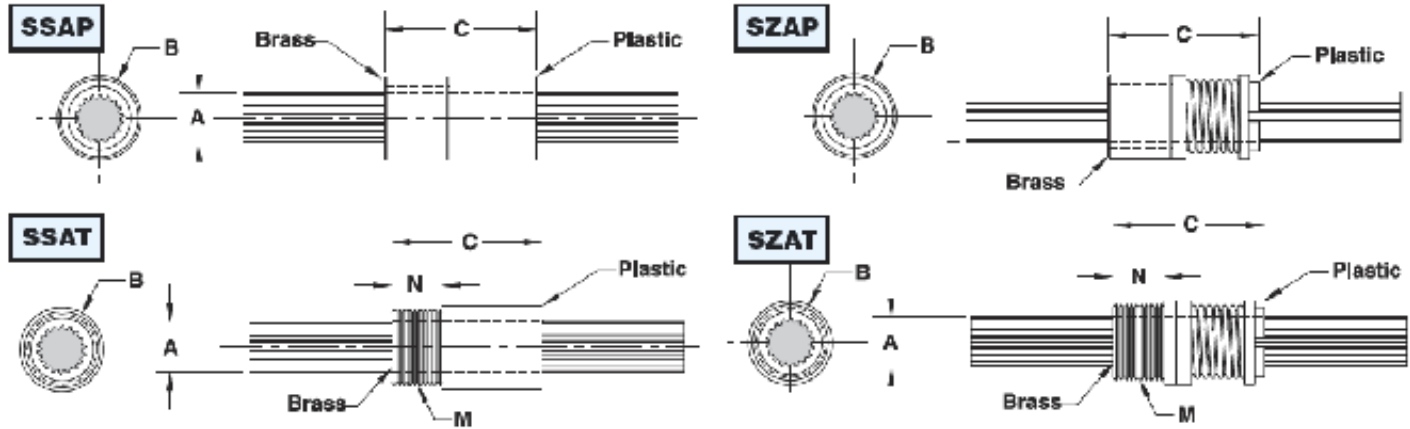
The GR Series linear rail system has been designed for light load applications where low cost, minimum frictional drag and long wear life are primary design considerations. The assembly consists of a centerless ground and burnished stainless steel shaft mated with a Kerkite® composite polymer bushing. The material combinations have been selected so that thermal fluctuations have minimal effect on system performance. Additional lubricity and extended life can be obtained by using a low friction Kerkote® TFE coating on support shafts available in both stainless and alloy steel. Standard shaft straightness is .002-in (0.05mm) per foot and typical radial clearance between shaft and bushing is .0005-in (.013mm) on non-coated assemblies and .001-in (.025mm) on Kerkote TFE coated assemblies. Bushings are manufactured with standard retaining ring grooves.

■ Identifying the Spline Shafts and Guide Rails Part Number Codes when Ordering

SZ	A	P	04	1	K	08	XXX
Prefix	Nut Style	Mounting	Rail Diameter	Number of Bushings per Rail	Lubrication	Length in Inches (Rounded up)	Unique Identifier
SS = Spline Shaft	A = Assembly B = Bushing only	T = Threaded (for Spline Shafts only)	02 = 1/8-in 04 = 1/4-in 06 = 3/8-in 08 = 1/2-in 12 = 3/4-in	0 1 2 3 4 5	S = Uncoated K = Kerkote® B = Black Ice™ N = Bushing only	Example: 06 = 6-in 08 = 8-in 00 = Bushing only	Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.
SZ = Anti-Backlash Spline Shaft	S = Shaft only	G = Snap ring groove (for Guide Rails only)					
GR = Guide Rail		P = Plain (no features) S = Shaft only X = Custom		Use "0" for Shaft only and "1" if Bushing only			

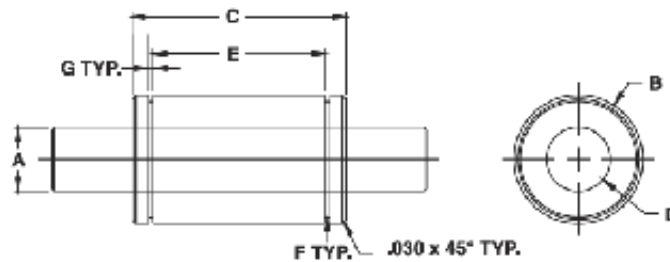
NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 603 213 6290.

■ SRA Series Standard ScrewRail Linear Actuators



Rail Diameter Code	Shaft	Root Diameter	Tube I.D.	Bushing Diameter	Bushing Length	Thread	Thread Length	Equivalent Diameter**	
	A in ± .002 (mm ± 0.05)	in ± .002 (mm ± 0.05)	in ± .002 (mm ± 0.05)	B in ± .001 (mm ± 0.025)	C in ± .01 (mm ± 0.25)	M	N in ± .002 (mm ± 0.05)	inch (mm)	
SS/SZ	02	0.125 (3.18)	0.095 (2.41)	NA	0.375 (9.53)	0.500 (12.70)	3/8-24	0.250 (6.35)	0.110 (2.79)
	04	0.250 (6.35)	0.202 (5.13)	NA	0.500 (12.70)	0.75 (19.1)	7/16-20	0.250 (6.35)	0.226 (5.74)
	06	0.375 (9.53)	0.306 (7.77)	NA	0.625 (15.88)	1.00 (25.4)	9/16-20	0.375 (9.53)	0.341 (8.65)
	08	0.500 (12.70)	0.419 (10.64)	NA	0.813 (20.65)	1.50 (38.1)	3/4-20	0.500 (12.70)	0.458 (11.63)
	12	0.750 (19.05)	0.630 (16.00)	NA	1.125 (28.58)	2.25 (57.2)	1-16	0.750 (19.05)	0.690 (17.53)

■ GR Series Linear Rails and Bushings



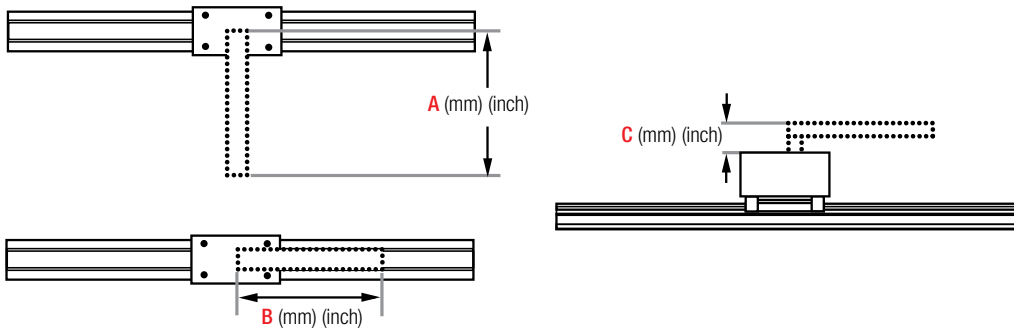
Rail Diameter Code	Standard Part Lengths	Rail Diameter	Rail Diameter w/TFE	Bushing Outside Diam.	Bushing Length	Bushing Inside Diam.	Snap Ring Groove Location	Snap Ring Groove Diam.	Snap Ring Groove Width	Rail Chamfer	Radial Load	
	in ± .010 (mm ± 0.25)	A in ± .0006 (mm ± 0.015)	A in ± .0006 (mm ± 0.015)	B in ± .0006 (mm ± 0.015)	C in ± .010 (mm ± 0.25)	D in ± .0005 (mm ± 0.013)	E in +.010 -.000 (+0.25 -0.00)	F in ± .004 (mm ± 0.100)	G in ± .0003 (mm ± 0.008)	H in (mm)	lb (Kg)	
GR	04	6/8 10/12	.2475 (6.267)	.2472 (6.279)	.5000 (12.700)	.765 (19.43)	.2485 (6.311)	.535 (13.59)	.450 (11.43)	.040 (1.02)	.020 (.51)	5 (2.3)
	06	6/12 15/18	.3715 (9.436)	.3712 (9.428)	.7500 (19.050)	1.275 (32.39)	.3725 (9.462)	.995 (25.27)	.676 (17.17)	.046 (1.17)	.020 (.51)	10 (4.5)
	08	12/15 18/24	.4965 (12.611)	.4962 (12.603)	1.0000 (25.400)	1.660 (42.16)	.4975 (12.637)	1.330 (33.78)	.900 (22.86)	.048 (1.17)	.020 (.51)	15 (6.8)
	12	18/24 36	.7415 (18.834)	.7412 (18.826)	1.2500 (31.750)	2.036 (51.72)	.7425 (18.860)	1.620 (41.15)	1.125 (28.60)	.058 (1.47)	.030 (.76)	25 (11.4)

Linear Rail Checklist

Information needed to properly size a linear rail system

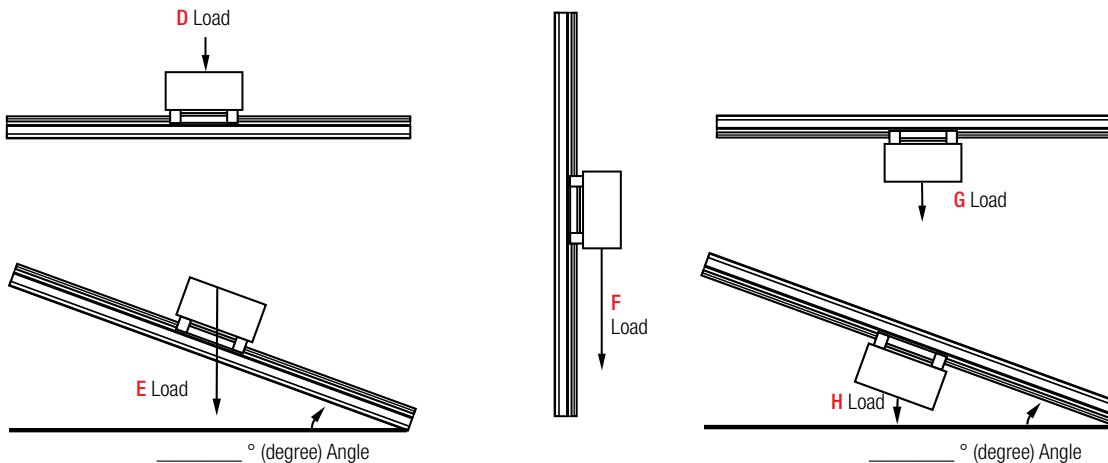
Our Linear Rail Systems are designed to be precision motion devices. Many variables must be considered before applying a particular rail system in an application. The following is a basic checklist of information needed that will make it easier for the Haydon Kerk Pittman Engineering Team to assist you in choosing the proper linear rail. See **order form** on page 4.

- Maximum Load? _____ (N or lbs.)
- Load Center of Gravity (cg) Distance and Height (mm or inches)? See illustrations (A) (B) (C) below.
Dimensions: mm or inch A _____, or B _____ and C _____



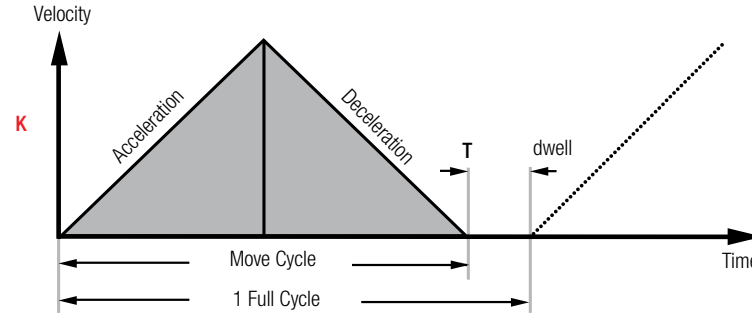
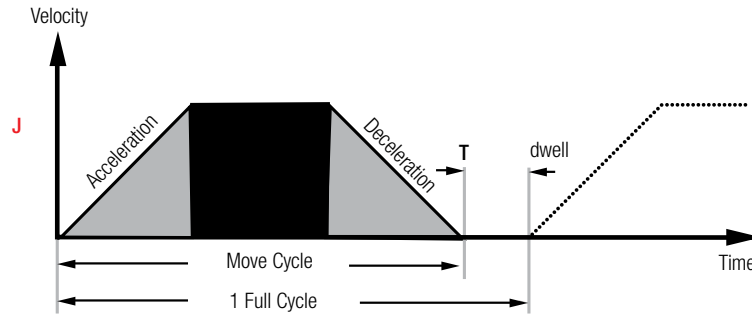
- Rail Mount Orientation? The force needed to move the load is dependent on the orientation of the load relative to the force of gravity. For example, total required force in the horizontal plane (D) is a function of friction and the force needed for load acceleration ($F_f + F_a$). Total force in the vertical plane is a function of friction, load acceleration, and gravity ($F_f + F_a + F_g$).

Orientation: D _____ F _____ G _____
 E _____ ° H _____ °



- Stroke Length to Move Load? _____ (mm or inches)
Overall rail size will be a function of stroke length needed to move the load, the rail frame size (load capability), the motor size, and whether or not an integrated stepper motor programmable drive system is added.

5. Move Profile? A *trapezoidal* move profile divided into 3 equal segments (**J**) is a common move profile and easy to work with. Another common move profile is a *triangular* profile divided into 2 equal segments (**K**).



If using a *trapezoidal* (J) or *triangular* (K) move profile, the following is needed.

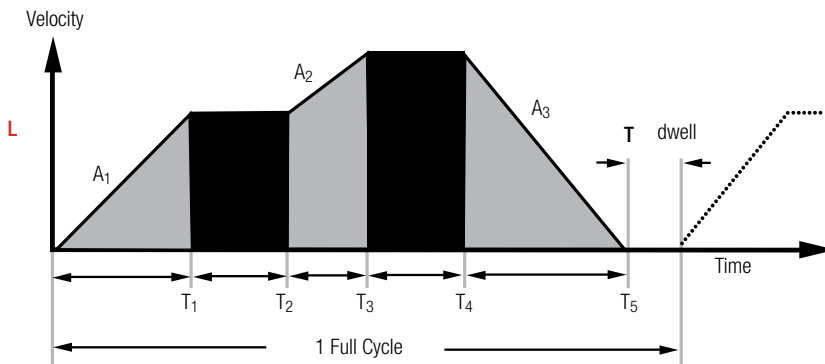
- Point to point move distance _____ (mm or inches)
- Move time _____ (seconds) including time of acceleration and deceleration
- Dwell time between moves _____ (seconds)

The trapezoidal move profile (J) is a good starting point in helping to size a system for prototype work.

A *complex* move profile (L) requires more information.

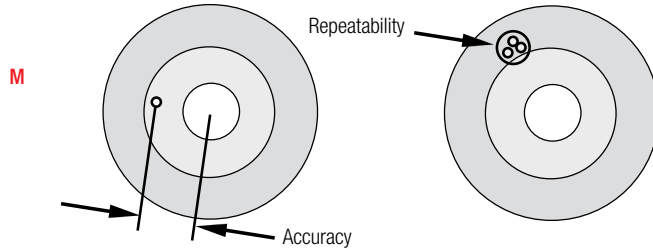
- Time (in seconds) including: $T_1, T_2, T_3, T_4, T_5 \dots T_n$ and T_{dwell}
- Acceleration / Deceleration (mm/sec^2 or $\text{inches}/\text{sec}^2$) including: $A_1, A_2, A_3 \dots A_n$

6. Position Accuracy Required? _____ (mm or inches)



Accuracy is defined as the difference between the theoretical position and actual position capability of the system. Due to manufacturing tolerances in components, actual travel will be slightly different than theoretical "commanded" position. See **M**.

7. Position Repeatability Required? _____ (mm or inches)
 Repeatability is defined as the range of positions attained when the rail is commanded to approach the same position multiple times under identical conditions. See **M**.



8. Positioning Resolution Required? _____ (mm/step or inches/step)
 Positioning resolution is the smallest move command that the system can generate. The resolution is a function of many factors including the drive electronics, lead screw pitch, and encoder (if required). The terms "resolution" and "accuracy" should never be used interchangeably.
9. Closed-Loop Position Correction Required? YES NO
 In stepper motor-based linear rail systems, position correction is typically accomplished using a rotary incremental encoder (either optical or magnetic).
10. Life Requirement? (select the most important application parameter)
- Total mm or inches _____, or
 - Number of Full Strokes _____, or
 - Number of Cycles _____
11. Operating Temperature Range _____ (°C or °F)
- Will the system operate in an environment in which the worst case temperature is above room temperature?
 - Will the system be mounted in an enclosure with other equipment generating heat?
12. Controller / Drive Information?
- Haydon Kerk IDEA™ Drive (with Size 17 Stepper Motors only)
 - Customer Supplied Drive. Type? Chopper Drive L / R Drive
 Model / Style of Drive: _____
13. Power Supply Voltage? _____ (VDC)
14. Step Resolution?* a. Full Step b. Half-Step c. Micro-Step
15. Drive Current?* _____ (A_{rms} / Phase) and _____ (A_{peak} / Phase)
16. Current Boost Capability?* _____ (%)

*NOTE: If the Haydon Kerk IDEA™ Drive is used with 43000 Series Size 17 linear actuator stepper motor disregard items 14, 15, and 16.

Linear Rail Application Checklist

Upon completion, email to: info.haydonkerk@ametek.com

Name _____ Company _____
Address _____ City _____ State _____ Zip _____
Country _____ Phone _____ Email _____

1. Maximum Load? _____ (N or lbs.)
2. Load Center of Gravity (cg) Distance and Height (mm or inches)? See illustrations (A) (B) (C) below.
Dimensions: mm or inch A _____, or B _____ and C _____
3. Rail Mount Orientation? The force needed to move the load is dependent on the orientation of the load relative to the force of gravity. For example, total required force in the horizontal plane (D) is a function of friction and the force needed for load acceleration ($F_f + F_a$). Total force in the vertical plane is a function of friction, load acceleration, and gravity ($F_f + F_a + F_g$).
Orientation: D _____ E _____ ° F _____ G _____ H _____ °
4. Stroke Length to Move Load? _____ (mm or inches) Overall rail size will be a function of stroke length needed to move the load, the rail frame size (load capability), the motor size, and whether or not an integrated stepper motor programmable drive system is added.
5. Move Profile? A *trapezoidal* move profile divided into 3 equal segments (J) is a common move profile and easy to work with. Another common move profile is a *triangular* profile divided into 2 equal segments (K).

If using a *trapezoidal* (J) or *triangular* (K) move profile, the following is needed.

- a. Point to point move distance _____ (mm or inches)
- b. Move time _____ (seconds) including time of acceleration and deceleration
- c. Dwell time between moves _____ (seconds)

The trapezoidal move profile (J) is a good starting point in helping to size a system for prototype work.

A *complex* move profile (L) requires more information.

- a. Time (in seconds) including: $T_1, T_2, T_3, T_4, T_5, \dots, T_n$ and T_{dwell}
- b. Acceleration / Deceleration (mm/sec.² or inches/sec.²) including: $A_1, A_1, A_1 \dots A_n$

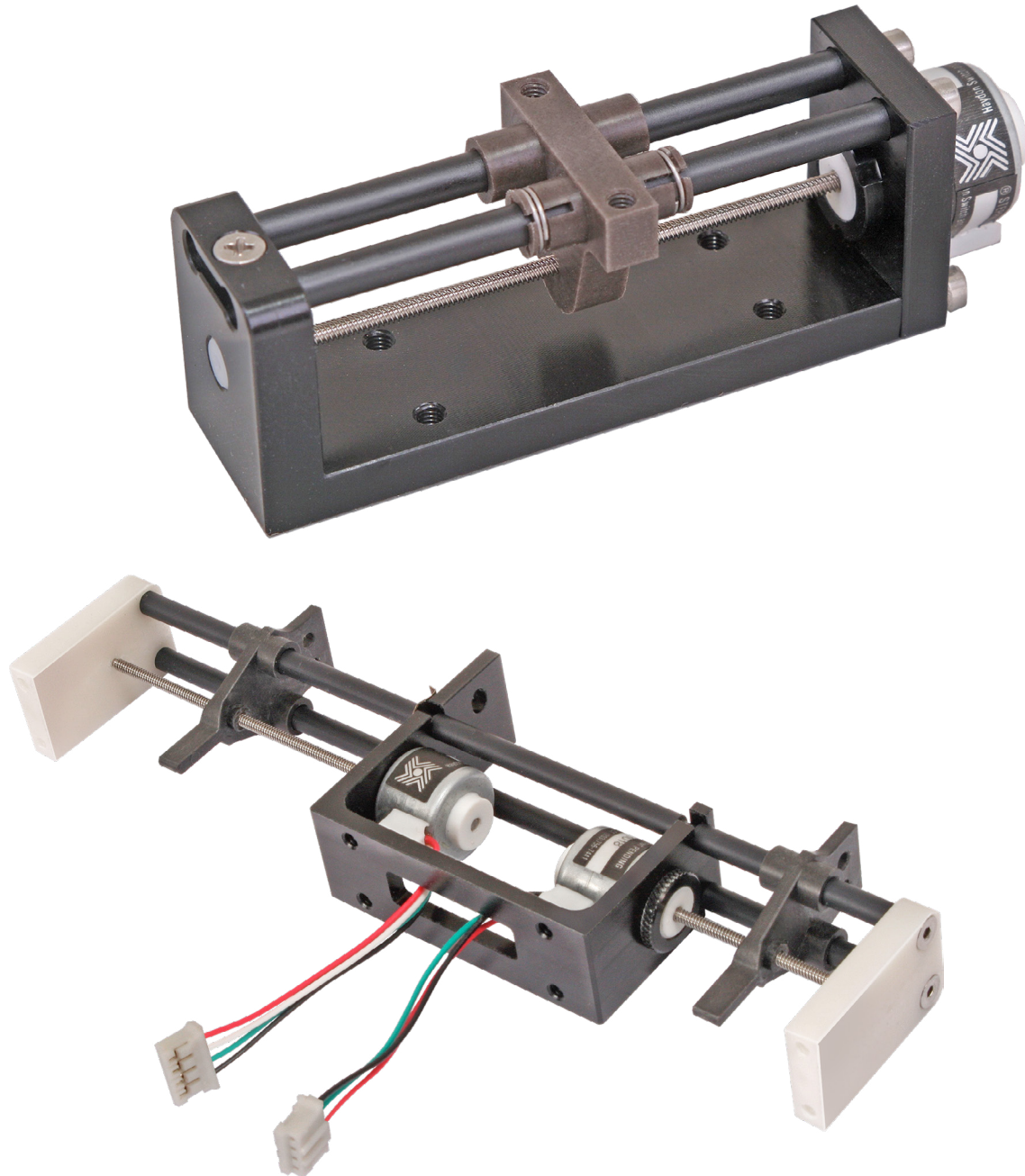
6. Position Accuracy Required? _____ (mm or inches)
Accuracy is defined as the difference between the theoretical position and actual position capability of the system. Due to manufacturing tolerances in components, actual travel will be slightly different than theoretical "commanded" position. See **M**.
7. Position Repeatability Required? _____ (mm or inches) Repeatability is defined as the range of positions attained when the rail is commanded to approach the same position multiple times under identical conditions. See **M**.
8. Positioning Resolution Required? _____ (mm/step or inches/step) Positioning resolution is the smallest move command that the system can generate. The resolution is a function of many factors including the drive electronics, lead screw pitch, and encoder (if required). The terms "resolution" and "accuracy" should never be used interchangeably.
9. Closed-Loop Position Correction Required? YES NO In stepper motor-based linear rail systems, position correction is typically accomplished using a rotary incremental encoder (either optical or magnetic).
10. Life Requirement? (select the most important application parameter)
a. Total mm or inches _____, or b. Number of Full Strokes _____, or c. Number of Cycles _____
11. Operating Temperature Range _____ (°C or °F)
a. Will the system operate in an environment in which the worst case temperature is above room temperature?
b. Will the system be mounted in an enclosure with other equipment generating heat?
12. Controller / Drive Information?
a. Haydon Kerk IDEA™ Drive (with Size 17 Stepper Motors only)
b. Customer Supplied Drive. Type? Chopper Drive L / R Drive
Model / Style of Drive: _____
13. Power Supply Voltage? _____ (VDC)
- 14*. Step Resolution?* a. Full Step b. Half-Step c. Micro-Step
- 15*. Drive Current?* _____ (A_{rms} / Phase) and _____ (A_{peak} / Phase)
- 16*. Current Boost Capability?* _____ (%)

*NOTE: If the Haydon Kerk IDEA™ Drive is used with 43000 Series Size 17 linear actuator stepper motor disregard items 14, 15, and 16.

AMETEK Haydon Kerk Pittman **Linear Rails and Slides Customization**

Haydon Kerk Pittman takes great pride in designing and developing customized solutions for your application needs.

Our Design and Development Engineers begin with our standard catalog products and build ideal solutions for your motion needs. Our factories bring your solutions into production.



PITTMAN[®]

AMETEK[®]

To complement the Haydon Kerk[®] brand of products AMETEK[®] Advanced Motion Solutions also offers the PITTMAN[®] brand of DC motor products. Our experienced team of sales engineers will work with you to help you determine the optimum motion solution.

PITTMAN offers a broad range of DC brush and brushless motors with various power ratings, sizes, lengths, and options to meet just about any motion application. In addition to a standard offering of optional components such as drives, encoders, brakes, and gearboxes, motors can be further customized to include unique motor windings, special wire harnesses, EMI/RFI suppression, shaft modifications, custom output devices such as pinions and worm gears, and just about any other value-added feature to help streamline and simplify your product design and manufacturing.





Full Line Catalog

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Brushless DC Motors
Brushed DC Motors
Gearboxes
Encoders
Drives
Brakes

www.haydonkerkpittman.com



S...
ations.
Pittman Motors can be configured with standard
options, including unique motor windings, wire harnesses,
pos. governors, gears, etc.), or any other value-added features.

Automation Grade Motors

For applications that require feedback connectivity to
other machinery components, #460-Rated.

Pittman Automation Grade Brushless DC Motors are
PES-rated construction packaged in a rugged and
compact enclosure. Integrated encoders provide high
resolution and frequency response:

- Quick disconnect connectors,
heavy duty shafts and bearings
- Extreme power densities
- NEMA mounts
- Specialty windings, sensors,
resolvers and connection options available



Skidless, Brushless Motors

For applications that require high acceleration and
precision control at all speeds, torque production is
predictable and very controllable.

Pittman Skidless Brushless DC Motors offer many
advantages over conventional skidless motor
construction. High-grade magnetic coupling provides
improved torque efficiency and enables extremely
smooth, quiet motion.

Low inductance and high current bandwidth provide
precise control. Skidless construction also provides
excellent winding heat transfer for high thermal
efficiency and transient load capacity.

- Internal Hall Effect feedback sensors for linear
speed torque characteristics, high starting
torque and variable speed control with appropriate
drive electronics
- Modifications to the shaft, winding and mechanical
mounting are available for OEM applications

Brush Commutated Motors

For applications that require reliability and performance
with basic control. Yield high efficiency by
consuming less electricity.

Pittman Brush Commutated DC Motors have a wide
range of frame sizes and magnetic technologies from
22 to 32mm in diameter. Motors are designed to offer
smooth low speed performance, quiet operation and
long life. Armatures are skewed to minimize magnetic
cogging, while brush and commutator designs maintain
noise.

- Available options: brush materials, EMRFI
suppression networks, shaft modifications,
special windings, heat sink assemblies, gear and
planetary gearing
- Holding brakes, and customer specified pulleys and
gears
- Multiple encoder platforms with a wide range of
resolutions available



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Full Line Catalog



Brushless DC Motors

Brushed DC Motors

Gearboxes

Encoders

Drives

Brakes

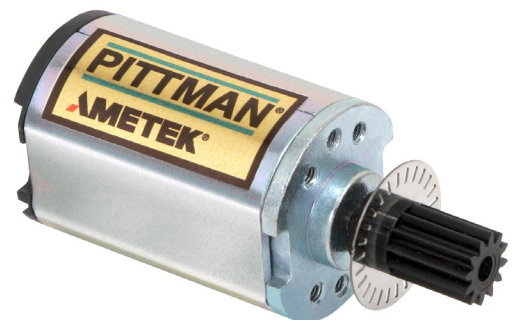
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PITTMAN

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Custom motors also available.
 Contact our Application Engineers for assistance.
 e: info.pittman-motors@ametech.com

DC Brush and Brushless Motors

With various power ratings, sizes, lengths and options to meet most motion applications.

To streamline and simplify your product design and manufacturing, Pittman Motors can be configured with standard components such as encoders, brakes and gearboxes, and customized with unique motor windings, wire harnesses, EMI/RFI suppression, shaft modifications, custom output devices (pinions, gears, etc.), or any other value-added features.

EC Instrument Grade Motors

For applications that require uniform motion control at all speeds. Capable of high acceleration.

Pittman Instrument Grade Brushless DC Motors are used in a wide variety of OEM applications including business machines, light industrial equipment, robots, pumps, traction drives and medical equipment.

- Motors are available in diameters from 33 to 121mm with rated torques up to 6 N-m
- Choice of sizes, power densities, speed capabilities, windings and connection options
- Further customization and adaptation to your equipment can offer design solutions not previously envisioned
- Complementary ranges of gears, brakes and encoders available to optimize performance

EC Instrument Grade Motors with IDEA® Drive

- All inclusive, high-torque, precision servo motor and IDEA® Drive
- Suitable for distributed or autonomous control
- Available in 3 motor lengths with continuous torque up to 0.15 Nm

EA Automation Grade Motors

For applications that require feedback connectivity to other machinery components. IP-65 Rated.

Pittman Automation Grade Brushless DC Motors are IP65 rated construction packaged in a rugged and compact enclosure. Integrated encoders provide high resolution and frequency response.

- Quick disconnect connectors, heavy duty shafts and bearings
- Extreme power densities
- NEMA mounts
- Specialty windings, encoders, resolvers and connection options available





ES Slotless, Brushless Motors

For applications that require high acceleration and precision control at all speeds. Torque production is predictable and very controllable.

Pittman Slotless Brushless DC Motors offer many advantages over conventional slotted stator construction. Negligible magnetic cogging provides improved servo efficiency and enables extremely smooth, quiet motion.

Low inductance and high current bandwidth provides precise control. Slotless construction also provides excellent winding heat transfer for high thermal efficiency and transient load capacity.

- Internal Hall Effect feedback sensors for linear speed-torque characteristics, high starting torque and variable speed control with appropriate drive electronics
- Modifications to the shaft, winding and mechanical mounting are available for OEM applications

DC Brush Commutated Motors

For applications that require reliability and performance with basic control. Yields high efficiencies by consuming less electricity.

Pittman Brush Commutated DC Motors have a wide range of frame sizes and magnetic technologies from 22 to 83mm in diameter. Motors are designed to offer smooth low speed performance, quiet operation and long life. Armatures are skewed to minimize magnetic cogging, while brush and commutator designs minimize noise.

- Available options: brush materials, EMI/RFI suppression networks, shaft modifications, special windings, lead wire assemblies, spur and planetary gearing
- Holding brakes, and customer specified pulleys and gears
- Multiple encoder platforms with a wide range of resolutions available



Information needed to properly select a DC Motor

1. What type of control is required?

Open loop speed control

Closed loop torque control

Closed loop speed control

Closed loop position control

Other _____

2. What are the application requirements?

Speed _____ Torque _____

Other _____

3. Duty Cycle, continuous or intermittent (specify interval on time, off time, repeat duration).

Helpful Hint: Continuous torque value will determine the frame size. Required speed will determine if frame size will meet needed parameters.

4. What motor technology is required? Brushed DC Brushless DC (BLDC)

Helpful Hint: Performance requirements define which type of motor is best suited for the application. See following page for selection criteria.

5. What are the size constraints? _____

6. What voltage and power input is available? _____

7. Do you need an encoder? YES NO

8. Do you need a brake? YES NO

9. Are there any environmental considerations? YES NO If yes, specify: _____

Basic Rotary Power Output Equations

Speed (rad/sec) x Torque (Nm) = Watts

or

Speed (RPM) x Torque (oz-in) x 7.4 x 10⁻⁴ = Watts

Name _____ Company _____

Address _____ City _____ State _____ Zip _____

Country _____ Phone _____ Email _____

1. Application Description _____
2. Initial Quantity and Delivery _____ / _____, Annual Quantity and Delivery _____ / _____
3. Target Price Range _____

4. Mechanical					
Load Speed	rpm	Load Inertia	oz-in-sec ²	Diameter	in max
Continuous Load Torque	oz-in rms	Acceleration Time	sec	Length (w/o Shaft)	in max
Peak Load Torque	oz-in pk	Duty Cycle		Weight	oz max

5. Electrical					
Applied Voltage	VDC	Continuous Current	A	Peak Current	A

6. Environmental					
Ambient Temperature Range	°C	Ambient Humidity Range	°C		

7. Unusual Conditions _____
8. Additional Requirements _____

9. Physical Characteristics and Velocity Profiles _____

10. Other important information _____

Upon completion, email to: info.pittman-motors@ametec.com

Model	Shop Online eCommerce Part No.	Integrated Drive	Rated Voltage	Gear Series	Gear Ratio	Gear Type	Continuous Output Torque	
							(Nm)	(oz-in)
DC026C-3	8693S037-SP		12				0.022	3.2
DC030A-1	GM8212-11-SP		19.1	G35A	6.3	standard spur	0.045	6.4
DC030A-1	GM8212-21-SP		19.1	G35A	19.5	standard spur	0.13	18
DC030A-1	GM8212-31-SP		19.1	G35A	60.5	standard spur	0.36	50
DC030A-1	GM8212-41-SP		19.1	G35A	187	standard spur	0.71	100
DC030B-3	8224S004-SP		12				0.018	2.6
DC030B-3	8224S006-SP		24				0.018	2.6
DC030B-3	GM8224S010-SP		24	G35A	6.3	standard spur	0.11	16
DC030B-3	GM8224S012-SP		12	G35A-WF	9.9	wide face spur	0.16	23
DC030B-3	GM8224S016-SP		24	G35A-WF	19.5	wide face spur	0.31	44
DC030B-3	GM8224S020-SP		12	G35A-WF	60.5	wide face spur	0.86	120
DC030B-3	GM8224S024-SP		12	G35A-WF	95.9	wide face spur	1.2	175
DC030B-3	GM8224S028-SP		24	G35A-WF	187	wide face spur	1.2	175
DC030C-1	8541A001-R1-SP		12				0.018	2.5
DC030C-1	8541A002-R1-SP		24				0.018	2.5
DC030C-1	8541S040-SP		24				0.018	2.5
DC030C-2	8542A003-R1-SP		12				0.04	5.6
DC030C-2	8542S041-SP		24				0.04	5.6
DC030C-2	GM8542S049-SP		12	G30A	216	planetary	6.2	880
DC030C-2	GM8542S056-SP		24	G30A	216	planetary	6.2	880
DC030C-3	8543A005-R1-SP		12				0.059	8.3
DC030C-3	8543A006-R1-SP		24				0.059	8.3
DC030C-3	8543S042-SP		24				0.059	8.3
DC030C-3	GM8543S044-SP		12	G35A-WF	9.9	wide face spur	0.51	72
DC030C-3	GM8543S045-SP		12	G35A-WF	19.5	wide face spur	0.99	140
DC030C-3	GM8543S046-SP		12	G35A-WF	30.9	wide face spur	1.2	175
DC030C-3	GM8543S047-SP		12	G30A	36	planetary	1.7	240
DC030C-3	GM8543S048-SP		12	G30A	96	planetary	4.1	580
DC030C-3	GM8543S050-SP		24	G35A	6.3	standard spur	0.35	50
DC030C-3	GM8543S051-SP		24	G35A-WF	9.9	wide face spur	0.51	72
DC030C-3	GM8543S052-SP		24	G35A-WF	19.5	wide face spur	0.99	140
DC030C-3	GM8543S053-SP		24	G35A-WF	30.9	wide face spur	1.2	175
DC030C-3	GM8543S054-SP		24	G30A	36	planetary	1.7	240
DC030C-3	GM8543S057-SP		24	G35A	6.3	standard spur	0.35	50
DC030C-3	GM8543S058-SP		24	G35A-WF	19.5	wide face spur	0.99	140
DC030C-3	GM8543S059-SP		24	G30A	36	planetary	1.7	240

Output Speed @ Cont. Torque (RPM)	Motor Voltage Constant		Motor Torque Constant		Encoder Series	Encoder Resolution	Encoder Output Channels
	V/(rad/s)	(V/krpm)	Nm/A	(oz-in)/A			
740	0.0122	1.28	0.0122	1.73			
65.4	0.0216	2.26	0.0216	3.06			
21.1	0.0216	2.26	0.0216	3.06			
6.81	0.0216	2.26	0.0216	3.06			
2.2	0.0216	2.26	0.0216	3.06			
816	0.0109	1.14	0.0109	1.54			
845	0.0218	2.29	0.0218	3.09			
33.4	0.0436	4.57	0.0436	6.18			
20.3	0.0218	2.29	0.0218	3.09			
10.8	0.0436	4.57	0.0436	6.18			
3.35	0.0218	2.29	0.0218	3.09			
2.12	0.0218	2.29	0.0218	3.09			
1.12	0.0436	4.57	0.0436	6.18			
439	0.0158	1.66	0.0158	2.24			
438	0.0316	3.31	0.0316	4.48			
438	0.0316	3.31	0.0316	4.48	E35A	500	A + B
405	0.0157	1.65	0.0157	2.23			
556	0.0315	3.30	0.0315	4.46	E35A	500	A + B
0.933	0.0248	2.60	0.0248	3.51			
1.16	0.0496	5.19	0.0496	7.02			
400	0.0184	1.92	0.0184	2.60			
472	0.0374	3.91	0.0374	5.29			
472	0.0374	3.91	0.0374	5.29	E35A	500	A + B
29.6	0.0236	2.47	0.0236	3.34			
15.1	0.0236	2.47	0.0236	3.34			
9.56	0.0236	2.47	0.0236	3.34			
8.22	0.0236	2.47	0.0236	3.34			
3.08	0.0236	2.47	0.0236	3.34			
52.7	0.0474	4.96	0.0474	6.71			
33.3	0.0474	4.96	0.0474	6.71			
17	0.0474	4.96	0.0474	6.71			
10.7	0.0474	4.96	0.0474	6.71			
9.23	0.0474	4.96	0.0474	6.71			
52.7	0.0474	4.96	0.0474	6.71	E35A	500	A + B
17	0.0474	4.96	0.0474	6.71	E35A	500	A + B
9.23	0.0474	4.96	0.0474	6.71	E35A	500	A + B

Model	Shop Online eCommerce Part No.	Integrated Drive	Rated Voltage	Gear Series	Gear Ratio	Gear Type	Continuous Output Torque	
							(Nm)	(oz-in)
DC040A-2	GM9213-1-SP		12	G51A	5.9	standard spur	0.11	16
DC040A-2	GM9213-2-SP		12	G51A	19.7	standard spur	0.33	47
DC040A-2	GM9213-3-SP		12	G51A	65.5	standard spur	0.99	140
DC040A-2	GM9213-4-SP		12	G51A	218	standard spur	1.2	175
DC040A-2	GM9213-5-SP		12	G51A	728	standard spur	1.2	175
DC040B-3	9234S006-R1-SP		24				0.043	6.1
DC040B-3	9234S007-R1-SP		24				0.043	6.1
DC040B-3	GM9234S017-R1-SP		24	G51A-HT	11.5	high torque spur	0.45	63
DC040B-3	GM9234S023-R1-SP		24	G51A-WF	38.3	wide face spur	1.4	200
DC040B-3	GM9234S029-R1-SP		24	G51A-WF	127	wide face spur	3.5	500
DC040B-3	GM9234S032-R1-SP		24	G51A-WF	218	wide face spur	3.5	500
DC040B-5	9236S008-R1-SP		24				0.067	9.5
DC040B-5	9236S009-R1-SP		24				0.067	9.5
DC040B-5	GM9236S014-R1-SP		24	G51A-HT	5.9	high torque spur	0.36	50
DC040B-5	GM9236S015-R1-SP		24	G51A-HT	5.9	high torque spur	0.36	50
DC040B-5	GM9236S020-R1-SP		24	G51A-WF	19.7	wide face spur	1.1	160
DC040B-5	GM9236S026-R1-SP		24	G51A-WF	65.5	wide face spur	3.5	490
DC040B-5	GM9236S027-R1-SP		24	G51A-WF	65.5	wide face spur	3.5	490
DC040B-6	9237S010-R1-SP		24				0.081	12
DC040B-6	9237S011-R1-SP		24				0.081	12
DC054B-3	14203S009-SP		24				0.15	21
DC054B-4	14204S005-SP		24				0.18	26
DC054B-4	14204S006-SP		24				0.18	26
DC054B-4	GM14904S011-R1-SP		24	G51A-HT	5.9	high torque spur	0.97	140
DC054B-4	GM14904S012-R1-SP		24	G51A-HT	5.9	high torque spur	0.97	140
DC054B-4	GM14904S015-R1-SP		24	G51A-WF	19.7	wide face spur	3	430
DC054B-4	GM14904S016-R1-SP		24	G51A-WF	19.7	wide face spur	3	430
DC054B-6	14206S011-SP		24				0.26	37
DC054B-7	14207S007-SP		24				0.35	50
DC054B-7	14207S008-SP		24				0.35	50
EC033A-2	1312S103-SP		24				0.046	6.5
EC042B-1	EC042B-10M0-805-SP		24				0.062	8.8
EC042B-1	EC042B-10MP-915	IDEA RS485	12-60				0.062	8.8
EC042B-1	EC042B-10MP-935	IDEA CANopen	12-60				0.062	8.8
EC042B-1	EC042B-1PM0-801-SP		24	PLG42S	4	planetary	0.16	22
EC042B-1	EC042B-1PM0-802-SP		24	PLG42S	16	planetary	0.56	80
EC042B-1	EC042B-1PM0-803-SP		24	PLG42S	25	planetary	0.88	125
EC042B-1	EC042B-1PM0-804-SP		24	PLG42S	100	planetary	3.18	450

Output Speed @ Cont. Torque (RPM)	Motor Voltage Constant		Motor Torque Constant		Encoder Series	Encoder Resolution	Encoder Output Channels
	V/(rad/s)	(V/krpm)	Nm/A	(oz-in)/A			
8.65	0.0395	4.14	0.0395	5.60			
2.6	0.0395	4.14	0.0395	5.60			
0.779	0.0395	4.14	0.0395	5.60			
0.234	0.0395	4.14	0.0395	5.60			
0.0701	0.0395	4.14	0.0395	5.60			
527	0.0365	3.82	0.0365	5.17			
527	0.0365	3.82	0.0365	5.17	E30B	500	A + B + Index
32.1	0.0459	4.81	0.0459	6.50			
9.62	0.0459	4.81	0.0459	6.50			
2.88	0.0459	4.81	0.0459	6.50			
1.69	0.0459	4.81	0.0459	6.50			
416	0.0458	4.80	0.0458	6.49			
416	0.0458	4.80	0.0458	6.49	E30B	500	A + B + Index
69.4	0.0458	4.80	0.0458	6.49			
69.4	0.0458	4.80	0.0458	6.49	E30B	500	A + B + Index
20.8	0.0458	4.80	0.0458	6.49			
6.24	0.0458	4.80	0.0458	6.49			
6.24	0.0458	4.80	0.0458	6.49	E30B	500	A + B + Index
457	0.0424	4.44	0.0424	6.00			
457	0.0424	4.44	0.0424	6.00	E30B	500	A + B + Index
309	0.0654	6.85	0.0654	9.26			
335	0.0612	6.41	0.0612	8.67			
335	0.0612	6.41	0.0612	8.67	E30B	500	A + B + Index
56.1	0.0612	6.41	0.0612	8.67			
56.1	0.0612	6.41	0.0612	8.67	E30B	500	A + B + Index
16.8	0.0612	6.41	0.0612	8.67			
16.8	0.0612	6.41	0.0612	8.67	E30B	500	A + B + Index
290	0.0706	7.39	0.0706	10.00			
294	0.0706	7.39	0.0706	10.00			
294	0.0706	7.39	0.0706	10.00	E30B	500	A + B + Index
5350	0.0311	3.25	0.0311	4.40	U	1000	A + B + Index
4090	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
4090	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
4090	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
1000	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
250	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
160	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index
40	0.0448	4.69	0.0448	6.34	E30D	1000	A + B + Index

Model	Shop Online eCommerce Part No.	Integrated Drive	Rated Voltage	Gear Series	Gear Ratio	Gear Type	Continuous Output Torque	
							(Nm)	(oz-in)
EC042B-2	EC042B-20M0-804-SP		24				0.12	16.9
EC042B-2	EC042B-20MP-914	IDEA RS485	12-60				0.12	16.9
EC042B-2	EC042B-20MP-934	IDEA CANopen	12-60				0.12	16.9
EC042B-2	EC042B-2PM0-801-SP		24	PLG42S	4	planetary	0.35	50
EC042B-2	EC042B-2PM0-802-SP		24	PLG42S	16	planetary	1.26	179
EC042B-2	EC042B-2PM0-803-SP		24	PLG42S	25	planetary	1.97	279
EC042B-2	EC042B-2PM0-804-SP		24	PLG42S	100	planetary	7.11	1008
EC042B-3	EC042B-30M0-803-SP		24				0.159	22.6
EC042B-3	EC042B-30MP-913	IDEA RS485	12-60				0.159	22.6
EC042B-3	EC042B-30MP-933	IDEA CANopen	12-60				0.159	22.6
EC042B-3	EC042B-3PM0-801-SP		24	PLG42S	4	planetary	0.48	67
EC042B-3	EC042B-3PM0-802-SP		24	PLG42S	16	planetary	1.72	243
EC042B-3	EC042B-3PM0-803-SP		24	PLG52	28.12	planetary	2.9	411
EC042B-3	EC042B-3PM0-804-SP		24	PLG52	91.12	planetary	8.47	1200
EC044A-1	EC044A-10M0-806-SP		24				0.041	5.8
EC044A-1	EC044A-1PM0-801-SP		24	PLG42S	4	planetary	0.09	13.2
EC044A-1	EC044A-1PM0-802-SP		24	PLG42S	16	planetary	0.34	47.6
EC044A-1	EC044A-1PM0-803-SP		24	PLG42S	25	planetary	0.53	74
EC044A-1	EC044A-1PM0-804-SP		24	PLG42S	100	planetary	1.9	268
EC044A-2	EC044A-20M0-804-SP		24				0.061	8.6
EC044A-2	EC044A-2PM0-801-SP		24	PLG42S	4	planetary	0.17	23.4
EC044A-2	EC044A-2PM0-802-SP		24	PLG42S	16	planetary	0.59	84.1
EC044A-2	EC044A-2PM0-803-SP		24	PLG42S	25	planetary	0.93	132
EC044A-2	EC044A-2PM0-804-SP		24	PLG42S	100	planetary	3.3	474
EC044A-3	EC044A-30M0-803-SP		24				0.075	11
EC044A-3	EC044A-3PM0-801-SP		24	PLG42S	4	planetary	0.22	30.5
EC044A-3	EC044A-3PM0-802-SP		24	PLG42S	16	planetary	0.78	110
EC044A-3	EC044A-3PM0-803-SP		24	PLG42S	25	planetary	1.2	171
EC044A-3	EC044A-3PM0-804-SP		24	PLG42S	100	planetary	4.4	618
EC057C-2	N2342S104-SP		24				0.13	18
EC057C-4	N2344S105-SP		38.2				0.25	36
ES030A-2	3442S100-SP		38.2				0.037	5.2
ES040A-2	4442S101-SP		38.2				0.097	14
ES050A-3	5443S102-SP		38.2				0.27	39

Output Speed @ Cont. Torque (RPM)	Motor Voltage Constant		Motor Torque Constant		Encoder Series	Encoder Resolution	Encoder Output Channels
	V/(rad/s)	(V/krpm)	Nm/A	(oz-in)/A			
4400	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
4400	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
4400	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
1000	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
250	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
160	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
40	0.0444	4.65	0.0444	6.29	E30D	1000	A + B + Index
4690	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
4690	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
4690	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
1000	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
250	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
142	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
44	0.0427	4.47	0.0427	6.04	E30D	1000	A + B + Index
4246	0.0413	4.33	0.0413	5.86	E30D	1000	A + B + Index
1062	0.0413	4.33	0.0413	5.86	E30D	1000	A + B + Index
265	0.0413	4.33	0.0413	5.86	E30D	1000	A + B + Index
170	0.0413	4.33	0.0413	5.86	E30D	1000	A + B + Index
42	0.0413	4.33	0.0413	5.86	E30D	1000	A + B + Index
4438	0.0423	4.43	0.0423	5.99	E30D	1000	A + B + Index
1109	0.0423	4.43	0.0423	5.99	E30D	1000	A + B + Index
277	0.0423	4.43	0.0423	5.99	E30D	1000	A + B + Index
178	0.0423	4.43	0.0423	5.99	E30D	1000	A + B + Index
44	0.0423	4.43	0.0423	5.99	E30D	1000	A + B + Index
4110	0.0462	4.84	0.0462	6.55	E30D	1000	A + B + Index
1027	0.0462	4.84	0.0462	6.55	E30D	1000	A + B + Index
257	0.0462	4.84	0.0462	6.55	E30D	1000	A + B + Index
164	0.0462	4.84	0.0462	6.55	E30D	1000	A + B + Index
41	0.0462	4.84	0.0462	6.55	E30D	1000	A + B + Index
5980	0.0342	3.58	0.0342	4.84	U	1000	A + B + Index
6120	0.0555	5.81	0.0555	7.86	U	1000	A + B + Index
5750	0.0486	5.09	0.0486	6.88	U	1000	A + B + Index
5190	0.0612	6.41	0.0612	8.67	U	1000	A + B + Index
3950	0.0865	9.06	0.0865	12.30	U	1000	A + B + Index



EC033A Series

The EC033A Series Brushless DC Motor is a high torque density model brushless motor in a 33mm diameter housing. It is offered in 3 motor lengths with continuous torque from 0.025 – 0.060 Nm.

■ Benefits

- Speeds up to 12,000 RPM possible
- DC bus voltage up to 60 VDC
- 33mm diameter housing
- Eight standard windings, Special windings available
- 4 pole rare earth design

■ Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G30A, G35A
- Programmable Drives: PBL4850E, BGE3004A, BGE6015A

■ Motor Characteristics

Motor Data	Units	Series		
		EC033A-1	EC033A-2	EC033A-3
Max DC Terminal Voltage V_T	V	60		
Max Speed (Mechanical) ω_{MAX}	rpm	12000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.025	0.049	0.060
	oz-in	3.5	7.0	8.5
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.081	0.16	0.19
	oz-in	12	22	27
Coulomb Friction Torque T_f	Nm	0.0028	0.0042	0.0056
	oz-in	0.40	0.60	0.80
Viscous Damping Factor D	Nm/(rad/s)	9.4E-07	1.6E-06	2.2E-06
	oz-in/krpm	0.014	0.023	0.032
Thermal Time Constant τ_{th}	min	7.8	9.0	11
Thermal Resistance R_{th}	°C/W	15	13	11
Max. Winding Temperature θ_{MAX}	°C	130	130	130
Rotor Inertia J_r	kg-m ²	1.2E-06	1.9E-06	2.7E-06
	oz-in-s ²	1.7E-04	2.8E-04	3.9E-04
Motor Weight W_m	g	130	180	240
	oz	4.5	6.5	8.5

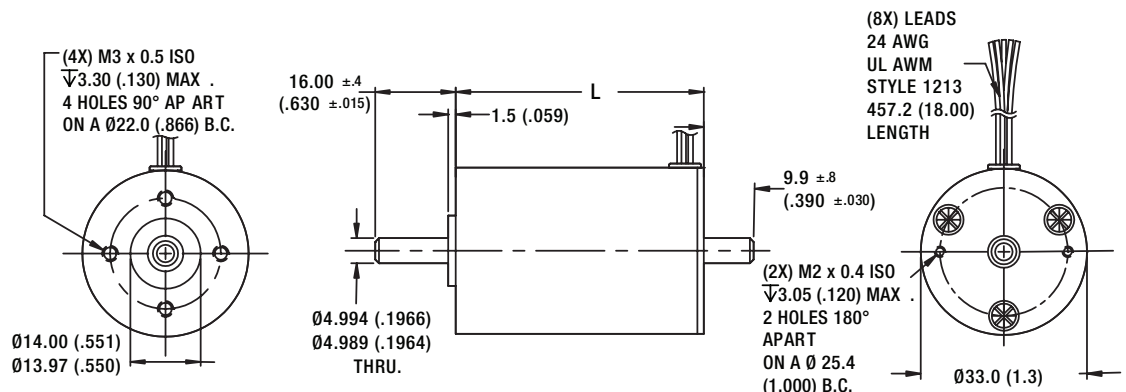
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

Dimensional Drawings: EC033A-1 • EC033A-2 • EC033A-3

Dimensions = mm (inches)

L = Lengths Available

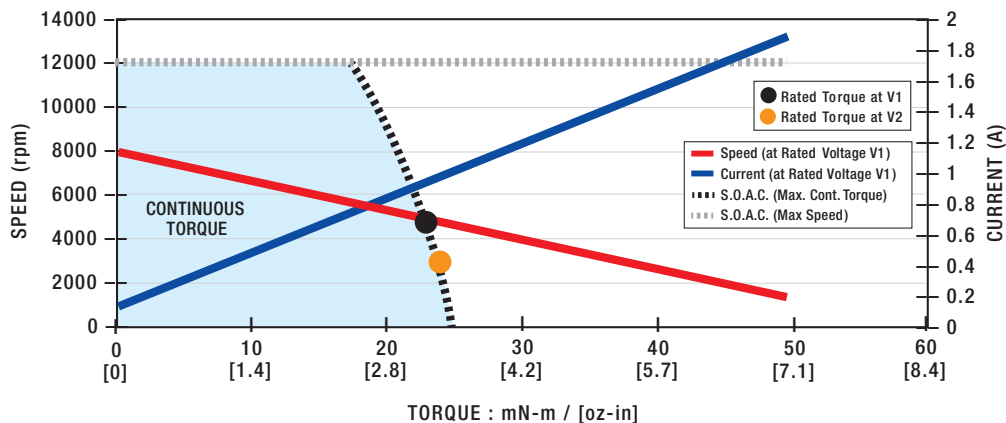
EC033A-1 = 38.1 (1.500) Max.
 EC033A-2 = 50.8 (2.000) Max.
 EC033A-3 = 63.5 (2.500) Max.



■ Performance Data & Graph: EC033A-1

Motor Data		Units								
Rated Voltage V1	V _r	V	4.78	6.00	7.58	9.55	12.0	15.2	19.1	24.0
Rated Torque ¹ •	T _r	Nm	0.024	0.024	0.023	0.023	0.023	0.023	0.023	0.023
		oz-in	3.4	3.4	3.3	3.3	3.3	3.3	3.3	3.3
Rated Speed ¹	ω _r	rpm	3430	3850	4090	4340	4540	4490	4620	4750
Rated Current ¹	I _r	A	4.9	3.9	2.9	2.4	1.9	1.4	1.2	0.93
Rated Power ¹	P _r	W	8.6	9.5	10	11	11	11	11	11
No Load Speed	ω _{nl}	rpm	6960	7020	6830	7020	7050	6900	7040	7080
No Load Current	I _{nl}	A	0.57	0.46	0.35	0.29	0.23	0.18	0.15	0.12
Rated Voltage V2	V _r	V	3.79	4.78	6.00	7.58	9.55	12.0	15.2	19.1
Rated Torque ¹ •	T _r	Nm	0.024	0.024	0.024	0.024	0.024	0.024	0.024	0.024
		oz-in	3.5	3.4	3.4	3.4	3.4	3.4	3.4	3.4
Rated Speed ¹	ω _r	rpm	1680	2120	2370	2590	2800	2730	2890	3000
Rated Current ¹	I _r	A	5.0	4.0	3.0	2.4	1.9	1.5	1.2	0.97
Rated Power ¹	P _r	W	4.3	5.4	6.0	6.5	7.0	6.9	7.2	7.5
No Load Speed	ω _{nl}	rpm	5460	5540	5360	5530	5570	5410	5560	5600
No Load Current	I _{nl}	A	0.55	0.44	0.34	0.28	0.22	0.17	0.14	0.11
Motor Constant	K _M	Nm/√W	0.0099	0.010	0.011	0.011	0.011	0.011	0.011	0.011
		oz-in/√W	1.4	1.5	1.5	1.5	1.6	1.6	1.6	1.6
Torque Constant	K _T	Nm/A	0.00622	0.00776	0.0101	0.0124	0.0156	0.0201	0.0248	0.0310
		oz-in/A	0.880	1.10	1.43	1.76	2.20	2.85	3.52	4.39
Voltage Constant	K _E	V/(rad/s)	0.00622	0.00776	0.0101	0.0124	0.0156	0.0201	0.0248	0.0310
		V/krpm	0.651	0.813	1.06	1.30	1.63	2.11	2.60	3.25
Terminal Resistance	R _{mt}	Ω	0.395	0.569	0.863	1.29	1.94	3.14	4.81	7.36
Inductance	L	mH	0.14	0.22	0.38	0.57	0.90	1.5	2.3	3.6
Peak Current	I _{pk}	A	12	11	8.8	7.4	6.0	4.8	3.9	3.0
Electrical Time Constant	τ _e	ms	0.36	0.39	0.44	0.44	0.46	0.48	0.48	0.49
Mechanical Time Constant	τ _m	ms	12	11	9.9	9.8	9.3	9.0	9.1	8.9

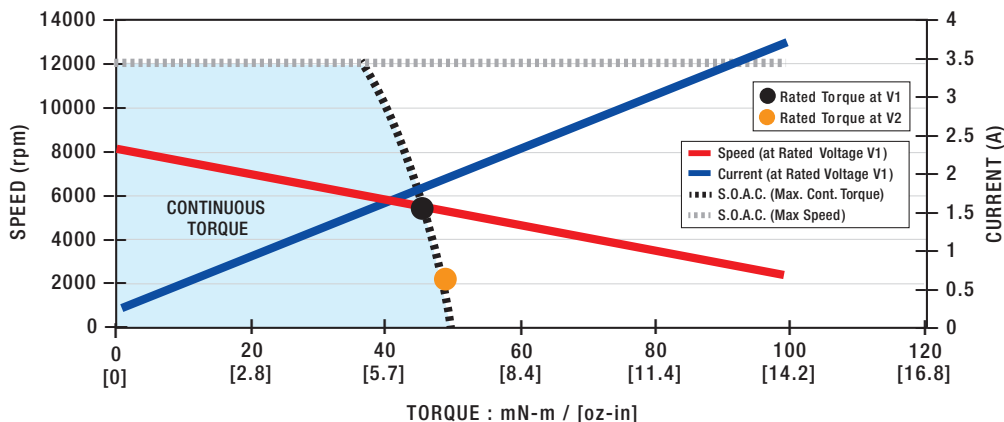
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n; for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC033A-2

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.047	0.046	0.046	0.046	0.046	0.046	0.045	0.045
		oz-in	6.6	6.6	6.5	6.5	6.5	6.5	6.4	6.4
Rated Speed ¹	ω _r	rpm	4780	4990	5060	5220	5350	5200	5350	5450
Rated Current ¹	I _r	A	4.6	3.7	2.8	2.3	1.8	1.4	1.1	0.90
Rated Power ¹	P _r	W	23	24	24	25	26	25	25	26
No Load Speed	ω _{nl}	rpm	7120	7140	7000	7140	7180	6970	7140	7180
No Load Current	I _{nl}	A	0.44	0.35	0.27	0.22	0.18	0.14	0.11	0.087
Rated Voltage V2	V _r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3
Rated Torque ¹ •	T _r	Nm	0.049	0.049	0.049	0.049	0.049	0.049	0.049	0.048
		oz-in	6.9	6.9	6.9	6.9	6.9	6.9	6.9	6.9
Rated Speed ¹	ω _r	rpm	1660	1890	1990	2090	2240	2160	2220	2330
Rated Current ¹	I _r	A	4.8	3.9	3.0	2.4	1.9	1.5	1.2	0.95
Rated Power ¹	P _r	W	8.5	9.7	10	11	11	11	11	12
No Load Speed	ω _{nl}	rpm	4420	4460	4350	4440	4500	4350	4440	4490
No Load Current	I _{nl}	A	0.40	0.32	0.25	0.20	0.17	0.13	0.10	0.080
Motor Constant	K _M	Nm/√W	0.016	0.017	0.017	0.017	0.018	0.018	0.018	0.018
		oz-in/√W	2.3	2.4	2.5	2.5	2.5	2.5	2.5	2.5
Torque Constant	K _T	Nm/A	0.0124	0.0156	0.0201	0.0248	0.0310	0.0404	0.0498	0.0622
		oz-in/A	1.76	2.20	2.85	3.52	4.39	5.72	7.05	8.80
Voltage Constant	K _E	V/(rad/s)	0.0124	0.0156	0.0201	0.0248	0.0310	0.0404	0.0498	0.0622
		V/krpm	1.30	1.63	2.11	2.60	3.25	4.23	5.21	6.51
Terminal Resistance	R _{mt}	Ω	0.584	0.870	1.35	2.06	3.13	5.12	7.88	12.1
Inductance	L	mH	0.27	0.42	0.71	1.1	1.7	2.9	4.3	6.8
Peak Current	I _{pk}	A	15	12	9.0	7.5	6.0	4.5	3.6	3.0
Electrical Time Constant	τ _e	ms	0.46	0.49	0.53	0.53	0.54	0.56	0.55	0.56
Mechanical Time Constant	τ _m	ms	7.4	7.0	6.5	6.5	6.3	6.1	6.2	6.1

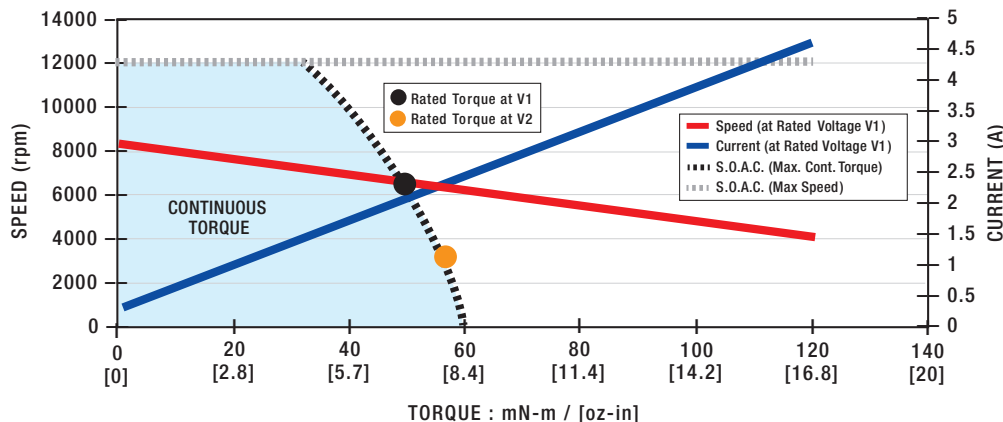
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC033A-3

Motor Data		Units								
Rated Voltage V1	V _R	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.0
Rated Torque ¹ •	T _R	Nm	0.052	0.051	0.050	0.049	0.049	0.048	0.049	0.049
		oz-in	7.3	7.2	7.1	7.0	6.9	6.9	6.9	6.9
Rated Speed ¹	ω _R	rpm	6060	6450	6590	6460	6670	6790	6550	6650
Rated Current ¹	I _R	A	4.3	3.4	2.7	2.1	1.7	1.3	1.0	0.83
Rated Power ¹	P _R	W	33	34	34	33	34	34	33	34
No Load Speed	ω _{nl}	rpm	7360	7610	7650	7400	7600	7660	7410	7520
No Load Current	I _{nl}	A	0.49	0.40	0.32	0.25	0.20	0.16	0.13	0.099
Rated Voltage V2	V _R	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _R	Nm	0.057	0.057	0.057	0.056	0.056	0.056	0.056	0.056
		oz-in	8.1	8.1	8.0	8.0	8.0	7.9	7.9	7.9
Rated Speed ¹	ω _R	rpm	2790	3030	3150	3170	3270	3340	3250	3340
Rated Current ¹	I _R	A	4.7	3.8	3.0	2.3	1.9	1.5	1.2	0.93
Rated Power ¹	P _R	W	17	18	19	19	19	20	19	20
No Load Speed	ω _{nl}	rpm	4600	4740	4760	4650	4750	4770	4640	4750
No Load Current	I _{nl}	A	0.45	0.37	0.29	0.23	0.19	0.15	0.12	0.090
Motor Constant	K _M	Nm/√W	0.021	0.021	0.022	0.022	0.022	0.022	0.023	0.023
		oz-in/√W	2.9	3.0	3.1	3.2	3.1	3.2	3.2	3.2
Torque Constant	K _T	Nm/A	0.0152	0.0186	0.0233	0.0303	0.0372	0.0466	0.0605	0.0746
		oz-in/A	2.15	2.64	3.30	4.29	5.27	6.60	8.57	10.6
Voltage Constant	K _E	V/(rad/s)	0.0152	0.0186	0.0233	0.0303	0.0372	0.0466	0.0605	0.0746
		V/krpm	1.59	1.95	2.44	3.17	3.90	4.88	6.34	7.81
Terminal Resistance	R _{mt}	Ω	0.532	0.774	1.17	1.84	2.82	4.32	7.10	11.0
Inductance	L	mH	0.26	0.39	0.62	1.0	1.6	2.5	4.2	6.3
Peak Current	I _{pk}	A	15	12	9.6	7.5	6.0	4.8	3.6	3.0
Electrical Time Constant	τ _e	ms	0.49	0.51	0.53	0.56	0.56	0.57	0.59	0.58
Mechanical Time Constant	τ _m	ms	6.3	6.1	5.9	5.5	5.5	5.4	5.3	5.3

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n; for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC042B Series

The EC042B Series Brushless DC Motor is an excellent choice for both power transmission and precision motion control applications. It is offered in 3 motor lengths with continuous torque from 0.064 - 0.170 Nm. The EC042B is a high torque density 4 pole model designed as an economical yet higher performance general purpose servo motor. It is a great choice if more torque is needed in a 42 mm motor.



Shown with optional assemblies.

Benefits

- Speeds up to 9,000 RPM possible
- DC bus voltage up to 96 VDC
- Large bearings for high side loads
- Metric mounting
- Eight standard windings per stack, special windings available

Optional Assemblies

- Encoders: E30C/D
- Gearboxes: PLG42S, PLG52
- Programmable Drives: PBL4850E, BGE3004A, BGE6015A

Motor Characteristics

Motor Data	Units	Series			
		EC042B-1	EC042B-2	EC042B-3	
Max DC Terminal Voltage	V_T	96			
Max Speed (Mechanical)	ω_{MAX}	9000			
Continuous Stall Torque ¹	T_{CS}	Nm	0.064	0.120	0.170
		oz-in	9.0	17	24
Peak Torque (Maximum) ¹	T_{pk}	Nm	0.38	0.39	0.55
		oz-in	54	55	79
Coulomb Friction Torque	T_f	Nm	0.0014	0.0028	0.0042
		oz-in	0.20	0.40	0.60
Viscous Damping Factor	D	V/(rad/s)	3.4E-06	4.7E-06	6.7E-06
		oz-in/krpm	0.050	0.070	0.10
Thermal Time Constant	τ_{th}	min	5.1	11	16
Thermal Resistance	R_{th}	°C/W	9.1	5.9	4.4
Max. Winding Temperature	θ_{MAX}	°C	105	105	105
Rotor Inertia	J_r	kg-m ²	1.4E-05	1.8E-05	2.1E-05
		oz-in-s ²	0.0021	0.0025	0.0029
Motor Weight	W_m	g	340	540	730
		oz	12	19	26

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC042B-1 • EC042B-2 • EC042B-3

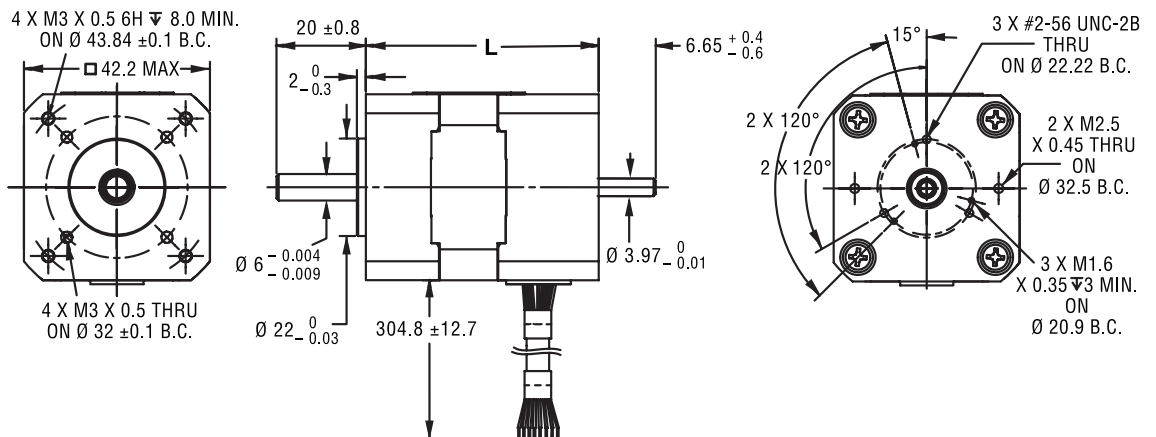
Dimensions = metric [mm]

L = Lengths Available

EC042B-1 = 54.5 mm

EC042B-2 = 74.5 mm

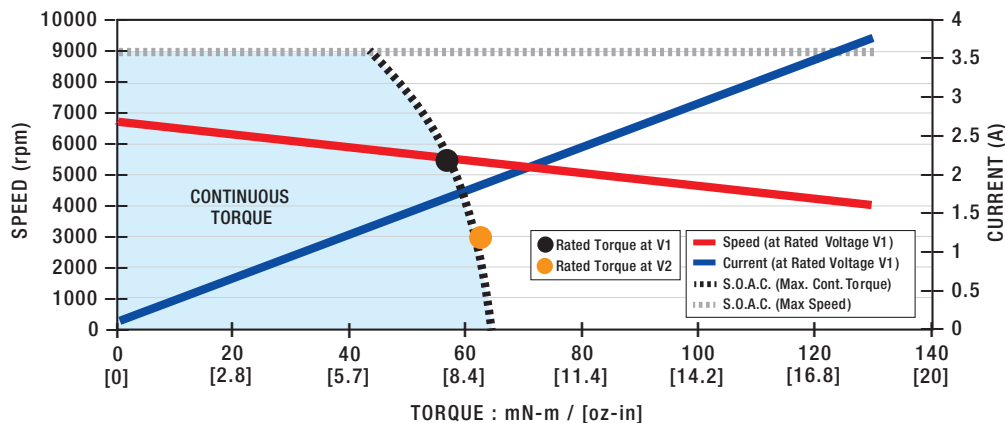
EC042B-3 = 94.5 mm



■ Performance Data & Graph: EC042B-1

Motor Data		Units										
Rated Voltage V1	V _r	V	12.0	15.2	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _r	Nm	0.057	0.057	0.057	0.057	0.058	0.058	0.058	0.056	0.056	0.058
		oz-in	8.1	8.1	8.1	8.1	8.2	8.2	8.2	8.0	8.0	8.2
Rated Speed ¹	ω _r	rpm	5380	5310	5380	5310	5360	5400	5530	5160	5100	5460
Rated Current ¹	I _r	A	3.4	2.7	3.4	2.7	2.2	1.8	1.4	1.0	0.82	0.70
Rated Power ¹	P _r	W	32	32	32	32	33	33	34	31	30	33
No Load Speed	ω _{nl}	rpm	6280	6210	6280	6210	6250	6280	6400	6090	6030	6340
No Load Current	I _{nl}	A	0.21	0.16	0.21	0.16	0.13	0.11	0.082	0.061	0.048	0.041
Rated Voltage V2	V _r	V	7.58	9.55	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.062	0.063	0.062	0.063	0.064	0.063	0.064	0.061	0.061	0.063
		oz-in	8.8	8.9	8.8	8.9	9.0	9.0	9.1	8.7	8.7	8.9
Rated Speed ¹	ω _r	rpm	2900	2840	2900	2840	2880	2930	2990	2740	2710	2950
Rated Current ¹	I _r	A	3.7	2.9	3.7	2.9	2.4	1.9	1.5	1.1	0.88	0.75
Rated Power ¹	P _r	W	19	19	19	19	19	19	20	18	17	19
No Load Speed	ω _{nl}	rpm	3960	3900	3960	3900	3920	3970	4030	3820	3800	3990
No Load Current	I _{nl}	A	0.16	0.13	0.16	0.13	0.097	0.079	0.064	0.047	0.037	0.032
Motor Constant	K _M	Nm/√W	0.027	0.027	0.027	0.027	0.028	0.027	0.028	0.027	0.026	0.027
		oz-in/√W	3.8	3.8	3.8	3.8	3.9	3.9	3.9	3.8	3.7	3.9
Torque Constant	K _T	Nm/A	0.0181	0.0231	0.0181	0.0231	0.0289	0.0361	0.0448	0.0592	0.0751	0.0903
		oz-in/A	2.56	3.27	2.56	3.27	4.09	5.11	6.34	8.39	10.6	12.8
Voltage Constant	K _E	V/(rad/s)	0.0181	0.0231	0.0181	0.0231	0.0289	0.0361	0.0448	0.0592	0.0751	0.0903
		V/krpm	1.89	2.42	1.89	2.42	3.03	3.78	4.69	6.20	7.87	9.46
Terminal Resistance	R _{mt}	Ω	0.446	0.724	0.446	0.724	1.10	1.72	2.61	4.97	8.05	10.9
Inductance	L	mH	0.57	0.94	0.57	0.94	1.5	2.3	3.5	6.2	9.9	14
Peak Current	I _{pk}	A	23	9.0	23	9.0	7.5	6.0	4.8	3.6	2.7	2.4
Electrical Time Constant	τ _e	ms	1.3	1.3	1.3	1.3	1.3	1.3	1.4	1.2	1.2	1.3
Mechanical Time Constant	τ _m	ms	20	20	20	20	19	19	19	20	21	19

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.

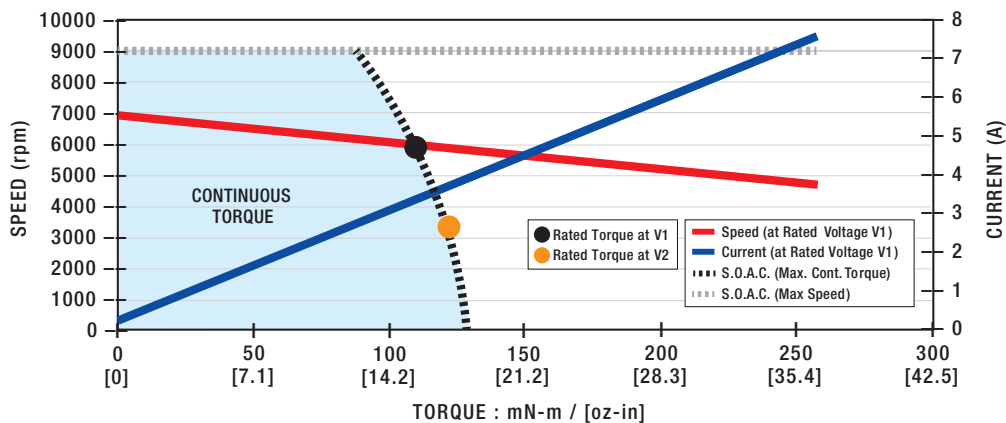


Performance Data & Graph: EC042B-2

Motor Data		Units								
Rated Voltage V1	V _r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _r	Nm	0.11	0.11	0.11	0.11	0.11	0.11	0.11	0.11
		oz-in	15	16	16	16	16	16	16	16
Rated Speed ¹	ω _r	rpm	5850	5810	5780	5850	5620	5620	5610	5700
Rated Current ¹	I _r	A	5.2	4.3	3.4	2.7	2.1	1.6	1.3	1.0
Rated Power ¹	P _r	W	66	67	68	69	65	65	65	65
No Load Speed	ω _{nl}	rpm	6490	6440	6410	6470	6270	6270	6260	6350
No Load Current	I _{nl}	A	0.28	0.22	0.17	0.14	0.11	0.082	0.065	0.053
Rated Voltage V2	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.12	0.12	0.12	0.12	0.12	0.12	0.12	0.12
		oz-in	17	17	18	18	17	17	17	17
Rated Speed ¹	ω _r	rpm	3260	3250	3270	3290	3130	3150	3140	3180
Rated Current ¹	I _r	A	5.7	4.7	3.8	3.0	2.3	1.8	1.4	1.1
Rated Power ¹	P _r	W	41	42	43	43	40	40	40	40
No Load Speed	ω _{nl}	rpm	4070	4040	4050	4080	3940	3960	3940	3990
No Load Current	I _{nl}	A	0.22	0.18	0.14	0.11	0.083	0.066	0.052	0.043
Motor Constant	K _M	Nm/√W	0.042	0.043	0.044	0.044	0.043	0.043	0.043	0.042
		oz-in/√W	5.9	6.1	6.2	6.2	6.0	6.1	6.0	6.0
Torque Constant	K _T	Nm/A	0.0222	0.0281	0.0355	0.0444	0.0577	0.0725	0.0918	0.114
		oz-in/A	3.14	3.98	5.03	6.29	8.17	10.3	13.0	16.1
Voltage Constant	K _E	V/(rad/s)	0.0222	0.0281	0.0355	0.0444	0.0577	0.0725	0.0918	0.114
		V/krpm	2.33	2.95	3.72	4.65	6.05	7.60	9.61	11.9
Terminal Resistance	R _{mt}	Ω	0.280	0.427	0.655	1.03	1.83	2.89	4.63	7.29
Inductance	L	mH	0.42	0.67	1.1	1.7	2.8	4.5	7.2	11
Peak Current	I _{pk}	A	18	15	12	9.6	7.2	5.7	4.5	3.6
Electrical Time Constant	τ _e	ms	1.5	1.6	1.6	1.6	1.5	1.5	1.5	1.5
Mechanical Time Constant	τ _m	ms	10	9.5	9.2	9.2	9.7	9.7	9.7	9.9

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).

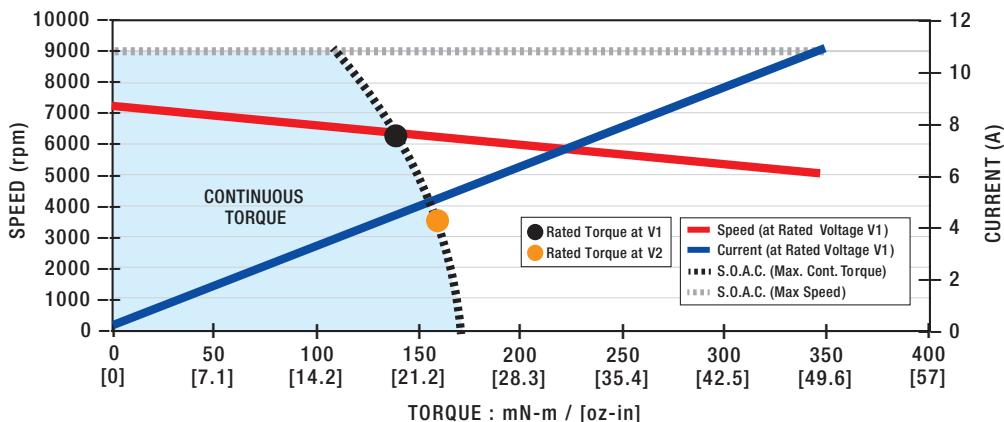
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC042B-3

Motor Data		Units								
Rated Voltage V1	V_r	V	19.1	24.0	30.3	38.2	48.0	60.6	76.4	96.0
Rated Torque ¹ •	T_r	Nm	0.14	0.14	0.15	0.15	0.15	0.15	0.15	0.15
		oz-in	20	20	21	21	21	21	21	21
Rated Speed ¹	ω_r	rpm	6170	6220	6210	6190	6000	6220	6200	6240
Rated Current ¹	I_r	A	5.8	4.6	3.8	3.0	2.4	1.9	1.5	1.2
Rated Power ¹	P_r	W	91	93	95	95	95	98	97	98
No Load Speed	ω_{nl}	rpm	6710	6750	6730	6720	6540	6730	6720	6750
No Load Current	I_{nl}	A	0.34	0.27	0.22	0.17	0.13	0.11	0.084	0.067
Rated Voltage V2	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.16	0.16	0.17	0.17	0.17	0.17	0.17	0.17
		oz-in	23	23	24	24	24	24	24	24
Rated Speed ¹	ω_r	rpm	3470	3540	3520	3490	3410	3540	3510	3560
Rated Current ¹	I_r	A	6.4	5.2	4.2	3.3	2.6	2.1	1.7	1.4
Rated Power ¹	P_r	W	58	60	62	61	61	63	62	64
No Load Speed	ω_{nl}	rpm	4210	4270	4240	4220	4120	4240	4220	4260
No Load Current	I_{nl}	A	0.27	0.22	0.17	0.14	0.11	0.085	0.067	0.054
Motor Constant	K_M	Nm/ \sqrt{W}	0.050	0.051	0.052	0.052	0.053	0.053	0.053	0.053
		oz-in/ \sqrt{W}	7.1	7.2	7.4	7.3	7.5	7.5	7.5	7.6
Torque Constant	K_T	Nm/A	0.0270	0.0337	0.0427	0.0539	0.0696	0.0854	0.108	0.135
		oz-in/A	3.82	4.77	6.04	7.64	9.86	12.1	15.3	19.1
Voltage Constant	K_E	V/(rad/s)	0.0270	0.0337	0.0427	0.0539	0.0696	0.0854	0.108	0.135
		V/krpm	2.82	3.53	4.47	5.65	7.29	8.94	11.3	14.1
Terminal Resistance	R_{mt}	Ω	0.289	0.441	0.670	1.09	1.74	2.58	4.16	6.38
Inductance	L	mH	0.41	0.65	1.0	1.7	2.8	4.1	6.6	10
Peak Current	I_{pk}	A	21	17	14	11	8.4	6.9	5.4	4.5
Electrical Time Constant	τ_e	ms	1.4	1.5	1.5	1.5	1.6	1.6	1.6	1.6
Mechanical Time Constant	τ_m	ms	8.3	8.1	7.6	7.8	7.5	7.3	7.4	7.3

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC044A Series

The EC044A Series Brushless DC Motor is a medium torque density 4 pole model designed as an economical upgrade to brushed motors. The EC044A is an excellent choice for both power transmission and precision motion control applications. It is offered in 3 motor lengths with continuous torque from 0.043 – 0.081 Nm in a 44 mm diameter.



Shown with optional assemblies.

Benefits

- Speeds up to 15,000 RPM possible
- DC bus voltage up to 48 VDC
- Metric mounting
- Eight standard windings per stack, special windings available

Optional Assemblies

- Encoders: E30C/D
- Gearboxes: PLG42S, G51A, PLG52
- Brake: B30A
- Programmable Drives: PBL4850E, BGE3004A, BGE6015A

Motor Characteristics

Motor Data	Units	Series		
		EC044A-1	EC044A-2	EC044A-3
Max DC Terminal Voltage V_T	V	48		
Max Speed (Mechanical) ω_{MAX}	rpm	15000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.043	0.065	0.081
	oz-in	6.0	9.2	11
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.20	0.36	0.45
	oz-in	29	51	64
Coulomb Friction Torque T_f	Nm	0.0028	0.0028	0.0028
	oz-in	0.40	0.40	0.40
Viscous Damping Factor D	Nm/(rad/s)	2.0E-06	4.0E-06	5.4E-06
	oz-in/krpm	0.030	0.060	0.080
Thermal Time Constant τ_{th}	min	5.4	9.0	13
Thermal Resistance R_{th}	°C/W	10	8.5	7.5
Max. Winding Temperature θ_{MAX}	°C	125	125	125
Rotor Inertia J_r	kg-m ²	2.1E-06	3.0E-06	4.0E-06
	oz-in-s ²	3.0E-04	4.2E-04	5.6E-04
Motor Weight W_m	g	260	350	430
	oz	9.2	12	15

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC044A-1 • EC044A-2 • EC044A-3

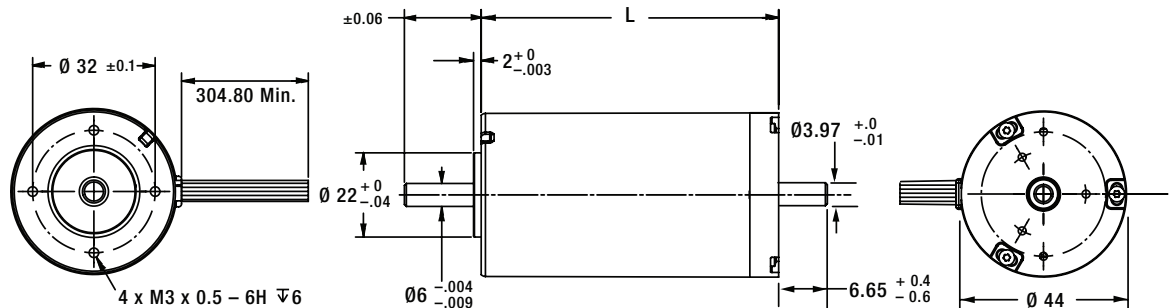
Dimensions = metric (mm)

L = Lengths Available

EC044A-1 = 52.3 mm

EC044A-2 = 65.0 mm

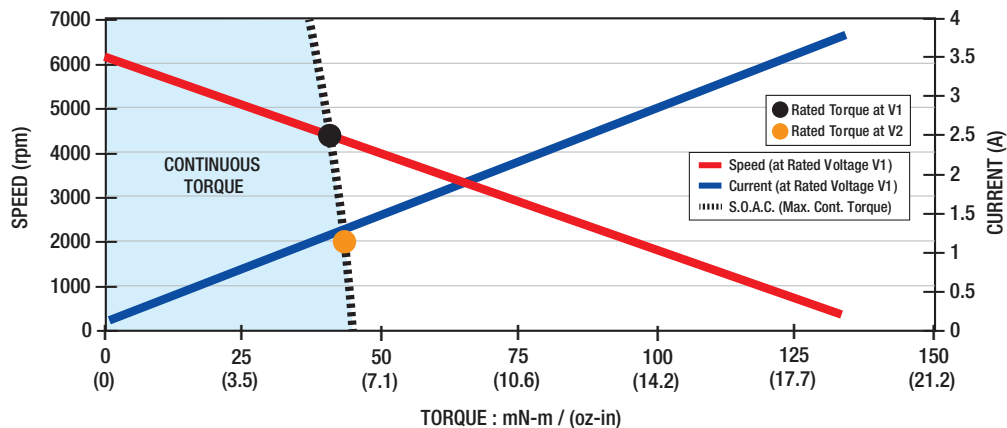
EC044A-3 = 77.7 mm



■ Performance Data & Graph: EC044A-1

Motor Data		Units								
Rated Voltage V1	V _R	V	7.58	9.55	12.0	15.2	19.1	24.0	30.2	38.1
Rated Torque ¹ •	T _R	Nm	0.039	0.041	0.041	0.041	0.041	0.041	0.041	0.041
		oz-in	5.6	5.8	5.8	5.8	5.8	5.8	5.8	5.8
Rated Speed ¹	ω _R	rpm	4240	4060	4130	4190	4190	4250	4140	4240
Rated Current ¹	I _R	A	3.7	2.9	2.3	1.9	1.5	1.2	0.93	0.74
Rated Power ¹	P _R	W	17	17	18	18	18	18	18	18
No Load Speed	ω _{nl}	rpm	5490	5280	5340	5370	5380	5430	5340	5420
No Load Current	I _{nl}	A	0.31	0.24	0.19	0.15	0.12	0.097	0.075	0.061
Rated Voltage V2	V _R	V	4.78	6.00	7.58	9.55	12.0	15.2	19.1	24.0
Rated Torque ¹ •	T _R	Nm	0.042	0.043	0.043	0.044	0.043	0.044	0.044	0.044
		oz-in	5.9	6.2	6.1	6.2	6.1	6.2	6.2	6.2
Rated Speed ¹	ω _R	rpm	1880	1780	1850	1880	1880	1940	1870	1910
Rated Current ¹	I _R	A	3.9	3.1	2.5	2.0	1.6	1.3	0.99	0.78
Rated Power ¹	P _R	W	8.2	8.1	8.4	8.6	8.5	8.9	8.6	8.7
No Load Speed	ω _{nl}	rpm	3440	3290	3350	3350	3350	3420	3350	3390
No Load Current	I _{nl}	A	0.28	0.21	0.17	0.14	0.11	0.086	0.067	0.054
Motor Constant	K _M	Nm/√W	0.019	0.020	0.020	0.020	0.020	0.020	0.020	0.020
		oz-in/√W	2.7	2.8	2.8	2.9	2.8	2.8	2.9	2.8
Torque Constant	K _T	Nm/A	0.0129	0.0169	0.0210	0.0265	0.0332	0.0413	0.0529	0.0658
		oz-in/A	1.83	2.39	2.98	3.75	4.71	5.86	7.49	9.32
Voltage Constant	K _E	V/(rad/s)	0.0129	0.0169	0.0210	0.0265	0.0332	0.0413	0.0529	0.0658
		V/krpm	1.35	1.77	2.20	2.77	3.48	4.33	5.54	6.89
Terminal Resistance	R _{mt}	Ω	0.450	0.720	1.11	1.73	2.75	4.24	6.90	10.8
Inductance	L	mH	0.31	0.54	0.83	1.3	2.1	3.2	5.2	8.1
Peak Current	I _{pk}	A	17	13	11	8.8	6.9	5.7	4.4	3.5
Electrical Time Constant	τ _e	ms	0.69	0.75	0.75	0.76	0.75	0.76	0.76	0.75
Mechanical Time Constant	τ _m	ms	5.7	5.3	5.3	5.2	5.3	5.3	5.2	5.3

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

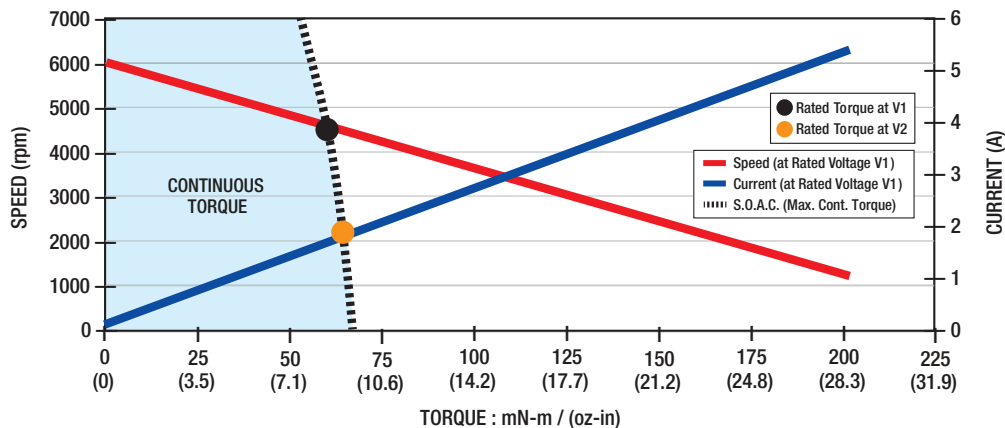


Performance Data & Graph: EC044A-2

Motor Data		Units								
Rated Voltage V1	V _r	V	12.0	15.2	19.1	24.0	30.2	38.1	48.0	48.0
Rated Torque ¹ •	T _r	Nm	0.059	0.061	0.061	0.061	0.061	0.060	0.061	0.063
		oz-in	8.3	8.7	8.6	8.6	8.7	8.6	8.6	8.9
Rated Speed ¹	ω _r	rpm	4550	4360	4430	4440	4430	4530	4440	3220
Rated Current ¹	I _r	A	3.4	2.7	2.1	1.7	1.4	1.1	0.85	0.71
Rated Power ¹	P _r	W	28	28	28	28	28	29	28	21
No Load Speed	ω _{nl}	rpm	5470	5270	5340	5330	5340	5410	5340	4280
No Load Current	I _{nl}	A	0.25	0.19	0.16	0.13	0.096	0.078	0.061	0.045
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	38.1	48.0
Rated Torque ¹ •	T _r	Nm	0.064	0.066	0.065	0.066	0.066	0.065	0.064	0.063
		oz-in	9.0	9.3	9.3	9.3	9.3	9.3	9.0	8.9
Rated Speed ¹	ω _r	rpm	2220	2100	2140	2180	2160	2220	3160	3220
Rated Current ¹	I _r	A	3.6	2.8	2.3	1.8	1.4	1.2	0.89	0.71
Rated Power ¹	P _r	W	15	15	15	15	15	15	21	21
No Load Speed	ω _{nl}	rpm	3440	3300	3340	3370	3360	3400	4230	4280
No Load Current	I _{nl}	A	0.21	0.16	0.13	0.11	0.080	0.065	0.055	0.045
Motor Constant	K _M	Nm/√W	0.026	0.027	0.027	0.027	0.027	0.027	0.027	0.027
		oz-in/√W	3.7	3.8	3.8	3.8	3.8	3.8	3.8	3.8
Torque Constant	K _T	Nm/A	0.0206	0.0271	0.0336	0.0423	0.0532	0.0662	0.0846	0.105
		oz-in/A	2.92	3.84	4.76	5.99	7.53	9.37	12.0	14.9
Voltage Constant	K _E	V/(rad/s)	0.0206	0.0271	0.0336	0.0423	0.0532	0.0662	0.0846	0.105
		V/krpm	2.16	2.84	3.52	4.43	5.57	6.93	8.86	11.0
Terminal Resistance	R _{mt}	Ω	0.629	1.02	1.59	2.49	3.96	6.10	9.95	15.6
Inductance	L	mH	0.50	0.86	1.3	2.1	3.3	5.1	8.4	13
Peak Current	I _{pk}	A	19	15	12	9.6	7.6	6.2	4.8	3.1
Electrical Time Constant	τ _e	ms	0.79	0.84	0.83	0.84	0.83	0.84	0.84	0.83
Mechanical Time Constant	τ _m	ms	4.4	4.1	4.2	4.1	4.2	4.1	4.1	4.2

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/r: for example, DC030C-1 (3.31 V/krpm).

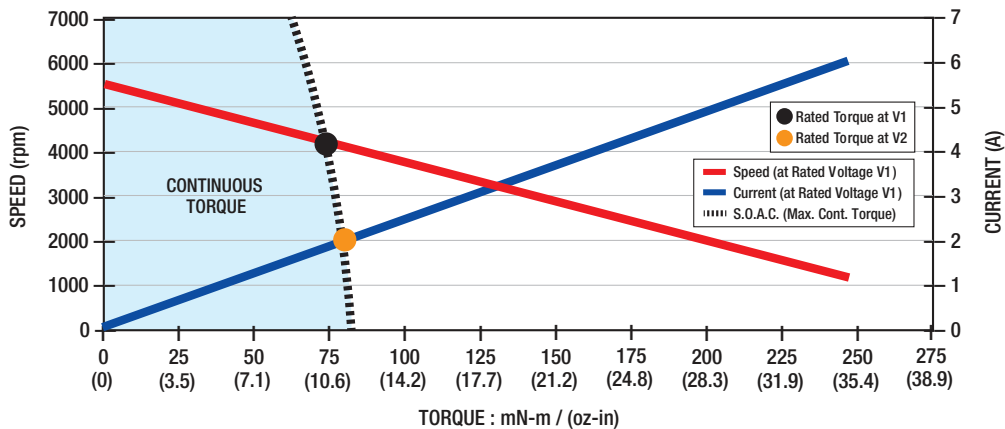
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC044A-3

Motor Data		Units									
Rated Voltage V1	V_R	V	15.2	19.1	24.0	30.2	38.1	48.0	48.0	48.0	
Rated Torque ¹ •	T_R	Nm	0.073	0.075	0.075	0.075	0.075	0.075	0.075	0.079	0.081
		oz-in	10	11	11	11	11	11	11	11	11
Rated Speed ¹	ω_R	rpm	4260	4040	4110	4110	4120	4200	2940	2060	
Rated Current ¹	I_R	A	3.0	2.4	1.9	1.5	1.2	0.97	0.80	0.65	
Rated Power ¹	P_R	W	32	32	32	32	32	33	24	17	
No Load Speed	ω_{nl}	rpm	5050	4830	4890	4890	4910	4980	3880	3120	
No Load Current	I_{nl}	A	0.20	0.15	0.13	0.097	0.078	0.062	0.044	0.032	
Rated Voltage V2	V_R	V	9.52	12.0	15.2	19.1	24.0	30.2	38.1	38.1	
Rated Torque ¹ •	T_R	Nm	0.079	0.081	0.080	0.081	0.081	0.081	0.081	0.081	0.082
		oz-in	11	11	11	11	11	11	11	12	12
Rated Speed ¹	ω_R	rpm	2080	1970	2040	2040	2030	2070	2020	1320	
Rated Current ¹	I_R	A	3.2	2.5	2.0	1.6	1.3	1.0	0.81	0.66	
Rated Power ¹	P_R	W	17	17	17	17	17	18	17	11	
No Load Speed	ω_{nl}	rpm	3150	3030	3090	3090	3090	3120	3080	2470	
No Load Current	I_{nl}	A	0.17	0.13	0.099	0.079	0.063	0.051	0.040	0.030	
Motor Constant	K_M	Nm/√W	0.031	0.031	0.031	0.031	0.031	0.031	0.031	0.031	0.031
		oz-in/√W	4.3	4.5	4.4	4.5	4.4	4.5	4.5	4.5	4.4
Torque Constant	K_T	Nm/A	0.0284	0.0372	0.0462	0.0582	0.0731	0.0909	0.116	0.145	
		oz-in/A	4.02	5.27	6.55	8.24	10.3	12.9	16.5	20.5	
Voltage Constant	K_E	V/(rad/s)	0.0284	0.0372	0.0462	0.0582	0.0731	0.0909	0.116	0.145	
		V/krpm	2.97	3.90	4.84	6.09	7.65	9.52	12.2	15.1	
Terminal Resistance	R_{mt}	Ω	0.860	1.40	2.18	3.42	5.44	8.40	13.7	21.5	
Inductance	L	mH	0.68	1.2	1.8	2.9	4.5	7.0	11	18	
Peak Current	I_{pk}	A	18	14	11	8.8	7.0	5.7	3.5	2.2	
Electrical Time Constant	τ_e	ms	0.79	0.84	0.83	0.84	0.83	0.83	0.83	0.82	
Mechanical Time Constant	τ_m	ms	4.2	4.0	4.0	4.0	4.0	4.0	4.0	4.0	

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC057C Series



The EC057C Series Brushless DC Motor is a high torque density model brushless motor in a NEMA 23 configuration. It is offered in 4 motor lengths with continuous torque from 0.078 – 0.280 Nm.

■ Benefits

- Speeds up to 12,000 RPM possible
- DC bus voltage up to 76.4 VDC
- NEMA 23 configuration
- Eight standard windings per stack, special windings available
- 4 Pole rare earth design

■ Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G40A, PLG42S, G51A, PLG52
- Brake: B49A
- Programmable Drives: BGE3004A, BGE6015A

■ Motor Characteristics

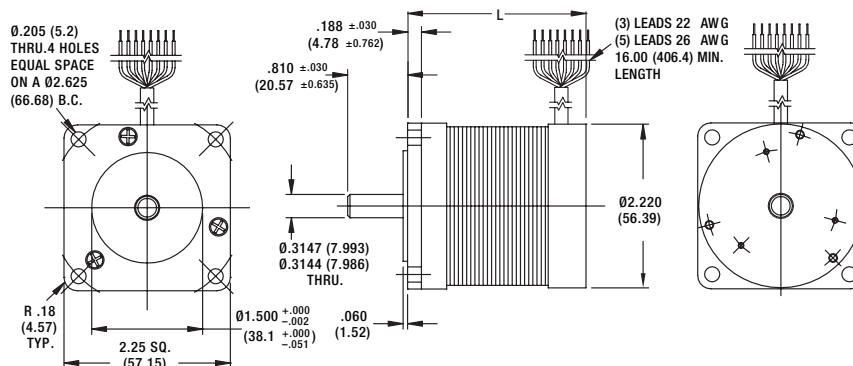
Motor Data	Units	Series			
		EC057C-1	EC057C-2	EC057C-3	EC057C-4
Max DC Terminal Voltage V_T	V	90			
Max Speed (Mechanical) ω_{MAX}	rpm	12000			
Continuous Stall Torque ¹ T_{CS}	Nm	0.078	0.140	0.220	0.280
	oz-in	11	20	31	40
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.25	0.44	0.70	0.88
	oz-in	36	63	99	130
Coulomb Friction Torque T_f	Nm	0.0066	0.0078	0.0092	0.011
	oz-in	0.93	1.1	1.3	1.5
Viscous Damping Factor D	Nm/(rad/s)	8.1E-07	2.1E-06	3.5E-06	4.9E-06
	oz-in/krpm	0.012	0.031	0.052	0.072
Thermal Time Constant τ_{th}	min	13	17	21	25
Thermal Resistance R_{th}	°C/W	11	7.9	5.2	4.7
Max. Winding Temperature Θ_{MAX}	°C	130	130	130	130
Rotor Inertia J_r	kg-m ²	4.2E-06	7.8E-06	1.1E-05	1.5E-05
	oz-in-s ²	6.0E-04	0.0011	0.0016	0.0021
Motor Weight W_m	g	370	510	670	830
	oz	13	18	24	29

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC057C-1 • EC057C-2 • EC057C-3 • EC057C-4

Dimensions = inches (mm)

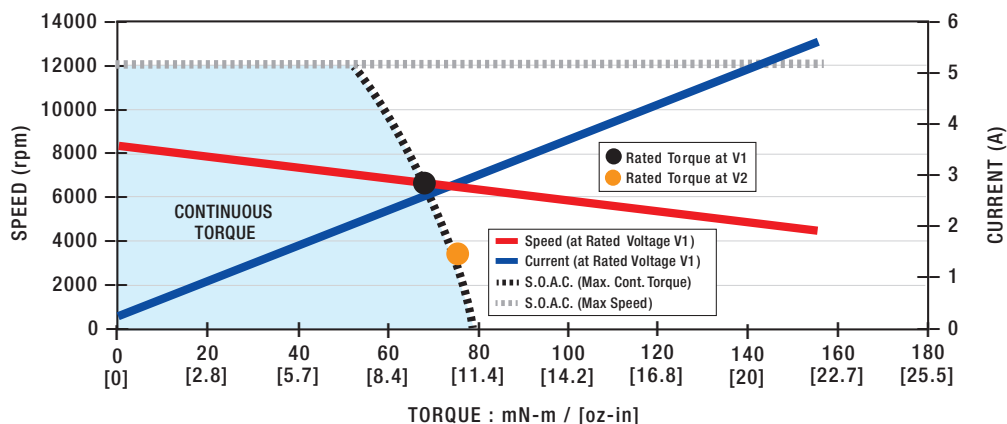
L = Lengths Available
 EC057C-1 = 1.464 (37.19) Max.
 EC057C-2 = 1.914 (48.62) Max.
 EC057C-3 = 2.414 (61.32) Max.
 EC057C-4 = 2.914 (74.02) Max.



■ Performance Data & Graph: EC057C-1

Motor Data		Units									
Rated Voltage V1	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0	
Rated Torque ¹ •	T_r	Nm	0.071	0.070	0.069	0.068	0.068	0.067	0.067	0.067	
		oz-in	10	9.9	9.7	9.6	9.6	9.5	9.5	9.5	
Rated Speed ¹	ω_r	rpm	6290	6260	6590	6700	6540	6740	6820	6590	
Rated Current ¹	I_r	A	7.2	5.5	4.4	3.5	2.7	2.1	1.7	1.3	
Rated Power ¹	P_r	W	47	46	47	48	46	47	48	46	
No Load Speed	ω_{nl}	rpm	7610	7360	7580	7630	7390	7580	7630	7380	
No Load Current	I_{nl}	A	0.62	0.48	0.39	0.31	0.24	0.20	0.16	0.12	
Rated Voltage V2	V_r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3	
Rated Torque ¹ •	T_r	Nm	0.077	0.076	0.076	0.075	0.075	0.075	0.075	0.075	
		oz-in	11	11	11	11	11	11	11	11	
Rated Speed ¹	ω_r	rpm	3070	3180	3380	3460	3440	3540	3570	3480	
Rated Current ¹	I_r	A	7.8	5.9	4.8	3.8	2.9	2.4	1.9	1.4	
Rated Power ¹	P_r	W	25	25	27	27	27	28	28	27	
No Load Speed	ω_{nl}	rpm	4740	4620	4730	4760	4650	4750	4770	4630	
No Load Current	I_{nl}	A	0.60	0.46	0.38	0.30	0.23	0.19	0.15	0.12	
Motor Constant	K_M	Nm/√W	0.025	0.027	0.027	0.028	0.028	0.028	0.028	0.029	
		oz-in/√W	3.5	3.8	3.8	3.9	4.0	4.0	4.0	4.1	
Torque Constant	K_T	Nm/A	0.0117	0.0153	0.0188	0.0235	0.0305	0.0375	0.0470	0.0610	
		oz-in/A	1.66	2.16	2.66	3.33	4.31	5.31	6.65	8.64	
Voltage Constant	K_E	V/(rad/s)	0.0117	0.0153	0.0188	0.0235	0.0305	0.0375	0.0470	0.0610	
		V/krpm	1.23	1.60	1.97	2.46	3.19	3.93	4.92	6.39	
Terminal Resistance	R_{mt}	Ω	0.220	0.330	0.480	0.730	1.16	1.77	2.76	4.50	
Inductance	L	mH	0.24	0.41	0.62	0.97	1.6	2.5	3.9	6.5	
Peak Current	I_{pk}	A	25	19	15	12	9.6	7.8	6.3	4.8	
Electrical Time Constant	τ_e	ms	1.1	1.2	1.3	1.3	1.4	1.4	1.4	1.5	
Mechanical Time Constant	τ_m	ms	6.8	6.0	5.8	5.6	5.3	5.3	5.3	5.1	

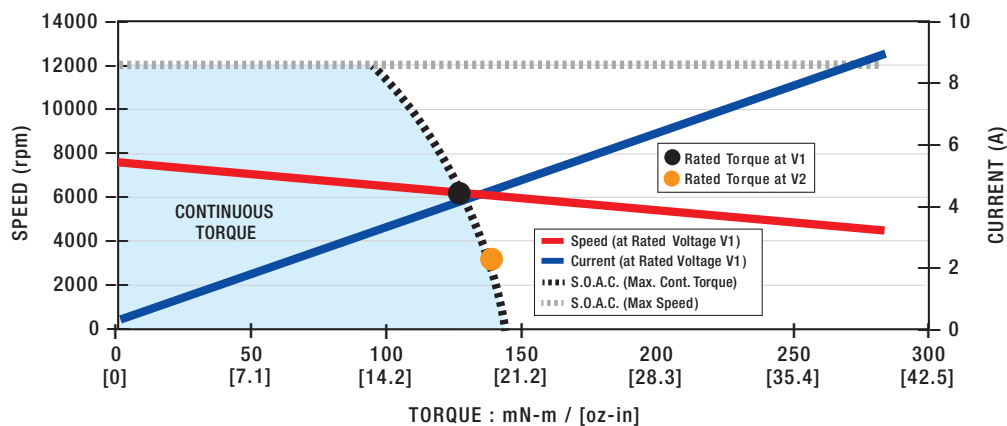
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC057C-2

Motor Data		Units								
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.13	0.13	0.13	0.13	0.13	0.13	0.13	0.13
		oz-in	19	18	18	18	18	18	18	18
Rated Speed ¹	ω_r	rpm	5690	5890	5780	5980	6090	5930	6070	6070
Rated Current ¹	I_r	A	8.9	7.1	5.4	4.3	3.4	2.6	2.1	1.7
Rated Power ¹	P_r	W	79	80	78	80	81	78	80	80
No Load Speed	ω_{nl}	rpm	6620	6730	6490	6630	6700	6500	6640	6690
No Load Current	I_{nl}	A	0.54	0.44	0.34	0.27	0.22	0.17	0.14	0.11
Rated Voltage V2	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.14	0.14	0.14	0.14	0.14	0.14	0.14	0.14
		oz-in	20	20	20	20	20	20	19	20
Rated Speed ¹	ω_r	rpm	2970	3100	3080	3260	3310	3220	3320	3310
Rated Current ¹	I_r	A	9.5	7.6	5.8	4.6	3.7	2.9	2.3	1.9
Rated Power ¹	P_r	W	44	45	45	47	48	46	48	48
No Load Speed	ω_{nl}	rpm	4160	4210	4060	4180	4210	4070	4180	4210
No Load Current	I_{nl}	A	0.51	0.41	0.32	0.26	0.21	0.16	0.13	0.11
Motor Constant	K_M	Nm/ \sqrt{W}	0.039	0.040	0.042	0.043	0.043	0.044	0.044	0.044
		oz-in/ \sqrt{W}	5.6	5.7	6.0	6.1	6.1	6.3	6.3	6.2
Torque Constant	K_T	Nm/A	0.0171	0.0213	0.0278	0.0342	0.0427	0.0555	0.0683	0.0855
		oz-in/A	2.42	3.02	3.94	4.84	6.04	7.86	9.67	12.1
Voltage Constant	K_E	V/(rad/s)	0.0171	0.0213	0.0278	0.0342	0.0427	0.0555	0.0683	0.0855
		V/krpm	1.79	2.23	2.91	3.58	4.47	5.81	7.15	8.95
Terminal Resistance	R_{mt}	Ω	0.190	0.280	0.430	0.630	0.970	1.56	2.39	3.84
Inductance	L	mH	0.28	0.44	0.74	1.1	1.8	3.0	4.5	7.4
Peak Current	I_{pk}	A	30	24	18	15	12	9.3	7.5	6.0
Electrical Time Constant	τ_e	ms	1.5	1.6	1.7	1.8	1.8	1.9	1.9	1.9
Mechanical Time Constant	τ_m	ms	5.1	4.8	4.3	4.2	4.1	3.9	4.0	4.1

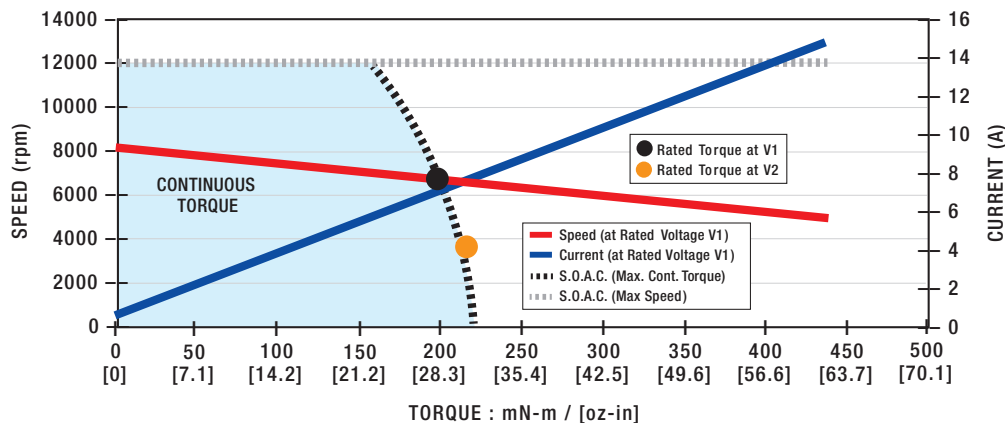
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC057C-3

Motor Data	Units									
Rated Voltage V1	V _R	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _R	Nm	0.21	0.21	0.20	0.20	0.20	0.20	0.19	0.19
		oz-in	30	29	29	28	28	28	28	27
Rated Speed ¹	ω _R	rpm	5940	6060	6340	6470	6360	6570	6630	6460
Rated Current ¹	I _R	A	15	11	9.0	7.1	5.4	4.4	3.5	2.7
Rated Power ¹	P _R	W	130	130	130	140	130	130	140	130
No Load Speed	ω _{nl}	rpm	7060	6900	7060	7100	6890	7070	7090	6880
No Load Current	I _{nl}	A	0.74	0.57	0.47	0.37	0.29	0.23	0.19	0.15
Rated Voltage V2	V _R	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _R	Nm	0.22	0.22	0.22	0.22	0.22	0.21	0.21	0.21
		oz-in	31	31	31	31	30	30	30	30
Rated Speed ¹	ω _R	rpm	3080	3220	3430	3590	3540	3650	3720	3630
Rated Current ¹	I _R	A	16	12	9.6	7.7	5.8	4.7	3.8	2.9
Rated Power ¹	P _R	W	71	74	78	81	80	82	83	81
No Load Speed	ω _{nl}	rpm	4450	4330	4430	4490	4330	4430	4470	4330
No Load Current	I _{nl}	A	0.68	0.52	0.43	0.34	0.26	0.22	0.17	0.13
Motor Constant	K _M	Nm/√W	0.046	0.051	0.052	0.054	0.057	0.057	0.058	0.059
		oz-in/√W	6.6	7.2	7.4	7.7	8.0	8.1	8.1	8.3
Torque Constant	K _T	Nm/A	0.0160	0.0208	0.0256	0.0320	0.0416	0.0512	0.0641	0.0834
		oz-in/A	2.27	2.95	3.62	4.53	5.90	7.25	9.07	11.8
Voltage Constant	K _E	V/(rad/s)	0.0160	0.0208	0.0256	0.0320	0.0416	0.0512	0.0641	0.0834
		V/krpm	1.68	2.18	2.68	3.35	4.36	5.36	6.71	8.73
Terminal Resistance	R _{mt}	Ω	0.120	0.170	0.240	0.350	0.540	0.810	1.24	2.00
Inductance	L	mH	0.17	0.28	0.42	0.66	1.1	1.7	2.6	4.5
Peak Current	I _{pk}	A	48	39	30	25	19	15	12	9.3
Electrical Time Constant	τ _e	ms	1.4	1.6	1.8	1.9	2.1	2.1	2.1	2.2
Mechanical Time Constant	τ _m	ms	5.3	4.4	4.1	3.9	3.5	3.5	3.4	3.3

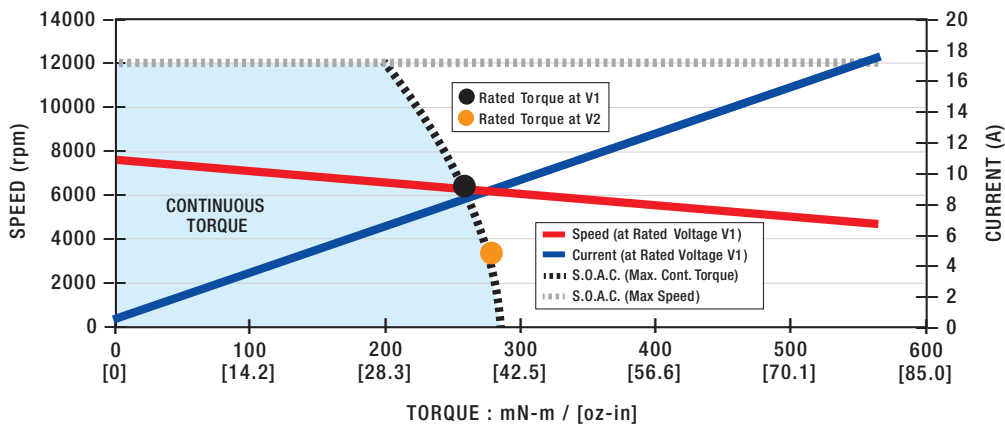
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC057C-4

Motor Data		Units								
Rated Voltage V1	V_r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T_r	Nm	0.27	0.26	0.26	0.26	0.25	0.25	0.25	0.25
		oz-in	38	37	37	36	36	36	35	35
Rated Speed ¹	ω_r	rpm	5870	5850	6110	6270	6120	6280	6360	6190
Rated Current ¹	I_r	A	14	11	8.6	6.8	5.2	4.2	3.3	2.6
Rated Power ¹	P_r	W	170	160	170	170	160	170	170	160
No Load Speed	ω_{nl}	rpm	6750	6510	6650	6730	6530	6660	6720	6540
No Load Current	I_{nl}	A	0.66	0.50	0.41	0.33	0.26	0.21	0.17	0.13
Rated Voltage V2	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.28	0.28	0.28	0.28	0.28	0.28	0.28	0.28
		oz-in	40	40	40	39	39	39	39	39
Rated Speed ¹	ω_r	rpm	3100	3180	3410	3510	3430	3550	3600	3490
Rated Current ¹	I_r	A	15	11	9.2	7.3	5.6	4.6	3.6	2.8
Rated Power ¹	P_r	W	92	94	100	100	99	100	100	100
No Load Speed	ω_{nl}	rpm	4230	4080	4200	4230	4090	4200	4230	4100
No Load Current	I_{nl}	A	0.60	0.46	0.38	0.30	0.23	0.19	0.15	0.12
Motor Constant	K_M	Nm/√W	0.057	0.062	0.065	0.067	0.069	0.069	0.070	0.071
		oz-in/√W	8.1	8.8	9.1	9.4	9.7	9.8	9.8	10
Torque Constant	K_T	Nm/A	0.0213	0.0278	0.0342	0.0427	0.0555	0.0683	0.0855	0.111
		oz-in/A	3.02	3.94	4.84	6.04	7.86	9.67	12.1	15.7
Voltage Constant	K_E	V/(rad/s)	0.0213	0.0278	0.0342	0.0427	0.0555	0.0683	0.0855	0.111
		V/krpm	2.23	2.91	3.58	4.47	5.81	7.15	8.95	11.6
Terminal Resistance	R_{mt}	Ω	0.140	0.200	0.280	0.410	0.650	0.980	1.51	2.45
Inductance	L	mH	0.22	0.37	0.56	0.88	1.5	2.3	3.5	6.0
Peak Current	I_{pk}	A	48	36	29	24	18	15	12	9.0
Electrical Time Constant	τ_e	ms	1.6	1.9	2.0	2.1	2.3	2.3	2.3	2.4
Mechanical Time Constant	τ_m	ms	4.6	3.8	3.6	3.3	3.1	3.1	3.1	3.0

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC057B Series

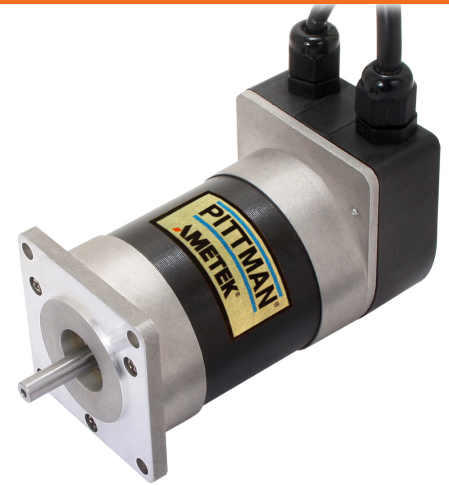
The EC057B Series Brushless DC Motor is a high torque density model brushless motor in a NEMA 23 configuration. It is offered in 4 motor lengths with continuous torque from 0.15 – 0.59 Nm.

Benefits

- Speeds up to 6,000 RPM possible
- DC bus voltage up to 170 VDC
- NEMA 23 configuration
- Six standard windings
- 4 Pole rare earth design

Optional Assemblies

- Encoders: E30C/D, Q Type
- Gearbox: PLG52
- Programmable Drives: BGE6015A, BGE6060A



Motor Characteristics

Motor Data	Units	Series				
		EC057B-1	EC057B-2	EC057B-3	EC057B-4	
Max DC Terminal Voltage	V_T	170				
Max Speed (Mechanical)	ω_{MAX}	6000				
Continuous Stall Torque ¹	T_{CS}	Nm	0.15	0.32	0.40	0.59
		oz-in	21	45	56	83
Peak Torque (Maximum) ¹	T_{pk}	Nm	0.46	0.98	1.3	1.8
		oz-in	65	140	180	260
Coulomb Friction Torque	T_f	Nm	0.0049	0.0084	0.011	0.015
		oz-in	0.69	1.2	1.6	2.1
Viscous Damping Factor	D	Nm/(rad/s)	6.7E-06	1.3E-05	1.3E-05	2.0E-05
		oz-in/krpm	0.10	0.20	0.20	0.30
Thermal Time Constant	τ_{th}	min	10	10	15	15
Thermal Resistance	R_{th}	°C/W	4.8	3.1	2.8	2.1
Max. Winding Temperature	Θ_{MAX}	°C	125	125	125	125
Rotor Inertia	J_r	kg-m ²	7.1E-06	1.2E-05	1.8E-05	2.3E-05
		oz-in-s ²	0.0010	0.0017	0.0025	0.0032
Motor Weight	W_m	g	540	740	1000	1300
		oz	19	26	36	45

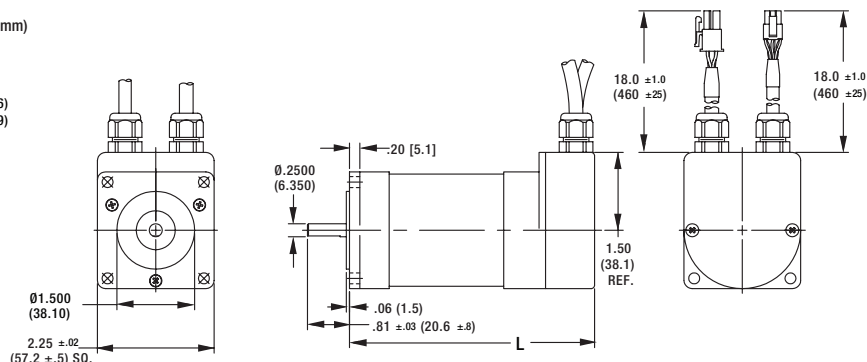
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC057B-1 • EC057B-2 • EC057B-3 • EC057B-4

Dimensions = inches (mm)

L = Lengths Available

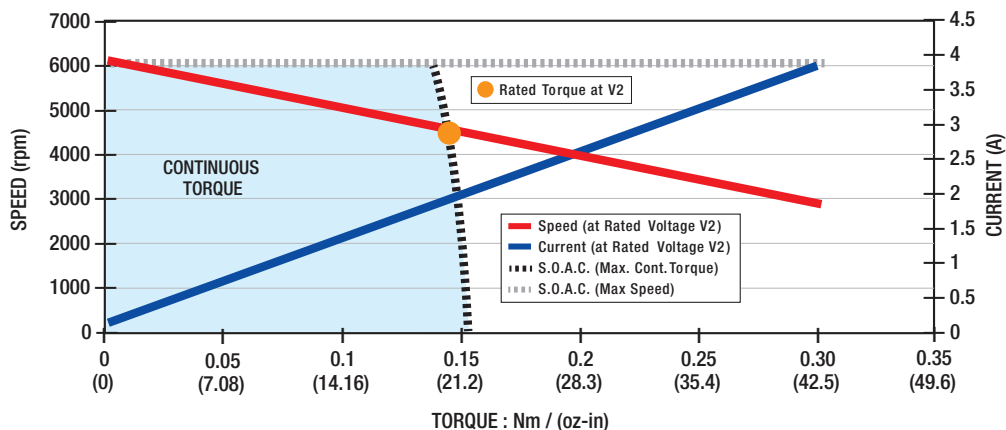
EC057B-1 = 3.15 (80)
 EC057B-2 = 3.94 (75.06)
 EC057B-3 = 4.72 (119.9)
 EC057B-4 = 5.51 (140)



Performance Data & Graph: EC057B-1

Motor Data	Units							
Rated Voltage V1	V _r	V	30.0	38.0	48.0	60.0	76.0	76.0
Rated Torque ¹ •	T _r	Nm	0.13	0.13	0.13	0.13	0.13	0.13
		oz-in	19	19	19	19	19	19
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	5.8	4.6	3.6	2.9	2.4	1.8
Rated Power ¹	P _r	W	83	83	83	83	84	84
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.34	0.28	0.22	0.18	0.14	0.11
Rated Voltage V2	V _r	V	19.1	24.0	30.0	38.0	48.0	48.0
Rated Torque ¹ •	T _r	Nm	0.14	0.14	0.14	0.14	0.14	0.14
		oz-in	19	19	19	19	19	20
Rated Speed ¹	ω _r	rpm	5890	5930	5720	5950	6000	4390
Rated Current ¹	I _r	A	5.8	4.6	3.6	2.9	2.4	1.9
Rated Power ¹	P _r	W	84	84	82	84	86	66
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	5390
No Load Current	I _{nl}	A	0.34	0.28	0.22	0.18	0.14	0.11
Motor Constant	K _M	Nm/√W	0.041	0.041	0.041	0.041	0.042	0.042
		oz-in/√W	5.8	5.8	5.9	5.8	5.9	5.9
Torque Constant	K _T	Nm/A	0.0267	0.0334	0.0430	0.0528	0.0658	0.0840
		oz-in/A	3.79	4.73	6.09	7.48	9.32	11.9
Voltage Constant	K _E	V/(rad/s)	0.0267	0.0334	0.0430	0.0528	0.0658	0.0840
		V/krpm	2.80	3.50	4.50	5.53	6.89	8.80
Terminal Resistance	R _{mt}	Ω	0.420	0.660	1.08	1.65	2.51	4.10
Inductance	L	mH	0.69	1.1	1.8	2.7	4.2	6.8
Peak Current	I _{pk}	A	20	16	12	9.9	8.1	6.3
Electrical Time Constant	τ _e	ms	1.6	1.7	1.7	1.6	1.7	1.7
Mechanical Time Constant	τ _m	ms	4.2	4.2	4.1	4.2	4.1	4.1

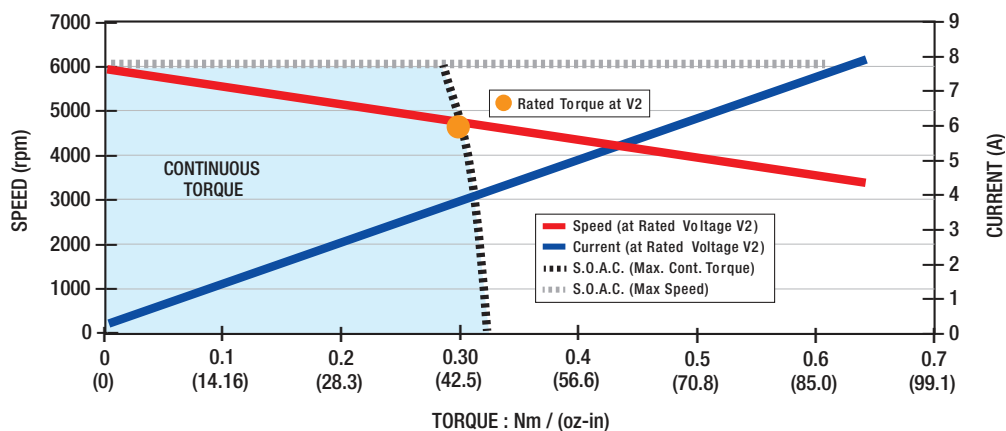
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC057B-2

Motor Data		Units						
Rated Voltage V1	V _r	V	38.0	48.0	60.0	76.0	76.0	152
Rated Torque ¹ •	T _r	Nm	0.27	0.27	0.28	0.27	0.28	0.28
		oz-in	39	39	39	39	39	39
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	8.5	7.2	5.7	4.6	3.7	2.3
Rated Power ¹	P _r	W	170	170	170	170	170	170
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.46	0.39	0.31	0.25	0.20	0.12
Rated Voltage V2	V _r	V	24.0	30.0	38.0	48.0	48.0	76.0
Rated Torque ¹ •	T _r	Nm	0.29	0.28	0.28	0.28	0.30	0.31
		oz-in	40	40	40	40	42	43
Rated Speed ¹	ω _r	rpm	5600	5950	5930	6000	4600	4390
Rated Current ¹	I _r	A	8.7	7.2	5.7	4.6	3.9	2.4
Rated Power ¹	P _r	W	170	170	180	180	140	140
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	5220	5030
No Load Current	I _{nl}	A	0.46	0.39	0.31	0.25	0.19	0.11
Motor Constant	K _M	Nm/√W	0.070	0.070	0.070	0.070	0.070	0.071
		oz-in/√W	10	9.9	9.9	9.9	9.9	10
Torque Constant	K _T	Nm/A	0.0372	0.0442	0.0561	0.0698	0.0870	0.143
		oz-in/A	5.27	6.26	7.95	9.89	12.3	20.3
Voltage Constant	K _E	V/(rad/s)	0.0372	0.0442	0.0561	0.0698	0.0870	0.143
		V/krpm	3.90	4.63	5.88	7.31	9.11	15.0
Terminal Resistance	R _{mt}	Ω	0.280	0.400	0.640	1.00	1.55	4.08
Inductance	L	mH	0.57	0.80	1.3	2.0	3.1	8.4
Peak Current	I _{pk}	A	30	25	20	16	13	7.8
Electrical Time Constant	τ _e	ms	2.0	2.0	2.0	2.0	2.0	2.1
Mechanical Time Constant	τ _m	ms	2.4	2.5	2.4	2.5	2.5	2.4

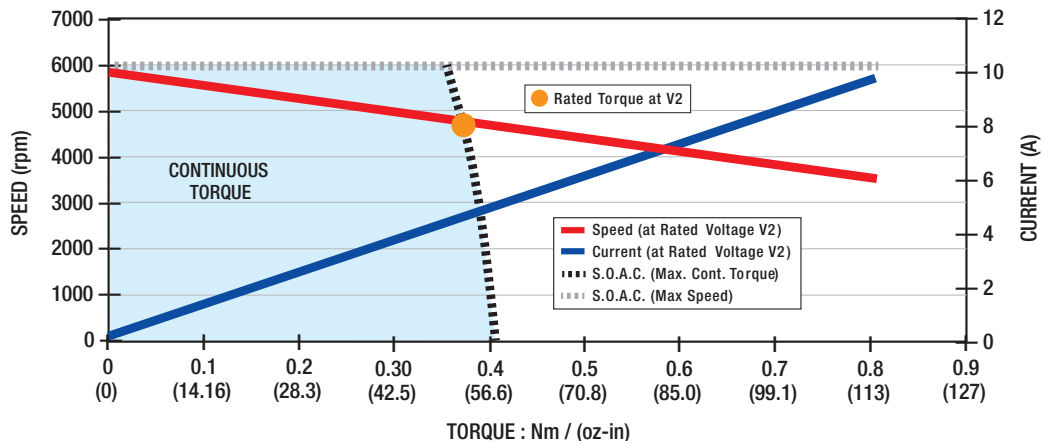
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC057B-3

Motor Data		Units							
Rated Voltage V1	V _r	V	38.0	48.0	60.0	76.0	76.0	152	170
Rated Torque ¹ •	T _r	Nm	0.33	0.34	0.34	0.34	0.34	0.34	0.34
		oz-in	47	48	48	48	49	49	47
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	11	8.9	7.1	5.6	4.5	2.8	1.9
Rated Power ¹	P _r	W	210	210	210	210	220	220	210
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.55	0.46	0.36	0.29	0.23	0.14	0.098
Rated Voltage V2	V _r	V	24.0	30.0	38.0	48.0	48.0	76.0	76.0
Rated Torque ¹ •	T _r	Nm	0.34	0.34	0.35	0.35	0.37	0.38	0.38
		oz-in	48	49	49	49	53	53	54
Rated Speed ¹	ω _r	rpm	5910	6000	6000	6000	4690	4520	2850
Rated Current ¹	I _r	A	11	8.9	7.1	5.6	4.8	3.0	2.1
Rated Power ¹	P _r	W	210	220	220	220	180	180	110
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	5170	5010	3520
No Load Current	I _{nl}	A	0.55	0.46	0.36	0.29	0.22	0.13	0.081
Motor Constant	K _M	Nm/√W	0.084	0.083	0.084	0.084	0.083	0.085	0.081
		oz-in/√W	12	12	12	12	12	12	11
Torque Constant	K _T	Nm/A	0.0366	0.0439	0.0561	0.0708	0.0879	0.144	0.204
		oz-in/A	5.18	6.22	7.95	10.0	12.5	20.4	28.9
Voltage Constant	K _E	V/(rad/s)	0.0366	0.0439	0.0561	0.0708	0.0879	0.144	0.204
		V/krpm	3.83	4.60	5.88	7.41	9.21	15.1	21.4
Terminal Resistance	R _{mt}	Ω	0.190	0.280	0.450	0.710	1.12	2.88	6.42
Inductance	L	mH	0.39	0.57	0.93	1.5	2.3	6.2	13
Peak Current	I _{pk}	A	39	33	25	20	16	9.9	6.6
Electrical Time Constant	τ _e	ms	2.1	2.0	2.1	2.1	2.1	2.1	2.0
Mechanical Time Constant	τ _m	ms	2.5	2.6	2.5	2.5	2.5	2.5	2.7

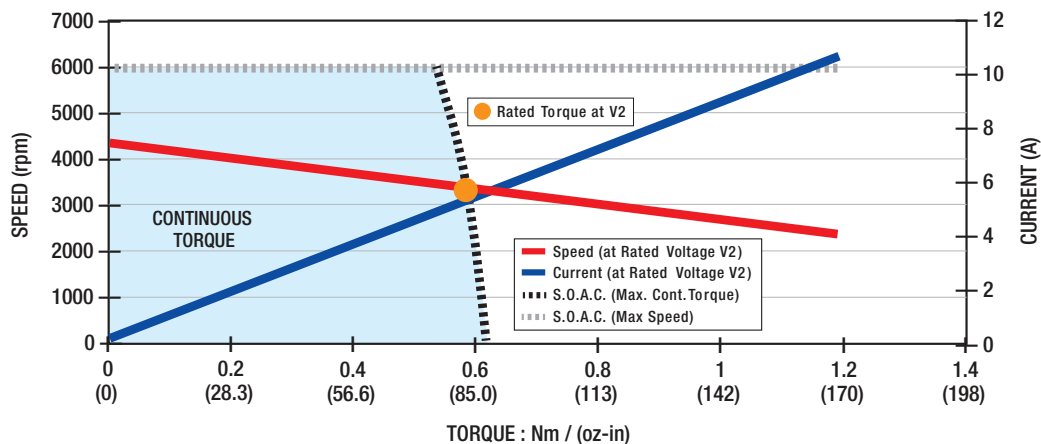
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC057B-4

Motor Data		Units						
Rated Voltage V1	V _r	V	48.0	60.0	76.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	0.50	0.50	0.50	0.52	0.51	0.52
		oz-in	70	70	71	74	72	74
Rated Speed ¹	ω _r	rpm	6000	6000	6000	5770	6000	5840
Rated Current ¹	I _r	A	13	10	8.1	4.9	3.8	2.5
Rated Power ¹	P _r	W	310	310	310	310	320	320
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.64	0.50	0.40	0.24	0.19	0.12
Rated Voltage V2	V _r	V	30.0	38.0	48.0	48.0	76.0	76.0
Rated Torque ¹ •	T _r	Nm	0.51	0.51	0.51	0.58	0.57	0.60
		oz-in	72	72	72	82	81	85
Rated Speed ¹	ω _r	rpm	6000	6000	6000	3290	4260	2460
Rated Current ¹	I _r	A	13	10	8.1	5.5	4.2	2.8
Rated Power ¹	P _r	W	320	320	320	200	250	150
No Load Speed	ω _{nl}	rpm	6000	6000	6000	3840	4720	3060
No Load Current	I _{nl}	A	0.64	0.50	0.40	0.20	0.17	0.092
Motor Constant	K _M	Nm/√W	0.11	0.11	0.11	0.11	0.11	0.11
		oz-in/√W	15	15	15	15	16	15
Torque Constant	K _T	Nm/A	0.0439	0.0561	0.0708	0.118	0.153	0.235
		oz-in/A	6.22	7.94	10.0	16.8	21.6	33.3
Voltage Constant	K _E	V/(rad/s)	0.0439	0.0561	0.0708	0.118	0.153	0.235
		V/krpm	4.60	5.87	7.41	12.4	16.0	24.6
Terminal Resistance	R _{mt}	Ω	0.170	0.270	0.440	1.20	1.94	4.63
Inductance	L	mH	0.44	0.74	1.2	3.3	5.5	13
Peak Current	I _{pk}	A	48	36	29	18	14	9.0
Electrical Time Constant	τ _e	ms	2.6	2.7	2.7	2.8	2.8	2.8
Mechanical Time Constant	τ _m	ms	2.0	1.9	2.0	1.9	1.9	1.9

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC057A Series

The EC057A Series Brushless DC Motor is a high torque model brushless motor designed in a NEMA 23 package. It is offered in 3 motor lengths with continuous torque from 0.38 – 0.93 Nm.



■ Benefits

- Speeds up to 6,000 RPM possible
- DC bus voltage up to 170 VDC
- NEMA 23 configuration
- Seven standard windings
- 4 Pole rare earth design

■ Optional Assemblies

- Encoders: E30C/D, Q Type, C Type
- Programmable Drives: BGE6015A, BGE6060A

■ Motor Characteristics

Motor Data	Units	Series		
		EC057A-1	EC057A-2	EC057A-3
Max DC Terminal Voltage V_T	V	170		
Max Speed (Mechanical) ω_{MAX}	rpm	6000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.38	0.71	0.93
	oz-in	54	100	130
Peak Torque (Maximum) ¹ T_{pk}	Nm	1.2	2.2	2.9
	oz-in	170	310	410
Coulomb Friction Torque T_f	Nm	0.0075	0.013	0.016
	oz-in	1.1	1.8	2.3
Viscous Damping Factor D	Nm/(rad/s)	2.0E-05	4.0E-05	8.1E-05
	oz-in/krpm	0.30	0.60	1.2
Thermal Time Constant τ_{th}	min	20	15	15
Thermal Resistance R_{th}	°C/W	1.5	1.3	1.3
Max. Winding Temperature Θ_{MAX}	°C	125	125	125
Rotor Inertia J_r	kg-m ²	1.3E-05	2.6E-05	3.9E-05
	oz-in-s ²	0.0019	0.0037	0.0055
Motor Weight W_m	g	660	1000	1400
	OZ	23	36	48

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC057A-1 • EC057A-2 • EC057A-3

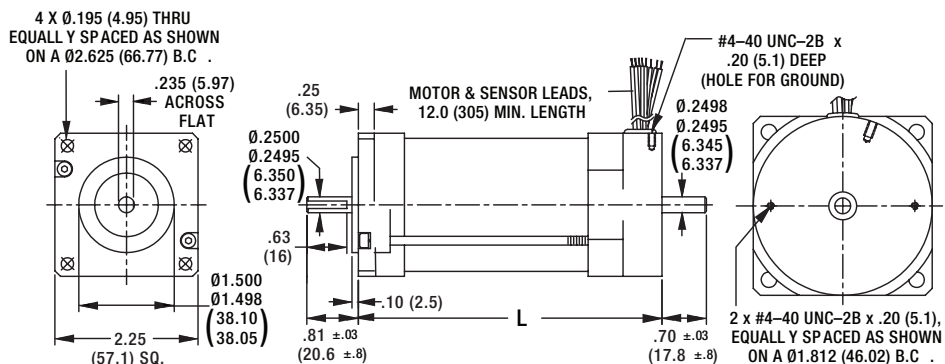
Dimensions = inches (mm)

L = Lengths Available

EC057A-1 = 2.8 (71.1)

EC057A-2 = 3.8 (96.5)

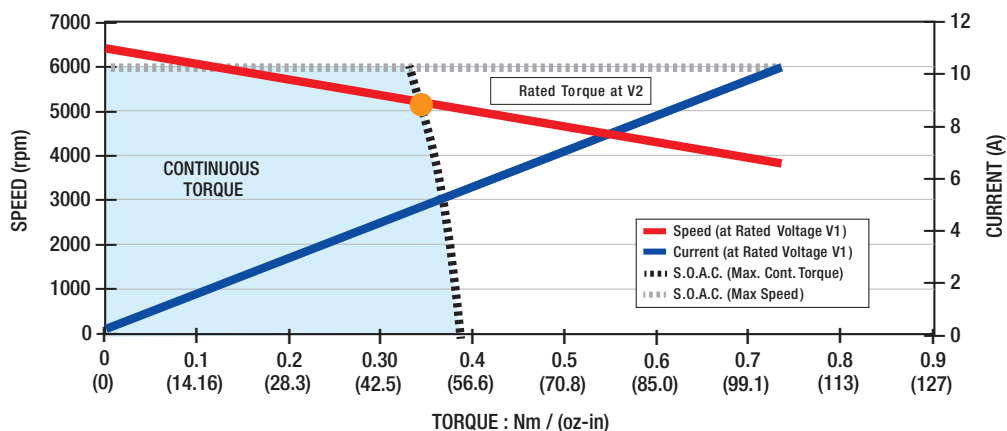
EC057A-3 = 4.8 (121.9)



■ Performance Data & Graph: EC057A-1

Motor Data	Units								
Rated Voltage V1	V _r	V	38.0	48.0	60.0	76.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	0.32	0.34	0.34	0.33	0.34	0.33	0.34
		oz-in	46	48	48	46	48	46	48
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	9.6	7.4	5.9	4.8	3.7	2.4	2.4
Rated Power ¹	P _r	W	200	210	210	210	210	210	210
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.51	0.38	0.31	0.26	0.19	0.13	0.13
Rated Voltage V2	V _r	V	24.0	30.0	38.0	48.0	48.0	76.0	76.0
Rated Torque ¹ •	T _r	Nm	0.34	0.36	0.36	0.34	0.37	0.36	0.37
		oz-in	48	51	50	49	53	51	53
Rated Speed ¹	ω _r	rpm	5180	4790	4870	5180	3560	3810	3620
Rated Current ¹	I _r	A	9.9	7.8	6.2	5.0	4.0	2.6	2.6
Rated Power ¹	P _r	W	180	180	180	190	140	140	140
No Load Speed	ω _{nl}	rpm	5670	5320	5390	5670	4250	4490	4310
No Load Current	I _{nl}	A	0.49	0.36	0.29	0.25	0.16	0.11	0.10
Motor Constant	K _M	Nm/√W	0.072	0.074	0.074	0.073	0.074	0.072	0.074
		oz-in/√W	10	10	10	10	10	10	10
Torque Constant	K _T	Nm/A	0.0401	0.0535	0.0668	0.0802	0.107	0.160	0.167
		oz-in/A	5.68	7.57	9.47	11.4	15.1	22.7	23.7
Voltage Constant	K _E	V/(rad/s)	0.0401	0.0535	0.0668	0.0802	0.107	0.160	0.167
		V/krpm	4.20	5.60	7.00	8.40	11.2	16.8	17.5
Terminal Resistance	R _{mt}	Ω	0.310	0.520	0.820	1.23	2.09	4.91	5.12
Inductance	L	mH	0.22	0.40	0.62	0.90	1.6	3.6	3.9
Peak Current	I _{pk}	A	33	26	20	17	13	8.4	8.1
Electrical Time Constant	τ _e	ms	0.71	0.77	0.76	0.73	0.77	0.73	0.76
Mechanical Time Constant	τ _m	ms	2.6	2.4	2.5	2.6	2.5	2.6	2.5

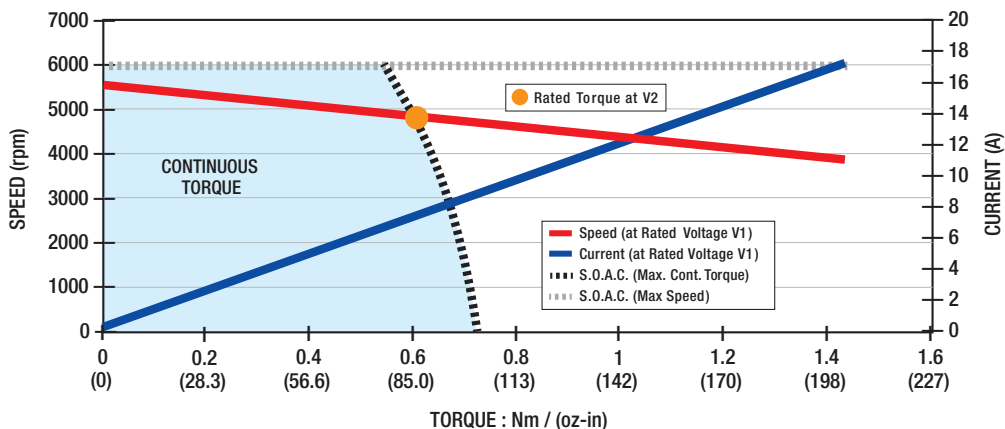
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC057A-2

Motor Data		Units							
Rated Voltage V1	V_r	V	48.0	60.0	76.0	121	152	152	170
Rated Torque ¹ •	T_r	Nm	0.53	0.52	0.54	0.53	0.53	0.53	0.53
		oz-in	75	73	77	75	74	75	75
Rated Speed ¹	ω_r	rpm	6000	6000	6000	6000	6000	6000	6000
Rated Current ¹	I_r	A	12	9.3	6.9	4.7	3.6	3.0	2.4
Rated Power ¹	P_r	W	330	330	340	330	330	330	330
No Load Speed	ω_{nl}	rpm	6000	6000	6000	6000	6000	6000	6000
No Load Current	I_{nl}	A	0.72	0.58	0.41	0.29	0.23	0.18	0.15
Rated Voltage V2	V_r	V	30.0	38.0	48.0	48.0	76.0	76.0	76.0
Rated Torque ¹ •	T_r	Nm	0.57	0.55	0.61	0.66	0.62	0.66	0.68
		oz-in	81	78	86	93	88	93	96
Rated Speed ¹	ω_r	rpm	5290	5410	4790	3080	3940	3040	2260
Rated Current ¹	I_r	A	13	9.8	7.6	5.7	4.2	3.6	2.9
Rated Power ¹	P_r	W	320	310	300	210	260	210	160
No Load Speed	ω_{nl}	rpm	5330	5400	4870	3410	4150	3370	2700
No Load Current	I_{nl}	A	0.67	0.54	0.36	0.21	0.18	0.13	0.092
Motor Constant	K_M	Nm/ \sqrt{W}	0.12	0.12	0.13	0.12	0.12	0.12	0.12
		oz-in/ \sqrt{W}	17	18	18	18	18	18	18
Torque Constant	K_T	Nm/A	0.0535	0.0668	0.0936	0.134	0.174	0.214	0.267
		oz-in/A	7.57	9.47	13.3	18.9	24.6	30.3	37.9
Voltage Constant	K_E	V/(rad/s)	0.0535	0.0668	0.0936	0.134	0.174	0.214	0.267
		V/krpm	5.60	7.00	9.80	14.0	18.2	22.4	28.0
Terminal Resistance	R_{mt}	Ω	0.190	0.290	0.540	1.16	1.96	2.96	4.64
Inductance	L	mH	0.17	0.26	0.52	1.1	1.8	2.7	4.3
Peak Current	I_{pk}	A	45	36	27	18	14	11	9.3
Electrical Time Constant	τ_e	ms	0.89	0.90	0.96	0.92	0.92	0.92	0.92
Mechanical Time Constant	τ_m	ms	1.7	1.7	1.6	1.7	1.7	1.7	1.7

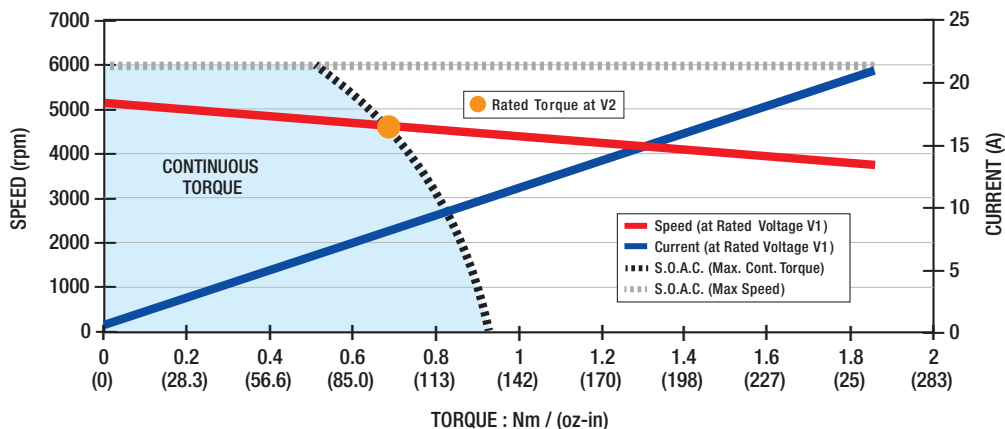
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC057A-3

Motor Data		Units						
Rated Voltage V1	V _r	V	48.0	60.0	76.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	0.51	0.50	0.50	0.50	0.51	0.71
		oz-in	72	70	71	71	72	100
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	4570
Rated Current ¹	I _r	A	11	7.9	6.4	5.3	3.2	2.7
Rated Power ¹	P _r	W	320	310	310	320	320	340
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	4500
No Load Current	I _{nl}	A	1.2	0.84	0.67	0.56	0.34	0.17
Rated Voltage V2	V _r	V	30.0	38.0	48.0	48.0	76.0	76.0
Rated Torque ¹ •	T _r	Nm	0.66	0.68	0.68	0.76	0.80	0.91
		oz-in	94	97	96	110	110	130
Rated Speed ¹	ω _r	rpm	4830	4560	4610	3700	3490	1930
Rated Current ¹	I _r	A	13	10	8.2	7.6	4.7	3.3
Rated Power ¹	P _r	W	340	330	330	300	290	180
No Load Speed	ω _{nl}	rpm	4740	4500	4550	3790	3600	2250
No Load Current	I _{nl}	A	0.94	0.68	0.55	0.41	0.24	0.11
Motor Constant	K _M	Nm/√W	0.16	0.16	0.16	0.16	0.16	0.16
		oz-in/√W	22	22	22	22	23	23
Torque Constant	K _T	Nm/A	0.0602	0.0802	0.100	0.120	0.201	0.321
		oz-in/A	8.52	11.4	14.2	17.0	28.4	45.4
Voltage Constant	K _E	V/(rad/s)	0.0602	0.0802	0.100	0.120	0.201	0.321
		V/krpm	6.30	8.40	10.5	12.6	21.0	33.6
Terminal Resistance	R _{mt}	Ω	0.150	0.260	0.410	0.590	1.56	3.92
Inductance	L	mH	0.13	0.24	0.37	0.54	1.5	3.8
Peak Current	I _{pk}	A	54	39	33	27	17	11
Electrical Time Constant	τ _e	ms	0.87	0.92	0.90	0.92	0.96	0.98
Mechanical Time Constant	τ _m	ms	1.6	1.6	1.6	1.6	1.5	1.5

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.





EC083A Series

The EC083A Series Brushless DC Motor is a high torque model brushless motor designed in a NEMA 34 package. It is offered in 6 motor lengths with continuous torque from 0.91 – 2.1 Nm.

Benefits

- Speeds up to 6,000 RPM possible
- DC bus voltage up to 325 VDC
- Capable of 24 VDC bus systems
- NEMA 34 package
- 8 pole rare earth design

Optional Assemblies

- Encoders: Z Type, C Type
- Programmable Drive: BGE6060A

Motor Characteristics

Motor Data	Units	Series						
		EC083A-1	EC083A-2	EC083A-3	EC083A-4	EC083A-5	EC083A-6	
Max DC Terminal Voltage	V_T	325						
Max Speed (Mechanical)	ω_{MAX}	6000						
Continuous Stall Torque ¹	T_{CS}	Nm	0.91	1.4	1.7	1.9	2.1	2.1
		oz-in	130	200	240	260	300	300
Peak Torque (Maximum) ¹	T_{pk}	Nm	2.9	4.5	5.2	5.9	6.8	6.9
		oz-in	410	640	740	830	970	970
Coulomb Friction Torque	T_f	Nm	0.020	0.030	0.038	0.041	0.045	0.047
		oz-in	2.8	4.3	5.4	5.8	6.4	6.7
Viscous Damping Factor	D	Nm/(rad/s)	1.3E-05	1.3E-05	4.7E-05	4.7E-05	6.7E-05	6.7E-05
		oz-in/krpm	0.20	0.20	0.70	0.70	1.0	1.0
Thermal Time Constant	τ_{th}	min	15	15	15	15	15	15
Thermal Resistance	R_{th}	°C/W	1.5	1.4	1.4	1.4	1.3	1.1
Max. Winding Temperature	Θ_{MAX}	°C	125	125	125	125	125	125
Rotor Inertia	J_r	kg-m ²	6.8E-05	1.0E-04	1.2E-04	1.6E-04	2.0E-04	2.4E-04
		oz-in-s ²	0.0096	0.014	0.018	0.022	0.029	0.034
Motor Weight	W_m	g	1400	2000	2500	3000	3500	4100
		oz	50	70	88	110	120	140

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

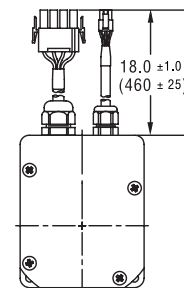
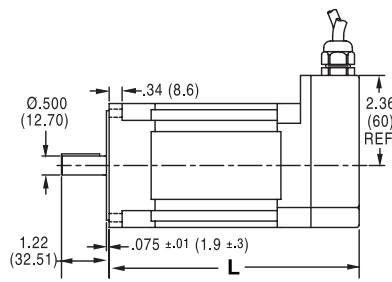
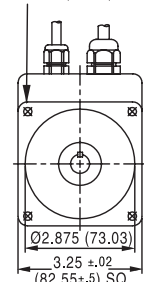
Dimensional Drawings: EC083A-1 • EC083A-2 • EC083A-3 • EC083A-4 • EC083A-5 • EC083A-6

Dimensions = inches (mm)

L = Lengths Available

- EC083A-1** = 4.05 (102.9)
- EC083A-2** = 4.55 (115.6)
- EC083A-3** = 5.05 (128.3)
- EC083A-4** = 5.55 (141.0)
- EC083A-5** = 6.05 (153.7)
- EC083A-6** = 6.55 (166.4)

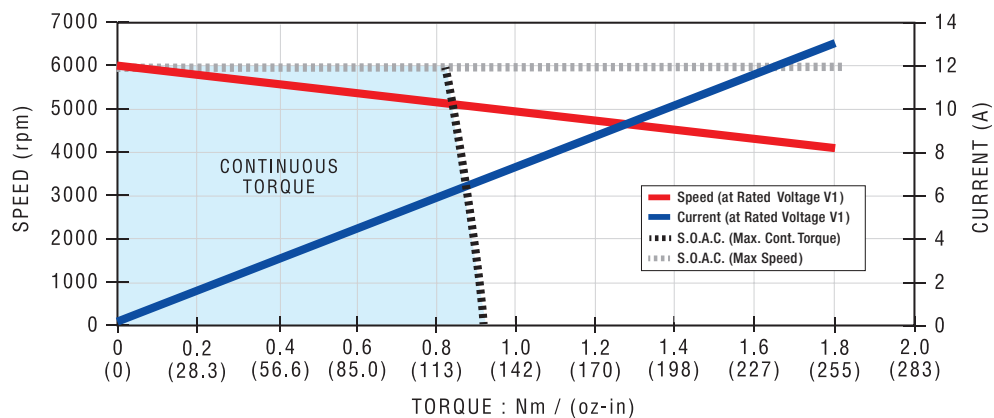
Ø .218 (5.54) THRU (4)
EQUALLY SPACED ON A
Ø3.875 (98.43) B.C.



■ Performance Data & Graph: EC083A-1

Motor Data		Units						
Rated Voltage V1	V_r	V	60.0	76.0	96.0	152	305	305
Rated Torque ¹ •	T_r	Nm	0.80	0.81	0.81	0.79	0.78	0.78
		oz-in	110	110	120	110	110	110
Rated Speed ¹	ω_r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I_r	A	31	23	18	12	9.9	6.3
Rated Power ¹	P_r	W	500	510	510	500	490	490
No Load Speed	ω_{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I_{nl}	A	0.97	0.71	0.55	0.39	0.31	0.20
Rated Voltage V2	V_r	V	38.0	38.0	76.0	76.0	152	152
Rated Torque ¹ •	T_r	Nm	0.81	0.83	0.82	0.81	0.79	0.79
		oz-in	110	120	120	110	110	110
Rated Speed ¹	ω_r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I_r	A	31	23	18	12	9.9	6.3
Rated Power ¹	P_r	W	510	520	510	510	500	500
No Load Speed	ω_{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I_{nl}	A	0.97	0.71	0.55	0.39	0.31	0.20
Motor Constant	K_M	Nm/ \sqrt{W}	0.15	0.15	0.16	0.15	0.15	0.15
		oz-in/ \sqrt{W}	21	22	22	21	21	21
Torque Constant	K_T	Nm/A	0.0294	0.0405	0.0516	0.0736	0.0921	0.143
		oz-in/A	4.17	5.73	7.30	10.4	13.0	20.3
Voltage Constant	K_E	V/(rad/s)	0.0294	0.0405	0.0516	0.0736	0.0921	0.143
		V/krpm	3.08	4.24	5.40	7.71	9.64	15.0
Terminal Resistance	R_{mt}	Ω	0.0400	0.0700	0.110	0.240	0.370	0.920
Inductance	L	mH	0.14	0.26	0.43	0.88	1.4	3.3
Peak Current	I_{pk}	A	110	81	63	42	36	22
Electrical Time Constant	τ_e	ms	3.5	3.7	3.9	3.7	3.8	3.6
Mechanical Time Constant	τ_m	ms	3.1	2.9	2.8	3.0	3.0	3.0

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.

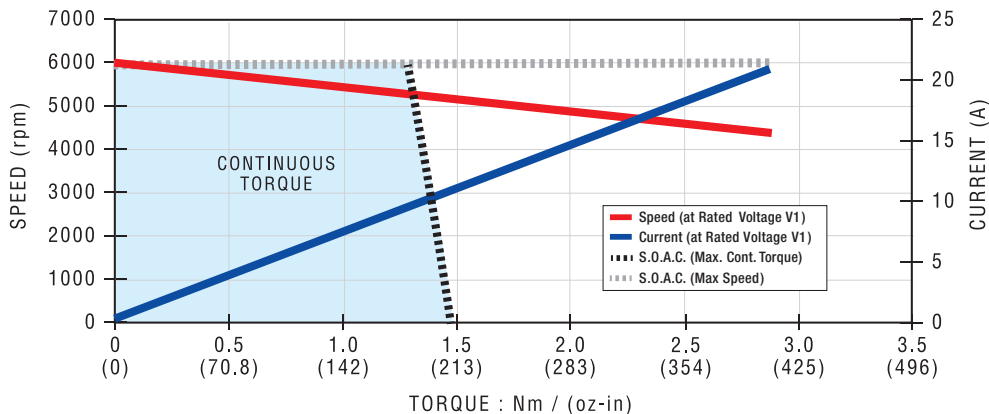


Performance Data & Graph: EC083A-2

Motor Data		Units						
Rated Voltage V1	V _r	V	76.0	76.0	152	152	305	305
Rated Torque ¹ •	T _r	Nm	1.2	1.3	1.2	1.2	1.2	1.2
		oz-in	180	180	180	180	170	170
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	23	18	12	9.8	6.3	5.1
Rated Power ¹	P _r	W	780	790	780	780	770	760
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	0.65	0.51	0.33	0.28	0.18	0.15
Rated Voltage V2	V _r	V	38.0	48.0	76.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	1.3	1.3	1.3	1.3	1.3	1.3
		oz-in	180	180	180	190	180	180
Rated Speed ¹	ω _r	rpm	5930	5860	5930	4920	6000	5270
Rated Current ¹	I _r	A	23	19	12	10	6.3	5.2
Rated Power ¹	P _r	W	800	800	800	690	790	710
No Load Speed	ω _{nl}	rpm	5970	5920	5970	5050	6000	5370
No Load Current	I _{nl}	A	0.65	0.51	0.33	0.27	0.18	0.15
Motor Constant	K _M	Nm/√W	0.21	0.21	0.22	0.22	0.21	0.21
		oz-in/√W	30	30	31	31	30	30
Torque Constant	K _T	Nm/A	0.0606	0.0772	0.121	0.143	0.222	0.269
		oz-in/A	8.59	10.9	17.2	20.3	31.4	38.1
Voltage Constant	K _E	V/(rad/s)	0.0606	0.0772	0.121	0.143	0.222	0.269
		V/krpm	6.35	8.08	12.7	15.0	23.2	28.2
Terminal Resistance	R _{mt}	Ω	0.0800	0.130	0.310	0.440	1.07	1.65
Inductance	L	mH	0.33	0.54	1.4	1.9	4.5	6.7
Peak Current	I _{pk}	A	84	66	42	36	23	18
Electrical Time Constant	τ _e	ms	4.1	4.2	4.4	4.3	4.2	4.1
Mechanical Time Constant	τ _m	ms	2.2	2.2	2.1	2.2	2.2	2.3

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/r: for example, DC030C-1 (3.31 V/krpm).

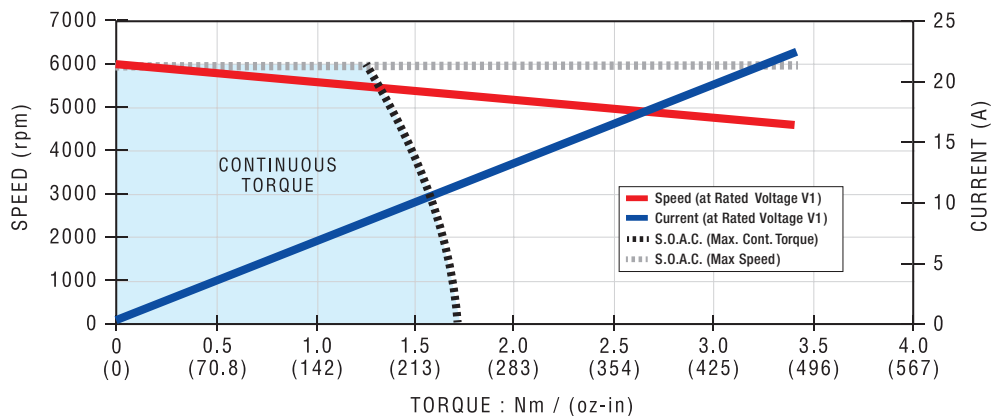
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC083A-3

Motor Data		Units					
Rated Voltage V1	V _r	V	76.0	96.0	152	305	305
Rated Torque ¹ •	T _r	Nm	1.2	1.2	1.2	1.2	1.2
		oz-in	170	170	170	170	170
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	27	18	13	11	8.9
Rated Power ¹	P _r	W	740	750	760	750	760
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	1.4	0.86	0.63	0.53	0.43
Rated Voltage V2	V _r	V	38.0	48.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	1.2	1.2	1.2	1.2	1.2
		oz-in	170	180	170	170	170
Rated Speed ¹	ω _r	rpm	6000	5890	6000	6000	6000
Rated Current ¹	I _r	A	27	18	13	11	8.9
Rated Power ¹	P _r	W	760	770	770	760	770
No Load Speed	ω _{nl}	rpm	6000	5730	6000	6000	6000
No Load Current	I _{nl}	A	1.4	0.84	0.63	0.53	0.43
Motor Constant	K _M	Nm/√W	0.25	0.25	0.26	0.26	0.25
		oz-in/√W	36	36	36	36	35
Torque Constant	K _T	Nm/A	0.0507	0.0797	0.109	0.130	0.159
		oz-in/A	7.18	11.3	15.4	18.5	22.6
Voltage Constant	K _E	V/(rad/s)	0.0507	0.0797	0.109	0.130	0.159
		V/krpm	5.31	8.35	11.4	13.7	16.7
Terminal Resistance	R _{mt}	Ω	0.0400	0.100	0.180	0.260	0.410
Inductance	L	mH	0.17	0.42	0.78	1.1	1.7
Peak Current	I _{pk}	A	120	75	54	45	36
Electrical Time Constant	τ _e	ms	4.3	4.2	4.3	4.3	4.1
Mechanical Time Constant	τ _m	ms	1.9	2.0	1.9	1.9	2.0

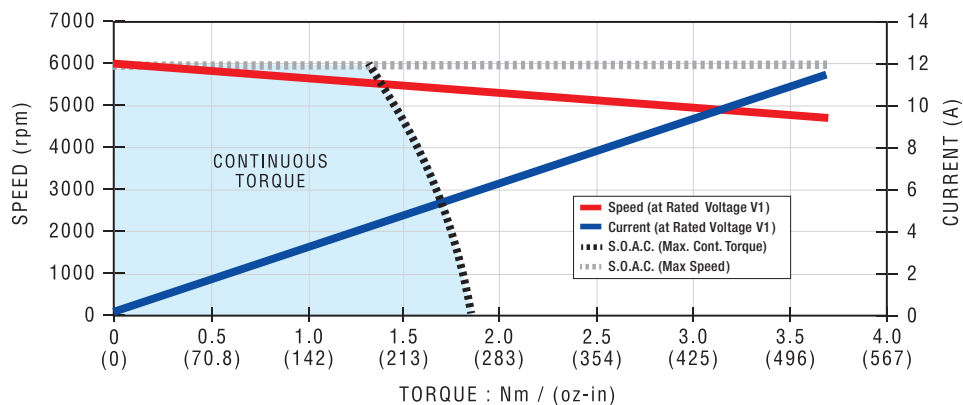
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC083A-4

Motor Data		Units						
Rated Voltage V1	V _r	V	76.0	76.0	152	152	305	305
Rated Torque ¹ •	T _r	Nm	1.3	1.3	1.3	1.3	1.3	1.3
		oz-in	190	190	180	190	180	180
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	22	16	11	8.1	5.4	4.4
Rated Power ¹	P _r	W	840	830	820	840	820	810
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	1.1	0.73	0.51	0.37	0.26	0.21
Rated Voltage V2	V _r	V	38.0	48.0	76.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	1.5	1.5	1.4	1.7	1.4	1.6
		oz-in	210	220	200	240	200	220
Rated Speed ¹	ω _r	rpm	5260	4820	5290	3700	5290	4250
Rated Current ¹	I _r	A	24	18	12	9.8	5.9	5.2
Rated Power ¹	P _r	W	810	770	800	660	800	700
No Load Speed	ω _{nl}	rpm	5150	4740	5150	3750	5150	4240
No Load Current	I _{nl}	A	0.95	0.67	0.48	0.31	0.24	0.19
Motor Constant	K _M	Nm/√W	0.27	0.28	0.28	0.28	0.28	0.27
		oz-in/√W	38	40	39	39	39	38
Torque Constant	K _T	Nm/A	0.0702	0.0964	0.140	0.193	0.281	0.341
		oz-in/A	9.94	13.7	19.9	27.3	39.8	48.3
Voltage Constant	K _E	V/(rad/s)	0.0702	0.0964	0.140	0.193	0.281	0.341
		V/krpm	7.35	10.1	14.7	20.2	29.4	35.7
Terminal Resistance	R _{mt}	Ω	0.0700	0.120	0.260	0.480	1.04	1.60
Inductance	L	mH	0.26	0.49	1.1	2.0	4.2	6.2
Peak Current	I _{pk}	A	93	69	48	33	23	19
Electrical Time Constant	τ _e	ms	3.7	4.1	4.0	4.1	4.0	3.9
Mechanical Time Constant	τ _m	ms	2.2	2.0	2.1	2.0	2.1	2.2

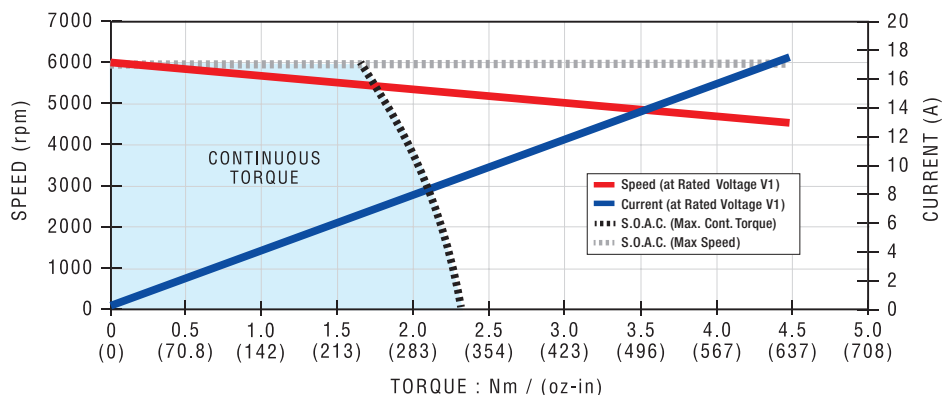
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC083A-5

Motor Data		Units						
Rated Voltage V1	V _r	V	76.0	96.0	121	152	305	305
Rated Torque ¹ •	T _r	Nm	1.3	1.3	1.4	1.4	1.4	1.6
		oz-in	180	190	190	200	190	230
Rated Speed ¹	ω _r	rpm	6000	6000	6000	6000	6000	6000
Rated Current ¹	I _r	A	24	19	17	12	9.7	6.9
Rated Power ¹	P _r	W	790	840	860	890	860	1000
No Load Speed	ω _{nl}	rpm	6000	6000	6000	6000	6000	6000
No Load Current	I _{nl}	A	1.4	1.1	0.92	0.64	0.52	0.32
Rated Voltage V2	V _r	V	38.0	96.0	96.0	76.0	152	152
Rated Torque ¹ •	T _r	Nm	1.3	1.3	1.4	1.6	1.4	1.8
		oz-in	180	190	190	220	200	250
Rated Speed ¹	ω _r	rpm	6000	6000	6000	5490	6000	5380
Rated Current ¹	I _r	A	24	19	17	13	9.7	7.4
Rated Power ¹	P _r	W	800	840	860	900	870	1000
No Load Speed	ω _{nl}	rpm	5700	6000	6000	5260	6000	5280
No Load Current	I _{nl}	A	1.4	1.1	0.92	0.60	0.52	0.31
Motor Constant	K _M	Nm/√W	0.32	0.32	0.30	0.32	0.31	0.28
		oz-in/√W	45	45	43	45	44	40
Torque Constant	K _T	Nm/A	0.0634	0.0845	0.0951	0.137	0.169	0.274
		oz-in/A	8.98	12.0	13.5	19.5	23.9	38.8
Voltage Constant	K _E	V/(rad/s)	0.0634	0.0845	0.0951	0.137	0.169	0.274
		V/krpm	6.64	8.85	9.96	14.4	17.7	28.7
Terminal Resistance	R _{mt}	Ω	0.0400	0.0700	0.100	0.190	0.290	0.940
Inductance	L	mH	0.17	0.30	0.38	0.81	1.2	3.2
Peak Current	I _{pk}	A	120	90	78	57	45	29
Electrical Time Constant	τ _e	ms	4.3	4.3	3.8	4.3	4.2	3.4
Mechanical Time Constant	τ _m	ms	2.0	2.0	2.2	2.0	2.1	2.5

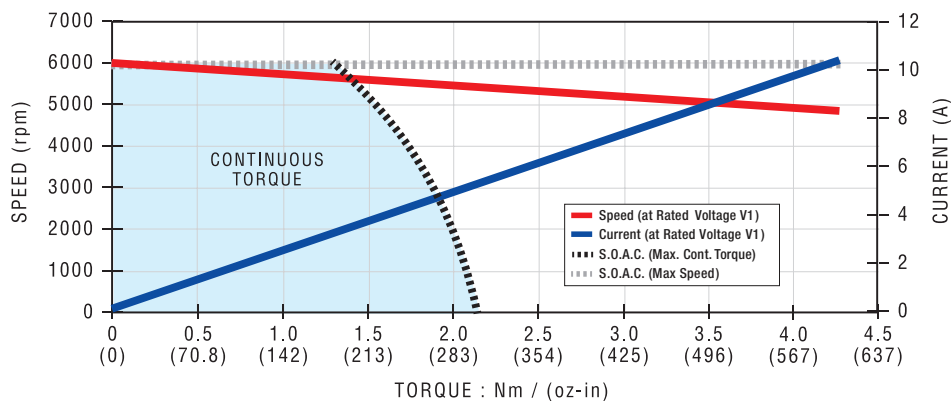
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC083A-6

Motor Data		Units							
Rated Voltage V1	V_r	V	76.0	76.0	152	152	305	305	305
Rated Torque ¹ •	T_r	Nm	1.4	1.4	1.3	1.3	1.3	1.3	1.3
		oz-in	190	200	190	190	190	190	180
Rated Speed ¹	ω_r	rpm	6000	6000	6000	6000	6000	6000	6000
Rated Current ¹	I_r	A	28	24	10	8.5	6.8	5.2	3.4
Rated Power ¹	P_r	W	860	890	830	840	840	840	800
No Load Speed	ω_{nl}	rpm	6000	6000	6000	6000	6000	6000	6000
No Load Current	I_{nl}	A	1.6	1.3	0.59	0.48	0.39	0.30	0.21
Rated Voltage V2	V_r	V	38.0	48.0	76.0	76.0	152	152	152
Rated Torque ¹ •	T_r	Nm	1.4	1.4	1.6	1.8	1.4	1.6	1.9
		oz-in	200	200	230	260	190	230	270
Rated Speed ¹	ω_r	rpm	6000	6000	4940	3900	6000	4920	3240
Rated Current ¹	I_r	A	28	24	12	11	6.8	6.2	4.8
Rated Power ¹	P_r	W	870	900	840	750	850	850	640
No Load Speed	ω_{nl}	rpm	6000	6000	4740	3850	6000	4740	3270
No Load Current	I_{nl}	A	1.6	1.3	0.53	0.40	0.39	0.27	0.16
Motor Constant	K_M	Nm/ \sqrt{W}	0.29	0.32	0.33	0.32	0.32	0.32	0.31
		oz-in/ \sqrt{W}	42	45	46	45	45	46	44
Torque Constant	K_T	Nm/A	0.0588	0.0706	0.153	0.188	0.235	0.306	0.442
		oz-in/A	8.33	9.99	21.6	26.6	33.3	43.3	62.6
Voltage Constant	K_E	V/(rad/s)	0.0588	0.0706	0.153	0.188	0.235	0.306	0.442
		V/krpm	6.16	7.39	16.0	19.7	24.6	32.0	46.3
Terminal Resistance	R_{mt}	Ω	0.0400	0.0500	0.220	0.350	0.540	0.900	2.06
Inductance	L	mH	0.13	0.19	0.91	1.4	2.2	3.6	7.8
Peak Current	I_{pk}	A	130	110	51	42	33	26	17
Electrical Time Constant	τ_e	ms	3.3	3.8	4.1	3.9	4.0	4.0	3.8
Mechanical Time Constant	τ_m	ms	2.7	2.4	2.2	2.4	2.3	2.3	2.5

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



EC121A Series

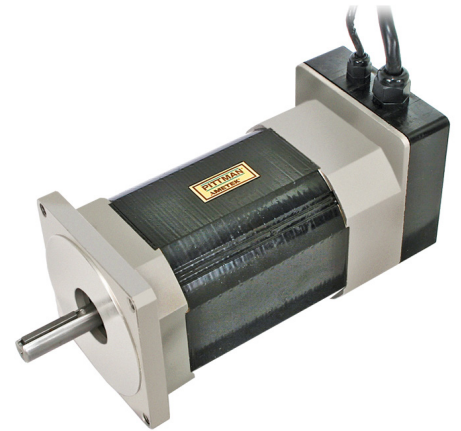
The EC121A Series Brushless DC Motor is a high torque model brushless motor designed in a NEMA 48 package. It is offered in 4 motor lengths with continuous torque from 3.0 – 6.5 Nm.

Benefits

- Speeds up to 4,000 RPM possible
- DC bus voltage up to 325 VDC
- Capable of 48 VDC bus systems
- NEMA 48 package
- 8 pole rare earth design

Optional Assemblies

- Encoder: C Type
- Programmable Drive: BGE6060A



Motor Characteristics

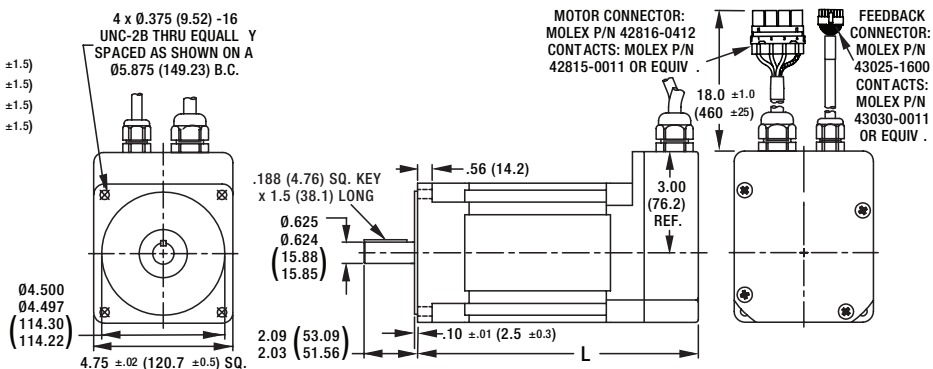
Motor Data	Units	Series			
		EC121A-1	EC121A-2	EC121A-2	EC121A-4
Max DC Terminal Voltage V_T	V	325			
Max Speed (Mechanical) ω_{MAX}	rpm	4000			
Continuous Stall Torque ¹ T_{CS}	Nm	3.0	3.6	4.2	6.5
	oz-in	430	510	590	930
Peak Torque (Maximum) ¹ T_{pk}	Nm	9.4	12	14	20
	oz-in	1300	1700	2000	2800
Coulomb Friction Torque T_f	Nm	0.051	0.065	0.086	0.10
	oz-in	7.3	9.3	12	14
Viscous Damping Factor D	Nm/(rad/s)	1.3E-04	2.0E-04	1.3E-04	3.2E-04
	oz-in/krpm	1.9	3.0	2.0	4.7
Thermal Time Constant τ_{th}	min	15	15	15	15
Thermal Resistance R_{th}	°C/W	0.96	0.81	0.86	0.65
Max. Winding Temperature Θ_{MAX}	°C	125	125	125	125
Rotor Inertia J_r	kg-m ²	7.9E-04	1.2E-03	1.7E-03	2.1E-03
	oz-in-s ²	0.11	0.18	0.24	0.30
Motor Weight W_m	g	7100	9900	12000	15000
	oz	250	350	440	530

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: EC121A-1 • EC121A-2 • EC121A-3 • EC121A-4

Dimensions = inches (mm)

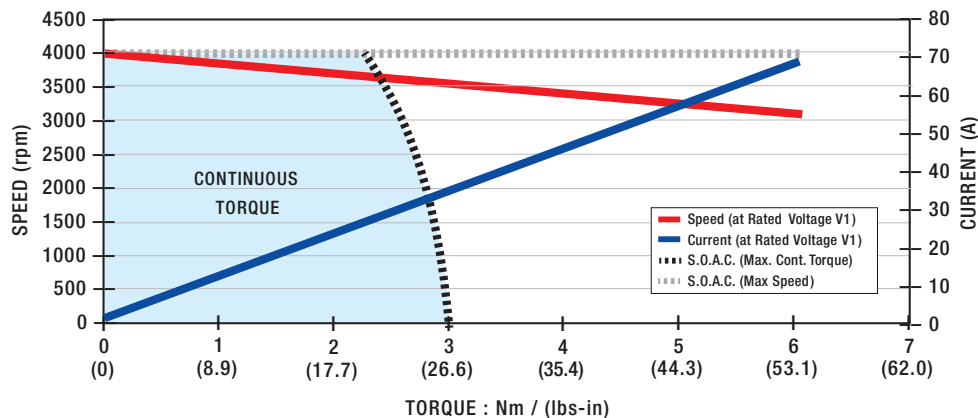
- EC121A-1 = 6.91 ±.06 (175.5 ±1.5)
- EC121A-2 = 8.31 ±.06 (211.1 ±1.5)
- EC121A-3 = 9.71 ±.06 (246.6 ±1.5)
- EC121A-4 = 11.1 ±.06 (281.9 ±1.5)



Performance Data & Graph: EC121A-1

Motor Data		Units							
Rated Voltage V1	V _r	V	60.0	76.0	76.0	121	152	152	305
Rated Torque ¹ •	T _r	Nm	2.2	2.3	2.4	2.3	2.3	2.3	2.3
		oz-in	320	320	330	330	330	330	320
Rated Speed ¹	ω _r	rpm	4000	4000	4000	4000	4000	4000	4000
Rated Current ¹	I _r	A	28	25	21	18	14	11	8.5
Rated Power ¹	P _r	W	930	950	990	960	970	960	960
No Load Speed	ω _{nl}	rpm	4000	4000	4000	4000	4000	4000	4000
No Load Current	I _{nl}	A	1.2	1.0	0.82	0.70	0.57	0.45	0.34
Rated Voltage V2	V _r	V	30.0	38.0	48.0	170	76.0	76.0	152
Rated Torque ¹ •	T _r	Nm	2.6	2.5	2.5	2.3	2.4	2.6	2.3
		oz-in	370	350	360	320	330	370	330
Rated Speed ¹	ω _r	rpm	3080	3490	3610	4000	3970	3090	4000
Rated Current ¹	I _r	A	31	27	22	18	14	13	8.5
Rated Power ¹	P _r	W	830	910	950	960	980	850	970
No Load Speed	ω _{nl}	rpm	3050	3440	3540	4000	3870	3090	4000
No Load Current	I _{nl}	A	0.99	0.93	0.77	0.70	0.56	0.40	0.34
Motor Constant	K _M	Nm/√W	0.42	0.40	0.41	0.41	0.40	0.40	0.40
		oz-in/√W	59	56	58	57	56	57	57
Torque Constant	K _T	Nm/A	0.0936	0.105	0.129	0.152	0.187	0.234	0.315
		oz-in/A	13.3	14.9	18.3	21.5	26.5	33.1	44.6
Voltage Constant	K _E	V/(rad/s)	0.0936	0.105	0.129	0.152	0.187	0.234	0.315
		V/krpm	9.80	11.0	13.5	15.9	19.6	24.5	33.0
Terminal Resistance	R _{mt}	Ω	0.0500	0.0700	0.100	0.140	0.220	0.340	0.610
Inductance	L	mH	0.27	0.34	0.51	0.72	1.1	1.7	3.1
Peak Current	I _{pk}	A	110	99	84	69	57	45	33
Electrical Time Constant	τ _e	ms	5.4	4.9	5.1	5.1	5.0	5.0	5.1
Mechanical Time Constant	τ _m	ms	4.5	5.0	4.7	4.8	5.0	4.9	4.9

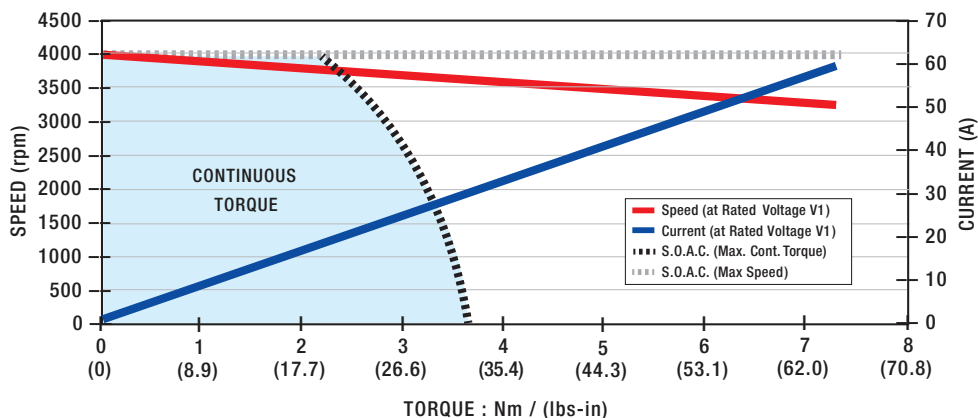
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC121A-2

Motor Data		Units						
Rated Voltage V1	V_r	V	76.0	76.0	152	152	305	305
Rated Torque ¹ •	T_r	Nm	2.1	2.3	2.3	2.3	2.3	2.4
		oz-in	300	320	330	330	320	330
Rated Speed ¹	ω_r	rpm	4000	4000	4000	4000	4000	4000
Rated Current ¹	I_r	A	19	18	14	11	7.3	5.3
Rated Power ¹	P_r	W	880	950	980	970	960	990
No Load Speed	ω_{nl}	rpm	4000	4000	4000	4000	4000	4000
No Load Current	I_{nl}	A	1.2	1.1	0.73	0.62	0.41	0.29
Rated Voltage V2	V_r	V	38.0	48.0	76.0	76.0	152	152
Rated Torque ¹ •	T_r	Nm	2.9	2.9	2.6	3.0	2.3	3.2
		oz-in	410	410	370	420	330	450
Rated Speed ¹	ω_r	rpm	2850	3190	3730	3090	4000	2850
Rated Current ¹	I_r	A	25	22	15	14	7.3	6.9
Rated Power ¹	P_r	W	850	960	1000	960	970	950
No Load Speed	ω_{nl}	rpm	2760	3050	3510	2970	3870	2760
No Load Current	I_{nl}	A	0.95	0.87	0.68	0.53	0.40	0.24
Motor Constant	K_M	Nm/ \sqrt{W}	0.50	0.53	0.53	0.53	0.52	0.54
		oz-in/ \sqrt{W}	70	75	75	75	74	76
Torque Constant	K_T	Nm/A	0.131	0.150	0.206	0.244	0.374	0.524
		oz-in/A	18.6	21.2	29.2	34.5	53.0	74.2
Voltage Constant	K_E	V/(rad/s)	0.131	0.150	0.206	0.244	0.374	0.524
		V/krpm	13.7	15.7	21.6	25.5	39.2	54.9
Terminal Resistance	R_{mt}	Ω	0.0700	0.0800	0.150	0.210	0.510	0.950
Inductance	L	mH	0.32	0.42	0.80	1.1	2.7	5.2
Peak Current	I_{pk}	A	96	90	66	57	36	26
Electrical Time Constant	τ_e	ms	4.6	5.3	5.3	5.4	5.2	5.5
Mechanical Time Constant	τ_m	ms	5.1	4.4	4.4	4.4	4.5	4.3

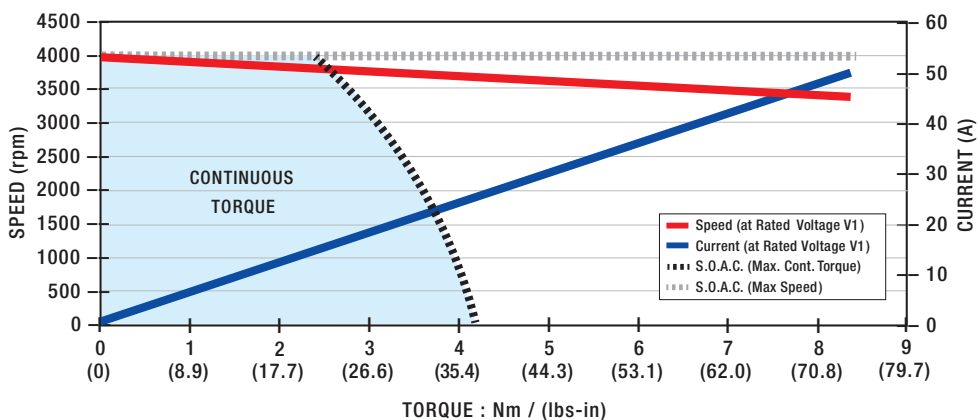
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n; for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: EC121A-3

Motor Data	Units							
Rated Voltage V1	V _r	V	76.0	152	152	305	305	305
Rated Torque ¹ •	T _r	Nm	2.4	2.7	2.7	2.6	2.6	2.7
		oz-in	340	380	390	370	380	390
Rated Speed ¹	ω _r	rpm	4000	4000	4000	4000	4000	4000
Rated Current ¹	I _r	A	16	15	11	9.4	7.6	5.6
Rated Power ¹	P _r	W	1000	1100	1100	1100	1100	1100
No Load Speed	ω _{nl}	rpm	4000	4000	4000	4000	4000	4000
No Load Current	I _{nl}	A	0.79	0.69	0.51	0.44	0.35	0.25
Rated Voltage V2	V _r	V	48.0	76.0	76.0	170	152	152
Rated Torque ¹ •	T _r	Nm	3.3	2.9	3.7	2.6	2.9	3.7
		oz-in	470	410	520	370	410	530
Rated Speed ¹	ω _r	rpm	2640	3760	2660	4000	3770	2640
Rated Current ¹	I _r	A	21	16	15	9.4	8.1	7.4
Rated Power ¹	P _r	W	920	1200	1000	1100	1100	1000
No Load Speed	ω _{nl}	rpm	2530	3500	2550	4000	3500	2530
No Load Current	I _{nl}	A	0.68	0.66	0.43	0.44	0.33	0.22
Motor Constant	K _M	Nm/√W	0.60	0.62	0.64	0.62	0.63	0.64
		oz-in/√W	85	88	90	88	89	91
Torque Constant	K _T	Nm/A	0.181	0.207	0.285	0.330	0.413	0.573
		oz-in/A	25.6	29.3	40.3	46.8	58.6	81.1
Voltage Constant	K _E	V/(rad/s)	0.181	0.207	0.285	0.330	0.413	0.573
		V/krpm	19.0	21.7	29.8	34.6	43.3	60.0
Terminal Resistance	R _{mt}	Ω	0.0900	0.110	0.200	0.280	0.430	0.790
Inductance	L	mH	0.46	0.60	1.1	1.1	2.4	4.6
Peak Current	I _{pk}	A	81	75	57	48	39	28
Electrical Time Constant	τ _e	ms	5.1	5.5	5.7	4.0	5.6	5.8
Mechanical Time Constant	τ _m	ms	4.7	4.4	4.2	4.4	4.3	4.1

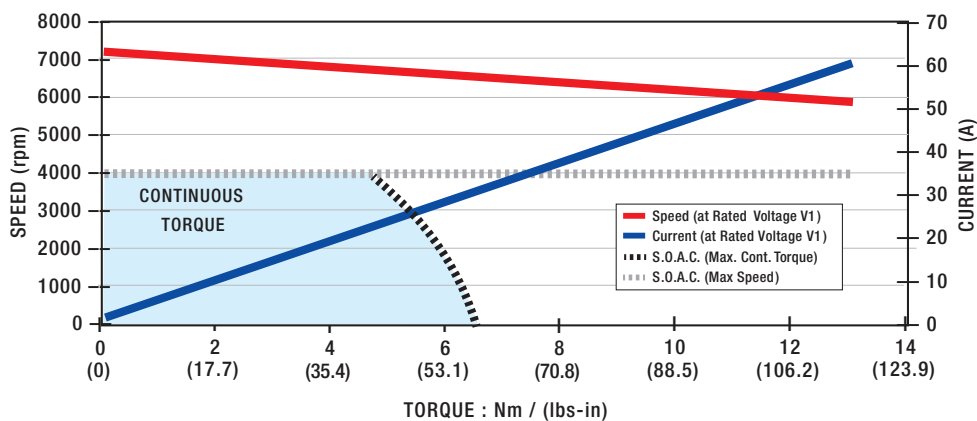
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: EC121A-4

Motor Data		Units			
Rated Voltage V1	V_r	V	152	305	305
Rated Torque ¹ •	T_r	Nm	4.7	4.7	4.7
		oz-in	660	660	660
Rated Speed ¹	ω_r	rpm	4000	4000	4000
Rated Current ¹	I_r	A	24	15	12
Rated Power ¹	P_r	W	2000	2000	2000
No Load Speed	ω_{nl}	rpm	4000	4000	4000
No Load Current	I_{nl}	A	1.1	0.65	0.53
Rated Voltage V2	V_r	V	76.0	152	152
Rated Torque ¹ •	T_r	Nm	5.4	4.8	5.4
		oz-in	770	670	770
Rated Speed ¹	ω_r	rpm	3240	4000	3240
Rated Current ¹	I_r	A	27	15	14
Rated Power ¹	P_r	W	1800	2000	1800
No Load Speed	ω_{nl}	rpm	3220	3970	3220
No Load Current	I_{nl}	A	0.93	0.64	0.47
Motor Constant	K_M	Nm/ \sqrt{W}	0.62	0.63	0.62
		oz-in/ \sqrt{W}	88	89	88
Torque Constant	K_T	Nm/A	0.224	0.365	0.449
		oz-in/A	31.8	51.7	63.6
Voltage Constant	K_E	V/(rad/s)	0.224	0.365	0.449
		V/krpm	23.5	38.2	47.0
Terminal Resistance	R_{mt}	Ω	0.130	0.340	0.520
Inductance	L	mH	0.93	1.6	3.7
Peak Current	I_{pk}	A	100	63	51
Electrical Time Constant	τ_e	ms	7.2	4.7	7.2
Mechanical Time Constant	τ_m	ms	5.5	5.5	5.5

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.





EC042B IDEA® Motor Series

The IDEA® Motor Series integrates a high-torque, precision servo motor and IDEA Drive as a single compact unit. The IDEA Motor enables distributed control without the use of a costly PLC or external motion controller. EC042B is offered in 3 motor lengths with continuous torque up to 0.15 Nm.

CANopen DS-301 / DS-402 communication or GUI programming interface with RS485

■ CANopen

- DS-301 / DS-402 communication
- Connect up to 127 drives on the same network
- Integrated inputs, outputs and encoder

■ RS485

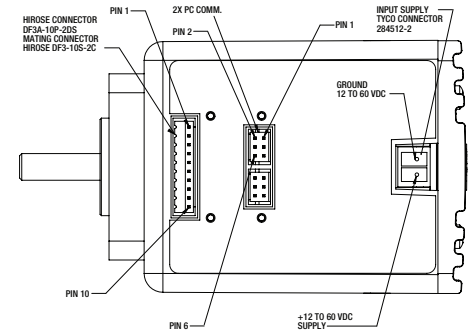
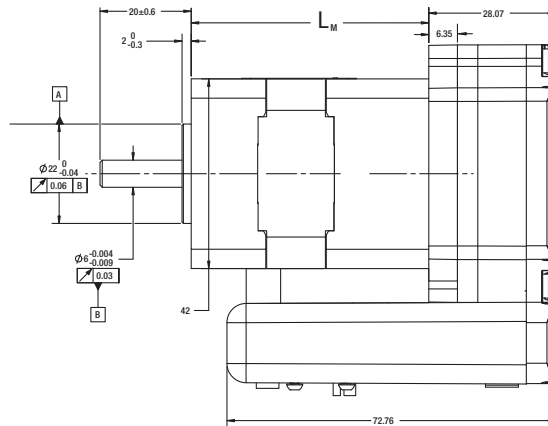
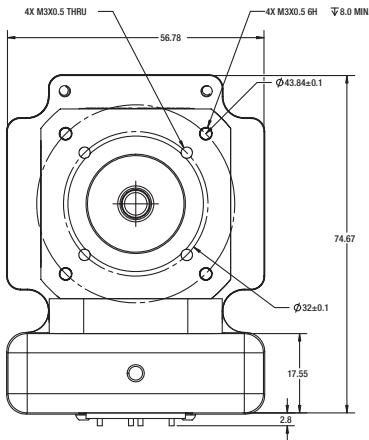
- GUI programming interface
- Integrated trapezoidal and S-curve trajectory generator with movement profile plotter
- Program execution
- I/O-driven nested prioritized vectored interrupts
- Polled I/O for autonomous real-time control
- Connect up to 256 drives on the same network
- Integrated inputs, outputs and encoder

■ Motor Characteristics

Motor Data		Units	Series		
			EC042B-1	EC042B-2	EC042B-3
Length	L_M	mm / inch	52.6mm / 2.071"	72.6mm / 2.8"	92.6mm / 3.646"
Rated Power Output ²	P_r	W	25	54	70
Input Voltage Range	V_i	Vdc	12 - 60		
Rated Voltage ¹	V_1	Vdc	24		
No Load Speed ¹	ω_{nl}	rpm	4825	4856	5182
Rated Speed ¹	ω_r	rpm	3930	4022	4460
Rated Torque ¹	T_r	Nm	0.06	0.12	0.15
		oz-in	8.2	16.0	21.0
Rated Input Current ¹	I_r	A	1.4	2.93	3.4
Continuous Input Power ¹	P_{cs}	W	38	70	89
Rotor Inertia	J_r	kg-m ²	0.000014	0.000018	0.000021
		oz-in-sec ²	0.0021	0.0025	0.0029
Motor Weight	W_m	g	423	623	815
		oz	15	22	29

¹Values specified at Rated Voltage. ²Values specified at Rated Voltage, Speed and Torque.

Drive input current is capable up to 8Arms continuous and 20A peak (1 sec) when within motor capabilities maximum winding temperature at 25°C ambient and without heatsink.



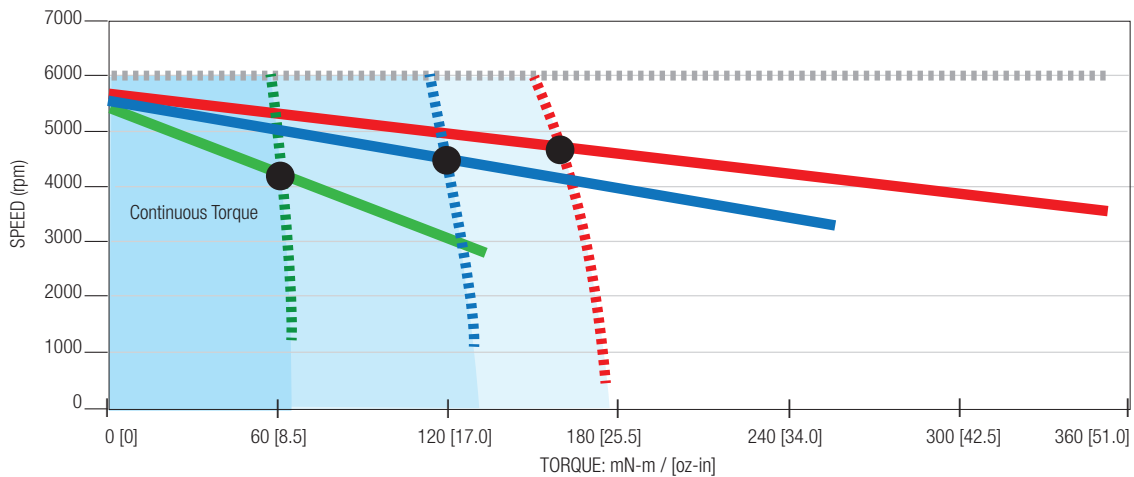
Drive Specifications

Digital I/O Voltage Range	5-24 VDC
Digital Inputs	4
Digital Outputs	4
Digital Sinking Outputs	200mA (each)
Digital Input Maximum Current	8mA (each)
Maximum Temperature	70°C (at heat sink)
Program Storage Size / Type	85 Kbytes / Flash
Max. Number of Stored Programs	85
Position Counter Range	64bit

I/O Pin Positions

PIN 1	GROUND I/O SUPPLY (5 to 24 Vdc)
PIN 2	I/O SUPPLY (5 to 24 Vdc)
PIN 3	INPUT 1
PIN 4	INPUT 2
PIN 5	INPUT 3
PIN 6	INPUT 4
PIN 7	OUTPUT 1
PIN 8	OUTPUT 2
PIN 9	OUTPUT 3
PIN 10	OUTPUT 4

Performance Graph



- Rated Torque at V1
- Speed EC042B-2 (at Rated Voltage V1)
- S.O.A.C. (Max. Cont. Torque)
- Speed EC042B-1 (at Rated Voltage V1)
- Speed EC042B-3 (at Rated Voltage V1)
- S.O.A.C. (Max Speed)

■ **Optional Accessories**

Part No.	Option	Description
56-1348	Cables	Power cable, 1 meter (39.37)
56-1352		I/O Cable, 1 meter (39.37)
56-1536-4		Communication Cable, 1 meter (39.37) for daisy chaining IDEA Motors
56-2322		USB to RS485/CANopen Cable, 1 meter (39.37) Use with 52-870 or 52-879
PLG42S	Gearboxes	Configured to be integrated directly with EC042B IDEA Motor
PLG52		
52-870	Converters	USB to CANopen Converter
52-879		USB to RS485 Converter



■ **PLG42S Characteristics**

See page 114 for full product description.

Specifications	Units	4:1	8:1	16:1	25:1	32:1	50:1	64:1	100:1	128:1	156:1	200:1	256:1	400:1	512:1
Maximum Load	Nm	0.7	0.7	1.3	1.3	1.3	1.3	1.3	3	3	3	3	3	3	3
	oz-in	99	99	184	184	184	184	184	425	425	425	425	425	425	425
Weight (Mass)	g	160	160	200	200	200	200	200	250	250	250	250	250	250	250
	oz	5.64	5.64	7.1	7.1	7.1	7.1	7.1	8.8	8.8	8.8	8.8	8.8	8.8	8.8
Length (Lg)	mm	48.2	48.2	60.0	60.0	60.0	60.0	60.0	71.8	71.8	71.8	71.8	71.8	71.8	71.8
	inches	1.90	1.90	2.36	2.36	2.36	2.36	2.36	2.83	2.83	2.83	2.83	2.83	2.83	2.83
Stage	–	1	1	2	2	2	2	2	3	3	3	3	3	3	3
Ratio	–	4 / 1	8 / 1	16 / 1	25 / 1	32 / 1	50 / 1	64 / 1	100 / 1	128 / 1	156.25/1	200 / 1	256 / 1	400 / 1	512 / 1
Efficiency	–	0.90	0.90	0.81	0.81	0.81	0.81	0.81	0.73	0.73	0.73	0.73	0.73	0.73	0.73
Shaft Rotation	–	CW	CW	CW	CW	CW	CW	CW	CW	CW	CW	CW	CW	CW	CW

Notes:

1. Maximum load represents gearbox capability only. Continuous load torque capability will vary with gear ratio, motor selection, and operating conditions.
2. Shaft rotation is designated while looking at output shaft with motor operating in a clockwise direction. Gearboxes have bi-directional capability.

■ **PLG52 Characteristics**

See page 116 for full product description.

Specifications	Units	4.5:1	6.25:1	15:1	20.2:1	28.1:1	36:1	50:1	91.1:1	126.5:1	162:1	225:1	288:1	400:1
Maximum Load	Nm	1.2	1.2	8	8	8	8	8	24					
	oz-in	170	170	1133	1133	1133	1133	1133	3399					
Weight (Mass)	g	560	560	720	720	720	720	720	880					
	oz	19.8	19.8	25.4	25.4	25.4	25.4	25.4	31.0					
Length (Lg)	mm	50.0	50.0	65.5	65.5	65.5	65.5	65.5	80.5					
	inches	1.97	1.97	2.58	2.58	2.58	2.58	2.58	3.17					
Stage	–	1	1	2	2	2	2	2	3					
Ratio	–	4.5/1	6.25/1	15/1	20.25/1	28.12/1	36/1	50/1	91.12/1	126.5/1	162/1	225/1	288/1	288/1
Efficiency	–	0.90	0.90	0.81	0.81	0.81	0.81	0.81	0.73					
Shaft Rotation	–	CW												

■ **Factory Options**

- Gearbox-ready for PLG42S, PLG52
- Lead screws, linear rails and slides



EC057B IDEA® Motor Series

The IDEA® Motor Series integrates a high-torque, precision servo motor and IDEA Drive as a single compact unit. The IDEA Motor enables distributed control without the use of a costly PLC or external motion controller. EC057B

■ CANopen

- DS-301 / DS-402 communication
- Connect up to 127 drives on the same network
- Integrated inputs, outputs and encoder

■ RS485

- GUI programming interface
- Integrated trapezoidal and S-curve trajectory generator with movement profile plotter
- Program execution
- I/O-driven nested prioritized vectored interrupts
- Polled I/O for autonomous real-time control

■ Drive Specifications

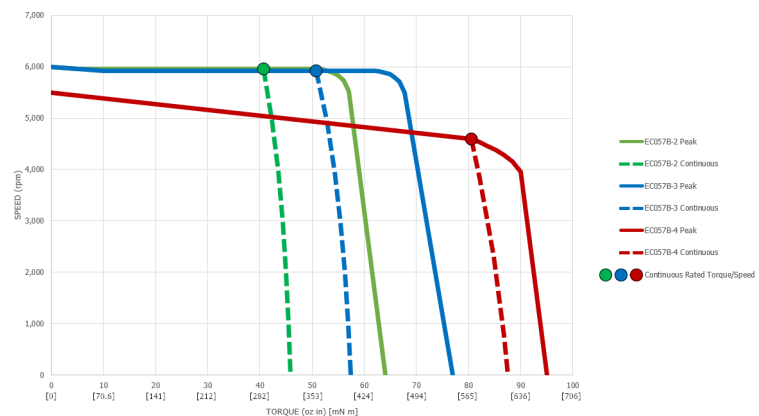
Digital I/O Voltage Range	5-24 VDC
Digital Inputs	4
Digital Outputs	4
Digital Sinking Outputs	200mA (each)
Digital Input Maximum Current	8mA (each)
Maximum Temperature	70°C (at heat sink)
Program Storage Size / Type	85 Kbytes / Flash
Max. Number of Stored Programs	85
Position Counter Range	64bit

■ Motor Characteristics

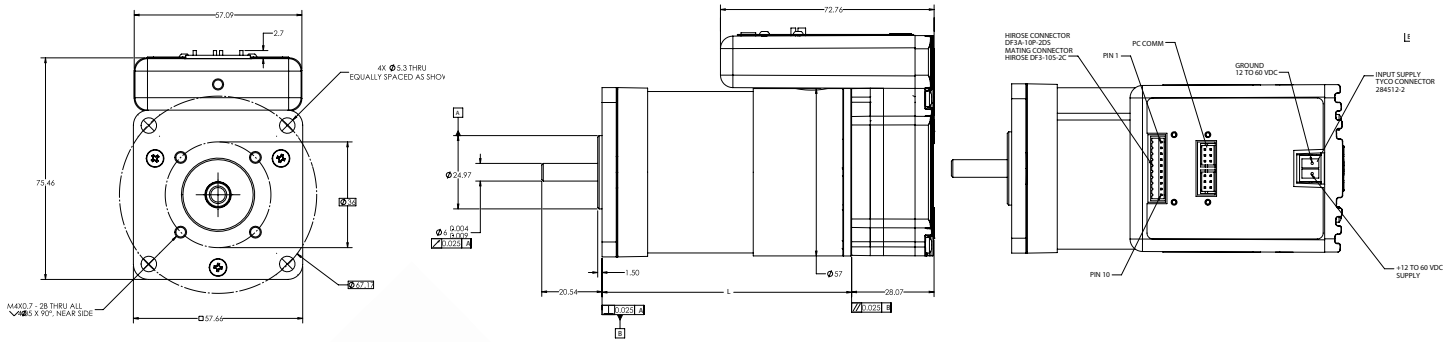
Motor Data	Units	Part No.			
		EC057B-2	EC057B-3	EC057B-4	
Length	LM	mm / inch	113mm / 4.45"	133mm / 5.24"	153mm / 6.03"
Rated Power Output ²	Pr	W	170	195	300
Input Voltage Range	Vi	Vdc	12 - 60		
Rated Voltage ¹	V1	Vdc	48		
No Load Speed ¹	ω_{nl}	rpm	6,000		
Rated Speed ¹	ω_r	rpm	5,900		
Rated Torque ¹	Tr	Nm	0.27	0.31	0.48
		oz-in	39	44	67
Rated Input Current ¹	Ir	A	5.0	5.5	7.0
Continuous Input Power ¹	Pcs	W	240	265	370
Rotor Inertia	Jr	kg-m ²	0.000012	0.000018	0.000023
		oz-in-sec ²	0.0017	0.0025	0.0032
Motor Weight	Wm	g	860	1100	1380
		oz	30	39	49

¹Values specified at Rated Voltage. ²Values specified at Rated Voltage, Speed and Torque.
Drive input current is capable up to 8Arms continuous and 20A peak (1 sec) when within motor capabilities maximum winding temperature at 25°C ambient and without heatsink.

■ Performance Graph



■ Dimensional Drawings (mm)



■ Factory Options

Gearbox-ready for PLG52
Lead screws, linear rails and slides

■ Optional Accessories

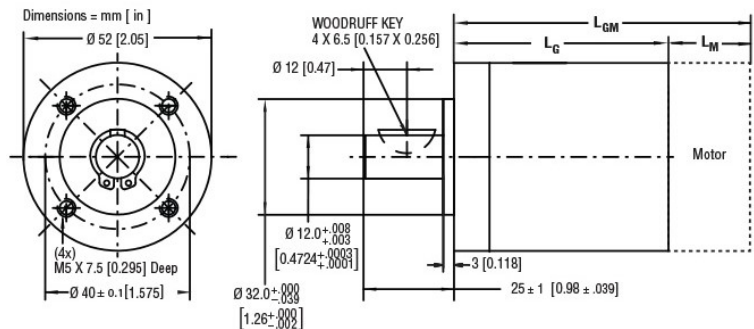
Part No.	Option	Description
PLG52	Gearbox	Configured to be integrated directly with EC057B IDEA Motor
56-1348	Cables	Power cable, 1 meter (39.37")
56-1352		I/O Cable, 1 meter (39.37")
UTR4852	Converter	USB to RS485 Converter, use with 56-1346 and 56-1536-4
56-1346	Cables	USB Cable (A to mini B), 2 meters (78.74")
56-1536-4		RS485 Cable, 1 meter (39.37")
52-870	Converters	USB to CANopen Converter, use with 56-2322
52-879		USB to RS485 Converter, use with 56-2322
56-2322	Cable	USB to CANopen/RS485 Cable, 2 meters (78.74") Use with 52-870 or 52-879

Motor Data	Units	Part No.			
		EC057B-2	EC057B-3	EC057B-4	
Length	L	mm / inch	113mm / 4.45"	133mm / 5.24"	153mm / 6.03"

■ I/O Pin Positions

PIN 1	GROUND I/O SUPPLY (5 to 24 Vdc)	PIN 6	INPUT 4
PIN 2	I/O SUPPLY (5 to 24 Vdc)	PIN 7	OUTPUT 1
PIN 3	INPUT 1	PIN 8	OUTPUT 2
PIN 4	INPUT 2	PIN 9	OUTPUT 3
PIN 5	INPUT 3	PIN 10	OUTPUT 4

■ Dimensions: Optional Gearbox, PLG52



Add L from EC057B IDEA Motor Dimensional Drawing above to determine L_M and L_{GM} motor lengths

■ PLG52 Characteristics

Gear Data	Units	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52	PLG52
		4.5:1	6.25:1	15:1	20.2:1	28.1:1	36:1	50:1	91.1:1	126.5:1	162:1	225:1	288:1	400:1
Maximum Load	Nm	1.2				8								24
	oz-in	170				1133								3399
Weight (Mass)	g	560				720								880
	oz	19.8				25.4								31.0
Length (L)	mm	50.0				65.5								80.5
	inches	1.97				2.58								3.17
Stages	–	1				2								3
Efficiency	–	0.90				0.81								0.73
Shaft Rotation	–													CW

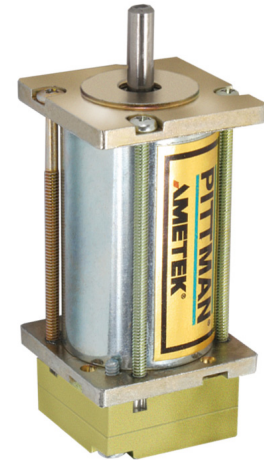
ES030A Series

The ES030A Series Brushless DC Motor is a high torque density model brushless motor with a slotless design in a NEMA 14 configuration. It is offered in 2 motor lengths with continuous torque from 0.029 – 0.041 Nm.

Motor Characteristics

Motor Data	Units	Series		
		ES030A-1	ES030A-2	
Max DC Terminal Voltage	V_T	V	60	
Max Speed (Mechanical)	ω_{MAX}	rpm	8000	
Continuous Stall Torque ¹	T_{CS}	Nm	0.029	0.041
		oz-in	4.1	5.8
Peak Torque (Maximum) ¹	T_{pk}	Nm	0.085	0.13
		oz-in	12	18
Coulomb Friction Torque	T_f	Nm	9.9E-04	9.9E-04
		oz-in	0.14	0.14
Viscous Damping Factor	D	Nm/(rad/s)	1.1E-06	2.5E-06
		oz-in/krpm	0.016	0.037
Thermal Time Constant	τ_{th}	min	14	15
Thermal Resistance	R_{th}	°C/W	8.1	7.9
Max. Winding Temperature	θ_{MAX}	°C	130	130
Rotor Inertia	J_r	kg-m ²	9.9E-07	1.4E-06
		oz-in-s ²	1.4E-04	2.0E-04
Motor Weight	W_m	g	170	210
		oz	6.0	7.4

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Shown with optional assembly.

Benefits

- Speeds up to 8,000 RPM possible
- DC bus voltage up to 60 VDC
- NEMA 14 configuration
- Eight standard windings, special windings available
- 4 pole rare earth design

Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G30A, G35A, G40A
- Brake: B30A
- Programmable Drives: PBL4850E, BGE6015A

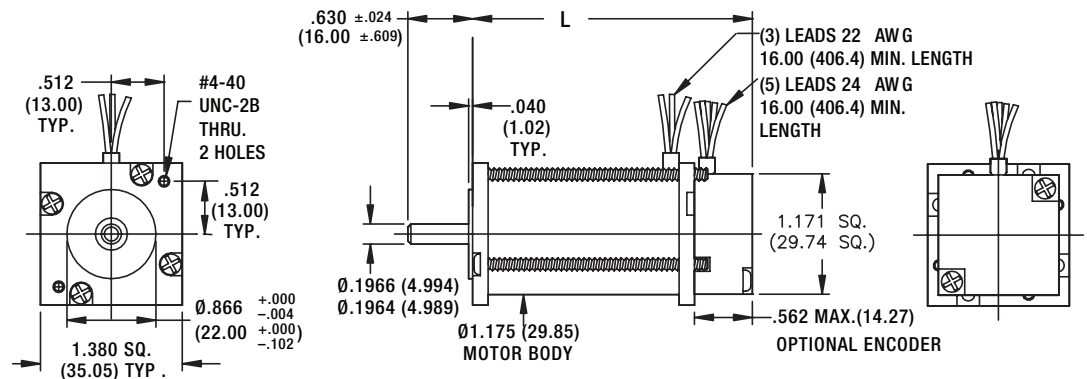
Dimensional Drawings: ES030A-1 • ES030A-2

Dimensions = inches (mm)

L = Lengths Available

ES030A-1 = 2.322 (58.98) Max.

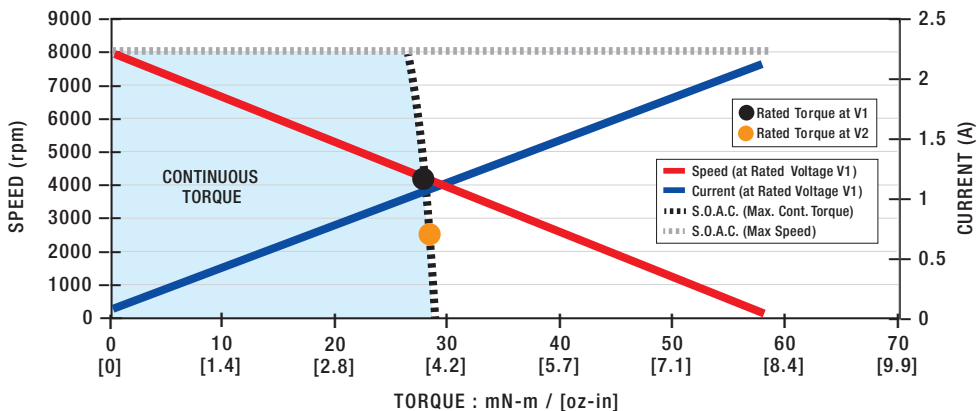
ES030A-2 = 2.722 (69.14) Max.



Performance Data & Graph: ES030A-1

Motor Data		Units								
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.028	0.028	0.028	0.028	0.028	0.028	0.028	0.028
		oz-in	4.0	4.0	4.0	4.0	4.0	4.0	4.0	4.0
Rated Speed ¹	ω_r	rpm	4140	3630	3950	4160	3600	4240	4160	3600
Rated Current ¹	I_r	A	2.1	1.7	1.3	1.0	0.84	0.66	0.52	0.42
Rated Power ¹	P_r	W	12	11	12	12	11	12	12	11
No Load Speed	ω_{nl}	rpm	7090	7180	7140	7110	7160	7150	7120	7160
No Load Current	I_{nl}	A	0.12	0.092	0.072	0.057	0.046	0.036	0.029	0.023
Rated Voltage V2	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.029	0.029	0.029	0.029	0.029	0.028	0.029	0.029
		oz-in	4.0	4.1	4.0	4.0	4.1	4.0	4.0	4.1
Rated Speed ¹	ω_r	rpm	2450	1860	2240	2450	1860	2510	2450	1860
Rated Current ¹	I_r	A	2.1	1.7	1.3	1.1	0.85	0.67	0.53	0.43
Rated Power ¹	P_r	W	7.3	5.6	6.7	7.3	5.6	7.5	7.3	5.6
No Load Speed	ω_{nl}	rpm	5630	5650	5670	5640	5650	5660	5650	5650
No Load Current	I_{nl}	A	0.11	0.083	0.066	0.052	0.042	0.033	0.026	0.021
Motor Constant	K_M	Nm/√W	0.011	0.010	0.011	0.011	0.010	0.011	0.011	0.010
		oz-in/√W	1.6	1.5	1.5	1.6	1.5	1.6	1.6	1.5
Torque Constant	K_T	Nm/A	0.0159	0.0198	0.0250	0.0316	0.0395	0.0500	0.0631	0.0791
		oz-in/A	2.24	2.80	3.54	4.48	5.60	7.09	8.94	11.2
Voltage Constant	K_E	V/(rad/s)	0.0159	0.0198	0.0250	0.0316	0.0395	0.0500	0.0631	0.0791
		V/krpm	1.66	2.07	2.62	3.31	4.14	5.24	6.61	8.28
Terminal Resistance	R_{mt}	Ω	1.98	3.55	5.25	7.90	14.2	19.6	31.6	56.8
Inductance	L	mH	0.18	0.32	0.46	0.70	1.3	1.8	2.8	5.1
Peak Current	I_{pk}	A	6.1	4.3	3.6	3.0	2.1	1.9	1.5	1.1
Electrical Time Constant	τ_e	ms	0.091	0.090	0.088	0.089	0.090	0.093	0.089	0.090
Mechanical Time Constant	τ_m	ms	7.8	9.0	8.3	7.8	9.0	7.7	7.8	9.0

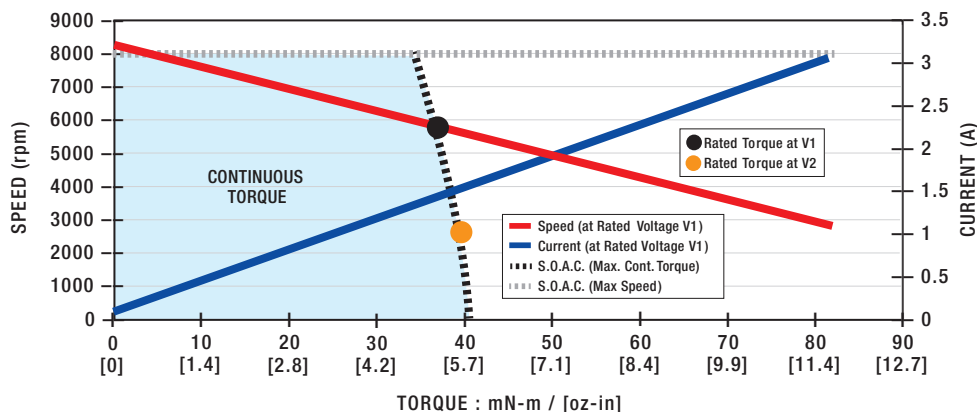
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: ES030A-2

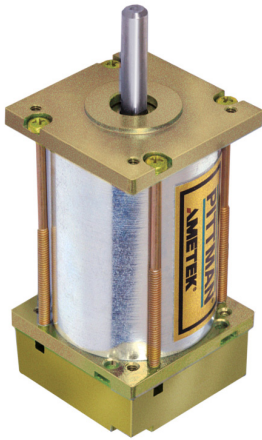
Motor Data		Units								
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.038	0.037	0.038	0.037	0.038	0.037	0.037	0.038
		oz-in	5.4	5.3	5.3	5.2	5.3	5.2	5.2	5.3
Rated Speed ¹	ω_r	rpm	5170	5380	5320	5800	5350	5750	5800	5360
Rated Current ¹	I_r	A	3.0	2.3	1.9	1.5	1.1	0.91	0.73	0.56
Rated Power ¹	P_r	W	21	21	21	22	21	22	22	21
No Load Speed	ω_{nl}	rpm	7360	7190	7390	7410	7170	7390	7400	7170
No Load Current	I_{nl}	A	0.20	0.15	0.13	0.097	0.072	0.061	0.048	0.037
Rated Voltage V2	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.040	0.040	0.040	0.040	0.040	0.040	0.040	0.040
		oz-in	5.7	5.6	5.7	5.6	5.6	5.6	5.6	5.6
Rated Speed ¹	ω_r	rpm	1970	2230	2080	2590	2230	2510	2580	2240
Rated Current ¹	I_r	A	3.1	2.3	1.9	1.5	1.2	0.96	0.76	0.59
Rated Power ¹	P_r	W	8.3	9.3	8.7	11	9.3	10	11	9.3
No Load Speed	ω_{nl}	rpm	4640	4500	4630	4680	4500	4630	4660	4510
No Load Current	I_{nl}	A	0.15	0.11	0.091	0.073	0.055	0.046	0.037	0.028
Motor Constant	K_M	Nm/ \sqrt{W}	0.015	0.016	0.015	0.016	0.016	0.016	0.016	0.016
		oz-in/ \sqrt{W}	2.1	2.2	2.1	2.3	2.2	2.3	2.3	2.2
Torque Constant	K_T	Nm/A	0.0153	0.0199	0.0243	0.0305	0.0397	0.0486	0.0610	0.0794
		oz-in/A	2.16	2.81	3.43	4.31	5.63	6.88	8.64	11.2
Voltage Constant	K_E	V/(rad/s)	0.0153	0.0199	0.0243	0.0305	0.0397	0.0486	0.0610	0.0794
		V/krpm	1.60	2.08	2.54	3.19	4.16	5.09	6.39	8.31
Terminal Resistance	R_{mt}	Ω	1.10	1.63	2.67	3.62	6.52	9.32	14.5	26.0
Inductance	L	mH	0.12	0.19	0.29	0.48	0.76	1.2	1.9	3.0
Peak Current	I_{pk}	A	9.3	7.2	5.7	4.8	3.6	2.9	2.3	1.8
Electrical Time Constant	τ_e	ms	0.11	0.12	0.11	0.13	0.12	0.12	0.13	0.12
Mechanical Time Constant	τ_m	ms	6.8	5.9	6.5	5.6	6.0	5.7	5.6	6.0

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



ES040A Series

The ES040A Series Brushless DC Motor is a high torque density model brushless motor with a slotless design in a NEMA 17 configuration. It is offered in 3 motor lengths with continuous torque from 0.085 – 0.134 Nm.



Shown with optional assembly.

Benefits

- Speeds up to 8,000 RPM possible
- DC bus voltage up to 120 VDC
- NEMA 17 configuration
- Eight standard windings, special windings available
- 4 pole rare earth design

Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G40A, PLG42S, G51A, PLG52
- Brakes: B30A, B49A
- Programmable Drives: PBL4850E, BGE6015A

Motor Characteristics

Motor Data	Units	Series			
		ES040A-1	ES040A-2	ES040A-3	
Max DC Terminal Voltage	V_T	V			
Max Speed (Mechanical)	ω_{MAX}	rpm			
Continuous Stall Torque ¹	T_{CS}	Nm	0.085	0.100	0.134
		oz-in	12	14	19
Peak Torque (Maximum) ¹	T_{pk}	Nm	0.26	0.31	0.41
		oz-in	36	43	59
Coulomb Friction Torque	T_f	Nm	0.0011	0.0011	0.0011
		oz-in	0.15	0.15	0.15
Viscous Damping Factor	D	Nm/(rad/s)	1.6E-06	1.8E-06	2.2E-06
		oz-in/krpm	0.024	0.027	0.033
Thermal Time Constant	τ_{th}	min			
Thermal Resistance	R_{th}	°C/W			
Max. Winding Temperature	θ_{MAX}	°C			
Rotor Inertia	J_r	kg-m ²	4.5E-06	5.7E-06	6.1E-06
		oz-in-s ²	6.4E-04	8.0E-04	8.6E-04
Motor Weight	W_m	g	400	450	510
		oz	14	16	18

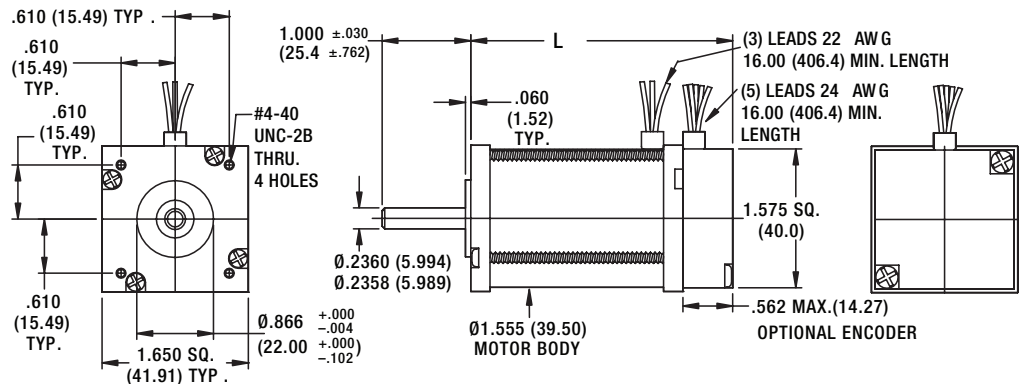
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: ES040A-1 • ES040A-2 • ES040A-3

Dimensions = inches (mm)

L = Lengths Available

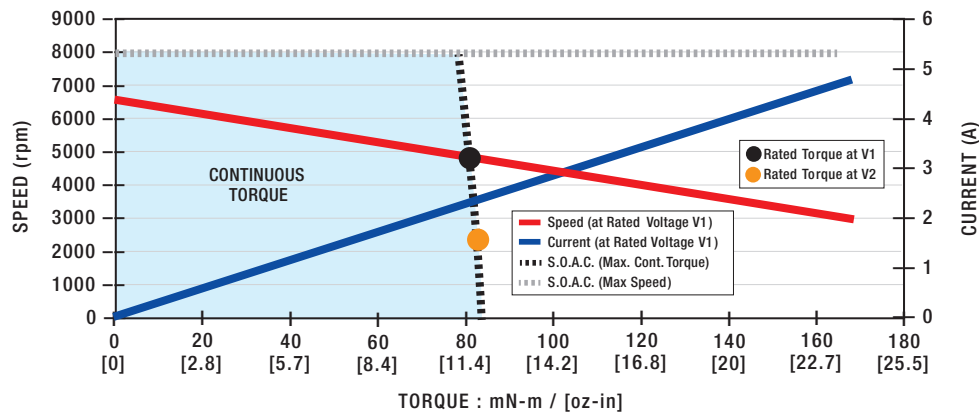
ES040A-1 = 2.655 (67.44) Max.
 ES040A-2 = 2.955 (75.06) Max.
 ES040A-3 = 3.255 (82.68) Max.



■ Performance Data & Graph: ES040A-1

Motor Data		Units								
Rated Voltage V1	V _R	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _R	Nm	0.081	0.081	0.081	0.081	0.081	0.081	0.081	0.081
		oz-in	12	12	12	12	12	12	12	12
Rated Speed ¹	ω _R	rpm	4810	4790	4790	4800	4790	4790	4800	4790
Rated Current ¹	I _R	A	3.7	3.0	2.4	1.9	1.5	1.2	0.94	0.74
Rated Power ¹	P _R	W	41	41	41	41	41	41	41	41
No Load Speed	ω _{NL}	rpm	5800	5760	5790	5790	5760	5790	5800	5760
No Load Current	I _{NL}	A	0.082	0.065	0.052	0.041	0.033	0.026	0.021	0.017
Rated Voltage V2	V _R	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _R	Nm	0.083	0.083	0.083	0.083	0.083	0.083	0.083	0.083
		oz-in	12	12	12	12	12	12	12	12
Rated Speed ¹	ω _R	rpm	2360	2350	2370	2360	2350	2360	2360	2350
Rated Current ¹	I _R	A	3.8	3.0	2.4	1.9	1.5	1.2	0.96	0.76
Rated Power ¹	P _R	W	21	20	21	21	20	21	21	20
No Load Speed	ω _{NL}	rpm	3640	3620	3660	3650	3620	3650	3650	3620
No Load Current	I _{NL}	A	0.068	0.054	0.043	0.034	0.027	0.022	0.017	0.014
Motor Constant	K _M	Nm/√W	0.029	0.029	0.029	0.029	0.029	0.029	0.029	0.029
		oz-in/√W	4.1	4.1	4.1	4.1	4.1	4.1	4.1	4.1
Torque Constant	K _T	Nm/A	0.0249	0.0315	0.0394	0.0498	0.0630	0.0788	0.0993	0.126
		oz-in/A	3.53	4.46	5.58	7.05	8.93	11.2	14.1	17.9
Voltage Constant	K _E	V/(rad/s)	0.0249	0.0315	0.0394	0.0498	0.0630	0.0788	0.0993	0.126
		V/krpm	2.61	3.30	4.13	5.21	6.60	8.25	10.4	13.2
Terminal Resistance	R _{mt}	Ω	0.750	1.19	1.89	3.00	4.76	7.56	12.0	19.0
Inductance	L	mH	0.14	0.21	0.34	0.54	0.84	1.3	2.2	3.4
Peak Current	I _{pk}	A	12	9.3	7.2	5.7	4.5	3.6	2.9	2.3
Electrical Time Constant	τ _e	ms	0.19	0.18	0.18	0.18	0.18	0.18	0.18	0.18
Mechanical Time Constant	τ _m	ms	5.5	5.5	5.5	5.5	5.4	5.5	5.5	5.4

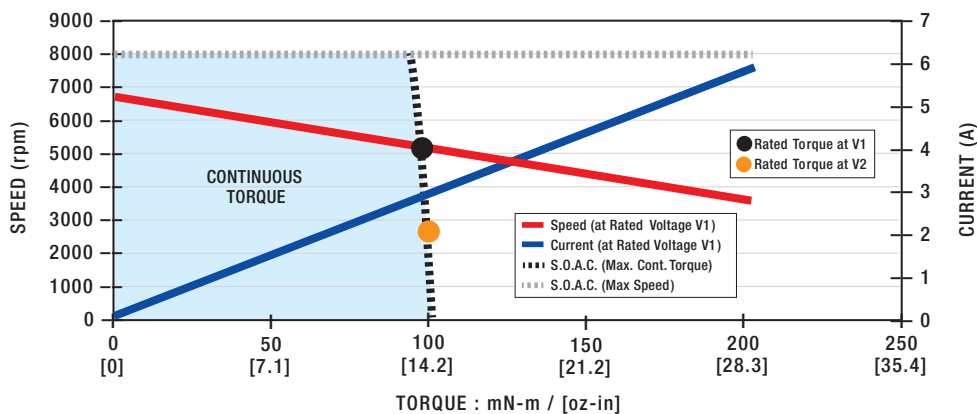
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: ES040A-2

Motor Data		Units								
Rated Voltage V1	V_r	V	19.1	24.0	30.3	38.2	48.0	60.6	76.4	96.0
Rated Torque ¹ •	T_r	Nm	0.097	0.097	0.097	0.097	0.097	0.097	0.097	0.097
		oz-in	14	14	14	14	14	14	14	14
Rated Speed ¹	ω_r	rpm	5200	5160	5200	5190	5160	5210	5190	5160
Rated Current ¹	I_r	A	3.7	2.9	2.3	1.8	1.4	1.2	0.91	0.72
Rated Power ¹	P_r	W	53	53	53	53	53	53	53	53
No Load Speed	ω_{nl}	rpm	5950	5920	5970	5940	5910	5980	5950	5910
No Load Current	I_{nl}	A	0.072	0.057	0.046	0.036	0.029	0.023	0.018	0.015
Rated Voltage V2	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.10	0.10	0.10	0.10	0.10	0.10	0.10	0.10
		oz-in	14	14	14	14	14	14	14	14
Rated Speed ¹	ω_r	rpm	2680	2690	2690	2670	2680	2690	2680	2680
Rated Current ¹	I_r	A	3.7	3.0	2.4	1.9	1.5	1.2	0.93	0.74
Rated Power ¹	P_r	W	28	28	28	28	28	28	28	28
No Load Speed	ω_{nl}	rpm	3730	3750	3760	3730	3730	3770	3730	3730
No Load Current	I_{nl}	A	0.058	0.047	0.037	0.029	0.024	0.019	0.015	0.012
Motor Constant	K_M	Nm/ \sqrt{W}	0.034	0.034	0.033	0.034	0.034	0.034	0.034	0.034
		oz-in/ \sqrt{W}	4.8	4.8	4.7	4.8	4.8	4.7	4.8	4.8
Torque Constant	K_T	Nm/A	0.0306	0.0386	0.0483	0.0612	0.0773	0.0964	0.122	0.155
		oz-in/A	4.33	5.46	6.84	8.67	10.9	13.7	17.3	21.9
Voltage Constant	K_E	V/(rad/s)	0.0306	0.0386	0.0483	0.0612	0.0773	0.0964	0.122	0.155
		V/krpm	3.20	4.04	5.06	6.41	8.09	10.1	12.8	16.2
Terminal Resistance	R_{mt}	Ω	0.820	1.31	2.08	3.30	5.24	8.32	13.2	21.0
Inductance	L	mH	0.16	0.26	0.41	0.64	1.0	1.6	2.6	4.2
Peak Current	I_{pk}	A	11	9.0	7.2	5.7	4.5	3.6	2.9	2.3
Electrical Time Constant	τ_e	ms	0.20	0.20	0.20	0.19	0.20	0.19	0.20	0.20
Mechanical Time Constant	τ_m	ms	5.0	5.0	5.1	5.0	5.0	5.1	5.0	5.0

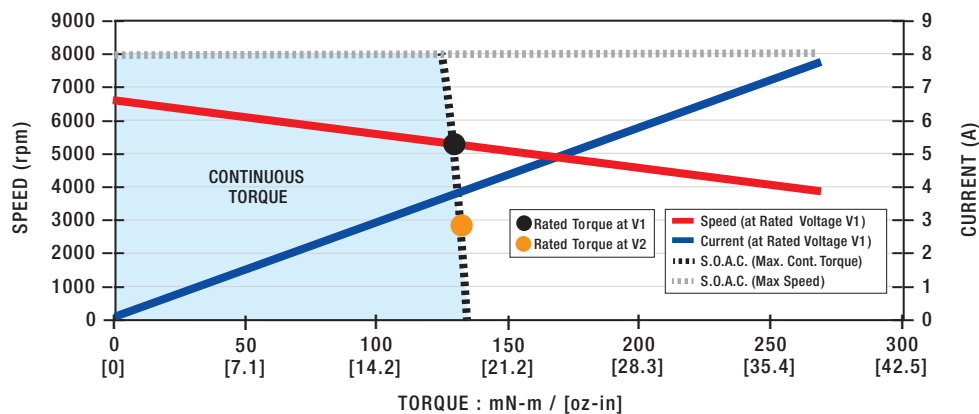
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: ES040A-3

Motor Data		Units								
Rated Voltage V1	V _r	V	24.0	30.3	38.2	48.0	60.6	76.4	96.0	121
Rated Torque ¹ •	T _r	Nm	0.13	0.13	0.13	0.13	0.13	0.13	0.13	0.13
		oz-in	18	18	18	18	18	18	18	18
Rated Speed ¹	ω _r	rpm	5250	5250	5270	5240	5230	5270	5250	5240
Rated Current ¹	I _r	A	3.8	3.0	2.4	1.9	1.5	1.2	0.95	0.75
Rated Power ¹	P _r	W	71	71	72	71	71	72	71	71
No Load Speed	ω _{nl}	rpm	5840	5840	5870	5830	5810	5860	5840	5830
No Load Current	I _{nl}	A	0.062	0.049	0.040	0.031	0.025	0.020	0.016	0.013
Rated Voltage V2	V _r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _r	Nm	0.13	0.13	0.13	0.13	0.13	0.13	0.13	0.13
		oz-in	19	19	19	19	19	19	19	19
Rated Speed ¹	ω _r	rpm	2820	2800	2790	2800	2800	2790	2800	2800
Rated Current ¹	I _r	A	3.9	3.1	2.4	1.9	1.5	1.2	0.97	0.77
Rated Power ¹	P _r	W	39	39	39	39	39	39	39	39
No Load Speed	ω _{nl}	rpm	3700	3680	3690	3680	3660	3680	3680	3680
No Load Current	I _{nl}	A	0.050	0.039	0.031	0.025	0.020	0.016	0.013	0.0097
Motor Constant	K _M	Nm/√W	0.041	0.041	0.041	0.041	0.042	0.041	0.041	0.041
		oz-in/√W	5.9	5.9	5.8	5.9	5.9	5.9	5.9	5.9
Torque Constant	K _T	Nm/A	0.0392	0.0495	0.0620	0.0784	0.0993	0.124	0.157	0.198
		oz-in/A	5.54	7.00	8.78	11.1	14.1	17.6	22.2	28.0
Voltage Constant	K _E	V/(rad/s)	0.0392	0.0495	0.0620	0.0784	0.0993	0.124	0.157	0.198
		V/krpm	4.10	5.18	6.49	8.21	10.4	13.0	16.4	20.7
Terminal Resistance	R _{mt}	Ω	0.890	1.42	2.26	3.58	5.68	9.04	14.3	22.7
Inductance	L	mH	0.19	0.30	0.47	0.74	1.2	1.9	3.0	4.8
Peak Current	I _{pk}	A	12	9.3	7.5	6.0	4.5	3.6	2.9	2.3
Electrical Time Constant	τ _e	ms	0.21	0.21	0.21	0.21	0.21	0.21	0.21	0.21
Mechanical Time Constant	τ _m	ms	3.5	3.5	3.6	3.5	3.5	3.5	3.5	3.5

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



ES050A Series

The ES050A Series Brushless DC Motor is a high torque density model brushless motor with a slotless design in a NEMA 23 configuration. It is offered in 3 motor lengths with continuous torque from 0.18 – 0.30 Nm.



Shown with optional assembly.

Benefits

- Speeds up to 5,000 RPM possible
- DC bus voltage up to 120 VDC
- NEMA 23 configuration
- Eight standard windings, special windings available
- 4 pole rare earth design

Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G40A, PLG42S, PLG52
- Brake: B49A
- Programmable Drives: PBL4850E, BGE6015A

Motor Characteristics

Motor Data	Units	Series		
		ES050A-1	ES050A-2	ES050A-3
Max DC Terminal Voltage V_T	V	120		
Max Speed (Mechanical) ω_{MAX}	rpm	5000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.18	0.25	0.30
	oz-in	25	35	43
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.54	0.77	0.94
	oz-in	76	110	130
Coulomb Friction Torque T_f	Nm	0.0030	0.0037	0.0040
	oz-in	0.42	0.52	0.57
Viscous Damping Factor D	Nm/(rad/s)	1.3E-05	1.5E-05	1.7E-05
	oz-in/krpm	0.19	0.22	0.25
Thermal Time Constant τ_{th}	min	14	17	22
Thermal Resistance R_{th}	°C/W	4.8	4.5	4.4
Max. Winding Temperature θ_{MAX}	°C	130	130	130
Rotor Inertia J_r	kg-m ²	1.7E-05	2.8E-05	3.4E-05
	oz-in-s ²	0.0025	0.0040	0.0048
Motor Weight W_m	g	620	850	990
	oz	22	30	35

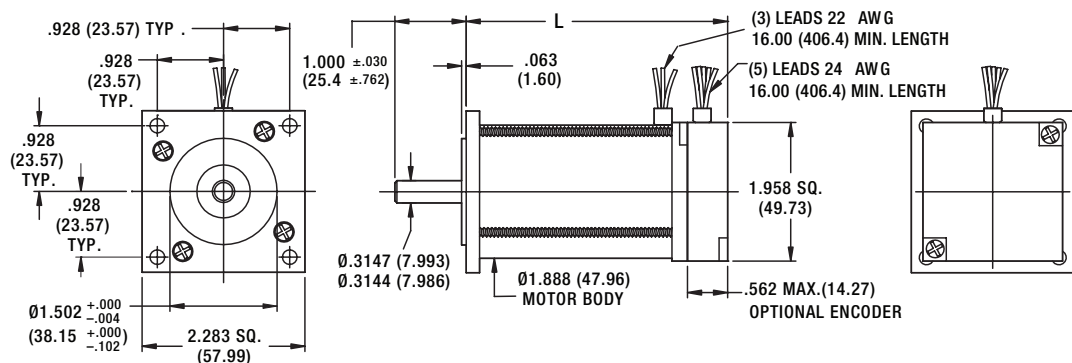
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

Dimensional Drawings: ES050A-1 • ES050A-2 • ES050A-3

Dimensions = inches (mm)

L = Lengths Available

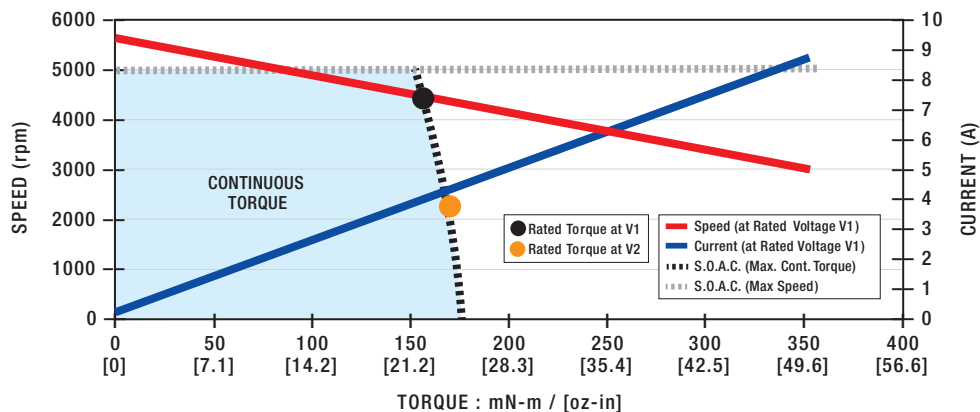
ES050A-1 = 3.165 (80.39) Max.
 ES050A-2 = 3.665 (93.09) Max.
 ES050A-3 = 4.165 (105.79) Max.



■ Performance Data & Graph: ES050A-1

Motor Data		Units								
Rated Voltage V1	V _r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _r	Nm	0.16	0.16	0.16	0.16	0.16	0.16	0.16	0.16
		oz-in	23	23	22	22	22	22	22	22
Rated Speed ¹	ω _r	rpm	4480	4320	4460	4430	4490	4470	4430	4500
Rated Current ¹	I _r	A	9.1	6.6	5.1	4.1	3.2	2.6	2.0	1.6
Rated Power ¹	P _r	W	75	72	73	73	73	73	73	74
No Load Speed	ω _{nl}	rpm	5000	5000	5000	4980	5000	5000	4990	5000
No Load Current	I _{nl}	A	0.47	0.34	0.27	0.22	0.17	0.14	0.11	0.086
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.17	0.17	0.17	0.17	0.17	0.17	0.17	0.17
		oz-in	24	24	24	24	24	24	24	24
Rated Speed ¹	ω _r	rpm	2150	2140	2290	2300	2320	2290	2290	2320
Rated Current ¹	I _r	A	9.5	6.9	5.5	4.3	3.5	2.7	2.2	1.7
Rated Power ¹	P _r	W	39	38	41	41	41	41	41	41
No Load Speed	ω _{nl}	rpm	3420	3160	3140	3150	3170	3140	3150	3180
No Load Current	I _{nl}	A	0.37	0.26	0.20	0.16	0.13	0.10	0.079	0.064
Motor Constant	K _M	Nm/√W	0.042	0.046	0.049	0.049	0.049	0.049	0.049	0.049
		oz-in/√W	5.9	6.5	6.9	6.9	6.9	6.9	6.9	6.9
Torque Constant	K _T	Nm/A	0.0209	0.0286	0.0361	0.0456	0.0570	0.0722	0.0911	0.114
		oz-in/A	2.96	4.04	5.11	6.46	8.07	10.2	12.9	16.1
Voltage Constant	K _E	V/(rad/s)	0.0209	0.0286	0.0361	0.0456	0.0570	0.0722	0.0911	0.114
		V/krpm	2.19	2.99	3.78	4.78	5.97	7.56	9.54	11.9
Terminal Resistance	R _{mt}	Ω	0.250	0.390	0.550	0.880	1.37	2.20	3.52	5.48
Inductance	L	mH	0.060	0.10	0.17	0.27	0.41	0.66	1.1	1.7
Peak Current	I _{pk}	A	29	21	17	13	11	8.4	6.6	5.4
Electrical Time Constant	τ _e	ms	0.24	0.26	0.31	0.31	0.30	0.30	0.30	0.30
Mechanical Time Constant	τ _m	ms	10	8.3	7.4	7.4	7.4	7.4	7.4	7.4

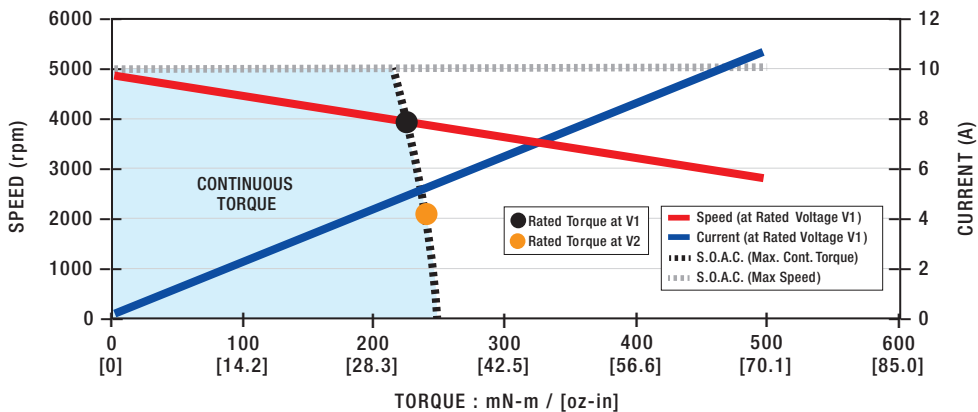
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: ES050A-2

Motor Data		Units								
Rated Voltage V1	V_r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T_r	Nm	0.23	0.23	0.22	0.22	0.22	0.22	0.22	0.22
		oz-in	32	32	32	32	32	32	32	32
Rated Speed ¹	ω_r	rpm	4090	3860	3950	3940	3980	3930	3940	3980
Rated Current ¹	I_r	A	8.8	6.4	5.0	4.0	3.2	2.5	2.0	1.6
Rated Power ¹	P_r	W	97	92	92	92	93	92	93	93
No Load Speed	ω_{nl}	rpm	4760	4380	4350	4360	4390	4340	4370	4390
No Load Current	I_{nl}	A	0.37	0.26	0.20	0.16	0.13	0.099	0.080	0.064
Rated Voltage V2	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.24	0.24	0.24	0.24	0.24	0.24	0.24	0.24
		oz-in	34	34	34	34	34	34	34	34
Rated Speed ¹	ω_r	rpm	2040	1970	2100	2080	2100	2080	2080	2090
Rated Current ¹	I_r	A	9.2	6.7	5.3	4.2	3.3	2.6	2.1	1.7
Rated Power ¹	P_r	W	51	50	52	52	52	52	52	52
No Load Speed	ω_{nl}	rpm	2990	2750	2750	2740	2760	2740	2750	2760
No Load Current	I_{nl}	A	0.28	0.20	0.16	0.13	0.097	0.076	0.061	0.049
Motor Constant	K_M	Nm/ \sqrt{W}	0.056	0.061	0.064	0.064	0.064	0.065	0.064	0.064
		oz-in/ \sqrt{W}	8.0	8.6	9.1	9.1	9.1	9.1	9.1	9.1
Torque Constant	K_T	Nm/A	0.0303	0.0413	0.0523	0.0660	0.0826	0.105	0.132	0.165
		oz-in/A	4.29	5.86	7.41	9.34	11.7	14.9	18.7	23.4
Voltage Constant	K_E	V/(rad/s)	0.0303	0.0413	0.0523	0.0660	0.0826	0.105	0.132	0.165
		V/krpm	3.17	4.33	5.48	6.91	8.65	11.0	13.8	17.3
Terminal Resistance	R_{mt}	Ω	0.290	0.460	0.660	1.06	1.65	2.66	4.25	6.62
Inductance	L	mH	0.080	0.13	0.21	0.34	0.53	0.86	1.4	2.1
Peak Current	I_{pk}	A	28	21	16	13	10	8.1	6.6	5.1
Electrical Time Constant	τ_e	ms	0.28	0.28	0.32	0.32	0.32	0.32	0.32	0.32
Mechanical Time Constant	τ_m	ms	8.9	7.6	6.8	6.9	6.8	6.8	6.9	6.8

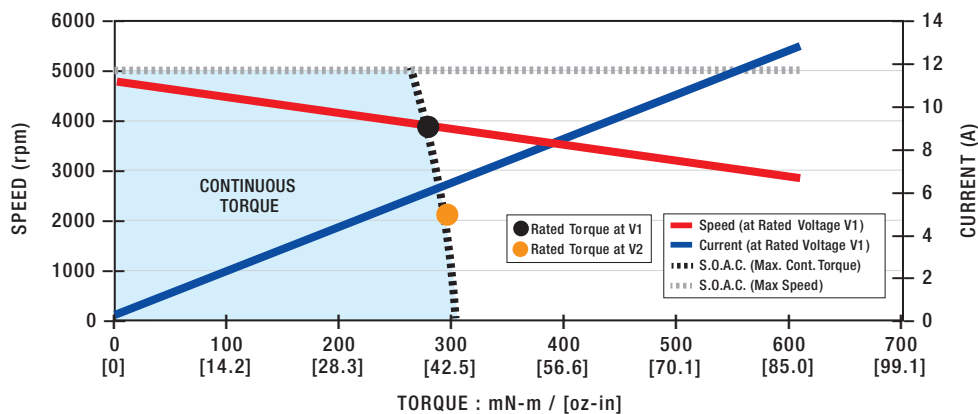
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: ES050A-3

Motor Data		Units								
Rated Voltage V1	V_r	V	19.1	24.0	30.3	38.2	48.0	60.6	76.4	96.0
Rated Torque ¹ •	T_r	Nm	0.28	0.28	0.27	0.27	0.27	0.27	0.27	0.27
		oz-in	39	39	39	39	39	39	39	39
Rated Speed ¹	ω_r	rpm	4120	3870	3950	3950	3970	3970	3950	3970
Rated Current ¹	I_r	A	8.1	6.0	4.6	3.7	2.9	2.3	1.8	1.5
Rated Power ¹	P_r	W	120	110	110	110	110	110	110	110
No Load Speed	ω_{nl}	rpm	4570	4220	4210	4200	4230	4220	4200	4230
No Load Current	I_{nl}	A	0.31	0.22	0.17	0.14	0.11	0.085	0.067	0.054
Rated Voltage V2	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.29	0.29	0.29	0.29	0.29	0.29	0.29	0.29
		oz-in	42	42	41	41	41	41	41	41
Rated Speed ¹	ω_r	rpm	2160	2080	2160	2140	2170	2160	2140	2170
Rated Current ¹	I_r	A	8.5	6.3	4.9	3.9	3.1	2.5	1.9	1.6
Rated Power ¹	P_r	W	66	64	66	66	66	66	66	66
No Load Speed	ω_{nl}	rpm	2870	2670	2650	2640	2670	2660	2640	2670
No Load Current	I_{nl}	A	0.23	0.17	0.13	0.10	0.081	0.064	0.051	0.041
Motor Constant	K_M	Nm/ \sqrt{W}	0.069	0.074	0.079	0.079	0.078	0.078	0.079	0.078
		oz-in/ \sqrt{W}	9.8	11	11	11	11	11	11	11
Torque Constant	K_T	Nm/A	0.0397	0.0540	0.0685	0.0865	0.108	0.137	0.173	0.216
		oz-in/A	5.63	7.65	9.70	12.3	15.3	19.3	24.5	30.6
Voltage Constant	K_E	V/(rad/s)	0.0397	0.0540	0.0685	0.0865	0.108	0.137	0.173	0.216
		V/krpm	4.16	5.66	7.17	9.06	11.3	14.3	18.1	22.6
Terminal Resistance	R_{mt}	Ω	0.330	0.530	0.760	1.21	1.90	3.03	4.85	7.60
Inductance	L	mH	0.090	0.16	0.26	0.41	0.65	1.0	1.7	2.6
Peak Current	I_{pk}	A	26	19	15	12	9.6	7.5	6.0	4.8
Electrical Time Constant	τ_e	ms	0.27	0.30	0.34	0.34	0.34	0.34	0.34	0.34
Mechanical Time Constant	τ_m	ms	7.1	6.2	5.5	5.5	5.6	5.5	5.5	5.6

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.





Shown with optional assembly.

DC026C Series

The DC026C Series Brush Commutated DC Motor is a 26 mm diameter, high performance unit offered in 3 lengths with continuous output torques of 0.0134 to 0.0226 Nm.

Motor Characteristics

Motor Data	Units	Series		
		DC026C-1	DC026C-2	DC026C-3
Max DC Terminal Voltage V_T	V	48		
Max Speed (Mechanical) ω_{MAX}	rpm	10000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.0134	0.0170	0.0226
	oz-in	1.9	2.4	3.2
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.059	0.084	0.13
	oz-in	8.3	12	19
Coulomb Friction Torque T_f	Nm	0.0021	0.0021	0.0021
	oz-in	0.30	0.30	0.30
Viscous Damping Factor D	Nm/(rad/s)	1.2E-06	1.3E-06	1.5E-06
	oz-in/krpm	0.018	0.020	0.022
Thermal Time Constant τ_{th}	min	13	13	12
Thermal Resistance R_{th}	°C/W	19	18	16
Max. Winding Temperature θ_{MAX}	°C	130	130	130
Rotor Inertia J_r	kg-m ²	9.9E-07	1.2E-06	1.6E-06
	oz-in-s ²	1.4E-04	1.7E-04	2.3E-04
Motor Weight W_m	g	76	86	110
	oz	2.7	3.1	3.7

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

Benefits

- Speeds up to 10,000 RPM possible
- DC bus voltage up to 48 VDC
- Eight standard windings, special windings available
- 2 pole stator with rare earth magnets
- 7 slot skewed armature cogging reduction
- Ball bearings
- Copper graphite brushes, RFI suppression available

Optional Assemblies

- Encoders: E21C/D, E30C/D
- Gearboxes: G30A, G35A
- Brake: B30A
- Programmable Drive: PBL4850E**

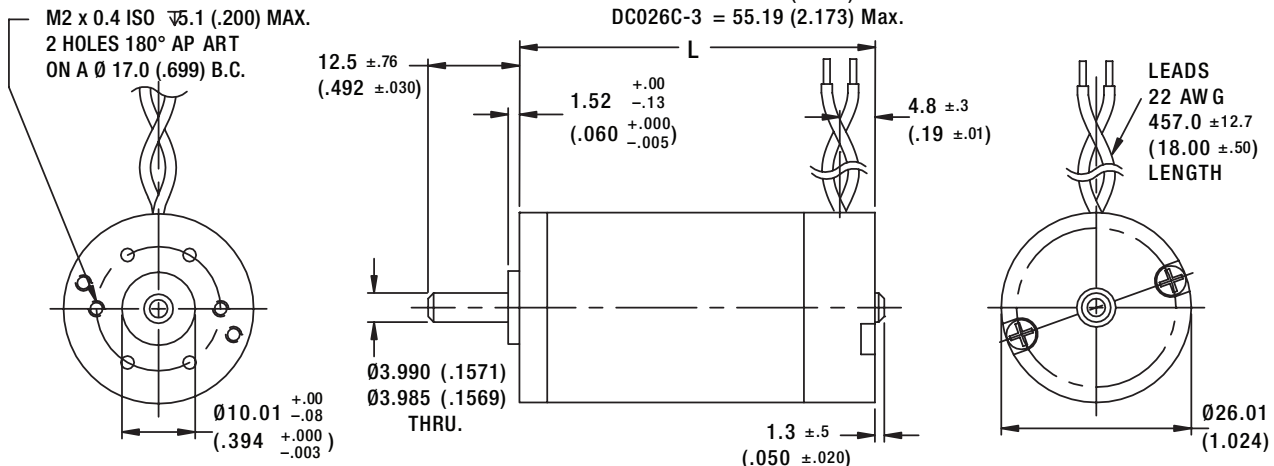
Dimensional Drawings: DC026C-1 • DC026C-2 • DC026C-3

L = Lengths Available

DC026C-1 = 45.67 (1.798) Max.

DC026C-2 = 48.84 (1.923) Max.

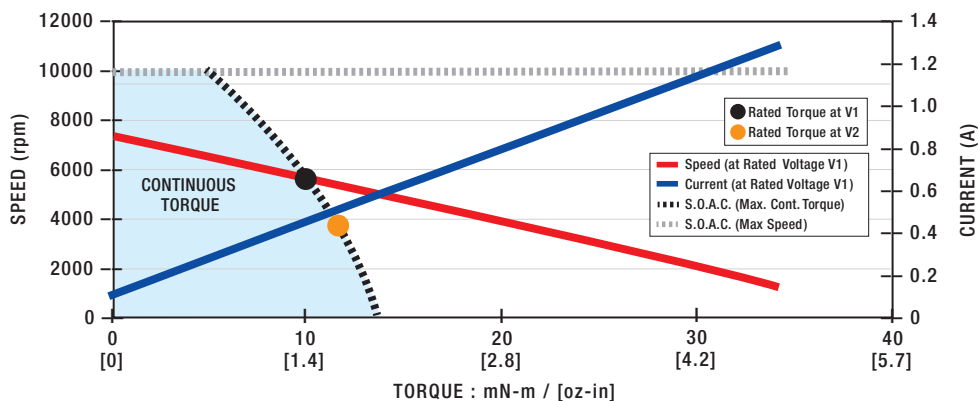
DC026C-3 = 55.19 (2.173) Max.



■ Performance Data & Graph: DC026C-1

Motor Data		Units								
Rated Voltage V1	V _r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3
Rated Torque ¹ •	T _r	Nm	0.011	0.011	0.010	0.010	0.010	0.010	0.010	0.010
		oz-in	1.5	1.5	1.5	1.4	1.4	1.4	1.4	1.4
Rated Speed ¹	ω _r	rpm	5080	5250	5350	5450	5610	5570	5530	5580
Rated Current ¹	I _r	A	1.9	1.5	1.1	0.92	0.73	0.57	0.45	0.36
Rated Power ¹	P _r	W	5.7	5.8	5.7	5.8	5.9	5.8	5.8	5.8
No Load Speed	ω _{nl}	rpm	6970	6990	6910	7000	7100	7030	6970	7010
No Load Current	I _{nl}	A	0.40	0.32	0.25	0.20	0.16	0.13	0.098	0.079
Rated Voltage V2	V _r	V	4.78	6.00	7.58	9.55	12.0	15.2	19.1	24.0
Rated Torque ¹ •	T _r	Nm	0.012	0.012	0.012	0.012	0.011	0.011	0.011	0.011
		oz-in	1.7	1.7	1.6	1.6	1.6	1.6	1.6	1.6
Rated Speed ¹	ω _r	rpm	3260	3380	3520	3620	3690	3730	3700	3700
Rated Current ¹	I _r	A	2.0	1.6	1.2	1.0	0.79	0.62	0.49	0.39
Rated Power ¹	P _r	W	4.1	4.2	4.3	4.4	4.4	4.5	4.4	4.4
No Load Speed	ω _{nl}	rpm	5500	5480	5430	5520	5560	5550	5500	5510
No Load Current	I _{nl}	A	0.37	0.30	0.23	0.19	0.15	0.12	0.092	0.074
Motor Constant	K _M	Nm/√W	0.0085	0.0088	0.0090	0.0090	0.0090	0.0091	0.0092	0.0091
		oz-in/√W	1.2	1.2	1.3	1.3	1.3	1.3	1.3	1.3
Torque Constant	K _T	Nm/A	0.00763	0.00964	0.0123	0.0153	0.0191	0.0243	0.0307	0.0386
		oz-in/A	1.08	1.37	1.74	2.16	2.70	3.43	4.35	5.46
Voltage Constant	K _E	V/(rad/s)	0.00763	0.00964	0.0123	0.0153	0.0191	0.0243	0.0307	0.0386
		V/krpm	0.799	1.01	1.29	1.60	2.00	2.54	3.22	4.04
Terminal Resistance	R _{mt}	Ω	0.800	1.22	1.87	2.89	4.47	7.08	11.3	17.8
Inductance	L	mH	0.41	0.66	1.1	1.6	2.6	4.1	6.6	10
Peak Current	I _{pk}	A	7.5	6.2	5.1	4.2	3.4	2.7	2.1	1.7
Electrical Time Constant	τ _e	ms	0.51	0.54	0.56	0.56	0.57	0.58	0.58	0.58
Mechanical Time Constant	τ _m	ms	14	13	12	12	12	12	12	12

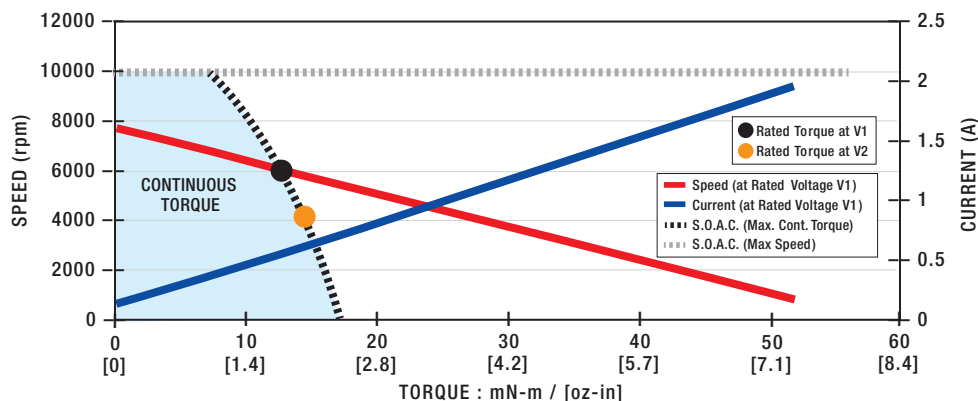
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC026C-2

Motor Data		Units								
Rated Voltage V1	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.013	0.013	0.013	0.013	0.013	0.013	0.013	0.013
		oz-in	1.9	1.9	1.8	1.8	1.8	1.8	1.8	1.8
Rated Speed ¹	ω_r	rpm	5720	5880	5900	6080	6130	6100	6100	6140
Rated Current ¹	I_r	A	1.9	1.5	1.1	0.91	0.72	0.57	0.45	0.36
Rated Power ¹	P_r	W	8.0	8.1	8.0	8.1	8.1	8.0	8.0	8.0
No Load Speed	ω_{nl}	rpm	7320	7330	7270	7370	7410	7350	7350	7370
No Load Current	I_{nl}	A	0.34	0.27	0.22	0.17	0.14	0.11	0.085	0.068
Rated Voltage V2	V_r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3
Rated Torque ¹ •	T_r	Nm	0.015	0.015	0.015	0.014	0.014	0.014	0.014	0.014
		oz-in	2.1	2.1	2.1	2.0	2.0	2.0	2.0	2.0
Rated Speed ¹	ω_r	rpm	3820	4000	4050	4140	4240	4220	4190	4240
Rated Current ¹	I_r	A	2.0	1.6	1.2	0.99	0.79	0.62	0.49	0.39
Rated Power ¹	P_r	W	6.0	6.1	6.2	6.3	6.4	6.3	6.3	6.4
No Load Speed	ω_{nl}	rpm	5750	5780	5750	5790	5860	5820	5790	5810
No Load Current	I_{nl}	A	0.32	0.26	0.20	0.16	0.13	0.10	0.079	0.063
Motor Constant	K_M	Nm/√W	0.010	0.010	0.010	0.011	0.011	0.011	0.011	0.011
		oz-in/√W	1.4	1.5	1.5	1.5	1.5	1.5	1.5	1.5
Torque Constant	K_T	Nm/A	0.00932	0.0117	0.0149	0.0186	0.0233	0.0295	0.0372	0.0469
		oz-in/A	1.32	1.66	2.11	2.64	3.30	4.18	5.27	6.64
Voltage Constant	K_E	V/(rad/s)	0.00932	0.0117	0.0149	0.0186	0.0233	0.0295	0.0372	0.0469
		V/krpm	0.976	1.23	1.56	1.95	2.44	3.09	3.90	4.91
Terminal Resistance	R_{mt}	Ω	0.860	1.30	2.02	3.10	4.84	7.67	12.2	19.2
Inductance	L	mH	0.47	0.76	1.2	1.9	3.0	4.8	7.6	12
Peak Current	I_{pk}	A	8.8	7.3	5.9	4.9	3.9	3.1	2.5	2.0
Electrical Time Constant	τ_e	ms	0.55	0.58	0.60	0.61	0.61	0.62	0.62	0.63
Mechanical Time Constant	τ_m	ms	12	11	11	11	11	11	11	10

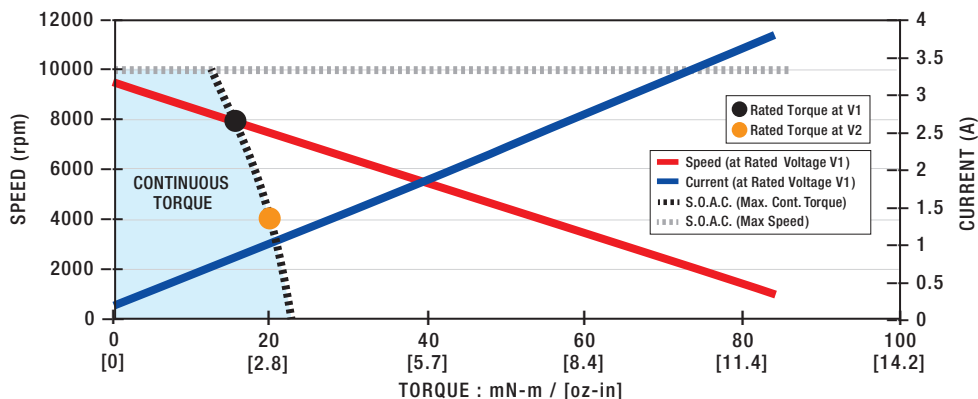
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC026C-3

Motor Data		Units									
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0	
Rated Torque ¹ •	T _r	Nm	0.017	0.016	0.016	0.015	0.015	0.015	0.015	0.015	
		oz-in	2.3	2.3	2.2	2.2	2.2	2.1	2.1	2.1	
Rated Speed ¹	ω _r	rpm	7540	7760	7880	7900	7980	8110	8090	8030	
Rated Current ¹	I _r	A	2.2	1.7	1.3	1.0	0.82	0.65	0.51	0.41	
Rated Power ¹	P _r	W	13	13	13	13	13	13	13	13	
No Load Speed	ω _{nl}	rpm	8920	8950	8970	8910	8970	9080	9050	8970	
No Load Current	I _{nl}	A	0.36	0.29	0.23	0.18	0.15	0.12	0.092	0.072	
Rated Voltage V2	V _r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3	
Rated Torque ¹ •	T _r	Nm	0.020	0.020	0.020	0.020	0.020	0.020	0.020	0.020	
		oz-in	2.9	2.8	2.8	2.8	2.8	2.8	2.8	2.8	
Rated Speed ¹	ω _r	rpm	3510	3740	3820	3860	3970	4010	3980	3990	
Rated Current ¹	I _r	A	2.5	2.0	1.6	1.2	0.98	0.79	0.62	0.49	
Rated Power ¹	P _r	W	7.4	7.8	7.9	7.9	8.1	8.2	8.2	8.2	
No Load Speed	ω _{nl}	rpm	5550	5600	5580	5550	5630	5680	5630	5610	
No Load Current	I _{nl}	A	0.31	0.25	0.20	0.16	0.13	0.099	0.078	0.062	
Motor Constant	K _M	Nm/√W	0.011	0.012	0.012	0.012	0.012	0.012	0.012	0.012	
		oz-in/√W	1.6	1.7	1.7	1.7	1.7	1.7	1.7	1.7	
Torque Constant	K _T	Nm/A	0.00974	0.0122	0.0155	0.0196	0.0244	0.0305	0.0386	0.0489	
		oz-in/A	1.38	1.73	2.19	2.77	3.46	4.31	5.46	6.92	
Voltage Constant	K _E	V/(rad/s)	0.00974	0.0122	0.0155	0.0196	0.0244	0.0305	0.0386	0.0489	
		V/krpm	1.02	1.28	1.62	2.05	2.56	3.19	4.04	5.12	
Terminal Resistance	R _{mt}	Ω	0.730	1.08	1.67	2.59	4.02	6.28	9.96	15.8	
Inductance	L	mH	0.39	0.61	0.98	1.6	2.4	3.8	6.1	9.8	
Peak Current	I _{pk}	A	13	11	9.1	7.4	6.0	4.8	3.8	3.0	
Electrical Time Constant	τ _e	ms	0.53	0.56	0.59	0.60	0.61	0.61	0.61	0.62	
Mechanical Time Constant	τ _m	ms	12	12	11	11	11	11	11	11	

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



DC030B Series

The DC030B Series Brush Commutated DC Motor is a 30 mm diameter unit offered in 3 lengths with continuous output torques of 0.0113 to 0.0184 Nm.



Shown with optional assemblies.

■ Benefits

- Speeds up to 10,000 RPM possible
- DC bus voltage up to 48 VDC
- Eight standard windings, special windings available
- 2 pole stator with ceramic magnets
- 7 slot skewed armature cogging reduction
- Sintered bronze bearings, ball bearings; copper graphite brushes, RFI suppression available

■ Optional Assemblies

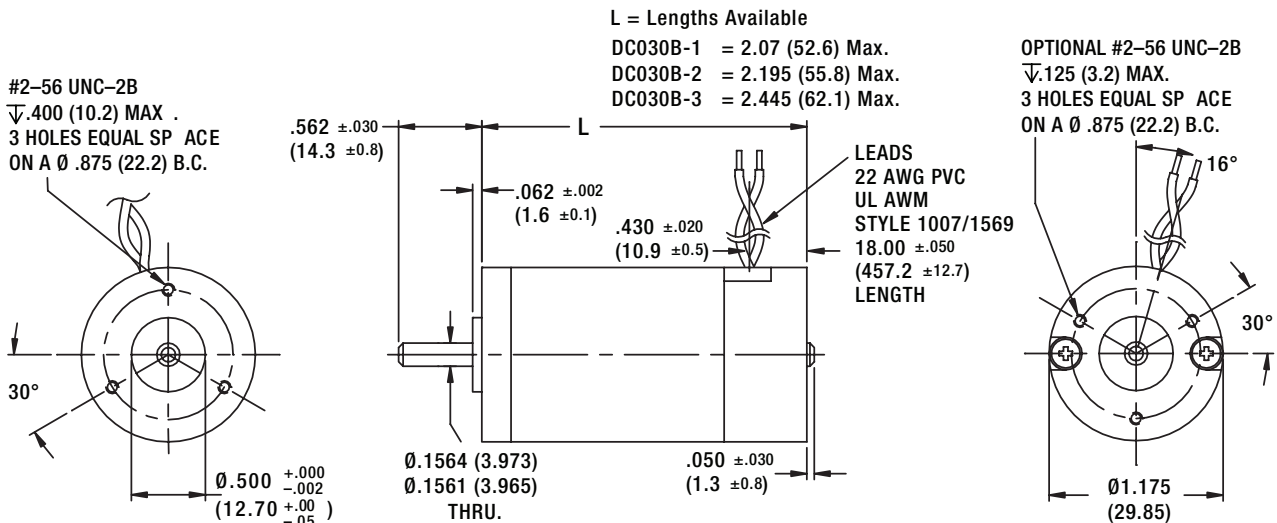
- Encoder: E30C/D
- Gearboxes: G30A, G35A
- Brake: B30A
- Programmable Drive: PBL4850E**

■ Motor Characteristics

Motor Data	Units	Series		
		DC030B-1	DC030B-2	DC030B-3
Max DC Terminal Voltage V_T	V	48		
Max Speed (Mechanical) ω_{MAX}	rpm	10000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.0113	0.0140	0.0184
	oz-in	1.6	2.0	2.6
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.045	0.065	0.10
	oz-in	6.4	9.2	15
Coulomb Friction Torque T_f	Nm	0.0025	0.0025	0.0025
	oz-in	0.35	0.35	0.35
Viscous Damping Factor D	Nm/(rad/s)	1.0E-06	1.2E-06	1.4E-06
	oz-in/krpm	0.016	0.018	0.021
Thermal Time Constant τ_{th}	min	7.8	9.0	11
Thermal Resistance R_{th}	°C/W	24	23	21
Max. Winding Temperature Θ_{MAX}	°C	155	155	155
Rotor Inertia J_r	kg-m ²	9.9E-07	1.2E-06	1.6E-06
	oz-in-s ²	1.4E-04	1.7E-04	2.3E-04
Motor Weight W_m	g	130	140	160
	oz	4.7	5.1	5.8

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

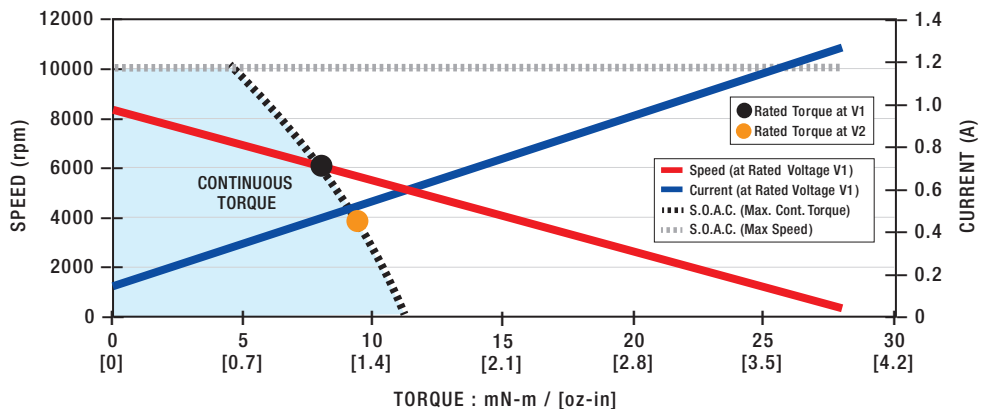
Dimensional Drawings: DC030B-1 • DC030B-2 • DC030B-3



■ Performance Data & Graph: DC030B-1

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.0082	0.0081	0.0080	0.0079	0.0080	0.0079	0.0079	0.0079
		oz-in	1.2	1.1	1.1	1.1	1.1	1.1	1.1	1.1
Rated Speed ¹	ω _r	rpm	5810	5940	6120	6100	6050	6110	6110	6100
Rated Current ¹	I _r	A	1.2	0.93	0.74	0.58	0.46	0.36	0.29	0.23
Rated Power ¹	P _r	W	5.0	5.0	5.1	5.1	5.0	5.1	5.0	5.0
No Load Speed	ω _{nl}	rpm	7630	7710	7810	7740	7700	7730	7700	7700
No Load Current	I _{nl}	A	0.30	0.25	0.20	0.16	0.13	0.096	0.076	0.061
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.0095	0.0094	0.0094	0.0093	0.0093	0.0093	0.0093	0.0093
		oz-in	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3
Rated Speed ¹	ω _r	rpm	3580	3700	3780	3850	3820	3820	3850	3860
Rated Current ¹	I _r	A	1.3	1.0	0.81	0.64	0.51	0.40	0.32	0.25
Rated Power ¹	P _r	W	3.6	3.7	3.7	3.8	3.7	3.7	3.7	3.8
No Load Speed	ω _{nl}	rpm	5970	6060	6090	6090	6050	6050	6030	6050
No Load Current	I _{nl}	A	0.29	0.23	0.19	0.15	0.12	0.091	0.072	0.058
Motor Constant	K _M	Nm/√W	0.0078	0.0077	0.0078	0.0079	0.0079	0.0079	0.0079	0.0079
		oz-in/√W	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1
Torque Constant	K _T	Nm/A	0.0110	0.0137	0.0171	0.0217	0.0274	0.0345	0.0436	0.0548
		oz-in/A	1.56	1.93	2.42	3.07	3.88	4.88	6.18	7.76
Voltage Constant	K _E	V/(rad/s)	0.0110	0.0137	0.0171	0.0217	0.0274	0.0345	0.0436	0.0548
		V/krpm	1.15	1.43	1.79	2.27	2.87	3.61	4.57	5.74
Terminal Resistance	R _{mt}	Ω	2.01	3.10	4.81	7.61	12.1	19.1	30.3	48.0
Inductance	L	mH	1.0	1.6	2.5	3.9	6.3	9.9	16	25
Peak Current	I _{pk}	A	4.8	3.9	3.2	2.5	2.0	1.6	1.3	1.0
Electrical Time Constant	τ _e	ms	0.50	0.51	0.51	0.52	0.52	0.52	0.52	0.52
Mechanical Time Constant	τ _m	ms	16	16	16	16	16	16	16	16

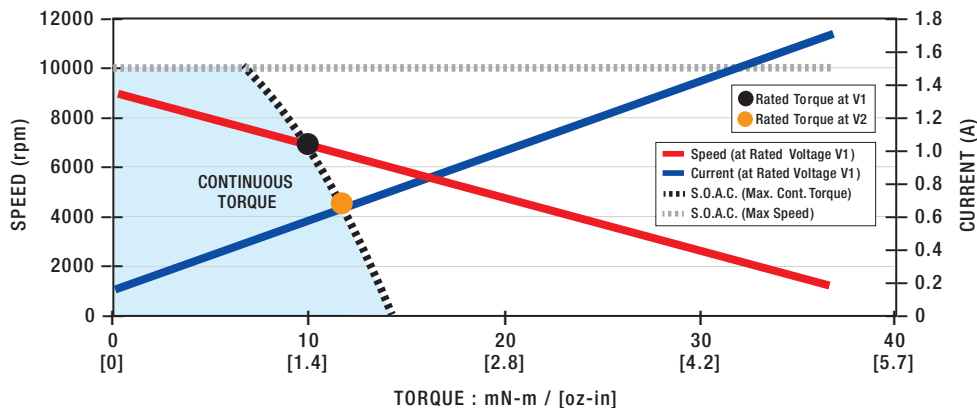
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: DC030B-2

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.010	0.010	0.0099	0.0099	0.0098	0.0098	0.0097	0.0098
		oz-in	1.5	1.4	1.4	1.4	1.4	1.4	1.4	1.4
Rated Speed ¹	ω _r	rpm	6520	6590	6790	6890	6840	6870	6890	6840
Rated Current ¹	I _r	A	1.5	1.2	0.90	0.72	0.57	0.45	0.35	0.28
Rated Power ¹	P _r	W	7.0	7.0	7.0	7.1	7.0	7.0	7.0	7.0
No Load Speed	ω _{nl}	rpm	8100	8060	8120	8230	8130	8150	8140	8100
No Load Current	I _{nl}	A	0.34	0.27	0.21	0.17	0.14	0.11	0.084	0.066
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.012	0.012	0.012	0.012	0.012	0.012	0.012	0.012
		oz-in	1.7	1.7	1.6	1.6	1.6	1.6	1.6	1.6
Rated Speed ¹	ω _r	rpm	4220	4330	4430	4570	4550	4530	4560	4560
Rated Current ¹	I _r	A	1.6	1.3	1.0	0.80	0.63	0.50	0.39	0.31
Rated Power ¹	P _r	W	5.3	5.3	5.4	5.5	5.5	5.5	5.5	5.5
No Load Speed	ω _{nl}	rpm	6370	6360	6360	6490	6420	6400	6410	6390
No Load Current	I _{nl}	A	0.32	0.25	0.20	0.16	0.13	0.099	0.078	0.062
Motor Constant	K _M	Nm/√W	0.0089	0.0090	0.0092	0.0091	0.0092	0.0092	0.0092	0.0093
		oz-in/√W	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3
Torque Constant	K _T	Nm/A	0.0105	0.0133	0.0167	0.0207	0.0264	0.0332	0.0419	0.0530
		oz-in/A	1.49	1.88	2.37	2.93	3.73	4.71	5.94	7.51
Voltage Constant	K _E	V/(rad/s)	0.0105	0.0133	0.0167	0.0207	0.0264	0.0332	0.0419	0.0530
		V/krpm	1.10	1.39	1.75	2.17	2.76	3.48	4.39	5.55
Terminal Resistance	R _{mt}	Ω	1.40	2.17	3.34	5.20	8.24	13.1	20.6	32.9
Inductance	L	mH	0.73	1.2	1.8	2.9	4.6	7.3	12	18
Peak Current	I _{pk}	A	6.8	5.5	4.6	3.7	2.9	2.3	1.9	1.5
Electrical Time Constant	τ _e	ms	0.52	0.54	0.54	0.55	0.55	0.56	0.56	0.56
Mechanical Time Constant	τ _m	ms	15	15	14	15	14	14	14	14

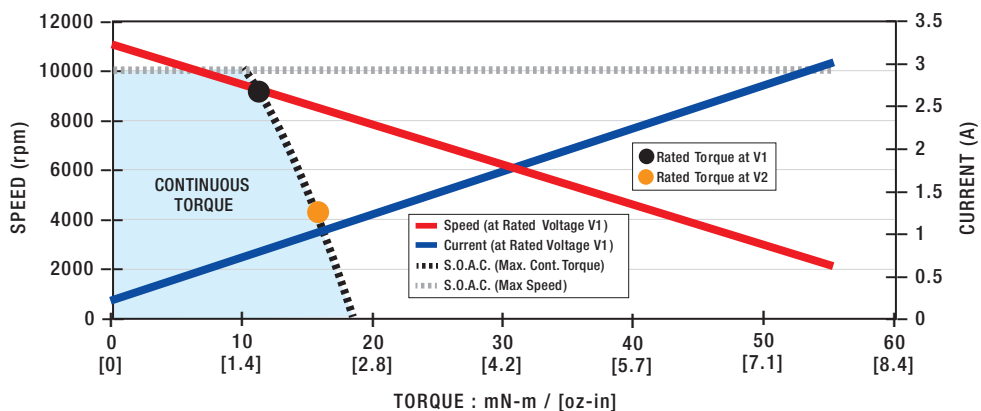
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC030B-3

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.013	0.012	0.012	0.012	0.011	0.011	0.011	0.011
		oz-in	1.8	1.7	1.7	1.6	1.6	1.6	1.6	1.6
Rated Speed ¹	ω _r	rpm	8500	8850	9020	9080	9170	9350	9310	9260
Rated Current ¹	I _r	A	2.1	1.7	1.3	0.99	0.79	0.63	0.49	0.39
Rated Power ¹	P _r	W	11	11	11	11	11	11	11	11
No Load Speed	ω _{nl}	rpm	9830	9960	9930	9900	9940	10000	10000	9970
No Load Current	I _{nl}	A	0.45	0.36	0.29	0.23	0.18	0.15	0.12	0.090
Rated Voltage V2	V _r	V	6.00	7.58	9.55	12.0	15.2	19.1	24.0	30.3
Rated Torque ¹ •	T _r	Nm	0.016	0.016	0.016	0.016	0.016	0.016	0.016	0.016
		oz-in	2.3	2.3	2.3	2.3	2.2	2.2	2.2	2.2
Rated Speed ¹	ω _r	rpm	3630	3940	4070	4140	4270	4330	4300	4320
Rated Current ¹	I _r	A	2.5	2.0	1.6	1.2	0.98	0.79	0.62	0.49
Rated Power ¹	P _r	W	6.3	6.7	6.8	6.9	7.1	7.1	7.1	7.1
No Load Speed	ω _{nl}	rpm	6090	6210	6160	6140	6220	6280	6220	6220
No Load Current	I _{nl}	A	0.39	0.31	0.25	0.20	0.16	0.13	0.098	0.077
Motor Constant	K _M	Nm/√W	0.0099	0.010	0.010	0.010	0.011	0.010	0.011	0.011
		oz-in/√W	1.4	1.4	1.5	1.5	1.5	1.5	1.5	1.5
Torque Constant	K _T	Nm/A	0.00876	0.0109	0.0138	0.0175	0.0219	0.0272	0.0346	0.0436
		oz-in/A	1.24	1.54	1.96	2.47	3.10	3.85	4.90	6.18
Voltage Constant	K _E	V/(rad/s)	0.00876	0.0109	0.0138	0.0175	0.0219	0.0272	0.0346	0.0436
		V/krpm	0.917	1.14	1.45	1.83	2.29	2.85	3.62	4.57
Terminal Resistance	R _{mt}	Ω	0.790	1.17	1.80	2.79	4.33	6.75	10.7	17.0
Inductance	L	mH	0.37	0.58	0.94	1.5	2.3	3.7	5.9	9.4
Peak Current	I _{pk}	A	12	10	8.4	6.8	5.5	4.5	3.6	2.8
Electrical Time Constant	τ _e	ms	0.47	0.50	0.52	0.54	0.54	0.54	0.55	0.55
Mechanical Time Constant	τ _m	ms	17	16	15	15	15	15	15	15

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



DC030C Series

The DC030C Series Brush Commutated DC Motor is a 30 mm diameter unit offered in 3 lengths with continuous output torques of 0.0177 to 0.0586 Nm.



Shown with optional assemblies.

■ Benefits

- High torque
- Speeds up to 10,000 RPM possible
- DC bus voltage up to 48 VDC
- Eight standard windings, special windings available
- 2 pole stator with magnetic cogging reduction
- Bonded rare earth magnets
- 7 slot armature
- Long life graphite brushes, RFI suppression available

■ Optional Assemblies

- Encoder: E30C/D
- Gearboxes: G30A, G35A, G51A
- Brake: B30A
- Programmable Drive: PBL4850E**

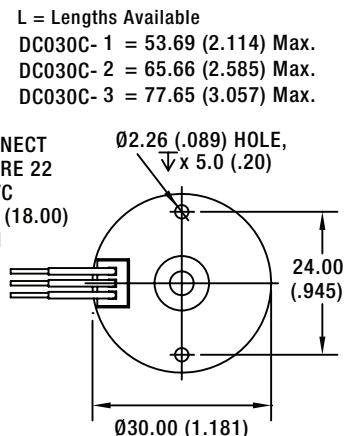
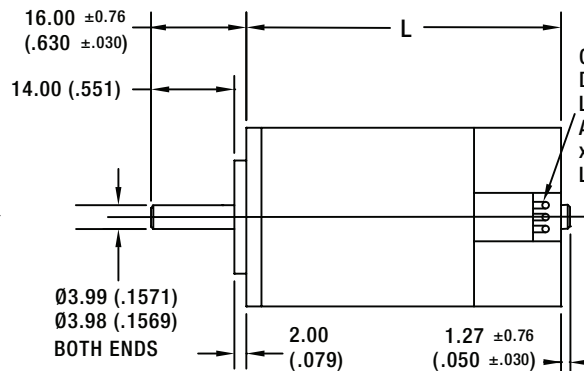
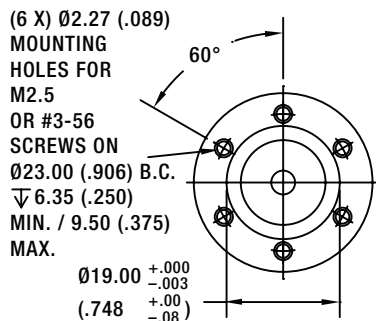
■ Motor Characteristics

Motor Data	Units	Series		
		DC030C-1	DC030C-2	DC030C-3
Max DC Terminal Voltage V_T	V	48		
Max Speed (Mechanical) ω_{MAX}	rpm	10000		
Continuous Stall Torque ¹ T_{CS}	Nm	0.0177	0.0410	0.0586
	oz-in	2.7	5.8	8.5
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.068	0.22	0.36
	oz-in	9.6	31	51
Coulomb Friction Torque T_f	Nm	0.0035	0.0042	0.0049
	oz-in	0.50	0.60	0.70
Viscous Damping Factor D	Nm/(rad/s)	3.0E-06	3.4E-06	3.7E-06
	oz-in/krpm	0.045	0.050	0.055
Thermal Time Constant τ_{th}	min	10	13	16
Thermal Resistance R_{th}	°C/W	17	14	11
Max. Winding Temperature θ_{MAX}	°C	155	155	155
Rotor Inertia J_r	kg-m ²	2.0E-06	3.7E-06	5.8E-06
	oz-in-s ²	2.9E-04	5.2E-04	8.2E-04
Motor Weight W_m	g	130	170	210
	oz	4.7	6.1	7.6

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

Dimensional Drawings: DC030C-1 • DC030C-2 • DC030C-3

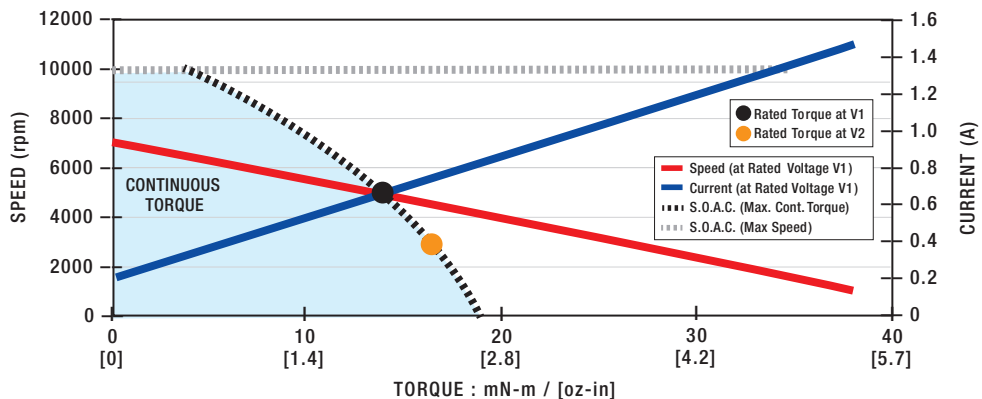
Dimensions = mm (inches)



■ Performance Data & Graph: DC030C-1

Motor Data		Units								
Rated Voltage V1	V _R	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _R	Nm	0.014	0.014	0.014	0.014	0.014	0.014	0.014	0.014
		oz-in	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Rated Speed ¹	ω _R	rpm	4850	4840	4830	4780	4830	4840	4790	4760
Rated Current ¹	I _R	A	1.7	1.3	1.0	0.83	0.66	0.52	0.41	0.33
Rated Power ¹	P _R	W	7.1	7.0	7.0	7.0	7.0	7.0	7.0	7.0
No Load Speed	ω _{nl}	rpm	6820	6720	6750	6740	6740	6770	6730	6720
No Load Current	I _{nl}	A	0.46	0.36	0.29	0.23	0.18	0.15	0.12	0.090
Rated Voltage V2	V _R	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _R	Nm	0.016	0.016	0.016	0.016	0.016	0.016	0.016	0.016
		oz-in	2.3	2.3	2.3	2.3	2.3	2.3	2.3	2.3
Rated Speed ¹	ω _R	rpm	2890	2920	2850	2870	2910	2880	2850	2850
Rated Current ¹	I _R	A	1.8	1.4	1.1	0.91	0.72	0.57	0.45	0.36
Rated Power ¹	P _R	W	4.9	5.0	4.9	4.9	5.0	4.9	4.9	4.9
No Load Speed	ω _{nl}	rpm	5350	5280	5270	5300	5300	5290	5270	5280
No Load Current	I _{nl}	A	0.43	0.33	0.27	0.21	0.17	0.14	0.11	0.083
Motor Constant	K _M	Nm/√W	0.010	0.010	0.010	0.010	0.010	0.010	0.010	0.010
		oz-in/√W	1.4	1.5	1.4	1.4	1.5	1.4	1.4	1.4
Torque Constant	K _T	Nm/A	0.0124	0.0159	0.0200	0.0251	0.0316	0.0397	0.0503	0.0633
		oz-in/A	1.76	2.24	2.83	3.56	4.48	5.63	7.13	8.97
Voltage Constant	K _E	V/(rad/s)	0.0124	0.0159	0.0200	0.0251	0.0316	0.0397	0.0503	0.0633
		V/krpm	1.30	1.66	2.09	2.63	3.31	4.16	5.27	6.63
Terminal Resistance	R _{mt}	Ω	1.50	2.37	3.81	6.08	9.50	15.1	24.3	38.6
Inductance	L	mH	1.1	1.8	2.9	4.6	7.3	12	18	29
Peak Current	I _{pk}	A	6.4	5.1	4.0	3.1	2.5	2.0	1.6	1.2
Electrical Time Constant	τ _e	ms	0.76	0.77	0.77	0.76	0.77	0.77	0.76	0.76
Mechanical Time Constant	τ _m	ms	20	19	20	20	19	20	20	20

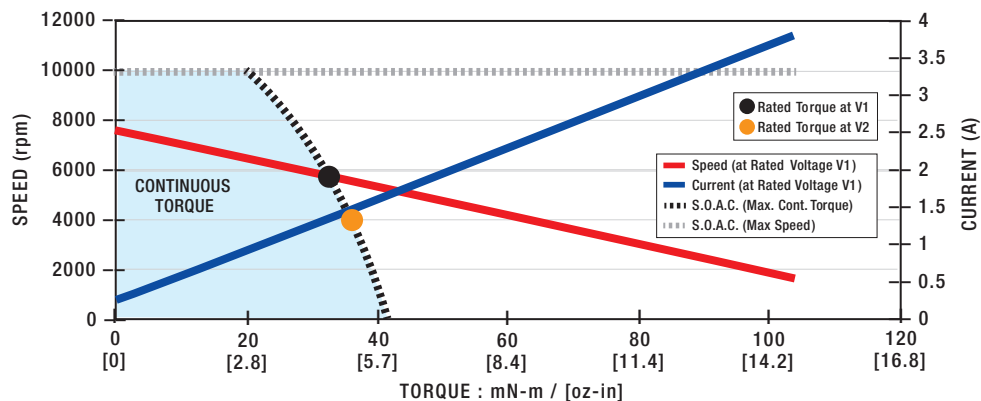
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC030C-2

Motor Data		Units								
Rated Voltage V1	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.037	0.036	0.035	0.033	0.032	0.031	0.031	0.031
		oz-in	5.3	5.2	5.0	4.7	4.5	4.4	4.4	4.4
Rated Speed ¹	ω_r	rpm	3410	4180	4960	5550	5750	6040	6010	6040
Rated Current ¹	I_r	A	3.8	2.9	2.3	1.7	1.3	1.1	0.83	0.66
Rated Power ¹	P_r	W	13	16	18	19	19	20	20	20
No Load Speed	ω_{nl}	rpm	6950	6940	7130	7110	7060	7180	7150	7150
No Load Current	I_{nl}	A	0.54	0.43	0.35	0.28	0.22	0.18	0.14	0.11
Rated Voltage V2	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.039	0.039	0.038	0.036	0.036	0.035	0.035	0.035
		oz-in	5.6	5.5	5.3	5.1	5.0	5.0	5.0	4.9
Rated Speed ¹	ω_r	rpm	1620	2410	3090	3740	3950	4160	4150	4210
Rated Current ¹	I_r	A	3.9	3.0	2.4	1.9	1.4	1.1	0.91	0.72
Rated Power ¹	P_r	W	6.7	9.7	12	14	15	15	15	15
No Load Speed	ω_{nl}	rpm	5460	5480	5590	5630	5590	5660	5650	5660
No Load Current	I_{nl}	A	0.50	0.40	0.32	0.26	0.20	0.16	0.13	0.11
Motor Constant	K_M	Nm/ \sqrt{W}	0.013	0.014	0.015	0.016	0.017	0.018	0.018	0.018
		oz-in/ \sqrt{W}	1.8	2.0	2.1	2.3	2.4	2.5	2.5	2.5
Torque Constant	K_T	Nm/A	0.0124	0.0158	0.0196	0.0248	0.0315	0.0392	0.0496	0.0624
		oz-in/A	1.76	2.23	2.77	3.52	4.46	5.54	7.02	8.83
Voltage Constant	K_E	V/(rad/s)	0.0124	0.0158	0.0196	0.0248	0.0315	0.0392	0.0496	0.0624
		V/krpm	1.30	1.65	2.05	2.60	3.30	4.10	5.19	6.53
Terminal Resistance	R_{mt}	Ω	0.960	1.29	1.71	2.27	3.33	4.90	7.83	12.2
Inductance	L	mH	0.49	0.79	1.2	2.0	3.2	5.0	8.0	13
Peak Current	I_{pk}	A	9.9	9.3	8.9	8.4	7.2	6.2	4.9	3.9
Electrical Time Constant	τ_e	ms	0.51	0.61	0.71	0.86	0.95	1.0	1.0	1.0
Mechanical Time Constant	τ_m	ms	23	19	16	14	12	12	12	12

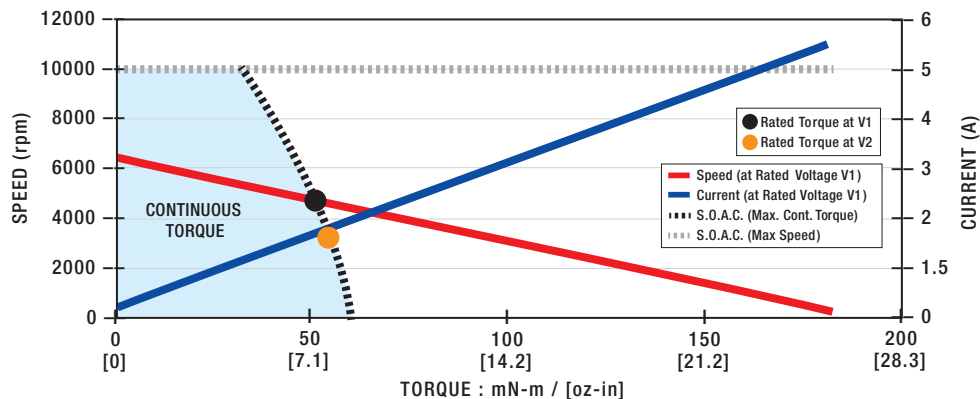
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC030C-3

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.056	0.054	0.052	0.050	0.051	0.050	0.048	0.048
		oz-in	7.9	7.7	7.3	7.1	7.2	7.0	6.8	6.7
Rated Speed ¹	ω _r	rpm	3320	4040	4620	4900	4770	4940	5140	5190
Rated Current ¹	I _r	A	4.7	3.6	2.7	2.1	1.7	1.3	1.0	0.80
Rated Power ¹	P _r	W	19	23	25	26	25	26	26	26
No Load Speed	ω _{nl}	rpm	6050	6060	6010	6070	6000	5980	6020	5980
No Load Current	I _{nl}	A	0.51	0.40	0.31	0.25	0.20	0.16	0.13	0.097
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.058	0.057	0.055	0.054	0.054	0.054	0.053	0.052
		oz-in	8.2	8.0	7.8	7.6	7.7	7.6	7.5	7.4
Rated Speed ¹	ω _r	rpm	1810	2550	3100	3410	3290	3440	3640	3710
Rated Current ¹	I _r	A	4.8	3.7	2.8	2.3	1.8	1.4	1.1	0.85
Rated Power ¹	P _r	W	11	15	18	19	19	19	20	20
No Load Speed	ω _{nl}	rpm	4770	4800	4720	4810	4760	4720	4760	4750
No Load Current	I _{nl}	A	0.47	0.38	0.29	0.24	0.19	0.15	0.12	0.090
Motor Constant	K _M	Nm/√W	0.017	0.019	0.022	0.023	0.023	0.024	0.025	0.025
		oz-in/√W	2.5	2.7	3.1	3.2	3.2	3.3	3.5	3.6
Torque Constant	K _T	Nm/A	0.0145	0.0183	0.0236	0.0294	0.0373	0.0474	0.0595	0.0752
		oz-in/A	2.06	2.60	3.34	4.17	5.29	6.71	8.42	10.7
Voltage Constant	K _E	V/(rad/s)	0.0145	0.0183	0.0236	0.0294	0.0373	0.0474	0.0595	0.0752
		V/krpm	1.52	1.92	2.47	3.08	3.91	4.96	6.23	7.88
Terminal Resistance	R _{mt}	Ω	0.700	0.900	1.17	1.66	2.74	4.04	5.87	8.98
Inductance	L	mH	0.42	0.64	1.0	1.6	2.6	4.1	6.6	10
Peak Current	I _{pk}	A	14	13	13	12	8.8	7.5	6.5	5.3
Electrical Time Constant	τ _e	ms	0.60	0.71	0.89	0.98	0.94	1.0	1.1	1.2
Mechanical Time Constant	τ _m	ms	19	16	12	11	11	10	9.6	9.2

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 *Recorded at maximum winding temperature at 25°C ambient and without heatsink.



DC040B Series



Shown with optional assemblies.

The DC040B Series Brush Commutated DC Motor is a 40 mm diameter unit offered in 6 lengths with continuous output torques of 0.017 to 0.081 Nm.

Benefits

- Speeds up to 8,500 RPM possible
- DC bus voltage up to 48 VDC
- Eight standard windings. Special windings, sintered bronze bearings, ball bearings; copper graphite brushes, RFI suppression available
- 2 pole stator with ceramic magnets
- 7 slot skewed armature cogging reduction

Optional Assemblies

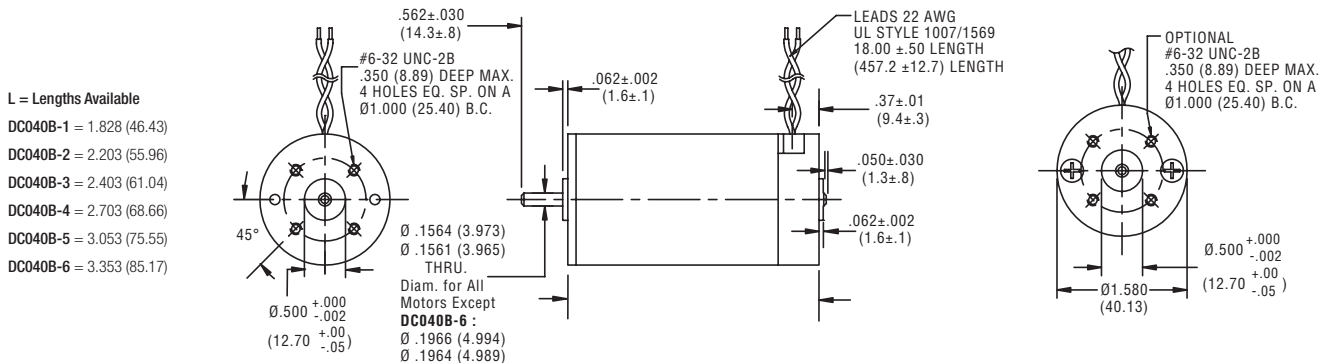
- Encoder: E21C/D, E30C/D
- Gearboxes: G30A, G40A, PLG42S, G51A
- Brakes: B30A, B49A
- Drives: BGE6060A, PBL4850E**

Motor Characteristics

Motor Data	Units	Series						
		DC040B-1	DC040B-2	DC040B-3	DC040B-4	DC040B-5	DC040B-6	
Max DC Terminal Voltage	V_T	48						
Max Speed (Mechanical)	ω_{MAX}	8000				7000		
Continuous Stall Torque ¹	T_{CS}	Nm	0.017	0.033	0.043	0.049	0.067	0.081
		oz-in	2.4	4.7	6.1	6.9	9.5	12
Peak Torque (Maximum) ¹	T_{pk}	Nm	0.086	0.20	0.26	0.32	0.40	0.50
		oz-in	12	28	37	45	56	71
Coulomb Friction Torque	T_f	Nm	0.0035	0.0042	0.0042	0.0046	0.0056	0.0056
		oz-in	0.50	0.60	0.60	0.65	0.80	0.80
Viscous Damping Factor	D	Nm/(rad/s)	1.8E-06	2.3E-06	2.6E-06	3.0E-06	3.5E-06	3.7E-06
		oz-in/krpm	0.028	0.034	0.039	0.045	0.053	0.055
Thermal Time Constant	τ_{th}	min	7.2	11	12	13	14	14
Thermal Resistance	R_{th}	°C/W	23	19	17	15	14	11
Max. Winding Temperature	Θ_{MAX}	°C	155	155	155	155	155	155
Rotor Inertia	J_r	kg-m ²	1.9E-06	3.2E-06	4.2E-06	5.6E-06	7.1E-06	8.5E-06
		oz-in-s ²	2.7E-04	4.6E-04	5.9E-04	7.9E-04	0.0010	0.0012
Motor Weight	W_m	g	200	250	290	340	390	440
		oz	7.0	8.9	10	12	14	16

¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

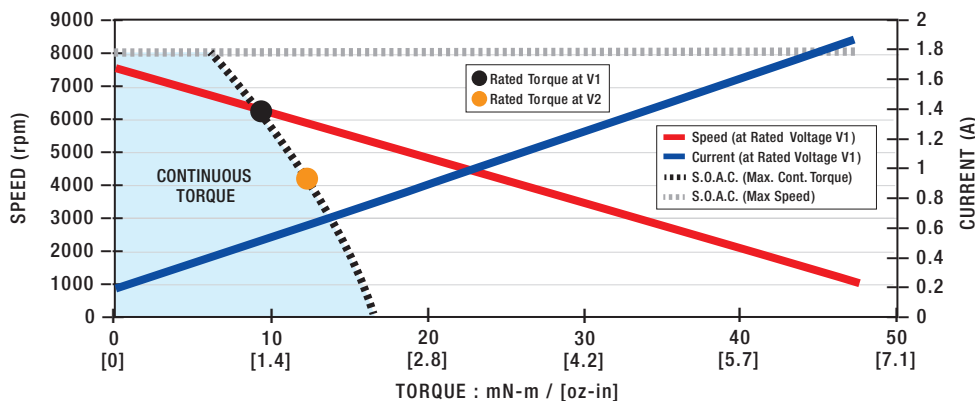
Dimensional Drawings: DC040B-1 • DC040B-2 • DC040B-3 • DC040B-4 • DC040B-5 • DC040B-6



■ Performance Data & Graph: DC040B-1

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.010	0.0099	0.0095	0.0094	0.0093	0.0092	0.0092	0.0092
		oz-in	1.5	1.4	1.3	1.3	1.3	1.3	1.3	1.3
Rated Speed ¹	ω _r	rpm	6020	6080	6230	6230	6260	6320	6300	6290
Rated Current ¹	I _r	A	1.4	1.1	0.83	0.65	0.51	0.40	0.32	0.25
Rated Power ¹	P _r	W	6.5	6.3	6.2	6.1	6.1	6.1	6.0	6.0
No Load Speed	ω _{nl}	rpm	6930	6850	6910	6880	6890	6910	6880	6880
No Load Current	I _{nl}	A	0.40	0.32	0.25	0.20	0.16	0.13	0.099	0.079
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.013	0.013	0.012	0.012	0.012	0.012	0.012	0.012
		oz-in	1.8	1.8	1.8	1.7	1.7	1.7	1.7	1.7
Rated Speed ¹	ω _r	rpm	3970	4060	4130	4200	4220	4230	4230	4250
Rated Current ¹	I _r	A	1.6	1.2	0.98	0.77	0.61	0.48	0.38	0.30
Rated Power ¹	P _r	W	5.4	5.4	5.4	5.4	5.4	5.4	5.4	5.4
No Load Speed	ω _{nl}	rpm	5440	5400	5400	5420	5430	5430	5410	5430
No Load Current	I _{nl}	A	0.38	0.30	0.24	0.19	0.15	0.12	0.093	0.074
Motor Constant	K _M	Nm/√W	0.011	0.011	0.011	0.011	0.011	0.011	0.011	0.011
		oz-in/√W	1.5	1.6	1.6	1.6	1.6	1.6	1.6	1.6
Torque Constant	K _T	Nm/A	0.0122	0.0156	0.0196	0.0247	0.0310	0.0391	0.0495	0.0622
		oz-in/A	1.73	2.20	2.77	3.50	4.39	5.53	7.00	8.80
Voltage Constant	K _E	V/(rad/s)	0.0122	0.0156	0.0196	0.0247	0.0310	0.0391	0.0495	0.0622
		V/krpm	1.28	1.63	2.05	2.59	3.25	4.09	5.18	6.51
Terminal Resistance	R _{mt}	Ω	1.25	1.93	2.99	4.70	7.38	11.6	18.5	29.2
Inductance	L	mH	0.72	1.2	1.8	2.9	4.6	7.3	12	19
Peak Current	I _{pk}	A	7.6	6.2	5.1	4.1	3.3	2.6	2.1	1.6
Electrical Time Constant	τ _e	ms	0.58	0.60	0.61	0.63	0.63	0.63	0.63	0.63
Mechanical Time Constant	τ _m	ms	16	15	15	15	15	14	14	14

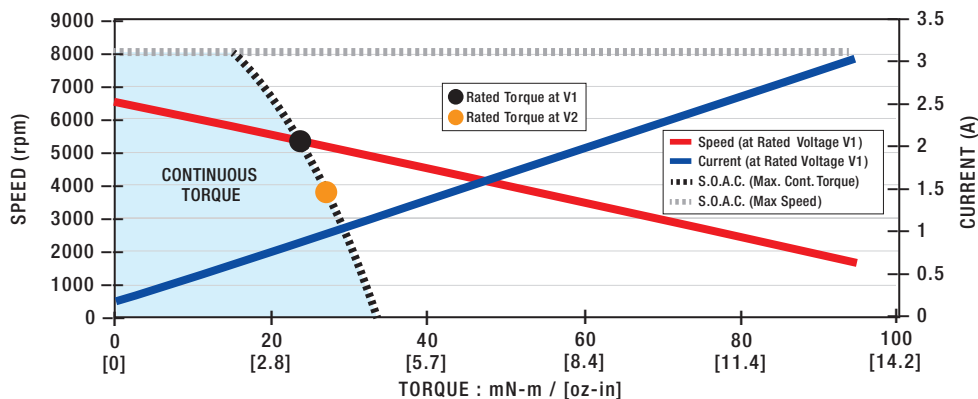
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC040B-2

Motor Data		Units								
Rated Voltage V1	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.026	0.025	0.024	0.024	0.024	0.023	0.023	0.023
		oz-in	3.6	3.5	3.4	3.4	3.3	3.3	3.3	3.3
Rated Speed ¹	ω_r	rpm	5000	5100	5300	5310	5350	5360	5390	5390
Rated Current ¹	I_r	A	2.4	1.8	1.4	1.1	0.89	0.70	0.55	0.44
Rated Power ¹	P_r	W	13	13	13	13	13	13	13	13
No Load Speed	ω_{nl}	rpm	5870	5810	5920	5870	5880	5860	5880	5880
No Load Current	I_{nl}	A	0.38	0.30	0.25	0.19	0.16	0.12	0.095	0.076
Rated Voltage V2	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.028	0.028	0.027	0.027	0.027	0.027	0.027	0.027
		oz-in	4.0	3.9	3.9	3.8	3.8	3.8	3.8	3.8
Rated Speed ¹	ω_r	rpm	3440	3570	3680	3750	3790	3780	3810	3830
Rated Current ¹	I_r	A	2.6	2.0	1.6	1.2	0.98	0.77	0.61	0.49
Rated Power ¹	P_r	W	10	10	11	11	11	11	11	11
No Load Speed	ω_{nl}	rpm	4630	4600	4650	4650	4660	4620	4640	4660
No Load Current	I_{nl}	A	0.36	0.29	0.23	0.18	0.15	0.12	0.090	0.072
Motor Constant	K_M	Nm/ \sqrt{W}	0.017	0.018	0.018	0.019	0.019	0.019	0.019	0.019
		oz-in/ \sqrt{W}	2.5	2.6	2.6	2.6	2.7	2.7	2.7	2.7
Torque Constant	K_T	Nm/A	0.0148	0.0188	0.0234	0.0297	0.0372	0.0472	0.0593	0.0746
		oz-in/A	2.10	2.66	3.31	4.21	5.27	6.68	8.40	10.6
Voltage Constant	K_E	V/(rad/s)	0.0148	0.0188	0.0234	0.0297	0.0372	0.0472	0.0593	0.0746
		V/krpm	1.55	1.97	2.45	3.11	3.90	4.94	6.21	7.81
Terminal Resistance	R_{mt}	Ω	0.720	1.08	1.63	2.53	3.94	6.21	9.78	15.4
Inductance	L	mH	0.52	0.84	1.3	2.1	3.3	5.3	8.3	13
Peak Current	I_{pk}	A	13	11	9.3	7.5	6.1	4.9	3.9	3.1
Electrical Time Constant	τ_e	ms	0.72	0.78	0.79	0.82	0.84	0.85	0.85	0.85
Mechanical Time Constant	τ_m	ms	11	9.9	9.7	9.3	9.2	9.1	9.0	9.0

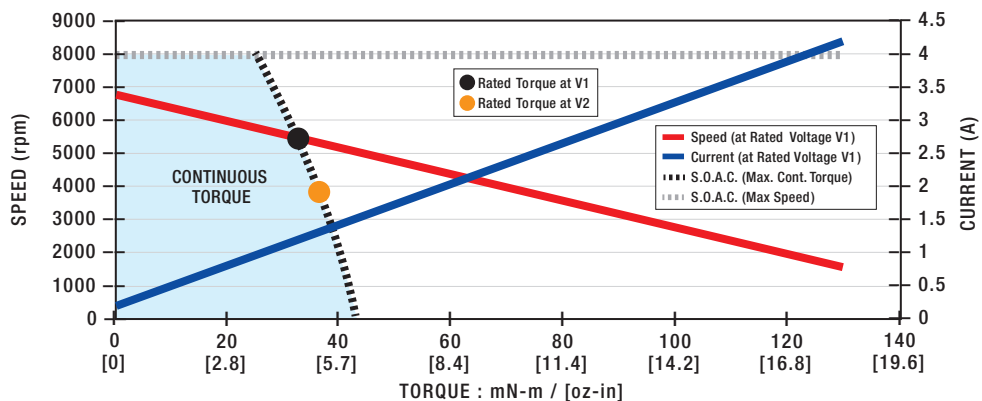
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC040B-3

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.035	0.034	0.034	0.033	0.033	0.033	0.032	0.032
		oz-in	5.0	4.9	4.8	4.7	4.7	4.6	4.6	4.6
Rated Speed ¹	ω _r	rpm	5030	5170	5280	5450	5430	5480	5490	5490
Rated Current ¹	I _r	A	3.2	2.5	1.9	1.5	1.2	0.95	0.75	0.59
Rated Power ¹	P _r	W	19	19	19	19	19	19	19	19
No Load Speed	ω _{nl}	rpm	6050	6020	6000	6090	6030	6050	6040	6030
No Load Current	I _{nl}	A	0.41	0.33	0.26	0.21	0.17	0.13	0.11	0.081
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.038	0.038	0.037	0.037	0.036	0.036	0.036	0.036
		oz-in	5.4	5.3	5.3	5.2	5.2	5.1	5.1	5.1
Rated Speed ¹	ω _r	rpm	3460	3620	3690	3870	3870	3890	3910	3930
Rated Current ¹	I _r	A	3.4	2.7	2.1	1.7	1.3	1.0	0.81	0.65
Rated Power ¹	P _r	W	14	14	14	15	15	15	15	15
No Load Speed	ω _{nl}	rpm	4780	4770	4720	4830	4780	4780	4770	4780
No Load Current	I _{nl}	A	0.39	0.31	0.24	0.20	0.16	0.13	0.096	0.077
Motor Constant	K _M	Nm/√W	0.019	0.020	0.021	0.021	0.021	0.021	0.021	0.021
		oz-in/√W	2.7	2.8	2.9	3.0	3.0	3.0	3.0	3.0
Torque Constant	K _T	Nm/A	0.0144	0.0182	0.0232	0.0287	0.0365	0.0459	0.0581	0.0731
		oz-in/A	2.04	2.58	3.29	4.07	5.17	6.50	8.22	10.3
Voltage Constant	K _E	V/(rad/s)	0.0144	0.0182	0.0232	0.0287	0.0365	0.0459	0.0581	0.0731
		V/krpm	1.51	1.91	2.43	3.01	3.82	4.81	6.08	7.65
Terminal Resistance	R _{mt}	Ω	0.560	0.830	1.26	1.89	2.96	4.62	7.30	11.5
Inductance	L	mH	0.39	0.63	1.0	1.6	2.5	4.0	6.4	10
Peak Current	I _{pk}	A	17	14	12	10	8.1	6.6	5.2	4.2
Electrical Time Constant	τ _e	ms	0.70	0.76	0.81	0.83	0.85	0.86	0.87	0.87
Mechanical Time Constant	τ _m	ms	11	10	9.7	9.5	9.3	9.1	9.0	9.0

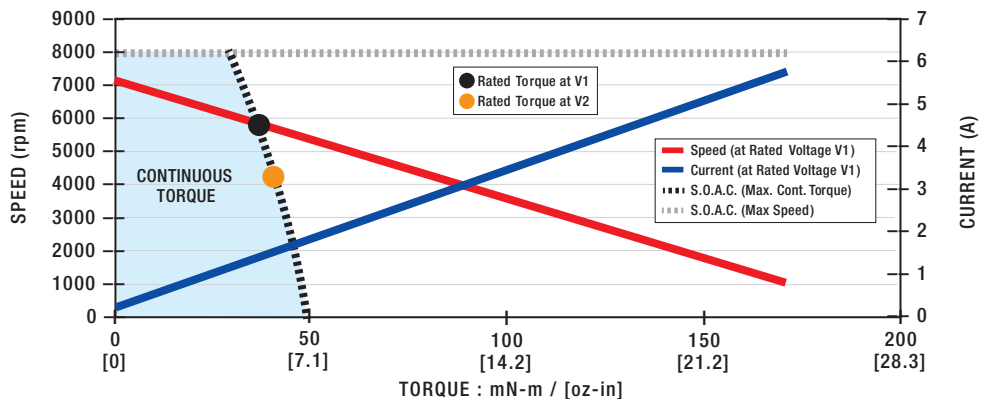
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC040B-4

Motor Data		Units								
Rated Voltage V1	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T_r	Nm	0.040	0.038	0.037	0.037	0.036	0.036	0.036	0.036
		oz-in	5.6	5.4	5.3	5.2	5.1	5.1	5.0	5.0
Rated Speed ¹	ω_r	rpm	5160	5480	5640	5660	5810	5810	5850	5820
Rated Current ¹	I_r	A	3.7	2.9	2.2	1.7	1.4	1.1	0.86	0.68
Rated Power ¹	P_r	W	22	22	22	22	22	22	22	22
No Load Speed	ω_{nl}	rpm	6180	6290	6290	6220	6320	6280	6310	6260
No Load Current	I_{nl}	A	0.47	0.38	0.30	0.24	0.19	0.15	0.12	0.094
Rated Voltage V2	V_r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T_r	Nm	0.043	0.042	0.042	0.041	0.041	0.040	0.040	0.040
		oz-in	6.1	6.0	5.9	5.8	5.7	5.7	5.7	5.7
Rated Speed ¹	ω_r	rpm	3560	3860	3960	4060	4170	4160	4200	4200
Rated Current ¹	I_r	A	3.9	3.1	2.4	1.9	1.5	1.2	0.94	0.74
Rated Power ¹	P_r	W	16	17	17	17	18	18	18	18
No Load Speed	ω_{nl}	rpm	4880	4990	4950	4940	5020	4960	4980	4970
No Load Current	I_{nl}	A	0.44	0.36	0.28	0.22	0.18	0.14	0.12	0.088
Motor Constant	K_M	Nm/√W	0.020	0.021	0.022	0.023	0.023	0.023	0.023	0.023
		oz-in/√W	2.9	3.0	3.1	3.2	3.2	3.3	3.3	3.3
Torque Constant	K_T	Nm/A	0.0141	0.0175	0.0222	0.0282	0.0349	0.0443	0.0557	0.0705
		oz-in/A	2.00	2.47	3.14	3.99	4.94	6.27	7.88	9.98
Voltage Constant	K_E	V/(rad/s)	0.0141	0.0175	0.0222	0.0282	0.0349	0.0443	0.0557	0.0705
		V/krpm	1.48	1.83	2.32	2.95	3.65	4.64	5.83	7.38
Terminal Resistance	R_{mt}	Ω	0.480	0.680	1.02	1.56	2.37	3.72	5.83	9.23
Inductance	L	mH	0.33	0.51	0.82	1.3	2.1	3.3	5.2	8.4
Peak Current	I_{pk}	A	20	18	15	12	10	8.1	6.6	5.2
Electrical Time Constant	τ_e	ms	0.69	0.75	0.80	0.85	0.86	0.89	0.89	0.90
Mechanical Time Constant	τ_m	ms	13	12	12	11	11	11	10	10

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.

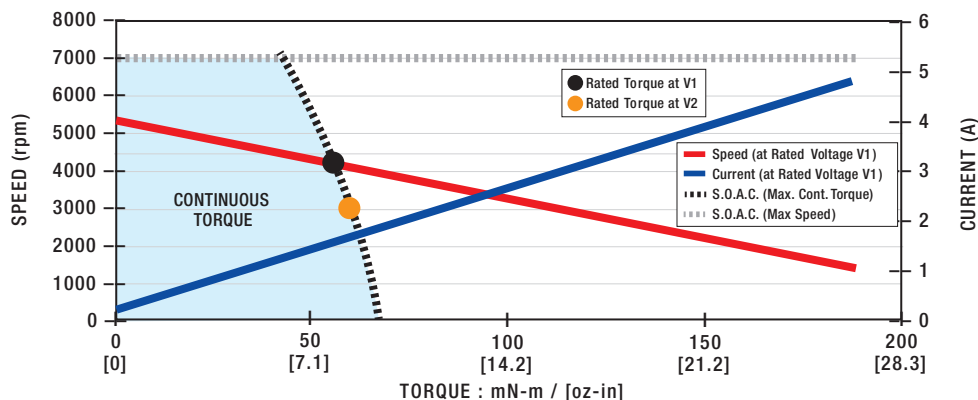


■ Performance Data & Graph: DC040B-5

Motor Data		Units								
Rated Voltage V1	V _r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	48.0
Rated Torque ¹ •	T _r	Nm	0.059	0.057	0.056	0.056	0.055	0.055	0.055	0.055
		oz-in	8.3	8.1	8.0	7.9	7.8	7.8	7.8	7.8
Rated Speed ¹	ω _r	rpm	3730	3980	4090	4110	4210	4230	4250	4230
Rated Current ¹	I _r	A	4.0	3.2	2.5	1.9	1.6	1.2	0.96	0.76
Rated Power ¹	P _r	W	23	24	24	24	24	24	24	24
No Load Speed	ω _{nl}	rpm	4720	4810	4800	4750	4820	4800	4810	4780
No Load Current	I _{nl}	A	0.40	0.33	0.26	0.21	0.17	0.13	0.11	0.081
Rated Voltage V2	V _r	V	7.58	9.55	12.0	15.2	19.1	24.0	30.3	38.2
Rated Torque ¹ •	T _r	Nm	0.062	0.061	0.060	0.060	0.059	0.059	0.059	0.059
		oz-in	8.8	8.6	8.5	8.5	8.4	8.4	8.4	8.3
Rated Speed ¹	ω _r	rpm	2530	2770	2840	2920	3000	3000	3030	3030
Rated Current ¹	I _r	A	4.2	3.3	2.6	2.0	1.6	1.3	1.0	0.81
Rated Power ¹	P _r	W	16	18	18	18	19	19	19	19
No Load Speed	ω _{nl}	rpm	3730	3810	3770	3770	3820	3790	3800	3790
No Load Current	I _{nl}	A	0.39	0.31	0.25	0.20	0.16	0.13	0.097	0.077
Motor Constant	K _M	Nm/√W	0.026	0.027	0.028	0.029	0.029	0.029	0.030	0.030
		oz-in/√W	3.7	3.9	4.0	4.1	4.1	4.2	4.2	4.2
Torque Constant	K _T	Nm/A	0.0185	0.0229	0.0291	0.0370	0.0458	0.0582	0.0731	0.0925
		oz-in/A	2.62	3.25	4.12	5.23	6.49	8.24	10.4	13.1
Voltage Constant	K _E	V/(rad/s)	0.0185	0.0229	0.0291	0.0370	0.0458	0.0582	0.0731	0.0925
		V/krpm	1.94	2.40	3.05	3.87	4.80	6.09	7.66	9.69
Terminal Resistance	R _{mt}	Ω	0.500	0.710	1.07	1.64	2.49	3.91	6.14	9.72
Inductance	L	mH	0.43	0.66	1.1	1.7	2.6	4.2	6.7	11
Peak Current	I _{pk}	A	19	17	14	12	9.6	7.7	6.2	4.9
Electrical Time Constant	τ _e	ms	0.86	0.93	0.99	1.0	1.1	1.1	1.1	1.1
Mechanical Time Constant	τ _m	ms	10	9.5	8.9	8.5	8.4	8.2	8.1	8.0

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n; for example, DC030C-1 (3.31 V/krpm).

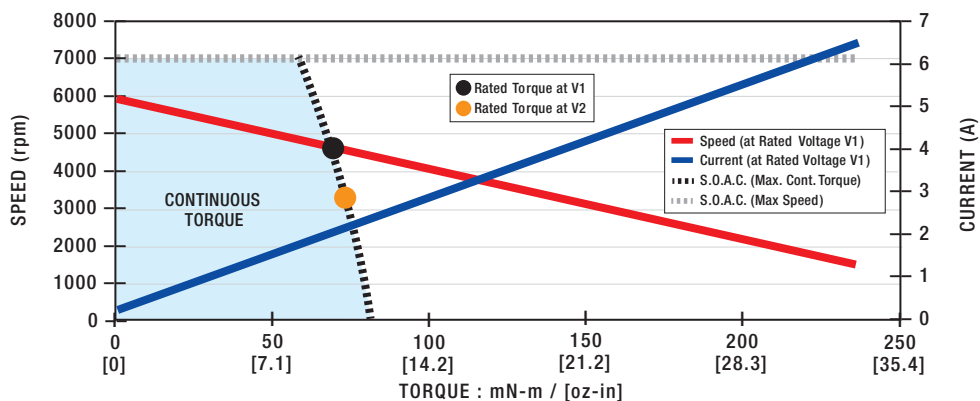
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC040B-6

Motor Data		Units									
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	48.0	
Rated Torque ¹ •	T_r	Nm	0.071	0.070	0.069	0.068	0.068	0.068	0.068	0.068	0.072
		oz-in	10	9.9	9.8	9.7	9.6	9.6	9.6	9.6	10
Rated Speed ¹	ω_r	rpm	4260	4540	4590	4590	4730	4730	4720	3390	
Rated Current ¹	I_r	A	4.2	3.3	2.6	2.0	1.6	1.3	1.0	0.85	
Rated Power ¹	P_r	W	32	33	33	33	34	34	33	26	
No Load Speed	ω_{nl}	rpm	5210	5330	5290	5220	5330	5310	5270	4170	
No Load Current	I_{nl}	A	0.37	0.30	0.24	0.19	0.15	0.12	0.092	0.069	
Rated Voltage V2	V_r	V	9.55	12.0	15.2	19.1	24.0	30.3	38.2	38.2	
Rated Torque ¹ •	T_r	Nm	0.075	0.074	0.073	0.073	0.072	0.072	0.072	0.072	0.075
		oz-in	11	10	10	10	10	10	10	10	11
Rated Speed ¹	ω_r	rpm	2970	3170	3270	3290	3380	3390	3410	2360	
Rated Current ¹	I_r	A	4.4	3.5	2.7	2.1	1.7	1.4	1.1	0.88	
Rated Power ¹	P_r	W	23	25	25	25	26	26	26	19	
No Load Speed	ω_{nl}	rpm	4130	4200	4190	4150	4210	4200	4190	3310	
No Load Current	I_{nl}	A	0.35	0.28	0.22	0.18	0.14	0.11	0.087	0.066	
Motor Constant	K_M	Nm/ \sqrt{W}	0.029	0.030	0.030	0.031	0.031	0.031	0.032	0.032	
		oz-in/ \sqrt{W}	4.0	4.2	4.3	4.4	4.4	4.5	4.5	4.5	
Torque Constant	K_T	Nm/A	0.0212	0.0263	0.0333	0.0424	0.0524	0.0664	0.0840	0.106	
		oz-in/A	3.00	3.72	4.72	6.00	7.42	9.40	11.9	15.0	
Voltage Constant	K_E	V/(rad/s)	0.0212	0.0263	0.0333	0.0424	0.0524	0.0664	0.0840	0.106	
		V/krpm	2.22	2.75	3.49	4.44	5.49	6.95	8.80	11.1	
Terminal Resistance	R_{mt}	Ω	0.550	0.790	1.20	1.85	2.82	4.45	6.98	11.1	
Inductance	L	mH	0.49	0.75	1.2	2.0	3.0	4.9	7.7	12	
Peak Current	I_{pk}	A	22	19	16	13	11	8.6	6.9	4.3	
Electrical Time Constant	τ_e	ms	0.89	0.95	1.0	1.1	1.1	1.1	1.1	1.1	
Mechanical Time Constant	τ_m	ms	10	9.7	9.2	8.7	8.7	8.6	8.4	8.4	

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



DC054B Series

The DC054B Series Brush Commutated DC Motor is a 54 mm diameter unit offered in 7 lengths with continuous output torques of 0.071 to 0.350 Nm.

■ Benefits

- Speeds up to 6,00 RPM possible
- DC bus voltage up to 80 VDC
- Eight standard windings. Special windings, sintered bronze bearings, ball bearings; copper graphite brushes, RFI suppression available
- 2 pole stator with ceramic magnets
- 7 slot skewed armature cogging reduction

■ Optional Assemblies

- Encoder: E30C/D, Q Type
- Gearboxes: G40A, PLG42S, G51A, PLG52
- Drives: BGE6060A, PBL4850E**



Shown with optional assemblies.

■ Motor Characteristics

Motor Data	Units	Series							
		DC054B-1	DC054B-2	DC054B-3	DC054B-4	DC054B-5	DC054B-6	DC054B-7	
Max DC Terminal Voltage V_T	V	48							
Max Speed (Mechanical) ω_{MAX}	rpm	6000				5000			
Continuous Stall Torque ¹ T_{CS}	Nm	0.071	0.099	0.150	0.180	0.220	0.260	0.350	
	oz-in	10	14	21	26	31	37	50	
Peak Torque (Maximum) ¹ T_{pk}	Nm	0.39	0.67	1.0	1.3	1.4	1.8	2.6	
	oz-in	55	95	140	180	200	260	370	
Coulomb Friction Torque T_f	Nm	0.0085	0.0085	0.011	0.011	0.014	0.014	0.016	
	oz-in	1.2	1.2	1.6	1.6	2.0	2.0	2.2	
Viscous Damping Factor D	Nm/(rad/s)	1.1E-05	1.1E-05	1.2E-05	1.2E-05	1.3E-05	1.3E-05	1.7E-05	
	oz-in/krpm	0.17	0.17	0.18	0.18	0.19	0.19	0.25	
Thermal Time Constant τ_{th}	min	22	24	26	29	29	34	32	
Thermal Resistance R_{th}	°C/W	9.9	9.0	8.1	7.7	7.3	6.8	5.0	
Max. Winding Temperature θ_{MAX}	°C	155	155	155	155	155	155	155	
Rotor Inertia J_r	kg-m ²	1.1E-05	1.6E-05	2.1E-05	2.6E-05	3.1E-05	3.7E-05	4.7E-05	
	oz-in-s ²	0.0016	0.0023	0.0030	0.0037	0.0044	0.0052	0.0067	
Motor Weight W_m	g	590	740	880	1000	1100	1300	1500	
	oz	21	26	31	35	40	45	55	

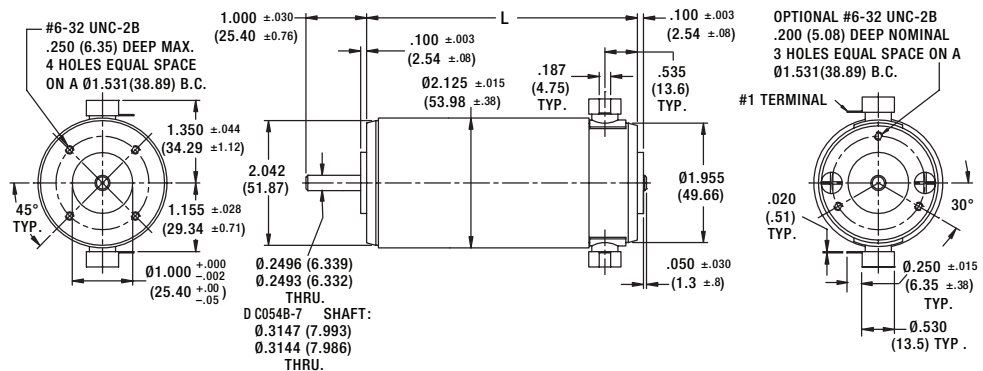
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink. **For PBL4850E to operate a brush motor, an encoder is required.

Dimensional Drawings: DC054B-1 • DC054B-2 • DC054B-3 • DC054B-4 • DC054B-5 • DC054B-6 • DC054B-7

Dimensions = Inches (mm)

L = Lengths Available

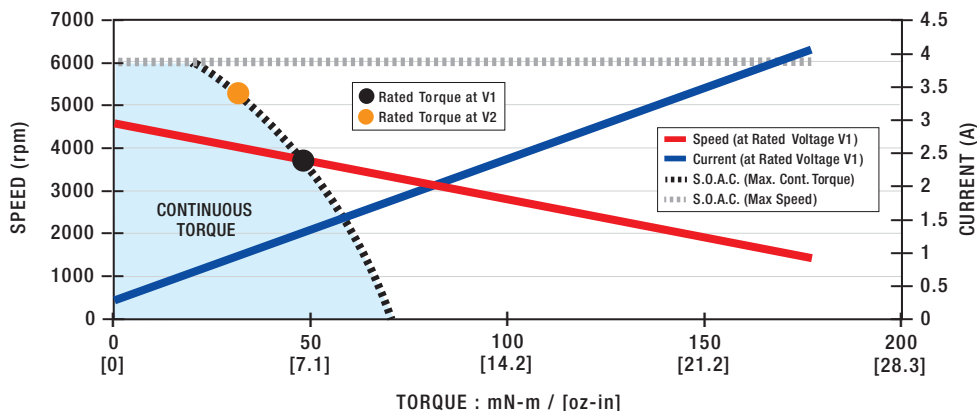
- DC054B-1 = 2.953 (75.01) Max.
- DC054B-2 = 3.203 (81.36) Max.
- DC054B-3 = 3.703 (94.06) Max.
- DC054B-4 = 4.078 (103.6) Max.
- DC054B-5 = 4.453 (113.1) Max.
- DC054B-6 = 4.953 (125.8) Max.
- DC054B-7 = 5.703 (144.9) Max.



Performance Data & Graph: DC054B-1

Motor Data		Units								
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.049	0.048	0.048	0.048	0.048	0.047	0.048	0.048
		oz-in	6.9	6.8	6.8	6.8	6.7	6.7	6.7	6.7
Rated Speed ¹	ω_r	rpm	3680	3780	3750	3740	3720	3770	3750	3720
Rated Current ¹	I_r	A	2.7	2.1	1.7	1.3	1.0	0.83	0.65	0.51
Rated Power ¹	P_r	W	19	19	19	19	19	19	19	19
No Load Speed	ω_{nl}	rpm	4140	4200	4170	4150	4120	4170	4150	4120
No Load Current	I_{nl}	A	0.52	0.42	0.33	0.26	0.21	0.17	0.13	0.11
Rated Voltage V2	V_r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T_r	Nm	0.033	0.031	0.031	0.031	0.031	0.031	0.031	0.031
		oz-in	4.7	4.4	4.4	4.4	4.4	4.3	4.3	4.3
Rated Speed ¹	ω_r	rpm	5250	5320	5280	5290	5250	5300	5300	5250
Rated Current ¹	I_r	A	2.1	1.6	1.3	0.99	0.77	0.62	0.49	0.39
Rated Power ¹	P_r	W	18	17	17	17	17	17	17	17
No Load Speed	ω_{nl}	rpm	5270	5300	5250	5260	5210	5260	5260	5210
No Load Current	I_{nl}	A	0.57	0.46	0.36	0.29	0.23	0.18	0.15	0.12
Motor Constant	K_M	Nm/ \sqrt{W}	0.031	0.031	0.031	0.031	0.032	0.032	0.032	0.032
		oz-in/ \sqrt{W}	4.4	4.4	4.4	4.5	4.5	4.5	4.5	4.5
Torque Constant	K_T	Nm/A	0.0263	0.0328	0.0416	0.0525	0.0668	0.0832	0.105	0.134
		oz-in/A	3.72	4.65	5.90	7.44	9.47	11.8	14.9	18.9
Voltage Constant	K_E	V/(rad/s)	0.0263	0.0328	0.0416	0.0525	0.0668	0.0832	0.105	0.134
		V/krpm	2.75	3.44	4.36	5.50	7.00	8.71	11.0	14.0
Terminal Resistance	R_{mt}	Ω	0.720	1.11	1.76	2.79	4.45	6.98	11.1	17.8
Inductance	L	mH	0.63	0.99	1.6	2.5	4.1	6.4	10	16
Peak Current	I_{pk}	A	17	14	11	8.6	6.8	5.5	4.3	3.4
Electrical Time Constant	τ_e	ms	0.88	0.89	0.90	0.91	0.92	0.91	0.92	0.92
Mechanical Time Constant	τ_m	ms	12	12	11	11	11	11	11	11

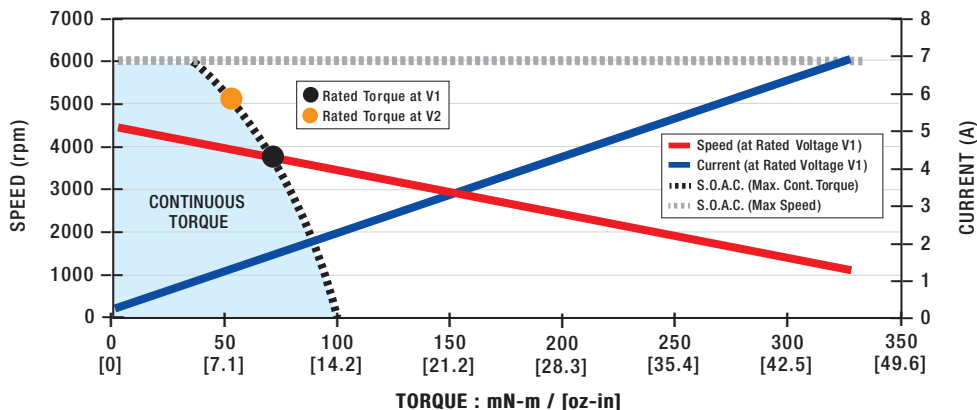
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC054B-2

Motor Data	Units									
Rated Voltage V1	V _R	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _R	Nm	0.072	0.071	0.070	0.070	0.070	0.070	0.070	0.070
		oz-in	10	10	9.9	9.9	9.9	9.9	9.9	9.9
Rated Speed ¹	ω _R	rpm	3720	3740	3790	3770	3780	3750	3790	3780
Rated Current ¹	I _R	A	3.5	2.7	2.2	1.7	1.4	1.1	0.86	0.67
Rated Power ¹	P _R	W	28	28	28	28	28	27	28	28
No Load Speed	ω _{nl}	rpm	4010	4010	4030	4010	4010	3970	4020	4000
No Load Current	I _{nl}	A	0.49	0.39	0.31	0.25	0.20	0.16	0.13	0.096
Rated Voltage V2	V _R	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _R	Nm	0.054	0.054	0.052	0.052	0.051	0.052	0.051	0.051
		oz-in	7.7	7.6	7.4	7.3	7.3	7.3	7.2	7.2
Rated Speed ¹	ω _R	rpm	5130	5100	5160	5160	5160	5100	5190	5160
Rated Current ¹	I _R	A	2.8	2.2	1.7	1.4	1.1	0.85	0.68	0.53
Rated Power ¹	P _R	W	29	29	28	28	28	28	28	27
No Load Speed	ω _{nl}	rpm	5090	5050	5080	5070	5070	5000	5090	5050
No Load Current	I _{nl}	A	0.54	0.42	0.34	0.27	0.21	0.17	0.14	0.11
Motor Constant	K _M	Nm/√W	0.041	0.041	0.042	0.042	0.042	0.042	0.042	0.042
		oz-in/√W	5.8	5.9	5.9	5.9	5.9	6.0	6.0	6.0
Torque Constant	K _T	Nm/A	0.0275	0.0349	0.0435	0.0551	0.0695	0.0884	0.110	0.139
		oz-in/A	3.89	4.94	6.17	7.80	9.84	12.5	15.6	19.7
Voltage Constant	K _E	V/(rad/s)	0.0275	0.0349	0.0435	0.0551	0.0695	0.0884	0.110	0.139
		V/krpm	2.88	3.65	4.56	5.77	7.28	9.26	11.5	14.6
Terminal Resistance	R _{mt}	Ω	0.450	0.710	1.09	1.73	2.74	4.37	6.85	10.9
Inductance	L	mH	0.63	1.0	1.6	2.5	4.1	6.6	10	16
Peak Current	I _{pk}	A	27	21	18	14	11	8.7	7.0	5.6
Electrical Time Constant	τ _e	ms	1.4	1.4	1.4	1.5	1.5	1.5	1.5	1.5
Mechanical Time Constant	τ _m	ms	9.7	9.5	9.3	9.3	9.2	9.1	9.2	9.1

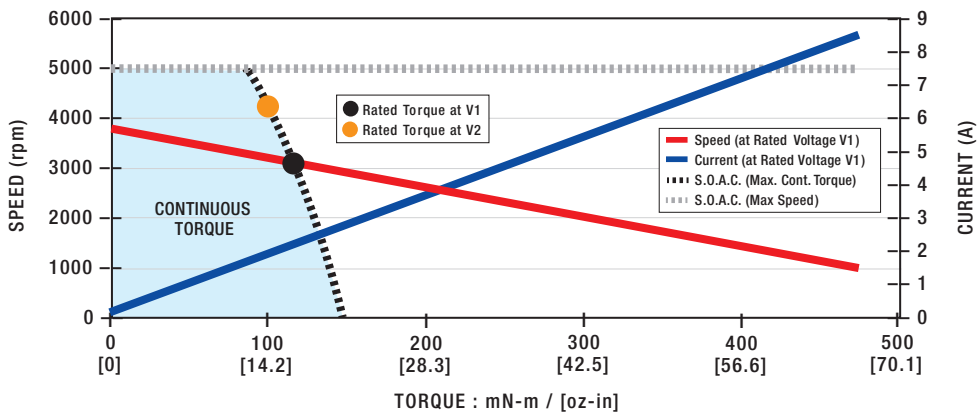
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: DC054B-3

Motor Data		Units								
Rated Voltage V1	V_r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T_r	Nm	0.12	0.12	0.12	0.12	0.12	0.12	0.12	0.12
		oz-in	17	17	17	17	17	16	17	17
Rated Speed ¹	ω_r	rpm	3050	3100	3090	3120	3120	3110	3090	3140
Rated Current ¹	I_r	A	4.7	3.7	2.9	2.3	1.8	1.4	1.1	0.91
Rated Power ¹	P_r	W	38	38	38	38	38	38	38	38
No Load Speed	ω_{nl}	rpm	3390	3390	3370	3390	3380	3360	3340	3390
No Load Current	I_{nl}	A	0.48	0.38	0.30	0.24	0.19	0.15	0.12	0.095
Rated Voltage V2	V_r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T_r	Nm	0.10	0.10	0.10	0.10	0.10	0.10	0.10	0.10
		oz-in	15	15	14	14	14	14	14	14
Rated Speed ¹	ω_r	rpm	4180	4190	4170	4240	4230	4190	4190	4240
Rated Current ¹	I_r	A	4.2	3.3	2.6	2.0	1.6	1.3	1.0	0.80
Rated Power ¹	P_r	W	46	45	45	45	44	44	44	44
No Load Speed	ω_{nl}	rpm	4300	4270	4240	4280	4270	4230	4220	4280
No Load Current	I_{nl}	A	0.52	0.41	0.32	0.26	0.21	0.16	0.13	0.11
Motor Constant	K_M	Nm/ \sqrt{W}	0.054	0.055	0.055	0.056	0.056	0.057	0.056	0.056
		oz-in/ \sqrt{W}	7.6	7.8	7.9	7.9	7.9	8.0	8.0	7.9
Torque Constant	K_T	Nm/A	0.0327	0.0413	0.0523	0.0654	0.0828	0.105	0.133	0.165
		oz-in/A	4.62	5.86	7.41	9.26	11.7	14.9	18.8	23.4
Voltage Constant	K_E	V/(rad/s)	0.0327	0.0413	0.0523	0.0654	0.0828	0.105	0.133	0.165
		V/krpm	3.42	4.33	5.48	6.85	8.67	11.0	13.9	17.3
Terminal Resistance	R_{mt}	Ω	0.370	0.570	0.890	1.38	2.19	3.46	5.53	8.68
Inductance	L	mH	0.56	0.91	1.5	2.3	3.6	5.8	9.3	15
Peak Current	I_{pk}	A	32	27	21	17	14	11	8.7	7.0
Electrical Time Constant	τ_e	ms	1.5	1.6	1.6	1.6	1.7	1.7	1.7	1.7
Mechanical Time Constant	τ_m	ms	7.3	7.1	6.9	6.8	6.8	6.6	6.6	6.7

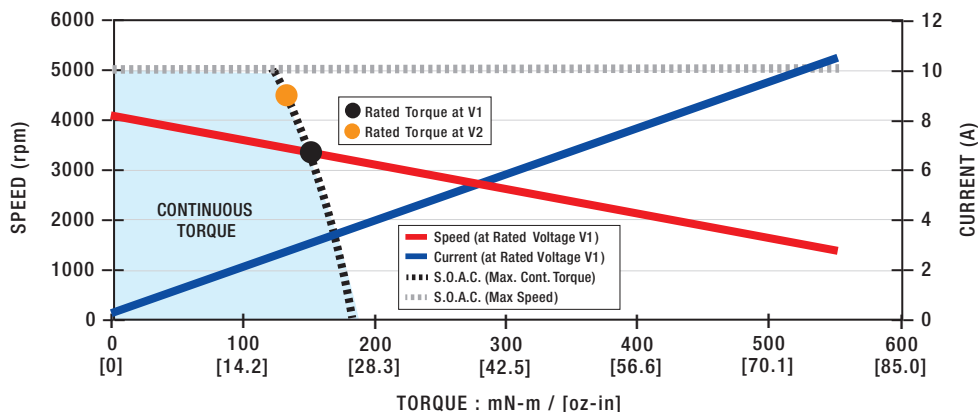
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC054B-4

Motor Data		Units								
Rated Voltage V1	V _R	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _R	Nm	0.15	0.15	0.15	0.15	0.15	0.15	0.15	0.15
		oz-in	22	22	21	21	21	21	21	21
Rated Speed ¹	ω _R	rpm	3280	3340	3350	3350	3400	3380	3380	3350
Rated Current ¹	I _R	A	6.3	5.0	3.9	3.1	2.5	1.9	1.5	1.2
Rated Power ¹	P _R	W	53	53	53	53	53	53	53	53
No Load Speed	ω _{NL}	rpm	3630	3670	3650	3630	3660	3630	3640	3600
No Load Current	I _{NL}	A	0.53	0.42	0.33	0.26	0.21	0.17	0.14	0.11
Rated Voltage V2	V _R	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _R	Nm	0.14	0.14	0.14	0.13	0.13	0.13	0.13	0.13
		oz-in	19	19	19	19	19	19	19	19
Rated Speed ¹	ω _R	rpm	4470	4500	4500	4520	4570	4520	4550	4510
Rated Current ¹	I _R	A	5.7	4.6	3.6	2.8	2.2	1.7	1.4	1.1
Rated Power ¹	P _R	W	64	64	64	63	63	63	63	62
No Load Speed	ω _{NL}	rpm	4610	4620	4590	4590	4620	4570	4600	4550
No Load Current	I _{NL}	A	0.57	0.45	0.36	0.28	0.23	0.18	0.15	0.11
Motor Constant	K _M	Nm/√W	0.059	0.059	0.060	0.061	0.061	0.062	0.061	0.062
		oz-in/√W	8.3	8.4	8.5	8.6	8.6	8.7	8.7	8.7
Torque Constant	K _T	Nm/A	0.0306	0.0383	0.0484	0.0612	0.0766	0.0974	0.122	0.156
		oz-in/A	4.33	5.42	6.86	8.67	10.8	13.8	17.3	22.0
Voltage Constant	K _E	V/(rad/s)	0.0306	0.0383	0.0484	0.0612	0.0766	0.0974	0.122	0.156
		V/krpm	3.20	4.01	5.07	6.41	8.02	10.2	12.8	16.3
Terminal Resistance	R _{mt}	Ω	0.270	0.420	0.650	1.01	1.57	2.50	3.96	6.33
Inductance	L	mH	0.40	0.62	1.0	1.6	2.5	4.0	6.4	10
Peak Current	I _{pk}	A	44	36	29	24	19	15	12	9.6
Electrical Time Constant	τ _e	ms	1.5	1.5	1.5	1.6	1.6	1.6	1.6	1.6
Mechanical Time Constant	τ _m	ms	7.5	7.5	7.2	7.0	7.0	6.9	6.9	6.8

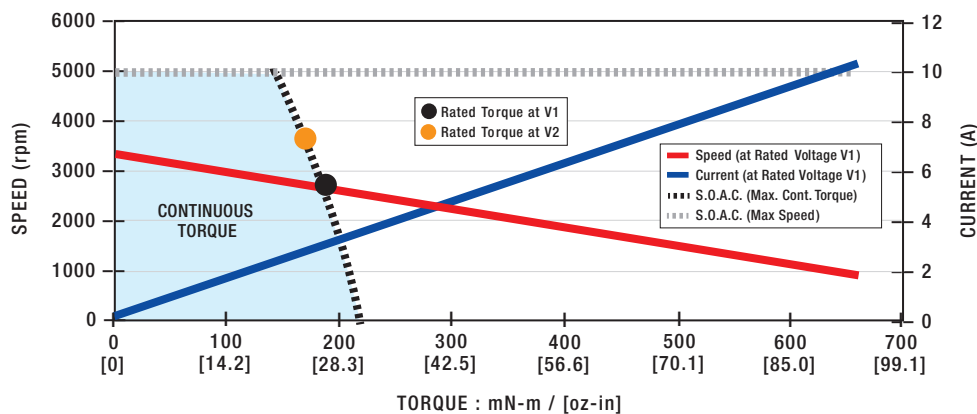
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: DC054B-5

Motor Data		Units								
Rated Voltage V1	V _r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _r	Nm	0.19	0.19	0.19	0.19	0.19	0.19	0.19	0.19
		oz-in	27	27	26	26	26	26	26	26
Rated Speed ¹	ω _r	rpm	2620	2700	2690	2690	2730	2720	2710	2700
Rated Current ¹	I _r	A	6.4	5.0	4.0	3.1	2.5	2.0	1.6	1.2
Rated Power ¹	P _r	W	52	53	53	53	53	53	53	52
No Load Speed	ω _{nl}	rpm	2990	3040	3010	3000	3020	3010	3000	2980
No Load Current	I _{nl}	A	0.49	0.40	0.31	0.25	0.20	0.16	0.13	0.097
Rated Voltage V2	V _r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _r	Nm	0.17	0.17	0.17	0.17	0.17	0.17	0.17	0.17
		oz-in	25	24	24	24	24	24	24	24
Rated Speed ¹	ω _r	rpm	3590	3650	3630	3650	3690	3660	3670	3640
Rated Current ¹	I _r	A	5.9	4.7	3.7	2.9	2.3	1.8	1.4	1.1
Rated Power ¹	P _r	W	66	66	65	65	65	65	65	65
No Load Speed	ω _{nl}	rpm	3800	3820	3790	3790	3820	3790	3800	3770
No Load Current	I _{nl}	A	0.52	0.42	0.33	0.26	0.21	0.17	0.13	0.11
Motor Constant	K _M	Nm/√W	0.068	0.069	0.070	0.070	0.070	0.071	0.071	0.071
		oz-in/√W	9.6	9.8	9.9	10	10	10	10	10
Torque Constant	K _T	Nm/A	0.0371	0.0463	0.0587	0.0741	0.0927	0.117	0.148	0.188
		oz-in/A	5.25	6.56	8.32	10.5	13.1	16.6	21.0	26.6
Voltage Constant	K _E	V/(rad/s)	0.0371	0.0463	0.0587	0.0741	0.0927	0.117	0.148	0.188
		V/krpm	3.88	4.85	6.15	7.76	9.71	12.3	15.5	19.7
Terminal Resistance	R _{mt}	Ω	0.300	0.450	0.710	1.11	1.73	2.75	4.36	6.97
Inductance	L	mH	0.45	0.71	1.1	1.8	2.8	4.5	7.2	12
Peak Current	I _{pk}	A	40	34	27	22	18	14	11	8.7
Electrical Time Constant	τ _e	ms	1.5	1.6	1.6	1.6	1.6	1.7	1.7	1.7
Mechanical Time Constant	τ _m	ms	6.8	6.5	6.4	6.3	6.3	6.2	6.2	6.1

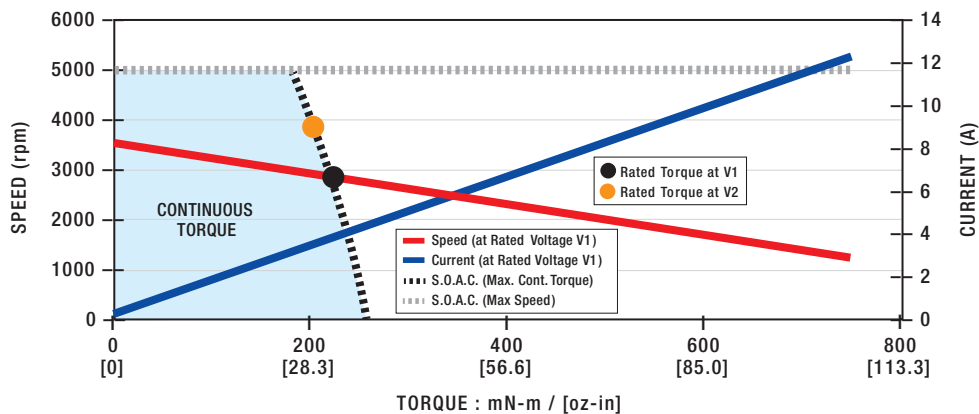
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



■ Performance Data & Graph: DC054B-6

Motor Data		Units								
Rated Voltage V1	V _r	V	12.0	15.2	19.1	24.0	30.3	38.2	48.0	60.6
Rated Torque ¹ •	T _r	Nm	0.23	0.22	0.22	0.22	0.22	0.22	0.22	0.22
		oz-in	32	32	32	31	31	31	31	31
Rated Speed ¹	ω _r	rpm	2940	2850	2880	2880	2890	2920	2900	2900
Rated Current ¹	I _r	A	8.3	6.2	4.9	3.9	3.0	2.4	1.9	1.5
Rated Power ¹	P _r	W	69	67	67	67	67	67	67	67
No Load Speed	ω _{nl}	rpm	3320	3160	3180	3150	3150	3170	3150	3150
No Load Current	I _{nl}	A	0.56	0.42	0.34	0.27	0.21	0.17	0.13	0.11
Rated Voltage V2	V _r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _r	Nm	0.21	0.21	0.21	0.20	0.20	0.20	0.20	0.20
		oz-in	30	29	29	29	29	29	29	29
Rated Speed ¹	ω _r	rpm	4000	3830	3870	3880	3880	3900	3890	3890
Rated Current ¹	I _r	A	7.8	5.8	4.6	3.6	2.8	2.3	1.8	1.4
Rated Power ¹	P _r	W	88	83	84	83	83	83	83	82
No Load Speed	ω _{nl}	rpm	4210	3980	4000	3990	3980	3990	3980	3970
No Load Current	I _{nl}	A	0.59	0.44	0.36	0.28	0.22	0.18	0.14	0.11
Motor Constant	K _M	Nm/√W	0.072	0.075	0.076	0.077	0.077	0.078	0.078	0.078
		oz-in/√W	10	11	11	11	11	11	11	11
Torque Constant	K _T	Nm/A	0.0335	0.0446	0.0557	0.0706	0.0892	0.112	0.141	0.179
		oz-in/A	4.75	6.32	7.88	9.99	12.6	15.8	20.0	25.3
Voltage Constant	K _E	V/(rad/s)	0.0335	0.0446	0.0557	0.0706	0.0892	0.112	0.141	0.179
		V/krpm	3.51	4.67	5.83	7.39	9.34	11.7	14.8	18.7
Terminal Resistance	R _{mt}	Ω	0.220	0.350	0.540	0.840	1.32	2.06	3.28	5.20
Inductance	L	mH	0.31	0.54	0.85	1.4	2.2	3.4	5.4	8.7
Peak Current	I _{pk}	A	55	43	35	29	23	19	15	12
Electrical Time Constant	τ _e	ms	1.4	1.5	1.6	1.6	1.6	1.6	1.7	1.7
Mechanical Time Constant	τ _m	ms	7.2	6.5	6.4	6.2	6.1	6.1	6.0	6.0

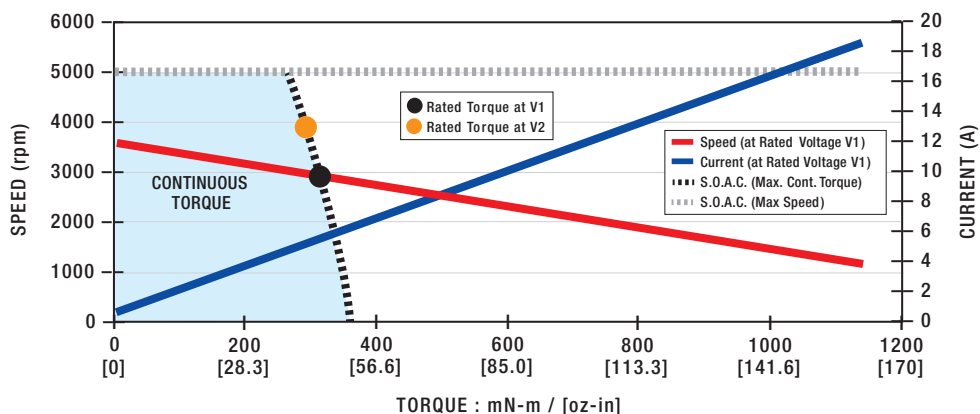
The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/h: for example, DC030C-1 (3.31 V/krpm).
 Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Performance Data & Graph: DC054B-7

Motor Data		Units								
Rated Voltage V1	V _r	V	15.2	19.1	24.0	30.3	38.2	48.0	60.6	76.4
Rated Torque ¹ •	T _r	Nm	0.31	0.31	0.31	0.31	0.31	0.31	0.31	0.31
		oz-in	44	44	44	44	44	44	43	43
Rated Speed ¹	ω _r	rpm	3000	2850	2900	2900	2920	2930	2930	2920
Rated Current ¹	I _r	A	8.9	6.7	5.3	4.2	3.3	2.6	2.1	1.6
Rated Power ¹	P _r	W	98	93	94	94	94	94	94	94
No Load Speed	ω _{nl}	rpm	3330	3140	3160	3140	3150	3160	3150	3140
No Load Current	I _{nl}	A	0.51	0.38	0.30	0.24	0.19	0.15	0.12	0.094
Rated Voltage V2	V _r	V	19.1	24.0	30.3	38.2	48.0	60.6	76.4	60.6
Rated Torque ¹ •	T _r	Nm	0.29	0.29	0.29	0.29	0.29	0.29	0.29	0.29
		oz-in	41	41	41	41	41	40	40	46
Rated Speed ¹	ω _r	rpm	4020	3820	3890	3880	3880	3920	3910	2150
Rated Current ¹	I _r	A	8.4	6.3	5.0	3.9	3.1	2.5	2.0	1.7
Rated Power ¹	P _r	W	120	120	120	120	120	120	120	72
No Load Speed	ω _{nl}	rpm	4190	3950	3990	3960	3960	3990	3980	2480
No Load Current	I _{nl}	A	0.55	0.40	0.33	0.26	0.20	0.16	0.13	0.089
Motor Constant	K _M	Nm/√W	0.086	0.091	0.092	0.093	0.094	0.093	0.094	0.094
		oz-in/√W	12	13	13	13	13	13	13	13
Torque Constant	K _T	Nm/A	0.0424	0.0565	0.0706	0.0897	0.113	0.141	0.179	0.226
		oz-in/A	6.00	8.01	9.99	12.7	16.0	20.0	25.3	32.0
Voltage Constant	K _E	V/(rad/s)	0.0424	0.0565	0.0706	0.0897	0.113	0.141	0.179	0.226
		V/krpm	4.44	5.92	7.39	9.39	11.8	14.8	18.7	23.7
Terminal Resistance	R _{mt}	Ω	0.240	0.390	0.590	0.930	1.46	2.29	3.64	5.78
Inductance	L	mH	0.31	0.56	0.87	1.4	2.2	3.5	5.6	8.9
Peak Current	I _{pk}	A	63	49	41	33	26	21	17	13
Electrical Time Constant	τ _e	ms	1.3	1.4	1.5	1.5	1.5	1.5	1.5	1.5
Mechanical Time Constant	τ _m	ms	6.3	5.8	5.6	5.5	5.4	5.4	5.4	5.4

The V1 and V2 ratings are intended to demonstrate the motor winding performance at different applied voltages. Use the voltage constant to specify the motor winding selection along with the motor p/n: for example, DC030C-1 (3.31 V/krpm).
¹Recorded at maximum winding temperature at 25°C ambient and without heatsink.



Cost-Effective Spur & Planetary Gearboxes

When added to our motors, Pittman gearboxes offer greater flexibility to the designer for low duty applications. Spur gearboxes provide an offset output shaft and are offered with sleeve or ball bearings, optional lubricants for extreme temperatures, and Delrin gears for reduced noise. Shortened housings are available for select ratios.

Our planetary gearbox series provides a centered output shaft for servo and continuous duty power transmission applications. Planetary gearboxes are offered with plastic or metal gears and can be customized with sleeve or ball bearings on the input and output shafts.

NOTE: Gearboxes are configured to be integrated directly with our motors. They are not designed to be sold separately..



Gear Data	Units	G35A	G51A	G30A	G40A	PLG42S	PLG52
Diameter	mm	34.8	50.8	30.0	40.0	42.0	52.0
	in	1.37	2.00	1.18	1.57	1.65	2.05
Min Load	Nm	0.706	1.2355	2.47	24.12	3.5	1.2
	oz-in	100	175	350	2000	496	170
Max Load	Nm	1.2355	3.53	8.83	24.12	14	24
	oz-in	175	500	1250	2000	1983	3399
Min Weight (Mass)	g	66.6	167.3	110.6	255.1	270	560
	oz	2.35	5.9	3.9	9	9.52	19.8
Max Weight (Mass)	g	92.1	231.9	1559	425.2	880	880
	oz	1.2	15	5.5	15	31	31
Min Length	mm	28.4	35.6	32.64	35.6	47.6	50
	in	1.12	1.4	1.285	1.4	1.87	1.97
Max Length	mm	29.6	38.8	50.17	58.4	71.2	80.5
	in	1.164	1.528	1.975	2.3	2.8	3.17
Stages Range		1-2	1-2	1-4	1-4	1-3	1-3
Reduction Range		6.3:1-1803.6:1	5.9:1-4732.5:1	4:1-1296:1	4:1-864:1	4:1-512:1	4.5:1-400:1

G35A Series



The G35A is an economical 35 mm offset spur gearbox suitable for lower torque applications. The wide range of sintered steel gears combinations especially complement brushed motors when speed reduction is required. Also available in high torque or wide faced gears for increased output loads.

Compatible Motors: DC026C, DC030B, DC030C, EC033A

■ Benefits

- Maximum Load torque up to 0.7 Nm in the standard model
- Load increased to 1.13 Nm in the high torque and up to 1.24 in wide face versions
- Standard bronze bearings

■ Optional Assembly

- Special lubrication for extreme conditions
- Ball bearings for high radial loads
- Delrin gears for noise reduction

■ Characteristics

Gear Data	Units	G35A 6.3:1	G35A 9.9:1	G35A 19.5:1	G35A 30.9:1	G35A 60.5:1	G35A 95.9:1
Maximum Load	Nm	0.706					
	oz-in	100					
Weight (Mass)	g	66.6	70.6	70.6	74.3	74.3	78.2
	oz	2.4	2.5	2.5	2.6	2.6	2.76
Length (L)	mm	24.6					
	inches	0.97					
Stages	–	1					
Ratio	–	6.3:1	9.9:1	19.5:1	30.9:1	60.5:1	95.9:1
Efficiency	–	0.81	0.73	0.73	0.66	0.66	0.57
Shaft Rotation	–	CW	CCW	CCW	CW	CW	CCW

Gear Data	Units	G35A 187.7:1	G35A 297.5:1	G35A 581.8:1	G35A 922.3:1	G35A 1803.6:1
Maximum Load	Nm	0.706				
	oz-in	100				
Weight (Mass)	g	78.2	88.2	88.2	92.1	92.1
	oz	2.76	3.11	3.11	3.25	3.25
Length (L)	mm	24.6	29.6	29.6	29.6	29.6
	inches	0.968	1.164	1.164	1.164	1.164
Stages	–	1	2	2	2	2
Ratio	–	187.7:1	297.5:1	581.8:1	922.3:1	1803.6:1
Efficiency	–	0.59	0.53	0.53	0.48	0.48
Shaft Rotation	–	CCW	CW	CW	CCW	CCW

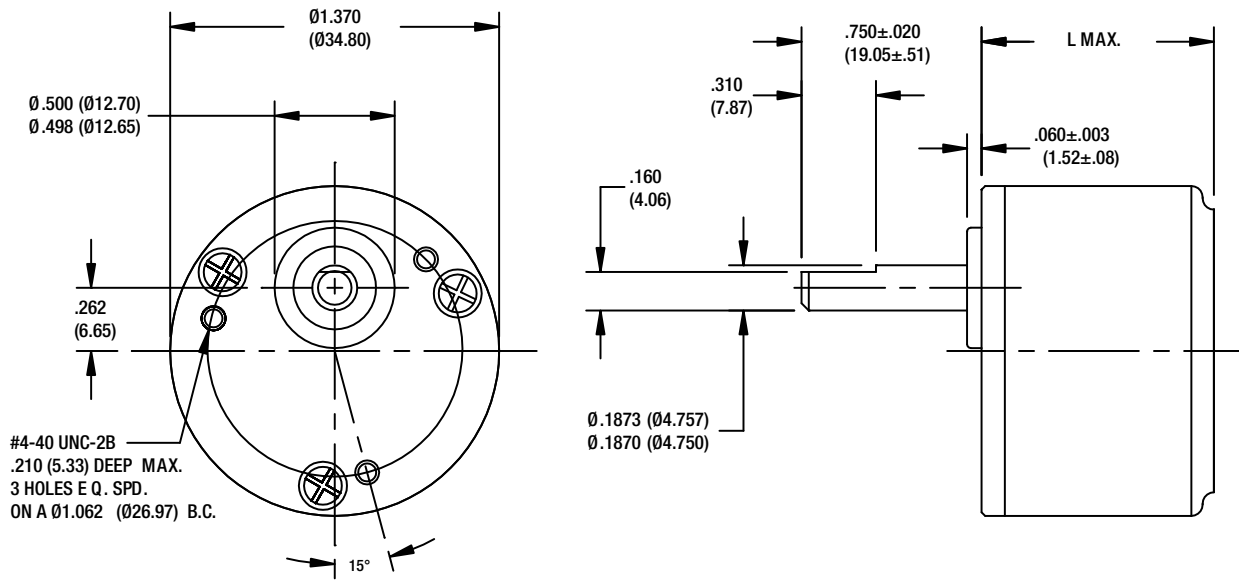
■ High Torque Characteristics

Gear Data	Units	G35A-HT 9.9:1	G35A-HT 19.5:1	G35A-HT 30.9:1	G35A-HT 60.5:1	G35A-HT 95.9:1
Maximum Load	Nm	1.130				
	oz-in	160				
Weight (Mass)	g	70.6	70.6	74.3	74.3	78.2
	oz	2.49	2.49	2.62	2.62	2.76
Length (L)	mm	24.6 mm / 0.968 inches				
Stages	–	1				
Ratio	–	9.9:1	19.5:1	30.9:1	60.5:1	95.9:1
Efficiency	–	0.73	0.73	0.66	0.66	0.59
Shaft Rotation	–	CCW	CCW	CW	CW	CCW
Gear Data	Units	G35A-HT 187.7:1	G35A-HT 297.5:1	G35A-HT 581.8:1	G35A-HT 922.3:1	G35A-HT 1803.6:1
Maximum Load	Nm	1.130				
	oz-in	160				
Weight (Mass)	g	78.2	88.2	88.2	92.1	92.1
	oz	2.76	3.11	3.11	3.25	3.25
Length (L)	mm	24.6	29.6	29.6	29.6	29.6
	inches	0.968	1.164	1.164	1.164	1.164
Stages	–	1	2	2	2	2
Ratio	–	187.7:1	297.5:1	581.8:1	922.3:1	1803.6:1
Efficiency	–	0.59	0.53	0.53	0.48	0.48
Shaft Rotation	–	CCW	CCW	CW	CW	CCW

■ Wide Face Characteristics

Gear Data	Units	G35A-WF 9.9:1	G35A-WF 19.5:1	G35A-WF 30.9:1	G35A-WF 60.5:1	G35A-WF 95.9:1
Maximum Load	Nm	1.236				
	oz-in	175				
Weight (Mass)	g	70.6	70.6	74.3	74.3	78.2
	oz	2.49	2.49	2.62	2.62	2.76
Length (L)	mm	24.6 mm / 0.968 inches				
Stages	–	1				
Ratio	–	9.9:1	19.5:1	30.9:1	60.5:1	95.9:1
Efficiency	–	0.73	0.73	0.66	0.66	0.59
Shaft Rotation	–	CCW	CCW	CW	CW	CCW
Gear Data	Units	G35A-WF 187.7:1	G35A-WF 297.5:1	G35A-WF 581.8:1	G35A-WF 922.3:1	G35A-WF 1803.6:1
Maximum Load	Nm	1.236				
	oz-in	175				
Weight (Mass)	g	78.2	88.2	88.2	92.1	92.1
	oz	2.76	3.11	3.11	3.25	3.25
Length (L)	mm	24.6	29.6	29.6	29.6	29.6
	inches	0.968	1.164	1.164	1.164	1.164
Stages	–	1	2	2	2	2
Ratio	–	187.7:1	297.5:1	581.8:1	922.3:1	1803.6:1
Efficiency	–	0.59	0.53	0.53	0.48	0.48
Shaft Rotation	–	CCW	CW	CW	CCW	CCW

Dimensional Drawings



■ Combined Length (L_{CM})

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC026C-1	74.4	79.2
DC026C-2	77.6	82.4
DC026C-3	83.9	88.7

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC030C-1	82.4	87.2
DC030C-2	94.4	99.2
DC030C-3	106.4	111.2

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC030B-1	75.6	80.4
DC030B-2	78.8	83.6
DC030B-3	85.2	90.0

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
EC033A-1	63.5	68.5
EC033A-2	75.4	80.4
EC033A-3	88.1	93.1

G51A Series

The G51A is an economical 51 mm offset spur gearbox suitable for lower torque applications. The wide range of sintered steel gears combinations especially complement brushed motors when speed reduction is required. Also available in high torque or wide faced gears for increased output loads.

Compatible Motors: DC030C, DC040B, DC054B, EC057C

■ Benefits

- Maximum Load torque up to 1.24 Nm in the standard model
- Load increased to 2.12 Nm in the high torque and up to 3.53 in wide face versions
- Standard bronze bearings

■ Optional Assembly

- Special lubrication for extreme condition
- Ball bearings for high radial loads
- Delrin gears for noise reduction



■ Characteristics

Gear Data	Units	G51A 5.9:1	G51A 11.5:1	G51A 19.7:1	G51A 38.3:1	G51A 65.5:1	G51A 127.8:1
Maximum Load	Nm	1.236					
	oz-in	175					
Weight (Mass)	g	167.3	167.3	177.5	177.5	187.7	187.7
	oz	5.9	2.9	6.26	6.26	6.62	6.62
Length (L)	mm	34.9					
	inches	1.373					
Stages	–	1					
Ratio	–	5.9:1	11.5:1	19.7:1	38.3:1	65.5:1	127.8:1
Efficiency	–	0.81	0.81	0.73	0.73	0.66	0.66
Shaft Rotation	–	CW	CW	CCW	CCW	CW	CW

Gear Data	Units	G51A 218.4:1	G51A 425.9:1	G51A 728.1:1	G51A 1419.8:1	G51A 2426.9:1	G51A 4732.5:1
Maximum Load	Nm	1.236					
	oz-in	175					
Weight (Mass)	g	197.9	197.9	208.1	208.1	231.9	231.9
	oz	6.98	6.98	7.34	7.34	8.18	8.18
Length (L)	mm	34.9	34.9	34.9	34.9	38.8	38.8
	inches	1.373	1.373	1.373	1.373	1.528	1.528
Stages	–	1	1	1	1	2	2
Ratio	–	218.4:1	425.9:1	728.1:1	1419.8:1	2426.9:1	4732.5:1
Efficiency	–	0.59	0.59	0.53	0.53	0.48	0.48
Shaft Rotation	–	CCW	CCW	CW	CW	CCW	CCW

High Torque Characteristics

Gear Data	Units	G51A-HT 5.9:1	G51A-HT 11.5:1	G51A-HT 19.7:1	G51A-HT 38.3:1	G51A-HT 65.5:1	G51A-HT 127.8:1
Maximum Load	Nm	2.118					
	oz-in	300					
Weight (Mass)	g	167.30	167.3	177.5	177.5	187.7	187.7
	oz	5.90	5.9	6.26	6.26	6.62	6.62
Length (L)	mm	34.9 mm / 1.373 inches					
Stages	–	1					
Ratio	–	5.9:1	11.5:1	19.7:1	38.3:1	65.5:1	127.8:1
Efficiency	–	0.81	0.81	0.73	0.73	0.66	0.66
Shaft Rotation	–	CW	CW	CCW	CCW	CW	CW

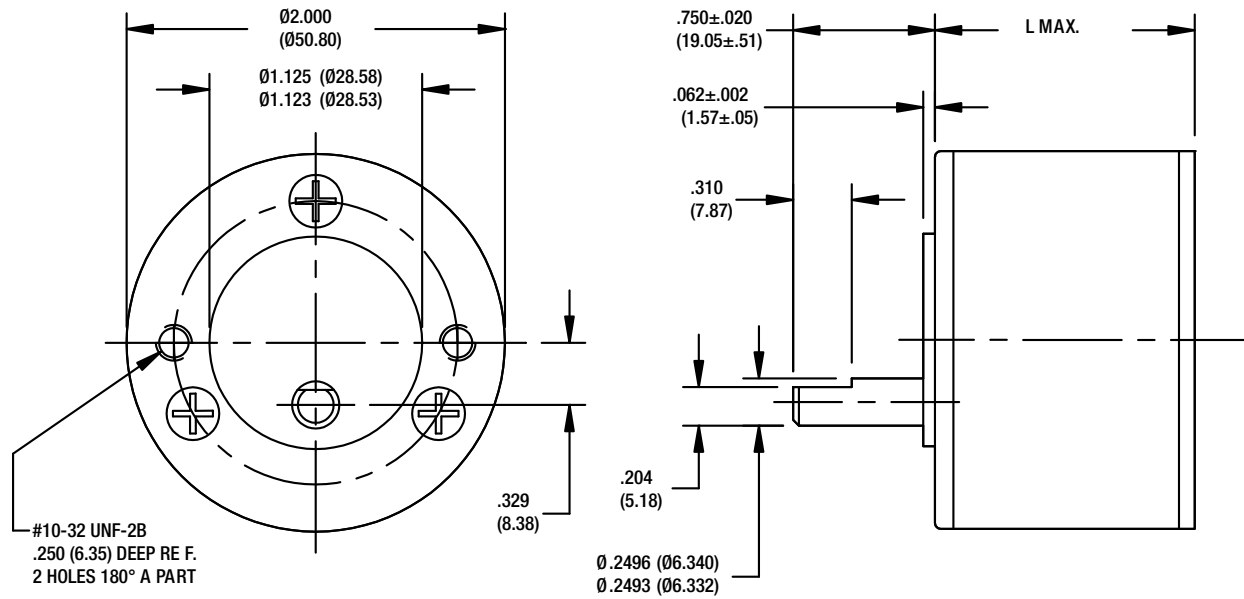
Gear Data	Units	G51A-HT 218.4:1	G51A-HT 425.9:1	G51A-HT 728.1:1	G51A-HT 1419.8:1	G51A-HT 2426.9:1	G51A-HT 4732.5:1
Maximum Load	Nm	2.118					
	oz-in	300					
Weight (Mass)	g	197.9	197.9	208.1	208.1	231.9	231.9
	oz	6.98	6.98	7.34	7.34	8.18	8.18
Length (L)	mm	34.9	34.9	34.9	34.9	38.8	38.8
	inches	1.373	1.373	1.373	1.373	1.528	1.528
Stages	–	1	1	1	1	2	2
Ratio	–	218.4:1	425.9:1	728.1:1	1419.8:1	2426.9:1	4732.5:1
Efficiency	–	0.59	0.59	0.53	0.53	0.48	0.48
Shaft Rotation	–	CCW	CCW	CW	CW	CCW	CCW

Wide Face Characteristics

Gear Data	Units	G51A-WF 19.7:1	G51A-WF 38.3:1	G51A-WF 65.5:1	G51A-WF 127.8:1
Maximum Load	Nm	3.53			
	oz-in	500			
Weight (Mass)	g	184.8	184.8	195	195
	oz	6.52	6.52	6.88	6.88
Length (L)	mm	34.9 mm / 1.373 inches			
Stages	–	1			
Ratio	–	19.7:1	38.3:1	65.5:1	127.8:1
Efficiency	–	0.73	0.73	0.66	0.66
Shaft Rotation	–	CCW	CCW	CW	CW

Gear Data	Units	G51A-WF 218.4:1	G51A-WF 425.9:1	G51A-WF 728.1:1	G51A-WF 1419.8:1
Maximum Load	Nm	3.53			
	oz-in	500			
Weight (Mass)	g	205.3	205.3	229.1	229.1
	oz	7.24	7.24	8.08	8.08
Length (L)	mm	34.9	34.9	38.8	38.8
	inches	1.373	1.373	1.53	1.53
Stages	–	1	1	2	2
Ratio	–	218.4:1	425.9:1	728.1:1	1419.8:1
Efficiency	–	0.59	0.59	0.53	0.53
Shaft Rotation	–	CCW	CCW	CW	CW

Dimensional Drawings



■ Combined Length (L_{GM})

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC030C-1	88.6	92.5
DC030C-2	100.6	104.5
DC030C-3	112.6	116.5

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC054B-1	109.9	113.8
DC054B-2	116.3	120.2
DC054B-3	129.0	132.9
DC054B-4	138.5	142.4
DC054B-5	148.0	151.9
DC054B-6	160.7	164.6
DC054B-7	179.8	183.7

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
DC040B-1	78.8	82.7
DC040B-2	88.3	92.2
DC040B-3	93.4	97.3
DC040B-4	101.0	104.9
DC040B-5	109.9	113.8
DC040B-6	117.5	121.4

Compatible Motors / Length (mm) Standard, High Torque, Wide Face		
Stage	1	2
EC057C-1	73.8	77.7
EC057C-2	85.2	89.1
EC057C-3	97.9	101.8
EC057C-4	110.6	114.5

G30A Series

The G30A is a 30mm planetary gearbox suitable for servo applications where DC Servo brush or BLDC motor technology is specified. The G30A provides maximum efficiency, minimum backlash, has a smaller mechanical footprint and is available with round and square mounting endbell configurations.

Compatible Motors: DC026C, DC030B, DC030C, DC040B, EC033A, EC044A, ES030A

■ Benefits

- Sintered metal gears for high torque capacity
- Sintered metal output bearing



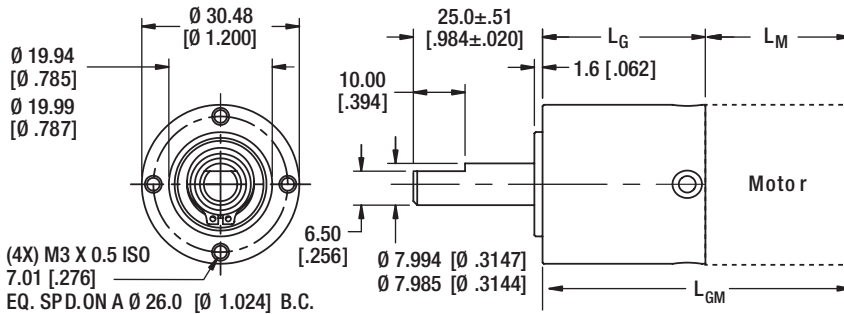
■ Characteristics

Gear Data	Units	G30A 4:1	G30A 6:1	G30A 16:1	G30A 24:1	G30A 36:1	G30A 64:1	G30A 96:1
Maximum Load	Nm	2.47	2.47	3.53	3.53	3.53	6.5	6.5
	oz-in	350	350	500	500	500	920	920
Weight (Mass)	g	110.6	110.6	124.7	124.7	124.7	138.9	138.9
	oz	3.9	3.9	4.4	4.4	4.4	4.9	4.9
Length (L)	mm	32.64	32.64	38.48	38.48	38.48	44.32	44.32
	inches	1.285	1.285	1.515	1.515	1.515	1.745	1.745
Stages	–	1	1	2	2	2	3	3
Ratio	–	4/1	6/1	16/1	24/1	36/1	64/1	96/1
Efficiency	–	0.90	0.90	0.81	0.81	0.81	0.73	0.73
Shaft Rotation	–	CW						

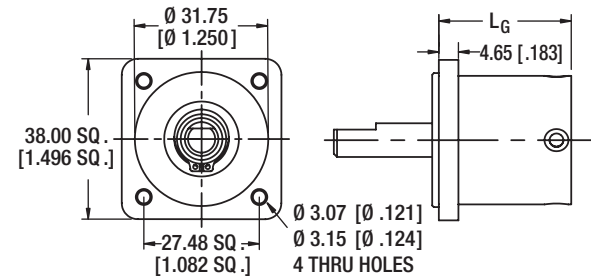
Gear Data	Units	G30A 144:1	G30A 216:1	G30A 256:1	G30A 384:1	G30A 576:1	G30A 864:1	G30A 1296:1
Maximum Load	Nm	6.5	6.5	8.83	8.83	8.83	8.83	8.83
	oz-in	920	920	1250	1250	1250	1250	1250
Weight (Mass)	g	138.9	138.9	155.9	155.9	155.9	155.9	155.9
	oz	4.9	4.9	5.5	5.5	5.5	5.5	5.5
Length (L)	mm	44.32	44.32	50.17	50.17	50.17	50.17	50.17
	inches	1.745	1.745	1.975	1.975	1.975	1.975	1.975
Stages	–	3	3	4	4	4	4	4
Ratio	–	144/1	216/1	256/1	384/1	576/1	864/1	1296/1
Efficiency	–	0.73	0.73	0.66	0.66	0.66	0.66	0.66
Shaft Rotation	–	CW						

Dimensional Drawings

Dimensions = mm [in]



With Optional Square Mounting Flange (G30AF)



■ Combined Length (L_{GM})

Compatible Motors / Length (mm)				
Stage	1	2	3	4
DC026C-1	78.3	84.2	90.0	95.8
DC026C-2	81.5	87.3	93.2	99.0
DC026C-3	87.8	93.7	99.5	105.4

Compatible Motors / Length (mm)				
Stage	1	2	3	4
EC033A-1	70.7	76.6	82.4	88.3
EC033A-2	83.4	89.3	95.1	101.0
EC033A-3	96.1	102.0	107.8	113.7

Stage	1	2	3	4
DC030B-1	85.2	91.1	96.9	102.7
DC030B-2	88.4	94.2	100.1	105.9
DC030B-3	94.7	100.6	106.4	112.3

Stage	1	2	3	4
EC044A-1	84.9	90.8	96.6	102.5
EC044A-2	97.6	103.5	109.3	115.2
EC044A-3	110.3	116.2	122.0	127.9

Stage	1	2	3	4
DC030C-1	86.3	92.2	98.0	103.9
DC030C-2	98.3	104.1	110.0	115.8
DC030C-3	110.3	116.1	122.0	127.8

Stage	1	2	3	4
ES030A-1	91.6	97.5	103.3	109.2
ES030A-2	101.8	107.6	113.5	119.3

Stage	1	2	3	4
DC040B-1	79.1	84.9	90.8	96.6
DC040B-2	88.6	94.4	100.3	106.1
DC040B-3	93.7	99.5	105.4	111.2
DC040B-4	101.3	107.1	113.0	118.8
DC040B-5	110.2	116.0	121.9	127.7
DC040B-6	117.8	123.6	129.5	135.3

G40A Series

The G40A is a 40 mm planetary gearbox suitable for servo applications where DC Servo brush or BLDC motor technology is specified.

Compatible Motors: DC040B, DC054B, EC057C, ES030A, ES040A, ES050A

Benefits

- Sintered metal gears for high torque capacity
- Sintered metal output bearing

Optional Assemblies

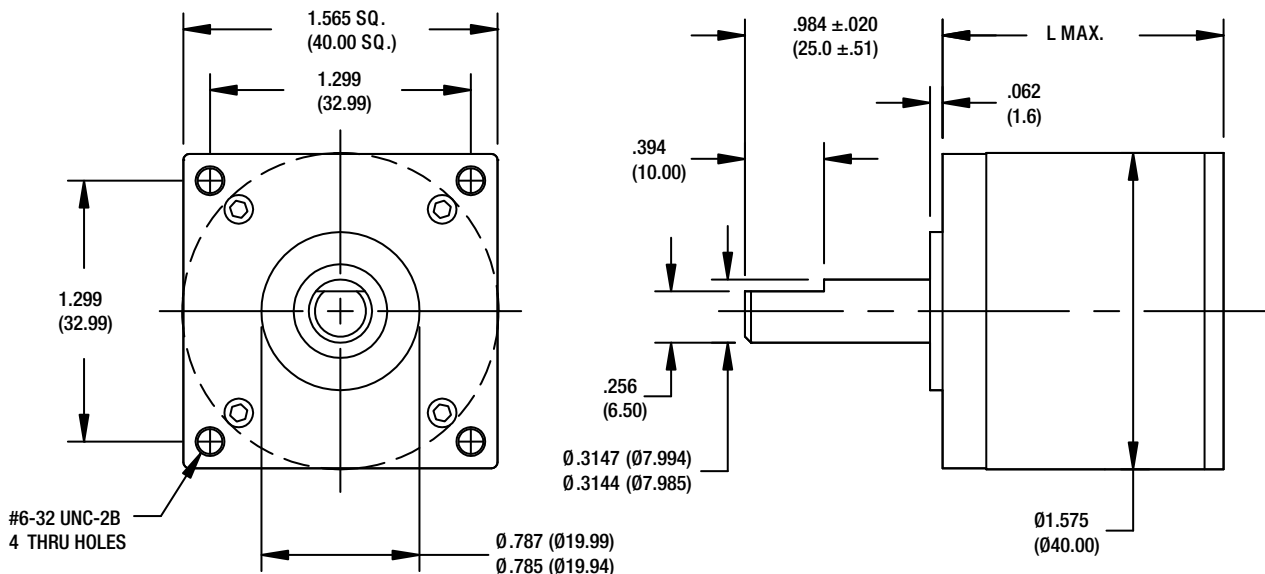
- Alternate mounting and shaft configurations
- Output ball bearing for high radial loads
- Additional ratios



Characteristics

Gear Data	Units	G40A 4:1	G40A 17.3:1	G40A 24:1	G40A 75.1:1	G40A 144:1	G40A 325.5:1	G40A 864:1
Maximum Load	Nm	14.12						
	oz-in	2000						
Weight (Mass)	g	255.1	311.8	311.8	368.5	368.5	425.2	425.2
	oz	9	11	11	13	13	15	15
Length (L)	mm	35.6	43.2	43.2	50.8	50.8	58.4	58.4
	inches	1.400	1.700	1.700	2.000	2.000	2.300	2.300
Stages	-							
Ratio	-	4/1	52/3	24/1	676/9	144/1	8768/27	864/1
Efficiency	-	0.90	0.81	0.81	0.73	0.73	0.65	0.65
Shaft Rotation	-	CW						

Dimensional Drawings



■ Combined Length (L_{GM})

Compatible Motors / Length (mm)				
Stage	1	2	3	4
DC040B-1	82.03	89.63	97.23	104.83
DC040B-2	91.56	99.16	106.76	114.36
DC040B-3	96.64	104.24	111.84	119.44
DC040B-4	104.26	111.86	119.46	127.06
DC040B-5	111.15	118.75	126.35	133.95
DC040B-6	120.77	128.37	135.97	143.57

Stage	1	2	3	4
DC054B-1	110.61	118.21	125.81	133.41
DC054B-2	116.96	124.56	132.16	139.76
DC054B-3	129.66	137.26	144.86	152.46
DC054B-4	139.20	146.80	154.40	162.00
DC054B-5	148.70	156.30	163.90	171.50
DC054B-6	161.40	169.00	176.60	184.20
DC054B-7	180.50	188.10	195.70	203.30

Compatible Motors / Length (mm)				
Stage	1	2	3	4
EC057C-1	74.5	82.1	89.7	97.3
EC057C-2	85.9	93.5	101.1	108.7
EC057C-3	98.6	106.2	113.8	121.4
EC057C-4	111.3	118.9	126.5	134.1

Stage	1	2	3	4
ES030A-1	94.58	102.18	109.78	117.38
ES030A-2	104.71	112.34	119.94	127.54

Stage	1	2	3	4
ES040A-1	103.04	110.64	118.24	125.84
ES040A-2	110.66	118.26	125.86	133.46
ES040A-3	118.28	125.88	133.48	141.08

Stage	1	2	3	4
ES050A-1	115.99	123.59	131.19	138.79
ES050A-2	128.69	136.29	143.89	151.49
ES050A-3	141.39	148.99	156.59	164.19

PLG42S Series

The PLG42S is a 42 mm planetary gearbox suitable for servo applications where DC Servo brush or BLDC motor technology is specified. The PLG42S provides excellent efficiency in a compact and industry compatible output configuration.

Compatible Motors: DC040B, DC054B, EC042B, EC044A, EC057C, ES040A, ES050A

■ Benefits

- Maximum Load torque up to 14 Nm
- All steel gearing for high torque capacity
- Dual ball bearings on output shaft
- High efficiency

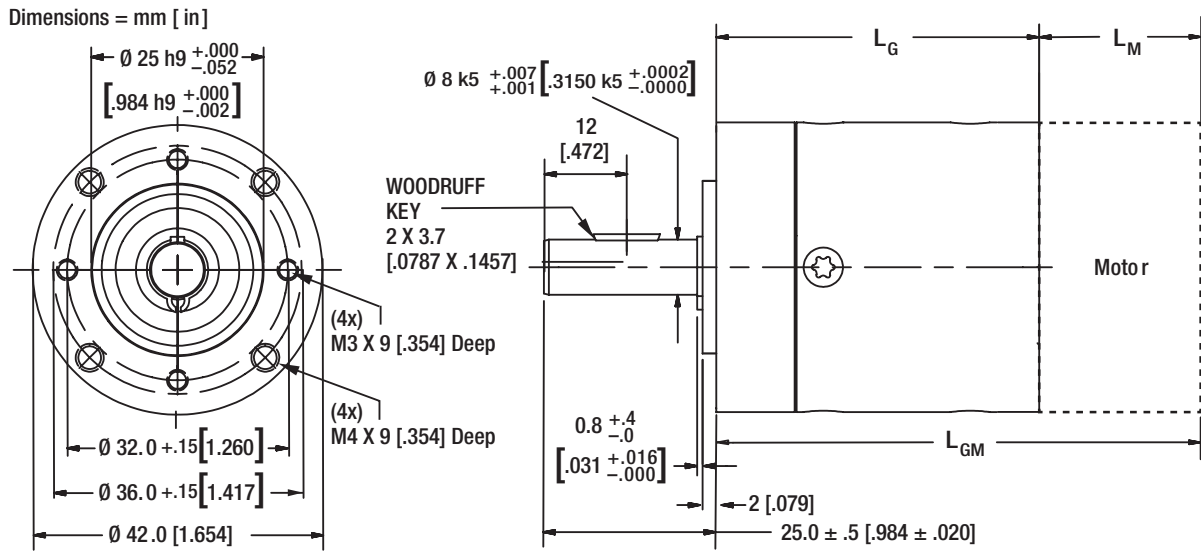


■ Characteristics

Gear Data	Units	PLG42S 4:1	PLG42S 8:1	PLG42S 16:1	PLG42S 25:1	PLG42S 32:1	PLG42S 50:1	PLG42S 64:1
Maximum Load	Nm	3.5	3.5	6	6	6	6	6
	oz-in	496	496	850	850	850	850	850
Weight (Mass)	g	270	270	370	370	370	370	370
	oz	9.52	9.52	13.1	13.1	13.1	13.1	13.1
Length (L)	mm	47.6	47.6	59.4	59.4	59.4	59.4	59.4
	inches	1.87	1.87	2.34	2.34	2.34	2.34	2.34
Stages	–	1	1	2	2	2	2	2
Ratio	–	4/1	8/1	16/1	25/1	32/1	50/1	64/1
Efficiency	–	0.90	0.90	0.81	0.81	0.81	0.73	0.73
Shaft Rotation	–	CW						

Gear Data	Units	PLG42S 100:1	PLG42S 128:1	PLG42S 156:1	PLG42S 200:1	PLG42S 200:1	PLG42S 200:1	PLG42S 200:1
Maximum Load	Nm	14						
	oz-in	1983						
Weight (Mass)	g	880						
	oz	31.0						
Length (L)	mm	71.2						
	inches	2.80						
Stages	–	3						
Ratio	–	100/1	128/1	156.25/1	200/1	256/1	400/1	512/1
Efficiency	–	0.73						
Shaft Rotation	–	CW						

Dimensional Drawings



■ Combined Length (L_{GM})

Compatible Motors / Length (mm)			
Stage	1	2	3
DC040B-1	94.0	105.8	117.6
DC040B-2	103.6	115.4	127.2
DC040B-3	108.6	120.4	132.2
DC040B-4	116.3	128.1	139.9
DC040B-5	123.2	135.0	146.8
DC040B-6	132.8	144.6	156.4

Stage	1	2	3
DC054B-1	122.6	134.4	146.2
DC054B-2	129.0	140.8	152.6
DC054B-3	141.7	153.5	165.3
DC054B-4	151.2	163.0	174.8
DC054B-5	160.7	172.5	184.3
DC054B-6	173.4	185.2	197.0
DC054B-7	192.5	204.3	216.1

Stage	1	2	3
EC042B-1	99.8	111.6	123.4
EC042B-2	119.8	131.6	143.4
EC042B-3	139.8	151.6	163.4

Compatible Motors / Length (mm)			
Stage	1	2	3
EC044A-1	100.3	112.1	123.9
EC044A-2	113.0	124.8	136.6
EC044A-3	125.7	137.5	149.3

Stage	1	2	3
EC057C-1	86.5	98.3	110.1
EC057C-2	97.9	109.7	121.5
EC057C-3	110.6	122.4	134.2
EC057C-4	123.3	135.1	146.9

Stage	1	2	3
ES040A-1	115.0	126.8	138.6
ES040A-2	122.7	134.5	146.3
ES040A-3	130.3	142.1	153.9

Stage	1	2	3
ES050A-1	128.0	139.8	151.6
ES050A-2	140.7	152.5	164.3
ES050A-3	153.4	165.2	177.0

PLG52 Series

The PLG52 is a 52 mm planetary gearbox suitable for servo applications where DC Servo brush or BLDC motor technology is specified. The PLG52 provides excellent efficiency in a compact and industry compatible output configuration.

Compatible Motors: DC054B, EC042B, EC044A, EC057B, EC057C, ES040A, ES050A

Benefits

- Maximum Load torque up to 24 Nm
- All steel gearing for high torque capacity
- Dual ball bearings on output shaft to withstand high loads
- High efficiency

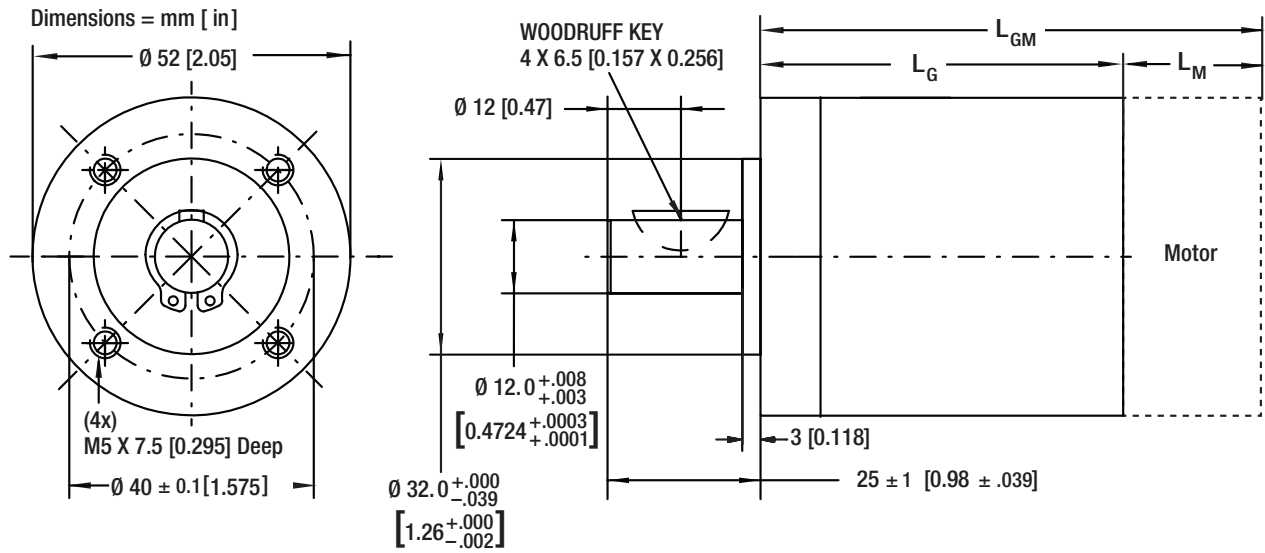


Characteristics

Gear Data	Units	PLG52 4.5:1	PLG52 6.25:1	PLG52 15:1	PLG52 20.2:1	PLG52 28.1:1	PLG52 36:1	PLG52 50:1
Maximum Load	Nm	1.2	1.2	8	8	8	8	8
	oz-in	170	170	1133	1133	1133	1133	1133
Weight (Mass)	g	560	560	720	720	720	720	720
	oz	19.8	19.8	25.4	25.4	25.4	25.4	25.4
Length (L)	mm	50.0	50.0	65.5	65.5	65.5	65.5	65.5
	inches	1.97	1.97	2.58	2.58	2.58	2.58	2.58
Stages	–	1	1	2	2	2	2	2
Ratio	–	4.5/1	6.25/1	15/1	20.25/1	28.12/1	36/1	50/1
Efficiency	–	0.90	0.90	0.81	0.81	0.81	0.81	0.81
Shaft Rotation	–	CW						

Gear Data	Units	PLG52 91.1:1	PLG52 126.5:1	PLG52 162:1	PLG52 225:1	PLG52 288:1	PLG52 400:1
Maximum Load	Nm	24					
	oz-in	3399					
Weight (Mass)	g	880					
	oz	31.0					
Length (L)	mm	80.5					
	inches	3.17					
Stages	–	3					
Ratio	–	91.12/1	126.5/1	162/1	225/1	288/1	400/1
Efficiency	–	0.73					
Shaft Rotation	–	CW					

Dimensional Drawings



■ Combined Length (L_{GM})

Compatible Motors / Length (mm)			
Stage	1	2	3
DC054B-1	127.0	142.5	157.5
DC054B-2	133.4	148.9	163.9
DC054B-3	146.1	161.6	176.6
DC054B-4	155.6	171.1	186.1
DC054B-5	165.1	180.6	195.6
DC054B-6	177.8	193.3	208.3
DC054B-7	196.9	212.4	227.4

Stage	1	2	3
EC042B-1	104.5	120.0	135.0
EC042B-2	124.5	140.0	155.0
EC042B-3	144.5	160.0	175.0

Stage	1	2	3
EC044A-1	102.3	117.8	132.8
EC044A-2	115.0	130.5	145.5
EC044A-3	127.7	143.2	158.2

Compatible Motors / Length (mm)			
Stage	1	2	3
EC057B-1	130.0	145.5	160.5
EC057B-2	125.1	140.6	155.6
EC057B-3	169.9	185.4	200.4
EC057B-4	190.0	205.5	220.5

Stage	1	2	3
EC057C-1	88.2	103.7	118.7
EC057C-2	99.6	115.1	130.1
EC057C-3	112.3	127.8	142.8
EC057C-4	125.0	140.5	155.5

Stage	1	2	3
ES040A-1	117.4	132.9	147.9
ES040A-2	125.1	140.6	155.6
ES040A-3	132.7	148.2	163.2

Stage	1	2	3
ES050A-1	131.8	147.3	162.3
ES050A-2	144.5	160.0	175.0
ES050A-3	157.2	172.7	187.7

E21 Series

Compact and low profile, E21 Series Encoders provide parameters of reflective optical technology, transmissive optical technology with and without differential line drivers, and multitude of line counts.

Modular and bearing construction options. Bearing style encoders provide significant performance upgrades in demanding applications. Factory installed and tested for quick start-up.

Benefits

- Resolutions from 120 to 8192
- TTL Quadrature output
- Frequency response to 960 kHz
- Low power consumption, 5V @ 60mA max.
- Locking connector

Optional Assemblies

- Index pulse
- Differential line driver with complementary outputs
- Detachable cable with optional axial orientation
- Through hole cover



Characteristics

Encoder Data	Units	Part No.		
		E21C	E21D	
Available Resolutions		120,125,128, 250, 256, 300, 360	500, 512, 1000, 1024, 1600, 2000, 2048, 3200, 4000, 4096, 6400, 8000, 8192	
Output		2-Channel Quadrature	2-Channel Quadrature with Index	
Output Interface		TTL Compatible	TTL Compatible	
Supply Voltage	V _{CC}	VDC	4.5 to 5.5	
Supply Current	I _{CC}	mA	20 max. 60 max.	
High Level Output Voltage	V _{OR}	V	2.4 min. 2.4 min.	
High Level Output Voltage	V _{OL}	V	0.4 max. 0.4 max.	
Max. Operating Frequency	f _{MAX}	kHz	40 (120-360 CPR)	55 (500-512 CPR)
				110 (1000-1024 CPR)
				220 (2000-2048 CPR)
				240 (1600 CPR)
				480 (3200-4096 CPR)
				960 (6400-8192 CPR)
Operating Temperature	Θ _{MAX}	°C	-20 to +85	-20 to +85
Encoder Weight (Mass)	W _E	oz	0.11	0.11
		g	3.1	3.1

Connection Chart

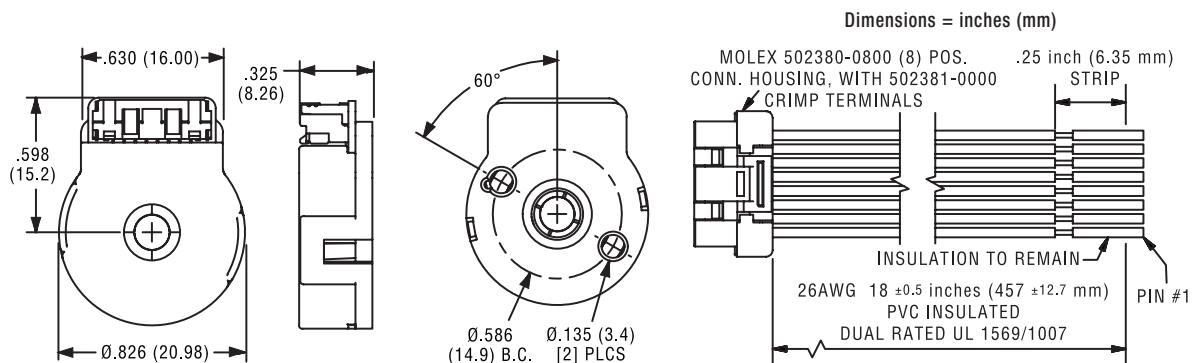
PIN	E21C ¹	E21D ¹	Optional Cable
1	Channel A		Blue/White
2	Vcc		White
3	Encoder Ground		Black
4	Channel A		Blue
5	Channel B		Violet/White
6	Channel B		Violet
7	—	Index I	Green/White
8	—	Index I	Green

¹Optional differential LD connections shown in gray.

Optional Cables

Cable for Encoder	Part No.	Description
E21C	84-90-3	2-Channel, Radial, Differential Outputs
E21D	84-90-1	3-Channel, Radial, Differential Outputs

Dimensional Drawings: E21C • E21D



E30 Series



Compact and low profile, E30 Series Encoders provide parameters of reflective optical technology, transmissive optical technology with and without differential line drivers, and multitude of line counts. Modular and bearing construction options. Bearing style encoders provide significant performance upgrades in demanding applications. Factory installed and tested for quick start-up.

■ Benefits

- Resolutions from 200 to 2048
- TTL Quadrature output
- Frequency response to 220 kHz
- Low power consumption, 5V @ 20mA max.
- Locking connector

■ Optional Assemblies

- Index pulse
- Differential line driver with complementary outputs
- Detachable cable with optional axial orientation

■ Characteristics

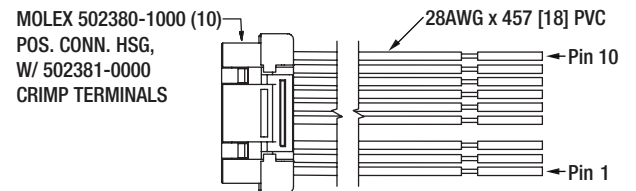
Encoder Data	Units	Part No.	
		E30C	E30D
Available Resolutions		200, 250, 256, 400, 500	500, 512, 1000, 1024, 2000, 2048
Output		2-Channel Quadrature	3-Channel Quadrature with Index
Output Interface		TTL Compatible	TTL Compatible
Supply Voltage	V _{CC}	VDC	4.5 to 5.5
Supply Current	I _{CC}	mA	20 max.
High Level Output Voltage	V _{OR}	V	2.4 min.
High Level Output Voltage	V _{OL}	V	0.4 max.
Max. Operating Frequency	f _{MAX}	kHz	55 (500-512 CPR)
			40 (200-500 CPR)
			110 (1000-1024 CPR)
			220 (2000-2048 CPR)
Operating Temperature	Θ _{MAX}	°C	-20 to +85
Encoder Weight (Mass)	W _E	oz	0.2
		g	5.6

■ Connection Chart / Radial Connector

PIN	COLOR	E30C	E30D	E30C ¹	E30D ¹
1	Black	Encoder Ground			
2	White	Vcc			
3	Green/White	-	-	-	Index I
4	-	-	-	-	-
5	Blue/White	-	-	Channel A	
6	Blue	Channel A		Channel A	
7	Violet	Channel B		Channel B	
8	Violet/White	-	-	Channel B	
9	Green	-	Index I	-	Index I
10	Green/Yellow	Motor Ground		Motor Ground	

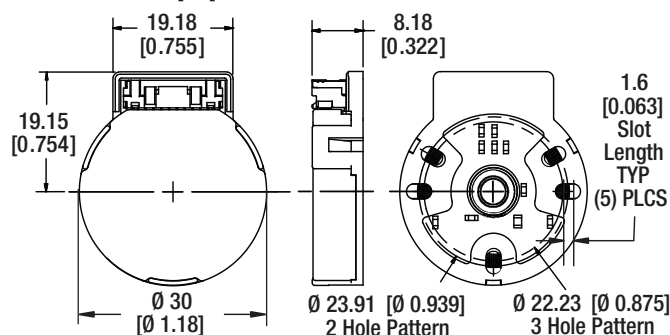
¹Optional differential LD connections shown in gray.

■ Optional Cable Assembly (82-1108-1)

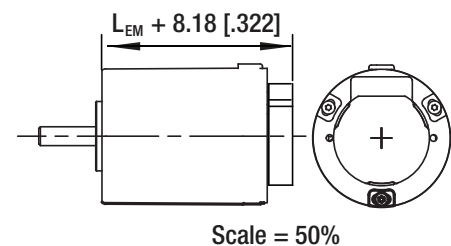


Dimensional Drawings: E30C • E30D

Dimensions = mm [in]



■ Typical Motor with Encoder



Q / V Series

Compact and low profile, Q / V Series Encoders provide parameters of reflective optical technology, transmissive optical technology with and without differential line drivers, and multitude of line counts.

Modular and bearing construction options. Bearing style encoders provide significant performance upgrades in demanding applications. Factory installed and tested for quick start-up.

Encoders are identical except for the mounting spring is configured for different motors.



■ Benefits

- Resolutions from 1000 to 5000
- Differential line driver is standard
- Frequency response to 500 kHz
- Rugged mechanical design
- Good for higher temperature
- Shielded cable

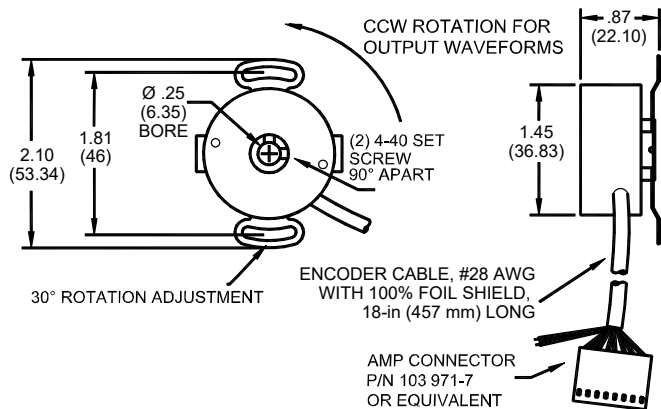
■ Characteristics

Encoder Data	Units	Part No.			
		Q1 V1	Q3 V3	Q5 V5	Q8 V8
Available Resolutions		1000	2000	2500	5000
Output		2-Channel Quadrature with Index			
Output Interface		TTL Compatible			
Supply Voltage	V _{CC}	VDC	4.75 to 5.25		
Supply Current	I _{CC}	mA	125 max.		
Max. Operating Frequency	f _{MAX}	kHz	500		
Operating Temperature	Θ _{MAX}	°C	-20 to +100		

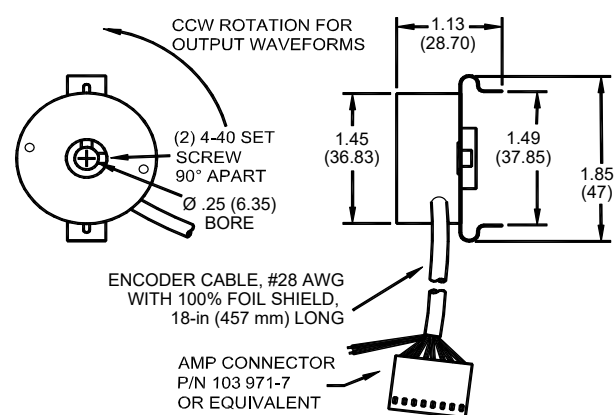
■ Connection Chart

PIN	Color	Q / V Series
1	Red	Vcc
2	Black	Encoder Ground
3	Brown	Channel A
4	White	Channel A
5	Blue	Channel B
6	Green	Channel B
7	Orange	Index I
8	Yellow	Index I
N/C	Black / White	Case Ground
N/C	Drain Wire	Cable Shield

Dimensional Drawings: Q Series



Dimensional Drawings: V Series



C / D Series



Compact and low profile, C / D Series Encoders provide parameters of reflective optical technology, transmissive optical technology with and without differential line drivers, and multitude of line counts.

Modular and bearing construction options. Bearing style encoders provide significant performance upgrades in demanding applications. Factory installed and tested for quick start-up.

Encoders are identical to the Q / V Series except for the additional motor commutation signals.

■ Benefits

- Resolutions from 1000 to 5000
- Rugged mechanical design
- Differential line driver is standard
- 1° (mech) accuracy of commutators
- Frequency response to 500 kHz
- IP 40 Rated

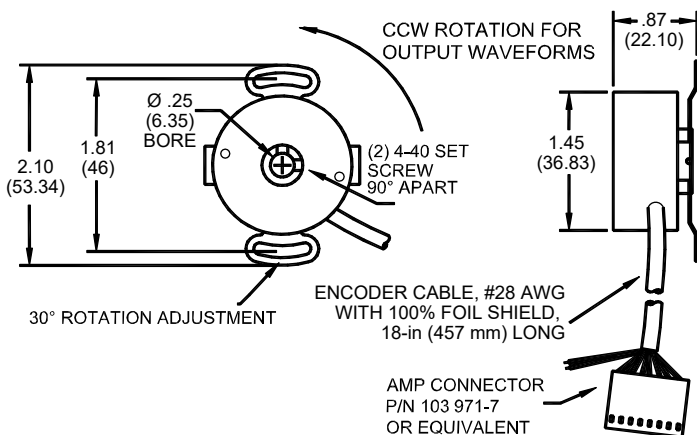
■ Connection Chart

COLOR	C / D Series
Red	VDC (+5V)
Black	Common
Brown	Output A
White	Output A'
Blue	Output B
Green	Output B'
Orange	Output Z
Yellow	Output Z'
Violet	Output U
Gray	Output U'
White / Brown	Output V
White / Red	Output V'
White / Orange	Output W
White / Yellow	Output W'
Back / White	Case Ground
Drain Wire	Cable Shield

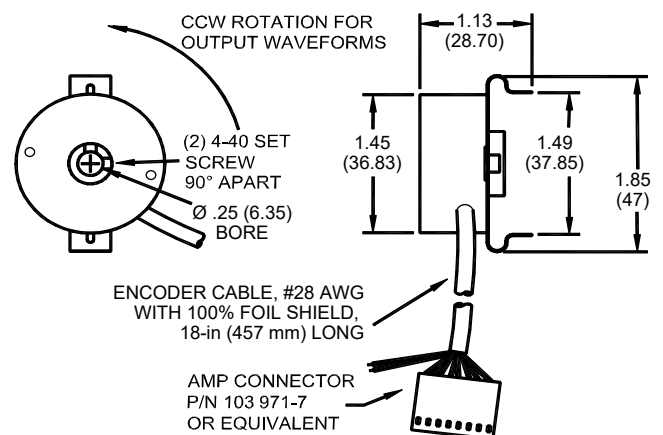
■ Characteristics

Encoder Data	Units	Part No.							
		C1 D1	CA	C3 D3	CC	C5 D5	CE	C8 D8	CH
Available Resolutions		1000		2000		2500		5000	
Motor Poles		4	8	4	8	4	8	4	8
Output		2-Channel Quadrature with Index							
Output Interface		TTL Compatible							
Supply Voltage V_{CC}	VDC	4.75 to 5.25							
Supply Current I_{CC}	mA	200 max.							
Max. Operating Frequency f_{MAX}	kHz	500							
Operating Temperature Θ_{MAX}	°C	-20 to +100							

Dimensional Drawings: C Series



Dimensional Drawings: D Series

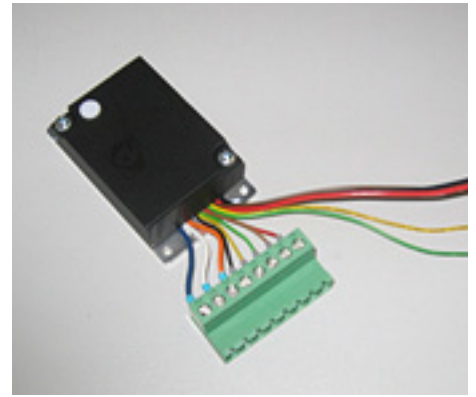


BGE3004A Non-Programmable Drive

The BGE3004A brushless motor drive is a non-programmable single-quadrant speed controller. Speeds can be controlled between 500 – 5000 rpm with a 0-10VDC reference voltage.

Benefits

- Speed control with PWM
- Integral potentiometer for speed setting
- Protection against under-voltage, reverse polarity, stall protection and over temperature
- Compact Size: 2.72 in x 1.58 in x .71 in (69 mm x 40 mm x 18 mm)



Wire Assignment

Color	Signal
Black	GND
Red	+Vc
Brown	N-analog
Yellow	cw / ccw
Green	Start / Stop

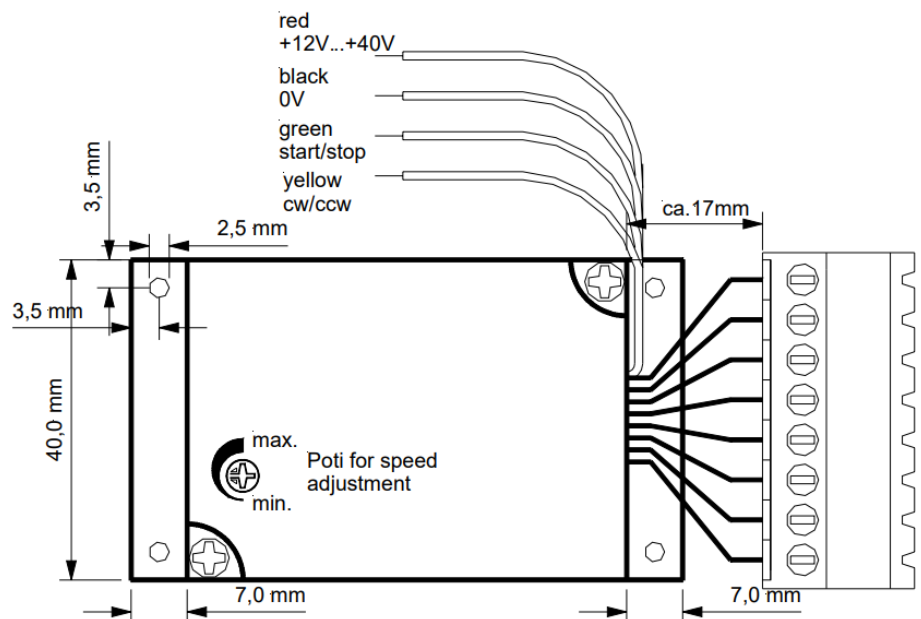
Wire Assignment

PIN	Color	BGE3004A
1	Black	Motor Phase B
2	Red	Motor Phase A
3	Brown	Motor Phase C
4	Black	GND (Hall)
5	Yellow	H1
6	Green	H2
7	Brown	H3
8	Red	+12 Vc (Hall)

Characteristics

Data	Units	Part No.
		BGE3004A
Voltage Range	V DC	12 to 40
Continuous Output Current	Amps	4 A rms
Communication (A)		0 to 10 V analog
Peak Output Current	Amps	34 A
Speed Range	RPM	500 - 5000
Torque Mode		No
Speed Mode		Yes
Position Mode		No
Size	mm	69 x 40 x 18

Dimensional Drawing: BGE3004A



PBL/ABL/CBL 6035E & 6070E Programmable Drives

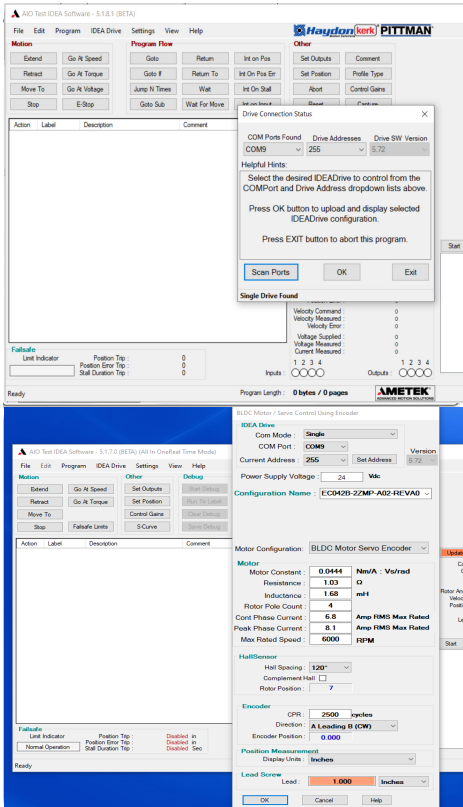


The PBL Series Drive brushless motor controller is a servo drive and fully programmable control unit which will simplify your machine building experience. An intuitive patent-pending Graphic User Interface (GUI) removes the complexity of programming while support tools simplify its quick integration.

■ Benefits

- RoHS Compliant
- Stand-alone drive unit
- Programming done through Graphic User Interface (GUI)
- Automatic population of motor and drive parameters
- Programmable motion program language ideal for autonomous complex precise repetitive motion sequences
- I/O control ideal for simple non repetitive motion (PDE / PWM / Joystick, etc.)
- Programmable Speed / Current / Accel-Decel / Current Boost / Interrupts / I/O
- Sinusoidal commutation
- USB, RS485, or CANopen Communications Protocol
- Movement profile plotter
- Interactive program debug feature
- Optional motor cables
- Streaming commands ideal for networked coordinated motion control

■ Characteristics



Simple to use drive software with on-screen button and easy to understand programming guides.

Data	Part No.	
	P/A/CBL6035E	P/A/CBL6070E
Drive Input Voltage Range	12 to 60 V DC	
Maximum Drive Current/Phase	3.5 A rms / 7 A peak	7.0 A rms / 10.0 A rms peak
Current Boost Capability	Optional 30% current boost capability during ramping	
Communications	USB / RS485 / CAN	
Commutation	Dependent on motor type	
Motor	Stepper / BLDC / BDC	
Hall Cell Spacing	60° / 120°	
Encoder (min. requirement)	5V, Incremental encoder with 128 CPR min	
Digital I/O Voltage Range	5 to 24 V DC	
Digital Inputs	4	
Digital Input Max Current	8 mA (each)	
Digital Outputs	4 at heat sink	
Digital Output Max Current	200 mA at heat sink	
Maximum Temperature	70° measured at heat sink	
Program Storage Size	85 Kbytes	
Program Storage Memory Type	Flash	
Maximum Number Stored Programs	85 - referenced by 10 character program names	
Position Counter Range	64 bit	
Ramping	Trapezoidal or S-Curve	
Interrupt Sources	4 Inputs (rising, falling or both edges). Internal Position Counter (when reaching a programmed position)	

I/O Connector TABLE "A"

PIN	Description	Note
1	GROUND I/O SUPPLY	5 - 24 VDC
2	+ I/O SUPPLY	5 - 24 VDC
3	INPUT 1	
4	INPUT 2	
5	INPUT 3	
6	INPUT 4	
7	OUTPUT 1	
8	OUTPUT 2	
9	OUTPUT 3	
10	OUTPUT 4	

I/O Connector TABLE "B"

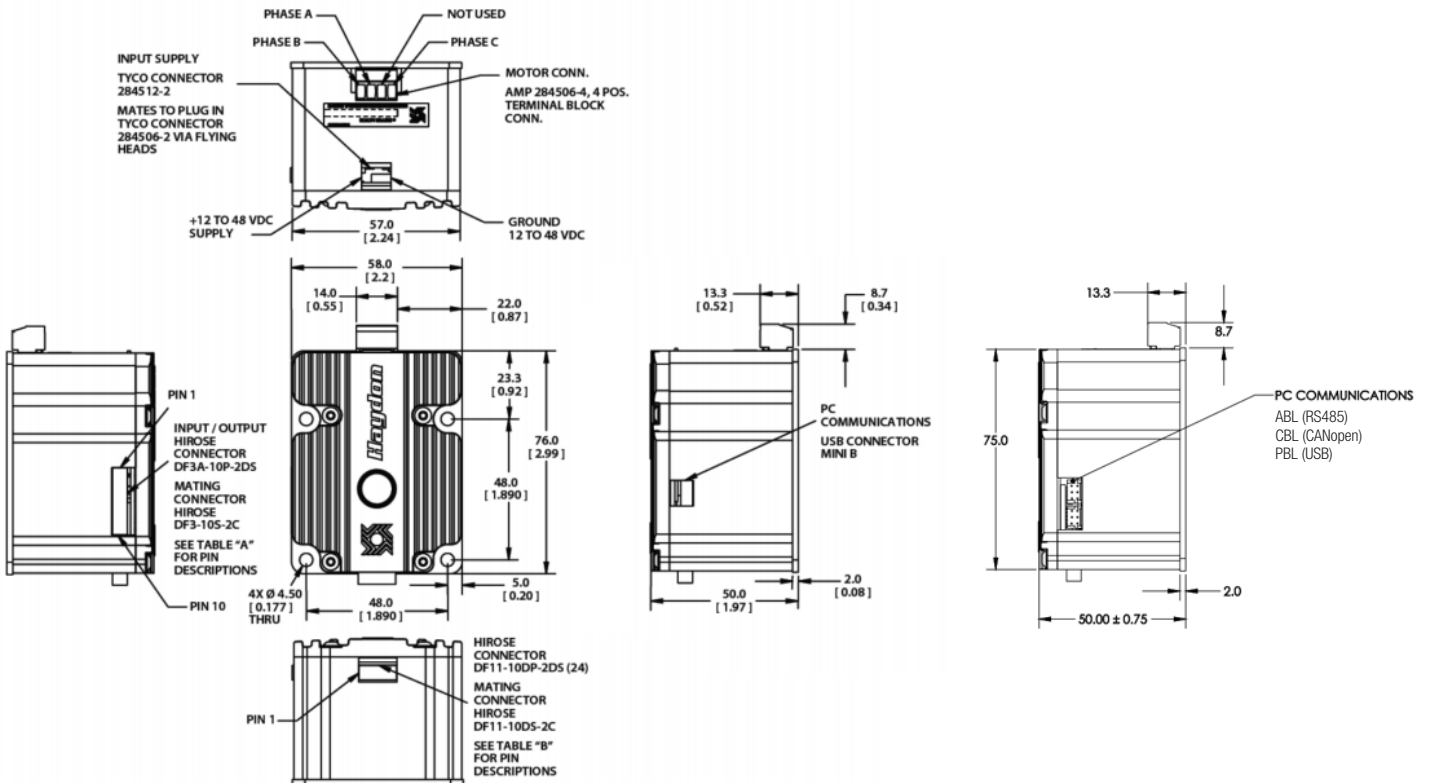
PIN	Description	Note
1	"A" CHANNEL	
2	HALL CELL A	
3	"B" CHANNEL	
4	HALL CELL B	
5	INDEX / ENCODER	
6	HALL CELL C	
7	+5 V DC	
8	+5 V DC	
9	GROUND	
10	GROUND	

Optional Accessories

Description	Part No.
USB Cable (A to Mini B), 2 meters	56-1346
Power Cable, 1 meter	56-1348
I/O Cable, 1 meter	56-1352
Motor Connector Screw Terminal	56-1570
Hall Cell & Encoder Cable	56-1856

Description	Part No.
RS485 Cable, 0.25 meter (9.84)	56-1536-1
RS485 Cable, 1 meter (39.37)	56-1536-4
USB to CANopen Cable, 2 meters (78.74) Use with 52-870 or 52-879	84-152
USB to RS485 Converter	UTR4852
USB to CANopen Converter	52-879
	52-870

Dimensional Drawing



BGE6005A Programmable Drive

The compact BGE6005A brushless motor drive is 4-quadrant servo controller designed for operation in speed, torque and position modes. Drive can operate as a stand-alone motion controller or as a slave in a CANopen network.



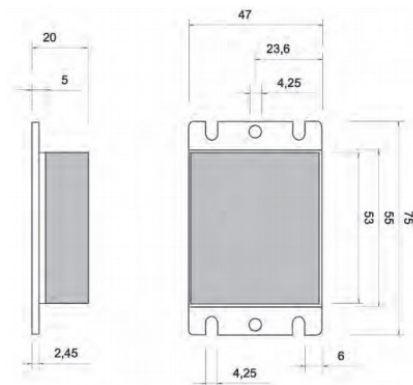
■ Benefits

- 4-quadrant servo controller
- Fully programmable control unit
- CANopen interface (DSP402)
- Protection against over-voltage, under-voltage and over-temperature
- Also capable of driving brushed type DC motors

■ Characteristics

Data	Units	Part No.
		BGE6005A
Voltage Range	V DC	10 to 60 V DC
Continuous Output Current	A	2 A rms
Peak Output Current	A	5.0 A rm
Digital Inputs		3
Digital Outputs		1
Analog Inputs		1 (0 to +10 V)
Communication		CANopen
Torque Mode		Yes
Speed Mode		Yes
Position Mode		Yes
Size	mm	75 x 47 x 20

Dimensional Drawing: BGE6005A



■ X2 Connector - Power Supply and Motor

PIN	Symbol	Description
1	+UP	Supply voltage power
2	GND	Earth for power supply
3	Ma	Motor connection A
4	Mb	Motor connection B
5	Mc	Motor connection C

■ X1 Connector - Sensors, Encoders and I/O

PIN	Symbol	Description
1	+UE	Supply voltage electronic
2	GND	Earth for electronic
3	AIN0	Analog input 0
4	DIN0	Digital input 0
5	DIN1	Digital input 1
6	DIN2/DOUT0	Digital input 2/ Digital output 0
7	CAN_HI	CAN high
8	CAN_LO	CAN low
9	H1	Hallsensor signal 1
10	H2	Hallsensor signal 2
11	H3/Inx	Hallsensor signal 3/Inc. Encoder Index
12	A	Inc. encoder track A
13	NB	Inc. encoder track B/
14	+UH	Power supply Hall/Enc+5V
15	GND	Earth for Hall/Encoder

BGE6015A Programmable Drive

The BGE6015A brushless motor drive is a larger 4-quadrant servo controller designed for operation in speed, torque and position modes. Drive can operate as a stand-alone motion controller or as a slave in a CANopen network.

Benefits

- 4-quadrant servo controller
- Fully programmable control unit
- CANopen interface (DSP402)
- Protection against over-voltage, under-voltage and over-temperature
- Also capable of driving brushed type DC motors

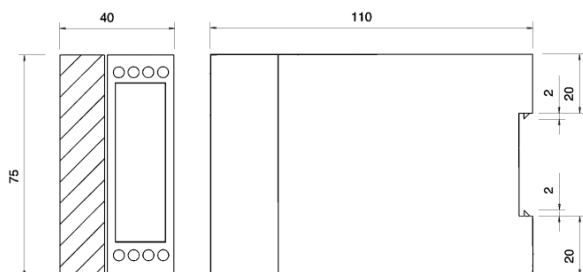
Characteristics

Data	Units	Part No.
		BGE6015A
Voltage Range	V DC	10 to 60 V DC
Continuous Output Current	A	9 A rms
Peak Output Current	A	15.0 A rm
Digital Inputs		5
Digital Outputs		1
Analog Inputs		1 (0 to +10 V)
Communication		CANopen
Torque Mode		Yes
Speed Mode		Yes
Position Mode		Yes
Size	mm	75 x 110 x 40

X1 Connector - Power Supply and Motor

PIN	Symbol	Description
1	PE	Earth
2	+UP	Power supply
3	GND	Ground 0V for power supply
4	Ma	Motor connection A
5	Mb	Motor connection B
6	Mc	Motor connection C

Dimensional Drawing: BGE6015A



X2 Connector - Hall Sensors and Encoders

PIN	Symbol	Description
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder channel A
5	B	Inc. encoder channel B
6	INX	Inc. encoder index channel
7	+UH	Power supply hall/encoder +5V
8	/H1	Hall sensor 1 inverted
9	/H2	Hall sensor 2 inverted
10	/H3	Hall sensor 3 inverted
11	/A	Inc. encoder channel A inverted
12	/B	Inc. encoder channel B inverted
13	/INX	inc. encoder index channel inverted
14	GND	Ground 0V for power supply hall/encoder

X3 Connector - Analog and Digital I/O

PIN	Symbol	Description
1	+UE	Power supply electronic
2	+AIN 0/DIN4	+ Analog input/ digital input 4
3	DIN 0	Digital input 0
4	DIN 1	Digital input 1
5	DIN 2	Digital input 2
6	DIN 3	Digital input 3
7	GND	Ground 0V for power supply electronic
8	-AIN 0	Analog input
9	DOUT 0	Digital output 0
10	CAN_HI	CAN high
11	CAN_LO	CAN low
12	CAN_GND	CAN ground



BGE6050A Programmable Drive

The BGE6060A brushless motor drive is the largest Pittman 4-quadrant servo controllers designed for operation in speed, torque and position modes. Operates as a stand-alone motion controller or as a slave in a CANopen network.

Benefits

- 4-quadrant servo controller
- Fully programmable control unit
- CANopen interface (DSP402)
- Protection against over-voltage, under-voltage and over-temperature
- Also capable of driving brushed type DC motors

Characteristics

Data	Units	Part No.
		BGE6060A
Voltage Range	V DC	10 to 60 V DC
Continuous Output Current	A	60 A rms
Peak Output Current	A	160.0 A rm
Digital Inputs		6
Digital Outputs		2
Analog Inputs		2 (0 to +10 V)
Communication		CANopen
Torque Mode		Yes
Speed Mode		Yes
Position Mode		Yes
Size	mm	100 x 111 x 30

X1 Connector - Power Supply and Motor

PIN	Symbol	Description
1	PE	Earth
2	+UP	Power supply
3	GND	Ground 0V for power supply
4	Ma	Motor connection A
5	Mb	Motor connection B
6	Mc	Motor connection C

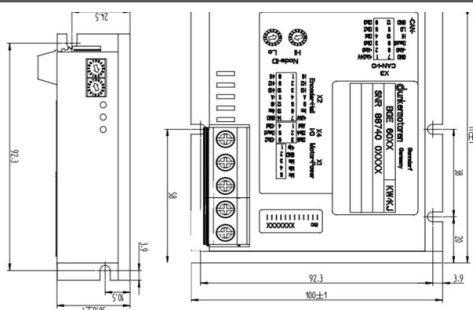
X2 Connector - Hall Sensors and Encoders

PIN	Symbol	Description
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder channel A
5	B	Inc. encoder channel B
6	INX	Inc. encoder index channel
7	+UH	Power supply hall/encoder +5V
8	/H1	Hall sensor 1 inverted
9	/H2	Hall sensor 2 inverted
10	/H3	Hall sensor 3 inverted
11	/A	Inc. encoder channel A inverted
12	/B	Inc. encoder channel B inverted
13	/INX	inc. encoder index channel inverted
14	GND	Ground 0V for power supply hall/encoder

X3 Connector - Analog and Digital I/O

PIN	Symbol	Description
1	+UE	"Power supply electronic "
2	+AIN 0/DIN4	+ Analog input/ digital input 4
3	DIN 0	Digital input 0
4	DIN 1	Digital input 1
5	DIN 2	Digital input 2
6	DIN 3	Digital input 3
7	res.	Reserved pin
8	-AIN 0	Analog input
9	DOUT 0	Digital output 0
10	CAN_HI	CAN high
11	CAN_LO	CAN low
12	CAN_GND	CAN ground

Dimensional Drawing: BGE6060A



B30A Brake

The B30A power off, fail safe holding brake is designed to hold a load in position when power is removed from the motor and brake. This compact 30 mm brake has a holding torque of 0.113 Nm (1 lb-in). The B30A is typically mounted to the motor rear.

Benefits

- Holding torque of 0.113 Nm
- Factory-set precision air gap
- Low profile mounting plate
- Rigid molded friction disk
- High rate compression spring
- MIL-W-22759/34D lead wires
- Hexagonal drive nut with set screw



Characteristics

Data	Units	12V	19V	24V	30V
Applied Voltage	V DC	12	19	24	30
Static Holding Torque	lb-in	1			
	Nm	0.113			
Current	Amps	0.33	0.21	0.17	0.13
Resistance	Ohms	36	90	134	219
Hub and Disc Inertia	oz-in-sec ²	4.0 x 10 ⁻⁵			
	kg-m ²	2.82E-2			
Weight	oz	2.2			
	g	62.4			

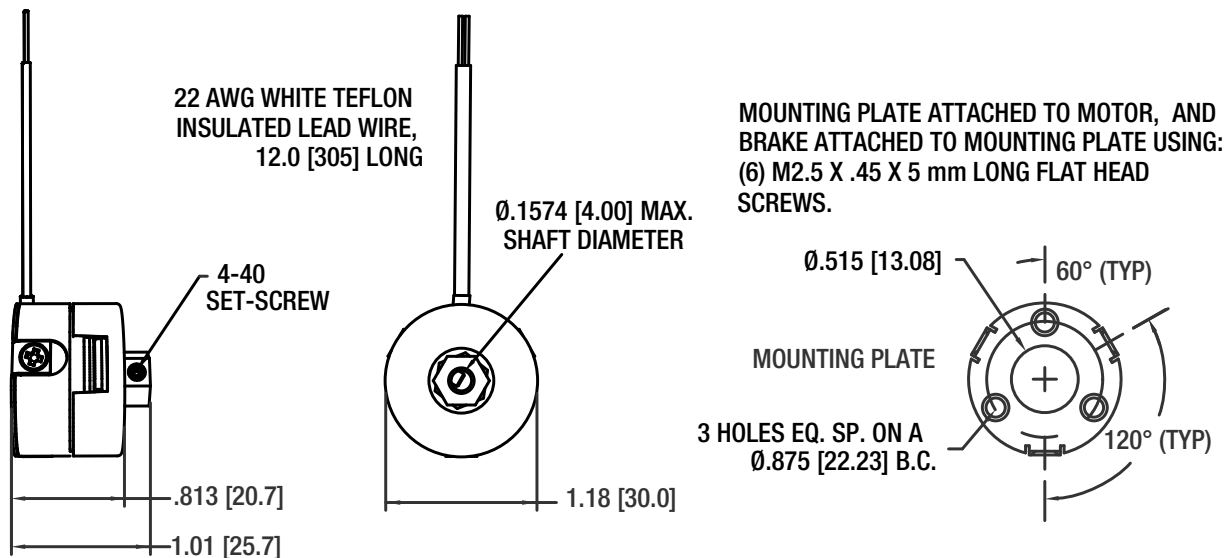
Compatible DC Motor

- DC026C
- DC030B
- DC030C
- DC040B
- ES030A
- ES040A

Mounting

- 3 holes eq. space on a 0.875 in (22.23 mm) BC

Dimensional Drawings: B30A





B49A Brake

Designed to hold a load in position when power is removed from the motor and brake, the B49A power off, fail safe holding brake is typically mounted to the motor rear. This brake has a holding torque of 3 lb-in.

Benefits

- Factory-set precision air gap
- High rate compression spring
- Rigid molded friction disk
- Square drive nut with set screw

Compatible DC Motors

- DC040B
- DC054B
- EC057C
- ES040A
- ES050A

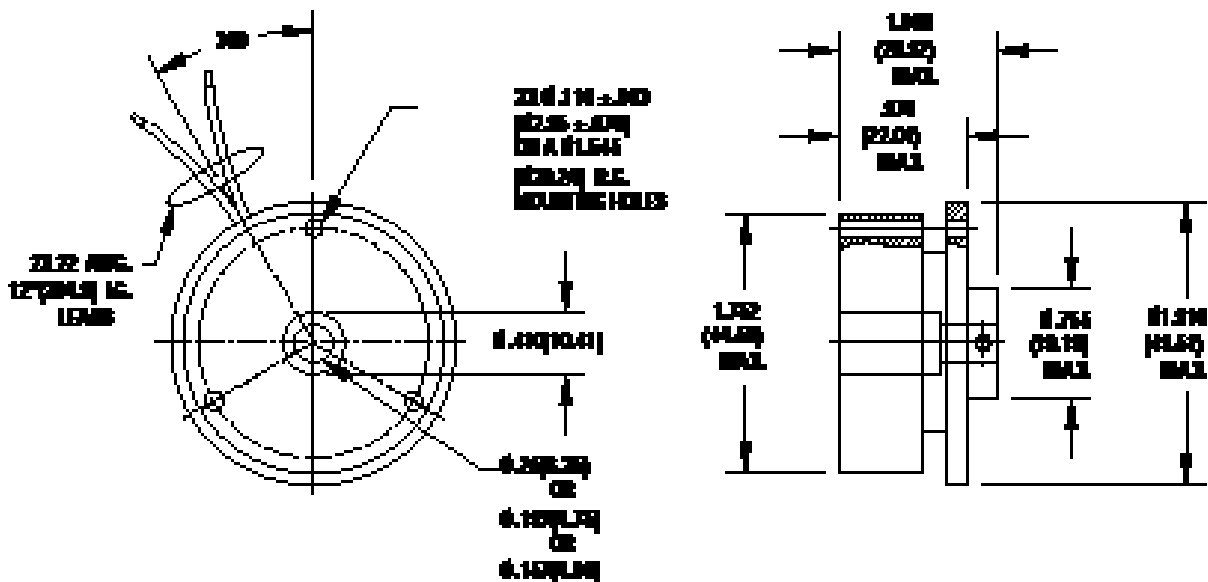
Mounting

- 3 holes eq. space on a 0.875 in (22.23 mm) BC

Characteristics

Data	Units	12V	24V
Applied Voltage	V DC	12	24
Static Holding Torque	lb-in	3	
	Nm	0.339	
Current	Amps	0.353	0.190
Resistance	Ohms	34	132
Hub and Disc Inertia	oz-in-sec ²	7.0 x 10 ⁻⁵	
	kg-m ²	4.94E-2	
Weight	oz	3	
	g	85	

Dimensional Drawings: B49A



Customization

Our dedicated team at Haydon Kerk Pittman takes great pride in designing and developing customized solutions for your application needs. Our design and development engineers engage with you to develop ideal solutions using the Haydon Kerk Pittman building blocks. Then, we apply our manufacturing capabilities to produce higher-level solutions that reduce your system design complexity, cost, and lead time.

Our advanced engineering and application expertise enable us to quickly design and manufacture customized motion solutions. We specialize in single- and multi-axis systems using our own, off-the-shelf or custom-designed components to your specifications. With our vertically integrated in-house manufacturing, we produce high-precision motion systems at all levels of sophistication, with integration that provides necessary mechanical, electrical and software features.

■ Motor Options

- Encoders
- Drives
- Custom Cables
- Gearboxes
- Brakes
- Integration of Haydon Kerk rails, lead screw and nut assemblies
- Integration of customer-defined parts

No matter the complexity, our team is committed to partnering with you to help achieve your objectives. Email us today at info.pittman-motors@ametek.com to discuss your customization needs or visit www.haydonkerkpittman.com to explore the possibilities.





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